



6<sup>th</sup> "Hiroshima" Symposium

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# The SiD Silicon Tracker for the ILC

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for the SiD Tracking Group

# Talk Outline

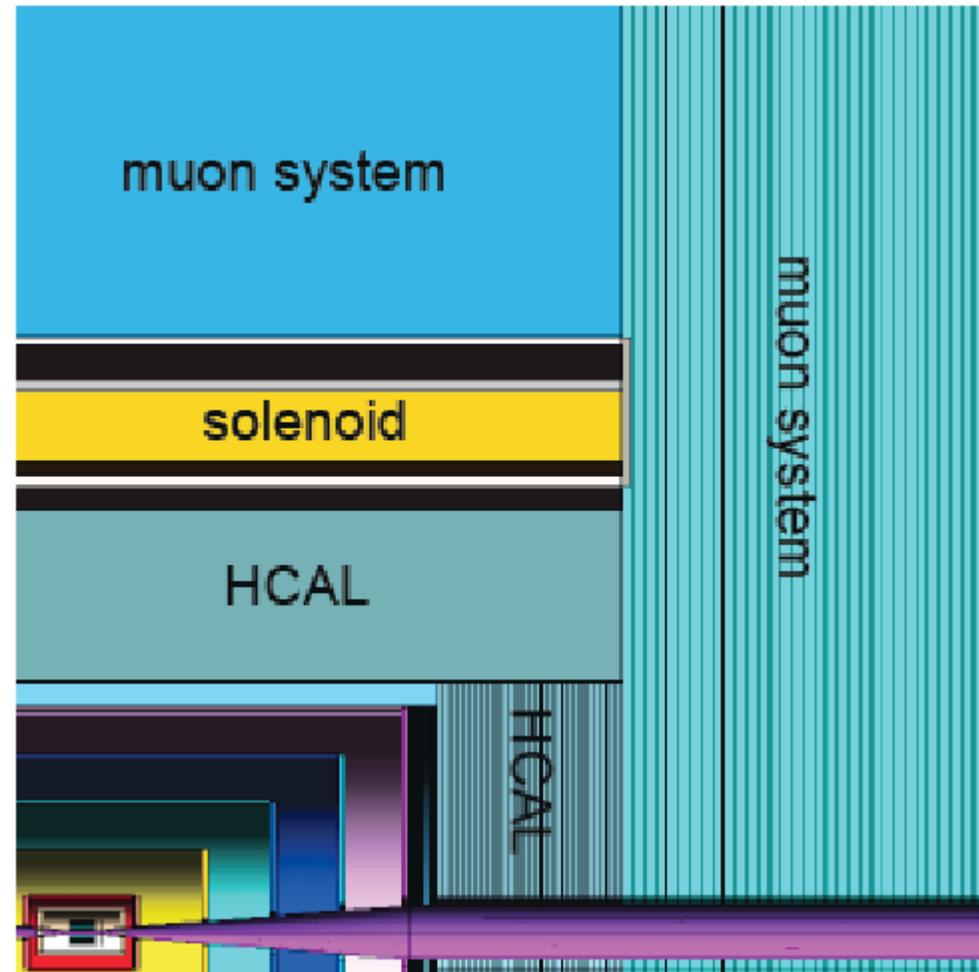
- ◆ Tracking in the SiD Concept
- ◆ Tracker Design
- ◆ Tracker Performance



# The SiD Concept

## Defining Features of SiD

- ◆ Si pixel vertex detector
  - Best possible flavor tagging and pattern recognition
- ◆ Si strip tracker
  - Highest precision tracking to measure charged particles
- ◆ Si/W EM calorimeter
  - Finest possible segmentation to identify/measure photons
- ◆ High field solenoid (5T)
  - Smallest possible vertex detector inner radius
  - Improves charged particle momentum resolution





# Tracking in the SiD Design Concept

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- ◆ Of the four ILC detector concepts, SiD is the only one to adopt an all-silicon tracker

## Why did we do this?

- ◆ Silicon provides the best resolution:
  - in position –  $\sim 7 \mu\text{m}$  hit resolution
  - in time – single bunch resolution
  - in 2-hit resolving power – typically a few strips ( $\sim 150 \mu\text{m}??$ )
  - in track reconstruction for a given tracker volume
- ◆ Silicon trackers are inherently stable devices
  - Geometry of strips on sensor is precisely known
  - Good mechanical stability for supporting structures possible
- ◆ Compact tracking volume reduces detector costs
  - It is clear that detector cost will be constrained
  - M. Briedenbach SiD cost model: total detector cost scales as  $R_{\text{tkr}}^{1.2}$



# Context and Focus

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- ◆ Several talks have already presented considerable material on tracking at the ILC
  - Marty Briedenbach gave SiD overview
  - Jim Brau previously covered the vertex detector
  - Bruce Schumm covered physics motivation and rationale for Si tracking
  - Several talks on pixel technologies that may be important for SiD
- ◆ Focus of this talk is to describe the SiD tracker baseline design
  - The baseline design has been developed within the SiD tracking group and represents a starting point to begin the process of optimizing the design
  - In many areas, there are alternative ideas / technologies that people are thinking about
  - We need R&D on technologies and detailed simulation of the design that can quantify performance of the baseline and alternatives to optimize the design
  - Lots of room for good ideas and contributions! Send me email if you would like to get involved.



