

Lecture 3: Magnetization, cables and ac losses

Magnetization

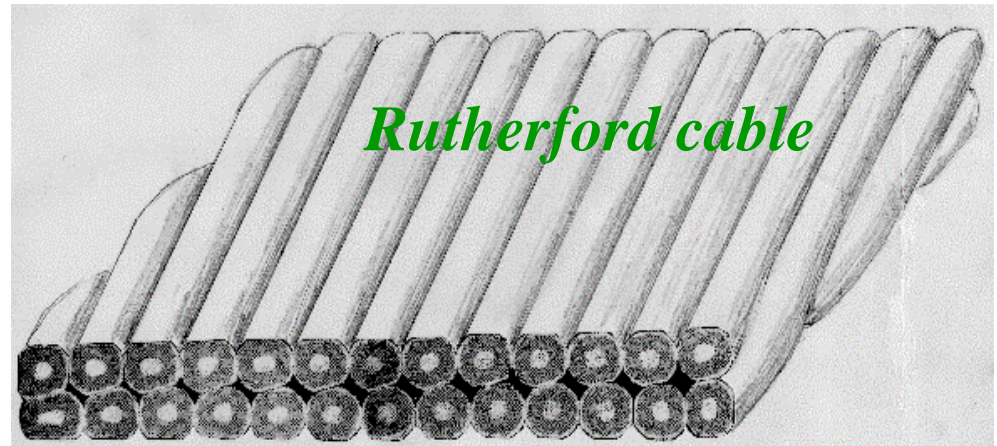
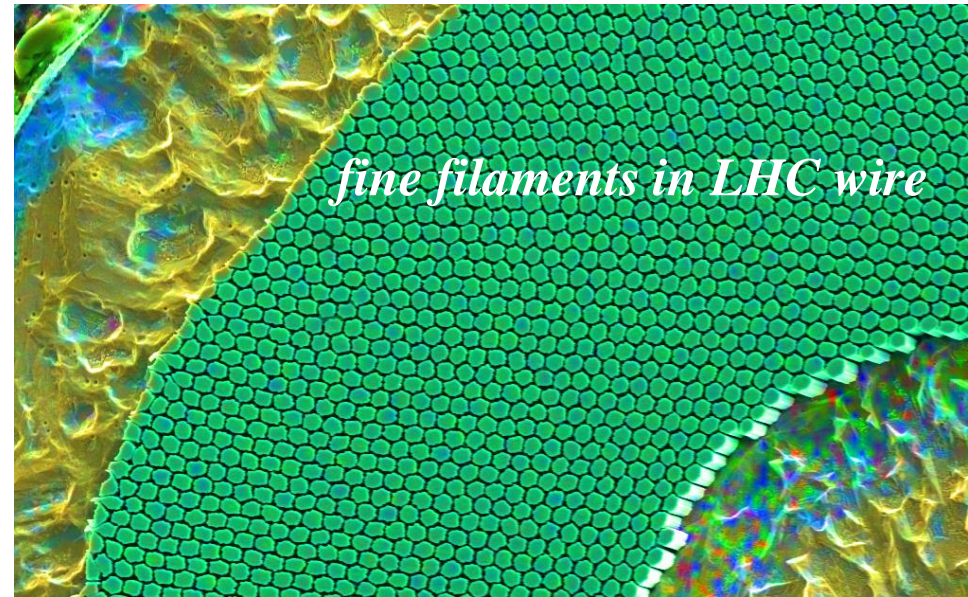
- magnetization of filaments
- coupling between filaments

Cables

- why cables?
- coupling in cables
- effect on field error in magnets

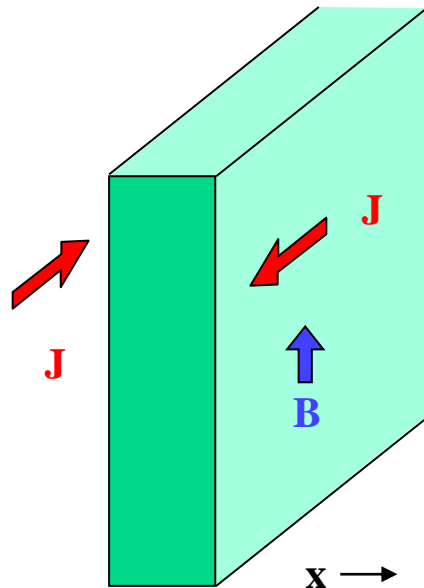
AC losses

- general expression
- losses within filaments
- losses from coupling



Recap: persistent screening currents

- **screening currents** are in addition to the **transport current**, which comes from the power supply
- like eddy currents but, because no resistance, they don't decay



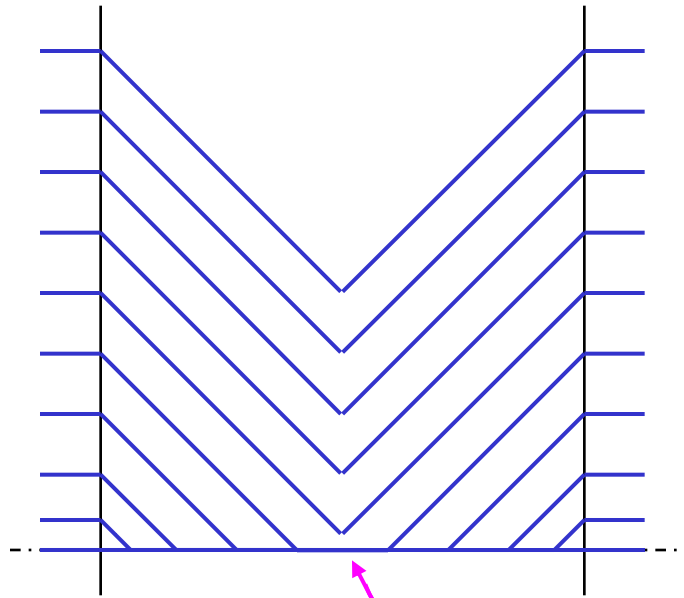
- $\frac{dB}{dt}$ induces an electric field **E** which drives the screening current up to critical current density J_c
- so we have $J = +J_c$ or $J = -J_c$ or $J = 0$ nothing else
- known as the **critical state model** or **Bean model**
- in the 1 dim infinite slab geometry, Maxwell's equation says

$$\frac{\partial B_y}{\partial x} = -\mu_0 J_z = \mu_0 J_c$$

- so uniform J_c means a constant field gradient inside the superconductor

The flux penetration process

plot field profile across the slab

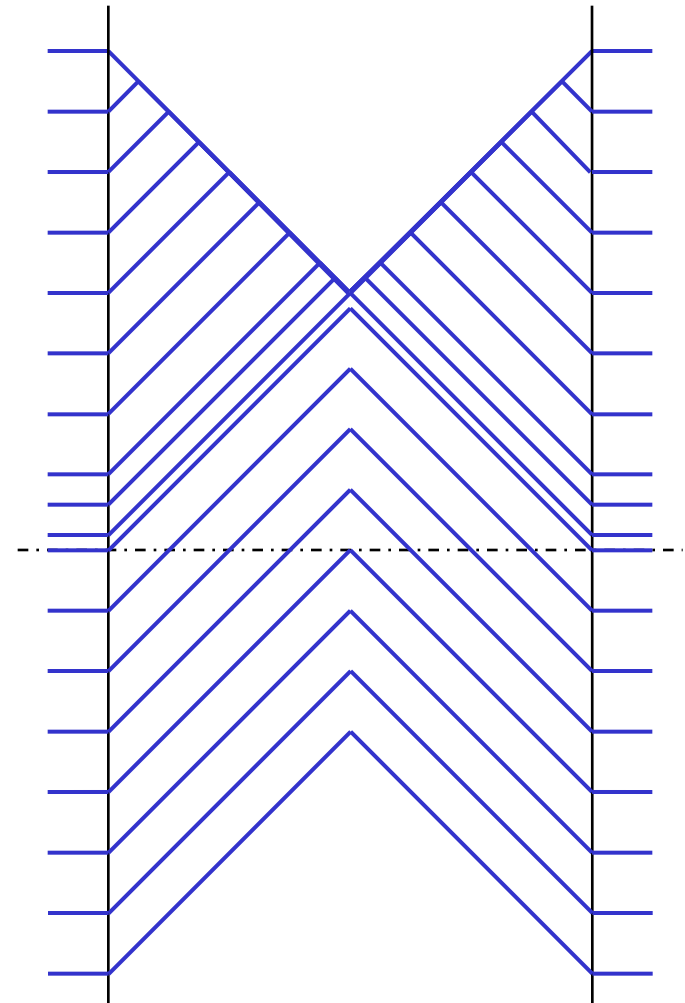


fully penetrated

field increasing from zero

Bean critical state model

- current density everywhere is $\pm J_c$ or zero
- change comes in from the outer surface



field decreasing through zero

Magnetization of the Superconductor

When viewed from outside the sample, the persistent currents produce a magnetic moment.

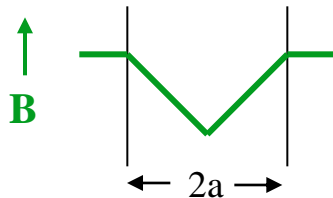
Problem for accelerators because it spoils the precise field shape

We can define a magnetization (magnetic moment per unit volume)

$$M = \sum_v \frac{I \cdot A}{V}$$

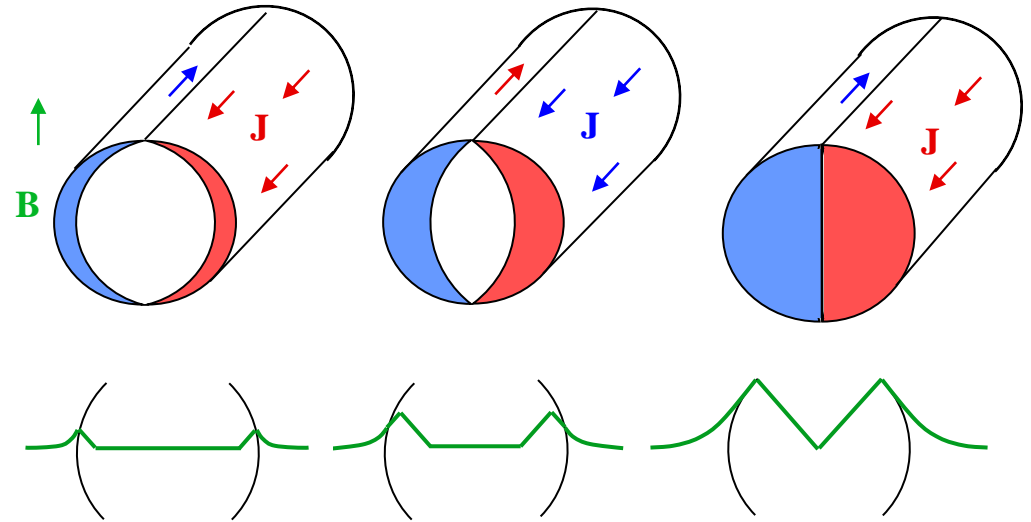
NB units of H

for a fully penetrated **slab**



$$M_s = \frac{1}{a} \int_0^a J_c \cdot x \cdot dx = \frac{J_c \cdot a}{2}$$

for **cylindrical** filaments the inner current boundary is roughly elliptical (controversial)



