# **LONGITUDINAL DYNAMICS**

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with lots of material from the course by Joël Le Duff Many Thanks!

**Introductory Level Accelerator Physics Course Granada, 28 October - 9 November 2012** 

# **Overview**

- Methods of Acceleration
- Accelerating Structures
- Synchronism Condition and Phase Stability (Linac)
- Bunching and bunch compression
- Circular accelerators: Cyclotron / Synchrotron
- Dispersion Effects in Synchrotron
- Synchrotron Oscillations
- Energy-Phase Equations
- Longitudinal Phase Space Motion
- Stationary Bucket
- Injection Matching

# Bibliography





And CERN Accelerator Schools (CAS) Proceedings

#### **Main Characteristics of an Accelerator**

Newton-Lorentz Force on a charged particle:

$$
\vec{F} = \frac{\mathrm{d}\vec{p}}{\mathrm{dt}} = e\left(\vec{E} + \vec{v} \times \vec{B}\right)
$$

2<sup>nd</sup> term always perpendicular to motion => no acceleration

ACCELERATION is the main job of an accelerator.

• It provides **kinetic energy** to charged particles, hence increasing their **momentum**.

 $\cdot$  In order to do so, it is necessary to have an electric field  $E$  , preferably along the direction of the initial momentum.

$$
\frac{dp}{dt} = eE_z
$$

BENDING is generated by a magnetic field perpendicular to the plane of the particle trajectory. The bending radius  $\rho$  obeys to the relation:

$$
\frac{p}{e} = B\rho
$$
 in practical units:  $B \rho$  [Tm]  $\approx \frac{p$  [GeV/c]}{0.3}

FOCUSING is a second way of using a magnetic field, in which the bending effect is used to bring the particles trajectory closer to the axis, hence to increase the beam density.

## **Energy Gain**

In relativistic dynamics, total energy *E* and momentum *p* are linked by

 $E^2 = E_0^2 + p^2 c^2$   $(E = E_0 + W)$  *W kinetic energy*  $E^2 = E_0^2 + p^2 c^2$ 0  $2 = E_0^2 +$ 

Hence: *dE* =*vdp*

The rate of energy gain per unit length of acceleration (along z) is then:

$$
\frac{dE}{dz} = v\frac{dp}{dz} = \frac{dp}{dt} = eE_z
$$

and the kinetic energy gained from the field along the z path is:

$$
dW = dE = eE_z dz \qquad \rightarrow \qquad W = e \int E_z dz = eV
$$

where *V* is just a potential.

Some relativistic relations:

$$
p = mv = \frac{E}{c^2} \beta c = \beta \frac{E}{c} = \beta \gamma m_0 c \qquad \gamma = \frac{E}{E_0} = \frac{m}{m_0} = \frac{1}{\sqrt{1 - \beta^2}} \qquad \beta = \frac{v}{c} = \sqrt{1 - \frac{1}{\gamma^2}}
$$

### **Velocity and Energy**

normalized velocity

$$
\beta = \frac{v}{c} = \sqrt{1 - \frac{1}{\gamma^2}}
$$

=> electrons almost reach the speed of light very quickly

 $\sqrt{1-v^2/2}$   $\sqrt{1-v^2/2}$ 

1

1

total energy

rest energy

 $m_0$   $\Big|1 - v\Big|$ 

γ

 $=\frac{\frac{1}{2}}{\frac{1}{2}}=\frac{\frac{1}{2}}{\frac{1}{2}}=\frac{\frac{1}{2}}{\frac{1}{2}}=\frac{\frac{1}{2}}{\frac{1}{2}}=\frac{\frac{1}{2}}{\frac{1}{2}}=\frac{\frac{1}{2}}{\frac{1}{2}}=\frac{\frac{1}{2}}{\frac{1}{2}}=\frac{\frac{1}{2}}{\frac{1}{2}}=\frac{\frac{1}{2}}{\frac{1}{2}}=\frac{\frac{1}{2}}{\frac{1}{2}}=\frac{\frac{1}{2}}{\frac{1}{2}}=\frac{\frac{1}{2}}{\frac{1}{2}}=\frac{\frac{1}{2}}{\frac{1}{2}}=\frac{\frac{1}{2}}{\frac{$ 

*E*

*E*

*m*



 $10$   $100$   $1$ 

E kinetic (MeV)



 $=\frac{1}{\sqrt{1-\beta^2}}$ 

1

2

*c*

0.1

 $1 \cdot 10^4$ 

 $1 \cdot 10^3$ 

# **Methods of Acceleration: Electrostatic**



#### **Electrostatic Field:**

Energy gain: W=n  $e(V_{2}-V_{1})$ 

limitation :  $V_{generator} = \sum V_i$ 

#### $\Rightarrow$  insulation problems maximum high voltage (~ 10 MV)

used for first stage of acceleration: particle sources, electron guns x-ray tubes



