# Probabilistic Reasoning in Physics 

- inference, forecasting, decision -

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"Probability is good sense reduced to a calculus" (Laplace)

## Outline

- "Science and hypothesis" (Poincaré)
- Uncertainty, probability, decision.
- Causes $\longleftrightarrow$ Effects
"The essential problem of the experimental method" (Poincaré).
- A toy model and its physics analogy: the six box game "Probability is either referred to real cases or it is nothing" (de Finetti).
- Probabilistic approach [ but ... What is probability?]
- Basic rules of probability and Bayes rule.
- Bayesian inference and its graphical representation: $\Rightarrow$ Bayesian networks
- Some examples of applications in Physics
- Conclusions

continuous Hypotheses discrete


## Physics


continuous Hypotheses discrete
(*) A quantity might be meaningful only within a theory/model

## From past to future



Task of physicists:

- Describe/understand the physical world
$\Rightarrow$ inference of laws and their parameters
- Predict observations
$\Rightarrow$ forecasting


## From past to future



## Process

- neither automatic
- nor purely contemplative
$\rightarrow$ 'scientific method'
$\rightarrow$ planned experiments ('actions') $\Rightarrow$ decision.


## From past to future


$\Rightarrow$ Uncertainty:

1. Given the past observations, in general we are not sure about the theory parameters (and/or the theory itself)
2. Even if we were sure about theory and parameters, there could be internal (e.g. Q.M.) or external effects (initial/boundary conditions, 'errors', etc) that make the forecasting uncertain.

## Inferential-predictive process

EXPERIMENTAL DATA


## Inferential-predictive process



## Inferential-predictive process


(S. Raman, Science with a smile)

## Inferential-predictive process


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Even if the (ad hoc) model fits perfectly the data, we do not believe the predictions because we don't trust the model!
[Many ‘good' models are ad hoc models!]

## 2011 IgNobel prize in Mathematics

- D. Martin of USA (who predicted the world would end in 1954)
- P. Robertson of USA (who predicted the world would end in 1982)
- E. Clare Prophet of the USA (who predicted the world would end in 1990)
- L.J. Rim of KOREA (who predicted the world would end in 1992)
- C. Mwerinde of UGANDA (who predicted the world would end in 1999)
- H. Camping of the USA (who predicted the world would end on September 6, 1994 and later predicted that the world will end on October 21, 2011)


## 2011 IgNobel prize in Mathematics

## "For teaching the world to be careful when making mathematical assumptions and calculations"

## Deep source of uncertainty



Uncertainty:

## Theory —? $\longrightarrow$ Future observations <br> Past observations - ? $\longrightarrow$ Theory <br> Theory $-? \longrightarrow$ Future observations

## Deep source of uncertainty



Uncertainty:

# Theory —? $\longrightarrow$ Future observations <br> Past observations - ? $\longrightarrow$ Theory <br> Theory —? $\longrightarrow$ Future observations <br> $\Longrightarrow$ Uncertainty about causal connections <br> CAUSE $\Longleftrightarrow$ EFFECT 

## Causes $\rightarrow$ effects

The same apparent cause might produce several,different effects


Given an observed effect, we are not sure about the exact cause that has produced it.

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$$
\mathbf{E}_{\mathbf{2}} \Rightarrow\left\{C_{1}, C_{2}, C_{3}\right\} ?
$$

## The "essential problem" of the Sciences

"Now, these problems are classified as probability of causes, and are most interesting of all their scientific applications. I play at écarté with a gentleman whom I know to be perfectly honest. What is the chance that he turns up the king? It is $1 / 8$. This is a problem of the probability of effects.

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I play with a gentleman whom I do not know. He has dealt ten times, and he has turned the king up six times. What is the chance that he is a sharper? This is a problem in the probability of causes. It may be said that it is the essential problem of the experimental method."
(H. Poincaré - Science and Hypothesis)

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## Why physics students are not taught how to tackle this kind of problems?

