

# Oscillators a basic training



**IQD**

Training material

# Agenda

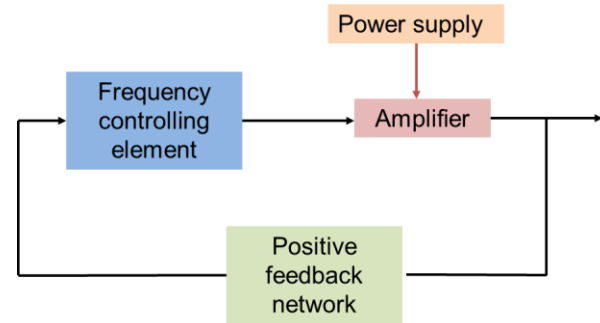
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- i. Intro to Oscillators
  - i. What is an Oscillator?
  - ii. Resonator Types
  - iii. Quartz Oscillator Types
  - iv. Specifying an Oscillator
  - v. Oscillator Noise


# What is an Oscillator?

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- An electronic oscillator can be considered as a device that provides an output waveform which fluctuates between two states in a repetitive, periodic and stable state.
- An oscillator needs two parameters to function:
- A positive feedback mechanism, and a gain greater than one.
  - This gain is known as the Barkhausen criteria:
  - *The loop gain must be at unity (1) or greater*
  - *The feedback loop must have a total phase shift of zero*
- A quartz crystal based oscillator uses the crystal as the frequency controlling element, while additional electronics provide the feedback and positive gain required to sustain oscillation.
- Quartz is the most common resonator used because of its piezoelectric property, which has very high Q. It also has a long history of technical development with well-understood parameters, which allow predictable behavior.



# Resonator Types

Resonator Types	Frequency Accuracy	Cost Indication	Frequency	Resonator Principle
LC/RC Oscillators	Stability $\pm 10\%$	\$0.05	1Hz to 500kHz	Controlled charge/discharge of capacitor via a damping mechanism
Ceramic Resonators	Stability $\pm 1000\text{ppm}$ to $\pm 5000\text{ppm}$ (0.1% to 0.5%)	\$0.05 to \$0.2	3MHz to 70MHz	Piezo coupling to mechanical resonance of shaped lead zirconate titanate (PZT)
Commodity Quartz Oscillators	Stability $\pm 0.5\text{ppm}$ to $\pm 100\text{ppm}$	\$0.1 to \$1	32.768kHz, 1MHz to 800MHz	Piezo coupling to mechanical resonance of shaped quartz 
MEMS Oscillators	Stability $\pm 0.5\text{ppb}$ to $\pm 50\text{ppm}$	\$1 to \$10	32.768kHz, 1MHz to 800MHz	Piezo coupling to mechanical resonance of shaped silicon
High Stability Quartz Oscillators (OCXO's)	Stability $\pm 0.2\text{ppb}$ to $\pm 50\text{ppb}$ ( $\pm 0.0002\text{ppm}$ to 0.05ppm)	\$100 to \$1k	10MHz to 100MHz	Piezo coupling to mechanical resonance of shaped quartz
Rubidium Oscillators	Stability $\pm 0.02\text{ppb}$ to $\pm 0.05\text{ppb}$ Ageing $\pm 5\text{E}-12$ in 24hours	\$500 to \$5k	6.834,682,610,904 GHz (coupled to Quartz to give 10MHz)	Microwave control loop inducing hyperfine transition of electrons in Rubidium-87 atoms
Cesium Clocks	Ageing $\pm 1\text{E}-12$ to $\pm 5\text{E}-13$	\$50k to \$100k	9.192,631,770 GHz (coupled to Quartz to give 10MHz)	Microwave control loop inducing hyperfine ground states of Cesium-133 atoms. Note: Current definition of the SI unit of second
Hydrogen Maser	Ageing $\pm 3\text{E}-16$ in 24hours	\$250k to \$500k	1.420,405,751,77 GHz (coupled to Quartz to give 10MHz)	Microwave control loop inducing hyperfine ground states of Hydrogen atoms
Optical Clocks	Ageing 1s in 15 billion years	Development only	THz	Optical Frequency control loop of various types

