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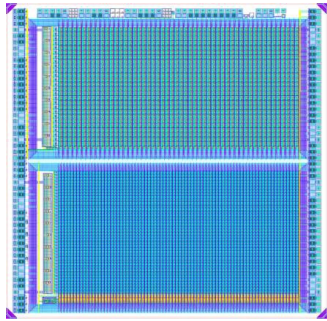
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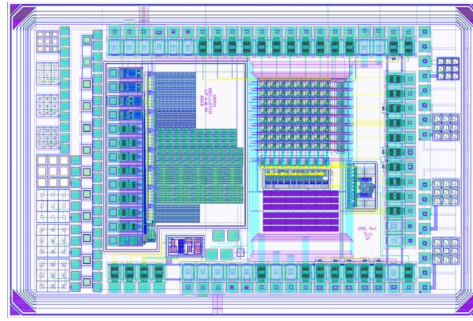
The RD50-MPW_x HV-CMOS Series elevated by the Caribou system

Bernhard Pils

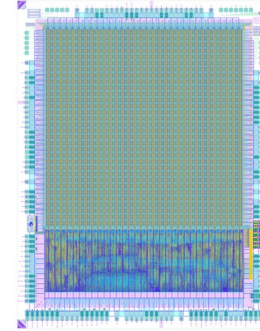
RD50 HV-CMOS Series



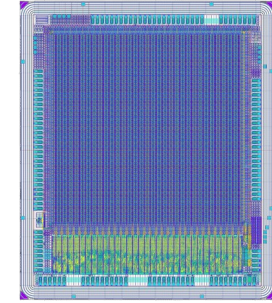
RD50-MPW1
(5mm x 5mm)



RD50-MPW2
(3.2mm x 2.1mm)



RD50-MPW3
(5.1mm x 6.6mm)



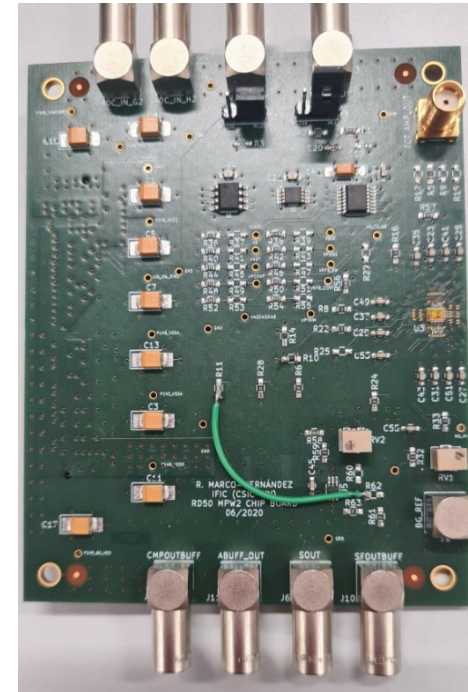
RD50-MPW4
(5.4mm x 6.3mm)



- HV-CMOS sensors fabricated in *LFoundry* 150nm process
- All sensors use Caribou as DAQ system

RD50-MPW2

- RD50-MPW1 suffered from high leakage current
- Designed to evaluate guard rings and in-pixel electronics
- 6x6 pixel matrix with 2 pixel flavors
- Analog only
- ADC on chip carrier board digitizing signals
 - Directly operated by FPGA on Xilinx Zynq ZC706
- Peary device used *just* to operate FPGA via AXI
- Configuration also done by FPGA
- Carboard DACs used for supply voltages



RD50-MPW3 / -MPW4

Both sensors feature:

- 64x64 pixel matrix arranged in 32 FEI-3 style double columns
- Active area of 4x4mm²
- Pixel-size of 62x62μm²
- 8 bit timestamp information (based on 25ns) for each hit
- 4 bit in-pixel trimming
- 640MHz readout
- Digital periphery with 128 / 64 word deep TX FIFOs
- Configuration via I²C

