





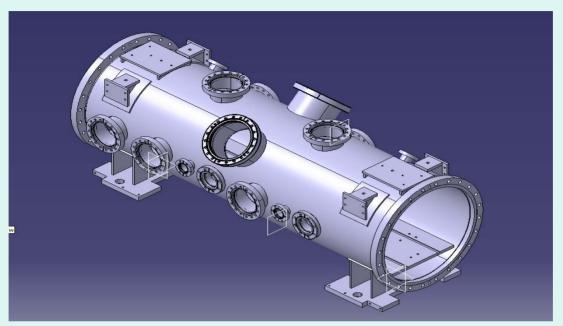
Pakistan – CLIC Collaboration by Azhar Nawaz, HMC-3 Taxila

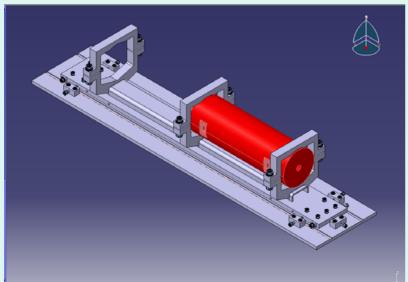
MAIN AGENDA:

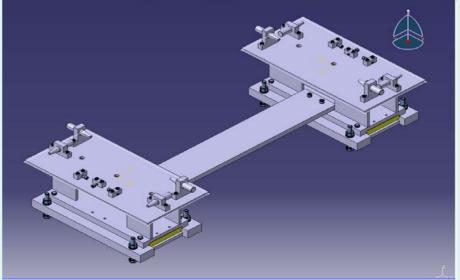
- 1- Present ongoing Collaboration in Design.
- 2- Production Jobs done for CLIC.
- 3- Possible Production of RF Structures.



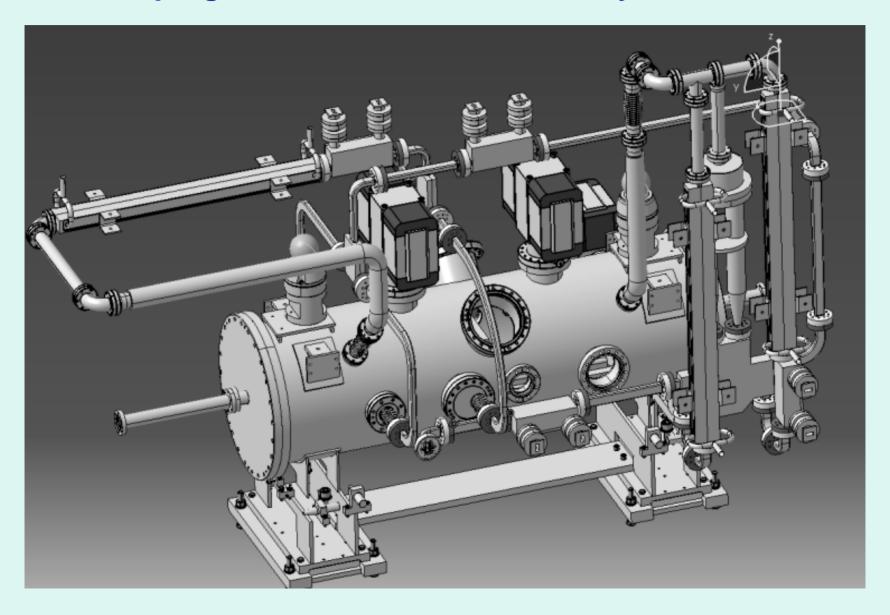
a) Design of ACS Tank, Support & Alignment System



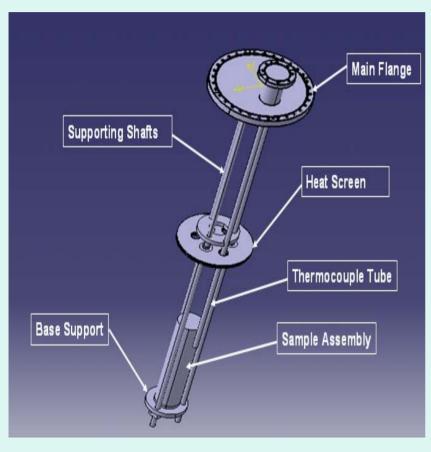




Present on going collaboration in Design. b) RF Piping & Vacuum Connection Layout

