

Summer Student Project

Test Beam Analysis for HGTD Sensors

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Outline:

1. Introduction:

The High Luminosity LHC, HGTD, LGAD.

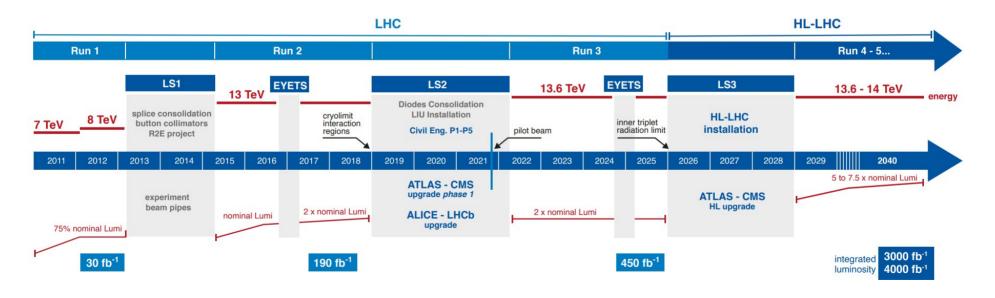
2. Setup: Test-Beam

3. Analysis and Results: Sensors Characterization

4. Conclusions

From 2026, LHC will be upgraded and in 2029, LHC will run in "High Luminosity" (HL-LHC)

- Instantaneous **luminosity** will be approximately a factor of ~5-7.5 higher than the LHC nominal values.
- Average number of interactions per bunch crossing (pileup events) reaches 200.
- Harsh radiation environment.
- ATLAS experiment also needs to be upgraded to meet the new requirements.



Introduction: The High Granularity Timing Detector (HGTD)

- Two instrumented double-sided layers mounted in two cooling/support disks per end-cap.
- Placed at z ≈ ±3.5 m from the nominal interaction point.
- Total radius **110 < r < 1000 mm**.
- Active detector region: 2.4 < |η|< 4, 120 mm < r < 640 mm. η is the pseudorapidity.
- Time resolution ~30-50 ps per track (start-finish).

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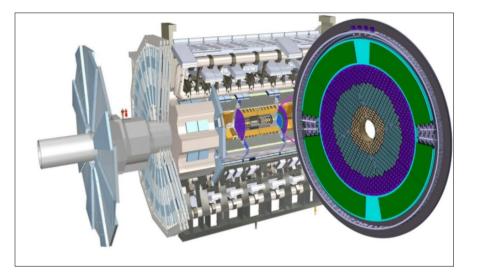


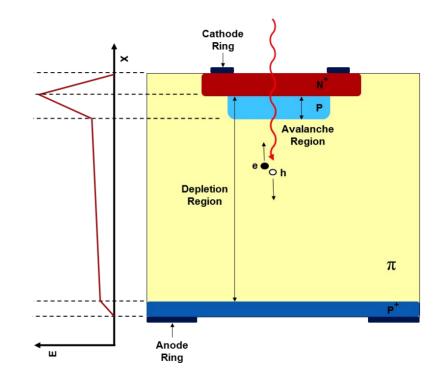
Figure 3: HGTD inserted in ATLAS.

• Although a track may appear to align spatially with a particular vertex, differences in the track's time and the selected vertex's time can be used to identify and discard pile-up tracks.

A good time resolution of HGTD will be achieved by using the *Low Gain Avalanche Detectors* (LGAD), the new semiconductor sensors technology meant for precise timing measurements.

Sensor technology: Low Detector (LGAD)

- **n-p Si** detector with an additional **p-type doped layer.**
- Excellent time resolution < 40 (50) ps pre-irradiation (after-irradiation).
- Expected charged collected larger than **15 (4) fC** preirradiation (after-irradiation).
- Hit efficiency > 95% at the end of lifetime.



Set-Up: Test-Beam

General Objective:

Characterization of the LGAD performance using Test Beam Data.

- Measuring Time Resolution
- Measuring Collected Charge
- **Test Beam Description:**

For this work were used the data obtained by 8 LGAD sensors for different design and fluency.

