

Special Relativity

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Overview

- The principle of special relativity
- Lorentz transformation and consequences
- Space-time
- 4-vectors: position, velocity, momentum, invariants, covariance.
- Derivation of $E=mc^2$
- Examples of the use of 4-vectors
- Inter-relation between β and γ , momentum and energy
- An accelerator problem in relativity
- Photons and wave 4-vector
- Radiation from an Accelerating Charge
- Motion faster than speed of light

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Reading

- W. Rindler: Introduction to Special Relativity (OUP 1991)
- D. Lawden: An Introduction to Tensor Calculus and Relativity
- N.M.J. Woodhouse: Special Relativity (Springer 2002)
- A.P. French: Special Relativity, MIT Introductory Physics Series (Nelson Thomes)
- Misner, Thorne and Wheeler: Relativity
- C. Prior: Special Relativity, CERN Accelerator School (Zeege)

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Historical Background

- Groundwork of Special Relativity laid by **Lorentz** in studies of electrodynamics, with crucial concepts contributed by **Einstein** to place the theory on a consistent footing.
- **Maxwell's** equations (1863) attempted to explain electromagnetism and optics through wave theory
 - light propagates with speed $c = 3 \times 10^8$ m/s in "ether" but with different speeds in other frames
 - the ether exists solely for the transport of e/m waves
 - Maxwell's equations not invariant under Galilean transformations
- To avoid setting e/m apart from classical mechanics, assume
 - light has speed c only in frames where source is at rest
 - the ether has a small interaction with matter and is carried along with astronomical objects such as the Earth

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Contradicted by Experiment

- Aberration of star light (small shift in apparent positions of distant stars)
- Fizeau's 1859 experiments on velocity of light in liquids
- Michelson-Morley 1907 experiment to detect motion of the earth through ether
- Suggestion: perhaps material objects contract in the direction of their motion

$$L(v) = L_0 \left(1 - \frac{v^2}{c^2} \right)^{1/2}$$

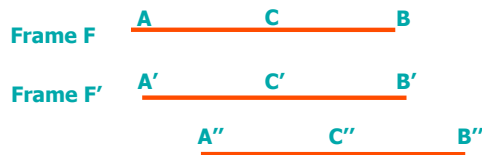
This was the last gasp of ether advocates and the germ of Special Relativity led by Lorentz, Minkowski and Einstein.

The Principle of Special Relativity

- A frame in which particles under no forces move with constant velocity is *inertial*.
- Consider relations between inertial frames where measuring apparatus (rulers, clocks) can be transferred from one to another: *related frames*.
- Assume:
 - Behaviour of apparatus transferred from F to F' is independent of mode of transfer
 - Apparatus transferred from F to F', then from F' to F'', agrees with apparatus transferred directly from F to F''.
- *The Principle of Special Relativity states that all physical laws take equivalent forms in related inertial frames, so that we cannot distinguish between the frames.*

Simultaneity

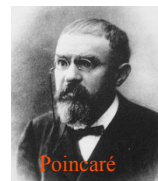
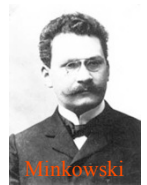
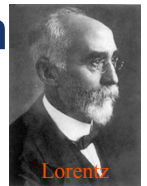
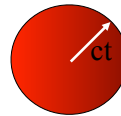
- Two clocks A and B are synchronised if light rays emitted at the same time from A and B meet at the mid-point of AB



- Frame F' moving with respect to F. Events simultaneous in F cannot be simultaneous in F'.
- Simultaneity is **not absolute** but frame dependent.

The Lorentz Transformation

- Must be linear to agree with standard Galilean transformation in low velocity limit
- Preserves wave fronts of pulses of light,
 - i.e. $P \equiv x^2 + y^2 + z^2 - c^2t^2 = 0$
 - whenever $Q \equiv x'^2 + y'^2 + z'^2 - c^2t'^2 = 0$
- Solution is the **Lorentz transformation** from frame F (t, x, y, z) to frame F' (t', x', y', z') moving with velocity v along the x-axis:



$$\begin{aligned} t' &= \gamma \left(t - \frac{vx}{c^2} \right) \\ x' &= \gamma (x - vt) \\ y' &= y \\ z' &= z \end{aligned}$$

where $\gamma = \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$

Outline of Derivation

Set $t' = \alpha t + \beta x$
 $x' = \gamma x + \delta t$
 $y' = \varepsilon y$
 $z' = \zeta z$

Then $P = kQ$

$$\Leftrightarrow c^2 t'^2 - x'^2 - y'^2 - z'^2 = k(c^2 t^2 - x^2 - y^2 - z^2)$$

$$\Rightarrow c^2(\alpha t + \beta x)^2 - (\gamma x + \delta t)^2 - \varepsilon^2 y^2 - \zeta^2 z^2 = k(c^2 t^2 - x^2 - y^2 - z^2)$$

Equate coefficients of x, y, z, t .

