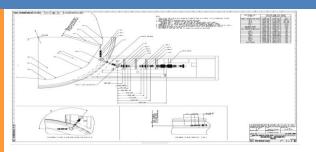
# Active CAD Geometry Handling System

This presentation shall describe;

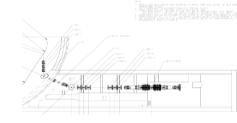
- The motivation to design a new system
- How the new system works and user interaction
  - Current work/results
    - Future work







#### **G4MICE**



My Initial Task:

- Examine technical drawings and surveys
  - Update G4MICE's geometry

Findings:

- Geometry was incorrect, so it became untrustworthy
  - Many people wrote their own geometries

Changes needed:

- A new system?
- Trustworthy and more importantly correct geometries
- A management system which can control this information

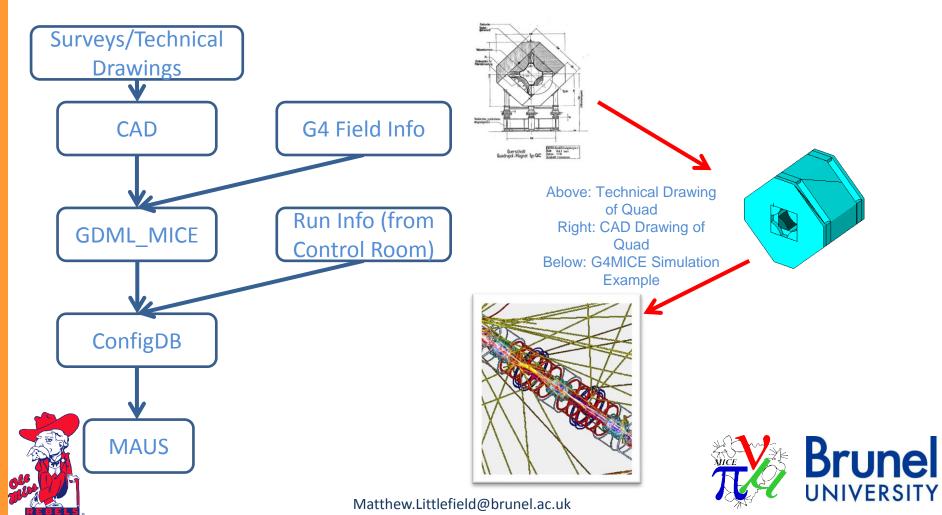
So, an investigation into CAD translation was conducted. It found that we could translate CAD and utilise the Configuration Database (CDB) to store the information.





## **The Designed System**

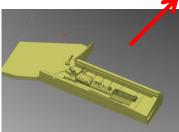
To use this transfer in an efficient manner a new geometry handling system was designed.



### **Current Status**

#### The First Version of this system is now complete!

- The code for the system is finished
- Jason Tarrant is currently working on a new version of the CAD

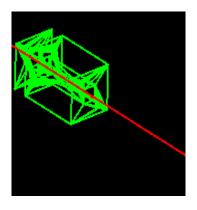


reasons are: Actual CAD is far too large It contains far too much detail Includes many unnecessary parts

Some initial simulations have been conducted 





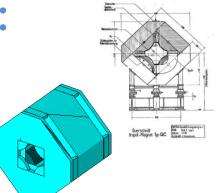


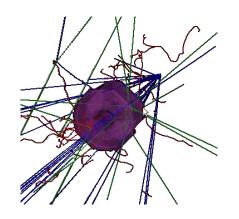
#### Current Simulations: Test Quad

Left: G4MICE Quad

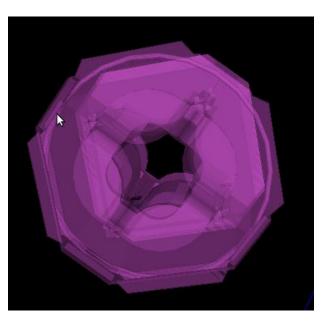
Right: CAD Quad

Below: CAD translated MAUS Quad



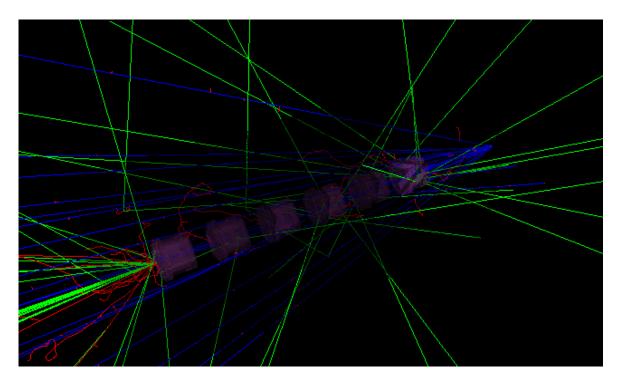








### Current Simulations: 6 Quads (Step 1)







### **User/Developer Interaction**

#### **Developers will:**

- 1. Run CAD through FastRad
- 2. Run one executable upon the GDML files which will upload the geometry to the CDB