## Uncertainty and probability

We, as physicists, consider absolutely natural and meaningful statements of the following kind

- $P\left(-10<\epsilon^{\prime} / \epsilon \times 10^{4}<50\right) \gg P\left(\epsilon^{\prime} / \epsilon \times 10^{4}>100\right)$
- $P\left(172 \leq m_{\text {top }} / \mathrm{GeV} \leq 174\right) \approx 70 \%$
- $P\left(M_{H}<125.5 \mathrm{GeV}\right)>P\left(M_{H}>125.5 \mathrm{GeV}\right)$


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[The fact that for several (most?) people in this audience this criticism is misterious is a clear indication of the confusion concerning this matter]


## Doing Science in conditions of uncertainty

The constant status of uncertainty does not prevent us from doing Science (in the sense of Natural Science and not just Mathematics)

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Indeed
"It is scientific only to say what is more likely and what is less likely" (Feynman)

## From 'true value' to observations



Given $\mu$ (exactly known) we are uncertain about $x$

## From 'true value' to observations

Uncertain $\mu$


Uncertainty about $\mu$ makes us more uncertain about $x$

Uncertain $\mu$


The observed data is certain: $\rightarrow$ 'true value' uncertain.


Where does the observed value of $x$ comes from?


We are now uncertain about $\mu$, given $x$.


Note the symmetry in reasoning.

## A very simple experiment

Let's make an experiment

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- Here
- Now


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For simplicity

- $\mu$ can assume only six possibilities:

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0,1, \ldots, 5
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- $x$ is binary:

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0,1
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[(1, 2); Black/White; Yes/Not; ...]

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[(1,2); Black/White; Yes/Not; ...]
$\Rightarrow$ Later we shall make $\mu$ continous.

## Which box? Which ball?

##  <br> $\mathrm{H}_{0}$ <br> $\mathrm{H}_{1}$ <br> $\mathrm{H}_{2}$ <br> $\mathrm{H}_{3}$ <br> $\mathrm{H}_{4}$ $\mathrm{H}_{5}$

Let us take randomly one of the boxes.

## Which box? Which ball?

| - - - - - | - - - - | - - - ○ | - - OOO | - 0000 | 00000 |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\mathrm{H}_{0}$ | $\mathrm{H}_{1}$ | $\mathrm{H}_{2}$ | $\mathrm{H}_{3}$ | $\mathrm{H}_{4}$ | $\mathrm{H}_{5}$ |

Let us take randomly one of the boxes.
We are in a state of uncertainty concerning several events, the most important of which correspond to the following questions:
(a) Which box have we chosen, $H_{0}, H_{1}, \ldots, H_{5}$ ?
(b) If we extract randomly a ball from the chosen box, will we observe a white ( $E_{W} \equiv E_{1}$ ) or black ( $E_{B} \equiv E_{2}$ ) ball?

Our certainties:

$$
\begin{aligned}
\cup_{j=0}^{5} H_{j} & =\Omega \\
\cup_{i=1}^{2} E_{i} & =\Omega .
\end{aligned}
$$

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- What happens after we have extracted one ball and looked its color?
- Intuitively feel how to roughly change our opinion about
- the possible cause
- a future observation


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- Can we do it quantitatively, in an 'objective way'?


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- What happens after we have extracted one ball and looked its color?
- Intuitively feel how to roughly change our opinion about
- the possible cause
- a future observation
- Can we do it quantitatively, in an 'objective way'?
- And after a sequence of extractions?


## The toy inferential experiment

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This toy experiment is conceptually very close to what we do in Physics
$\Rightarrow$ try to guess what we cannot see (the electron mass, a branching ratio, etc)
... from what we can see (somehow) with our senses.
The rule of the game is that we are not allowed to watch inside the box! (As we cannot open an electron and read its properties, unlike we read the MAC address of a PC interface.)

## Where is probability?

We all agree that the experimental results change

- the probabilities of the box compositions;
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## Where is the probability? Certainly not in the box!

## Subjective nature of probability

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Probability depends on the status of information of the subject who evaluates it.