Isotropy of space $\Rightarrow k = k(\vec{v}) = k(|\vec{v}|) = \pm 1$

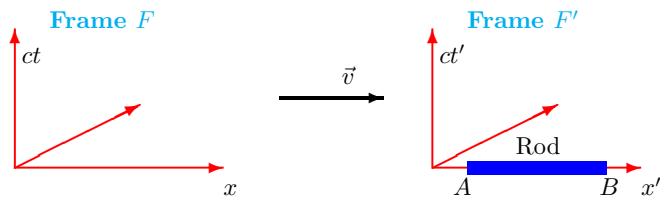
Apply some common sense (e.g. $\varepsilon, \zeta, k = +1$ and not -1)

General 3D form of Lorentz Transformation:

$$\vec{x}' = \vec{x} - \vec{v} \left(\gamma t - (\gamma - 1) \frac{\vec{v} \cdot \vec{x}}{v^2} \right)$$

$$t' = \gamma \left(t - \frac{\vec{v} \cdot \vec{x}}{c^2} \right)$$

Consequences: length contraction



A rod AB of length L' , fixed in frame F' at x'_A, x'_B . What is its length measured in F ?

Must measure position of ends in F at same time, so events in F are (ct, x_A) and (ct, x_B) .

By Lorentz:

$$\left. \begin{aligned} x'_A &= \gamma(x_A - vt) \\ x'_B &= \gamma(x_B - vt) \end{aligned} \right\} \Rightarrow \begin{aligned} L' &= x'_B - x'_A \\ &= \gamma(x_B - x_A) \\ &= \gamma L > L \end{aligned}$$

Moving objects appear contracted in the direction of the motion

Consequences: time dilation

- Clock in frame F at point with coordinates (x, y, z) at different times t_A and t_B



- In frame F' moving with speed v , Lorentz transformation gives

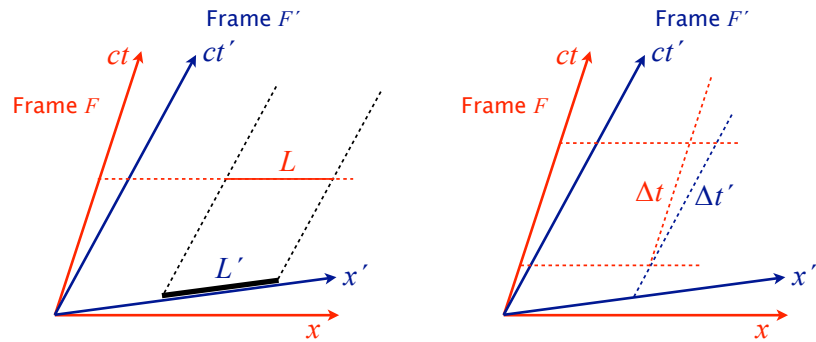
$$t'_A = \gamma \left(t_A - \frac{vx}{c^2} \right) \quad t'_B = \gamma \left(t_B - \frac{vx}{c^2} \right)$$

- So

$$\Delta t' = t'_B - t'_A = \gamma(t_B - t_A) = \gamma \Delta t > \Delta t$$

Moving clocks appear to run slow

Schematic Representation of the Lorentz Transformation



Length contraction $L < L'$

Rod at rest in F' . Measurements in F at a fixed time t , along a line parallel to x -axis

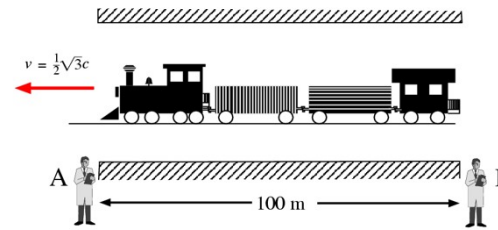
Time dilation $\Delta t < \Delta t'$

Clock at rest in F . Time difference in F' from line parallel to t' -axis



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Example: High Speed Train



All clocks synchronised.

A's clock and driver's clock read 0 as front of train emerges from tunnel.

