

# Superconducting Cables

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## Outline

- Cables vs. multi-filamentary composites
- Historical milestones for superconducting cables
- Transposition
- Strand movement
- Degradation
- Manufacturing aspects
- A chart about cabled conductor design

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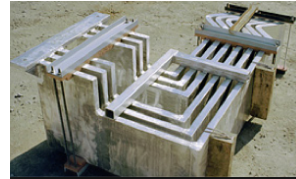
## Why Cables?

The word “cable”, opposite to “wire” is associated to high current.

However, very large current in the range of several ten kA, can be carried by bulky (non-cabled) Cu or Al profiles, with cross section exceeding several hundreds cm<sup>2</sup>...

So why do we need cables?

*In normal conductor technology, cables are used in AC application (eddy current issue) and to allow long conductor sections to be transported and installed (flexibility / bending).*



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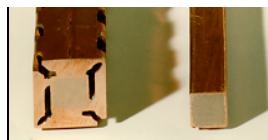


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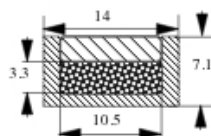
## Why Superconducting Cables?

Opposite to normal conductors, a superconductor is not a section of bulk metal, but a multi-filamentary composite, i.e. superconducting filaments embedded into a normal metal matrix, assembled by extrusion of billets.

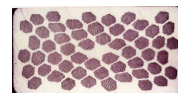
The limited size of the extrusion billets (<300 kg) and the need to achieve thin filaments (flux jump issues) sets boundaries to the maximum realistic cross section of a superconducting composite, typically < 50 mm<sup>2</sup>



NbTi square composite for MFTF coils, 42 mm<sup>2</sup> (≈1976)



Nb<sub>3</sub>Sn flat composite for TRIAM, 35 mm<sup>2</sup> (≈1986)



NbTi/CuNi/Cu composite for Tore Supra, 16 mm<sup>2</sup> (≈1987)

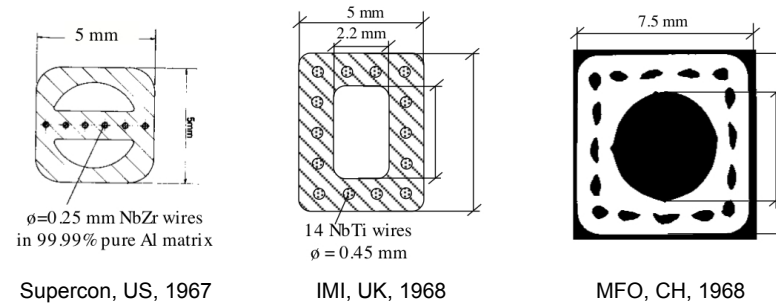
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## Force flow composites

In the late 60', with increasing demand for force flow conductors, hollow composites were manufactured by extrusion, with limited length, up to 100m – 300m. Beside the lack of transposition, the low extrusion ratio (thick filaments) was an issue.



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## Cables vs. Composites

Large composites require R&D, are expensive and have little market. *Today*, composites are mostly round strands with cross section  $< 2$  mm<sup>2</sup>. For operating current  $> 1$  kA, cables are preferred to large composites.

### Large Composites

High engineering current density  
Excellent current distribution  
Easy joining  
Easy application of insulation  
Potentially high ac loss  
Potentially poor transient stability  
Limited operating current

### Cabled Conductors

Unbalanced current distribution  
Complex joining technology  
Modular assembly  
Lost cross section (voids)  
Mechanically unstable (if not impregnated)  
Large operating current

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### The broad family of cabled superconductors

*Bath cooled*

*Co-extruded*

*Braided*

*Co-axial*

**MULTISTAGE**

*Wind & React*

*Forced flow*

*Armored*

*Hybrid*


*React & Wind*


*Soldered*

*Insulated*

*Cable-in-conduit*

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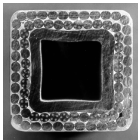


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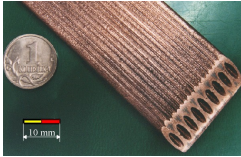
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### Three historical milestones of cables


**The OMEGA magnet (early 70' , cern)**  
 Forced flow single channel, fully transposed,  
 soldered, outer shell of copper wires  
 -> over 20 years of operation!




**The T-7 Tokamak (mid 70' , Kurchatov)**  
 Electrolytic copper assembly, non-transposed,  
 Force flow in 9 parallel channels  
 -> e.m. instability, blocked channels issues




**The Tevatron (late 70' , Fermilab)**  
 Flat "Rutherford" single stage cable, bath cooled,  
 wrapped, semi-transparent insulation  
 -> strand movement, training



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## Another two important milestones of cables

### The ALEPH detector (mid 80' , cern)

NbTi single stage flat cable of 16 strands, co-extruded with pure Al stabilizer, conduction cooled, self-protected for quench

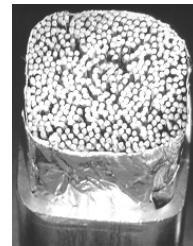
*The mother of all modern detector conductors*



### The LCT-WH TF coil (early 80' , Oak Ridge)

Nb<sub>3</sub>Sn Cable-in-conduit, wind&react&transfer, superalloy conduit

*The aunt of most fusion conductors*



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## Requirements for superconducting cables

The catalogue of requirements is the top level of specification. Requirements must be strictly enforced before choosing the various options for layout. The *top requirements are dictated by the application, not by the magnet design.*

E.g. “high field quality” is a requirement for the accelerators (application).