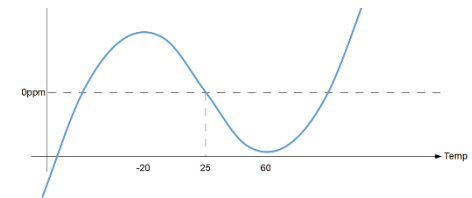
PCB mountable devices

Stand-alone units

# Quartz Oscillator types

Type	Device name	Description	Accuracy	Power
SPXO	Simple Packaged Crystal Oscillator	An oscillator based on the characteristics of AT-cut quartz but with no frequency adjustment or temperature compensation.	$\pm 10\text{ppm}$ to $\pm 100\text{ppm}$	50mW
VCXO	Voltage Controlled Crystal Oscillator	As SPXO but with ability to adjust the output frequency with an external control voltage.	$\pm 10\text{ppm}$ to $\pm 100\text{ppm}$	50mW
TCXO	Temperature Compensated Crystal Oscillator	As SPXO but with built-in temperature compensation circuitry to adjust for deviation over temperature due to AT-cut quartz characteristics.	$\pm 50\text{ppb}$ to $\pm 5\text{ppm}$	50mW
OCXO	Oven Controlled Crystal Oscillator	Oscillator that has a built-in heater to hold the SC-cut quartz crystal at a temperature near its inflection point where the frequency/temperature characteristic is flattest to achieve optimum frequency accuracy.	$\pm 1\text{ppb}$ to $\pm 50\text{ppb}$	1W to 5W
RBXO	Rubidium Controlled Crystal Oscillator	Oscillator consists of a rubidium 'physics package' that is locked to an OCXO. The OCXO provides the output signal while under control of the rubidium section.	$\pm 0.5\text{ppb}$	5W

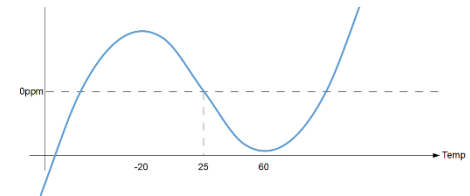
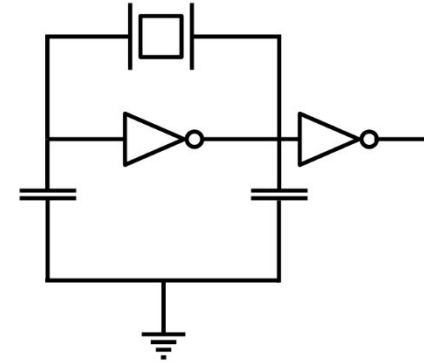
**XTAL**



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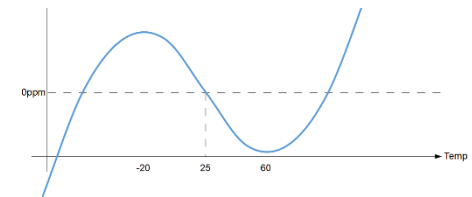
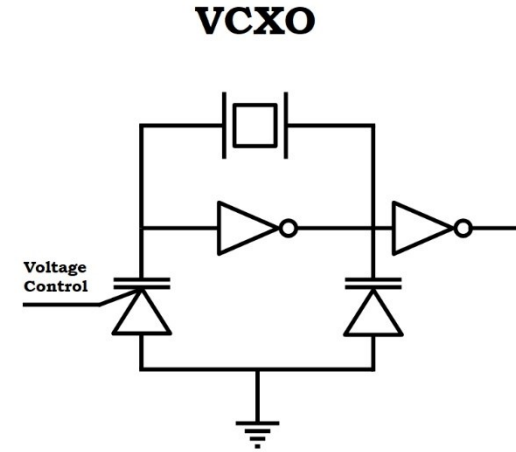
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## SPXO



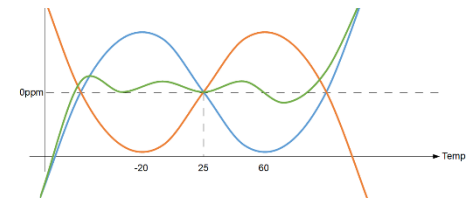
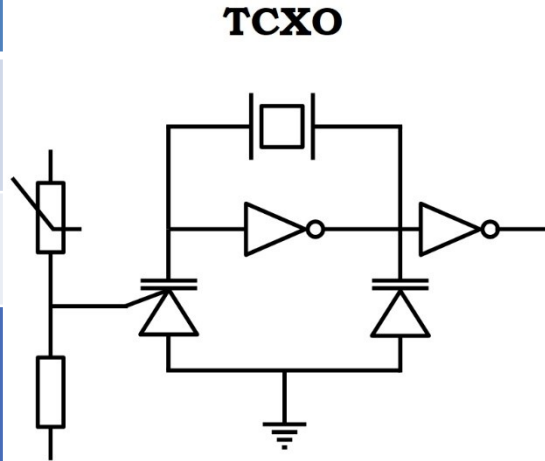
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# Quartz Oscillator types

