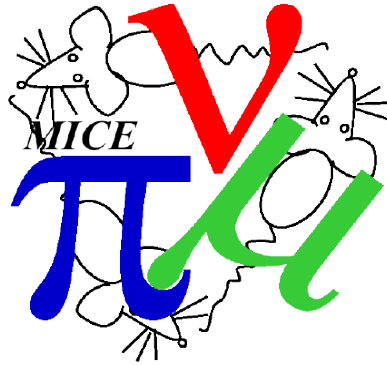




# MAUS – Analysis Issues

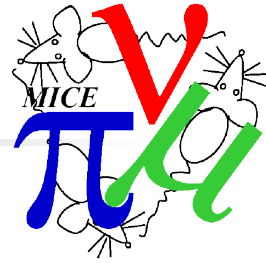
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Chris Rogers,  
ASTeC,  
Rutherford Appleton Laboratory

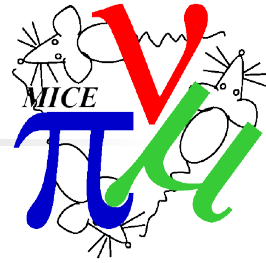


# MAUS Items for Analysis



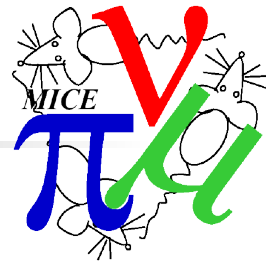
- Analysis group are interested in certain items in MAUS
  - Data structure + representation
    - Interface to analysis
  - Routines for generating Monte Carlo data sets
    - Used for doing truth vs recon studies
- Analysis group owns certain items in MAUS
  - Global reconstruction
  - Cooling channel geometry
  - Online tools for tuning the accelerator
- Go through these one by one

# Data Representation



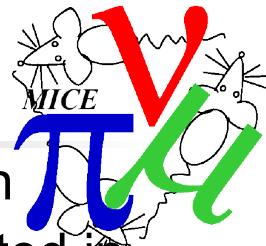
- Data currently represented in json
  - No way to enforce any structure
  - Developers can e.g. change the data structure during reconstruction
  - No way to enforce conventions
    - Like “all Space Points should have (x,y,z,time) field”
  - Some concerns over file size, access speed
    - Can probably be addressed using native json, e.g. use some compression routine
  - Naturally leads away from good practice – encapsulation, etc
- Propose using a ROOT data tree
  - More conventional
  - Maintain json functionality

# Data Structure



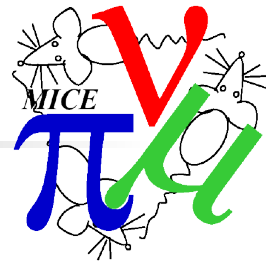
- Active discussion of how data is structured in MAUS
- Do we split into particle events after unpacking?
- Do we split into particle events after detector reconstructions?
- Do we group by reconstruction “stage“ or by detector
- Needs to be closed out and implemented by March run
  - Looks potentially tight
- Non-controversial
  - Add some metadata to the structure e.g. what run, what configuration, etc...

# Batch Production



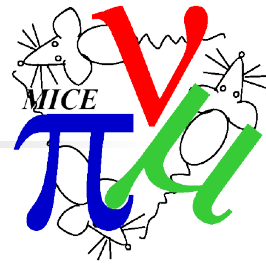
- Propose a batch production job for MC and Reconstruction
  - After a stage of settling analysis users won't be interested in details of this or that reconstruction routine
  - Nice to have “official” recon data sets for analysis
- Will be done on GRID
  - Automatically trigger as data is taken
  - Use a reference version which may not be the latest – chosen by analysis group
  - Rerun over data sets for new code version/calibration/etc can be requested by analysis group
- Needs (by mid-March):
  - GRID setup – okay
  - Input beam (next slide) – unlikely, workaround possible
  - Geometry import – at risk
  - Digitisation of TOF and other detectors - okay
  - ROOT IO and data structure – at risk

# Input Beam (g4bl)



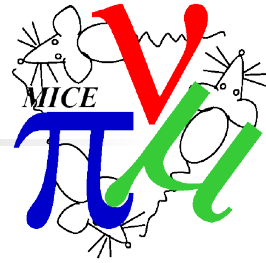
- I think we use G4BL for input beam to batch production
  - Need reasonable rate and time distribution
    - For multiparticle effects (pile up, dead time)
    - For tracker dead time model
  - Extract rate from GVA1
    - Fit to binomial distribution?
  - Extract time distribution in each spill from fit to TOF0 t
    - Fit to some exponential distribution? Saw tooth?
  - Means we need to do reconstruction job and then use reconstructed GVA1 and TOF0 to do the Monte Carlo
    - Circular dependency is unpleasant
      - Use recon as input to MC which is used to understand recon... urg...
    - Is there a better way?

