



Deep Finite Temperature Bootstrap

Costis Papageorgakis, Queen Mary University of London

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Based on 2508.08560 with V. Niarchos, A. Stratoudakis and M. Woolley

The bootstrap philosophy

Consistency conditions should be enough to completely determine physics

E.g. old S-matrix programme using analyticity, unitarity and crossing to determine observables for strong interactions

A version of this idea used to great effect in the modern conformal bootstrap

⇒ CFTs are ubiquitous: UV/IR behaviour of QFTs, critical phenomena, quantum gravity via AdS/CFT correspondence...

But there are many other applications:

- Modern S-matrix bootstrap
- Matrix quantum mechanics bootstrap
- Cosmological bootstrap
- Modular bootstrap

Motivation

Conformal bootstrap programme opens the way for nonperturbative solution of CFTs and numerical bootstrap has yielded impressive results,

Relies on leveraging sum rules arising from consistency conditions:

$$\sum_J \sum_{\Delta} \vec{x}_{\Delta,J} = 0$$

Infinite unknowns involved and non-convex: direct solution is hard

Workaround: The linear functional method maps to convex linear/semi-definite problem

⇒ Rigorous, high-precision results obtained through e.g. SDPB
[Rattazzi, Rychkov, Tonni, Vichi '08, Simmons-Duffin '15]

Revisit direct (constructive) solutions towards:

- Exploring the solution space and guiding rigorous approaches
- Developing more efficient numerics (e.g. scaling multi-correlator bootstrap)
- Applying bootstrap approach to scenarios without positivity (e.g. finite temperature, defects/boundaries, higher-point correlators, non-unitarity...)

However: How to attack a problem with infinite unknowns?

⇒ **Hard truncations:** drop all unknowns above a cutoff [Gliozzi '13]

⇒ **Soft truncations:** model contributions above a cutoff
(e.g. effective operators [Niarchos, CP, Richmond, Stapleton, Woolley '23],
Tauberian theorems [Marchetto, Miscioscia, Pomoni '23])

Can be effective for specific cases but in general **hard to control** in terms of systematic error...

Today

⇒ Introduce a novel framework for capturing all unknowns using **dispersion relations** and **neural networks**, without dropping any terms

⇒ Showcase a **numerical** application in the context of **thermal CFTs** dual to **black holes in AdS**

The main idea

Consider the following split of the sum rule:

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$$\boxed{\sum_{J>J_*} \sum_{\Delta} \vec{\chi}_{\Delta,J}} \leftarrow \sum_J \sum_{\Delta} \vec{\chi}_{\Delta,J} = 0$$

'High-spin' part
(approximated through
dispersion relations)

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$\sum_{J > J_*} \sum_{\Delta} \vec{\chi}_{\Delta,J}$

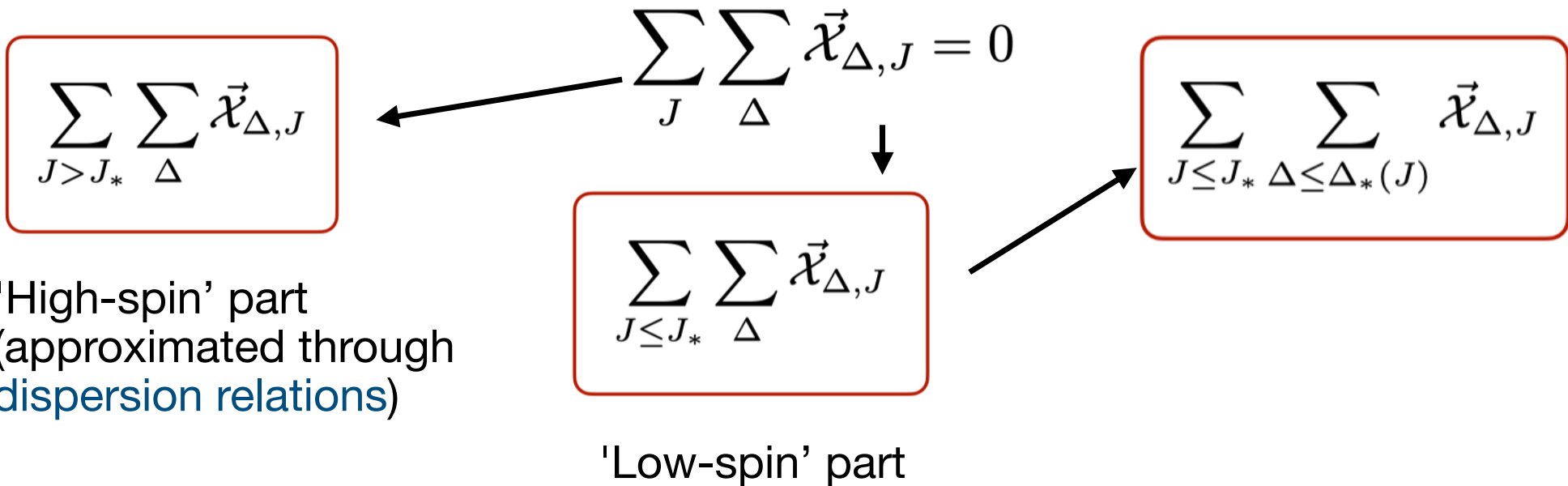
'High-spin' part
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$\sum_{J \leq J_*} \sum_{\Delta} \vec{\chi}_{\Delta,J}$