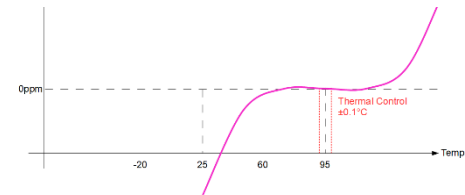
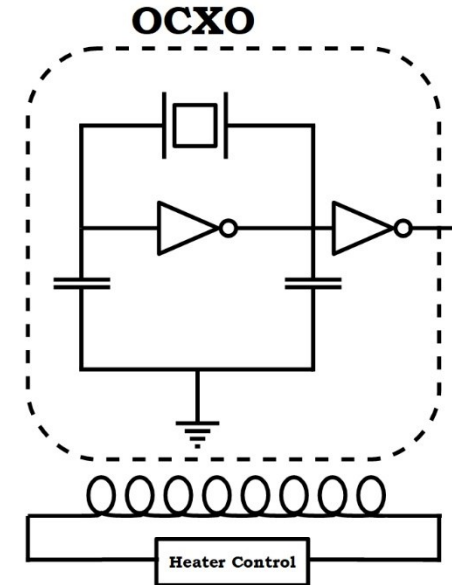
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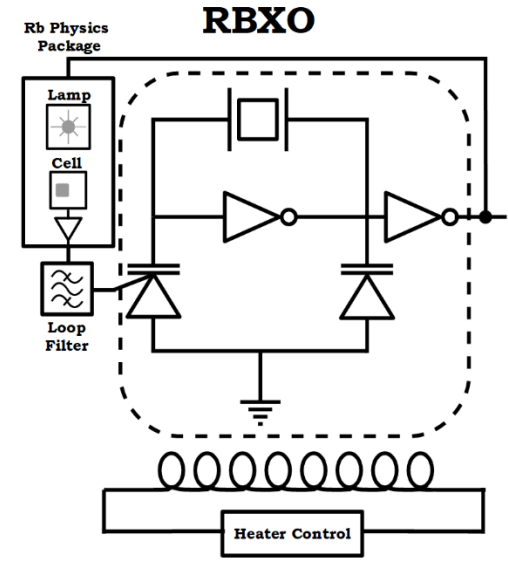
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# Specifying an Oscillator : Basics

The basic setup of an oscillator requirement will need to be defined

Value	Description	Example
Frequency	Low cost commodity oscillators are available in a wide range of frequencies. High performance oscillators may only be available in a few frequencies.	10.0MHz
Supply Voltage	Oscillators need stable power rails, as noise on the power rail can translate to frequency modulation on the output. Ovenised oscillators will need high power requirements and often higher voltage levels.	12V
Power	Warm up: For Ovenised oscillators, this may be very high for a brief period. It may be necessary to manage power delivery during warm up. Steady state: Power requirements during normal operation.	Warm up: @3.3V 800mA max 5min max Steady State: @3.3V 25°C 350mA max
Output	The output logic of the oscillator required for compatibility with other circuitry.	CMOS, Sine, LVPECL, LVDS
Frequency Tolerance	A measure of the maximum frequency accuracy at room temperature, normally 25°C (this can be removed using the pulling function).	±0.05ppb @ 25°C
Frequency Stability	A measure of the maximum frequency deviation when varied over the operating temperature range and relative to the tolerance value.	±0.3 ppb typical
Temperature Range	The temperature range over which the frequency stability figure is guaranteed.	-40 to 85°C
Pulling	An ability to change the frequency of the output by controlling an input, either via an analogue DC voltage level, or a digital input.	Pulling ±2ppb min Control Voltage 2.5V ±2.5V
Digital Control	Some digital control line functions may be available with the oscillator.	Enable/Disable of RF Input pin Oscillator Lock Output pin

# Specifying an Oscillator : Basics

Parameters of oscillators used in various WR devices

Value	WR Node (BabyWR)	WR Switch v3 / WR Node (SPEC)	WR Switch v4	Low Jitter Daughterboard
Frequency	125MHz	25 MHz	10 MHz	20 MHz
Supply Voltage	2.5V	3.0V	3.3V	
Power	Max 62mA @ 2.5V	Max 2mA @ 3.0V	Max 10mA @ 3.3V	
Output	LVC MOS	Sine, DC block, AC coupled	LVC MOS	
Frequency Tolerance				
Frequency Stability	±50ppb	±2.5ppm	±50ppb	
Temperature Range	-20 to +70°C	-30 to +70°C	0 to +70°C	
Pulling	±25ppm	±12ppm	±10ppm	
Digital Control	I2C, Output Enable	N/A	N/A	

# Specifying an Oscillator : Advanced

As the frequency stability specification increases, the effect of various environmental changes become more significant

Value	Description	Example
Ageing	Change of frequency over longer time periods.	Ageing (after 30days): ±0.005ppb max/day ±0.05ppb max/month ±0.5ppb max/year
Load Co-Efficient	Change of frequency caused by variations on the output load.	Load Variation (±5% change): ±5ppb max
★ Pushing	A measure of the slight change in frequency caused by variations in the supply voltage.	Supply Voltage Variation (±5% change): ±5ppb max
★ Shock/ Vibration/ Acceleration	Definition of the effect of physical motion on the oscillator. These figures are often statements of survivability of the oscillator, not a measure of the effect on the frequency during the effect.	Mechanical Shock: IEC 60068-2-27, Test Ea: Acceleration of 50G peak amplitude for 11ms duration
Retrace	A definition of the effect of power cycling the oscillator. How close will the frequency be compared to that before the power cycle?	Retrace (24hrs on, 1 hour off, 1 hour on): ±0.02ppb typ
★ Gravitational Force	Gravitational pull causes a change to the frequency of the oscillator, therefore oscillator orientation must be controlled.	±2E-12/g (Ref 2g tip over test)
★ Magnetic Field Sensitivity	Magnetic field changes induce a change in frequency of the oscillator, therefore movements of items causing changes to the magnetic field must be controlled.	±2E-11/Gauss

★ These points are relevant even in a stable system. The effect of the other points should be removed after power up, stabilisation and lock to external source.

