CERN ACCELERATOR SCHOOL 2012:

TECHNICAL ASPECTS: MAGNETIC SYSTEM DESIGN

Thomas Thuillier
LPSC,
53 rue des Martyrs
38026 Grenoble cedex
France
E-mail: thuillier@lpsc.in2p3.fr

L·PSC
Grenoble
Laboratoire de Physique
Subatomique et de Cosmologie

OUTLINE

- **Basics of Magnetostatic**
- **Permanent Magnets**
- **Room Temperature Coils**
- **Superconducting Coils**

Biot - Savard Law

- An electrical current flow I in a wire of length dl generates an elementary magnetic field dB at point M:

- $d\vec{B}(M) = \frac{\mu_0 I}{4\pi} \frac{\vec{dl}(P) \times \overrightarrow{PM}}{PM^3}$

- *For an arbitraty curve* C, *the magnetic Field is:*

- $\vec{B}(M) = \frac{\mu_0 I}{4\pi} \int_C \frac{\vec{dl}(P) \times \overrightarrow{PM}}{PM^3}$

  - *where point P follows* C *and* $\vec{dl}(P)$ *is the local tangent to the curve* C

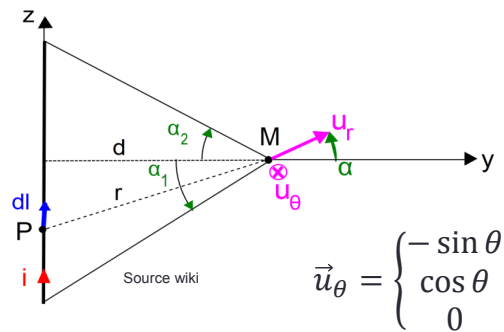- *For a Volumic conductor* V, *we define a volumic current density* J:

- $\vec{B}(M) = \iiint_V \frac{\mu_0}{4\pi} \frac{\vec{J} dV \times \overrightarrow{PM}}{PM^3}$

Magnetic Field Generated by a wire

- For a finite wire:

- $\vec{B}(M) = \frac{\mu_0 I}{4\pi d} (\sin \alpha_2 - \sin \alpha_1) \vec{u}_\theta$

- *For an Infinite wire:*
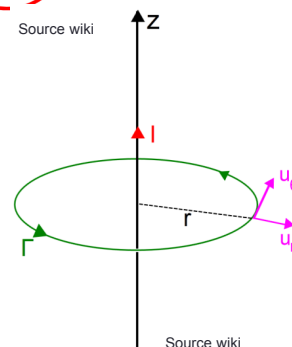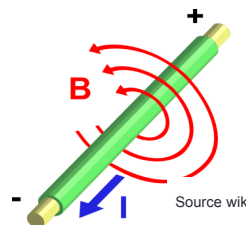
- $\vec{B}(M) = \frac{\mu_0 I}{2\pi d} \vec{u}_\theta$

$$\vec{u}_\theta = \begin{cases} -\sin\theta \\ \cos\theta \\ 0 \end{cases}$$

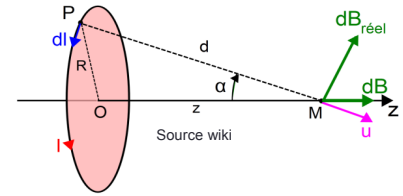$$\vec{u}_r = \begin{cases} \cos\theta \\ \sin\theta \\ 0 \end{cases}$$

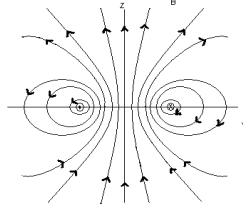Source wiki

Source wiki

Source wiki

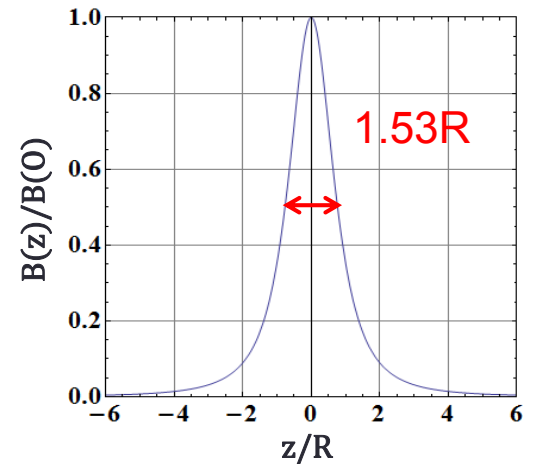# Magnetic Field generated by a single loop

- Magnetic field intensity on the loop axis:

- $\vec{B}(M) = \frac{\mu_0 I}{2R} \sin^3 \alpha \, \vec{z} = \frac{\mu_0 I}{2R} \frac{1}{(1+\left(\frac{z}{R}\right)^2)^{3/2}}$

- $B(O) = \frac{\mu_0 I}{2R}$

- $B(z_{1/2}) = \frac{B(O)}{2} \rightarrow 2z_{1/2} \sim 1.53R$

1.53R

B(z)/B(O)

z/R

- Magnetic Field out of the axis: non trivial formula

Magnetic Field Generated by a flat solenoid

- Consider an axial Coil with N turns covering 2a along Z
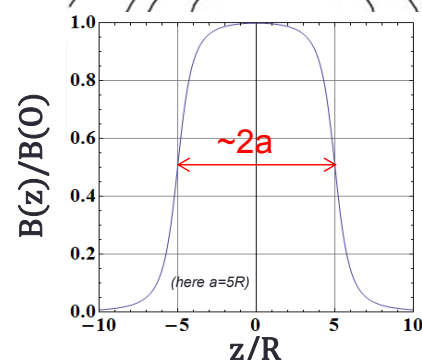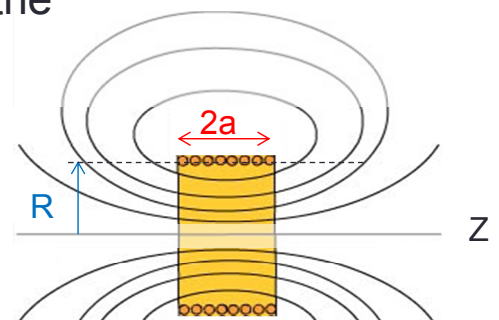- Total loop current in the coil is defined by the **Ampere.turns= N×I**

- $B(z) = \frac{\mu_0 NI}{4R} \left(\frac{1+\frac{z}{a}}{\sqrt{1+\left(\frac{z+a}{R}\right)^2}} + \frac{1-\frac{z}{a}}{\sqrt{1+\left(\frac{z-a}{R}\right)^2}} \right)$

2a

R

Z

- Field Intensity at the Coil center:

- $B(O) = \frac{\mu_0 NI}{2R} \frac{1}{\sqrt{1+\left(\frac{a}{R}\right)^2}}$

- Inductance

- $L = \mu_0 N^2 \frac{\pi R^2}{2a}$

B(z)/B(O)

~2a

(here a=5R)

z/R

Magnetic Field Generated by a Thick Coil

- A rough analytical estimate of B(0):

  - $B(O) = \dfrac{\mu_0 NI}{2<R>} \dfrac{1}{\sqrt{1+\left(a/_{<R>}\right)^2}}$

  - $N = N_z \times N_R$
  - $<R> = (R_1 + R_2)/2$

- Real Field should be studied by simulation

  - 2D FreeWare: Poisson Superfish, FEMM…

$B_z(r)$ (Z=0)

$B_z(z)$ On axis (R=0)

