

Generalised Geometric Track Finding Algorithm for IDEA

Andrea De Vita, Dolores Garcia, Briec Francois



FUTURE
CIRCULAR
COLLIDER



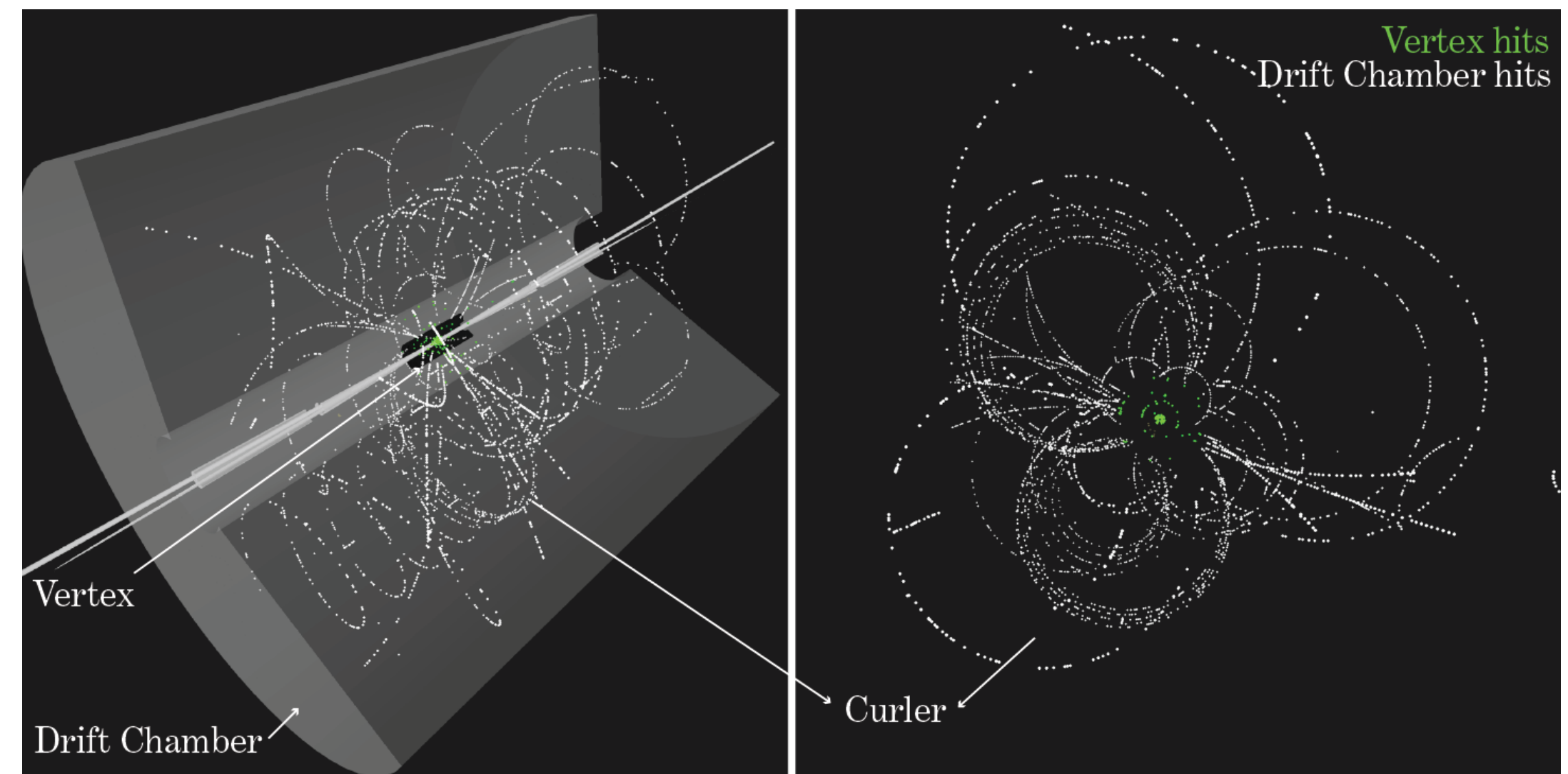
2nd FCC Italy&France Workshop
4-6 November 2024