'Low-spin' part

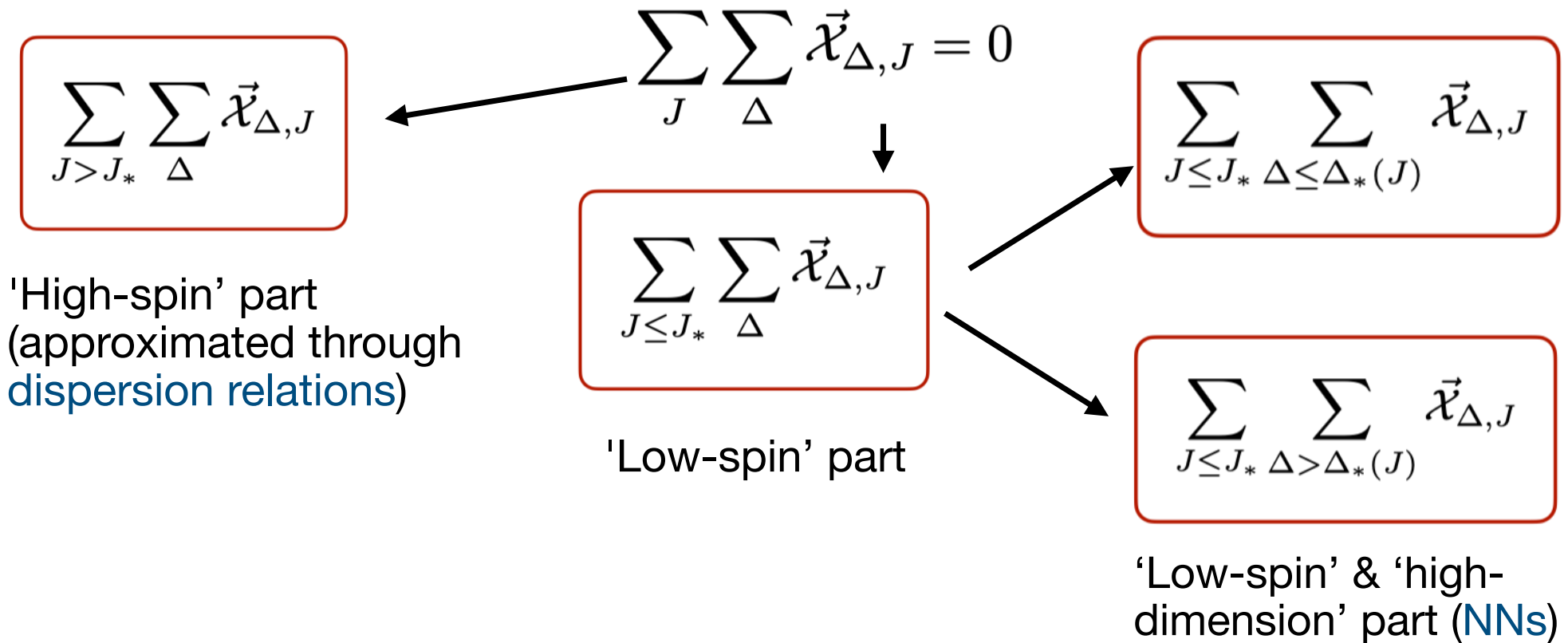
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