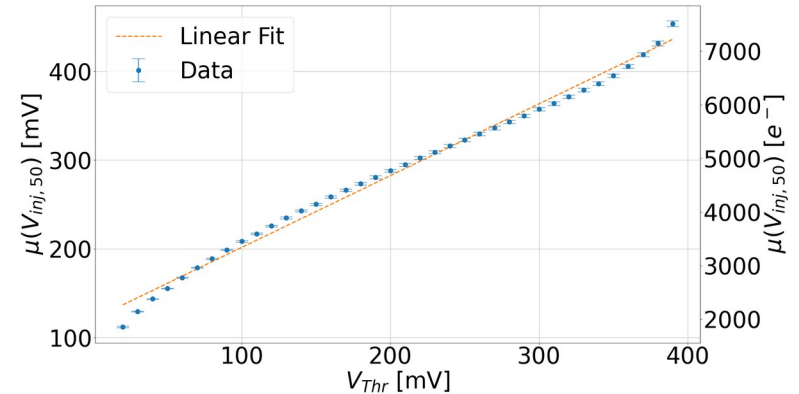
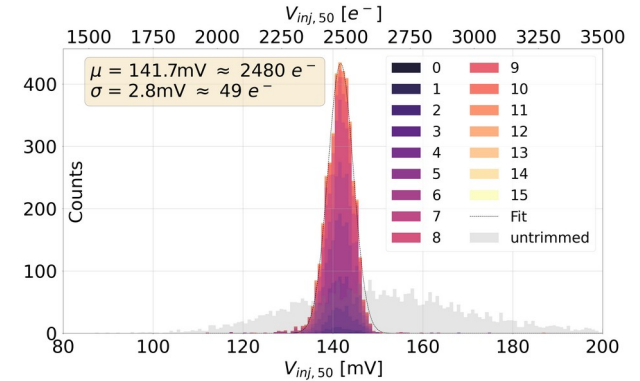
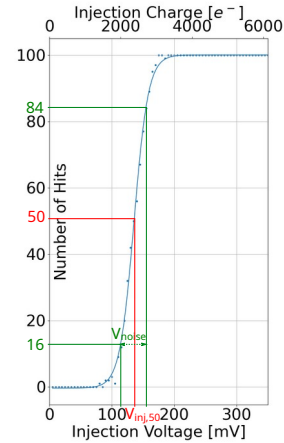


Modifications / Improvements MPW3 → MPW4

- Noise significantly reduced by
 - separating power domains of in-pixel and peripheral digital readout
 - improved routing of power lines
- Optimized guard rings
 - higher breakdown voltage → improved radiation hardness
- Backside processing
 - higher breakdown voltage → improved radiation hardness
- Length of EOC readout signals adjustable

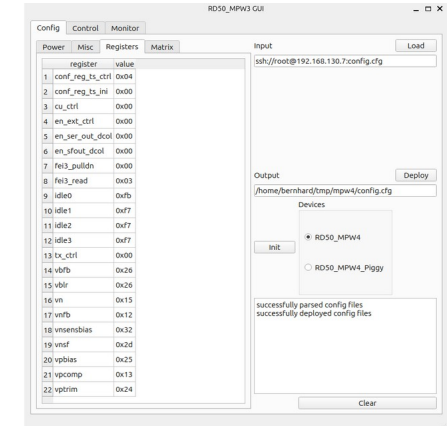
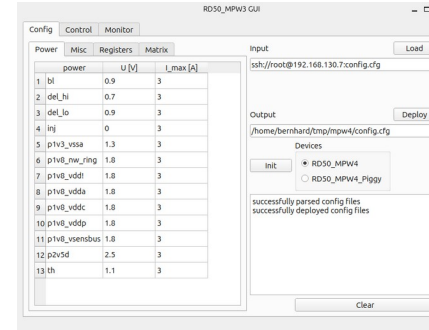
MPW3/4 Peary implementation

- Custom I²C interface implemented
 - Internal conversion from I²C → Wishbone
 - Non *standard* I²C implementation (SMBus 7 bit address range not sufficient)
 - Used for configuration of chip
- Data transfer from FPGA → Peary via AXI
- Laboratory measurements implemented in device
 - S-curve injection measurements
 - Hitmap
 - TrimDAC evaluation
- Preprocessed form of raw data stored to text files in Poky Linux
- Data analysis done via external Python tools



