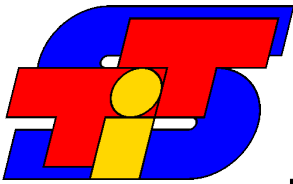


STD6 Symposium
Carmel, California
September 13, 2006

Design and Production of the LHCb Silicon Tracker

Olaf Steinkamp

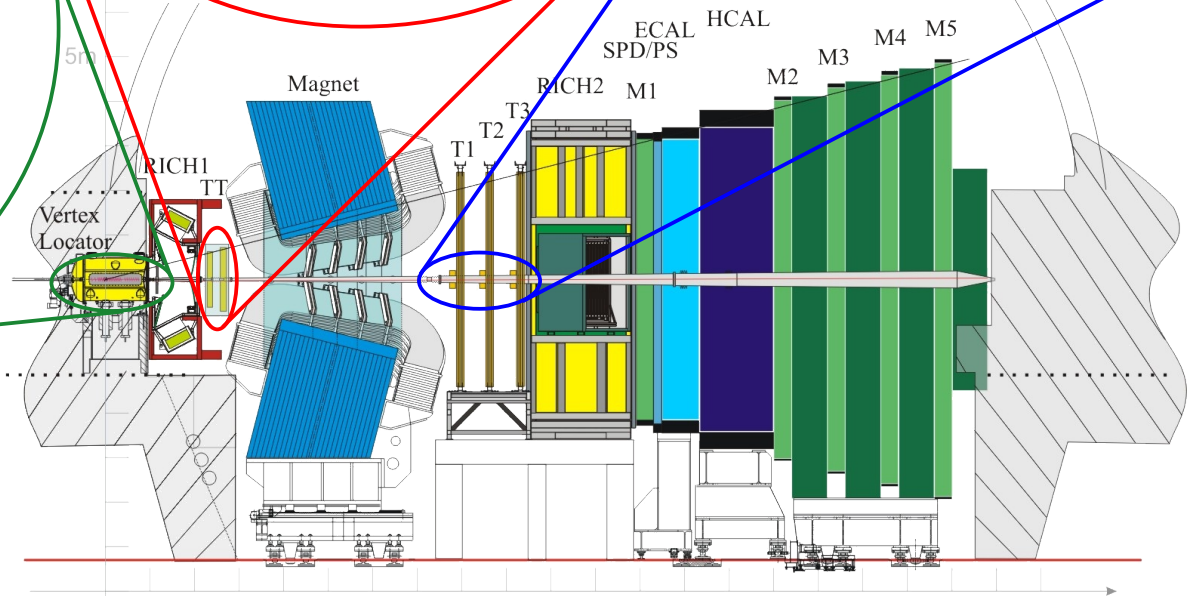
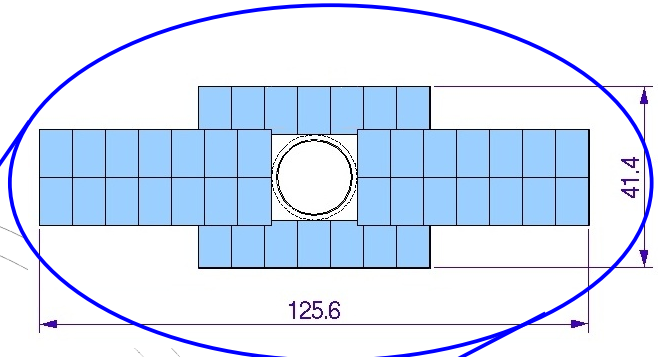
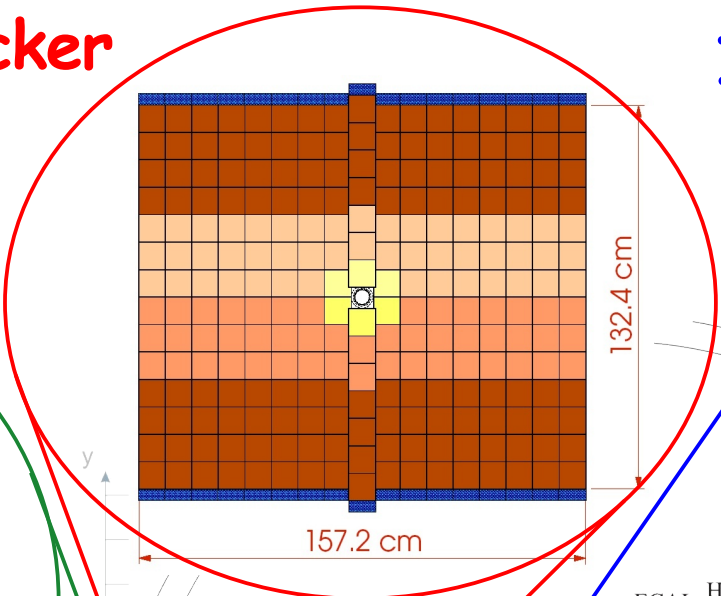
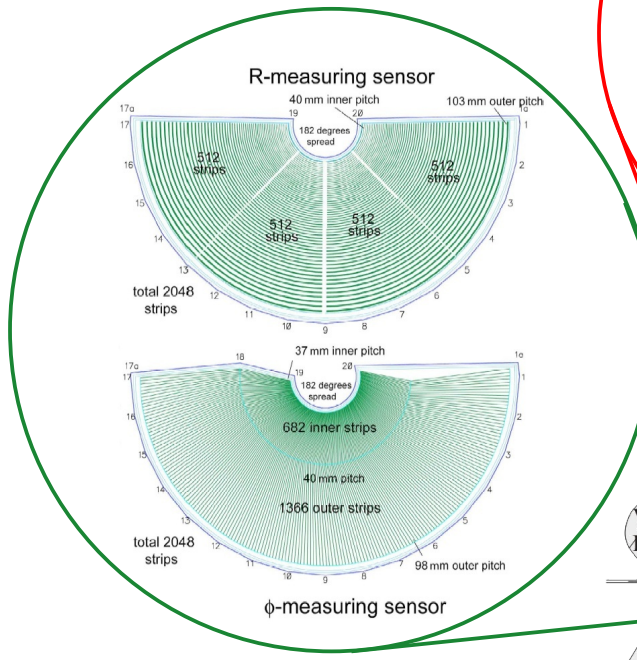
Physik-Institut der Universität Zürich
Winterthurerstrasse 190 CH-8057 Zürich
olafs@physik.unizh.ch



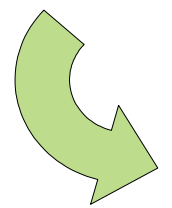
LHCb Silicon Detectors

Trigger Tracker (TT)

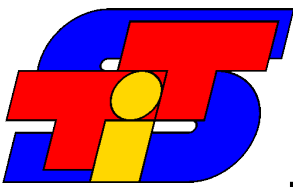
Inner Tracker (IT 1-3)



Vertex Locator (VELO)



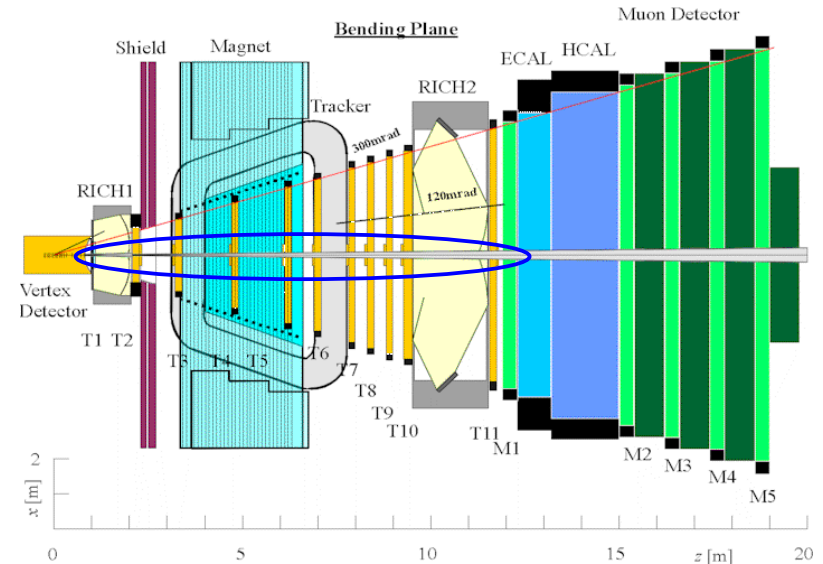
Martin van Beuzekom's talk at 9:20 tomorrow morning



A Short History

Once upon a time...

- LHCb "classic": 11 tracking stations
- each station: Inner & Outer Tracker
- Inner Tracker: some variety of Micro-Pattern Gaseous Detector (MSGC+GEM, 3GEM, Micromegas, Microwire)

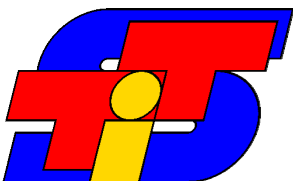


2000: start to investigate viability of a silicon micro-strip Inner Tracker

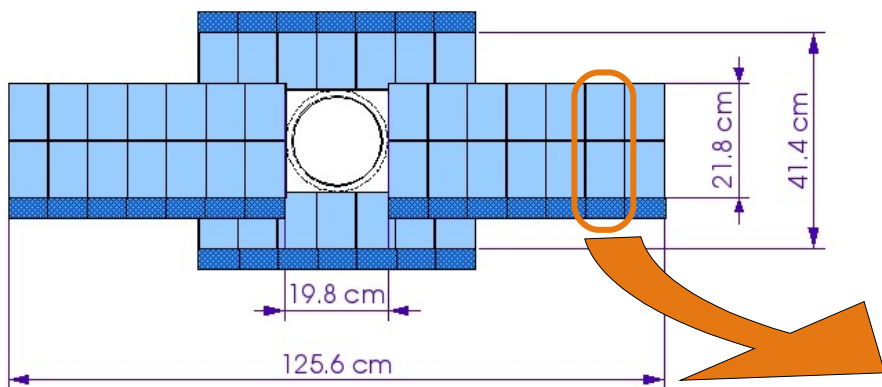
- adopted as baseline solution (for the 11-station detector) in May 2001
- Technical Design Report submitted in Nov 2002