# Specifying an oscillator : Noise

The primary function of an oscillator is to create a stable frequency. When all else is held constant, noise is a measure of the remaining instability of the signal.

Value	Description	Example
Phase Noise	Frequency domain measurement quantifying the power of frequencies at offsets from the main mode (carrier frequency).	Phase Noise (typ): -108dBc/Hz @ 1Hz -134dBc/Hz @ 10Hz -152dBc/Hz @ 100Hz -155dBc/Hz @ 1kHz -158dBc/Hz @ 10kHz -157dBc/Hz @ 100kHz
Spurious	Particularly found on oscillators containing digital components, this quantifies the power ratio of the main mode to any frequencies seen on the output which are not harmonics of the main mode	Spurious: -80dBc max
Jitter	Time domain measurement of the deviation from a perfect waveform.	Period Jitter (typ @ 10000 cycles @ 3.3V): 1.15ps RMS, 9.6ps pk-pk @ 25MHz 1.02ps RMS, 8.1ps pk-pk @ 50MHz
Short term Stability (ADEV)	Time domain measurement of the average deviation from a perfect wave at specific averaging time windows.	Short Term Stability (ADEV) typical: 1s 5.5E-11 10s 7.1E-12 100s 7.5E-12

# Oscillator Noise: Phase Noise

Measurement of power at offsets from the carrier frequency

The output is similar to that of a spectrum analyser.

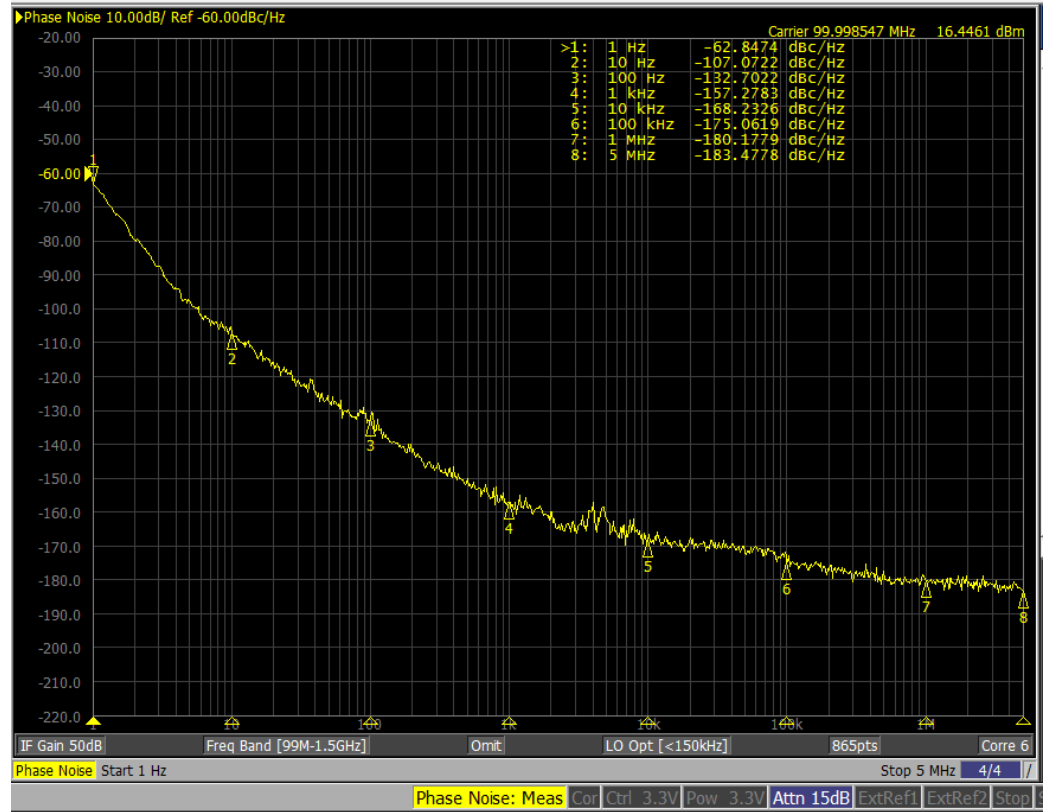
Specialised equipment is used to measure phase noise, >\$100kUSD

Its getting quicker but accurate phase noise measurements can still take a long time to make (5 mins to 1 hour)

Power supply, cabling, test fixture, screening will all make a very big difference to the measurement.

