# **LONGITUDINAL BEAM DYNAMICS**

### **JUAS 2025**

#### **COURSE 1: THE SCIENCE OF PARTICLE ACCELERATORS**

A. [Lasheen](mailto:alexandre.lasheen@cern.ch)



# **INTRODUCTION**





### **ACKNOWLEDGEMENTS**

- **JUAS FORMER LECTURERS AND THEIR LEGACY**
- **ELIAS, BENOIT, BIRK, DAVID, AND LEANDRO FOR THEIR SUPPORT**
- **THE CERN ACCELERATOR SCHOOL AND ITS NUMEROUS REFERENCES**
- **COLLEAGUES FROM THE RF AND ABP GROUPS, AND THE BR SECTION AT CERN**
- **AND YOU!**



### **RESOURCES**

#### **WEB**

E. Metral website, JUAS courses, exercises, exams and [corrections](http://emetral.web.cern.ch/)

#### **COURSES**

- G. Dôme, Theory of RF [Acceleration](http://cds.cern.ch/record/185457)
- L. Rinolfi, [Longitudinal](https://cds.cern.ch/record/446961) Beam Dynamics Application to synchrotron
- F. Tecker, [Longitudinal](https://cds.cern.ch/record/2746987) Beam Dynamics in Circular Accelerators
- B. Holzer, Introduction to [Longitudinal](https://cds.cern.ch/record/1693322/) Beam Dynamics
- H. Damerau, Introduction to Non-linear [Longitudinal](https://cds.cern.ch/record/2778374) Beam Dynamics  $\bullet$
- R. Garoby, RF Gymnastics in [Synchrotrons](https://cds.cern.ch/record/1407406)
- B. W. Montague, Single particle dynamics : [Hamiltonian](https://cds.cern.ch/record/864417) formulation  $\bullet$
- W. Pirkl, [Longitudinal](https://cds.cern.ch/record/302486) beam dynamics
- J. Le Duff, [Longitudinal](https://cds.cern.ch/record/398427/) beam dynamics in circular accelerators
- E. [Jensen,](https://cds.cern.ch/record/1982429) RF Cavity Design



# **RESOURCES**

#### **NOTES**

- H. G. Hereward, What are the equations for the phase oscillations in a [synchrotron?](http://cds.cern.ch/record/276214)
- J. A. MacLachlan, Difference Equations for [Longitudinal](https://inspirehep.net/files/53264e1b7375b69f6002ddcfdda4c793) Motion in a Synchrotron
- J. A. MacLachlan, Differential Equations for [Longitudinal](https://inspirehep.net/files/6aae2f39d623333c670b56503a1eee5c) Motion in a Synchrotron
- C. Bovet, R. Gouiran, I. [Gumowski,](https://cds.cern.ch/record/104153) K. H. Reich, A selection of formulae and data useful for the design of A.G. [synchrotrons](https://cds.cern.ch/record/104153)

#### **BOOKS**

- A. A. Kolomensky, A. N. Lebedev, Theory of Cyclic Accelerators
- H. Bruck, Accelerateurs Circulaires De Particules
- S. Y. Lee, Accelerator Physics
- S. Humphries, Principles of Charged Particle Acceleration
- T. P. Wangler, RF Linear Accelerators  $\bullet$
- H. Wiedemann, Particle Accelerator Physics
- M. Reiser, Theory and Design of Charged Particle Beams



#### **COURSE CONTENT**

- 1 Introductory session  $\bullet$
- 10 Teaching modules including
	- **Lecture**
	- Derivations  $\blacksquare$
	- Computational exercises  $\blacksquare$
	- Quizz  $\blacksquare$
	- Interleaving exercises with lecture. The last slot of each afternoon dedicated to  $\blacksquare$ tutorials/questions.
- Exam preparation  $\bullet$
- PyHEADTAIL workshop





