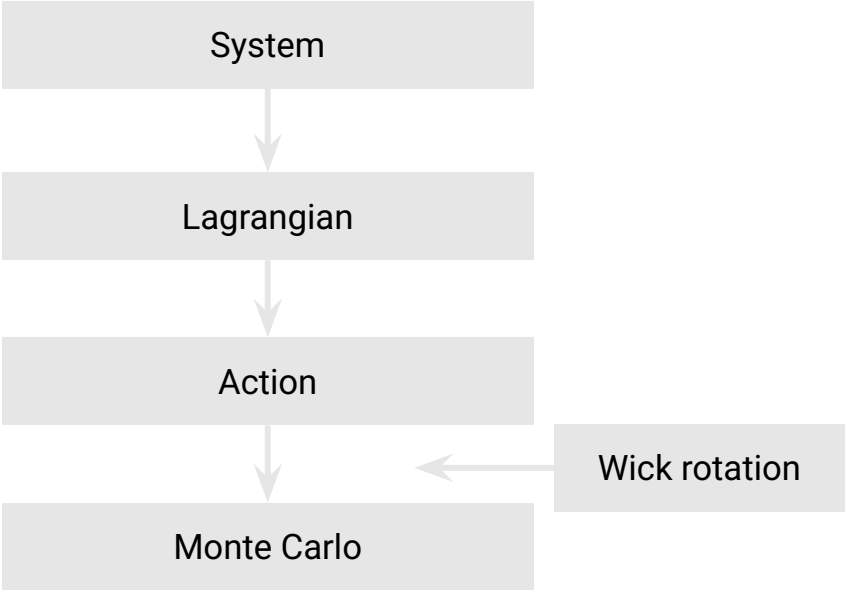




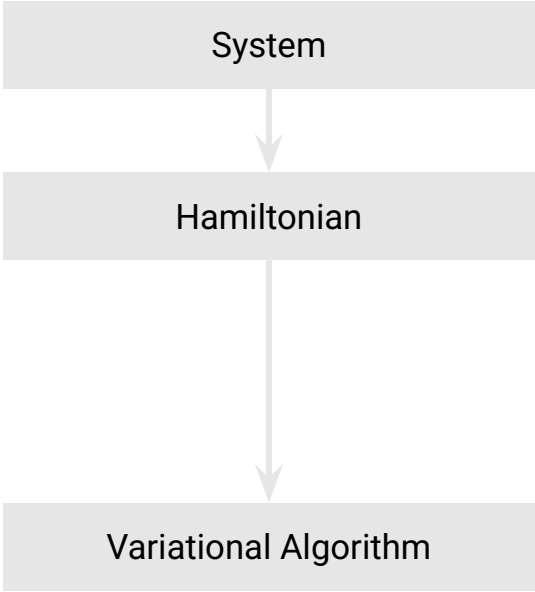
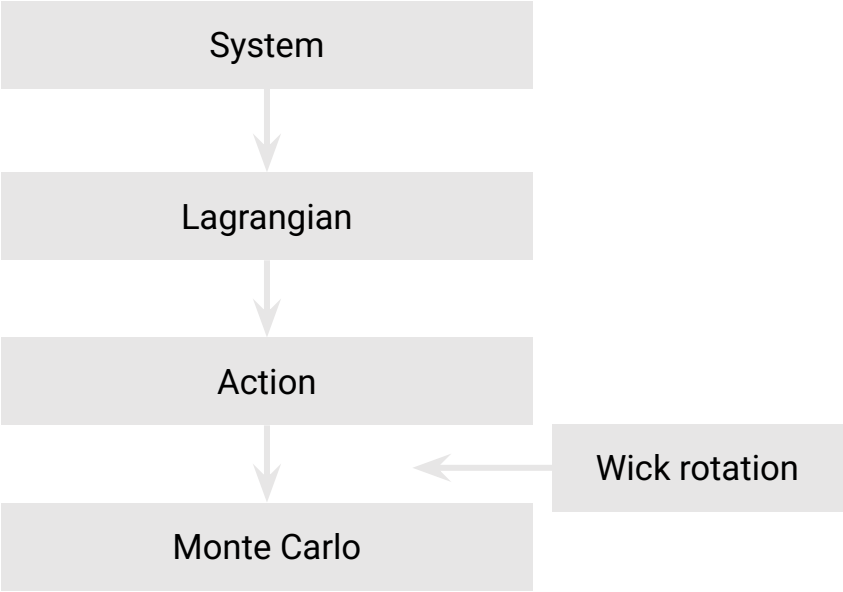
Projected Entangled Pair States for Lattice Gauge Theories with Dynamical Fermions

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The usual pipeline

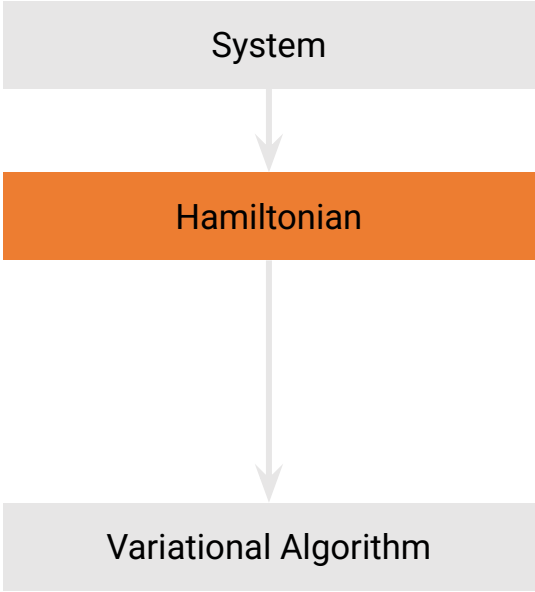
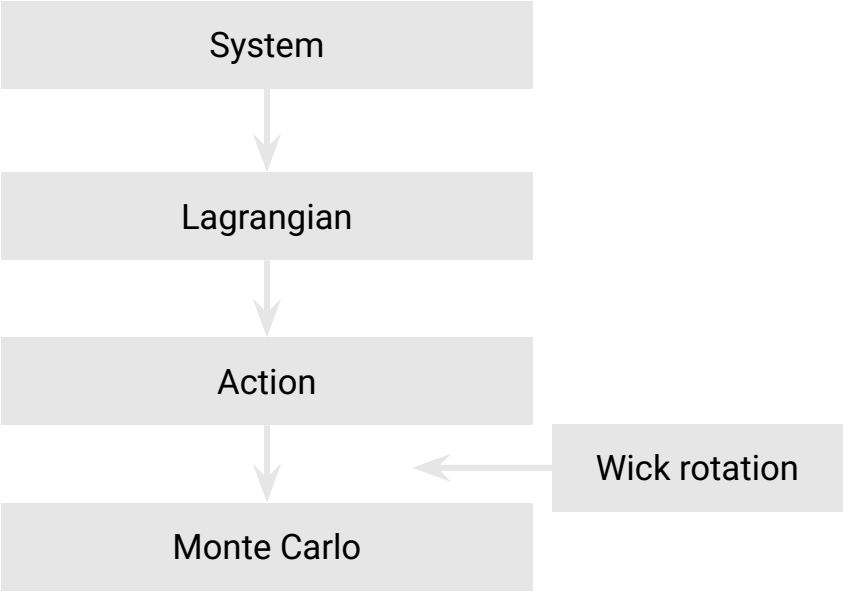


