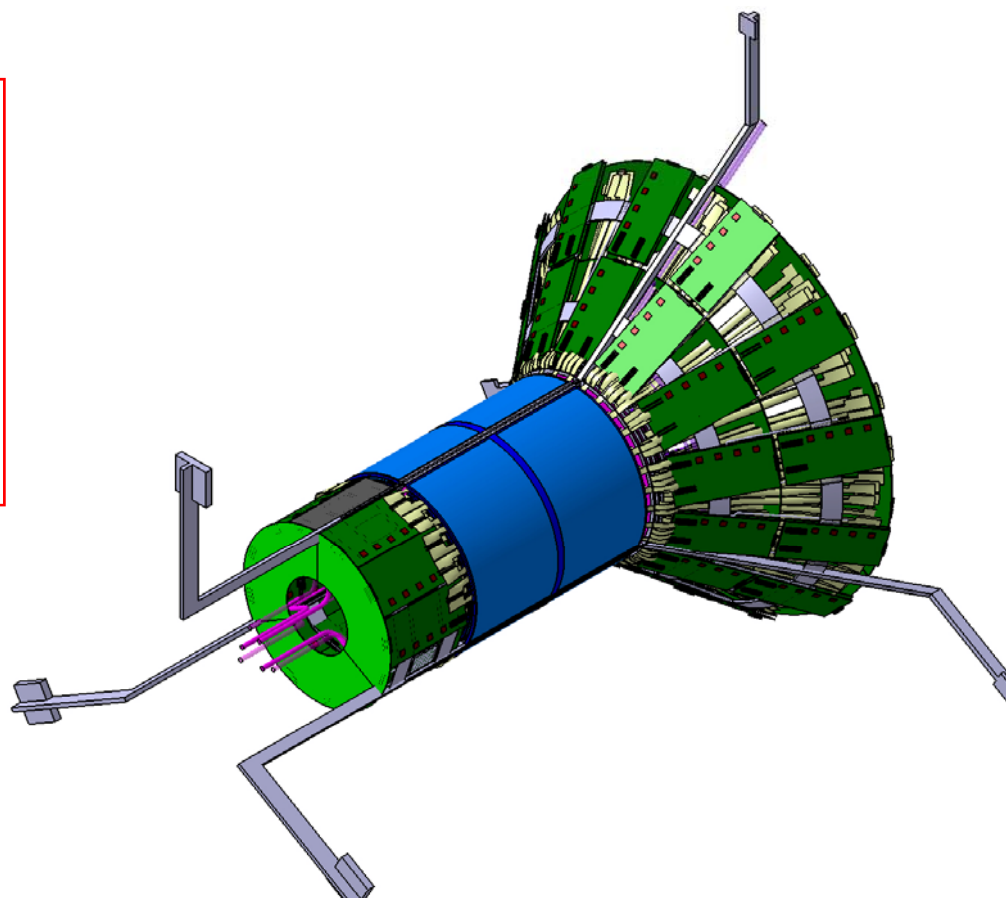


# Micromegas Tracker Project for CLAS12



Context  
Central tracker  
Bulk MM  
Simulations  
Tests



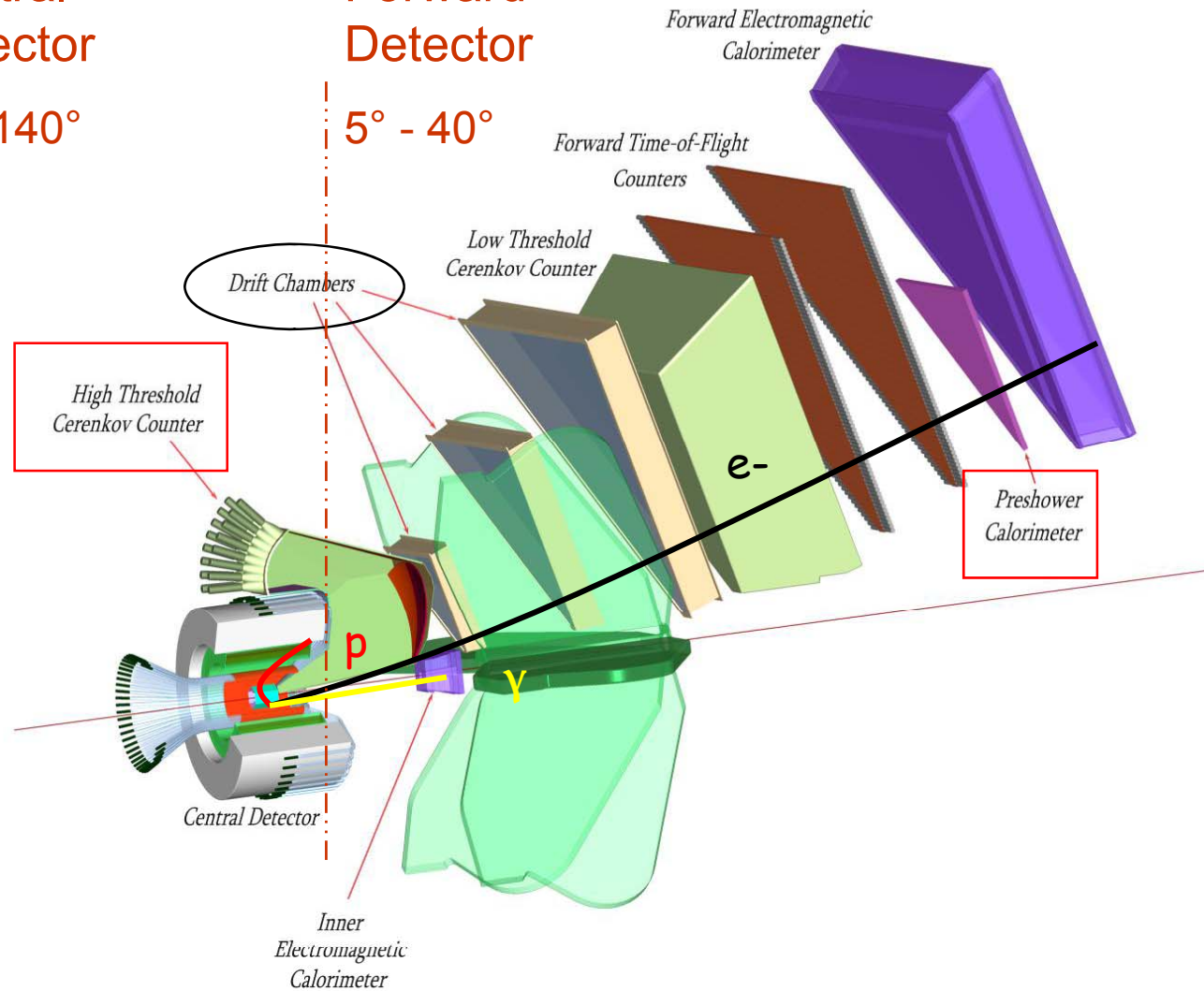
# CLAS UPGRADE = CLAS12

Central  
Detector

40°-140°

Forward  
Detector

5° - 40°



# CLAS upgrade for 11 GeV

## Physics constraints:

- higher momentum tracks, smaller cross sections

- **Detector goals:**

- 1% momentum resolution at 5 GeV/c

- capability to run at  $L = 10^{35} \text{ cm}^{-2}\text{s}^{-1}$ , good vertex resolution, reliability.

- **Detector designs:**

- Forward detector: (electrons, forward mesons)**

- Addition of high threshold Č counters **to improve  $e^-$  and  $\pi$  id.**

- Preshower to increase granularity of the calorimeter and discriminate  $\pi^0$  and  $\gamma$ .

- Revamping of regular equipment, DCs cells reduced, Torus modified to handle angular range from 5 to  $40^\circ$  (was 8 to  $142^\circ$ )

# CENTRAL DETECTOR

5 T Solenoid

Central Vertex Tracker

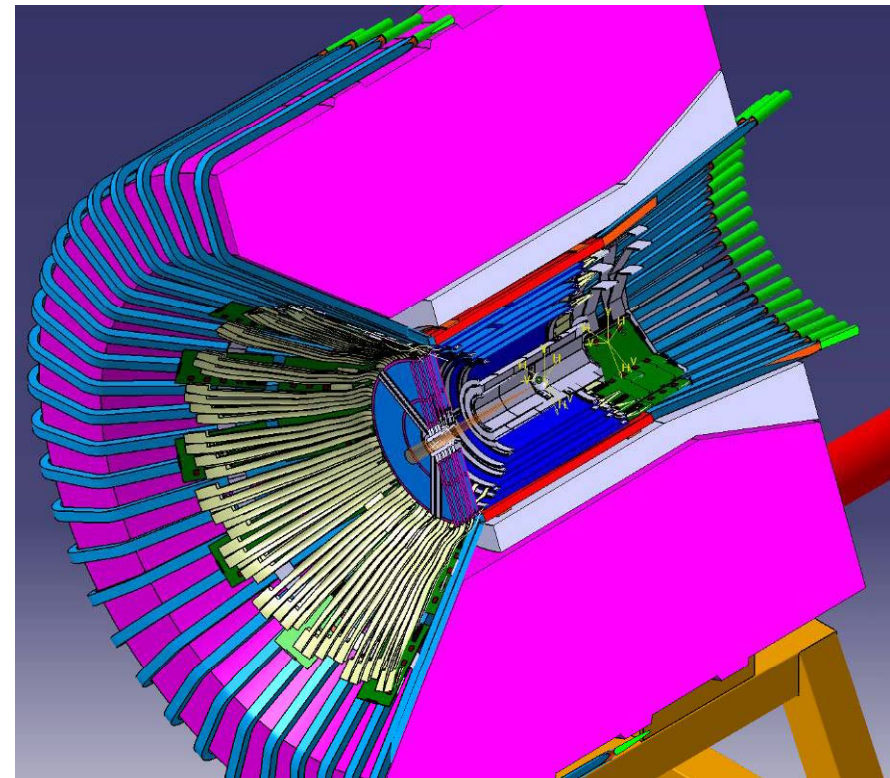
Forward vertex Tracker

Central Time of Flight

Neutron counter

Trigger rate : 10 kHz

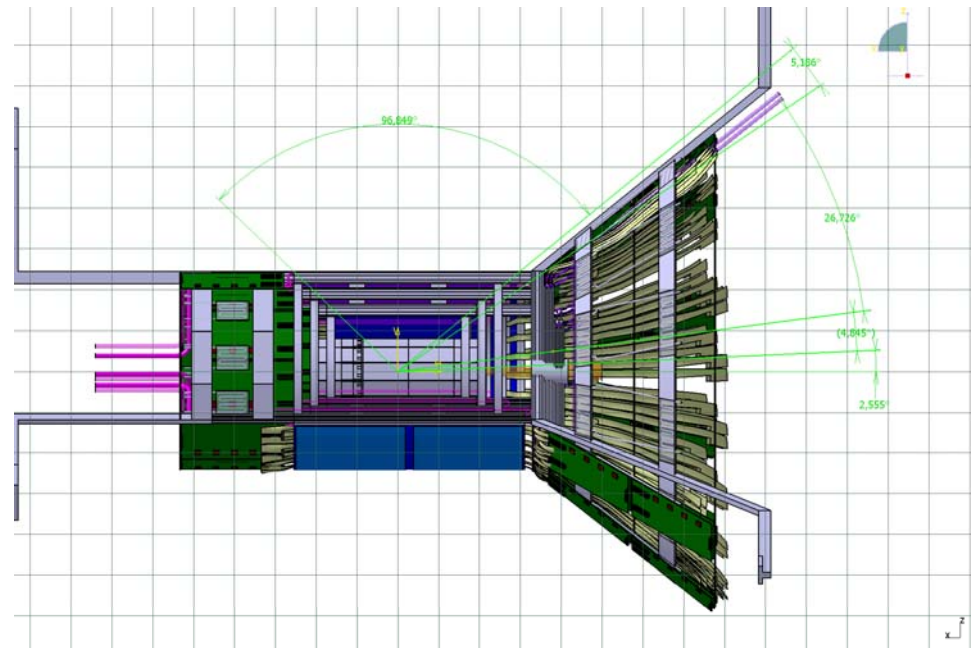
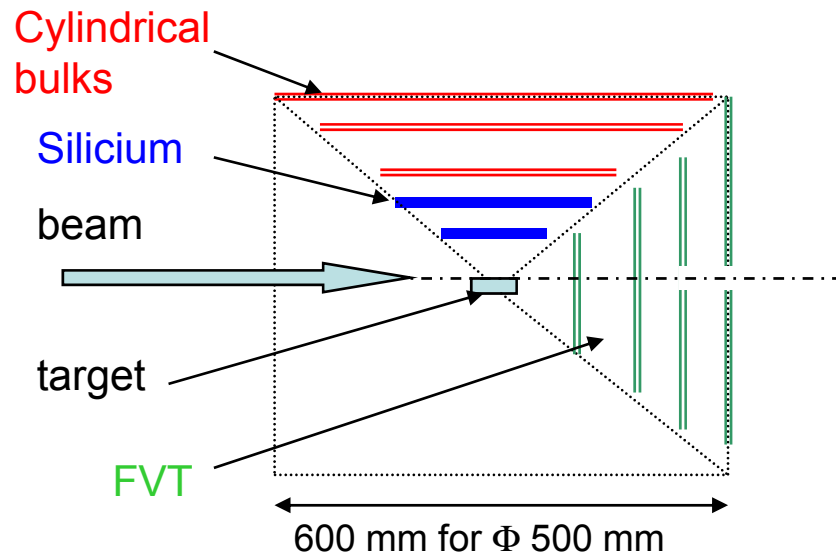
Singles rate : 2 – 20 MHz



# Bulk MM tracker Project

## Mixed solution: Silicium + Micromegas bulk

- Central detector
  - 2 planes of Silicium (X,Y)
  - 3 cylindrical bulks (XY): 3m<sup>2</sup>, pitch 0.6 mm ,10k channels.
- Forward detector
  - 4 plane bulks (XY): 1 m<sup>2</sup>, 3k channels.