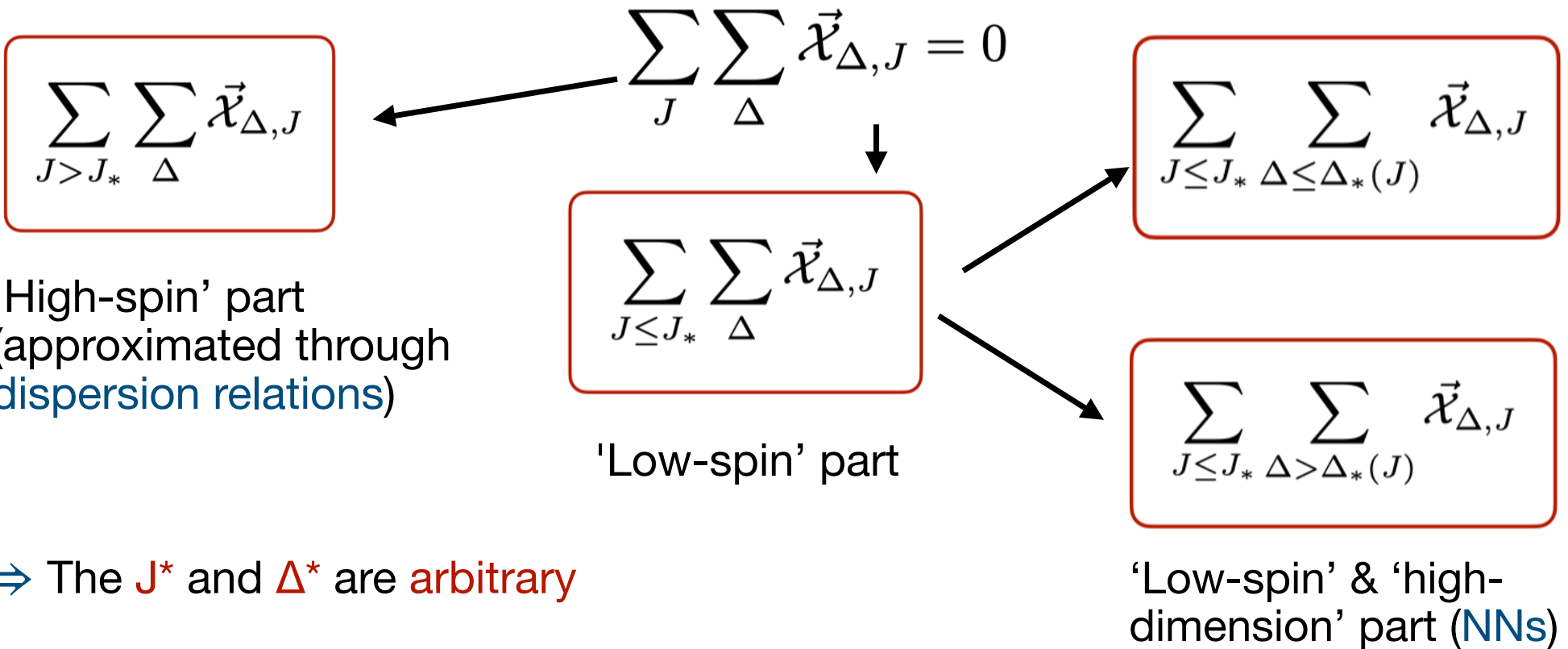
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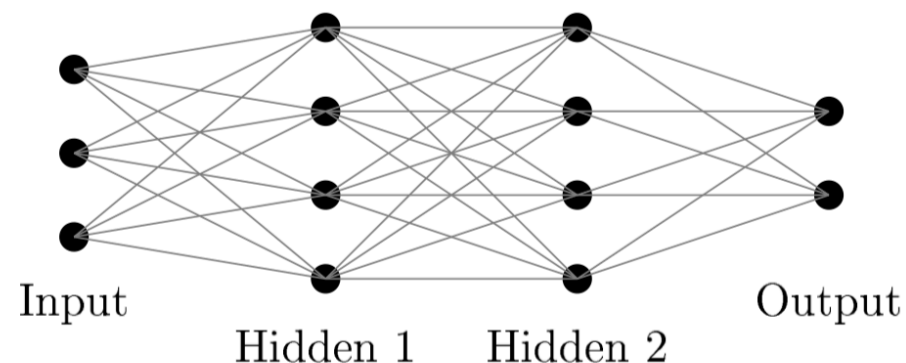