750 kV Cockroft-Walton generator at Fermilab (Proton source)

#### **Methods of Acceleration: Induction**

#### From Maxwell's Equations:

The electric field is derived from a scalar potential φ and a vector potential A The time variation of the magnetic field H generates an electric field E

$$
\vec{E} = -\vec{\nabla}\phi - \frac{\partial \vec{A}}{\partial t}
$$

$$
\vec{B} = \mu \vec{H} = \vec{\nabla} \times \vec{A}
$$

#### Example: **Betatron**

The varying magnetic field is used to guide particles on a circular trajectory as well as for acceleration. Limited by saturation in iron





Cylindrical electrodes (drift tubes) separated by gaps and fed by a RF generator, as shown above, lead to an alternating electric field polarity



#### **The advantages of resonant cavities**

- Considering RF acceleration, it is obvious that when particles get high velocities the drift spaces get longer and one loses on the efficiency. => The solution consists of using a higher operating frequency.
- The power lost by radiation, due to circulating currents on the electrodes, is proportional to the RF frequency.
	- => The solution consists of enclosing the system in a cavity which resonant frequency matches the RF generator frequency.



- The electromagnetic power is now constrained in the resonant volume
- Each such cavity can be independently powered from the RF generator
- Note however that joule losses will occur in the cavity walls (unless made of superconducting materials)

### **The Pill Box Cavity**



From Maxwell's equations one can derive the wave equations:

$$
\nabla^2 A - \varepsilon_0 \mu_0 \frac{\partial^2 A}{\partial t^2} = 0 \qquad (A = E \text{ or } H)
$$

Solutions for E and H are oscillating modes, at discrete frequencies, of types TM<sub>xyz</sub> (transverse magnetic) or  $TE_{xyz}$  (transverse electric).

Indices linked to the number of field knots in polar coordinates φ, r and z.

For  $k$  2a the most simple mode,  $TM<sub>010</sub>$ , has the lowest frequency, and has only two field components:



# **The Pill Box Cavity (2)**



The design of a pill-box cavity can be sophisticated in order to improve its performances:

- A nose cone can be introduced in order to concentrate the electric field around the axis

- Round shaping of the corners allows a better distribution of the magnetic field on the surface and a reduction of the Joule losses.

It also prevents from multipactoring effects.

A good cavity is a cavity which efficiently transforms the RF power into accelerating voltage.

#### **Multi-gap Accelerating Structures**









# *L*  $\omega_{RF} = 2\pi \frac{v_s}{I}$ Synchronism condition  $(g << L)$  $L = v_s T_{RF} = \beta_s \lambda_{RF}$ g  $L_1 \mid \cdot \mid \cdot \mid L_2 \mid \cdot \mid \cdot \mid \cdot \mid L_3 \mid \cdot \mid \cdot \mid \cdot \mid \cdot \mid L_4 \mid \cdot \mid \cdot \mid \cdot \mid \cdot \mid L_5$ RF generator  $(\sim)$ Used for protons, ions (50 - 200 MeV,  $f \sim 200$  MHz) **RF acceleration: Alvarez Structure LINAC 1 (CERN)**

#### **Transit time factor**

The accelerating field varies during the passage of the particle => particle does not see maximum field all the time => effective acceleration smaller

Defined as: 
$$
T_a = \frac{\text{energy gain of particle with } v = \beta c}{\text{maximum energy gain (particle with } v \rightarrow \infty)}
$$

In the general case, the transit time factor is:

$$
for E(s,r,t) = E_1(s,r) \cdot E_2(t)
$$

Simple model  
uniform field: 
$$
E_1(s,r) = \frac{V_{RF}}{g}
$$
  
follows:  $T_a = \left| \sin \frac{\omega_{RF} g}{g} \right|$ 

$$
E_1(s,r) = \frac{V_{RF}}{g} = \text{const.}
$$

$$
T_a = \left| \sin \frac{\omega_{RF}g}{2v} / \frac{\omega_{RF}g}{2v} \right|
$$

$$
T_a = \frac{\int_{-\infty}^{+\infty} E_1(s,r) \cos \left(\omega_{RF} \frac{s}{v}\right) ds}{\int_{-\infty}^{+\infty} E_1(s,r) ds}
$$

\n- $$
0 < T_a < 1
$$
\n- $T_a \rightarrow 1$  for  $g \rightarrow 0$ , smaller  $\omega_{RF}$
\n

Important for low velocities (ions)

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# **Important Parameters of Accelerating Cavities**

#### Shunt Impedance R



# Quality Factor Q



Relationship between gap voltage V and wall losses  $P_d$ 

Relationship between stored energy  $W_s$  in the volume and dissipated power on the walls

$$
\frac{R}{Q} = \frac{V^2}{\omega W_s}
$$

#### Filling Time τ

$$
P_d = -\frac{dW_s}{dt} = \frac{\omega}{Q}W_s
$$
 Exponential decay of the  
stored energy W<sub>s</sub> due to losses  $\tau = \frac{Q}{\omega}$ 

#### **Disc loaded traveling wave structures**

-When particles gets ultra-relativistic (v~c) the drift tubes become very long unless the operating frequency is increased. Late 40's the development of radar led to high power transmitters (klystrons) at very high frequencies (3 GHz).