#### **WEEK 1**







#### **WEEK 2**







#### **WEEK 3**







# **COURSE LAYOUT**

#### **INTRODUCTORY SESSION**

- What is longitudinal beam dynamics?  $\bullet$
- How does this lecture relates to the others?  $\bullet$

#### **LESSON 1 - FUNDAMENTALS OF PARTICLE ACCELERATION**

- Fields, forces
- Accelerator designs
- Relativistic relationships





# **COURSE LAYOUT**

#### **LESSON 2 - SYNCHROTRON DESIGN**

- Equations for the synchronous particle
- One word on betatronic acceleration, synchrotron radiation, self induced fields
- Momentum compaction, differential relationships

### **LESSON 3 - LONGITUDINAL EQUATIONS OF MOTION**

- Equations for non synchronous particles
- Introduction to tracking





# **COURSE LAYOUT**

#### **LESSON 4 - SYNCHROTRON MOTION**

- Linearized synchrotron motion  $\bullet$
- Phase stability and synchrotron frequency/tune
- Non-linear synchrotron motion  $\bullet$
- RF bucket, longitudinal emittance, non-linear synchrotron frequency

#### **LESSON 5 - REAL LIFE APPLICATIONS**

- Longitudinal bunch profile measurements
- Examples of RF operation
- Introduction to RF manipulations ("gymnastics")





### **TEACHING AGREEMENT**

#### **WHAT YOU SHOULD KNOW AT THE END OF THE COURSE**

- Understand how a beam is effectively accelerated in a particle accelerator.
- Understand fundamental concepts of longitudinal beam dynamics (i.e. synchrotron motion, the RF bucket and its parameters).
- How main equations/formulas are derived and underlying assumptions.

#### **WHAT YOU SHOULD BE ABLE TO DO AT THE END OF THE COURSE**

- Compute RF parameters and basic design parameters of a synchrotron.
- Interpret the longitudinal motion of a measured bunch of particles.





### **KEY ASPECTS OF LONGITUDINAL BEAM DYNAMICS**

**→ Particle acceleration**

**→ Focusing of particles in the longitudinal direction (bunching)**

**→ Synchrotron motion**





### **LAYOUT OF A REAL ACCELERATOR**

#### **THE LOW ENERGY ION RING (LEIR) AT CERN**





- Virtual walk [around](https://panoramas-outreach.cern.ch/viewer?id=36262111) LEIR... (visit on the 29/01!)
- To see other [accelerators](https://panoramas-outreach.cern.ch/index.html) at CERN...



#### *Accelerator seen from above...*



#### Bending magnets **Accelerating RF cavities**



*Accelerator seen from above, along the vertical*  $\overline{Y}$  *axis...* 



- The black line represents the (ideal) design trajectory of the beam around which a particle oscillate (blue).
- The accelerator layout can be described in fixed cartesian coordinates  $\left(\,X,Z,Y\,\right)$  . where the  $\overline{Y}$  direction is the vertical direction.
- However, this coordinate system is not suited to describe particle motion in circular accelerators.





#### **FRENET-SERRET COORDINATE SYSTEM**



- A particle trajectory follows a curved path, which can be described in the Frenet-Serret coordinate system.
- The particle coordinates are given as offsets with respect to the design trajectory with
	- *x* Horizontal
	- *y* Vertical
	- *z* Longitudinal
- The curvature of the trajectory has a local bending radius *ρ*.





*Accelerator* seen from above, along the vertical  $\acute{Y}$  axis...



- We use the Frenet-Serret coordinate system  $(\vec{x}, \vec{z}, \vec{y})$  as reference to describe the motion of particles.
- We introduce the mean radius

$$
R=\frac{C}{2\pi}
$$

where  $C$  is the path circumference and the generalized azimuth

 $\theta \in [0,2\pi]$ 



*Accelerator seen from above, along the vertical*  $\overline{Y}$  *axis...* 



- For a circular accelerator, this coordinate system is comparable to the cylindrical  $\mathsf{coordinate}$  system  $\left(\right.\vec{\rho},\theta,\vec{y}\left.\right)$
- A particle orbit and horzitonal positions are equivalent, as well as the longitudinal position and azimuth.
- Beware, definitions can be interchanged!