- Two design: USTC and IHEP. ۶
- Different Fluencies: ≻ 0, 1.5x10¹⁵, 2.5x10¹⁵ neg/cm²



Pions

From SPS

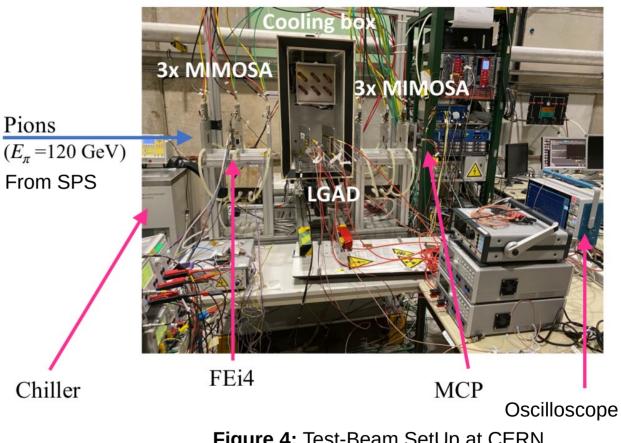
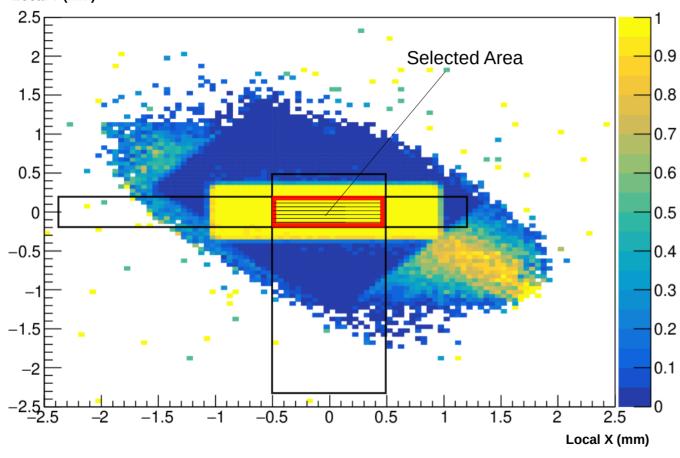


Figure 4: Test-Beam SetUp at CERN.

MCP: Micro Chamber Plate

Analysis and Results: 2D Plots of Local X vs Local Y



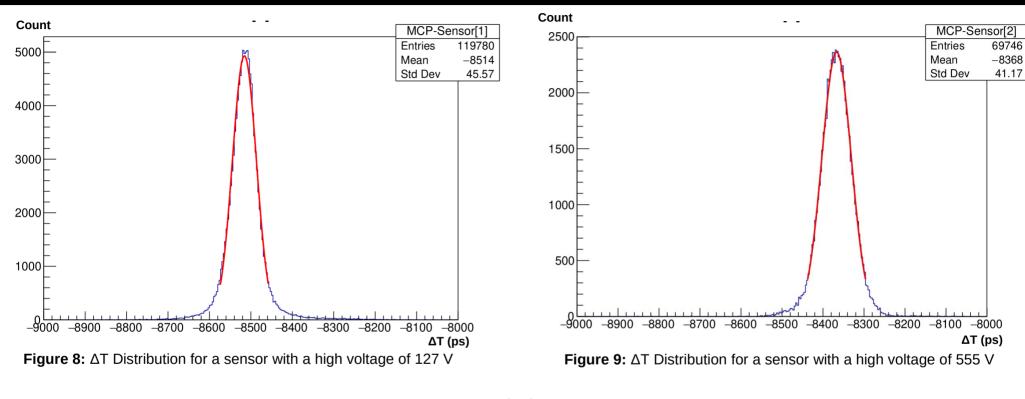


Explanation:

- In order to reduce the contribution of noise, events that pass through the center of the sensor are used for analysis.
- For each sensor **a cut in the** Local X and Local Y variables were applied.
- This same analysis was done with all of the sensors.