# Geometry Responsibility

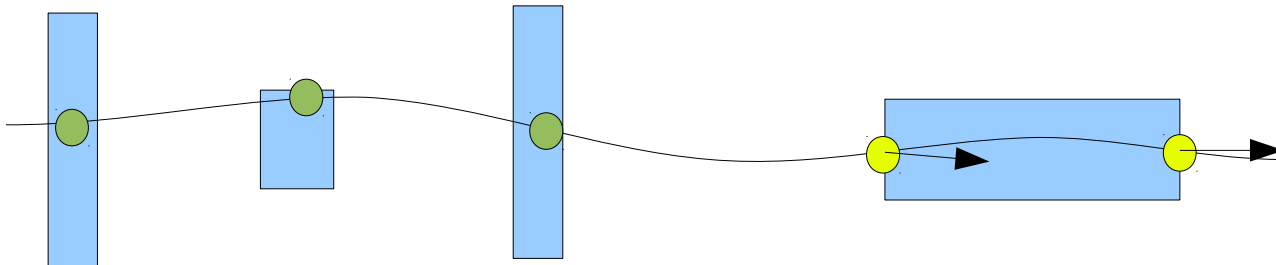


- We have a set of routines for pulling geometry from a reduced CAD model of MICE
- It needs someone to check that the geometry physics is correct
  - Detectors are responsible for checking that their geometry is correct
  - Beamline expert is responsible for checking geometry and fields in beamline is correct
  - Analysis group is responsible for checking cooling channel geometry and fields are correct
- Geometry release cycle goes like
  - CAD release from Jason Tarrant
  - Converted into Geant4 readable and uploaded to ConfigDB
  - Checked by experts
  - Tagged as a release of new geometry
- First attempt will follow survey being taken right now

# Global Recon

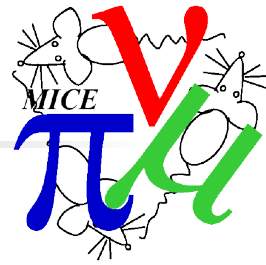


- We have some set of measured space points (TOF), tracks (tracker), Light yields (EMR, KL, Ckov) with some set of errors
- How do we tie these things together?
- Two somewhat separate things:
  - Track fitting
  - PID



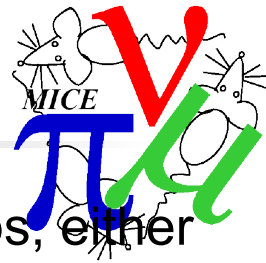


# Basic specification



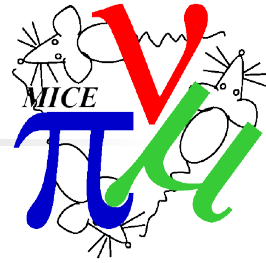
- We seek to get the following variables
  - $x, y, z, \text{time}$
  - $p_x, p_y, p_z, \text{energy}$
  - Preferred pid (gives charge, mass, etc)
  - On user-defined planes – typically spacial planes, probably not z-planes
    - Engineering geometry has  $x$  as the beam axis
- We seek errors
  - Covariance matrix of errors in ( $x, y, \text{time}, p_x, p_y, \text{energy}$ )
    - E.g. say we know  $x$  exactly but  $p_x$  we have some error
    - Propagate that measurement and we find we introduce uncertainty in  $x$
    - In fact there is a correlation between the  $x$ - $p_x$  uncertainty
    - Encode as a “covariance matrix”
  - $p(\text{electron}), p(\text{muon}), p(\text{pion})?$   $\sigma(\text{mass})?$  Not sure how to write down error in pid

# Track/Error propagation



- We can already do Runge Kutta through arbitrary field maps, either using G4 or custom tracking routines
- We can already calculate transfer matrices through arbitrary field maps
  - Numerical differentiation of the tracking
    - Generate a few different tracks
    - Do  $u_{\text{out}} = M u_{\text{in}}$
    - We can use G4 to calculate  $u_{\text{out}}$  from  $u_{\text{in}}$
    - We can solve as a simultaneous equation for **M**
  - Second order correction implemented and works
  - Direct integration not implemented but could be
- All implemented in Optics routines
  - Needs significant clean up and testing

# Next Steps

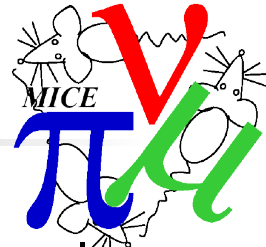


- Specification document is in progress
  - Aim to have first draft ready next week at software workshop
- Definition of data structure
- Definition of class structure
  - We already have some optics infrastructure in place, currently in a tidy-up phase
- Seek comments early and often
  - I am a novice – analysis experts in MICE have done it all before

