

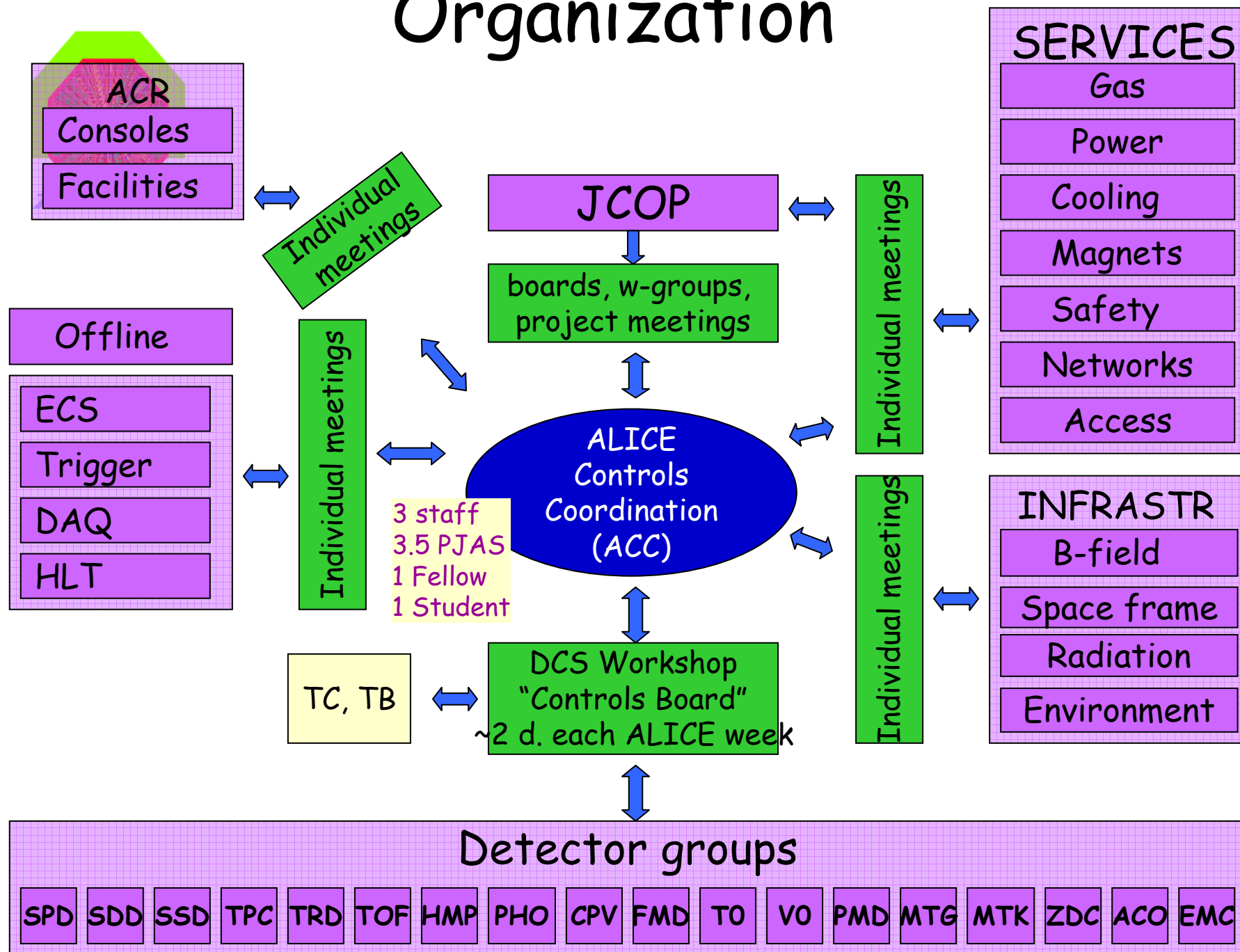


ALICE DCS part 1

DCS workshop 3.4.06
L.Jirden for the ALICE team

- ◆ Organization & responsibilities
- ◆ Coordination role
- ◆ JCOP participation
- ◆ Installation & commissioning
- ◆ Critical issues part 1

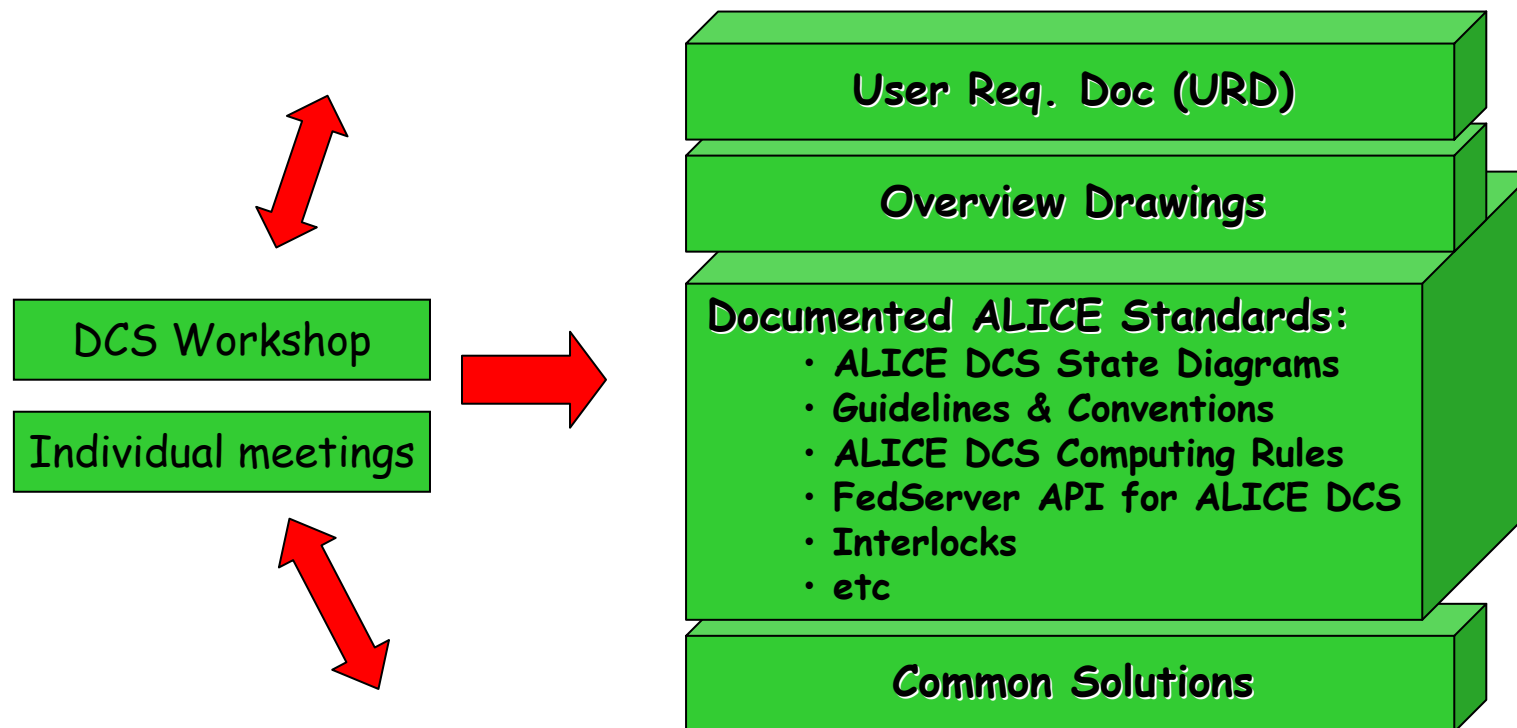
Organization



Liaison with Detectors



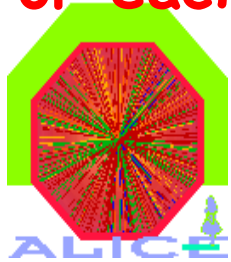
ALICE
Controls
Coordination
(ACC)