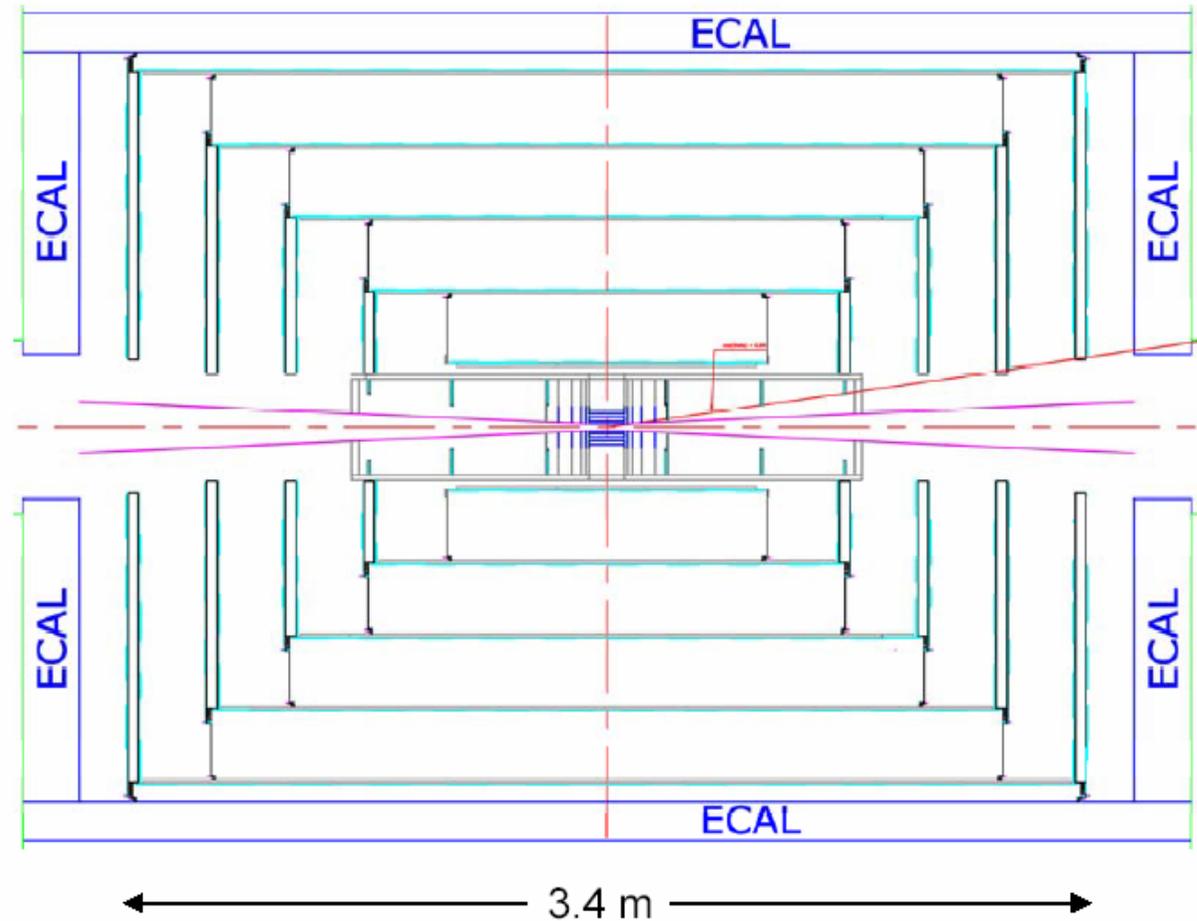
# Baseline Tracker Layout

## Outer Tracker

- ◆ Silicon strips
- ◆ 5 barrel layers
- ◆ 4 disks per end
- ◆ Supported by ECAL

## Vertex Detector

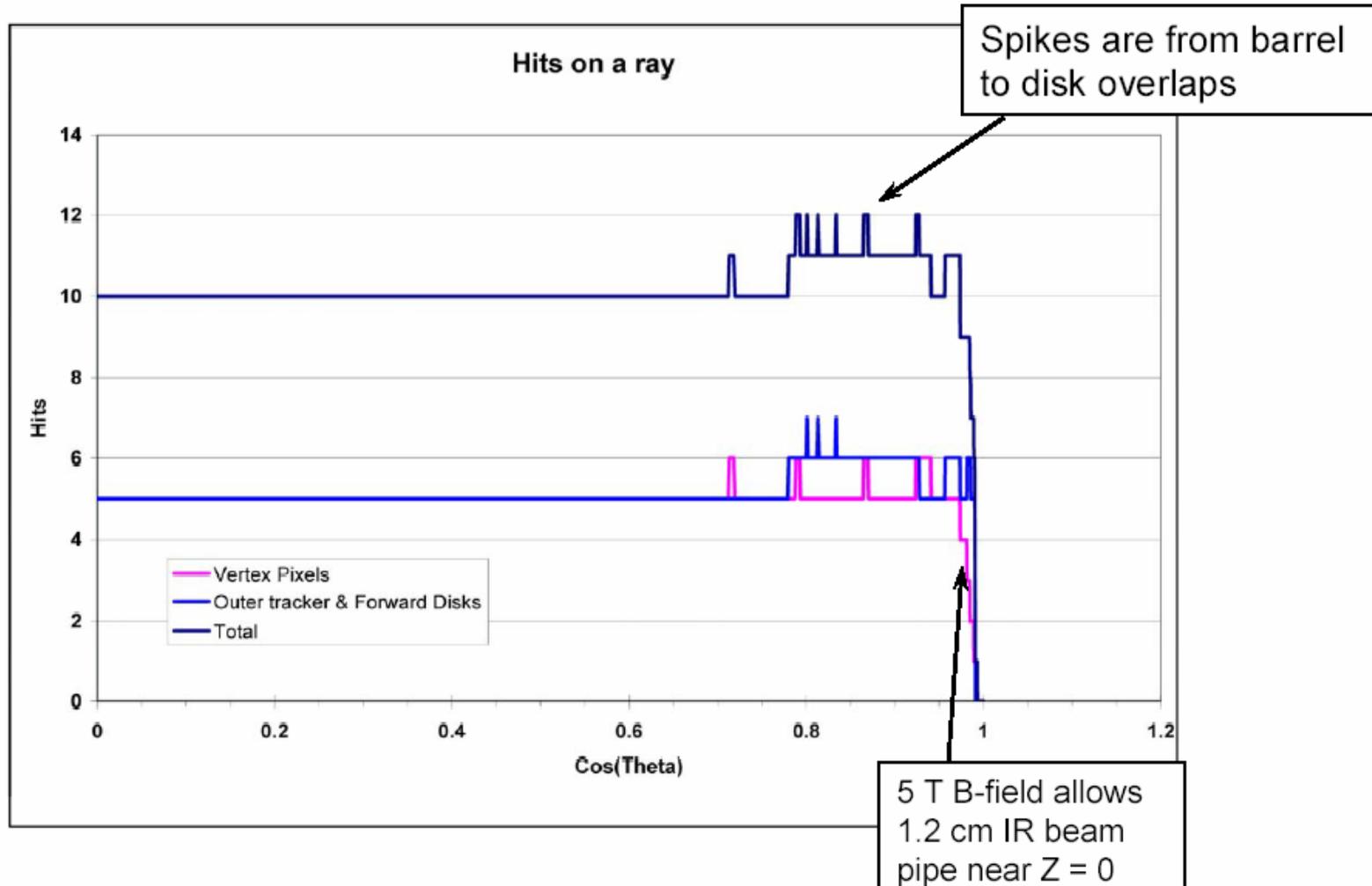
- ◆ Silicon Pixels
- ◆ 5 barrel layers
- ◆ 7 disks per end
- ◆ Supported by beam pipe





