



Faculty of Physics
University of Rijeka

The MUonE detector at CERN

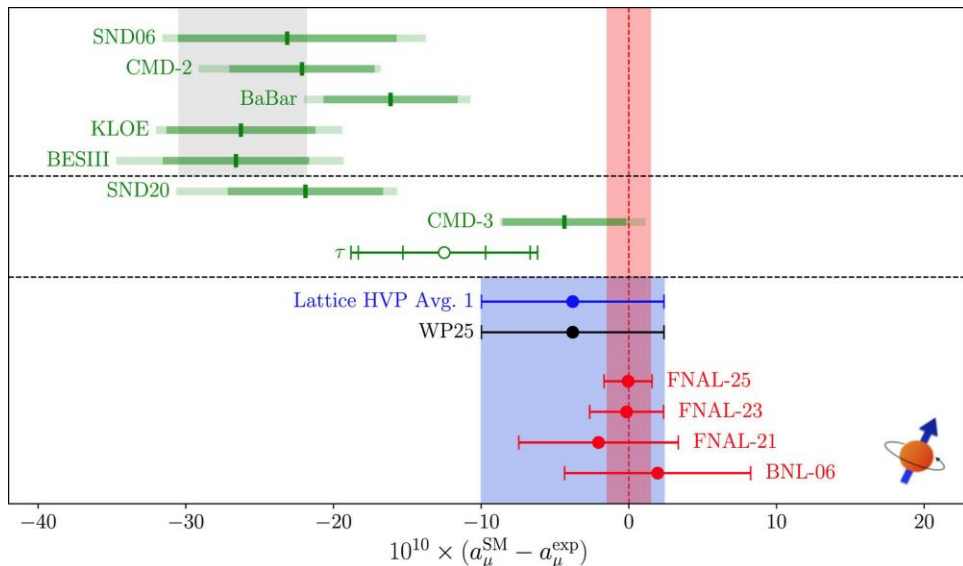
Aldo Arena

On behalf of the MUonE Collaboration

14th Beam Telescopes and Test Beams Workshop, Mainz, Germany.

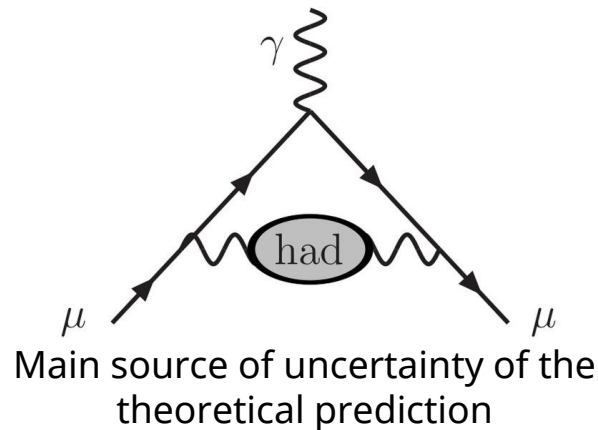


Muon g-2: current status



<https://www.sciencedirect.com/science/article/pii/S0370157325002157>

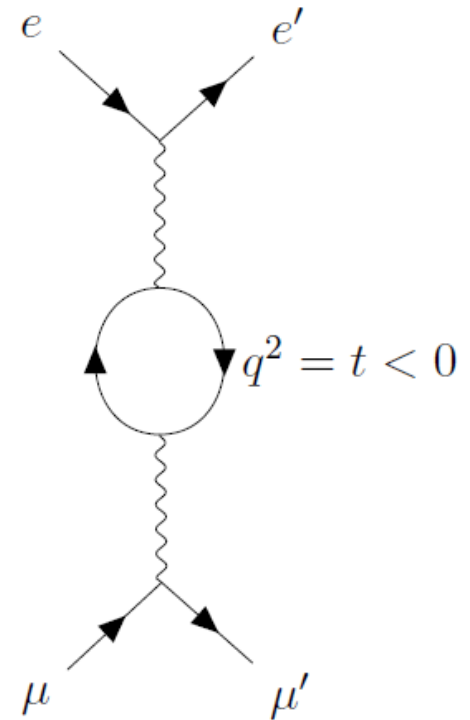
Tensions in the evaluation of $a_\mu^{\text{HVP,LO}}$ using lattice QCD (WP2025) or e^+e^- hadronic cross sections



A clarification of the theoretical prediction is needed

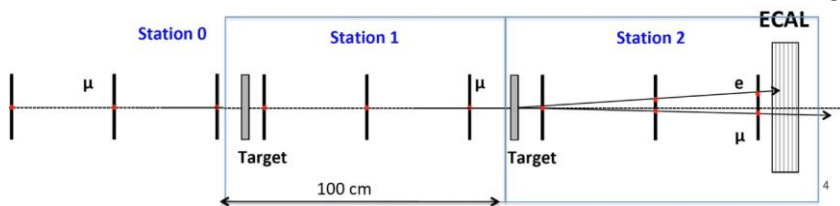
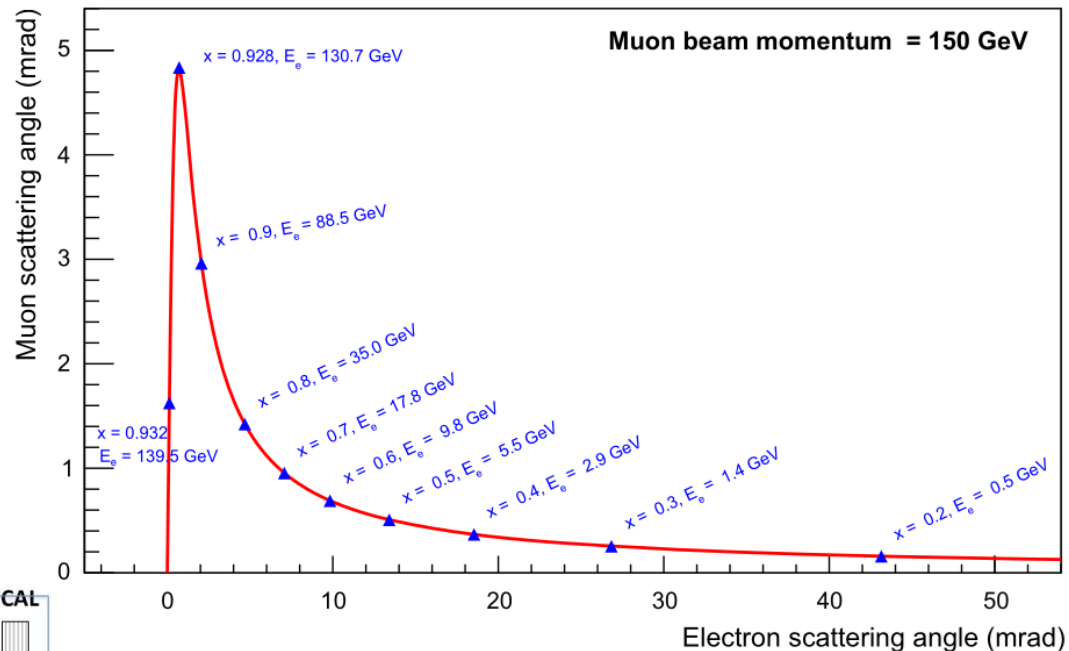
MUonE

