

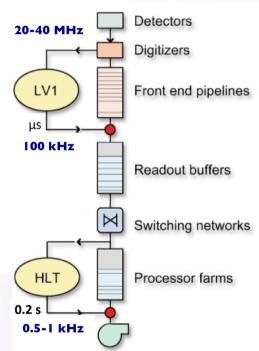
introduction

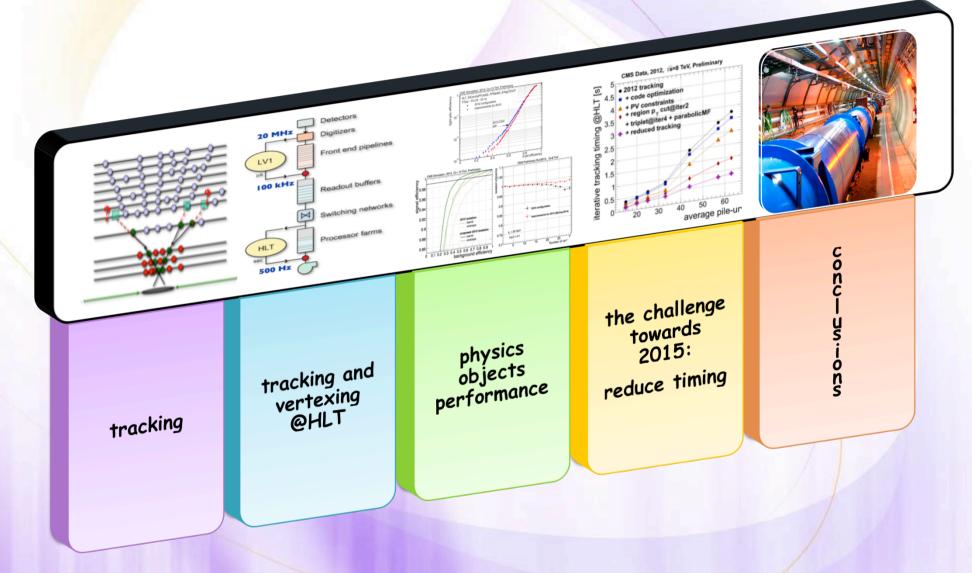
CMS has a wide physics goal for Run2 [√s=13 TeV, L~O(10³⁴)cm⁻²s⁻¹, 25 ns]

- BSM searches, Higgs sector (SM and BSM), SM measurement, b-physics =
- different physics objects
- different energy regime
- different phase-space

CMS plan for Run2 at High Level Trigger (HLT)

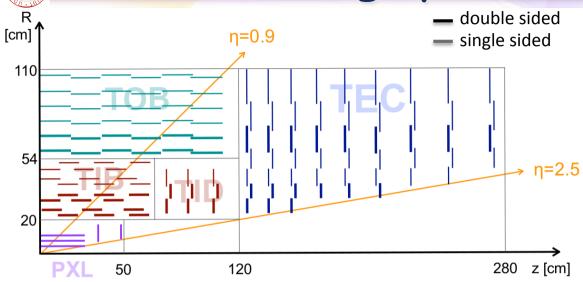
- > keep interesting events for physics analyses [maximize efficiency]
- keep rate under control
 - signal efficiency and background rejection
 - improves physics objects performance to match the offline ones
 [b-tagging, lepton, object isolation, tau and jet/MET]
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 - extend the usage of Particle Flow technique which implies efficient and more precise tracking
- > challenge (luminosity/pileup): hits multiplicity:>60k
 - dramatic combinatorics and timing increase at very high PU
 - offline reconstruction does not fit the online timing constraints [200ms]
- technical solution:
 still keeping the same algorithm as offline drastically reduce tracking timing





INFN

CMS tracking system



pixel hits resolution: 10x(20,40) μm

strip hits resolution: $(10,40)x(230,530) \mu m$

immersed in a 3.8 T magnetic field

performance:

[typically ~15 hits per track] $\sigma(p_T)/p_T \sim 1-2\%$ @ 100 GeV/c $\sigma(IP) \sim 10-20$ µm @ 10-100 GeV/c

largest silicon tracker ever built

• active area: ~200 m²

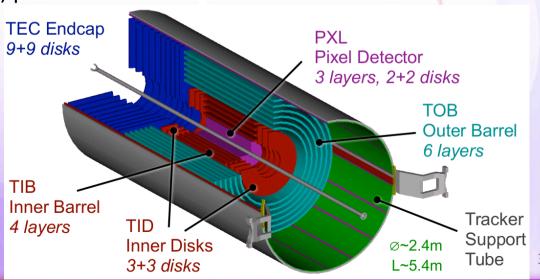
• acceptance: |η| < 2.5

Pixel detector [100x150 μm²]:

- 3 barrel layers [R=4.4 cm \rightarrow 10.2 cm]
- 2 endcap disks
- 66M readout channels

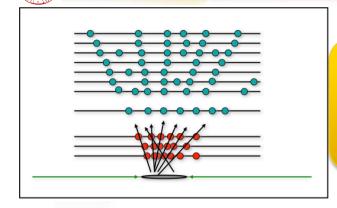
Strip detector [pitch: 80-180 µm]:

- 10 barrel layers [R=25.5 cm → 110 cm]
- 12 endcap disks
- 9M readout channels



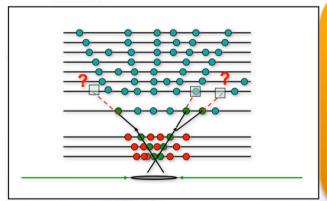


track reconstruction



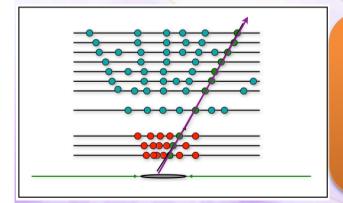
SEEDING

- starts from the <u>pixel tracks</u> or <u>pixel/strip hits</u> (triplets or pairs)
- seeds not compatible w/ the beamspot or PV are discarded



TRAJECTORY BUILDING

- each seed is <u>propagated to the successive layers</u>, using **Kalman Filter** or **Gaussian Sum Filter** technique [allowing for missing hits in a layer]
- propagation continues until there are no more layers or there's more than one missing hit [material effects + multiple scattering taken into account]



TRAJECTORY FITTING

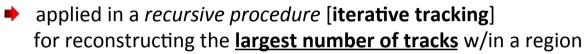
- more hits are added and the track <u>parameters estimation</u> is updated every time a new hit is found
- a final fit [Kalman Filter in-out+out-in] is performed to obtain the track parameters at the interaction point



tracking for trigger

Kalman Filter

- efficient and robust pattern recognition
- high efficiency, low fake-rate
- low contamination from spurious hits
- good track parameter resolutions
 - improve p_T resolution of muons hence their turn on curves [reduce fake, keeping low threshold]

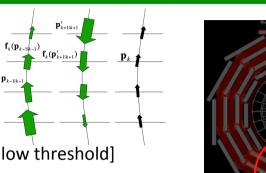


- is one of the key ingredients of the Particle Flow reconstruction
- improves jet/tau/MET resolution,

lepton and photon isolation efficiency, b-tagging performance

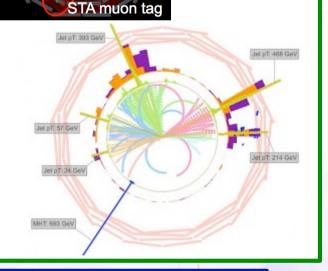
the **Iterative Tracking** reduces the combinatorics and improves both the efficiency and the fake rate

helps in reducing the event rate while keeping signal efficiency



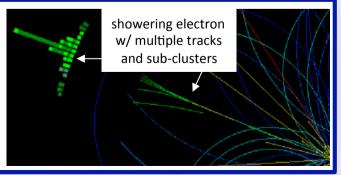
(P',covar(p'))