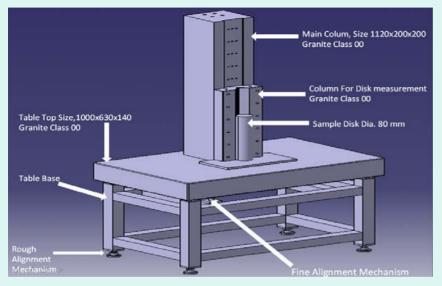


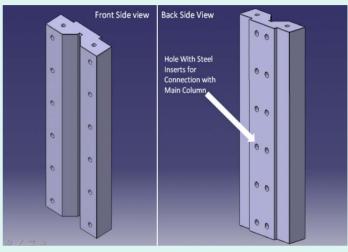
c) Baking Support for RF Assembly

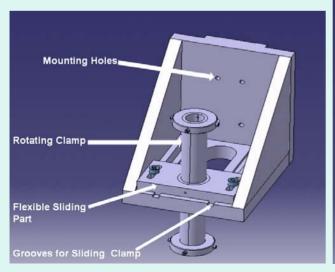


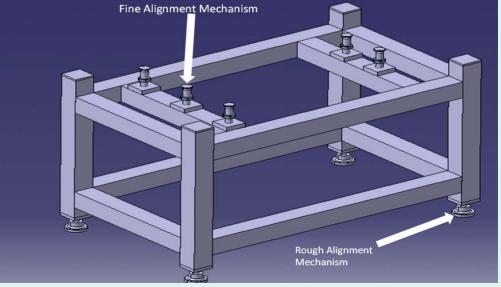


d) Measuring Table for RF Components

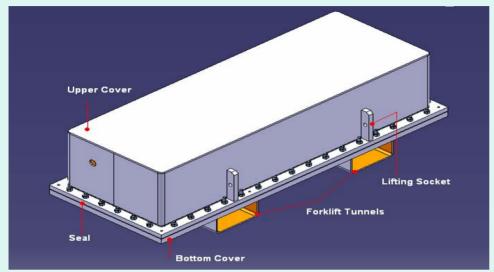


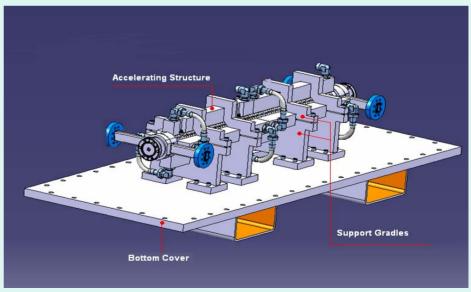




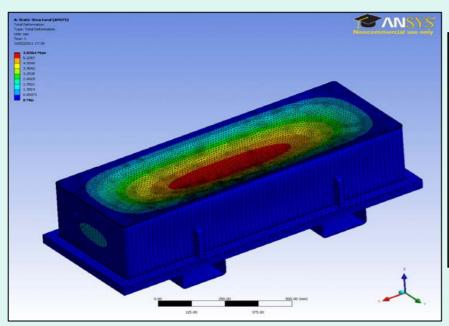


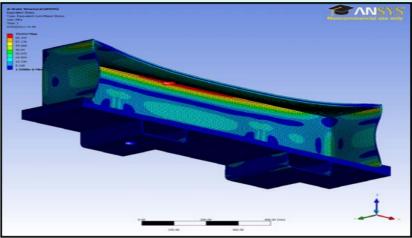
e) Transport Tank for Accelerating Structure.

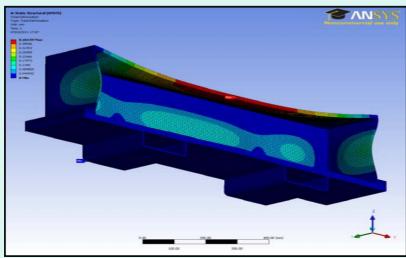


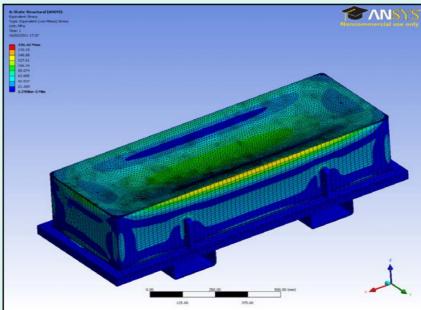


f) Analysis of Transportation Tank for PSI Structure

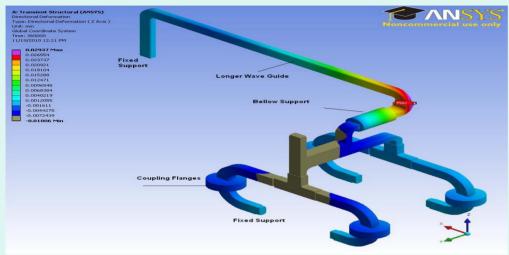


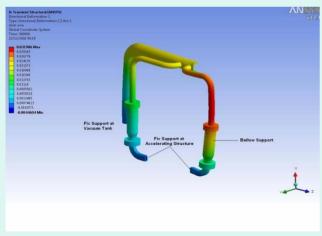


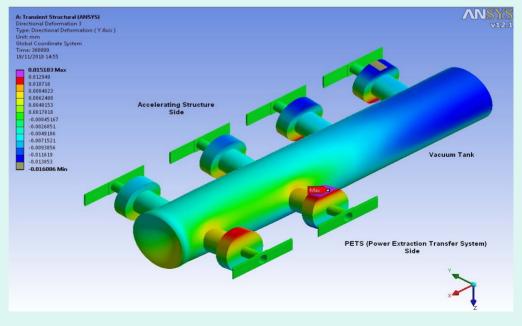




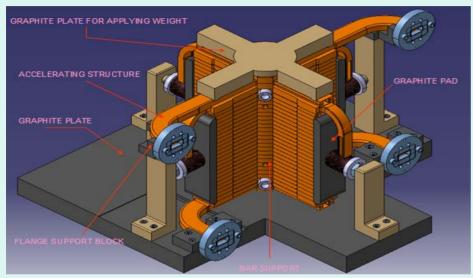
g) Finite Element Analysis of Vacuum Components

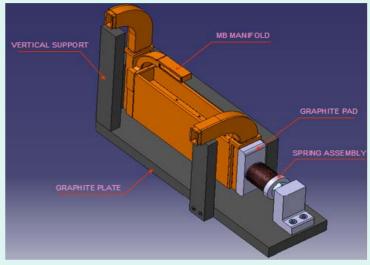


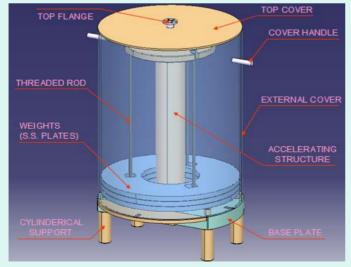


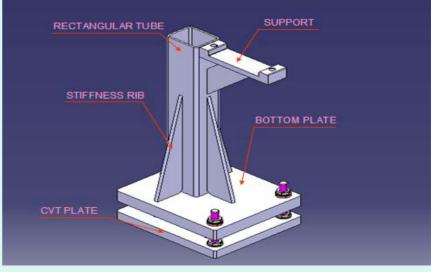


h) Design of Jigs and Fixtures for Holding Different Components of Accelerating Structure during Brazing.

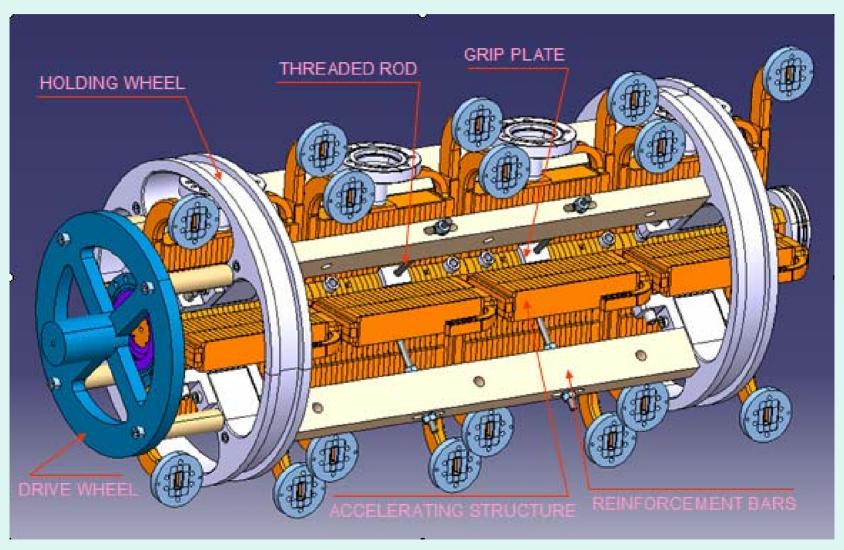




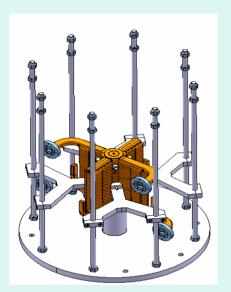


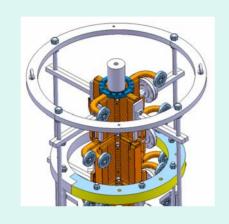


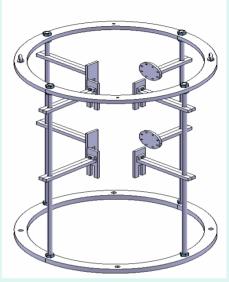
i) Design of Tooling for Electron Beam Welding of Accelerating Structure.