- Experiment proposed at CERN
- Phase-1 pilot run carried out on M2 beamline, summer 2025
 - ~160 GeV muon beam scattered on fixed target
- Direct independent determination of the hadronic contribution to the muon $g-2$ anomaly
- Measurement of the angular distribution from μ - e elastic scattering
- Aims at a precision of ~0.5%
 - ~3 years of data taking (integrated luminosity $\sim 1.5 \times 10^4 \text{ pb}^{-1}$)



MUonE experiment

- Elastic curve (leading order)
- Scattering angles of the leptons:
 - $0 < \theta_\mu < 5$ mrad
 - $0 < \theta_e \lesssim 32$ mrad



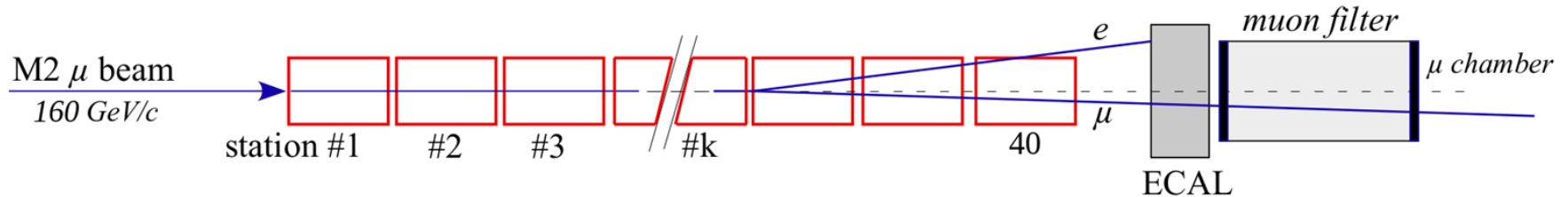
Abbiendi et al, Eur. Phys. J. C 77.3 (2017), 139

Considerations and requirements

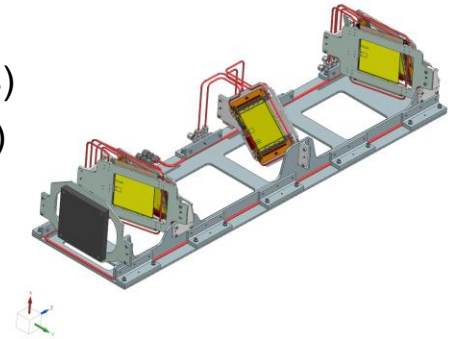
In order to control the systematic errors:

- Extreme precision in the alignment and detector stability
- Uniform efficiency over the full range of angles
- Background discrimination, e.g. pair production events, by direct measurement and simulations
- Precise measurement of the beam energy (few MeV)
- Angular resolution
- Study of Multiple Scattering effects

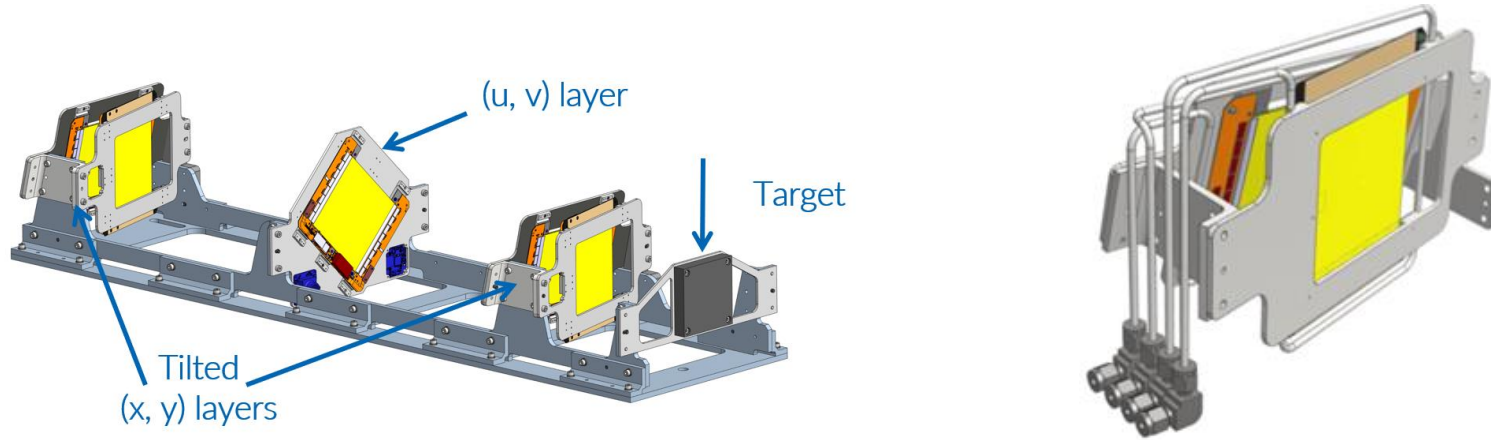
MUonE: Setup



- Tracking station: 6 planes of silicon microstrip sensors (CMS 2S Modules)
- Modules arranged in perpendicularly oriented pairs (X and Y coordinates)
- Middle pair rotated by 45° to resolve ambiguity (U and V)
- Be or C 1.5–2 cm target
- Final version: 40 tracking stations
- EM calorimeter and muon filter for particle identification and track validation