Detector groups

SPD SDD SSD TPC TRD TOF HMP PHO CPV FMD TO VO PMD MTG MTK ZDC ACO EMC

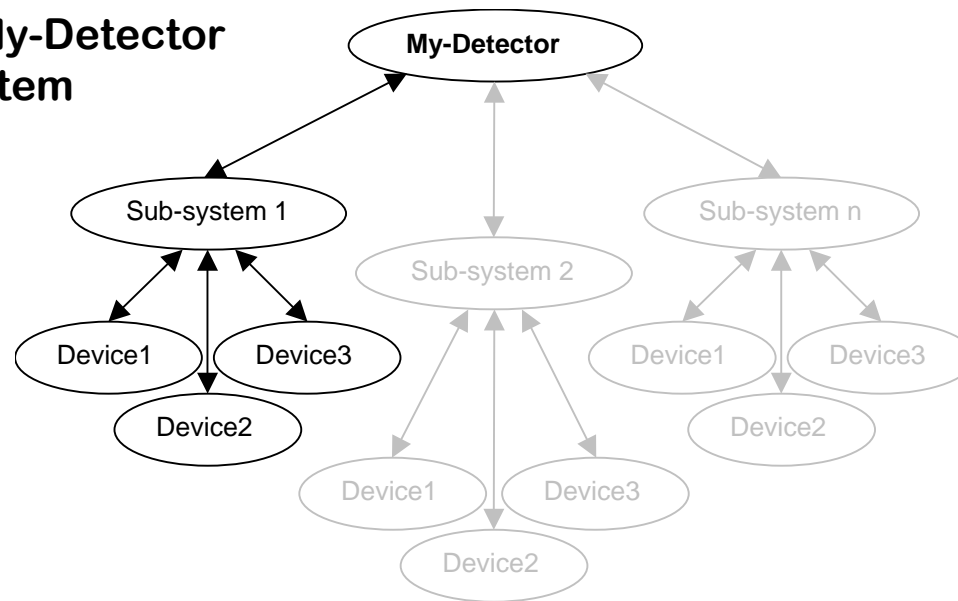
For each detector:



Template version 2 (19 December 2001)

DCS User Requirements Document for My-Detector Version x (dd month yyyy)

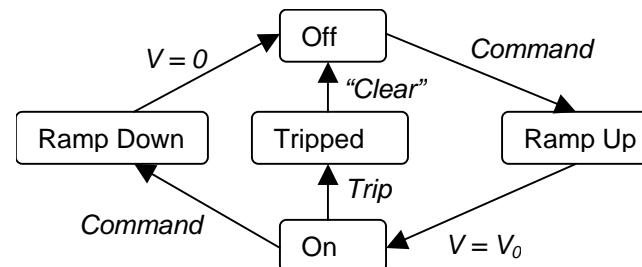
1. Introduction
2. Description of My-Detector
3. The Control System



I. Description and requirements of the Sub-systems

- 1) Sub-system 1
 - a) Functionality
 - b) Device or Equipment
 - c) Interlocks and Safety aspects
 - d) Operational and Supervisory aspects

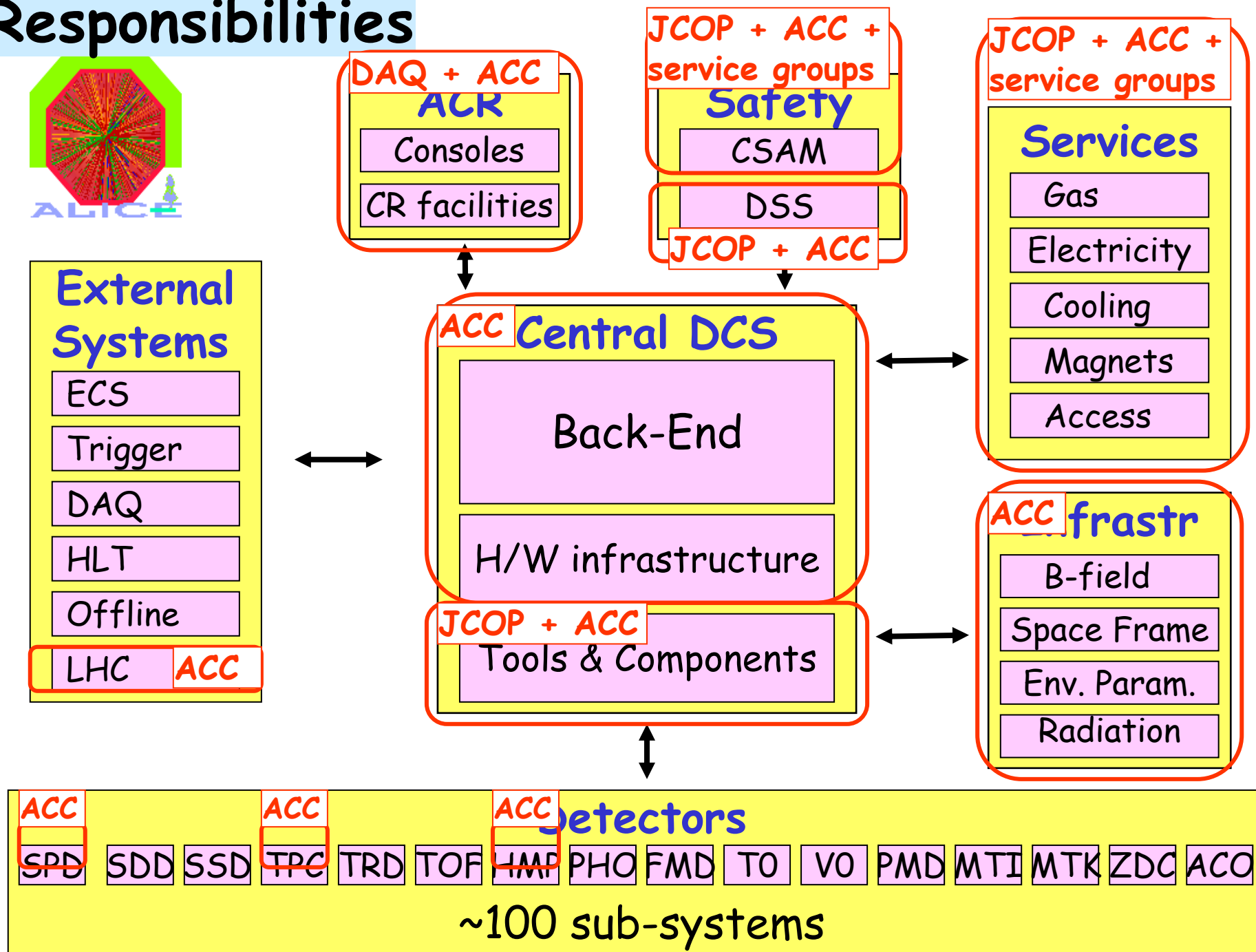
etc.