when fully penetrated, the magnetization is

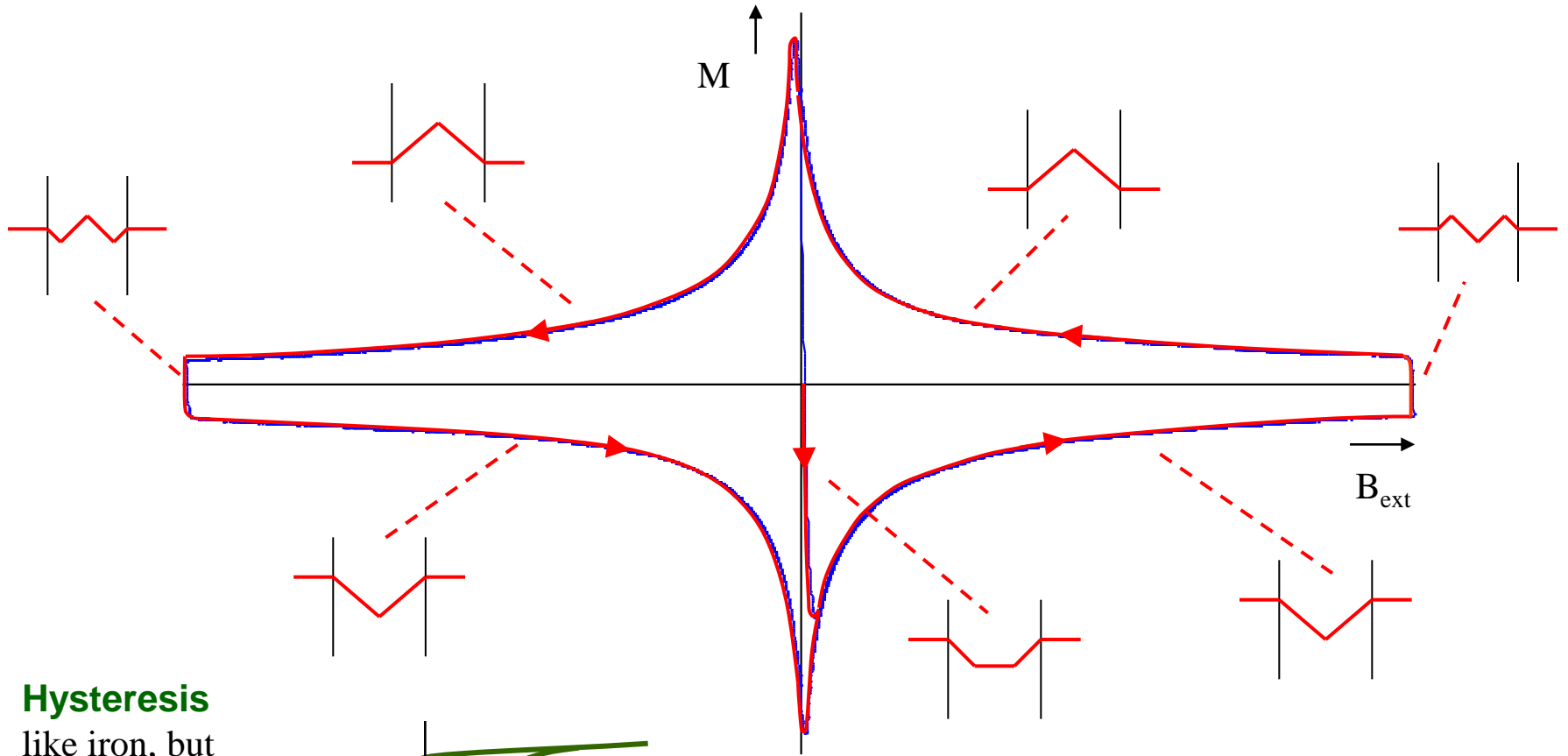
$$M_s = \frac{4}{3\pi} J_c a = \frac{2}{3\pi} J_c d_f$$

where a , d_f = filament radius, diameter

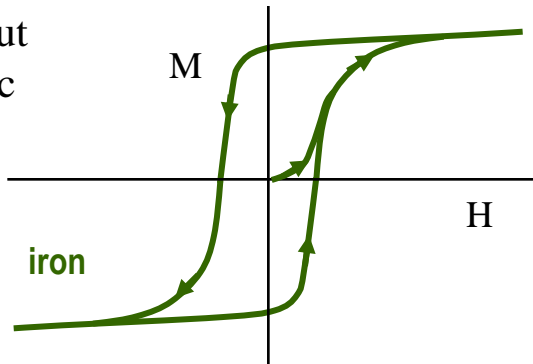
Note: M is here defined per unit volume of NbTi filament

to reduce M need small d - fine filaments

Magnetization of NbTi

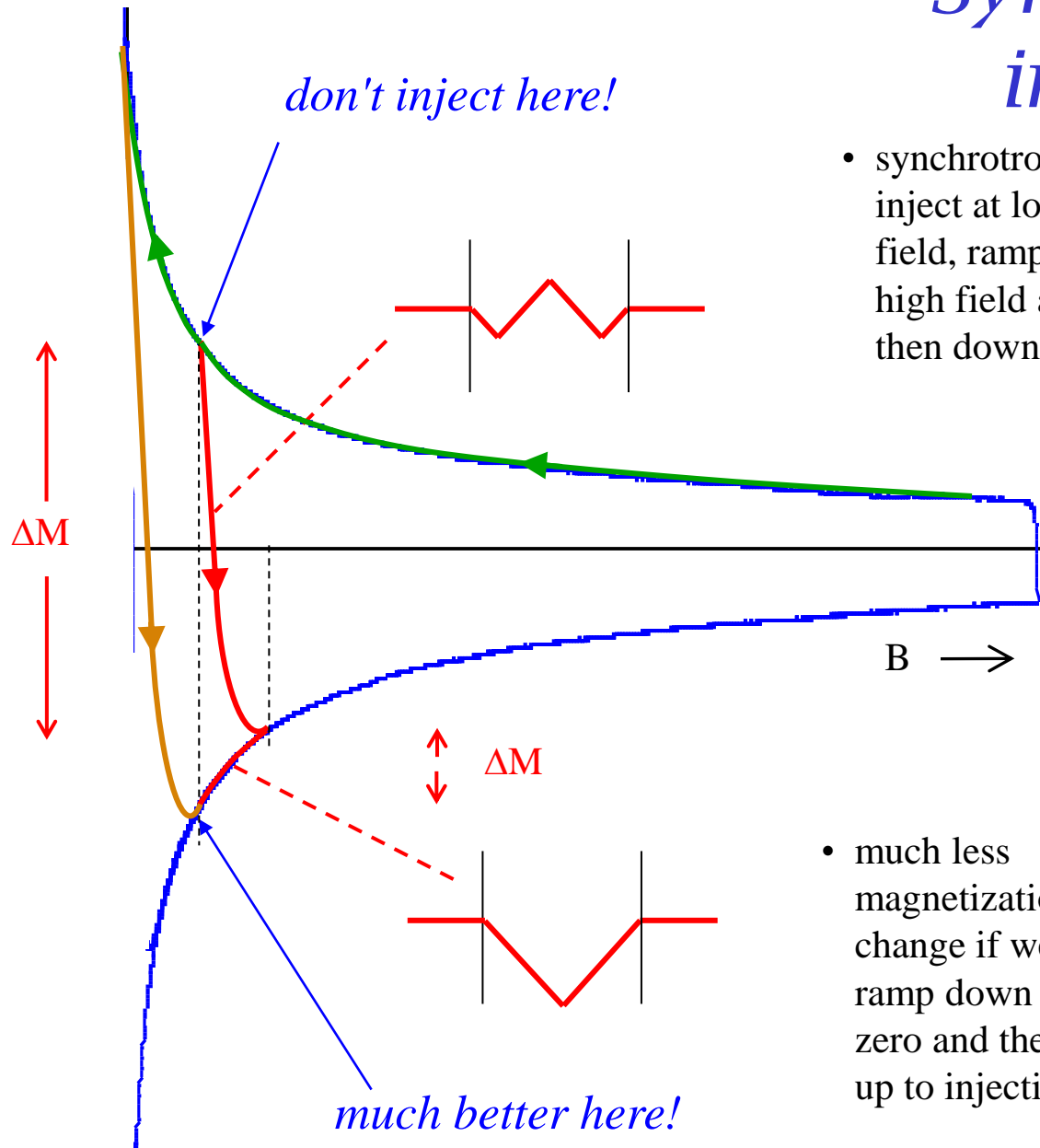


Hysteresis
like iron, but
diamagnetic

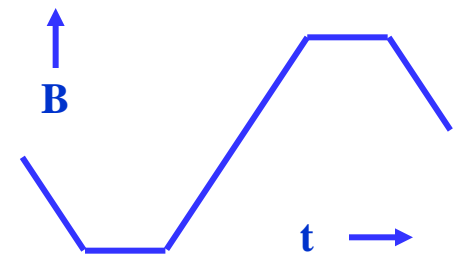


Magnetization is important because
it produces field errors and ac losses

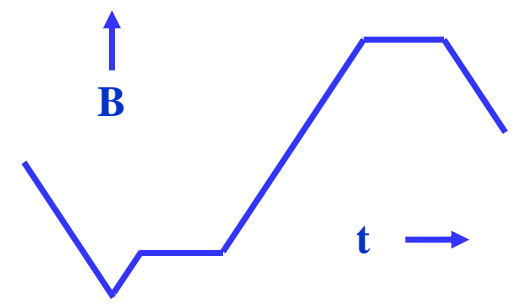
Synchrotron injection



- synchrotrons inject at low field, ramp to high field and then down again



- note how quickly the magnetization changes when we start the ramp up

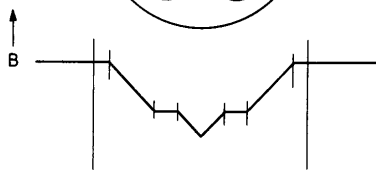
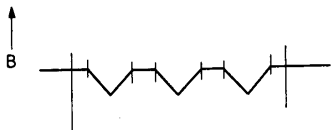
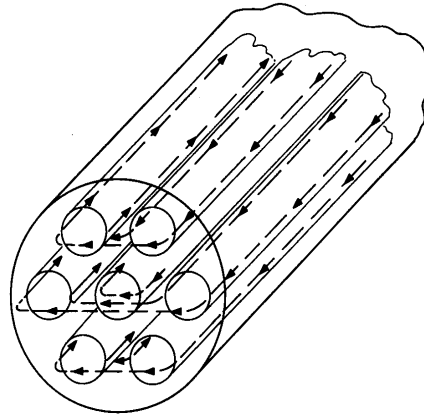
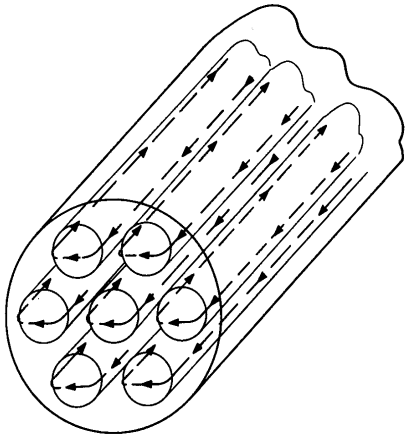
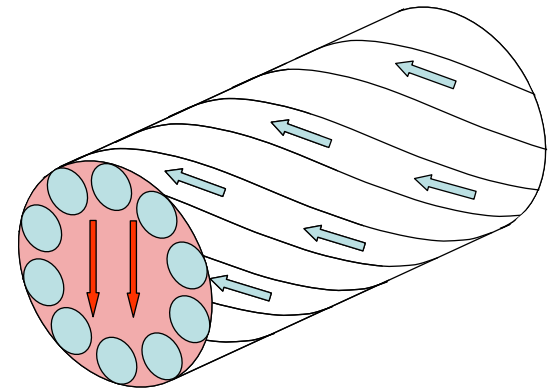
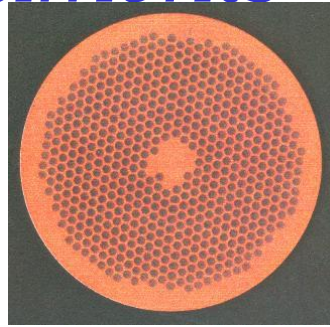


- much less magnetization change if we ramp down to zero and then up to injection

Coupling between filaments

recap
$$M_s = \frac{2}{3\pi} J_c d_f$$

- reduce M by making fine filaments
- for ease of handling, filaments are embedded in a copper matrix



- but in changing fields, the filaments are magnetically coupled
- screening currents go up the left filaments and return down the right

- coupling currents flow along the filaments and across the matrix
- fortunately they may be reduced by twisting the wire
- they behave like eddy currents and produce an additional magnetization

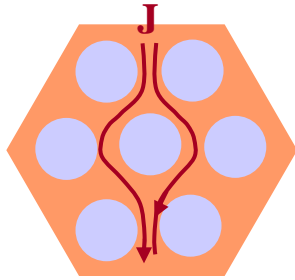
$$M_e = \frac{dB}{dt} \frac{1}{\rho_t} \left[\frac{p_w}{2\pi} \right]^2$$

per unit volume of wire

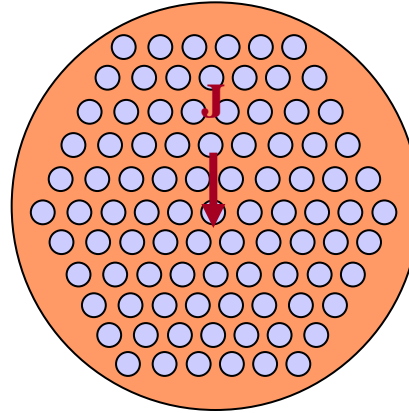
where ρ_t = resistivity across the matrix
and p_w = wire twist pitch