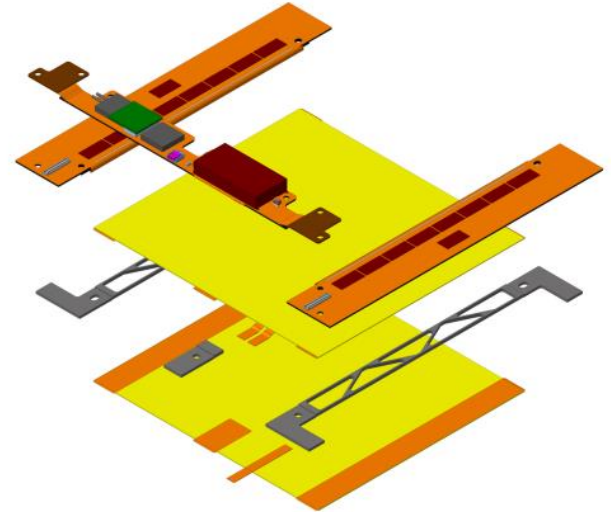
Tracking Station



- (x, y) layers tilted by 233 mrad: improved hit resolution, charge sharing increased
- Modular layout: each station is an independent detector
- Frames made from Invar (iron/nickel alloy): CTE ~ 1.2 ppm/K, stability < 10 μm
- Stepper motors for alignment; laser holographic system monitors stability

2S Modules

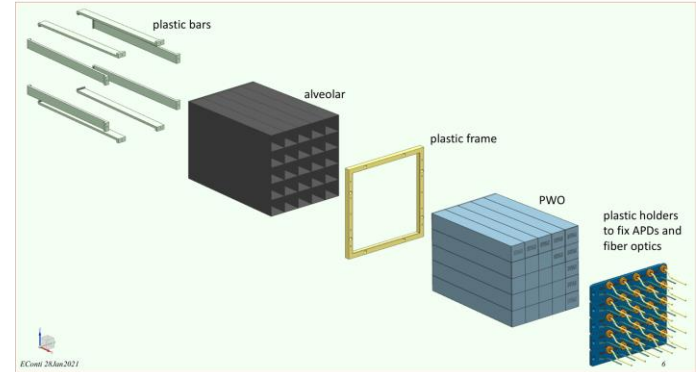
- Silicon strip sensors developed for CMS Phase-2 (HL-LHC) Outer Tracker - [CMS-TDR-014.pdf](#)
- Two close-by strip sensors reading the same coordinate, read out by CBC3.1 ASICs
- Correlations between sensors → "stubs" read out at 40 MHz
- Active area $\sim 10 \times 10 \text{ cm}^2$; 90 μm strip pitch, 4064 channels per module
- Binary readout → resolution $\sim 26 \mu\text{m}$
- All MUonE tracking systems (TK, BMS, μFilter) use the same technology



[CMS Tracker TDR](#)

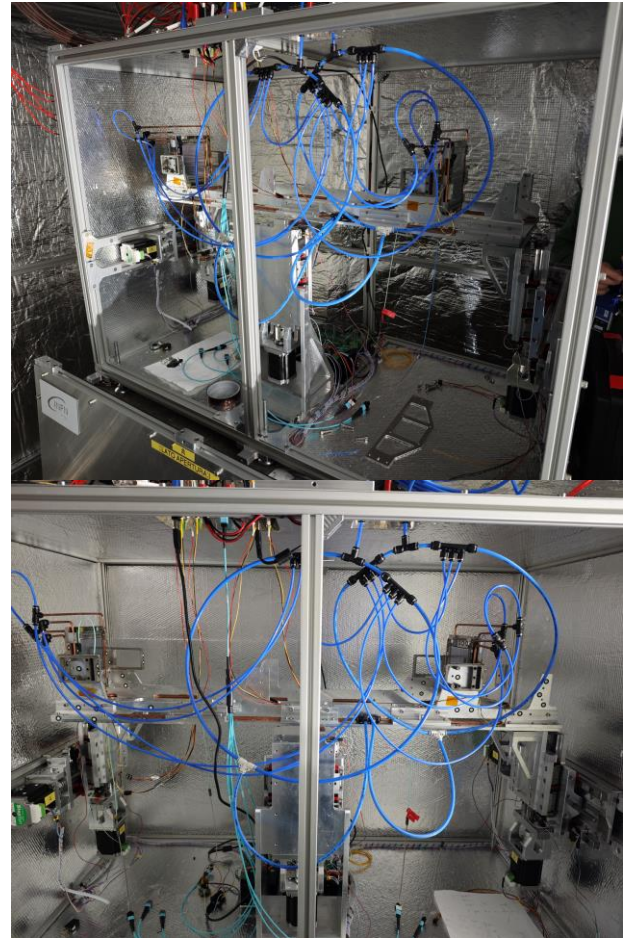
Electromagnetic Calorimeter

- Prototype used in MUonE Phase-1 2025
- 25 lead tungstate crystals (PbWO_4) from CMS ECAL endcap
 - Area: $2.85 \times 2.85 \text{ cm}^2$; Length: 22 cm ($\sim 25 X_0$)
- APDs coupled to the crystals; MGPA preamplifier ASICs + 16-bit ADCs
- Transmission to DAQ via FC7 at full 40 MHz rate
- Covers $\sim 14 \times 14 \text{ cm}^2$
- Independent measurement of electron energies (1–150 GeV)
- Compare energy against track angle to filter radiative background
- Also useful for an independent direct measurement of $\Delta\alpha_{\text{had}}$



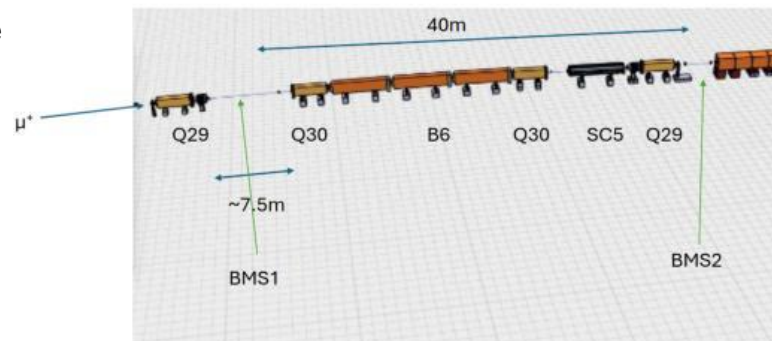
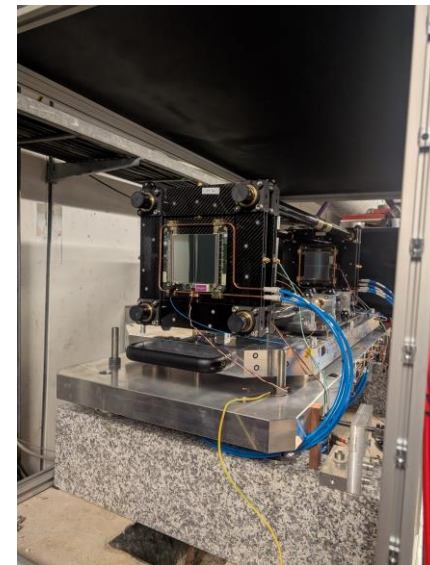
Muon Filter