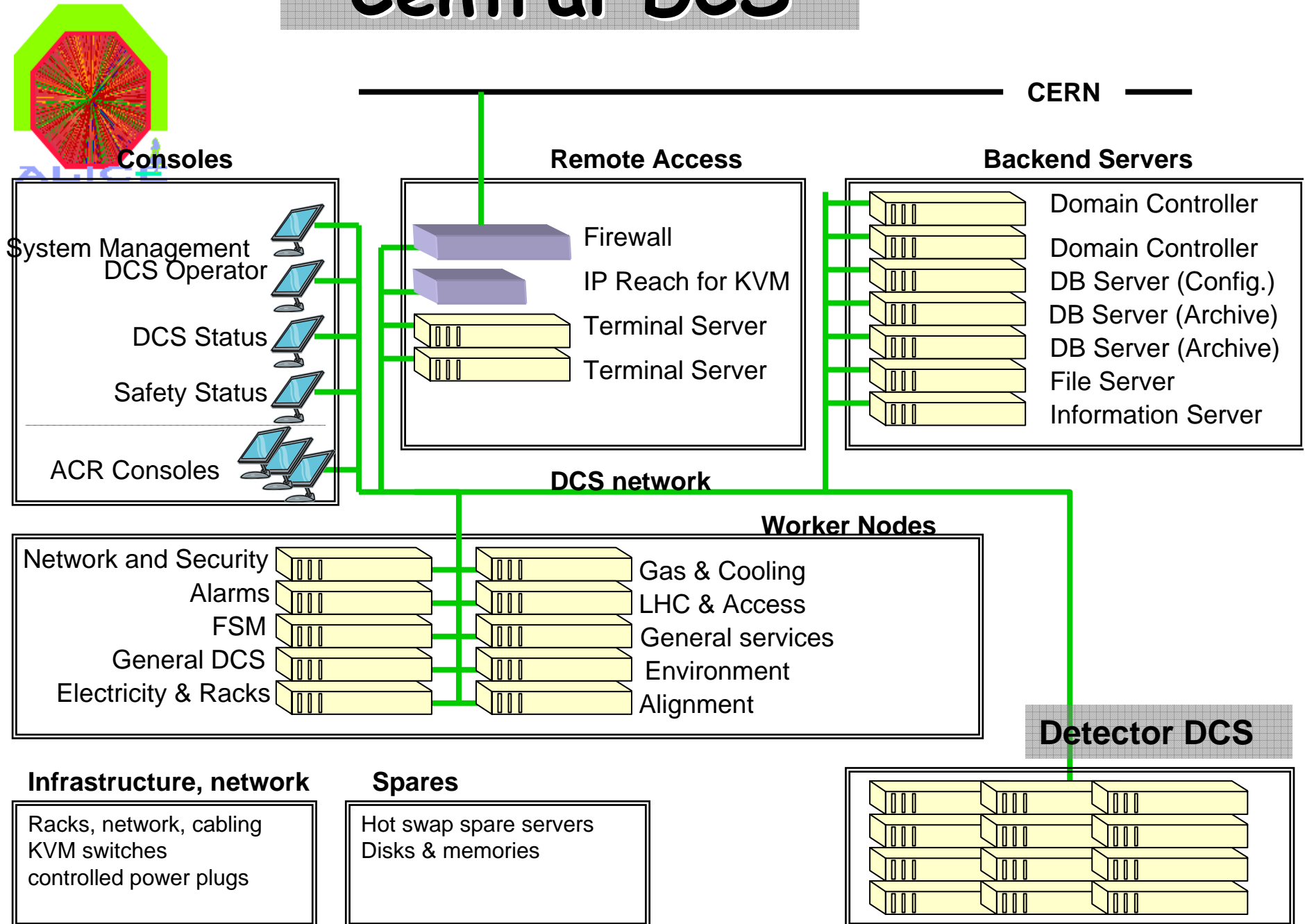


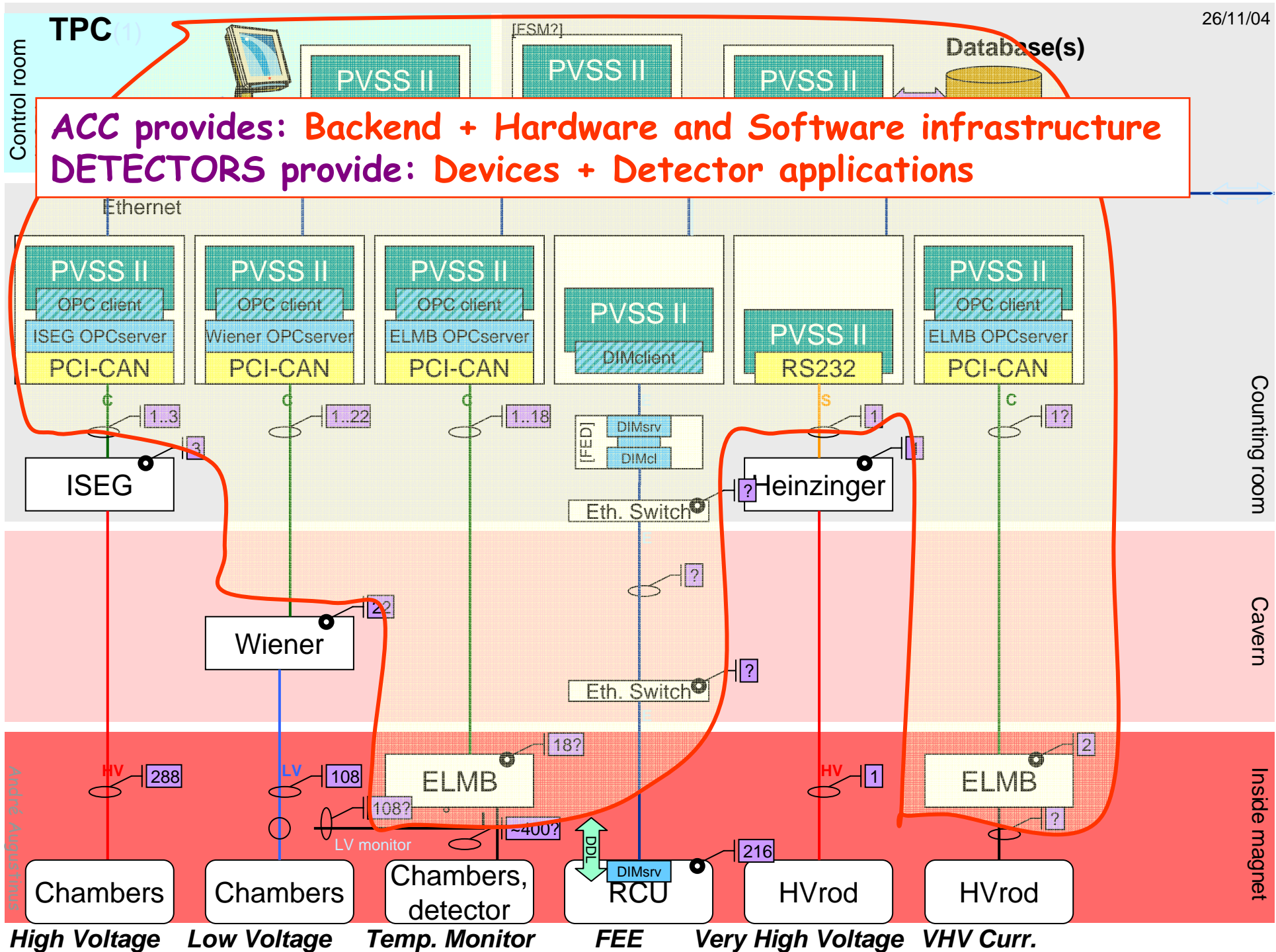
	Common/specific	7
	Unknown	2
TOTAL		105