*Accelerator seen from above, along the vertical*  $\vec{Y}$  *axis...* 



It is also important to disembiguate *ρ* which is the bending radius and  $R$  which is the particle orbit including straight sections of total length  $L$ . We have

$$
C=2\pi R=L+2\pi\rho
$$





# **PARTICLE ACCELERATION**

- The primary purpose of a particle accelerator is to produce a beam of particles with a precise energy *E*.
- The energy can be provided to the particles applying the Lorentz force to charged particles

$$
\frac{d\vec{p}}{dt} = \vec{F} = q\left(\vec{\cal{E}} + \vec{v}\times\vec{\cal{B}}\right)
$$

where

- $\vec{p} = m\vec{v}$  is the particle momentum
- $\overline{q}$  is the particle charge
- $\overline{m}$  is the particle (relativistic) mass
- $\vec{v}$  is the particle velocity
- $F$  is a force
- $\acute{\mathcal{E}}$  is an electric field
- $\overline{\mathcal{B}}$  is a magnetic field



# **PARTICLE ACCELERATION**

#### **ELECTRIC FIELD CONTRIBUTION**

$$
\vec{F_{\mathcal{E}}} = q \ \vec{\mathcal{E}}
$$

- An electric field can effectively **accelerate (or decelerate) particles**.
- Electric fields can also be used to **deflect particles** if applied transversally to the particle trajectory.

#### **MAGNETIC FIELD CONTRIBUTION**

$$
\vec{F}_{\mathcal{B}}=q\left(\vec{v}\times\vec{\mathcal{B}}\right)
$$

- The force applied by a magnetic field is always orthogonal to the particle trajectory and therefore **cannot accelerate the beam**.
- Magnetic fields are used to **steer the beam**.



#### **ACCELERATION ALONG THE LONGITUDINAL DIRECTION**



• The acceleration is done by applying an electric field tangential to the beam trajectory with

$$
\vec{\cal E}={\cal E}_z\vec{e_z}
$$

- Except at extremely low energies (e.g. particle sources), the momentum of a particle is almost exclusively directed towards the longitudinal direction  $z$  with small angles in the transverse  $x$ and  $y$  directions.
- Assumptions:  $p_z \gg p_{x,y}$  and  $p \approx p_z$



#### **STEERING THE DESIGN TRAJECTORY**



The beam trajectory is steered horizontally by applying a vertical magnetic field with

$$
\vec{\mathcal B} = \mathcal B_y \vec{e_y}
$$

- The applied force depends on the particle velocity  $v_z$ . For particles with different momenta, the steering and trajectories will be different than the design one.
- This effect is called dispersion and will be covered in both transverse and longitudinal beam dynamics lectures.





#### **EVOLUTION OF RELATIVE PARTICLE POSITIONS**



- In the longitudinal direction, a particle can be in front (in advance), or behind (late) with respect to the **ideal particle (on time)**.
- The relative distance between particles can change
	- Because a particle can also have a smaller/larger velocity  $v_z$  (and momentum  $p_z$ ).





#### **EVOLUTION OF RELATIVE PARTICLE POSITIONS**



*Red is faster but at larger orbit, while blue is slower but inner orbit.*

*How do we accelerate all three particles evenly? How do we keep these particles together?*

- In the longitudinal direction, a particle can be in front (in advance), or behind (late) with respect to the **ideal particle (on time)**.
- The relative distance between particles can change
	- Because a particle can also have a smaller/larger velocity  $v_z$  (and momentum  $p_z$ ).
	- Because of a shorter/longer path length in a bending (i.e. smaller/larger orbit), which depends on the particle momentum.