-Next came the idea of suppressing the drift tubes using traveling waves. However to get a continuous acceleration the phase velocity of the wave needs to be adjusted to the particle velocity.





solution: slow wave quide with irises ==> iris loaded structure

#### **The Traveling Wave Case**



$$
E_z = E_0 \cos(\omega_{RF} t - kz)
$$
  

$$
k = \frac{\omega_{RF}}{v_{\varphi}}
$$
 wave number

$$
z = v(t - t_0)
$$

 $v_{\varphi}$  = phase velocity  $v =$  particle velocity

The particle travels along with the wave, and k represents the wave propagation factor.

$$
E_z = E_0 \cos \left( \omega_{RF} t - \omega_{RF} \frac{v}{v_{\varphi}} t - \phi_0 \right)
$$

If synchronism satisfied:  $v = v_\varphi$  and  $E_z = E_0 \cos \phi_0$ 

where  $\Phi_0$  is the RF phase seen by the particle.

#### **Principle of Phase Stability (Linac)**

Let's consider a succession of accelerating gaps, operating in the  $2\pi$  mode, for which the synchronism condition is fulfilled for a phase <sup>Φ</sup>**s .**



#### **A Consequence of Phase Stability**



Transverse focusing fields at the entrance and defocusing at the exit of the cavity. Electrostatic case: Energy gain inside the cavity leads to focusing RF case: Field increases during passage => transverse defocusing!

Longitudinal phase stability means:

\n
$$
\frac{\partial V}{\partial t} > 0 \Rightarrow \frac{\partial E_z}{\partial z} < 0
$$
\nThe divergence of the field is zero according to Maxwell:

\n
$$
\nabla \cdot \vec{E} = 0 \Rightarrow \frac{\partial E_x}{\partial x} + \frac{\partial E_z}{\partial z} = 0 \Rightarrow \frac{\partial E_x}{\partial x} > 0
$$

**External focusing (solenoid, quadrupole) is then necessary**

#### **Energy-Phase Equations**

Rate of energy gain for the synchronous particle:

$$
\frac{dE_s}{dz} = \frac{dp_s}{dt} = eE_0 \sin \phi_s
$$

Rate of energy gain for a non-synchronous particle, expressed in reduced  $w = \frac{W - W}{W - W_s} = E - E_s$  and  $\dot{\varphi} = \phi - \phi_s$ 

$$
\frac{dw}{dz} = eE_0[\sin(\phi_s + \varphi) - \sin \phi_s] \approx eE_0 \cos \phi_s \varphi \quad (small \varphi)
$$

Rate of change of the phase with respect to the synchronous one:

$$
\frac{d\varphi}{dz} = \omega_{RF} \left( \frac{dt}{dz} - \left( \frac{dt}{dz} \right)_s \right) = \omega_{RF} \left( \frac{1}{v} - \frac{1}{v_s} \right) \approx -\frac{\omega_{RF}}{v_s^2} \left( v - v_s \right)
$$
\n
$$
\text{Since:} \quad v - v_s = c \left( \beta - \beta_s \right) \approx \frac{c}{2\beta_s} \left( \beta^2 - \beta_s^2 \right) \approx \frac{w}{m_0 v_s \gamma_s^3}
$$

#### **Energy Phase Oscillations**

one gets:

$$
\frac{d\varphi}{dz} = -\frac{\omega_{RF}}{m_0 v_s^3 \gamma_s^3} w
$$

Combining the two first order equations into a second order one:



with

$$
\Omega_s^2 = \frac{eE_0\omega_{RF}\cos\phi_s}{m_0v_s^3\gamma_s^3}
$$

Stable harmonic oscillations imply:

$$
\Omega_s^2 > 0 \quad \text{and real}
$$

hence:

$$
\cos\phi_s > 0
$$

 $\sin \phi_s > 0$ 

One finally gets the results:

And since acceleration also means:

$$
0<\phi_{s}<\frac{\pi}{2}
$$

## **Longitudinal phase space**





The particle trajectory in the phase space  $(\Delta p/p, \phi)$  describes its longitudinal motion.