- Observers A and B at exit and entrance of tunnel say the train is moving, has contracted and has length

$$\frac{100}{\gamma} = 100 \times \left(1 - \frac{v^2}{c^2}\right)^{1/2} = 100 \times \left(1 - \frac{3}{4}\right)^{1/2} = 50\text{m}$$

- But the tunnel is moving relative to the driver and guard on the train and they say the train is 100 m in length but the tunnel has contracted to 50 m



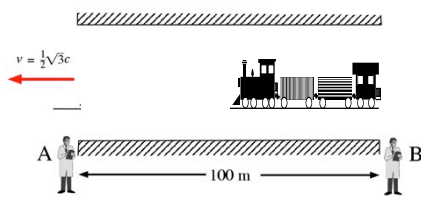
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Question 1



A's clock and the driver's clock read zero as the driver exits tunnel.

What does B's clock read when the guard goes in?



Moving train length 50m, so driver has still 50m to travel before he exits and his clock reads 0. A's clock and B's clock are synchronised. Hence the reading on B's clock is

$$-\frac{50}{v} = -\frac{100}{\sqrt{3}c} \approx -200\text{ns}$$

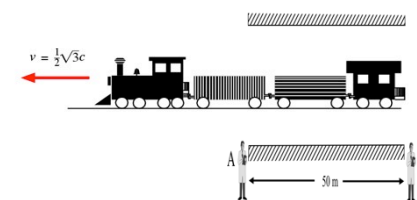


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Question 2



What does the guard's clock read as he goes in?



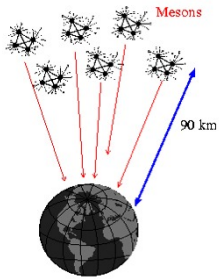
To the guard, tunnel is only 50m long, so driver is 50m past the exit as guard goes in. Hence clock reading is

$$+\frac{50}{v} = +\frac{100}{\sqrt{3}c} \approx +200\text{ns}$$



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Example: Cosmic Rays



- Muons are created in the upper atmosphere, 90km from earth. Their half life is $\tau=2 \mu\text{s}$, so they can travel at most $2 \times 10^{-6}c=600 \text{ m}$ before decaying. So **how do more than 50% reach the earth's surface?**

- Muons see distance contracted by γ , so

$$v\tau \approx \frac{90}{\gamma} \text{ km}$$

- Earthlings say muons' clocks run slow so their half-life is $\gamma\tau$ and

$$v(\gamma\tau) \approx 90 \text{ km}$$

- Both give

$$\frac{\gamma v}{c} = \frac{90 \text{ km}}{c\tau} = 150, \quad v \approx c, \quad \gamma \approx 150$$



Space-time

- An invariant is a quantity that has the same value in all inertial frames.

- Lorentz transformation is based on invariance of

$$c^2t^2 - (x^2 + y^2 + z^2) = (ct)^2 - \vec{x}^2$$

- 4D-space with coordinates (t,x,y,z) is called **space-time** and the point $(t,x,y,z)=(t,\mathbf{x})$ is called an **event**.

- Fundamental invariant (preservation of speed of light):

$$\begin{aligned} \Delta s^2 &= c^2\Delta t^2 - \Delta x^2 - \Delta y^2 - \Delta z^2 = c^2\Delta t^2 \left(1 - \frac{\Delta x^2 + \Delta y^2 + \Delta z^2}{c^2\Delta t^2}\right) \\ &= c^2\Delta t^2 \left(1 - \frac{v^2}{c^2}\right) = c^2 \left(\frac{\Delta t}{\gamma}\right)^2 \end{aligned}$$

$\tau = \int \frac{dt}{\gamma}$ is called proper time, the time in the instantaneous rest-frame and an invariant. Δs is called the **separation** between two events.



4-Vectors

The Lorentz transformation can be written in matrix form as

$$\begin{aligned} t' &= \gamma \left(t - \frac{vx}{c^2}\right) \\ x' &= \gamma(x - vt) \\ y' &= y \\ z' &= z \end{aligned} \quad \Rightarrow \quad \begin{pmatrix} ct' \\ x' \\ y' \\ z' \end{pmatrix} = \begin{pmatrix} \gamma & -\frac{\gamma v}{c} & 0 & 0 \\ -\frac{\gamma v}{c} & \gamma & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix}$$

$$X' = LX$$

↑
Lorentz matrix L
↑
Position 4-vector X

An object made up of 4 elements which transforms like X is called a 4-vector (analogous to the 3-vector of classical mechanics)



4-Vector Invariants

Basic invariant:

$$c^2t^2 - x^2 - y^2 - z^2 = (ct, x, y, z) \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & -1 & 0 & 0 \\ 0 & 0 & -1 & 0 \\ 0 & 0 & 0 & -1 \end{pmatrix} \begin{pmatrix} ct \\ x \\ y \\ z \end{pmatrix} = X^t g X = X \cdot X$$