- Track muons after the ECAL, where electrons have been absorbed
- Improve PID by connecting tracks before and after the ECAL
- Both ECAL and μ Filter help disambiguate muon vs electron in the region $\theta < 5$ mrad
- μ identification also filters beam contamination (e.g. pions, pile-up muons)
- Study of Multiple Scattering effects on muon track tagging
- Phase-1 (2025): four 2S modules (2 X-Y non-tilted planes)
- Final detector: 2S Modules or Scintillating Fibers (R&D ongoing)



Beam Momentum Spectrometer

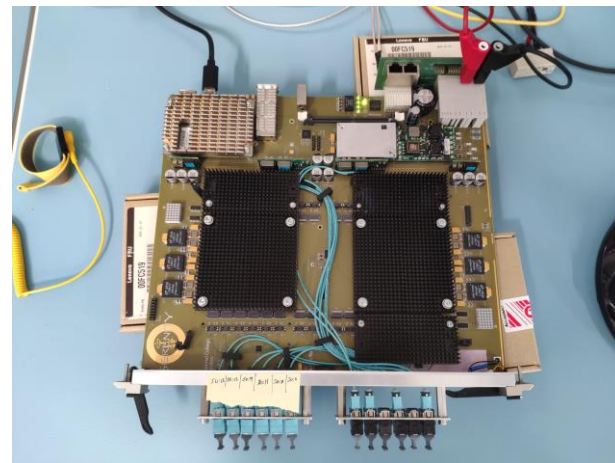
- Improves measurement of incoming beam momentum event by event
 - M2 beamline $\sigma(p)/p$: 3.75% \rightarrow aim to measure better than 0.5%
- Replaces previous scintillator-based COMPASS BMS
- Two locations (before/after M2 16 T·m bending magnets, ~30 m apart)
 - 4 2S modules at each location (2 X-Y pairs, non-tilted)
- Modular mechanical design using carbon-fibre composite
 - Sliding CF plate for fine-tuning to few μm , CTE stability
 - Prototypes an alternative station design for Phase 2
- First integrated in August 2025 – preliminary analysis underway



MUonE DAQ

<https://serenity.web.cern.ch/serenity/>

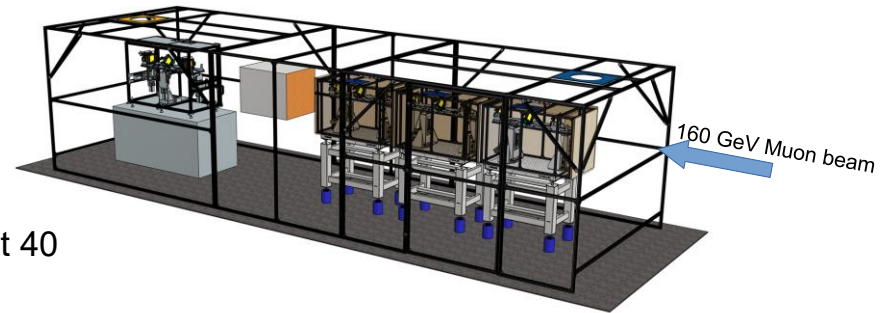
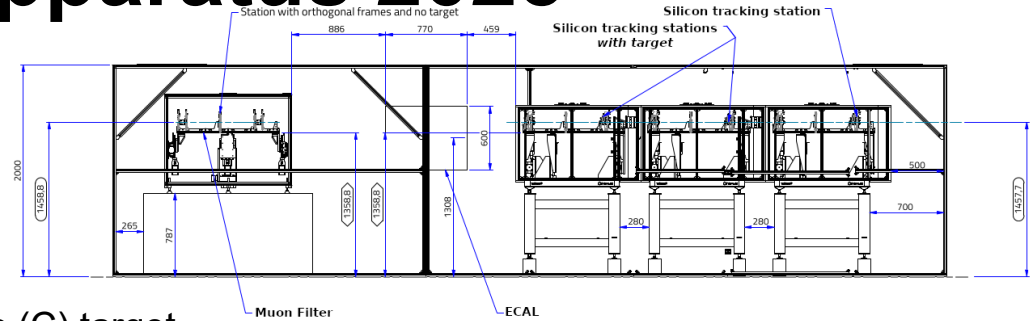
- FPGA-based readout, triggerless architecture at 40 MHz clock cycles
 - Serenity ATCA platform (CMS Phase-2): Z1 with 2× KU15P FPGAs; new S1 with VU13P - <https://serenity.web.cern.ch/serenity/>
- DAQ firmware split over 2 FPGAs:
 - FPGA 1: decoding, per-station aggregation, event selection using module occupancy topologies at 40 MHz
 - FPGA 2: AXI-Stream event building, collecting fragments from all subdetectors, ethernet interface
- Online event selection: 40 MHz → ~500 kHz averaged (1.5 MHz in-spill), >99% efficiency
 - First successful demonstration for the entire 2025 run
- Online decoding provides analysis-ready NTuples in real time (Kubernetes-based, fault tolerant)



MUonE Phase-1 Apparatus 2025

Mini MUonE experimental setup:

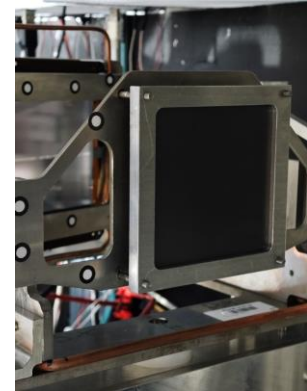
- 1st station without target
- 2nd and 3rd stations with 2 cm graphite (C) target
- ECAL
- MuonID station with 4 tracking planes (XY-XY)
- Timing detector (scintillator tiles + PMTs)
- Upstream: 2 BMS stations between bending magnets
- All detector systems integrated into unified DAQ at 40 MHz
- Two months of data taking (May–August 2025)
- Proof-of-principle $\Delta\alpha_{\text{lep}}$ measurement; aiming at $\sim 20\% \Delta\alpha_{\text{had}}$