Emittance: phase space area including all the particles

> NB: if the emittance contour correspond to a possible orbit in phase space, its shape does not change with time (matched beam)

#### **The Capture Problem**

- Previous results show that at ultra-relativistic energies (γ>> 1) the longitudinal motion is frozen. Since this is rapidly the case for electrons, all traveling wave structures can be made identical (phase velocity=c).

- Hence the question is: can we capture low kinetic electrons energies (γ< 1), as they come out from a gun, using an iris loaded structure matched to c ?

*E z* = *E*<sup>0</sup> sinφ(*t*)

The electron entering the structure, with velocity  $v \cdot c$ , is not synchronous with the wave. The path difference, after a time dt, between the wave and the particle is:

$$
dz = (c - v)dt
$$

Since  $\phi = \omega_{\scriptscriptstyle{BF}} t - k z$  with propagation factor one gets  $dz = -d\phi = -\frac{8}{3}d\phi$  and  $\phi = \omega_{RF}t - kz$  with propagation factor  $k = \frac{\omega_{RF}}{\omega_{RF}}$  $v_{\varphi}$ =  $\omega_{_{RF}}$ *c*  $dz = \frac{c}{c}$  $\omega_{_{RF}}$  $d\phi = \frac{\lambda_g}{2}$  $2\pi$  $d\phi$  and  $\frac{d\phi}{d\phi}$ *dt* =  $2\pi$  $\lambda_{_g}$  $c(1-\beta)$ 

#### **The Capture Problem (2)**

 $\sqrt{2}$ 

From Newton-Lorentz:

$$
\frac{d}{dt}(mv) = m_0 c \frac{d}{dt}(\beta \gamma) = m_0 c \frac{d}{dt} \left( \frac{\beta}{\left(1 - \beta^2\right)^{\frac{1}{2}}} \right) = eE_0 \sin \phi
$$

Introducing a suitable variable:

 $\beta$  = cos  $\alpha$ 



# **Bunching with a Pre-buncher**

A long bunch coming from the gun enters an RF cavity. The reference particle is the one which has no velocity change. The others get accelerated or decelerated, so the bunch gets an energy and velocity modulation.

After a distance L bunch gets shorter: bunching effect. This short bunch can now be captured more efficiently by a TW structure  $(v<sub>ω</sub>=c)$ .



#### **Bunching with a Pre-buncher (2)**

The bunching effect is a space modulation caused by a velocity modulation, similar to the phase stability phenomenon. Let's look at the particles in the vicinity of the reference and use a classical approach.

Energy gain as a function of cavity crossing time:

$$
\Delta W = \Delta \left(\frac{1}{2}m_0 v^2\right) = m_0 v_0 \Delta v = eV_0 \sin \phi \approx eV_0 \phi \qquad \Delta v = \frac{eV_0 \phi}{m_0 v_0}
$$

Perfect linear bunching will occur after a time delay τ, corresponding to a distance L, when the path difference is compensated between a particle and the reference one:

$$
\Delta v \tau = \Delta z = v_0 \Delta t = v_0 \frac{\phi}{\omega_{RF}}
$$

(assuming the reference particle enters the cavity at time t=0)

Since  $L = v_0 \tau$  one gets:

$$
L = \frac{2v_0 W}{eV_0 \omega_{RF}}
$$

#### **Bunch compression**

At ultra-relativistic energies (γ>> 1) the longitudinal motion is frozen. This is rapidly the case for electrons.

For example for linear colliders, you need very short bunches (few 100-50 $\mu$ m). Solution: introduce energy/time correlation with a magnetic chicane.



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#### **Bunch compression (2)**



Longitudinal phase space evolution for a bunch compressor (PARMELA code simulations)

Introducing correlated energy spread increases total energy spread in the bunch. => chromatic effects (depend on relative energy spread ΔE/E) Solution: compress at low energy before further acceleration => absolute energy spread constant but relative is decreased

#### **Circular accelerators: Cyclotron**



#### **Cyclotron / Synchrocyclotron**



Synchrocyclotron: Same as cyclotron, except a modulation of  $\omega_{RF}$ 

 $B = constant$  $\gamma \omega_{RF}$  = constant  $\omega_{RF}$  decreases with time

The condition:

$$
\omega_{s}(t) = \omega_{RF}(t) = \frac{q B}{m_{0} \gamma(t)}
$$

Allows to go beyond the non-relativistic energies

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#### **Circular accelerators: The Synchrotron**



- 1.  $\omega_{RF}$  and  $\omega$  increase with energy
- 2. To keep particles on the closed orbit, B should increase with time

#### **Circular accelerators: The Synchrotron**

The synchrotron is a synchronous accelerator since there is a synchronous RF phase for which the energy gain fits the increase of the magnetic field at each turn. That implies the following operating conditions:



If v≈c,  $\omega_r$  hence  $\omega_{RF}$  remain constant (ultra-relativistic e-)

#### **Circular accelerators: The Synchrotron**



**EPA (CERN) Electron Positron Accumulator** 



Examples of different proton and electron synchrotrons at CERN

**PS (CERN) Proton Synchrotron © CERN Geneva** 

#### **The Synchrotron**

Energy ramping is simply obtained by varying the B field (frequency follows v):

$$
p = eB\rho \Rightarrow \frac{dp}{dt} = e\rho \dot{B} \Rightarrow (\Delta p)_{turn} = e\rho \dot{B}T_r = \frac{2\pi e\rho R\dot{B}}{v}
$$

Since:

$$
E^2 = E_0^2 + p^2 c^2 \implies \Delta E = v \Delta p
$$

$$
(\Delta E)_{\text{turn}} = (\Delta W)_{\text{s}} = 2\pi e\rho R\dot{B} = e\hat{V}\sin\phi_{\text{s}}
$$

Stable phase  $\varphi_{s}$  changes during energy ramping

$$
\sin \phi_s = 2\pi \rho R \frac{\dot{B}}{\dot{V}_{RF}} \qquad \phi_s = \arcsin\left(2\pi \rho R \frac{\dot{B}}{\dot{V}_{RF}}\right)
$$

- The number of stable synchronous particles is equal to the harmonic number h. They are equally spaced along the circumference.
- Each synchronous particle satisfies the relation p=eBρ. They have the nominal energy and follow the nominal trajectory.

#### **The Synchrotron**

During the energy ramping, the RF frequency increases to follow the increase of the revolution frequency :

$$
\omega_r = \frac{\omega_{RF}}{h} = \omega(B, R_s)
$$

Hence: 
$$
\frac{f_{RF}(t)}{h} = \frac{v(t)}{2\pi R_s} = \frac{1}{2\pi} \frac{ec^2}{E_s(t)} \frac{\rho}{R_s} B(t)
$$
 (using  $p(t) = eB(t)\rho$ ,  $E = mc^2$ )

Since  $E^2 = (m_0 c^2)^2 + p^2 c^2$  the RF frequency must follow the variation of the B field with the law

$$
\frac{f_{RF}(t)}{h} = \frac{c}{2\pi R_s} \left\{ \frac{B(t)^2}{(m_0c^2 / ec\rho)^2 + B(t)^2} \right\}^{1/2}
$$

This asymptotically tends towards  $f_r \rightarrow \frac{c}{2 \pi R}$  when B becomes large  $\epsilon$  compared to  $m_0 c^2$  /(ecp)  $2 \pi R_s$ which corresponds to  $\nu \rightarrow c$ *c*

#### **Dispersion Effects in a Synchrotron**



**p=particle momentum R=synchrotron physical radius fr=revolution frequency**

If a particle is slightly shifted in momentum it will have a different orbit and the length is different.

The "momentum compaction factor" is defined as:



$$
\alpha = \frac{p}{L} \frac{dL}{dp}
$$

If the particle is shifted in momentum it will have also a different velocity. As a result of both effects the revolution frequency changes:

$$
\eta = \frac{df_r}{dp} \Rightarrow \eta = \frac{p}{f_r} \frac{df_r}{dp}
$$

#### **Dispersion Effects in a Synchrotron (2)**

$$
\alpha = \frac{p}{L} \frac{dL}{dp} \qquad \qquad ds_0 = \rho d\theta
$$

$$
ds = (\rho + x) d\theta
$$

#### **The elementary path difference from the two orbits is:**

definition of dispersion  $D_{x}$ 

$$
\frac{dl}{ds_0} = \frac{ds - ds_0}{ds_0} = \frac{x}{\rho} = \frac{D_x}{\rho} \frac{dp}{p}
$$



**leading to the total change in the circumference:**

$$
dL = \int_C dl = \int \frac{x}{\rho} ds_0 = \int \frac{D_x}{\rho} \frac{dp}{p} ds_0
$$



**With ρ=∞ in straight sections we get:**

$$
\alpha = \frac{\left\langle D_{x}\right\rangle_{m}}{R}
$$

 $\langle \rangle$ <sub>m</sub> means that the average is considered over the bending magnet only

