



Integration and System Qualification of the ALICE Silicon Pixel Detector

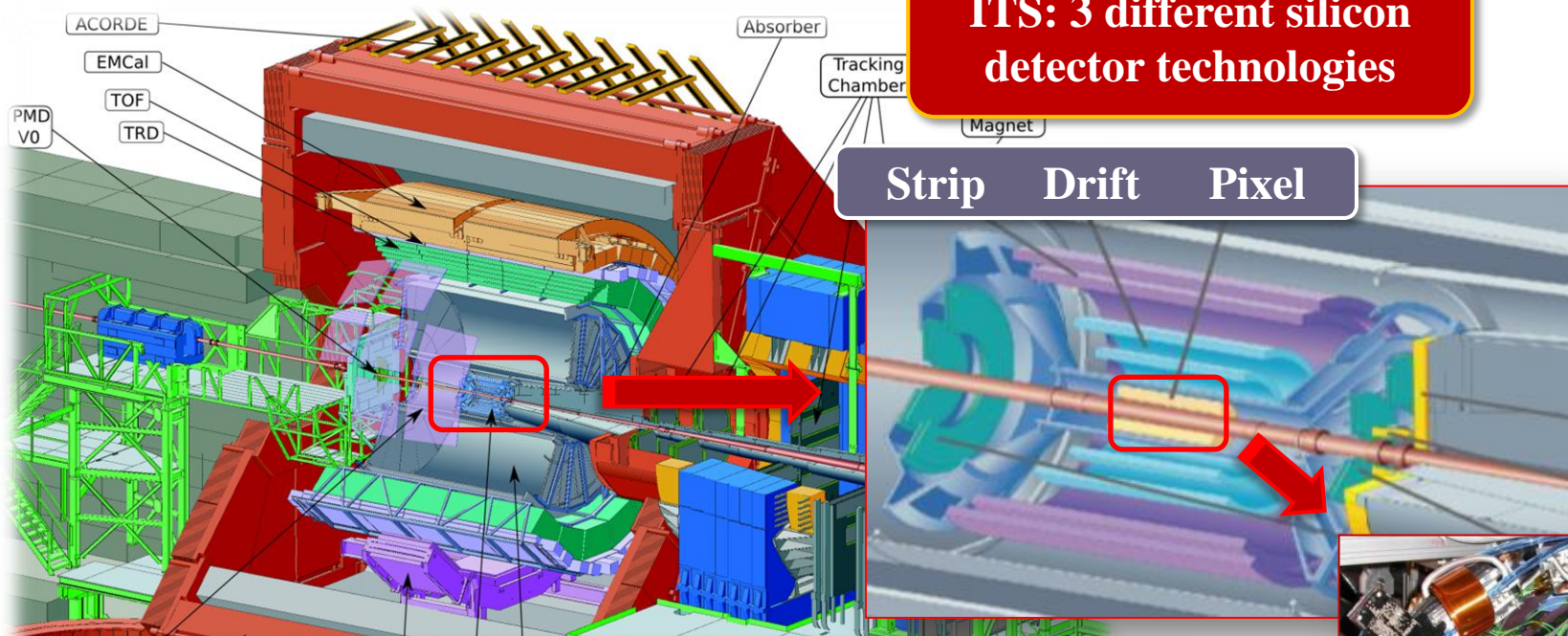


R. Santoro

On behalf of the SPD collaboration in the ALICE experiment at LHC

- ▶ Silicon Pixel Detector in the ALICE experiment
- ▶ Mechanical accuracy
- ▶ Pre-commissioning
- ▶ Installation
- ▶ Optical link synchronization
- ▶ Monitor and debug tools

SPD in the ALICE experiment



ITS: 3 different silicon detector technologies

Strip Drift Pixel

Pixel

beam pipe

The SPD contribution in ALICE

- ▶ Secondary vertex reconstruction (c, b decays)
 - ▶ Good track impact parameter resolution ($< 60 \mu\text{m}$ (r_ϕ) for $p_t > 1 \text{ GeV}/c$ in Pb-Pb)
- ▶ Improve primary vertex reconstruction and momentum resolution
- ▶ Prompt L0 trigger capability ($< 800 \text{ ns}$)
- ▶ Measurements of charged particle pseudorapidity distribution
 - ▶ First Physics measurement both in p-p and Pb-Pb