2002: experiment-wide effort to reduce material budget (LHCb "light")

- reduce number of tracking stations from eleven to four
- the first of these all-silicon (→ Trigger Tracker)
- "Re-optimised Detector" Technical Design Report submitted in Sep 2003



Inner Tracker

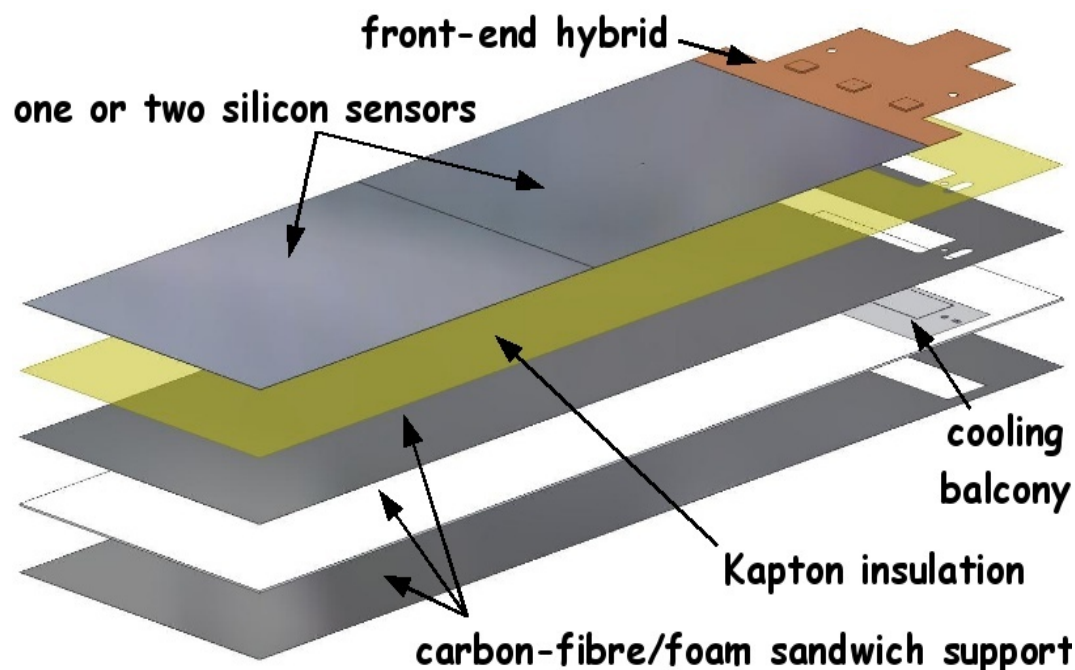


Three stations with four layers each:

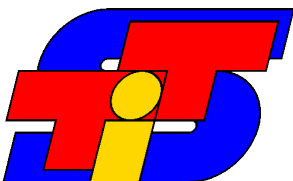
- 1-sensor ladders above/below beam pipe
- 2-sensor ladders left/right of beam pipe

Concerns in design phase:

- material budget
 - sensors as thin as possible
 - 320 μm for 1-sensor ladders
 - 410 μm for 2-sensor ladders
 - supports / cooling etc
- cost (number of r/o channels)
 - large pitch (197 μm)
- modularity (11 stations !)



**~ 4.2 m², 504 silicon sensors,
336 modules, 130k readout strips**



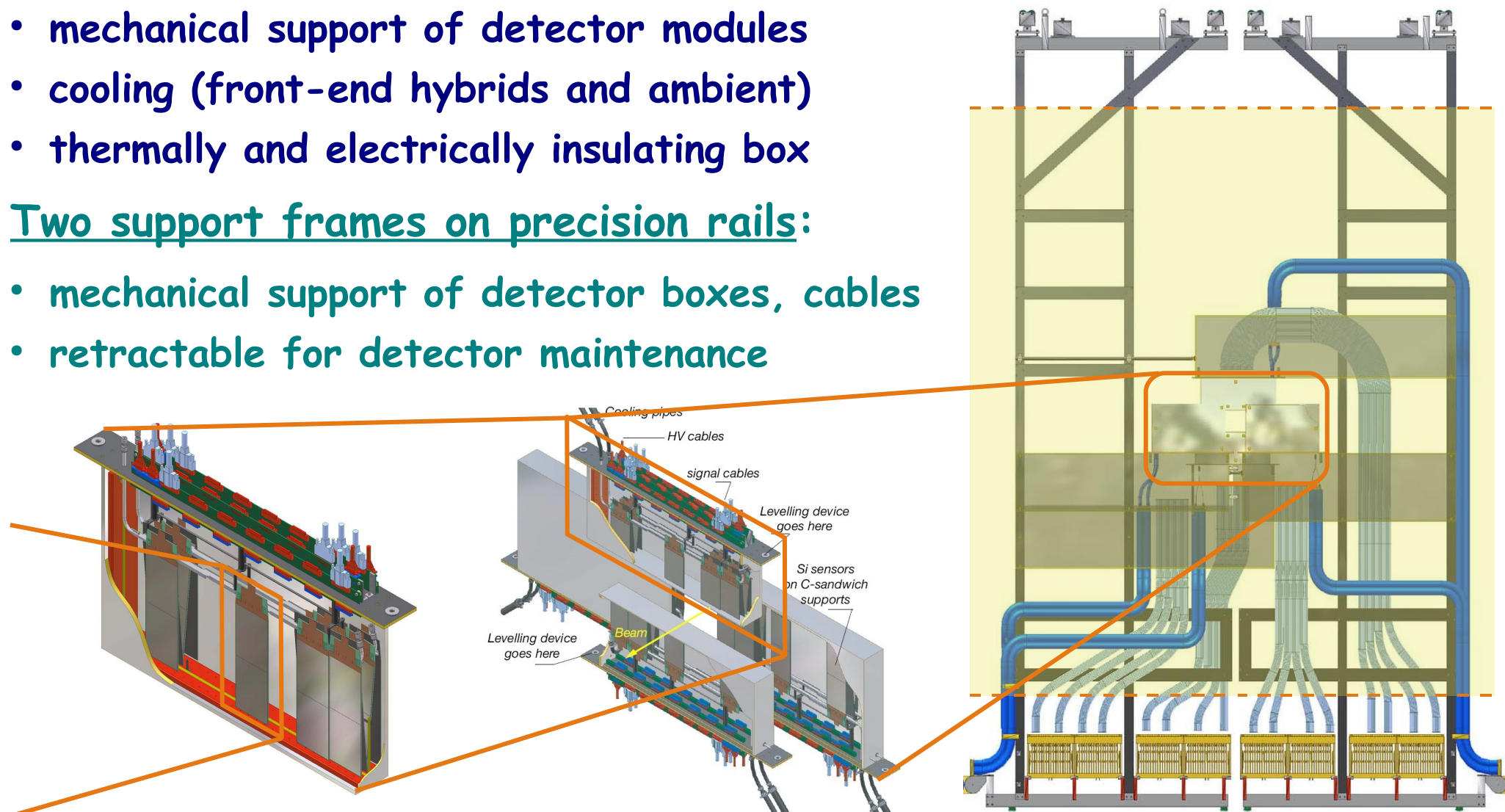
Inner Tracker Station

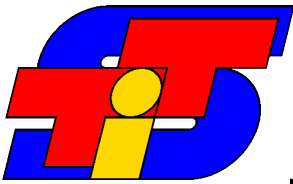
Four individual detector boxes surrounding LHC beam pipe:

- mechanical support of detector modules
- cooling (front-end hybrids and ambient)
- thermally and electrically insulating box

Two support frames on precision rails:

- mechanical support of detector boxes, cables
- retractable for detector maintenance