In terms of *winding*, it means “*precise position of the conductors*”.

In terms of *cable*, it means “*homogenous current distribution*”

In terms of *strand*, it means “*low residual magnetization*”

The conductor designer translates the requirement into specifications for a particular design. In the case of “high field quality requirement”, the designer may specify thin filaments, monolithic conductor (large composite or soldered cable).

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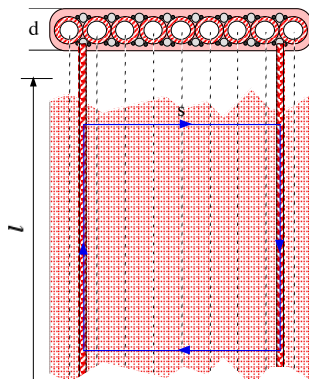


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## Typical cable requirements – Full Transposition

“each current carrying element exchanges its position in the cable”

Full transposition is an illusion in a superconductor (the filaments are not transposed in a strand). Transposition provides uniform current distribution during the charge (but not necessarily in steady state).



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**The case of T-7.** The parallel, non-transposed strands form a huge loop of coupling currents for self field or external field change:

$$I_{cc} = \frac{V}{R} = \frac{\dot{B}(l \cdot s)}{\rho_{cu}(s/d \cdot l)} = \frac{\dot{B} l^2 d}{\rho_{cu}}$$

With  $l \approx 200\text{m}$ , even at  $dB/dt = 0.1\text{G/s}$ , the induced current is in MA range, leading to saturation / flux jumps. Nonetheless, the very low  $J_{cu}$  and transverse resistance helps recovery and T7 achieved 80% of the nominal current.



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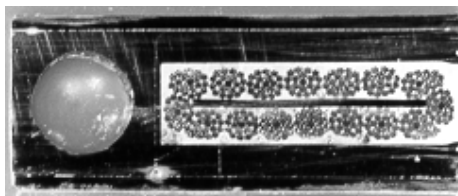
## Transposition and current re- distribution - 1

In multifilament composites the outer shell of filaments quickly saturate at charging, but smooth re-distribution is achieved through the low resistivity matrix.

**The effect of non-perfectly transposition in cables is mitigated by low transverse resistance.**

SULTAN, high grade  $\text{Nb}_3\text{Sn}$  conductor, R&W (1985):

The 1. and 2. cable stage are non-transposed, core+6x(1+6)+12x(1+6), but the solder matrix promotes current re-distribution. The 1. and 2. cable stages behave as a composite with  $\varnothing = 1.7\text{ mm}$



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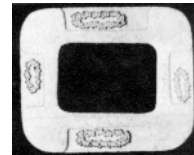


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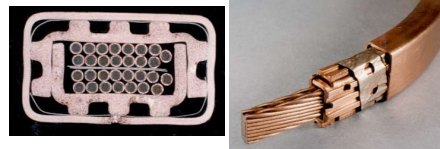
## Transposition and current re- distribution - 2

Two Nb<sub>3</sub>Sn **non-transposed** cabled conductors from ETL (JA) are reported to satisfactorily operate in model coils:

ETL 1978, four rotary braids of Nb<sub>3</sub>Sn strands, R&W, soldered in slots of a rectangular copper pipe



ETL mid 80', two flat cables of Nb<sub>3</sub>Sn strands, R&W, encased between shells of copper stabilizer



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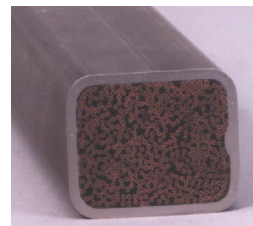
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## Transposition and current re- distribution - 3

Two NbTi **fully-transposed** cabled conductors did not achieve 100% performance in coils

DPC-U (JA), late 80', CICC of 486 insulated NbTi strands, 3x3x3x3x6, fully transposed.

*The coil quenched 1 s after full current charge due to unbalanced current re-distribution: from the "inductive", balanced distribution, the current re-distributes in steady state according to joint resistance distribution. When an overloaded strand hits the critical current, another current re-distribution should take place, but the diffusion time from the weak spot to the joint is much too long compared to the quench propagation*



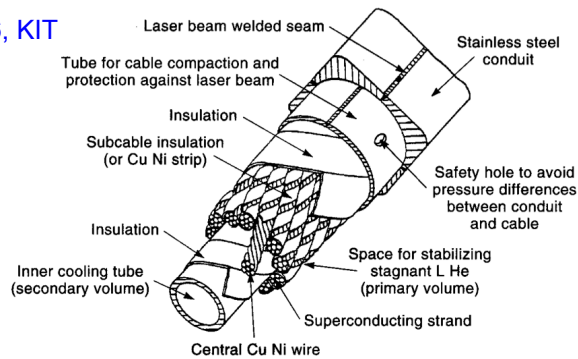
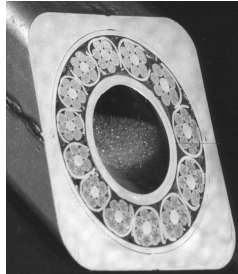
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## Transposition and current re- distribution - 4

The Polo conductor/coil,  $\approx 86$ , KIT



Two separate channels, stagnant supercritical and forced flow 2-phase. 78 NbTi strands, **fully transposed**, (core +6)x13. Insulation between subcables. The joints preserve the **separation among subcables**.