<E_{loss>}



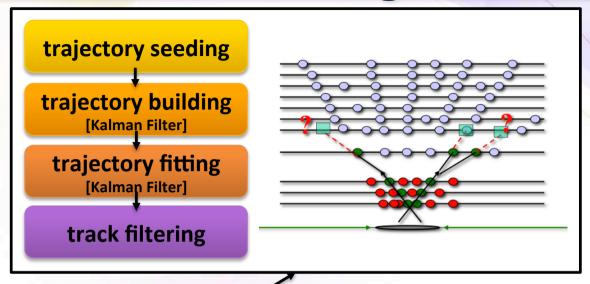
Gaussian Sum Filter [non-linear generalization of Kalman Filter]

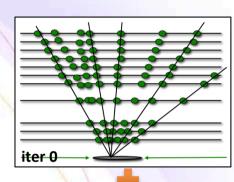
- efficient and robust pattern recognition
- high efficiency, low fake-rate
- good track parameter resolutions [takes into account effect of interaction w/ tracker material] (P,covar(R))
 - improve p_T resolution of electrons
 hence their turn on curves [reduce fake, keeping efficiency]





iterative tracking overview

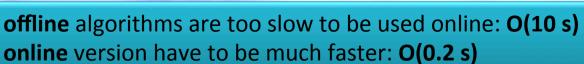


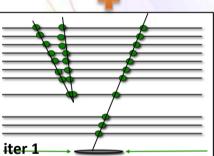


ITERATIVE TRACKING :=

track reconstruction procedure done iteratively where each step is meant for reconstructing a specific subset of tracks (prompt, low/high p_T, displaced, ...)

- reconstruct the most energetic tracks [starting from the high p_T seeds]
- remove hits associated to reconstructed tracks
- <u>repeat</u> the pattern recognition <u>w/looser set of cuts</u>







iterative tracking at HLT

main differences between HLT and offline tracking:

- considered only region of interest
 - **Regional** ← → Global
 - strip clustering OnDemand ←→!OnDemand

• fewer iterations | iter0: prompt tracks high p_T w/ pixelTracks [78%]

iter1: prompt tracks low p_T w/ pixel triplets [15%]

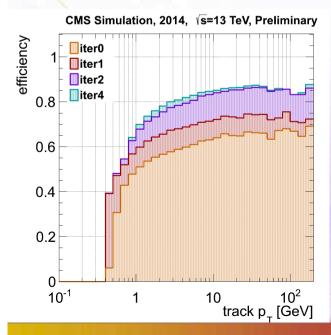
iter2: recover prompt tracks high p_T w/ pixel pairs [5%]

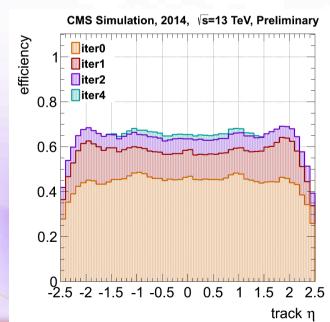
iter4(*): displaced tracks w/ strip triplets [2%]

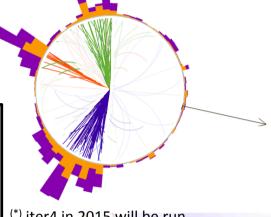
seeding

iter0 seeded by pixelTracks [instead of pixel triplets] smaller number of strip layer combinations, tighter cut)