Our Approach



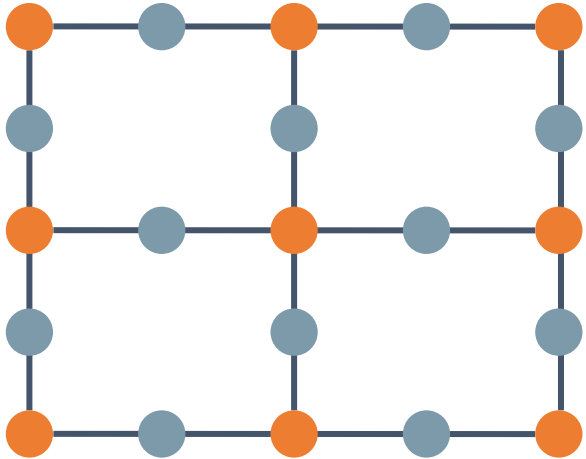
Mari Carmen Bañuls and Krzysztof Cichy (2020) Rep. Prog. Phys. 83 p. 024401;
John Kogut and Leonard Susskind (1975) Phys. Rev. D 11 pp. 395–408;
Kenneth G. Wilson (1974) Phys. Rev. D 10 pp. 2445–2459

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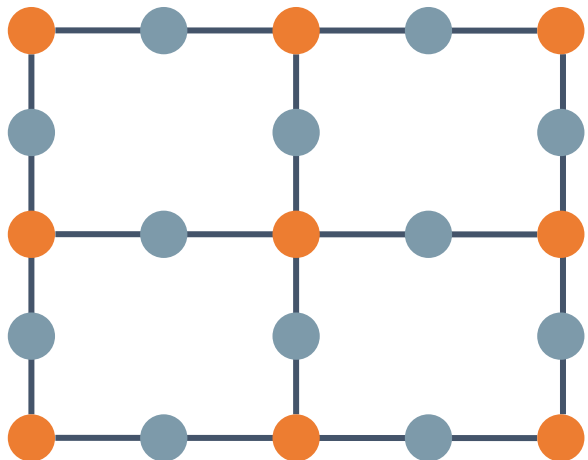
Hilbert spaces and Lattices



Hilbert space

$$\mathcal{H} \subset \mathcal{H}_{\text{gauge fields}} \otimes \mathcal{H}_{\text{fermions}}$$

Hilbert spaces and Lattices



Hilbert space

$$\mathcal{H} \subset \mathcal{H}_{\text{gauge fields}} \otimes \mathcal{H}_{\text{fermions}}$$

A general state

$$|\Psi\rangle = \int D\mathcal{G} |\mathcal{G}\rangle |\psi_F(\mathcal{G})\rangle$$

$$\text{with } D\mathcal{G} = \prod_{x,k} dg(x,k)$$

Which way to go?

Quantum Computation/
Quantum Simulation

Classical Simulation

C. W. Bauer, Z. Davoudi, N. Klco, and M. J. Savage, Nat Rev Phys 5, 420 (2023).

M. C. Bañuls and K. Cichy, Rep. Prog. Phys. **83**, 024401 (2020).

M. C. Bañuls et al., Eur. Phys. J. D 74, 165 (2020).

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Computing an Expectation Value

Assume that the observable acts only on the gauge field and is diagonal in the group element basis:

$$\begin{aligned}\langle \Psi | O | \Psi \rangle &= \frac{\langle \Psi | O | \Psi \rangle}{\langle \Psi | \Psi \rangle} \\ &= \frac{\int D\mathcal{G} \langle \mathcal{G} | O | \mathcal{G} \rangle \langle \psi_F(\mathcal{G}) | \psi_F(\mathcal{G}) \rangle}{\int \mathcal{G}' \langle \psi_F(\mathcal{G}') | \psi_F(\mathcal{G}') \rangle}\end{aligned}$$

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with

$$p(\mathcal{G}) = \frac{\langle \psi_F(\mathcal{G}) | \psi_F(\mathcal{G}) \rangle}{\int D\mathcal{G}' \langle \psi_F(\mathcal{G}') | \psi_F(\mathcal{G}') \rangle}$$

A wishlist

General State Formulation

$$|\Psi\rangle = \int D\mathcal{G} |\mathcal{G}\rangle |\psi_F(\mathcal{G})\rangle$$

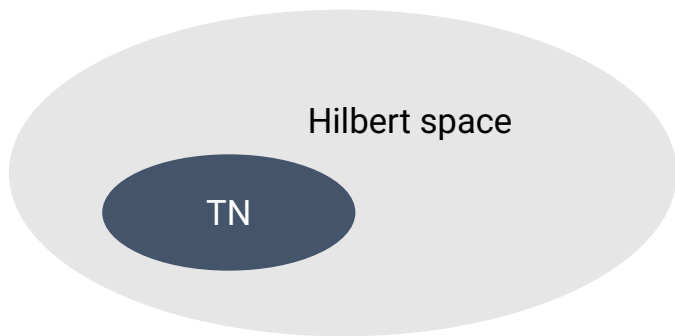
ToDo List

1. How do we construct $|\psi_F(\mathcal{G})\rangle$?
2. How do we efficiently calculate the expectation values?
3. Are those states useful?