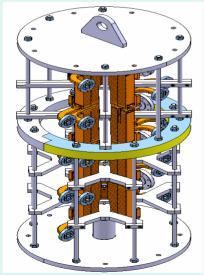


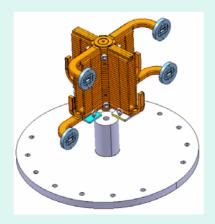
j) Super-AS Stack Tooling Design for Brazing & Handling.

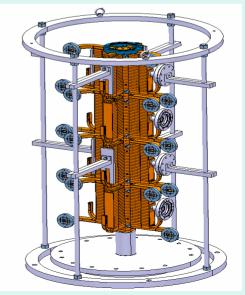




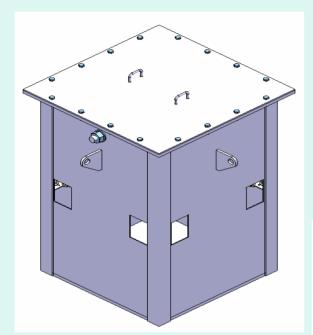


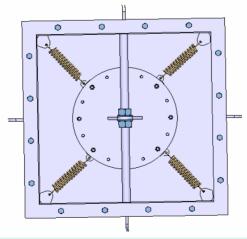


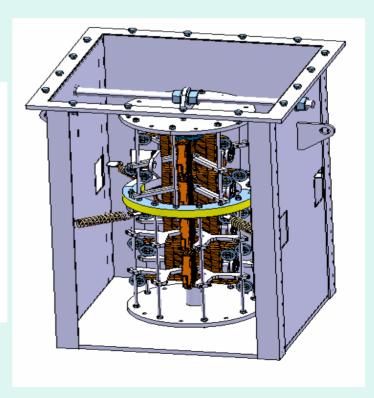




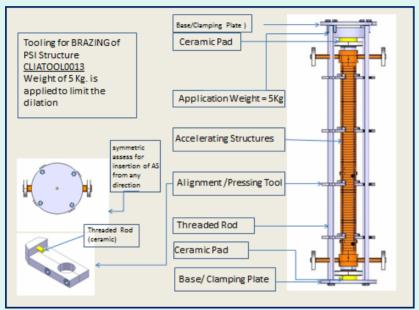
k) Transport Chamber for Super-AS Stack.

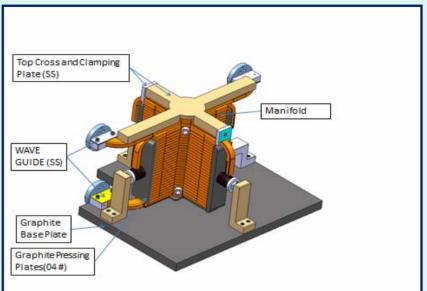


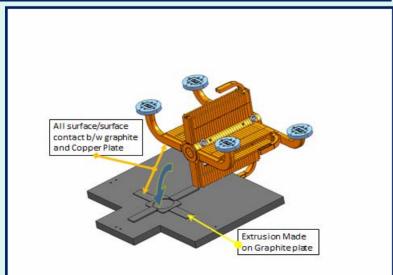


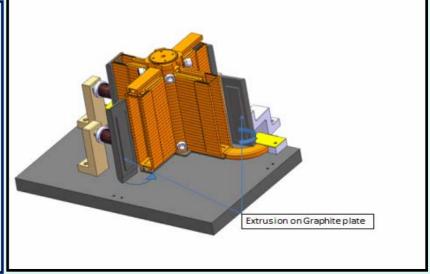


1) Tooling for Brazing of PSI Structure & Manifold.









- 1. Participation in Design, assembly and installation of High frequency CLIC proto-type structure: (from June, 2007 to Nov., 2009.
- 2. Collaboration for Phase 3 &4 of CLIC: (from Aug., 2010 to Dec., 2012).

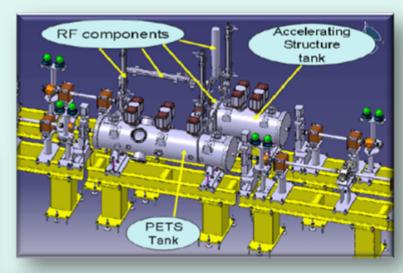
a) TL2-MTV Assy – Optical Monitors for CLIC: Mechanical structures of 4Nos. of Optical Transition Radiation Monitors (OTRM) were manufactured for CTF-3 project of CLIC.

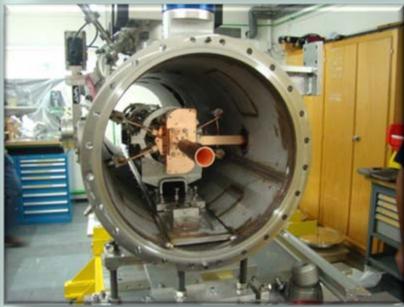




b) 02Nos. of Vacuum Vessels (PETS) for CLIC:

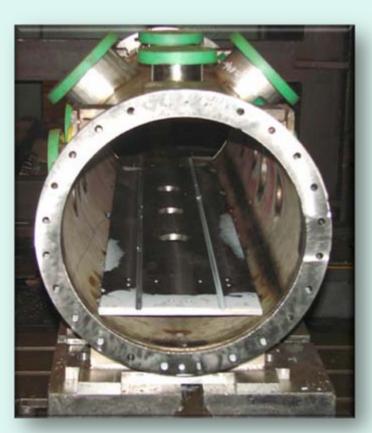






c) 02Nos. of Vacuum Vessels (AS) and Internal support

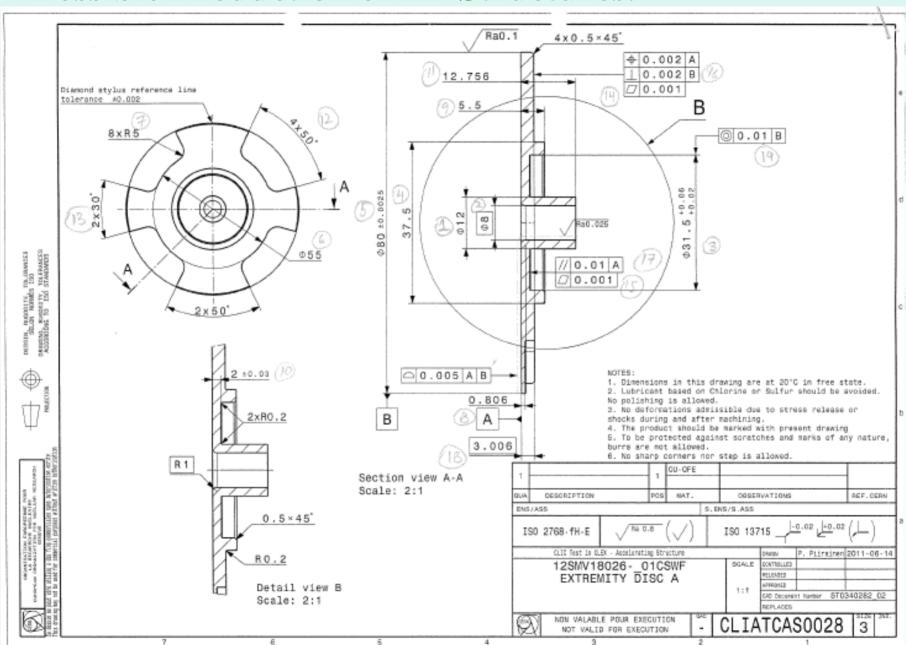
Structures for ACS Tanks for CLIC:





Possible Production of RF Structures.

Possible Production of RF Structures.



Extremity	

COMPANY PART NO PART NO CMM NO Proj Drwg No Date	VAE :	Extremity Disc 01 500323 CERN 27-10-2011	(A1)			
	None	ACT	Dev	иртої	LoTol	OTo l
vim #01						
vian	DIAM DIAZ 12.00	29 FEAT(CR1) MM 00 11.974	-0.026	0.100	-0.100	*- ++++
vim #03 vian	DIAM DIAS	31 FEAT(CR4) MM 00 31.526	0.026	0.060	0.020	+*++
oin #04 oian	DIAM DIAS	32 FEAT(CR5) MM 37.469	-0.031	0.200	-0.200	* ++++
oin #05 oian	DIAM DIA	33 FEAT(CR14) MM 30 80.009	0.009	0.003	-0.003	0.006
oin #06 oian	DIAM DIAS	34 FEAT(CR15) MM 00 54.979	-0.021	0.200	-0.200	* ++++
rim #07 kad	RAD RADS	3 FEAT(CR6) MM 30 5.025	0.025	0.050	-0.050	++*+
tad	RAD RADS	S FEAT(CR8) MM 00 S.032	0.032	0.050	-0.050	++*+
Rad	RAD RADI 5.00	6 FEAT(CR9) MM 00 4.994	-0.006	0.050	-0.050	
tad	RAD RAD	7 FEAT(CR10) MM DO 5.023	0.023	0.050	-0.050	+++
Rad	5.0		-0.001	0.050	-0.050	* ++++
tad	5.0		0.022	0.050	-0.050	+*++
tad	5.0	11 FEAT(CR13) MP 00 4.988	-0.012	0.050	-0.050	* ++++
oin #09 oistb	DISTB DTB	92 FEAT(PL4) FEA 00 5.534	NT(PL5) MM 0.034	0.050	-0.050	+++++
bim #10 bistb	DISTB DTB	93 FEAT(PL4) FEA 00 2.036	NT(PL6) MM 0.036	0.030	-0.030	0.006
dim #11 Distb	DISTB DTB	94 FEAT(PL4) FEA 56 12.774	NT(PL7) MM 0.018	0.100	-0.100	*+++
oim #12 Anglb	ANGLE ASS 50.0	6 FEAT(LM9) FEAT 00 50.007	r(LM8) ANGDEC Page 1			

			Extremi	ty pisc	(AL).txt		
Anglb	ANGLB ABB7 50.00		8) FEAT(LN7 0.243) ANGDE	C		
Dim #1	3						
Anglb	ANGLB ABBS 30.000	FEAT(LN 29	6) FEAT(LN7 .767) ANGDE	C		
Anglb	ANGLB ABB9 50.000		6) FEAT(LM5 .959) ANGDE	C		
Anglb	ANGLB ABB1 50.000	0 FEAT(L 50	N4) FEAT(LN .029	5) ANGE	DEC		
Anglb	ANGLB ABB1 50.000	4 FEAT(L 50	N3) FEAT(LN .182	M) ANGO	XEC		
Anglb	ANGLB ABBI 30.000	2 FEAT(L 29	M2) FEAT(LN .506	ANGO	XEC		
Anglb	ANGLB ABB1 50.000		M9) FEAT(LN .007	iB) ANGE	DEC		
Din #1							
Flat	FLAT FLT1		2) MM 0.033	0.033	0.001		0.032
Dim #1							
Flat	FLAT FLT2		0.007	0.009	0.001		0.006
Din #1) FA(CY2) M		0.000		0.004
Perp			0.086	0.086	0.002		0.084
Dim #1 Parlel	PARLEL PAR4		FA(PL2) PM 0.032	0.032	0.000		0.032
Dim #1	9						
Concen		NS FA(CR	4) FA(CR14) 0.006	0.006	0.000		0.006
Dim #0 Dim #1		.806 0 .006 2	,781-0.788 .982-2.985	(throug	ph micrometer) ph micrometer)		
Inspec	ted By:(Lubna La	tif)		Checked By:	(Shahida Khatoo	n)