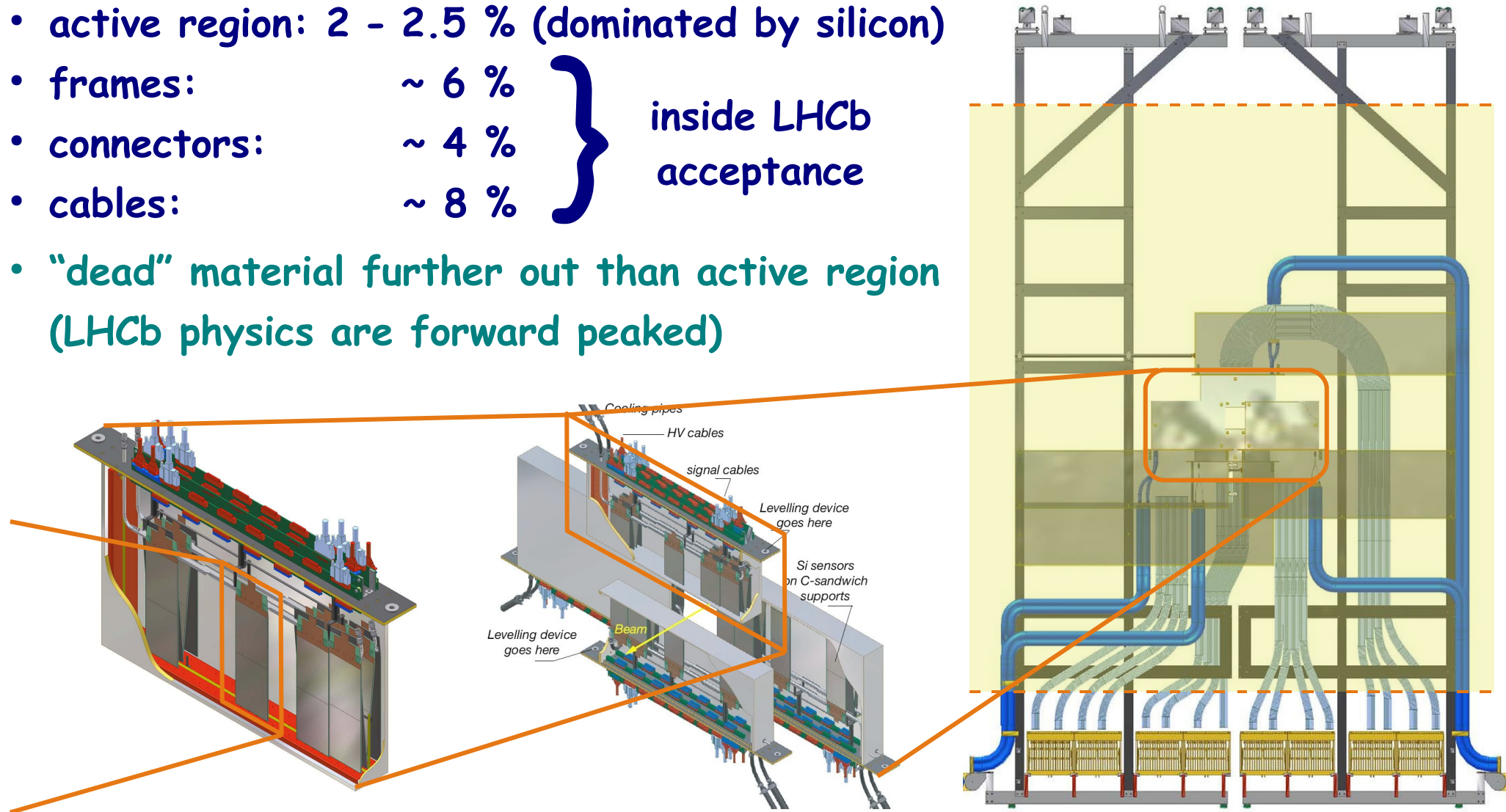


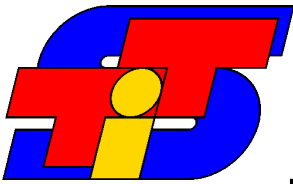


Inner Tracker Station

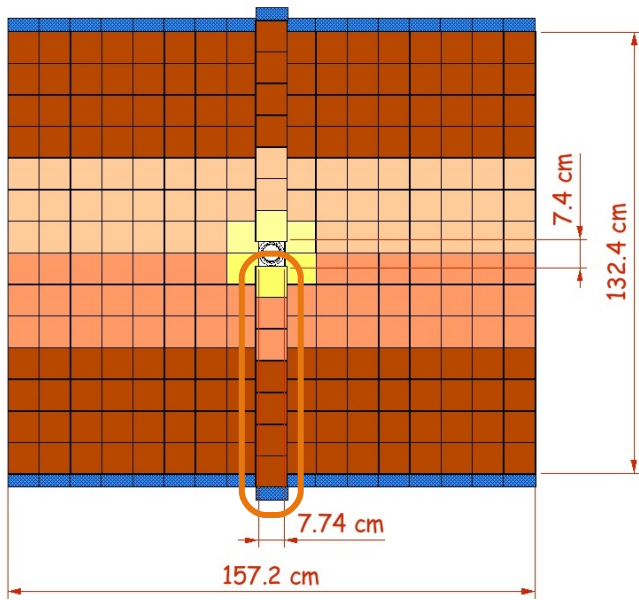
Material budget per Inner Tracker station:

- active region: 2 - 2.5 % (dominated by silicon)
 - frames: ~ 6 %
 - connectors: ~ 4 %
 - cables: ~ 8 %
- } inside LHCb acceptance
- "dead" material further out than active region (LHCb physics are forward peaked)





Trigger Tracker

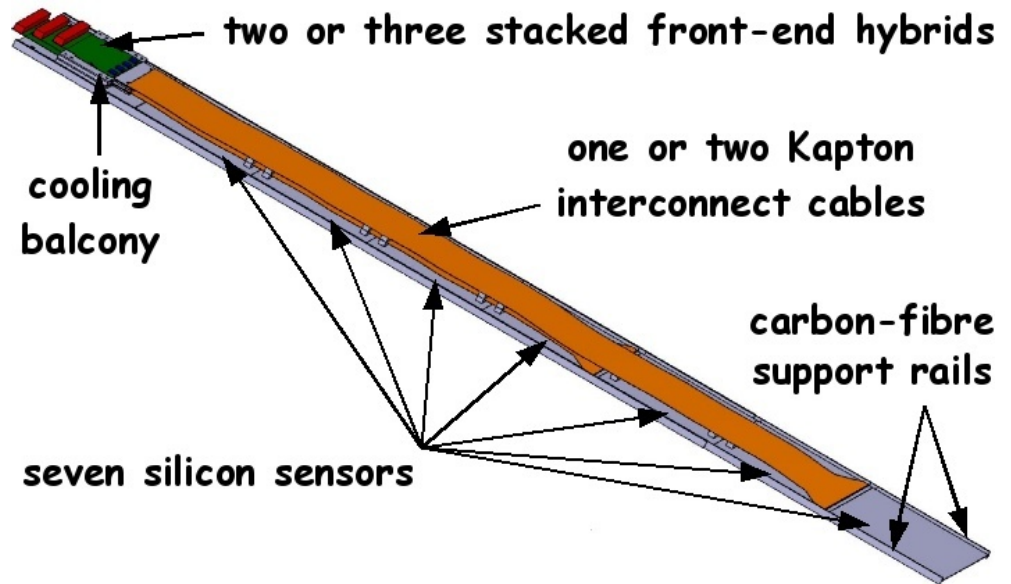


One station with four detection layers:

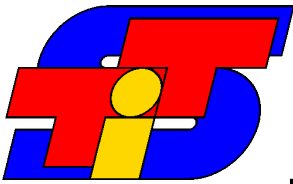
- 7-sensor long “half-modules”
- 1-/2-/3- and 4-sensor long readout sectors
- all r/o hybrids at one end of the module
- “inner” r/o sectors: Kapton interconnects

Concerns in design phase:

- material budget:
 - r/o electronics outside acceptance
- cost (number of r/o channels)
 - large pitch (183 μm)
 - long strips (up to 37 cm)
- S/N for very long readout strips



**~ 8.2 m², 896 silicon sensors,
280 r/o sectors, 143k r/o strips**



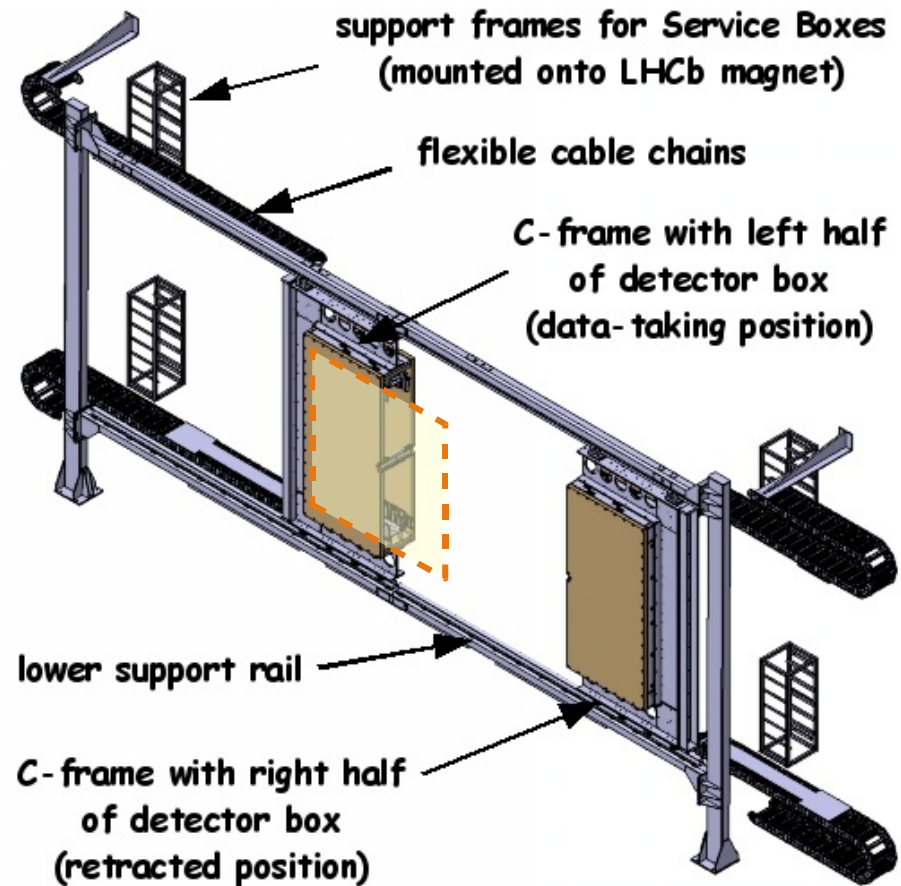
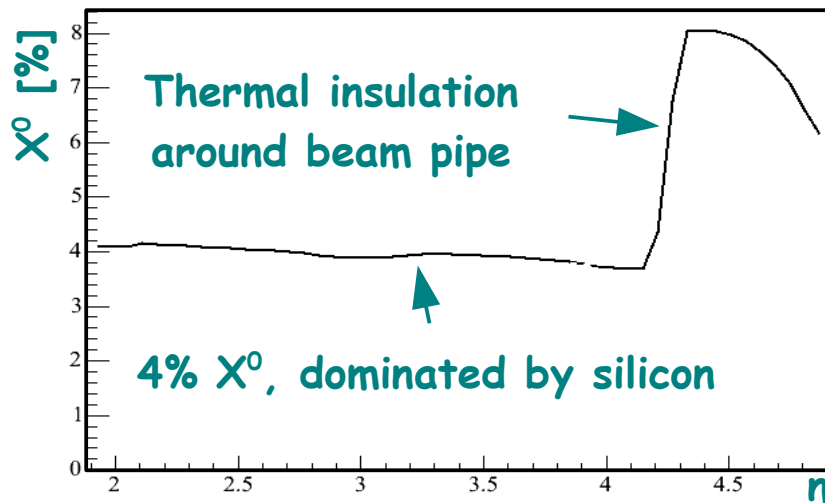
Trigger Tracker Station

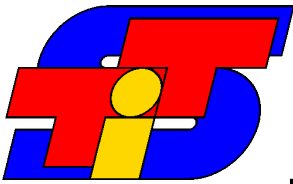
Two half stations, retractable for detector maintenance:

- support rails, frames and cables
- cooling (front-end hybrids and ambient)
- thermally and electrically insulating box
 - lightweight polyurethane foam sheets clad with thin aluminium / Kevlar foils
 - one large volume when closed

} outside of LHCb acceptance

Material budget inside acceptance:

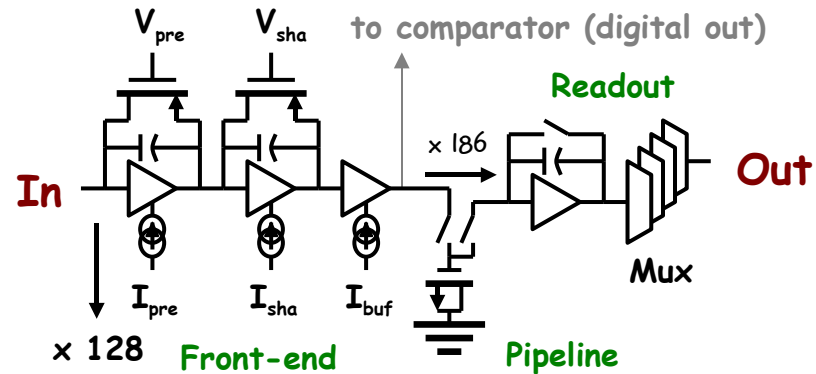




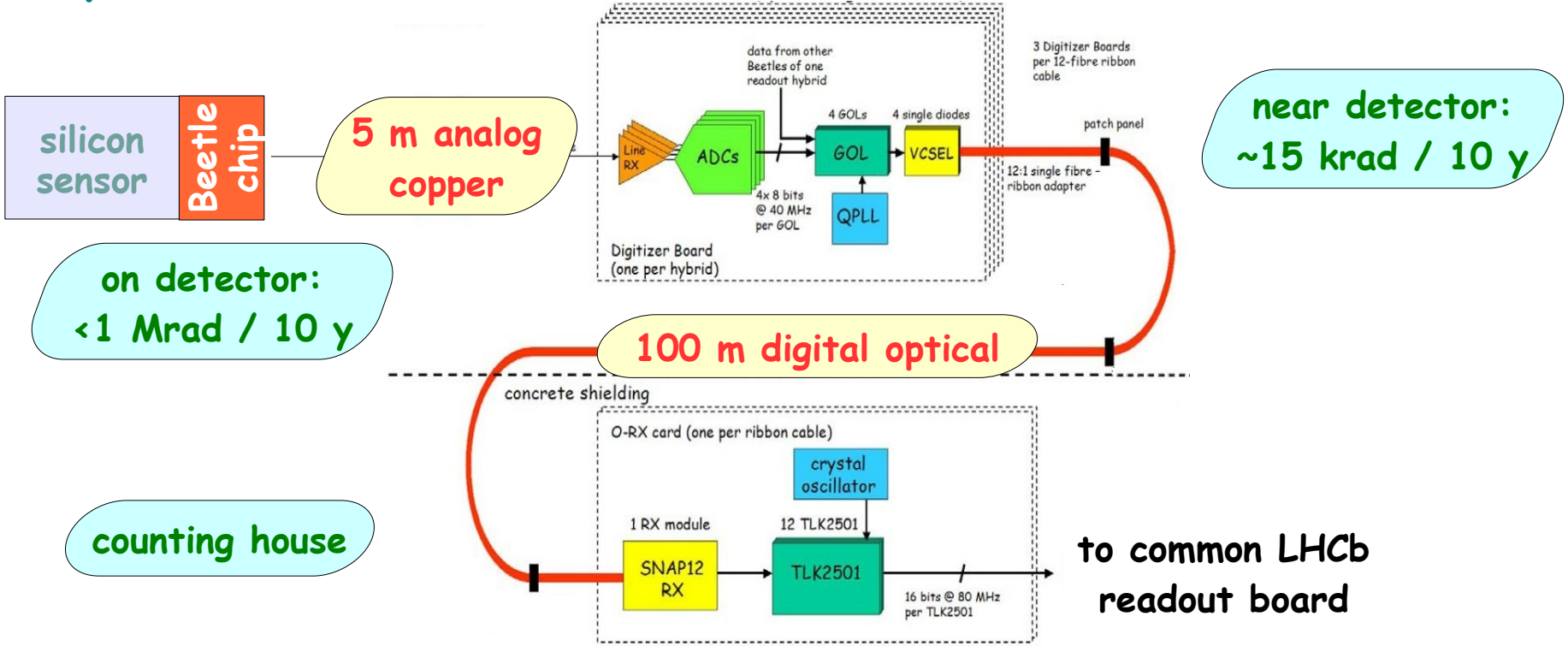
Silicon Tracker Readout

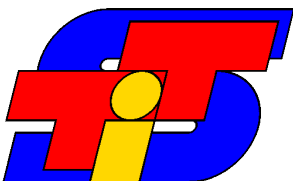
"Beetle" front-end readout chip:

- radiation-hard design in 0.25 μm CMOS
- analog pipeline, multiplexed analog readout
- adjustable shaping time of ~ 25 ns (via V_{fs})



Digital optical readout link:





Silicon Tracker R&D

Main concern: detector performance

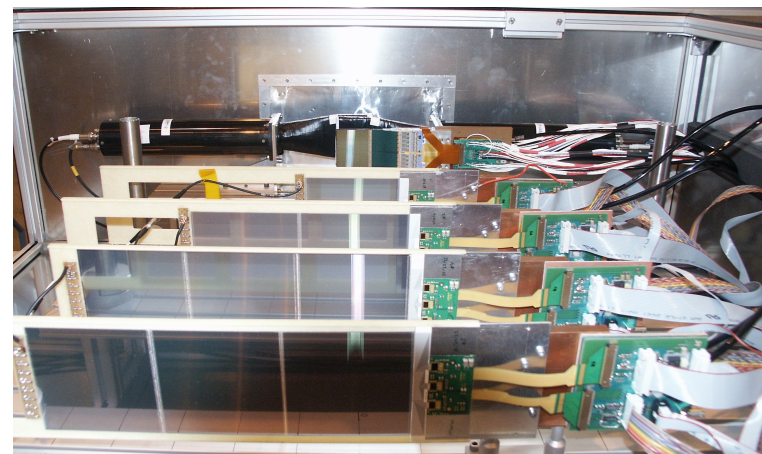
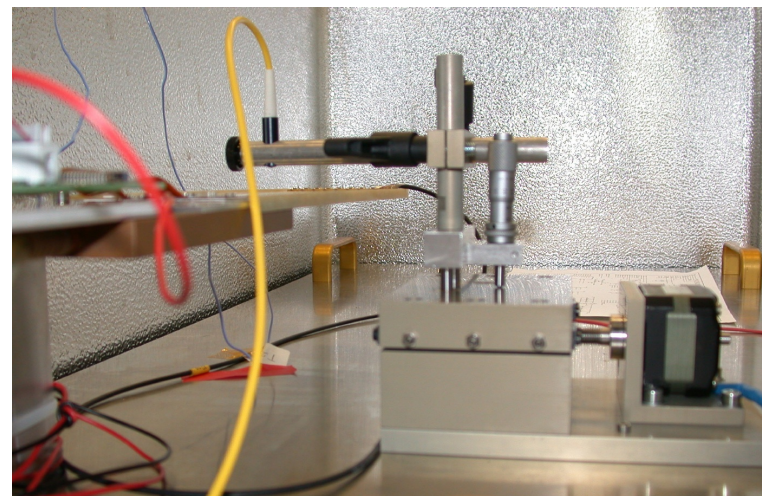
- required sensor thickness for Inner Tracker
- S/N for long r/o strips of Trigger Tracker (up to 37 cm, read out at 25 ns !)
- signal integrity for Trigger Tracker readout sectors with Kapton interconnect

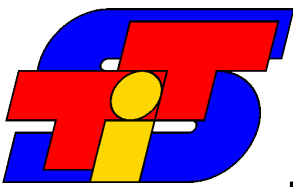
Infra-red laser test stand:

- pulsed infra-red laser, focussed to $\sim 10 \mu\text{m}$
- signal shape, charge sharing, CCE as function of inter-strip position of charge deposition

Test beams (120 GeV/c pions from SPS):

- beam telescope to determine particle impact position on detector under test to $\sim 15 \mu\text{m}$
- S/N and detection efficiency as function of inter-strip position

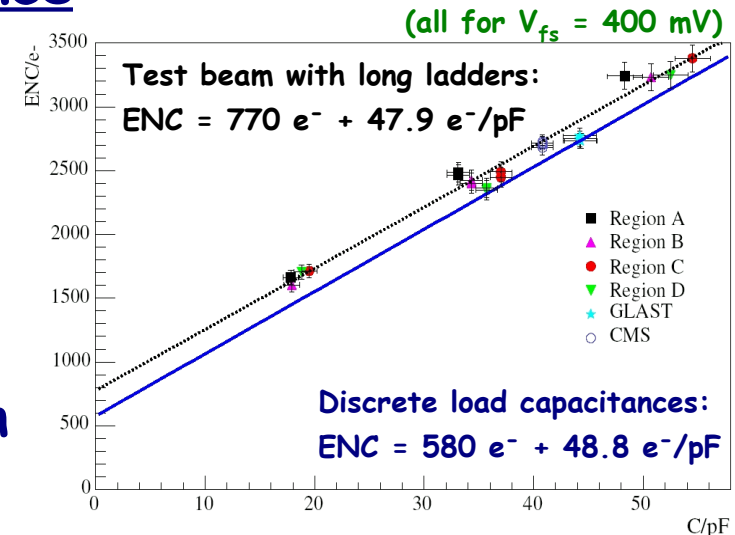




Main Findings from R&D

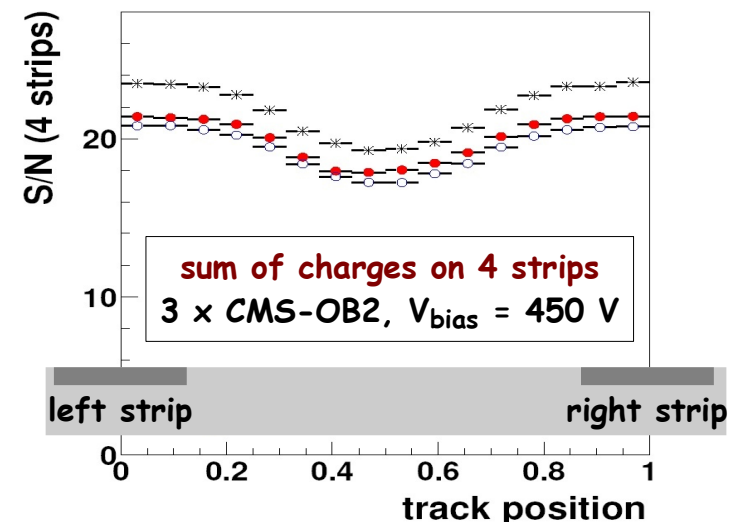
1) S/N scales linearly with detector capacitance:

- no significant contribution from strip resistance even for the longest readout strips (33 cm)
- confirmed by a combined SPICE simulation of r/o strips and Beetle front-end amplifier
- careful: strong dependence on interplay between noise spectrum of detector (resonances) and bandwidth of amplifier → do not generalise !