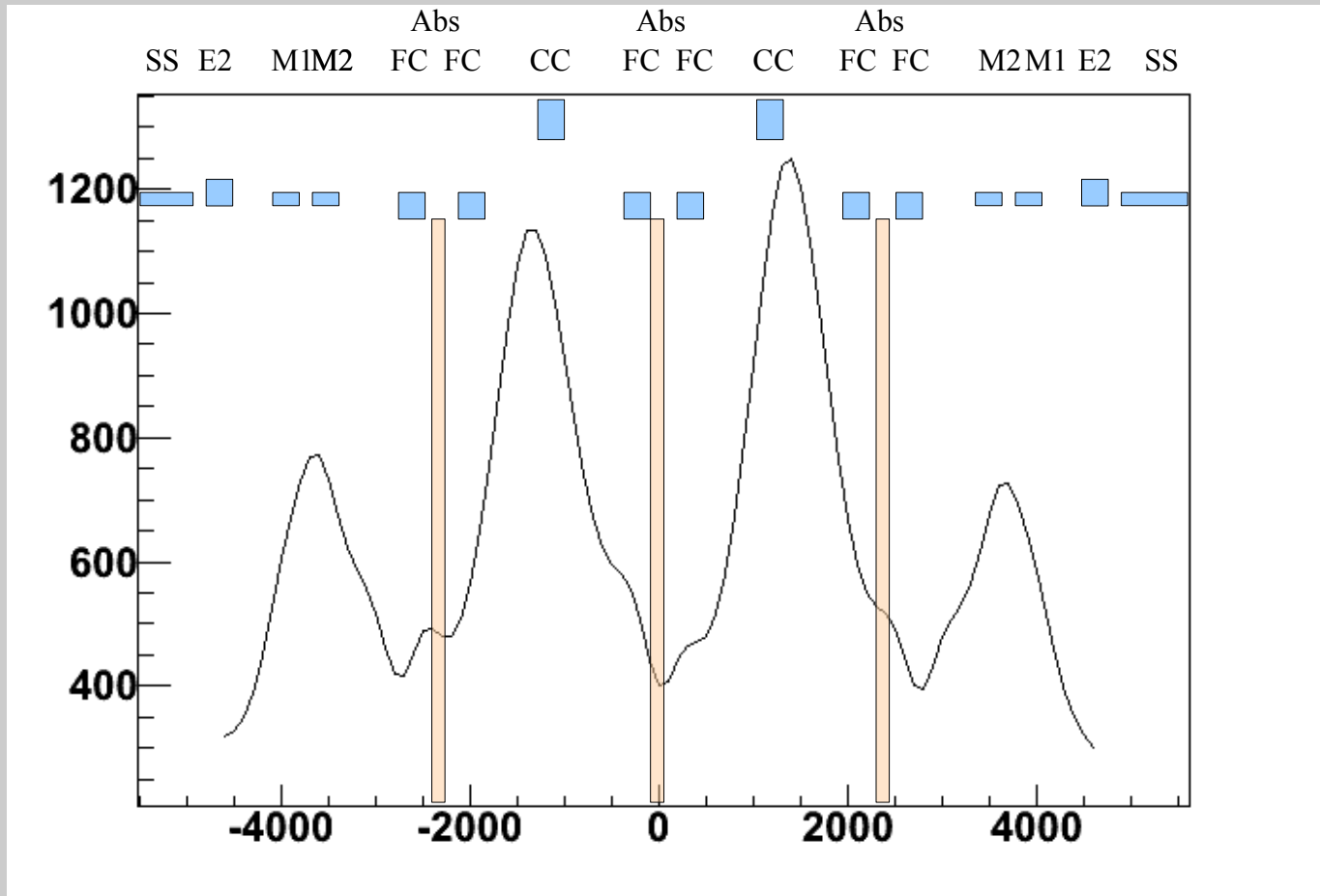


# Optics Tool

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- Request was made for a light weight tool to evolve beam envelopes for use in control room
- Propose following tool
  - (powerpoint prototype of a GUI)
  - Allows to define a set of magnet currents and input beam
  - Then plot resultant beam envelope, momenta, etc down the accelerator
  - Geometry shown is Stage 6 geometry
  - In principle we should be able to handle any geometry e.g. would hope to include Q4-9, etc
- Seek comments



Beam

Z (mm)  definition  ▼

beta (mm)

alpha

em. (mm)

Beamline

E1 (A)  M1 (A)

SS (A)  M2 (A)