*Excellent performance for transient field (1000T/s) and ac loss ( $\tau = 0.2$  ms), but **only 70% of  $I_c$**  achieved in dc, likely due to current unbalance at the coil terminal*

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## Conclusion on transposition and current re- distribution

Despite dogmatic statements about transposition, **non-transposed cables may work** in steady state, provided that low transverse resistance is granted for current re-distribution.

The performance of fully transposed cables with **very large (infinite) transverse resistance** is limited by the homogeneity of the resistance distribution at the joints/terminals.

**Full transposition remains mandatory for pulsed and AC applications.**  
*Transverse resistance for local current re-distribution is a design parameter of paramount importance: it must be targeted as low as the ac loss allows.*

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## Conductor movement

Conductor movement, either slip-stick of individual strands inside a cable or full conductor movement in a winding, may be easily *restricted by solder / epoxy impregnation*.

In case of **bath cooling and cable-in-conduit**, impregnation is not applicable.

Any displacement,  $\Delta L$ , of a current carrying element in a background magnetic field causes a change of **stored energy**, e.m. ( $B \cdot I \cdot \Delta L$ ) and, if applicable, elastic. Depending on the friction coefficient, a fraction of  $\Delta E$  can be locally dissipated.

**Slow displacements** do not generate a quench because the dissipated power is lower than the heat removal rate.

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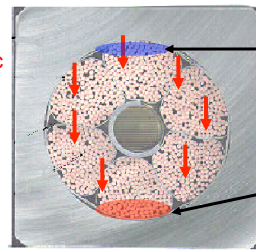


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## Strand movements in a cable in conduit - 1

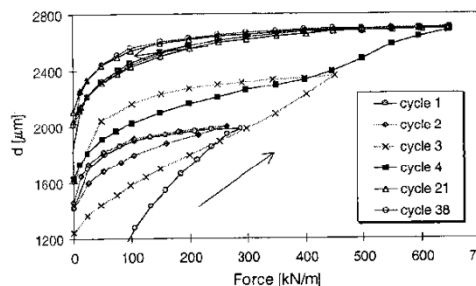
The internal e.m. forces push the strand bundle to one side of the conduit. The energy over one load cycle is measured as "mechanical hysteresis". Energy and power are smaller than the magnetization hysteresis loss,  $\approx 5 \text{ mJ/cm}^3 \rightarrow$  **no issue for conductor stability**

Magnetic forces



Maximum displacement

Maximum pressure



Less than 5% of the work done on the strand bundle is dissipated as frictional energy

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## Strand movements in a cable in conduit - 2

Slip-stick of an individual strand. With  $I_{strand}$  of the order of 100-200 A and displacement  $\Delta L$  of the order of 0.1 mm, the energy is

$$\Delta E / \ell = \Delta L \cdot I_{strand} \cdot B \approx 0.2 \text{ J/m}$$

Assuming than 1 cm long section of strand is involved in the slip-stick, the actual change of stored energy is  $\Delta E \approx 2 \text{ mJ}$

We assume that 5% of  $\Delta E$  is dissipated by friction in the strand, leading to  $\Delta E / V \approx 10 \text{ mJ/cm}^3$

which on the time scale of ms, i.e. strictly adiabatically, *could lead to a local quench*. However, the local helium enthalpy and the current sharing to neighboring strands promote a safe recovery.

(Slip-stick cannot occur in solder filled cables)

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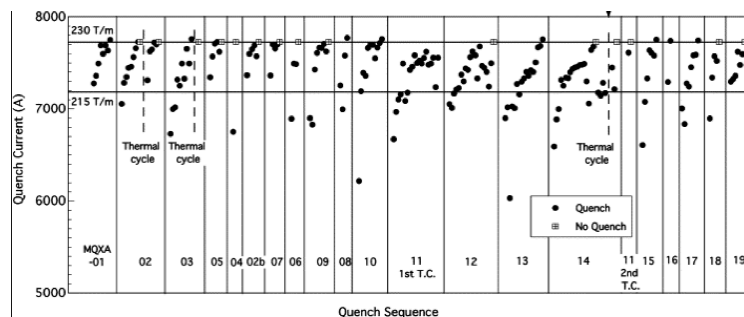


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## Conductor movements in bath cooled windings

Training in accelerator magnets can be considered as a particular case of slip stick, involving more than one strand.

