Imperial College London



### MICE Tracker Software

### A. Dobbs CM32 9<sup>th</sup> Feb 2012







### Outline

- Software requirements
- Data flow
- Framework
- Configuration and geometry
- Monte Carlo
- Digitisation
- Reconstruction
- A few results
- Conclusion

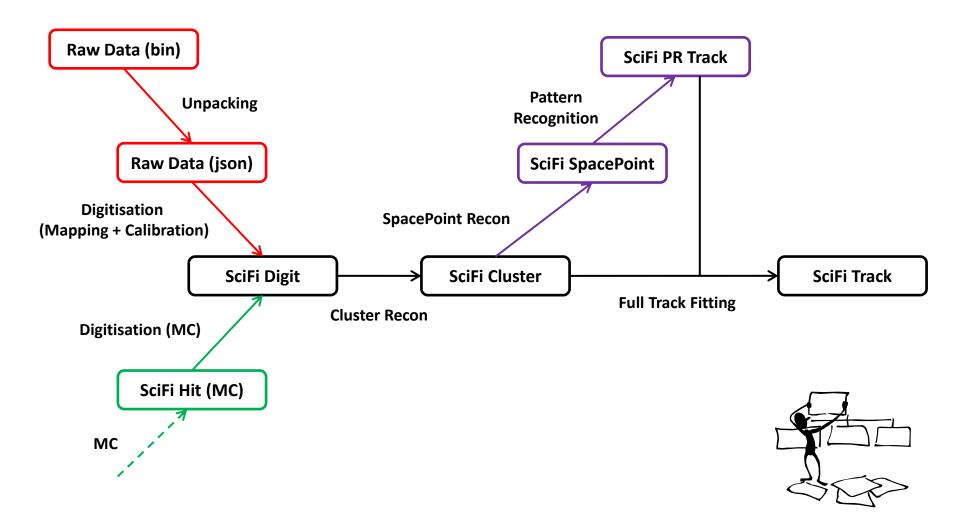


### Software requirements

- Built within MAUS framework
- Unpack real data from DAQ using MAUS unpacker
- Digitise real data
- Create reasonable Monte Carlo data
- Digitise MC data
- Reconstruct MC and real data
- Final output: particle tracks in JSON format for use by the Analysis group



### Data flow





### Framework

- C++ class based system
- Single interface to JSON format data provided on a spill-byspill basis by MAUS
- Interface currently being used written by Ed, to be replaced with interface written by Alex Richards when ready (JSON ⇔ C++ ⇔ ROOT)
- 3 *mappers* used in MAUS to call tracker algorithms:
  - Real data digitisation
  - MC digitisation
  - Reconstruction
- Geometry and Configuration data to be extracted from CDB



## **Configuration and Geometry**

- Currently using data from Mice Modules in legacy G4MICE code in MAUS
- This needs verifying or replacing (believed to be effecting reconstruction efficiency)
- Final system is to query CDB and pull down config data for relevant run / data / etc
- Uses an API either based on Python with C++ wrapper or possibly a native C++ interface using SOAP to CDB
- Data is then stored in memory as classes (Geometry class, Configuration class, etc)
- Team of Oleg, Ken, Anthony, and Matt Robinson





### Monte Carlo

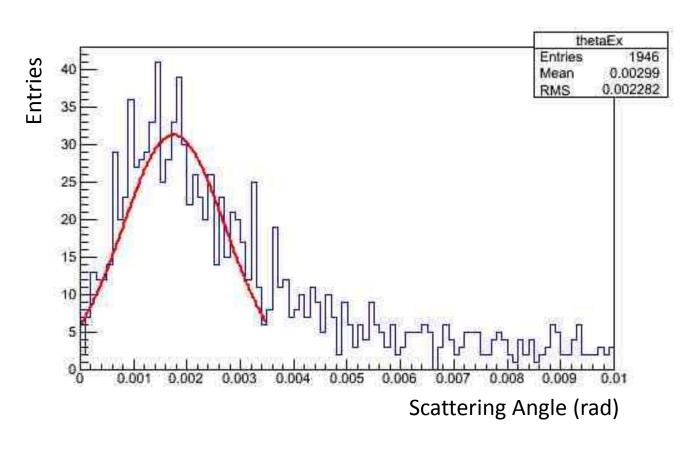


- MC produces SciFiHits (truth) which has been reconstructed up to SciFiDigits...
- ... but displays some strange features
   Hits distribution in stations is odd
  - Some questions over energy deposition
  - Current suspicion is that problem lies in the digitisation...
- Paul Kyberd leading the effort with Anastasia and Stefania (+ Ed + Me)



### MC Scattering Analysis Very Preliminary!

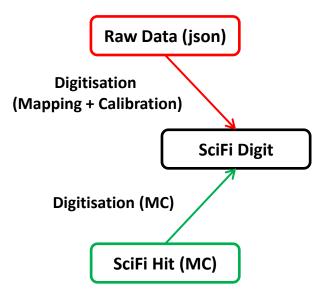
by Paul Kyberd



- Gaussian fit in red, mean of 1.75 mrad
- RMS of the whole distribution is 2 mrad
- Calculation based on the Gaussian approx to the ms is 1.90 mrad
- Tail expected from physics and the way plot was produced
  - Agreement is surprisingly (suspiciously?) good