Inner product of two four vectors $A = (a_0, \vec{a})$, $B = (b_0, \vec{b})$:

$$A \cdot B = A^T g B = a_0 b_0 - a_1 b_1 - a_2 b_2 - a_3 b_3 = a_0 b_0 - \vec{a} \cdot \vec{b}$$

Invariance:

$$A' \cdot B' = (LA)^T g (LB) = A^T (L^T g L) B = A^T g B = A \cdot B$$



4-Vectors in S.R. Mechanics

- Velocity: $V = \frac{dX}{d\tau} = \gamma \frac{dX}{dt} = \gamma \frac{d}{dt}(ct, \vec{x}) = \gamma(c, \vec{v})$
- Note invariant: $V \cdot V = \gamma^2(c^2 - \vec{v}^2) = \frac{c^2 - \vec{v}^2}{1 - \vec{v}^2/c^2} = c^2$
- Momentum: $P = m_0 V = m_0 \gamma(c, \vec{v}) = (mc, \vec{p})$

$m = m_0 \gamma$ is the relativistic mass
 $p = m_0 \gamma \vec{v} = m \vec{v}$ is the relativistic 3-momentum



4-Force

From Newton's 2nd Law expect 4-Force given by

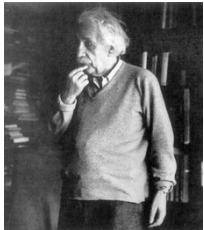
$$\begin{aligned}
 F &= \frac{dP}{d\tau} = \gamma \frac{dP}{dt} \\
 &= \gamma \frac{d}{dt}(mc, \vec{p}) = \gamma \left(c \frac{dm}{dt}, \frac{d\vec{p}}{dt} \right) \\
 &= \gamma \left(c \frac{dm}{dt}, \vec{f} \right)
 \end{aligned}$$

Note: 3-force equation: $\vec{f} = \frac{d\vec{p}}{dt} = m_0 \frac{d}{dt}(\gamma \vec{v})$



Einstein's Relation: Energy and Mass

- Momentum invariant $P \cdot P = m_0^2 V \cdot V = m_0^2 c^2$
 - Differentiate $P \cdot \frac{dP}{d\tau} \Rightarrow V \cdot \frac{dP}{d\tau} = 0 \Rightarrow V \cdot F = 0$
 $\Rightarrow \gamma(c, \vec{v}) \cdot \gamma \left(c \frac{dm}{dt}, \vec{f} \right) = 0$
 $\Rightarrow \frac{d}{dt}(mc^2) - \vec{v} \cdot \vec{f} = 0$
- $\vec{v} \cdot \vec{f}$ = rate at which force does work
 = rate of change of kinetic energy



Therefore kinetic energy is
 $T = mc^2 + \text{constant} = m_0 c^2 (\gamma - 1)$

$E=mc^2$ is total energy



Summary of 4-Vectors

Position	$X = (ct, \vec{x})$
Velocity	$V = \gamma(c, \vec{v})$
Momentum	$P = m_0 V = m(c, \vec{v}) = \left(\frac{E}{c}, \vec{p} \right)$
Force	$F = \gamma \left(c \frac{dm}{dt}, \vec{f} \right) = \gamma \left(\frac{1}{c} \frac{dE}{dt}, \vec{f} \right)$



Example of Transformation: Addition of Velocities

An object has velocity $\vec{u} = (u_x, u_y)$ in frame F' , which moves with velocity $\vec{v} = (v, 0)$ with respect to frame F .

The 4-velocity $U = \gamma_u(c, u_x, u_y)$ has to be Lorentz transformed to F , resulting in a 4-velocity $W = \gamma_w(c, w_x, w_y)$:

$$\begin{pmatrix} c\gamma_w \\ \gamma_w w_x \\ \gamma_w w_y \end{pmatrix} = \begin{pmatrix} \gamma & \gamma v/c & 0 \\ \gamma v/c & \gamma & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} c\gamma_u \\ \gamma_u u_x \\ \gamma_u u_y \end{pmatrix}$$

$$\begin{aligned} \gamma_w &= \gamma \gamma_u \left(1 + \frac{vu_x}{c^2} \right) \\ \gamma_w w_x &= \gamma \gamma_u (v + u_x) \\ \gamma_w w_y &= \gamma_u u_y \end{aligned}$$