The power of the noise is concentrated at the carrier and reduces to a noise floor.

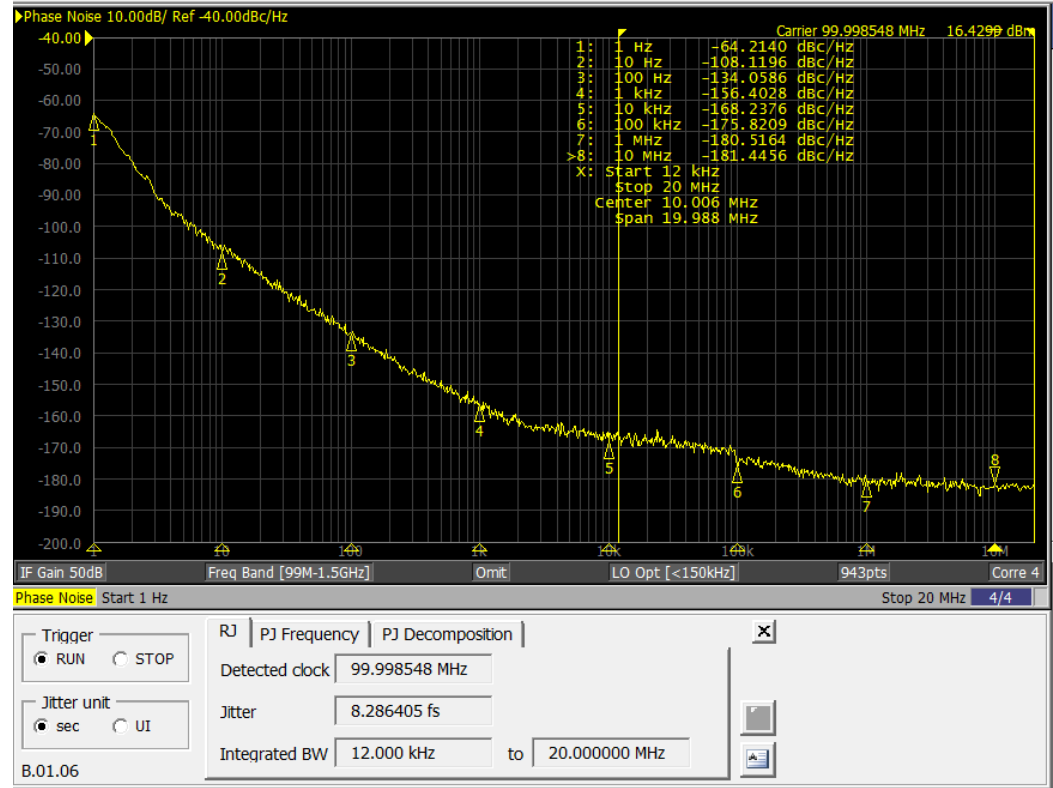
Close-in noise is attributed to the resonator.



# Oscillator Noise: Phase Jitter

Phase jitter is calculated from the area under the PN Plot within some band width