Figure 7: Charge Efficiency Plot for a irradiated sensor with a High Voltage of 150 V

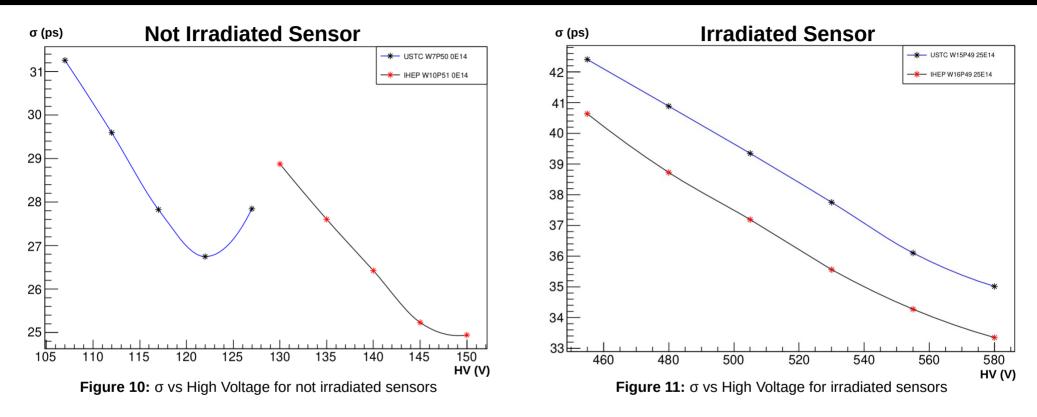
Analysis and Results: ΔT (MCP and Sensor Time Difference)



- $\Delta T = tCFD_{MCP} tCDFD_{sensor}$
- Gaussian Fit

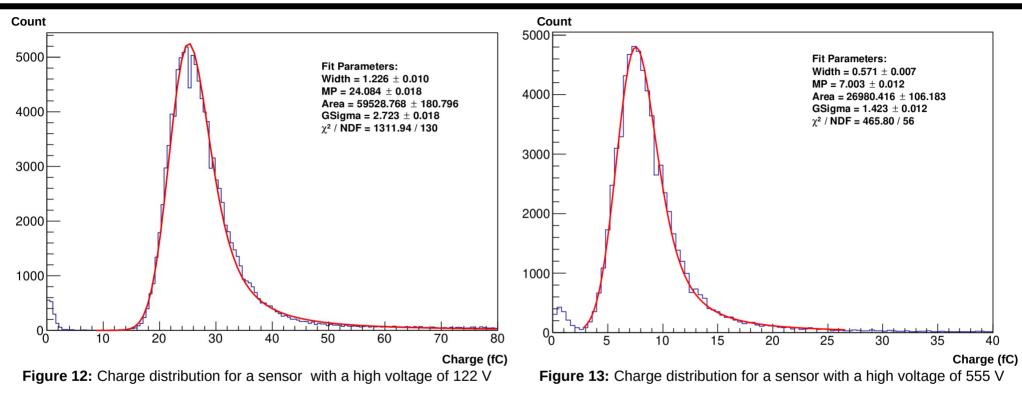
MCP resolution =
$$\sigma_{MCP}$$
 = 10.6 ps

Analysis and Results: ΔT vs High Voltage (HV)



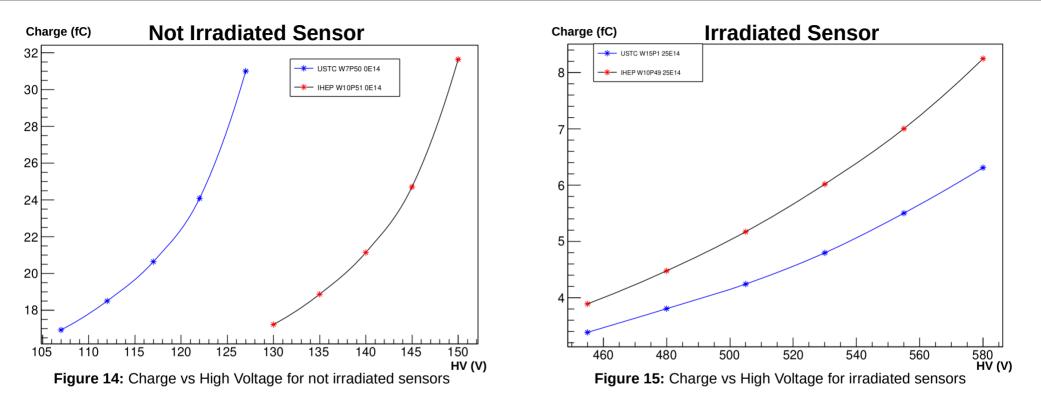
- As the voltage increase, the resolution improves.
- At some point, the HV is so high that the resolution gets worse.
- The irradiated and not irradiated sensors behave as expected.