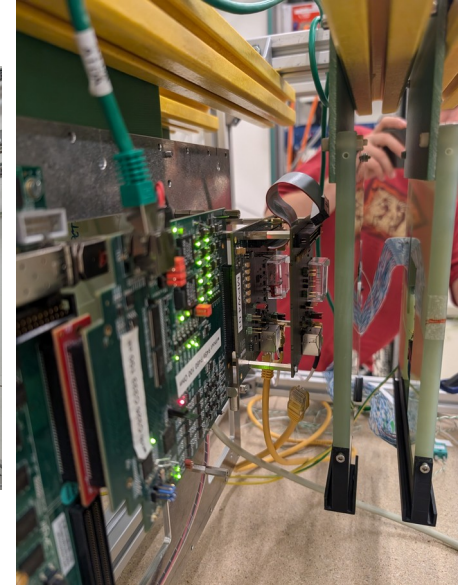
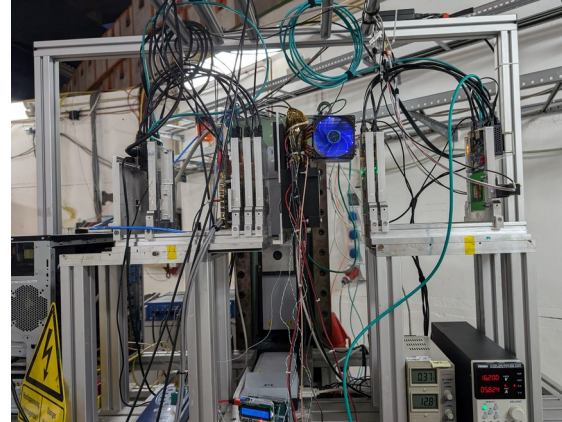
Generic GUI

- 23 global registers and 16 registers for each double column
- Every single pixel has 8 bit config options
- Implemented GUI for user friendly generation of Peary-style config-files
- GUI could be used by other pixel detectors
 - Fully configurable by JSON config file
- Features EUDAQ2 monitor (hitmap)



MPW3/4 testbeam DAQ

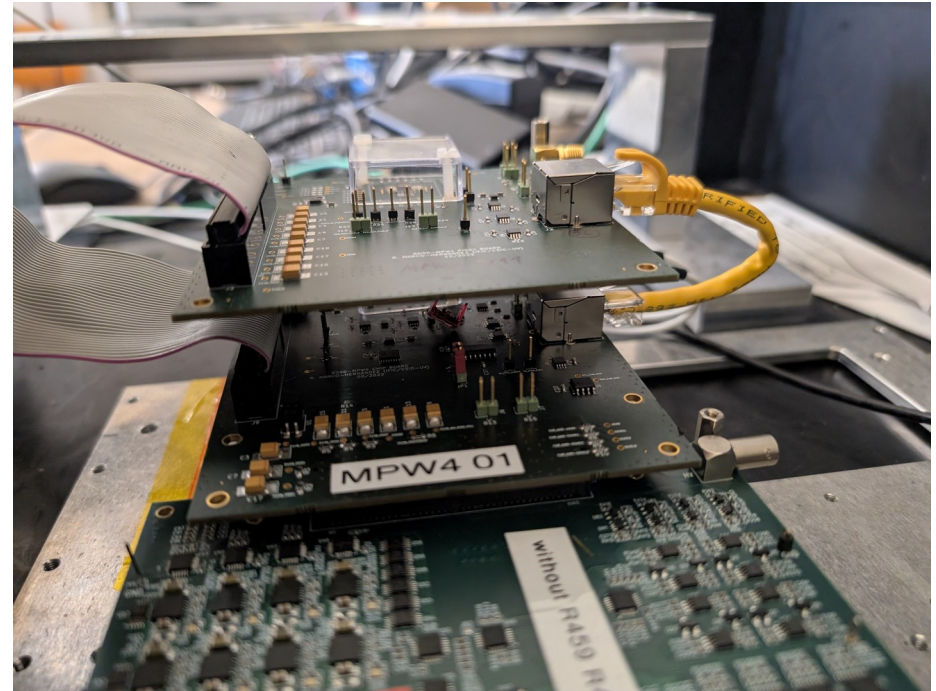
- Utilizing EUDAQ2's Caribou producer
- Data taking:
 - Our *standard* data path via AXI FIFOs too slow for testbeam usage
 - Implemented fast data path: FPGA dispatches UDP packages
 - Custom EUDAQ2 data collector developed
 - Multi threaded approach
 - Data rate of up to 1 Gbit/s possible (not needed at our usual testbeam sites)
- Entire setup mounted on aluminium frame and placed into beam telescope
 - No *proper / flexible* FMC cables available
 - Suggestions for improvements very welcome!



