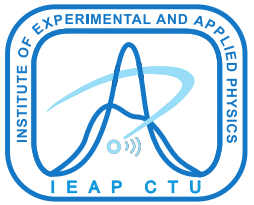
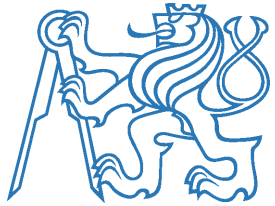




Integrating Track Lab with Constellation for distributed DAQ of Timepix3 and Timepix4 detector networks

Petr Mánek[1,2], Benedikt Bergmann, Stephan Lachnit, Simon Spannagel, Peter Švihra

[1]Institute of Experimental and Applied Physics, Czech Technical University, Prague
[2]Department of Physics and Astronomy, University College London

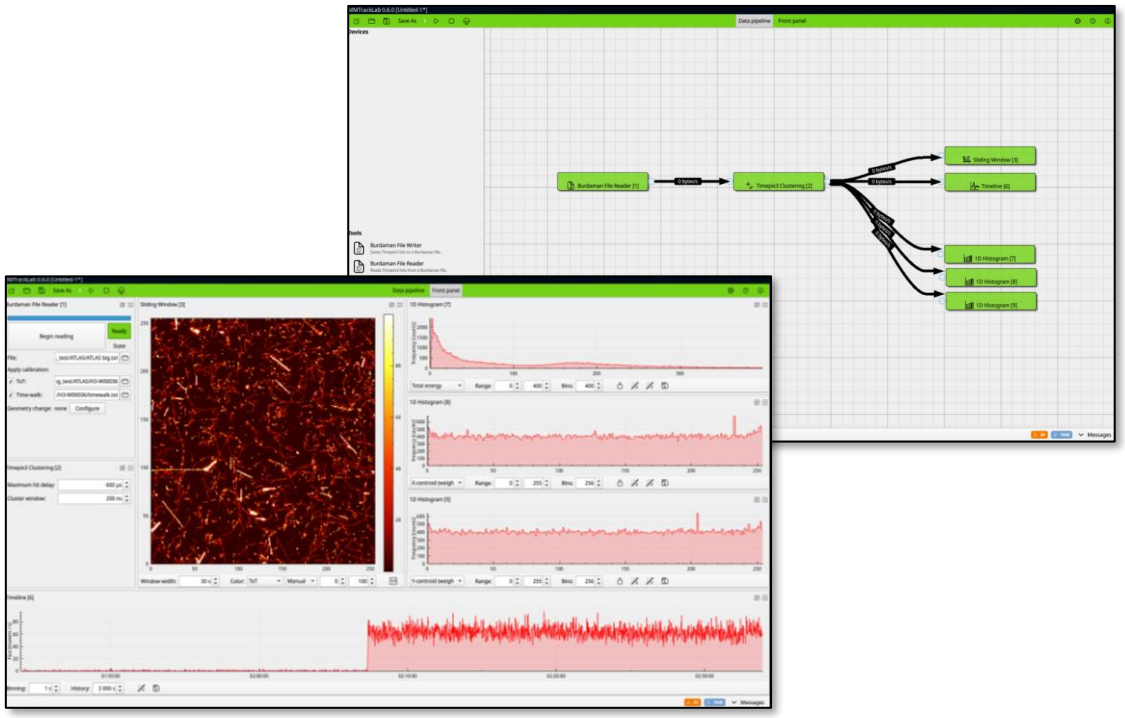
On the menu today…

- Recap of the Track Lab concept
- Current hardware support
- Proposal to integrate with Constellation:
  - Multi-threaded vs. multi-process architecture
  - Distributing computational load
  - Physically detached experiments
  - Interoperability between languages and platforms
  - Finite-state machines
- Summary, request for comments

Previously featured at DRD3:
- 06/2024: High-performance software package for Timepix3 data acquisition, online analysis and automation