Analysis and Results: Collected Charge



- Fit with Landau-Gaussian convolution Distribution.
- From the fit Parameters was taken the Most Probable value (MP).
- This plots were repeated with all the sensors.

Analysis and Results: Collected Charge vs High Voltage (HV)



- As the HV increase, the collected charge also increase for irradiated and not irradiated sensors.
- This behavior is expected for all the cases.

Conclusion

• **8 LGAD sensors** with **different fluence** and from different vendors were Characterized.

-Events passing at the center of the LGAD were selected in the analysis to reduce the noise contribution.

- -Time resolution and collected charge as a function high voltage were studied.
- Time resolution and collected charge as a function high voltage was studied. **All sensors meet the requirements:**
 - -Collected charge > 15 fC (4fC) for not irradiated (irradiated) sensor
 - -Time resolution > 40 ps (50 ps) for not irradiated (irradiated) sensor

• Next steps:

-Study other sensor characteristics, i.e. efficiency, size of the sensor -Actively participate to test-beam.

Thank You!

The Pile-up will be caused by the increase of the instantaneous luminosity

- Pile-up <> = 200 interactions per bunch crossing, spread in ~45 mm along the beam axis.
- The Inner Tracker (ITk) mostly mitigates the pile-up effect but is still challenging in the forward region.
- To discriminate between pile-up and hard scattering interaction, the HGTD will be added in the forward region with the goal to have **30-50 ps** per track time resolution (beginning-end).
- By utilizing both spatial and timing information, we can confidently link tracks to vertices in the forward region.

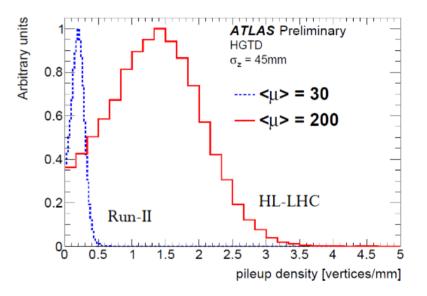
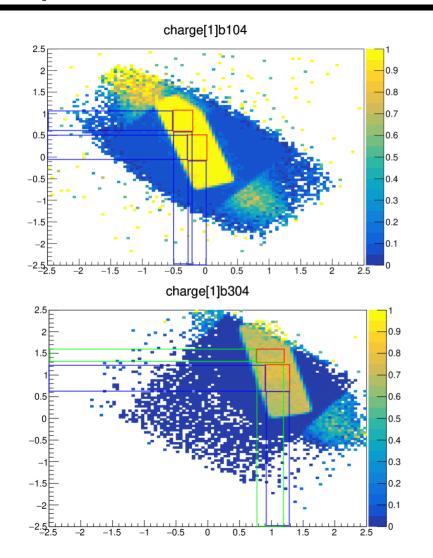
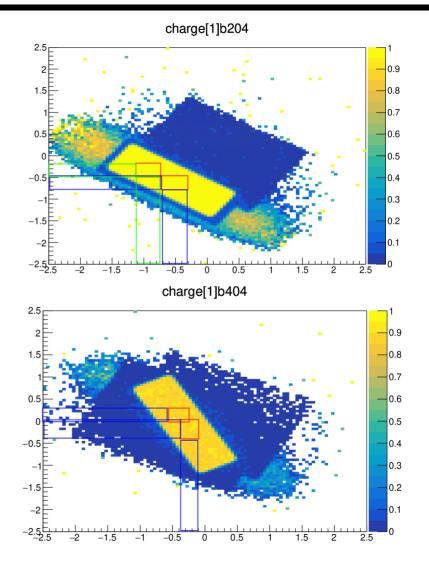


Figure 2: Pile-up differences.