#### **Dispersion Effects in a Synchrotron (3)**

$$
f_r = \frac{\beta c}{2\pi R} \implies \frac{df_r}{f_r} = \frac{d\beta}{\beta} - \frac{dR}{R} = \frac{d\beta}{\beta} - \alpha \frac{dp}{p}
$$
\n
$$
p = mv = \beta \gamma \frac{E_0}{c} \implies \frac{dp}{p} = \frac{d\beta}{\beta} + \frac{d(1-\beta^2)^{-\frac{1}{2}}}{(1-\beta^2)^{-\frac{1}{2}}} = \frac{(1-\beta^2)^{-1}}{\gamma^2} \frac{d\beta}{\beta}
$$
\n
$$
\frac{df_r}{f_r} = \left(\frac{1}{\gamma^2} - \alpha\right) \frac{dp}{p} \qquad \frac{\frac{df_r}{f_r} = \eta \frac{dp}{p}}{\gamma^2} \qquad \eta = \frac{1}{\gamma^2} - \alpha
$$
\n
$$
\eta = 0 \text{ at the transition energy} \qquad \gamma_{tr} = \frac{1}{\sqrt{\alpha}}
$$

#### **Phase Stability in a Synchrotron**

From the definition of η it is clear that an increase in momentum gives

- below transition (η > 0) a higher revolution frequency (increase in velocity dominates) while
- above transition  $(n \cdot 0)$  a lower revolution frequency ( $v \approx c$  and longer path) where the momentum compaction (generally  $> 0$ ) dominates.



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#### **Crossing Transition**

At transition, the velocity change and the path length change with momentum compensate each other. So the revolution frequency there is independent from the momentum deviation.

Crossing transition during acceleration makes the previous stable synchronous phase unstable. The RF system needs to make a 'phase jump'.



### **Synchrotron oscillations**

Simple case (no accel.):  $B = \text{const.}$ , below transition  $\gamma < \gamma_{tr}$ 

The phase of the synchronous particle must therefore be  $\phi_0 = 0$ .

- 
- $\phi_1$  The particle is accelerated
	- Below transition, an increase in energy means an increase in revolution frequency
	- The particle arrives earlier tends toward  $\phi_0$



- $\phi_2$  The particle is decelerated
	- decrease in energy decrease in revolution frequency
	- The particle arrives later tends toward  $\phi_0$

#### **Synchrotron oscillations (2)**



#### **Synchrotron oscillations (3)**



#### **Longitudinal Dynamics**

It is also often called "synchrotron motion".

The RF acceleration process clearly emphasizes two coupled variables, the energy gained by the particle and the RF phase experienced by the same particle. Since there is a well defined synchronous particle which has always the same phase φ**s,** and the nominal energy  $E_{s}$ , it is sufficient to follow other particles with respect to that particle.

So let's introduce the following reduced variables:



#### **First Energy-Phase Equation**



$$
f_{RF} = hf_r \implies \Delta\phi = -h\Delta\theta
$$
 with  $\theta = \int \omega_r dt$ 

particle ahead arrives earlier => smaller RF phase

For a given particle with respect to the reference one:

$$
\Delta \omega_r = \frac{d}{dt} (\Delta \theta) = -\frac{1}{h} \frac{d}{dt} (\Delta \phi) = -\frac{1}{h} \frac{d\phi}{dt}
$$



#### **Second Energy-Phase Equation**

The rate of energy gained by a particle is:

$$
\frac{dE}{dt} = e\hat{V}\sin\phi \frac{\omega_r}{2\pi}
$$

**The rate of relative energy gain with respect to the reference particle is then:**  $2\pi\Delta\Big(\frac{\dot{E}}{}$  $\omega_{_r}$  $\sqrt{}$  $\setminus$  $\overline{\phantom{a}}$ ' (  $\int$  =  $e\hat{V}(\sin\phi - \sin\phi_s)$ 

**Expanding the left-hand side to first order:** 

$$
\Delta(\dot{E}T_r) \cong \dot{E}\Delta T_r + T_{rs}\Delta\dot{E} = \Delta E\dot{T}_r + T_{rs}\Delta\dot{E} = \frac{d}{dt}(T_{rs}\Delta E)
$$

**leads to the second energy-phase equation:**

$$
2\pi \frac{d}{dt} \left( \frac{\Delta E}{\omega_{rs}} \right) = e\hat{V} \left( \sin \phi - \sin \phi_{s} \right)
$$

#### **Equations of Longitudinal Motion**



This second order equation is non linear. Moreover the parameters within the bracket are in general slowly varying with time.