## Probability is always conditional probability

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where $I_{s}$ is the information available to subject $s$.

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## $\longrightarrow$ Three boxes TV contests

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$\Rightarrow$ How much we believe something

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$\rightarrow$ 'Degree of belief' $\leftarrow$

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"The usual touchstone, whether that which someone asserts is merely his persuasion - or at least his subjective conviction, that is, his firm belief - is betting. It often happens that someone propounds his views with such positive and uncompromising assurance that he seems to have entirely set aside all thought of possible error. A bet disconcerts him. Sometimes it turns out that he has a conviction which can be estimated at a value of one ducat, but not of ten. For he is very willing to venture one ducat, but when it is a question of ten he becomes aware, as he had not previously been, that it may very well be that he is in error." (Kant)


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, Coherent bet:
- you state the odds according on your beliefs;
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"His [Bouvard] calculations give him the mass of Saturn as 3,512 th part of that of the sun. Applying my probabilistic formulae to these observations, I find that the odds are 11,000 to 1 that the error in this result is not a hundredth of its value." (Laplace)


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$\rightarrow P\left(3477 \leq M_{\text {Sun }} / M_{\text {Sat }} \leq 3547 \mid I(\right.$ Laplace $\left.)\right)=99.99 \%$


## ‘C.L.’ Vs Degree of Confidence

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Hint: $P\left(\theta \leq \theta_{o b s} \mid m_{0}\right) \neq P\left(m \geq m_{o} \mid \theta_{o b s}\right)!\mid$
$\Rightarrow$ more in second lecture.

## Standard textbook definitions

$$
p=\frac{\# \text { favorable cases }}{\# \text { possible equiprobable cases }}
$$

$p=\frac{\# \text { times the event has occurred }}{\# \text { independent trials under same conditions }}$

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It is easy to check that 'scientific' definitions suffer of circularity

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Note!: "Iorsque rien ne porte à croire que l'un de ces cas doit arriver plutot que les autres" (Laplace)
Replacing 'equi-probable’ by 'equi-possible' is just cheating students (as I did in my first lecture on the subject...).

## Standard textbook definitions

It is easy to check that 'scientific' definitions suffer of circularity, plus other problems

$n \rightarrow \infty: \rightarrow$ "usque tandem?"
$\rightarrow$ "in the long run we are all dead"
$\rightarrow$ It limits the range of applications

## 'Definitions' $\rightarrow$ evaluation rules

Very useful evaluation rules

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BUT they cannot define the concept of probability!

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- Rule $A$ is recovered immediately (under the assumption of equiprobability, when it applies).
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In the probabilistic approach we are following

- Rule $A$ is recovered immediately (under the assumption of equiprobability, when it applies).
- Rule $B$ results from a theorem (under well defined assumptions): $\Rightarrow$ Laplace's rule of succession


## Unifying role of subjective probability

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- Probability statements all have the same meaning no matter to what they refer and how the number has been evaluated.
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- $P\left(M_{H} \leq 125.5 \mathrm{GeV}\right)=68 \%$
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They all convey unambiguously the same confidence on something.

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- You might agree or disagree, but at least You know what this person has in his mind. (NOT TRUE with "C.L.'s"!)
- If a person has these beliefs and he/she has the chance to win a rich prize bound to one of these events, he/she is indifferent to the choice.


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## We can talk very naturally about probabilities of true values!

## Probability Vs "probability",

## Errors on ratios of small numbers of events F. James ${ }^{(*)}$ and M. Roos <br> Nucl. Phys. B172 (1980) 475

(http://ccdb4fs.kek.jp/cgi-bin/img_index?8101205)

When the result of the measurement of a physical quantity is published as $R=R_{0} \pm \sigma_{0}$ without further explanation, it is implied that $R$ is a Gaussiandistributed measurement with mean $R_{0}$ and variance $\sigma_{0}{ }^{2}$. This allows one to calculate various confidence intervals of given "probability", i.e. the "probability" P that the true value of $R$ is within a given interval. $P$ is given by the area under the corresponding part of the Gaussian curve, and is the basis of well-known rules-of-thumb such as "the probability of exceeding two standard deviations is $5 \%^{\prime \prime}$.
${ }^{(*)}$ Influential CERN 'frequentistic guru' of HEP community

## Mathematics of beliefs

## The good news:

The basic laws of degrees of belief are the same we get from the inventory of favorable and possible cases, or from events occurred in the past.
[Details skipped...]

