Uncertainty Quantification with Discrepant Data Sets

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with

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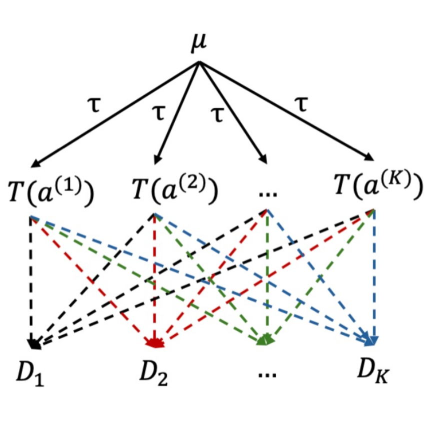
[arxiv: 2406.01664](https://arxiv.org/abs/2406.01664)

@CTEQ Meeting 2024 – Christopher Newport Universsity



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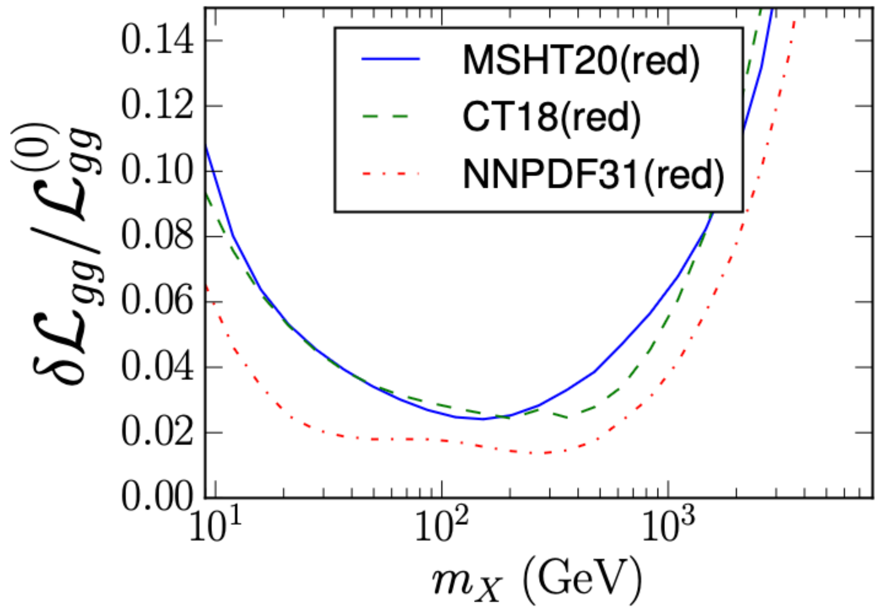
Differing methodologies lead to different uncertainties among different groups



Opportunity to go back to the drawing board and test our methodologies.

PDFLHC21, arXiv:2203.05506

Motivation

- Precision measurements need precise PDFs
- PDF fitting groups have to contend with tension in data
  - Many strategies to deal with this: For example, the use of tolerance ($\Delta\chi^2 = T^2$)
- PDF fitting groups also have to contend with epistemic uncertainties arising from model choice.
- This talk will describe an implementation of Bayesian Model Averaging (BMA) using the Gaussian Mixture Model (GMM).

Outline

- Simple 1-D toy example with W-boson mass
  - PDG scale factors
  - Bayesian Model Averaging and Information Criteria
- Demonstrate idea with a toy model of PDFs
- Summary

Simple 1-D toy example

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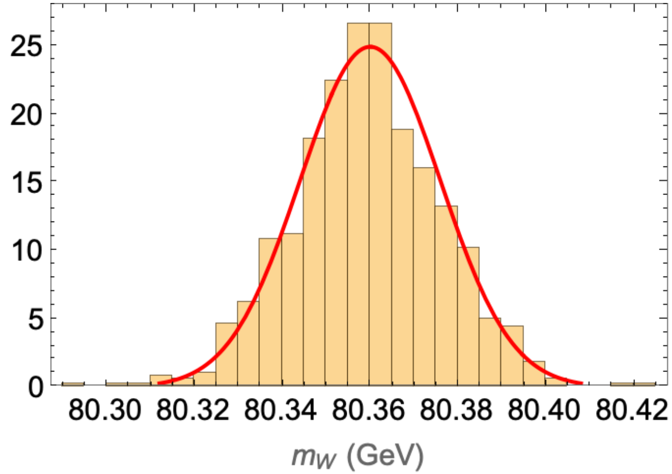
Measuring Mass (Weight) PHY-101 Lab

- Measure mass of W-boson
- Repeat measurement several times
- Minimize log-likelihood or loss function
  - $\chi^2 = \sum_i \frac{(\mu - x_i)^2}{\sigma_i^2}$
  - $L = \prod_i \frac{e^{\left[\frac{(\mu - x_i)^2}{\sigma_i^2}\right]}}{\sqrt{2\pi}\sigma_i}$
- Determine best-fit value
  - $m_W = \mu = 80.36 \pm 0.016\ GeV$

ATLAS-CONF-2023-004

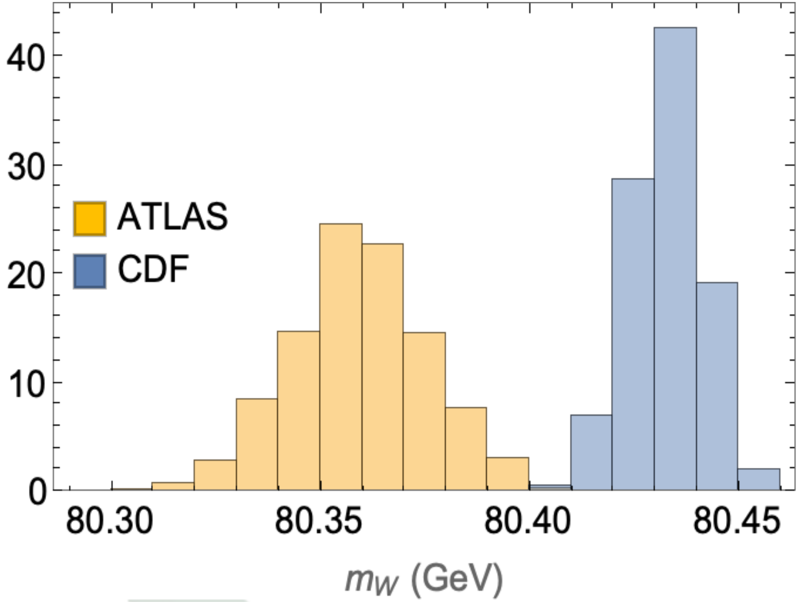


Manufactured by ATLAS

Measuring Mass (Weight) PHY-101 Lab

Repeat measurements with another balance

[CDF *Science 376* (2022)]



