

Study on the bias analysis and correction in MPGD μ TPC mode

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1. μ TPC mode in MPGD

- Measuring **Time** in each strip
- For track with **large incident angle**
- Good spatial resolution** ($\sim 50 \mu\text{m}$)

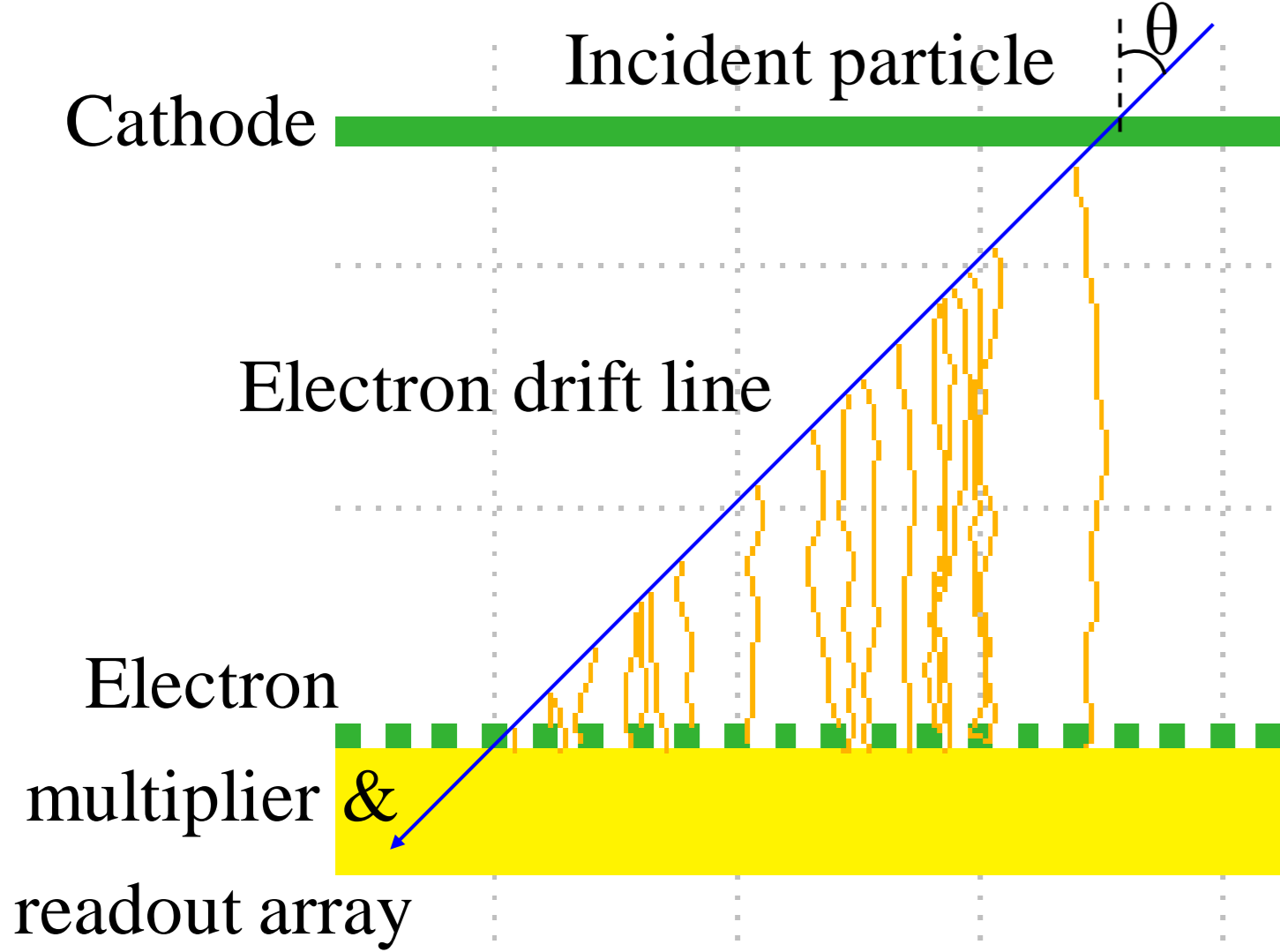


Fig. 1 Typical μ TPC mode in MPGD.