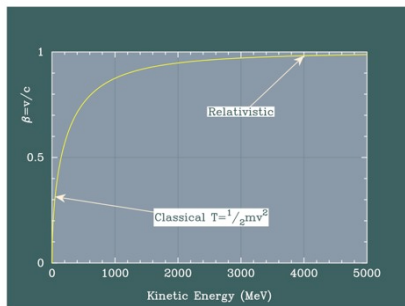
$$\begin{aligned} w_x &= \frac{v + u_x}{\left(1 + \frac{vu_x}{c^2} \right)} \\ w_y &= \frac{u_y}{\gamma \left(1 + \frac{vu_x}{c^2} \right)} \end{aligned}$$

Basic Quantities used in Accelerator Calculations

Relative velocity	$\beta = \frac{v}{c}$
Velocity	$v = \beta c$
Momentum	$p = mv = m_0 \gamma v = m_0 \gamma \beta c$
Kinetic energy	$T = mc^2 - m_0 c^2 = (\gamma - 1)m_0 c^2 = (\gamma - 1)E_0$

$$\begin{aligned} \gamma &= \left(1 - \frac{v^2}{c^2} \right)^{-\frac{1}{2}} = (1 - \beta^2)^{-\frac{1}{2}} \\ \Rightarrow (\beta\gamma)^2 &= \frac{\gamma^2 v^2}{c^2} = \gamma^2 - 1 \Rightarrow \beta^2 = \frac{v^2}{c^2} = 1 - \frac{1}{\gamma^2} \end{aligned}$$

Velocity and Energy



$$T = m_0(\gamma - 1)c^2$$

$$\gamma = 1 + \frac{T}{m_0 c^2}$$

$$\beta = \sqrt{1 - \frac{1}{\gamma^2}}$$

$$p = m_0 \beta \gamma c$$

$$\text{For } v \ll c, \quad \gamma = \left(1 - \frac{v^2}{c^2} \right)^{-\frac{1}{2}} \approx 1 + \frac{1}{2} \frac{v^2}{c^2} + \frac{3}{8} \frac{v^4}{c^4} + \dots$$

$$\text{so } T = m_0 c^2 (\gamma - 1) \approx \frac{1}{2} m_0 v^2$$

Energy-Momentum

$$\begin{aligned} P \cdot P &= m_0^2 V \cdot V = m_0^2 c^2 \quad \text{and} \quad P = \left(\frac{E}{c}, \vec{p} \right) \\ \frac{E^2}{c^2} - \vec{p}^2 &= m_0^2 c^2 = \frac{1}{c^2} E_0^2 \quad \text{where } E_0 \text{ is rest energy} \\ \Rightarrow p^2 c^2 &= E^2 - E_0^2 \\ &= (E - E_0)(E + E_0) \\ &= T(T + 2E_0) \end{aligned}$$

Example: ISIS at RAL accelerates protons ($E_0 = 938$ MeV) to 800 MeV

$$\begin{aligned} \Rightarrow pc &= \sqrt{800 \times (800 + 2 \times 938)} \text{ MeV} \\ &= 1.463 \text{ GeV} \end{aligned}$$

$$\begin{aligned} \beta\gamma &= \frac{m_0 \beta \gamma c^2}{m_0 c^2} = \frac{pc}{E_0} = 1.56 \\ \gamma^2 &= (\beta\gamma)^2 + 1 \Rightarrow \gamma = 1.85 \\ \beta &= \frac{\beta\gamma}{\gamma} = 0.84 \end{aligned}$$

Relationships between small variations in parameters ΔE , ΔT , Δp , $\Delta\beta$, $\Delta\gamma$

$$\begin{aligned} (\beta\gamma)^2 &= \gamma^2 - 1 \\ \Rightarrow \beta\gamma\Delta(\beta\gamma) &= \gamma\Delta\gamma \\ \Rightarrow \beta\Delta(\beta\gamma) &= \Delta\gamma \end{aligned} \quad (1)$$

$$\begin{aligned} \frac{1}{\gamma^2} &= 1 - \beta^2 \\ \Rightarrow \frac{1}{\gamma^3}\Delta\gamma &= \beta\Delta\beta \end{aligned} \quad (2)$$

$$\begin{aligned} \frac{\Delta p}{p} &= \frac{\Delta(m_0\beta\gamma c)}{m_0\beta\gamma c} = \frac{\Delta(\beta\gamma)}{\beta\gamma} \\ &= \frac{1}{\beta^2} \frac{\Delta\gamma}{\gamma} = \frac{1}{\beta^2} \frac{\Delta E}{E} \\ &= \gamma^2 \frac{\Delta\beta}{\beta} \\ &= \frac{\gamma}{\gamma+1} \frac{\Delta T}{T} \quad (\text{exercise}) \end{aligned}$$