Manufactured by CDF

$$m_W^{CDF} = 80.433 \pm 0.009\ GeV$$
$$m_W^{ATLAS} = 80.36 \pm 0.016\ GeV$$

Manufactured by ATLAS

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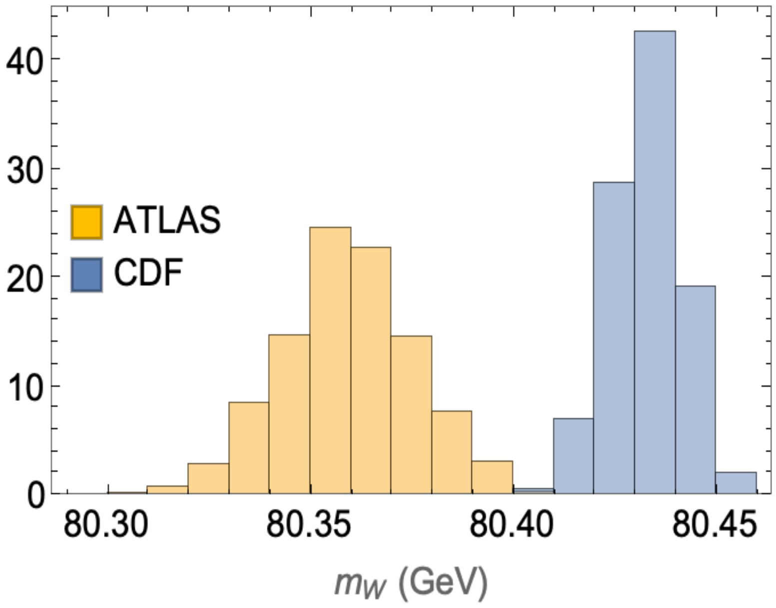
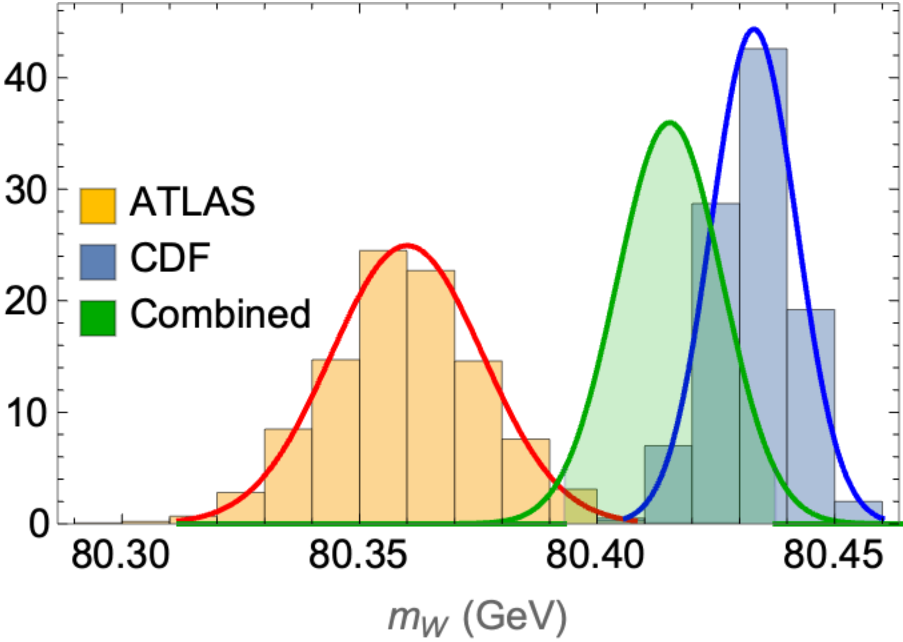
What should we do in this situation?

- **Ideal:** Understand why each experiment predicts a different value of mass
  - E.g. Maybe we didn't calibrate our balance properly?
  - Also make measurements with balances manufactured by different companies.
- **Less than ideal:** Combine the results in a statistically meaningful way that captures our lack of knowledge about the discrepancy – unknown systematics



Measuring Mass (Weight) PHY-101 Lab

- How should we combine these two discrepant measurements to give one value of mass?
- **Attempt #1**: Let's repeat earlier exercise
  - Minimize loss function
    - $\chi^2 = \sum_i \frac{(\mu - x_i)^2}{\sigma_i^2}$
    - $m_W = 80.415 \pm 0.011\ GeV$



- 2σ band does not cover both means
  - How should we interpret this?
- One familiar proposal
  - Increase tolerance $\Delta\chi^2 = T^2; T > 1$
  - Does not provide a faithful representation of the probability distribution of m_W, drawn from our sample of experiments and results in poor goodness of fit

PDG proposal – rescale uncertainties by a factor

- If the reduced $\chi^2 < 1$, the results are accepted and there is **no scaling**.
- If the reduced $\chi^2 > 1$, and the experiments are of comparable precision, then all errors are re-scaled by a common factor S, given by the $S_{PDG} = \sqrt{\frac{\chi^2}{N-1}}$
- If some of the individual errors are much smaller than others, then S_{PDG} is computed from only the most precise experiments. The criterium for these is given with reference to an ad hoc cutoff value.
- This tends to set the $\chi^2 \to 1$

W boson mass combination

Experiment	W-boson mass	Uncertainty
DO-I [1]	80.483	0.084
CDF-I [2]	80.433	0.079
LEP [3]	80.376	0.033
DO-II [4]	80.375	0.023
LHCB [5]	80.354	0.032
CDF-II [6]	80.4335	0.0094
ATLAS23 [7]	80.36	0.016

$$\overline{m}_W|_{\chi^2} = 80.4065 \pm 0.0072$$

$$\chi^2/\mathrm{d.o.f} \simeq 3.3.$$

Scale CDF uncertainty from 9.4 MeV to 35~40 MeV gives $\frac{\chi^2}{d.o.f} \sim 1$

$$m_W \sim 80.384 \pm 0.01\ GeV$$

Using goodness of fit to simultaneously evaluate the fit as well as to test model consistency.