Introduction

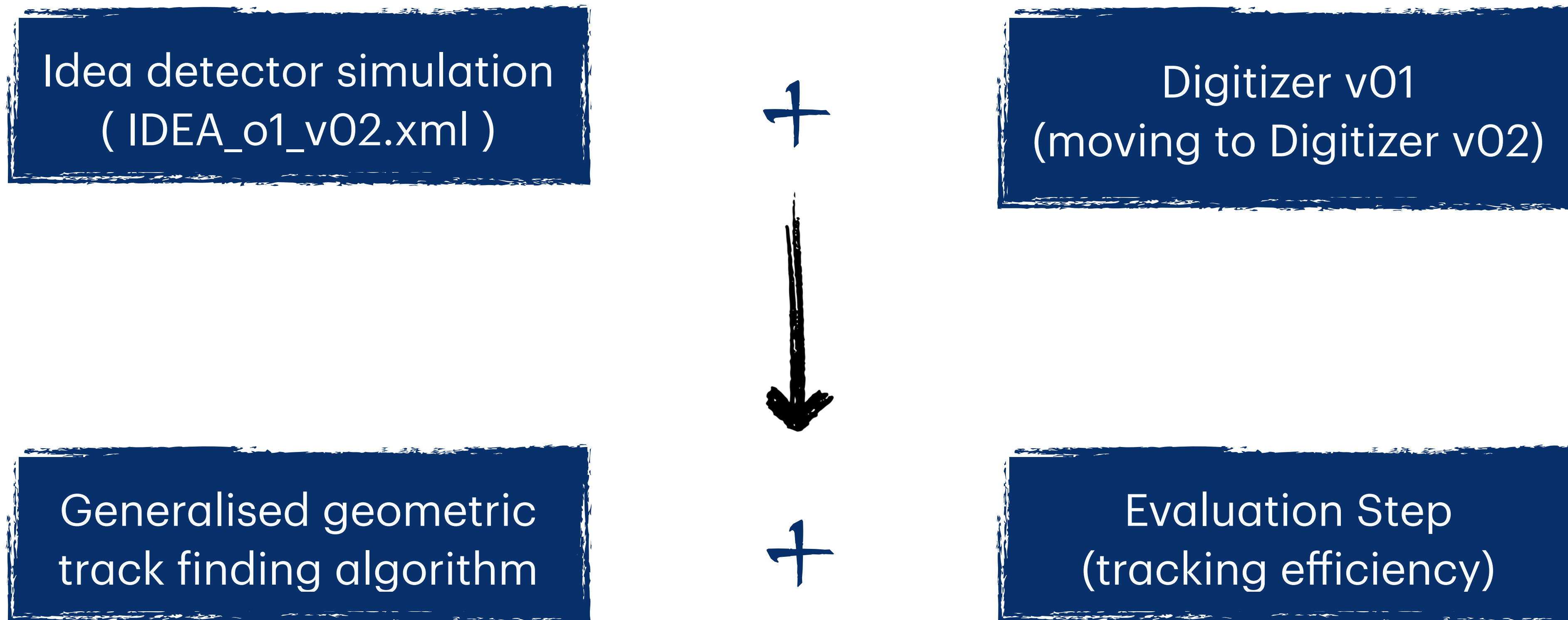
The tracking algorithm is typically tailored to the specific sub-detectors in use. This study, however, introduces a **generalized geometric method for track finding**.

An end-to-end pipeline can be employed to process hits from all tracking systems, producing a complete set of tracks and **evaluating tracking performance**.

The analyses focus on the IDEA detector, which utilises a **vertex detector and a drift chamber**.