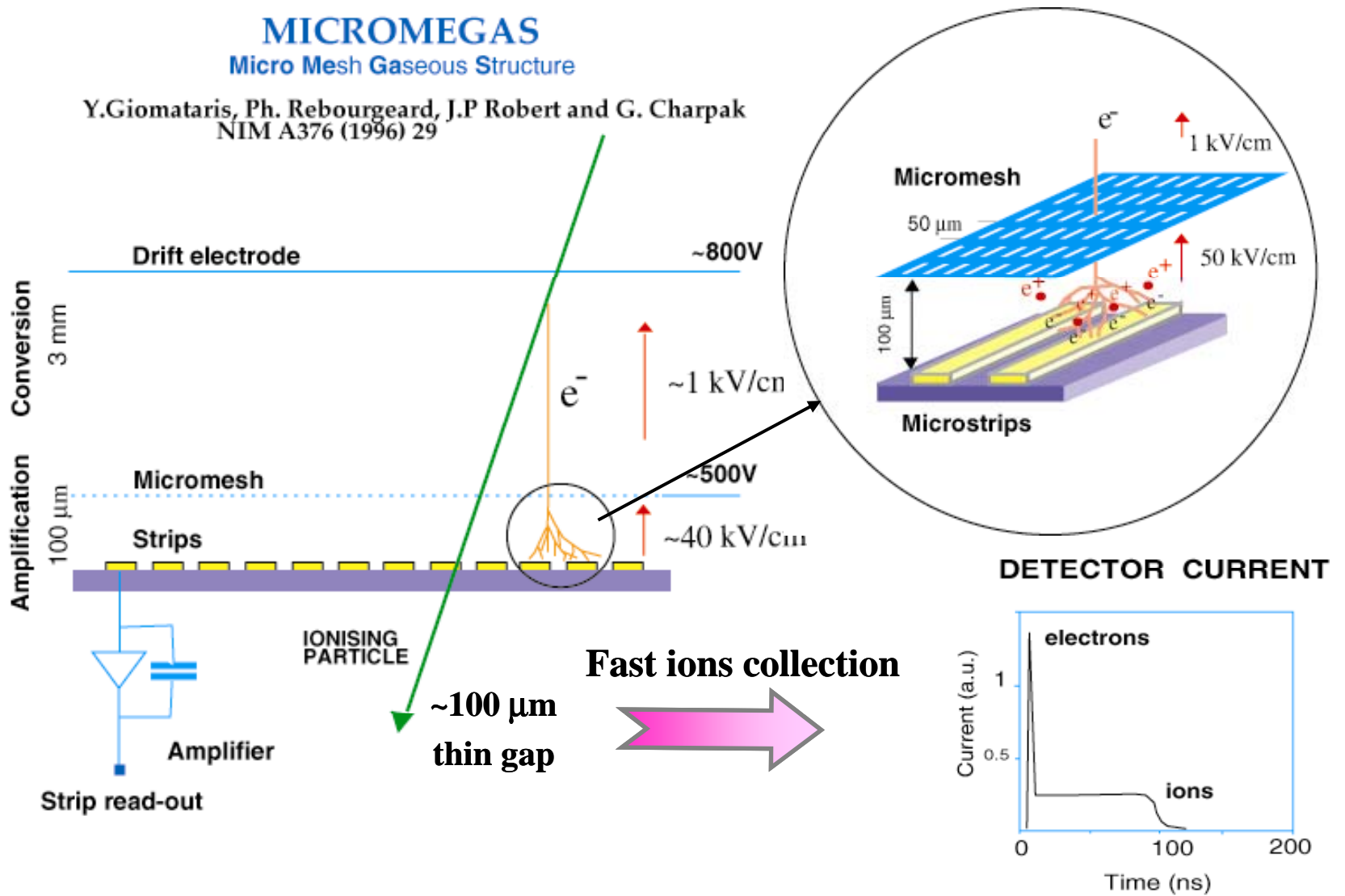


# What is a MicroMégas ?

## MICROME GAS

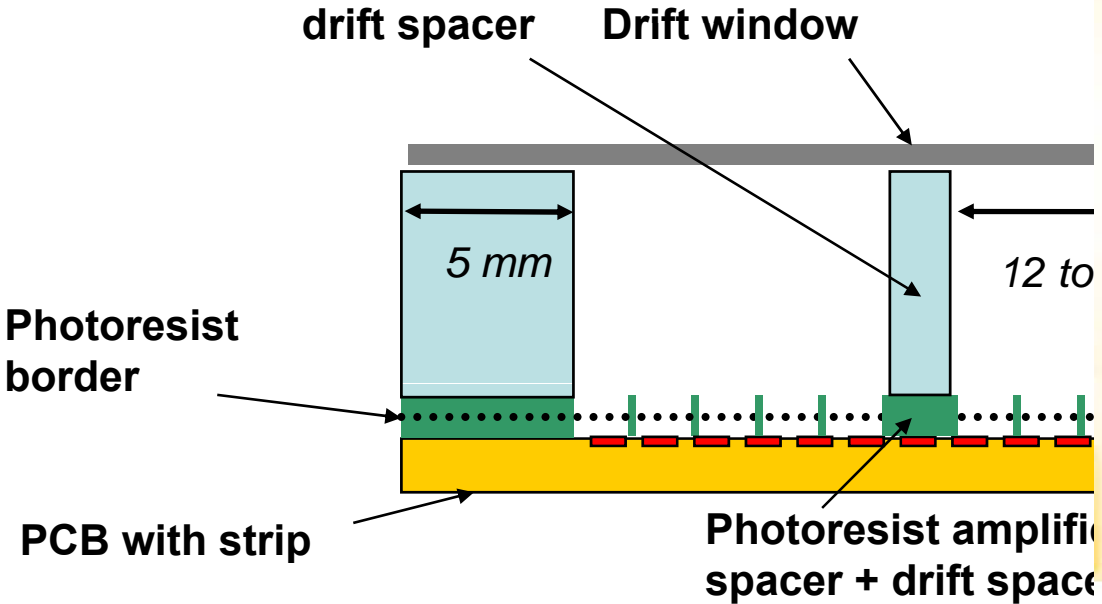
Micro Mesh Gaseous Structure

Y.Giomataris, Ph. Rebourgeard, J.P Robert and G. Charpak  
NIM A376 (1996) 29



# What is a bulk Micromegas ?

The basic idea is to build the whole detector in **one process**:  
 the anode plane with the copper strips,  
 a photo resistive film having the right thickness, and the cloth mesh  
 are laminated together at high temperature, forming a single object.  
 By photolithographic method then the photo resistive material is etched  
 producing the pillars.



# Resolutions comparison

(Sébastien Procureur)



(for  $\pi$  @ 0.6 GeV/c ,  $\theta = 90^\circ$ )

	4 x 2MM	4 x 2SI	2 x 2SI + 3 x 2MM	Specs.
$\sigma_{p_T}/p_T$ (%)	2.9	2.1	1.6	5
$\sigma_\theta$ (mrad)	1.3	15.1	1.4	10
$\sigma_\phi$ (mrad)	10.9	2.9	2.6	5
$\sigma_z$ ( $\mu\text{m}$ )	212	1522	267	tbd.

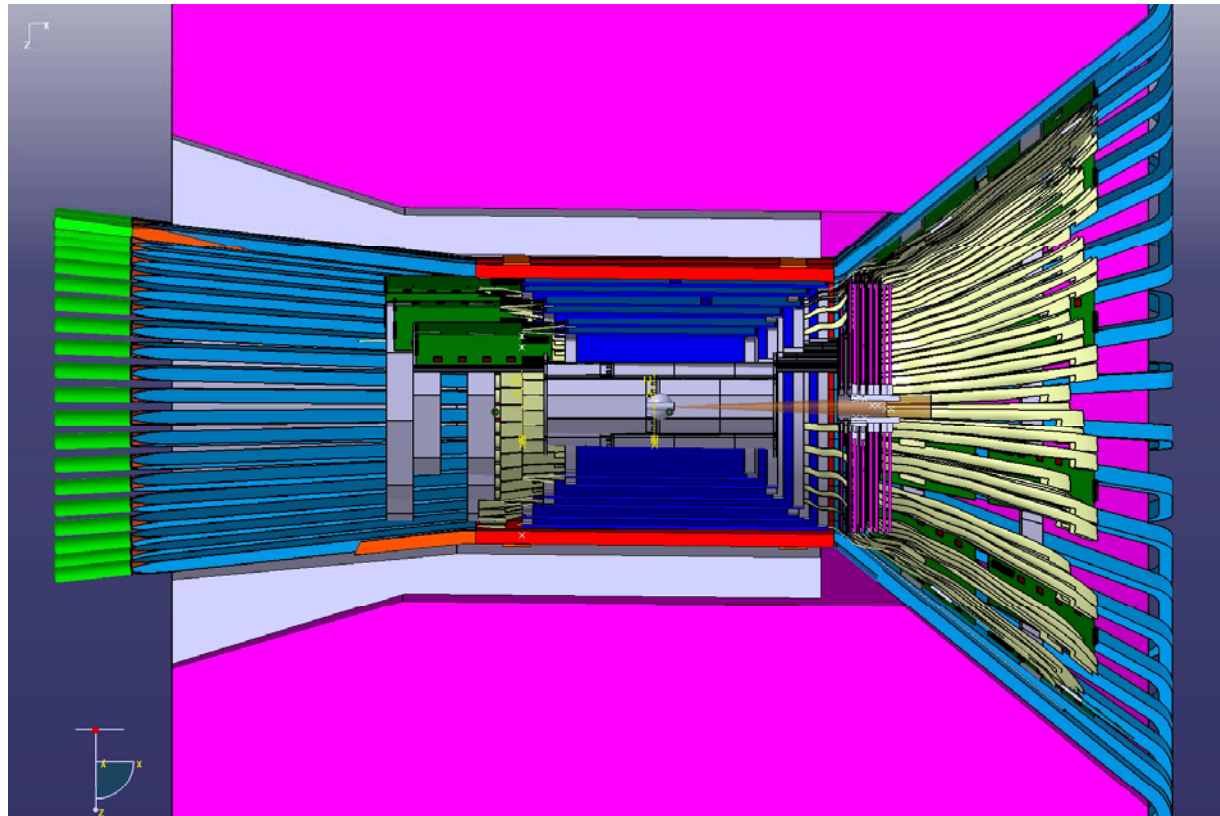
→ The mixed solution benefits of advantages from both SI and MM!

→ The « Si only » solution is never the best...



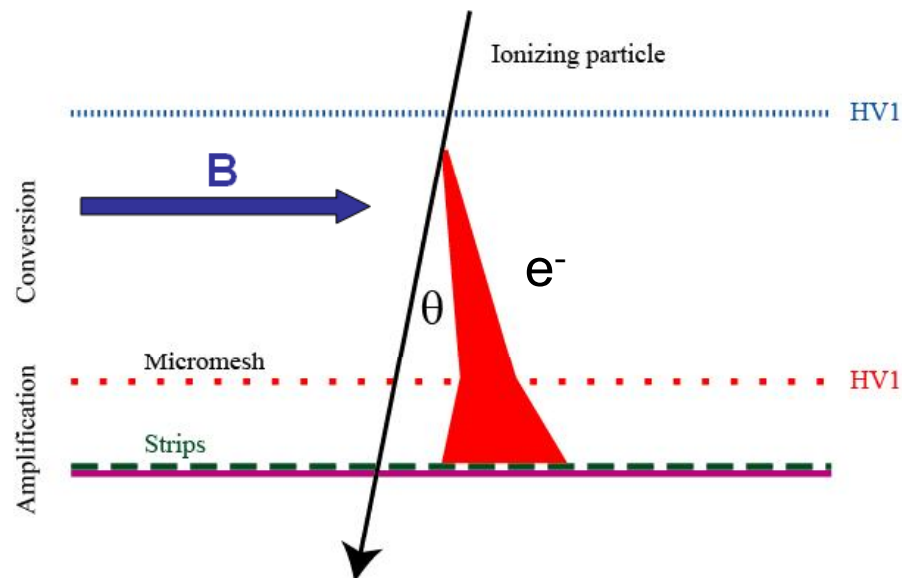
## MM tracker project Design

- Drawings to show difficulties and help to find solutions
- Mechanical structure, electronics integration



## Main issues to deal with ..

- Full characterization of a bulk cylindrical detector under different gas mixtures, with different radii.
- Magnetic environment to deal with : 5 T orthogonal to the detector !



$$\tan\theta = v \times B / E$$

Standard conditions :

$$E = 1 \text{ kV/cm}, v = 8 \text{ cm}/\mu\text{sec}$$

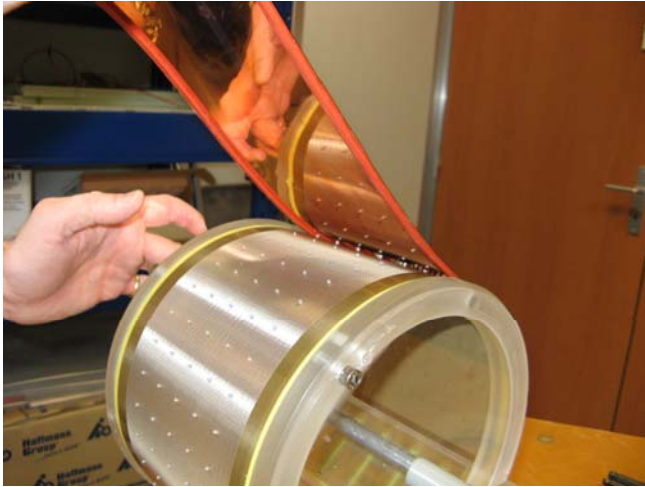
$$\theta = 75^\circ$$

Adapted conditions:

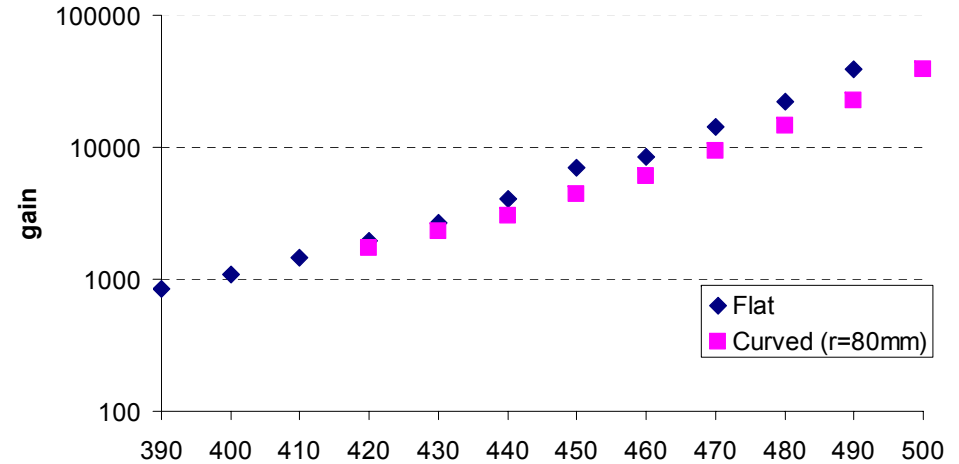
$$E = 10 \text{ kV/cm}, v = 5 \text{ cm}/\mu\text{sec}$$

$$\theta = 14^\circ$$

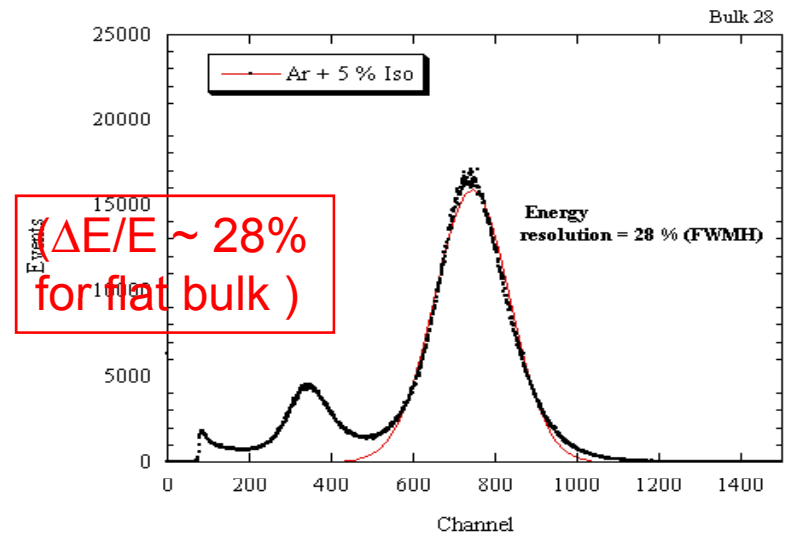
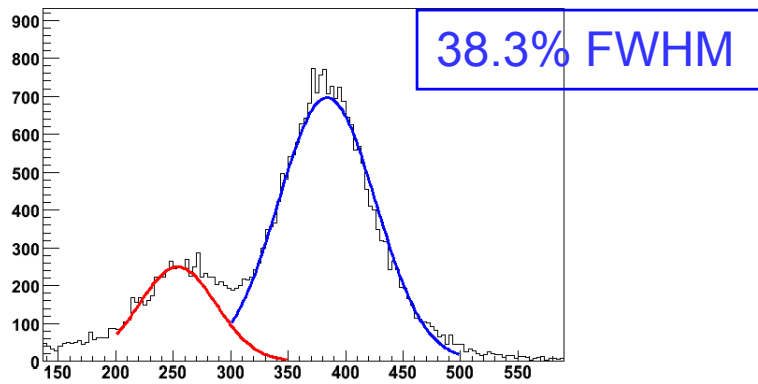
# Cylindrical prototypes tests



Flexible bulk (gap 150 microns)  
with Ar+ 5% C4H10



1<sup>st</sup> Fe<sup>55</sup> observed on a curved bulk



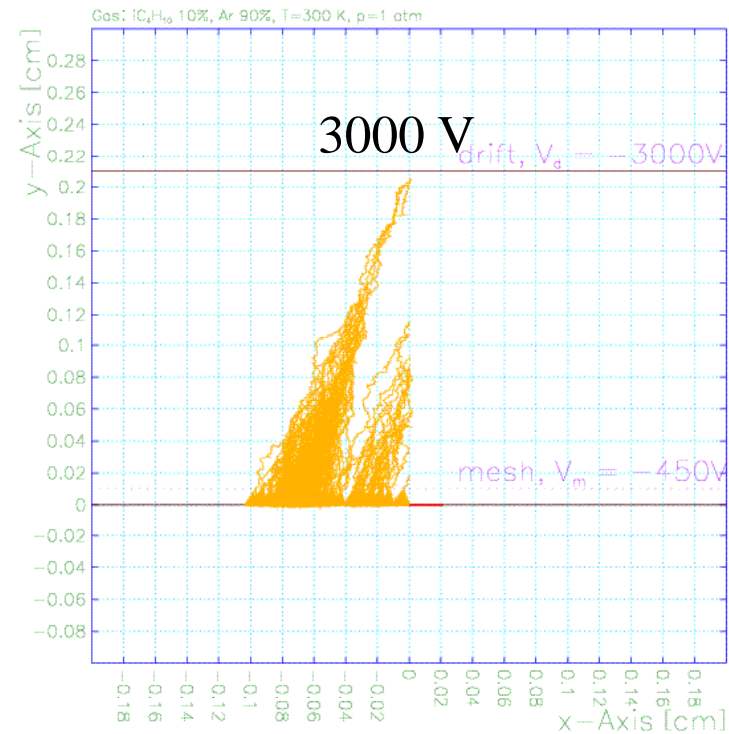
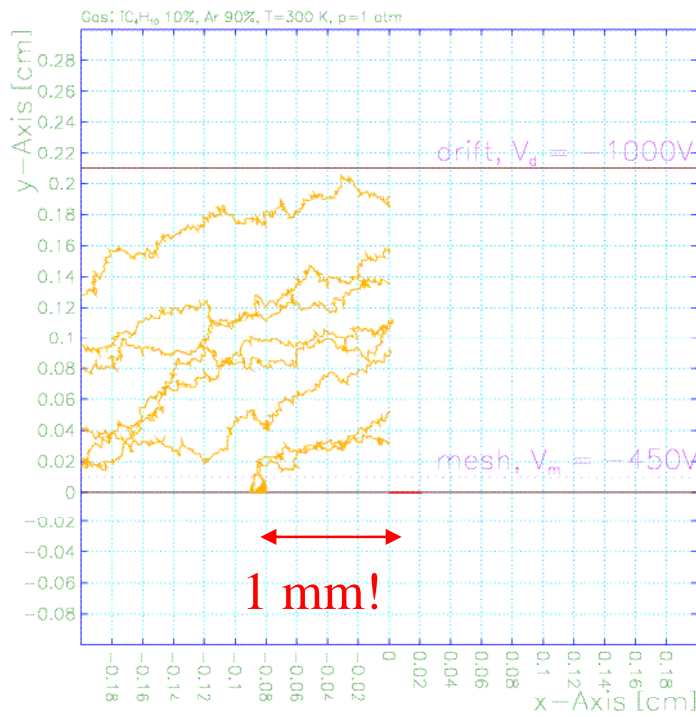
# B- Simulations (S. Procureur)

→ GARFIELD code (CERN)

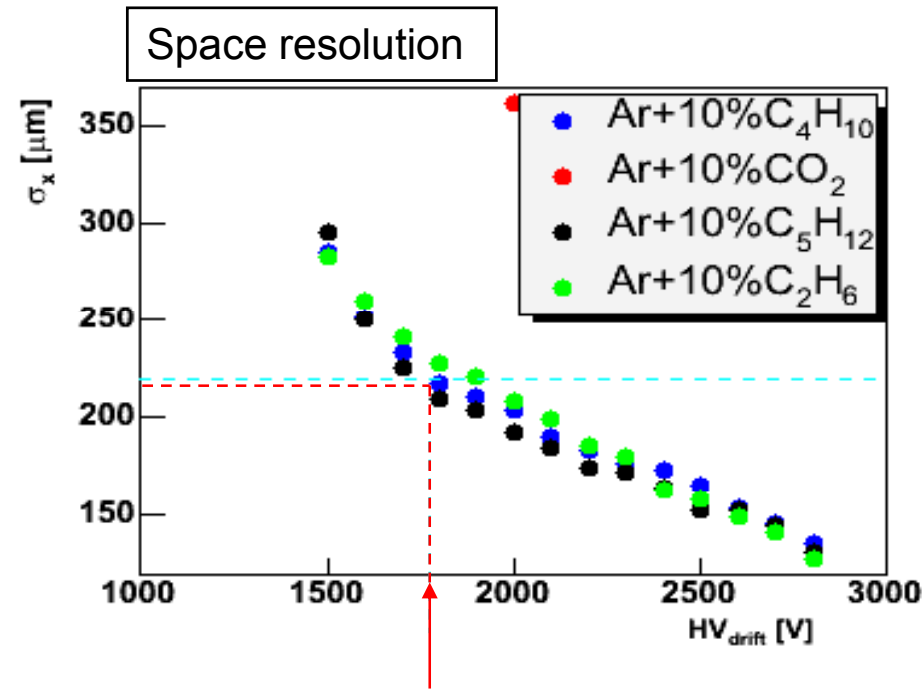
Regular electric field configuration :

- Large Lorentz angle (~ 75°)**
- higher drift field
- reduce conversion gap

Layout of the cell



# Why we need tests in B-field

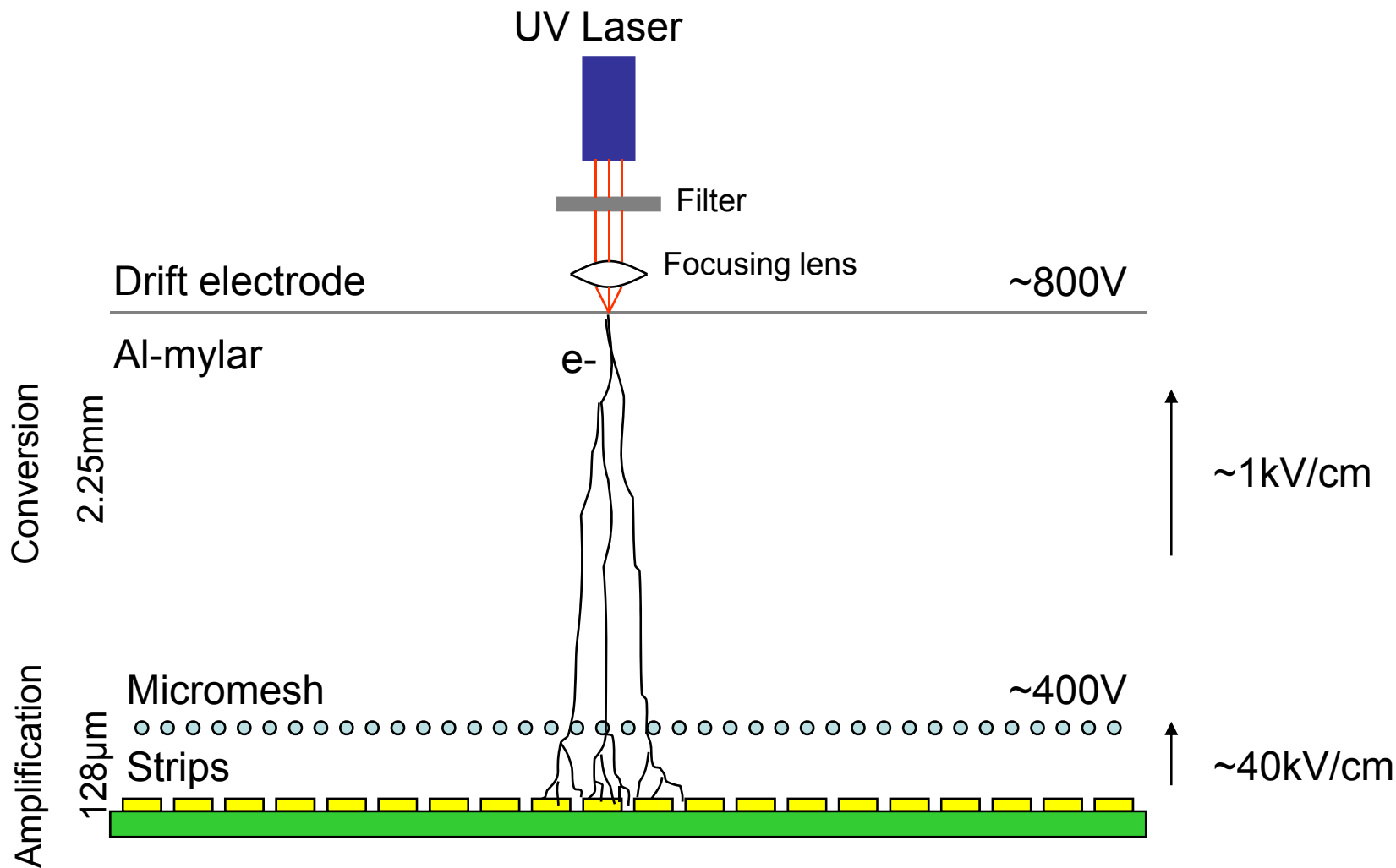


*Argon gas -  $V_{\text{mesh}} = 450\text{V}$  - pitch =  $600\mu\text{m}$  - gaps =  $(2.0\text{mm}; 100\mu\text{m})$  -  $\pi$  @  $1\text{ GeV}$  &  $90^\circ$*

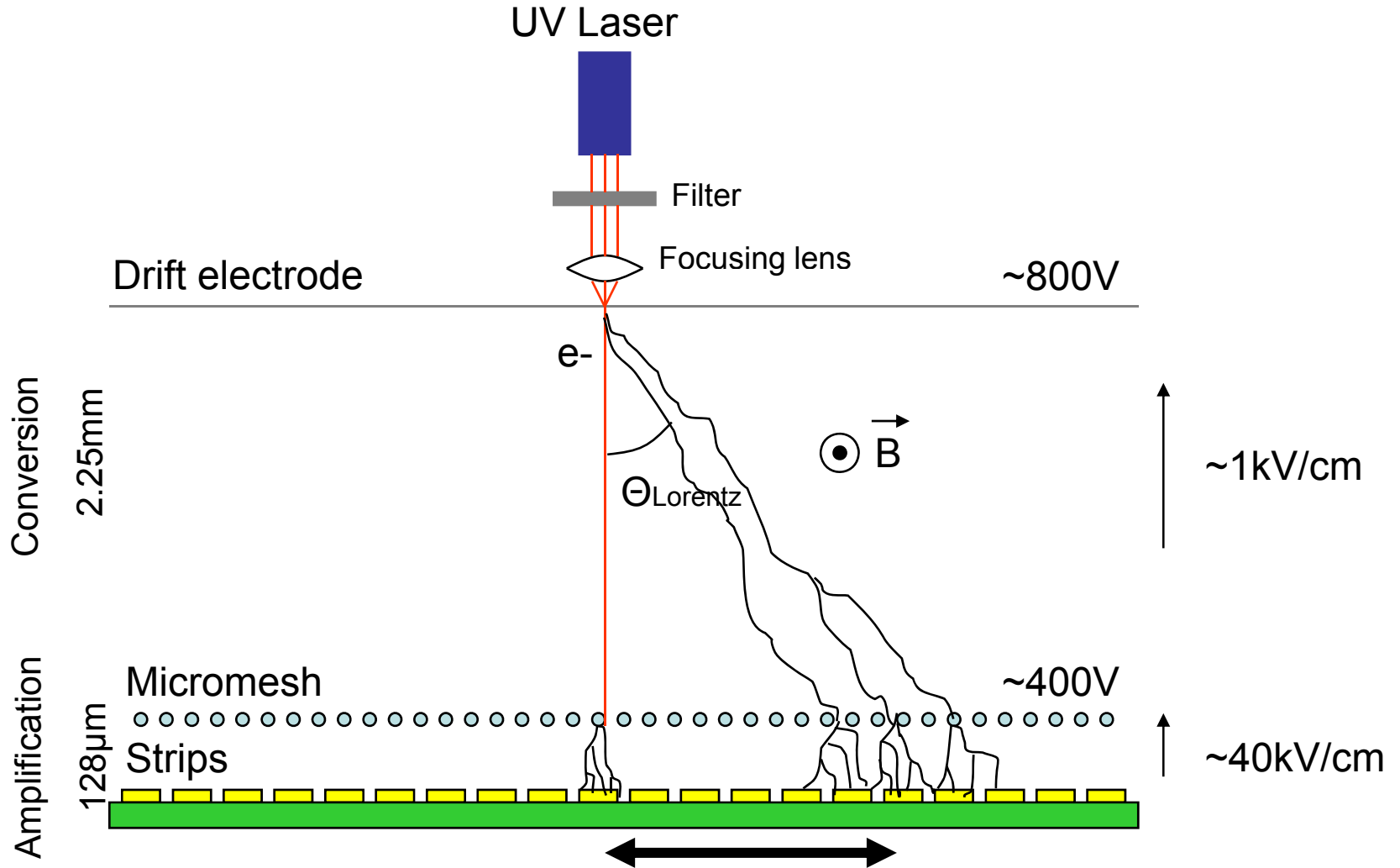
But we need to check:

1. how realistic GARFIELD simulation is
2. can we reach a satisfactory voltage setup with a thin cylindrical Micromegas detector.