Poisson (LANL,USA)
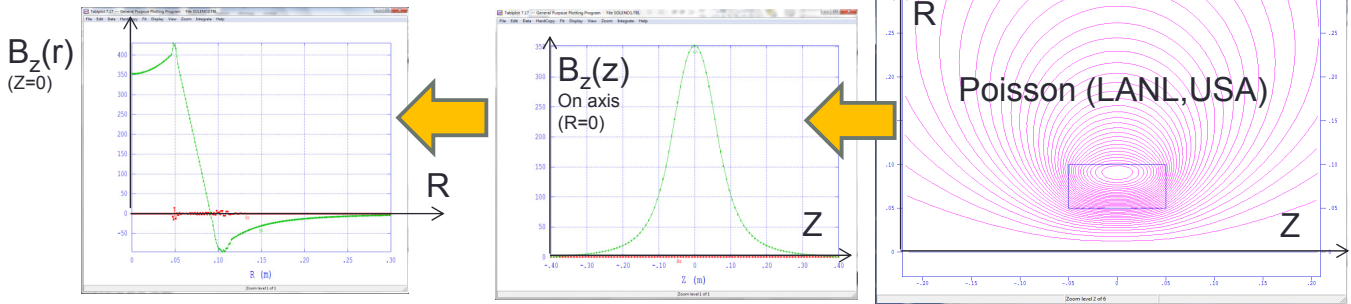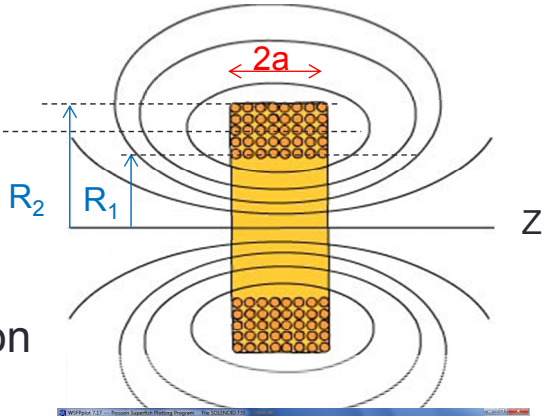
Forces on Coil

- Any magnetic Field B acting on a volumic current loop generates a magnetic Force:

  - $F = \int J \overrightarrow{dl} \times \vec{B} \; dV$

  $\vec{F}$

  $\vec{B}$

  J $\overrightarrow{dl}$
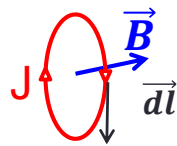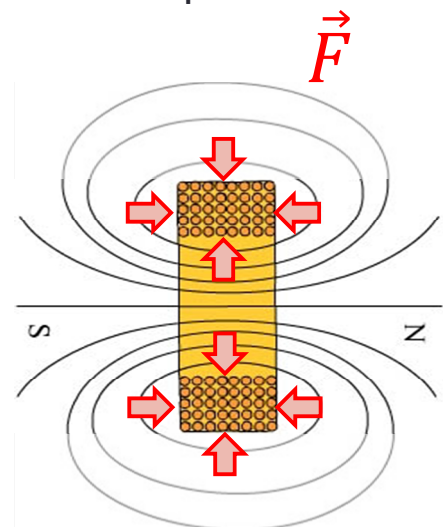
 - the magnetic field generated by the coil induces a global force field acting on the coil

  - So the epoxy between the wire loops does insulate and hold magnetic forces

- Forces must be computed at the time of conception to carefully choose the material able to hold this force field

Magnetic Properties of Materials: Permeability μ

- Magnetic permeability μ
  - μ Depicts the way a material acts in presence of an <u>externally applied auxilliary magnetic Field H</u>
  - B is the resulting magnetic field intensity <u>inside the material</u>
  - $B = \mu H = \mu_0 \mu_r H$
  - $\mu_0 = 4\pi \times 10^{-7} \frac{Henry}{m}$ is the permeability of vacuum ($B = \mu_0 H$ in vacuum)

  - $\mu_r = \frac{\mu}{\mu_0}$ is the relative permeability of a material
- The magnetic property of a material is defined by its <u>internal magnetization</u> M:
  - $B = \mu H = \mu_0 \mu_r H = \mu_0 (H + M)$
  - $M = \frac{\mu - \mu_0}{\mu_0} H = (\mu_r - 1)H$
- Magnetic Susceptibility: X_m
  - $X_m = \mu_r - 1 \; \rightarrow M = X_m H$
- The magnetization M <u>modifies the local magnetic field H intensity outside the material</u>

$\vec{H}$

$\vec{M}$

$\mu_r \geq 1$
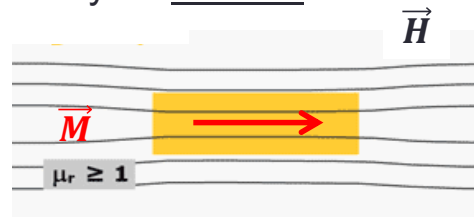
Microscopic origin of magnetism

i $\vec{s}$
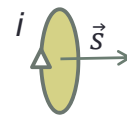
- The Ampère Model
  - A magnetic material can be modelized by a set of microscopic individual dipolar magnetic moments $\vec{\mu} = i\vec{s}$ generated by electron circulation around atoms
    - i **current in the loop**
    - $\vec{s}$ **oriented area of the loop**
  - Each individual current loop generates an infinitesimal magnetic field B
  - The global magnetization of a material appears if the elementary magnetic dipole moments are aligned in the same direction
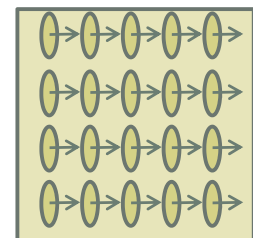
Material with all
Individual magnetic
moments aligned
=> High magnetization
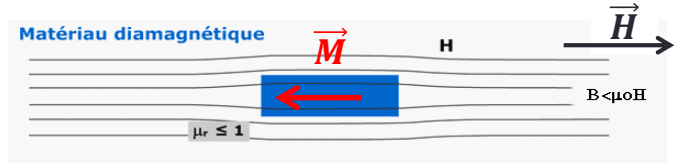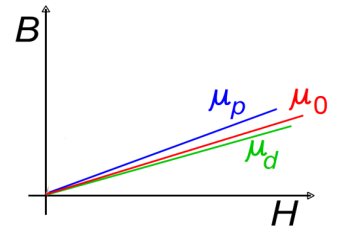
Diamagnetism - Paramagnetism

- $B = \mu_0 \mu_r H = \mu_0(H + M)$
- $M = X_m H$
- Diamagnetism: the material tends to expell the field lines
  $\rightarrow X_m < 0$
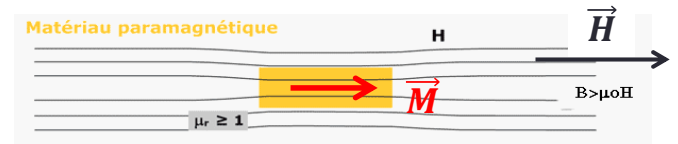 - M is opposed to H
  - Water, earth, Cu, Hg, Au, Bi… ($|X_m| \ll 1$)
  - Superconductors: X_m=-1!!!

- Paramagnetism: the material sucks up the field lines $\rightarrow X_m > 0$
- M in the same direction as H
- Au, Cs, W, Mg… ($X_m \ll 1$)

Ferromagnetism
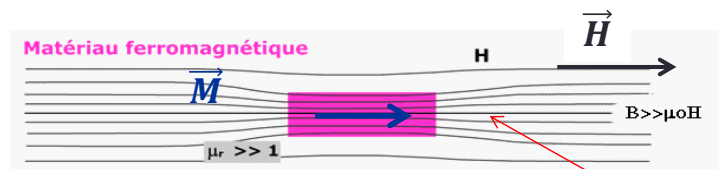

- $B = \mu_0 \mu_r H = \mu_0(H + M)$
- $M = X_m H$
- Ferromagnetic materials feature a high capacity to suck up magnetic field lines ($\mu_r \gg 1, so\ X_m \gg 1$)
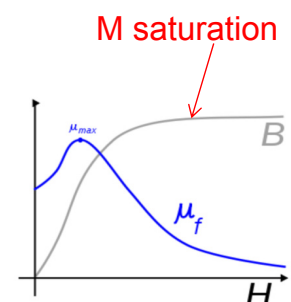- M saturates above a given H
- M is a function of Temperature: $X_m = f(T)$
- Ferromagnetism damps to paramagnetism above the <u>Curie Temperature</u> T_c

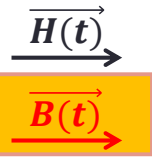Near to a ferromagnetic Material, B intensity can be highly amplified

Ferromagnetic Material	μ_r	Curie Temp. °C
Co	250	1 115
Fe	10 000	770
Mu-metal	150 000	420
Ni	600	358

M saturation

Ferromagnetism

- ## Hysteresis Curve:
  - A ferromagnetic material keeps the memory of its former magnetization state

$\overrightarrow{H(t)}$

$\overrightarrow{B(t)}$

3 Remanence Br:
When H→0, The material keeps a part of its magnetization: **the Remanent field Br**

2 Saturation of magnetization: Above H>Hs, the magnetization saturates to Bs

4 Coercivity Hc:
The absolute value of H<0 for which the magnetization B →0 from the magnetization saturation

1 First magnetization curve: If B=0 prior to applying H, the material magnetizes following the curve A

5 Magnetization reversal: When H<-Hc, the elementary spins of material orientates toward the new H opposite direction and magnet saturates to -Bs