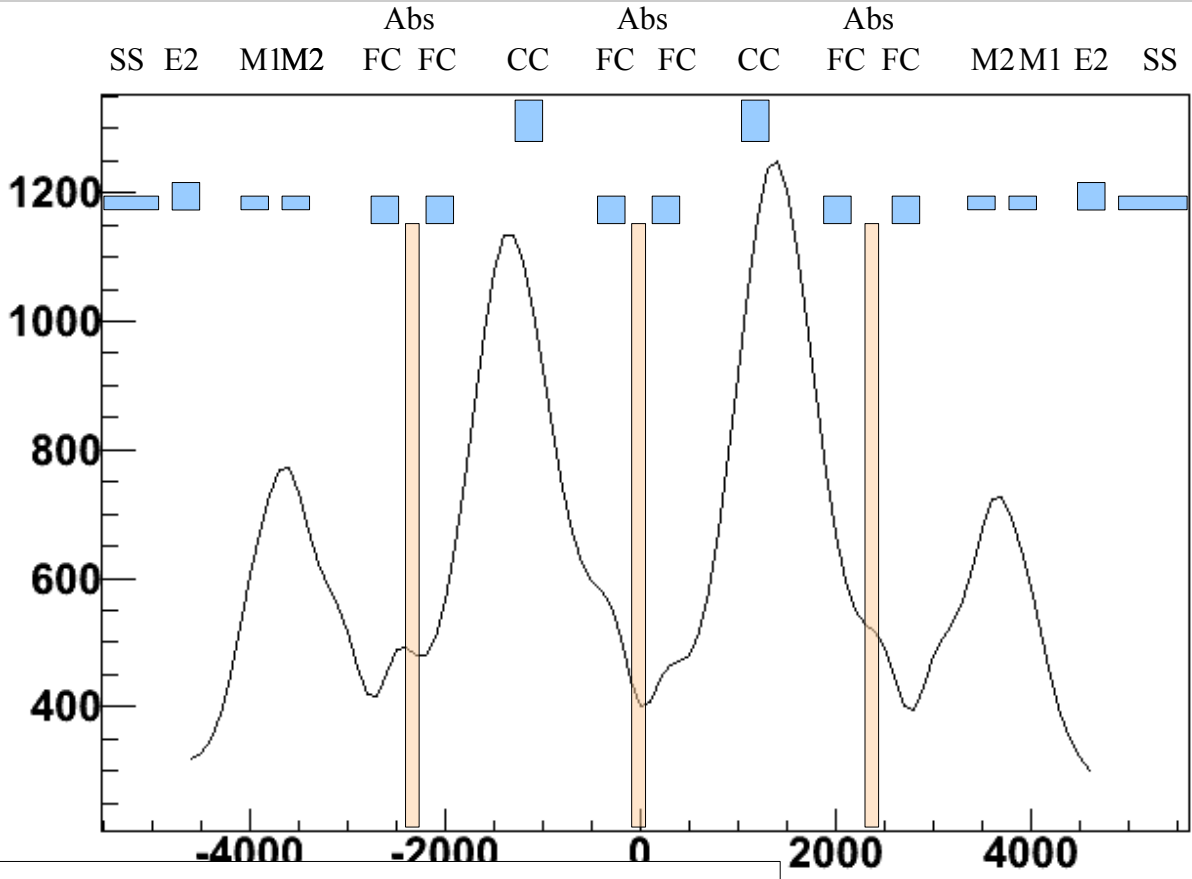
E2 (A)  FC (A)

CC (A)

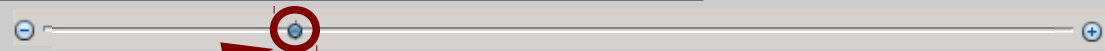
Plot

ordinate  ▼

Show optical elements



Slider or text input to define beam z-position



Beam

Z (mm)  definition  ▼

beta (mm)

alpha

em. (mm)

Beamline

E1 (A)  M1 (A)

SS (A)  M2 (A)