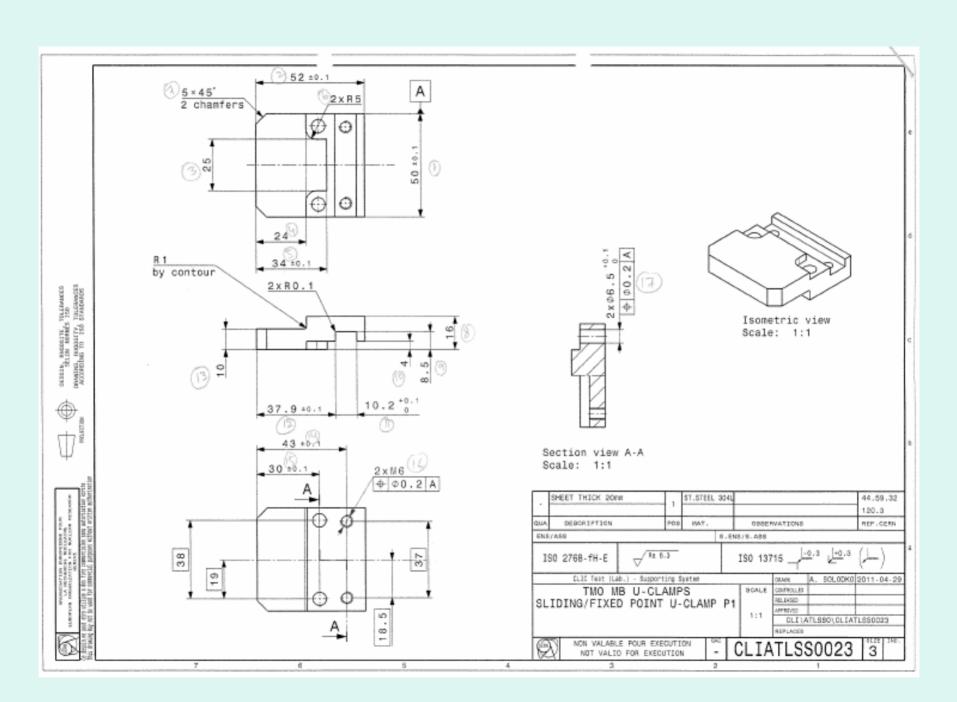


Extremity Disc (Copper).txt COMPANY NAME : 1: PART NAME : Extremity Disc (Copper) PART NO : 01. : 500323 CMM NO Proj : CERN Drwg.No : 27-10-2011 pate ото1 LoTol UpTo Dev More Act ----pin #01 DIAM DIA29 FEAT(CR1) MM -0.100 *---|++++ -0.0790.10012.000 brian 11.921 pin #02 DIAM DIA30 FEAT(CR3) MM -0.100 ----|*+++ 0.1000.0198.000 8.019 priam Dim #03 DIAM DIA31 FEAT(CR4) MH 0.020 0.0160.0600.076 31,500 31.576 piam Dim #04 DIAM DIA32 FEAT(CRS) MN --*-|++++ -0.20037.435 -0.0650.200 37.500 Diam Dim #05 DIAM DIA33 FEAT(CR14) MM -0.015-0.003 0.003 79.982 -0.01880,000 Driam Dim #06 DIAM DIA34 FEAT(CR15) MM --*- ++++ -0.200-0.0780.200 55.000 54.922 Diam Din #07 RAD RAD3 FEAT(CR6) HM -------0.050 -0.0500.048 5.000 5.048 Rad RAD RAD4 FEAT(CR7) MM -0.050----|+++++ 0.030 0.050 5.000 5.030 Rad RAD RADS FEAT(CR8) MM -0.050----|+*++ 0.050 0.022 5.000 5.022 Rad RAD RAD6 FEAT(CR9) MM -0.050-----5.039 0.039 0.050 5.000 Rad RAD RAD7 FEAT(CR10) MM -------0.050 0.033 0.050 5.000 5.033 Rad RAD RADS FEAT(CR11) HM ---- ++*+ -0.050 0.037 0.050 5.000 5.037 Rad RAD RADIO FEAT(CR12) HM -0.050---- +*++ 0.050 0.018Rad 5.000 5.018 RAD RAD11 FEAT(CR13) HM 0.050 -0.0500.028 5.028 Rad 5.000 Dim #09 DISTB DTB92 FEAT(PL4) FEAT(PL5) MM -0.0500.050 0.034 5.500 5.534 Distb Dim #10 DISTB DTB93 FEAT(PL4) FEAT(PL6) MM 0.0060.030 -0.0302.036 0.036 Distb 2.000

Page 1

Extremity Disc (Copper).txt	
DISTE DISTE DIESS FEAT(PLS) FEAT(PLS) MM	
Distb 12.756 12.774 0.018 0.100 -0.100 *+++	
Dim #12	
ANGLE ABB6 FEAT(LM9) FEAT(LM8) ANGDEC Anglb 50.000 50.125	
ANGLE ABB7 FEAT(LN8) FEAT(LN7) ANGDEC Anglb 50.000 49.959	
Din #13	
ANGLE ABBE FEAT(LN6) FEAT(LN7) ANGDEC Anglb 30.000 29.897	
ANGLB ABB9 FEAT(LM6) FEAT(LM5) ANGDEC Anglb 50.000 50.135	
ANGLE ABBIO FEAT(LN4) FEAT(LN5) ANGDEC Anglb 50.000 50.275	
ANGLE ABB14 FEAT(LN3) FEAT(LN4) ANGDEC Anglb 50.000 50.118	
ANGLE ABEL FEAT(LN2) FEAT(LN3) ANGDEC Anglb 30.000 29.723	
ANGLE ABELS FEAT(LN9) FEAT(LN8) ANGDEC Anglb 50.000 50.125	
Din #14	
Flat FLT1 FEAT(PL2) MM 0.031 0.001 0.030)
Din #15	
Flat FLT2 FEAT(PL6) MM 0.003 0.001 0.002	1
Dim #16 PERP PER10 FA(PL2) FA(CY2) MM	
Perp 0.109 0.109 0.002 0.107	
Dim #17 PARLEL PAR2 FA(PL6) FA(PL4) MM	
Parlel 0.029 0.029 0.001 0.028	ŝ
Din #19	
CONCEN CNNS FA(CR4) FA(CR14) MM Concen 0.007 0.007 0.000 0.007	r
Dim #08: 0.806 0.810-0.816(through Micrometer) Dim #18: 3.006 2.999-3.001(through Micrometer)	
Inspected By: (Lubna Latif) Checked By: (Shahida Khatoon)	