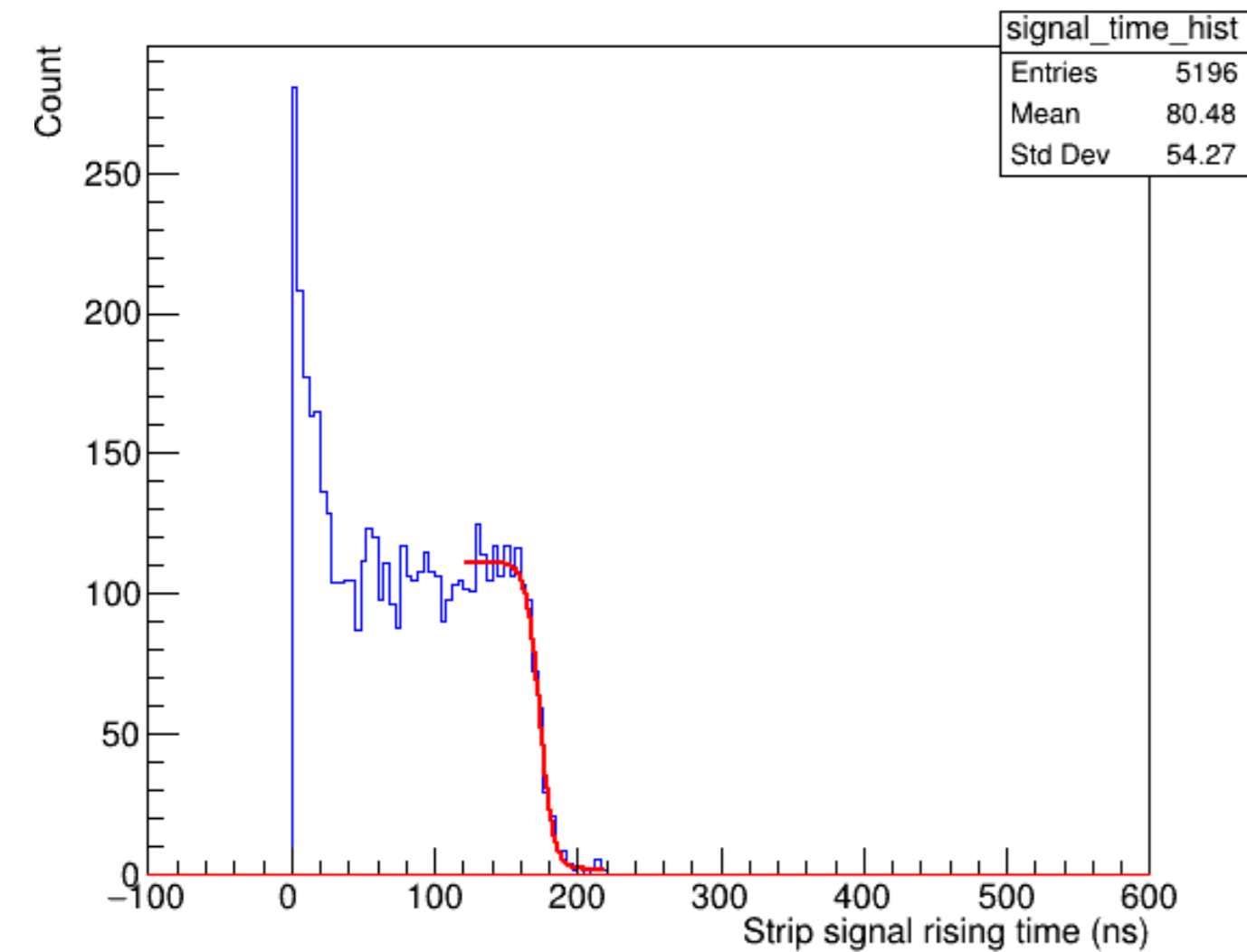


Fig. 2 Typical strip time distribution in μ TPC.

2. Spatial measurement bias in μ TPC mode

- Strip signal consists of **more than 1** primary electrons
- Signal of **1st electron** determines strip time, having a in-advanced **time bias**
- The reconstructed track is "lower" than real track, introducing **spatial bias**