# Experimental principle



With a magnetic field



This distance is related to  $\theta_{\text{Lorentz}}$

# Experimental setup

**Magnet refurbishing:** Fall 2007

**Tests started:** February 2008

**Magnetic field:** 0 to 1.5 T

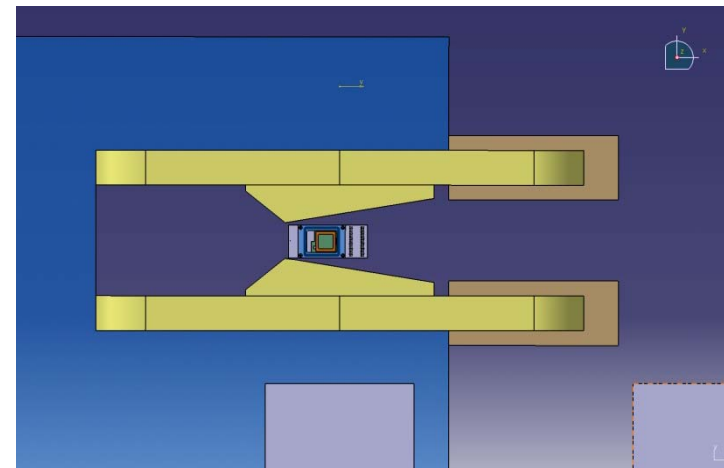
**Laser:** UV 355nm + neutral filters

<50 $\mu$ J/pulse, 2ns pulse, very good  
beam size and divergence

**Detector:** MM prototype V3

Bulk MM detector equipped with Gassiplex  
Board (96 channels)

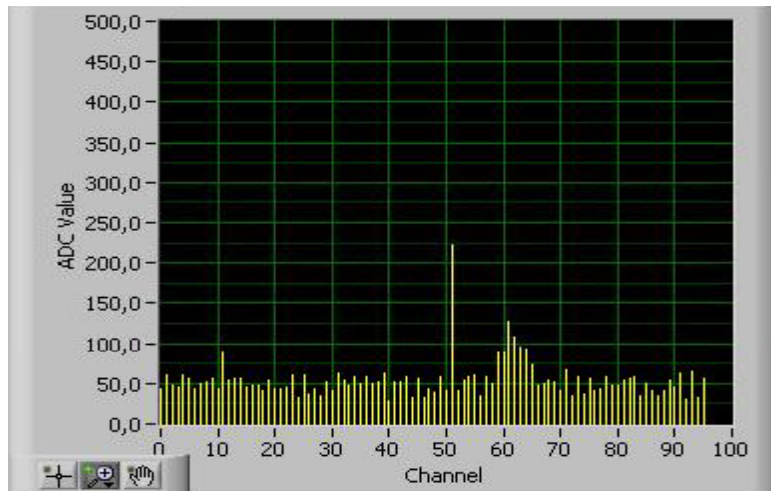
Active area 30x30 mm<sup>2</sup>, pitch 300  $\mu$ m  
2.25mm Drift-Mesh, 128 $\mu$ m Mesh-Strips  
Gas: 5% iC<sub>4</sub>H<sub>10</sub> + 95% Ar





# Lorentz angle behaviour with the magnetic field

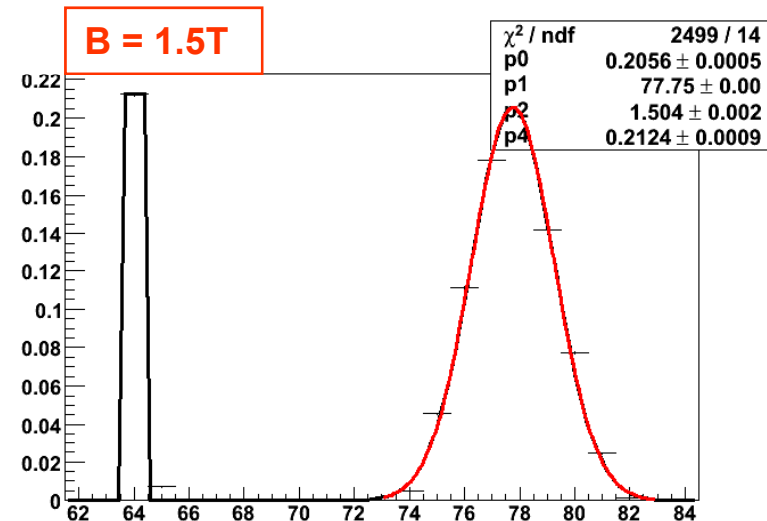
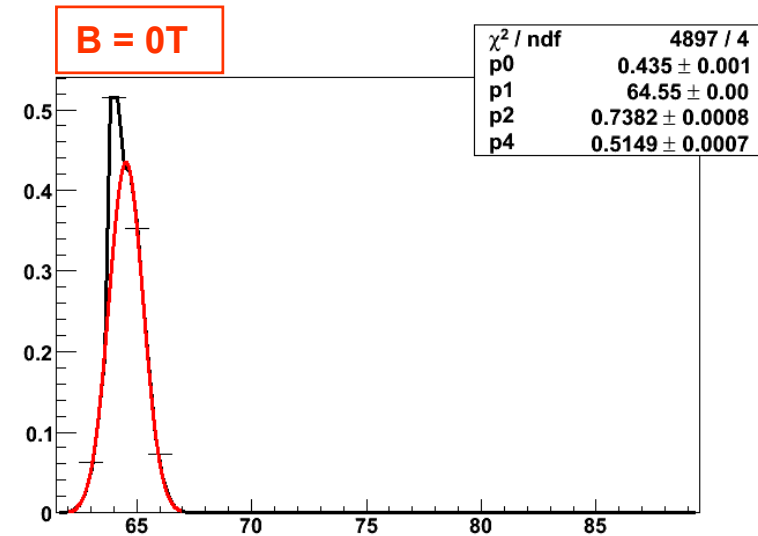
- Lorentz angle measured from the deviation of the B=0T peak
- Drift distance: 2.25mm
- The signal spreads out with the Lorentz deviation → increase the resolution



Labview DAQ

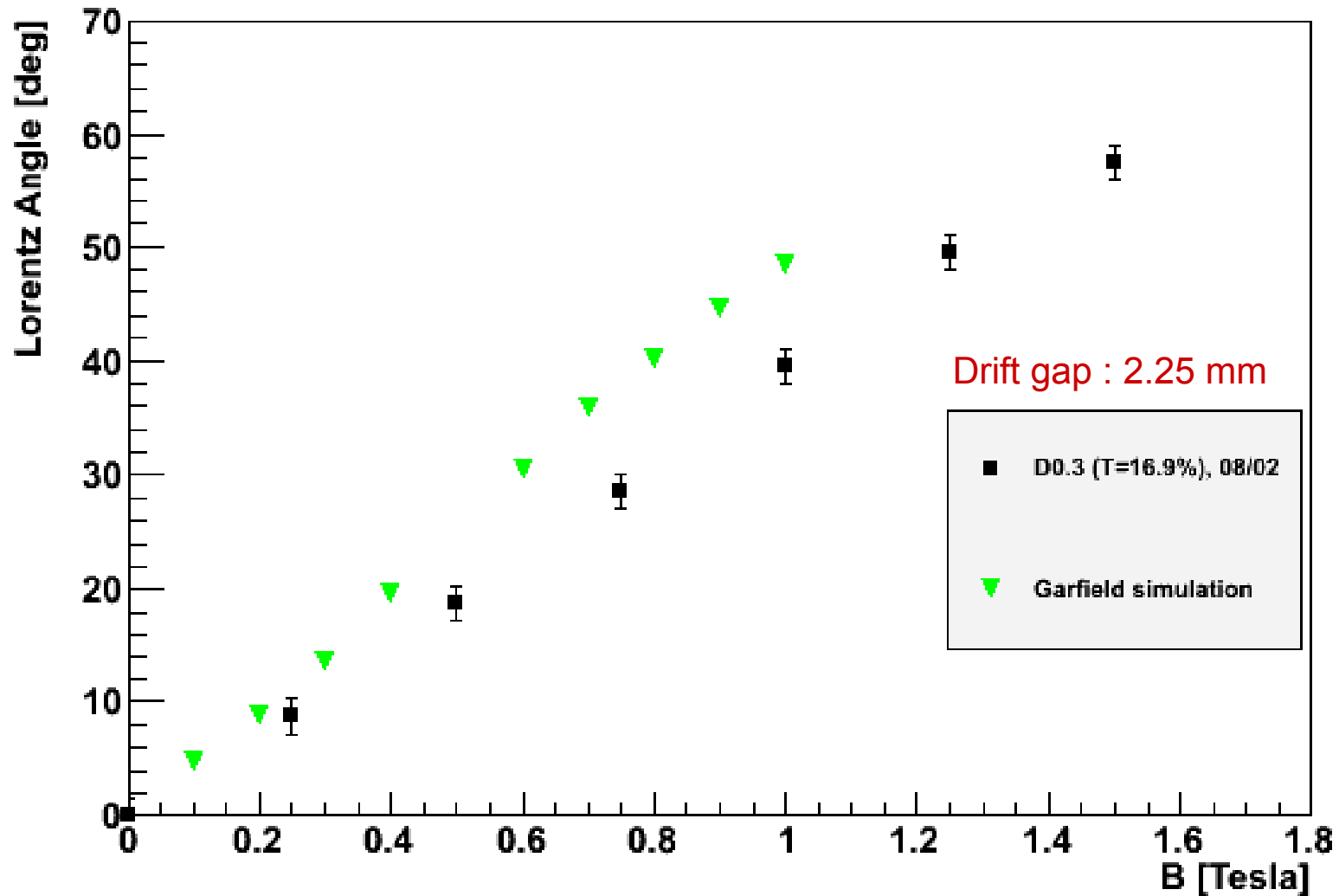
01/09/2008

J.Ball - PSD8 C



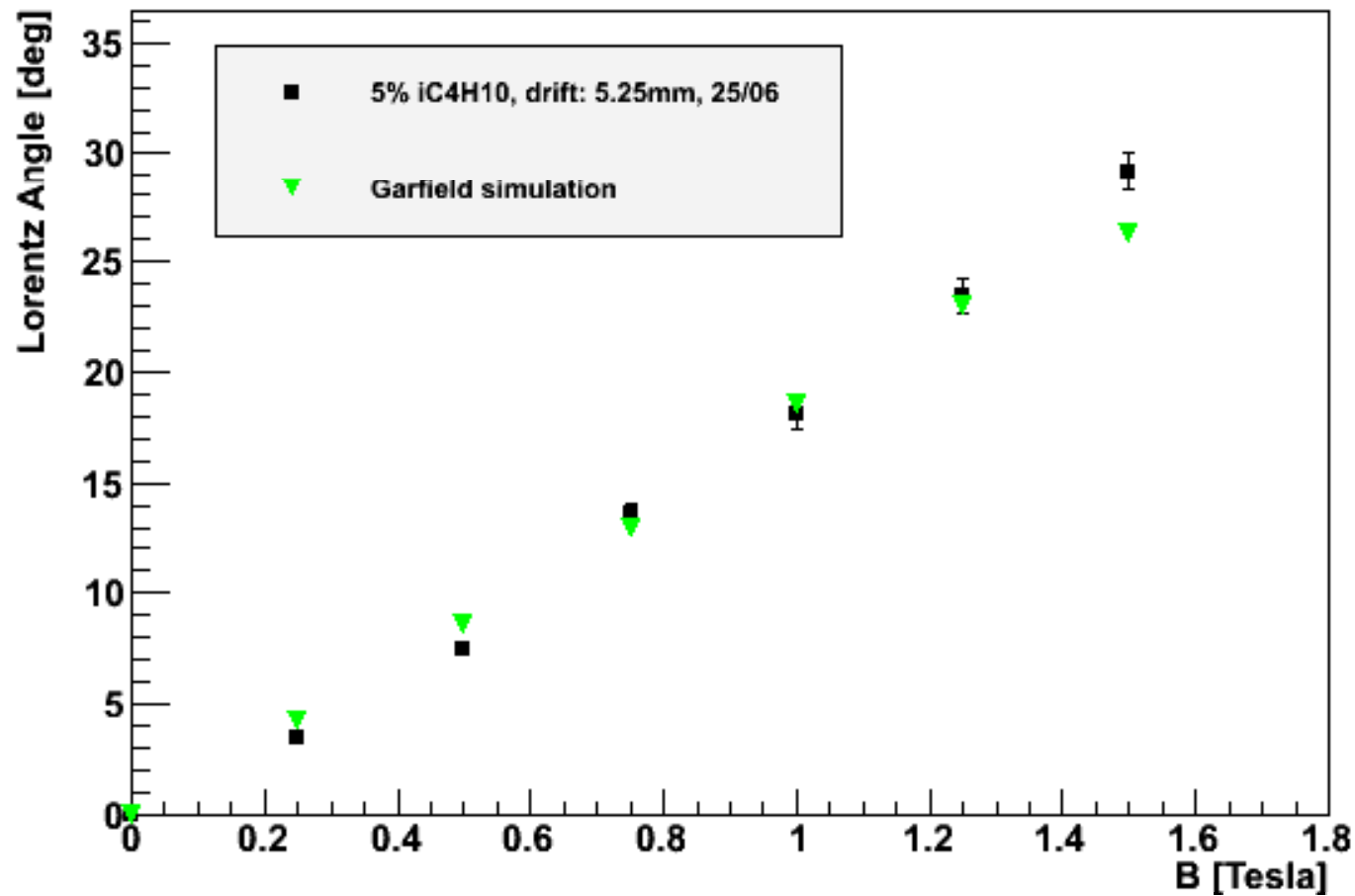
# Lorentz angle behaviour (1)