Complete Pipeline

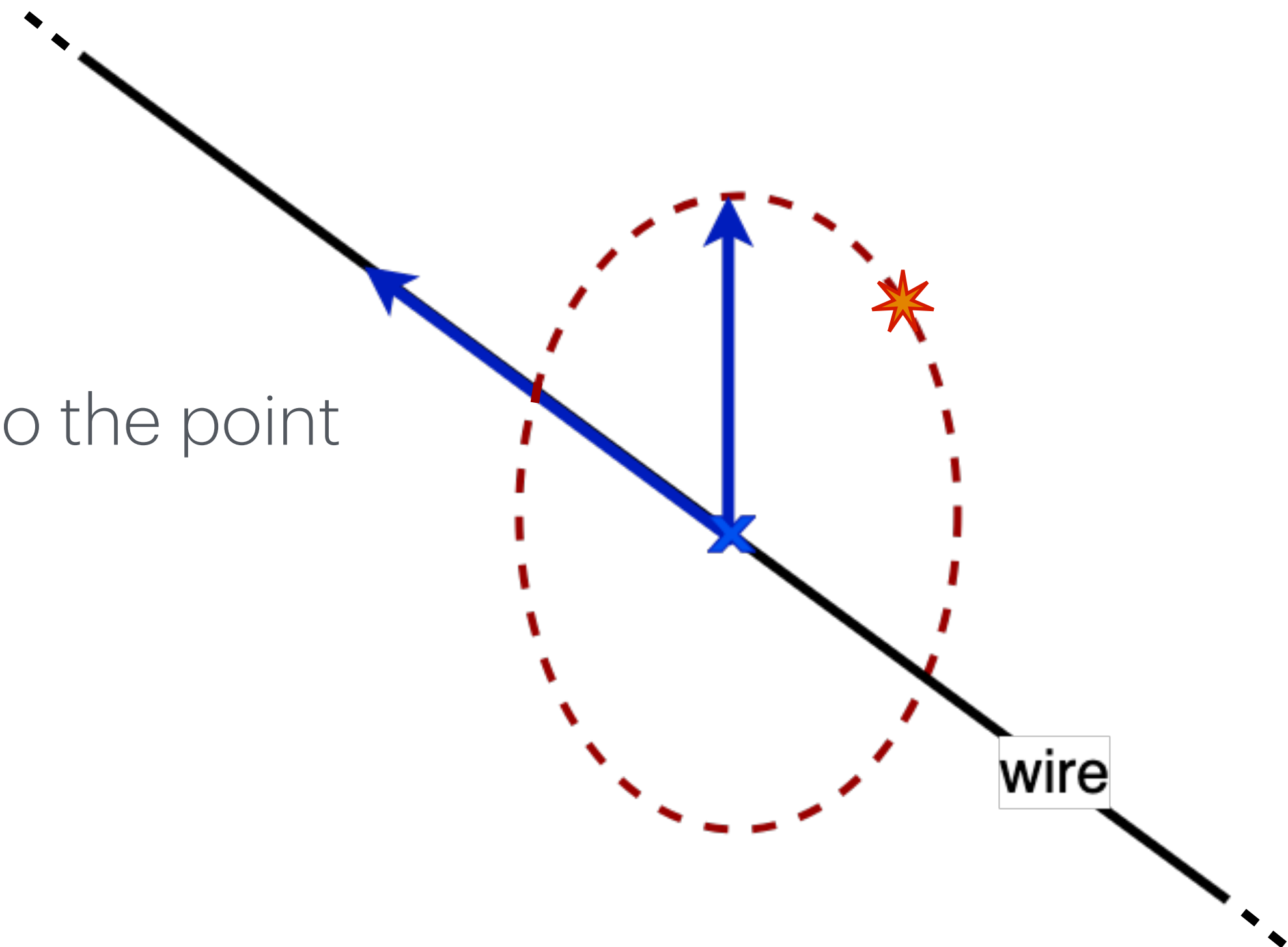


From Simulation to Digitizer

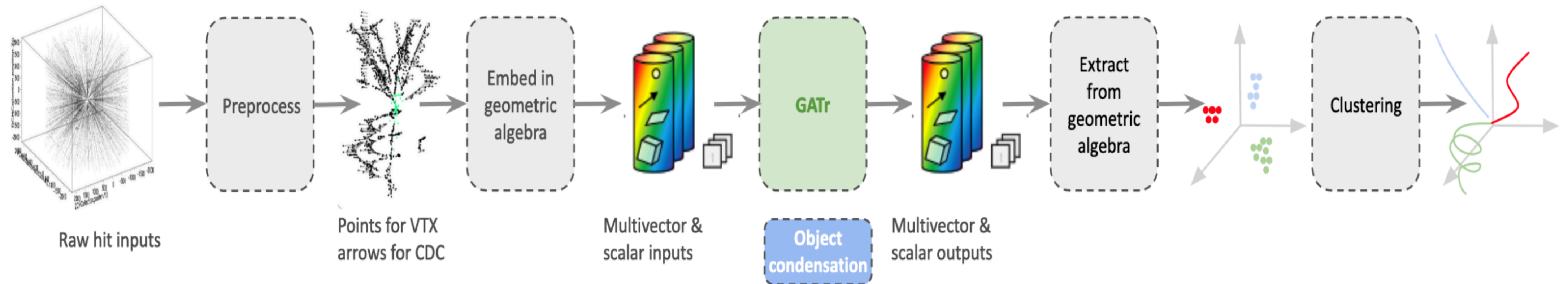
Digitizer v01 vs Digitizer v02

Drift chamber hits exhibit a **positional ambiguity**, as it is necessary to consider all possible positions along a circle with its center coinciding with the wire.

- Digitizer v01 describes the drift chamber hits through two positions, **left** and **right** of the wire.
- Digitizer v02 uses three quantities:
 1. the **position of the point on the wire** closest to the point where the particle passed through;
 2. **radius** of the circle;
 3. the **direction of the wire**;



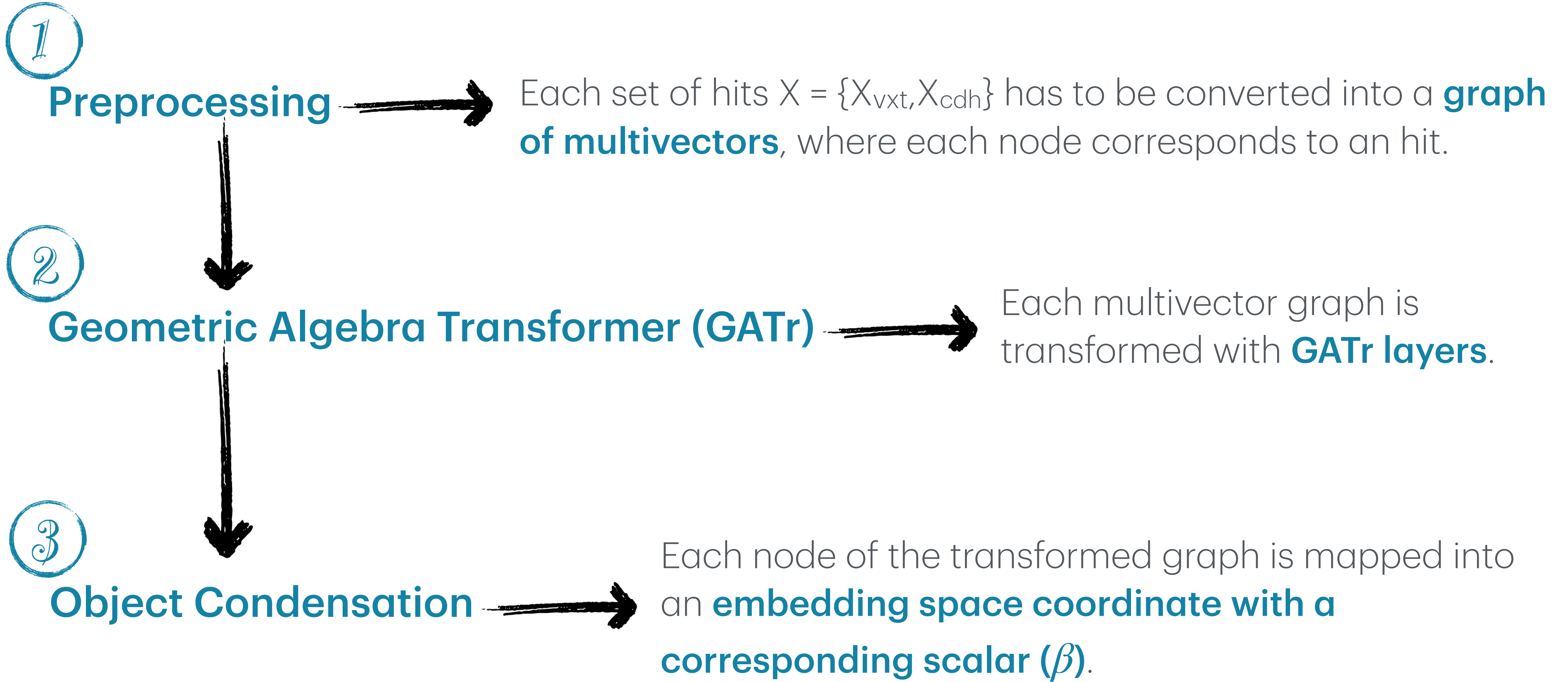
Generalised Geometric Track Finding algorithm



ML step: The Track-finding approach is based on a graph structure of the inputs, where geometric algebra transformations are applied. The result is a set of pairs $(\beta, \text{coordinates})$ in the embedding space.