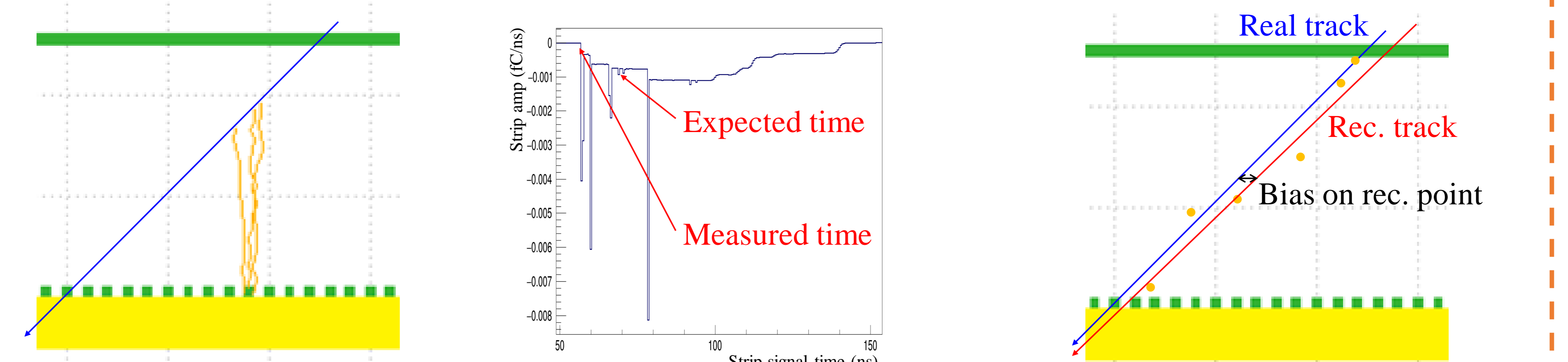


Fig. 3 Schematic of generation principle of spatial bias in μ TPC mode.

3. Parameters influence the bias

- Track incident angle
- Drift length
- Gas property (electron drift velocity, diffusion coefficient)
- Magnetic field
- Strip width and pitch
- Timing resolution of electronic system

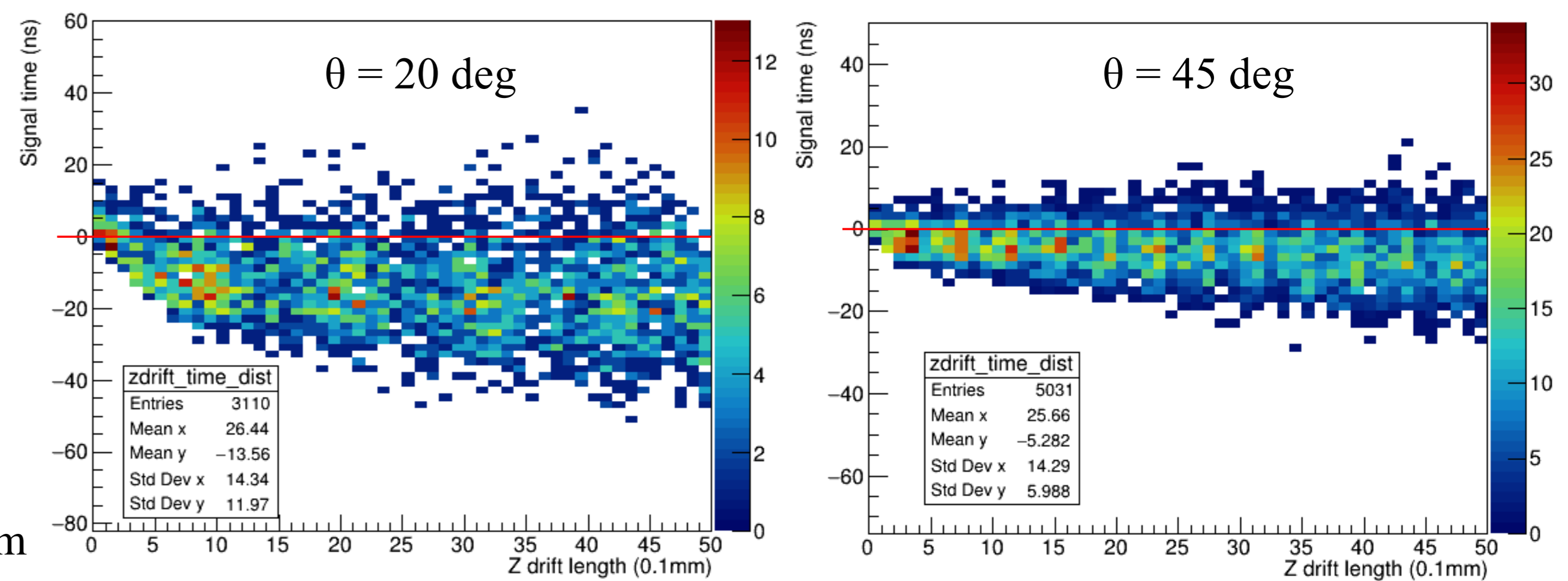


Fig. 4 Relationship between time bias and drift length, with different incident angle.