Artificial Neural Networks

Multi-Layer Perceptron (MLP): $f_{\theta} : \mathbb{R}^{\text{in}} \rightarrow \mathbb{R}^{\text{out}}$

Each layer takes: $\vec{h}^{(\ell+1)} = \sigma\left(W^{(\ell)}\vec{h}^{(\ell)} + \vec{b}^{(\ell)}\right)$

The parameters $\vec{\theta} = \{W^{(\ell)}, \vec{b}^{(\ell)}\}$ are learnt during **training**, aiming to **minimise the loss**



Universal approximation theorem: for nonlinear σ the NN can approximate any continuous function

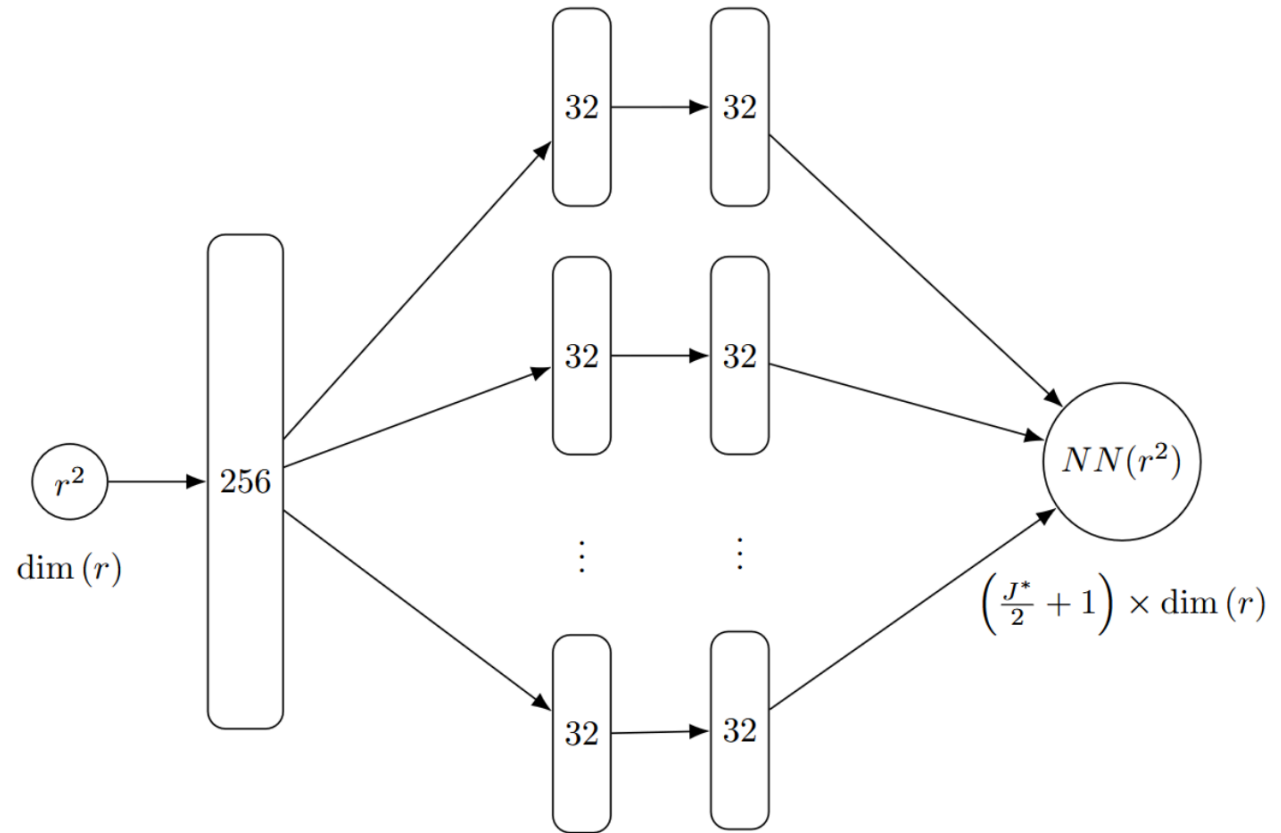
More explicitly for thermal CFTs:

$$\sum_{J \leq J_*} \sum_{\Delta > \Delta_*(J)} \vec{\chi}_{\Delta, J}$$



$$\sum_{J < J_*} A_J(r) C_J^{(d)}(\cos \theta)$$

and the $A_J(r)$ are 1D **tail** functions approximated using PINNs



Summary so far

Try to find **constructive** solutions to sum rules for bootstrap problem

Capture ‘**high-spin**’ contributions through **dispersion relations**, and **optimise** for the ‘**low-spin**’ contributions (**discrete data** and **NNs** for ‘tails’)

Organise search in terms of a semi-positive definite loss function $\mathcal{L}(D, \vec{\theta})$ that we want to **minimise** (D : discrete data $\vec{\theta}$: NN parameters)

Choose for loss function:

- L_p norm of the crossing vector (‘abs-loss’ for $p=1$)
- A dot-product loss for the crossing vector (‘dot-loss’)

Application to Thermal Bootstrap

Consider CFT on $\mathbb{R}^{d-1} \times S^1_\beta$ and associated 2pt function:

$$g(\tau, |x|) = \langle \phi(x)\phi(0) \rangle_\beta, \quad |x| = \sqrt{\tau^2 + \vec{x}^2}$$

Choose $\vec{x} = (\sigma, 0, \dots, 0)$ and $z := \tau + i\sigma = r\omega$, $\bar{z} := \tau - i\sigma = r\omega^{-1}$

The Kubo-Martin-Schwinger (KMS) condition dictates (for $\beta = 1$, $|x| = r$)
[El-Showk, Papadodimas '11]

$$g(\tau, r) = g(1 - \tau, r)$$

$$g(1 - z, 1 - \bar{z}) = g(z, \bar{z})$$

Expand 2pt function using ‘thermal OPE’

$$g(rw, rw^{-1}) = \sum_{\mathcal{O}_{\Delta, J} \in \phi \times \phi} a_{\mathcal{O}_{\Delta, J}} C_J^{\left(\frac{d-2}{2}\right)} \left(\frac{1}{2}(w + w^{-1}) \right) r^{\Delta - 2\Delta_{\phi}}$$

where the thermal 1pt functions $b_{\mathcal{O}}$ are encoded through

$$a_{\mathcal{O}} := \frac{f_{\phi\phi\mathcal{O}} b_{\mathcal{O}}}{c_{\mathcal{O}}} \frac{J!}{2^J \left(\frac{d-2}{2}\right)_J}$$