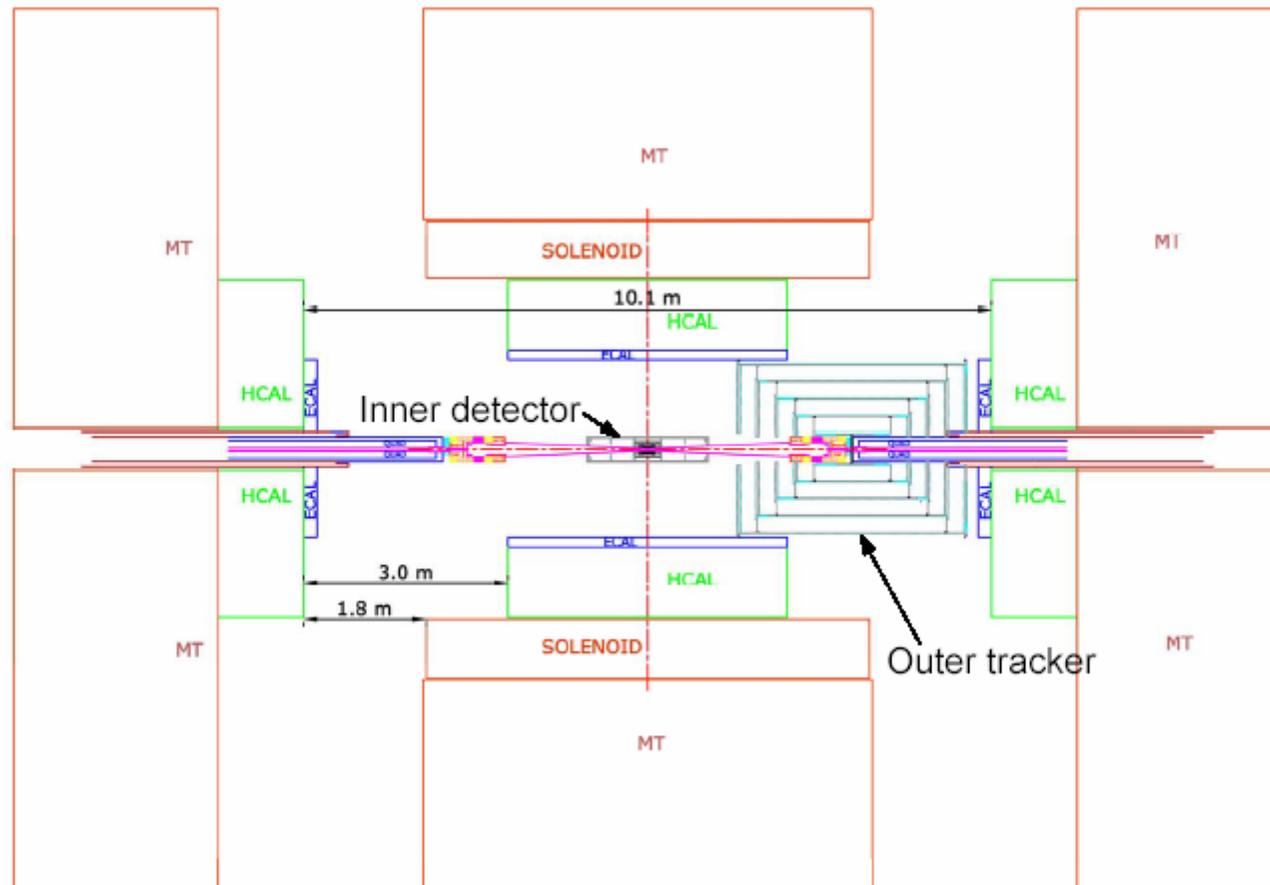
# Solid Angle Coverage

- ◆ Full coverage for  $|\cos\theta| < 0.99$  (10 hits typical)



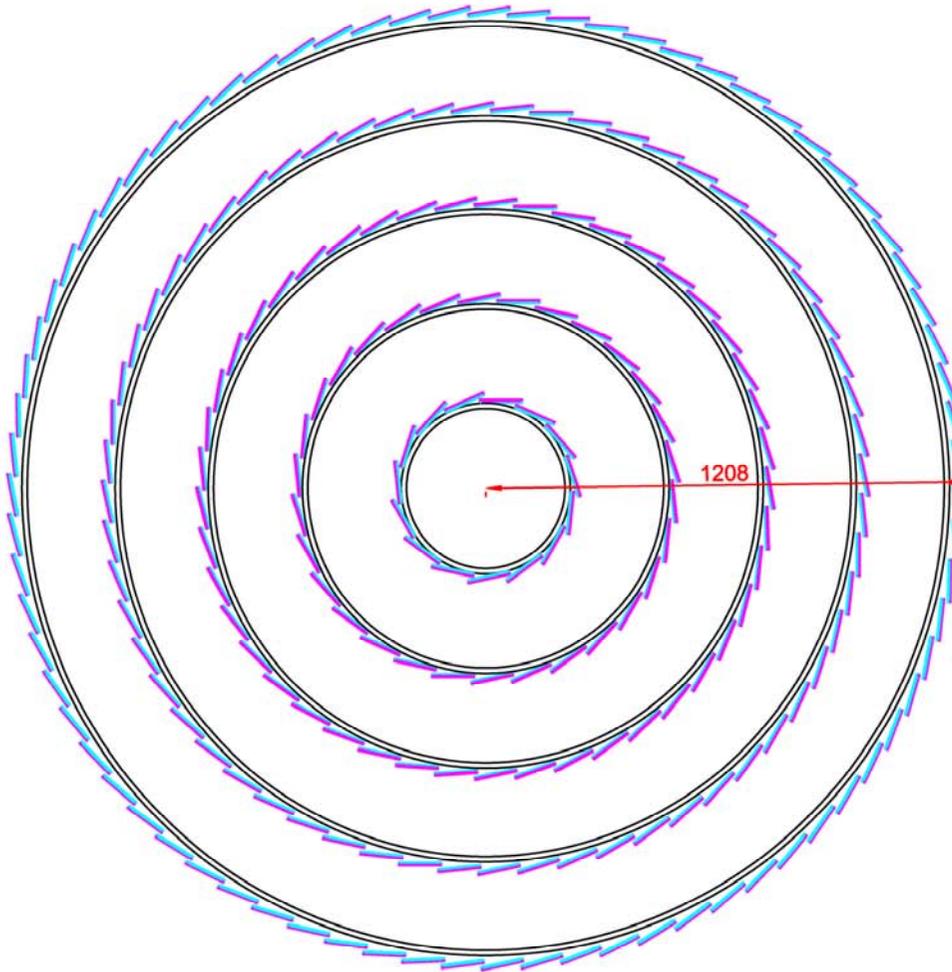
# Access to Vertex Detector

- ◆ Providing access to vertex detector constrains outer tracker to  $r > 20$  cm