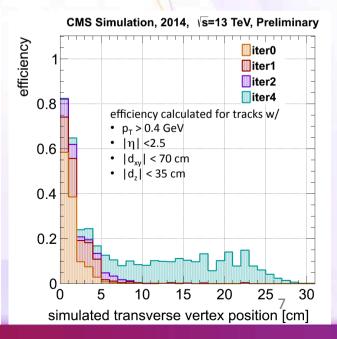
different builder





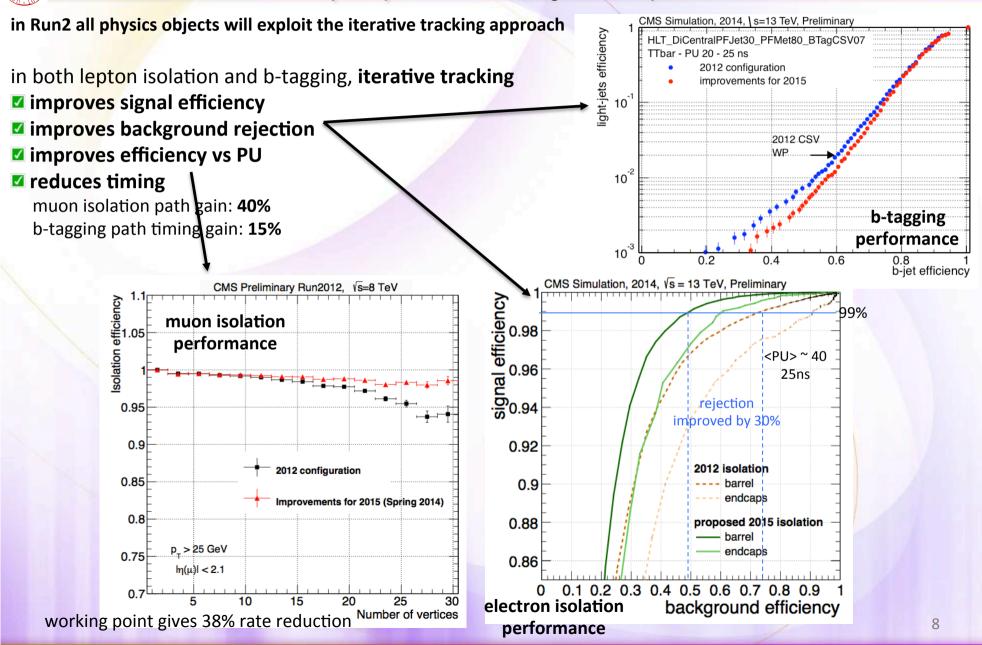


(*) iter4 in 2015 will be run only in a sub set of trigger paths where displaced tracks are needed



CMS

effects on physics object performance

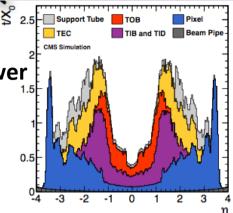


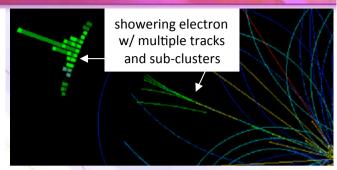
GSF tracking

at CMS

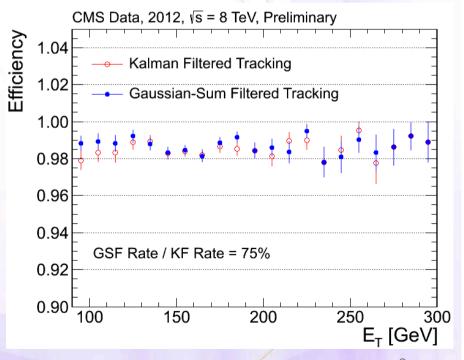
electrons frequently initiate an EM shower in the tracking system (= 0.5 to 2 X₀)

- complicating both clustering and tracking
- →suffer large backgrounds from jet mis-identification





in electron reconstruction **GSF** tracking gives a **25% rate reduction**and **~0 efficiency loss** w.r.t. **KF** tracking



has track parameters varying vs R



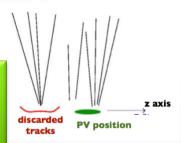
vertexing at HLT

vertexing performance crucial for physics objects performance

- identification of the primary interaction [primary vertex (PV)]
 - reference point for track reconstruction
 - check compatibility w/ reconstructed objects [muons, taus, jets, ..]
- reconstruction of secondary vertex [SV]
 - precise measurements of decay lengths/time [b-tagging]
- estimate number of PU interactions
- ▲ timing constraints

vertexing algorithms used at HLT

- Divisive Vertex Finder 1D (z) clustering tracks along z
 - > fast reconstruction algorithm: ~ O(1ms)
 - separation along z ~O(0.5 mm)
 - > high efficiency