Recap of the Track Lab concept

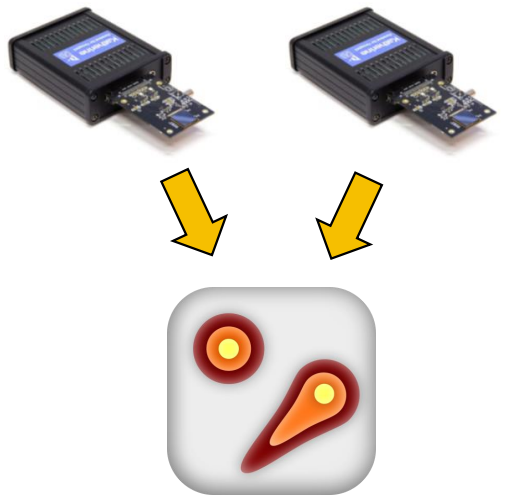
- Data acquisition (DAQ) and analysis software for pixel detectors
- Analysis composed of single-purpose building blocks



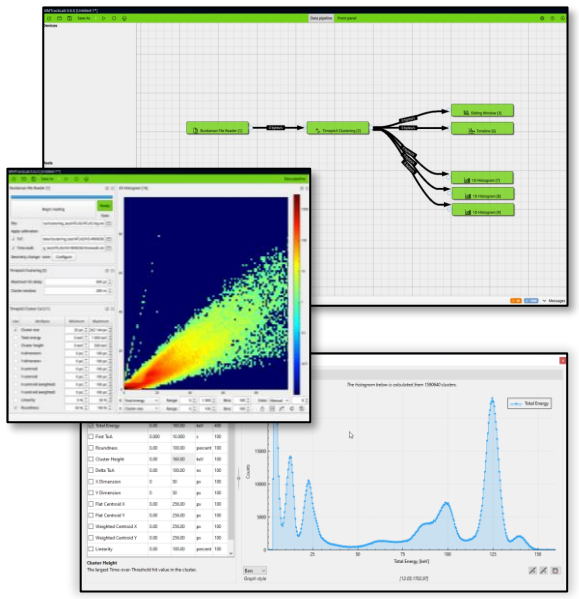
Aiming for:

- High performance: scaling
- Versatility: arbitrary topologies
- Extendibility: plug-in system

What can Track Lab do?



Take data from detectors

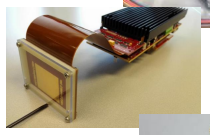


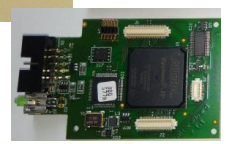
Run analysis in real-time

Automate repetitive tasks

Photo credit: University of West Bohemia, Standa LTD, Amptek Inc., Universal Robots A/S

Hardware: current support





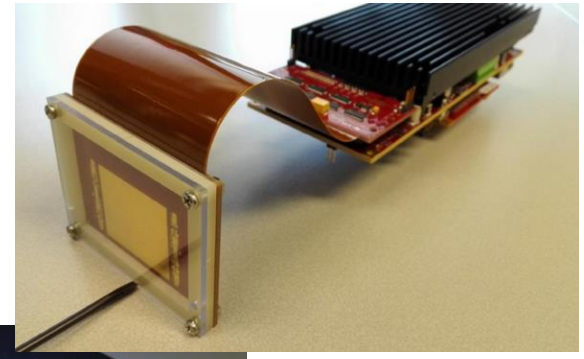
Readout	Sensor(s)	Connection
Katherine Gen1	1x Timepix3	1 Gbit Ethernet
	1x Timepix2	1 Gbit Ethernet
Katherine Gen2	8x Timepix3	1 Gbit Ethernet
		USB 3
		PCIe 3 x4
HardPix	1x Timepix3	USB 3
SPIDR4	1x Timepix4	10 Gbit Ethernet
COMBO+Spectrig	1x SiPM	USB 2
MicroDAQ	28x PMT	1 Gbit Ethernet

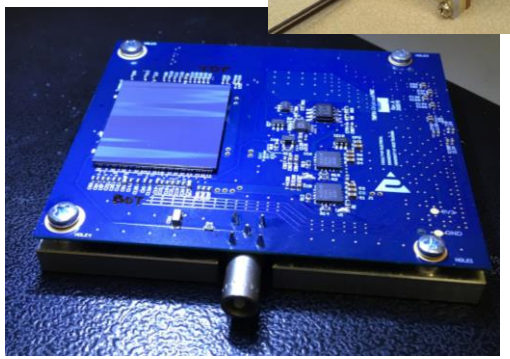
Readout	Sensor(s)	Conn.
Timepix2 Lite	1x Timepix2	USB 2
MiniPIX EDU	1x Timepix	USB 2
MiniPIX	1x Timepix	USB 2
	1x Timepix2	USB 2
	1x Timepix3	USB 2
AdvaPIX	1x Timepix	USB 3
	1x Timepix3	USB 3
WidePIX L	10x Medipix3	1 Gb. E.