Finding an Ansatz

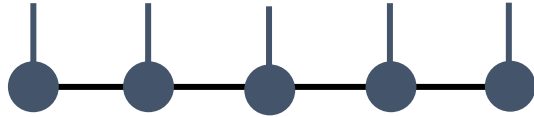
Idea

Use an Ansatz with polynomially many parameters although the Hilbert space has exponentially many states



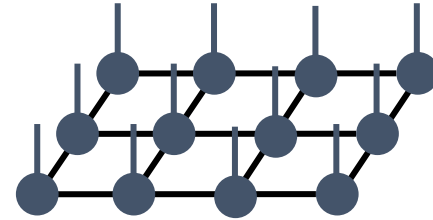
We explore only a small part of the Hilbert space

Different Families of Tensor Networks



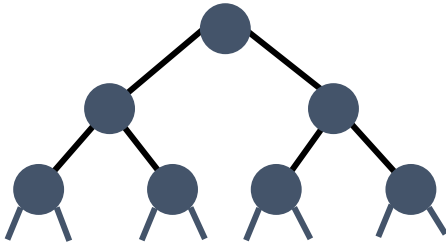
Matrix Product States (MPS)

M. Fannes, B. Nachtergaele, and R. F. Werner (1992)
Commun.Math. Phys. 144 pp. 443–490



Projected Entangled Pair States (PEPS)

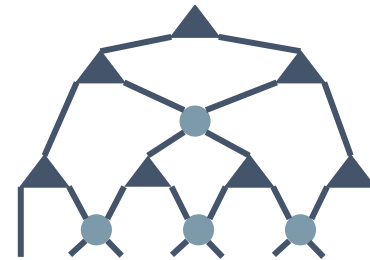
F. Verstraete and J. I. Cirac, arXiv:cond-mat/0407066.



Tree Tensor Network

Y.-Y. Shi, L.-M. Duan, and G. Vidal, Phys. Rev. A 74,
022320 (2006).

T. Felser, S. Notarnicola, and S. Montangero, Phys. Rev.
Lett. 126, 170603 (2021).



Multiscale Entanglement Renormalization Ansatz (MERA)

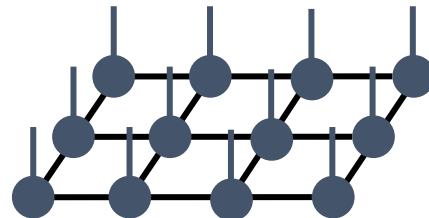
G. Vidal, Phys. Rev. Lett. 101, 110501 (2008).

Different Families of Tensor Networks



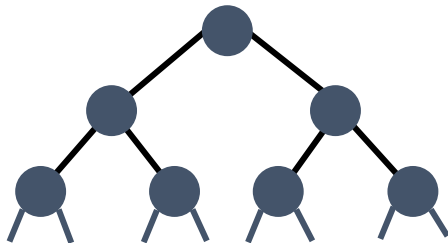
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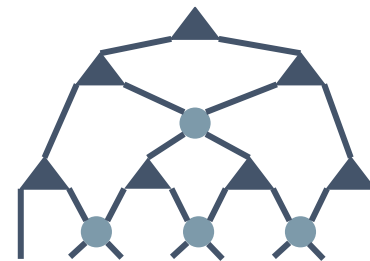
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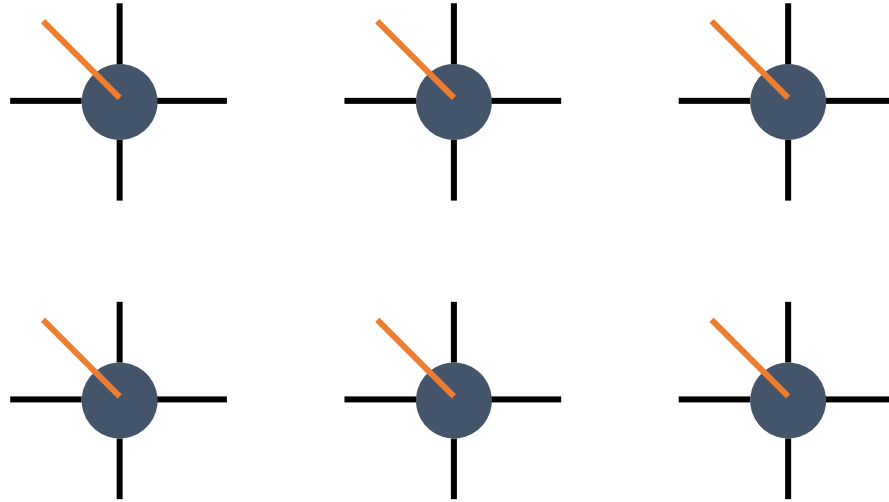
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**Multiscale Entanglement
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G. Vidal, Phys. Rev. Lett. 101, 110501 (2008).

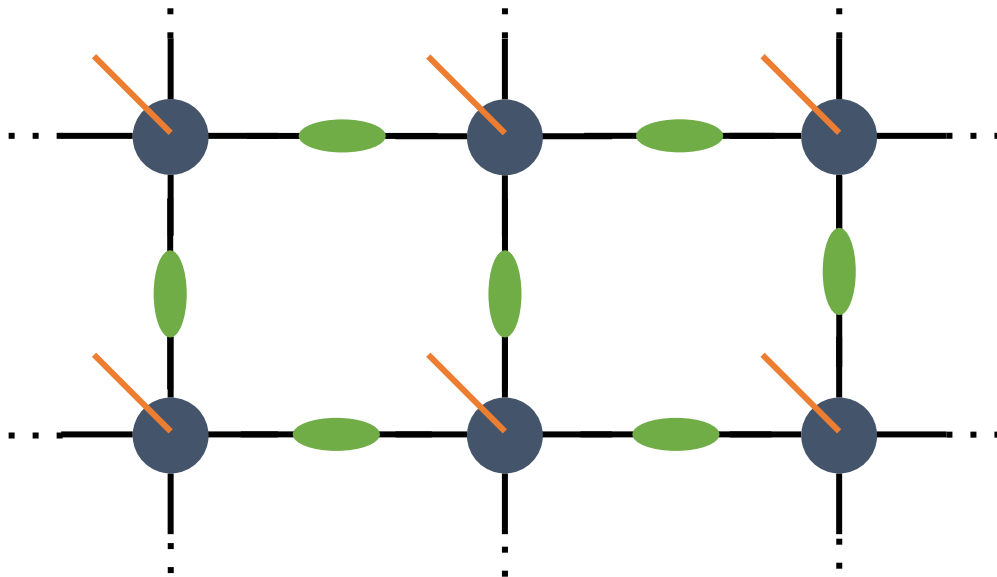
Building a State – GGPEPS



Construction

$$\prod_x \mathcal{A}(x) |\Omega\rangle$$

Building a state



Construction

$$|\psi_0\rangle = \langle \Omega_v | \prod_{\ell} \omega_{\ell} \prod_{\mathbf{x}} \mathcal{A}(\mathbf{x}) | \Omega \rangle$$

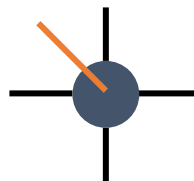
Local Gauge Invariance

Goal

Couple the gauge field to the state such that it is locally invariant under gauge transformations.