# Layout of Outer Tracker Barrels



## Sensors:

Cut dim's: 104.44 W x 84 L

Active dim's: 102.4 W x 81.96 L

## Boxes:

Outer dim's: 107.44 W x 87 L x 4 H

## Support cylinders:

OR: 213.5, 462.5, 700, 935, 1170

Number of phi: 15, 30, 45, 60, 75

Central tilt angle: 10 degrees

## Sensor phi overlap (mm):

Barrel 1: 5.3

Barrel 2: 0.57

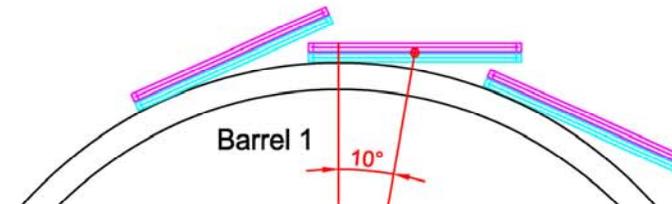
Barrel 3: 0.40

Barrel 4: 0.55

Barrel 5: 0.63

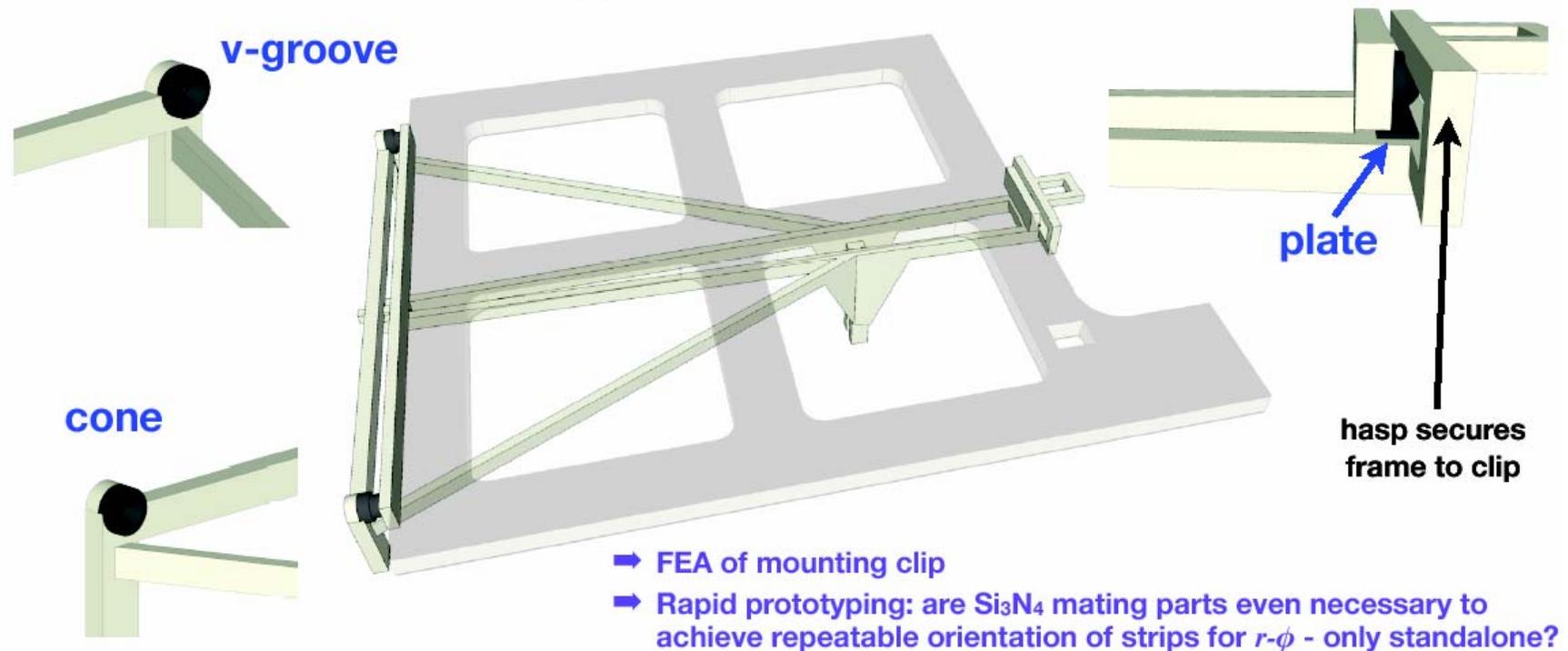
Cyan and magenta sensors and boxes are assumed to be at different Z's and to overlap in Z.

Within a given barrel, cyan sensors overlap in phi as do magenta sensors.

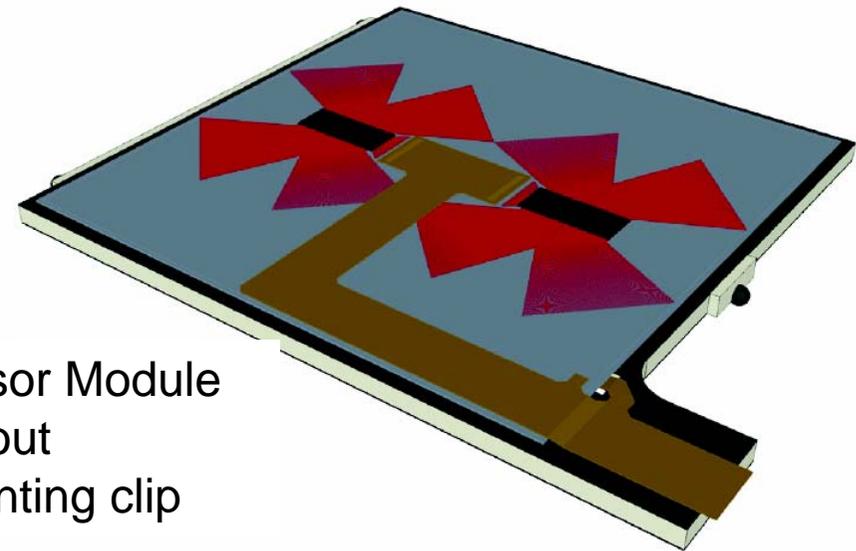


# Sensor Module Supports

- ◆ Sensor modules are mounted on support cylinders
  - Support cylinders provide overall mechanical stability
  - Constructed using carbon fiber + Rohacell foam + carbon Fiber sandwich
- ◆ Modules are attached to support cylinder using a mounting clip with 3-point support