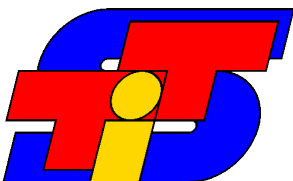


2) significant loss of CCE in between strips:

- independent of strip length and shaping time
- depends ~ linearly on (pitch-width) / thickness
- interpreted as being due to charge trapping at silicon bulk / oxide interface between strips



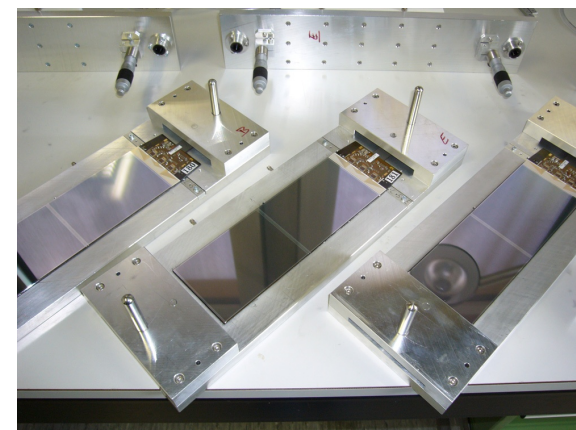
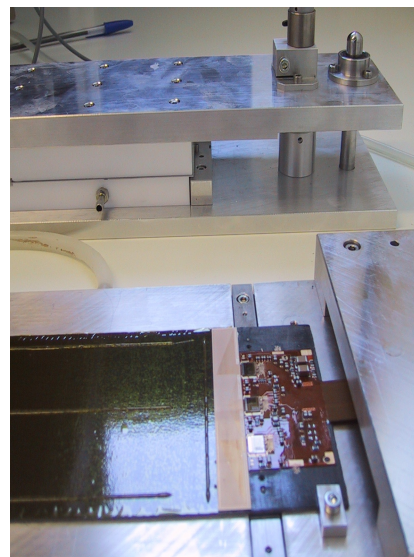
3) no deterioration of signal integrity due to Kapton interconnects

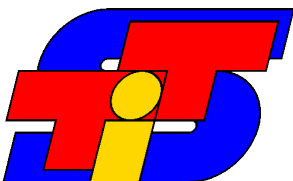


Inner Tracker Production

Main production steps:

- position hybrid & pitch adaptor, glue them to the sandwich support
- **r/o functionality test**
- position silicon sensor(s), glue it/them to the support
- **measure sensor alignment**
- bond hybrid & pitch adaptor, bond bias and GND to the sensor
- **r/o functionality and HV test**
- bond all readout strips
- **24h burn-in test:**
 - IV curves, strip noise to identify bad strips (shorts, opens, pinholes)
 - several temperature cycles between 20°C and 5°C

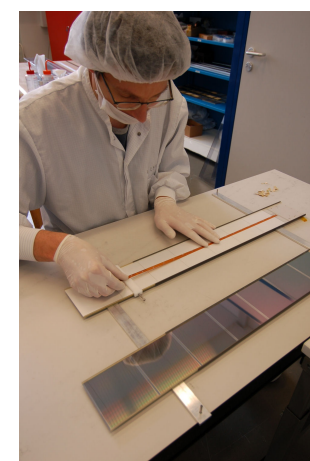
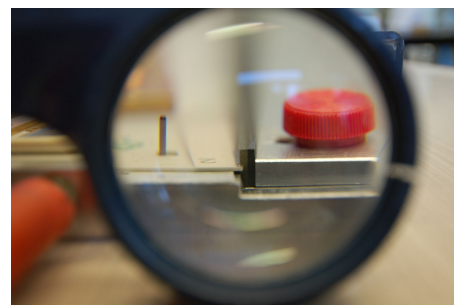
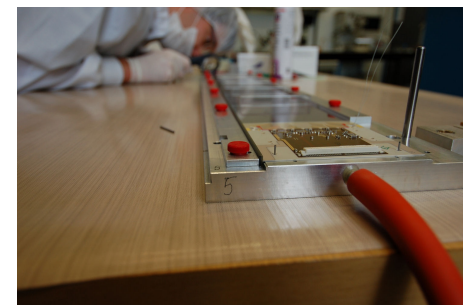
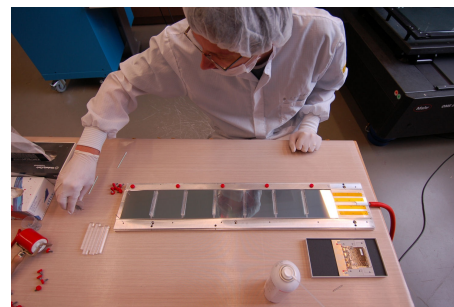


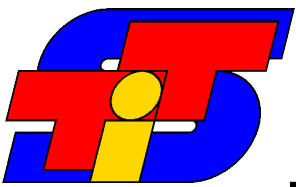


Trigger Tracker Production

"Stage I" production steps:

- place seven sensors and lower hybrid (use sensor edges for positioning)
- verify and correct alignment (CMM)
- glue support rails along the edges
- measure final sensor alignment
- glue bias voltage cable along back of module, apply GND and bias connections (using silver glue)
- bond sensor(s) to pitch adaptor
- 24h burn-in test:
 - IV curves, CCE curves, pulse-shape scans
 - analysis of strip noise to identify bad strips
 - several temperature cycles between $\sim 20^{\circ}\text{C}$ and 5°C

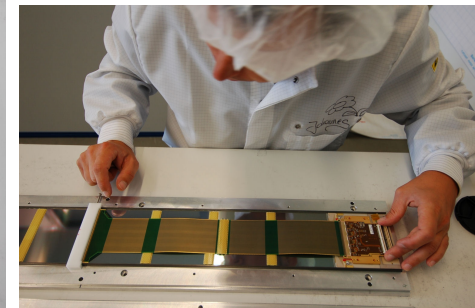
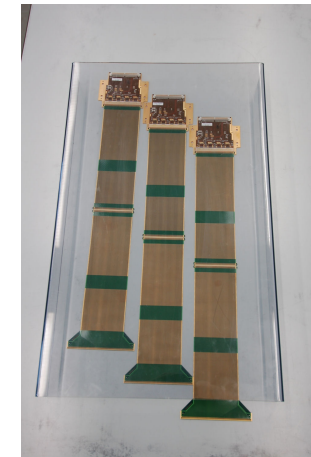
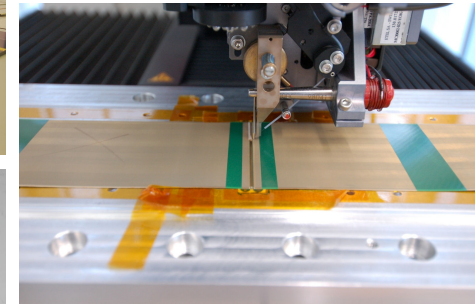




Trigger Tracker Production

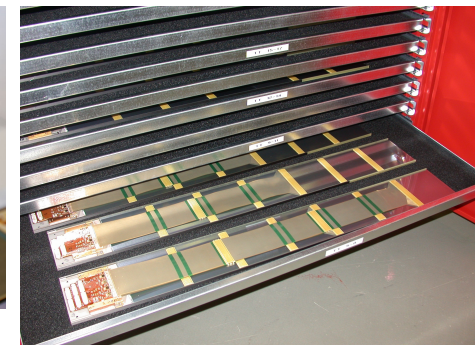
"Stage II" production steps:

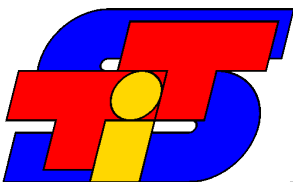
- glue Kevlar protection caps over bonds
- assemble and bond Kapton interconnect cable and upper hybrid
- mount interconnect & hybrid onto detector module, bond cable to sensor
- solder GND connections to lower hybrid
- 36h burn-in test with similar programme as after stage I



"Stage III" production steps:

- for modules with three read-out sectors, repeat stage-II steps for 2nd interconnect and 3rd hybrid
- 36h burn-in test with similar programme as after stage I and II

