SuperB SR details

## **Some SuperB IR Details**

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For

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## Outline

- Some extra topics
  - Solenoid compensation
  - HOMs
  - Assembly and Removal
  - Vibrations
  - ?

#### • Summary

#### Simplified detector solenoid model in the IR

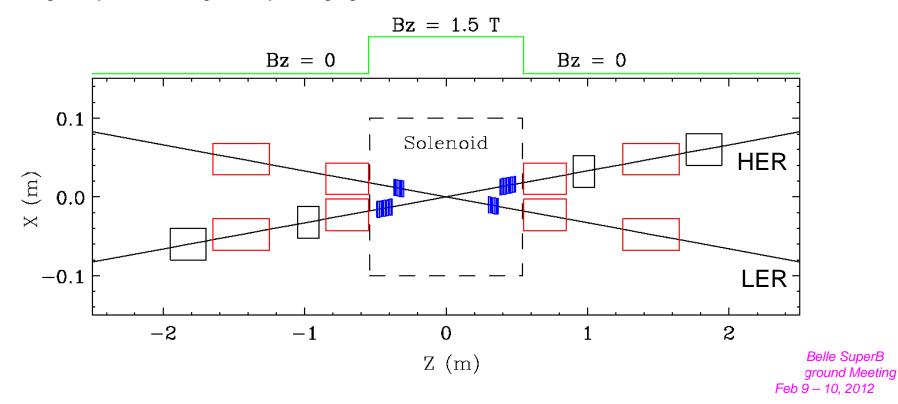
Assumptions and simplifications based on proposed scheme by K. Bertsche and M. Sullivan:

• Detector solenoid field is 1.5 T in the ±55 cm region near IP (between left and right SC cryostats) and cancelled outside of this region by means of compensating solenoids. MAD model:

• Hard edge solenoid is tilted with respect to beams by ±33 mrad (for v.12 crossing angle).

• Overlap of permanent quads and the solenoid is modeled using thin lens quads with thick solenoid slices between them.

Note: Constant solenoid field profile can be easily replaced by a more realistic Z-dependent profile using many slices with gradually changing field.

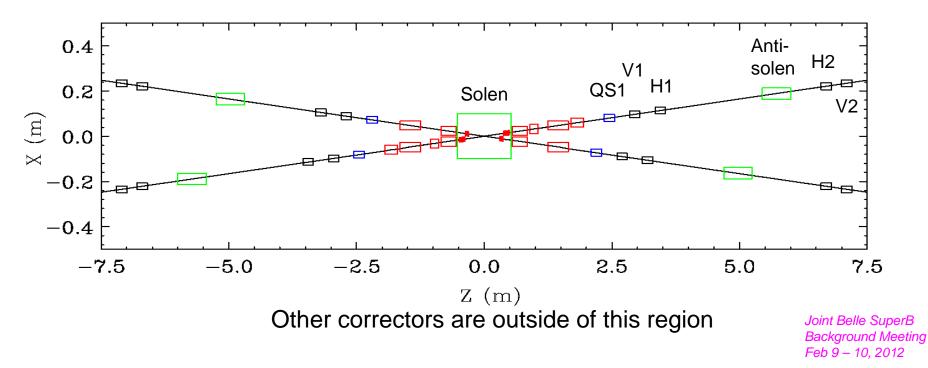


### **Correction system**

The designed correction system compensates each half-IR independently and contains on each side of IP:

- Rotated permanent quads.
- Skew winding on SC quads to simulate rotation.
- SC anti-solenoid of strength 1.5T x 0.55 m aligned with the beam axis.
- 2 vertical and 2 horizontal dipole correctors for orbit correction.
- 4 skew quads at non-dispersive locations for coupling correction.
- 2 skew quads at dispersive locations for correction of vertical dispersion and slope.