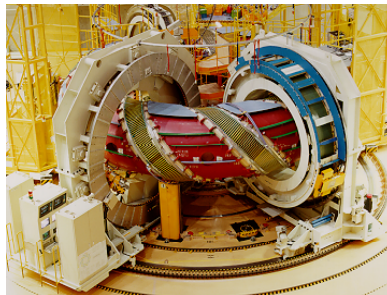
Opposite to the cable-in-conduit, the *limited local helium inventory*, the *cable insulation* and the *high current density* may lead to a stability issue, i.e. to a quench. As most of the slip sticks are irreversible events, a “training” effect is observed, i.e. the same slip stick will not occur again at next charge and the winding learns to behave at each lesson at increasing  $I \cdot B$  load.



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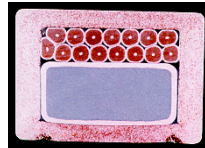


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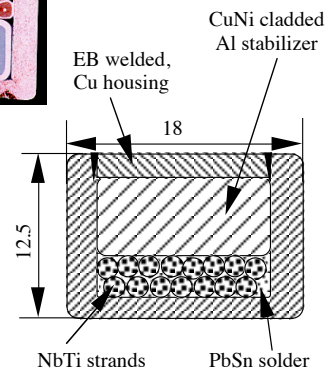
### The case of LHD NIFS 1996, Japan

Highly engineered conductor, 13 kA, 6.9 T



Bath cooled, flat cable of 15 NbTi strands, high RRR Al stabilizer, sheathed by CuNi. Cable and stabilizer are solder filled into a Cu housing, sealed by two longitudinal EB welds.

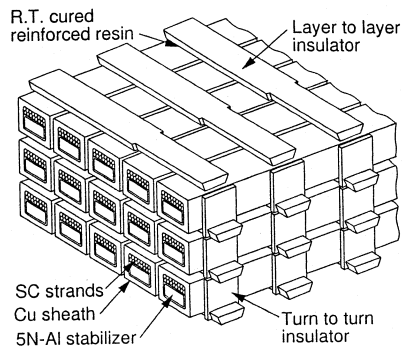
**The design is driven by cryo-stability. The copper surface is treated (CuO) to improve the heat exchange to helium.**



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### Helical Coil Winding

The design is a compromise between a solid support of the winding pack against the loads and the large wet surface for stability. The turn and layer insulation are obtained by spacers (2 and 3.5 mm), with coverage graded from 69 % (low field, high stress) to 42% (peak field, low stress).

In LHD, no strand movement is possible (soldered cable), but a collective sliding of the winding pack happens, with large dissipated energy.

The expected cryo-stability by cold-end recovery was actually not achieved. The operating current had to be limited to 11.3 kA due to observed propagating normal zone. A limited improvement is obtained by sub-cooling the bath.

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## Degradation

Performance below design is stigmatized as “degradation”: it can be due either to *accidental event in the manufacture* or to *intrinsic feature of the design*.

**Coil Degradation:** winding movement (LHD), training (LHC), insufficient cooling, radiation damage, insulation failure

**Conductor Degradation:** mechanical irreversibility ( $\text{Nb}_3\text{Sn}$ ), self-field instability, flux jumps, lack of transposition, unbalanced current distribution

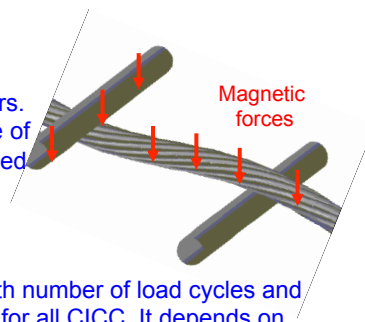
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## Conductor degradation examples – $\text{Nb}_3\text{Sn}$ in CICC

The transverse load on the strand bundle leads locally to stress concentration at the strand crossovers and to deflection between crossovers. When the stress exceeds the reversibility range of the  $\text{Nb}_3\text{Sn}$  strands, filament breakage is observed and the conductor performance degrades by broadening of the transition (reduced n-index).



The transverse load degradation progresses with number of load cycles and thermal cycles. The degradation is not identical for all CICC. It depends on

- Robustness of the strand (reversible range)
- Void fraction in the strand bundle
- Size / Aspect ratio of the strand bundle
- Sequence of the twist pitches

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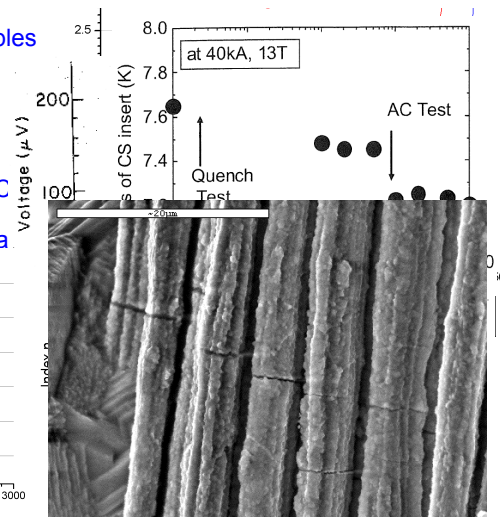
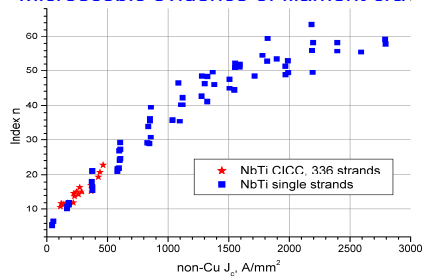