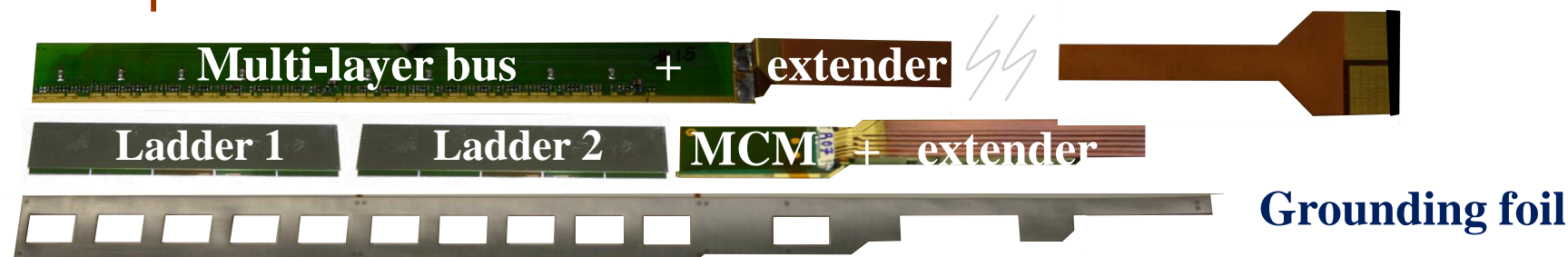
Mechanical accuracy



Basic module assembly: Half-stave



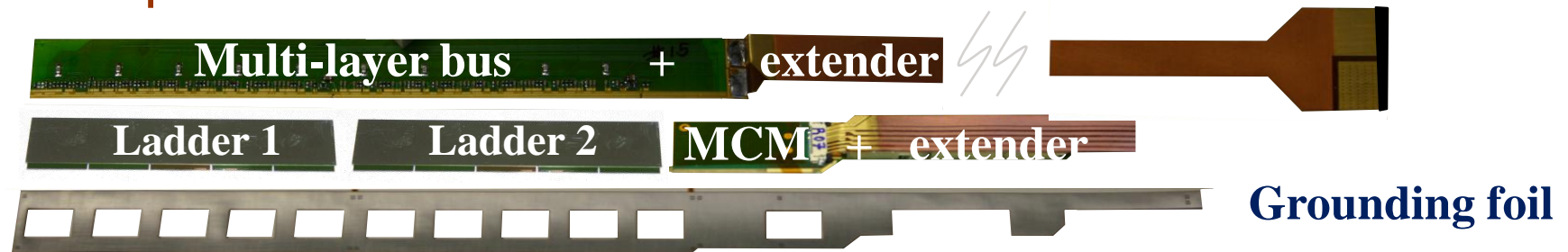
Components



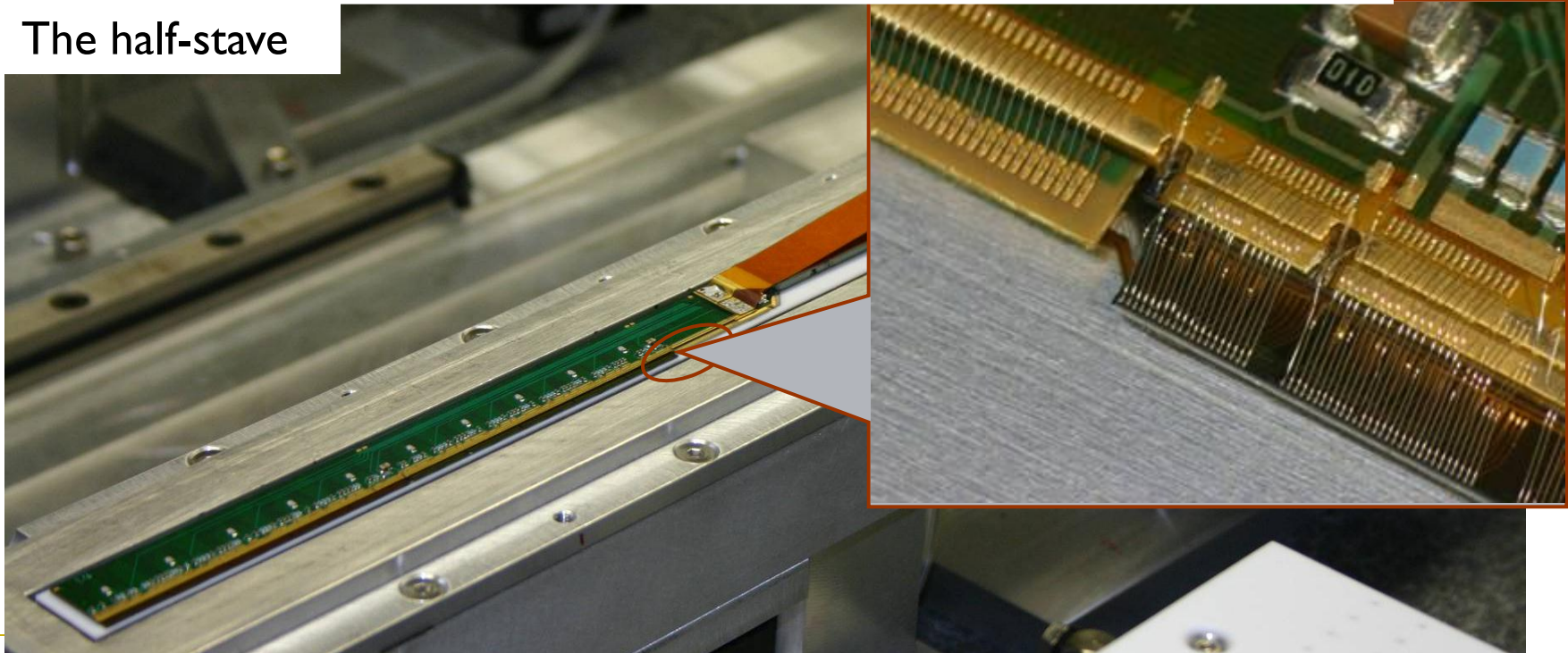
- ▶ Grounding foil: aluminum-polyimide foil (25 + 50 μm thick) with 11 windows to improve the thermal coupling between the backside of the FE chips and the cooling tube
- ▶ 2 hybrid pixel modules: ladders
 - ▶ A p+n silicon sensor matrix 200 μm thick with 40960 pixels arranged in 256 rows and 160 columns
 - ▶ 5 FE chips Flip-chip bonded to the sensor through Sn-Pb bumps
 - ▶ The pixel cell has the dimensions of 50 μm (r ϕ) x 425 μm (z)
- ▶ MCM: Multi Chip Module to configure and read-out the half-stave
- ▶ Pixel Bus: aluminum-polyimide multi-layer bus to connect the MCM and FE chip
 - ▶ More than 1,000 wire bonding for each half-stave

Basic module assembly: Half-stave

Components

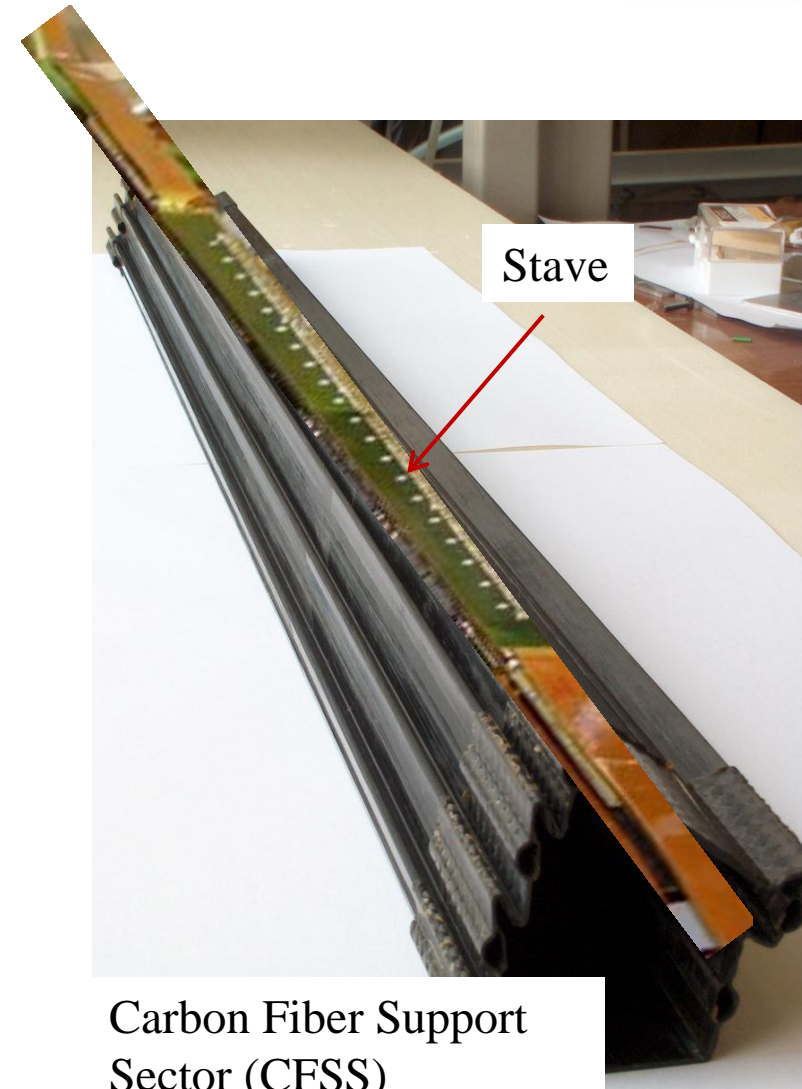
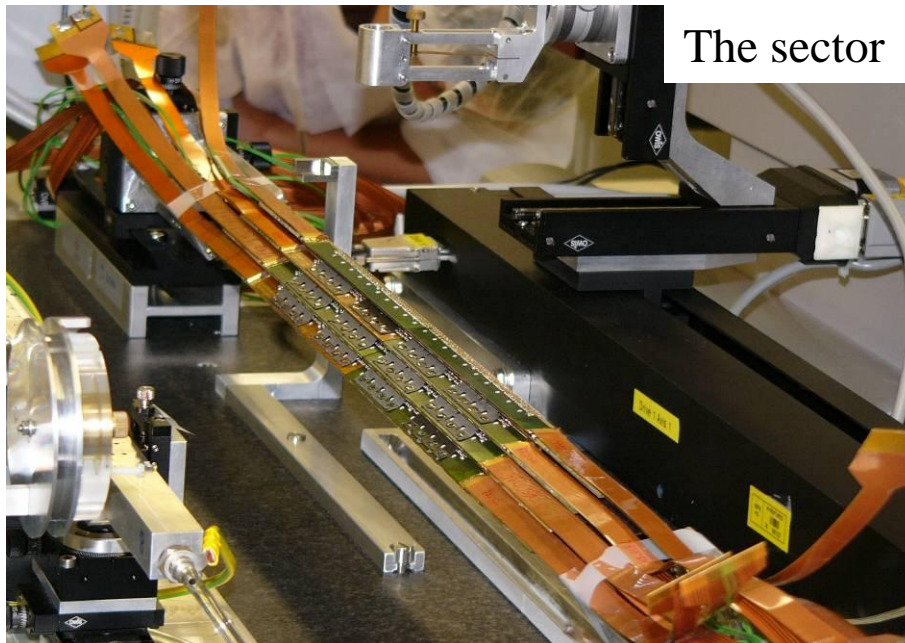


The half-stave



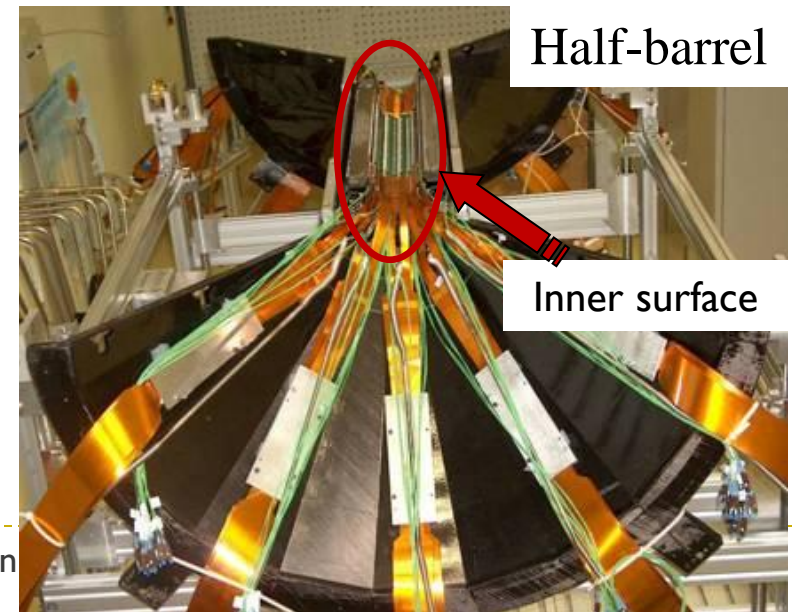
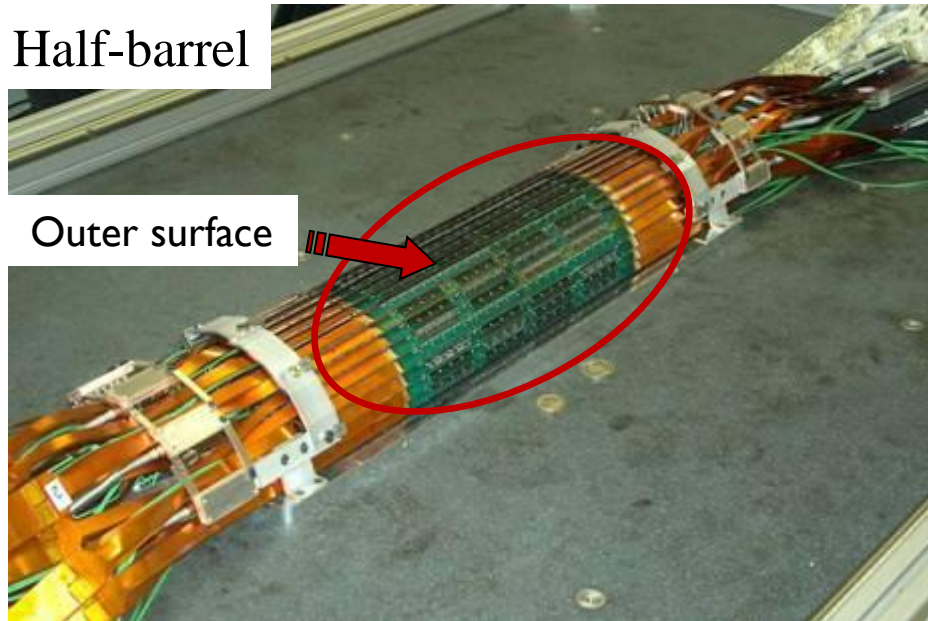
Sector