6. And so on…
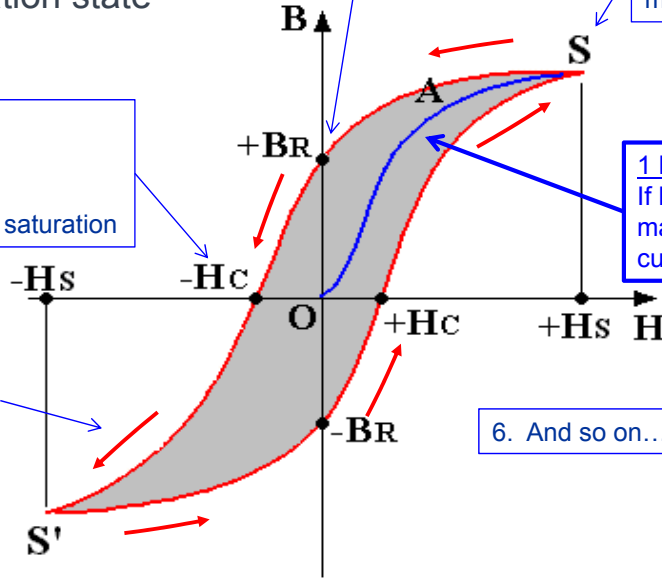
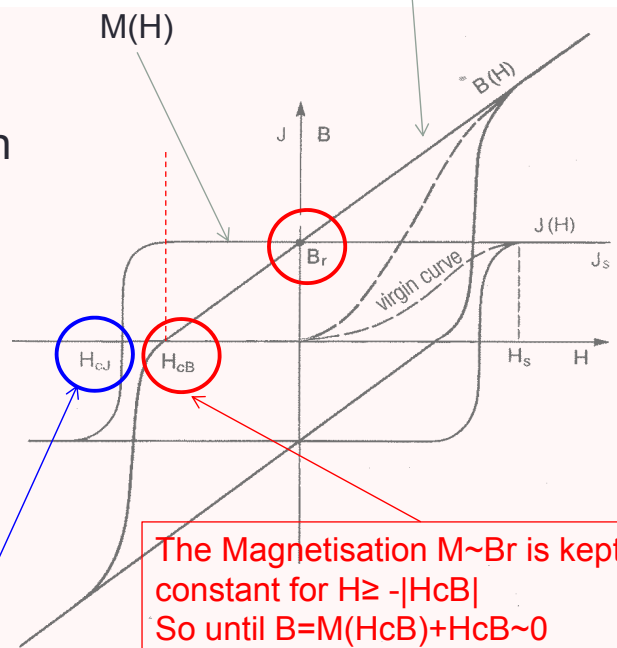# Permanent Magnets

- Permanent magnet are ferromagnetic materials with High Coercivity and High Magnetization values
- Sm_2Co_{17} magnets
  - Br~0.9-1.1T
  - H_{cJ}~2.5-0.8 T
  - T<200°C
- FeNdB magnets
  - Br~1.1-1.5 T
  - H_{cJ}~3.3-1.1 T
  - T~20-60° for reliable operation

B(H)=M(H)+H

M(H)

The Magnetisation M~Br is kept constant for H≥ -|HcB|
So until B=M(HcB)+HcB~0

For -|HcJ|≤H≤ -|HcB|
M decreases +/- rapidly to 0

Plot extracted from Vacuumschmelze documentation

Forces on magnets

- The force acting on a magnetic material volume V is:
  - $\vec{F} = \iiint \overrightarrow{J_m} \times \vec{B} \, dV$
    - J_m is the magnetization current density caused by aligning atomic magnetic dipoles.
    - $\overrightarrow{J_m} = \vec{\nabla} \times \vec{M}$

- The global magnetic force for a mixture of electromagnet and ferromagnet is :
  - $\vec{F} = \iiint (\overrightarrow{J_m} + \vec{J}) \times \vec{B} \, dV$
    - J is the electrical current density in an electromagnet
- The force should be computed numerically
  - Poisson 2D, Tosca/Opera 3D, Radia…

repulsive force

attractive force
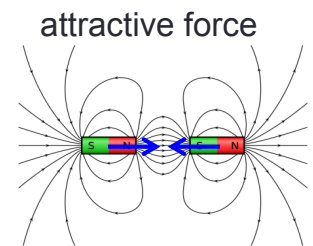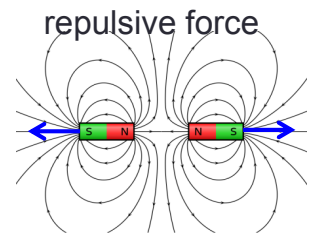
Designing a structure with a set of permanent magnets

- The working point of each individual magnet must be carefully checked
  - 3D Magnetic Simulation is necessary to Check the working point of each individual magnet vs T°
  - 3D Freeware: Radia (ESRF, requires Mathematica)
  - 3D Software: Opera, Ansys…

$\frac{\vec{H}.\vec{M}}{M}$ inside a hexapole
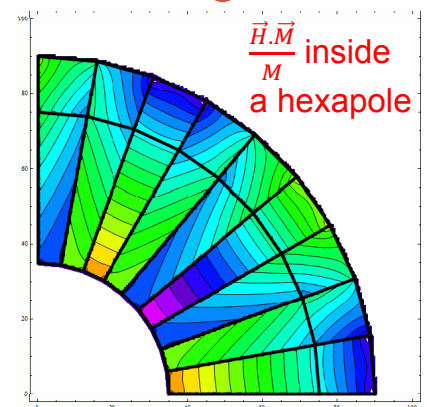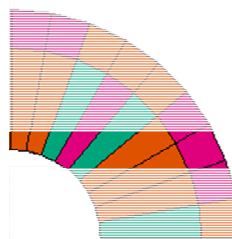
¼ hexapole simulated with Radia/Mathematica

The magnet 1 generates an auxilliary field H_1 in the space around it.
In the magnet 2, $B_2 = M_2 - |H_1|$.
One must check that $|H_1| < H_{cB}$

H_1
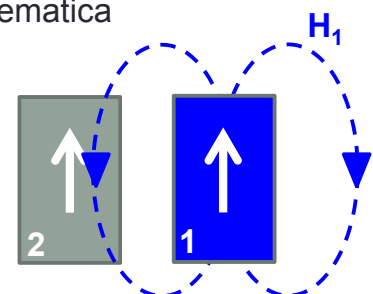
Copper Coil at room temperature

- Three families for three range of magnetic field
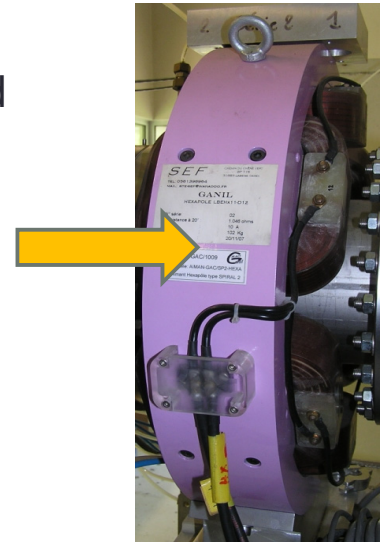 - If J<4 A/mm2 => no cooling required
    - Eg: magnetic Steerer
    - Right picture: hexapole to correct dipole aberrations
    - Generates field up to ~0.01-0.02 Tesla

  - J~10-20 A/mm2 => water cooling with 2-10 l/min
    - Classical electro-magnet
    - B~0.1-1 Tesla

  - J~100 -300 A/mm2 => high flow watercooling (20-100 l/min)
    - Bitter Coil, polyhelix coil
    - B~1-35 Tesla (!)