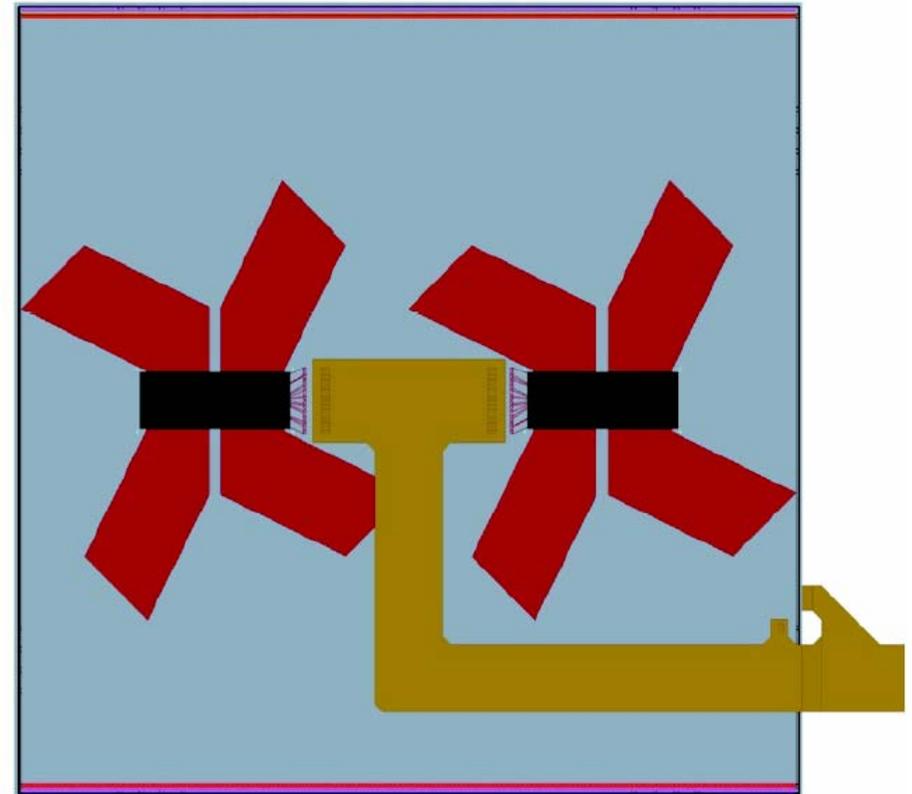


- ◆ Modules overlap in both  $\phi$  and  $z$  coordinates to minimize gaps, assist in alignment
- ◆ Modules can have either one or two sensors mounted on module frame
- ◆ Baseline design has one sensor/module
  - Vertex detector serves as primary source of 3D pattern recognition
  - Outer tracker provides precise momentum measurement and resolves ambiguities, fakes



Sensor Module  
without  
mounting clip

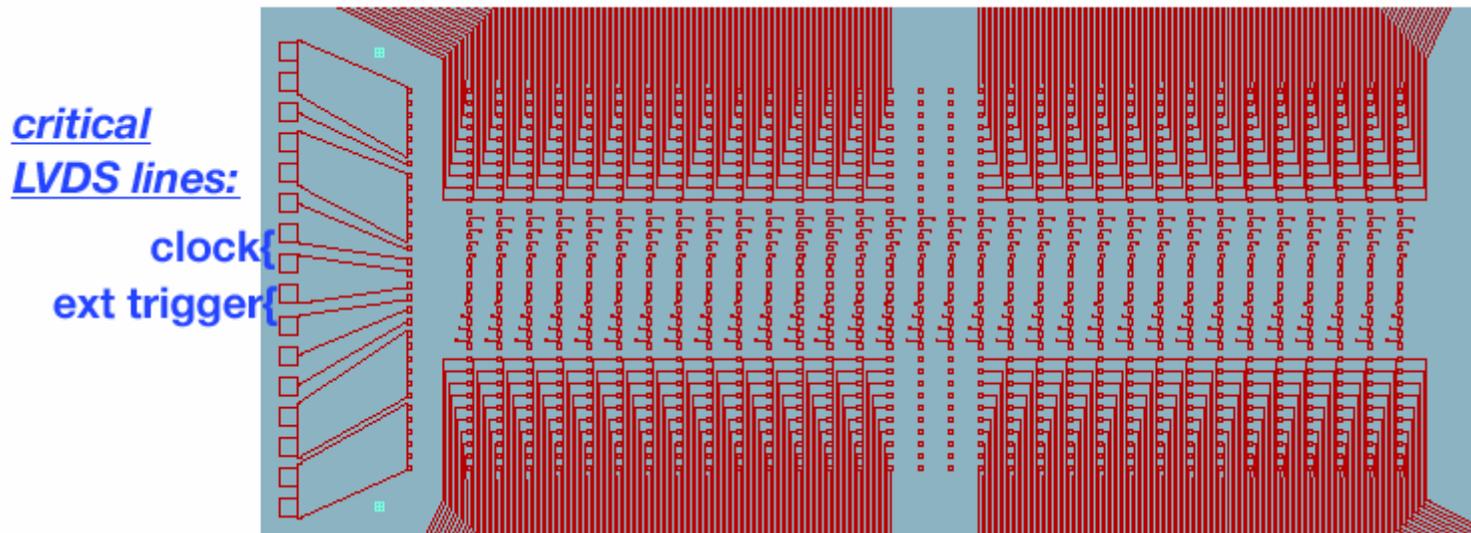
- ◆ Single-sided p on n sensors
- ◆ AC coupled, polysilicon bias R's
- ◆ 93.5 mm square
- ◆ 25  $\mu\text{m}$  strip pitch
- ◆ 50  $\mu\text{m}$  readout pitch
- ◆ 1840 readout strips
- ◆ Two KPiX readout chips bump bonded to sensor
- ◆ Readout cable signals wire-bonded to sensor
- ◆ Double metal layer used to route strip and readout cable signals



Submission to Hamamatsu  
planned for this fall

# Double Metal Routing

- ◆ Plan to first try bonding KPiX, readout chip directly to sensor
- ◆ One concern is clock coupling into strips under clock lines
  - Clock lines are synchronous and balanced, so it should be OK
  - Backup plan is to introduce a small hybrid between sensor and KPiX
- ◆ Groups of neighboring strips routed to rows of neighboring pins, nearest neighbor readout logic being added to KPiX