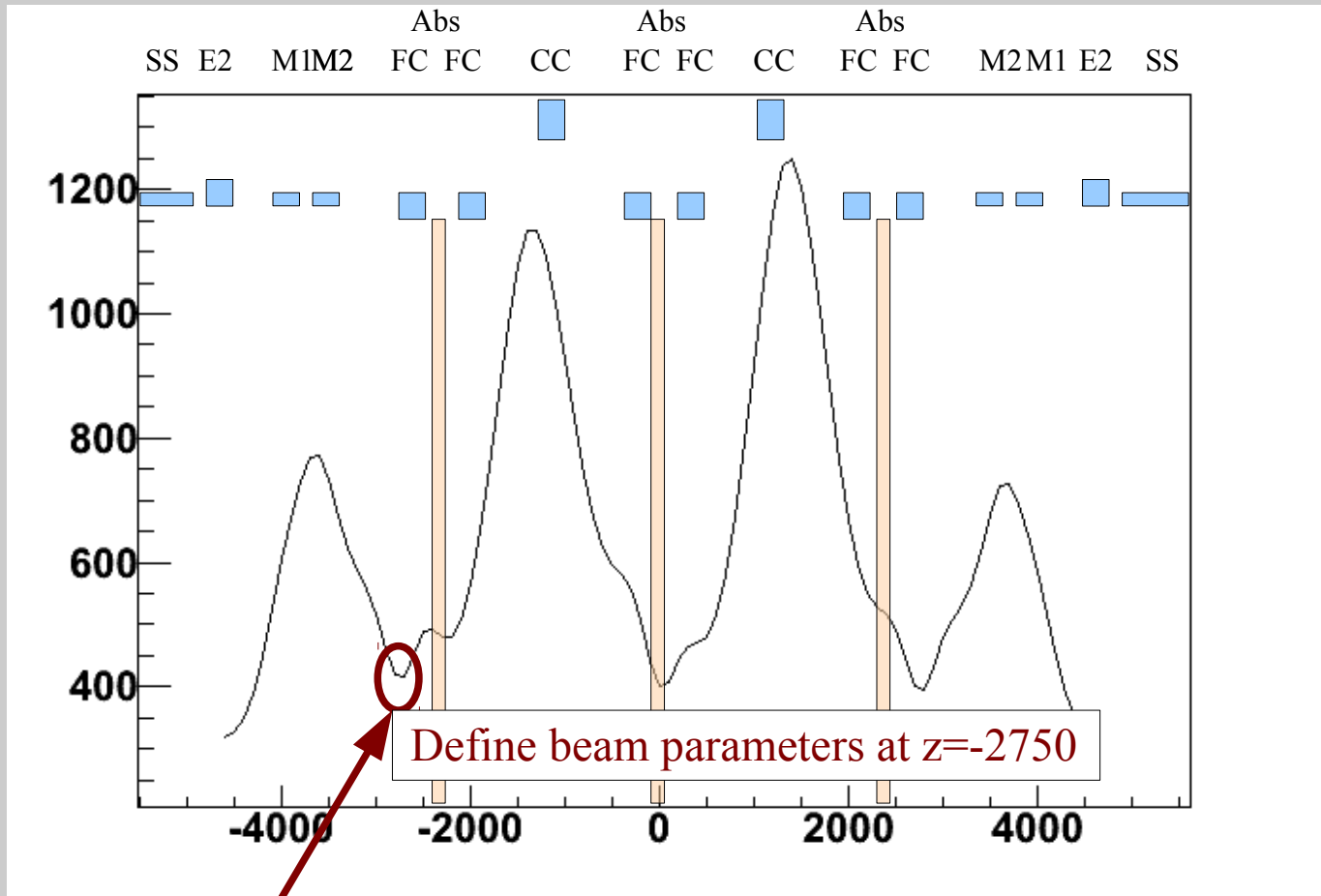
E2 (A)  FC (A)

CC (A)

Plot

ordinate  ▼

Show optical elements



Beam

Z (mm)  definition  ▼

beta (mm)

alpha

em. (mm)

Beamline

E1 (A)  M1 (A)

SS (A)  M2 (A)

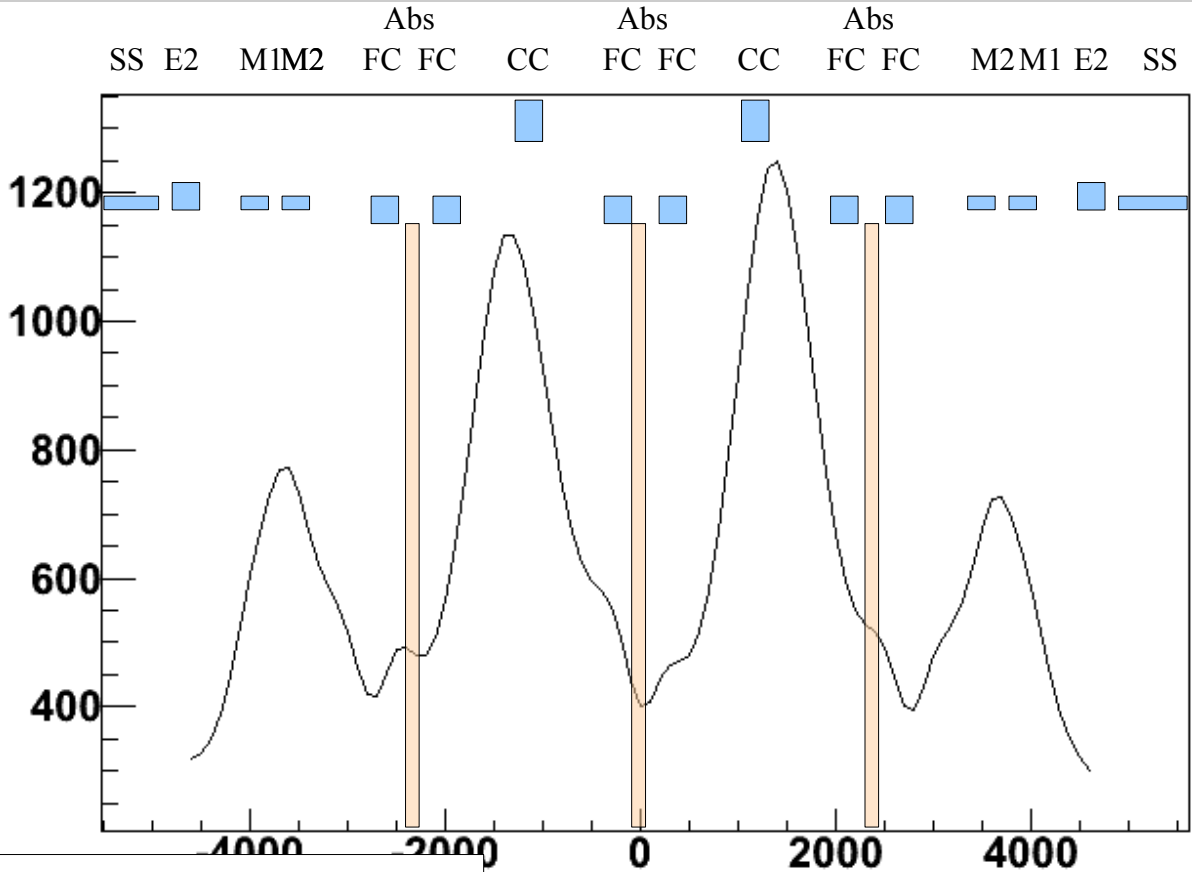
E2 (A)  FC (A)