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### Evidence of irreversible degradation – Nb<sub>3</sub>Sn in CICC

- I<sub>c</sub> test on strands extracted from cables
- Resistive behavior upon cyclic load
- T<sub>CS</sub> degradation on ITER CSMC
- N-index comparison, strand vs CICC
- Microscopic evidence of filament cra



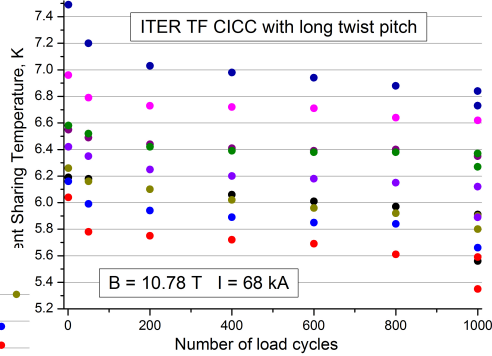
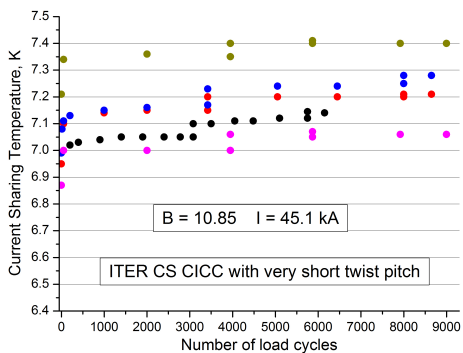
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### The ITER CICC

The TF CICC (long pitches) degrade



The recent "very short" pitch is ok

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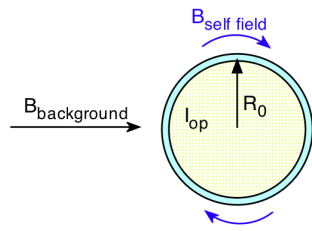


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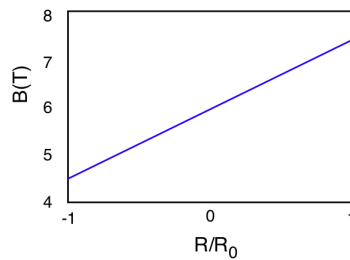
### Conductor degradation examples – NbTi self field effect

In cabled conductors with *high operating current* and *low background field*, the superconducting transition may be “sudden”, without visible current sharing. The correct name for these case is “**self-field instabilities**”.

Example: NbTi medium size CICC



$R_0 = 8.3 \text{ mm}$   $I_{op} = 60 \text{ kA}$   $B_b = 6 \text{ T}$



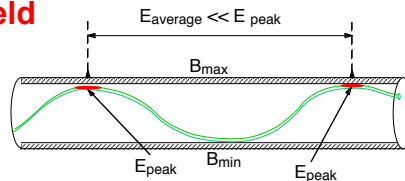
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### Local and Average Electric Field

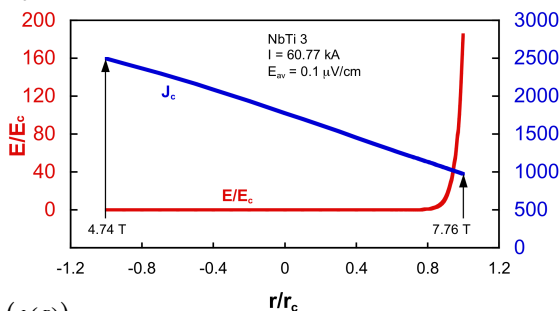
In twisted superconductors, the strands travel continuously from the low field to the high field. The field gradient can be several Tesla and the strands hit the critical surface and develop voltage only at a very short length



The *local electric field*,

$$E(R) = E_c \left( \frac{J}{J_c(R)} \right)^n$$

may vary substantially over few mm.



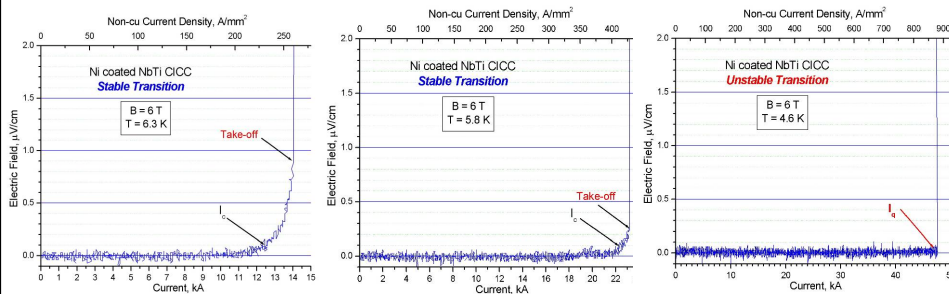
The E field distribution is

$$\frac{E}{E_c} = \int_{-r_c}^{r_c} 2 \frac{(r_c^2 - r^2)^{1/2}}{\pi r_c^2} \left( \frac{J}{J_c(B)} \right)^n J_c(B) dr$$