- ▶ 2 half-staves are coupled to form a stave
 - ▶ The sensitive area is in the center, while the services are at the 2 edges
- ▶ The staves are mounted onto the low-mass carbon fiber support (sector) in the upper and bottom part to form the 2 layer-structure



Half - barrels

- ▶ 5 sectors are joint one close to the other to form the half-barrel
- ▶ The 2 half-barrels are mounted face-to-face around the beam-pipe



Mechanical accuracy



- ▶ The ladders positioning in the half-stave has the accuracy of the order of few microns
- ▶ The stave positioning onto the sector has the accuracy of the order of tenths of microns
- ▶ The sectors were joint one close to the other in the half-barrel with the accuracy of the order of hundred microns
- ▶ The SPD positioning around the beam – pipe is of the order of few hundred of microns
- ▶ No survey was done at the end

Is this enough for the physics?

- ▶ Alignment:
 - ▶ The survey measurement is an important input for the alignment algorithm
 - ▶ Although, using the estimated mechanical accuracy as input, we aligned the detector within the expectation
- ▶ Simulation:
 - ▶ The description and the alignment of the passive components has to be very accurate. The transport code is unpredictable if you superimpose two materials in the same region
 - ▶ We experienced this problem which still has to be solved
 - ▶ Temporary solution adopted in ALICE: simulate collision with a perfectly aligned geometry and reconstruct the events with the residual misalignment geometry



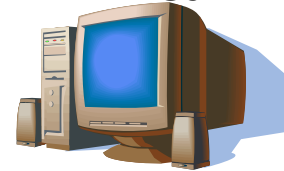
System pre-commissioning



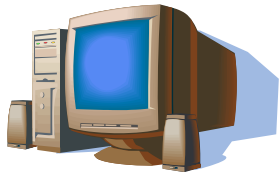
Pre-commissioning (I)

Test performed using the final readout chain, power supplies, DCS system, cooling system, cables, interlock ...

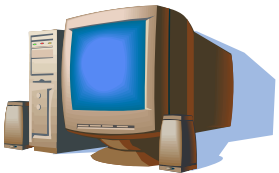
FE-DCS



On-line/Off-line



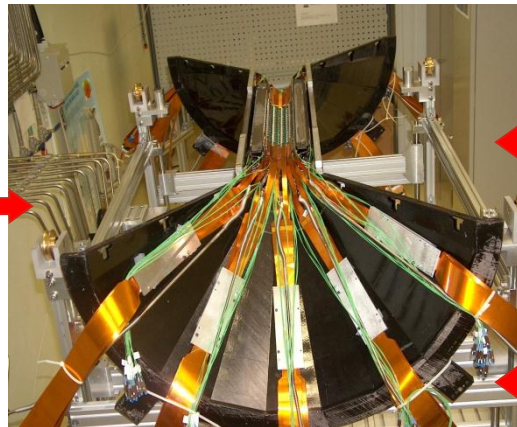
DAQ



Off-detector
electronic and
trigger



Half Barrel



Cooling system

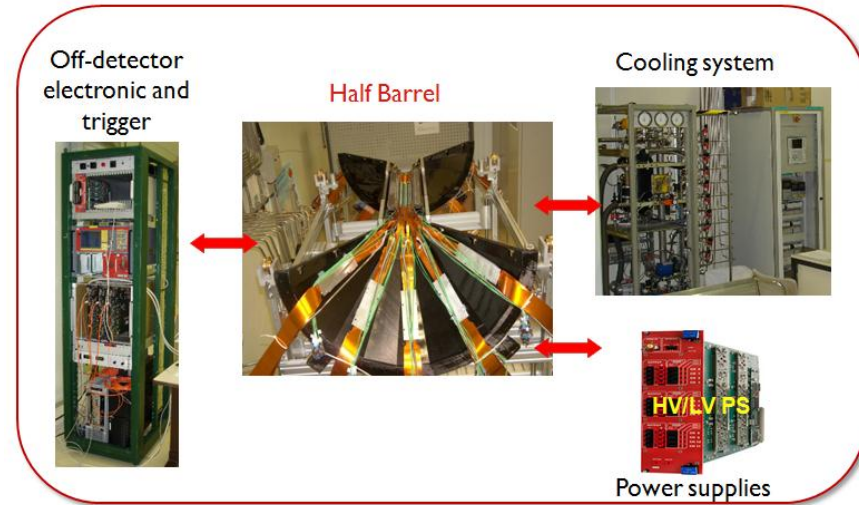


Power supplies

Pre-commissioning (II)

This is the first opportunity to commissioning the full system

- ▶ It is a crucial task:
 - ▶ You have to run the system by remote as in the experiment
 - ▶ You have to be sure that all the safety procedures (i.e. interlock) behave properly
 - ▶ The system has to be characterized and the informations stored in the construction DB
 - ▶ Everybody in the collaboration wants prompt feedback!!!



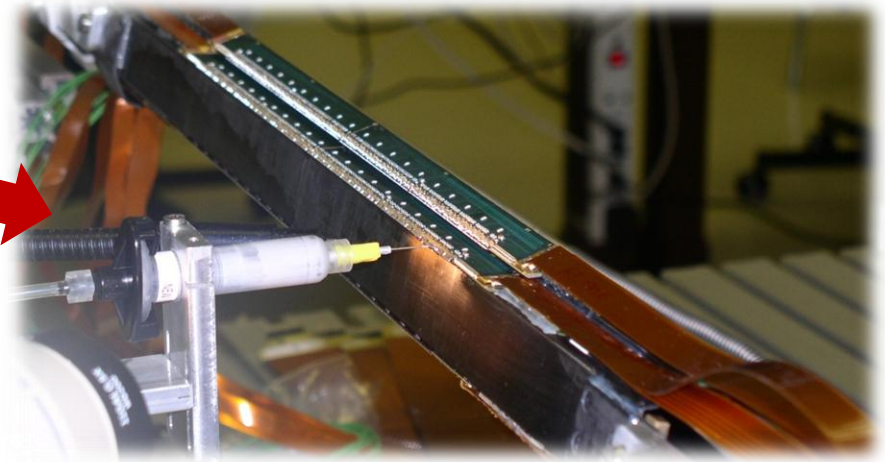
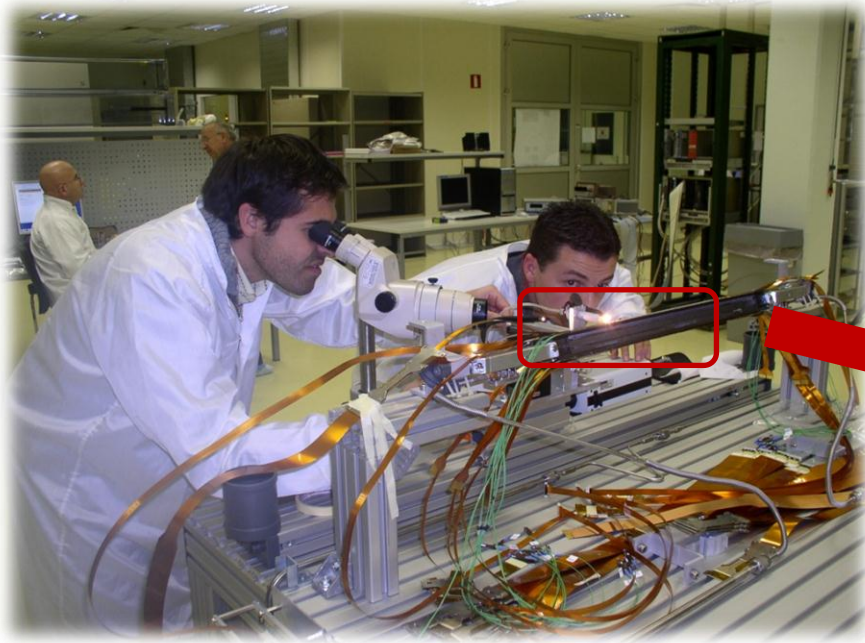
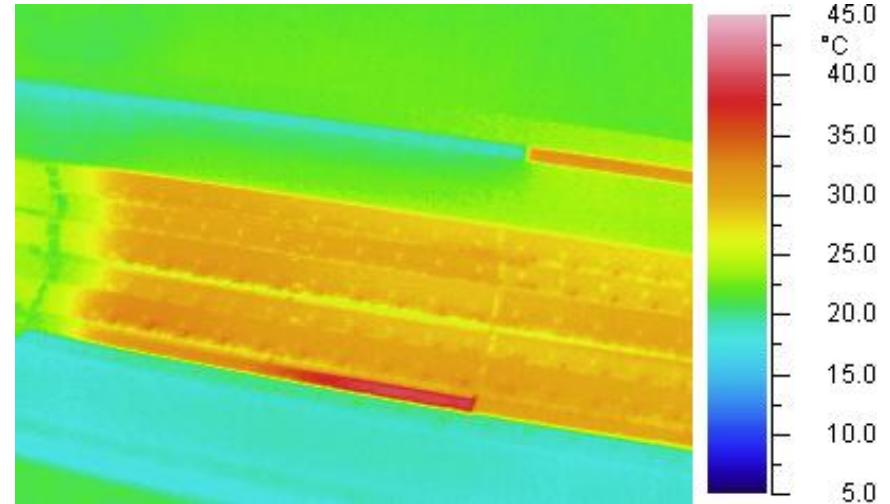
... but it is still better than the experiment because you have access to the hardware

