

# Performance benchmarks & Tools Geometry

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# Outline

- Evolution of performance from 5.2.p02 to 8.2.p01
  - Pure tracking geometrical tests
  - Benchmarks with field
- Considerations following questions from reviewers
- Geometry tools and usability
  - Tools for building and setup geometry models
  - Tools for debugging geometries
  - Interfaces to CAD and external applications

# 'Pure tracking' benchmark

- Honeycomb calorimeter

- Basic benchmark application used since early days
  - Calorimeter setup from CERN School of Computing 1995
  - Consisting of two modules, a matrix of 26 by 50 tubes each
- Tracking 'geantinos' along predefined directions

Geant4 version	User time (s)	System time (s)	Ratio
5.2.p02	2.570	0.000	0.84
6.2.p02	3.050	0.100	1.00
7.0.p01	3.000	0.000	0.98
7.1.p01	3.060	0.010	1.00
8.0.p01	3.070	0.020	1.00
8.1.p02	3.020	0.020	0.99
8.2.p01	3.140	0.010	1.03

(1)

(2)

## 'Pure tracking' benchmark - 2

(1) - G4Navigator becomes a base class in 6.0

– Good portion of key methods become virtual

➤ To accommodate Tgeo/VMC interface

(2) - LocateGlobalPointAndSetup() method in G4Navigator becomes virtual

➤ To accommodate Tgeo/VMC interface

➤ Total CPU penalty from 5.2.p02 to 8.2.p01 for pure tracking sums up to ~ 20%

# Benchmarks with field

- **BaBar tracker**

- Geant4 *NTST* benchmark
- Consists of simulating the BaBar silicon tracker and 40 layers drift chamber, in a 1.5 T constant magnetic field
- Only transportation, no physics. 100 B-Bbar events simulated

<b>Release</b>	<b>sec/event</b>	<b>Ratios</b>	
<b>7.1.p01a</b>	2.23	1.00	
<b>8.0.p01</b>	2.23	1.00	
<b>8.1.p02</b>	2.33	1.04	<--- <i>G4FieldTrack::LoadFromArray()</i> not inline
<b>8.2</b>	2.49	1.12	<--- <i>LocateGlobalPointAndSetup()</i> becomes virtual
<b>8.2.p01</b>	2.49	1.12	
<b>8.2.ref02</b>	2.50	1.12	

The number of steps and calls to fields are almost the same in all cases

# Benchmarks with field - 2

- BaBar tracker using QGSP\_EMV physics list
  - Same benchmark test as in the previous slide, but this time with the QGSP\_EMV Physics List. 100 B-Bbar events simulated

Release	sec/event	Ratios	
7.1.p01a	3.40	1.00	(QGSP_GN)
8.0.p01	4.29	1.26	
8.1.p02	4.32	1.27	
8.2	4.00	1.18	
8.2.p01	4.33	1.28	
8.2.ref02	4.17	1.23	

- *Variations mainly due to tuning and adding safety checks to Urban Multiple Scattering model*

# Considerations

1. The Geant4 geometry modeler provides since long time constructs and tools for tuning optimal navigation tracking and transportation in field within Geant4
  - Volume assemblies, replicas, parameterised volumes, regions
  - Geometry optimisation options
  - Parameters for field tuning and different stepper algorithms
  - Automatically generated/converted geometries/setups will inevitably introduce a penalty, depending on the complexity
2. By default Geant4 runs in “verbose” mode
  - To allow for proper debugging and information
  - 5-15% CPU improvement (depending on application) can be achieved in transportation/navigation in “no-verbose” mode

# Considerations - 2

- Recent CPU comparisons made in ALICE with Tgeo/VMC reveal
  - Comparable results for pure-tracking benchmarks on different geometry setups and with or without physics
    - without considering points (1) and (2)
  - A penalty in performance induced when L3 field is activated on TPC (5K Hijing particles at 0.5-999 GeV)
    - Particular setup, where low-energy particles are forced to perform small steps
    - First investigations indicating a “conservative” estimation of the geometrical ‘safety’ in Geant4 when field activated
    - Will review the estimation of isotropic ‘safety’
    - May require proper tuning of the field for such use case
    - Further aspects under investigation