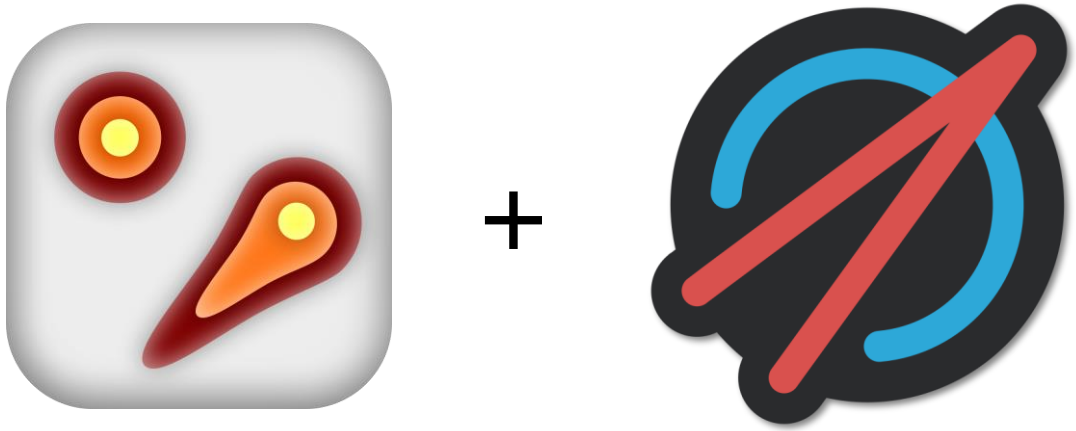
Tested / in development / planned

Hardware: outlook for 2025

- Currently working on:
  - SPIDR4: API partially implemented, prototype expected in Jan 2025.
  - Katherine for Timepix4: before Nov 2024 final hardware unavailable, we plan to start software tests in Dec 2024.
- Also working on hardware plugins for:
  - Seifert high voltage generator for X-ray tubes
  - Stepper motor controllers by Phytron and PI
  - Advacam readouts: AdvaPIX, WidePIX





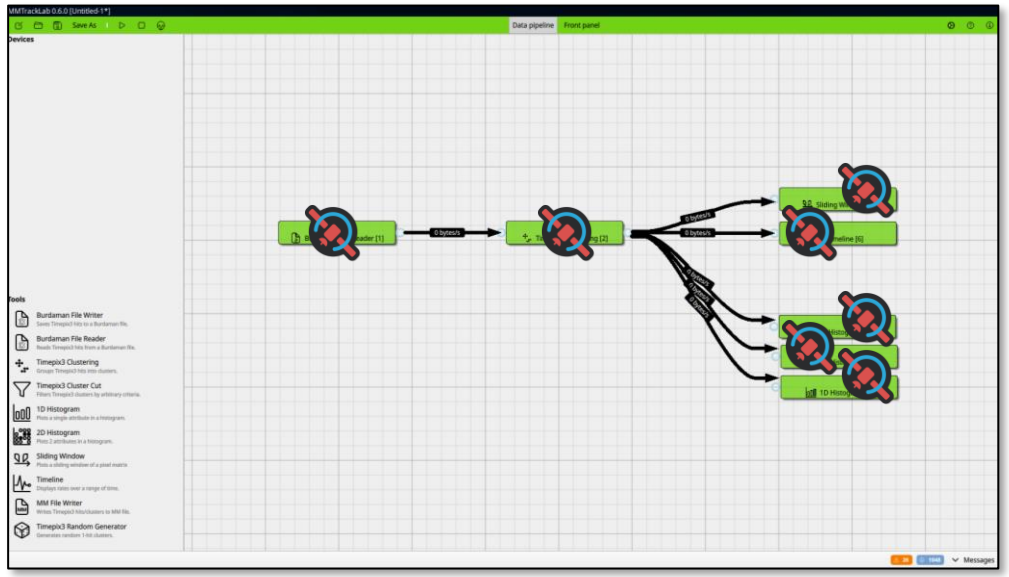


A proposal to integrate Track Lab with Constellation

Logo credit: DESY and the Constellation authors

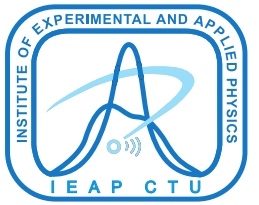
How would it work?