Lorentz Angle [deg] vs. B [Tesla]



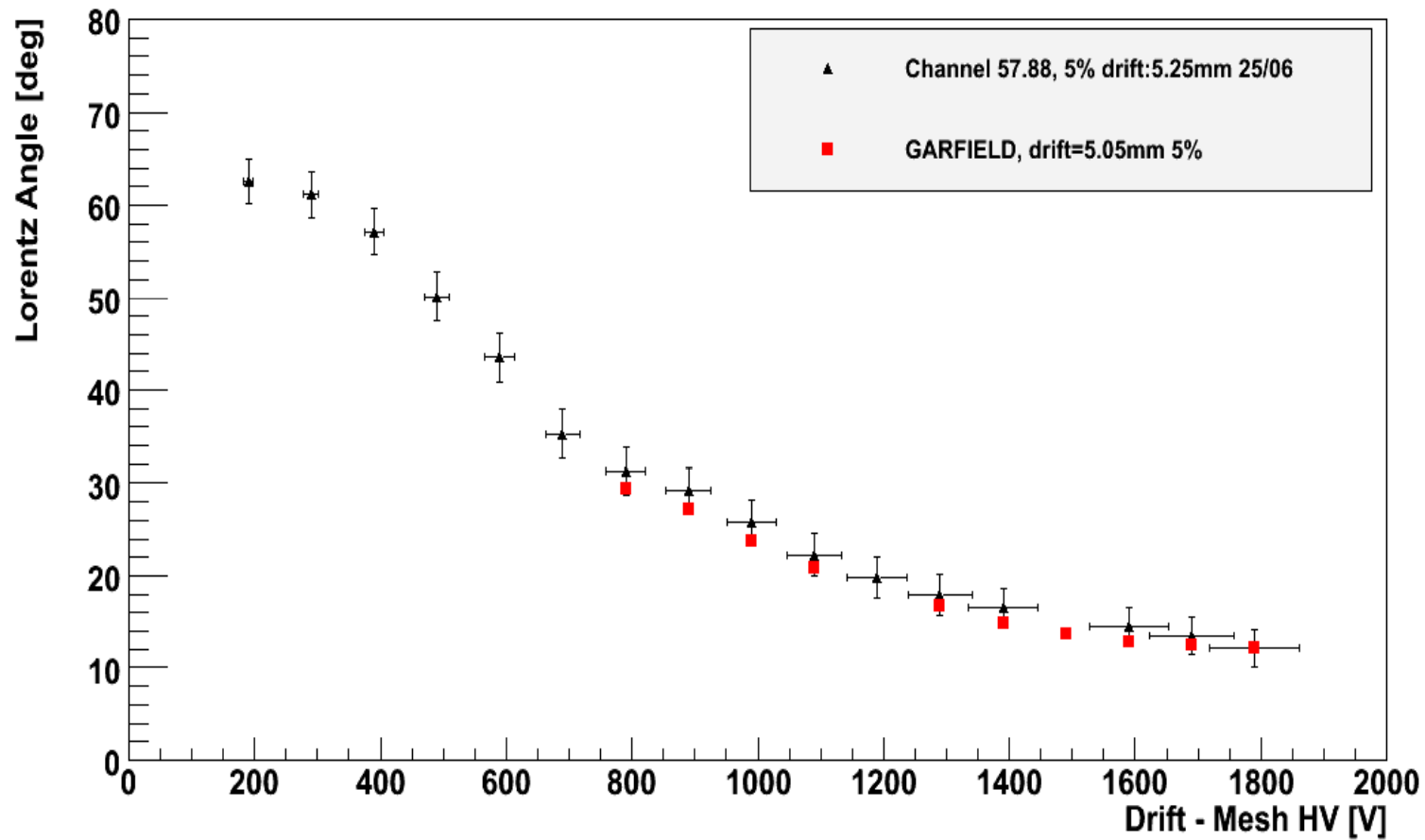
# Lorentz angle behaviour with the magnetic field (2)

Lorentz Angle [deg] vs. B [Tesla]



# Lorentz angle behaviour with the drift HV

Lorentz Angle [deg] vs. Drift - Mesh HV [V], B=1.5T

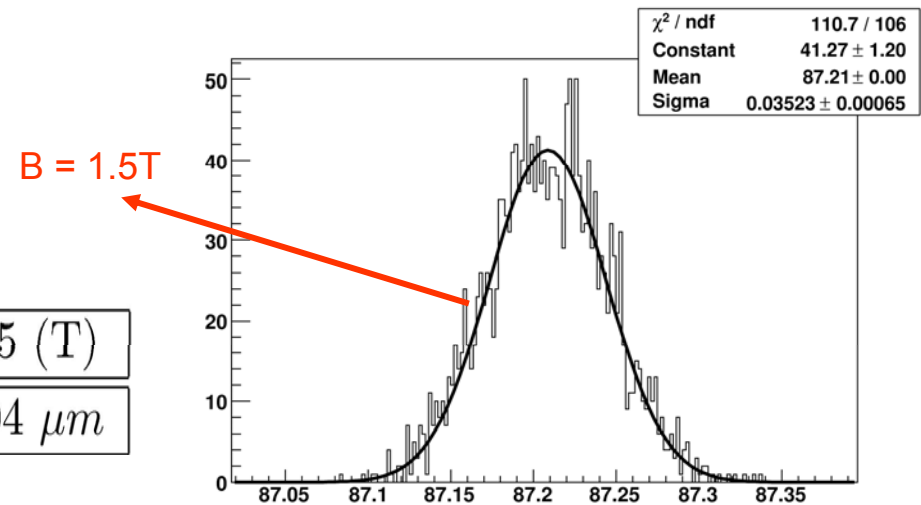
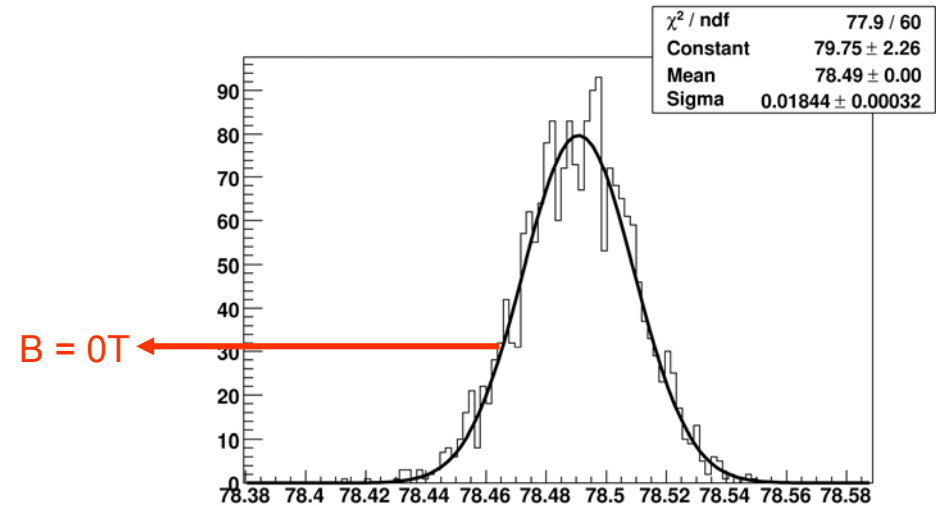


# « Spatial resolution »



- Sigma of the average position calculated event by event
- $\sigma^2_{exp} = (\sigma^2_{laser} + \sigma^2_{det}) / N$
- When the magnetic field increases → the resolution increases
- Test the detector homogeneity

	B0 (T)	B0.5 (T)	B1 (T)	B1.5 (T)
<i>exp</i>	5.53 $\mu m$	6.84 $\mu m$	8.46 $\mu m$	10.04 $\mu m$



## One type of Bulk:

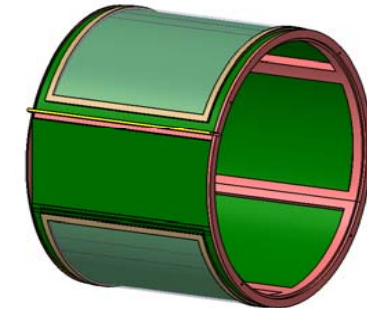
Active area; 115 mm for 288 strips, 500 mm long

Material: 100  $\mu\text{m}$  PCB, 5  $\mu\text{m}$  Cu, 18 $\mu\text{m}$  mesh, 20 $\mu\text{m}$  Mylar

## Two type of structure, X and Y, for Bulk integration:

Cylindrical for Y:  $\phi$  ext: 220 mm

Tile for X:  $\phi$  int 180 mm



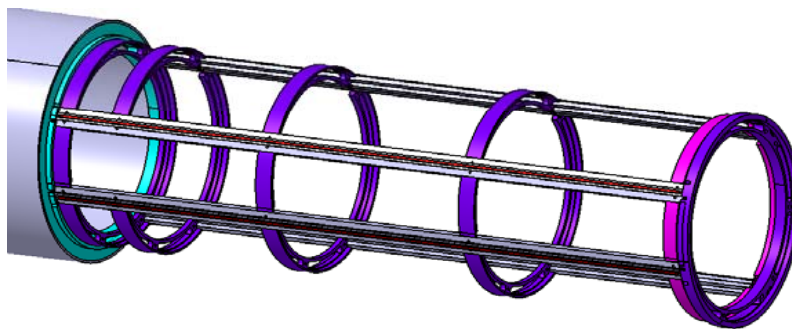
Y cylinder

## One support for up to 3 X tiles and 3 Y cylinders:

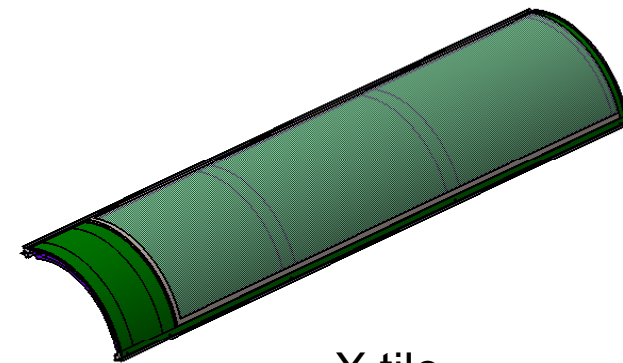
Channels: 1728 read by AFTER ASIC (T2K)

Active area: 0.34  $\text{m}^2$

*Dead zone between detectors not optimized on the prototype !!!*



Support structure

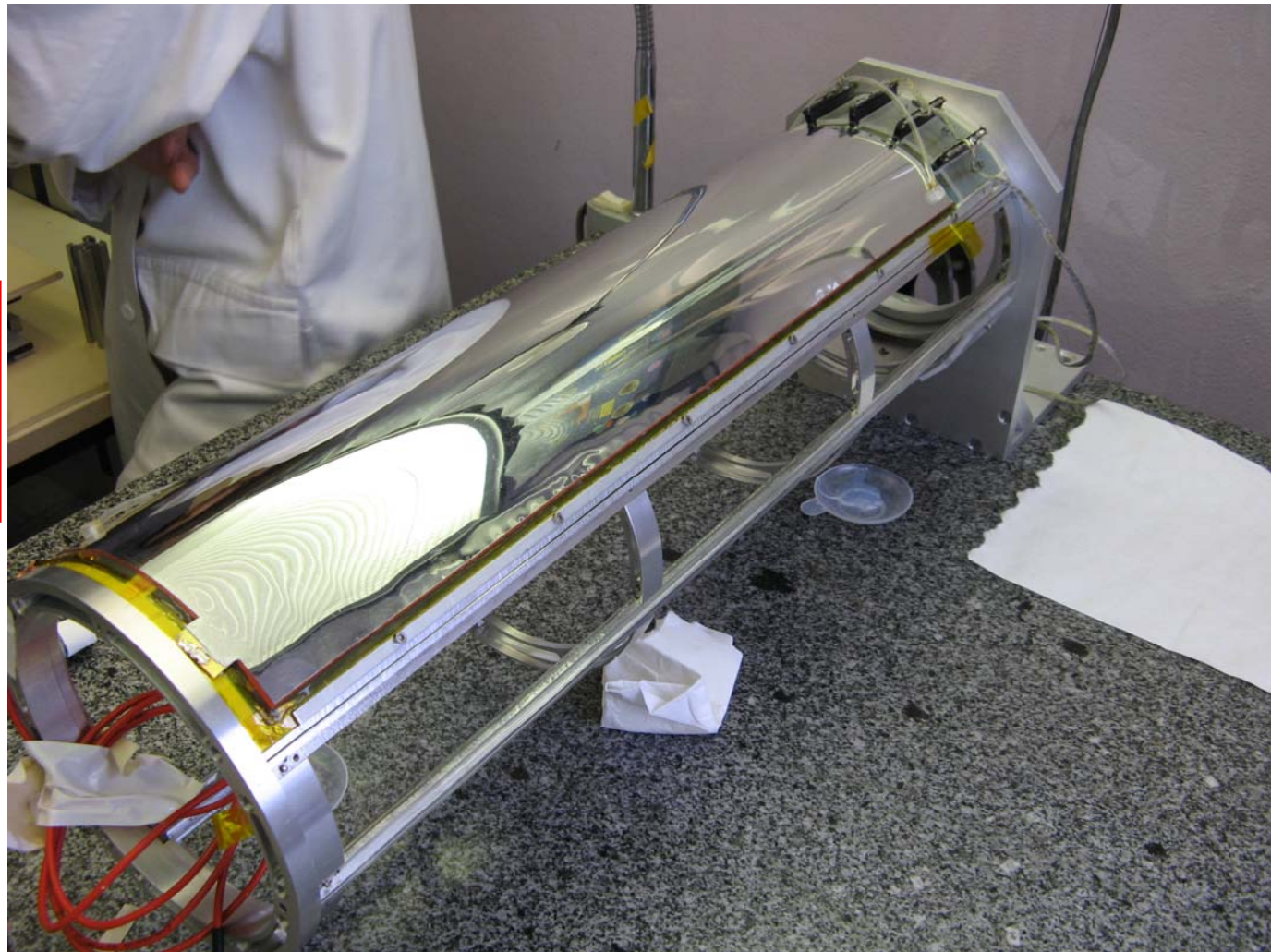


X tile

# Cylindrical Prototype

Cylindrical prototype

**Length:**  
600 mm  
**Diameter:**  
180 / 220 mm



## Bulk MM tracker project schedule

SPhN: J.Ball, M. El Yakoubi, P. Konczykowski, S. Procureur, F. Sabatié

SEDI: S. Aune, M. Combet, C. Lahonde-Hamdoun, O. Meunier

I. Giomataris

### October – December 2008 :

- High magnetic field tests at JLab (DVCS magnet: 4.7 T)
- Tests and validation of X and Y tiles