Transverse resistivity across the matrix

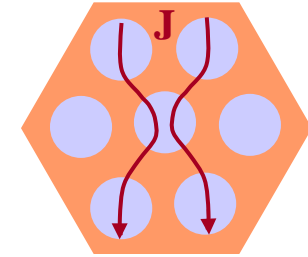
Poor contact to filaments



$$\rho_t = \rho_{Cu} \frac{1 + \lambda_{sw}}{1 - \lambda_{sw}}$$



Good contact to filaments



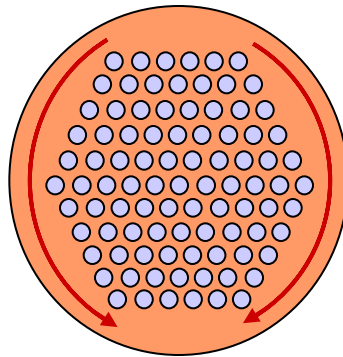
$$\rho_t = \rho_{Cu} \frac{1 - \lambda_{sw}}{1 + \lambda_{sw}}$$

where λ_{sw} is the fraction of superconductor in the wire cross section (after J Carr)

Some complications

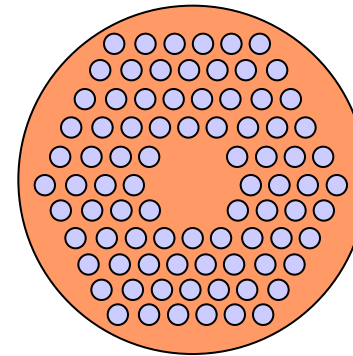
Thick copper jacket

include the copper jacket as a resistance in parallel

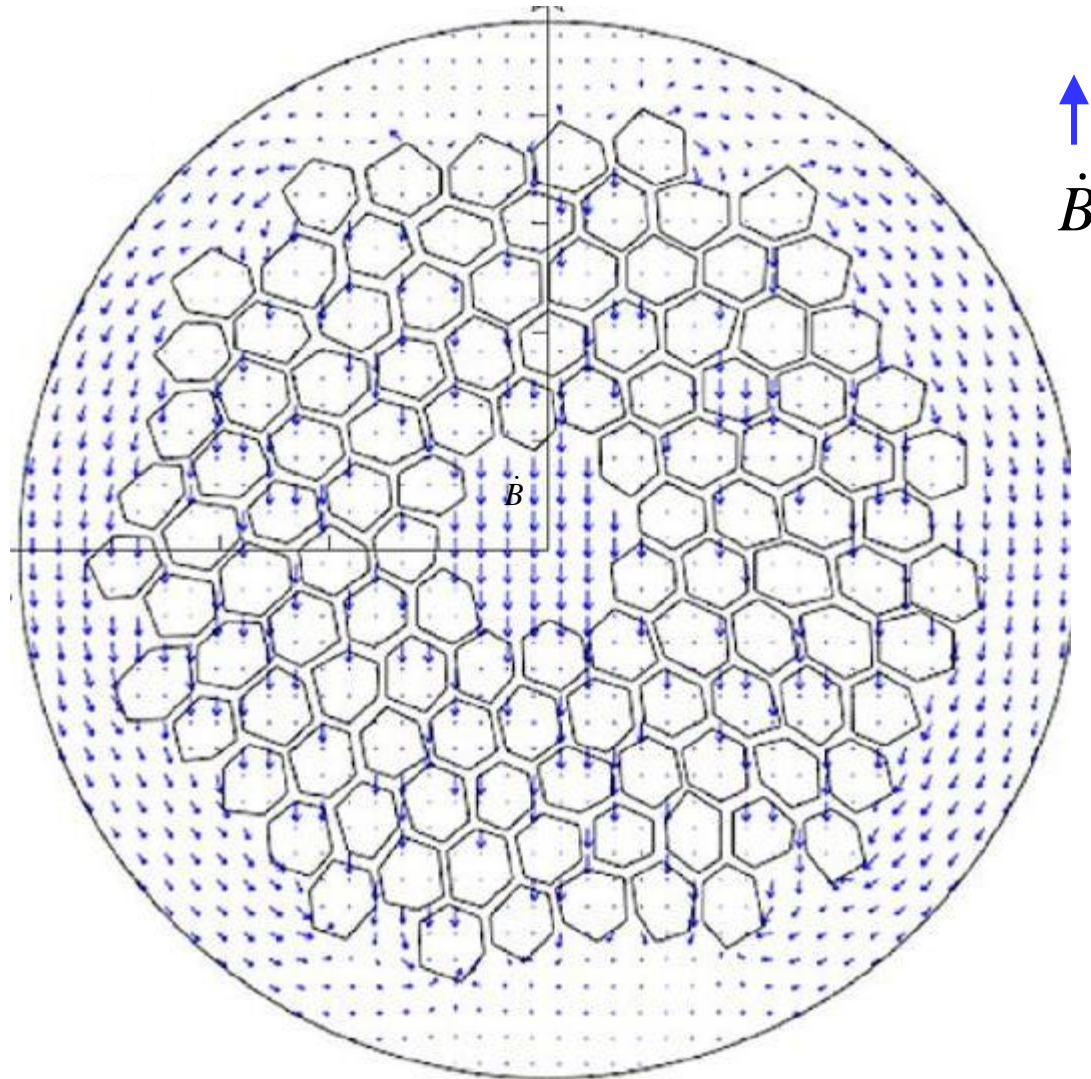


Copper core

resistance in series for part of current path



Computation of current flow across matrix



*calculated using
the COMSOL
code by
P.Fabbricatore et
al JAP, 106,
083905 (2009)*

Two components of magnetization

1) persistent current within the filaments

$$M_s = \lambda_{su} \frac{2}{3\pi} J_c(B) d_f$$

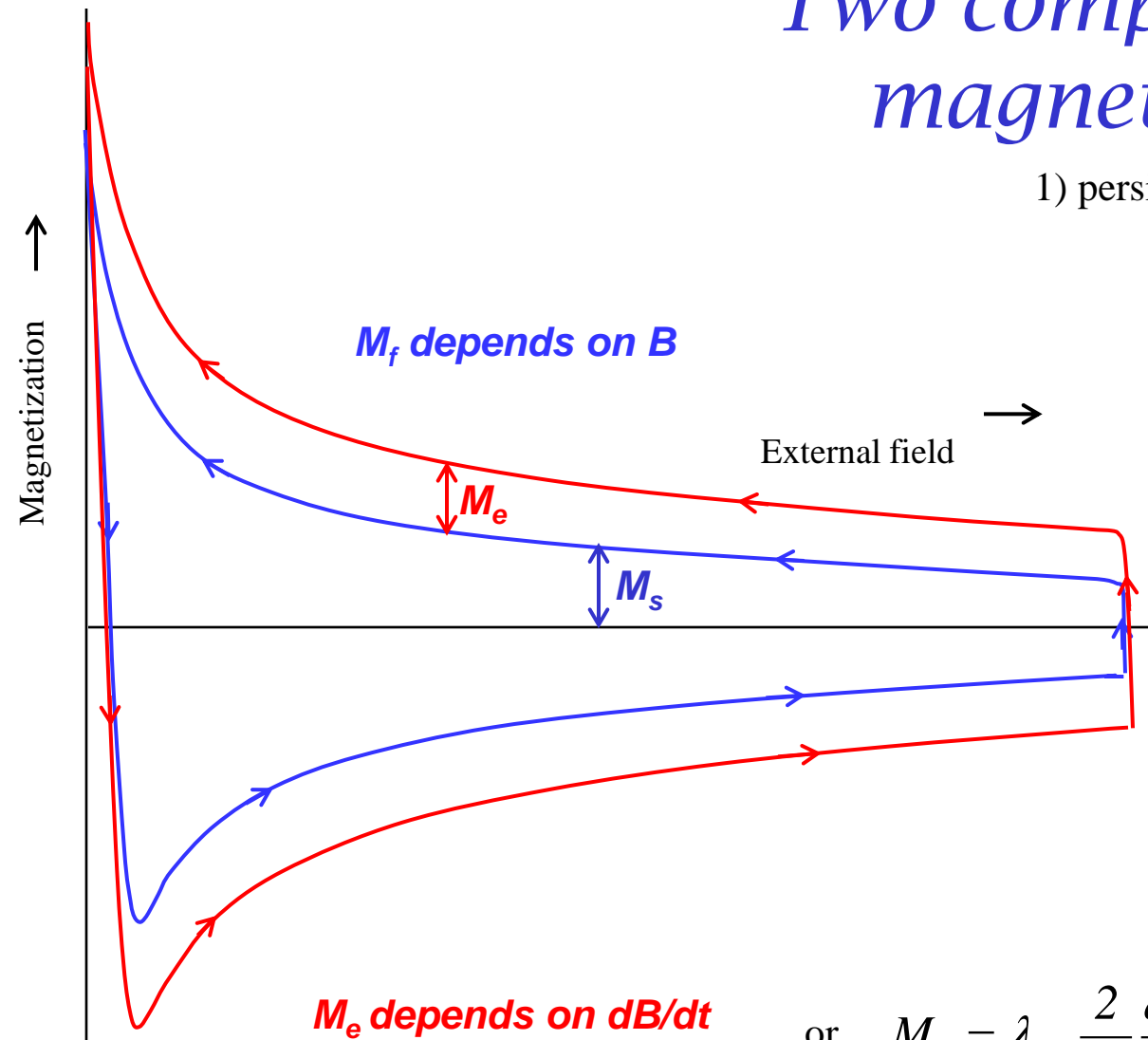
where λ_{su} = fraction of superconductor in the unit cell

2) eddy current coupling between the filaments

$$M_e = \lambda_{wu} \frac{dB}{dt} \frac{1}{\rho_t} \left[\frac{p_w}{2\pi} \right]^2$$

or
$$M_e = \lambda_{wu} \frac{2}{\mu_o} \frac{dB}{dt} \tau \quad \text{where} \quad \tau = \frac{\mu_o}{2\rho_t} \left[\frac{p_w}{2\pi} \right]^2$$

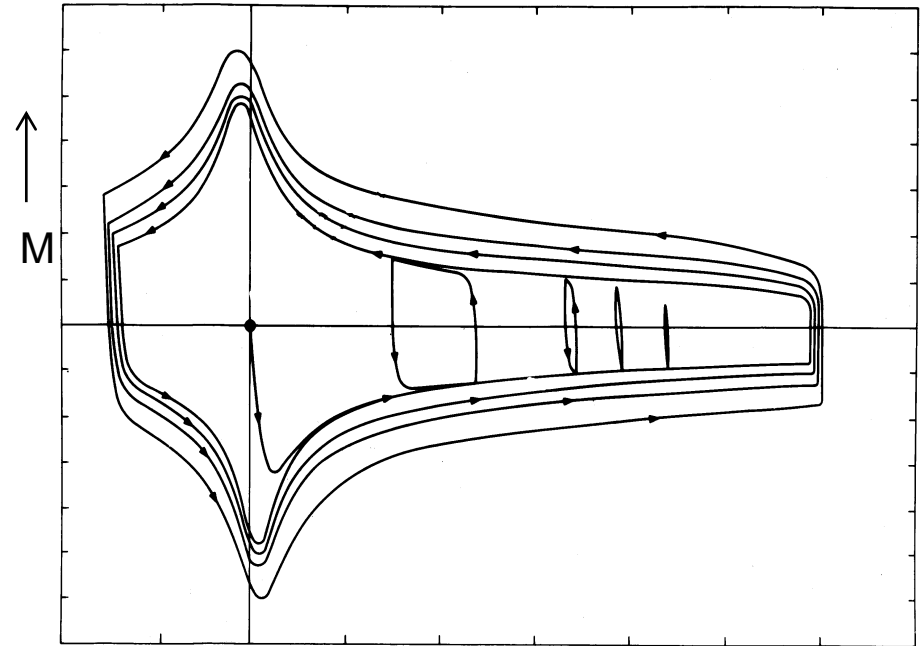
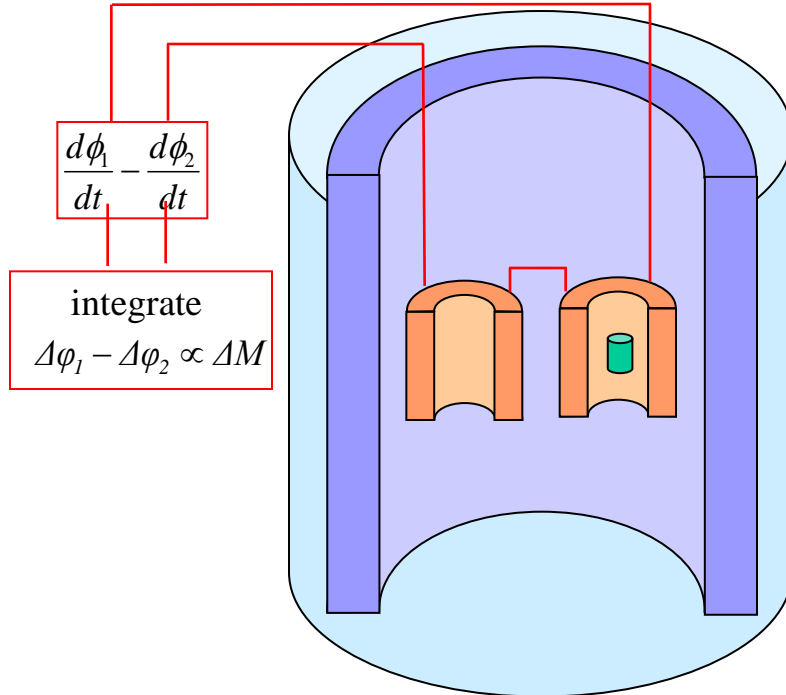
where λ_{wu} = fraction of wire in the section



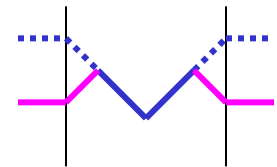
Magnetization is averaged over the unit cell

Measurement of magnetization

In field, the superconductor behaves just like a magnetic material. We can plot the magnetization curve using a magnetometer. It shows hysteresis - just like iron only in this case the magnetization is both diamagnetic and paramagnetic.