Gauging Procedure

$$|\psi_0\rangle = \langle \Omega_v | \prod_{\ell} \omega_{\ell} \prod_x \mathcal{A}(x) | \Omega \rangle$$



Local Gauge Invariance

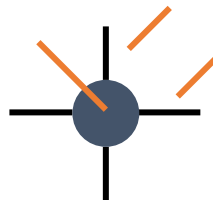
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$$\rightarrow \langle \Omega_v | \prod_{\ell} \omega_{\ell} \prod_x \mathcal{A}(x) | 0 \rangle_{x,1} | 0 \rangle_{x,2} | \Omega \rangle$$



Local Gauge Invariance

Goal

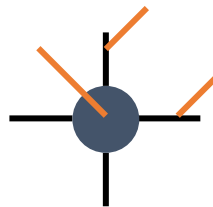
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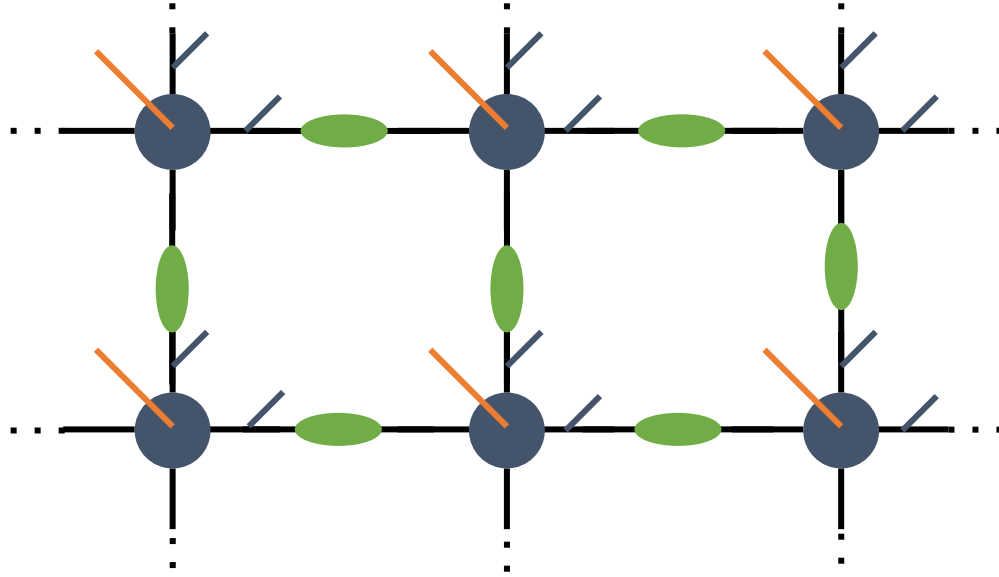
$$|\psi_0\rangle = \langle \Omega_v | \prod_{\ell} \omega_{\ell} \prod_x \mathcal{A}(x) | \Omega \rangle$$

$$\rightarrow \langle \Omega_v | \prod_{\ell} \omega_{\ell} \prod_x \mathcal{A}(x) |0\rangle_{x,1} |0\rangle_{x,2} | \Omega \rangle$$

$$|\psi\rangle = \langle \Omega_v | \prod_{\ell} \omega_{\ell} \prod_x \mathcal{U}_G(x, 1) \mathcal{U}_G(x, 2) \prod_x \mathcal{A}(x) |0\rangle_{x,1} |0\rangle_{x,2} | \Omega \rangle$$



Building a State – GGPEPS



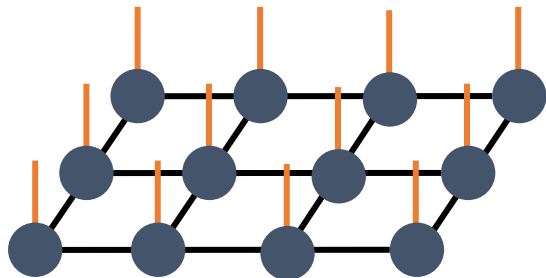
Construction

$$|\psi_F(\mathcal{G})\rangle = \langle \Omega_v | \prod_{\ell} \omega_{\ell} \prod_{\ell} U_{\ell}(\mathcal{G}) \prod_{\mathbf{x}} \mathcal{A}(\mathbf{x}) | \Omega \rangle$$

How to compute an expectation value?

ToDo List

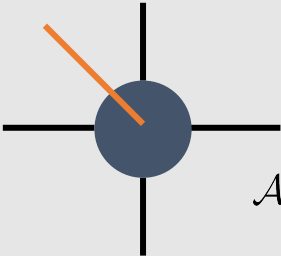
1. How do we construct $|\psi_F(\mathcal{G})\rangle$ ✓
2. How do we efficiently calculate the observables?
3. Are those states useful?



Contracting PEPS is hard!

A Gauged Gaussian PEPS

Tensor



$$\mathcal{A}(\mathbf{x}) = \exp(T_{ij} a_i^\dagger(\mathbf{x}) b_j^\dagger(\mathbf{x}))$$

Projector



$$\omega(\mathbf{x}, k) = \omega_k(\mathbf{x}) \Omega_k(\mathbf{x}) \omega_k^\dagger(\mathbf{x})$$

$$\omega_0(\mathbf{x}) = \exp(l_+^\dagger(\mathbf{x} + \mathbf{e}_1) r_-^\dagger(\mathbf{x})) \exp(l_-^\dagger(\mathbf{x} + \mathbf{e}_1) r_+^\dagger(\mathbf{x}))$$

Use covariance matrices instead

Covariance Matrices

Goal

Estimate the numerator

$$p(\mathcal{G}) = \frac{\langle \psi_F(\mathcal{G}) | \psi_F(\mathcal{G}) \rangle}{\int D\mathcal{G}' \langle \psi_F(\mathcal{G}') | \psi_F(\mathcal{G}') \rangle}$$

Covariance Matrices

Goal

Estimate the numerator

$$p(\mathcal{G}) = \frac{\langle \psi_F(\mathcal{G}) | \psi_F(\mathcal{G}) \rangle}{\int D\mathcal{G}' \langle \psi_F(\mathcal{G}') | \psi_F(\mathcal{G}') \rangle}$$