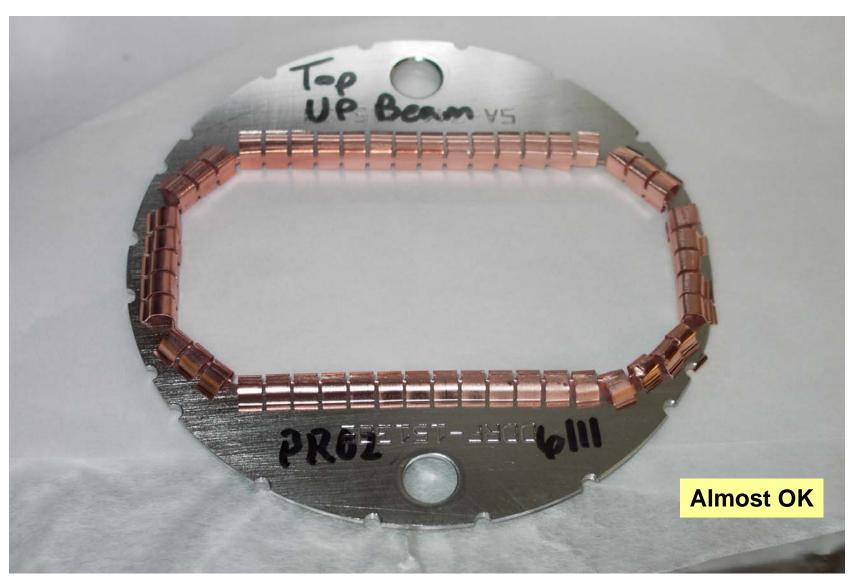
• The nominal FF quads are used to rematch the Twiss functions and horizontal dispersion.

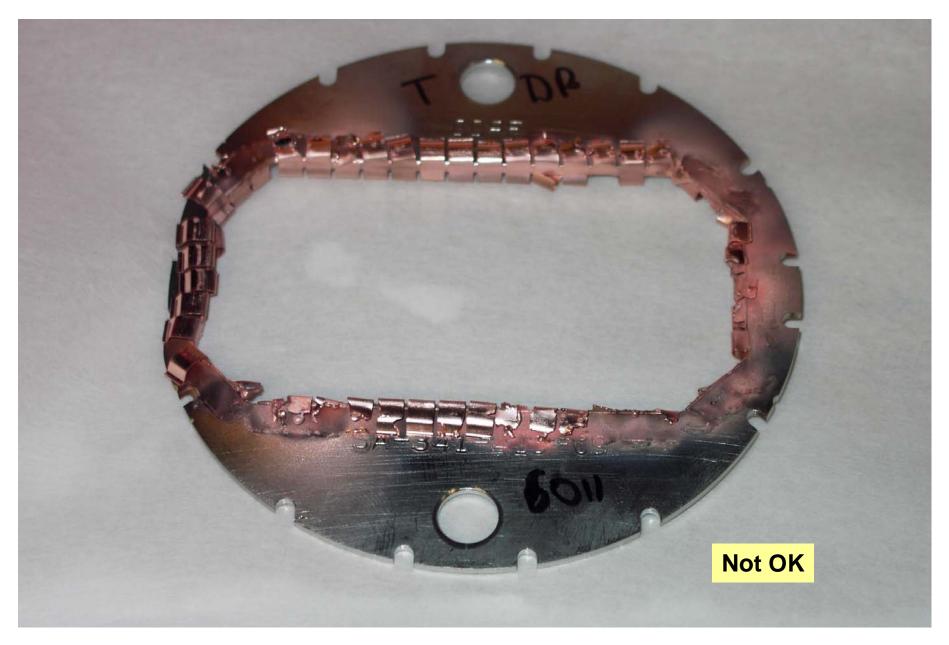


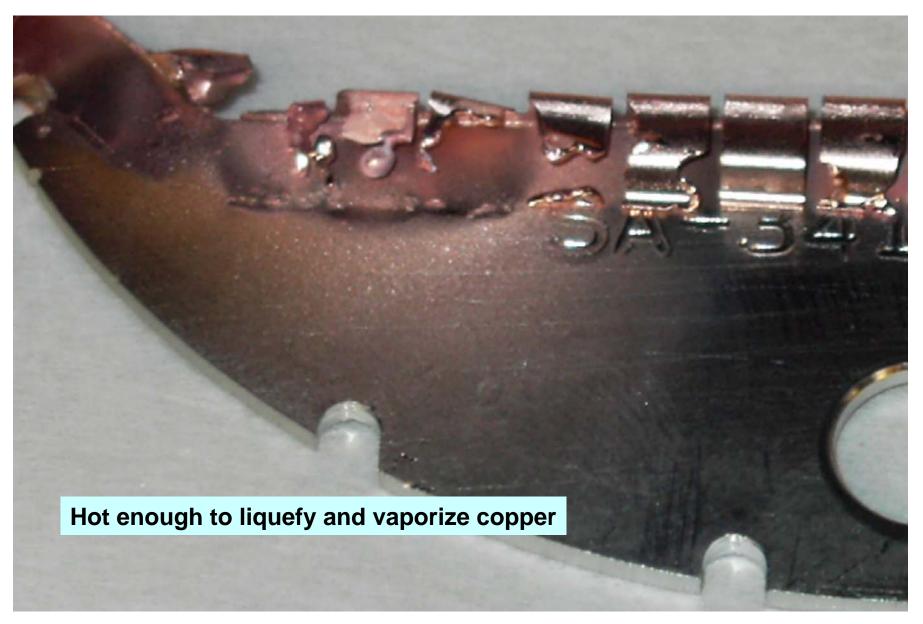
## HOMs

- Analysis not complete until an engineered beam pipe is designed
- The devil is in the details
  - A HOM analysis needs to be done as soon as possible so that unexpected "hot spots" (places where HOM power is being absorbed that is not properly cooled) can be addressed