- ▶ ... and this is extremely useful to:
 - ▶ Debug the software and the integration
 - ▶ Tune the monitoring and archival tools (voltages, current and temperature measurements)
 - ▶ Fix the number convention (i.e. software-hardware module correspondence)
 - ▶ ... and in case of small accident ... there is still something that can be done!!!



... one example

- ▶ We measured a poor thermal contact which caused higher temperature in one half-stave ...
- ▶ We decided to operate surgically the stave instead of rework the full sector

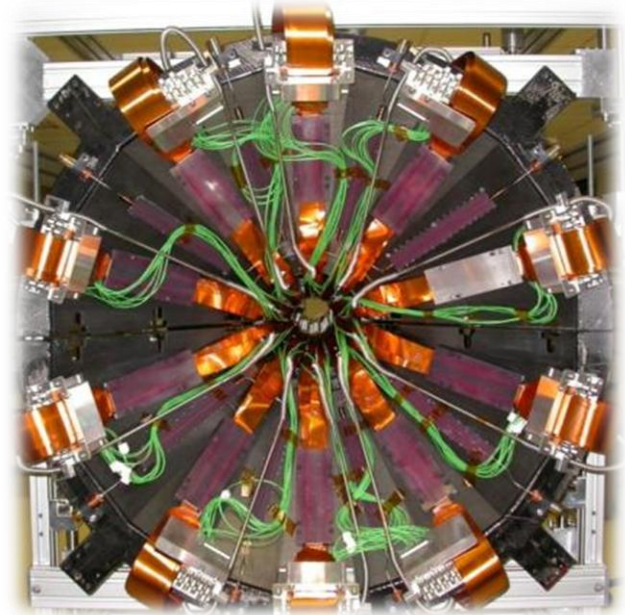




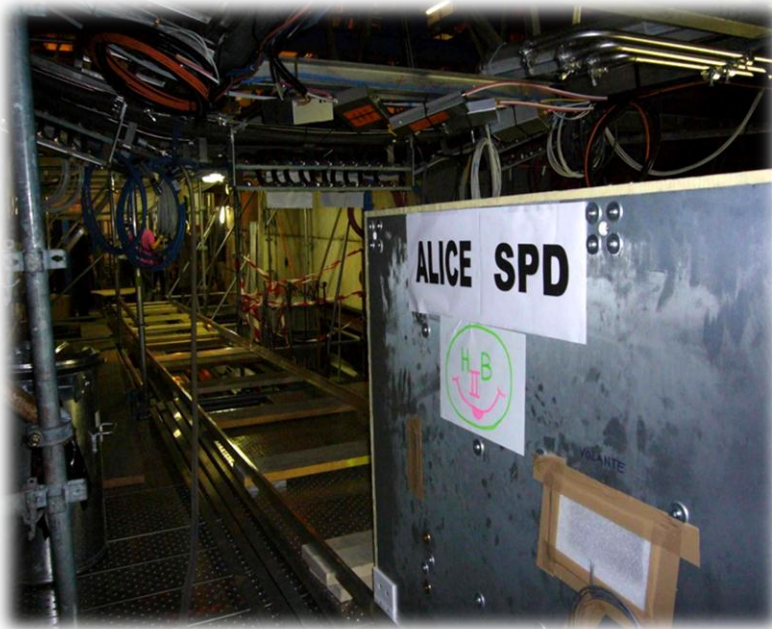
Mechanical integration



Integration in the Department Silicon Facility

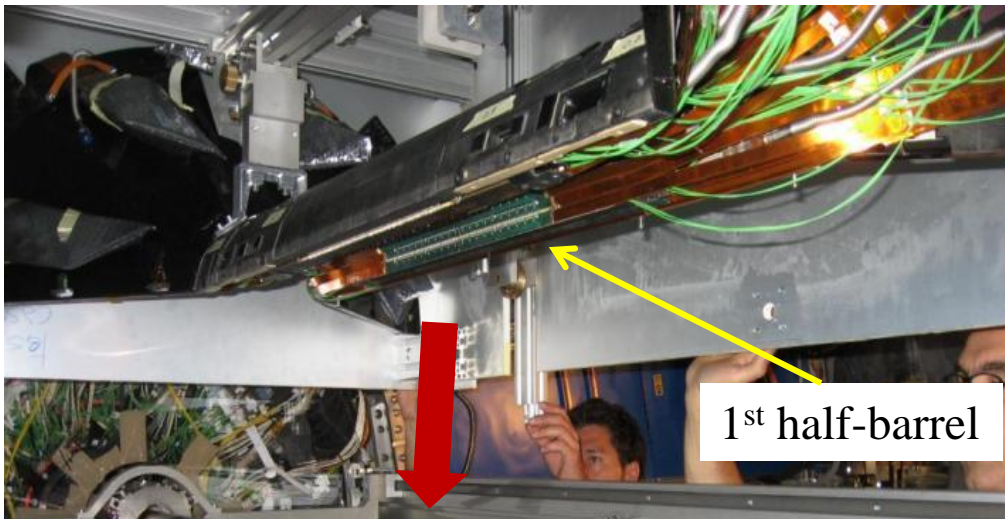


The travel inside the heart of ALICE



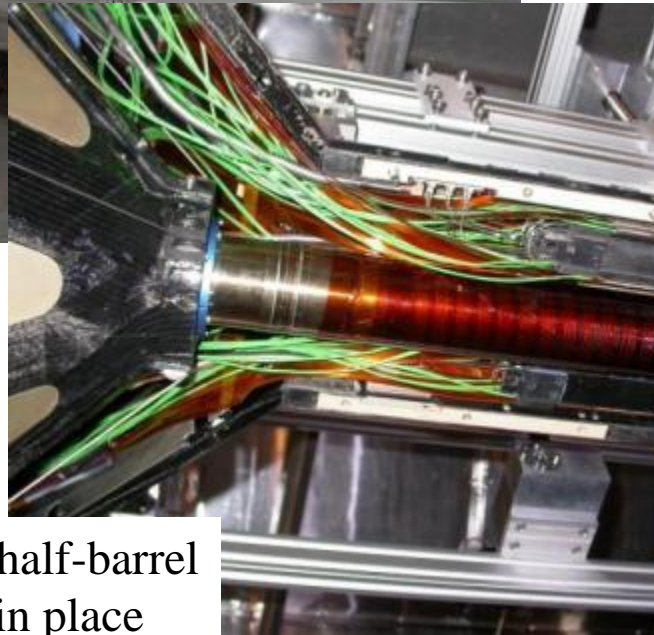
Installation: ...for the press (I)