Doubling the number of DUTs in one Caribou system

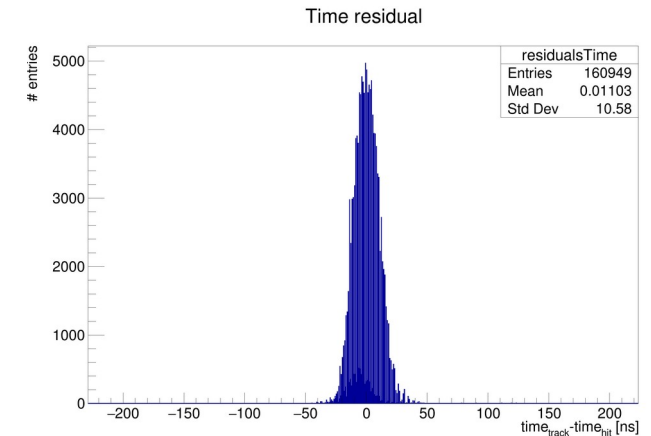
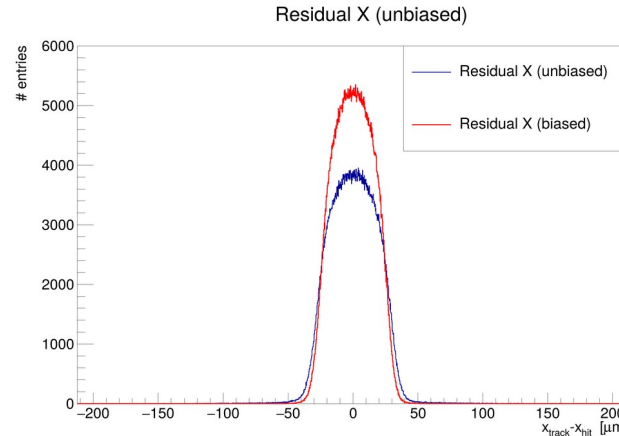
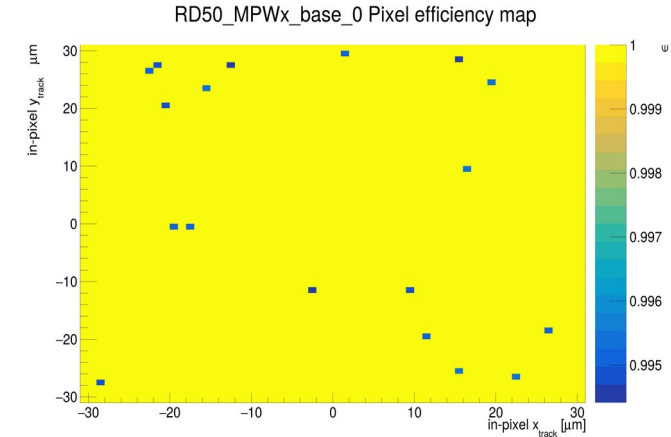
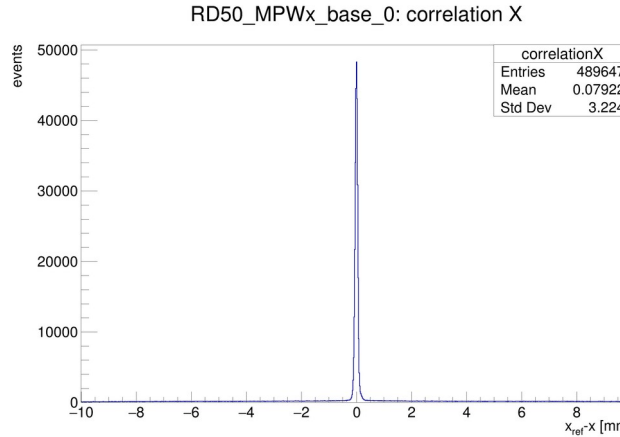
The Piggy Board

- Initial idea:
 - Readout and operate two RD50-MPW3/4s with just one Caribou system
 - Easy to install / remove DUTs for testbeam scenarios
- Implementation:
 - Developed second chip carrier board
 - Reduced number of electronic components
 - Connected to *main* chip board via a ribbon cable (bias voltages, slow signals) and an Ethernet cable (data and clock lines)
- Both DUTs readout by the same FW / FPGA via separate serial data lines