#### Vacuum components destroyed by a few Watts of RF



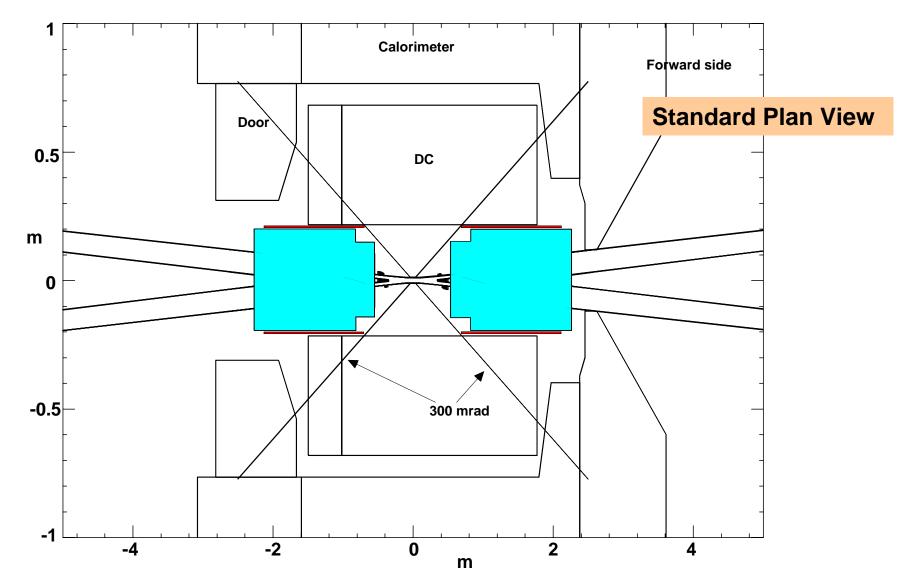




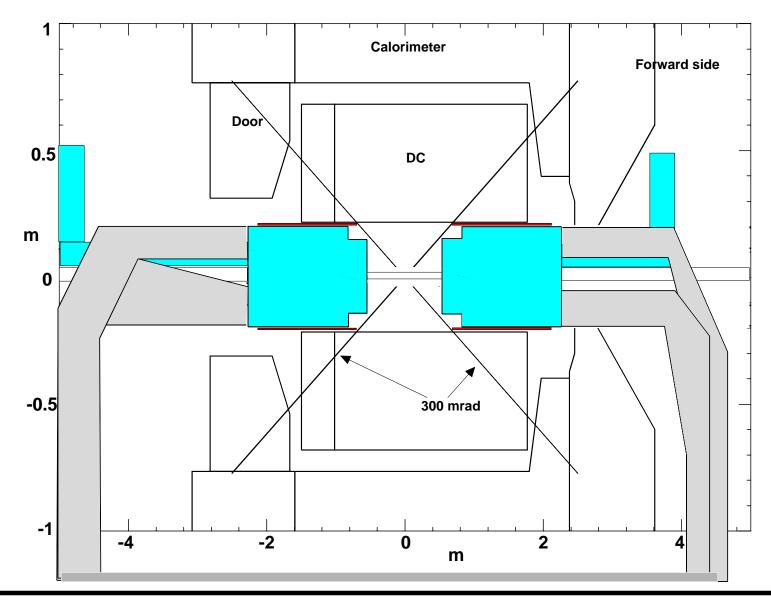
## Access to the central region

- Rapid access to the central region
- SuperB presently does not have an *in situ* way of disconnecting the central chambers
- We have to connect the two cryostats to a common structure – probably under the detector