The Covariance Matrix

$$\Gamma_{a,b} = \frac{i}{2} \langle [\gamma_a, \gamma_b] \rangle = \frac{i}{2} \frac{\langle \Phi | [\gamma_a, \gamma_b] | \Phi \rangle}{\langle \Phi | \Phi \rangle}$$

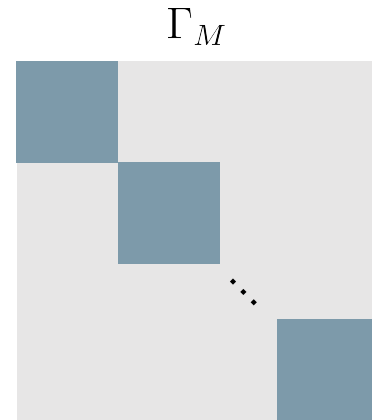
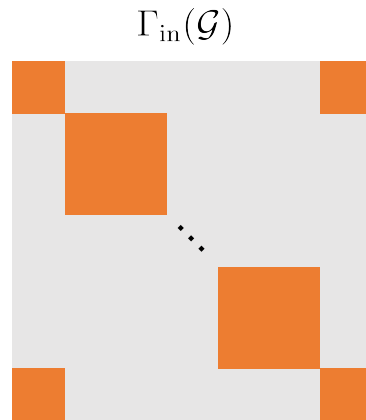
Covariance Matrices for GGPEPS

$$|\psi_F(\mathcal{G})\rangle = \langle \Omega_v | \underbrace{\prod_{\ell} \omega_{\ell} \prod_{\ell} U_{\ell}(\mathcal{G})}_{\Gamma_{\text{in}}(\mathcal{G})} \underbrace{\prod_{\mathbf{x}} \mathcal{A}(\mathbf{x})}_{\Gamma_M} | \Omega \rangle$$

Computing the Norm

Covariance Matrices for GGPEPS

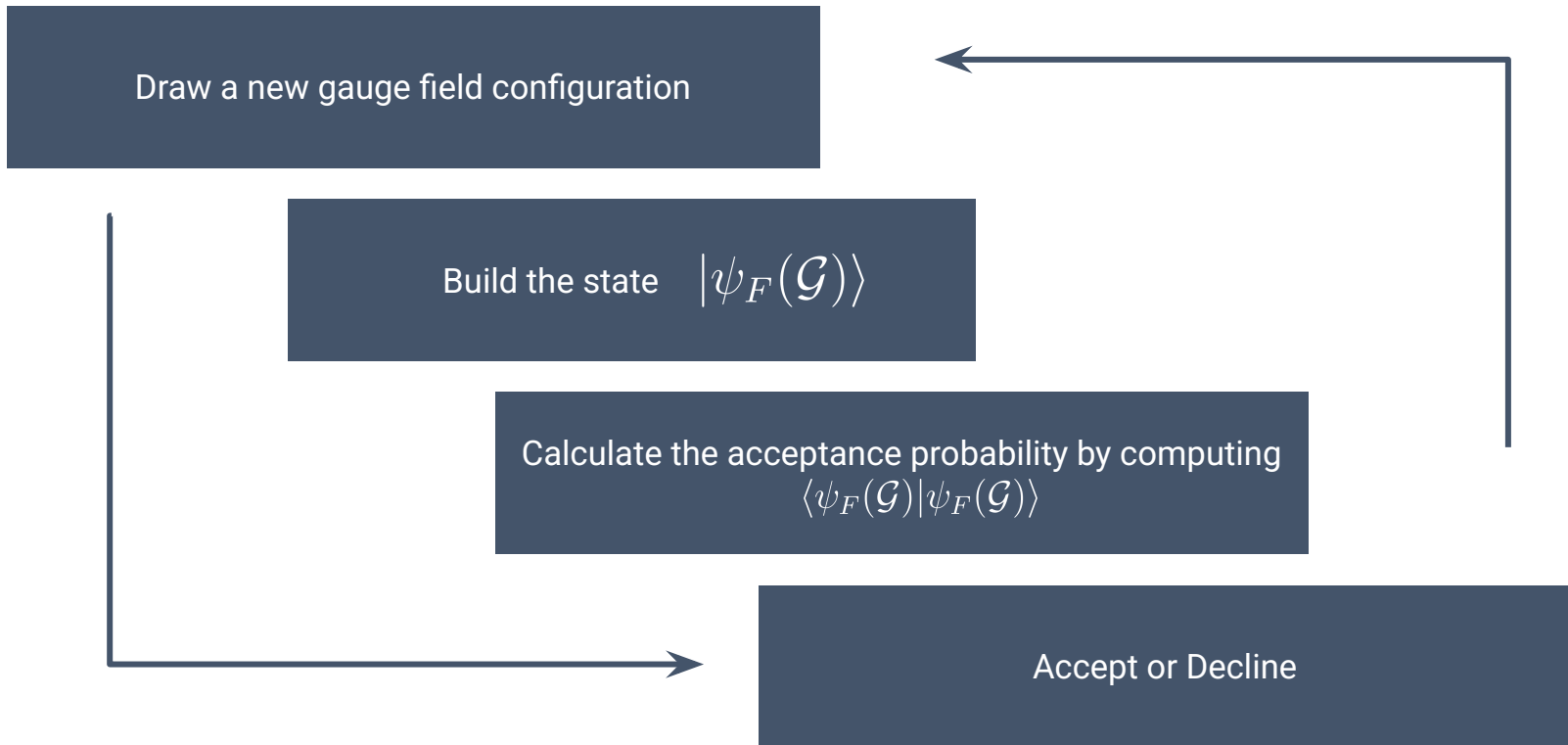
$$|\psi_F(\mathcal{G})\rangle = \langle \Omega_v | \underbrace{\prod_{\ell} \omega_{\ell} \prod_{\ell} U_{\ell}(\mathcal{G})}_{\Gamma_{\text{in}}(\mathcal{G})} \underbrace{\prod_{\mathbf{x}} \mathcal{A}(\mathbf{x})}_{\Gamma_M} | \Omega \rangle$$