Bootstrap: Assuming knowledge of zero-temperature data ($f_{\phi\phi\mathcal{O}}$, Δ) KMS condition poses nontrivial constraints for thermal 1pt functions

Use our framework ('high/low-spin') to write the 2pt function as:

$$\begin{aligned}
 g(rw, rw^{-1}) &= \sum_{J=0}^{J_*} \sum_{\Delta \leq \Delta_*(J)} a_{\Delta, J} C_J^{(\nu)} \left(\frac{1}{2}(w + w^{-1}) \right) r^{\Delta - 2\Delta_\phi} && \text{Discrete data} \\
 &+ \sum_{J=0}^{J_*} A_{\Delta_*(J), J}(r) C_J^{(\nu)} \left(\frac{1}{2}(w + w^{-1}) \right) && \text{Tail functions} \\
 &+ 2 \left(\int_{-\infty}^{-r^{-1}} + \int_{r^{-1}}^{\infty} \right) dw' \mathcal{K}_{J_*}(w, w') \text{Disc} \left[g(rw', rw'^{-1}) \right] && \text{controlled approx.}
 \end{aligned}$$

Δ_*, J_* are freely **tuneable**. The discontinuity involves reduced theory-specific input.

Exact: No terms have been dropped!

Calibration: Generalised Free Fields

Analytic solution known. For a scalar with dimension Δ_ϕ :

double-twist operators

$$g(z, \bar{z}) = \sum_{m=-\infty}^{\infty} \frac{1}{[(m-z)(m-\bar{z})]^{\Delta_\phi}}$$

$\longrightarrow [\phi\phi]_{n,J}, \quad n = 0, 1, \dots, \quad J = 2\ell \quad \ell = 0, 1, \dots$
 $\Delta_{n,J} = 2\Delta_\phi + 2n + 2\ell$

$$g(rw, rw^{-1}) = r^{-2\Delta_\phi} + \sum_{n=0}^{\infty} \sum_{\ell=0}^{\infty} a_{n,2\ell} C_{2\ell}^{(\nu)} \left(\frac{1}{2}(w + w^{-1}) \right) r^{2(n+\ell)}$$

$$a_{n,J} = 2\zeta(2\Delta_\phi + 2n + J) \frac{(J + \nu)(\Delta_\phi)_{J+n}(\Delta_\phi - \nu)_n}{n!(\nu)_{J+n+1}}$$

Given this knowledge, how good is our approximate KMS condition?

J_*	\mathcal{L}_{abs}	$\mathcal{L}_{\text{dot}(0)}$
0	0.1177	0.0125
2	0.0300	1.3×10^{-5}
4	0.0067	1.6×10^{-7}
6	0.0013	3.3×10^{-9}
8	0.0002	0.8×10^{-10}

0 discrete data

J_*	$\mathcal{L}_{\text{dot}(1)}$	$a_{1,0} + 3 a_{2,0}$ from dot loss
2	9.5×10^{-6}	15.16582
4	1.4×10^{-6}	15.07614
6	7.8×10^{-8}	15.06252
8	3.5×10^{-9}	15.06049
		Exact value: 15.06013

1 discrete datum

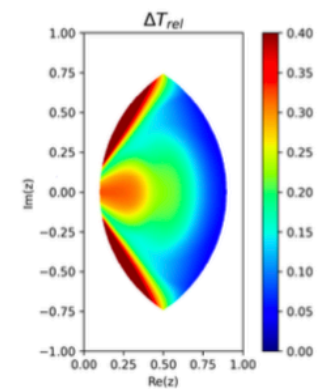
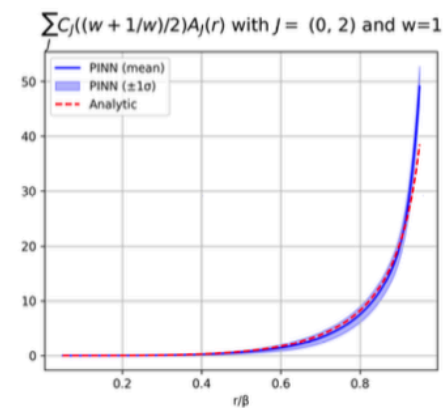
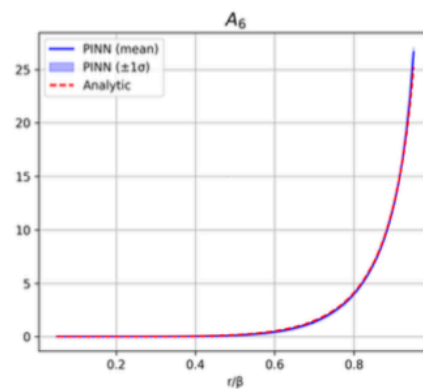
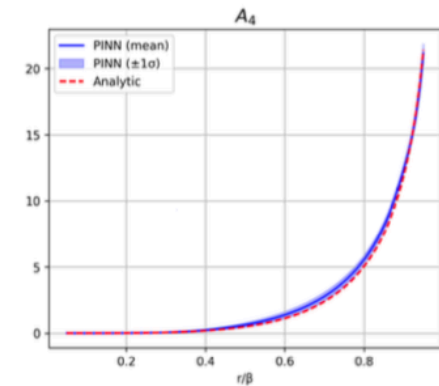
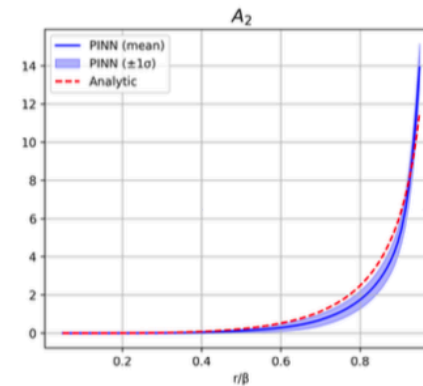
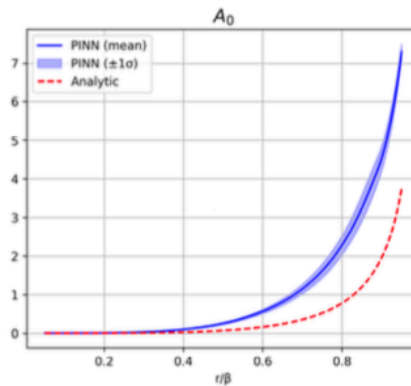
⇒ Approximation works well and **improves systematically** as J^* increases