Responsibilities



Central DCS







Coordination in purchase of equipment

◆ Purchased by ACC

◆ Computers

- ◆ Servers for back-end
- ◆ PC's for back-end and front-end (~90)
 - ◆ all details on DCS web page:
<http://alicedcs.web.cern.ch/AliceDCS/Meetings/>
- ◆ PCI's: Kvaser, Peak, Caen PCI-VME bridge, MXI

◆ Network

- ◆ Global network (~400 ports), sub-contracted to IT/CS
- ◆ On-detector network (~1000 ports) by ACC

◆ Devices


- ◆ ELMB's (~150) + ELMB power
- ◆ Serial device (RS232)



Serial devices (RS232)

◆ Aim for standard way of interfacing this class

◆ *Physical interface (cables and alike)*

- ◆ Needs a COM port on a PC; cable length is limited
- ◆ A standard (and transparent !) way to use serial over Ethernet overcomes this limit 
- ◆ CERN *standard*, expertise exists
- ◆ Examples exist, several detectors start using it
- ◆ Exist in single and multi-port version

◆ *Software interface (transporting the data)*

- ◆ PVSSII has all one needs to 'drive' a serial connection
- ◆ Examples exist

◆ *Functional interface (exchange sensible data)*

- ◆ Application dependent
- ◆ to be developed by the detector (using the above!)





Coordination in purchase of equipment

◆ Coordinated by ACC

◆ LVPS

- ◆ Wiener PL512, water-cooled (6 detectors ~115 units)
 - ◆ Caen Easy (7 detectors ~110 units)
 - ◆ Caen SY1527 (2 detectors, 1 units)
 - ◆ AREM Pro (1 detector, 6 units)
-

◆ HVPS

- ◆ ISEG, 4 module types (4 detectors, ~15 crates)
- ◆ Caen SY1527 (13 detectors, ~20 main-frames)

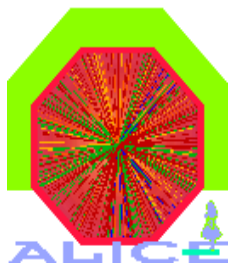
◆ VME

- ◆ Wiener 6U & 9U, local PS, water & air cooled (15 detectors, ~60 crates)

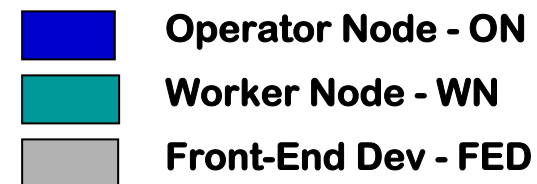


Detector computer distribution

- ◆ **Strict separation per detector, to allow for:**
 - ◆ Staged installation
 - ◆ Independent operation
- ◆ **Distribution of sub systems based on:**
 - ◆ Number of channels
 - ◆ Estimated resources needed by a sub system
 - ◆ Performance tests done by several groups
 - ◆ Some specific requests



Detector computers



SPD

Operator Node
HV + LV
FED + Crate
FED
FED

SDD

Operator Node
HV
LV + FED + Crate
FED

SSD

Operator Node
HV + LV
FED + Crate + ELMB
FED

TPC

Operator Node
HV
LV + ELMB
VHV
FED
Pulser
Laser
Laser
Drift velocity
FED

TRD

Operator Node
HV
LV
FED
FED
FED

TOF

Operator Node
HV
LV
FED + Crate
FED [18]

HMPID

Operator Node
HV + LV
Crate + PLC

PHOS

Operator Node
HV + FED + LED
LV + ELMB + Crate
FED

CPV

Operator Node
HV + LV + ELMB

Muon Trk

Operator Node
HV
LV
Crate + ELMB + GMS

Muon Trg

Operator Node
HV + LV
Crate + ELMB

FMD

Operator Node
HV + LV + FED
FED

T0

Operator Node
HV + LV
FED + Crate + Laser
FED

V0

Operator Node
HV + LV + Crate

PMD

Operator Node
HV + LV
Crate + ELMB

ZDC

Operator Node
HV + Crate

ACORDE

Operator Node
HV + LV

EMC

Operator Node
HV + LV + FED
FED



PVSS & FSM distribution

◆ PVSS

◆ Baseline approach

- ◆ Each detector DCS will be a *distributed* PVSS system
- ◆ Each WN will run a single PVSS project
 - ◆ when several sub systems are controlled from a single WN these shall be grouped in a single project
- ◆ All detector DCS's will form one big distributed system (of distributed systems)

◆ FSM

- ◆ integrated in the respective PVSS projects
 - ◆ One PVSS project can have several FSMs
 - ◆ Detector DCS FSM' to run on least loaded node



Training & Tutorials

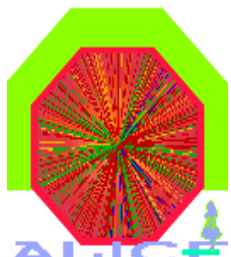
- ◆ JCOP courses
 - ◆ Are appreciated
 - ◆ At least one person from each detector has now taken the basic course
 - ◆ Problem: manpower changes, students graduating
 - ◆ Make handouts available
- ◆ DCS workshops
 - ◆ ALICE “tutorials”
- ◆ DCS week planned
 - ◆ JCOP advanced course + ALICE tutorials



ALICE DCS week

◆ Program (preliminary)

◆ Monday		hours
◆ Framework tools & components; recap	IT/CO	8
◆ Tuesday		
◆ Alarm handling	IT/CO	2
◆ Configuration Dbase	IT/CO	5
◆ Access control	IT/CO	1
◆ Wednesday		
◆ FSM	IT/CO + ALICE	8
◆ Thursday		
◆ DIM	IT/CO	1
◆ Framework devices	IT/CO	1.5
◆ Conditions	ALICE	1.5
◆ Distributed systems	ALICE	1
◆ ALICE Front-End Device (FED)	ALICE	2
◆ ALICE FEE configuration	ALICE	1
◆ Friday		
◆ ALICE DCS guidelines/standards/rules	ALICE	2
◆ Detector specific applications & AOB	ALICE	6