Note: valid to first order only

	$\frac{\Delta\beta}{\beta}$	$\frac{\Delta p}{p}$	$\frac{\Delta T}{T}$	$\frac{\Delta E}{E} = \frac{\Delta\gamma}{\gamma}$
$\frac{\Delta\beta}{\beta} =$	$\frac{\Delta\beta}{\beta}$	$\frac{1}{\gamma^2} \frac{\Delta p}{p}$ $\frac{\Delta p}{p} - \frac{\Delta\gamma}{\gamma}$	$\frac{1}{\gamma(\gamma+1)} \frac{\Delta T}{T}$	$\frac{1}{\beta^2\gamma^2} \frac{\Delta\gamma}{\gamma}$ $\frac{1}{\gamma^2-1} \frac{\Delta\gamma}{\gamma}$
$\frac{\Delta p}{p} =$	$\gamma^2 \frac{\Delta\beta}{\beta}$	$\frac{\Delta p}{p}$	$\frac{\gamma}{\gamma+1} \frac{\Delta T}{T}$	$\frac{1}{\beta^2} \frac{\Delta\gamma}{\gamma}$
$\frac{\Delta T}{T} =$	$\gamma(\gamma+1) \frac{\Delta\beta}{\beta}$	$\left(1 + \frac{1}{\gamma}\right) \frac{\Delta p}{p}$	$\frac{\Delta T}{T}$	$\frac{\gamma}{\gamma-1} \frac{\Delta\gamma}{\gamma}$
$\frac{\Delta E}{E} =$	$(\beta\gamma)^2 \frac{\Delta\beta}{\beta}$	$\beta^2 \frac{\Delta p}{p}$	$\left(1 - \frac{1}{\gamma}\right) \frac{\Delta T}{T}$	$\frac{\Delta\gamma}{\gamma}$
$\frac{\Delta\gamma}{\gamma} =$	$(\gamma^2 - 1) \frac{\Delta\beta}{\beta}$	$\frac{\Delta p}{p} - \frac{\Delta\beta}{\beta}$		

Table 1: Incremental relationships between energy, velocity and momentum.

4-Momentum Conservation

- Equivalent expression for 4-momentum $P = m_0\gamma(c, \vec{v}) = (mc, \vec{p}) = \left(\frac{E}{c}, \vec{p}\right)$

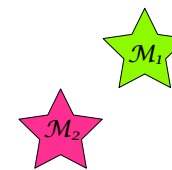
- Invariant $m_0^2 c^2 = P \cdot P = \frac{E^2}{c^2} - \vec{p}^2 \Rightarrow \frac{E^2}{c^2} = \vec{p}^2 + m_0^2 c^2$

- Classical momentum conservation laws \rightarrow conservation of 4-momentum. Total 3-momentum and total energy are conserved.

$$\sum_{\text{particles}, i} P_i = \text{constant}$$

$$\Rightarrow \sum_{\text{particles}, i} E_i \text{ and } \sum_{\text{particles}, i} \vec{p}_i \text{ constant}$$

Problem



A body of mass M disintegrates while at rest into two parts of rest masses M_1 and M_2 .

Show that the energies of the parts are given by

$$E_1 = c^2 \frac{M^2 + M_1^2 - M_2^2}{2M}, \quad E_2 = c^2 \frac{M^2 - M_1^2 + M_2^2}{2M}$$

Solution

Before: ☺
 $P = (Mc, \vec{0})$

After: ☺
 $P_1 = \left(\frac{E_1}{c}, \vec{p}\right)$
 $P_2 = \left(\frac{E_2}{c}, -\vec{p}\right)$

Conservation of 4-momentum:

$$\begin{aligned} P &= P_1 + P_2 \Rightarrow P - P_1 = P_2 \\ &\Rightarrow (P - P_1) \cdot (P - P_1) = P_2 \cdot P_2 \\ &\Rightarrow P \cdot P - 2P \cdot P_1 + P_1 \cdot P_1 = P_2 \cdot P_2 \\ &\Rightarrow M^2 c^2 - 2ME_1 + M_1^2 c^2 = M_2^2 c^2 \\ &\Rightarrow E_1 = \frac{M^2 + M_1^2 - M_2^2}{2M} c^2 \end{aligned}$$

Example of use of invariants

- Two particles have equal rest mass m_0 .
 - Frame 1: one particle at rest, total energy is E_1 .
 - Frame 2: centre of mass frame where velocities are equal and opposite, total energy is E_2 .