Results: GFF with no analytic input

For $d=4$, $J^* = 6$,
 $\Delta_\phi = 1.68$ and one
discrete datum we have
the 4 tails and also:

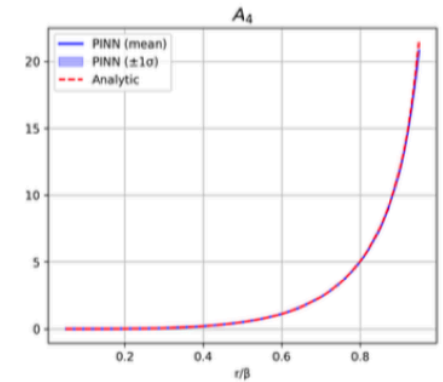
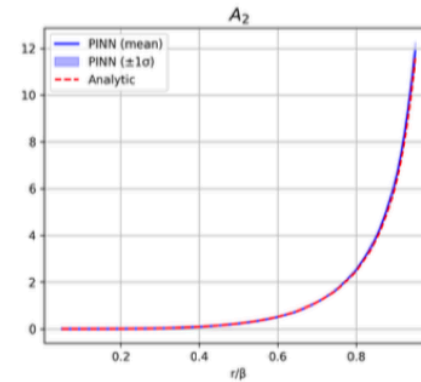
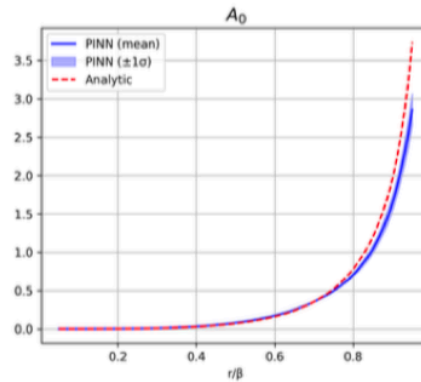
$$a_{1,0} + 3a_{0,2} = 13.29 \pm 2.82$$

with analytic 15.06013

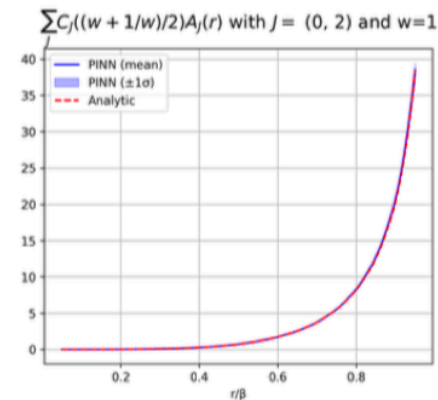
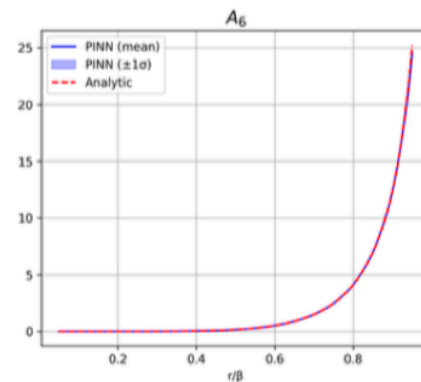