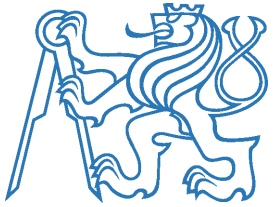
- Satellites ↔ data processing elements in the workflow
- ZeroMQ data handling ↔ ZeroMQ data handling
- Satellite state machine ↔ Track Lab state machine
- Controller ↔ Track Lab core



Logo credit: DESY and the Constellation authors

Multi-threaded vs. multi-process



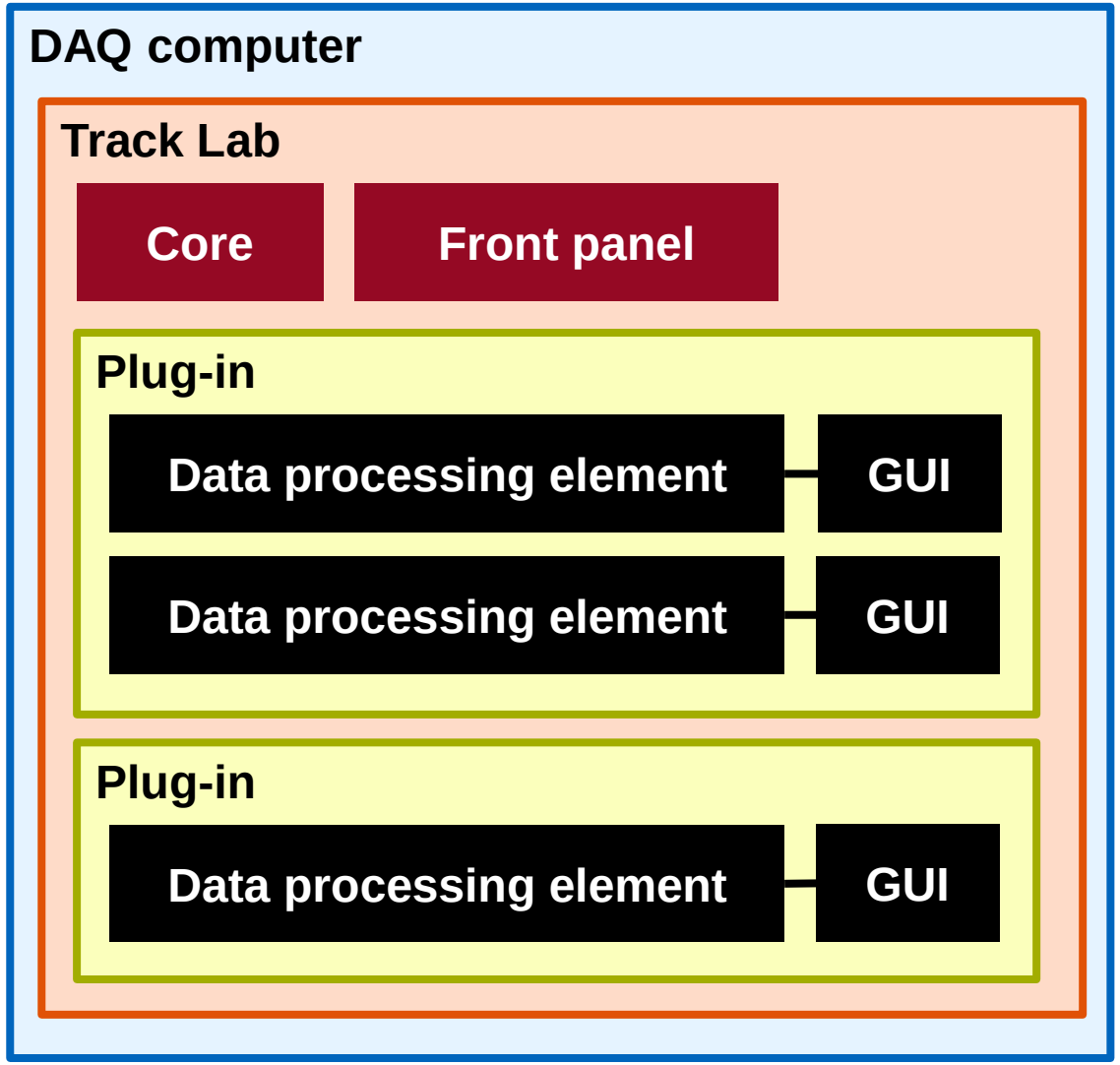


- Now: all plug-ins run within the same process
  - Easy (and fast) to share memory between threads.
  - Easy to synchronize activities, start and stop.
  - Failure of a single plug-in takes down the entire program.

- Future: plug-ins instantiated in separate processes
  - Memory sharing not affected within plug-ins, otherwise a problem.
  - Still easy to synchronize thanks to the state machine.
  - Increased resiliency, but added overhead for error handling.