Problem: Relate E_1 to E_2

☺ → ☼
 $P_1 = \left(\frac{E_1 - m_0 c^2}{c}, \vec{p}\right)$ $P_2 = (m_0 c, \vec{0})$ Total energy E_1
 (Fixed target experiment)

☺ → ☼ ←
 $P_1 = \left(\frac{E_2}{2c}, \vec{p}'\right)$ $P_2 = \left(\frac{E_2}{2c}, -\vec{p}'\right)$ Total energy E_2
 (Colliding beams experiment)

Invariant: $P_2 \cdot (P_1 + P_2)$

$$\begin{aligned} m_0 c \times \frac{E_1}{c} - 0 \times p &= \frac{E_2}{2c} \times \frac{E_2}{c} + p' \times 0 \\ \Rightarrow 2m_0 c^2 E_1 &= E_2^2 \end{aligned}$$

Collider Problem

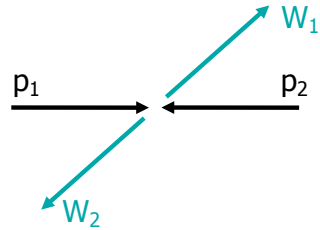
In an accelerator, a proton p_1 with rest mass m_0 collides with an anti-proton p_2 (with the same rest mass), producing two particles W_1 and W_2 with equal rest mass $M_0 = 100m_0$

- Experiment 1: p_1 and p_2 have equal and opposite velocities in the lab frame. Find the minimum energy of p_2 in order for W_1 and W_2 to be produced.
- Experiment 2: in the rest frame of p_1 , find the minimum energy E' of p_2 in order for W_1 and W_2 to be produced.

Experiment 1

$$\frac{E^2}{c^2} = \vec{p}^2 + m_0^2 c^2 \implies$$

Particles with same rest-mass and same momentum have same energies.



Total 3-momentum is zero before collision, so is zero afterwards

4-momenta before collision:

$$P_1 = \left(\frac{E}{c}, \vec{p} \right) \quad P_2 = \left(\frac{E}{c}, -\vec{p} \right)$$

4-momenta after collision:

$$P_1 = \left(\frac{E'}{c}, \vec{q} \right) \quad P_2 = \left(\frac{E'}{c}, -\vec{q} \right)$$

Total energy is conserved $\implies 2E = 2E'$
 $\implies E = E' > \text{rest energy} = M_0 c^2 = 100 m_0 c^2$

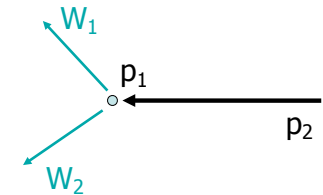
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Experiment 2

Before collision

$$P_1 = (m_0 c, \vec{0}), \quad P_2 = \left(\frac{E'}{c}, \vec{p} \right)$$

Total energy is $E_1 = E' + m_0 c^2$



Use previous result $2m_0 c^2 E_1 = E_2^2$ to relate E_1 to total energy E_2 in the centre of mass frame

$$2m_0 c^2 E_1 = E_2^2$$

$$\implies 2m_0 c^2 (E' + m_0 c^2) = (2E)^2 > (200 m_0 c^2)^2$$

$$\implies E' > (2 \times 10^4 - 1) m_0 c^2 \approx 20,000 m_0 c^2$$

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Photons and Wave 4-Vectors

- Monochromatic plane wave: $\sin(\omega t - \vec{k} \cdot \vec{x})$
- \vec{k} is the wave vector, $|\vec{k}| = \frac{2\pi}{\lambda}$; ω is the angular frequency, $\omega = 2\pi\nu$
- The phase $\frac{1}{2\pi}(\omega t - \vec{k} \cdot \vec{x})$ is the number of wave crests passing an observer

Invariant: $\omega t - \vec{k} \cdot \vec{x} = (ct, \vec{x}) \cdot \left(\frac{\omega}{c}, \vec{k} \right)$

Position 4-vector Wave 4-vector

- 4-momentum $P = \left(\frac{E}{c}, \vec{p} \right) = \hbar \left(\frac{\omega}{c}, \vec{k} \right) = \hbar K$

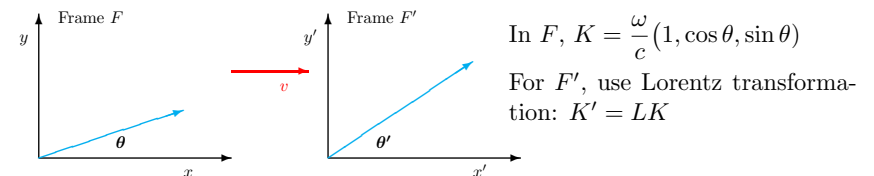


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Relativistic Doppler Shift

For light rays $\omega = c|\vec{k}|$ so $K = \left(\frac{\omega}{c}, \vec{k} \right)$ is a null vector

and can be written $K = \frac{\omega}{c}(1, \vec{n})$ where $|\vec{n}| = 1$.