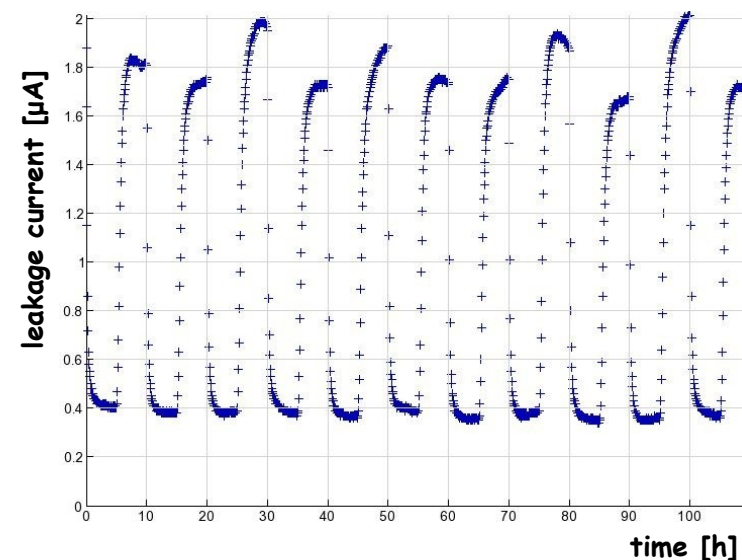
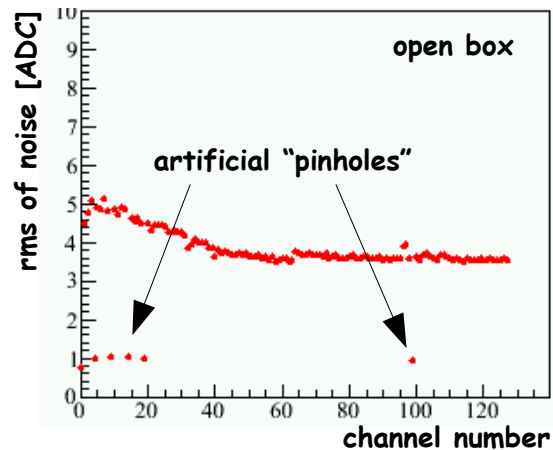
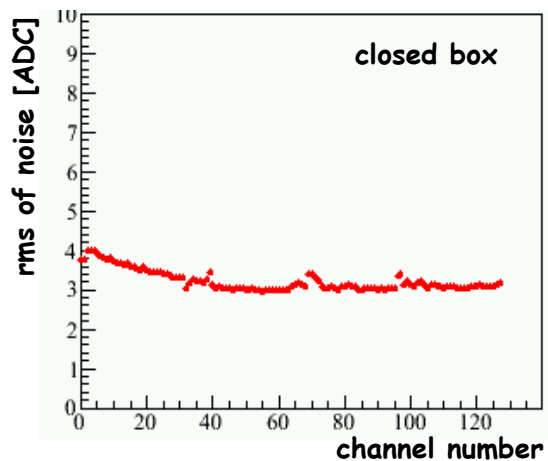
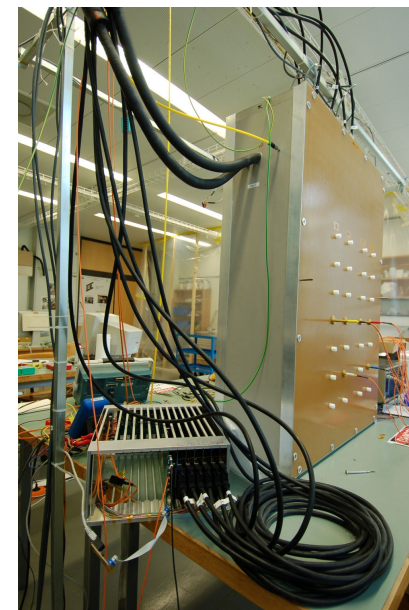
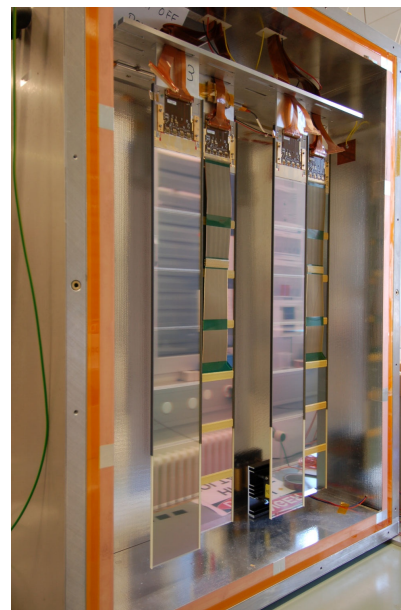


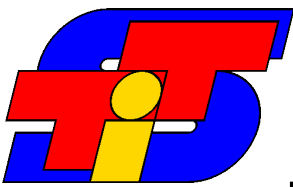


Burn-In

Example: TT burn-in test stand

- fully automatic operation (LabView)
- temperature cycling between r.t. and 5°C
- continuous monitoring of leakage currents
- pulsed IR diodes to generate charge at defined positions on the sensors
- also: exercise final readout link
- also: test final cooling concept





Comments on Production

Module production largely “manual” and run by small production teams

- IT: 6 physicists / technicians from Lausanne and Santiago de Compostela
- TT: 5 physicists / technicians from Uni Zürich

Small team means flexibility in decision making processes

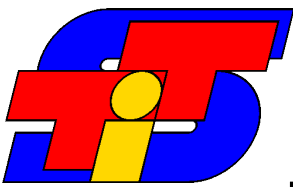
- short production meetings to discuss problems and decide the programme for the coming week
- lots of ad-hoc decisions in the production room

Small team means simple logistics

- hybrids from MPI Heidelberg, silicon sensors (from HPK) via Uni Zürich
- IT assembly in Lausanne, bonding and testing at CERN (40 km distance)
- TT production entirely at Uni Zürich

But it also means lack of redundancy in manpower and equipment

- we have been lucky no accidents happened (except for one broken hand)



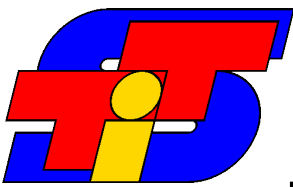
Comments on Planning

Projected production speeds could be reached and maintained

- Inner Tracker:
 - producing 12 modules / week using five production templates in parallel
 - currently about 230 modules out of 380 fully produced and tested
- Trigger Tracker:
 - produced 5 modules / week in stage-I, using two templates in parallel
 - stage-I production finished last week, stage-II/III by end October
- as expected, testing takes up more resources than the actual production

Transition from prototyping to production much slower than expected

- unforeseen problems when building the first "final" modules
- problems at vendors when going from prototype to series production
- training of unexperienced bonders can take a lot of time
- should have known all this and reserved more time in our project planning
- finally we are okay since LHC schedule slipped by a similar amount of time



Module Quality

Fraction of "problematic" modules so far quite low

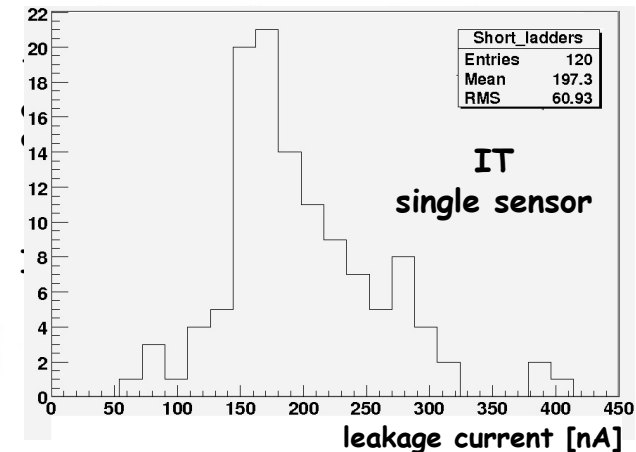
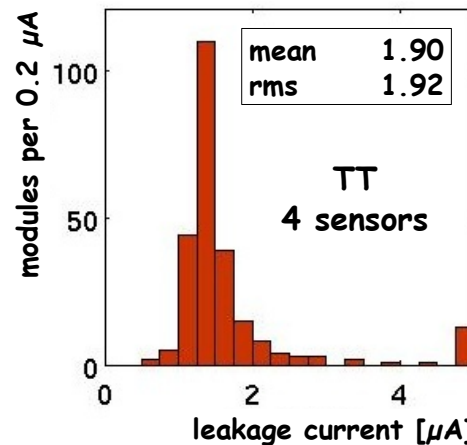
- 5 (IT) + 4 (TT) modules lost (damaged sensor, pitch adaptor or r/o hybrid)
- 1 + 0 modules with more than 2 bad strips (could be used if needed)
- 1 + 3 modules probably repairable (strange IV curve or r/o problem)
- planned for 50 + 20 spare modules (15 %)
 - hopefully no need to install these problematic modules
 - have a closer look at them once the main production is finished

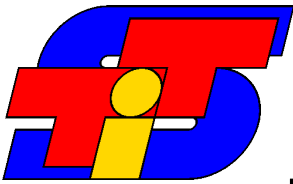
Fraction of bad strips so far quite low ("bad" = interrupt, short, pinhole)

- IT: 82 out of ~ 85 k tested
- TT: 141 out of ~ 134 k tested

Leakage currents very low

- normally < 500 nA per sensor at 500 V (HPK sensors !!!!)