### Digitisation

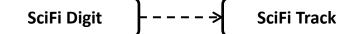
- Real data unpacking, mapping and calibration all working and producing SciFiDigits...
- ...although mapping and calibration will probably need to be redone when we move to MICE hall
- MC SciFiHits also producing SciFiDigits but remains suspect

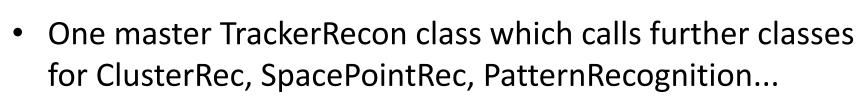






### Reconstruction





- These operate on container classes such as SciFiDigits, SciFiClusters, SciFiSpacePoints...
- Bundled together in a SciFiEvent class
- Working all the way up to space points and (almost) in the trunk (great effort from Ed Santos)
- Pattern Recognition starting to produce first straight tracks in class based framework



SciFi SpacePoint

### **Cluster and SP Recon**



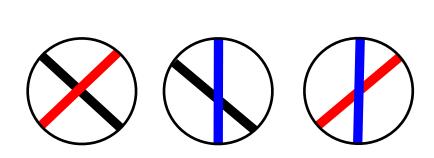
### SciFi Plane



~10% region of overlap:

Muons crossing in this region will deposit energy in two different channels. We must sum the energy deposit in both before applying cuts based on the number of photo electrons

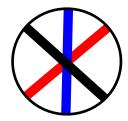
 $\rightarrow$  Clustering



**SpacePoint Recon** 

**SciFi Cluster** 

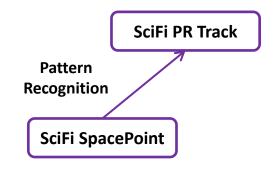
The position of a space-point is calculated by averaging the crossing position of the 3 possible cluster combinations.





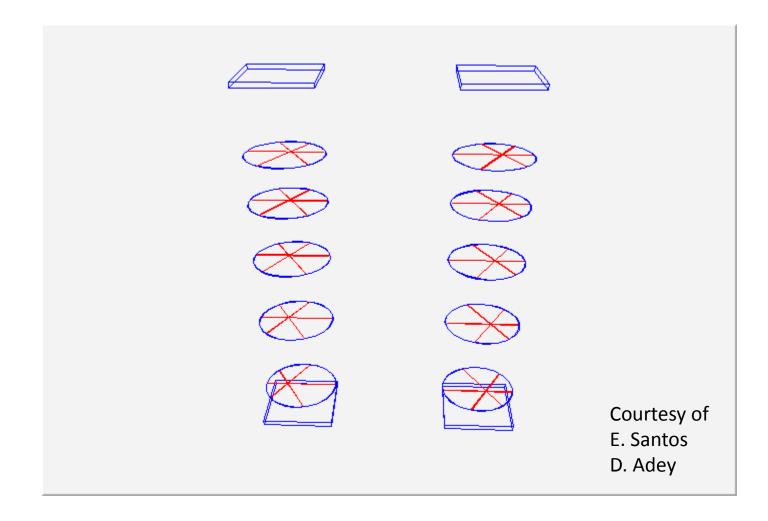
# Pattern Recognition (Straight)

- Draw a straight line between pair of space points in outer and inner most stations
- Check how far space points in intermediate station vary from the line ("road cuts")
- If enough points pass the road cuts, fit a line (linear least squares) with best matches
- If fit passes chi^2 test, accept track
- Loop round again using unused space points



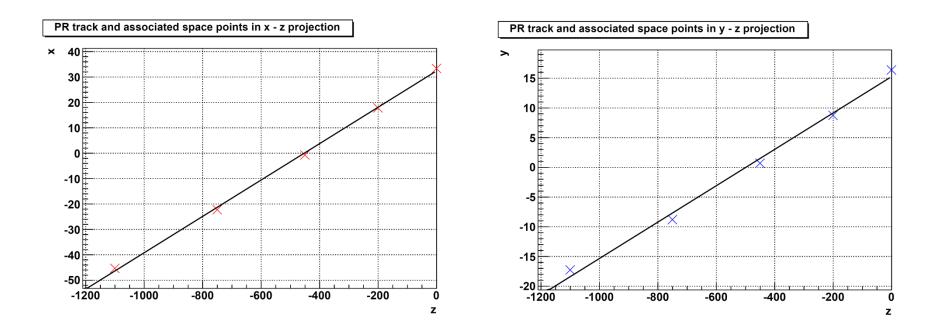


### Some Results: SP Visualisation





### Some Results: Cosmic PR



Black lines are 5 point Pattern Recognition tracks and the crosses are the space points used to form them. Units of [mm] in tracker coordinate system.



### Conclusion

- Tracker software is proceeding well
- Lots of progress since last CM
- Geometry and Configuration needs to be validated, finished and then used
- MC needs to be validated / fixed
- Proceed with implementing higher level reconstruction

# Thanks

- David Adey
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- Stefania Riccardi
- Alex Richards
- Chris Rogers
- Ed Santos
- Anthony Wilson