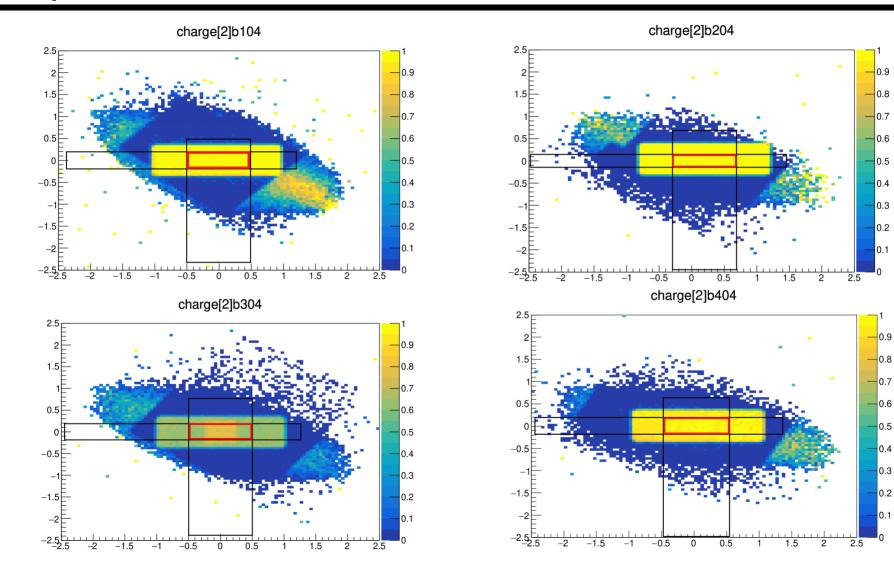
| Table of Sensors | | |
|------------------|-------------------|-------------------|
| Batch | Sensor 1 | Sensor 2 |
| 1 | USTC W7P50 0E14 | IHEP W16P52 15E14 |
| 2 | IHEP W16p43 0E14 | IHEP W16P52 15E14 |
| 3 | USTC W15P49 25E14 | IHEP W16P49 25E14 |
| 4 | USTC W15P1 25E14 | IHEP W10P49 25E14 |

Back-Up: 2D Plots of Local X vs Local Y for Sensors 1

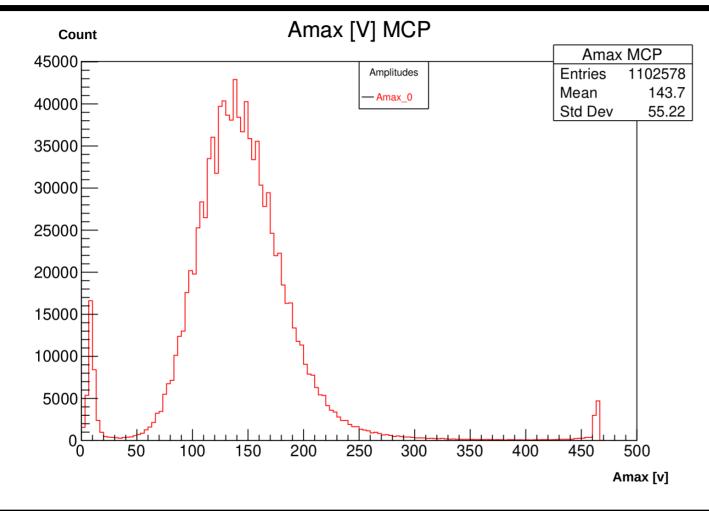




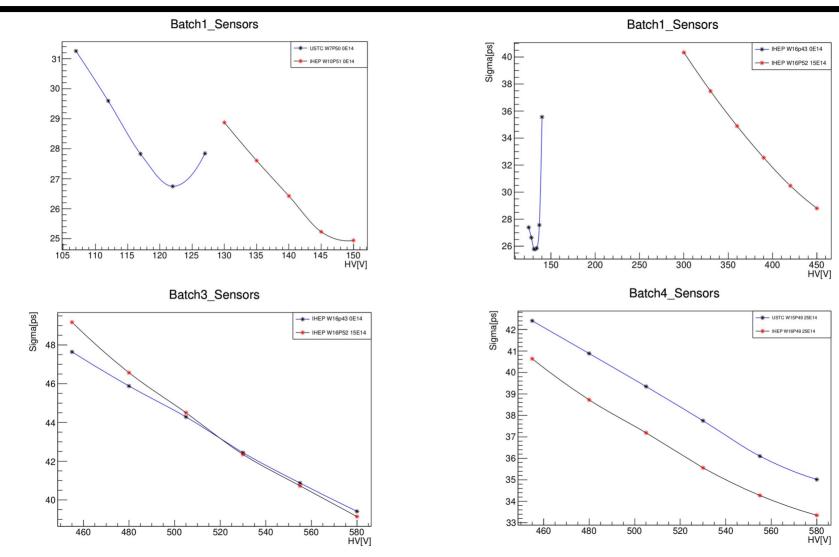
Back-Up: 2D Plots of Local X vs Local Y for Sensors 2