Classical water cooled Copper Coil technology

- J~10-20 A/mm2
- Copper tube with inner cooling water to compensate the Joule Effect
- Epoxy impregnated to insulate and hold electromagnetic forces
- High intensity (200-2000 A)
- Low resistance (1-50 mΩ)
- Small turn number (10-300)
- B~0.1-0.5 T on axis

Outward spiral   Inward spiral

4 double pancake coil

1 double pancake coil =1 copper tube
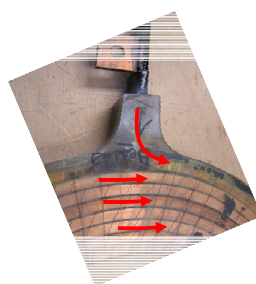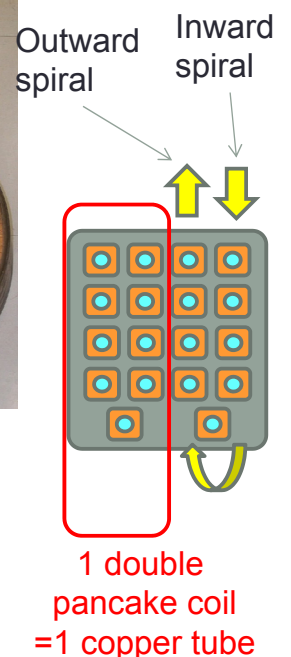
Passing from inward spiral to outward spiral, keeping same direction of coil rotation

Classical Copper Coil – Electric properties

Electrical engineering:

- Coil Length : $L \sim 2\pi \langle R \rangle \times N_{turn}$ (see slide 7)
- Coil Resistance:
  - $R = \frac{\rho L}{s}$ ~ 10-100 mΩ
  - Copper resistivity $\rho(20°C) \sim 1.7 \times 10^{-8}\Omega.m$
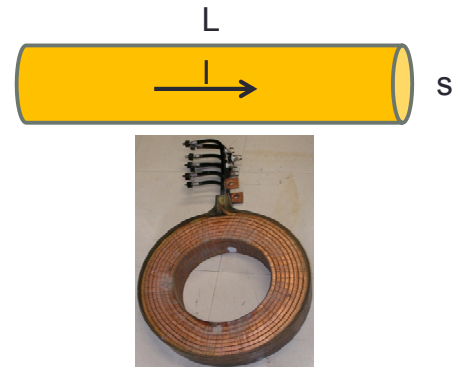- Dissipated power (Joule effect):
  - $P = RI^2 \sim 10 - 100 \ kW$!
- Forces on coil to be computed
  - F~100-1000 N
- Coil Inductance to be computed from the stored magnetic energy
  - $\frac{1}{2}LI^2 = \frac{1}{2}\iiint \vec{B}.\vec{H}dV$
  - L~1-100 mH

Classical Copper coil – Water flow and pressure drop

- Waterflow engineering
  - De-ionized water is mandatory
  - Volume Flow rate and Pressure drop in the coil given by the Poiseuille law:

- $Q = \dfrac{\pi R^4}{8\eta L}\Delta P$

- $Q = \dfrac{dV}{dt}$ volume flow rate

- η fluid viscosity ($\eta = f(T)$ see table)
- R, L are pipe radius, pipe length
- ΔP pressure drop through the pipe,
- usually fixed by the water pump
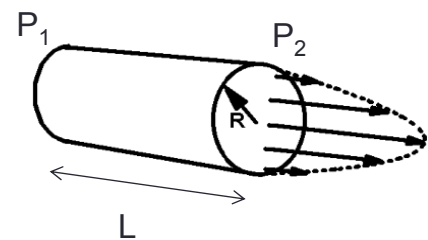
Water temperature (°C)	Water Viscosity (Pa.s)
0	1.8×10⁻³
20	1.0×10⁻³
50	0.55×10⁻³
100	0.28×10⁻³

Heat Exchange in a water cooled copper coil

- Water is an excellent cooler
- The heat exchange balance in the coil is performed by <u>forced convection</u>:
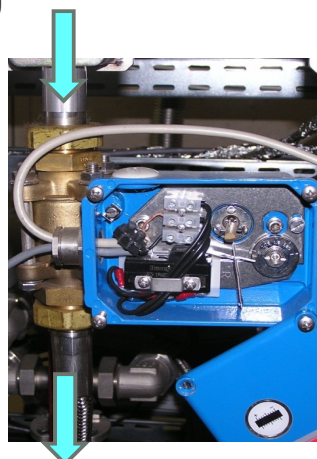
  - $W = hS\Delta T$ power dissipated in the fluid
    - S surface of exchange $S = L \times p = L \times 2\pi R$
    - ΔT elevation of temperature in the coil
    - h mean coefficient of heat exchange W/m²/°C
    - $h{\sim}5000$ for liquid water
    - h can be calculated
  - A well balanced water cooled copper coils features a $\Delta T \sim 20 - 30°C$
- Another approach to calculate the dissipated power:
  - $W = \dot{m}C_p\Delta T$
  - $\dot{m} = \rho\dfrac{dV}{dt}$ is the mass flow rate water
  - $C_p = 4{,}18kJ/kg/K$ is the specific heat of water
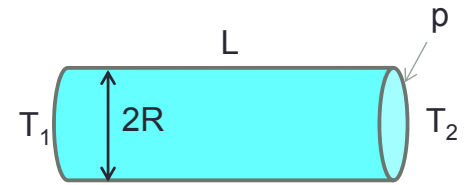
Copper Coil Interlocks

- Interlocks are there to check the good cooling of the coil
  - Water flow threshold
    (on the low pressure side)
  - Thermoswitch 60-70°C set in serial
- The power supply is stopped in case of a lack of cooling

Thermoswitch

Example of
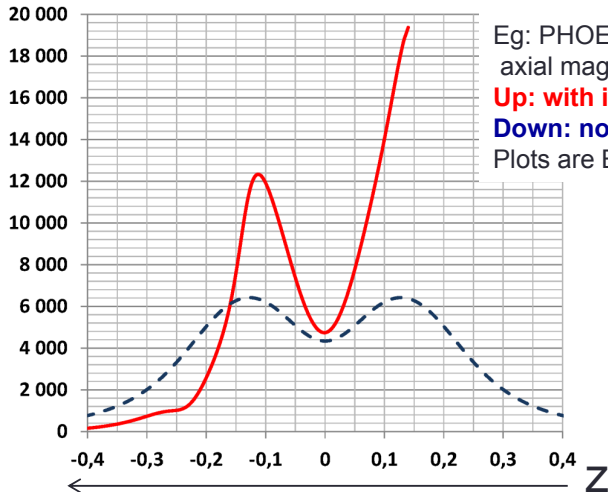Waterflow switch

Combining coils and ferromagnetic materials

- The high magnetization saturation M~2.15 T of low carbon Iron Alloy is very useful to design relatively high magnetic fields structure using room temperature magnets
 - Dipole, quadrupoles, ECR Ion sources…

Magnetic Field Lines

With iron

Z

Without iron

Z

Eg: PHOENIX V2 ion source
axial magnetic structure
Up: with iron
Down: no iron
Plots are Bz(z) on axis (Gauss)
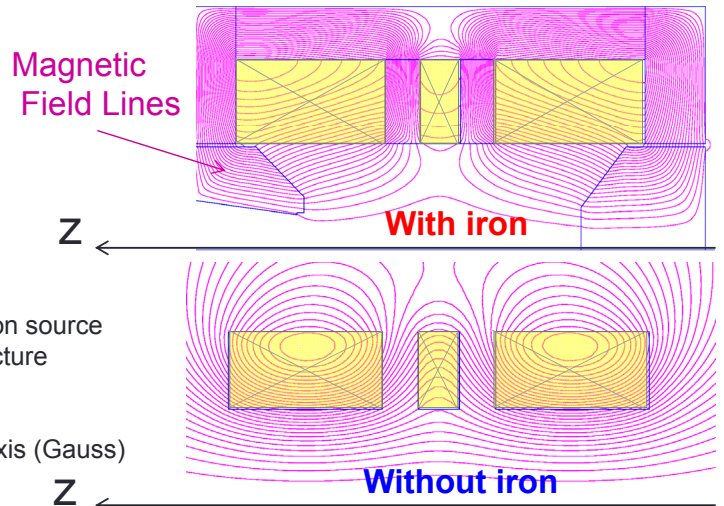
- The magnetic flux generated by the coils is totally canalized by a well optimized soft iron geometry to reach higher magnetic field intensity
  - Magnet Designers are surfing on $div(\vec{B}) = 0$