MUonE Phase-1 Apparatus 2025

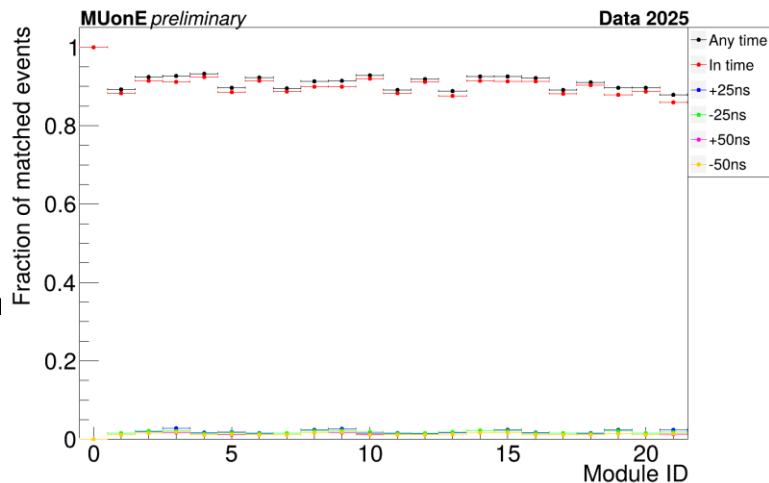
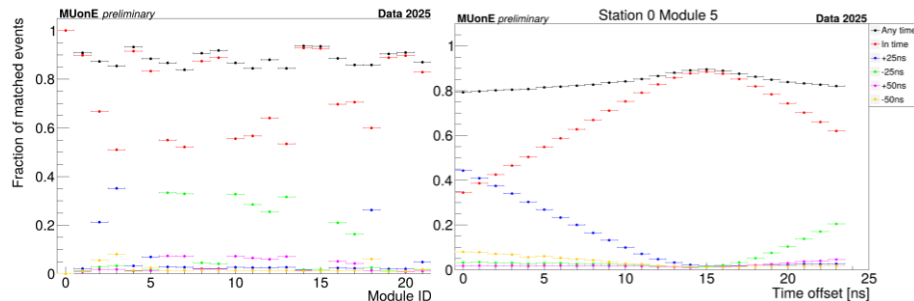


MUonE detectors during installation and after (inside the tent)



Phase-1: Detector Commissioning

- Multiple detectors distributed over ~80 m
 - System synchronisation to ~1 ns is a key challenge
 - Muons are asynchronous w.r.t. sampling clock
- Coarse delay scan: align all modules to within 25 ns
 - Using a reference module, find delay that maximises correlations
- Fine delay scans at CBC: align each module to < 1 ns
 - On-chip DLL scan of sampling clock offset
- Same technique for ECAL, using tracker as a reference
- System successfully synchronised for the entire 2025 run



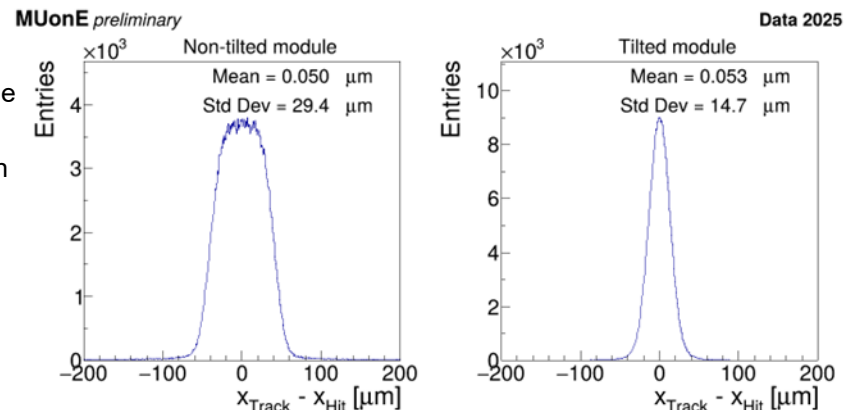
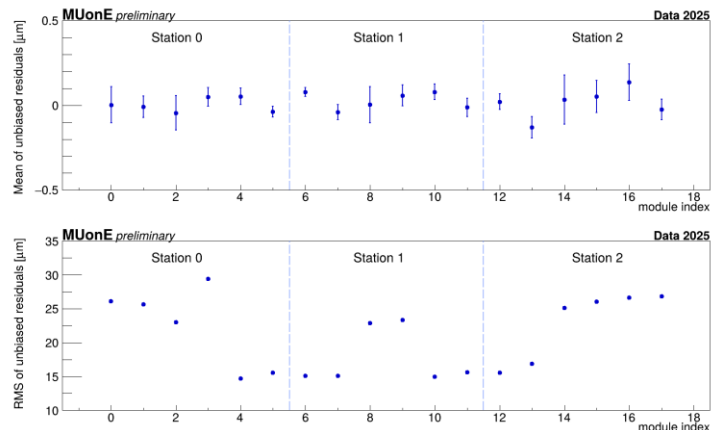
Tracker Alignment

Hardware, using stepper motors:

- 1) Centre each 2S module to the beam $< 500 \mu\text{m}$
- 2) Align the longitudinal axis of each station to the beam axis $< 0.5 \text{ mrad}$
- 3) Align the 3 stations relative to each other $< 200 \mu\text{m}$