BMA can be used to define an alternate measure of consistency

Bayesian Model Averaging
- Formalism

"All models are wrong, some are useful"- George Box

Review of Bayesian Formalism for χ^2

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Data $$D_i = \langle D_i \rangle + \sigma_i \Delta_i \ .$$

$$\langle f \rangle = (2\pi)^{N_D/2} \int f(\Delta) \prod_{i=1}^{N_D} d\Delta_i \exp\left(-\frac{1}{2}\Delta_i^2\right)$$

$$\langle g \rangle = \frac{1}{\sqrt{(2\pi)^{N_D} \det C}} \int g(D) \prod_{i,j=1}^{N_D} dD_i \exp\left(-\frac{1}{2}(D_i - \langle D_i \rangle)(D_j - \langle D_j \rangle)C_{ij}^{-1}\right)$$

$$P(D|T(a)) = \frac{1}{\sqrt{(2\pi)^{N_D} \det C}} dD \exp\left(-\frac{1}{2}\sum_{i,j=1}^{N_D}(D_i - T_i(a))(D_j - T_j(a))C_{ij}^{-1}\right)$$

$$P(T(a)|D) = \frac{P(D|T(a))P(T(a))}{P(D)}$$

See Kovarık, Nadolsky & Soper arXiv:1905.06957

Bayesian Model Averaging

Data from K different experiments $D_i^{(k)} = \langle D_i^{(k)} \rangle + \sigma_i^{(k)} \Delta_i^{(k)} = T_i(a^{(k)}) + \sigma_i^{(k)} \Delta_i^{(k)}$

$$P(T(a^{(k)})) = \int d\mu d\tau P(T(a^{(k)})|\mu,\tau)p(\mu,\tau) \equiv w_k \qquad \textstyle\sum_{k=1}^{K} w_k = 1.$$

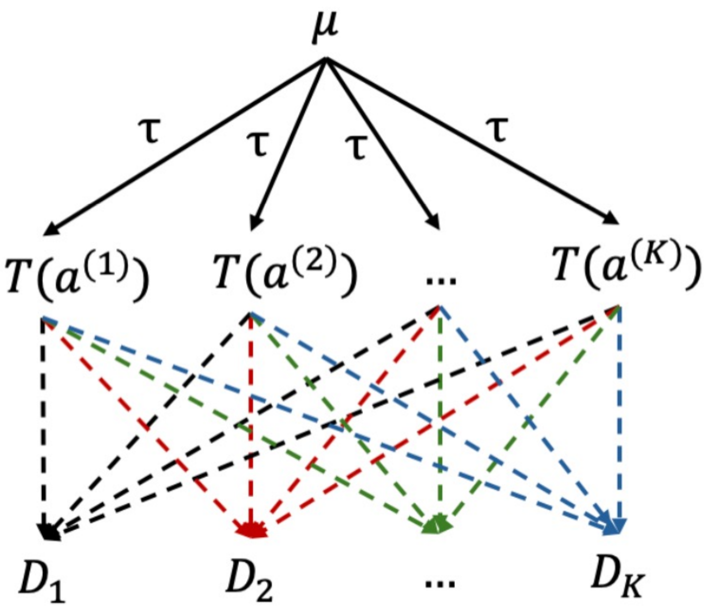
Bayes' Theorem

$$P(D_i|T(a^{(k)}))P(T(a^{(k)})) = w_k P(D_i|T(a^{(k)})) = P(T(a^{(k)})|D_i)P(D_i)$$

$$\prod_{i=1}^{N_D}\left(\sum_{k=1}^{K} P(T(a^{(k)})|D_i)\right) \propto \prod_{i=1}^{N_D}\left(\sum_{k=1}^{K} w_k \mathcal{N}(D_i|T(a^{(k)}),\sigma_i)\right)$$

Likelihood is a mixture model

Bayesian Model Averaging (BMA)



$$\prod_{i=1}^{N_D}\left(\sum_{k=1}^{K} P(T(a^{(k)})|D_i)\right) \propto \prod_{i=1}^{N_D}\left(\sum_{k=1}^{K} w_k \mathcal{N}(D_i|T(a^{(k)}), \sigma_i)\right)$$

Information Criteria

- Given multiple models to explain data we would like to determine which model best fits data
    - This is accomplished by the likelihood
- Many models can have good likelihood, how do we select a model out of many such models?
    - Parsimony/ Occam's razor – the simplest models are the ones you want
- How do we determine this balance between parsimony and goodness of fit?
    - Use information Criteria
- Many information criteria exist – the most popular being the Akaike Information Criteria (AIC) and Bayesian Information Criteria (BIC) and their variants

Akaike Information Criteria

- Test how similar two probability distributions are: $P(D|T)$ and $P(D)$.
- Several metrics for measuring the difference between probability distributions, Kullback–Leibler divergence is one of them
- $D_{KL}(P(D|T)||P(D)) = \int dD\ P(D) \log \frac{P(D|T)}{P(D)}$
- This can be determined asymptotically and leads to the AIC
- $AIC\ =\ -2\log(P(D|T)) +\ 2\ N_{parm}$

- The smallest value of AIC is a measure of the balance between goodness of fit and model complexity