We will study some cases later…

#### **Small Amplitude Oscillations**

Let's assume constant parameters R<sub>s</sub>, p<sub>s</sub>, ω<sub>s</sub> and η:

$$
\ddot{\phi} + \frac{\Omega_s^2}{\cos \phi_s} \left( \sin \phi - \sin \phi_s \right) = 0 \quad \text{with} \quad \Omega_s^2 = \frac{h \eta \omega_s e \hat{V} \cos \phi_s}{2 \pi R_s p_s}
$$

(for small Δφ**)**   $\sin\phi$ – $\sin\phi_s = \sin(\phi_s + \Delta\phi)$ – $\sin\phi_s \approx \cos\phi_s \Delta\phi$ Consider now small phase deviations from the reference particle:

and the corresponding linearized motion reduces to a harmonic oscillation:

$$
\ddot{\phi} + \Omega_s^2 \Delta \phi = 0
$$

where Ω**s** is the synchrotron angular frequency

#### **Stability condition for ϕ<sup>s</sup>**

Stability is obtained when  $\Omega_{\sf s}$  is real and so  $\Omega_{\sf s}^2$  positive:



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**For larger phase (or energy) deviations from the reference the second order differential equation is non-linear:**

$$
\ddot{\phi} + \frac{\Omega_s^2}{\cos \phi_s} \left( \sin \phi - \sin \phi_s \right) = 0 \qquad \text{($\Omega_s$ as previously defined)}\
$$

Multiplying by  $\dot{\phi}$  and integrating gives an invariant of the motion:

$$
\frac{\dot{\phi}^2}{2} - \frac{\Omega_s^2}{\cos \phi_s} \left( \cos \phi + \phi \sin \phi_s \right) = I
$$

**which for small amplitudes reduces to:**

 $\dot{\phi}^2$ 2 + Ω*<sup>s</sup>*  $_{2}\left( \Delta \phi \right) ^{2}$ 2 (the variable is  $\Delta\phi$ , and  $\phi_s$  is constant)

Similar equations exist for the second variable : ΔE∝dφ/dt

#### **Large Amplitude Oscillations (2)**





**Equation of the separatrix:**

$$
\frac{\dot{\phi}^2}{2} - \frac{\Omega_s^2}{\cos \phi_s} \left( \cos \phi + \phi \sin \phi_s \right) = - \frac{\Omega_s^2}{\cos \phi_s} \left( \cos (\pi - \phi_s) + (\pi - \phi_s) \sin \phi_s \right)
$$

**Second value** φ**m where the separatrix crosses the horizontal axis:**

$$
\cos\phi_m + \phi_m \sin\phi_s = \cos(\pi - \phi_s) + (\pi - \phi_s) \sin\phi_s
$$

**Area within this separatrix is called "RF bucket".**

#### **Energy Acceptance**

From the equation of motion it is seen that  $\dot{\phi}$  reaches an extreme when  $\ddot{\phi} = 0$  , hence corresponding to  $\phi = \phi_s$ . **Introducing this value into the equation of the separatrix gives:** 

$$
\dot{\phi}_{\text{max}}^2 = 2\Omega_s^2 \left\{ 2 + \left( 2\phi_s - \pi \right) \tan \phi_s \right\}
$$

**That translates into an acceptance in energy:**

$$
\left(\frac{\Delta E}{E_s}\right)_{\text{max}} = \pm \beta \sqrt{-\frac{e\hat{V}}{\pi h \eta E_s} G(\phi_s)}
$$

$$
G(\phi_s) = \left[2\cos\phi_s + (2\phi_s - \pi)\sin\phi_s\right]
$$

This "RF acceptance" depends strongly on  $φ_5$  and plays an important role **for the capture at injection, and the stored beam lifetime.**

#### **RF Acceptance versus Synchronous Phase**



The areas of stable motion (closed trajectories) are called "BUCKET".

As the synchronous phase gets closer to 90º the buckets gets smaller.

The number of circulating buckets is equal to "h".

The phase extension of the bucket is maximum for φ**<sup>s</sup> =**180º (or 0°) which correspond to no acceleration . The RF acceptance increases with the RF voltage.

#### **Potential Energy Function**

 $\frac{\partial}{\partial z} = F(\phi)$ *d* 2  $F(\phi) = -\frac{\partial U}{\partial \phi}$ The longitudinal motion is produced by a force that can be derived from a scalar potential:

 $\phi = -\frac{\partial U}{\partial \phi}$ 

*s*

*s*

2



*dt*

 $\frac{\gamma}{2}$  =

The sum of the potential energy and kinetic energy is constant and by analogy represents the total energy of a non-dissipative system.