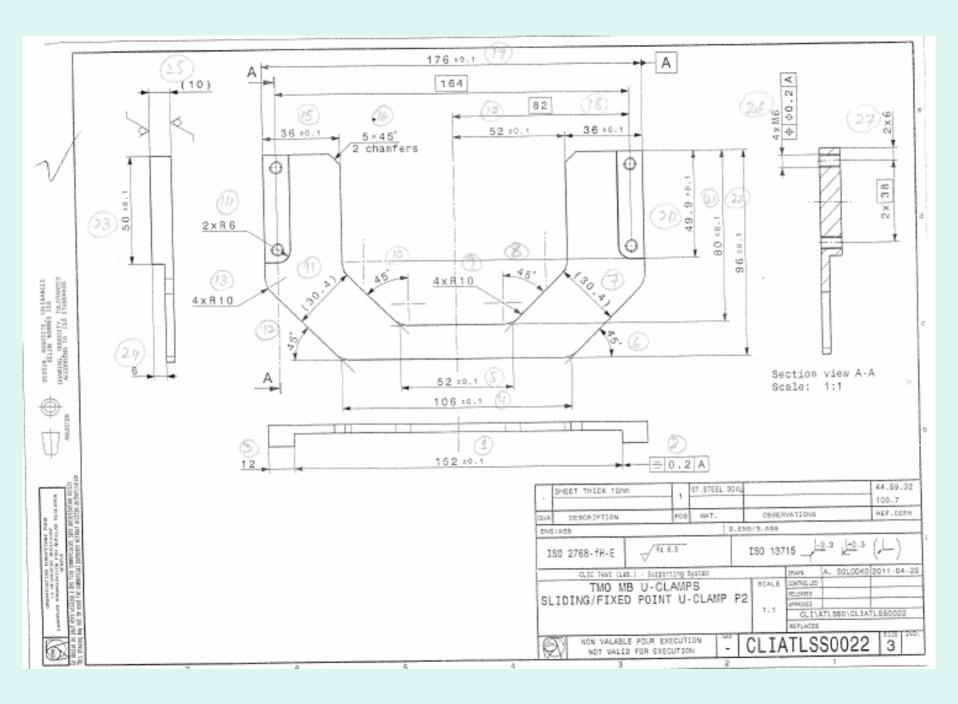




			sliding Fixed.	18ep		
COMPANY PART NAM PART NO CMM NO Proj Drwg.No Date	E : 51 : 01 : 50 : CE	0323	Point U-Clamp			
	NOW	Act	Dev	UpTol	LoTo1	ото1
Dim # 01 DI Distb	STB DTB98 50.000	FEAT(LNS) FE/ 50.003	AT(LN3) HM 0.003	0.100	-0.100	*+++
Dim # 02 DI Distb	STB DTB99 52.000	FEAT (LN1) FE/ 52.000	AT(LN4) HM -0.000	0.100	-0.100	* ++++
Distb	STB DTB100 25.000	FEAT(LMB) FE 25.013	EAT(LN10) MM 0.013	0.100	-0.100	*+++
Distb	STB DTB101 24.000	FEAT(LN18) 24.015	FEAT(LN1) MM 0.015	0.100	-0.100	*+++
Distb	STB DTB102 34.000	FEAT(LN9) FE 34.003	EAT(LH1) MM 0.003	0.100	-0.100	+++
Rad	5.000	FEAT(CR1) MM 5.006	0.006	0.050	-0.050	
Rad	RAD RAD13 5.000	FEAT(CR2) MM 5.000	-0.000	0.050	-0.050	* ++++
Dim # 07 Distb	STB DTB103 5.000	FEAT(PT2) FF 5.005	EAT (PT3) MM 0.005	0.050	-0.050	#+++
Distb	STB DTB104 5.000	FEAT(PT4) FI 4.998	EAT(PTS) MM -0.002	0.050	-0.050	* ++++
Anglb	GLB A8816 45.000	FEAT(LN5) FE/ 44.949	AT(LN6) ANGDEC -0.051	1.000	-1.000	
Ang1b AN	GLB A8817 45.000	FEAT(LN1) FE 45.005	AT(LN2) ANGDEC 0.005	1.000	-1.000	+++
Din # 08 DI Distb	STB DT8105 16.000	FEAT(PL1) F 15.992	EAT(PL6) MM -0.008	0.100	-0.100	* ++++
Din # 09 DI Distb	STB DTB106 8.500	FEAT(PL1) F 8.481	EAT(PLS) MM -0.019	0.100	-0.100	* ++++
Din # 10 Distb	5TB DTB109 4.000	FEAT(PL1) F	EAT(PL4). MM -0.024	0.050	-0.050	
Dim # 11 Distb	STB DTB110 10.200	FEAT(LM12) 10.189	FEAT(LN14) MM -0.011	0.100	-0.100	* ++++
Dim # 12		. Compression	Page 1			

DISTB DTB123 FEAT(LN1) FEA	Hiding Fixed.: NT(LM21) MM 0.007		-0.100	*+++
Dim # 13 DISTB DTB113 FEAT(PL1) FEA Distb 10.000 9.934		0.100	-0.100	
Dist # 14 DISTB DTB114 FEAT(LN1) FEA Distb 43.000 42.997	T(LN22) MM -0.003	0.100	-0.100	
Distb 01STB DTB116 FEAT(LN24) FE Distb 30.000 30.007	0.007	0.100	-0.100	*+++
Dim # 16 2D P2D2 FA(CR3),RFS MN 0.015	0.015	0.200		*+++
Dim # 17 2D P2D3 FA(CR5),RFS MM Tpos2d 0.015	0.015	0.200		++++
Inspected By: (Lubna Latif)	. Che	cked By:	(Shahida Kh	atoon)





		sliding U-Cla	mp.lRep		
PART NO CMM NO Proj Drwg.No Date	: Sliding/Fix : 01 : 500323 : CERN : 01-11-2011	ed Point U-Cla	пр		
Non	Act	Dev	ирто1	LoTol	σто1
Dim #01) FEAT(PL19) MM			
Distb 152.		12 -0.088	0.100	-0.100	* +++
Dim #02 SYM SYM Sym	1 FA(PT2) FA(0.0	PT3) MM 04 0.004	0.200		*++
Dim #03 DISTB DT Distb 12.0	8100 FEAT(PL1 000 12.0	6) FEAT(PL4) MM 05 0.005	0.100	-0.100	*+++
Din #04 DISTB DT Distb 106.	8101 FEAT(LN7 000 105.9) FEAT(LN8) MM 89 -0.011	0.100	-0.100	* ++++
Dim #05 DISTB DT Distb 52.0	8102 FEATCLN9 000 \$2.0) FEAT(LN10) MM 02 0.002	0.100	-0.100	*+++
Anglis As Anglis As		FEAT(PL7) ANGD 26	EC		
Dim #07 Distb Distb 30.		1) FEAT(PL7) MM 07 0.007	0.100	-0.100	*+++
Dim #08 ANGLB AB Anglb 45.0) FEAT(PL12) AN	GDEC		
	D12 FEAT(CR5)		0.100	-0.100	*+++
	D13 FEAT(CR6) 000 10.0		0.100	-0.100	
	D14 FEAT(CR7) 000 10.0		0.100	-0.100	+*++
	D15 FEAT(CR8) 000 10.0		0.100	-0.100	+++*
Dim ∉10 ANGLB AB Anglb 45.	818 FEAT(PL13) FEAT(PL12) AN	GDEC		
Distb 30.	B104 FEAT(PL1 400 30.4	3) FEAT(PL5) MM 02 0.002	0.100	-0.100	*+++
	819 FEAT(PL5) 000 45.02	FEAT(PL6) ANGD 4	EC		
		Page 1	Ĭ.		