Results: GFF with analytic 'anchor' at $r = 0.7$

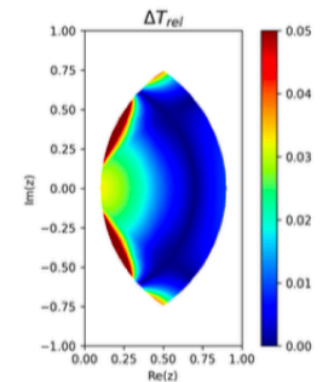
For $d=4$, $J^* = 6$,
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$$a_{1,0} + 3a_{0,2} = 15.0647 \pm 0.0291$$

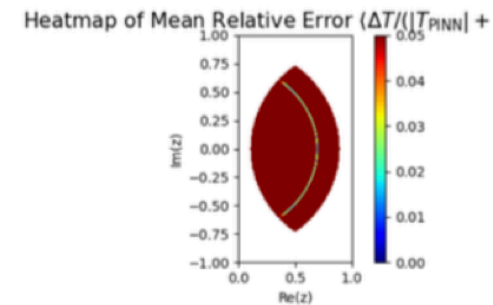
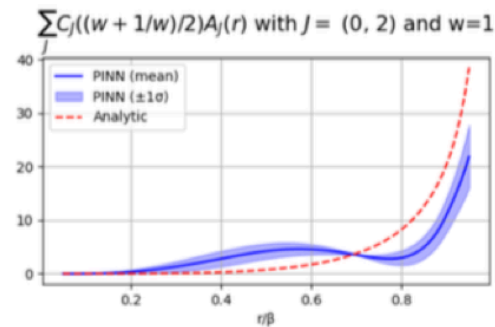
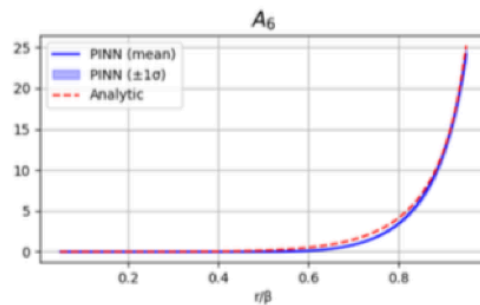
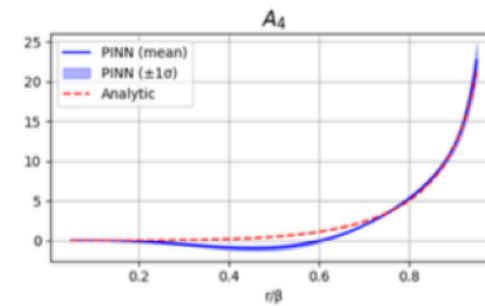
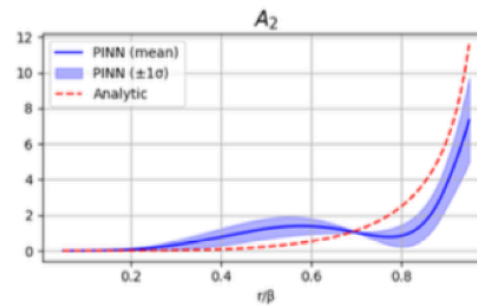
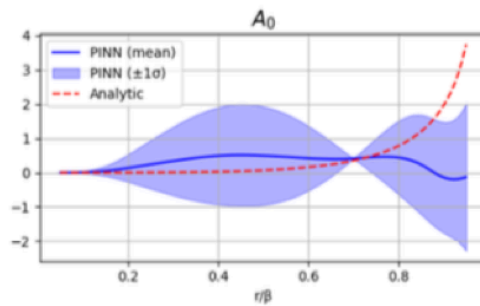


with analytic 15.06013



GFF results summary

- Recovering the approximate correlator is **not stable** without additional input
- But once correct ‘**anchor point**’ is provided solution is determined
- If an incorrect anchor point is provided **stability** is destroyed



Holographic correlators

⇒ Find solution through **stability argument** in cases of interest:
4D **holographic correlators** in a large- c CFT with a gravity dual

The OPE involves:

Operator	Scaling dimension Δ	Spin J	$a_{\Delta,J}$
Identity	0	0	$a_1 = 1$
$T_{\mu\nu}$	d	2	a_T
$[\phi\phi]_{n,J}$	$2(\Delta_\phi + n + \ell)$	$0 \leq 2\ell$	$a_{n,J}$
$[T^k]_J$	dk	$0 \leq 2\ell \leq 2k$	$a_J^{(k)}$

Note: Same spectrum, **infinite KMS solutions** corresponding to arbitrary higher-derivative gravities!

Holographic computation: Solve free wave equation on black brane background

- Energy momentum data determined from asymptotics [Fitzpatrick, Huang '19]
- Lowest-twist energy-momentum multi-trace data have $a_{2k}^{(k)} \propto a_T^k$ (universality)
- Double-twist data harder, requiring full bulk solution

Questions for bootstrap:

- Can we detect multiple KMS solutions corresponding to different gravities?
- Can we detect universality relations?
- Can we recover the double-twist data?