SPD Internal mean radius ≈ 3.9 cm
Beam pipe radius ≈ 3 cm

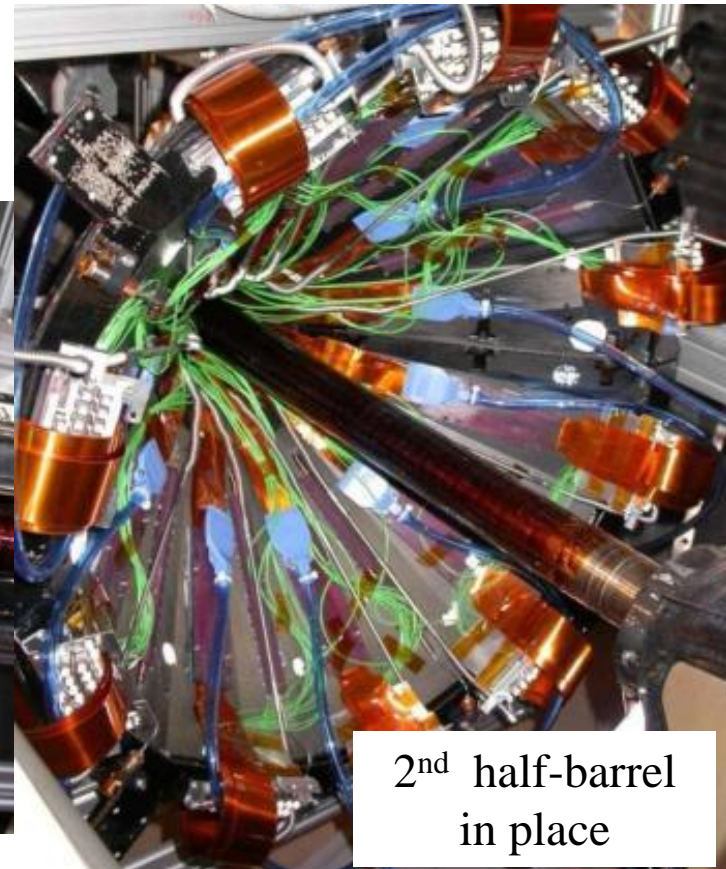


1st half-barrel

Beryllium Beam pipe



1st half-barrel
in place



2nd half-barrel
in place

Installation: ...for the press (II)

SPD fully connected
on side C

SDD + SSD

SDD+SSD moved over the
SPD to form the ITS

ITS fully connected
on side C

TPC

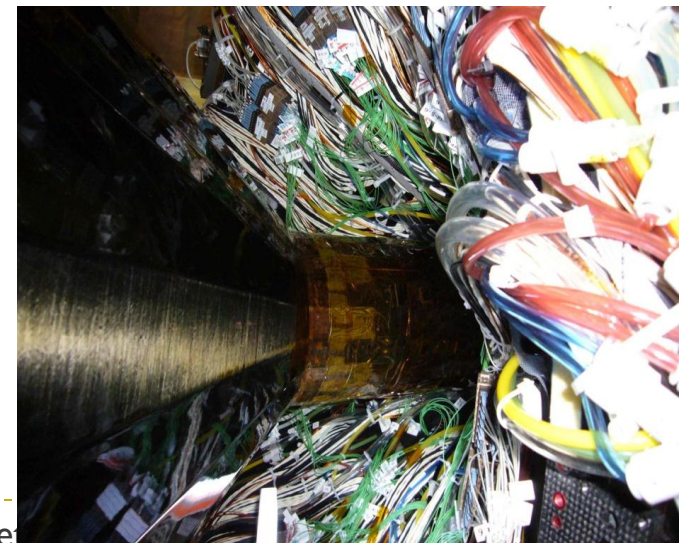
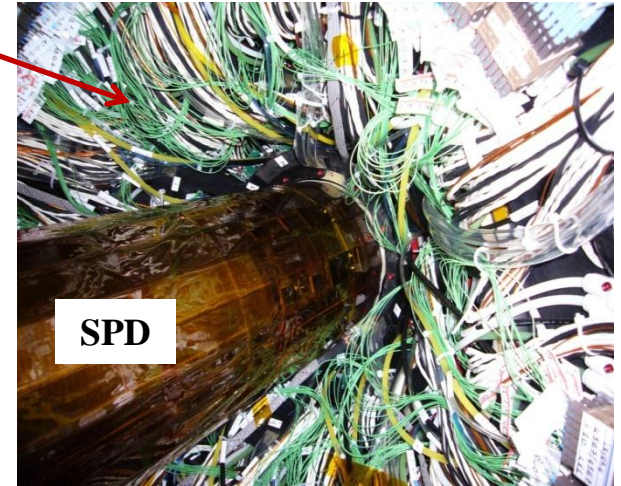
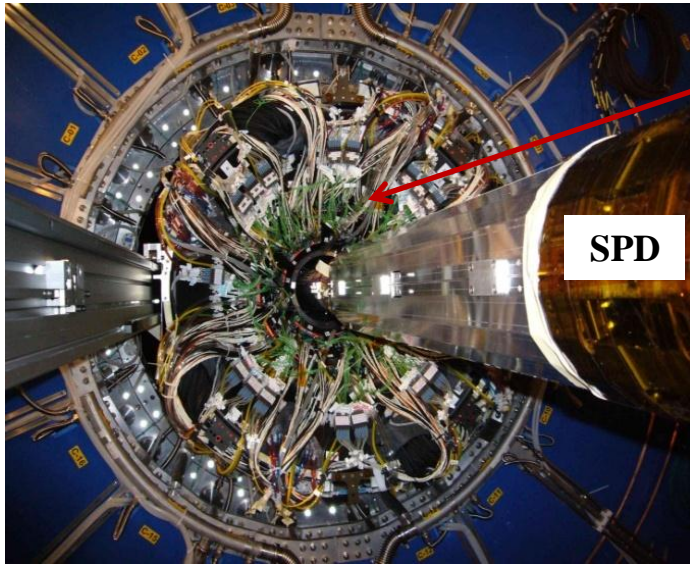
TPC moved over the ITS



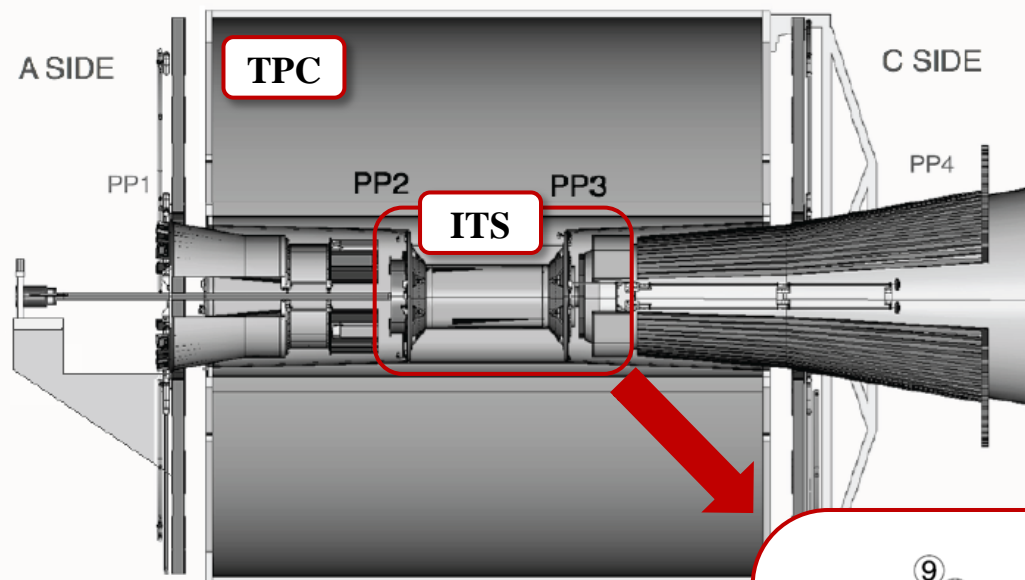
Installation: ...what really happened



SDD + SSD
services



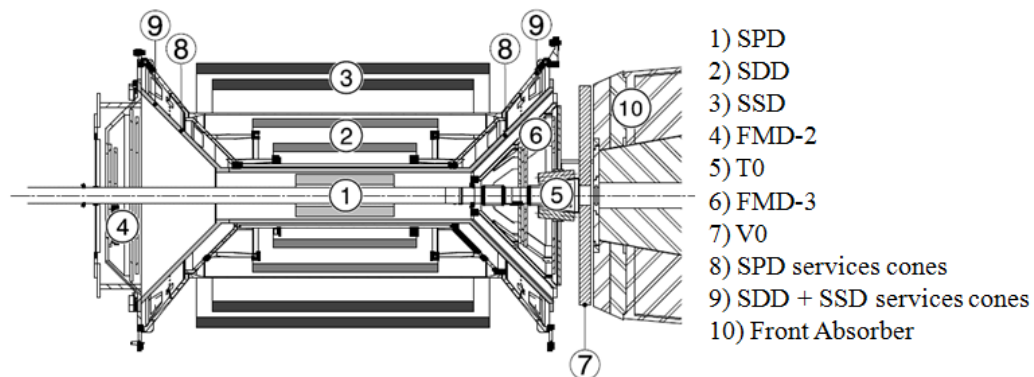
ITS + TPC: section view



Once the TPC is moved in the final position, there is no more access to the ITS and to the Forward detectors. In addition, two of the 4 patch panels (PP2 and PP3) used for services connections are not accessible anymore

Any access to the detectors or to the services needs a very long and risky procedure:

The time estimate to access the ITS has been recently estimated to be of the order of 7 months



What we experienced?