CC (A)

Plot

ordinate  ▼

Show optical elements



Different beam parameterisations:  
 penn  
 twiss

Z (mm)  definitio  ▼

beta\_x (mm)  beta\_y (mm)

alpha\_x  alpha\_y

em\_x (mm)  em\_y (mm)

Beamline

E1 (A)  M1 (A)

SS (A)  M2 (A)

E2 (A)  FC (A)

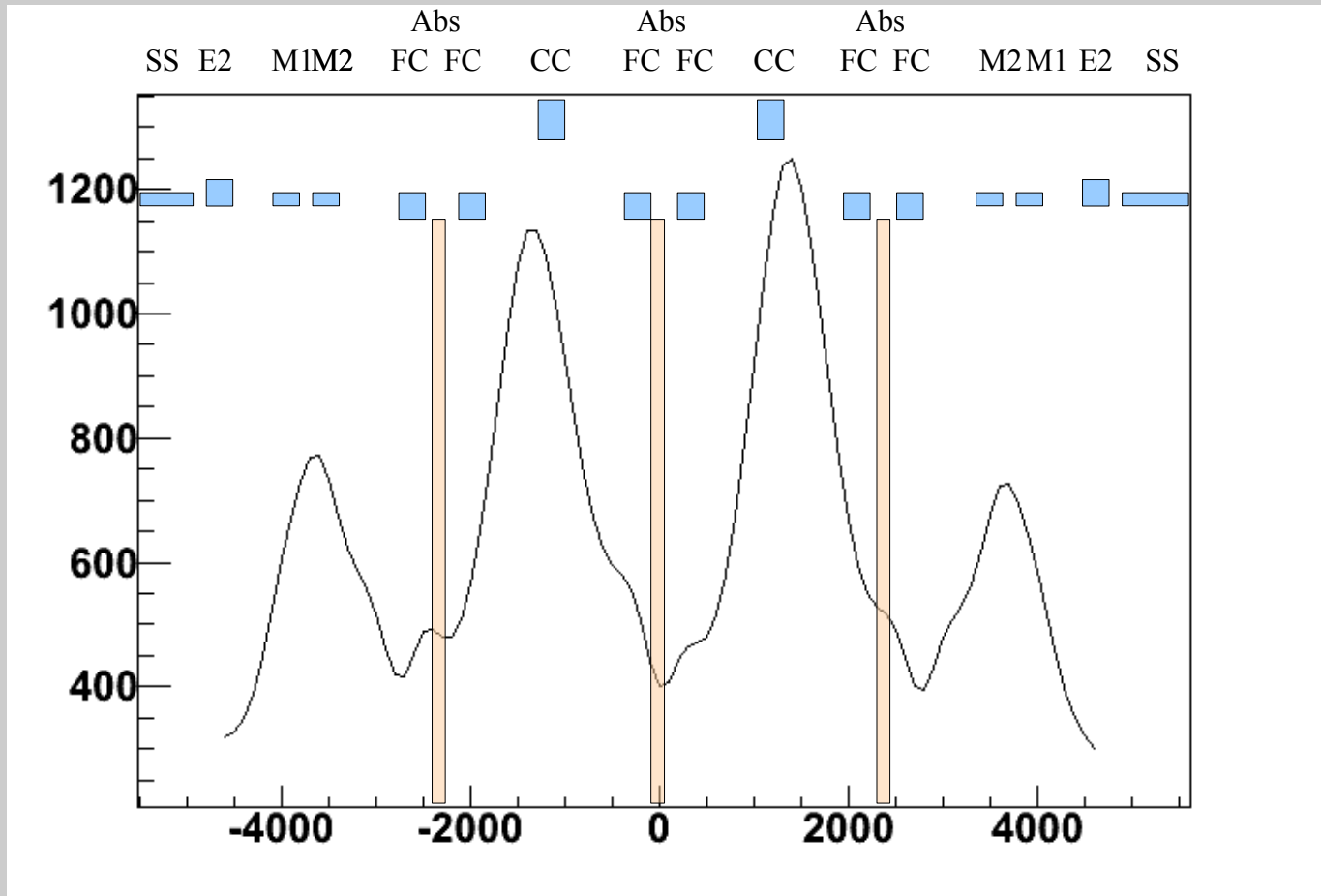
CC (A)