4. New algorithm to correct the bias

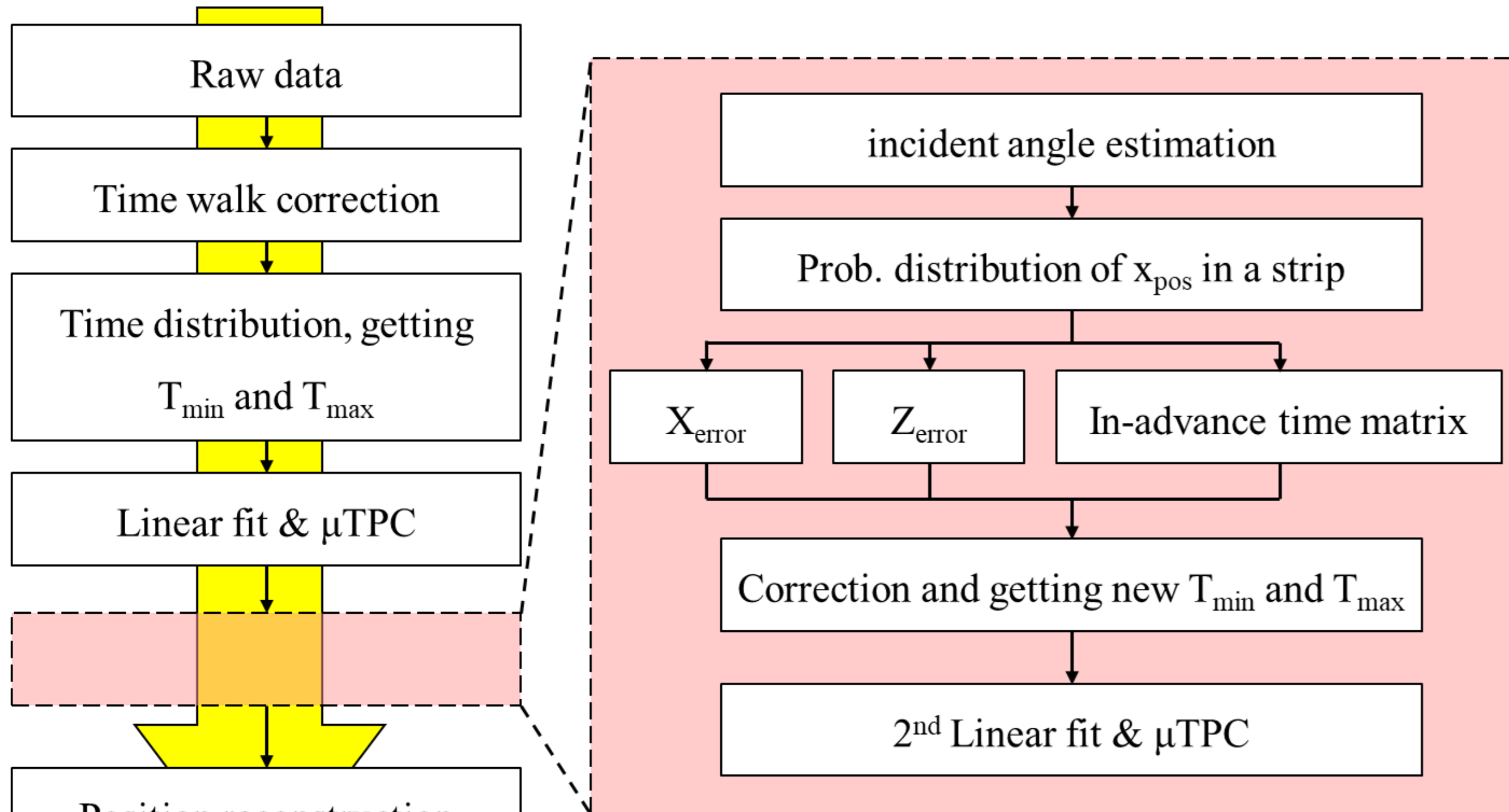


Fig. 6 New algorithm to correct bias in traditional μ TPC mode.