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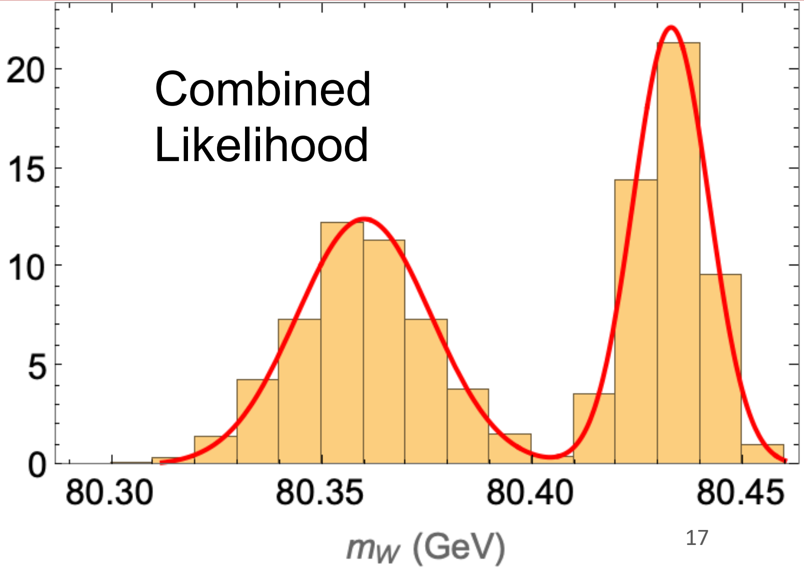
Gaussian Mixture Model for BMA

$$\mathcal{N} = \frac{e^{\left[\frac{(\mu-x_i)^2}{\sigma_i^2}\right]}}{\sqrt{2\pi}\sigma_i}$$

$$\pi(Y|\vec{\theta}) = \prod_{j=1}^{N_{\mathrm{pt}}} \pi(y_j, \Delta y_j|\vec{\theta}) = \prod_{j=1}^{N_{\mathrm{pt}}} \sum_{i=1}^{K} \omega_i \mathcal{N}(y_j, \Delta y_j|\theta_i),$$

$$0 \leq \omega_k \leq 1 \quad \text{and} \quad \sum_k \omega_k = 1,$$

- Start by parameterizing the likelihood as a sum of Gaussians
- In this simple example we know there are two Gaussians, i.e. K= 2
- In general, the value of K needs to be determined – discussed later
- Introduced a new parameter ω_k - weights
- Constraints on ω_k; ensures proper normalization and interpretation as a probability distribution function
- For simplicity we'll use equal weights here
- In reality – it is an additional fit parameter
- See Interpretation in Bayesian formalism later.



Determine mean and variance for GMM

$$\pi(Y|\vec{\theta}) = \prod_{j=1}^{N_{\rm pt}} \pi(y_j, \Delta y_j|\vec{\theta}) = \prod_{j=1}^{N_{\rm pt}} \sum_{i=1}^{K} \omega_i \mathcal{N}(y_j, \Delta y_j|\theta_i),$$

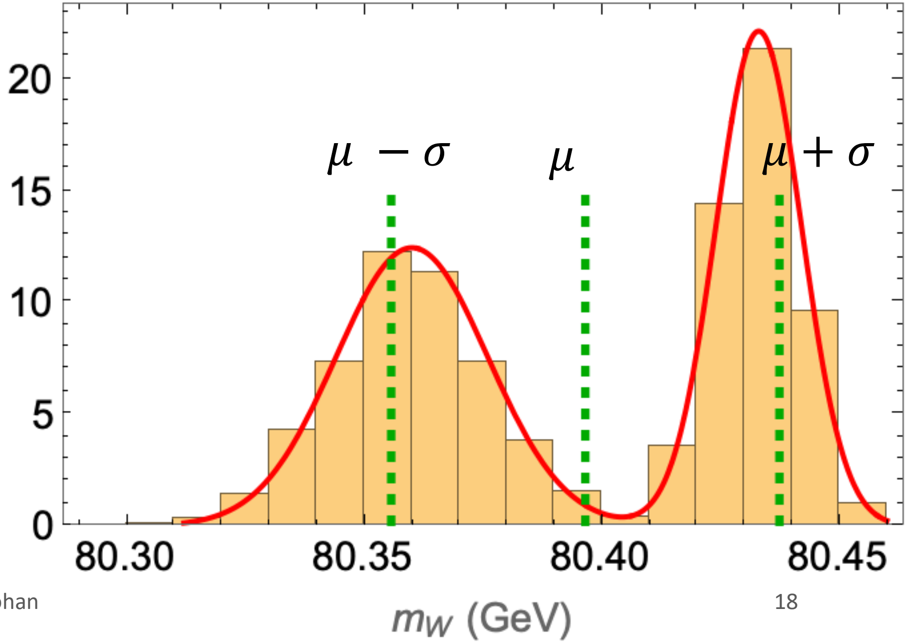
$$0 \leq \omega_k \leq 1 \quad \text{and} \quad \sum_k \omega_k = 1,$$

Mean $\mathbb{E}[\theta] = \sum_{i=1}^{K} \omega_i \hat{\theta}_i.$

$$\begin{aligned} \text{cov}_{\rm GMM} &= \sum_{i=1}^{K} \omega_i \ \text{cov}_{{\rm GMM},i} + \sum_{i=1}^{K} \omega_i (\mathbb{E}[\theta] - \hat{\theta}_i)^2 \\ &= \sum_{i=1}^{K} \omega_i \left(\sum_{j=1}^{N_{\rm pt}} \frac{1}{\Delta y_j^2} \left(\frac{\partial y_j(\theta_i)}{\partial \theta_i} \right)^2 \frac{\mathcal{N}(y_j, \Delta y_j|\theta_i)}{\pi(y_j, \Delta y_j|\vec{\theta})} \right)^{-1} + \sum_{i=1}^{K} \omega_i (\mathbb{E}[\theta] - \hat{\theta}_i)^2. \end{aligned}$$

Weighted sum of covariances of each Gaussian

Difference between Gaussians



Here we use the variance as an estimator for the standard error.
Alternatively, we could use the Observed Fisher Information Matrix

Determine mean and variance for GMM

$$\pi(Y|\vec{\theta}) = \prod_{j=1}^{N_{\rm pt}} \pi(y_j, \Delta y_j|\vec{\theta}) = \prod_{j=1}^{N_{\rm pt}} \sum_{i=1}^{K} \omega_i \mathcal{N}(y_j, \Delta y_j|\theta_i),$$