Plot

ordinate  ▼

Show optical elements





Beam

Z (mm)

beta (mm)

alpha

em. (mm)

Control magnet currents  
 •Should use currents like the ones typed into controls  
 PC

0

Beamline

E1 (A) 149.05 M1 (A) 149.05

SS (A) 222.01 M2 (A) 222.01

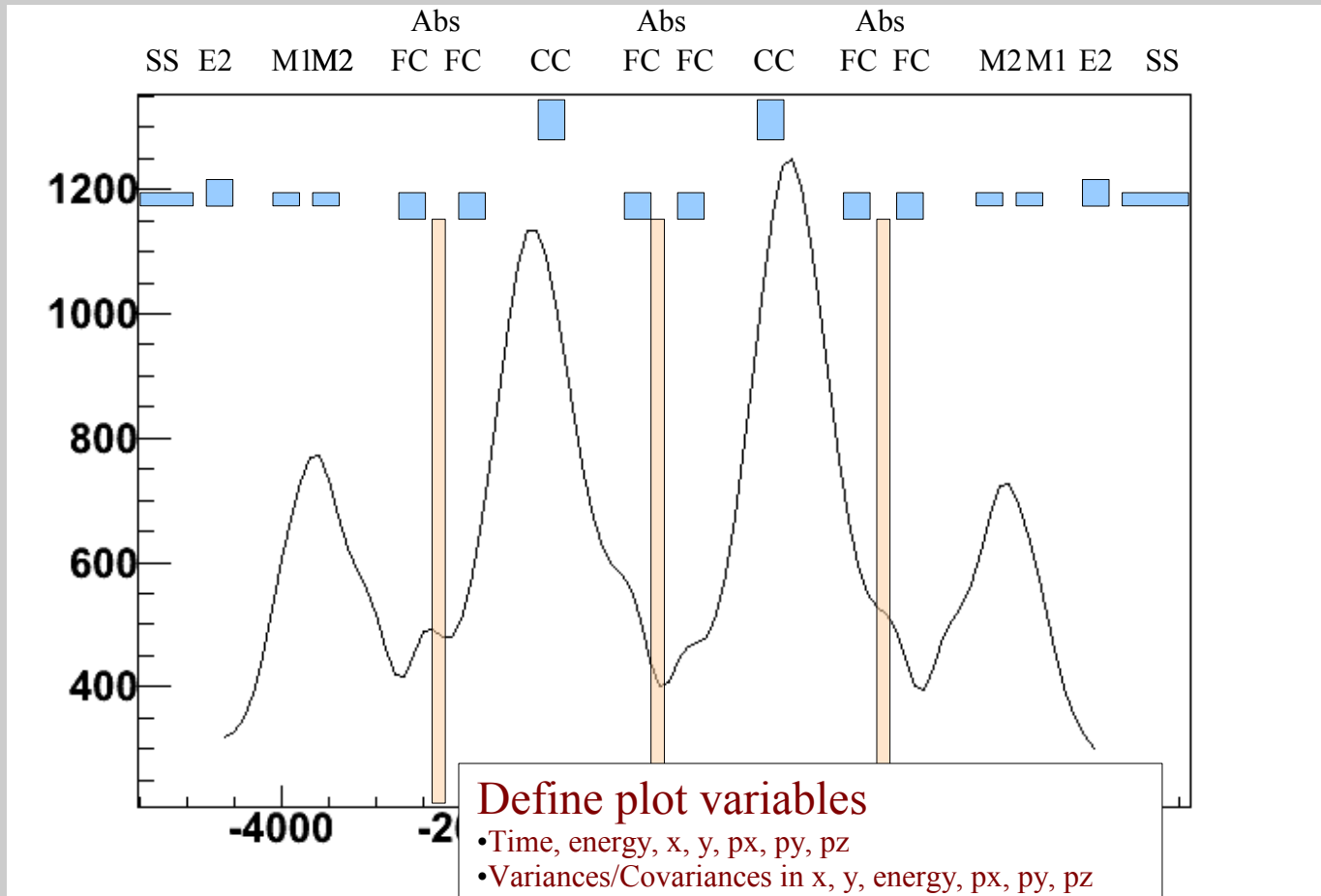
E2 (A) 109.12 FC (A) 109.12

CC (A) 109.12

Plot

ordinate beta\_perp ▼

Show optical elements



Beam

Z (mm)  definition

beta (mm)