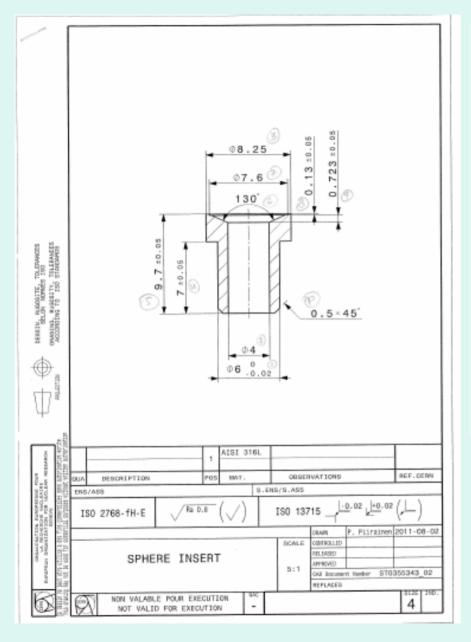
ep		
0.100	-0.100	
0.100	-0.100	+4++
0.100	-0.100	
0.100	-0.100	*+++
0.100	-0.100	
0.100	-0.100	++++
0.100	-0.100	
0.050	-0.050	*+++
0.050	-0.050	++++++++++++++++++++++++++++++++++
0.100	-0.100	
0.100	-0.100	
0.100	-0.100	-* +++
0.100	-0.100	+*++
0.100	-0.100	+++
0.100	-0.100	*- ++++
0.100	-0.100	* +++
0.100	-0.100	[+*+4
	0.100 0.100 0.100 0.100 0.100 0.100 0.100 0.050 0.050 0.100 0.100 0.100 0.100 0.100 0.100 0.100	0.100 -0.100 0.100 -0.100 0.100 -0.100 0.100 -0.100 0.100 -0.100 0.100 -0.100 0.100 -0.050 0.050 -0.050 0.100 -0.100 0.100 -0.100 0.100 -0.100 0.100 -0.100 0.100 -0.100 0.100 -0.100 0.100 -0.100

Dim #26 Tpos2d	2D P2D1 FA(C	R13),RFS MM 0.061	0.061	0.200		[+^+
Dim #27					Marie Control	
Distb	ISTB DTB1 FEA 6.000	T(PL3) FEAT: 5.990	-0.010	0.050	-0.050	*
DT	STB DTB2 FEAT	CPL 33 FEATO	28.1.30 HH			
Distb	6.000	6.030	0.030	0.050	-0.050	

Inspected By: (Lubna Latif)

Checked By: (Shahida Khatoon)





Sphere Insert.txt

COMPANY NAME	1 1
PART NAME	: Sphere Insert
PART NO	: 01
CMM NO	: 500323
Proj	: CERN
Drwg.No	:
Date	: 28-10-2011

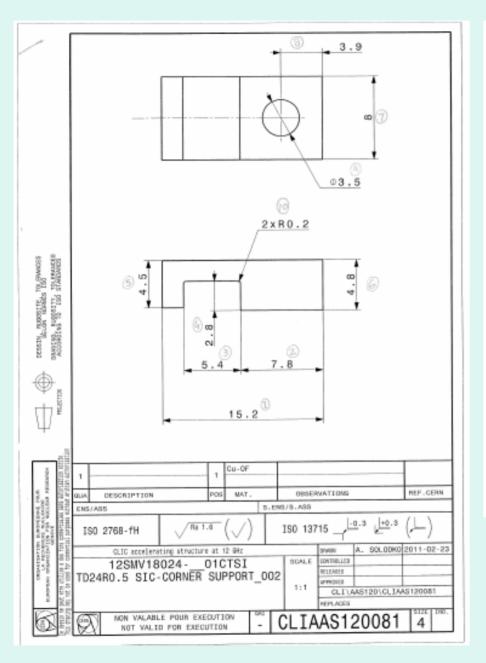
Dace	No		ACE	Dev	UpTol	L ото1	ото1
Dim #01 Diam		IA16	FEAT(CY1) MM 4.025	0.025	0.050	-0.050	++*+
Dim #02 Diam		EA17	FEAT(CY2) MM 6.008	0.008	0.020	0.000	
Dim #03 Dian		TA18 1.250	FEAT(CR8) MM 8.276	0.026	0.100	-0.100	+*++
pin #04 pistb	DISTB ₇	DT832	FEAT(PT15) 7.015	FEAT(PT16) MM 0.015	0.050	-0.050	+*++
pim #05 pistb		DTB33	FEAT(PT16) 9.720	FEAT(PL1) MM 0.020	0.050	-0.050	+*++

Dim #06 Can't Measured Dim #07 Can't Measured Dim #08 Can't Measured Dim #09 Can't Measured Dim #10 Can't Measured

Inspected By: (Lubna Latif)

Checked By: (Shahida Khatoon)