High magnetic Field Copper Coil

- The Bitter Coil technology
  - Thin (punched) Cu discs are stacked one on each other, separated by an electrical insulator
  - The stack is mechanically clamped to allow a good electrical contact between Cu discs and magnetic force containement
  - The water cooling is done axially through holes performed in the discs
  - Heat exchange through forced convection is highly optimized (h>10000-30000)
  - J~100-300 A/mm^2
  - B~20-35 Tesla!
  - P~5-20 MW!
  - Q~100-400 l/s!
  - Works better at high field (risk of loosy contact between discs for low J
  => destructive arc)

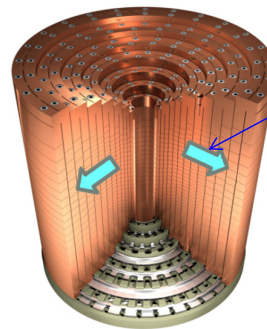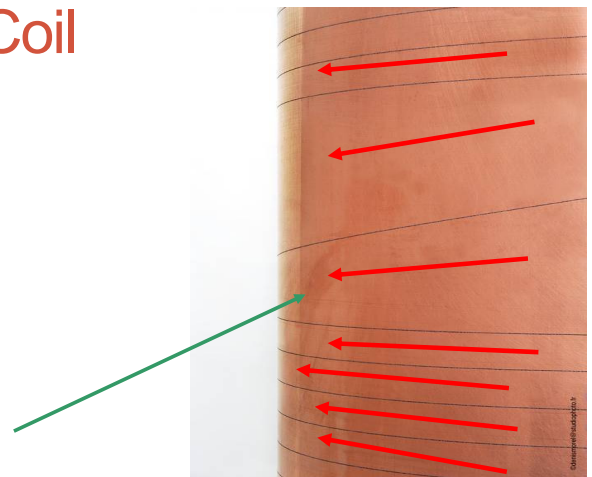Axial water flow

Electrical insulator

Current flow

Tallahassee, USA
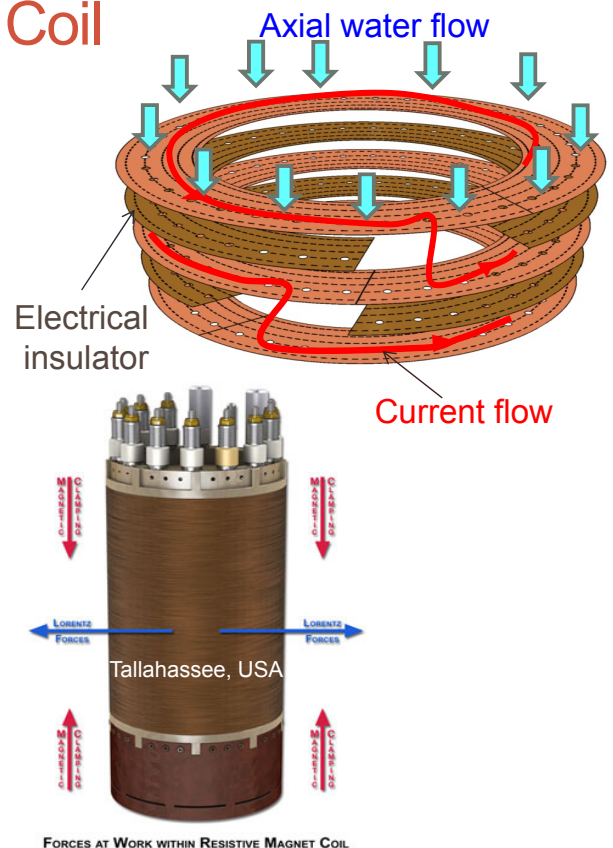
High magnetic Field Copper Coil

- ## The PolyHelix Technique
  - The coil is directly produced in a raw Cu cylinder (electro-discharge machining)
  - The coil is radially cooled
  - The current density can be continuously changed
  - The continuous change of the helix pitch allows a local adaptation of the current density and enables to tune the magnetic field profile finely
  - The small gap are spaced with kapton insulators
  - J~100-300 A/mm2
  - B~20-35 Tesla!
  - P~5-20 MW!
  - Q~100-400 l/s!

Axial water flow

Grenoble, France

High magnetic Field Coil environement

LNCMI

- Shematic of a DC High Field Facility (Nijmegen, Tallahassen, Grenoble, Tsukuba...)

Cellules de distribution 15 KV

Transformateurs 15KV/400V

Ponts à thyristors

Inverseurs de polarité

Jeu de barres

Switches

Cables

High field magnets

DTA1
TRA1
DTB1
AC
DC
TRB1
TRA2
DTA2
AC
DTB2
DC
TRB2

70 A / cm2

700 A / cm2

30000 A / cm2
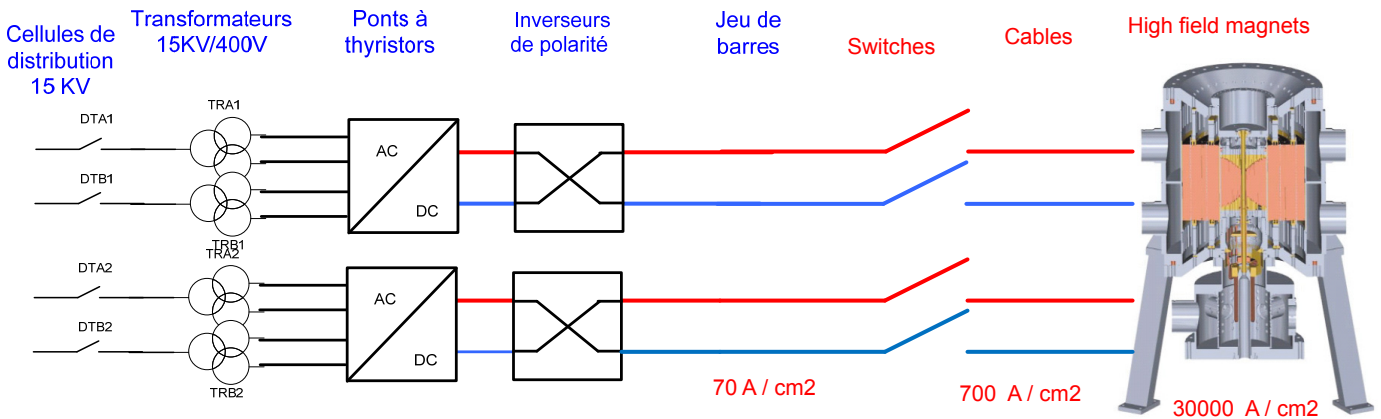
I = 16000 A (20 ppm)
U = 400 V

Aluminum bars to bring the current
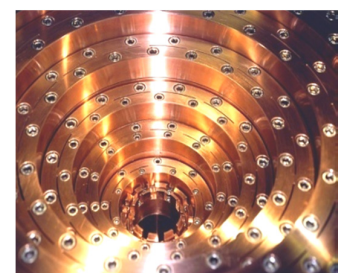
Superconductivity

- Superconductivity (SC) is a state of matter characterized by two specific properties:

  - **A zero electrical DC resistance**: the current flows without any Joule effect loss, so with a zero voltage drop => electrical power saving

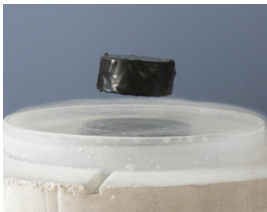 - **The Meissner effect**: When the material makes the transition between normal to SC state, it <u>expells out all its magnetic field lines</u>

    - Large currents are flowing on the surface of the SC that exactly compensate the externally applied magnetic field to reach B=0 inside
    - The penetration depth of currents inside the SC is $\lambda \sim 100$ nm! (λ=London penetration depth)

Spontaneous levitation of a SC above a magnet, Induced by the surface currents Generated by the Meissner effect (Source: wikipedia)

(Source: wikipedia)

Meissner Effect

http://hyperphysics.phy-astr.gsu.edu
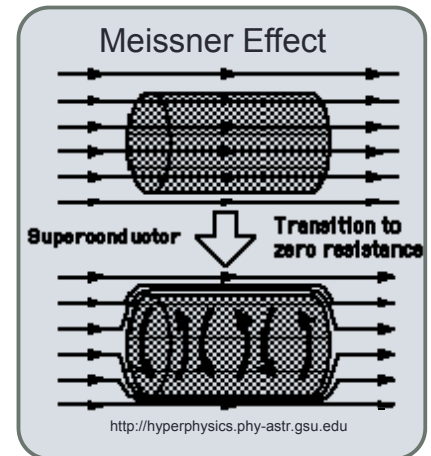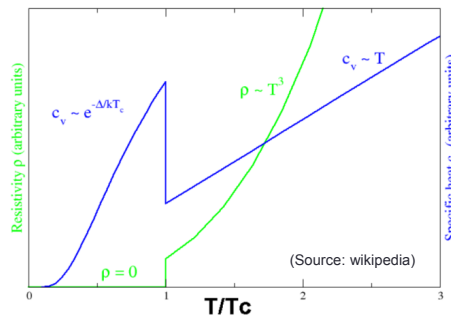
Condition to keep Superconductivity State