$$0 \leq \omega_k \leq 1 \quad \text{and} \quad \sum_k \omega_k = 1,$$

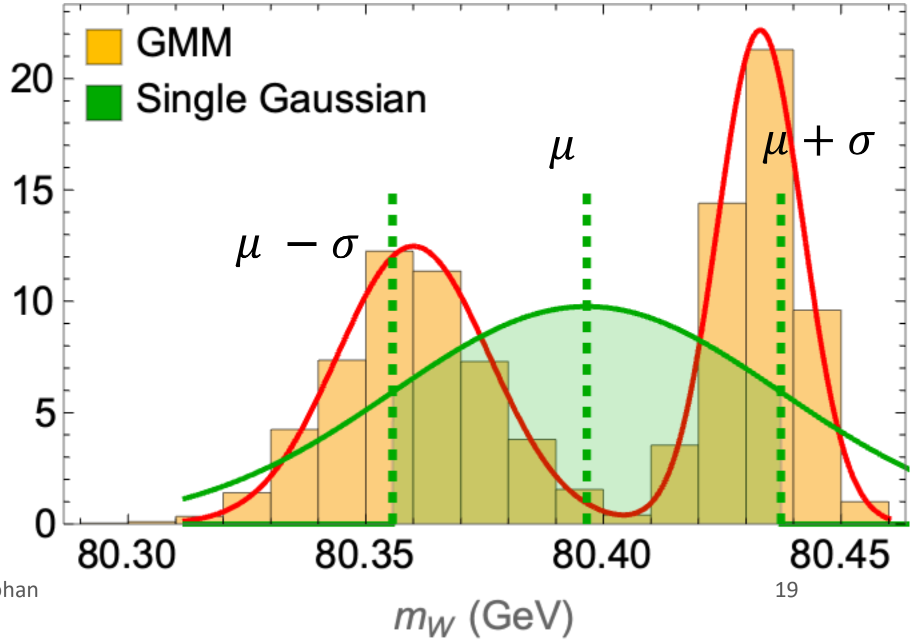
Mean $$\mathbb{E}[\theta] = \sum_{i=1}^{K} \omega_i \hat{\theta}_i.$$

$$\mathrm{cov}_{\rm GMM} = \sum_{i=1}^{K} \omega_i \, \mathrm{cov}_{{\rm GMM},i} + \sum_{i=1}^{K} \omega_i (\mathbb{E}[\theta] - \hat{\theta}_i)^2$$

$$= \sum_{i=1}^{K} \omega_i \left(\sum_{j=1}^{N_{\rm pt}} \frac{1}{\Delta y_j^2} \left(\frac{\partial y_j(\theta_i)}{\partial \theta_i} \right)^2 \frac{\mathcal{N}(y_j, \Delta y_j|\theta_i)}{\pi(y_j, \Delta y_j|\vec{\theta})} \right)^{-1} + \sum_{i=1}^{K} \omega_i (\mathbb{E}[\theta] - \hat{\theta}_i)^2.$$

Weighted sum of covariances of each Gaussian

Difference between Gaussians



Caveat about green curve: because we are used to it, it is possible to model this as a single Gaussian (green) – but we must be careful - it is **not** a faithful representation of the likelihood.

W boson mass combination

Experiment	W-boson mass	Uncertainty
DO-I [1]	80.483	0.084
CDF-I [2]	80.433	0.079
LEP [3]	80.376	0.033
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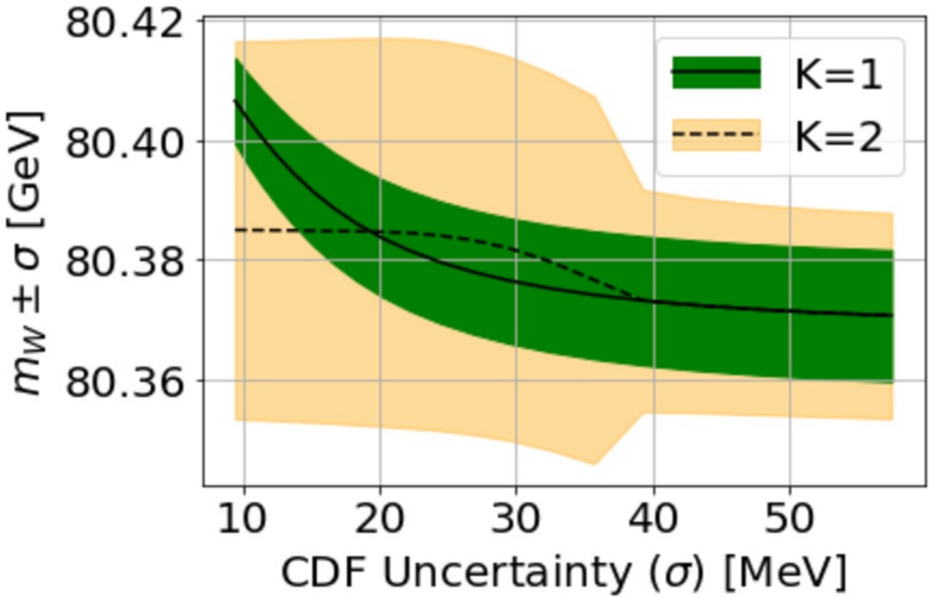
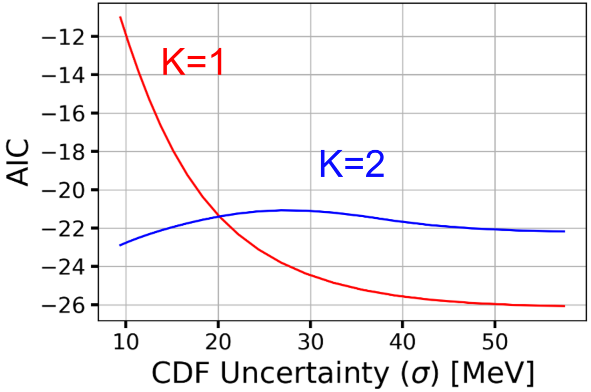




AIC: Setting CDF uncertainty to ~ 20 MeV makes data consistent, i.e. K=1 is favored.