### 1st semester 2009 :

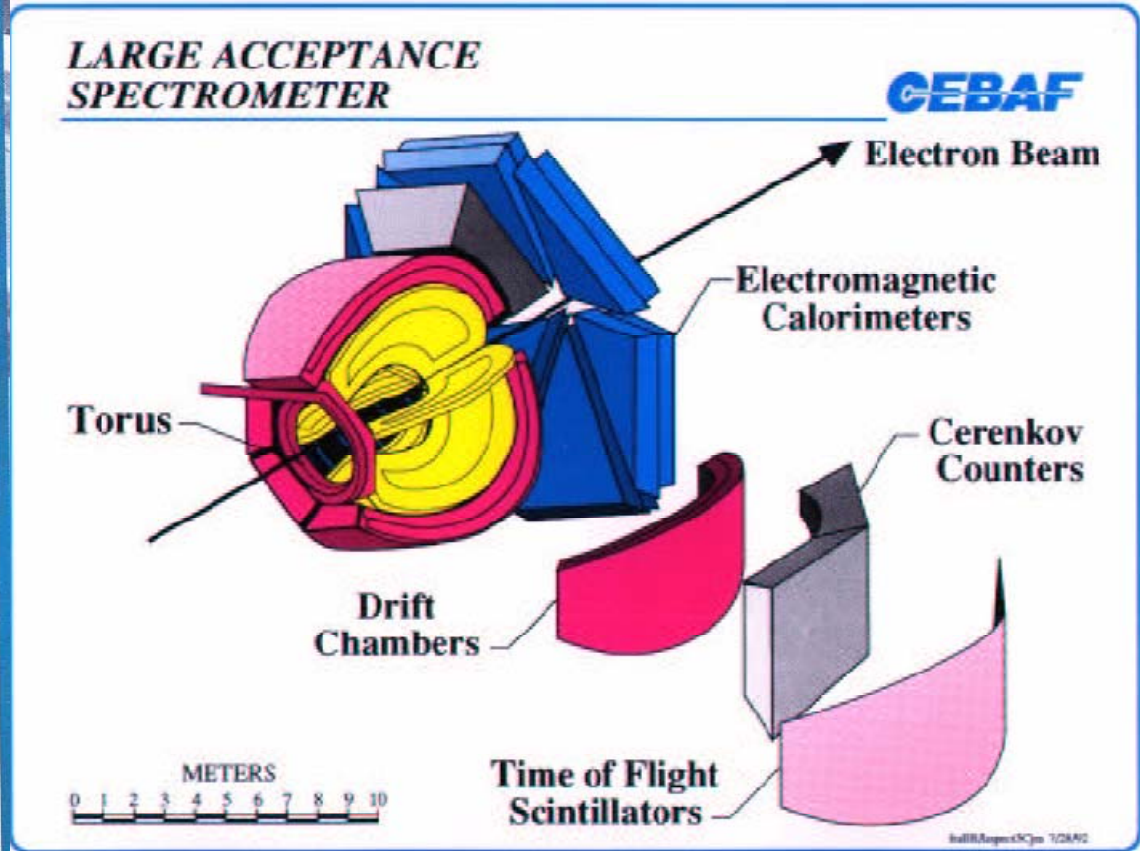
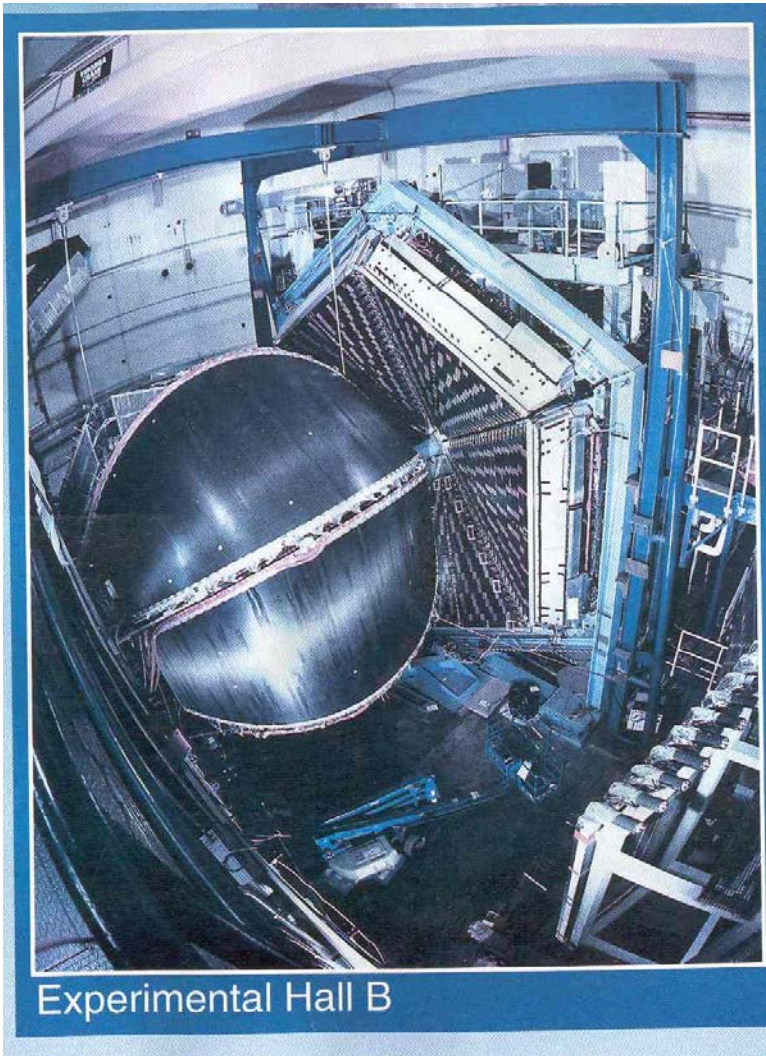
- Prototype test with beam at Jlab
- Front End electronics Definition and Design studies

→ Decision about Central Tracker in 2009...



- Additional slides

# CLAS



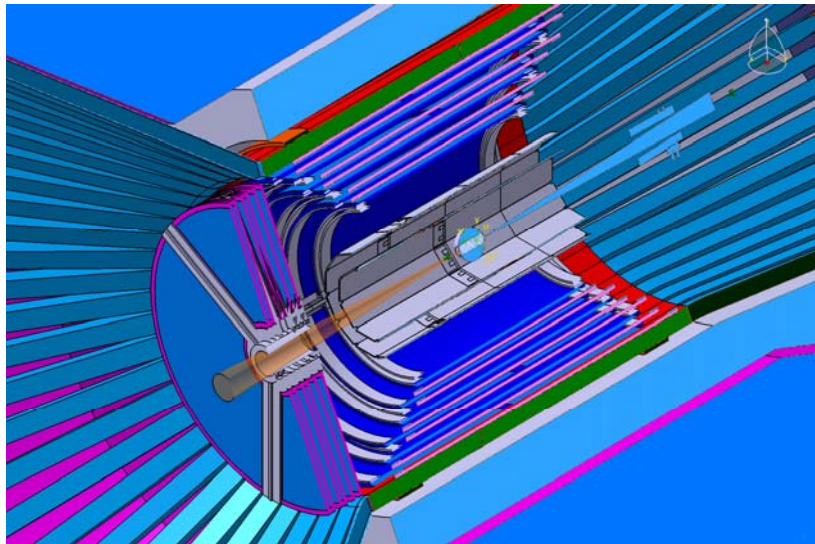
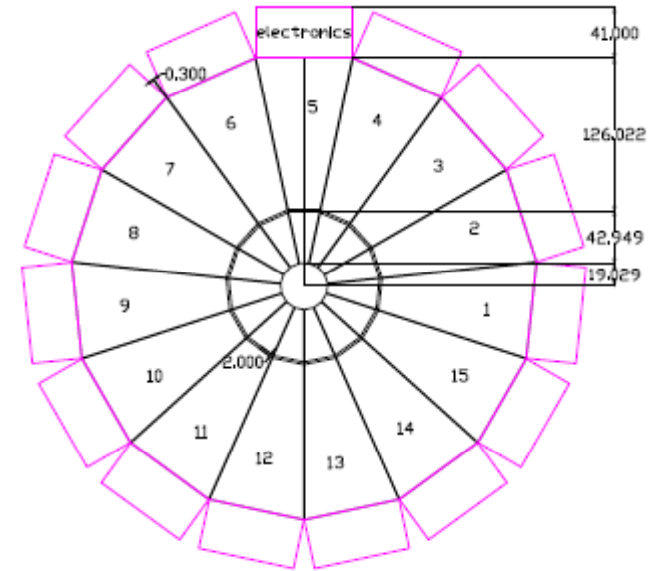
# Material thickness budget:

<i>Units:</i> $10^{-4} \times L_R$	Minimum	Maximum	Weighted average
Drift : 100 $\mu\text{m}$ Mylar foil	3.5	3.5	3.5
PCB : 50 $\mu\text{m}$ Kapton	1.7	1.7	1.7
Cu strips : 5 $\mu\text{m}$ (88% filling)	0	3.5	3.1
Mesh : 15 $\mu\text{m}$ Fe (20% filling)	0	8.5	1.7
95% Ar 5% Isobutane 3mm	0.27	0.27	0.27
Drift spacers 3mm (0.8%)	0	100 (?)	0.8 (?)
Mesh spacers 200 $\mu\text{m}$ (1%)	0	7 (?) Pure Si 300 $\mu\text{m}$ $\times 32 \times 10^{-4} L_R$	0.7 (?)
<b>TOTAL</b>	<b>9</b>	-	<b>11.4</b>

# Forward Tracker

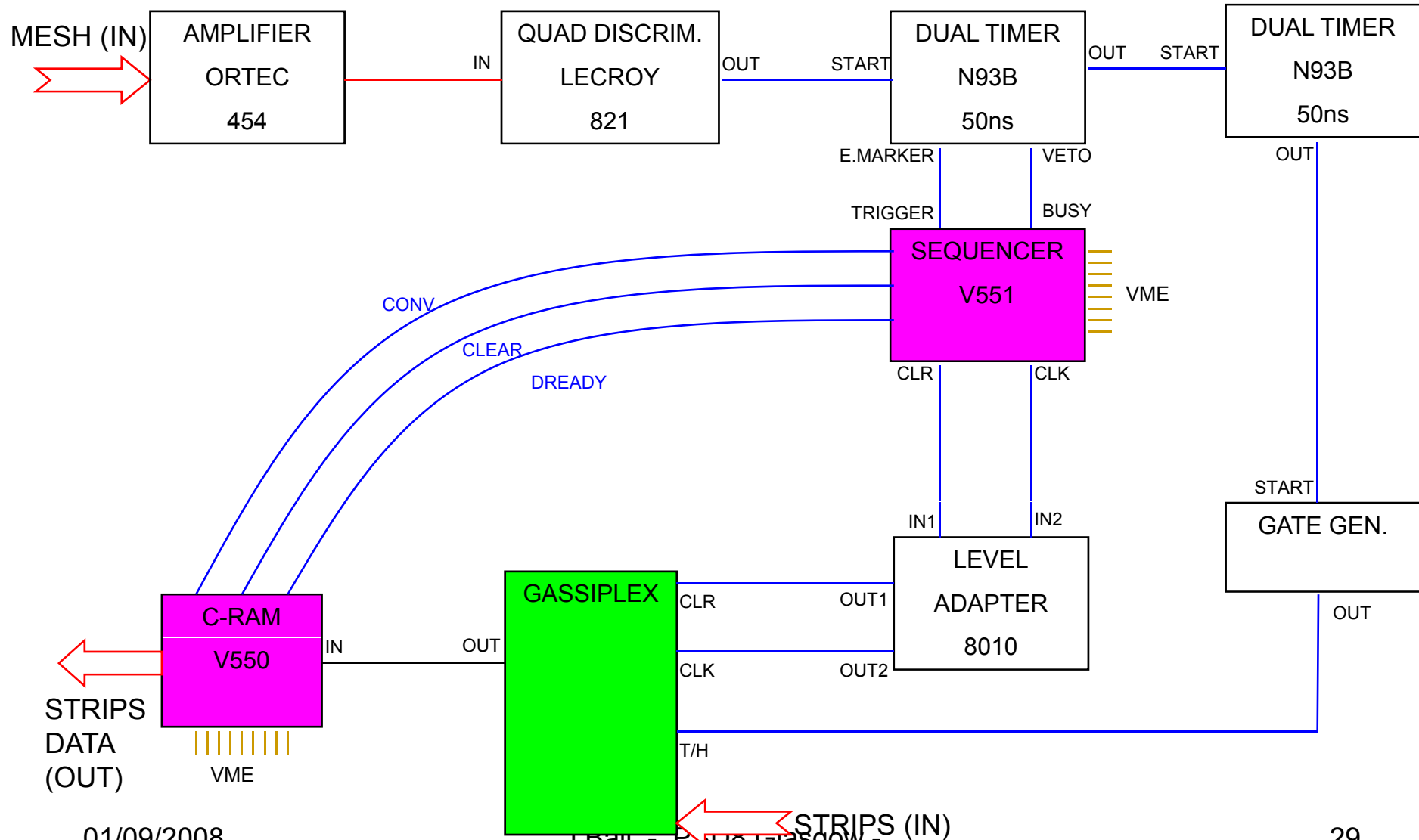
Considered options :