- ▶ **Mechanical integration**
 - ▶ In such a complex and extremely packed detector the good communication between teams or, even better, to have a unique team for the integration could help during the installation
 - ▶ Integration tests are also preferable although are not always easy
- ▶ **Services: better accessibility has to be a must**
 - ▶ See SPD cooling experience (Rosario Turrisi)
 - ▶ Cabling failure (1/120 HS in the SPD)



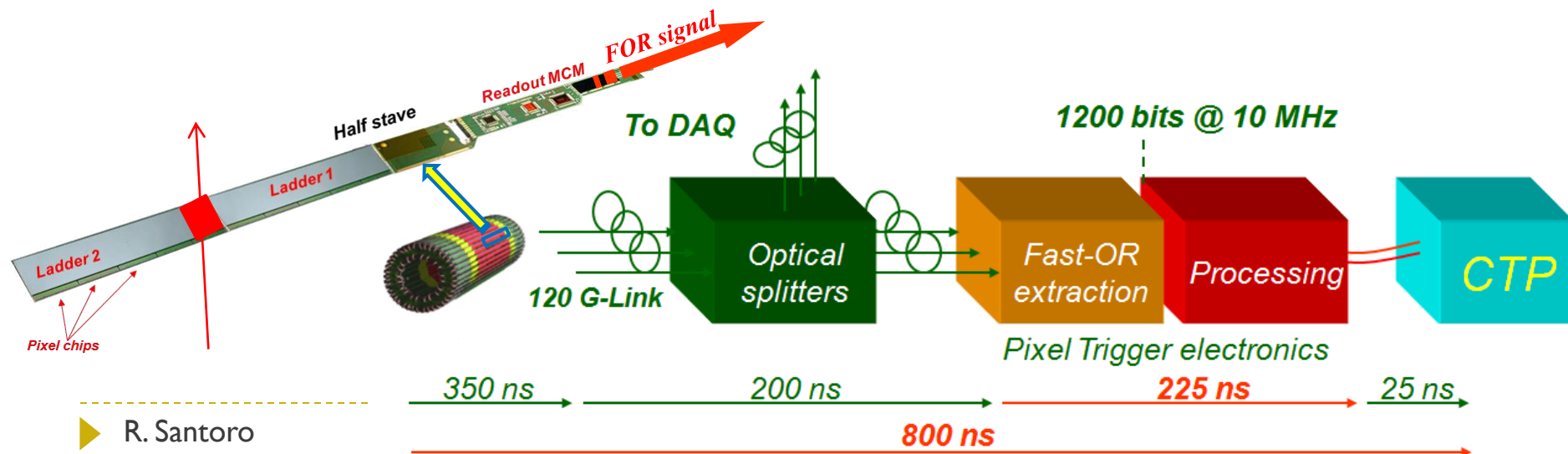
Optical link synchronization



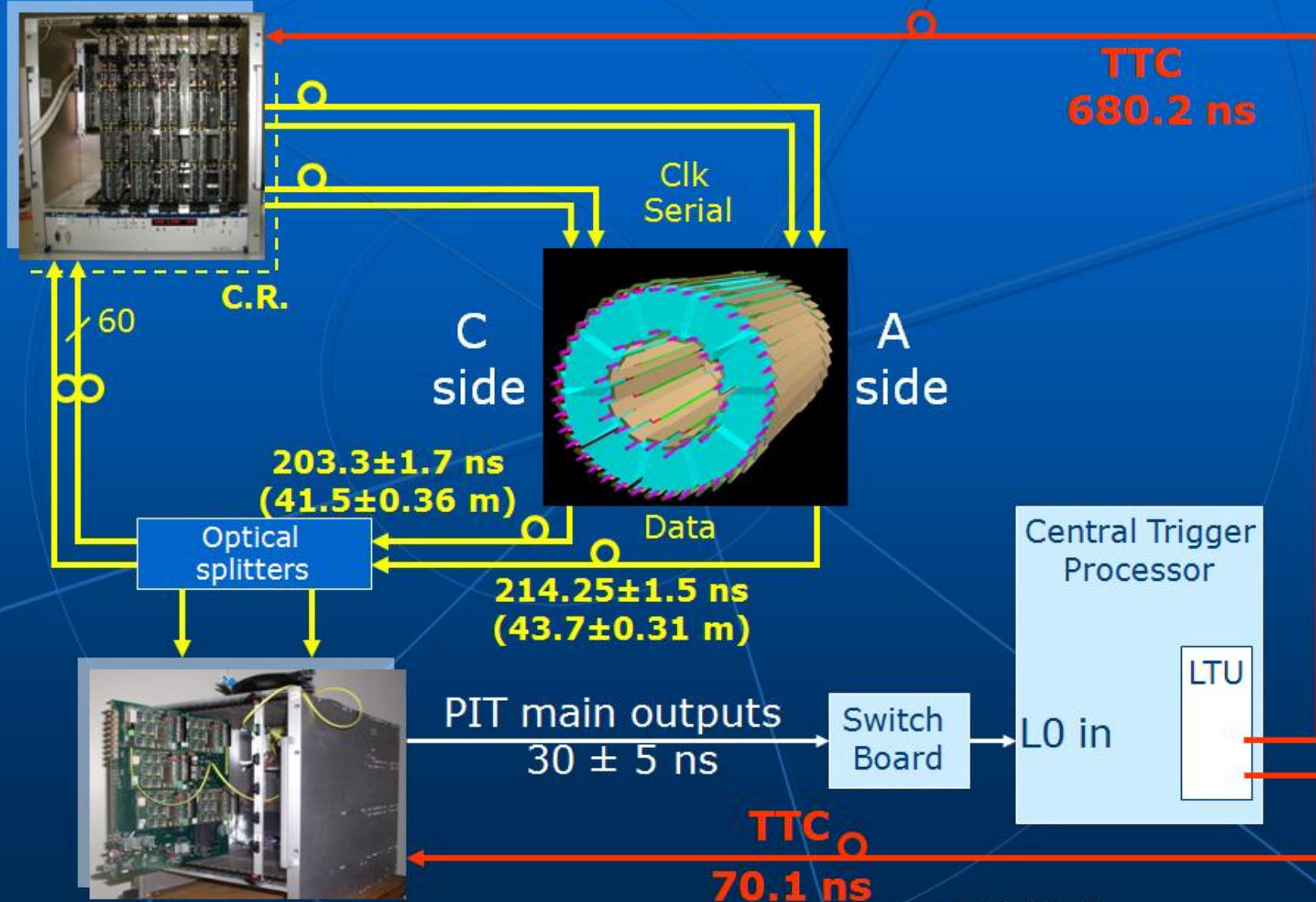
L0 trigger capability



- ▶ Pixel chip prompt Fast-OR
 - ▶ Active if at least one pixel hit in the chip matrix
 - ▶ 10 signals in each half-stave (1200 signals in total)
 - ▶ Transmitted every 100 ns
- ▶ Overall latency constrain 800 ns (CTP)
- ▶ Key timing processes are data deserialization and Fast-OR extraction
 - ▶ Algorithm processing time < 25 ns
- ▶ 10 Algorithms provided in parallel: useful for detectors commissioning, p-p and Pb-Pb physic
 - ▶ Cosmic, minimum bias and multiplicity algorithms
- ▶ FPGA remote programmable to guarantee maximum flexibility



Electronic layout

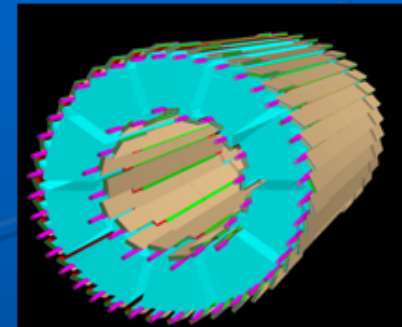
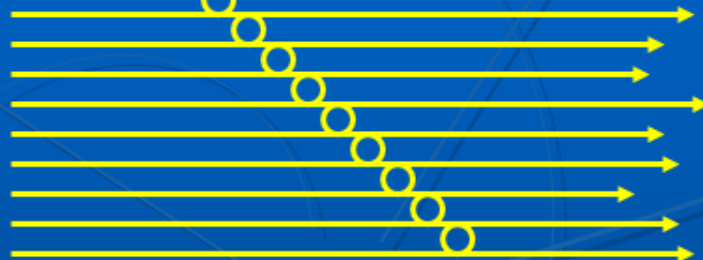


Detector clock phases alignment



Clk outputs

Clk fibers



Relative phases of 120 clocks of CR electronics: $\sigma = 0.63$ ns

Propagation delays due to 120 fibers measured: $\sigma = 0.9$ ns

Clock phases at SPD inputs without correction: $\sigma = 1.1$ ns

Delays added to the clock transmitters to compensate for differences

Clock phases at SPD inputs with correction: $\sigma = 0.08$ ns

What we learned?