Application of GMM and BMA to a toy model of PDFs

>1 parameter fits

A toy model of PDFs with inconsistent data

"truth" $$g(x) = a_0\, x^{a_1}(1-x)^{a_2} e^{x a_3}(1+x e^{a_4})^{a_5}$$

Parameters of model: $\{a_0, a_1, a_2, a_3, a_4, a_5\}$

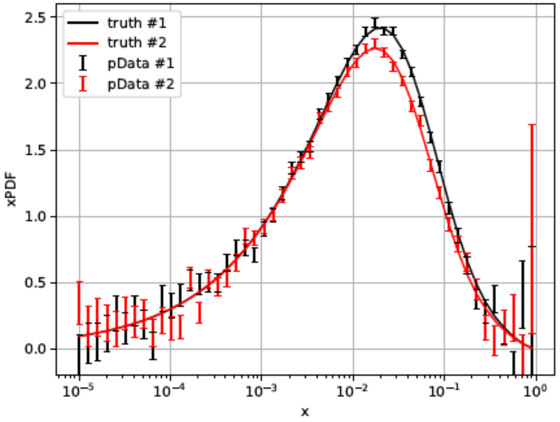
Pseudo-data generation

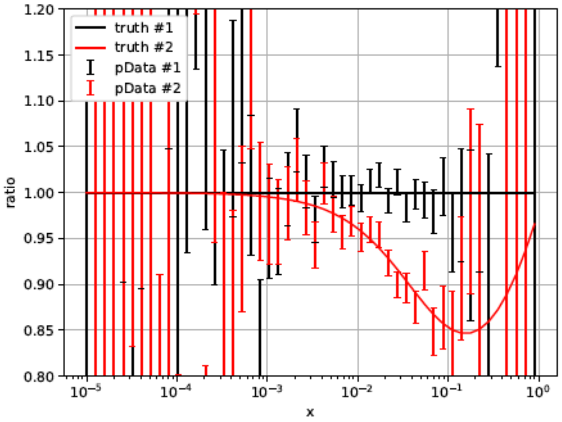
Central value $$g_D(x) = \Big(1 + r \times \Delta g(x)\Big) g(x)$$

Uncertainty $$\Delta g(x) = \frac{\alpha}{\sqrt{g(x)}}$$

	N_{pt}	a_0	a_1	a_2	a_3	a_4	a_5
pseudo-data #1	50	30	0.5	2.4	4.3	2.4	-3.0
pseudo-data #2	50	30	0.5	2.4	4.3	2.6	-2.8

Inconsistent Pseudo-data generated by starting with different values of a_4 & a_5

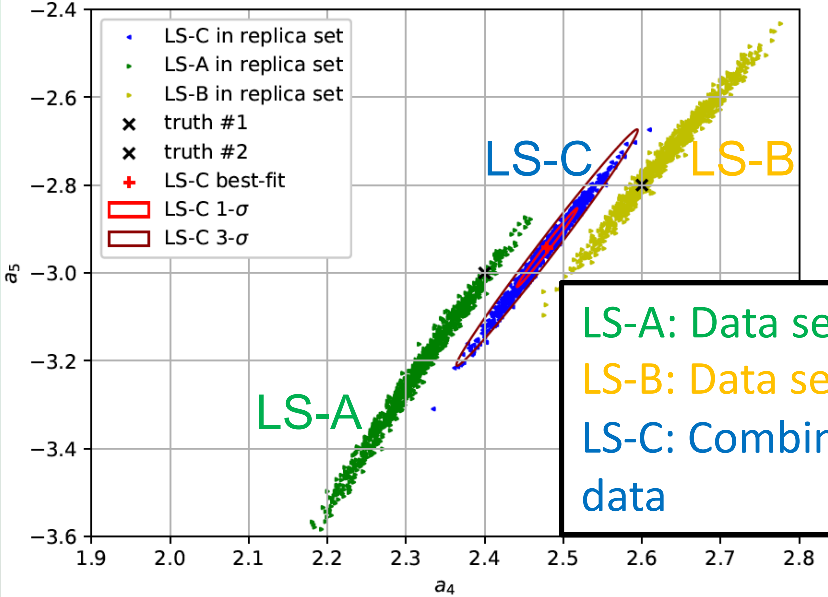




Fits to pseudo-data

$$\chi^2 = \sum_{j=1}^{N_{\mathrm{pt}}} \left(\frac{D_i - T_i(\theta)}{\Delta D_i} \right)^2$$

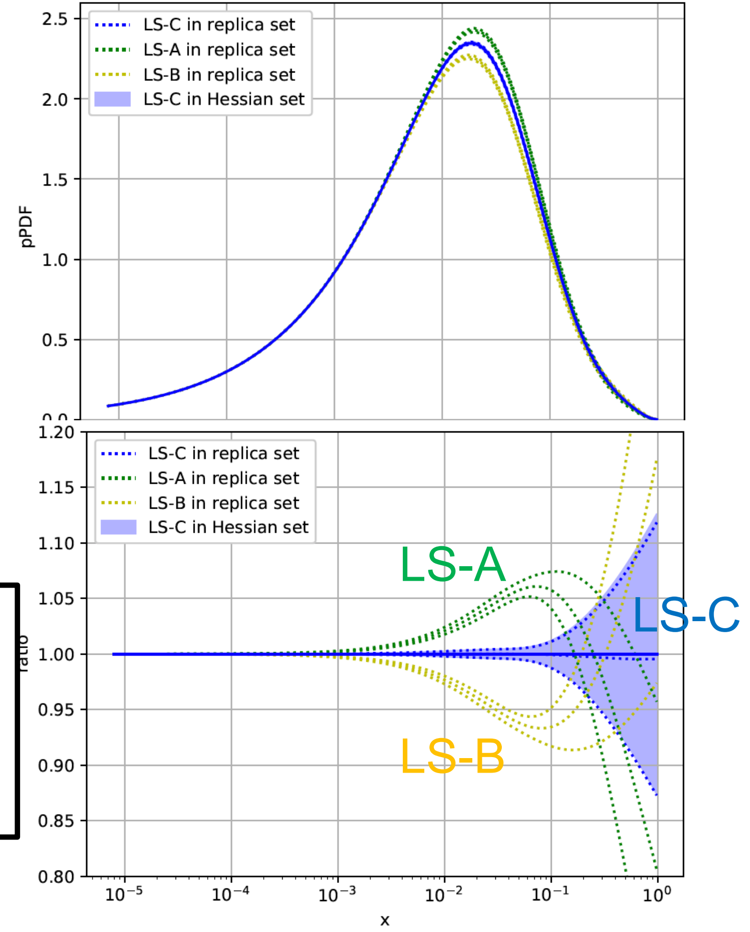
fits	pseudo-data	best-fit a_4	best-fit a_5	$\chi^2_{\#1}/N_{\mathrm{pt}}$	$\chi^2_{\#2}/N_{\mathrm{pt}}$
LS-A	# 1	2.32	-3.22	0.88	6.55
LS-B	# 2	2.63	-2.73	7.00	1.02
LS-C	# 1 and # 2	2.48	-2.94	2.27	2.56
truth	# 1	2.4	-3.0	-	-
truth	# 2	2.6	-2.8	-	-