## Basic rules of probability

1. $0 \leq P(A \mid I) \leq 1$
2. $\quad P(\Omega \mid I)=1$
3. $\quad P(A \cup B \mid I)=P(A \mid I)+P(B \mid I) \quad[$ if $P(A \cap B \mid I)=\emptyset]$
4. $\quad P(A \cap B \mid I)=P(A \mid B, I) \cdot P(B \mid I)=P(B \mid A, I) \cdot P(A \mid I)$

Remember that probability is always conditional probability!
$I$ is the background condition (related to information ' $I_{s}^{\prime}$ )
$\rightarrow$ usually implicit (we only care on 're-conditioning')

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1. $0 \leq P(A \mid I) \leq 1$
2. $\quad P(\Omega \mid I)=1$
3. $P(A \cup B \mid I)=P(A \mid I)+P(B \mid I) \quad[$ if $P(A \cap B \mid I)=\emptyset]$
4. $\quad P(A \cap B \mid I)=P(A \mid B, I) \cdot P(B \mid I)=P(B \mid A, I) \cdot P(A \mid I)$

Remember that probability is always conditional probability! $I$ is the background condition (related to information ' $I_{s}^{\prime}$ ) $\rightarrow$ usually implicit (we only care on 're-conditioning')

Note: 4. does not define conditional probability.
(Probability is always conditional probability!)

## Mathematics of beliefs

## An even better news:

## The fourth basic rule can be fully exploided!

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## The fourth basic rule can be fully exploided!

(Liberated by a curious ideology that forbits its use)

## A simple, powerful formula



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$$
P(A|B| I) P(B \mid I)=P(B \mid A, I) P(A \mid I)
$$

## A simple, powerful formula



## A simple, powerful formula



## Laplace's "Bayes Theorem"

"The greater the probability of an observed event given any one of a number of causes to which that event may be attributed, the greater the likelihood of that cause \{given that event\}.

$$
P\left(C_{i} \mid E\right) \propto P\left(E \mid C_{i}\right)
$$

## Laplace's "Bayes Theorem"

"The greater the probability of an observed event given any one of a number of causes to which that event may be attributed, the greater the likelihood of that cause \{given that event\}. The probability of the existence of any one of these causes \{given the event\} is thus a fraction whose numerator is the probability of the event given the cause, and whose denominator is the sum of similar probabilities, summed over all causes.

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P\left(C_{i} \mid E\right)=\frac{P\left(E \mid C_{i}\right)}{\sum_{j} P\left(E \mid C_{j}\right)}
$$

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"The greater the probability of an observed event given any one of a number of causes to which that event may be attributed, the greater the likelihood of that cause \{given that event\}. The probability of the existence of any one of these causes \{given the event\} is thus a fraction whose numerator is the probability of the event given the cause, and whose denominator is the sum of similar probabilities, summed over all causes. If the various causes are not equally probable a priory, it is necessary, instead of the probability of the event given each cause, to use the product of this probability and the possibility of the cause itself."

$$
P\left(C_{i} \mid E\right)=\frac{P\left(E \mid C_{i}\right) P\left(C_{i}\right)}{\sum_{j} P\left(E \mid C_{j}\right) P\left(C_{j}\right)}
$$

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"This is the fundamental principle (*) of that branch of the analysis of chance that consists of reasoning a posteriori from events to causes"
(*) In his "Philosophical essay" Laplace calls 'principles' the 'fondamental rules'.

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"This is the fundamental principle (*) of that branch of the analysis of chance that consists of reasoning a posteriori from events to causes"
(*) In his "Philosophical essay" Laplace calls 'principles' the 'fondamental rules'.