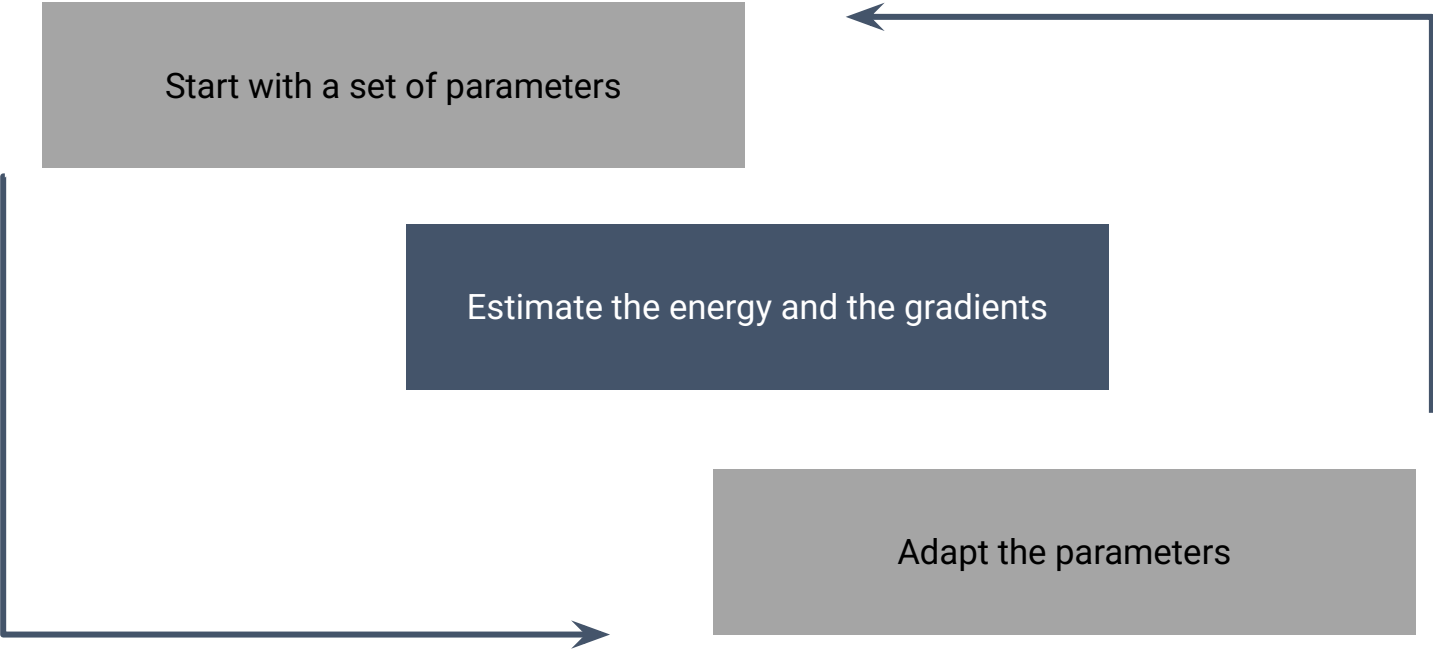
The Norm

$$|\psi_F(\mathcal{G})|^2 = \sqrt{\det \left(\frac{1 - \Gamma_{\text{in}}(\mathcal{G}) M_D}{2} \right)}$$

The MC Algorithm



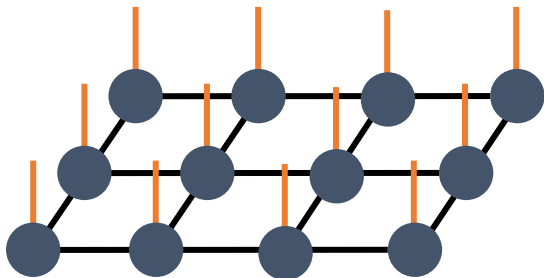
The Variational MC Algorithm



How to compute an expectation value?

ToDo List

1. How do we construct $|\psi_F(\mathcal{G})\rangle$ ✓
2. How do we efficiently calculate the observables? ✓
3. Are those states useful?



GGPEPS can be contracted via covariance matrices

Let's consider a Z2 LGT with Fermions

Kogut Susskind Hamiltonian

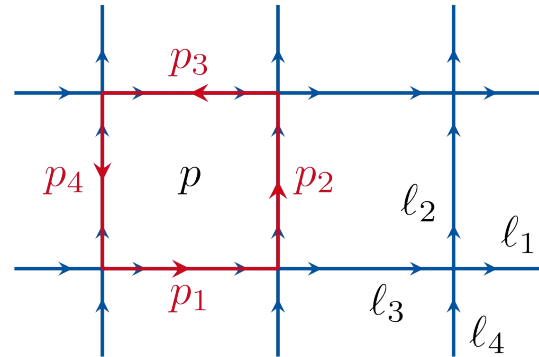
$$H = g_E H_E + g_B H_B + g_I H_I + g_M H_M$$

$$H_E = \sum_{\ell} 2 [1 - \sigma_{\ell}^z]$$

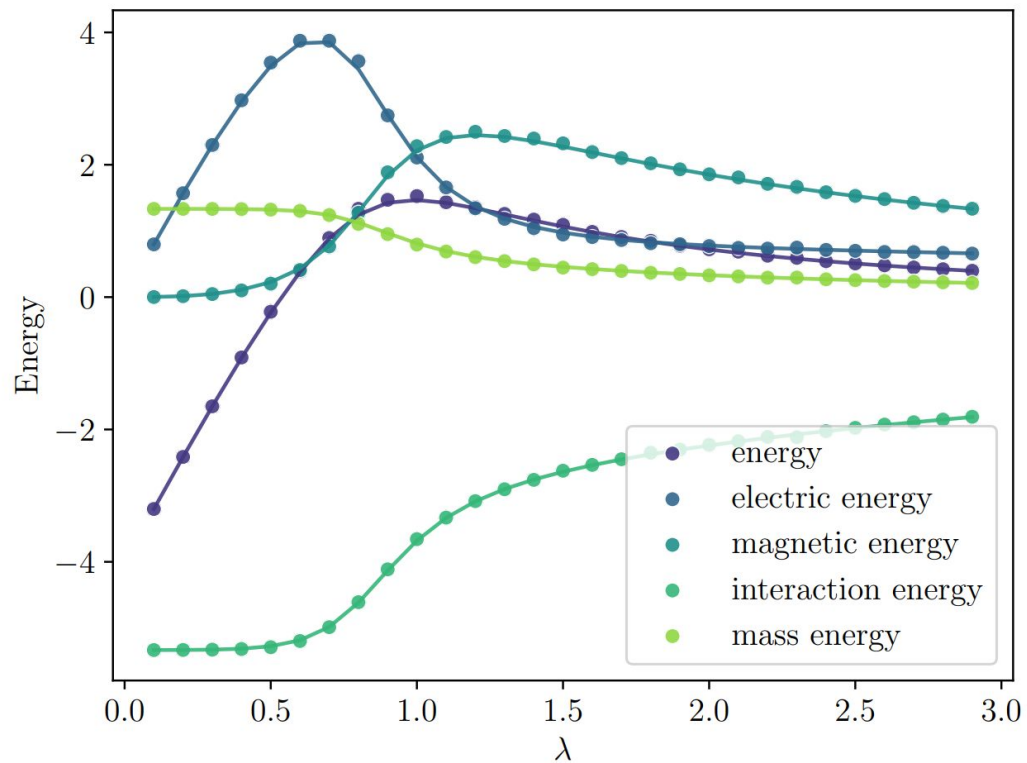
$$H_B = \sum_p [1 - \sigma_{p_1}^x \sigma_{p_2}^x \sigma_{p_3}^x \sigma_{p_4}^x]$$