- Vertex from Lepton Track
- used only for b-tagging
- Adaptive Vertex Fitter 3D
 tracks reconstructed by the iterative tracking
 w/in interesting jets

by using appropriate weights to avoid finding local minima, annealing is performed applying a Temperature on the $\sigma(d_z)$ of tracks

- $p_{ik} = \frac{\rho_k \exp\left[-\frac{1}{T} \frac{(z_i^T z_k^V)^2}{\sigma_i^{z^2}}\right]}{\sum_{k'} \rho_{k'} \exp\left[-\frac{1}{T} \frac{(z_i^T z_k^V)^2}{\sigma_i^{z^2}}\right]},$
- > needs full reconstructed tracks [slow]
- mildly fast reconstruction algorithm
- > robust performance
- >> high precision : ~O(20-30 μm)
- high efficiency



INFN

vertexing at HLT: pixel PV

pixelPV divisive vertex finder 1D (z)

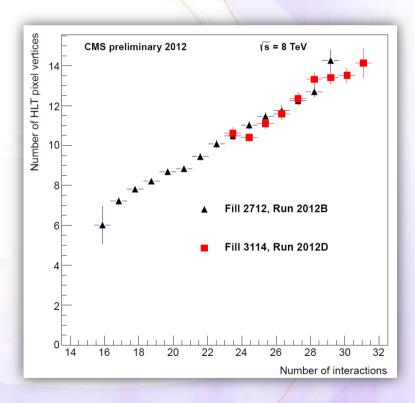
clustering pixel tracks along z

[w/ required criteria: impact parameter significance w.r.t. beam spot, number of hits, χ2]

- fast reconstruction algorithm: ~ O(1ms)
- linearity preserved during 2012 data taking
- > separation along z ~O(0.5 mm)
- **probust performance** of the reconstruction at HLT

for further speed-up, precision and efficiency

- only sub-set of pixel tracks are considered [around the already reconstructed object]
- > a constraint is applied
 - jet/tau/MET/photon → beam spot
 - leptons → lepton vertex
 [lepton track w/ beamspot constraint]
 - central jet → FastPV [next slide]



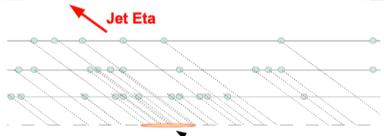


FastPV → central jet

given a jet

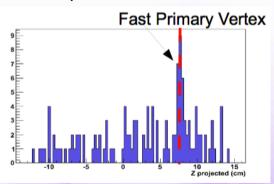
w/in the acceptance of the tracking system $|\eta|$ < 2.5

select compatible <u>pixel clusters along jet direction</u>

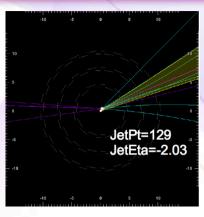


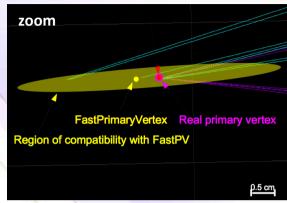
Primary vertex

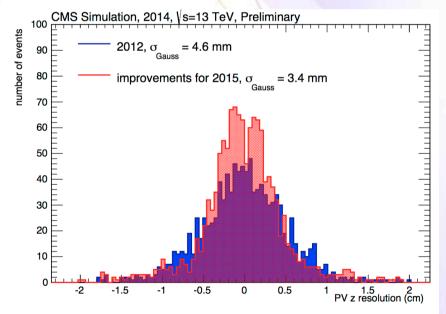
- clusters are <u>projected along jet direction onto z-axis</u>
- the peak in the z position is the FastPV



- > very fast algorithm
- increase primary vertex efficiency!