Note: denominator is just a normalization factor.

$$
\Rightarrow \quad P\left(C_{i} \mid E\right) \propto P\left(E \mid C_{i}\right) P\left(C_{i}\right)
$$

Most convenient way to remember Bayes theorem

## Telling it with Gauss' words

A reference to the Princeps Mathematicorum (Prince of Mathematicians) is a must in this town and in this place.

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P\left(C_{i} \mid \text { data }\right)=\frac{P\left(\text { data } \mid C_{i}\right)}{P(\text { data })} P_{0}\left(C_{i}\right)
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"post illa observationes" "ante illa observationes"
(Gauss)

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"post illa observationes" "ante illa observationes"
(Gauss)
Arguments used to derive Gaussian distribution

- $f(\mu \mid\{x\}) \propto f(\{x\} \mid \mu) \cdot f_{0}(\mu)$
- $f_{0}(\mu)$ 'flat' (all values a priory equally possible)
- posterior maximized at $\mu=\bar{x}$


## Cause-effect representation

## box content $\rightarrow$ observed color



## Cause-effect representation

## box content $\rightarrow$ observed color



An effect might be the cause of another effect


## A network of causes and effects



[^0]
## A network of causes and effects


and so on...
$\Rightarrow$ Physics applications

## Inferring 'proportions’

Let's turn the toy experiment to a 'serious' physics case:

- Inferring $H_{j}$ is the same as inferring the proportion of white balls:

$$
H_{j} \longleftrightarrow j \longleftrightarrow p=\frac{j}{5}
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$$
n: \quad 6 \rightarrow \infty
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$\Rightarrow p$ continous in $[0,1]$

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$$

$\Rightarrow p$ continous in $[0,1]$

- Generalize White/Black $\longrightarrow$ Success/Failure
$\Rightarrow$ efficiencies, branching ratios, ...


## Inferring Bernoulli's trial parameter $p$

Making several independent trials assuming the same $p$


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"independent Bernoulli trials"

"binomial distribution"

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Making several independent trials assuming the same $p$

"independent Bernoulli trials"

"binomial distribution"
$\Rightarrow$ In the light of the experimental information there will be values of $p$ we shall believe more, and others we shall believe less.

## Inferring Bernoulli's trial parameter $p$

Making several independent trials assuming the same $p$

"independent Bernoulli trials"

$$
\begin{gathered}
P\left(p_{i} \mid O_{1}, O_{2}, \ldots\right) \\
f\left(p \mid O_{1}, O_{2}, \ldots\right)
\end{gathered}
$$


"binomial distribution"

$$
\begin{gathered}
P\left(p_{i} \mid X, n\right) \\
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$$
\propto f\left(O_{1}, O_{2}, \ldots \mid p\right) \cdot f_{0}(p)
$$


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Are the two inferences the same?
(not obvious in principle)

## Graphical models

Before analysing in some detail this case let's make an overview of other important cases in physics

## Graphical models

Before analysing in some detail this case let's make an overview of other important cases in physics
$\Rightarrow$ Nowadays, thanks to progresses in mathematics and computing, drawing the problem as a 'belief network' is more than 1/2 step towards its solution!

## Signal and background



## Signal and background



## A different way to view fit issues



Determistic link $\mu_{x}$ 's to $\mu_{y}$ 's
Probabilistic links $\mu_{x} \rightarrow x, \mu_{y} \rightarrow y$
(errors on both axes!)
$\Rightarrow$ aim of fit: $\{\boldsymbol{x}, \boldsymbol{y}\} \rightarrow \boldsymbol{\theta}$

## A different way to view fit issues



Determistic link $\mu_{x}$ 's to $\mu_{y}$ 's
Probabilistic links $\mu_{x} \rightarrow x, \mu_{y} \rightarrow y$
(errors on both axes!)
$\Rightarrow$ aim of fit: $\{\boldsymbol{x}, \boldsymbol{y}\} \rightarrow \boldsymbol{\theta}$


Extra spread of the data points

## A different way to view fit issues

A physics case (from Gamma ray burts):

(Guidorzi et al., 2006)

## A different way to view fit issues



Adding systematics

## A different way to view fit issues

## Stated differently:



## A different way to view fit issues

Only systematics (on both axes)


## A different way to view fit issues

## In this approach systematic effects reflect our uncertainty

$\Rightarrow$ they can be handled rigorousely using probability theory!