Clustering step: Tracks can be identified in the embedding space by applying a clustering algorithm, establishing a one-to-one correspondence between clusters and tracks.

Track Finder - ML step



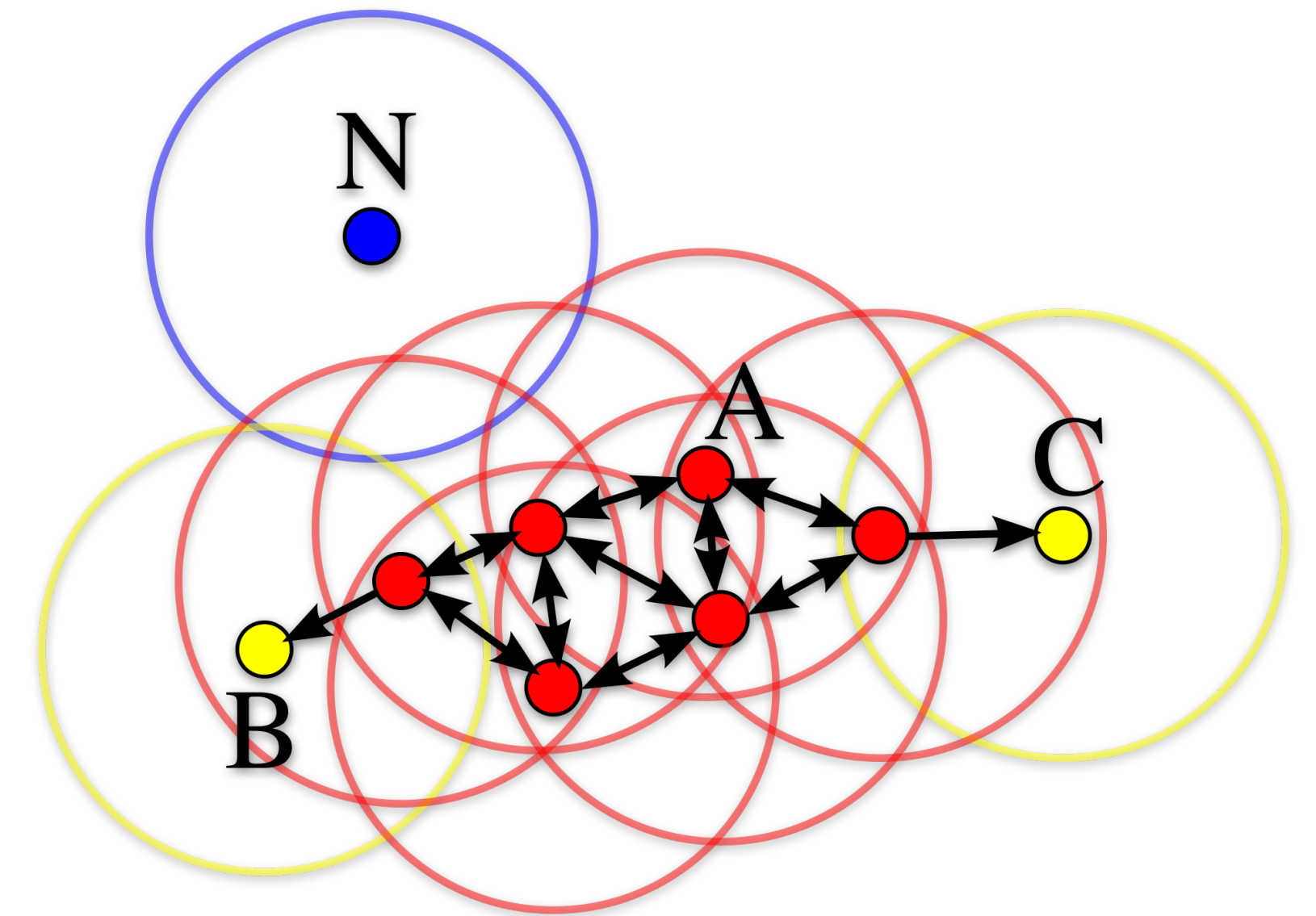
Track Finder - Clustering

The clustering algorithm is implemented with **DBSCAN**.

DBSCAN uses a definition of clusters based on the notion of **density**:

- if a point has a minimum number of points within a certain epsilon distance (ϵ), it is classified as a **core point**;
- If a point is not a core point and it is not close to a core point, then it is classified as **noise**;

Starting with the core points, the clusters are expanded until all points are classified as noise or belonging to a cluster.



Tracking Efficiency

Introduction

It is essential to define **tracking efficiency** in a way that aligns with the detector's design.

IDEA relies on a tracker with drift chambers and vertex detectors, so the hit collection is predominantly influenced by **contributions from the drift chambers**.

By analogy of design, the definition proposed by BELLE II is chosen, for which a particle is assigned to a track depending on **purity** and **efficiency** values.