Detectors

	H M P	T P C	S P D	T R D	T O F	M T K	M T G	T O	P M D	A C O	P H O	S D D	S S D	F M D	V O	Z D C	C P V	E M C
User requirements																		
Use of tools & components																		
Basic device control																		
FSM for at least one subsystem																		
Test with ECS/DAQ																		
All subsystems ready																		



done/used



not done/not used



JCOP ↔ **ALICE**

◆ **JCOP** → **ALICE**

- ◆ Most Fw components + DSS system + GAS control
- ◆ Advice, assistance: PLC applications, OPC tests, etc
- ◆ Participation in ALICE DCS workshops

◆ **ALICE** → **JCOP**

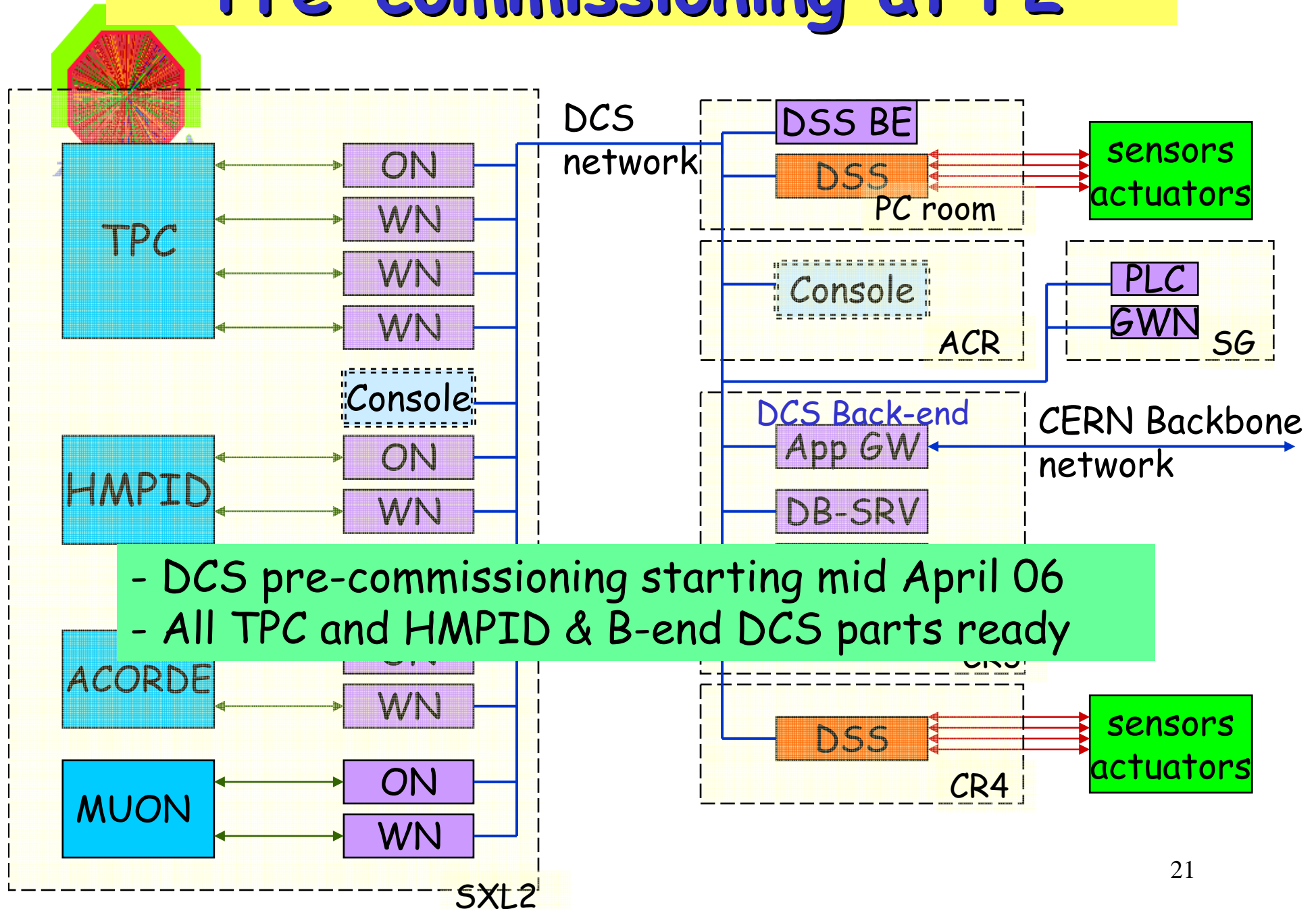
- ◆ ISEG component
- ◆ BCAM component
- ◆ Cooling control
- ◆ Terminal Server evaluation
- ◆ Performance testing
 - ◆ Caen HV
 - ◆ PVSS scaling
 - ◆ Oracle archiving

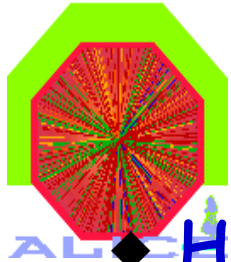


Main scheduled “challenges” before LHC start-up

- ◆ **Pre-commissioning on surface at P2**
 - ◆ **Functional verification of DCS including**
 - ◆ 2 detectors with final devices
 - ◆ all main sub-systems and services
 - ◆ **Final validation of ALICE approaches for**
 - ◆ Back-end, FSM, configuration, archival, alarms
 - ◆ Software & hardware interlocks
 - ◆ Interface with ECS, DAQ, TRG, HLT

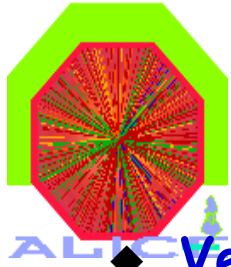
Pre-commissioning at P2





DCS final installation - procedure -

- ◆ **H/W and S/W infrastructure**
 - ◆ ACC install and verify network, PC's (with PCI), and base s/w
- ◆ **Detector hand over to ACC**
 - ◆ **S/W projects**
 - ◆ the detector PVSS project
 - ◆ 3rd party software with documentation and installation kits
 - ◆ Front-end configuration and control tools
 - ◆ **Documentation (stored on DCS web pages)**
 - ◆ Description of the PVSS hierarchy
 - ◆ Assignment of the managers to the detector computers
 - ◆ Configuration of the OPC servers (where they should run, what devices should be accessed)
 - ◆ FED servers (where they should run)
 - ◆ archival - what parameters are archived
 - ◆ parameters to be stored in the conditions database (including the datapoint names)
 - ◆ FER0 configuration description



DCS final installation - procedure -

◆ Verification

- ◆ ACC checks for obvious errors
 - ◆ incorrect path names, incorrect external dependencies, violations of the DCS conventions such as naming of the systems or DIM services etc.
- ◆ For viruses
- ◆ For completeness of documentation

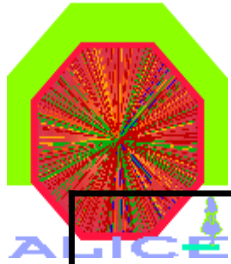
◆ Installation

- ◆ ACC uploads software to the installation server on DCS network
- ◆ ACC + Detector expert install on target machines
 - ◆ setting-up of the PVSS system
 - ◆ integration into global DCS,
 - ◆ configuration of database access and FW access control
- ◆ back-up

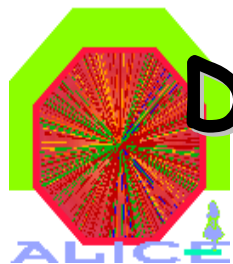
◆ Commissioning

- ◆ Detector expert validates functionality with devices
- ◆ Detector expert demonstrates functionality of alerts, operational panels, FSM, etc.