## Unfolding a discretized spectrum

Probabilistic links: Cause-bins $\leftrightarrow$ effect-bins


## Unfolding a discretized spectrum

Probabilistic links: Cause-bins $\leftrightarrow$ effect-bins


Sharing the observed events among the cause-bins


## Unfolding a discretized spectrum

Academic (quite nasty!) smearing matrices:



## Unfolding a discretized spectrum

Academic (quite nasty!) smearing matrices:



## Application to the six box problem



Remind:

- $E_{1}=$ White
- $E_{2}=$ Black


## Collecting the pieces of information we need

Our tool:

$$
P\left(H_{j} \mid E_{i}, I\right)=\frac{P\left(E_{i} \mid H_{j}, I\right)}{P\left(E_{i} \mid I\right)} P\left(H_{j} \mid I\right)
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- $P\left(H_{j} \mid I\right)=1 / 6$
- $P\left(E_{i} \mid I\right)=1 / 2$
- $P\left(E_{i} \mid H_{j}, I\right)$ :

$$
\begin{aligned}
& P\left(E_{1} \mid H_{j}, I\right)=j / 5 \\
& P\left(E_{2} \mid H_{j}, I\right)=(5-j) / 5
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$\xrightarrow{\rightarrow} P\left(H_{j} \mid I\right)=1 / 6$

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\end{aligned}
$$

Our prior belief about $H_{j}$

## Collecting the pieces of information we need

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- $P\left(H_{j} \mid I\right)=1 / 6$
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\end{aligned}
$$

Probability of $E_{i}$ under a well defined hypothesis $H_{j}$ It corresponds to the 'response of the apparatus in measurements.
$\rightarrow$ likelihood (traditional, rather confusing name!)

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Probability of $E_{i}$ taking account all possible $H_{j}$
$\rightarrow$ How much we are confident that $E_{i}$ will occur.

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Probability of $E_{i}$ taking account all possible $H_{j}$
$\rightarrow$ How much we are confident that $E_{i}$ will occur.
We can rewrite it as

$$
P\left(E_{i} \mid I\right)=\sum_{j} P\left(E_{i} \mid H_{j}, I\right) \cdot P\left(H_{j} \mid I\right)
$$

Now that we have set up our formalism, let's play a little

- analyse real data
- some simulations

Then

- $H_{j} \longleftrightarrow j \longleftrightarrow p_{j}$
- extending $p$ to a continuum:
$\Rightarrow$ Bayes' billiard
(prototype for all questions related to efficiencies, branching ratios)
- On the meaning of $p$


## Which box? Which ball?

Inferential/forecasting history:

1. $k=0$
$P_{0}\left(H_{j}\right)=P\left(H_{j} \mid I_{0}\right)$ (priors)
2. begin loop:
$k=k+1$
$\Rightarrow E^{(k)}$
( $k$-th extraction)
3. $P_{k}\left(H_{j} \mid I_{k}\right) \propto P\left(E^{(k)} \mid H_{j}\right) \times P_{k-1}\left(H_{j} \mid I_{k}\right)$

$$
P_{k}\left(E_{i} \mid I_{k}\right)=\sum_{j} P\left(E_{i} \mid H_{j}\right) \cdot P_{k}\left(H_{j} \mid I_{k}\right)
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4. $\rightarrow$ go to 2

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4. $\rightarrow$ go to 2

## Bayes' billiard

This is the original problem in the theory of chances solved by Thomas Bayes in late '700:

- imagine you roll a ball at random on a billiard;
- you mark the relative position of the ball along the billiard's length $(l / L)$ and remove the ball
- then you roll at random other balls
- write down if it stopped left or right of the first ball;
- remove it and go on with $n$ balls.
- Somebody has to guess the position of the first ball knowing only how mane balls stopped left and how many stoppe right


## Bayes' billiard and Bernoulli trials

It is easy to recongnize the analogy:

- Left/Right $\rightarrow$ Success/Failure
- if Left $\leftrightarrow$ Success:
- $l / L \leftrightarrow p$ of binomial (Bernoulli trials)


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f(p \mid S, S, F) & \propto f(F \mid p) \cdot f(p \mid S, S)=p^{2}(1-p)
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\cdots & \cdots \\
f(p \mid \# S, \# F) & \propto p^{\# S}(1-p)^{\# F}=p^{\# S}(1-p)^{(1-\# s)}
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f(p \mid x, n) & \propto p^{x}(1-p)^{(n-x)} \quad[x=\# S]
\end{aligned}
$$

## Parametric inference

$\rightarrow$ Choose a model and infer its parameter(s).
Bayes theorem for continuous variables has following structure

```
f(0|data) \proptof(data |0) f0}0(0
```

$$
\begin{aligned}
f(p \mid x, n, \mathcal{B}) & =\frac{f\left(x \mid \mathcal{B}_{n, p}\right) f_{0}(p)}{\int_{0}^{1} f\left(x \mid \mathcal{B}_{n, p}\right) f_{0}(p) d p} \\
& =\frac{\frac{n!}{(n-x)!x!} p^{x}(1-p)^{n-x} f_{0}(p)}{\int_{0}^{1} \frac{n!}{(n-x)!x!} p^{x}(1-p)^{n-x} f_{0}(p) d p} \\
& =\frac{p^{x}(1-p)^{n-x}}{\int_{0}^{1} p^{x}(1-p)^{n-x} d p},
\end{aligned}
$$

## Inferring the Binomial $p$

$$
f(p \mid x, n, \mathcal{B})=\frac{(n+1)!}{x!(n-x)!} p^{x}(1-p)^{n-x}
$$




## Inferring the Binomial $p$

$f(p \mid x, n, \mathcal{B})=\frac{(n+1)!}{x!(n-x)!} p^{x}(1-p)^{n-x}$,

$$
\mathrm{E}(p)=\frac{x+1}{n+2} \quad \text { Laplace's rule of successions }
$$

$\operatorname{Var}(p)=\frac{(x+1)(n-x+1)}{(n+3)(n+2)^{2}}$
$=\mathrm{E}(p)(1-\mathrm{E}(p)) \frac{1}{n+3}$.

## Interpretation of $\mathbf{E}(p)$

Think at any future event $E_{i>n}$ $\Rightarrow$ if we were sure of $p$, then our confidence on $E_{i>n}$ will be exactly $p$, i.e.

$$
P\left(E_{i} \mid p\right)=p .
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$$

But we are uncertain about $p$. How much should we believe $E_{i>n}$ ?.

$$
\begin{aligned}
P\left(E_{i>n} \mid x, n, \mathcal{B}\right) & =\int_{0}^{1} P\left(E_{i} \mid p\right) f(p \mid x, n, \mathcal{B}) \mathrm{d} p \\
& =\int_{0}^{1} p f(p \mid x, n, \mathcal{B}) \mathrm{d} p \\
& =\mathrm{E}(p) \\
& =\frac{x+1}{n+2} \quad \text { (for uniform prior). }
\end{aligned}
$$

## From frequencies to probabilities

$$
\begin{aligned}
\mathrm{E}(p) & =\frac{x+1}{n+2} \quad \text { Laplace's rule of successions } \\
\operatorname{Var}(p) & =\mathrm{E}(p)(1-\mathrm{E}(p)) \frac{1}{n+3} .
\end{aligned}
$$

For 'large' $n, x$ and $n-x$ : asymptotic behaviors of $f(p)$ :

$$
\begin{aligned}
\mathrm{E}(p) & \approx p_{m}=\frac{x}{n} \quad\left[\text { with } p_{m} \text { mode of } f(p)\right] \\
\sigma_{p} & \approx \sqrt{\frac{p_{m}\left(1-p_{m}\right)}{n}} \underset{n \rightarrow \infty}{ } 0 \\
p & \sim \mathcal{N}\left(p_{m}, \sigma_{p}\right) .
\end{aligned}
$$

Under these conditions the frequentistic "definition" (evaluation rule!) of probability $(x / n)$ is recovered.