In F , $K = \frac{\omega}{c}(1, \cos \theta, \sin \theta)$

For F' , use Lorentz transformation: $K' = LK$

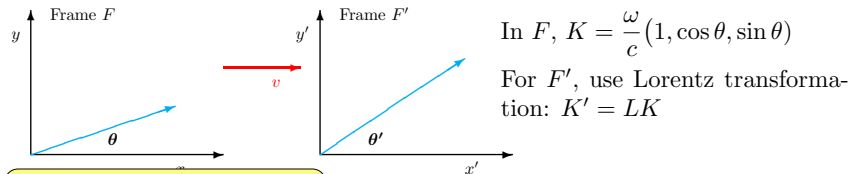
$$\begin{pmatrix} \omega'/c \\ (\omega'/c) \cos \theta' \\ (\omega'/c) \sin \theta' \end{pmatrix} = \begin{bmatrix} \gamma & -\gamma v/c & 0 \\ -\gamma v/c & \gamma & 0 \\ 0 & 0 & 1 \end{bmatrix} \begin{pmatrix} \omega/c \\ (\omega/c) \cos \theta \\ (\omega/c) \sin \theta \end{pmatrix}$$



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Relativistic Doppler Shift

For light rays $\omega = c|\vec{k}|$ so $K = \left(\frac{\omega}{c}, \vec{k}\right)$ is *a null vector*
 and can be written $K = \frac{\omega}{c}(1, \vec{n})$ where $|\vec{n}| = 1$.



In F , $K = \frac{\omega}{c}(1, \cos \theta, \sin \theta)$
 For F' , use Lorentz transformation: $K' = LK$

$\omega' = \gamma \left(\omega - \frac{v\omega \cos \theta}{c} \right)$ $\omega' \cos \theta' = \gamma \left(\omega \cos \theta - v \frac{\omega}{c} \right)$ $\omega' \sin \theta' = \omega \sin \theta$	$\omega' = \gamma \omega \left(1 - \frac{v}{c} \cos \theta \right)$ $\tan \theta' = \frac{\sin \theta}{\gamma \left(\cos \theta - \frac{v}{c} \right)}$	Note there is a transverse Doppler effect even when $\theta = \frac{1}{2}\pi$
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Radiation from an accelerating charged particle

• Rate of radiation, R , known to be invariant and proportional to $|\vec{a}|^2$ in instantaneous rest frame.

• But in instantaneous rest-frame $A \cdot A = -|\vec{a}|^2$

• Deduce $R \propto A \cdot A = -\gamma^6 \left(\left(\frac{\vec{v} \cdot \vec{a}}{c} \right)^2 + \frac{1}{\gamma^2} \vec{a}^2 \right)$

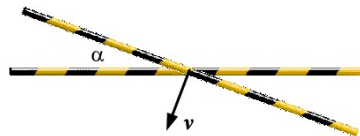
• Rearranged: $R = \frac{e^2}{6\pi\epsilon_0 c^3} \gamma^6 \left[|\vec{a}|^2 - \frac{(\vec{a} \times \vec{v})^2}{c^2} \right]$

Relativistic Larmor Formula

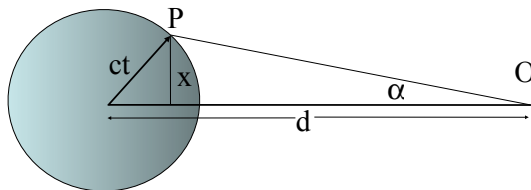
If $\vec{a} \parallel \vec{v}$, $R \propto \gamma^6$, but if $\vec{a} \perp \vec{v}$, $R \propto \gamma^4$

Motion faster than light

1. Two rods sliding over each other. Speed of intersection point is $v/\sin \alpha$, which can be made greater than c .



2. Explosion of planetary nebula. Observer sees bright spot spreading out. Light from P arrives $t = d\alpha^2/2c$ later.



$$t = \frac{d\alpha^2}{2c} \approx \frac{x}{c} \frac{\alpha}{2} \ll \frac{x}{c}$$