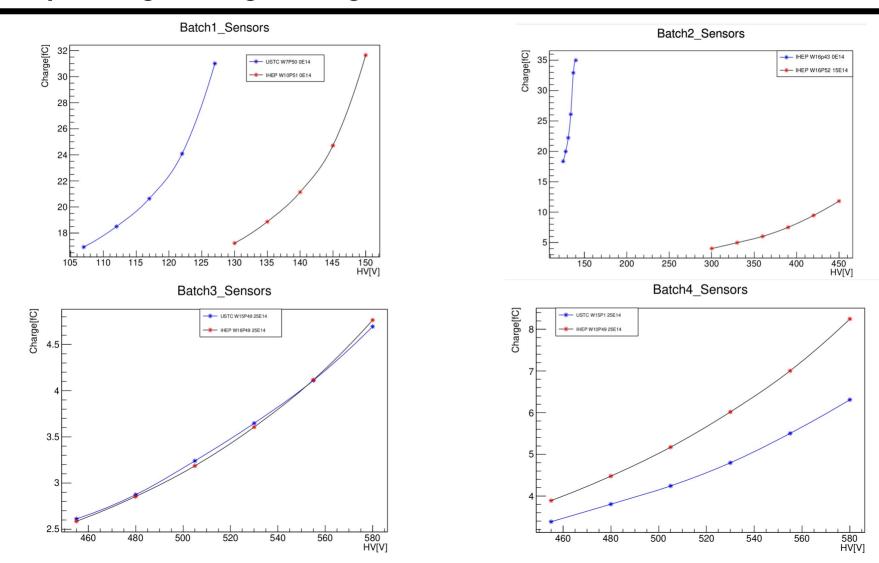
Back-Up: Maximum Amplitude for MCP [V]



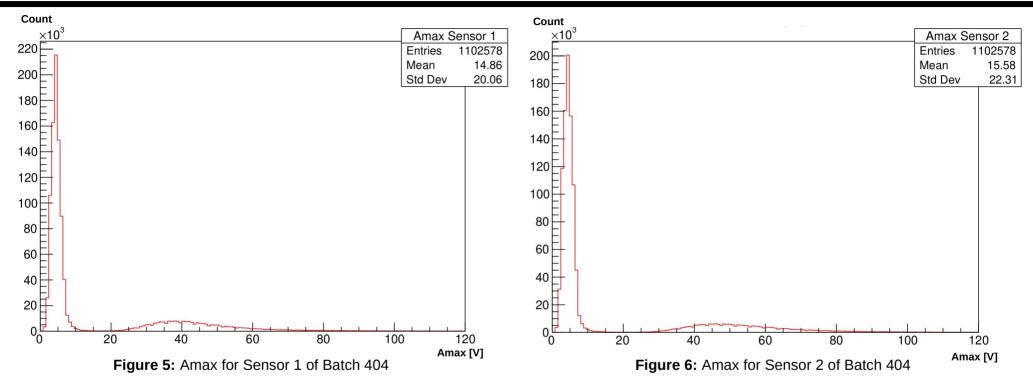
Back-Up: ΔT vs High Voltage



Back-Up: Charge vs High Voltage



Back-Up: Voltage Maximum Amplitude (Amax)



- The plots shows that there's always a big contribution in Amax due to noise.
- The higher the radiation damage, the smaller the Amax.
- For Highest fluence sensor the cut on Amax cannot separate signal from noise.

Introduction: HGTD Performance Example