12kHz to 20MHz: 8.3fs

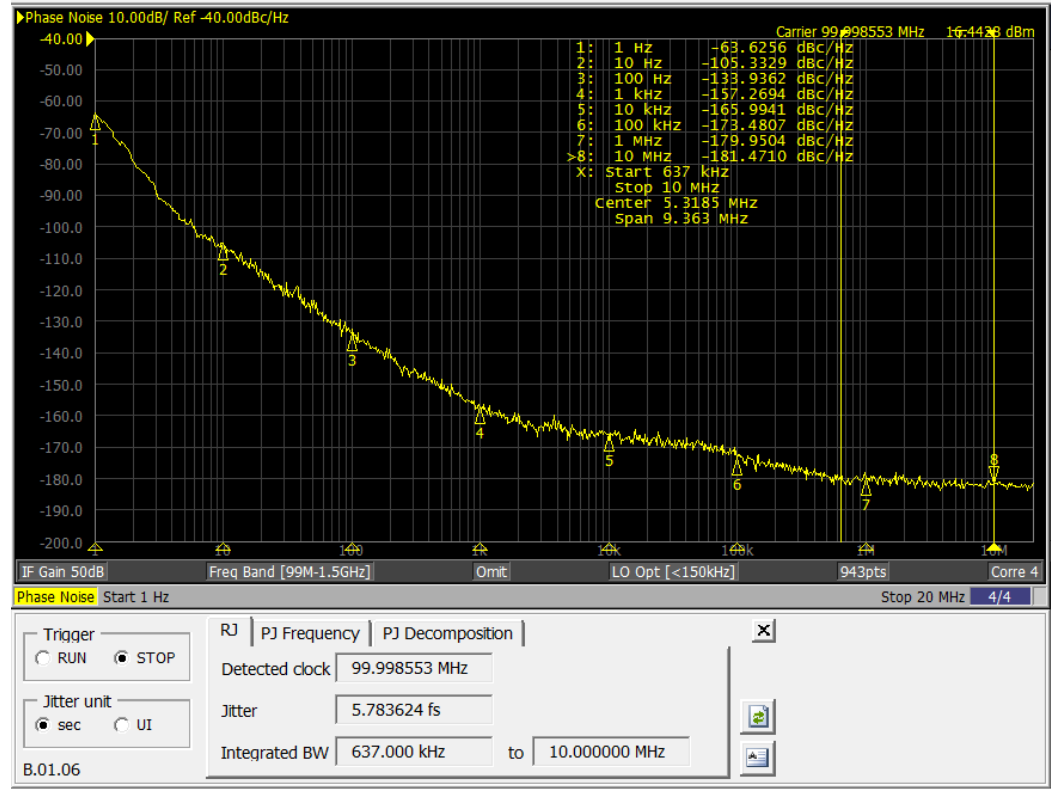




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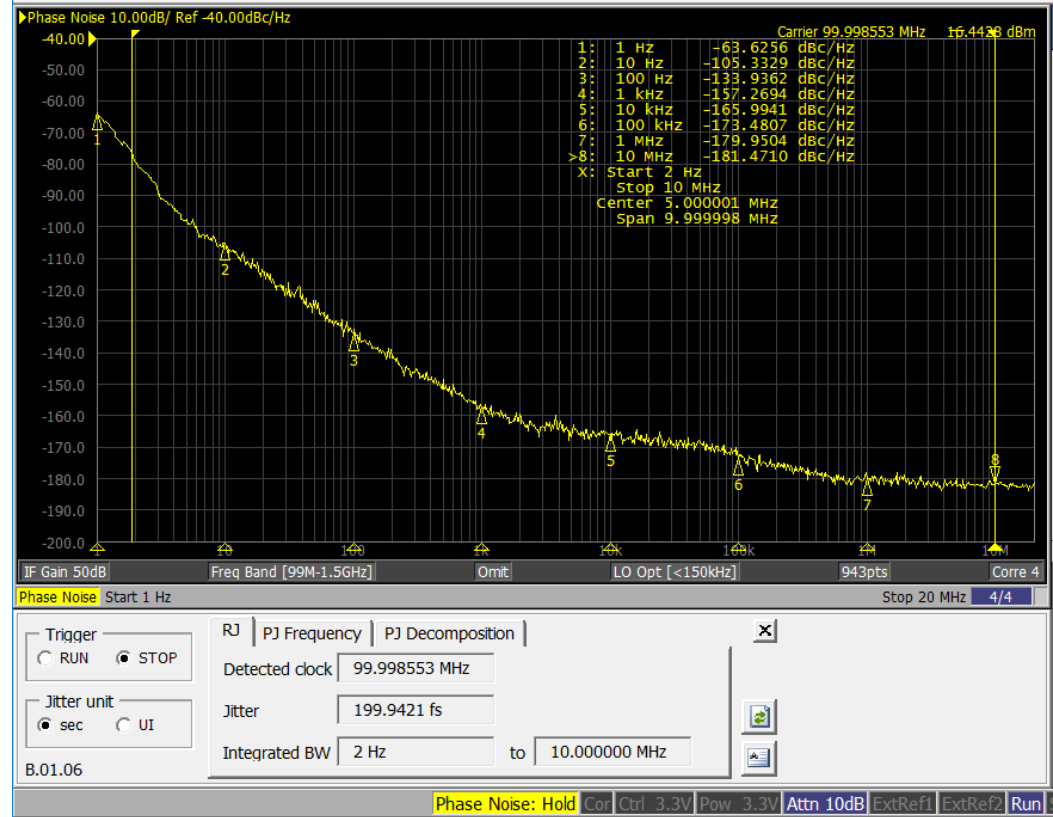
637kHz to 10MHz: 5.8fs



# Oscillator Noise: Phase Jitter

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2Hz to 10MHz: 200fs



# Oscillator Noise: Phase Jitter

Phase jitter is calculated from the area under the PN Plot within some band width

12kHz to 20MHz: 8.3fs

637kHz to 10MHz: 5.8fs

2Hz to 10MHz: 200fs

So BW is important to check

12kHz to 20MHz used as a standard for comparison. But perhaps not relevant for your application