Detector final installation planning



DETECTORS	From (D time)	To
PHOS, TOF, TRD, HMPID, ACORDE	10 July	1 Sept
TPC	4 Sept	2 Oct
SDD, SSD (ITS Barrel)	3 Oct	8 Nov
FMD, TO, VO on C-side	9 Nov	28 Nov
SPD, SDD, SSD	29 Nov	10 Jan 07
TOF, TRD	31 Jan 07	6 Mar 07
FMD, TO, VO, PMD on A-side	4 Apr 07	23 Apr 07



DCS final installation planning

For each sub-system (in total ~ 100):

Pre-commissioning on surface (institute/CERN) who ready

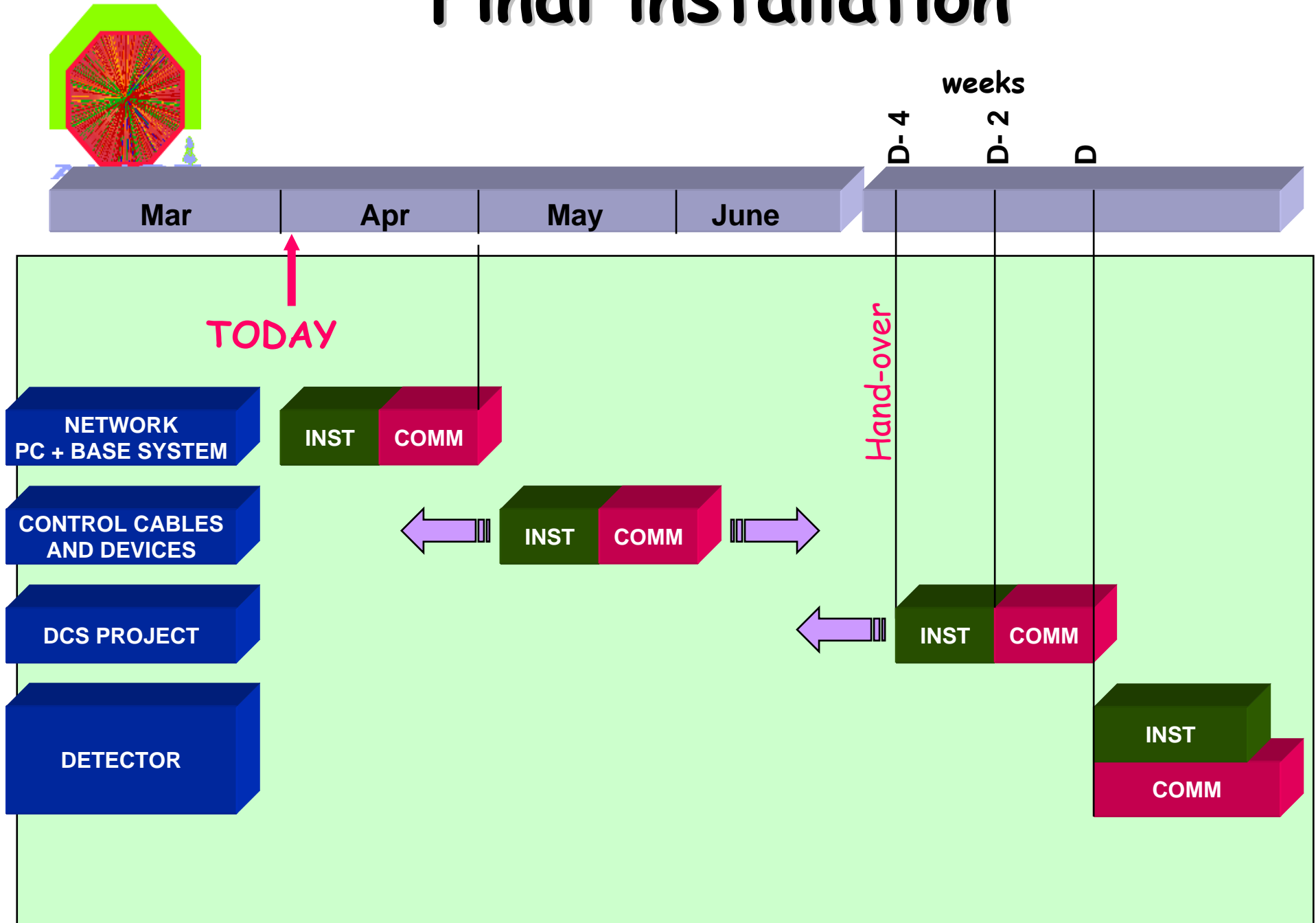
- ◆ PVSS - OPC - h/w device connection AA date
- ◆ FSM, configuration, archival, alarms BB date
- ◆ s/w interlocks, operations panels CC date

Commissioning in the experimental area who ready

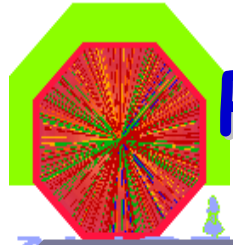
- ◆ s/w hand-over to ACC AA <D-4 weeks
- ◆ Installation & commissioning of devices BB <D-2 weeks
- ◆ Commissioning devices with detector CC D