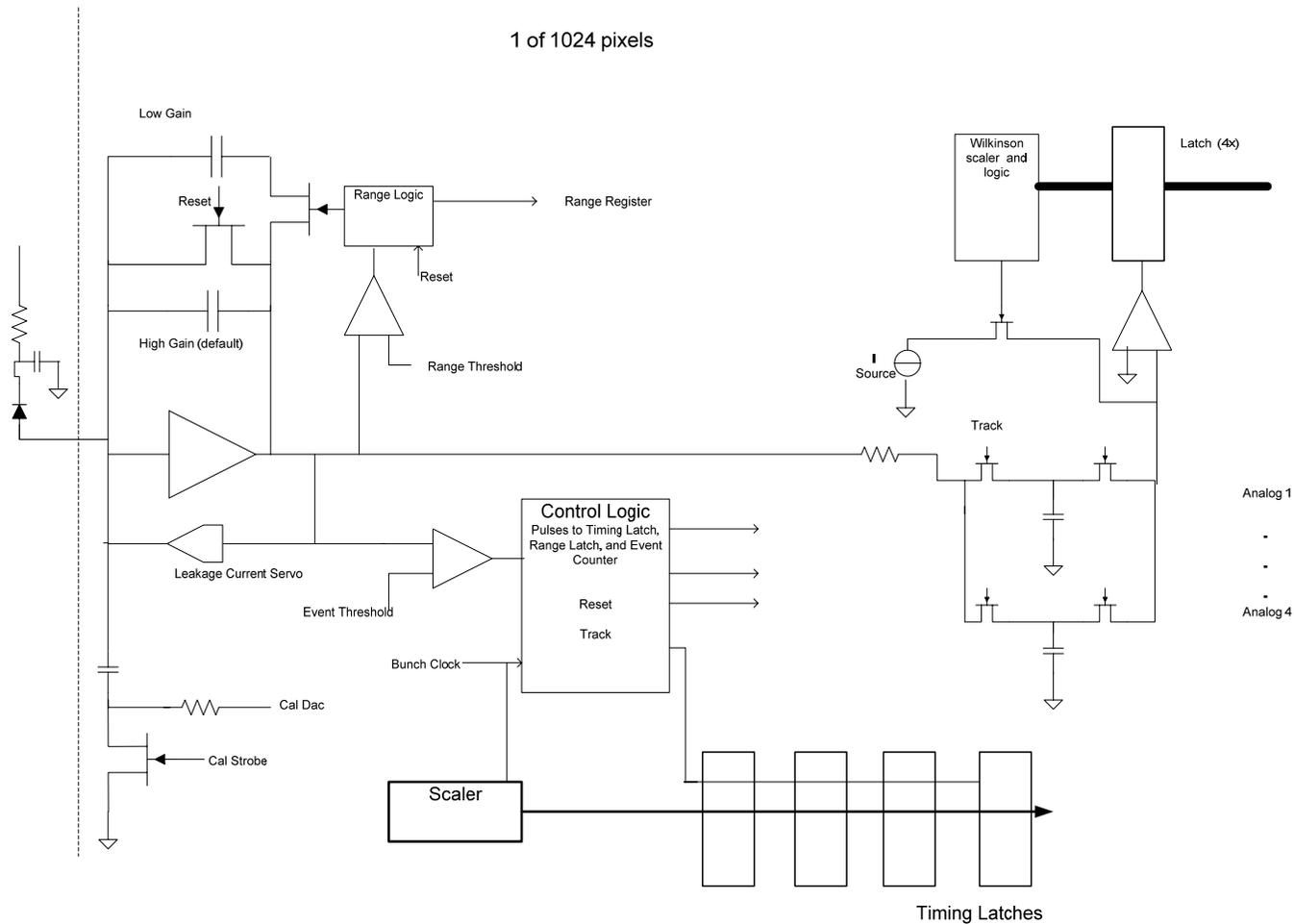


# KPiX Readout Chip

- ◆ Provides readout of up to 4 hits in bunch train

## Si-W Pixel Analog Section

1 of 1024 pixels





# Forward Disks

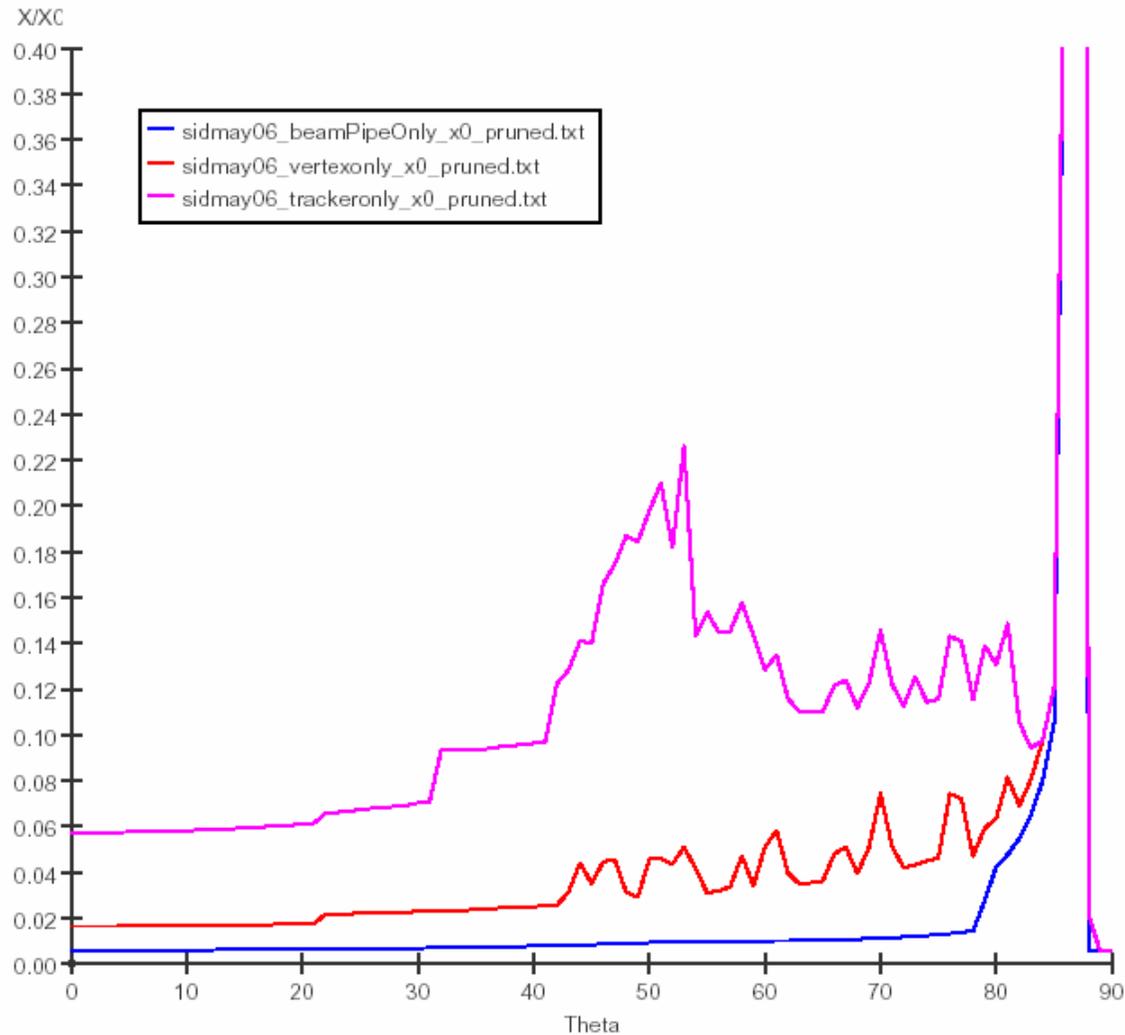
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- ◆ Forward disk design is much less developed than barrel design
- ◆ Expect many of the barrel features to carry over
  - Modules mounted on carbon fiber + Rohacell foam supports
  - KPiX readout mounted on sensors, all sensors read out individually
- ◆ One difference: baseline design has two sensors per disk to provide 3D space point measurements
- ◆ Baseline geometry of sensors has not been decided
  - Square sensors with 90° stereo
  - Hexagonal sensors with 60° stereo (e.g., disk 1 with x-u, 2 with x-v, etc.)
  - Wedges with strips parallel with sensor edges
- ◆ Need to study tracking performance in simulations to make a sensible choice