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- Can we recover the double-twist data? \Leftarrow Go for this

Results 3: Holographic theories

Pick $J^* = 6$, $\Delta_\phi = 1.5$ and optimise for $a_{1,0} + 3a_{0,2}$. Include the following 7 holography-provided data in the discontinuity:

$$\text{identity} + T_{\mu\nu} + [T^2]_0 + [T^2]_2 + [T^2]_4 + [T^3]_4 + [T^3]_6 + [T^4]_8$$

$$a_{T,\text{GR}} = 1.21761, \quad a_{0,\text{GR}}^{(2)} = -1.37668, \quad a_{2,\text{GR}}^{(2)} = 1.58848, \quad a_{4,\text{GR}}^{(2)} = -4.05945,$$
$$a_{4,\text{GR}}^{(3)} = 1.77035, \quad a_{6,\text{GR}}^{(3)} = 8.52362, \quad a_{8,\text{GR}}^{(4)} = -15.9641.$$

To help the search, use GFF finite-r input as a starting point, use a [hinge loss](#) and look for **stable** solutions

Results 3: Holographic theories

The loss function is then $\mathcal{L}_{\text{KMS}} + \mathcal{L}_{\text{ReLU}}$ with

$$\mathcal{L}_{\text{ReLU}} = \frac{1}{\frac{J_*}{2} + 1} \sum_J \text{ReLU} \left(\left| \mathcal{A}_J(r_i) - \mathcal{A}_J(r_i)|_{\text{GFF}} \right| - \mathbf{p} \times \left| \mathcal{A}_J(r_i)|_{\text{GFF}} \right| \right)$$

$$\text{ReLU}(x) = \max(0, x)$$



and varying p until we hit a **stable** configuration. This happens around $p = 0.20$

$$p = 0.20 : a_{10} + 3a_{02} = 9.37 \pm 0.44$$

Compare to zero-spatial separation result (using 40 energy-momentum data): 7.686
[Burić, Gusaev, Parnachev '25]

Summary

- Described a new framework to directly bootstrap without truncations
- High operator-dimension **tails** can be bootstrapped using **NNs**
- Presented examples in the case of the **thermal bootstrap** but the method can be applied to any other bootstrap context, including where positivity constraints are not available
- Within finite-T: Unlike other approaches, we work at **non-zero spatial separation** throughout

Outlook

- Improve optimisation accuracy: incorporate more energy-momentum data and dynamical discontinuities to get better double-twist data predictions in holographic CFTs
- Better understanding of the island of stability criteria for algorithm convergence
- Extend applications to zero-T, theories with defects/boundaries, higher-point bootstrap...

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Thank you

Note on loss functions

- L_p -norm (a rather obvious choice): If $\vec{\mathcal{F}}$ is the crossing vector we try to set to 0, then

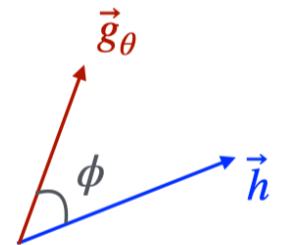
$$\mathcal{L}(\vec{\mathcal{F}}) := \left(\sum_{n=1}^{\dim \vec{\mathcal{F}}} |\mathcal{F}_n|^p \right)^{1/p} \quad \text{for } p \geq 1 \quad (\text{abs-loss for } p = 1)$$

- A (novel) alternative that works better: **dot-loss**

V1: D is empty (**no exposed CFT data**) and $\vec{\mathcal{F}} = \vec{g}_\theta - \vec{h}$ (\vec{g}_θ optimizable, \vec{h} known)

$$\mathcal{L}(\vec{\mathcal{F}}(\theta)) = \left[1 - \frac{|\vec{g}_\theta \cdot \vec{h}|}{|\vec{g}_\theta| |\vec{h}|} \right] + \left| 1 - \frac{\vec{g}_\theta \cdot \vec{h}}{|\vec{h}|^2} \right|$$

$$0 \leq 1 - |\cos(\phi)| \leq 1$$



V2: D has one element (**1 exposed CFT datum a**) and

$$\vec{\mathcal{F}}(a, \vec{\theta}) = a\vec{f} + \vec{g}_\theta - \vec{h} \quad (\vec{g}_\theta \text{ optimizable, } \vec{h} \text{ known, } \vec{f} \text{ known crossed block})$$

In this case:

$$\mathcal{L}(\vec{\mathcal{F}}(\theta)) = 1 - \frac{|(\vec{g}_\theta - \vec{h}) \cdot \vec{f}|}{|\vec{g}_\theta - \vec{h}| |\vec{f}|}$$

you optimize only with respect to the unknown tail functions and you get the coefficient a for free at the end

$$a = - \frac{(\vec{g}_{\theta_*} - \vec{h}) \cdot \vec{f}}{|\vec{f}|^2}$$