D = detector installation date

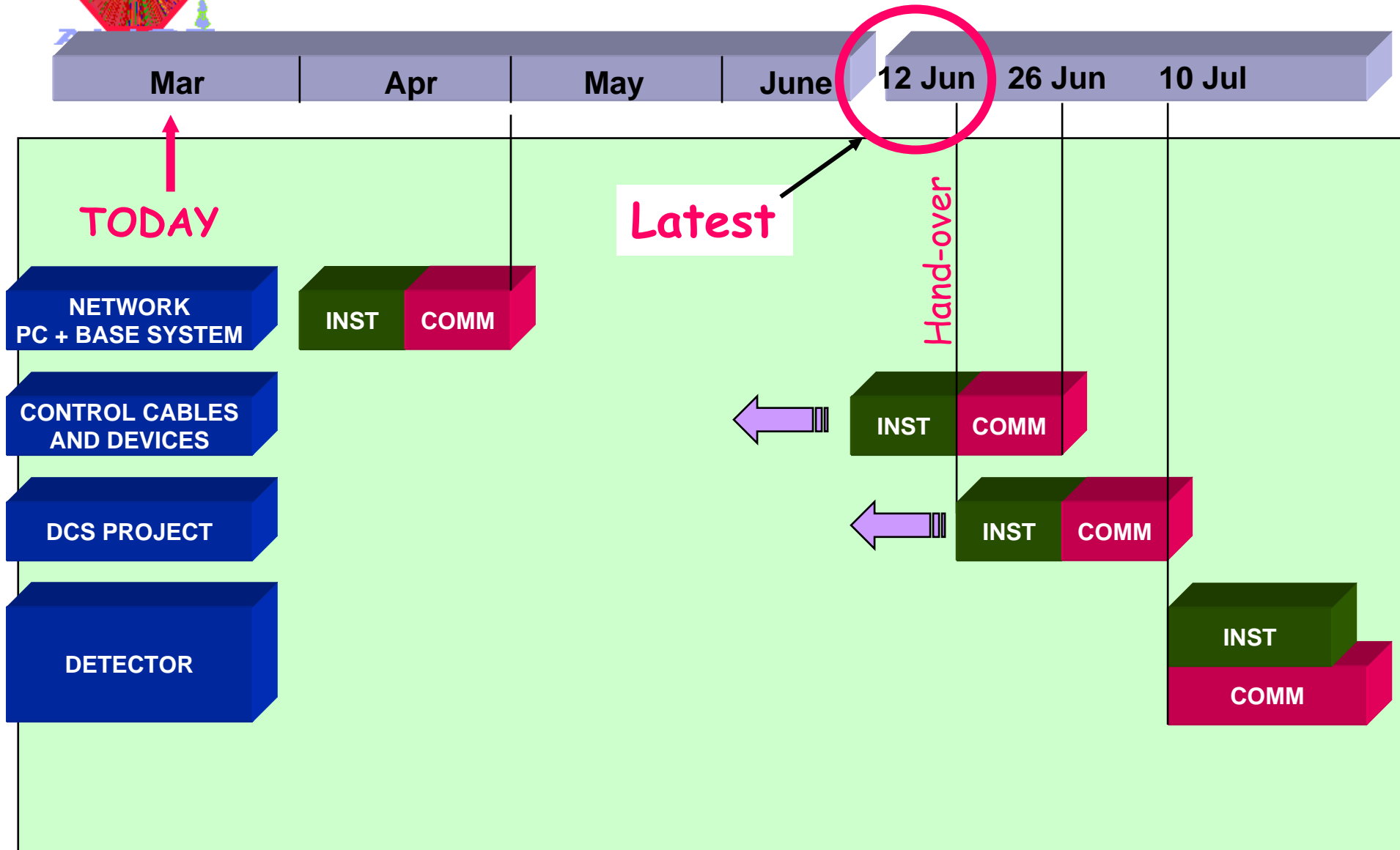
Final installation

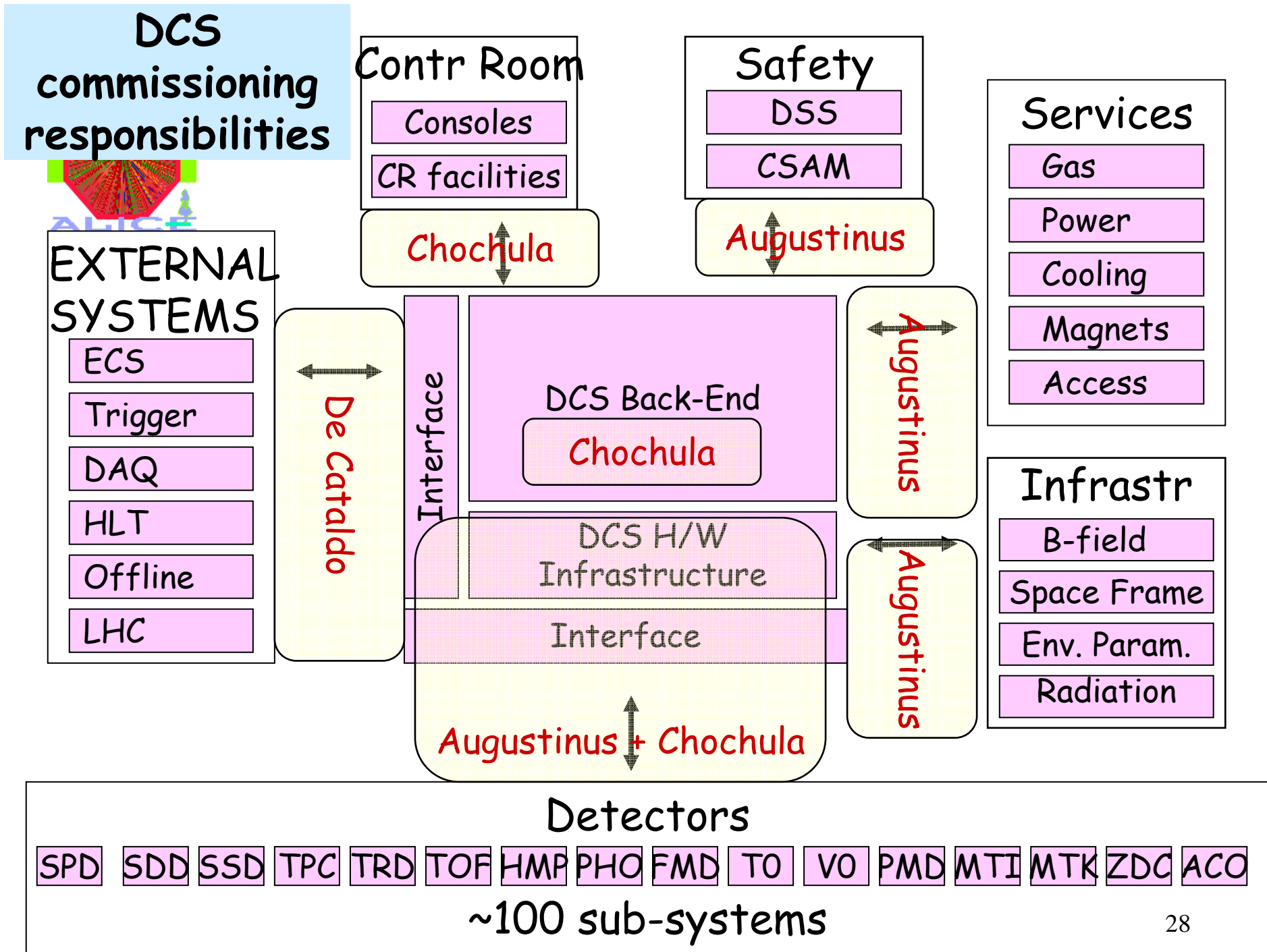


Final installation:



PHOS, TOF, TRD, HMPID, ACORDE







Testing and validating DIP

◆ First use/commissioning of DIP

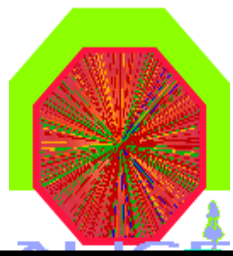
- ◆ CSAM data → DCS pre-commissioning May 06
- ◆ MCS data → DCS Magnet tests end May 06
- ◆ DCS data → LHC final commissioning end 06?

◆ Assistance from JCOP?