LS-A: Data set 1 only

LS-B: Data set 2 only

LS-C: Combines all data

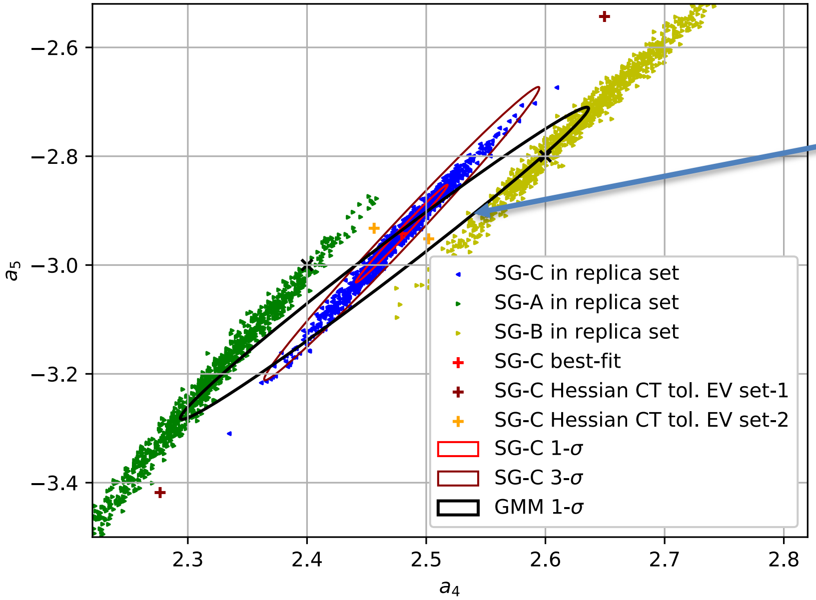


Fits to pseudo-data using the GMM

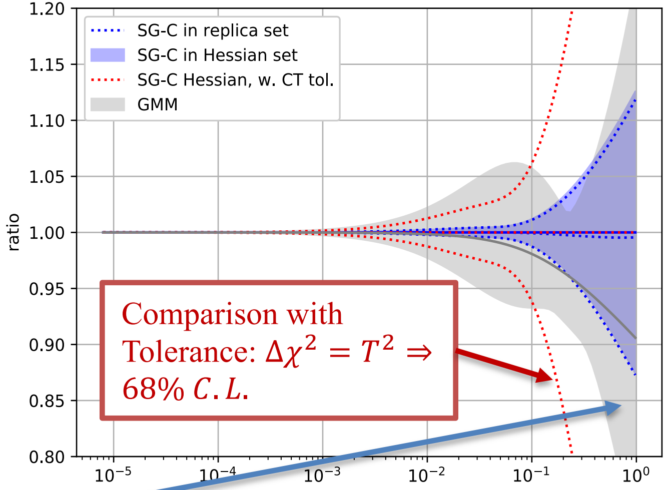
GMM uncertainty ellipse spans both replica sets. Unlike usual χ^2 method

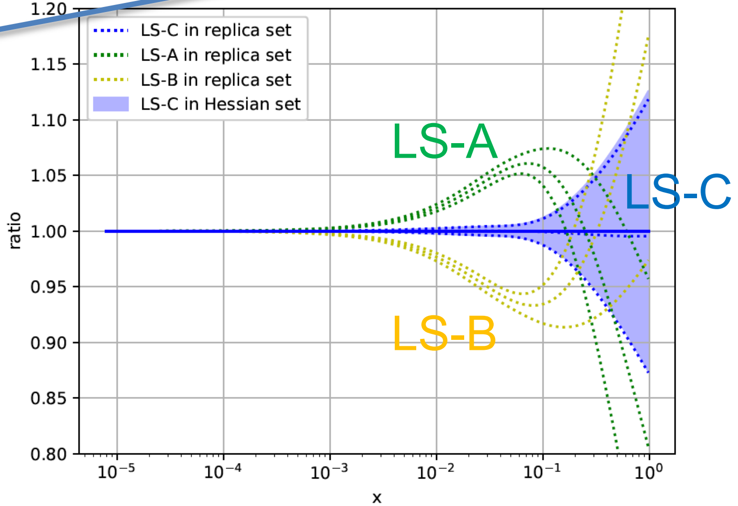
Axis of ellipse is different – covers uncertainties from individual data sets

Tolerance criteria both over and underestimates uncertainties in different regions

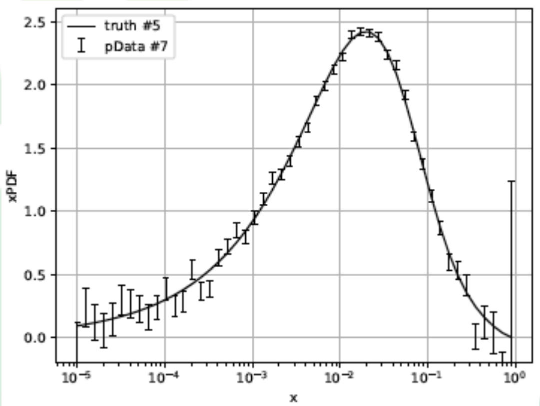


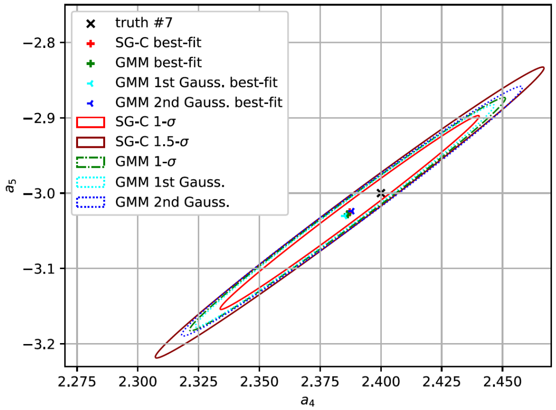
GMM
"1σ"