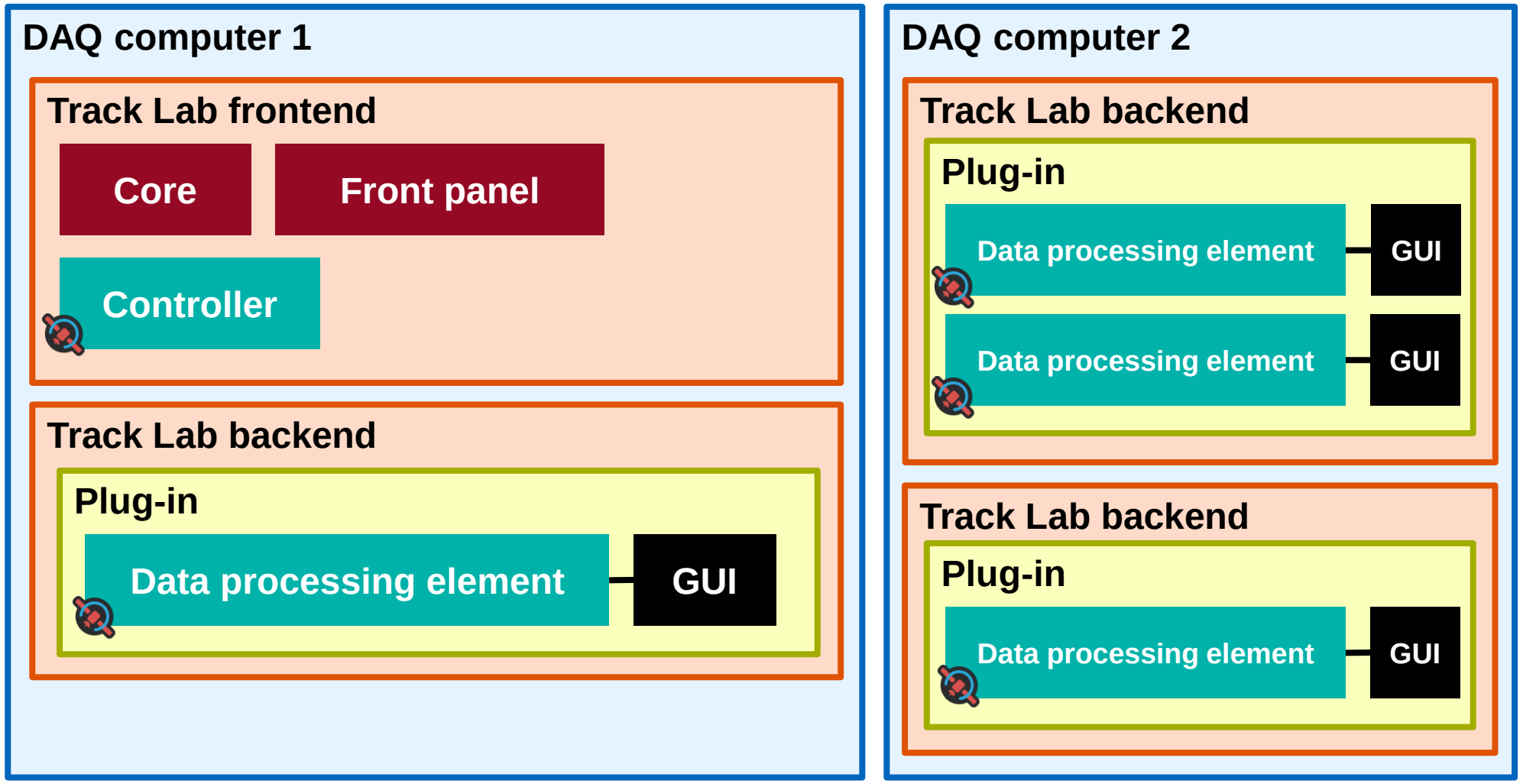
Multi-threaded vs. multi-process

- Now:



Multi-threaded vs. multi-process

- Future:



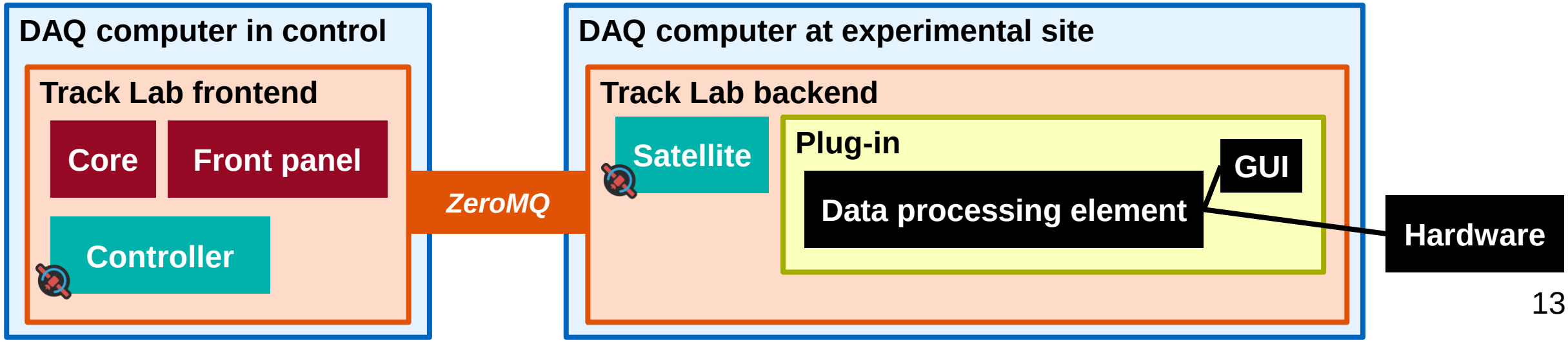
Logo credit: DESY and the Constellation authors

Distributing computational load

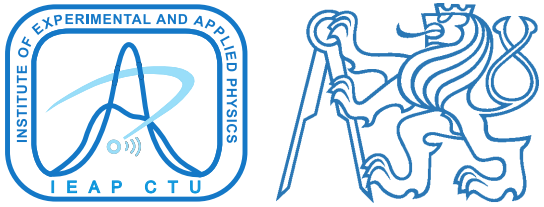
- Running plug-ins in processes allows to employ more CPUs.
- 2 main challenges:
  - Compatibility – will be verified and guaranteed by backend.
  - Lossy comm. channels – will need a reliable layer on top of ZeroMQ.
- What if a process exits/crashes:
  - Frontend – no problem, data acquisition continues in headless mode.
  - Backend – plug-ins hosted by the backend process fail.

Physically detached experiments

- This architecture can implement measurement networks.
  - Frontend operates at a console computer in the control room.
  - Backends are deployed close to hardware.
    …or even better: backends embedded inside instruments!
- For vast distances: tunnel ZeroMQ sockets over WireGuard.