Tracking Efficiency - Step 1

Reconstructable particles

A particle is defined as **reconstructable** if it satisfies the following conditions:

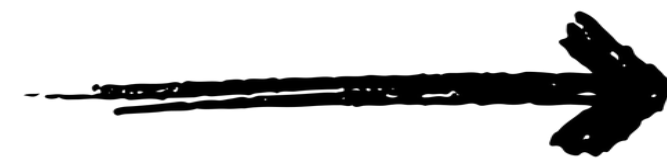
1. $p_T > 100$ MeV
2. $\cos(\theta) < 0.99$
3. Number of unique hits (Drift Chamber + Vertex) > 15
4. Number of Drift Chamber hits > 4
5. Generator Status == 1
6. Vertex < 50 mm

Tracking Efficiency - Step 2

Purity and efficiency - Assigned particles

Particle P

Track T



$$Pur_{MC_p}^{TRACK_t} = \frac{\text{num of hits from } MC_p \text{ in } TRACK_t}{\text{num of hits of } TRACK_t}$$

$$Eff_{TRACK_t}^{MC_p} = \frac{\text{num of hits from } TRACK_t \text{ in } MC_p}{\text{num of hits of } MC_p}$$

A **particle P** is assigned to the track **T** if $Pur_{MC_p}^{TRACK_t} > 0.5$ and $Eff_{TRACK_t}^{MC_p} > 0.5$

Tracking Efficiency - Step 3

Tracking efficiency and Fake Tracks

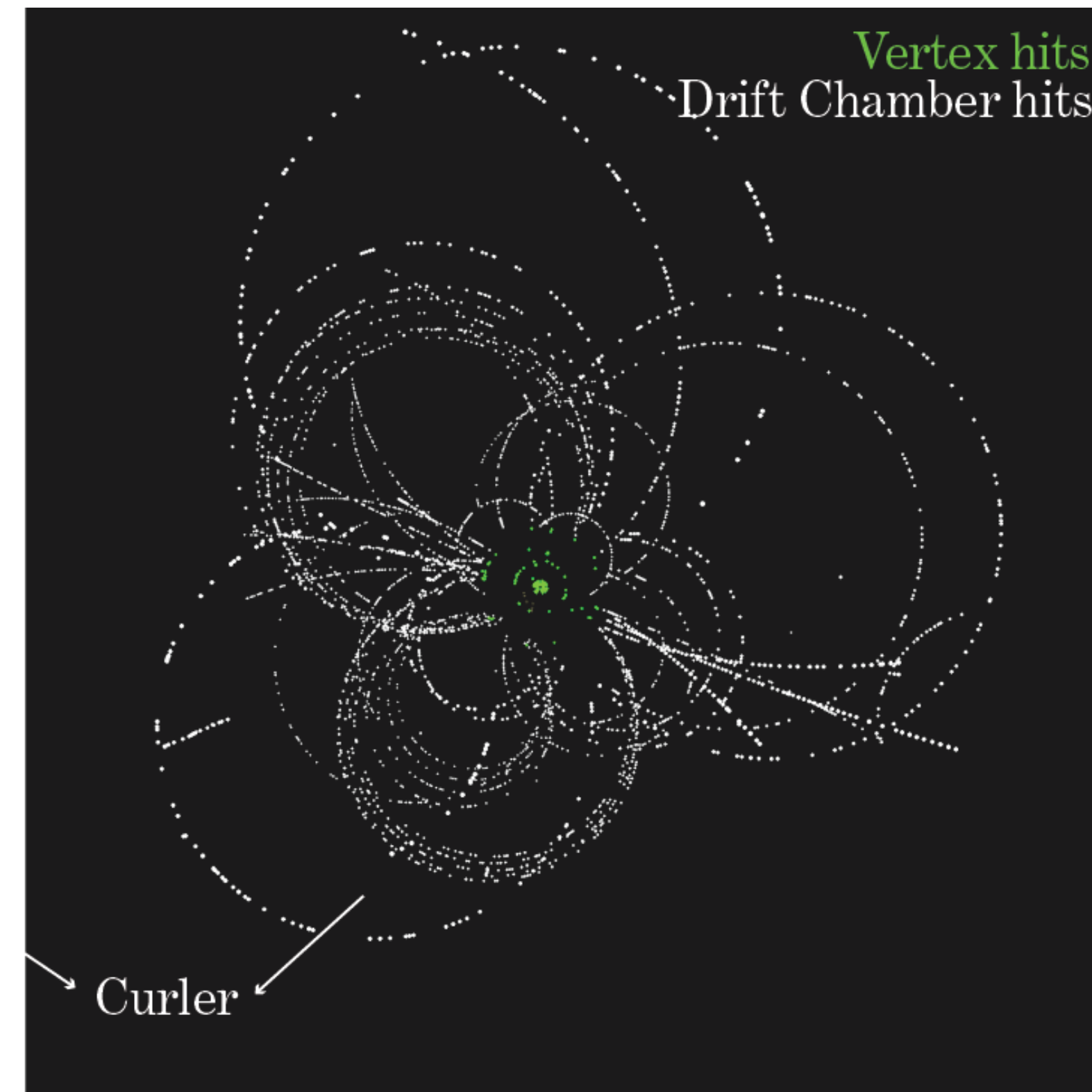
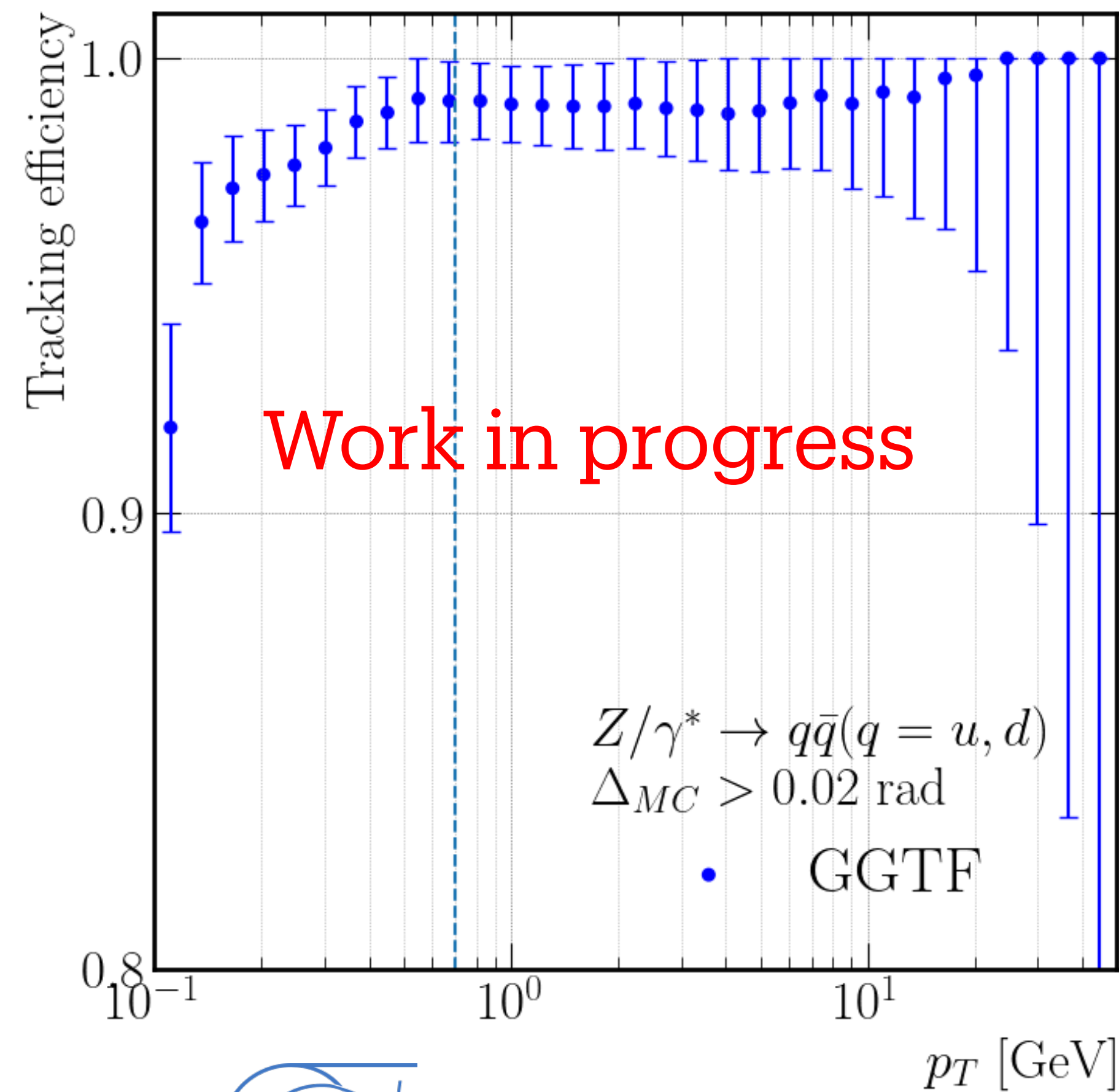
$$\text{Tracking efficiency} = \frac{\text{number of reconstructable and assigned particles}}{\text{number of reconstructable particles}}$$