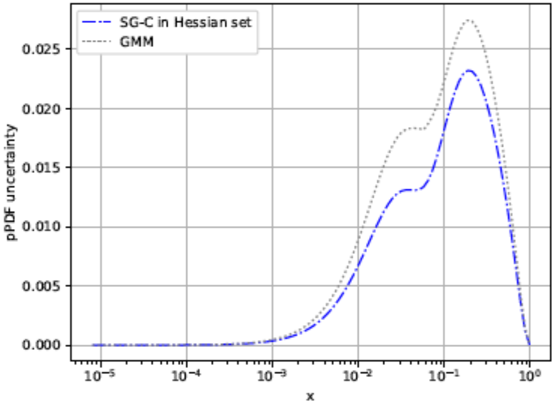


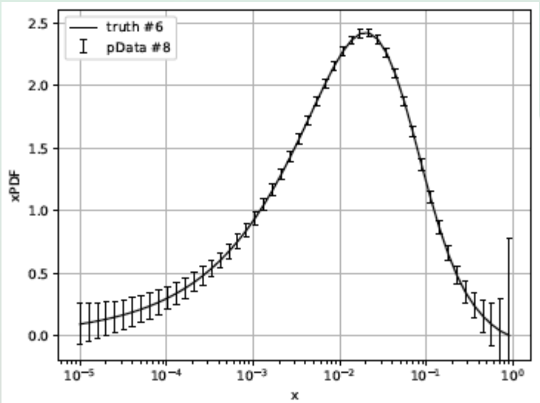


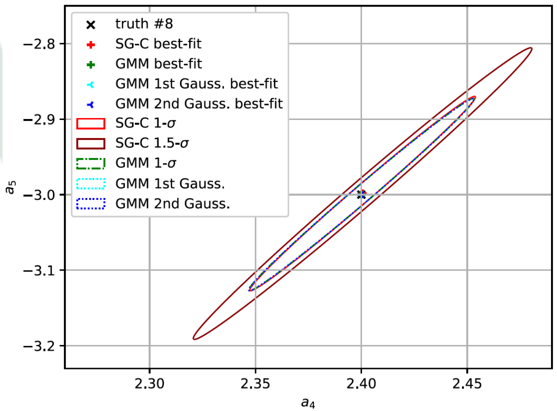
GMM reduces to the χ^2 likelihood (K= 1), when data is consistent

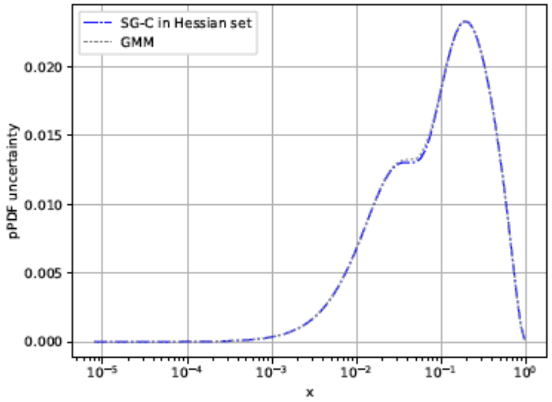












How many Gaussians? How do we determine K?

Akaike Information Criterion (AIC)
(Akaike, 1974)
Bayesian Information Criterion (BIC)
Schwarz (Ann Stat 1978, 6:461–464)

$$\mathrm{AIC} = N_{\mathrm{parm}} \log N_{\mathrm{pt}} - 2\log L\big|_{\theta=\hat{\theta}},$$
$$\mathrm{BIC} = 2N_{\mathrm{parm}} - 2\log L\big|_{\theta=\hat{\theta}}.$$

$$N_{\mathrm{parm}} = 2K + (K-1).$$

Use the lowest values of AIC & BIC to determine the best value of K and avoids over-fitting.

		$K=1$	$K=2$	$K=3$	$K=4$
case-1	AIC	-102.2	**-203.6**	-194.9	-187.9
	BIC	-106.1	**-211.2**	-206.4	-203.2
N_{pt}=100	$-\log L$	-55.0	**-109.6**	-109.2	**-109.6**
case-2	AIC	**-21.2**	-15.4	-7.9	-0.2
	BIC	**-25.0**	-23.0	-19.3	-15.5
N_{pt}=100	$-\log L$	-14.5	-15.5	**-15.7**	**-15.7**
case-3	AIC	-219.3	**-220.2**	-212.8	-205.0
	BIC	-223.2	**-227.8**	-224.3	-220.3
N_{pt}=100	$-\log L$	-113.6	**-117.9**	**-117.9**	-118.1
case-4	AIC	**-117.8**	-109.9	-102.1	-94.3
	BIC	**-121.6**	-117.6	-113.6	-109.6
N_{pt}=50	$-\log L$	**-62.8**	**-62.8**	**-62.8**	**-62.8**
case-5	AIC	**-169.3**	-161.5	-153.6	-145.8
	BIC	**-173.1**	-169.1	-165.1	-161.1
N_{pt}=50	$-\log L$	**-88.6**	**-88.6**	**-88.6**	**-88.6**

Strong tension (case-1)

Weak tension due to large uncertainty (case-2)

Consistent but data fluctuated (case-4)

Consistent - No fluctuation (case-5)

$$\pi(Y|\vec{\theta}) = \prod_{j=1}^{N_{\mathrm{pt}}} \pi(y_j, \Delta y_j|\vec{\theta}) = \prod_{j=1}^{N_{\mathrm{pt}}} \sum_{i=1}^{K} \omega_i \mathcal{N}(y_j, \Delta y_j|\theta_i),$$

$$0 \le \omega_k \le 1 \quad \text{and} \quad \sum_k \omega_k = 1,$$

Summary & Outlook

- Showed how to repurpose the GMM, a well-known machine learning classification tool, as a statistical model to estimate uncertainty in PDF fits
  - Can also be used to classify PDF fitting data and find tensions in data sets – unsupervised machine learning task
- Provides an implementation of Bayesian Model Averaging, to provide statistically robust estimates of uncertainty.
- Can be used in conjunction with both the Hessian and Monte-Carlo method of PDF uncertainty estimation
  - Tools to develop this already exist in machine learning packages like TensorFlow/PyTorch/ scikit-learn
- Here I only showed tension due to experimental inconsistencies, but this also applies to tension resulting from imprecise theoretical predictions.
- Can be used to determine a value of Tolerance in order to connect with existing prescriptions.
- Next steps: Apply to real data and pdf fit.