Integration with other on-line systems

- ◆ DCS ↔ ECS ↔ DAQ commissioning
 - ◆ Done for 2 detectors (HMPID and SPD)
 - ◆ Planned for TPC during pre-commissioning June 06



Global status today ("dashboard" on DCS website)

	SPD	SDD	SSD	TPC	TRD	TOF	HMP ID	PHO S	CPV	μ -trk	μ -trg	FMD	TO	VO	PMD	ZDC	ACO	EMC	Trig.	DCS
DET																				
HV	CAEN	iseg	CAEN Easy	iseg	iseg +distr	CAEN	CAEN	Iseg +V reg.	CAEN	CAEN +distr	CAEN	CAEN	CAEN	CAEN	CAEN	CAEN	CAEN	Iseg		
LV	CAEN Easy	AREM pro	CAEN Easy	Wiener	Wiener	ALICE box	CAEN Easy	Wiener	Wiener	Wiener	Wiener	CAEN Easy	CAEN	CAEN Easy	Easy +distr		CAEN Easy	Wiener		
VME	Wiener VME	Wiener VME	Wiener VME		Wiener VME	Wiener VME	Wiener VME	Wiener VME		Wiener VME	Wiener VME		Wiener VME	Wiener VME	Wiener VME	Wiener VME			Wiener VME	
MON			ELMB	ELMB			PLC	ELMB	ELMB	ELMB	ELMB				ELMB			?	DIM	ELMB
FED	JTAG	DCS	JTAG	RCU	DCS	DRM		RCU				RCU	DRM	DCS				RCU		
Cool																				
GAS																				
				VHV			Liquid	LED		GMS			Thresh			Position		LED?		RackCtrl
				Pulser				Crystal					Laser							Align
				Laser																BField
				Drift Vel.																RadMon

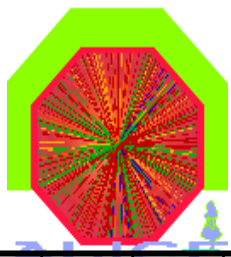
Control with FSM
 Basic control with PVSS

Activity started, without PVSS

Under definition

No (SW) activity started

No (SW) activity started, but common effort



5 "critical" detectors

	SPD	SDD	SSD	TPC	TRD	TOF	HMP ID	PHO S	CPV	μ -trk	μ -trg	FMD	TO	VO	PMD	ZDC	ACO	EMC	Trig.	DCS
DET																				
HV	CAEN	iseg	CAEN Easy	iseg	iseg +distr	CAEN	CAEN	Iseg +V reg.	CAEN	CAEN +distr	CAEN	CAEN	CAEN	CAEN	CAEN	CAEN	CAEN	Iseg		
LV	CAEN Easy	AREM pro	CAEN Easy	Wiener	Wiener	ALICE box	CAEN Easy	Wiener	Wiener	Wiener	Wiener	CAEN Easy	CAEN	CAEN Easy	Easy +distr		CAEN Easy	Wiener		
VME	Wiener VME	Wiener VME	Wiener VME		Wiener VME	Wiener VME	Wiener VME	Wiener VME		Wiener VME	Wiener VME		Wiener VME	Wiener VME	Wiener VME	Wiener VME			Wiener VME	
MON			ELMB	ELMB			PLC	ELMB	ELMB	ELMB	ELMB				ELMB			?	DIM	ELMB
FED	JTAG	DCS	JTAG	RCU	DCS	DRM		RCU				RCU	DRM	DCS				RCU		
Cool																				
GAS																				
				VHV			Liquid	LED		GMS			Thresh			Position		LED?		RackCtrl
				Pulser				Crystal					Laser							Align
				Laser																BField
				Drift Vel.																RadMon

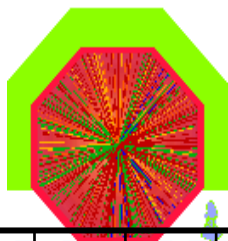
Control with FSM
 Basic control with PVSS

Activity started, without PVSS

Under definition



No (SW) activity started

No (SW) activity started, but common effort




15 "critical" subsystems

	SPD	SDD	SSD	TPC	TRD	TOF	HMP ID	PHOS	CPV	μ -trk	μ -trg	FMD	TO	VO	PMD	ZDC	ACO	EMC	Trig.	DCS
DET																				
HV	CAEN	iseg	CAEN Easy	iseg	iseg +distr	CAEN	CAEN	Iseg +V reg.	CAEN	CAEN +distr	CAEN	CAEN	CAEN	CAEN	CAEN	CAEN	CAEN	Iseg		
LV	CAEN Easy	AREM pro	CAEN Easy	Wiener	Wiener	ALICE box	CAEN Easy	Wiener	Wiener	Wiener	Wiener	CAEN Easy	CAEN	CAEN Easy	Easy +distr		CAEN Easy	Wiener		
VME	Wiener VME	Wiener VME	Wiener VME		Wiener VME	Wiener VME	Wiener VME	Wiener VME		Wiener VME	Wiener VME		Wiener VME	Wiener VME	Wiener VME	Wiener VME			Wiener VME	
MON			ELMB	ELMB			PLC	ELMB	ELMB	ELMB	ELMB				ELMB			?	DIM	ELMB
FED	JTAG	DCS	JTAG	RCU	DCS	DRM		RCU				RCU	DRM	DCS				RCU		
Cool																				
GAS																				
				VHV			Liquid	LED		GMS			Thresh			Position		LED?		RackCtrl
				Pulser				Crystal					Laser							Align
				Laser																BField
				Drift Vel.																RadMon

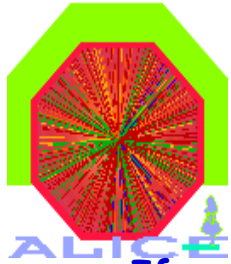
 Control with FSM
 Basic control with PVSS

 Activity started, without PVSS

 Under definition

 No (SW) activity started

 No (SW) activity started, but common effort



Remarks

- ◆ If not started on HV and LV, then mainly because of no hardware (waiting for PS)
- ◆ LV wiener, when application exist, it is with CANbus version of PL500
- ◆ For several detectors the environment monitoring is still under definition (number/type of sensors etc.)
- ◆ For HV/LV/ELMB detectors can profit from framework etc. For FEE more effort is needed from detectors. Thus red or yellow in FEE is more worrying than red in HV/LV
- ◆ For Crate control, cooling and gas an effort is expected from the ACC (thus less work for detectors)
- ◆ The FEE for TOF, TO is green/yellow: work on SW has started, some PVSS panels exist, but it need to be clarified if this adheres completely to the FED concept
- ◆ The FEE for FMD is yellow/red: They started to use the RCU, but not really using the 'DCS part' of it
- ◆ The Laser for TPC is green/yellow: all parts of the system have been worked on, not all under PVSS
- ◆ The Vo is indicated mainly red because of lack of information
- ◆ The environment monitoring for EMC is not yet defined. There will be a LED calibration system, the controls of it need to be clarified. EMC has experience with PVSS (older version of their FEE), but not with the sub-systems listed here



Progress monitoring

- ◆ For Public

- ◆ Status dashboard on web

- ◆ For Experts

- ◆ Status panel on DCS top node accessed via Terminal Server