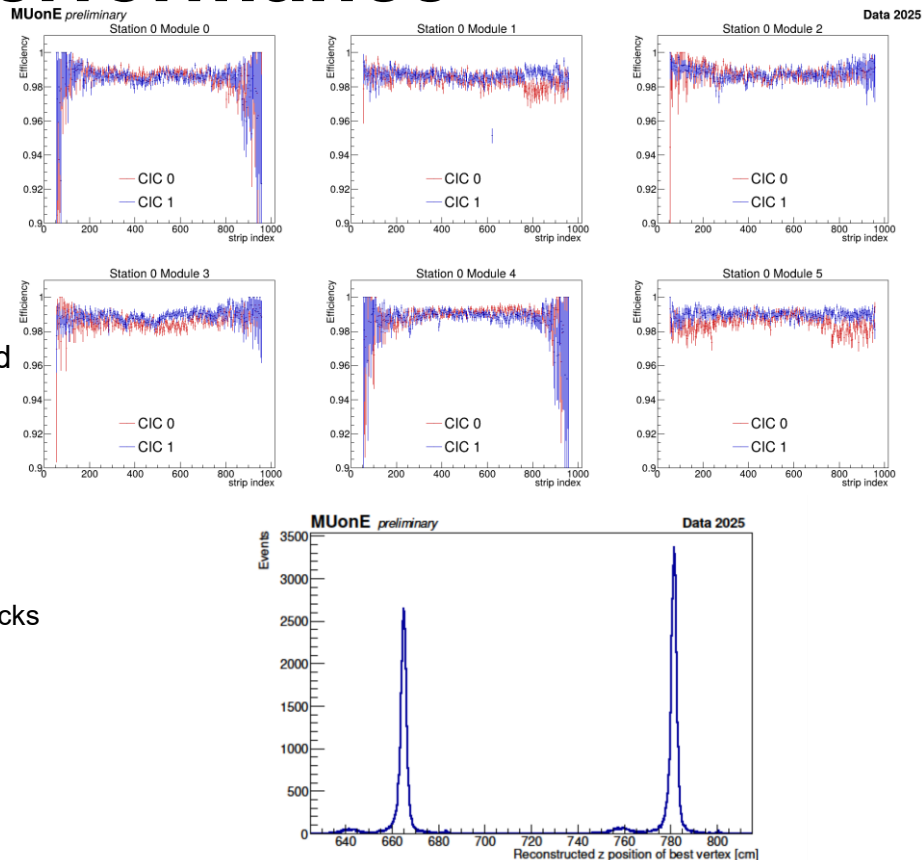
Software:

- Local χ^2 minimisation on clean single passing muon events (1 stub/module = 18 stubs/event)
- 3D scanner photogrammetry + laser survey: position + orientation of each module with $\sim 100 \mu\text{m}$ precision
- Survey results used as starting point for software alignment
- Residuals (track – stub) centred $< 0.05 \mu\text{m}$



Phase-1: Tracking Performance

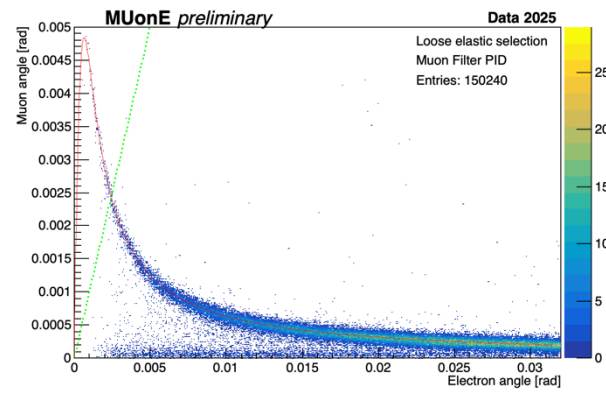
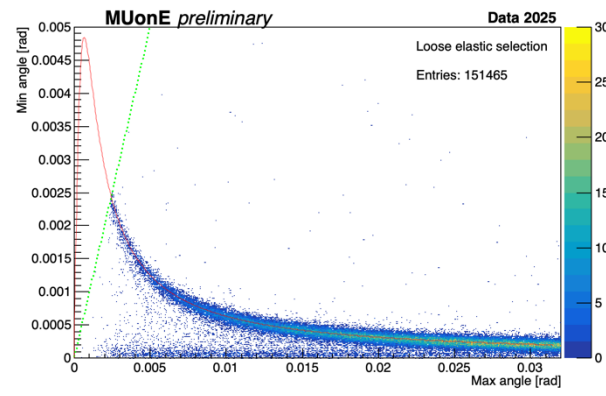
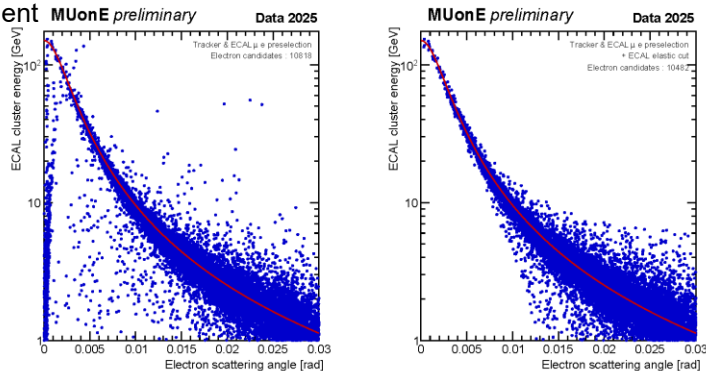
- Excellent tracking performance demonstrated
 - Efficiency typically 98–99% per module in Tracker
 - Efficiency independent of beam intensity
- Good effective hit resolution (preliminary from unbiased residuals):
 - Tilted XY modules: $\sigma \approx 11\text{-}12\ \mu\text{m}$
 - Non-tilted UV modules: $\sigma \approx 22\text{-}23\ \mu\text{m}$
 - Recall binary hit resolution: $90\ \mu\text{m}/\sqrt{12} \approx 26\ \mu\text{m}$
- Vertex reconstruction:
 - Vertex identified using incoming track + two outgoing tracks
 - Targets clearly visible; $\sigma_z(\text{vertex}) \sim 8\ \text{mm}$



Phase-1: Detector Performance

Very first results highlighting potential of PID:

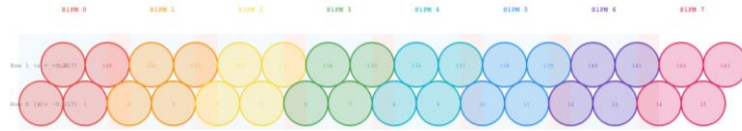
- Elastic curves show correlation of outgoing μ/e track angles
 - Loose cuts (vertex, acoplanarity) to identify elastic events
- μ Filter helps correctly identify muon vs electron in ambiguity region
- ECAL cluster energy compared against electron scattering angle
 - Track + ECAL centroid matching + elastic kinematics compatibility
 - Removes background – much potential for further PID improvement