- Threshold temperature Tc:

  - $T < T_c(J,H)$
  - $T \sim 4\text{-}20$ K

- Threshold Magnetic Field Hc:

  - $H < H_c(T,J)$
  - $H \sim 2\text{-}12$ T

- Limited Current density Jc:

  - $J < J_c(H,T)$
  - $J \sim 0.1\text{-}10$ kA/mm2

- SC transition= 2D surface in (T,B,J) space
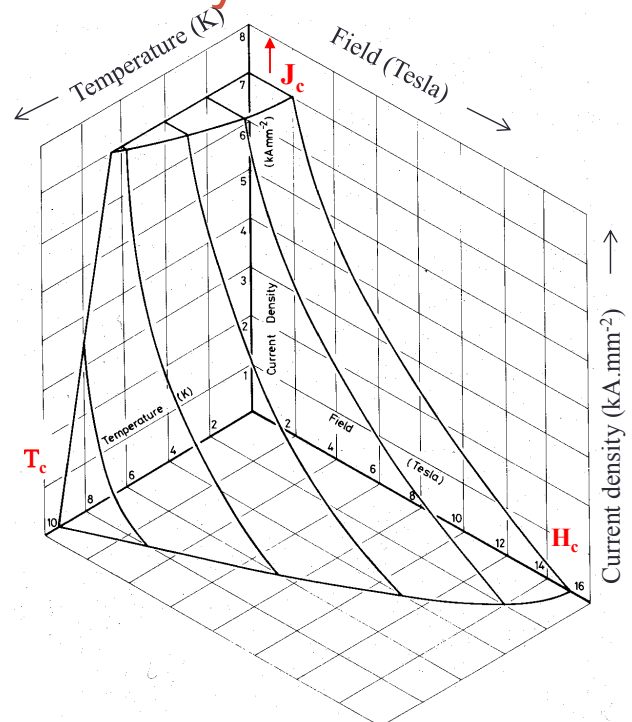
Source: M. Wilson, JUAS 2006

Type I & II Superconductors

- **Type I: Low Temperature SC (LTS)**
  - NbTi, Nb_3Sn…

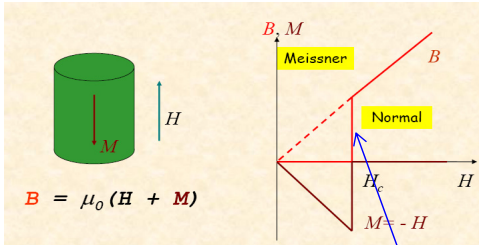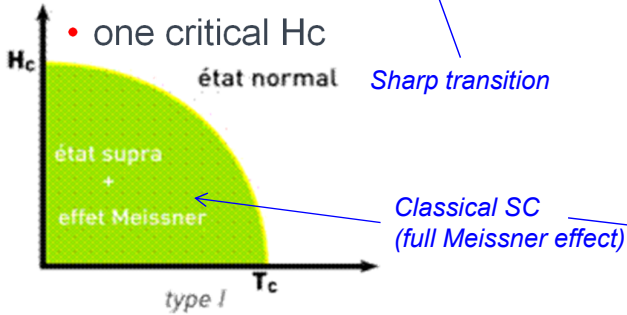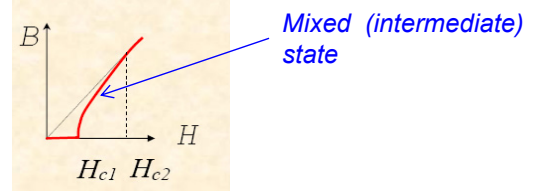$$B = \mu_0(H + M)$$

  - one critical Tc
  - one critical Hc

Sharp transition

Classical SC (full Meissner effect)

- **Type II: High(er) Temperature SC (HTS)**
  - YBCO, Bi-2223, MgB_2…

Mixed (intermediate) state

  - H<Hc1 classical Meissner effect
  - Hc1<H<Hc2 some magnetic vertexes penetrates the HTS

Mixed state with SC conduction (AND Non SC areas (vertex)
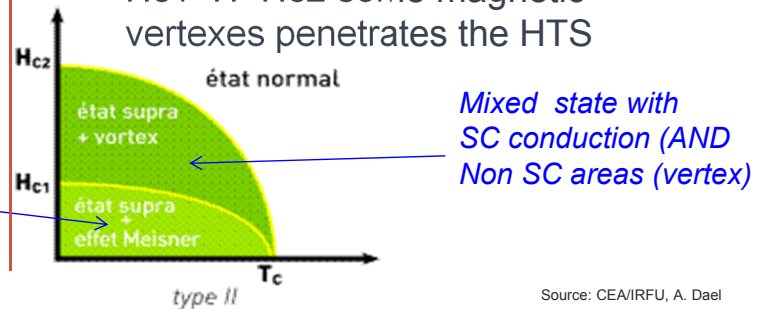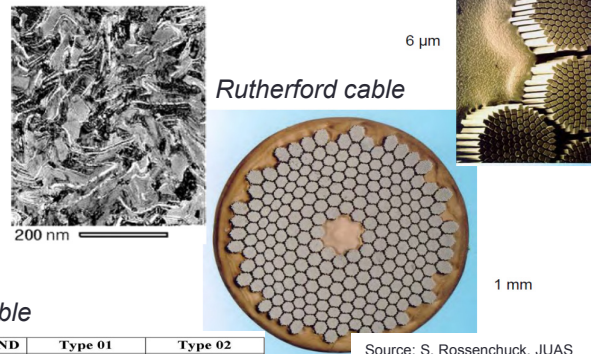
Source: CEA/IRFU, A. Dael

SC wires

- Strand Wire
  - Usually combined with Cu
 - Cu is a good conductor and reduces heat when NbTi is not in SC state
- Cable
  - A set of strands to produce high current cables
  - e.g. LHC cable

Rutherford cable

LHC SC cable

STRAND	Type 01	Type 02
Diameter (mm)	1.065	0.825
Cu/NbTi ratio	1.6-1.7 ± 0.03	1.9-2.0 ± 0.03
Filament diameter (μm)	7	6
Number of filaments	8800	6425
Jc (A/mm²) @1.9 K	1530 @ 10 T	2100 @ 7 T
μ_0M (mT) @1.9 K, 0.5 T	30 ±4.5	23 ±4.5
CABLE	**Type 01**	**Type 02**
Number of strands	28	36
Width (mm)	15.1	15.1
Mid-thickness (mm)	1.900 ±0.006	1.480 ±0.006
Keystone angle (degrees)	1.25 ±0.05	0.90 ±0.05
Cable Ic (A) @ 1.9 K	13750 @ 10T	12960 @ 7T
Interstrand resistance (μΩ)	10-50	20-80

Source: S. Rossenchuck, JUAS
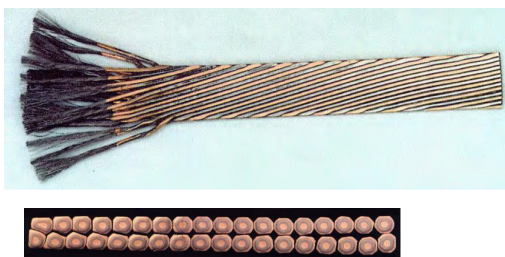
Conductor for NMR magnet
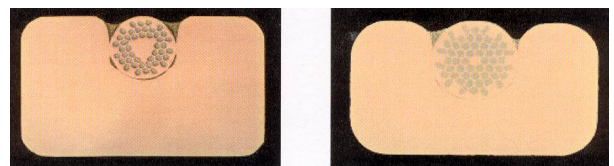
Wire in Channel
a x b = 1.10 x 1.70 mm² : 2.15 x 4.25 mm², Cu : NbTi ratio 10 to 20