Tracks with no assigned particles are considered **fake tracks**.

Particles that are assigned but are not reconstructable may indicate that it is possible to relax the definition of “reconstructable”.

Results

Performance for complex events - $Z/\gamma^* \rightarrow q\bar{q}$ ($q = u, d$)



What's next

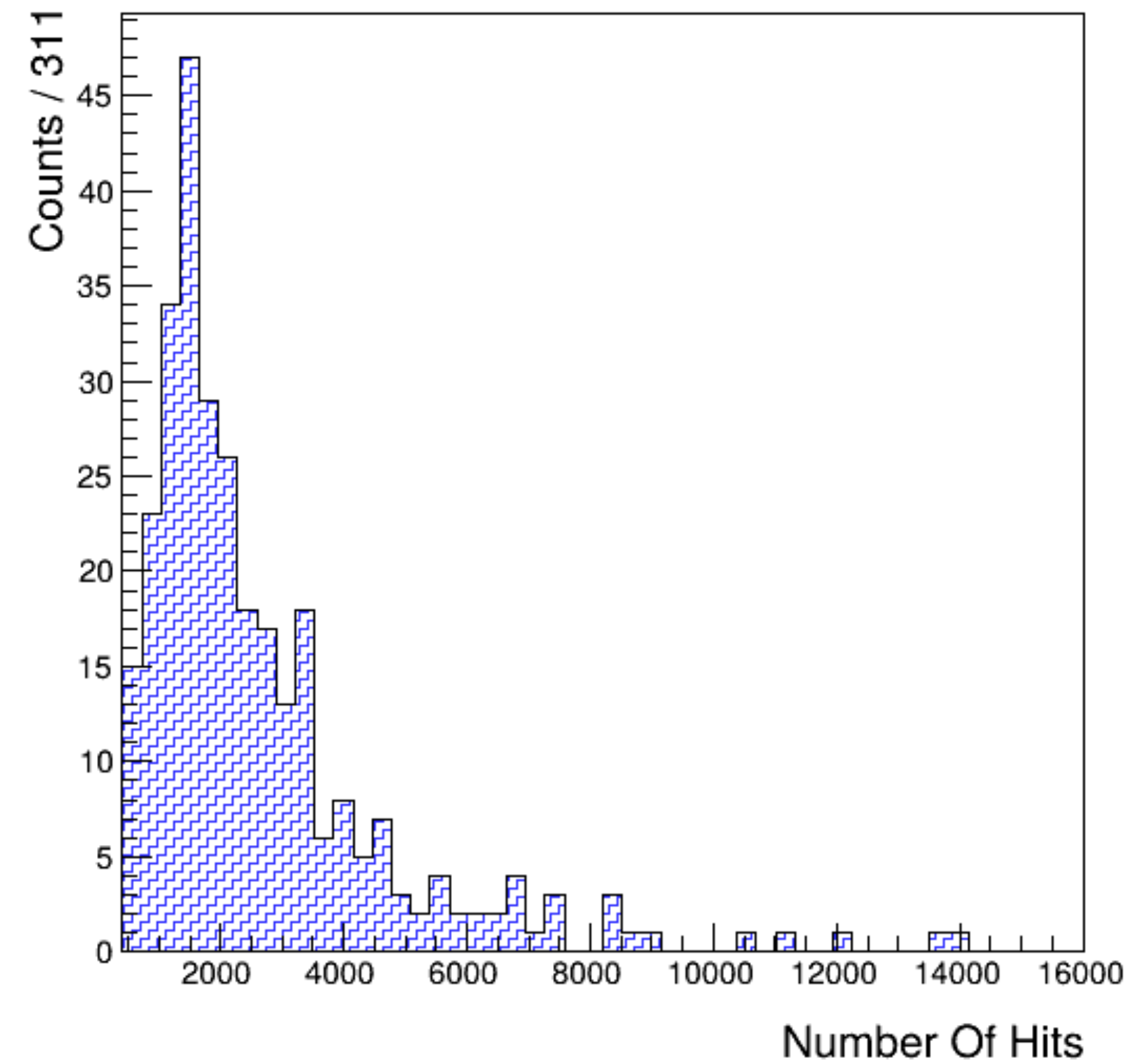
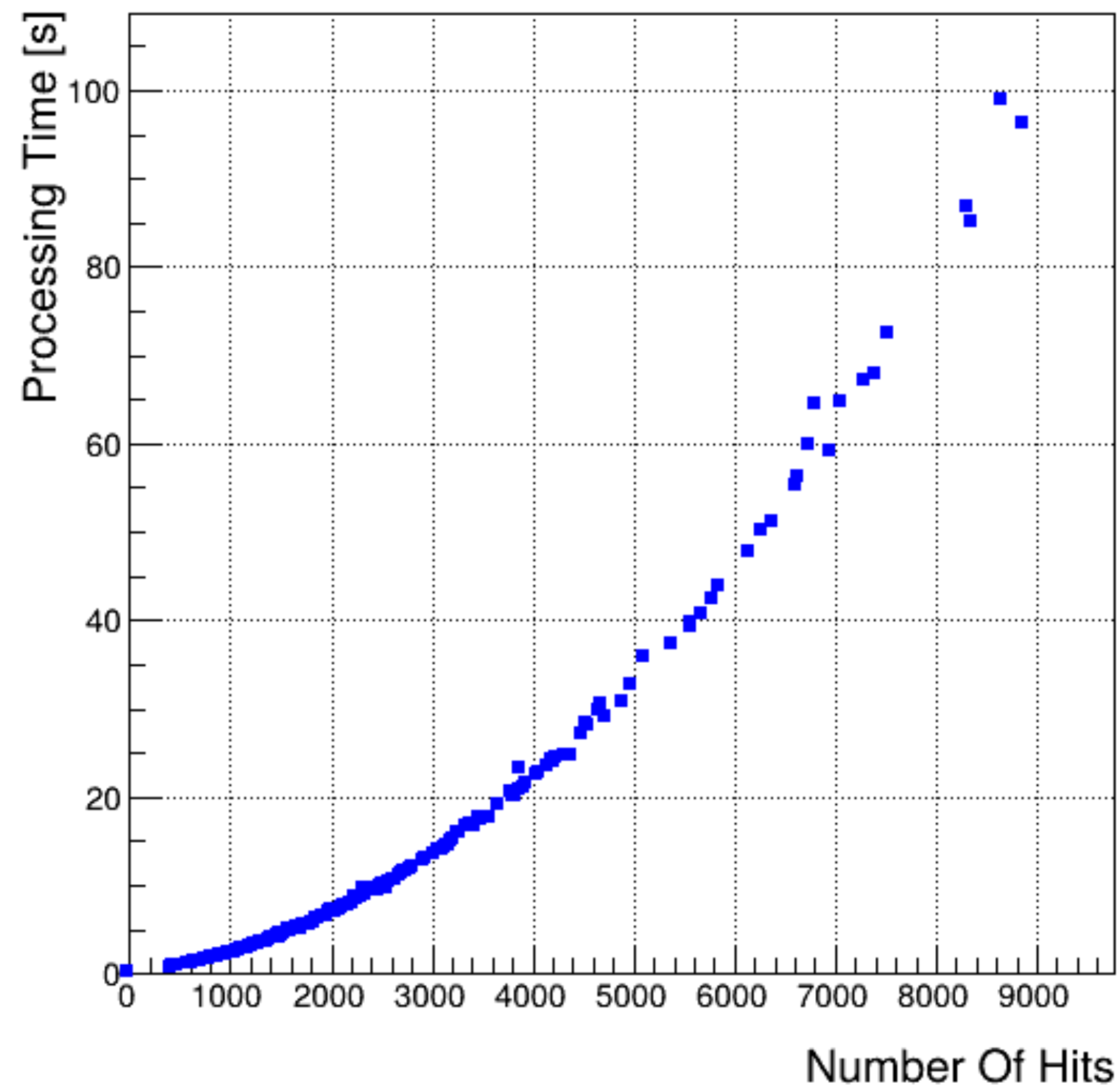
- **Optimization of the GGTF architecture** aims to enhance performance while reducing computational load.
- A pull request (PR) will be submitted to the central Key4Hep repository, implementing a **complete end-to-end pipeline for the GGTF**.
- Additionally, developing a **physics-based track-fitting** algorithm will be valuable as both an alternative and complementary tool to the ML-based track-finding algorithm.