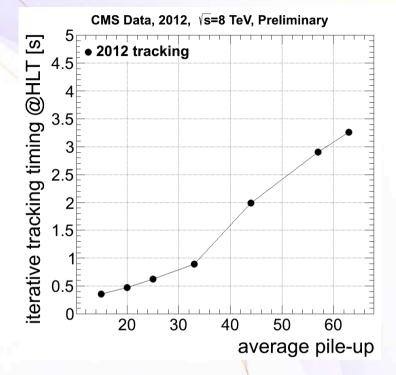




FastPV algorithm has been improved w.r.t. 2012 [extended jet acceptance, pixel end-cap clusters, regional pixel tracking]

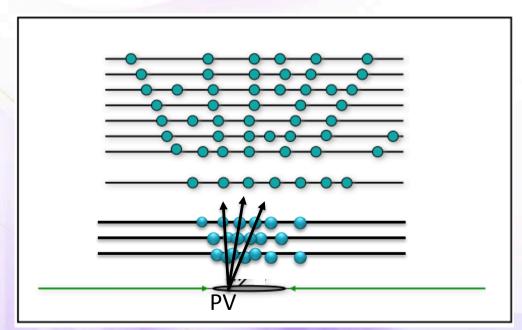


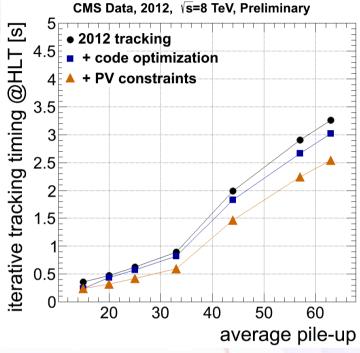
- ✓ Iterative Tracking is the main ingredient of Particle Flow
- CMS plans to extend the usage of Particle Flow at HLT in Run2 and to use the iterative tracking also in lepton isolation and b-tagging
- here is a large increase of timing at very high PU
- many studies and improvements have been developed during LS1 in order to mitigate the track reconstruction timing
 - 2012 tracking





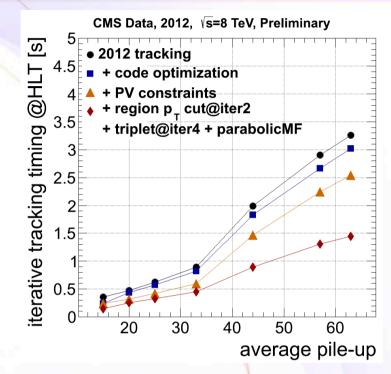
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- here is a large increase of timing at very high PU
- many studies and improvements have been developed during LS1 in order to mitigate the track reconstruction timing
 - 2012 tracking
 - code optimization [redesign and speed up reconstruction code]
 - PV constraint: PV constraint also at iter0
 [only pixelTracks (seed) compatible w/ PV are considered]





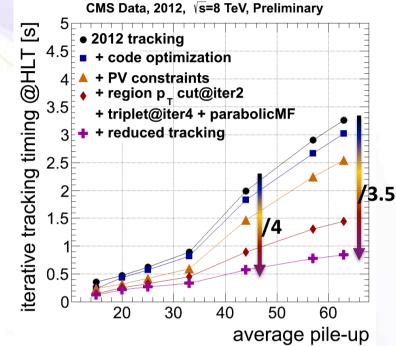


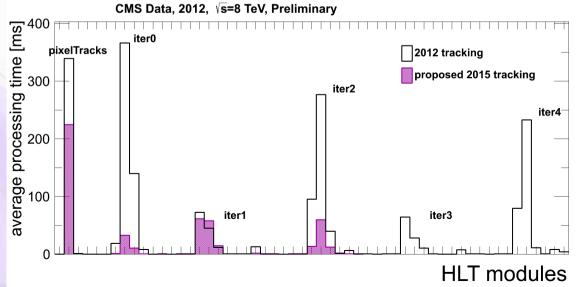
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 - 2012 tracking
 - code optimization
 - PV constraint : PV constraint also at iter0
 - region p_τ cuts@iter2 : tighter cut on region p_τ at iter2
 - triplet@iter4: strip triplets instead of pairs
 [mitigates the combinatorics and decrease the fake rate as well]
 - parabolic MF: magnetic field parameterized as a parabola
 [use a parameterized magnetic field in both building and fitting step]