### **LONGITUDINAL PHASE SPACE**



- We will introduce the notion of longitudinal phase space.
- The particle motion can be described in the  $(z,p_z)$ phase space, relative to the **ideal particle** following the design orbit and energy.
- As described before other particles can be
	- In front, or in advance in time (right)
	- In the back, or delayed in time (left)
	- Have higher momentum/velocity (top)
	- Have lower momentum/velocity (bottom)
- The motion of the particles in the longitudinal phase space is called **synchrotron motion**.



### **SYNCHROTRON OSCILLATIONS**

#### **WITH A FEW PARTICLES**



In a bunch, particles rotate around the ideal particle in black used a reference.

These are called **synchrotron oscillations**.





### **SYNCHROTRON OSCILLATIONS**

#### **WITH MANY PARTICLES**



- A bunch is usually composed of a very large number of particles, typically  $\mathcal{O}\left(10^{10}-10^{12}\right)$  at CERN.
- In a real machine, the coherent motion of a bunch can be measured and analyzed from the longitudinal bunch density (top line, projection along the *p<sup>z</sup>* axis, instantaneous beam current).
- You can notice the non-linear synchrotron motion in phase space at large amplitude.





### **TEMPORAL DEFINITION OF A BEAM**



- Controlling the synchrotron motion allows to define the temporal structure of a pulse of particles.
- The beam current is

$$
I=\frac{dQ}{dt}
$$



where *dQ* is the charge passing in a time *dt*.

Depending on the destination (experiment or next machine in a chain), parameters defining the synchrotron motion can be adjusted to deliver a continuous or bunched beam.





# **WHAT IS LONGITUDINAL BEAM DYNAMICS?**

- Longitudinal beam dynamics is the description of the acceleration and motion of particles along the forward path of the beam.
- Since the orbit of a particle also plays a role, we will see that the horizontal/radial position of a particle is an important parameter.
- We will derive the equations to describe synchrotron oscillations in longitudinal phase space.







# **RELATIONSHIP WITH OTHER COURSES**

#### **JUAS COURSE 1**

How do we focus the beam in the horizontal and vertical directions, how do we transport the beam to a target?

#### **→ Transverse Beam Dynamics**

Can we use the beam in another way than colliding on a target, what is the principle behind light sources ?

#### **→ Synchrotron radiation**

- Do charged particles interact with each other, can we accelerate an infinite amount of particles?
- **→ Collective Effects - Space Charge and Instabilities**





## **RELATIONSHIP WITH OTHER COURSES**

#### **JUAS COURSE 1**

- This course is devoted to describe fundamentals of longitudinal beam dynamics with specifities linked to the design of **Synchrotrons**.
- Dedicated courses are devoted to the specificities of **Linacs** and **Cyclotrons**.
- You will find similar concepts between the courses. Nonetheless, beware of definitions, conventions and assumptions used to derive formulas!





# **RELATIONSHIP WITH OTHER COURSES**

#### **JUAS COURSE 2**

- What systems do we use to provide the beam with an electric field, how are they designed ?
- **→ RF Engineering and Superconducting RF Cavities**
- How do we measure a bunch, specificially in the longitudinal plane?
- **→ Beam Instrumentation**





### **TAKE AWAY MESSAGE**

Lorentz force

$$
\frac{d\vec{p}}{dt} = \vec{F} = q\left(\vec{\cal{E}} + \vec{v}\times\vec{\cal{B}}\right)
$$

- Definition of coordinates
	- horizontal position *x*
	- $y$  vertical position
	- z longitudinal position

 $\vec{\mathcal{E}}$  to accelerate and deflect  $\vec{\mathcal{B}}$  to bend trajectories

- $\rho$  local bending radius
- $R$  mean radius / orbit
- azimuth *θ*
- Assumptions made so far:  $p_z \gg p_{x,y}$  and  $p \approx p_z$