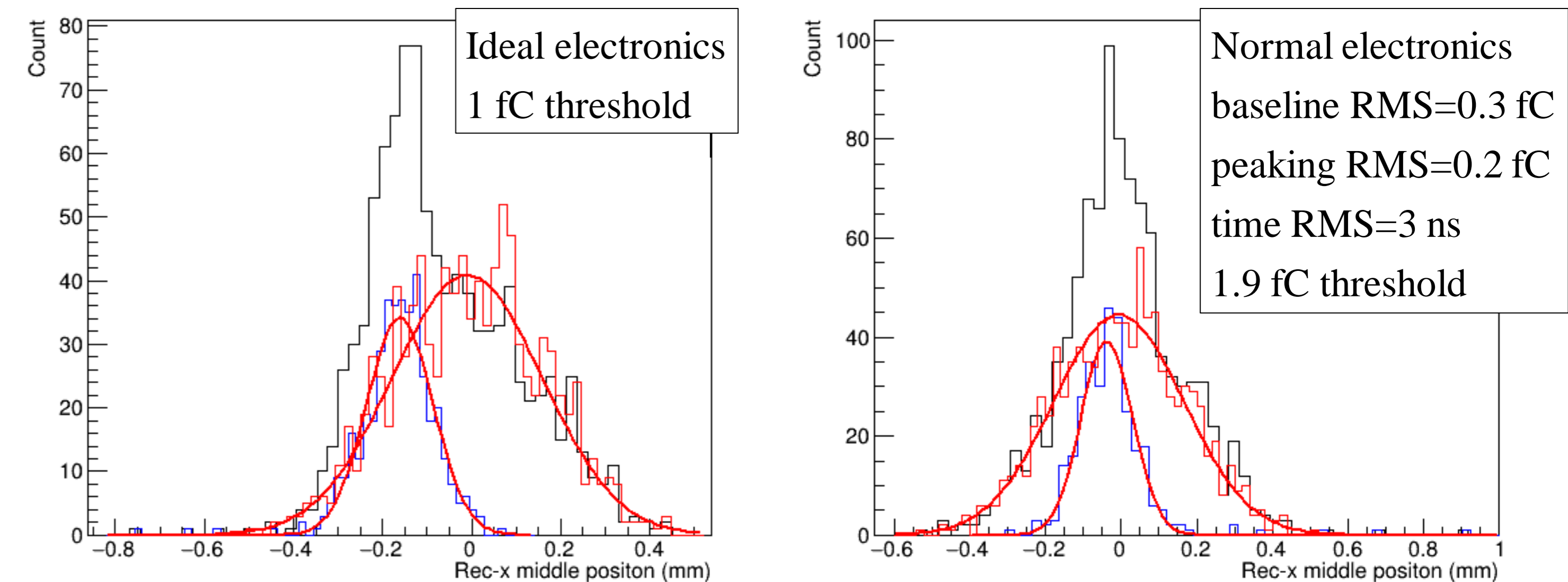


Fig. 5 Spatial resolution between μ TPC (blue hist.) and charge-centroid (red hist.) with 10 deg incident angle and different electronics setting.