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### The V-I Transition

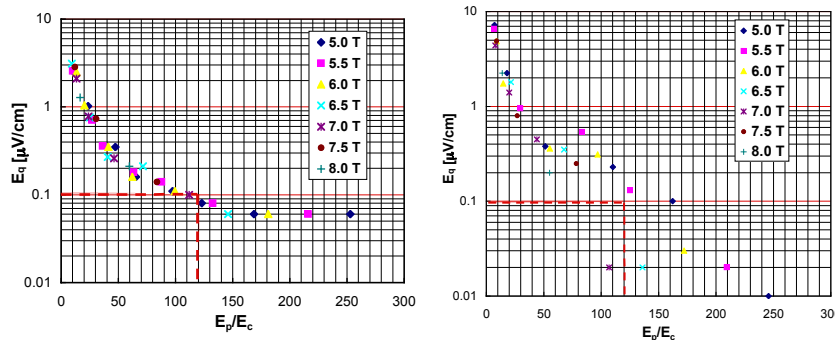


At low current density, i.e. low self field, the V-I curve is smooth with extended current sharing range.

At increasing current (e.g. decreasing the temperature), the take-off electric field decreases till it disappears in the noise and the transition looks “unstable”, but actually well reproducible.



### Sudden take-offs are peak field induced quench

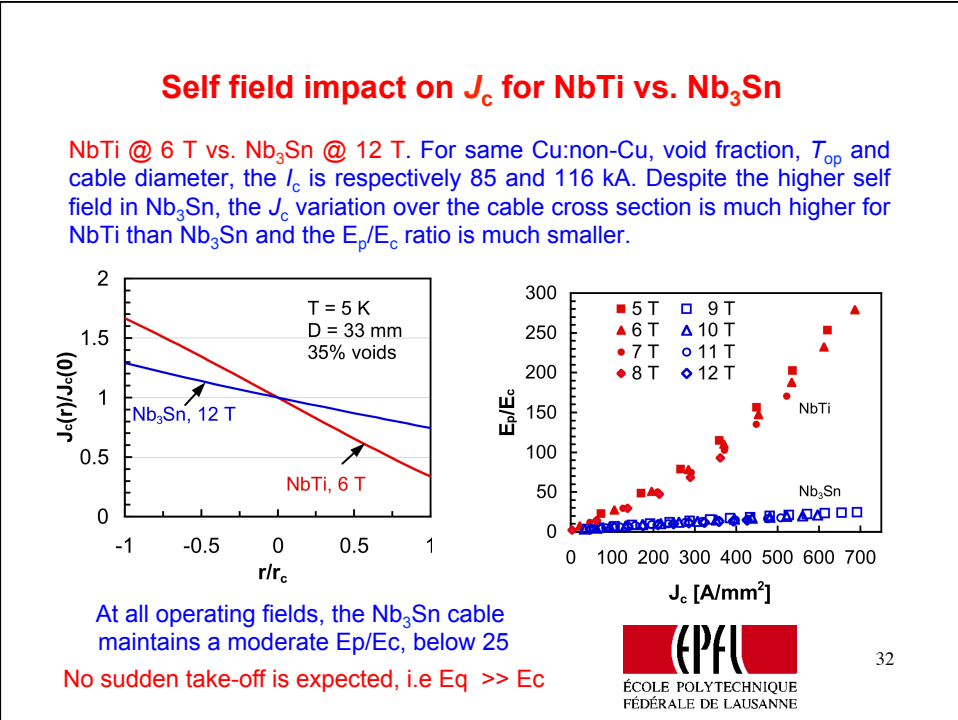
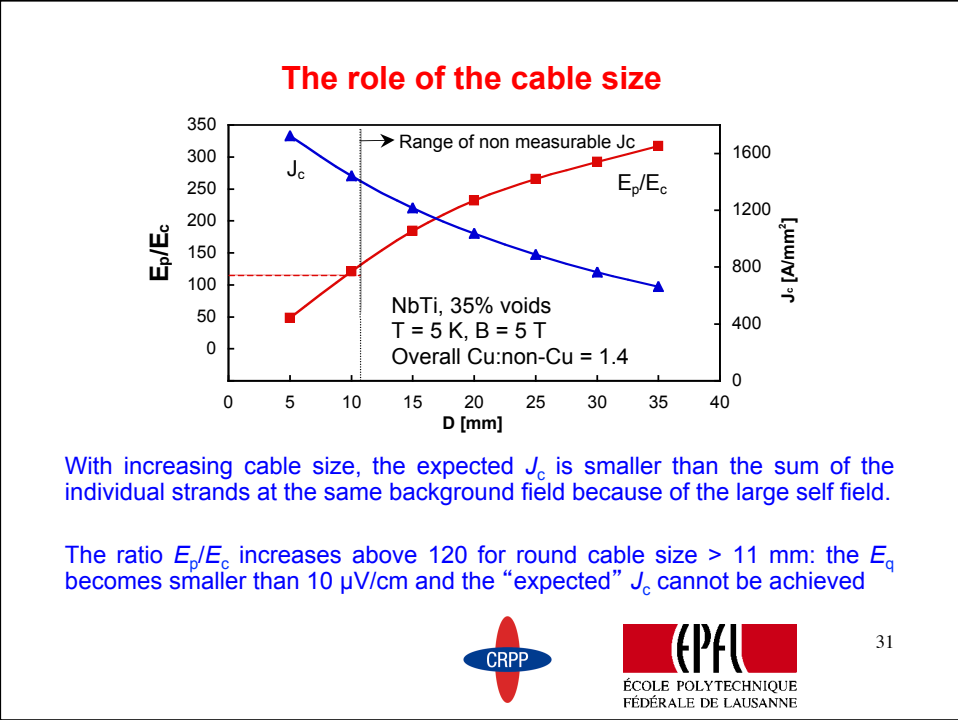