$$H_M = \sum_x \left(\frac{1}{2} + (-1)^x \psi^{\dagger}(x) \psi(x) \right)$$

$$H_I = \sum_x (\psi^{\dagger}(x) U(x, 1) \psi(x + e_1) + h.c.) + H_{I,2}$$



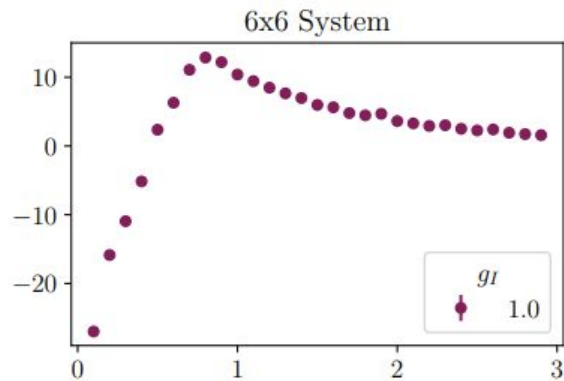
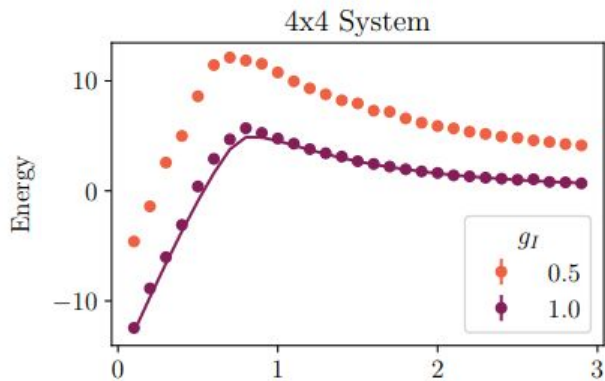
Results – 2x2 Benchmark



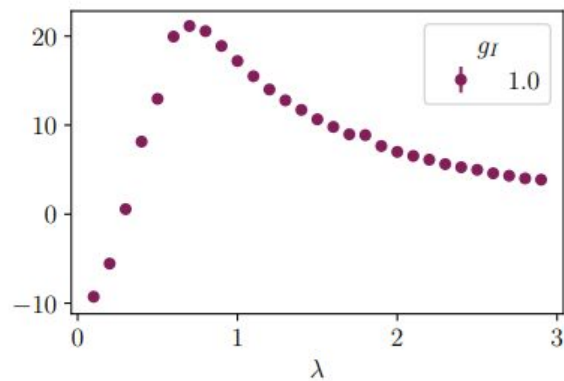
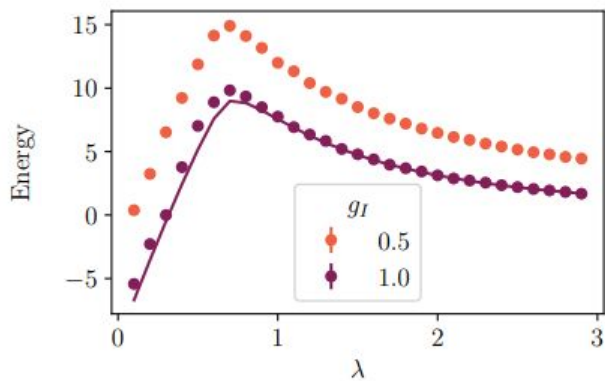
$$g_E = \lambda$$
$$g_I = 1.0$$
$$g_M = 1.0$$
$$g_B = 1/\lambda$$

Results – Monte Carlo Sampling

$g_M = 0.0$



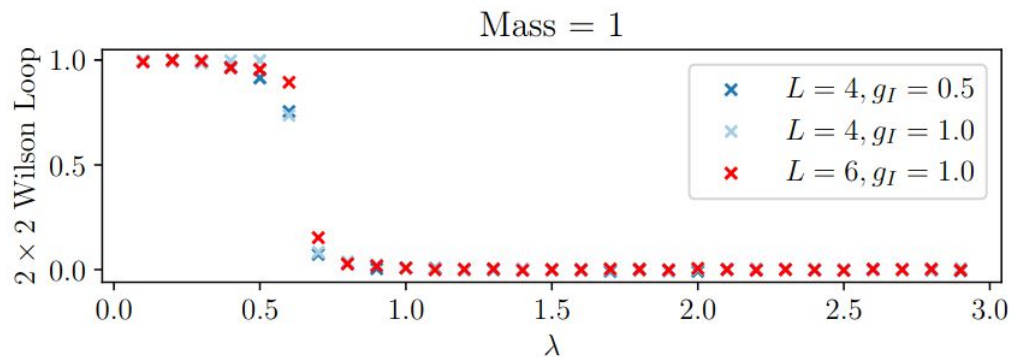
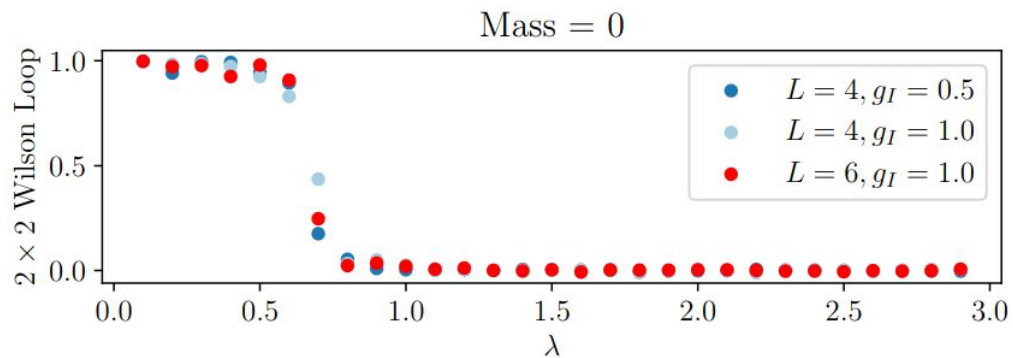
$g_M = 1.0$