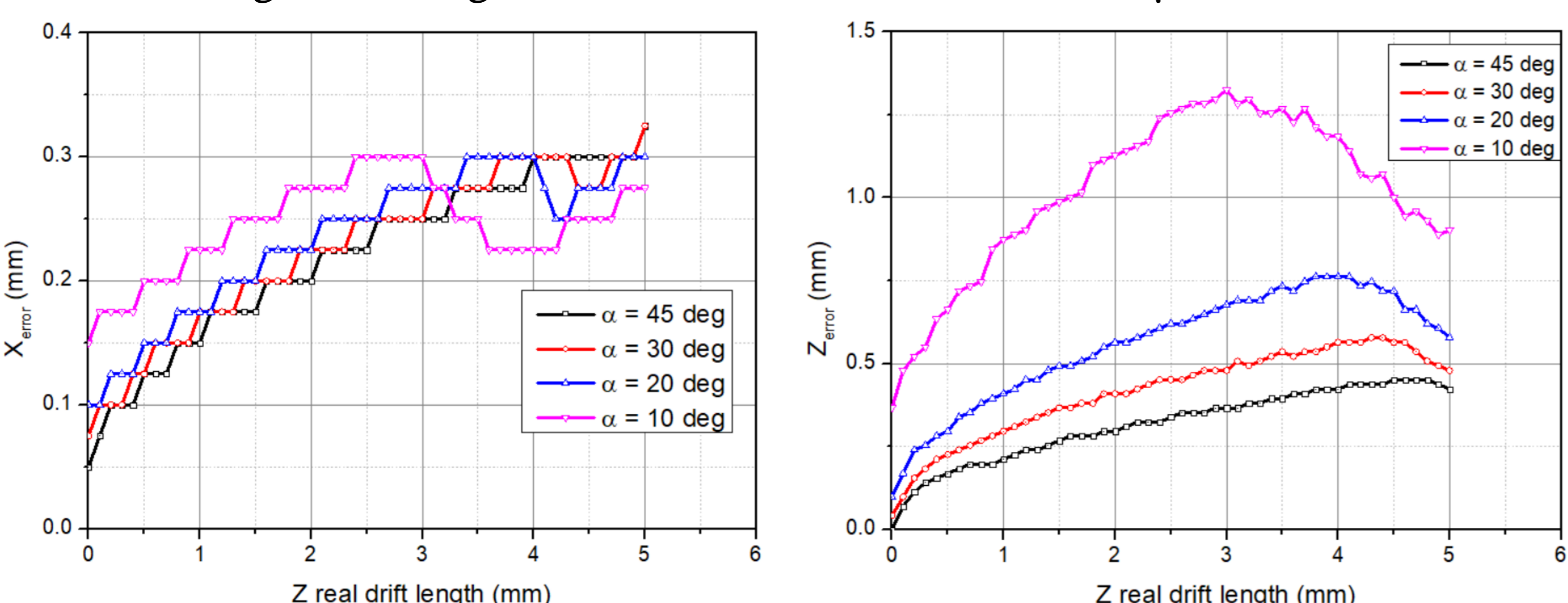


Fig. 7 X_{error} and Z_{error} distribution with various incident angle.

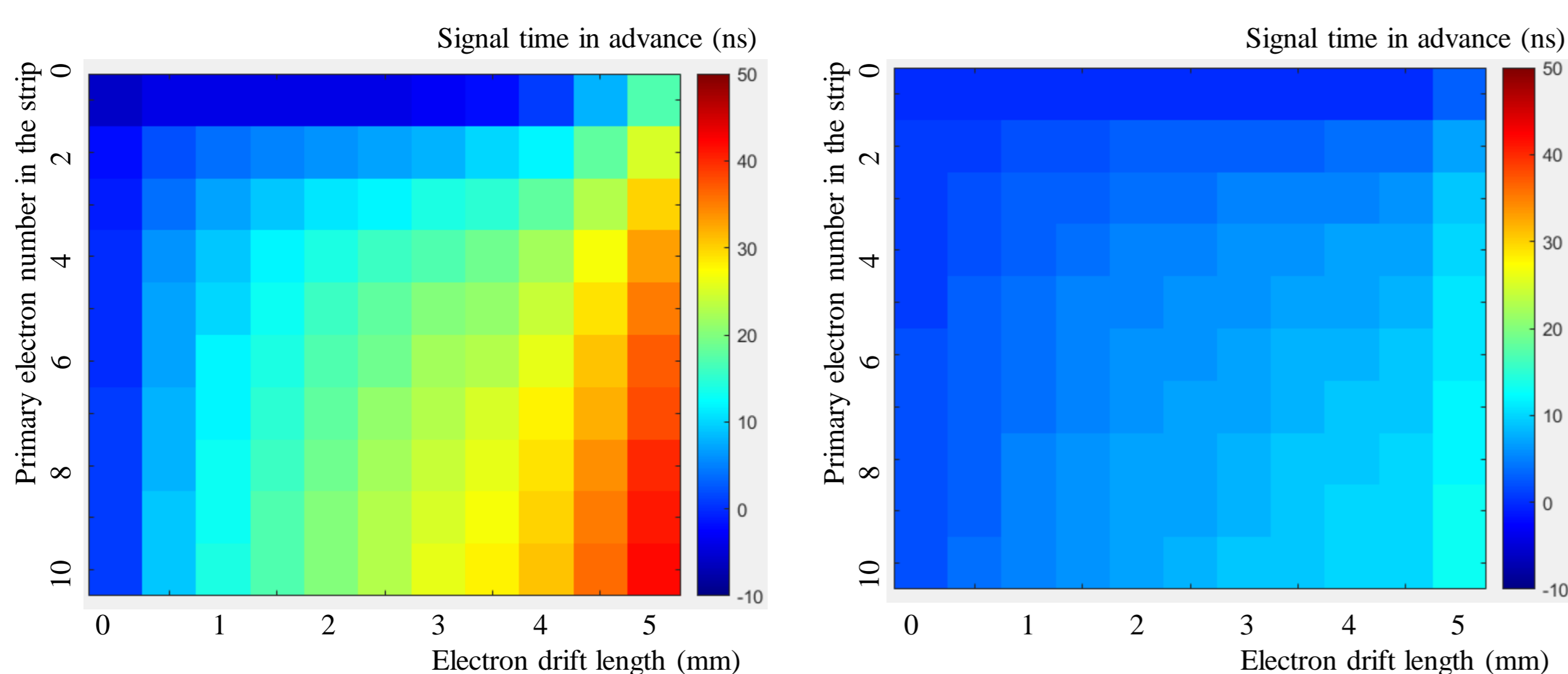


Fig. 8 Time advance matrix. Left: 10 deg angle. Right: 45 deg angle.