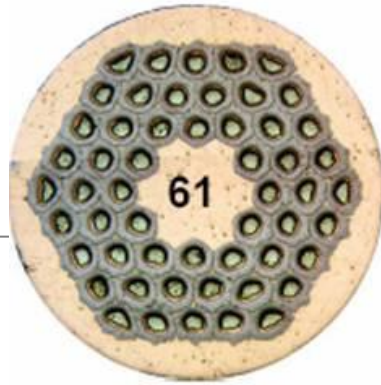
Note the minor loops, where field and therefore screening currents are reversing



Two balanced search coils connected in series opposition, are placed within the bore of a superconducting solenoid. With a superconducting sample in one coil, the integrator measures ΔM when the solenoid field is swept up and down

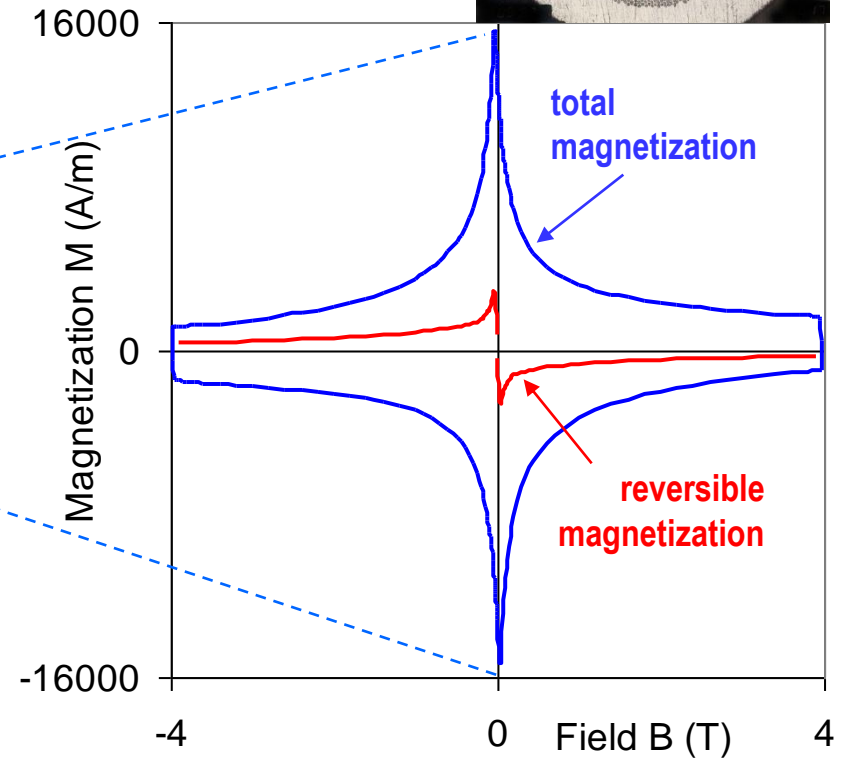
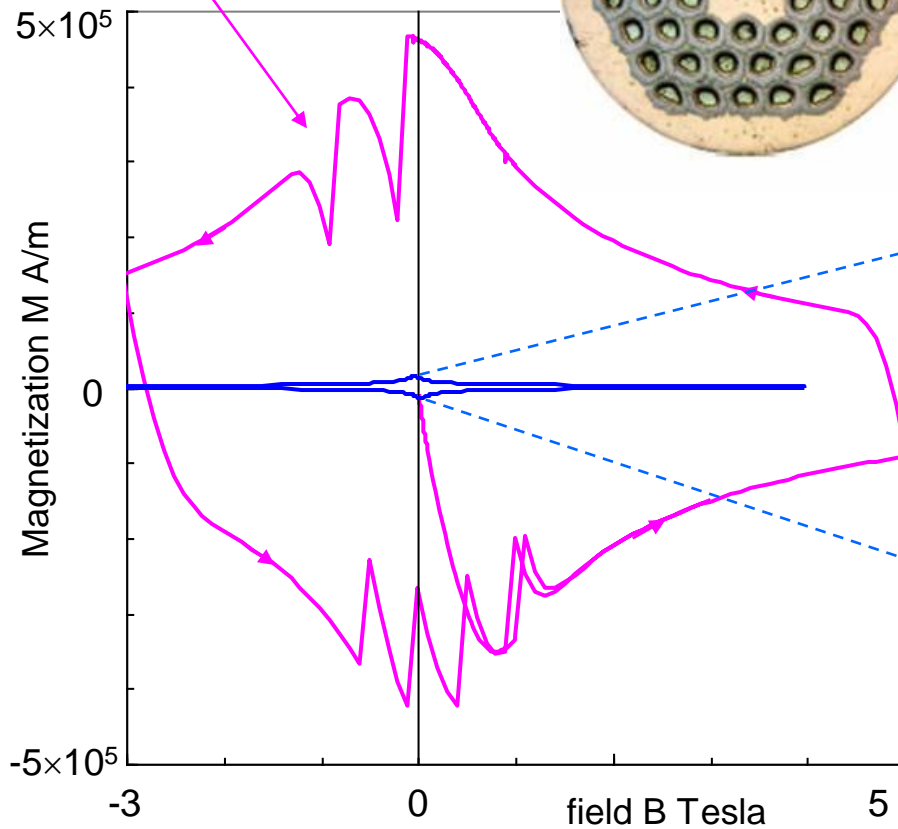
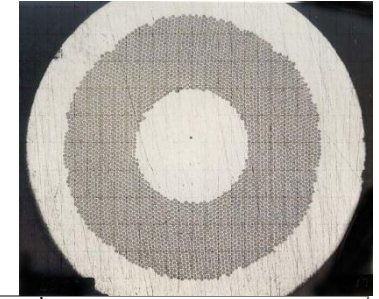
Magnetization measurements

flux jumping at low field caused by large filaments and high J_c



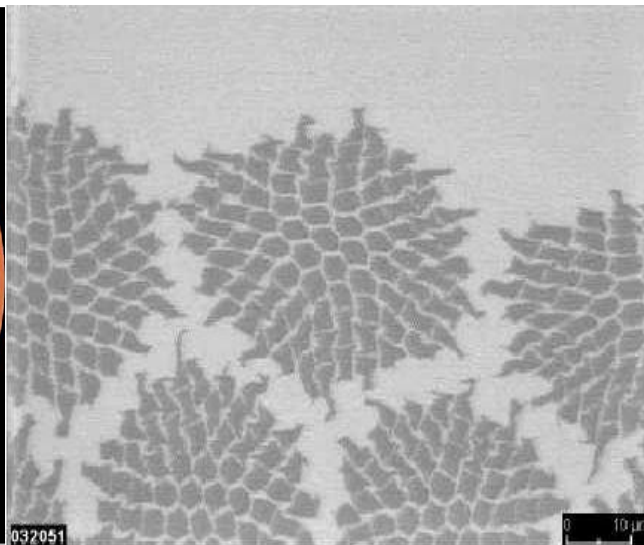
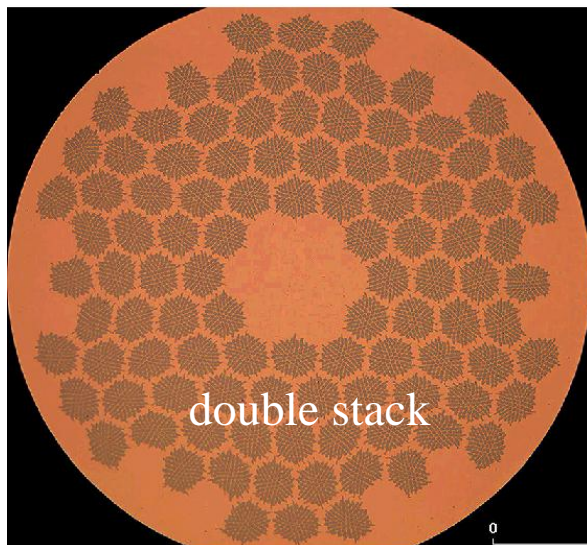
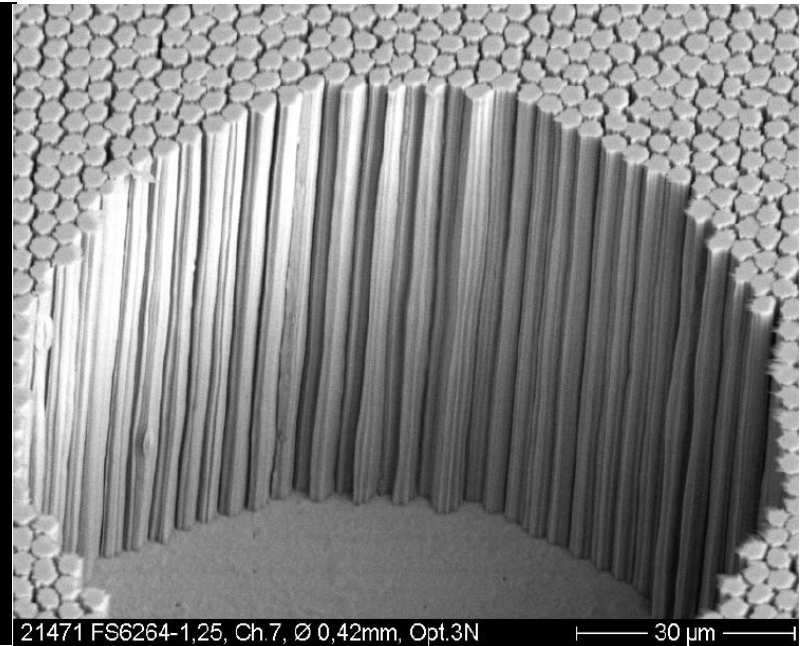
RRP Nb_3Sn wire with $50\mu m$ filaments

NbTi wire for RHIC with $6\mu m$ filaments



Fine filaments for low magnetization

Accelerator magnets need the finest filaments - to minimize field errors and ac losses



Typical diameters are in the range 5 - 10µm. Even smaller diameters would give lower magnetization, but at the cost of lower J_c and more difficult production.

Cables - why do we need them?