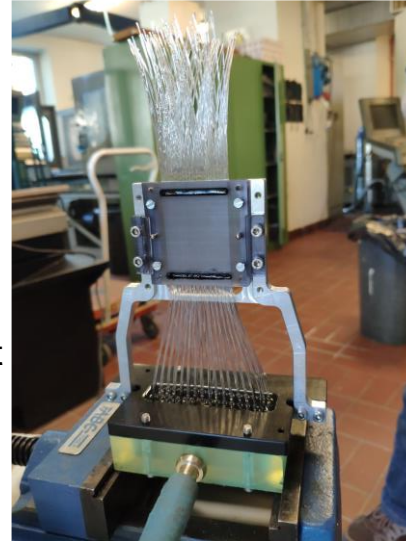
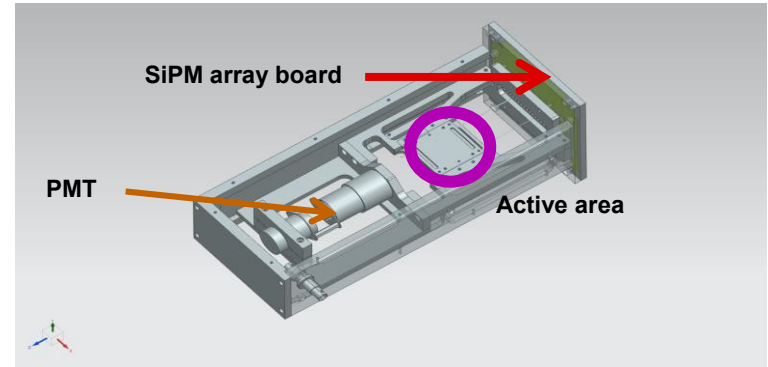
Conclusions

- Successful MUonE Phase-1 run demonstrated all detector technologies and their operation
 - Over 5×10^{11} pre-selected events to disk (~500 TB on EOS)
 - Expect confirmation of $\Delta\alpha_{\text{lep}}$ and ~20% measurement of $\Delta\alpha_{\text{had}}$
- Online event selection at full 40 MHz for the entire run
 - State-of-the-art FPGA-based processing; stable operation throughout
- Excellent tracking performance: >98% hit efficiency, synchronisation within 1 ns
- Phase 2 goal (after LS3, ~2030): 40 tracking stations
 - → $1.5 \times 10^4 \text{ pb}^{-1}$ integrated luminosity (3 years)
 - → < 0.5% on $a_{\mu}^{\text{(HVP, LO)}}$
- R&D activities ongoing: SciFi Muon Filter, IR HAM, ECAL, mechanics improvements
- 2026: analysis-focused year; EHN1 test beam requested for ECAL characterization and SciFi R&D

SciFi Muon Filter (R&D)

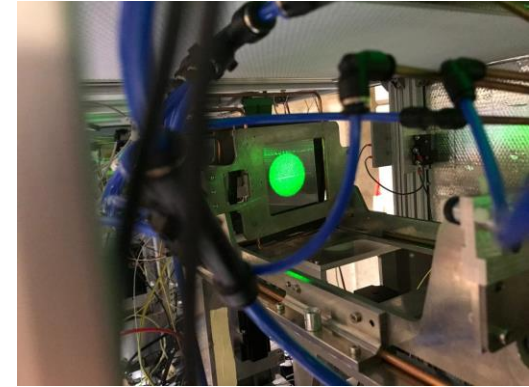
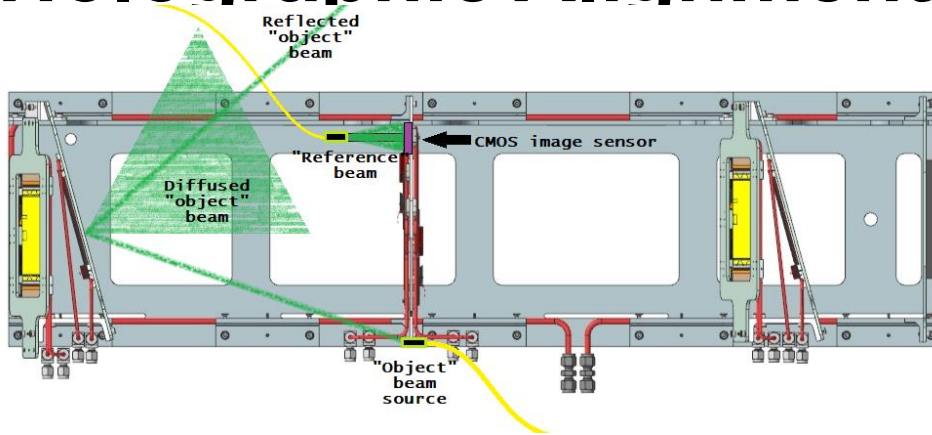


- Prototype for the Muon Filter upgrade (final detector)
- 0.5 mm dia. plastic scintillating fibers (Kuraray SCSF-78MJ)
 - Polystyrene core, double cladding (6% of thickness)
- Double and shifted layer array: 4 fibers coupled to 1 SiPM
 - SiPMs 1.3×1.3 mm² (Hamamatsu S13360-1350)
 - PMT (Hamamatsu R1924A) for triggering
- Pitch 1.25 mm – resolution ~360 μm
- Easy to cover large beam cross sections – easily scalable
- Custom front-end electronics (LIROC2 ASIC) in development



BACKUP

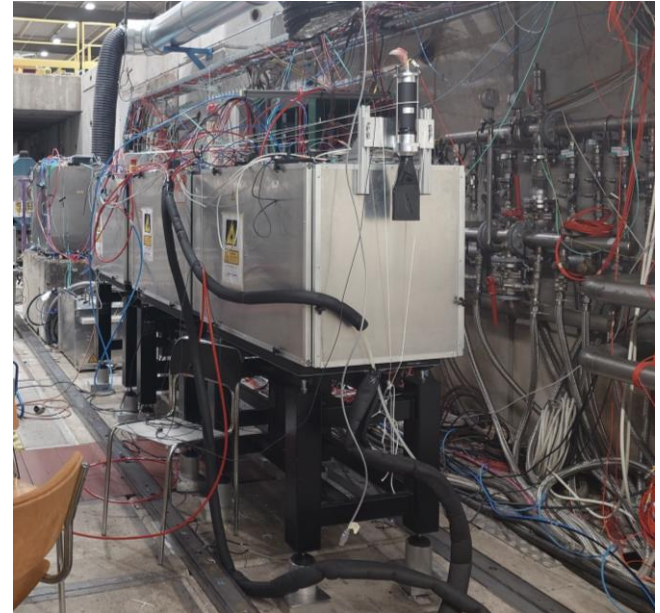
Holographic Alignment Monitor



- Monitors relative displacement between tracking planes within a station
- Relative position of the sensors must be stable $< 10 \mu\text{m}$
- Developed using custom digital holographic interferometric methods
- Sensitivity $\sim 0.25 \mu\text{m}$ (half wavelength) – 532 nm fiber-coupled laser
- Current limitation: 2S modules are sensitive to visible light \rightarrow cannot monitor continuously during beam
- Improvement: use IR laser ($> 1500 \text{ nm}$) where the silicon sensors are blind
 - HAM-IR would enable continuous monitoring without gaps during data-taking