# Material Estimate

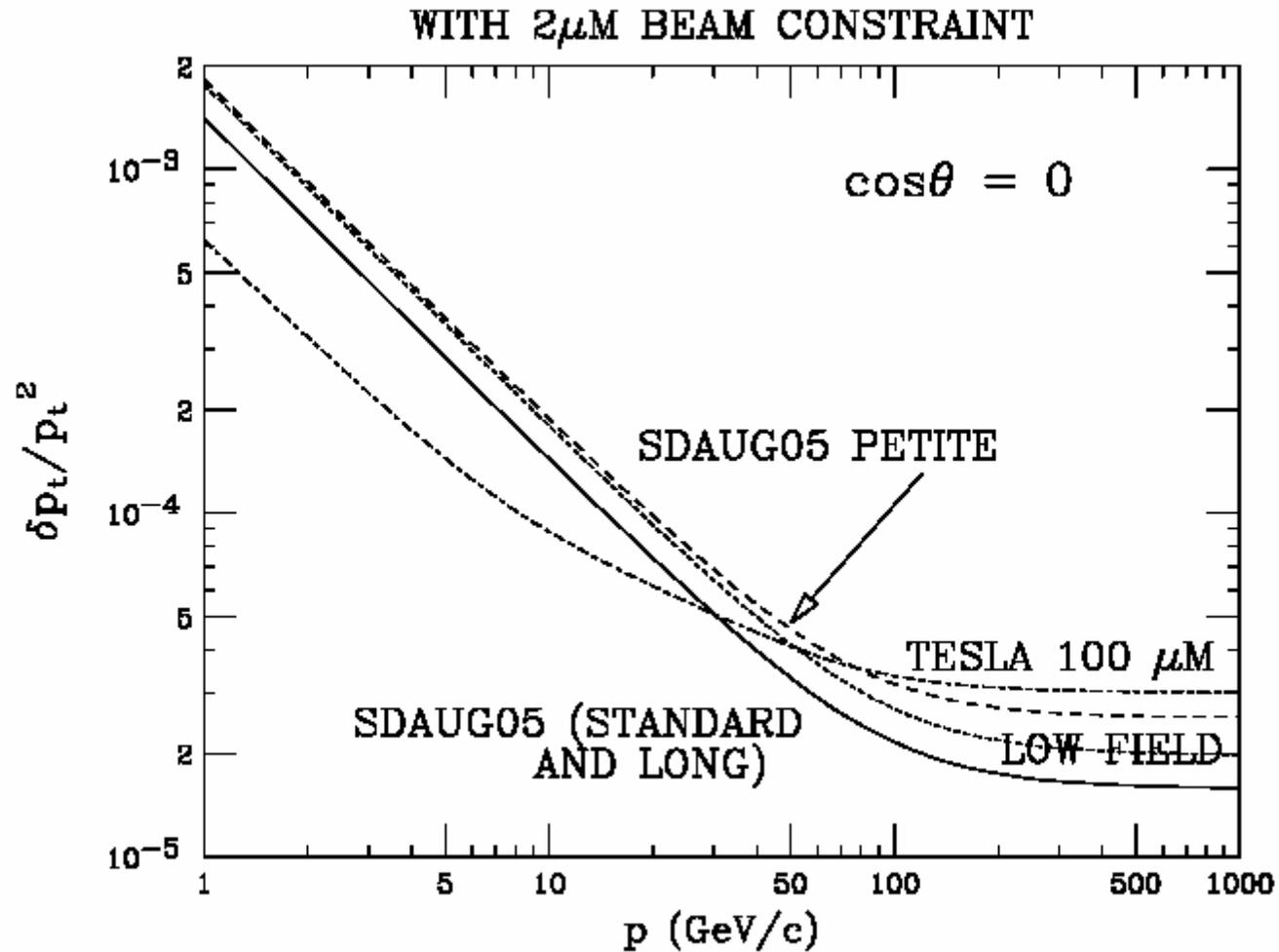
- ◆ Considerable emphasis on minimizing material in tracker