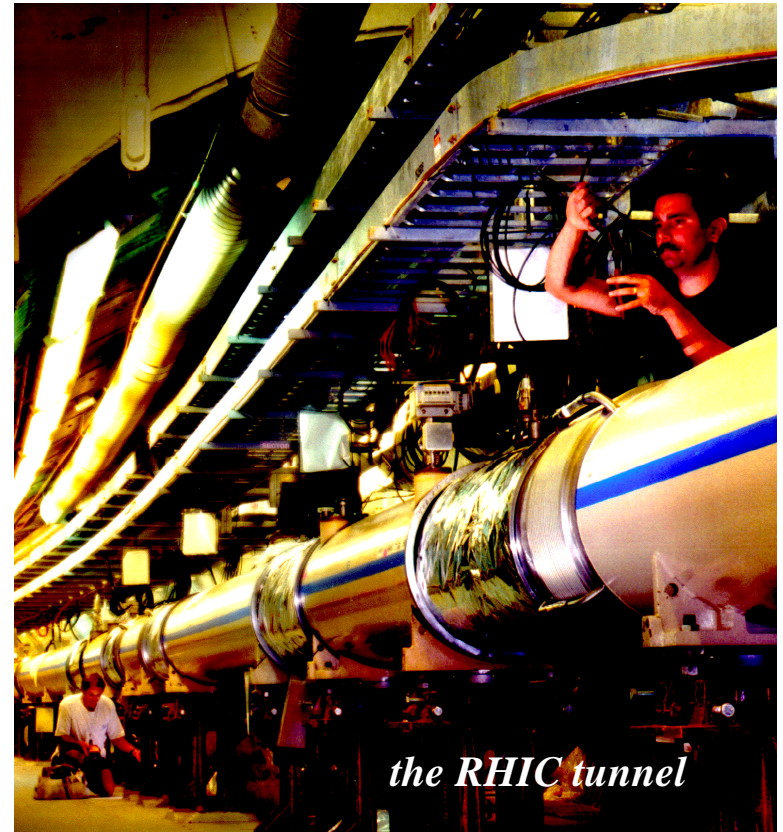
- for good tracking we connect synchrotron magnets in series
- if the stored energy is E , rise time t and operating current I , the charging voltage is

$$E = \frac{B^2}{2\mu_0} V = \frac{1}{2} LI^2 \qquad V = \frac{LI}{t} = \frac{2E}{It}$$

RHIC $E = 40\text{kJ/m}$, $t = 75\text{s}$, 30 strand cable
cable $I = 5\text{kA}$, charge voltage per km = **213V**
wire $I = 167\text{A}$, charge voltage per km = **6400V**

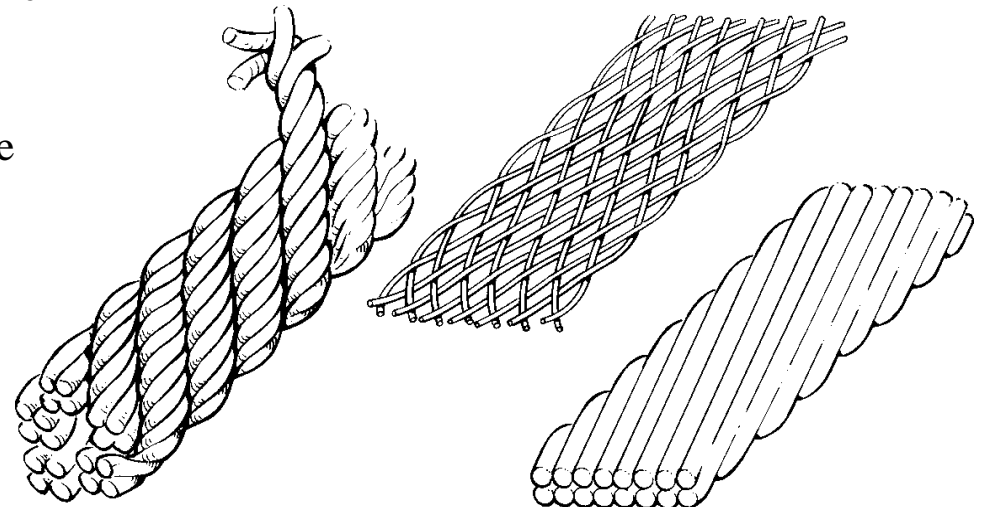
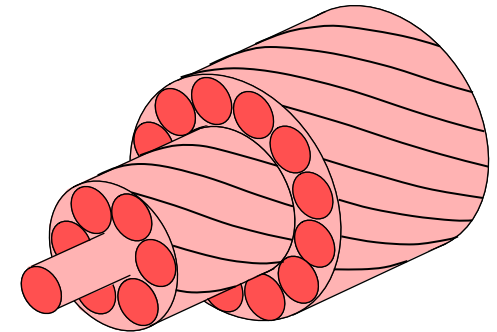
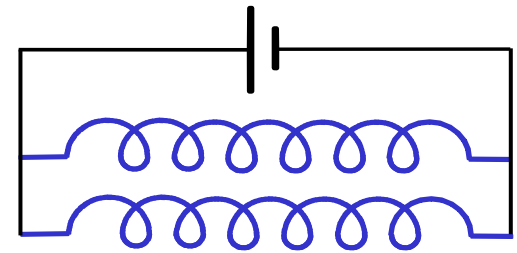
FAIR at GSI $E = 74\text{kJ/m}$, $t = 4\text{s}$, 30 strand cable
cable $I = 6.8\text{kA}$, charge voltage per km = **5.4kV**
wire $I = 227\text{A}$, charge voltage per km = **163kV**

- so we need high currents!
- a single $5\mu\text{m}$ filament of NbTi in 6T carries 50mA
- a composite wire of fine filaments typically has 5,000 to 10,000 filaments, so it carries 250A to 500A
- for 5 to 10kA, we need 20 to 40 wires in parallel - **a cable**

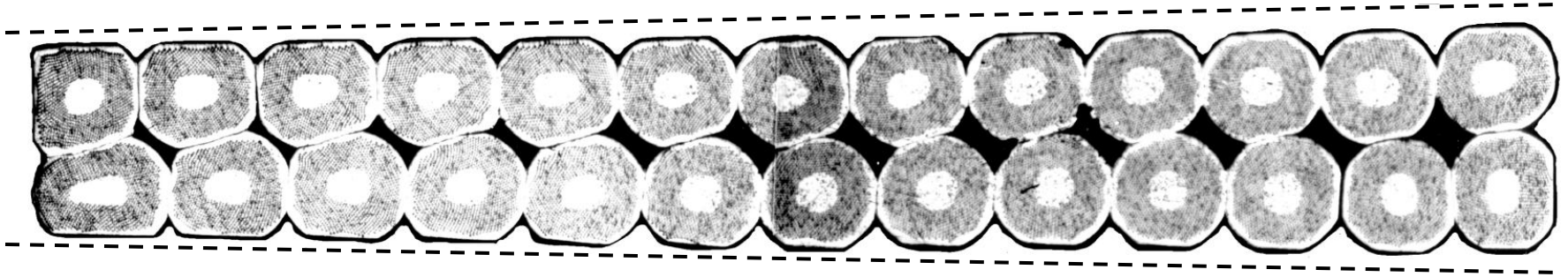


Cable transposition

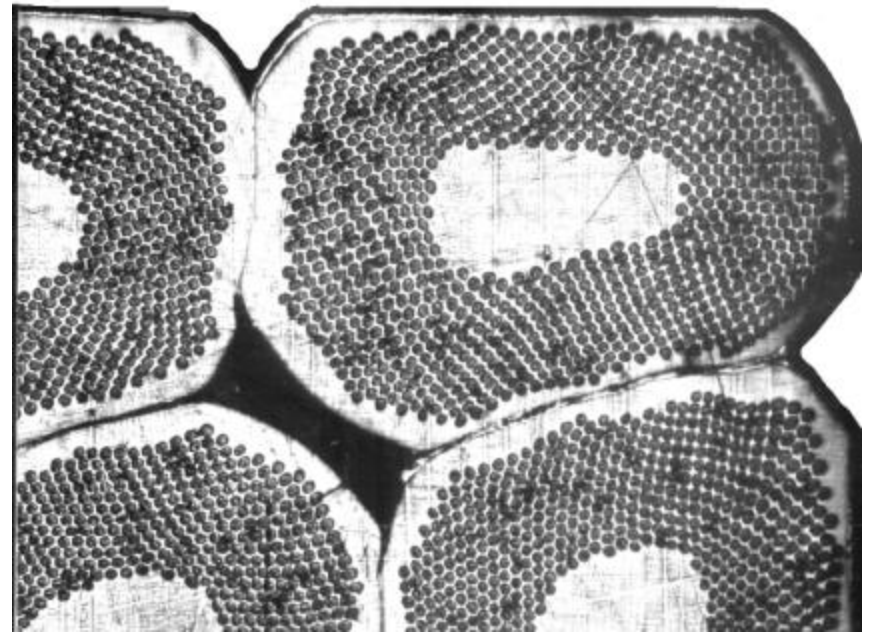
- many wires in parallel - want them all to carry same current
zero resistance - so current divides according to inductance
- in a simple twisted cable, wires in the centre have a higher self inductance than those at the outside
- current fed in from the power supply therefore takes the low inductance path and stays on the outside
- so outer wires reach J_c while inner are still empty
- so the wires must be fully **transposed**, ie every wire must change places with every other wire along the length
inner wires \Rightarrow outside outer wire \Rightarrow inside
- three types of fully transposed cable have been tried in accelerators
 - rope
 - braid
 - Rutherford

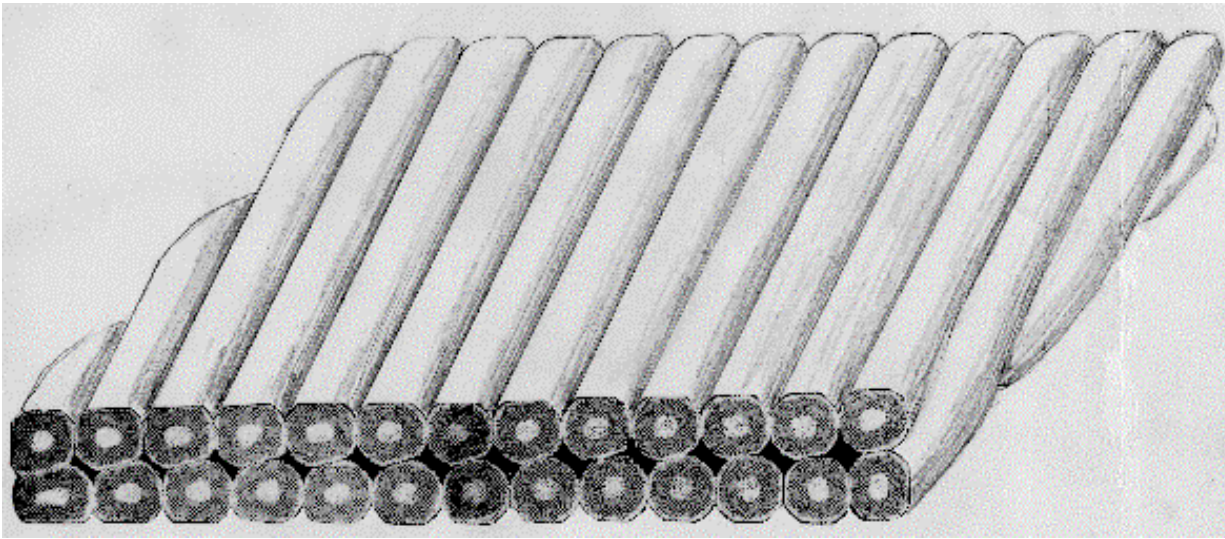


Rutherford cable



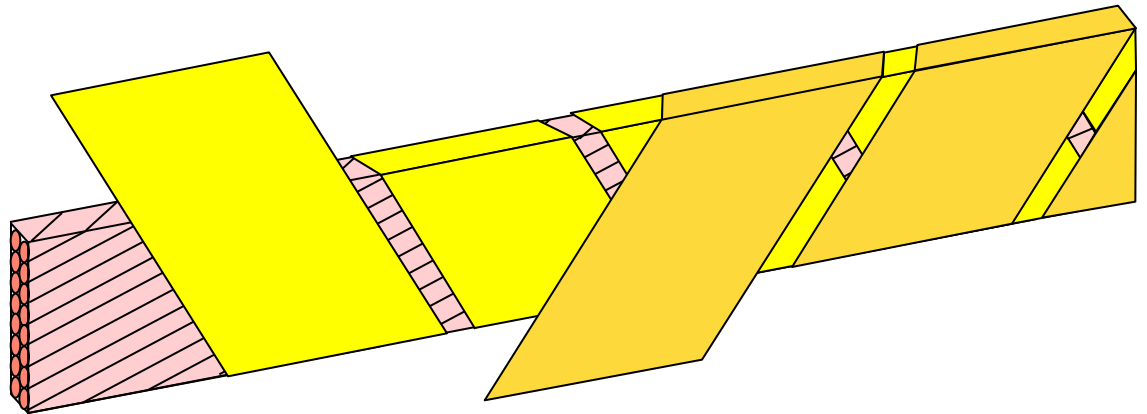
- Rutherford cable succeeded where others failed because it could be compacted to a high density (88 - 94%) without damaging the wires, and rolled to a good dimensional accuracy ($\sim 10\mu\text{m}$).
- Note the 'keystone angle', which enables the cables to be stacked closely round a circular aperture





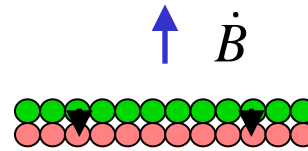
Rutherford cable

- the cable is insulated by wrapping 2 or 3 layers of Kapton; gaps may be left to allow penetration of liquid helium; the outer layer is treated with an adhesive layer for bonding to adjacent turns.
- Recapitulate: the adhesive faces outwards, don't bond it to the cable (avoid energy release by bond failure)
- allow liquid helium to permeate the cable
- increase the MQE