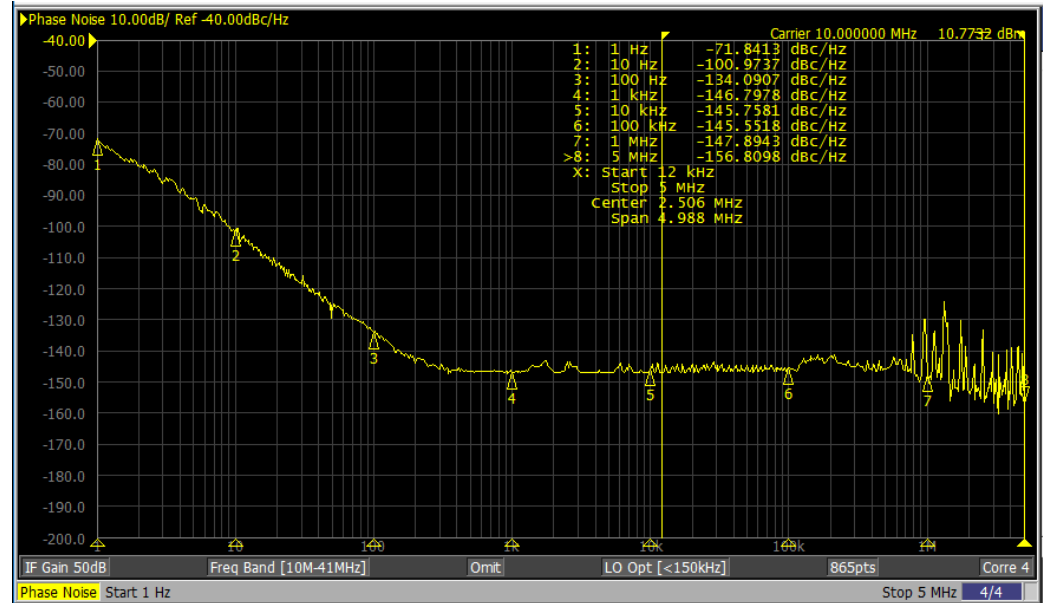
Application	Data rate	Bandwidth
10/100MB Ethernet	125MBPS	20kHz to 20MHz
Gb ethernet	1.25Gbps	637kHz to 10MHz
10G Ethernet	10.3225Gbps	637kHz to 20MHz
100G Ethernet	4x25Gbps	1.875 to 20MHz
XAUI	3.125Gbps	1.875 to 10MHz
Fiber Channel	1.0625Gbps	637kHz to 10MHz
Fiber Channel	2.125Gbps	1.275 to 10MHz
Fiber Channel	4.25Gbps	2.55 to 10MHz
SAS/SATA	6Gbps	600kHz to 20MHz
SONET OC-3	155Mbps	12kHz to 20MHz
SONET OC-12	622Mbps	12kHz to 20MHz
SONET OC-48	2.48Gbps	12kHz to 20MHz

# Oscillator Noise: Phase Noise Spurious

Complex systems, especially those including digital systems can show spurious peaks on the phase noise plot.

Designers attempted to move this noise outside the bandwidth of interest.

Normally quantified as being the dB difference between the peak of the spurious vs the carrier frequency e.g.  
Spurious frequency: 80dBc max



# Oscillator Noise: Jitter

Time domain measurement normally made on an oscilloscope.

Must have high bandwidth high sample rate scope.

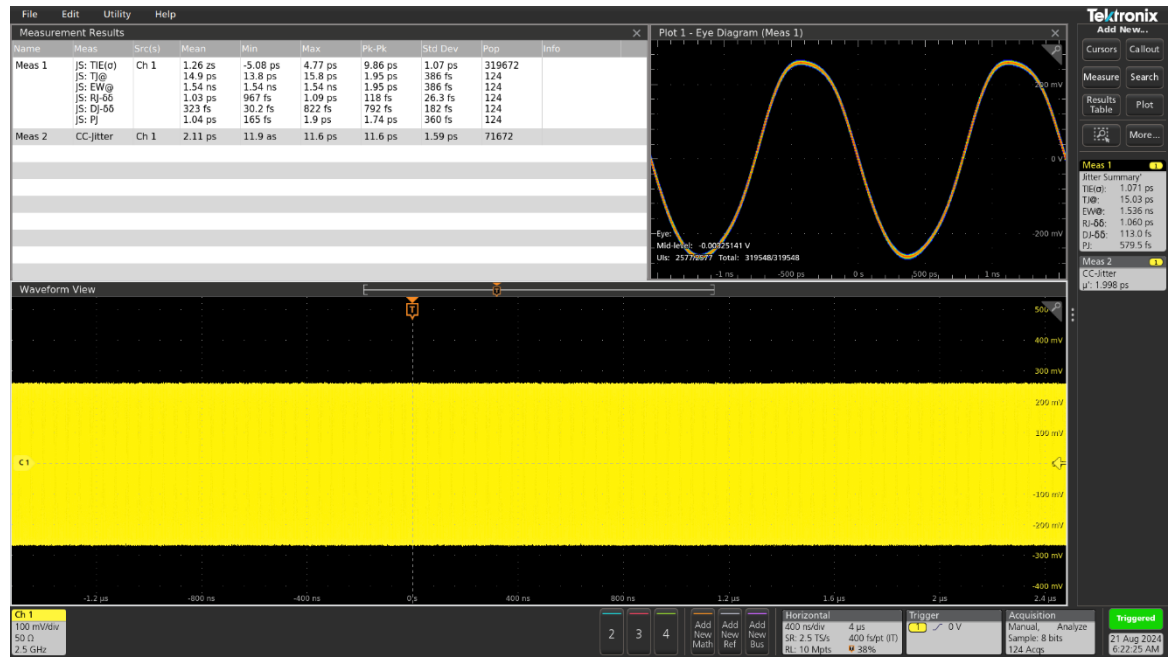
(Watch out for default settings as this may be a reduced sample rate.)