**Ni coating**

**Solder coating**

As the take-off electric field,  $E_q$ , decreases, the ratio of peak-to-average electric field increases. In our example, the  $E_c = 10 \mu\text{V/m}$  criterion for  $I_c$  cannot be reached when  $E_p/E_c > 120$ . The interstrand resistance in CICC (solder / Ni coating) has a marginal impact on the  $E_p/E_c$  threshold



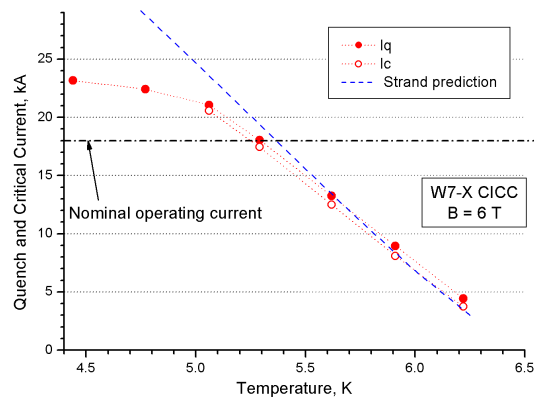


### Should we care about Self Field induced take-off ?

As long as the cable current is perfectly balanced among the strands, the self-field induced take-off is just a curiosity, i.e. no degradation.

At the sudden take-off, no current re-distribution is possible because the voltage is too low, even when the peak electric field is sufficiently high to drive a quench.

In case of current unbalance, the performance loss is high and unpredictable. NbTi CICC must be designed to operate below the threshold of sudden take-off

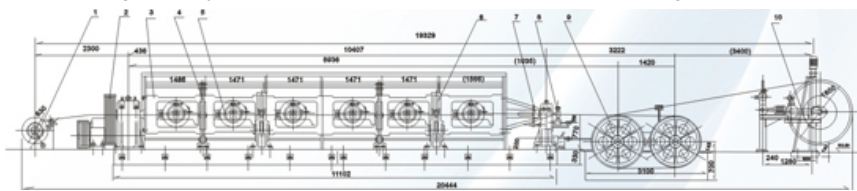


In W7-X CICC, the threshold for sudden take-off is about 20 kA compared to an operating current of 18 kA



### Manufacturing aspects – Tubular Stranding Machines

Suitable for small and medium size stranded cables, with short/medium twist pitch. The mass of the pay-off coils and take-up coil is not rotating. A “thin” cylinder surrounding the pay-off coils picks up the wire and rotates at high speed.



### Manufacturing aspects – Cage Stranding Machines

Suitable for large size stranded cables, with short/medium twist pitch. The mass of the pay-off coils is attached to one or more “planetary” holders and rotates. The production rate is limited by the rotating speed and cable pitch. The “cages” holding each pay-off coils can counter-rotate (back twist) to obtain a torsion-free cable.



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### Manufacturing aspects – Drum Twisters

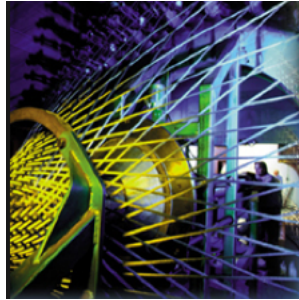
In a variation of the cage strander, the large individual pay-off coils are placed on ground on rotating holders. The cabling point is stationary and the take-up coil rotates.



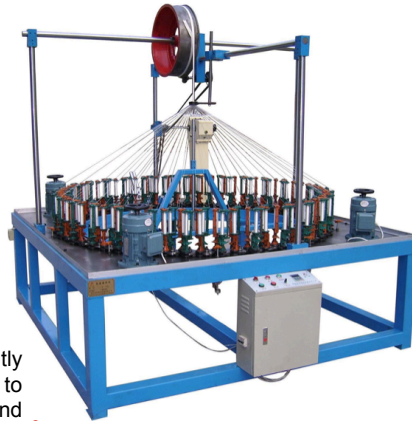
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### Manufacturing aspects – Braiders

Most common braiders are used for shielding / armoring of conductors (rotary braiders): the braid is a hollow cylinder made by two interleaved layers of parallel wires. Such braids are not transposed for parallel and transverse field.