Timing Reference

- Two 10×10 cm² plastic scintillator tiles with Hamamatsu H6410 PMTs
- Provides a global timing reference for incoming/outgoing particles
- M2 beam muons are asynchronous w.r.t. the 40 MHz sampling clock
 - Loss of efficiency when particles arrive near clock edges
- FC7 + FMC digitises signals with 0.89 ns precision
 - 28-bit TDC + ToT implemented in firmware
 - Full information transmitted to DAQ via in-FPGA 'emulated IpGBT' at 5 Gb/s

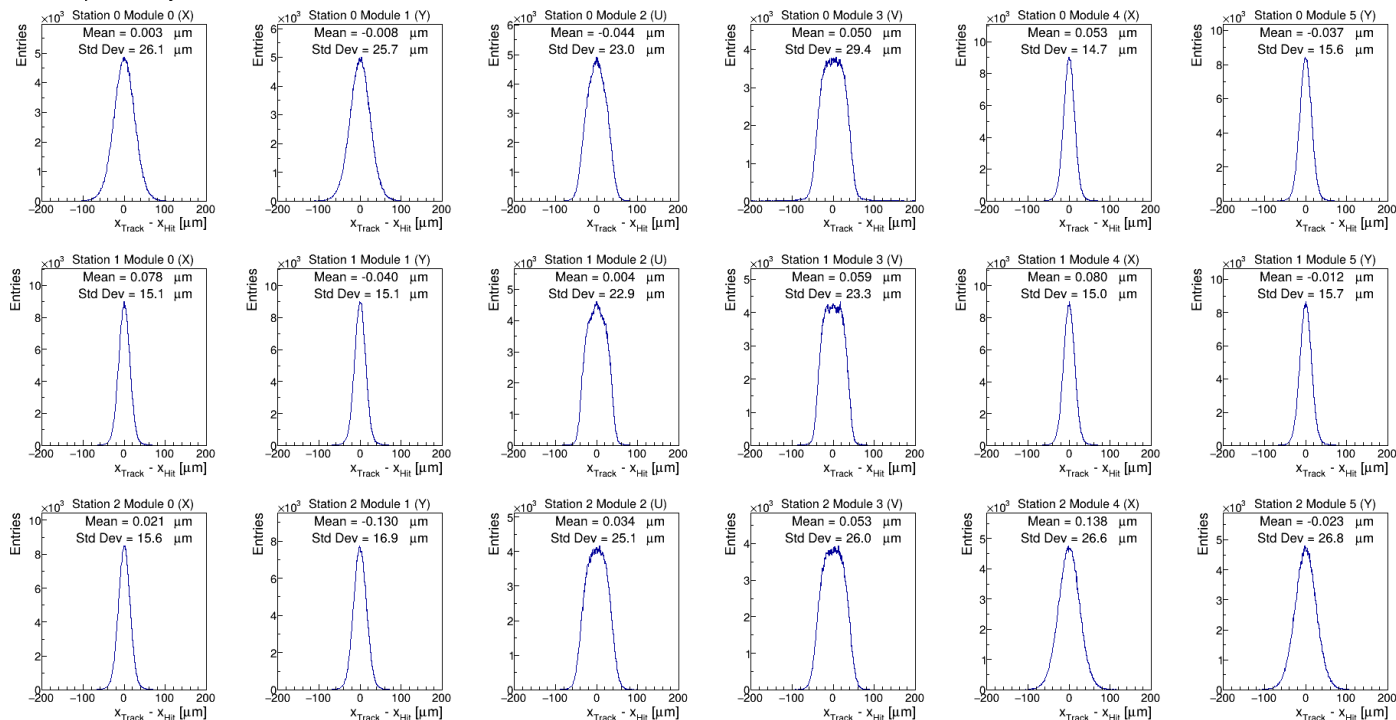


Tracker Software Alignment

Residuals (track – stub) centred $\sim 0.05 \mu\text{m}$

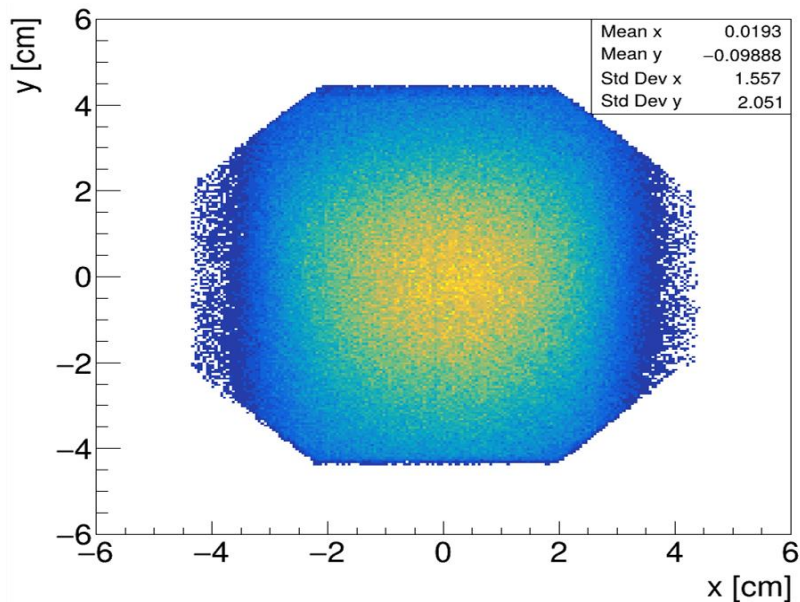
MUonE preliminary

Data 2025



Beam Characteristics

Beam spot @ 1st target



Beam direction