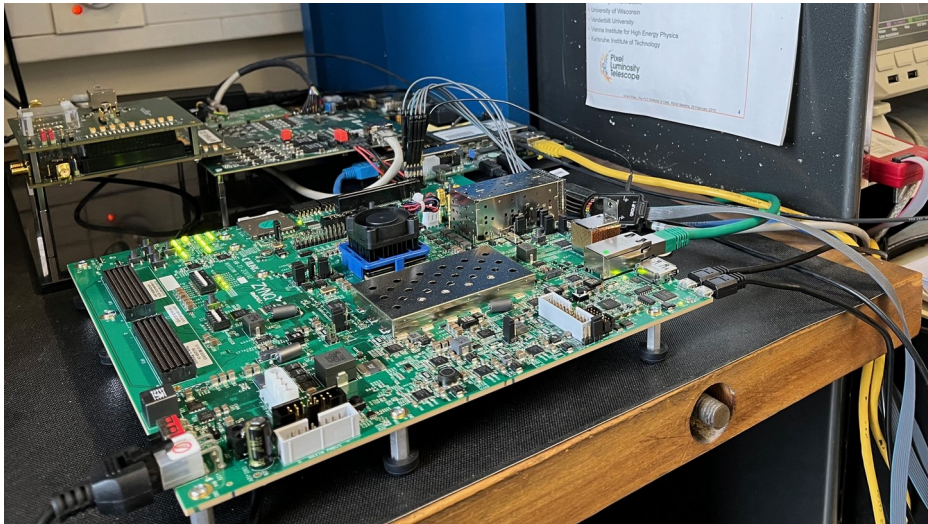


Testbeam performance of the RD50-MPW4

- Triggerless readout of RD50-MPW3/4
 - Timestamps utilized for synchronization
- Matching events of DUT with telescope done by employing the AIDA 2020 TLU
- Narrow correlation peak with very little background
- Efficiency > 99.9% evaluated
- Spatial resolution of $\sim 15.8\mu\text{m}$
- Time resolution of $\sim 10\text{ns}$



Developments towards Caribou 2.0



- In order to get fit for Caribou 2.0 started to port FW to Xilinx ZCU102
- So far managed to boot Peta Linux
- Currently trying to get DMA running
- Work in progress

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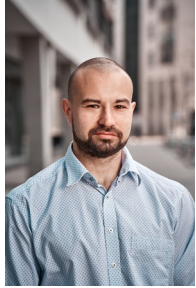
File Edit View Terminal Tabs Help
PetaLinux environment set to '/home/stefing/PetaLinux'
WARNING: /bin/sh is not bash!
bash is PetaLinux recommended shell. Please set your default shell to bash.
WARNING: This is not a supported OS
INFO: Checking free disk space
INFO: Checking installed tools
INFO: Checking installed development libraries
INFO: Checking network and other services
WARNING: No ftp server found - please refer to "/usr/104 2823.1 PetaLinux Tools Documentation Reference
part and solution
stefing@stefing-TinkStation-P350-~/Downloads$ cat /etc/os-release
PRETTY_NAME="Ubuntu 22.04.4 LTS"
NAME="Ubuntu"
VERSION_ID="22.04"
VERSION="22.04.4 LTS (Jammy Jellyfish)"
VERSION_CODENAME=jammy
ID=ubuntu
ID_LIKE=debian
HOME_URL="https://www.ubuntu.com/"
SUPPORT_URL="https://help.ubuntu.com/"
BUG_REPORT_URL="https://bugs.launchpad.net/ubuntu/"
PRIVACY_POLICY_URL="https://www.ubuntu.com/legal/terms-and-policies/privacy-policy"
UBUNTU_CODENAME=jammy
stefing@stefing-TinkStation-P350-~/Downloads$

```

```

~/dev/ttyUSB1 - PUTTY
root@ZCU102:~#
root@ZCU102:~# cat /etc/os-release
PRETTY_NAME="PetaLinux 2023.1+release-50501639 (langdale)"
VERSION_ID="2023.1+release-50501639"
VERSION="2023.1+release-50501639"
PRETTY_NAME="PetaLinux 2023.1+release-50501639 (langdale)"
ID="peta"
ID_LIKE="ubuntu"
root@ZCU102:~#

```



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Thank you for your attention! Questions?

This work has been partly performed in the framework of the CERN-RD50 collaboration.

The measurements leading to these results have been performed at the Test Beam Facility at DESY Hamburg (Germany), a member of the Helmholtz Association (HGF).

The research leading to these results has received funding from the European Union's Horizon Europe research and innovation programme under grant agreement no. 101057511.