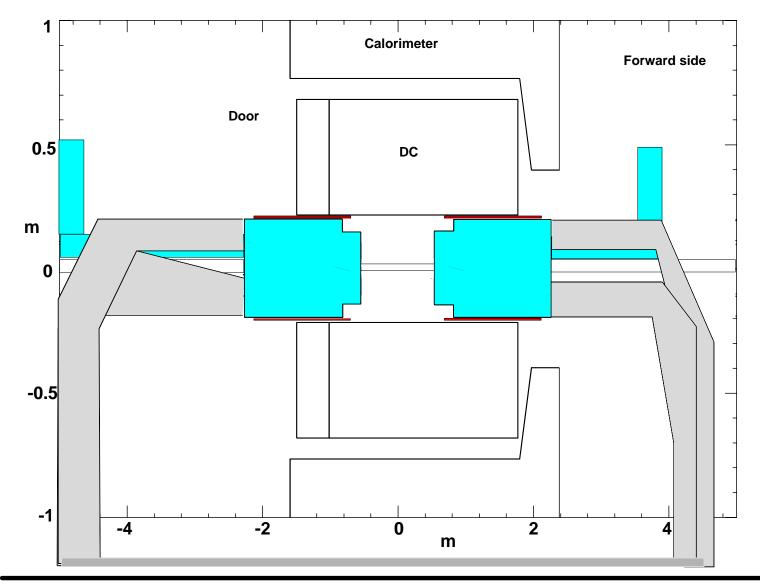
#### **Rapid Access Scenario**

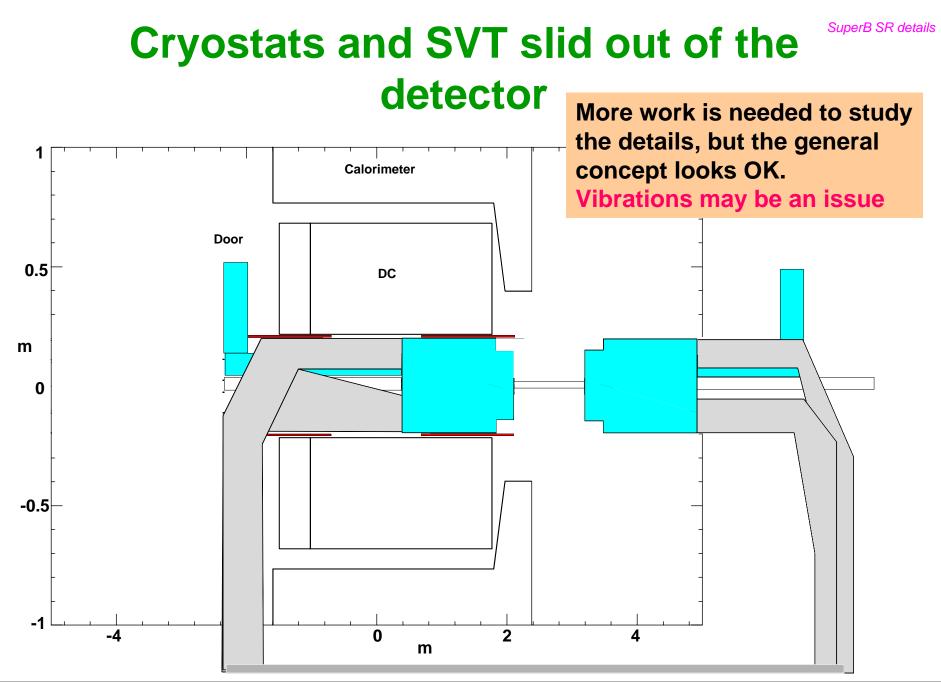


#### **Side view**



#### **Doors opened**





## Vibrations

- Certainly vibration control at some level is needed for the final focus elements
- For the machine, the only point of interest is to keep the beams in collision
  - We think we can do this by correcting the orbit of one beam wrt the other beam
  - This means we don't care if the IP moves around in the beam pipe
  - At least at some level. Too much motion and the orbits will not be stable enough. Few microns at the IP ok???

# Vibrations (2)

- Giuliana Rizzo brought up an interesting point at coffee yesterday
  - What about relative motion between L0 and the rest of the SVT?
  - For that matter, what about relative motion between the SVT and the DCH?
  - This is an issue for both detectors
- The motion could be large (microns)
  - Did BaBar do anything about the found motion of the support tube?

## Vibrations (3)

- Capacitive readout between L0 and the SVT?
- Laser interferometry between SVT and DCH or the rest of the detector?
- Should be thought about at least
  - Motion that is too fast to be corrected by track reconstruction will blur the vertex resolution
  - Even just measuring the motion to make sure it is small enough to ignore should be considered

## Summary

- There are still many things that need further study for both designs
  - I don't see the design teams running out of things to check and study more carefully
- The SuperB TDR should at least list these topics as well as study as many as possible