Source: A. Dael, IRFU

Challenges to design a SC coil

- ## Electromagnetic Design
  - Design the appropriate magnetic field with an appropriate current density
- ## Mechanical engineering
  - compute magnetic forces, design a technique to clamp the coil efficiently at low temperature
- ## Material Science, superconductivity
  - Use a SC cable in an appropriate way
- ## Cryogenic and vacuum engineering
  - Design the cryogenic system to ensure an appropriate temperature and cooling working point, able to resist to ANY accidental problem
- ## Electronic engineering
  - Design the room and low temperature instrumentation part
  - Build up a quench protection system (see next slides) to damp the huge stored energy

---

Critical Lines at 4.2 K
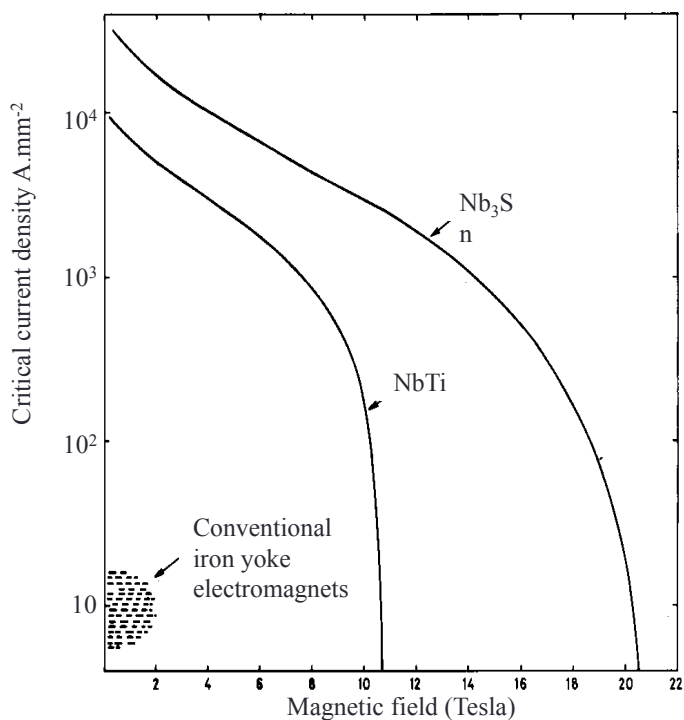
- because magnets usually work in boiling liquid helium, the critical surface is often represented by a curve of current versus field at 4.2K

- niobium tin Nb_3Sn has a much higher performance in terms of critical current field and temperature than NbTi

- but it is brittle intermetallic compound with poor mechanical properties

- note that both the field and current density of both superconductors are way above the capability of conventional electromagnets

M. Wilson Lecture – JUAS 2006

SC cable Quench

- A quench is the name for a local transition of a cable from SC to normal conducting state
  - Once the quench occured, the cable becomes <u>locally resistive</u>: the heat generated may possibly enlarge the non SC area and <u>the quench may propagate and increase dramatically the cable temperature</u> because of Joule Heating
  - <u>RISK OF CABLE DESTRUCTION</u>
  - The Magnet should be designed to resist to a quench
  - Once the quench has occured, the magnetic energy stored is converted into heat. The coil temperature increases and one needs to wait for the cryostat cooling down to magnetize again the coil
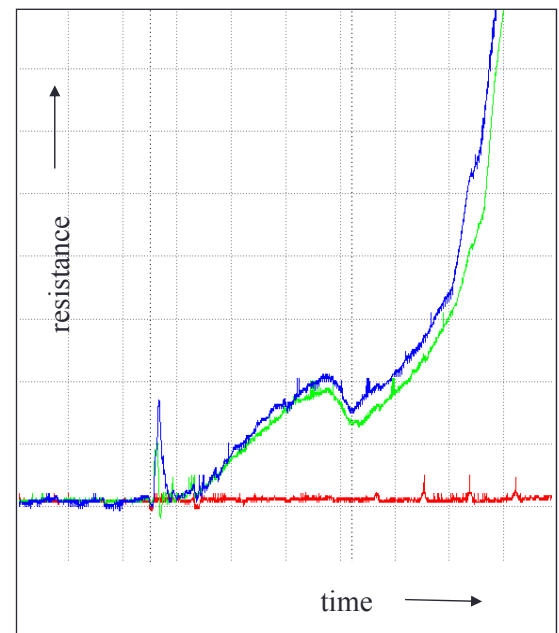

Quench initiation in LHC dipole

Source: M. Wilson Lecture – JUAS 2006


Causes of SC cable Quench

- Training quench
  - **A new coil does not reach directly reach its designed operation current, but undergoes several quenches before reaching it, at currents intensities lower than the expected SC cable properties**
    - The coils epoxy impregnation may crack a little when is it cooled down to low temperature, due to difference in mechanical contraction with the surrounding metal. At early magnetization cycles, micrometric imperfections in the epoxy impregnation of the coil may locally uncompensate the local force acting on the wire F~J.B.R. The local crack of epoxy dissipates a local energy that heats the wire which switches to normal conducting state.
    - A micrometric move of the conductor may also generate a quench.
    - Usually, after several training quenches, the coil reaches its nominal value.
    - Sometimes, it doesn't... This is very bad: The coil is good for garbage!
  - **H>Hc or J>Jc or T>Tc**
    - if the SC cable sees locally a thermodynamic/electromagnetic condition that overtakes its capability, it quenches. It is always the direct, or indirect cause of the quench
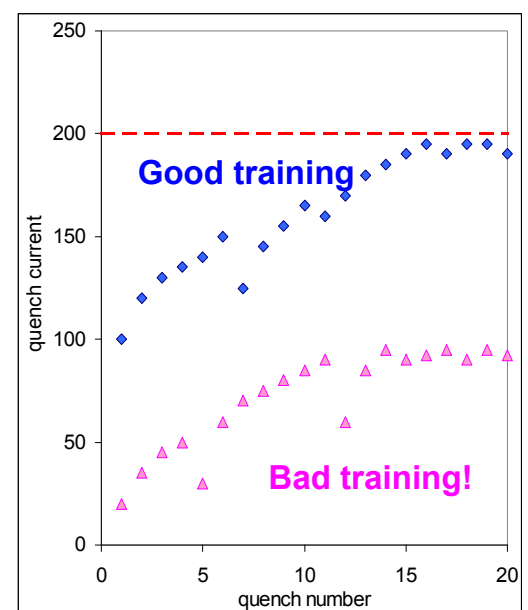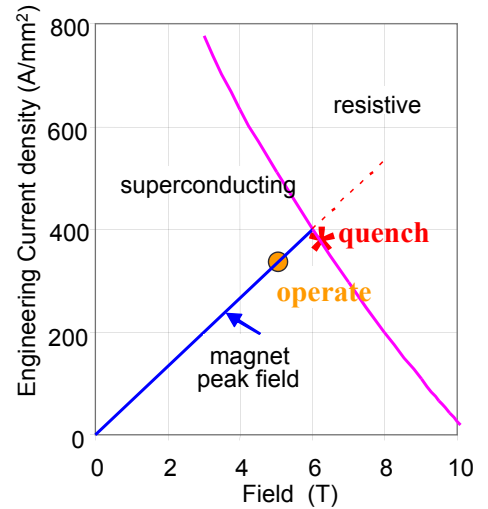

Source: M. Wilson Lecture – JUAS 2006

Coil Load Line – Safety margin

- Magnets are usually designed to work with a current density at 50-80% of the SC limit
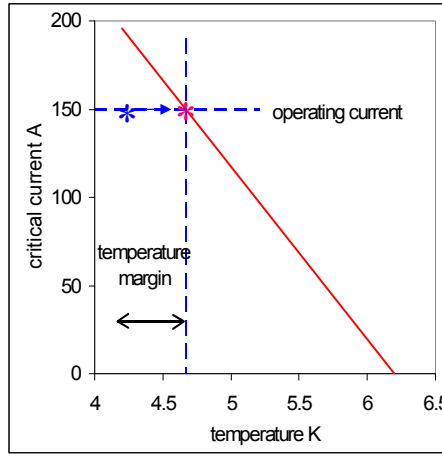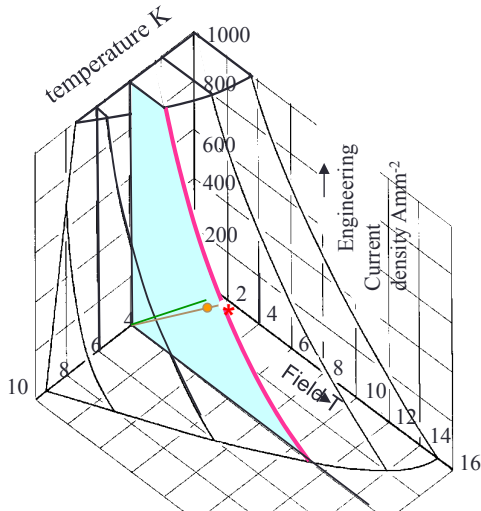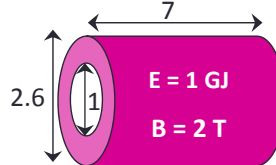