#### Users will be able to:

- 1. Download current geometry directly into MAUS or download a local copy
- 2. Download an old geometry directly into MAUS or download a local copy
- 3. Download geometry, from a particular run number, directly into MAUS or download a local copy





### **Future Work**

- Once Jason Tarrant's CAD is complete upload it to database (first official geometry
- Finalise details of management (Fastrad translation and internal detector geometries)

• Extend the code to include the merging of run data\field information (Provisions for this are already in the code, however the details of how the simulation will use this need to be finished)

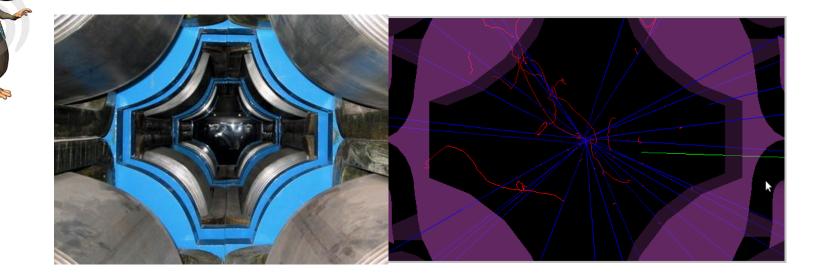
- Write code which downloads the geometry directly to the simulation (doesn't download a local copy)
- Collect internal geometries from each detector group (Oleg from the tracker and Gene from the CKOV have already begun) and then extend the GDML\_MICE schema



• As always TESTS! TESTS! TESTS!



#### **Any Questions?**



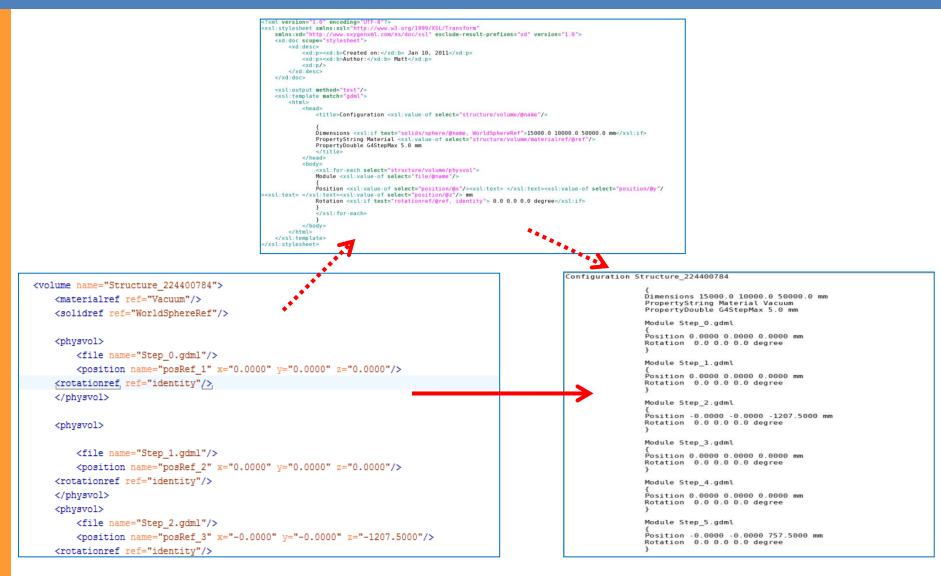


#### **Thank You for Listening**



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{	PropertyDouble BlueColour 0.75
Dimensions	PropertyDouble GreenColour 0.3
PropertyString Material AIR	PropertyDouble RedColour 0.75
PropertyDouble G4StepMax 5.0 mm	PropertyInt noOfVertices 96
Propercybouble ovstephax 5.0 mm	PropertyInt moOfTFacets 192
	PropertyInt moOfQFacets 0
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	PropertyHep3Vector Vector5 -222.9558 -91.8497 103.5149
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Rotation	PropertyHep3Vector Vector10 -252.1166 -50.8120 52.1187
hocación	PropertyHep3Vector Vector11 -257.2766 -28.6124 43.0242
1	PropertyHep3Vector Vector12 -259.4254 -4.4629 39.2369
	PropertyHep3Vector Vector13 -239.0388 -33.7846 75.1684
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Rotation	PropertyHep3Vector Vector17 -178.7701 -63.2373 181.3927
hototton	PropertyHep3Vector Vector18 -188.0163 -79.0831 165.0961 PropertyHep3Vector Vector19 -190.2712 -42.0461 161.1219
/	PropertyHep3Vector Vector20 -185.6786 -28.6449 169.2164
	PropertyHep3Vector Vector21 -182.9540 -13.2917 174.0184
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Rotation	
1	
1	
Module BeamLine/Step 4.dat	
/ / // beam.inc/step_4.uat	
1 Position 0.0000 0.0000 0.0000 mm	
MARITIAN D DODD D DODD D DODD MM	









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