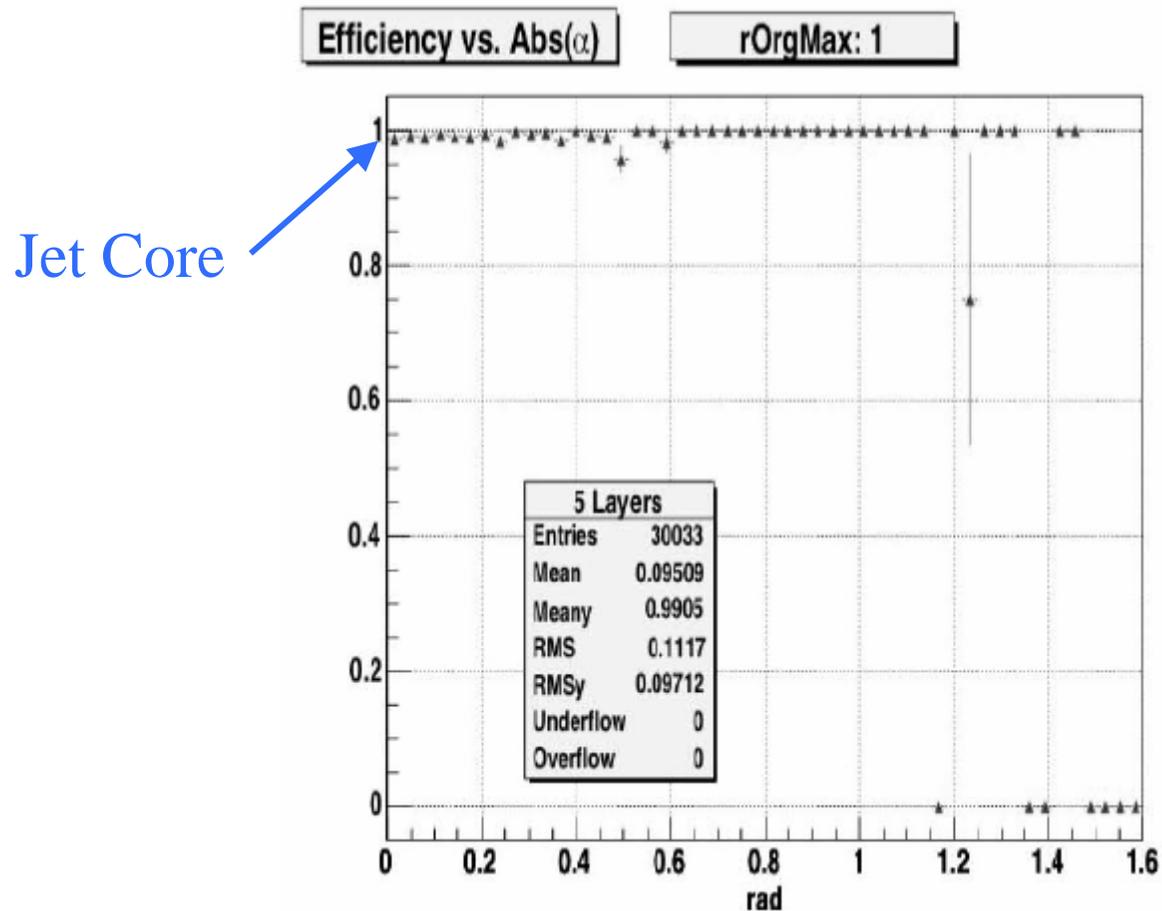
# Tracking Resolution

- ◆ Excellent momentum resolution ( $\sim 0.2\%$  for  $1 < p_T < 100$  GeV)



# Tracking Efficiency

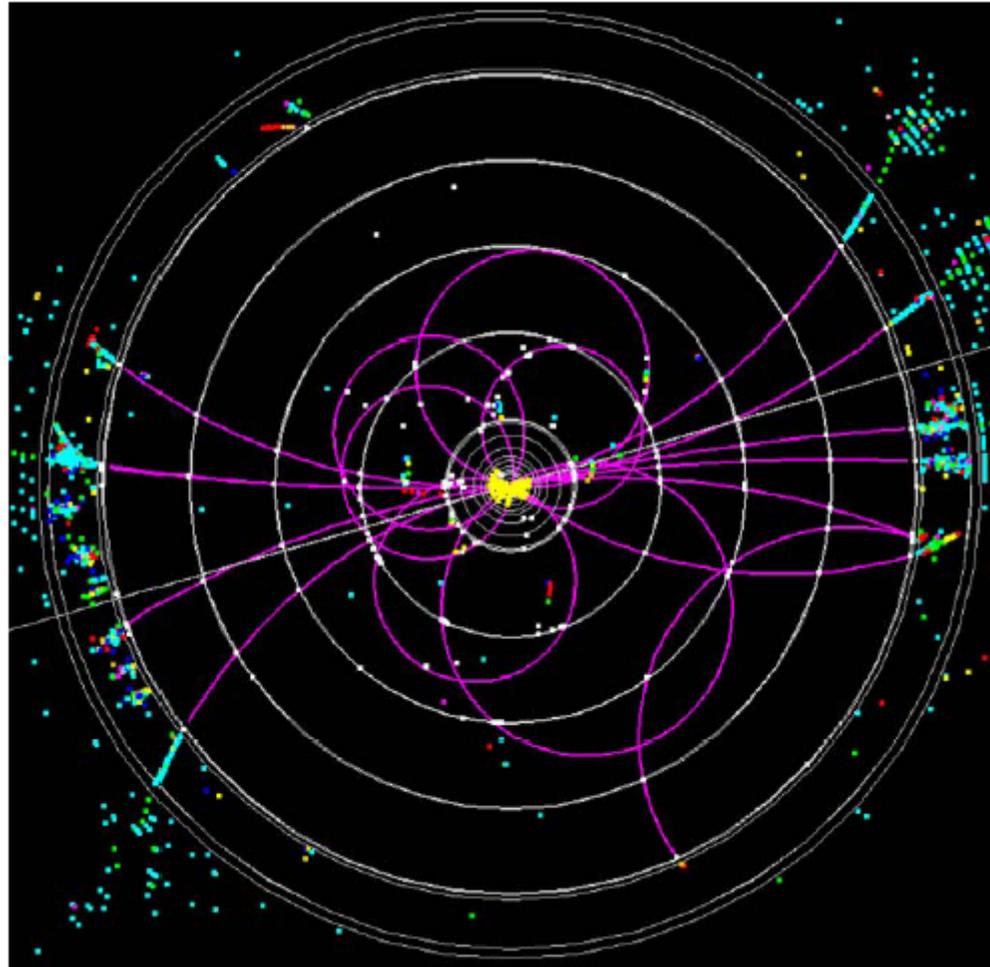
- ◆ Excellent tracking efficiency even in the core of jets for tracks originating within 1 cm of the IP





# Calorimeter Seeded Tracking

- ◆ Use fine-grained SiW calorimeter to seed tracks originating away from the IP





# Conclusions

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- ◆ Silicon tracker is a key and distinguishing feature of SiD
- ◆ Baseline design is well advanced in barrel tracker
- ◆ Expect to have module prototypes next year
- ◆ A similar level of detail is needed for the forward disks
- ◆ Simulation results are promising
  - Excellent resolution and efficiency for tracks originating near IP
  - Calorimeter can help with tracking for tracks originating away from IP – is this enough or are additional stereo layers needed?
  - Major effort underway to develop simulation tools needed to optimize the design