- ✓ Iterative Tracking is the main ingredient of Particle Flow
- CMS plans to extend the usage of Particle Flow at HLT in Run2 and to use the iterative tracking also in lepton isolation and b-tagging
- ▲ there is a large increase of timing at very high PU
- many studies and improvements have been developed during LS1 in order to mitigate the track reconstruction timing
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 - code optimization
 - PV constraint : PV constraint also at iter0
 - region p_τ cuts@iter2 : tighter cut on region p_τ at iter2
 - triplet@iter4 : strip triplets instead of pairs
 - parabolic MF: magnetic field parameterized as a parabola
 - reduced tracking: only iter 0,1,2
 [not use iter3 and iter4 for standard track reconstruction]



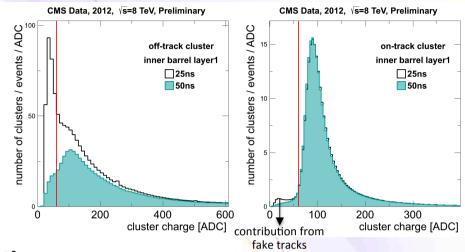




what about 25ns and OOTPU?

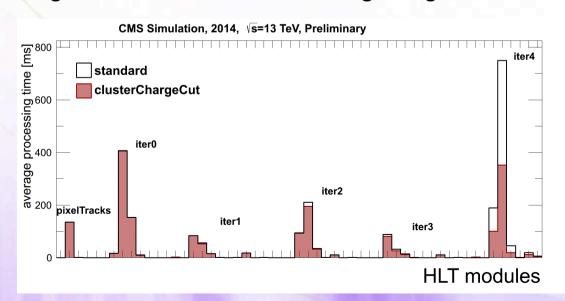
@25ns bunch spacing scheme, the out-of-time pile-up has a larger impact on track reconstruction

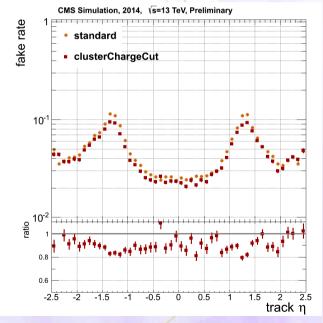
- ➤ larger cluster occupancy in the strip detector [+35%]
 - w/o special tuning, tracking is longer!
- strip cluster charge distribution shows an excess @low value in 25ns



a **simple cut on the strip cluster charge** [red line : 60 ADC] reduces capability for fractional charged searches

mitigate the OOTPU effects on tracking timing and fake rate





conclusion...

CMS plans to extend the usage of Particle Flow technique at **HLT** for Run2 and to use **tracking** also in lepton isolation and b-tagging

track and vertex reconstructions are very challenging at LHC [while guarantying the highest performance]

- dramatic combinatorics and timing increase at very high PU
 - △ offline reconstruction does not fit the online timing constraints

still keeping the same algorithm as offline

DONE drastically reduce iterative tracking timing by

- applying track reconstruction
 - at the end [after other requirements]
 - only in interesting regions
- specialized track and vertex reconstruction works very well
 - √ higher efficiency
 - √ lower fake rate
 - √ speed up

tracking [3 main flavours]

- I. Kalman Filter → muon
- 2. iterative tracking → jet, tau, MET, b-tagging, isolation
- 3. GSF tracking → electron
- vertexing [2 main flavours]
- 1. pixel vertices w/ constraint [depending on the physics object]
- 2. vertices w/ full tracking \rightarrow b-tagging

DONE tracking is widely used at HLT

- ✓ improves physics objects performance
 [b-tagging, lepton, tau and jet/MET]
- √ gain in signal efficiency and background rejection
 - **♦ keep rate under control**
 - keep interesting events for physics analyses

this is not the end, further tuning and improvements will continue, but the main goal for trigger developments towards physics project goals of Run2 has been addressed