Interoperability between languages and platforms

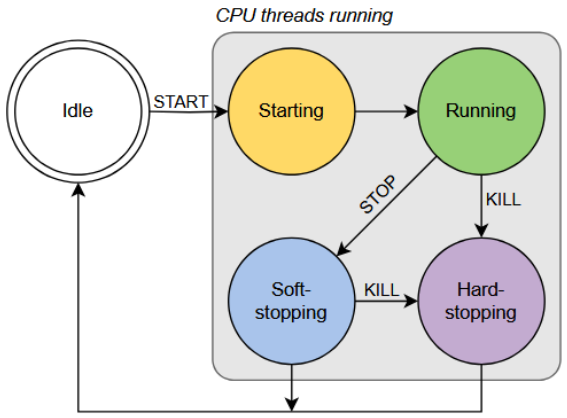


- Now: core and all plug-ins are coded in C++
  - …required by running in the same process and sharing STL.
- Future: plug-ins could be developed in any language, as long as ZeroMQ data exchange conforms to specification.
- This is not granted, it will depend on interactions between the backend process and plug-ins.
- Ideally have a small C library with many bindings, which can be linked from major programming languages.
- Particularly interesting: Python scripts!

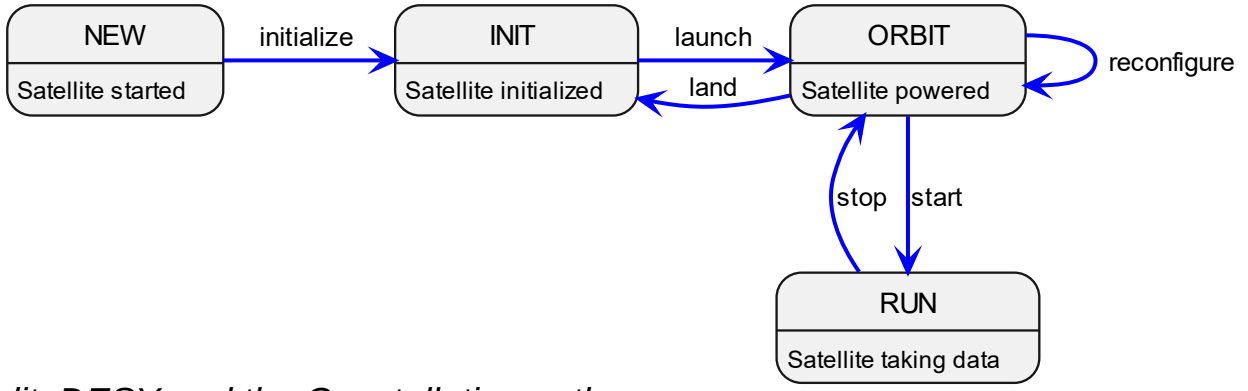
Finite state machines (FSM)

- Both programs use FSM to synchronize states of its elements.
- Track Lab's FSM can be adapted for Constellation.
  - Potential issue when stopping: land vs. soft/hard stop.
  - We can interpret hard stop as 'safe' state.

Track Lab FSM:



Constellation FSM:



Credit: DESY and the Constellation authors

Technical footnotes

- Build systems:
  - Track Lab uses cmake
  - Constellation uses meson
- Remote GUI handling: need to deliver Qt signals over sockets
  - Should GUI component of each plug-in to be serviced in frontend?
  - Should it be serviced in backends?
- Platform compatibility checks out: Windows, Linux, macOS
- Long term: support for ‘alien’ satellites?

Summary, request for comments

- Track Lab has been growing steadily for 4 years, the current version is 1.5 (Oct 2024). We have lots of plans for 2025.
- This proposal is currently under consideration. If adopted, it can be viewed as a roadmap to the next major release (2.0).
- No illusion that this would be easy to implement, but:
  - We anticipate that our current architecture may become a bottleneck.
  - Track Lab was originally designed with this type of deployment in mind.
  - Constellation provides an environment favorable to scaling up.
- We would like to request feedback on this proposal.

Thank you for listening!

Petr Mánek, petr.manek@utef.cvut.cz

Try out Track Lab now:

Download v1.5 from
https://software.utef.cvut.cz

Minimum requirements:

- glibc 2.35 [x86_64, aarch64]
- Windows 10 [x86_64, arm64]
- macOS Monterey [x86_64, M1]

See article for details:

Available in J. Inst.
or arXiv:2310.08974