(Planar detector) Drift time correction based on electron diffusion analysis:

- Decrease spatial bias by 40%-75%
- Slightly improve spatial resolution

(Cylindrical detector, with magnetic field): Strip position correction based on empirical formula:

$$ID = ID_0 \pm \left(\frac{1}{2} - \frac{1}{N+1} \right) \cdot f_w(\theta)$$

- N is the primary electron number
- $f_w(\theta)$ is the weighting field-related parameter
- Decrease spatial bias significantly, with 1.4 GeV/c muon

5. Discussion and conclusion

- Theoretically, the μ TPC mode has bias in spatial reconstruction, which is easily covered by the assembly error in planar detectors. In cylindrical detector, it is not negligible.
- New algorithms are developed to correct the bias, and should be optimized to cover all track incident angle range and cases.

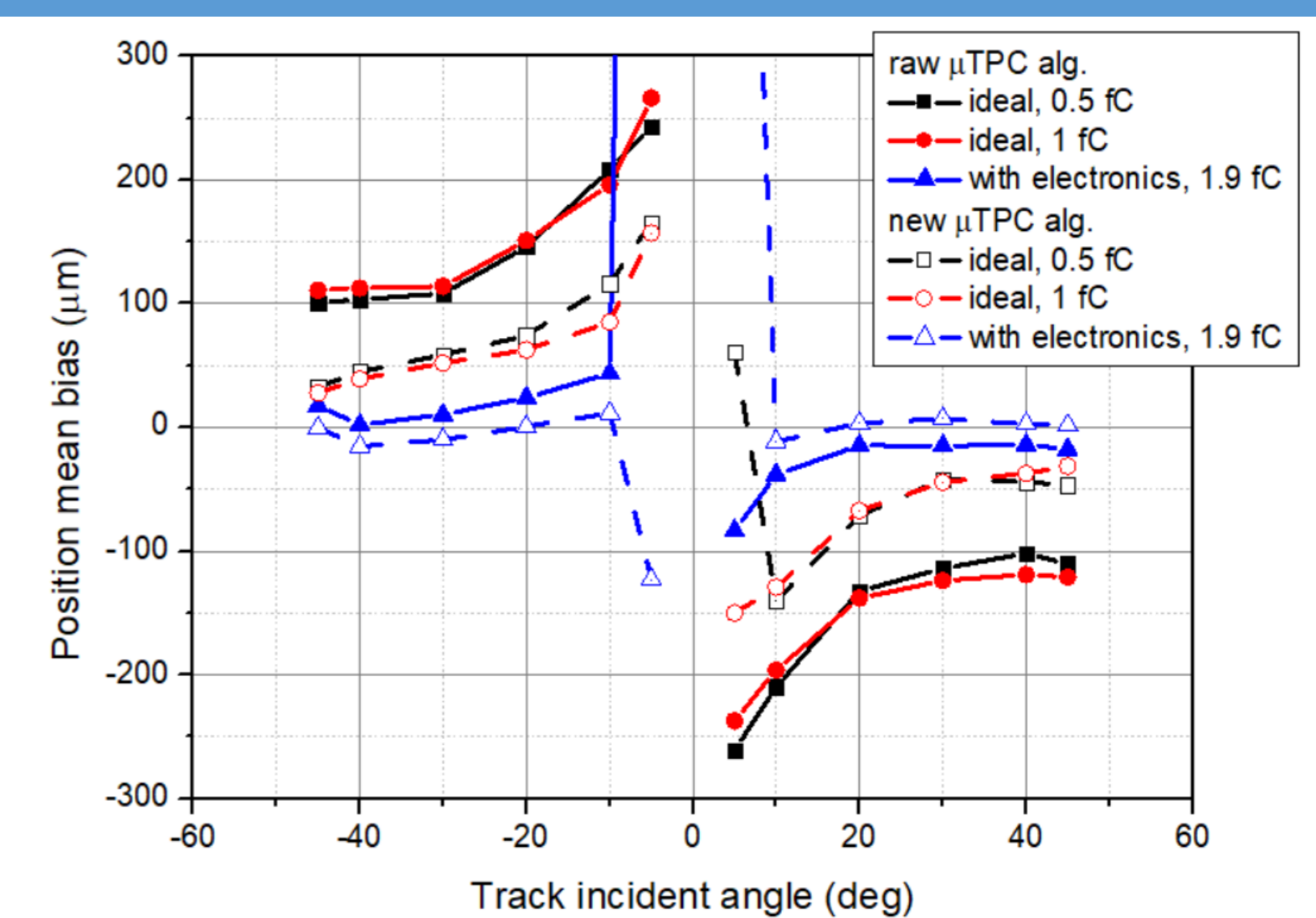


Fig. 9 Simulated bias correction performance.