- ▶ Use optical fibers with the same length is an important requirement but ...
- ▶ A flexible system is also better
 - ▶ Settings to equalize the delays in each channel
 - ▶ Settings to adjust the overall time w.r.t. the LHC clock

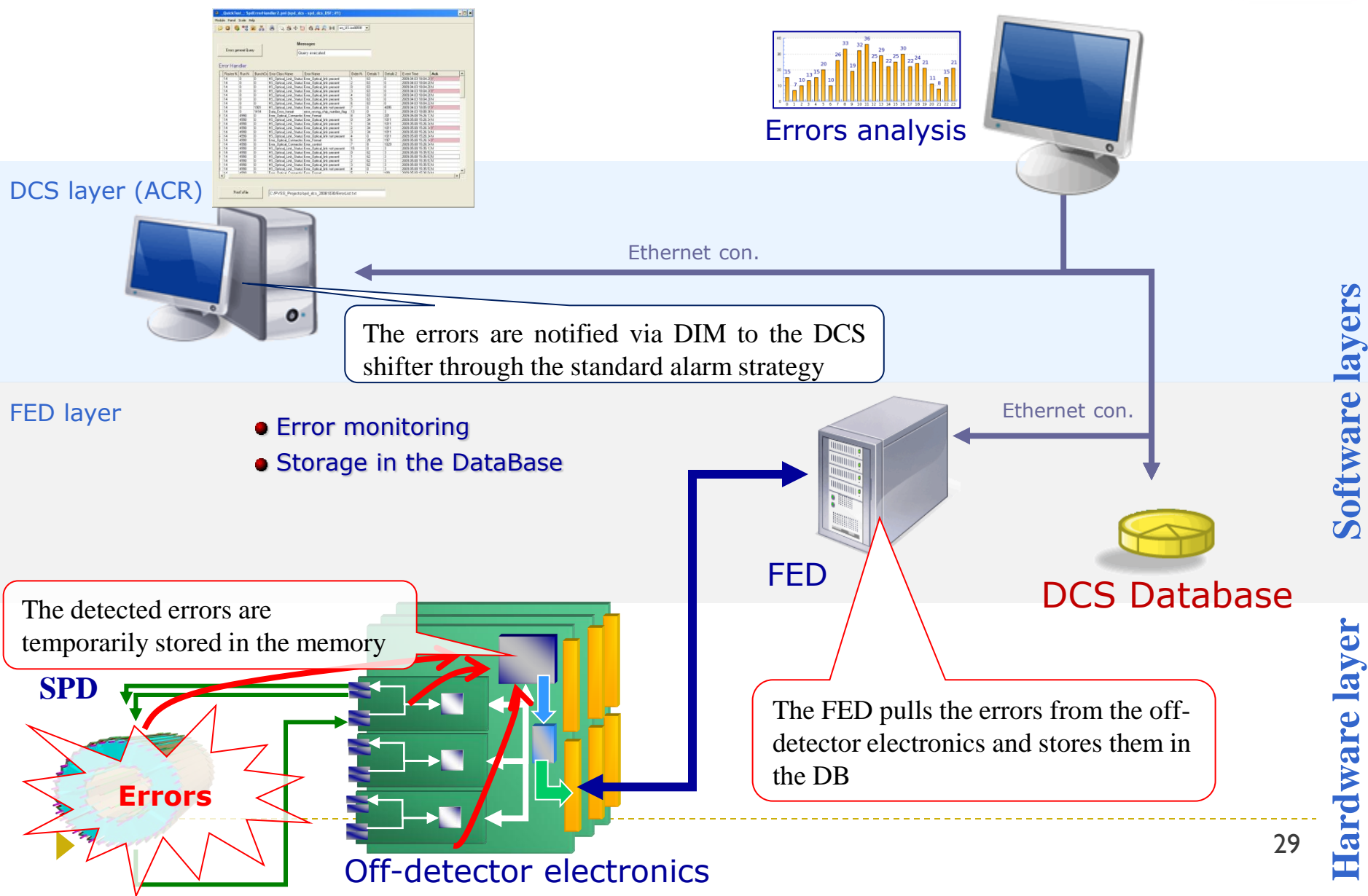


Tools to monitor the data
output



- ▶ Identify the source of problems and fix the failures in complex systems it is always a very hard tasks
 - ▶ FEE-electronics, Off-detector electronics, Link communication ...
- ▶ It is often hard and extremely time consuming to reproduce the problem and to correlate it with external condition
 - ▶ Trigger schema, partition schema, beam dependence ...
- ▶ This is the reason why a system capable to monitor the data output, to flag errors and to store the hardware conditions without disturbing the acquisition would help the expert... but, is that feasible?
- ▶ If the system would also be able to suggest the proper action and even to fix the problem by himself... it would be a dream!!!!
 - ▶ ... but don't be so excited... we don't have it!!!
 - ▶ Although, the “Error handler” tool is extremely useful

“Error handler” strategy



What we learned?



- ▶ The tool is extremely powerful and makes track of the low level information when the errors occur
- ▶ It is important to group errors in categories which can be masked accordingly to the expert needs
 - ▶ Useful to avoid that warnings fulfill the DB
- ▶ Statistic studies could be useful to monitor the electronics stability or to identify frequent failures



Thanks for your attention



Spares



Fast-OR Algorithms



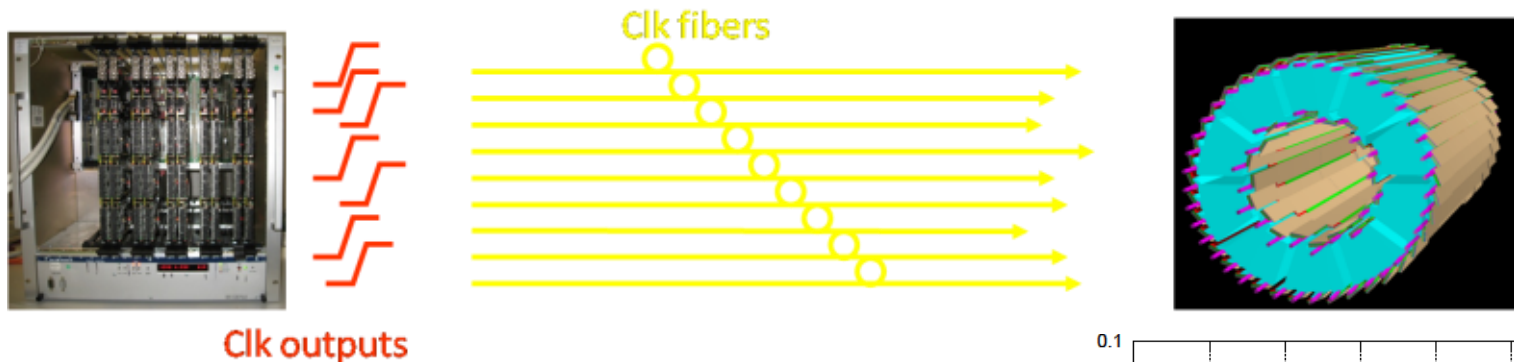
1	Minimum Bias	$(I+O) \geq th_{I+O,mb}$ and $I \geq th_{I,mb}$ and $O \geq th_{O,mb}$
2	High Multiplicity 1	$I \geq th_{I,hm1}$ and $O \geq th_{O,hm1}$
3	High Multiplicity 2	$I \geq th_{I,hm2}$ and $O \geq th_{O,hm2}$
4	High Multiplicity 3	$I \geq th_{I,hm3}$ and $O \geq th_{O,hm3}$
5	High Multiplicity 4	$I \geq th_{I,hm4}$ and $O \geq th_{O,hm4}$
6	Past Future Prot	$(I+O) \geq th_{I+O,pfp}$ and $I \geq th_{I,pfp}$ and $O \geq th_{O,pfp}$
7	Background(0)	$I \geq O + offset_O$
8	Background(1)	$O \geq I + offset_I$
9	Background(2)	$(I+O) \geq th_{(I+O),bnd}$
10	Cosmic	<i>Selectable coincidence, see following list</i>

Cosmic algorithms:

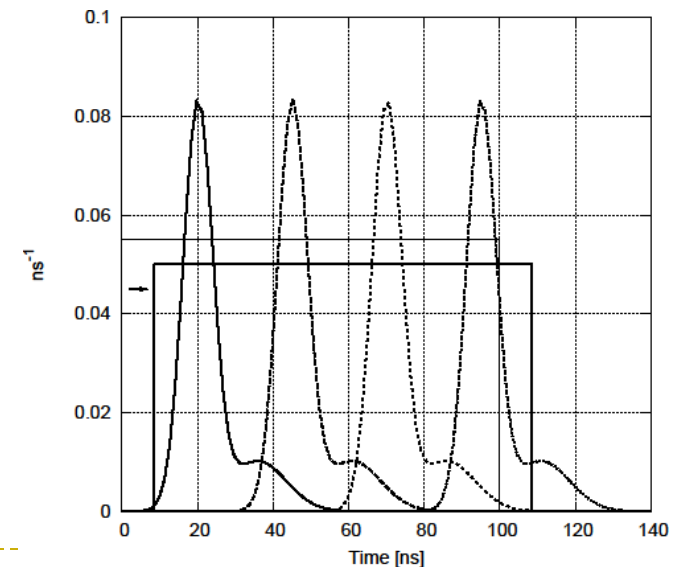
- ▶ TOP_outer and BOTTOM_outer
- ▶ OR_OUTER and OR_INNER
- ▶ DLAYER (≥ 2 FOs in the INNER and ≥ 2 FOs in the OUTER)
- ▶ TOP_outer and BOTTOM_outer and TOP_inner and BOTTOM_inner
- ▶ TOP_outer and BOTTOM_outer and OR_INNER
- ▶ GLOBAL_OR

Timing optimization

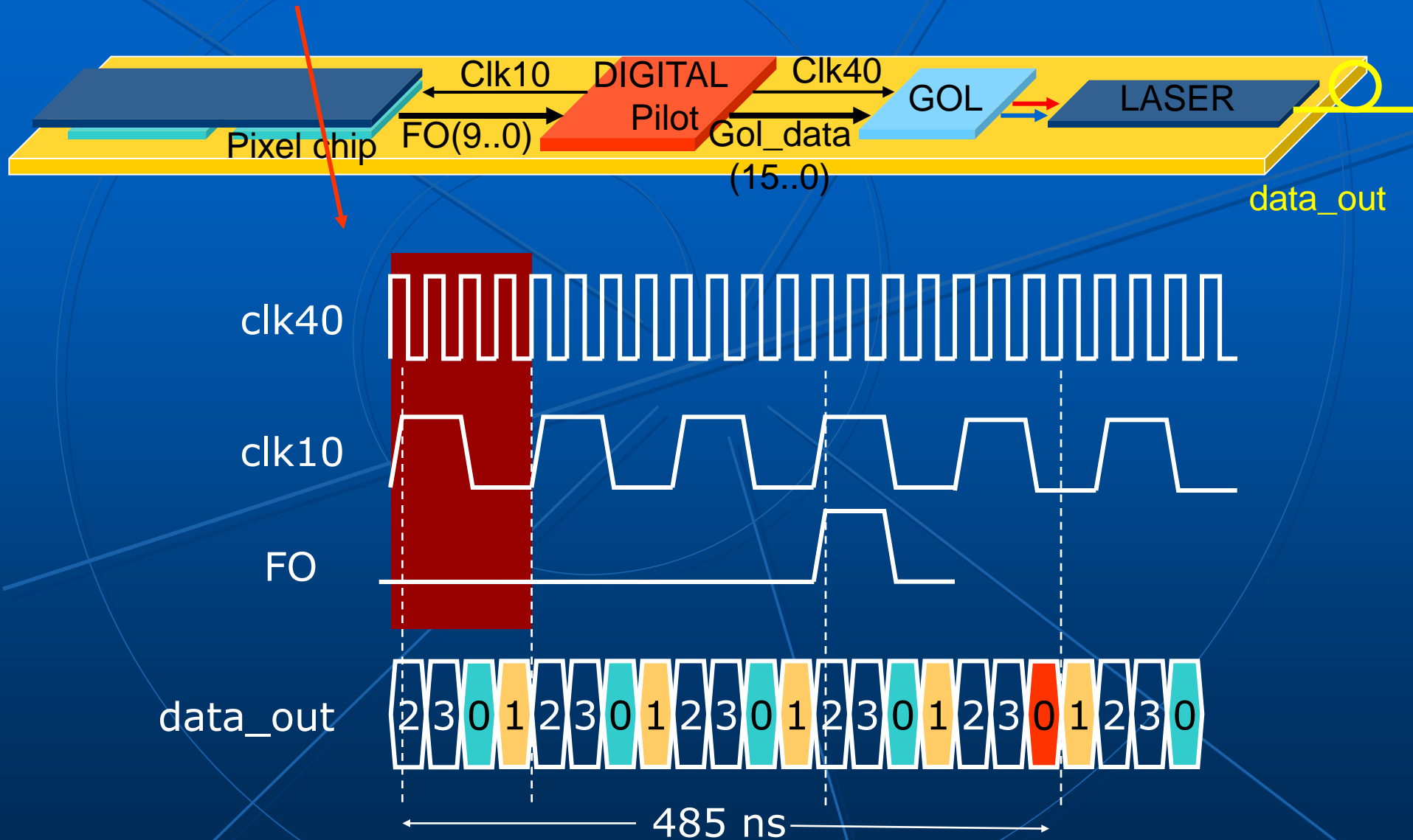
- ▶ Fine tuning of the timing for each individual Half-Stave
 - ▶ delay added to the clock transmitters to compensate for differences
 - ▶ Distribution of clock phases at SPD inputs after correction: $\sigma = 0.08$ ns



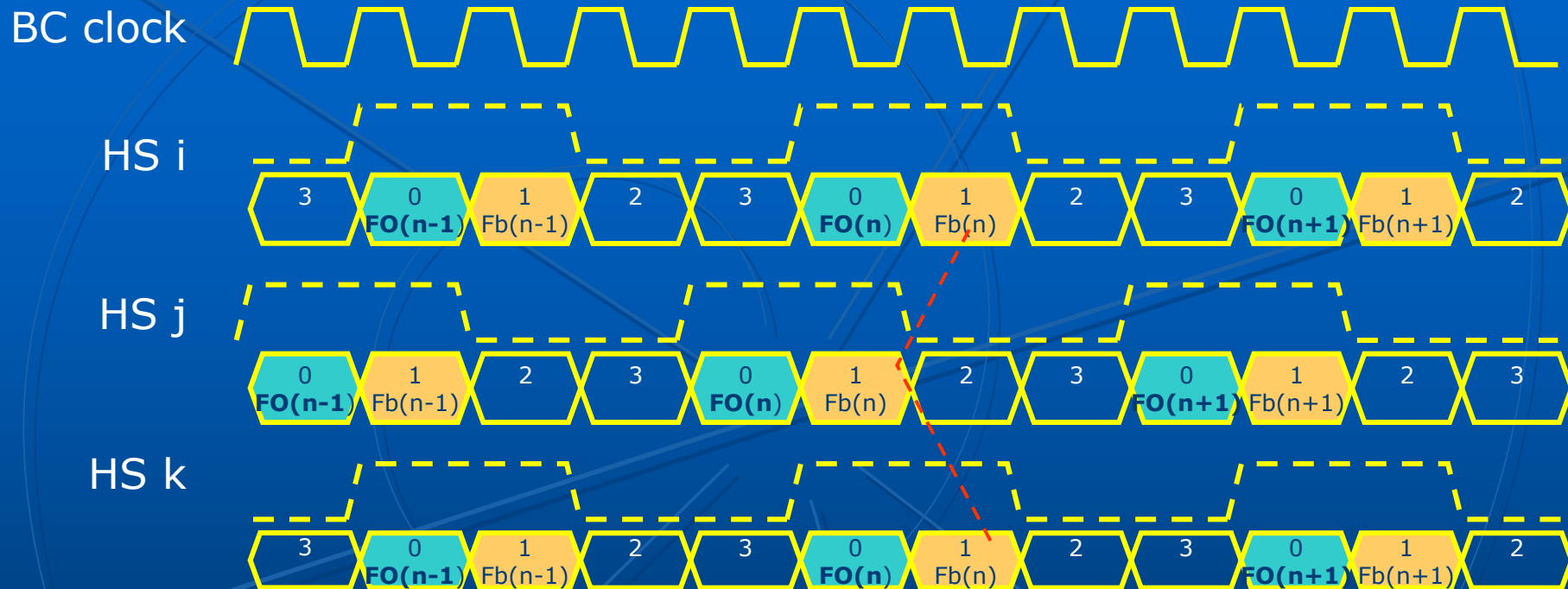
- ▶ Fine tuning of the SPD clock phase with respect to the LHC clock (SPD clock 10MHz)
 - ▶ Dedicated calibration during collisions has been performed
 - ▶ Measure pixel multiplicities versus clock phases
 - ▶ Set optimal phase in the clock domain



Fast OR timing



Synchronization



- 40 MHz clocks aligned by equalizing fibers length
- 10 MHz clock phases aligned by broadcast signal on TTC
- One clock period uncertainty left → Measure relative phases
 - **Measure arrival time of trigger feedback**

Frame alignment