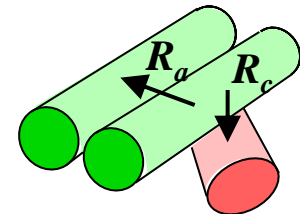
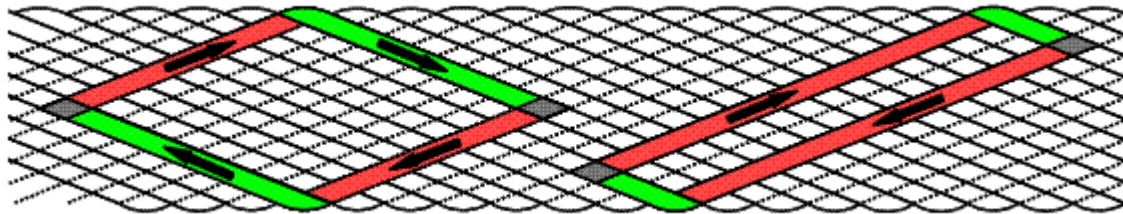


Coupling in Rutherford cables

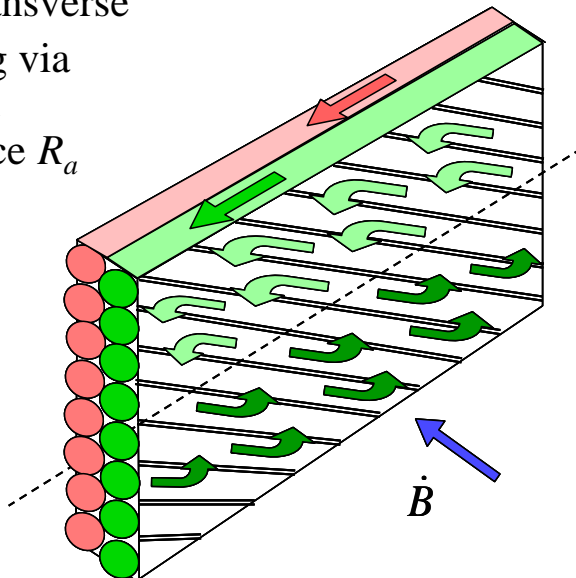
- Field transverse
coupling via crossover resistance R_c



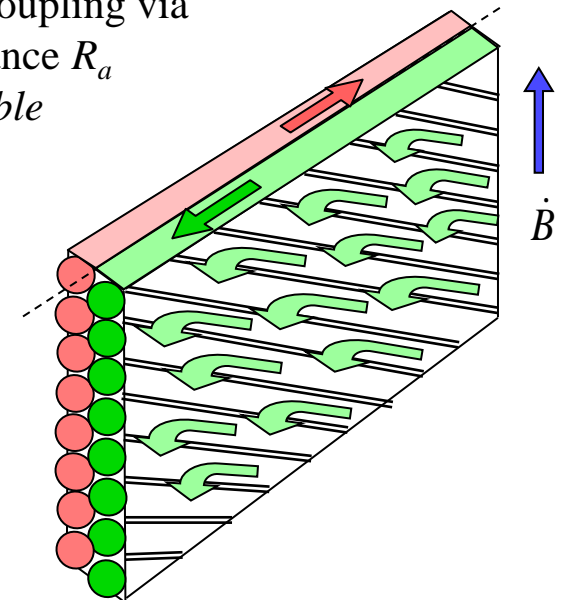
crossover resistance R_c
adjacent resistance R_a



- Field transverse
coupling via
adjacent
resistance R_a



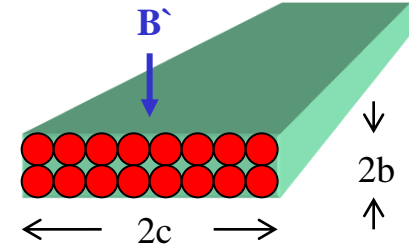
- Field parallel coupling via
adjacent resistance R_a
usually negligible



Magnetization from coupling in cables

- Field transverse coupling via crossover resistance R_c

$$M_{tc} = \frac{1}{120} \frac{\dot{B}_t}{R_c} \frac{c}{b} p N(N-1) = \frac{1}{60} \frac{\dot{B}_t}{r_c} p^2 \frac{c^2}{b}$$



where M = magnetization *per unit volume of cable*, p = twist pitch, N = number of strands
 R_c R_a resistance per crossover r_c r_a resistance per unit area of contact

- Field transverse

coupling via adjacent resistance R_a

where θ = slope angle of wires $\text{Cos}\theta \sim 1$

$$M_{ta} = \frac{1}{6} \frac{\dot{B}_t}{R_a} p \frac{c}{b} = \frac{1}{48} \frac{\dot{B}_t}{r_a} p^2 \frac{b}{\text{Cos}^2\theta}$$

- Field parallel

coupling via adjacent resistance R_a

$$M_{pa} = \frac{1}{8} \frac{\dot{B}_p}{R_a} p \frac{b}{c} = \frac{1}{64} \frac{\dot{B}_p}{r_a} p^2 \frac{b^3}{c^2 \text{cos}^2\theta}$$

(usually negligible)

- Field transverse ratio crossover/adjacent

$$\frac{M_{tc}}{M_{ta}} = \frac{R_a}{R_c} \frac{N(N-1)}{20} \approx 45 \frac{R_a}{R_c}$$

So without increasing loss too much can make R_a 50 times less than R_c - anisotropy

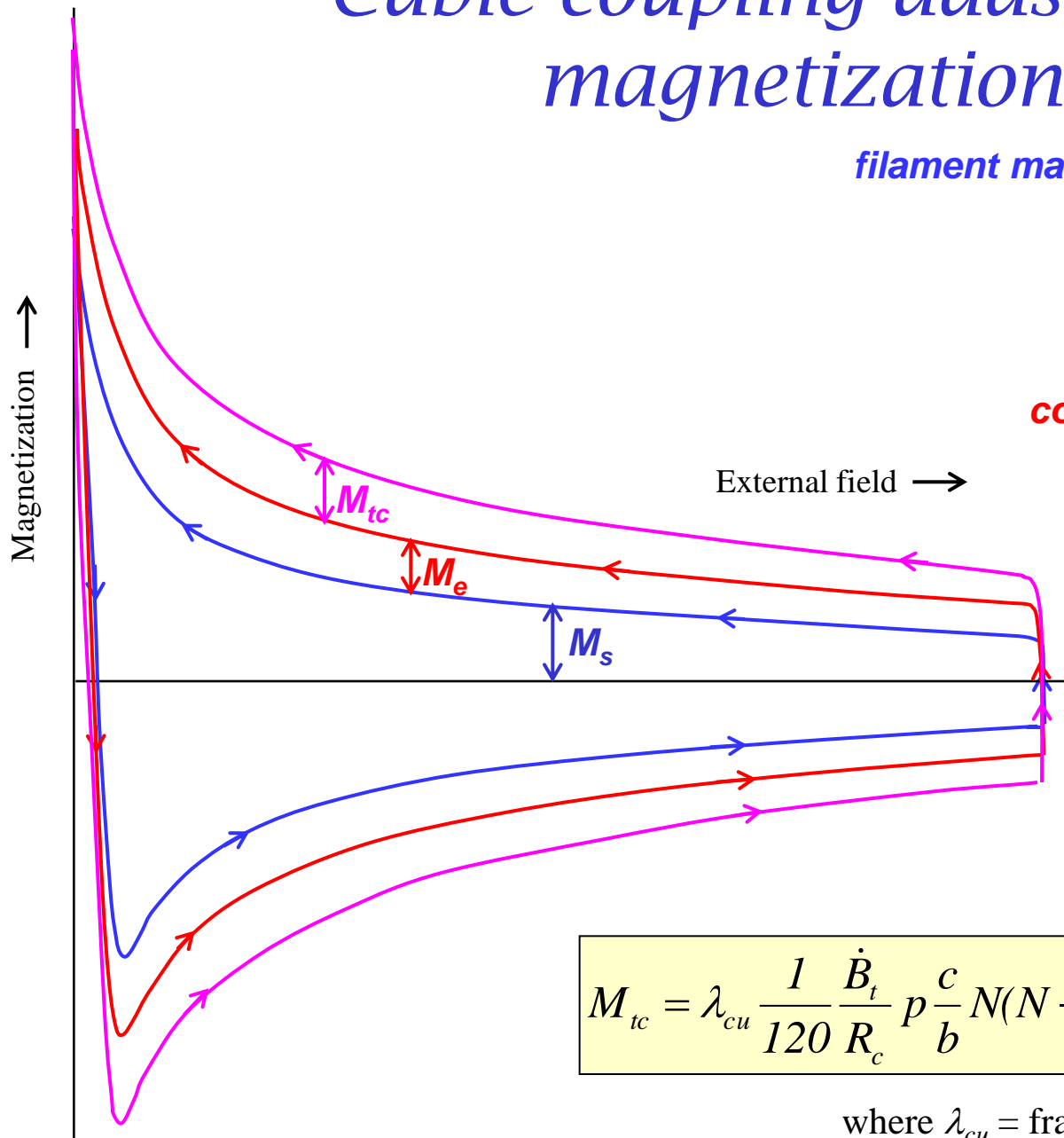
Cable coupling adds more magnetization

filament magnetization M_f depends on B

$$M_s = \lambda_{su} \frac{2}{3\pi} J_c(B) d_f$$

coupling between filaments M_e depends on dB/dt

$$M_e = \lambda_{wu} \frac{dB}{dt} \frac{1}{\rho_t} \left[\frac{p_w}{2\pi} \right]^2$$



coupling between wires in cable depends on dB/dt

$$M_{tc} = \lambda_{cu} \frac{1}{120} \frac{\dot{B}_t}{R_c} p \frac{c}{b} N(N-1)$$

$$M_{ta} = \lambda_{cu} \frac{1}{6} \frac{\dot{B}_t}{R_a} p \frac{c}{b}$$

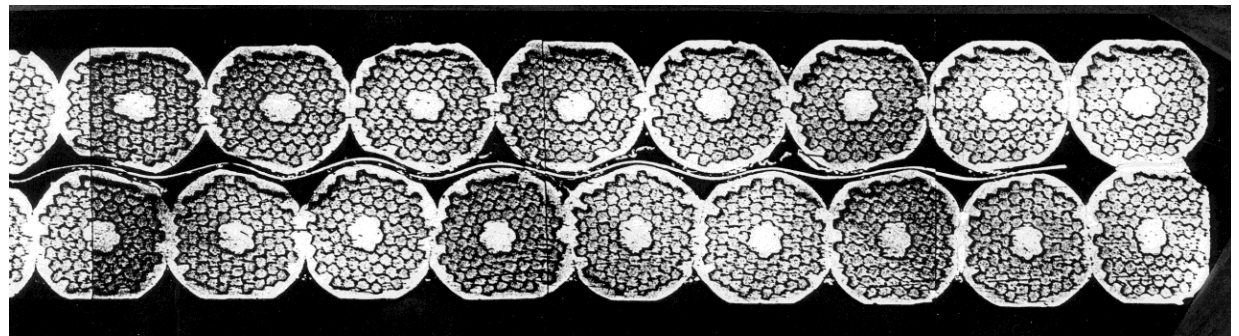
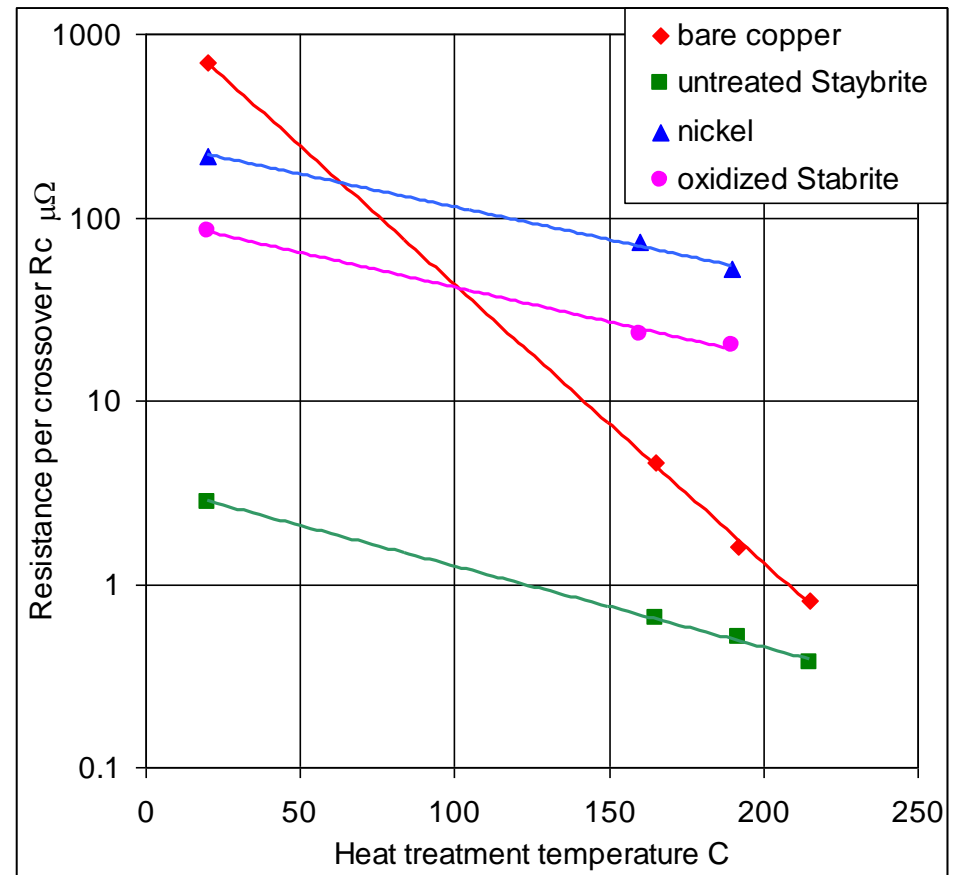
where λ_{cu} = fraction of cable in the section