- Silicium
- Micromegas

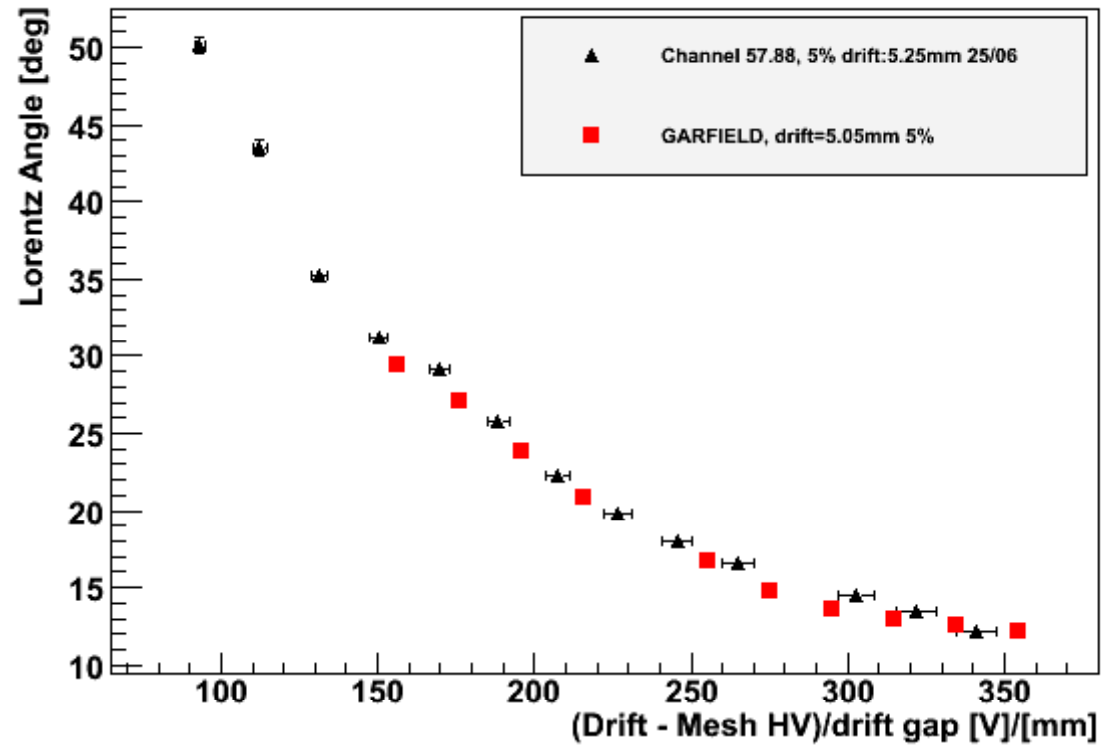


Issue : Interference with HTČC

# Electronics schematic

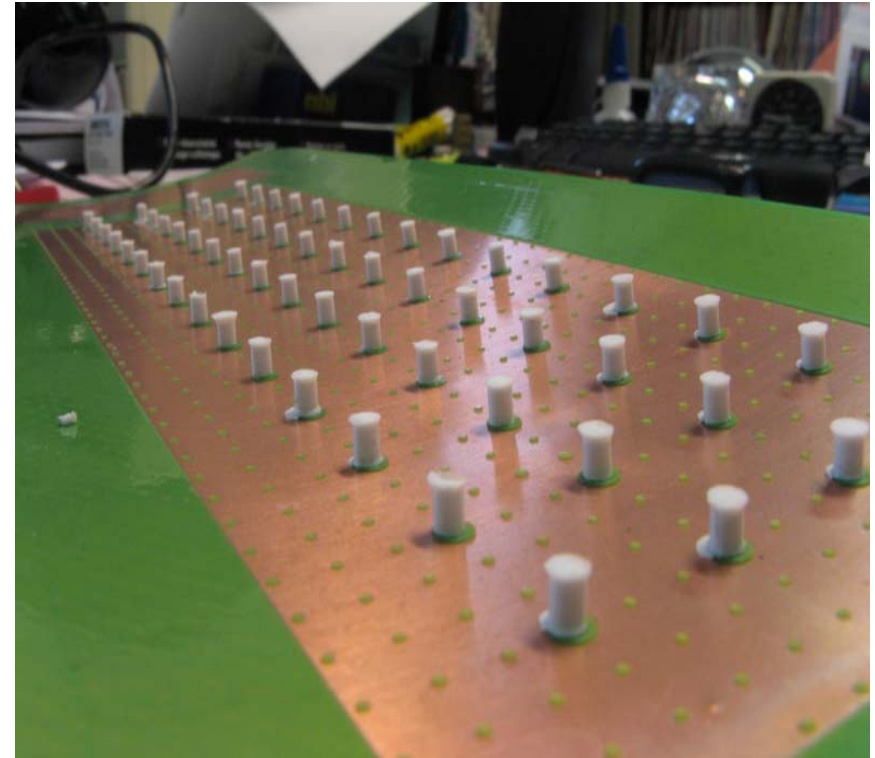
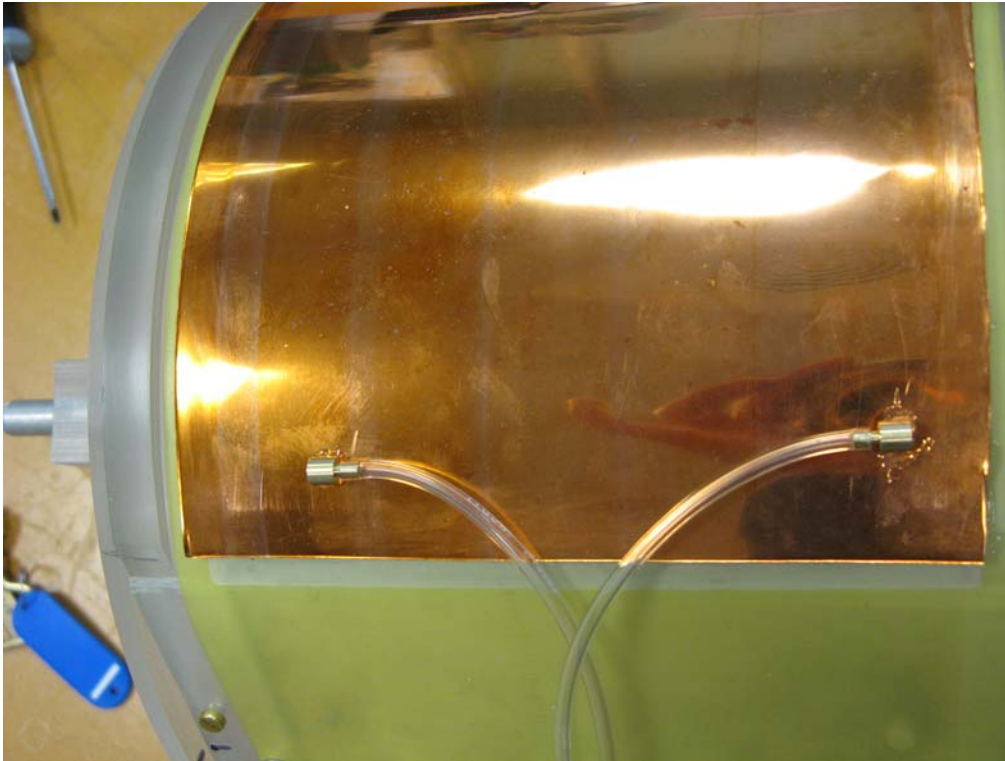


Lorentz Angle [deg] vs. (Drift - Mesh HV)/drift gap [V]/[mm], B=1.5T



## Drift Electrode integration

→ Drift plane set on silicon pillars, gas leak proof



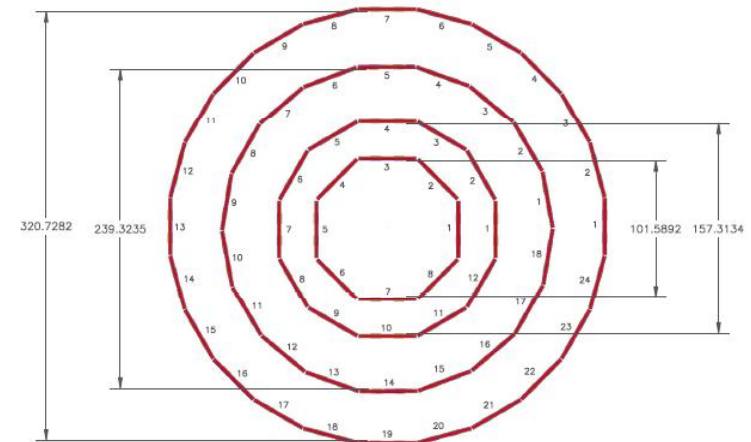
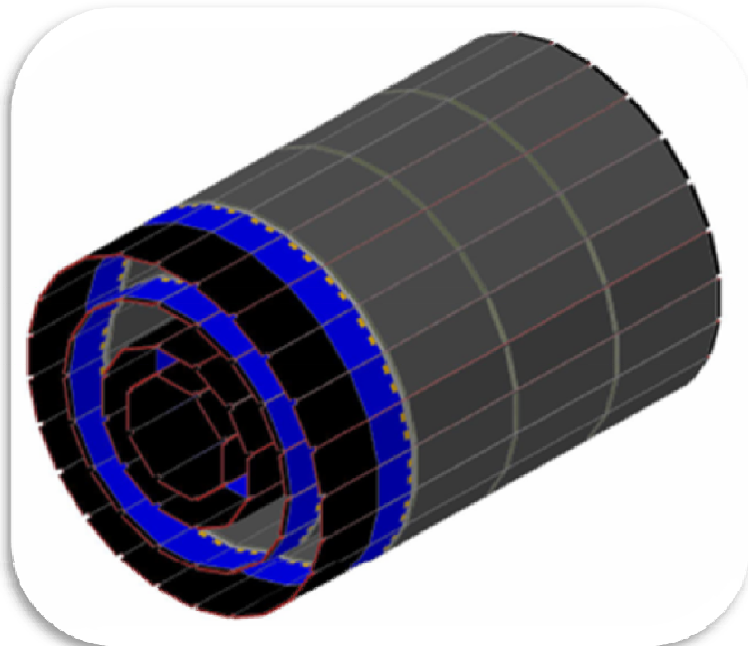
→ pillar spacing ? Sag < 0.1 mm from simul.

# Central Tracker

Two options considered : **SVT**, **Hybrid Bulk MM + SVT**

**SVT** : a barrel silicon tracker (**BST**) and a forward silicon tracker (**FST**).  
The BST has four regions with eight, twelve, eighteen, and twenty-four sectors respectively,

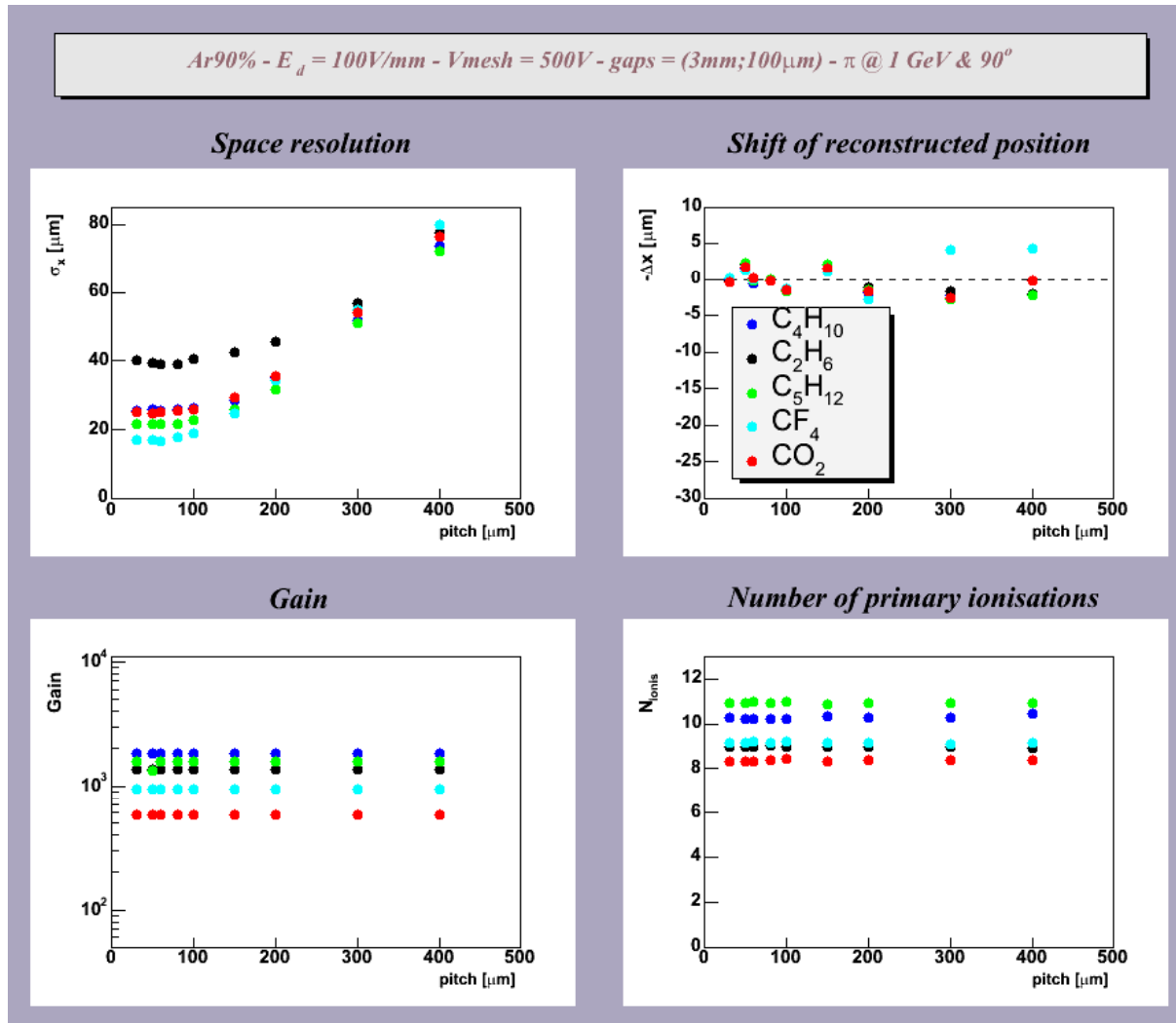
The FST has three regions, FR1–FR3, each consisting of fifteen sectors,





# Simulation of FVT with Garfield

In the FVT configuration, the space resolution is better, if the pitch is small enough



→ Systematics studies with different pitches, gas mixtures, resistive film, etc...

Resistive film will give a smaller “effective” pitch but a larger Time resolution, unlikely wrt background.