Random jitter: unpredictable electronic noise. Typically follows a normal distribution due to being caused by thermal noise in an electrical circuit.

Deterministic jitter: jitter that is predictable and reproducible. Has a known non-normal distribution.

Total Jitter: the sum of deterministic jitter plus random jitter

All values are calculated and discussed in statistical terms mean, pk-pk, Standard Dev etc



Jitter contributes to a total bit error rate calculation. A good oscillator will be a small contribution to the calculation

# Oscillator Noise: Allan Deviation, ADEV

Created by David Allan

A derivative of Time Interval Error

ADEV is the log-log plot of the square root of Allan Variance, AVAR

Mathematically complex to describe

Allan variance is intended to estimate stability due to noise processes and not that of systematic errors or imperfections such as frequency drift or temperature effects.

Measured on a counter or specialise instrument  
Must be gap free, i.e. no gap between samples

(note measurements of  $0.5E-11$  @ 1sec Tau is the 20ps limit of most equipment)

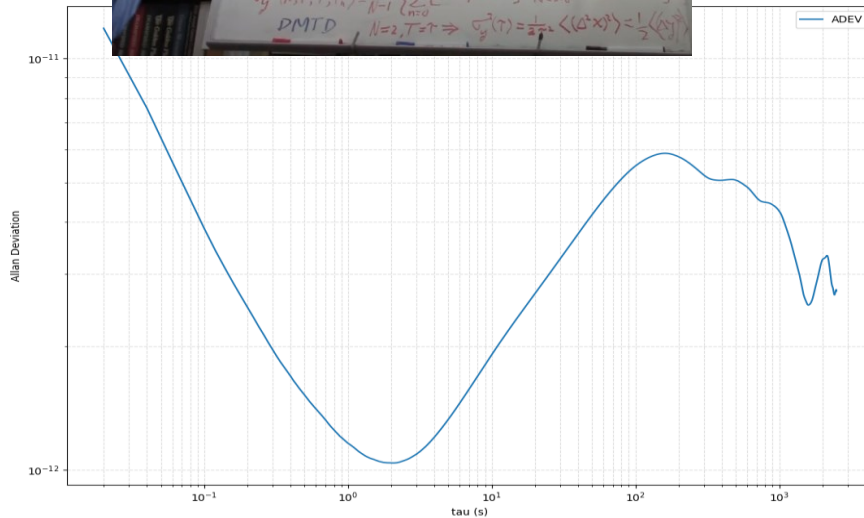
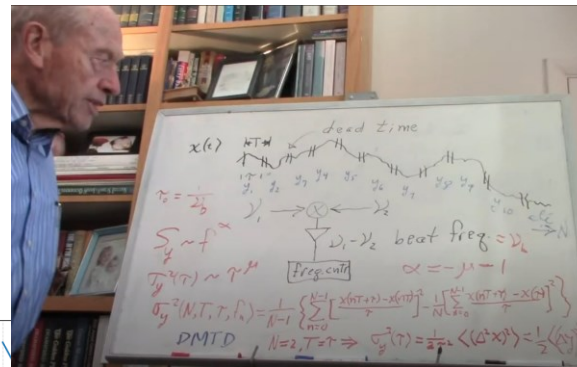
The plot shows us, from second to second how much will the frequency change, then for 10s, then 100s...

This plot shows:

$4E-11$  @ 0.1sec tau

$1E-12$  @ 1sec tau

$2E-11$  @ 10sec tau



# Further reading

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Open source information with more details on oscillators can be found here:

John R. Vig Quartz Crystal Resonators and Oscillators for Frequency Control and Timing Applications - A Tutorial  
<https://ieeefrequency.org/technical-committees/frequency-control/educational-resources>

Renesas: Understanding Jitter Units

<https://www.renesas.com/en/document/apn/815-understanding-jitter-units>

<https://www.iqdfrequencyproducts.com/en/support/document-library> IQD Phase Noise to Jitter Conversion

David Allan - Whiteboard Lesson

<https://www.youtube.com/watch?v=CGh8n8fyVhk>

Quartz Crystal for Electrical Circuits : Raymond A.Heising

Handbook of Quartz Crystal Devices : David Salt