Controlling R_a and R_c

- surface coatings on the wires are used to adjust the contact resistance
- the values obtained are very sensitive to pressure and heat treatments used in coil manufacture (to cure the adhesive between turns)
- *data from David Richter CERN*

Cored Cables

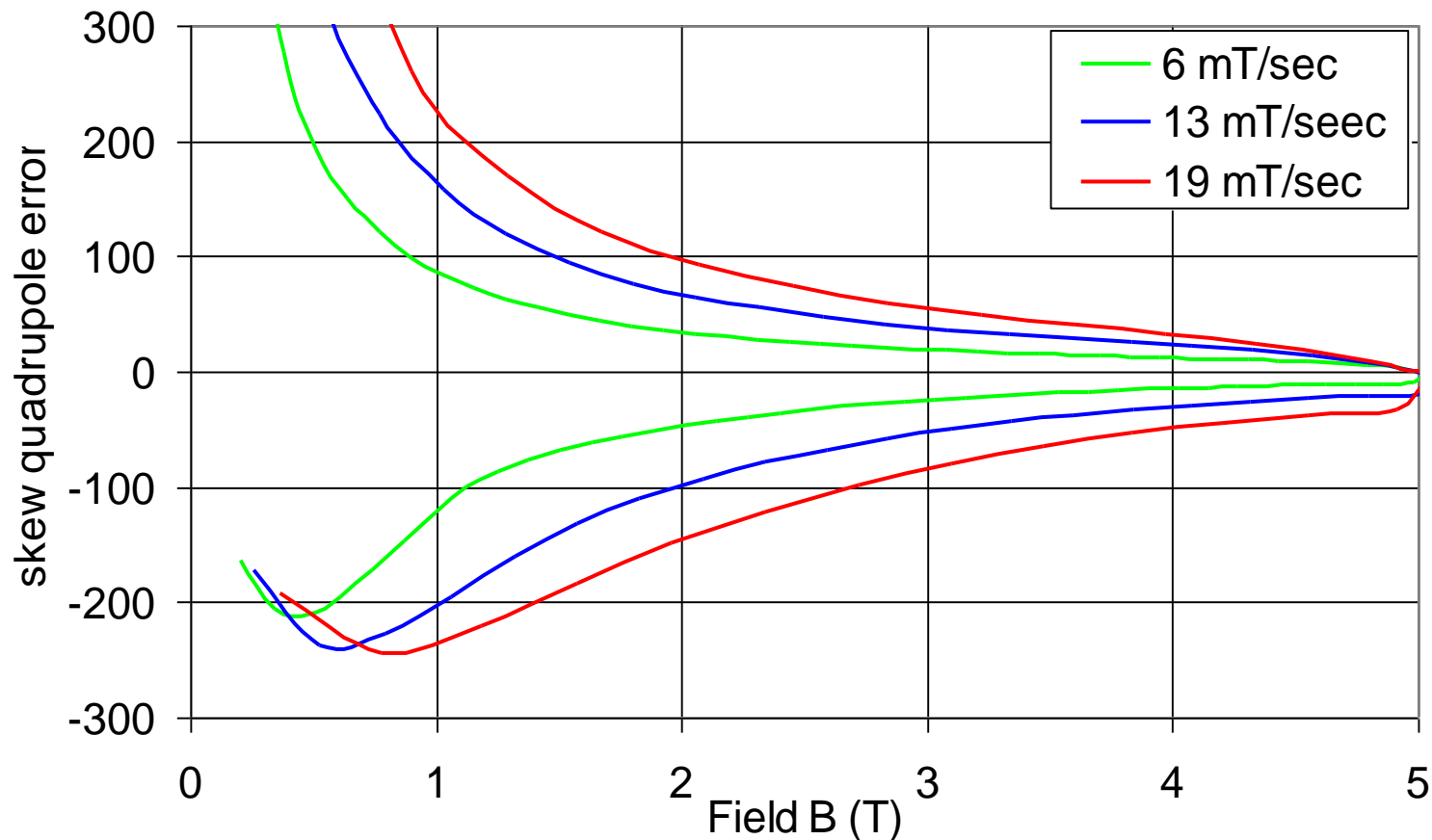
- using a resistive core allows us to increase R_c while keeping R_a the same
- thus we reduce losses but still maintain good current transfer between wires
- not affected by heat treatment



Magnetization and field errors - extreme case

Magnetization is important in accelerators because it produces field error. The effect is worst at injection because

- $\Delta B/B$ is greatest
- magnetization, ie ΔB is greatest at low field



*skew
quadrupole
error in
Nb₃Sn dipole
which has
exceptionally
large
coupling
magnetization
(University of
Twente)*

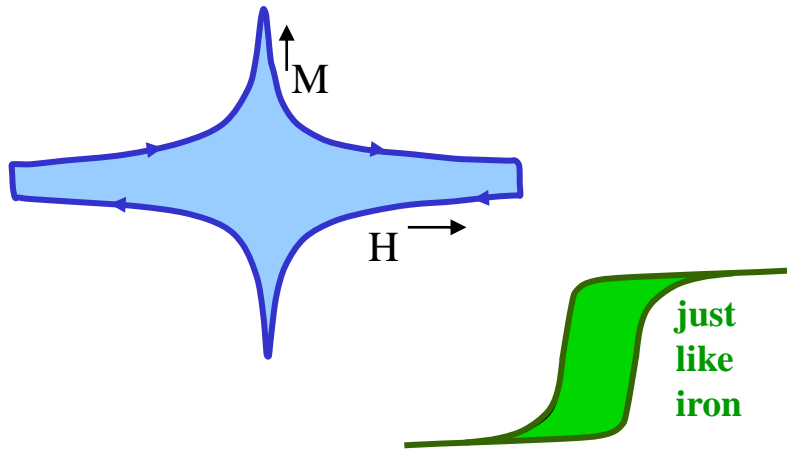
AC Losses

Physics viewpoint

the change in magnetic field energy

$$\delta E = H \delta B$$

(see textbooks on electromagnetism)



so work done on magnetic material

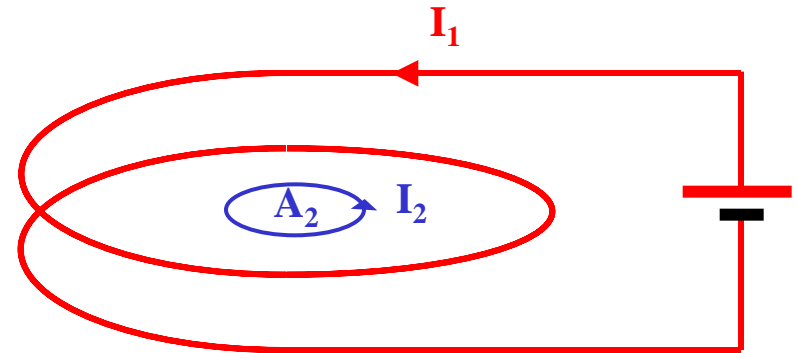
$$W = \int \mu_o H dM$$

around a **closed loop**, this integral must be the energy dissipated in the material

$$E = \int \mu_o H dM = \int \mu_o M dH$$

Engineering viewpoint

element of magnetization represented by current loop I_2



work done by battery to raise current I_1 in solenoid

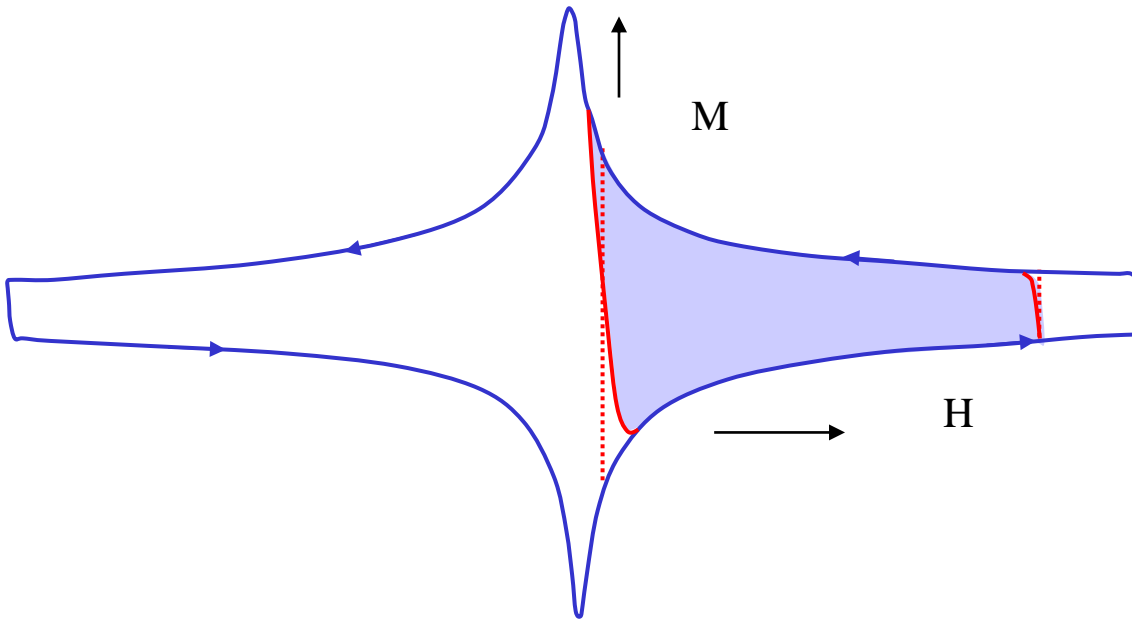
$$\begin{aligned} W &= \int V_1 I_1 dt = \int I_1 L_{11} \frac{dI_1}{dt} dt - \int I_1 L_{21} \frac{di_2}{dt} dt \\ &= \frac{1}{2} L_{11} I_1^2 - \int I_1 L_{21} di_2 \end{aligned}$$

first term is change in stored energy of solenoid
 $I_1 L_{21}$ is the flux change produced in loop 2

$$\int I_1 L_{21} di_2 = \int \mu_o H_1 A_2 di_2 = \int \mu_o H_1 dM_2$$

so work done on loop by battery = $\int \mu_o H_1 dM_2$

Loss Power



With the approximation of vertical lines at the **'turn around points'** and saturation magnetization in between, the hysteresis loss per cycle is

$$E = \oint \mu_o M dH \cong \oint M dB$$

$$W = \int \mu_o H dM = \int \mu_o M dH$$

This is the work done on the sample
 Strictly speaking, we can only say it is a heat dissipation if we integrate round a loop and come back to the same place
 - otherwise the energy might just be stored

Around a loop the red 'crossover' sections are complicated, but we usually approximate them as straight vertical lines (dashed)