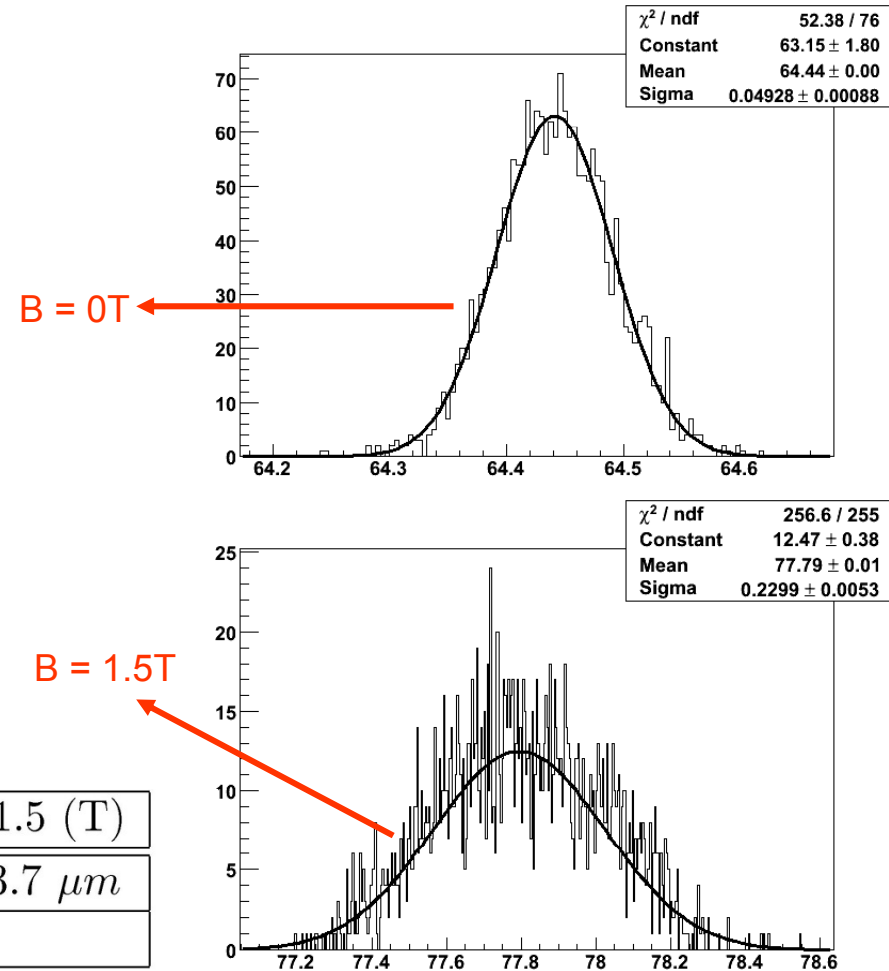
if resistive film possible (low transverse diffusion)(Ar+CF<sub>4</sub>);  
⇒  $\sigma = 20 \mu m$

⇒ if not,  $\sigma = 80 \mu m$  increase transverse diffusion (Ne+C<sub>2</sub>H<sub>6</sub>)

# Spatial resolution

- Sigma of the average position calculated event by event
- $\sigma^2 = (\sigma^2(\text{laser}) + \sigma^2(x)) / N$
- When the magnetic field increases  $\rightarrow$  the resolution increases
- Test the detector homogeneity

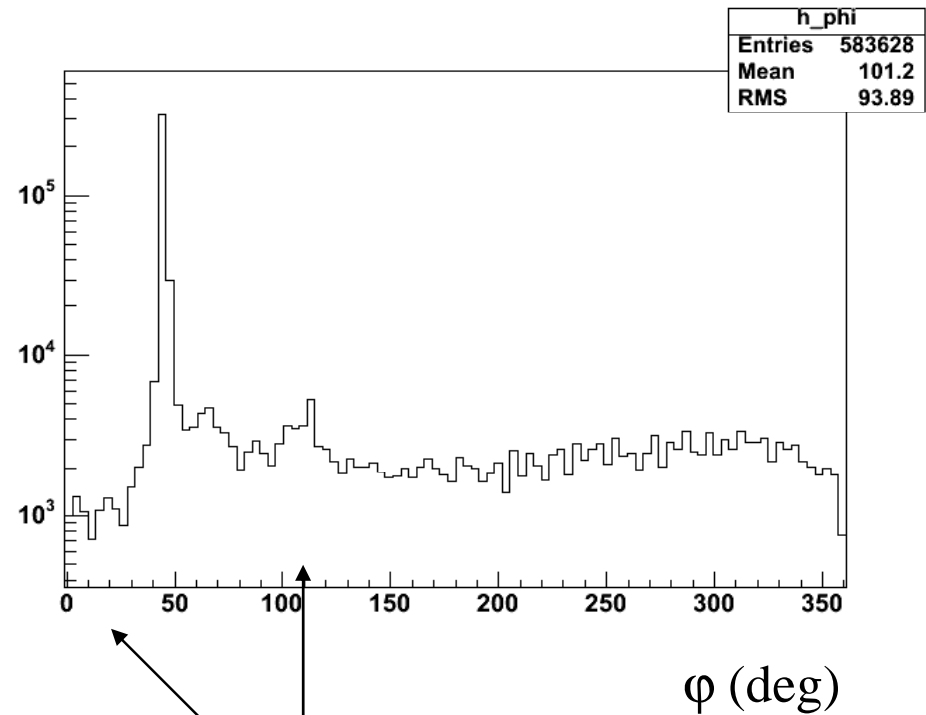
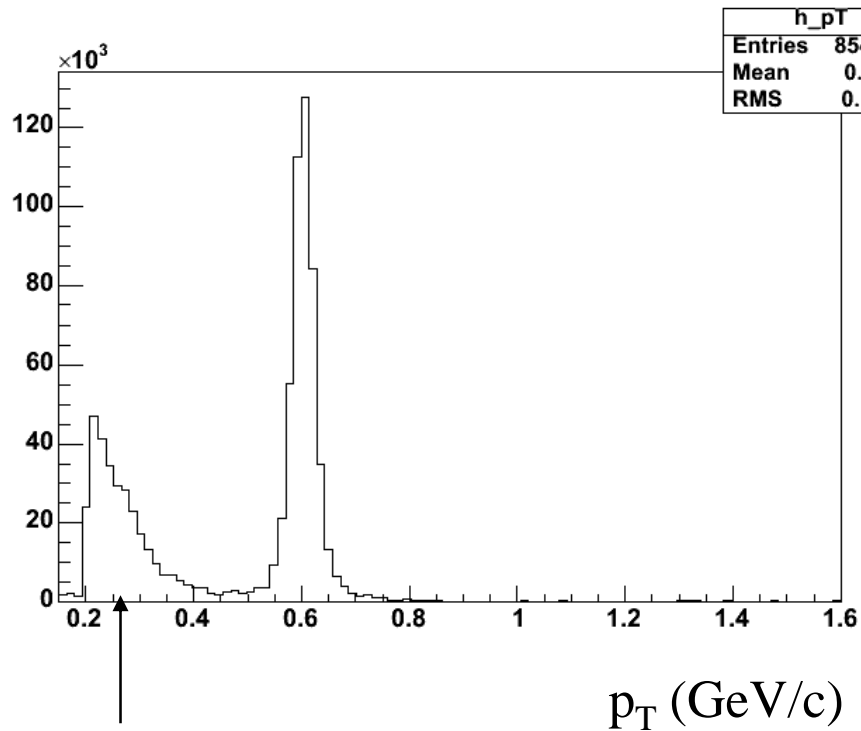
	B0 (T)	B0.5 (T)	B1 (T)	B1.5 (T)
exp	13.9 $\mu m$		26.5 $\mu m$	53.7 $\mu m$
sim	22 $\mu m$	38 $\mu m$	102 $\mu m$	



TAB. 1 – Spatial resolution at different magnetic fields

# Status of the central tracking

→ Track finder algorithm with 150 MHz background  
(now parameterized via Geant4 simul.).  
KF algorithm

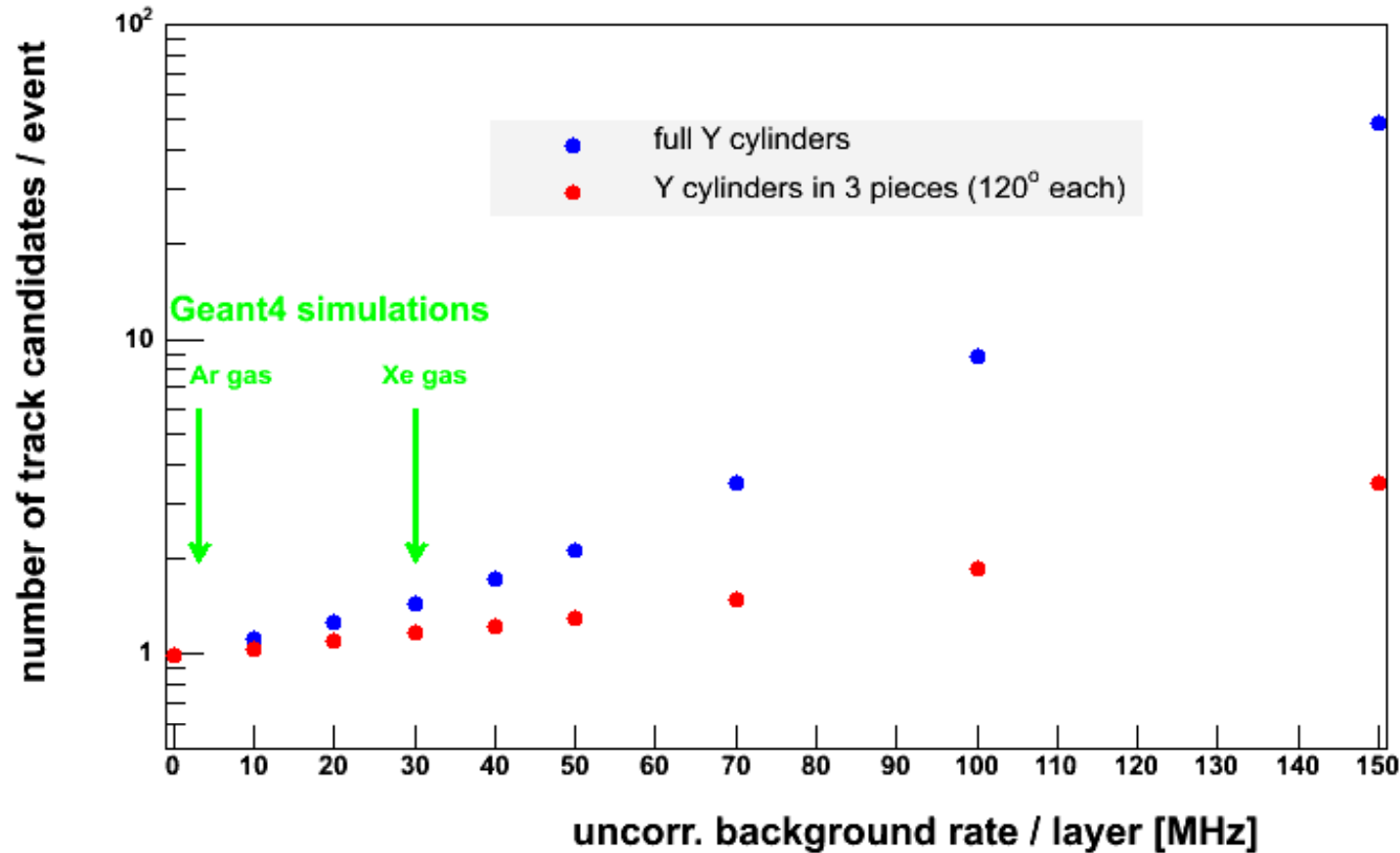


Fake tracks (small momentum,  
small  $\theta$ ).

Bugs (fixed)

# Status of the central tracking

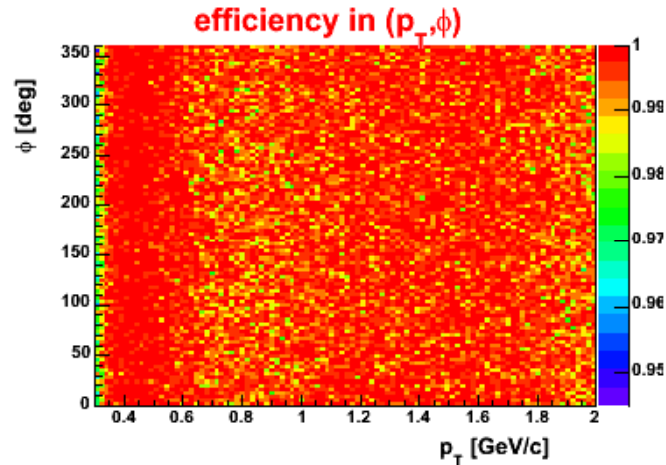
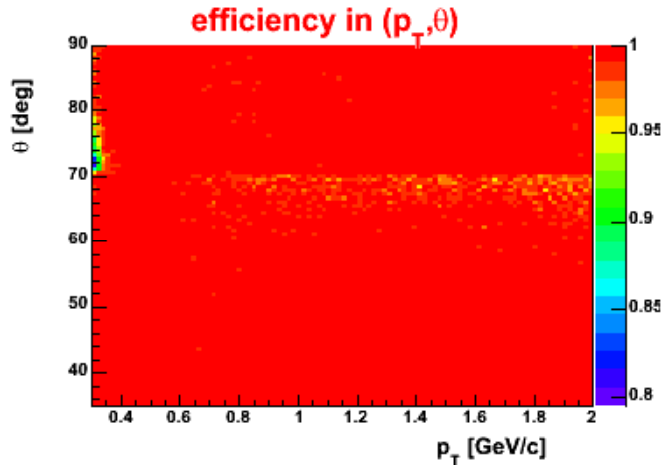
→ Effect of (uncorrelated) background on the number of reconstructed tracks (assuming a time window of 100 ns)



⇒ Can handle much more than what is expected by Geant4 simulations!

# Status of the central tracking

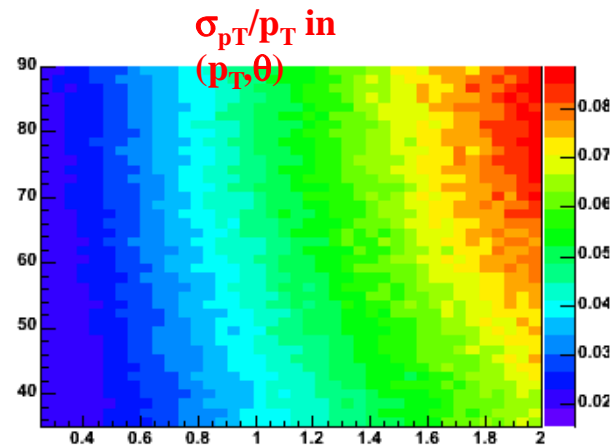
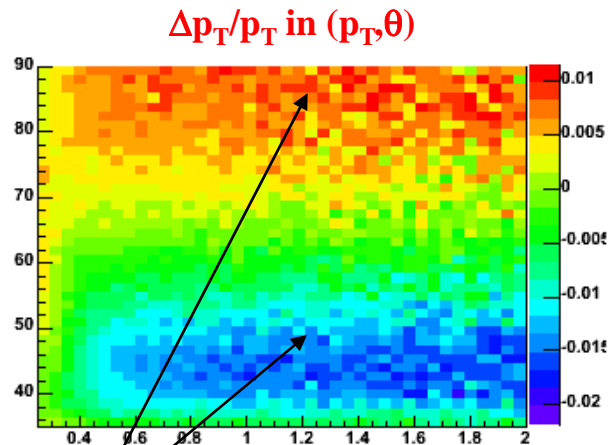
→ Reconstruction: efficiency and performances



⇒  $\epsilon = 99.0\%$

$0.25 < p_T < 2.0 \text{ GeV}/c$

$35^\circ < \theta < 90^\circ$



KF not perfect yet (small shift of the reconstructed momentum, depending on  $\theta$ )