BACKUP



@CMS electrons frequently initiate an EM shower

in the tracking system (= $0.5 \text{ to } 2 \text{ X}_0$),

- complicating both clustering and tracking
- suffer large backgrounds from jet misid

ELECTRON RECONSTRUCTION

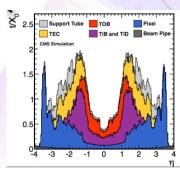
- 1. find cluster-of-clusters = "Superclusters" [SC], use primary vertex & SC centroid to define a search road
- 2. correct energy deposit by detector effects [laser corrections, energy conteinment, ...]
- 3. pixel seeding: look for 2-3 compatible hits in the road, build a candidate hit list from inside to outside[2 charge hypotheses tested]
- 4. fit trajectories using GSF algorithm w/ hit lists, keep the best one(s)
- 5. correct electron energy for losses

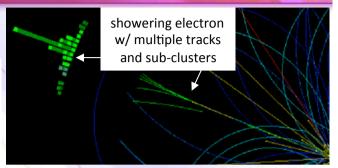
Gaussian Sum Filter [GSF] :=

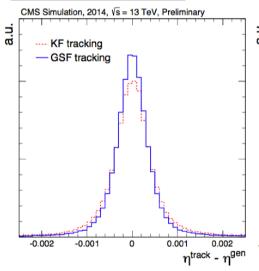
an extended Kalman Filter [KF] tracking technique, which takes into account the effect of the interaction of the tracker material w/ a particle on its trajectory @each layer of material,

re-estimate window to look for the next track hit based on Bethe-Heitler energy loss formula (approximated by a <u>sum of gaussians</u>)

 resulting GSF fit on candidate hits has track parameters varying vs R

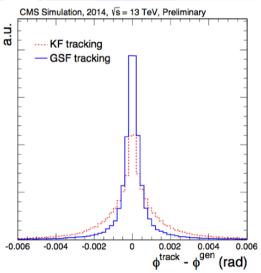






(P',covar(p'))

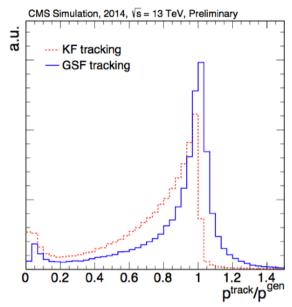
(P,covar(p))



in electron reconstruction GSF tracking gives a 25% rate reduction and ~0 efficiency loss w.r.t. KF tracking



GSF tracking



Gaussian Sum Filter [GSF] :=

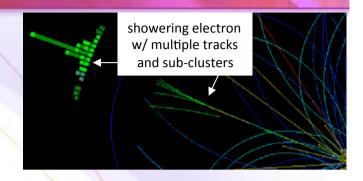
an extended Kalman Filter [KF] tracking technique, which takes into account the effect of the interaction of the tracker material w/ a particle on its trajectory @each layer of material,

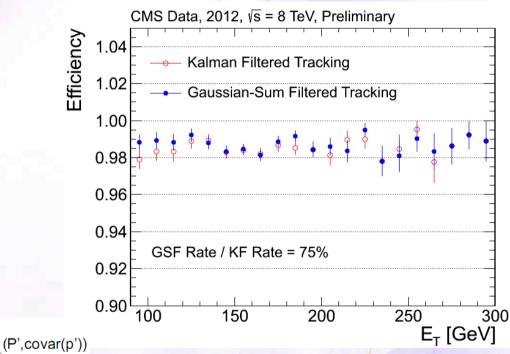
re-estimate window to look for the next track hit based on Bethe-Heitler energy loss formula (approximated by a <u>sum of gaussians</u>)

resulting GSE fit on candidate hits

(P,covar(p))

 resulting GSF fit on candidate hits has track parameters varying vs R





in electron reconstruction GSF tracking gives a 25% rate reduction and ~0 efficiency loss w.r.t. KF tracking