





EasyTracker II

ATLAS Forward Proton - SFT

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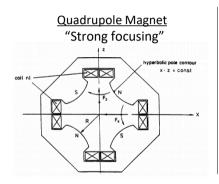
Supervisors: Dr. Tomas Sykora (Charles University)

Dr. Andrea Dell'Acqua (CERN)



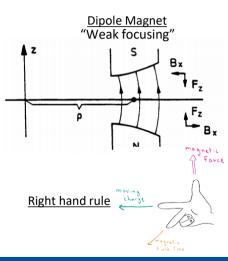


Accelerator optics



Lorentz Force equation

$$F = q \left[E + (v \times B) \right]$$



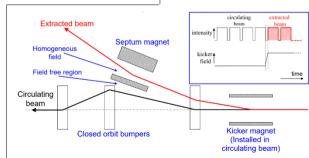


Accelerator optics

Focusing-defusing lenses s

Kicker For injedaseand extraction of the beam.

- Nominal particle along the central axis experiences no force.
- Other deviations are kept within the beam envelope.
- Travels in two directions around the ring.

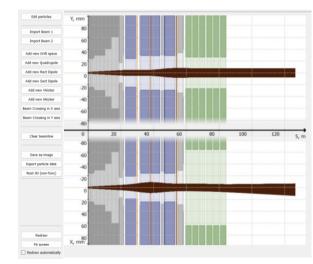




What is EasyTracker?

Software designed for real time visualisation of simulated beam optics and detector acceptance.

Figure (right): The graphical user interface (GUI) that users can see, interact with and edit in real time. The accelerator setup can be imported from input accelerator optics (TWISS) files.







What is EasyTracker?

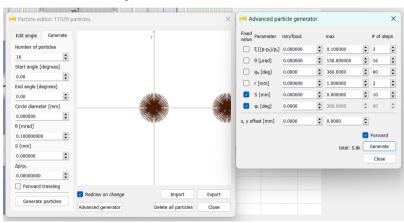


Figure: Controls to generate kinematics of the input particles (protons).





EasyTracker outputs

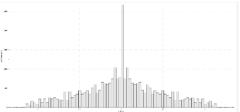
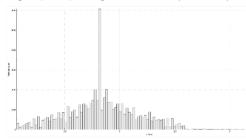


Figure (above): Histogram of x with respect to frequency.



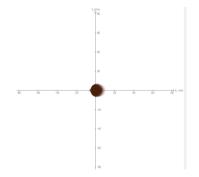


Figure (above): X and Y projection of simulated particles at this data plane.

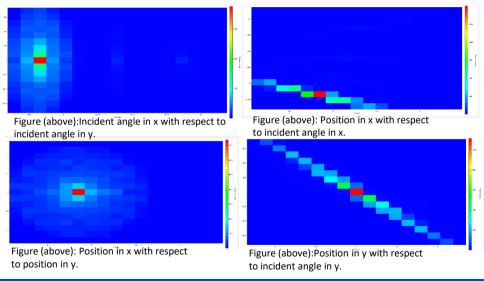
Figure (left): Histogram of y with respect to frequency.





August 9, 2024

EasyTracker outputs



CERN









Why is it needed?

The current industry standard is *MAD-X*, it does: "basic layout, design, and optimization of optics and for doing basic particle tracking and sensitivity analyses of beam lines, synchrotrons, storage rings, etc,"- <u>US Particle Accelerator</u>

School

300 pages of introductory documentation.