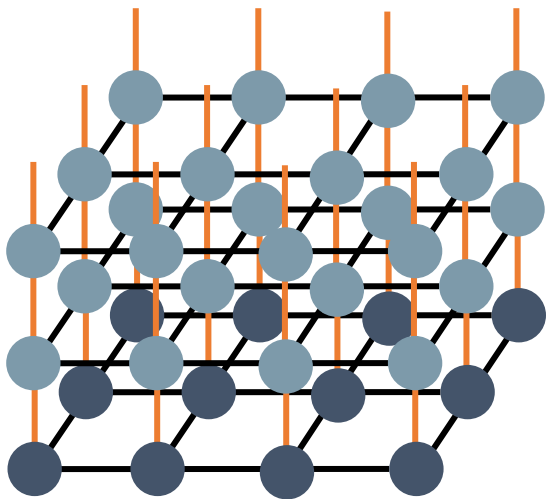
$$g_E = \lambda$$

$$g_B = 1/\lambda$$

Results – Resolving Phases



Some Thoughts on Time Evolution



Trotterization

$$e^{-iHT} \approx \left(e^{-iH_1t} e^{-iH_2t} \right)^N$$

Time Evolution (TDVP)

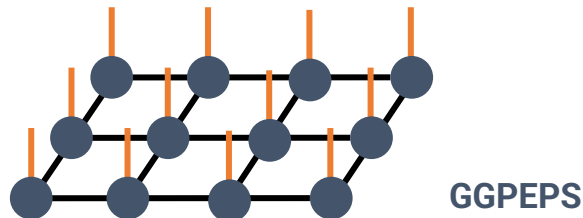
$$-i \frac{\partial}{\partial t} |\psi\rangle = P_{T_{\mathcal{M}}(|\psi\rangle)} H |\psi\rangle$$

Summary

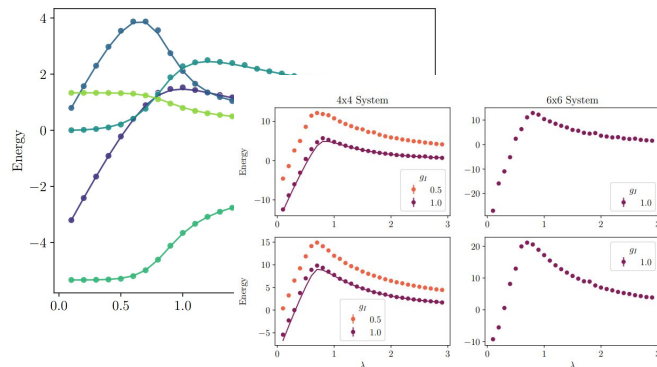
How do we construct $|\psi_F(\mathcal{G})\rangle$?

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Covariance Matrices and Variational Monte Carlo Sampling

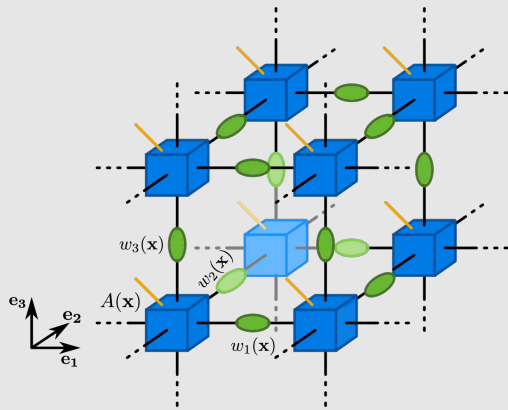


A. Kelman, U. Borla, P. Emonts, and E. Zohar, arXiv:2412.16951.

A. Kelman, U. Borla, I. Gomelski, J. Elyovich, G. Roose, P. Emonts, and E. Zohar, Phys. Rev. D 110, 054511 (2024).

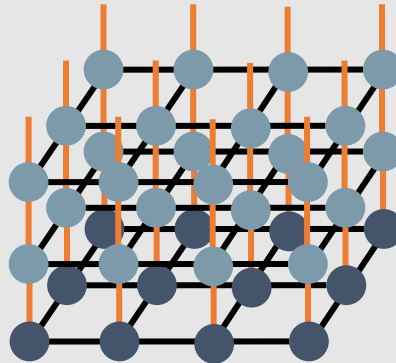
What are the next steps?

Three spatial dimensions?



P. Emonts and E. Zohar, Phys. Rev. D 108, 014514 (2023).

Time Evolution?



E. Zohar and J. I. Cirac, Phys. Rev. D 97, 034510 (2018).

Non-Abelian Gauge Groups?

D_6

$SU(2)$

$SU(3)$

Science is a team effort



Ariel Kelman



Umberto Borla



Itay Gomelski



Jonathan Elyovich

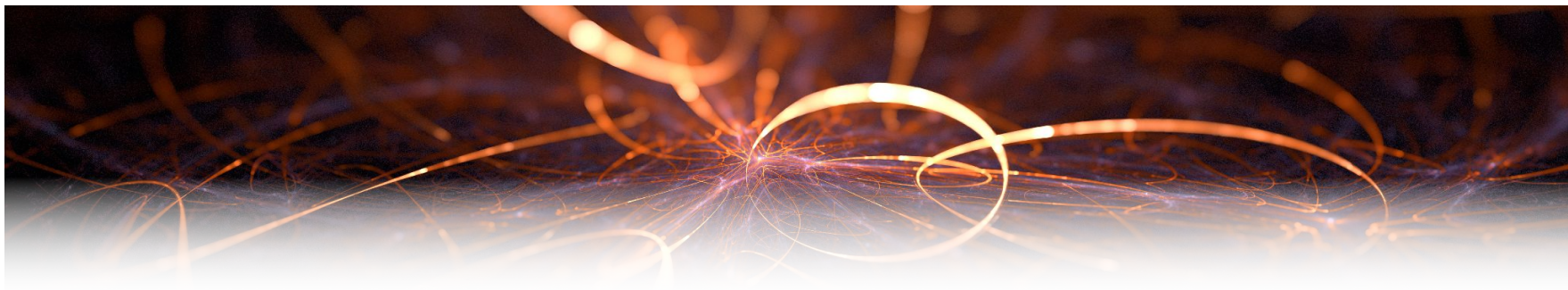


Gertian Roose



Erez Zohar





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