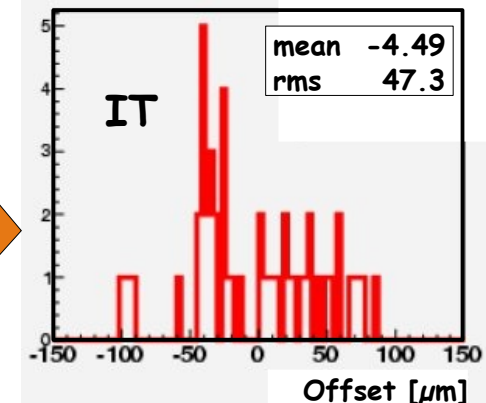
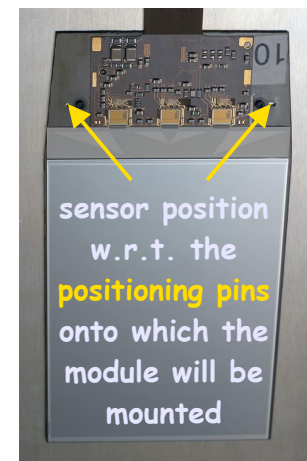
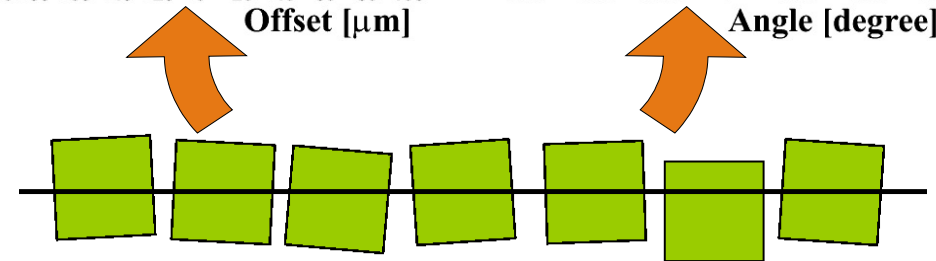
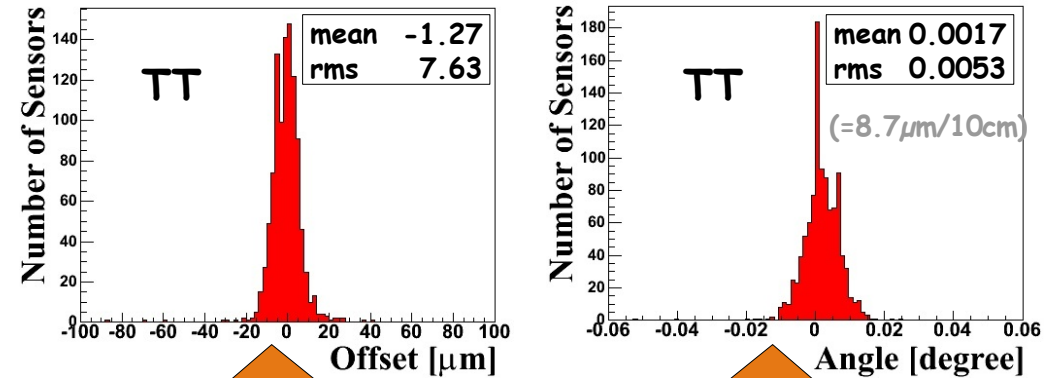


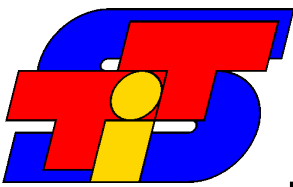


Module Quality

Positioning precision (benchmark: expected spatial resolution of $\sim 50 \mu\text{m}$)

- excellent relative positioning of the sensors on a module
- each module can be treated as one unit in software alignment, no need to align individual sensors
- positioning of sensors on supports worse than what we had hoped for (true for IT, not measured for TT)
- mainly due to worse than expected tolerances on production templates
- each module has to be aligned individually in software
- no problem: had always been foreseen



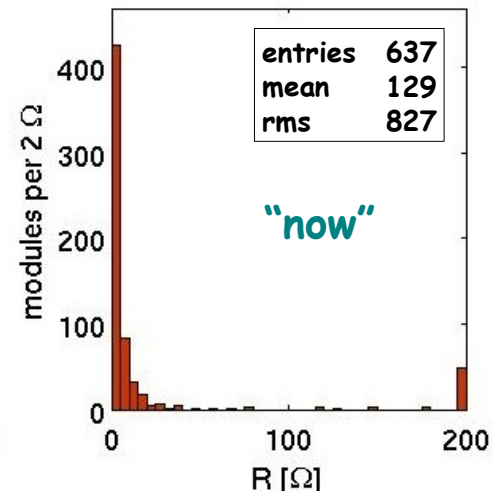
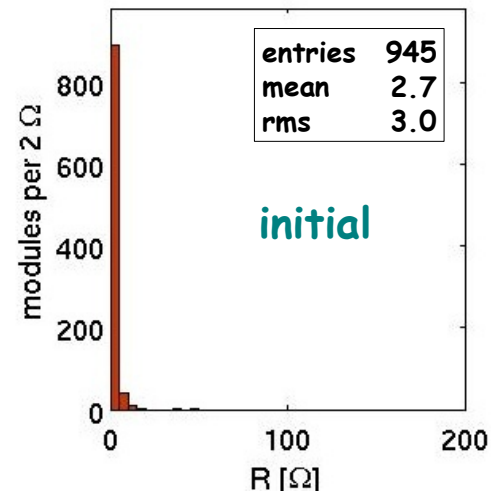


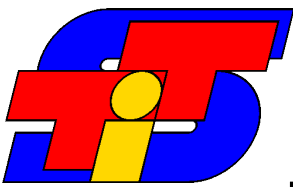
Silver Glue

Latest "discovery": silver glue on aluminium is a bad idea

(not entirely unexpected since similar effects were already observed by CMS)

- TT: use dedicated bias voltage cable along the back of the module
- used silver glue to connect bias voltage to the backplane
 - TT9-75: Elecolit 340 (one-component "silver paint")
 - TT76-155: Elecolit 325 (two-component epoxy)
- measured resistance of all connections
 - shortly after module production
 - again after a few weeks / months
- find significant increase of resistance
 - for both types of silver glue
 - typically a few hundred Ohms now
 - but the trend is worrisome
- decided to provide additional bond connections on all sensors





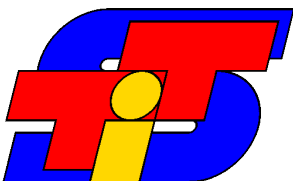
Summary

Where we could have done better:

- underestimated the transition from prototyping to production
→ should have tried to build a “final” module much earlier on
- may have spent too much effort on optimisation of sensor thickness (IT)
→ material is anyway dominated by supports, cooling, cables
→ having two types of sensors (320/410 μm) is a complication
- ended up having two types of TT modules for no good reason at all
→ unnecessarily complicates logistics, production of spares

What we might have gotten right:

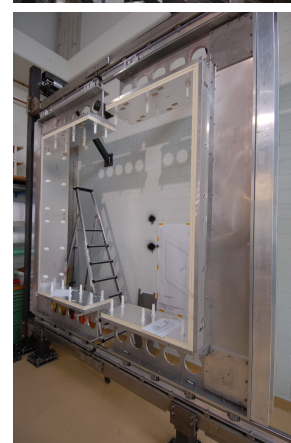
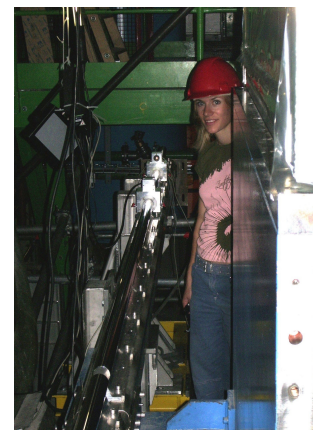
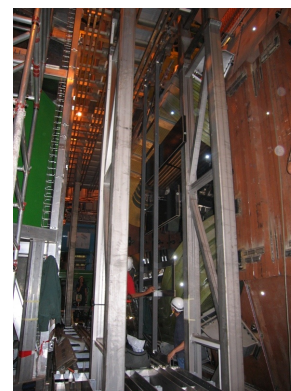
- relatively simple and robust module design (despite a few “ad-hoc” fixes)
- good sharing of responsibilities between participating groups
- entire production of all r/o hybrids in a single company (RHe, Germany)
- investment in automated burn-in test stands, using final components



Summary

Other activities:

- TT support frames installed
- IT support frames assembled and to be installed soon
- IT detector boxes being assembled
- TT detector station being assembled
- r/o electronics being produced
- work on monitoring / control software

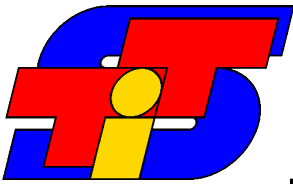


Main tasks for the coming year:

- finish module production and testing (TT: October, IT: February)
- station assembly and installation in the experiment (TT: Dec, IT: Dec-Feb)
- detector integration and "commissioning" without beam (Jan-Aug)
- hall closes end Aug, single p beam Nov/Dec, first p-p collisions end 2007

A scenic view of the Point Lobos coastline. The foreground is dominated by a large, light-colored rock formation with a sharp, pointed peak. A single, small, green tree stands on the right side of the rock. The ocean is visible in the background, with white waves crashing against the rocks. The sky is blue with scattered white clouds.

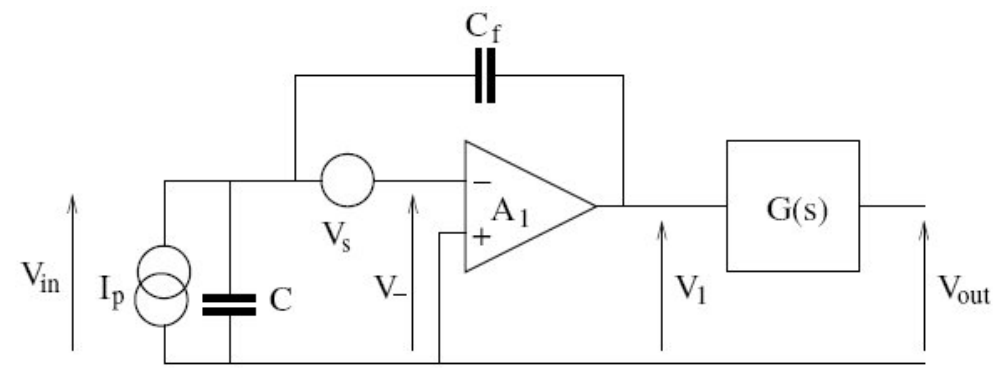
Extra slides



Noise Model

Charge-sensitive amplifier:

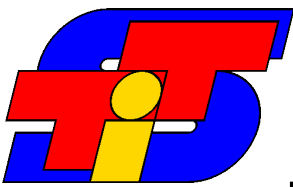
- $G(s)$: transfer function of shaper
- C : load capacitance
- V_s : serial noise of input FET
- I_p : parallel noise from leakage currents



$$ENC^2 = \int_0^{\infty} \frac{1}{2\pi} \cdot \left(\frac{8 kT}{3 g_m} (C + C_f)^2 \omega^2 + 2 e I_p \right) \cdot \frac{|L(V_0 \cdot v(t))|}{V_0} d\omega$$