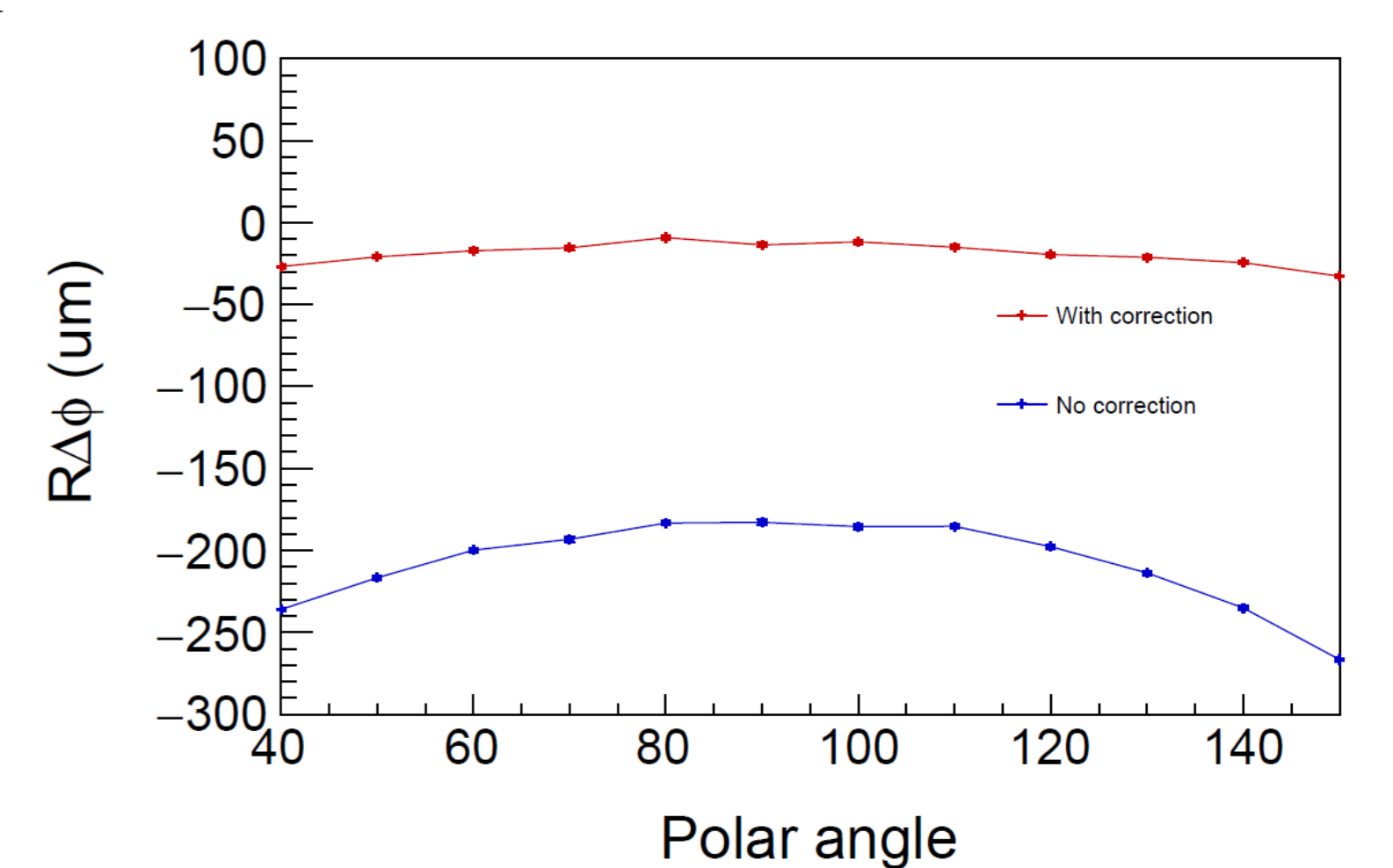


Fig. 10 Simulated bias correction performance.