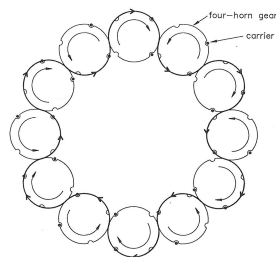
The pay-off coils must move independently (must have small radius). It is impossible to build braiders with large number of wires and large size/inventory of material



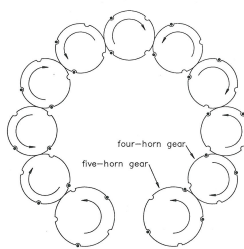
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### Manufacturing aspects – Special Braiders

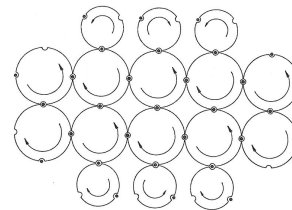
A modification of the rotary braider allows to produce a fully transposed flat braid (Isabelle, 80°). A further variation of the geometry/movements allow to produce a full braid (lattice braid) with fully transposed components.



Rotary Braid



Flat Braid



Lattice Braid

Due to the interleaved structure, braids have a superior mechanical modulus compared to stranded cables with same void fraction. The strand crossovers are at sharper angles. Only limited compaction is possible.



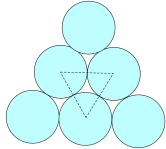
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### Manufacturing aspects – Rigid Compaction

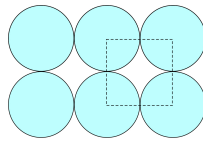
A bundle of round wires in a triangular array has a minimum void fraction of

$$1 - \frac{\pi}{2\sqrt{3}} = 0.093$$



For a square array, the minimum void fraction is

$$1 - \frac{\pi}{4} = 0.214$$



For single stage cables with “line contacts” between strands the nominal values of void fraction are realistic, except the issue of the twist angle. For multistage cables, with strand crossover, the minimum void fraction without plastic deformation is much larger, above 40%.



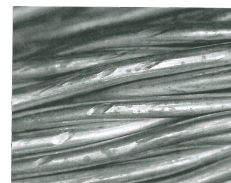
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### Manufacturing aspects – Plastic Compaction

In practical cables, plastic deformation occurs at the strand contacts, either lines or crossovers. The compaction of the strand bundle is substantially a plastic deformation.

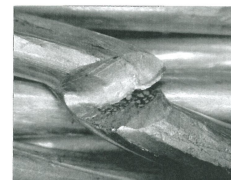
Most cable designs aim at low void fraction

- to restrict the strand movement (NbTi & Nb<sub>3</sub>Sn)
- to avoid strand degradation (Nb<sub>3</sub>Sn) under operating loads
- to enhance the engineering current density.



The practical lower limit for cable compaction is the strand damage. Such limit depends on the cable layout (number of stages, sequence of pitches) and on the deformation tolerance of the strand.

Beside “strand breakage”, other kinds of degradation are “broken diffusion barrier”, “disconnected filament array”.



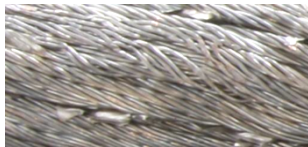
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### Manufacturing aspects – Compaction Limits

In multistage cables, the compaction process must be gradual, decreasing the void fraction at each cabling stage. In round CICC, practical lower limits are 25%-27%. Flat cables can go further down to 20%. Single stage cables are compacted down to 10% voids.

At large, cables made of NbTi and Bronze Nb<sub>3</sub>Sn strands better withstand large compaction loads.

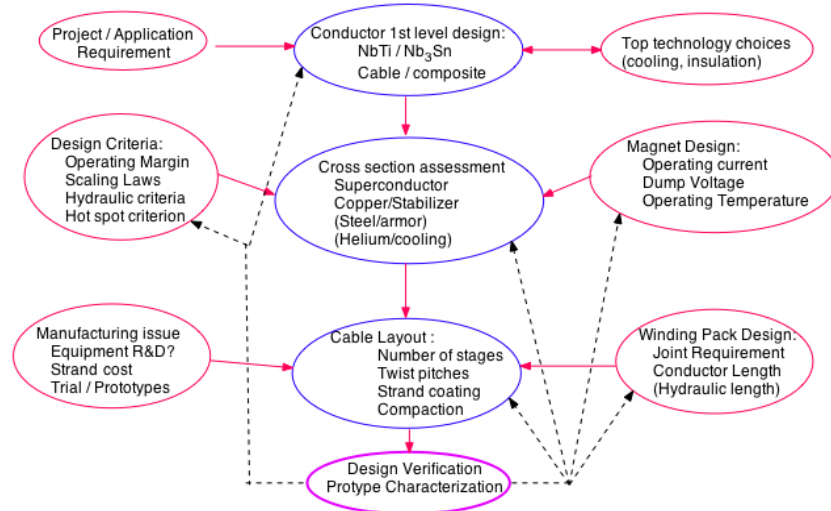


Strand damage is strictly forbidden by QA manuals, however it takes a lot of effort to substantial impair the conductor performance by “strand damage”!!



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### A chart for cabled conductor design



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### Moral Recommendations

- Carefully read what is done in the past, learn from former lessons
- Fix the source of a problem rather than cure its consequence
- Keep an open mind for a broad range of
  - Designs/layouts
  - Manufacturers / suppliers
  - Methods / technology
- Be ready for feed-back, constructive criticism, self-criticism
- Do not get caught in the success-oriented loop
- Adjust to budget and schedule boundaries



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