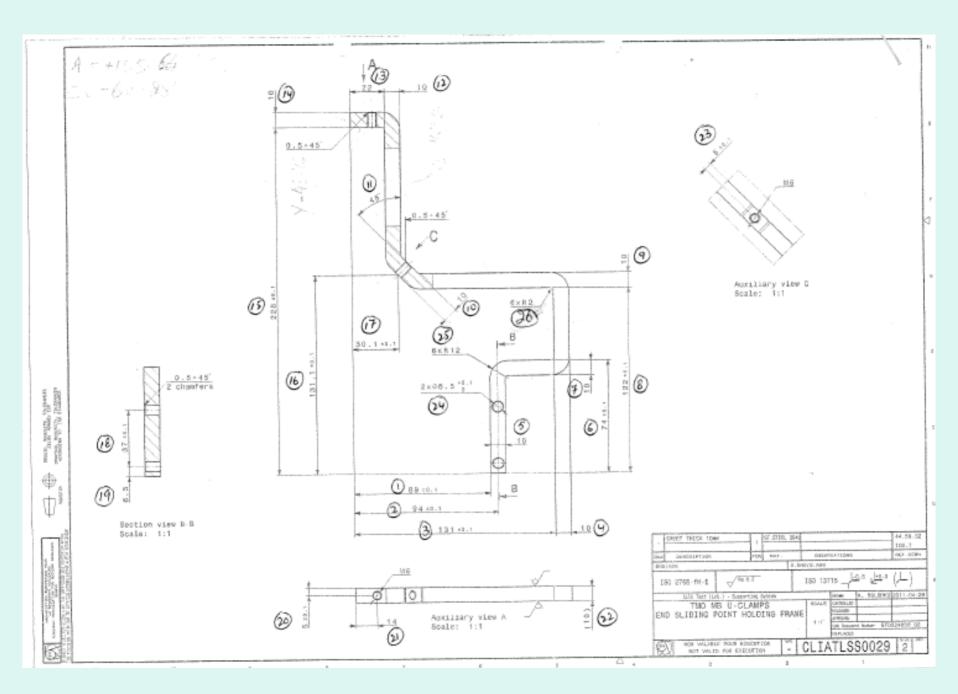


<u> </u>		Co	rner Suppo	rt.1Rep		
COMPANY NA PART NAME PART NO CMM ND Proj Date	: Co : 01 : 50	0323				
	Non	Act	Dev	UpTol	LoTol	OTol
	B DTB82 15.200	FEAT(PL4) FEAT 15.196		0.100	-0.100	* ++++
Dim #02 DIST Distb	в DTB83 7.800	FEAT(PL4) FEAT 7.784	(PL6) MM -0.016	0.100	-0.100	* ++++
Dim #03 DIST Distb		FEAT(PL8) FEAT 5.376	(PL6) MM -0.024	0.050	-0.050	*- ++++
Dim #04 DIST Distb	и рти85 2.800	FEAT(PL5) FEAT 2.796		0.050	-0.050	* ++++
Dim #05 DIST Distb	в ртп86 4.500	FEAT(PL9) FEAT 4.525	(PL3) MH 0.025	0.050	-0.050	+*++
Dim #06 DIST Distb	B DTB87 4.800	FEAT(PLS) FEAT 4.828	(PL3) MM 0.028	0.050	-0.050	++*+
pim #07 DIST Distb	8.000	FEAT(PL1) FEAT 8.094	(PL2) MM 0.094	0.100	-0.100	+++*
oim #08 DIST Distb	8 DT889 3.900	FEAT(PL4) FEAT(3.931	(CR1) MM 0.031	0.050	-0.050	++++
oin #09 DIA oiam	M DIA1 F	EAT(CY1) MM 3.519	0.019	0.050	-0.050	+++
oim ∉10 Can	't Measu	red				
Inspected B	v:	Calorin		thecked By:	Jan J	

(Lubna Latif)

(Shahida Khatoon)





Workplace: 199 / TMO MB U-CLAMPS END SLIDING POINT HOLDING FRAME	
Job Title: Hoteling Frame Control No: Sample Dwg No: CLIATLSS0029 Temperature: 20°C	
Equipment : CMM other wise mentioned	
Inspected by: Salman Khan and Saleem Ahmed	
olement no.nut. PP ninge name	
no. characteristic work length (1869)	
nominal value (oi. upper tot. lower tot. actual value deviation Tolerance utilis	atsom
1	
1 Vectorial position [4]	
1 X .89.000 D.000 -0.100 X -89.007 X -0.007 85%	*
2	
2/Vectorial position [X]	
1 X -94.000 0.100 -0.100 X -93.996 X 0.005 6%	-
3	
3 Vectorial position [X]	
1 X -131,000 0.100 -0.100 X -130,966 X 0.005 5%	
4	
4 Distance plane - plane [P3] 1 r 10,000 0.100 -0.100 r 9.960 r -0.037 -37%*-	
t r 10.000 0.100 -0.100 r 9.960 r -0.037 -37%*-	
S Distance plane - plane [10]	
1 r 10,000 0,100 -0,100 r 8,973 r -0,027 -27%	
6	
6 Vectorial position [Y]	
1 Y 74.000 0.100 -0.100 Y 73.052 Y -0.048 -48%*-	
7	
7 Distance plane - plane (R)	
1 r 10.000 0.100 -0.100 r 9.239 r -0.061 -81%	
B about out on the BB	
8 Visctorial position (Y) 1 Y 122,000 0.100 -0.100 Y 122,003 Y 0.003 3%	4
9	
†Distance plane - plane [R]	
1 r 10,000 0.100 -0.100 r 9.959 r -0.941 -41%*	
10	
10 Distance plane - plane [R]	
1 r 10.000 0.100 -0.100 r 9.980 r -0.020 -20%*	
11	
11 Angle plane - plane 1 457000 0 013000 -013000 4416319.1 -010640.9 -22%	
1 45°00'0.0 0°30'0.0 -0°30'0.0 44°63'19.1 -0°00'40.9 -22%^-	
12 Distance plane - plane [R]	
1 r 10.000 0.100 +0.100 r 9.960 r -0.002 -32%	
13	
13(Distance point - plane (RI)	
	,
14	
14 Distance plane - plane [R]	
1 r 10.000 0.100 -0.100 r 9.956 r -0.044 -44%*	,
15	
15/Vectorial position [1] 1 V 228,000 0.100 -0.100 Y 227.997 Y -0.003 -3%*	
1 Y 228.000 0.100 -0.100 Y 227.997 Y -0.003 -3%	
16[Vectorial position [1]]	
.1 Y 131.100 0.100 -0.100 Y 131.072 Y -0.028 -28%	,
17	
17 Vectorial position [X]	
1 X -30.100 0.100 -0.100 X -30.078 X 0.022 22%	, a Transaction
18	

stoment.	no. ref.	pp	range		пати			
no. characteristic	work	k. length			name			
nominal value (of. up	per tol. Fow	er toil.	actual	Volue	dewate	00	Tolerano	e utilisation
18 Distance point - point fr	1							
1 Y 37.000	D. 100	-0.100	Y	36.996	Y	-0.004	-4%	
19								
19 Vectorial position [Y]								
1 Y 6.500	0.100	-0.100	Y	6.451	Y	-0.019	-19%	
20								
20 Vectorial position [Z]								
1 2 -5.000	0.100	-0.100	Z	-5.055	2	-0.065	-65%	, Pare,
21								
21 Vectorial position [X]								
1 X -14.000	0.100	-0.100	×	-14.014	×	-0.014	-14%	
22								
22 Distance plane - plane (R)							
1 r 10.000	0.100	-0.100	- 1	9.951	r	-0.049	-49%	
23								
23 Vectorial position (Z)								
1 Z -5.000	0.100	-0.100	Z	-4.997	- 2	0.003	3%	
-4								
24 Diameter								
1 D 6.500	0.100	0.000	D	6.552		0.052	4%	
25/Diameter								
1 D 6.500	0.100	0.000	D	6.533	S.	0.033	-34%	
25 Radius								
R12		Qualify the	ough l	Radius (Sauge			
25 Radius								
H2		Qualify thro	ugh R	adius Or	ouge			