A complex network graph visualization on a dark blue background. The graph consists of numerous nodes and edges. The nodes are represented by small squares in light blue and red. The edges are represented by thin, overlapping lines in yellow and white, forming a dense, tangled web. A central white rectangular box with a dark blue border contains the word "Backup" in a dark blue, sans-serif font.

Backup

Results

Track finder - processing time



Performance for complex events CLD: tracking efficiency

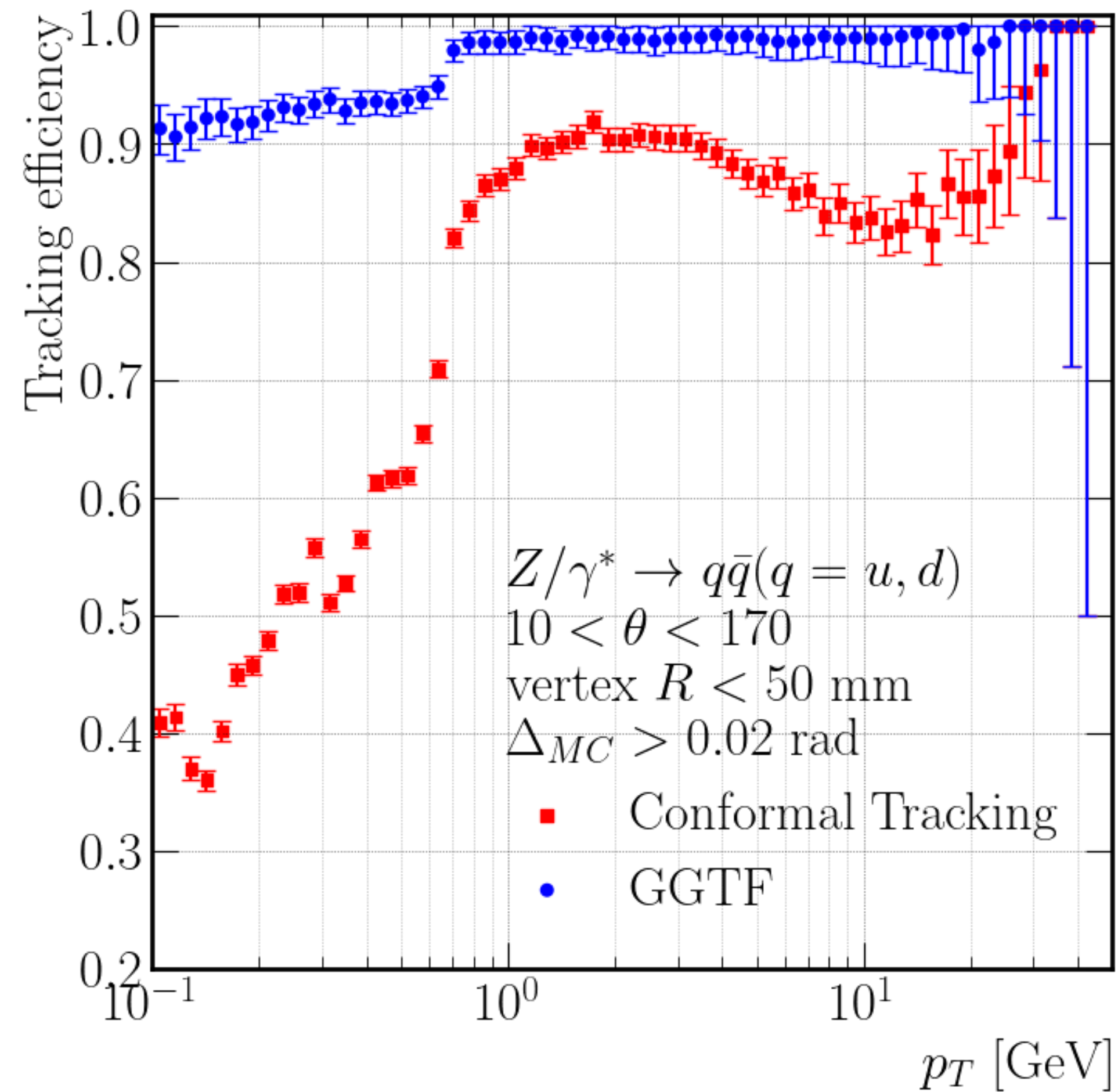


Table of Features

Structure

```
Event: 49
  PDG      pt  costheta  phi  ...  assigned_track  isReconstructable  isAssigned  isRecoAndAssigned
0      11  0.000000  1.000000  0.000000  ...             0                 0              0                0
1      11  0.000000  1.000000  0.000000  ...             0                 0              0                0
2      22  0.000000  1.000000  0.000000  ...             0                 0              0                0
3     -11  0.000000  1.000000  0.000000  ...             0                 0              0                0
4     -11  0.000000  1.000000  0.000000  ...             0                 0              0                0
..     ...      ...      ...      ...      ...             ...                 ...              ...                ...
```

- **Assigned_track**: index of the track which the particle has been assigned to (0 if not assigned)
- **isReconstructable**: boolean value which is 1 if the particle is reconstructable and 0 otherwise
- **isAssigned**: boolean value which is 1 if the particle is assigned and 0 otherwise
- **Purity**: purity of the track which the particle has been assigned to (-1 if not assigned)
- **Efficiency**: efficiency of the particle with respect to the track which the particle has been assigned to (-1 if not assigned)