alpha

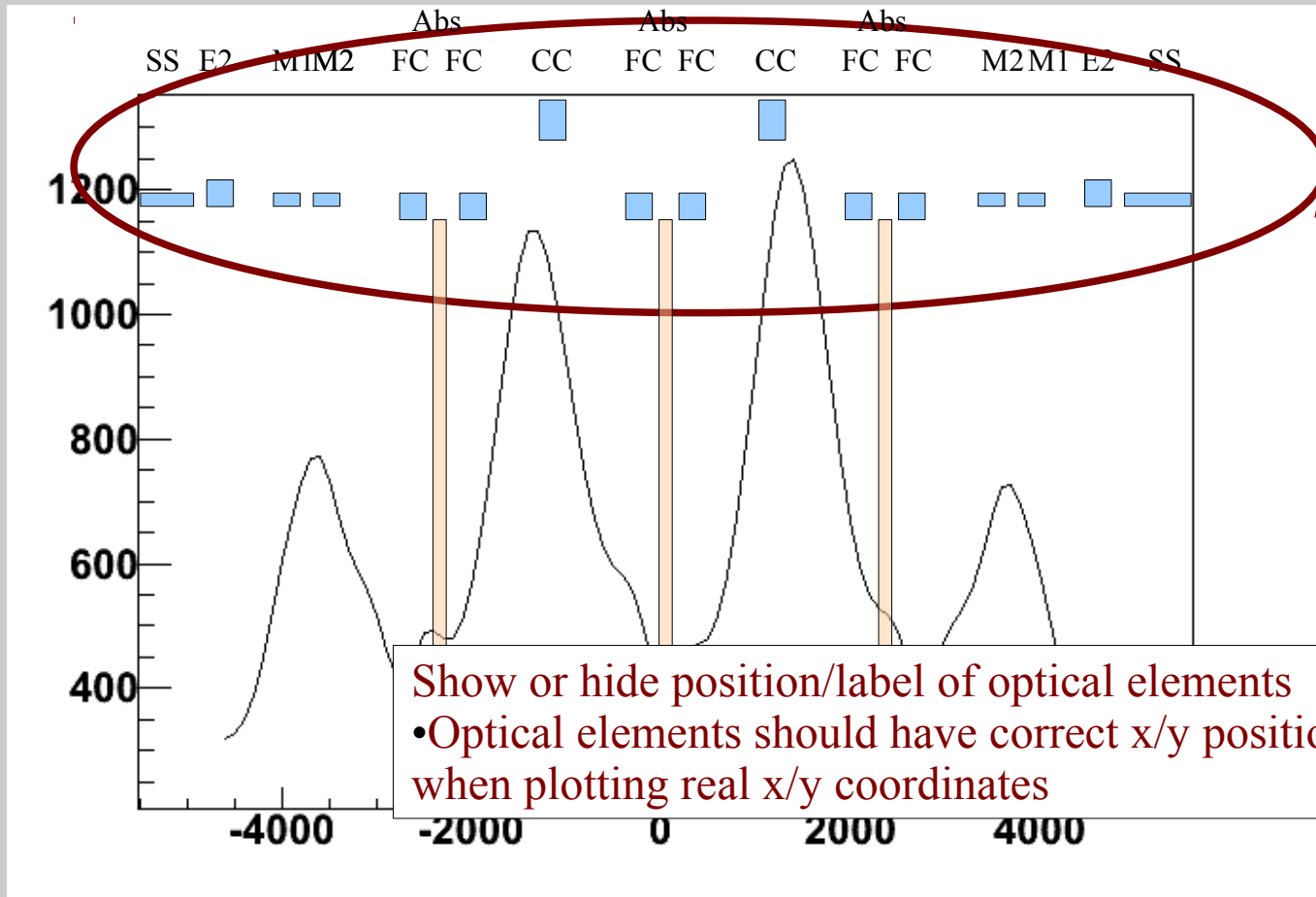
em. (mm)

CC (A)

Plot

ordinate

Show optical elements



Show or hide position/label of optical elements

- Optical elements should have correct x/y position when plotting real x/y coordinates



Beam

Z (mm)  definition  ▼

beta (mm)

alpha

em. (mm)

Beamline

E1 (A)  M1 (A)

SS (A)  M2 (A)

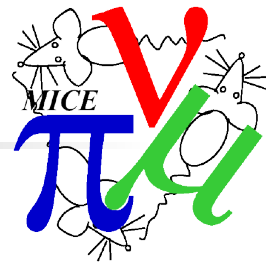
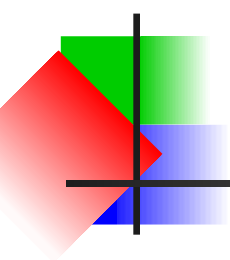
E2 (A)  FC (A)

CC (A)

Plot

ordinate  ▼

Show optical elements



FIN