- calculate serial noise using measured Beetle response function $V_0 \cdot v(t)$
 => good agreement with values measured on a test bench

V_{fs} [mV]	0	100	400	1000
calculated serial noise [e/pF]	51.2	50.9	49.0	43.0
measured serial noise [e/pF]	52.6	51.9	49.4	45.2

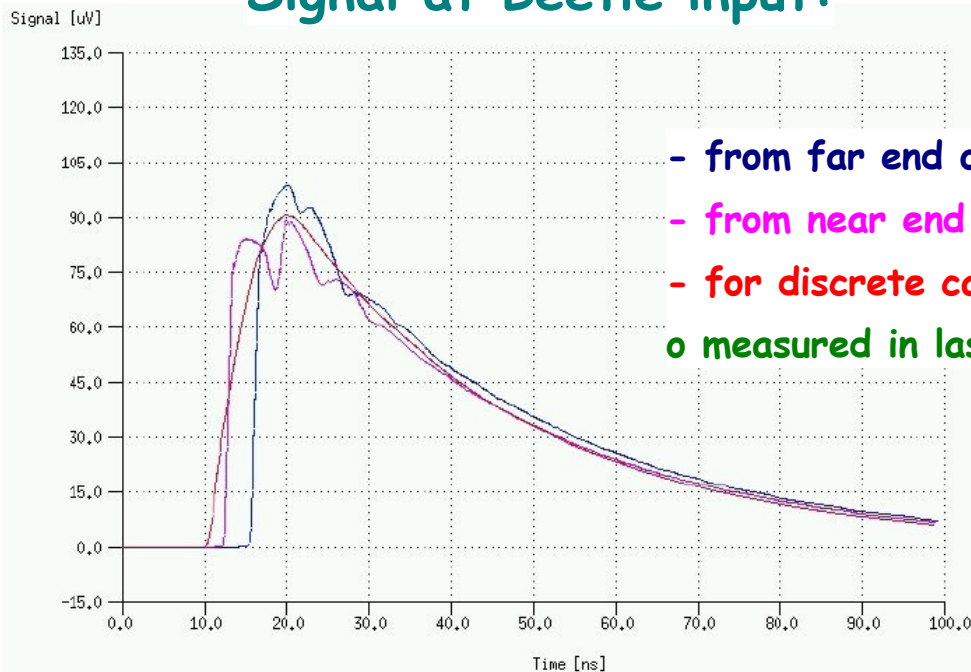


Calculated Signal Shapes

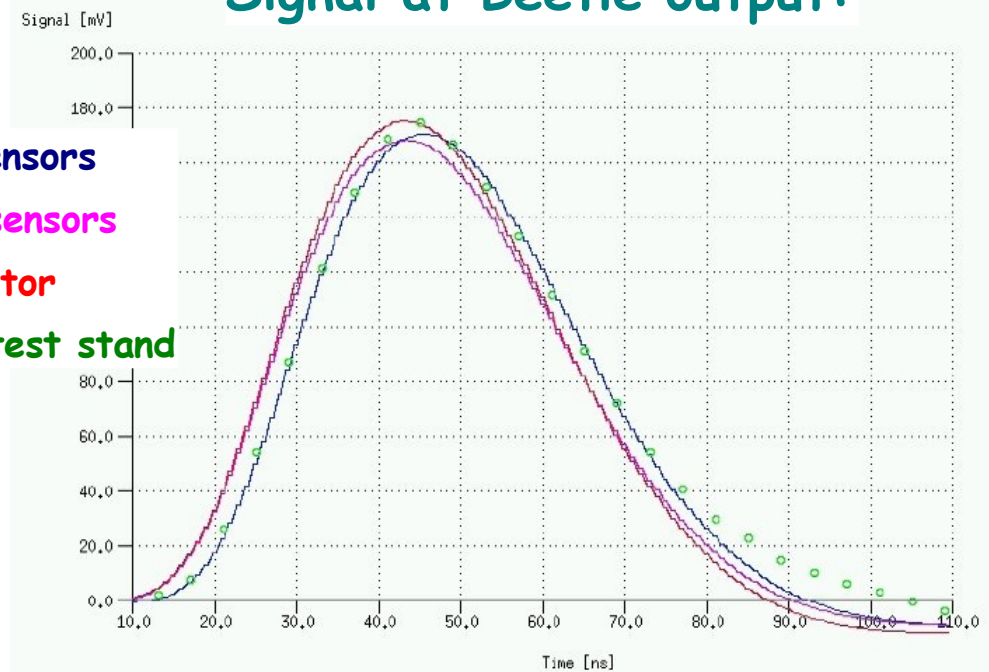
Spice simulation of long readout strips (10 RLC elements / cm):

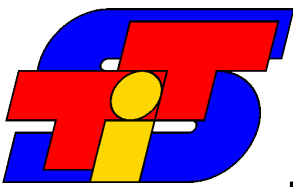
- Example: 3 sensor long CMS-OB2 ladder with Kapton interconnect cable
=> R,L,C determined separately for sensor and interconnect cable !
- Beetle output signal determined using measured Beetle response function
=> signal from far end: peaks ~ 3 ns later, pulse height is ~ 4% smaller

Signal at Beetle input:



Signal at Beetle output:





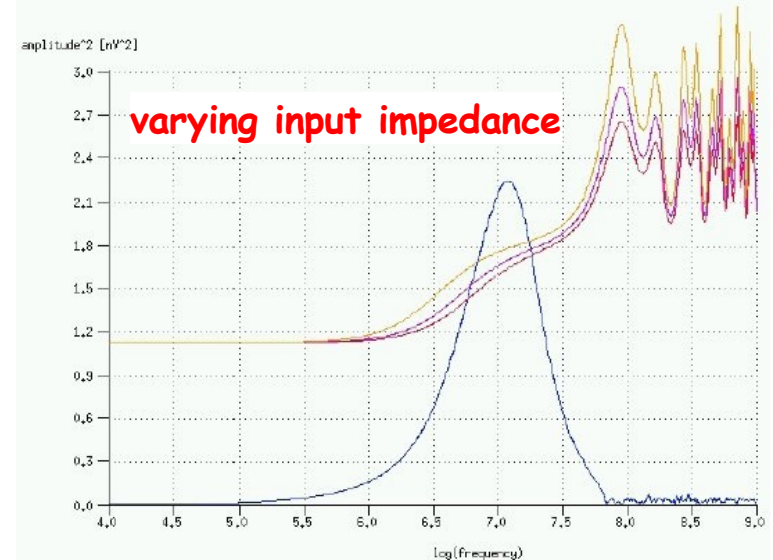
Serial Noise

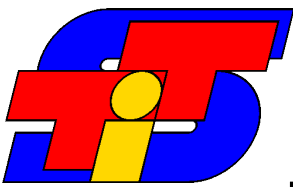
Noise spectrum from the same spice simulation:

- FET equivalent noise resistor (68Ω)
 - “white” noise spectrum
- strip lines:
 - negligible noise at low frequencies
 - resonating behaviour above 100 MHz (lowest Eigenfrequency of the system)

Beetle frequency response spectrum:

- peaks around 10 MHz
 - in rising part of noise spectrum
 - sensitive to details of simulation
 - e.g. significant systematic effect from effective Beetle input impedance





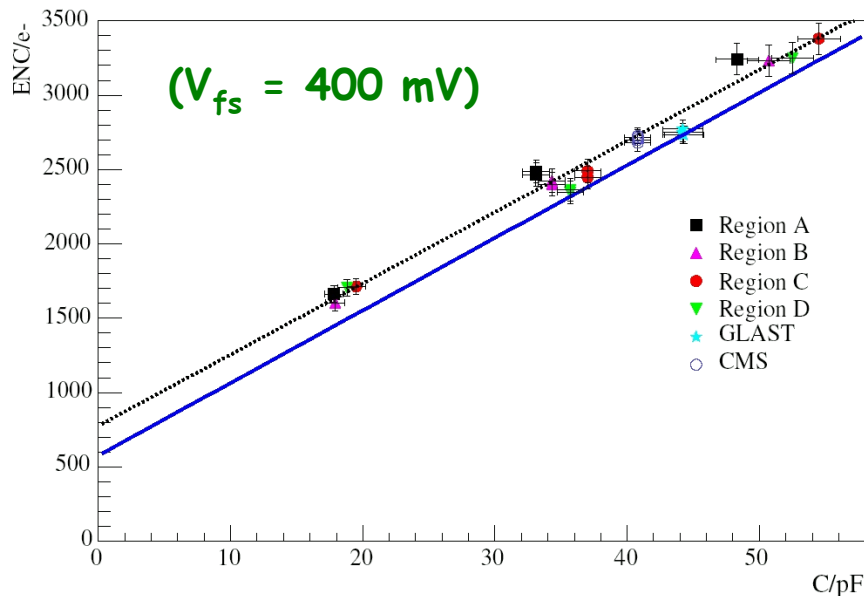
Serial Noise

Convolution of squared noise spectrum and Beetle response spectrum

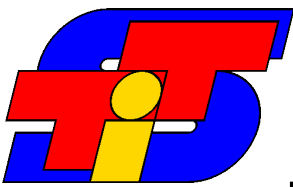
- for 3 x CMS + cable: 3800 e⁻
 - discrete capacitance of 57 pF: 3300 e⁻
- } ~ 15 % increase due to strip resistances

but: significant uncertainty on this result !!!!

Measured noise as a function of load capacitance:



- Test beam with long ladders:
 $ENC = 770 e^- + 47.9 e^- / pF$
- Test bench measurements with discrete load capacitances:
 $ENC = 580 e^- + 48.8 e^- / pF$
- good agreement of slopes, no indication for any effect from strip resistances



CCE Loss in Between Strips

Sum of the signals on four strips closest to particle impact point

- to avoid any possible bias due to clustering algorithms
- example: module of three CMS-OB2 sensors, $V_{\text{bias}} = 450 \text{ V}$ ($V_{\text{fd}} \approx 250 \text{ V}$)
- similar results for other testmodules / strip geometries
- relative CCE loss depends \sim linearly on the ratio (pitch-width) / thickness