## Special case with $x=0$

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f(p \mid 0, n, \mathcal{B}) & =(n+1)(1-p)^{n} \\
F(p \mid 0, n, \mathcal{B}) & =1-(1-p)^{n+1} \\
p_{m} & =0 \\
\mathrm{E}(p) & =\frac{1}{n+2} \longrightarrow \frac{1}{n} \\
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P\left(p \leq p_{u} \mid 0, n, \mathcal{B}\right) & =95 \% \\
& \Rightarrow p_{u}=1-\sqrt[n+1]{0.05}
\end{aligned}
$$

Probabilistic upper bound

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$\Rightarrow p_{m}=1 \quad$ [mode of posterior]
$\Rightarrow \mathrm{E}[p]=\int_{0}^{1} p f(p) d p=\frac{n+1}{n+2} \quad$ [expected value]


## Special case with $x=n$

$$
\begin{aligned}
\sigma^{2}(p) & =\mathrm{E}\left[(p-\mathrm{E}[p])^{2}\right]=\mathrm{E}\left[p^{2}\right]-\mathrm{E}^{2}[p] \\
& =\int_{0}^{1} p^{2} f(p) d p-\left(\frac{n+1}{n+2}\right)^{2} \\
& =\frac{n+1}{n+3}-\frac{(n+1)^{2}}{(n+2)^{2}}=\frac{n+1}{(n+3)(n+2)^{2}} \\
& \rightarrow \frac{1}{n^{2}} .
\end{aligned}
$$

$\Rightarrow$ Asymptotically $(n \rightarrow \infty)$ the variance is the same for the two cases $x=0$ and $x=n$ (just a question of symmetry)

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- A property of a physical system to behave in a certain way ('chance' $\rightarrow$ 'propensity').
The six box model can help to make the question clear.

$\mathrm{H}_{0}$
$\mathrm{H}_{1}$
$\mathrm{H}_{2}$
$\square$



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There is no need to adhere to the frequentistic ideology to say this

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Instead, "probability is the limit of frequency for $n \rightarrow \infty$ " is not more than an empty statement.

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Probability theory (in Laplage's sense) allows to attach probabilities to whatever we feel uncertain about!

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- Other important parameters are related to background, systematics, 'etc.' [arguments not covere here]


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(Diffidate chi vi promette di far germogliar zecchini nel Campo dei Miracoli! - Collodi docet)


## Conclusions

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- It makes little sense to stick to old 'ah hoc' methods that had their raison d'être in the computational barrier.
- Mistrust all results that sound as 'confidence', 'probability' etc about physics quantities, if they are obtained by methods that do not contemplate 'beliefs'.


## .. . postponed preamble

"The celebrated Monsieur Leibnitz has observed it to be a defect in the common systems of logic, that they are very copious when they explain the operations of the understanding in the forming of demonstrations, but are too concise when they treat of probabilities, and those other measures of evidence on which life and action entirely depend, and which are our guides even in most of our philosophical speculations."
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$\Rightarrow$ still very true after $\approx 300$ years!
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And, by the way, for those who

- are not familiar with David Hume
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"The type of critical reasoning which was required for the discovery of this central point was decisively furthered, in my case, especially by the reading of David Hume's and Ernst Mach's philosophical writings."
[And, in a different writing,]
"It is to the immortal credit of D. Hume and E. Mach that they, above all others, introduced this critical conception."
(Albert Einstein)


[^0]:    G. D'Agostini, Probabilistic Inference (Goettingen, 17 July 2012) - (C) G. D'Agostini - p. 35