In the (usual) situation where $dH \gg M$, we may write the loss between two fields B_1 and B_2 as

$$E \cong \int_{B_1}^{B_2} M dB$$

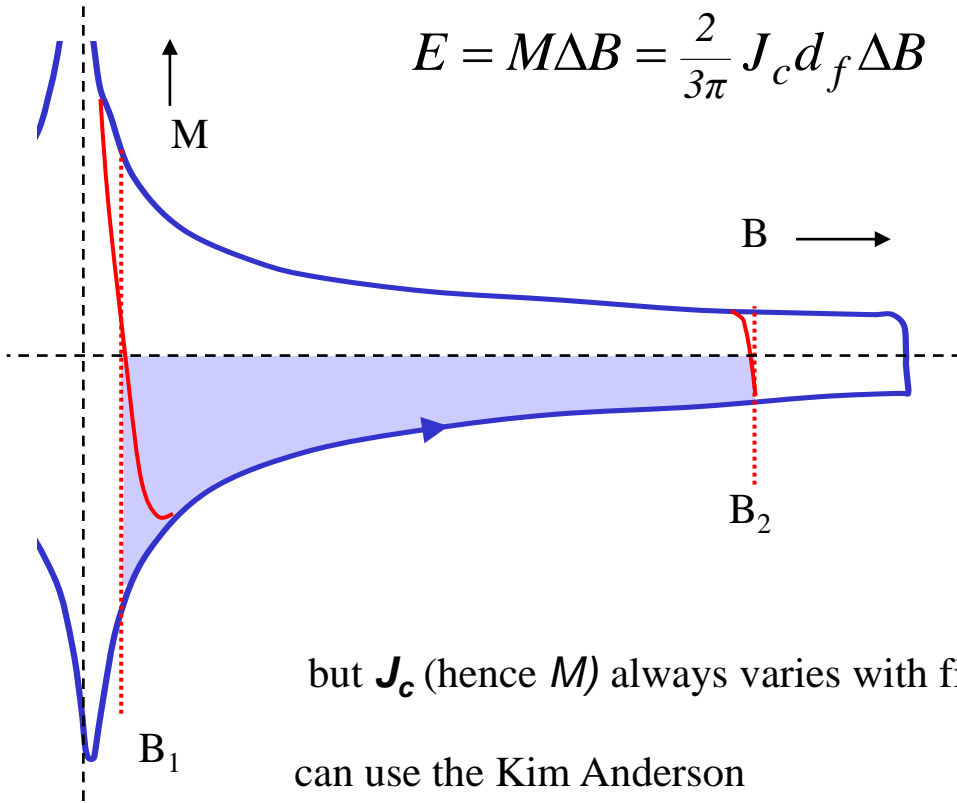
so the loss power is $P = M\dot{B}$

M in $A.m^{-1}$, B in Tesla, losses in $Joules.m^{-3}$ and $Watts.m^{-3}$ of superconductor

Hysteresis loss within in the superconducting filaments

with constant J_c $M = \frac{2}{3\pi} J_c d_f$

$$E = M\Delta B = \frac{2}{3\pi} J_c d_f \Delta B$$



but J_c (hence M) always varies with field

can use the Kim Anderson approximation

$$J_c(B) = \frac{J_o B_o}{(B + B_o)}$$

so $M = \frac{2}{3\pi} d_f \frac{J_o B_o}{(B + B_o)}$

$$E \cong \int_{B_1}^{B_2} M dB$$

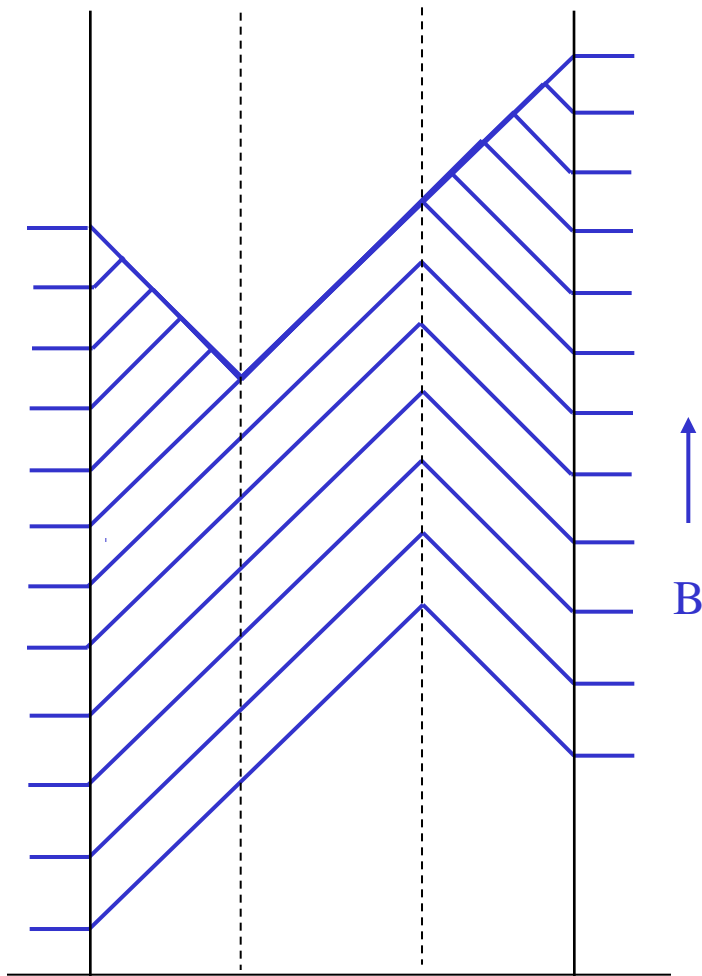
loss for ramp up from B_1 to B_2

$$E = \frac{2}{3\pi} \int_{B_1}^{B_2} \frac{J_o B_o}{(B + B_o)} d_f dB$$

$$E = \frac{2}{3\pi} d_f J_o B_o \ln \left\{ \frac{B_2 + B_o}{B_1 + B_o} \right\}$$

loss in Joules per m^3
of superconductor

The effect of transport current



plot field profile across the slab

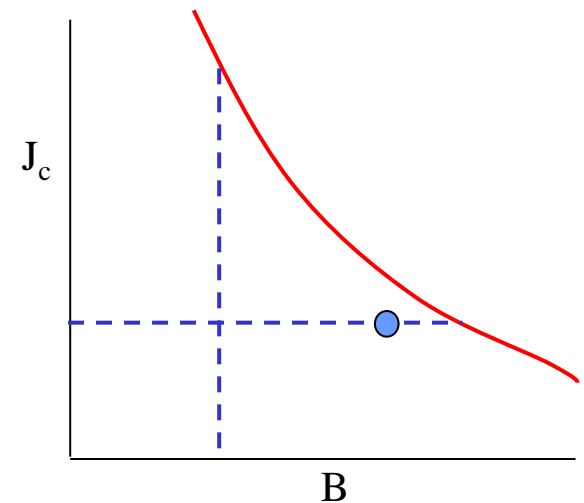
- in magnets there is a transport current, coming from the power supply, in addition to magnetization currents.
- because the transport current 'uses up' some of the available J_c the magnetization is reduced.
- but the loss is increased because the power supply does work and this adds to the work done by external field

total loss is increased by factor $(1+i^2)$ where $i = I_{max} / I_c$

$$E = \frac{2}{3\pi} d_f J_o B_o \ln \left\{ \frac{B_2 + B_o}{B_1 + B_o} \right\} (1+i^2)$$

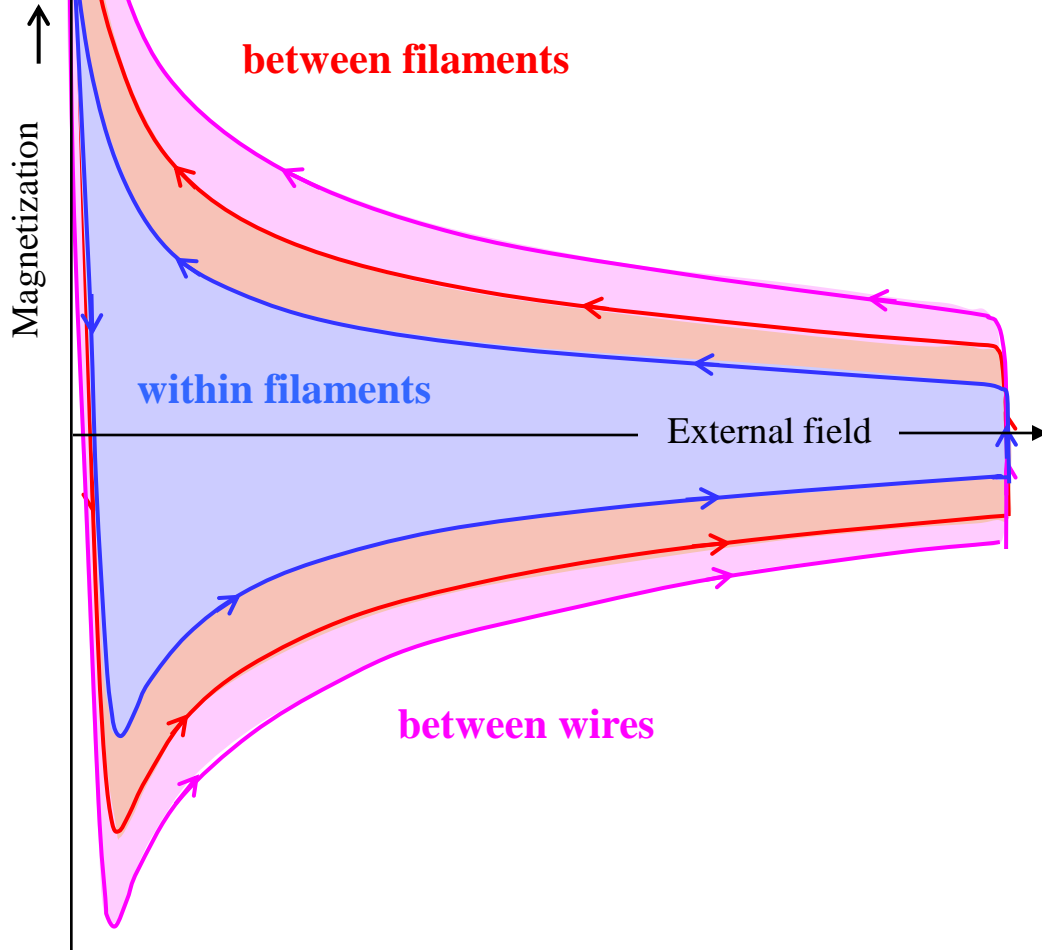
usually not such a big factor because

- *design for a margin in J_c*
- *most of magnet is in a field much lower than the peak*



AC losses from coupling

$P = \dot{B}M$ also applies to magnetization coming from coupling



1) Coupling between filaments within the wire

$$P_e = \lambda_{wu} \dot{B}^2 \frac{l}{\rho_t} \left[\frac{p_w}{2\pi} \right]^2$$

2) Coupling between wires in the cable

$$P_{tc} = \lambda_{cu} \frac{1}{120} \frac{\dot{B}_t^2}{R_c} \frac{c}{b} p_c N(N-1)$$

$$P_{ta} = \lambda_{cu} \frac{1}{6} \frac{\dot{B}_t^2}{R_a} p_c \frac{c}{b}$$

$$P_{pa} = \lambda_{cu} \frac{1}{8} \frac{\dot{B}_p^2}{R_a} p_c \frac{b}{c}$$

Summary of losses - per unit volume of winding

1) Persistent currents in filaments

power W.m^{-3}

$$P_f = \lambda_{su} M_f \dot{B} = \lambda_{su} \frac{2}{3\pi} J_c(B) d_f \dot{B}$$

loss per per ramp J.m^{-3}

$$E_f = \lambda_{su} \frac{2}{3\pi} d_f J_o B_o \ln \left\{ \frac{B_2 + B_o}{B_1 + B_o} \right\}$$

where λ_{su} , λ_{wu} , λ_{cu} = fractions of superconductor, wire and cable in the winding cross section

2) Coupling currents between filaments in the wire

power W.m^{-3}

$$P_e = \lambda_{wu} M_e \dot{B} = \lambda_{wu} \frac{\dot{B}^2}{\rho_t} \left(\frac{p}{2\pi} \right)^2$$

3) Coupling currents between wires in the cable

transverse field crossover
resistance power W.m^{-3}

$$P_{tc} = \lambda_{cu} \frac{1}{120} \frac{\dot{B}_t^2}{R_c} p \frac{c}{b} N(N-1)$$

transverse field adjacent
resistance power W.m^{-3}

$$P_{ta} = \lambda_{cu} \frac{1}{6} \frac{\dot{B}_t^2}{R_a} p \frac{c}{b}$$

don't forget the filling factors

parallel field adjacent
resistance power W.m^{-3}

$$P_{pa} = \lambda_{cu} \frac{1}{8} \frac{\dot{B}_p^2}{R_a} p \frac{b}{c}$$

Concluding remarks

- screening currents produce magnetization (magnetic moment per unit volume)
 - ⇒ lots of problems - field errors and ac losses
- in a synchrotron, the field errors from magnetization are worst at injection
- we reduce magnetization by making fine filaments - for practical use embed them in a matrix
- in changing fields, filaments are coupled through the matrix ⇒ increased magnetization
 - reduce it by twisting and by increasing the transverse resistivity of the matrix
- accelerator magnets must run at high current because they are all connected in series
 - combine wires in a cable, it must be fully transposed to ensure equal currents in each wire
- wires in cable must have some resistive contact to allow current sharing
 - in changing fields the wires are coupled via the contact resistance
 - different coupling when the field is parallel and perpendicular to face of cable
 - coupling produces more magnetization ⇒ more field errors
- irreversible magnetization ⇒ ac losses in changing fields
 - coupling between filaments in the wire adds to the loss
 - coupling between wire in the cable adds more

never forget that magnetization and ac loss are defined per unit volume - filling factors