 No interactive user interface (as far as I know).

```
640 MSS : SEXTUPOLE, L := 1.MSS, Emax := Kmax MSS, Emin := Emin MSS, Calib := Emax MSS / Imax MSS;
                        ---- SOLENOID
42 MBAS2 : SOLENOID, L := 1.MBAS2:
443 MBCS2 : SOLENOID, L := 1.MBCS2;
                         --- VCGBBECTOR
46 MCRCV - VCCGRECTOR, L -- 1.MCRCV. Esaw -- Esaw MCRCV. Esin -- Esin MCRCV. Calib -- Esaw MCRCV / Inaw MCRCV
   MCSV : VCGSBCCCS, L := 1.MCSV. Knaw := Emax MCSV. Emin := Emin MCSV. Calib := Emax MCSV / Tmax MCSV
MCBWV: VCORRECTOR, L:= 1.NCBWV, Emax:= Emax MCBWV, Emin:= Emin MCBWV, Calib:= Emax MCBWV / Imax MCBWV
   MCRXY : VCORRECTOR, L := 1.MCRXY, Emax := Emax MCRXY, Emin := Emin MCRXY, Calib := Emax MCRXY / Imax MCRXY
   HOBYY : VOORRECTOR, L := 1.HOBYY, EMAX := EMAX MOSTY, EMIN := EMIN MOSTY, Calib := EMAX MOSTY / IMAX MOSTY
   MBAN : VKICKER, L := 1.MBAW, Emax := Kmax MBAN, Emin := Kmin MBAN, Calib := Kmax MBAN / Imax MBAN:
   MERCHO ! VEICKER, L := 1.MENOND. Kmax := Kmax MERCHD. Kmin := Kmin MERCHD. Calib := Kmax MERCHD / Imax MERCHD.
   HENT : VEICKER, L := 1.MENT. Kmax := Kmax MENNT. Kmin := Kmin MENNT. Calib := Kmax MENNT / Imax MENNT!
(5) LHCB1 | SEQUENCE, refer - CENTRE, L = LHCLENGTH
   TP1:ONK.
     MBAR2 - 191 - MBAR2
                               at= 1.5+(0-IP1OFS.B1)*DS, mech sep= 0, slot id= 2209454
      TAG. 181 - TAG.
                               at= 20.015+(0-IP10FS.B1)*DS, mech sep= 0, slot_id= 102103,
                               at= 21.475+(0-IP10FS.B1)*DS, mech_mep= 0, slot_id= 104594,
      BOWEN, 191 B) - BOWEN
                               at= 26.15+(0-IP10FS.B1)*DS, mech sep= 0, slot id= 282126, assembly id= 102104
                               at= 29.842+(0-IP1OFS.B1)*DS, mech sep= 0, slot id= 282213, assembly id= 102104,
                               at= 29.842+(0-IPIOFS.B1)*DS, mech_sep= 0, slot_id= 282212, assembly_id= 102104,
                               at= 31.529+(0-IP10FS.B1)*DS, mech sep= 0, slot id= 241889, assembly id= 102105.
                               at 34.8+(0-IPIOFS.B11*DS, mech sep- 0, slot id- 241890, assembly id- 102105,
                               at= 38.019+(0-IP10FS.S1)*DS, mech_sep= 0, slot_id= 249450, assembly_id= 102105
                               at- 38.019*(0-IP1OFS.B1)*DS, mech_sep- 0, slot_id- 249451, assembly_id- 102105,
                               at= 41.3+/0-TP10FS.R1+DS. mech seps 0. slot id= 241892, assembly id= 102105.
                               at- 45.342+(0-IP10FS.B1)*DS, mech sep- 0, slot_id- 241893, assembly_id- 102106
                               at= 46.608+(0-IP10FS.B1)*DS, mech_sep= 0, slot_id= 282127, assembly id= 102106,
                               at= 50.15+(0-IF10FS.B1)*DS, mech_sep= 0, slot_id= 241895, assembly_id= 102106,
                               at= 53.814+(0-IP10FS.B1)*DS, mech mep= 0, mlot id= 249456, assembly id= 102106,
                               at= 53.814+(0-IP10FS.B1)*DS, mech sep= 0, slot id= 249457, assembly id= 102106,
```



Standing on the shoulders of honestly pretty normal people

- Version one was part of a 2013 Bachelor's Thesis by *Tomas Komarek* at Palacky University in Olomouc.
- Version two was created by Vitaly
 Shinkarenko in 2020 at Charles University in Prague.
- Last year a CERN summer student Andrej
 Sarnatskiy made great progress and created v2.2.1.





Physics aims

- EasyTracker will be useful to find optimal locations for detectors to achieve their best acceptances/performances.
- ATLAS forward proton (AFP) uses Roman Pot detectors to identify particles very close to the beam that have only been slightly deflected, they are currently on the hunt for instantons.



Roman Pots



Wrong Roman

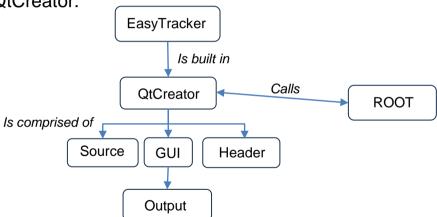




How has it been built?

Written in the C++ language and build within

QtCreator.







My contributions (so far)

1. Introduced Beam Crossing in x and y axis.



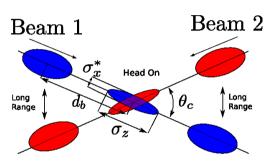


Figure (left): Window for editing element parameters.

The angle must not be dependent on the energy, as it is for the kicker.





My contributions (so far)

2. ROOT Macros for data handling

- Takes output .csv data file from EasyTracker and converts it into a ROOT file.
- Creates appropriate interactive ROOT histograms and graphs.
- Saves them all as PDFs for easy viewing and use.

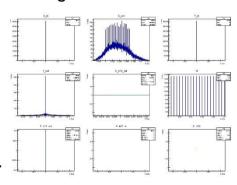


Figure: The output ROOT interface displaying required histograms.



My contributions (so far)

3. Ongoing attempts to integrate macros with Qt and debugging.

With the help of Serguei Kolos.







Future improvements

- Integrate existing ROOT macros into QtCreator.
- Automatically rebin the data properly so it looks presentable and is a more accurate depiction statistical of trends.
- Remove the auto-redraw problem and other bugs affecting EasyTracker.
- Finalise the beam going in the reverse direction.





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Questions?







Acknowledgements

- My patient and hardworking supervisors Tomas Sykora and Andrea Dell'Acqua.
- Serguei Kolos for support with ROOT/Qt integration.
- Tomas Komarek, Vitaly Shinkarenko and Andrej Sarnatskiy.
- CERN Summer Student organisers for making this possible.
- The CERN & Society foundation for funding my place here at CERN.
- My family and friends both back in the UK and here at CERN, including my Mum & Dad, Molly, Lauryn, Willow and dozens of others.