 $\cos \phi + \phi \sin \phi$ 

#### **Hamiltonian of Longitudinal Motion**

**h**<sub>n</sub> *l*<sub>n</sub>

Introducing a new convenient variable,  $W$ , leads to the 1st order equations:

$$
W=2\pi \left(\frac{\Delta E}{\omega_{rs}}\right)=2\pi R_s \Delta p \qquad \longrightarrow \qquad \frac{d\phi}{dt}=-\frac{1}{2\pi} \frac{h\eta\omega_{rs}}{p_s R_s}W
$$

$$
\frac{dW}{dt}=e\hat{V}(\sin\phi-\sin\phi_s)
$$

The two variables  $\phi$ , W are canonical since these equations of motion can be derived from a Hamiltonian  $H(\phi, W, t)$ :

$$
\frac{d\phi}{dt} = \frac{\partial H}{\partial W} \qquad \qquad \frac{dW}{dt} = -\frac{\partial H}{\partial \phi}
$$

$$
H(\phi, W, t) = e\hat{V}[\cos\phi - \cos\phi_s + (\phi - \phi_s)\sin\phi_s] - \frac{1}{4\pi}\frac{h\eta\omega_{rs}}{R_s p_s}W^2
$$

#### **Stationnary Bucket - Separatrix**

This is the case sin $\phi_s$ =0 (no acceleration) which means  $\phi_s$ =0 or  $\pi$ . The equation of the separatrix for  $\phi_s = \pi$  (above transition) becomes:

$$
\frac{\dot{\phi}^2}{2} + \Omega_s^2 \cos \phi = \Omega_s^2
$$

$$
\frac{\dot{\phi}^2}{2} = 2\Omega_s^2 \sin^2 \frac{\phi}{2}
$$

Replacing the phase derivative by the canonical variable W:



$$
W=2\pi\frac{\Delta E}{\omega_{rs}}=-2\pi\frac{p_s R_s}{h\eta_{\omega_{rs}}}\dot{\phi}
$$

and introducing the expression for Ω**s** leads to the following equation for the separatrix:

with 
$$
C = 2\pi R_s
$$
  

$$
W = \pm 2 \frac{C}{c} \sqrt{\frac{-e\hat{V}E_s}{2\pi h\eta}} \sin{\frac{\phi}{2}} = \pm W_{bk} \sin{\frac{\phi}{2}}
$$

#### **Stationnary Bucket (2)**

Setting  $\phi$ = $\pi$  in the previous equation gives the height of the bucket:

$$
W_{bk} = 2\frac{C}{c} \sqrt{\frac{-e\hat{V}E_s}{2\pi h\eta}}
$$

This results in the maximum energy acceptance:

$$
\Delta E_{\text{max}} = \frac{\omega_{rs}}{2\pi} W_{bk} = \beta_s \sqrt{2 \frac{-e\hat{V}_{RF}E_s}{\pi \eta h}}
$$

The area of the bucket is:

$$
A_{bk}=2\int_0^{2\pi} W d\phi
$$

Since:  
\n
$$
\int_0^{2\pi} \sin \frac{\phi}{2} d\phi = 4
$$
\n
$$
A_{bk} = 8W_{bk} = 16 \frac{C}{c} \sqrt{\frac{-e\hat{V}E_s}{2\pi h\eta}}
$$
\n
$$
W_{bk} = \frac{A_{bk}}{8}
$$

### **Effect of a Mismatch**

Injected bunch: short length and large energy spread after 1/4 synchrotron period: longer bunch with a smaller energy spread.



For larger amplitudes, the angular phase space motion is slower (1/8 period shown below)  $\Rightarrow$  can lead to filamentation and emittance growth



#### **Bunch Matching into a Stationnary Bucket**

A particle trajectory inside the separatrix is described by the equation:



# **Bunch Matching into a Stationnary Bucket (2)**

Setting  $\phi = \pi$  in the previous formula allows to calculate the bunch height:

$$
W_b = W_{bk} \cos \frac{\phi_m}{2} = W_{bk} \sin \frac{\hat{\phi}}{2} \qquad \text{or:} \qquad W_b = \frac{A_{bk}}{8} \cos \frac{\phi_m}{2}
$$

$$
\left(\frac{\Delta E}{E_s}\right)_b = \left(\frac{\Delta E}{E_s}\right)_{RF} \cos \frac{\phi_m}{2} = \left(\frac{\Delta E}{E_s}\right)_{RF} \sin \frac{\hat{\phi}}{2}
$$

This formula shows that for a given bunch energy spread the proper matching of a shorter bunch (φ<sub>m</sub> close to π,  $\hat{\phi}$  small) will require a bigger RF acceptance, hence a higher voltage

For small oscillation amplitudes the equation of the ellipse reduces to:

$$
W = \frac{A_{bk}}{16} \sqrt{\hat{\phi}^2 - (\Delta \phi)^2} \qquad \longrightarrow \qquad \left(\frac{16W}{A_{bk}\hat{\phi}}\right)^2 + \left(\frac{\Delta \phi}{\hat{\phi}}\right)^2 = 1
$$

Ellipse area is called longitudinal emittance

$$
A_b = \frac{\pi}{16} A_{bk} \hat{\phi}^2
$$

### **Effect of a Mismatch**

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#### **Capture of a Debunched Beam with Fast Turn-On**



#### **Capture of a Debunched Beam with Adiabatic Turn-On**