# Tools for building geometries

- Ability to replicate, divide and parameterise volumes to be placed
  - Especially useful for optimising memory consumption on complex geometries
  - Implementation of setups parameterised by material
- Ability to assemble volumes in patterns and replicate them
  - Available since release 3.2 in 2001
  - Especially useful for describing areas of detector which may be subject to misalignments
    - Unique transformation which can be changed at run time
- Ability to reflect volume hierarchies
- Ability to handle geometries which change in time
- Ability to customise production (cuts) by geometrical region
  - CPU performance optimisation
- Ability to customise local fields per volume (parameters and stepper algorithms)
  - CPU performance & precision optimisation

# Tools for building geometries - 2

- GGE (Graphical Geometry Editor)
  - GUI tool for relatively simple geometries
  - Ability to generate source code for geometry description
- Handling of ‘parallel’ geometries (since 8.2)
  - Setup of geometries and navigation tuning for fast parameterisations
  - Possibility to apply geometrical importance biasing for charged and not-charged particles
  - Setup of scoring/tallies in generic positions within the tracking geometry
- Other tools (since 8.0/8.1):
  - Ability to compute geometrical volume of a generic shape
    - Ability to estimate the ‘mass’ of a detector (hierarchy of volumes)
  - Ability to compute the surface area of a generic shape

# Tools for debugging geometries

- Ability to detect overlaps
  - Once geometry constructed
    - Run-time overlap checks, tuneable in resolution and level of deepness in the geometry tree (since release 4.0)
    - Graphical tool (DAVID) for analysing and highlight overlaps based on postscript output of geometrical model (since 1.0)
    - Since 8.1, possibility to verify overlaps for each placed volume in the tree (against daughter and mother volumes)
  - While constructing the geometry (since 8.1/8.2)
    - Checks for each volume being placed or parameterised
      - Being extended to support all available solids and also cases of ‘encapsulation’ of volumes
      - Now automatically activated during navigation in case of “stuck” tracks for the suspected volumes

# Tools for debugging geometries - 2

- Running G4Navigator in ‘check-mode’
  - Introduced in release 6.1
  - Flag which can be activated at run-time (in ‘verbose’ mode, the default)
  - Forces additional checks on correctness and accuracy of solids response
  - Allows for identifying potential problems in the geometry model

# Interface to external applications

- Possibility to import/export geometry models cross applications
  - Through GDML and related tools
    - Allows for import/export of models from/to Root/Tgeo
  - Through direct object persistency with Root/IO
- Possibility to import geometry models from CAD systems
  - Translation of geometrical shapes to - approximated - tessellated shapes through existing tools (e.g. STViewer)
  - Import translated geometries through GDML
    - Tessellated shapes imported as G4TessellatedSolid
  - ❖ Allows to import also complex geometry models and shapes
  - ❖ To be considered for integration of complex shapes otherwise difficult to code

# Planned developments for 2007 in Geometry

- Tunable geometrical tolerance - (1)
- Parallel navigation & transportation as default - (1)
- Re-factoring and revision of biasing/scoring processes - (1)
- New G4ExtrudedSolid specific shape - (1)
- Integration of *Geant4e*, error-propagation module - (1)/(2)
- Full application tuning & benchmark suite for field - (1)/(2)
- Optimised navigation for voxelised phantom geometries - (2)
- New G4Paraboloid specific shape - (2)/(\*)

*(1) - Major release 9.0 end of June 2007*

*(2) - Minor release 9.1 in December 2007*

*(\*) - If manpower will be assigned: summer student project*

# Manpower - Geant4 Geometry WG

- John Apostolakis, CERN - 10%
- Pedro Arce Dubois, CIEMAT - 10%
- Makoto Asai, SLAC - 10%
- Gabriele Cosmo, CERN - 25%
- Vladimir Grichine, CERN - 10%
- Alex Howard, CERN - 25%
- Ivana Hrivnacova, IPN Orsay - 5%
- Tatiana Nikitina, CERN - 80%
  
- Total (including development and support): **1.75 FTE**
  - Considering the effort and amount of requests, it is a concern !