M. Wilson Lecture – JUAS 2006

- As a consequence, this gives a temperature margin that reduces risk of quenching

---

Heat generated by a quench – Cu stabilization

- At low temperature (T~Tc)
  - $\rho_{Cu} \ll \rho_{NbTi}$
  - $\lambda_{Cu} \gg \lambda_{NbTi}$
- If a quench occurs in NbTi, the current will flow in Cu ($\rho_{Cu} \ll \rho_{NbTi}$), and the Joule heat will be much smaller
- The high Cu thermal conductivity will allow the local heat dissipation and the quench may not propagate
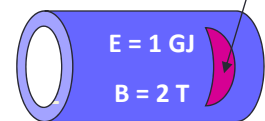
	Cu	NbTi
Electrical Resistivity ρ (Ω.m)	3×10^{-10}	7×10^{-7}
Thermal conductivity λ (W/mK/m²)	350	0.1

Resistive coil (Cu)   SC coil (no Cu)

Resistive part induced by quench

	Resistive Coil	SC Coil
Energy stored	1 GJ	1 GJ
J (A/mm²)	2	2×10 $\Rightarrow$ thickness/10
Total Volume (m³)	32	1.9
Electromagnetic Energy→Heat (J/m³)	32×10^6	$V_{resistive} \sim V_{tot}/10$ $E/V_{res}. \sim 5 \times 10^9$
Final temperature Of resistive part	$\Downarrow$ 65 K	$\Downarrow$ 1400 K

Adapted from :A. Dael, IRFU, Journees accenerateur 2011

Basics of Quench detection / Protection System

- Quench protection with a dump resistor:
  - The stored energy $E = \frac{1}{2}LI^2$ is dumped in an external resistance
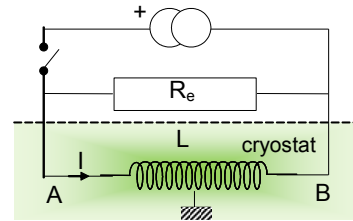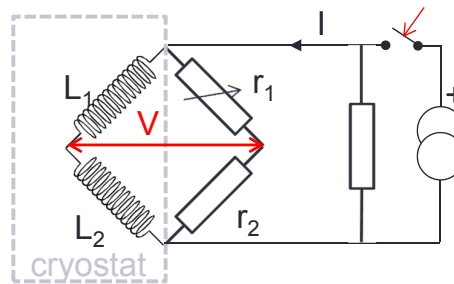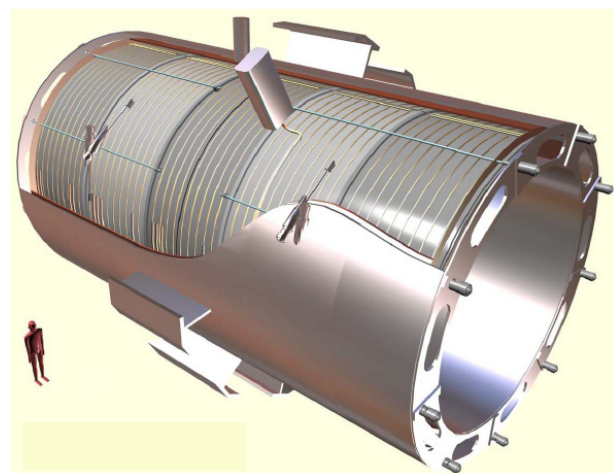

$$I = I_o e^{-\frac{t}{\tau}}$$

$$\tau = \frac{L}{R_e}$$

- Quench detection:
  - $V_{coil} = L\frac{dI}{dt} + rI$ Quench effect
  - Wheatstone Bridge Circuit
    - No quench: bridge equilibrated: V=0
    - Quench: $V_{bridge} \sim rI$ => detection

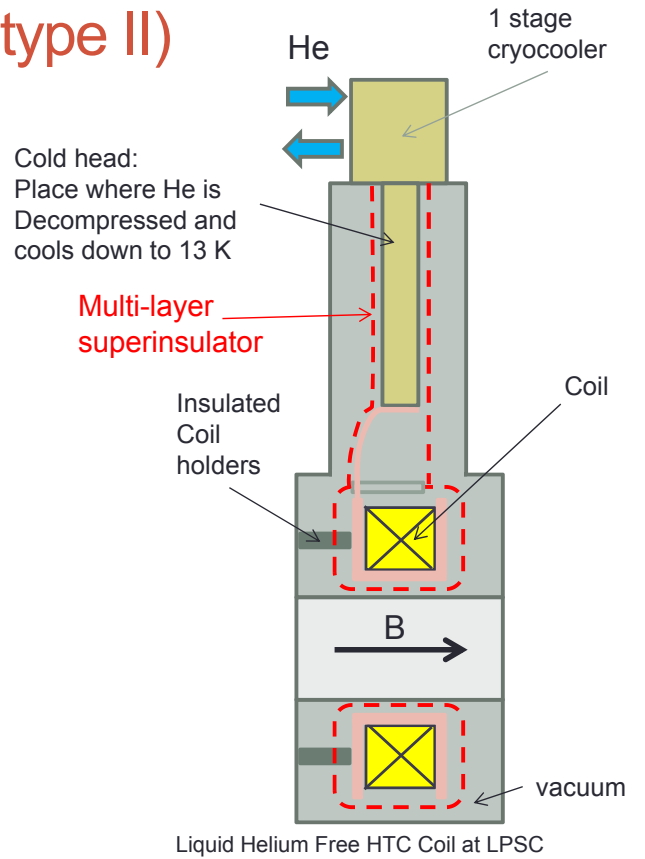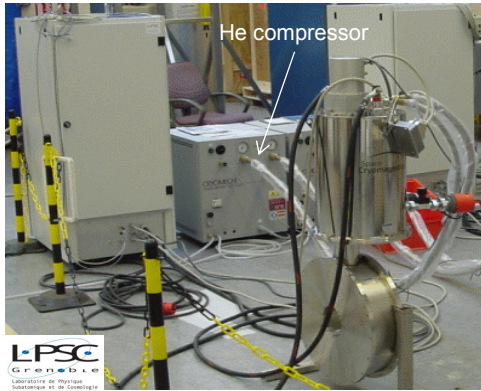# The World's Largest : CMS Superconducting Coil

CMS solenoid
4T at 20,000A
6 m diameter   12.5m long
stored energy 27000MJ

Source: M. Wilson Lecture – JUAS 2006

Design of a simple HTC Coil (type II)

- Example of a 2.2 T HTC Coil (LPSC)
  - Bi-2223 tape
  - $J\sim100$ A/mm^2
  - $T\sim15$ K
  - Coil is under vacuum (no convection)
  - Cooling is done with a cryocooler
    coolling is transferred to coil through a Cu Braid
  - Superinsulation to reduce radiation heat
  - $I\sim160A$, $L\sim1$ Henry, $B=2.2$ T on axis

He

1 stage cryocooler

Cold head:
Place where He is
Decompressed and
cools down to 13 K

Multi-layer
superinsulator

Insulated
Coil
holders

Coil

B

vacuum

Liquid Helium Free HTC Coil at LPSC

Design of a sophisticated NbTi SC magnet cryostat

- VENUS ECR Ion Source Cryostat
  - Axial Mirror 4-0.4-2.5 T
  - Hexapole 2.2 T
  - NbTi:Cu wire
  - LHe bath
  - 50 K shielding
  - 2 stage cryocoolers

HTC
leads

Current I

LN

LHe bath

Upper
Cryostat
(Service
Tower)

VACUUM
VESSEL
275 K
50k Shield

4.2k liquid
He vessel

Sol 1   Sol 3   Sol 2

Sextupole Coil #1 Winding

Sextupole Coil #2 Winding

Sol 1   Sol 3   Sol 2

Lower
Cryostat
with the coil
assembly
enclosed