## Quench 101

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Workshop on Accelerator Magnets, Superconductors, Design and Optimization

## Outline

- What is a quench ? Process and issues
- The transition from SC to NC state
- The event tree
- Physics of a quench
- Hot-spot temperature limits
  - External-dump and self-dump limits
  - Quench propagation and time scales
- Quench voltages
- Pressure and expulsion
- Conclusions and open questions

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## What is a quench ?



#### quench (kwěnch)

*tr.v.* quenched, quench·ing, quench·es

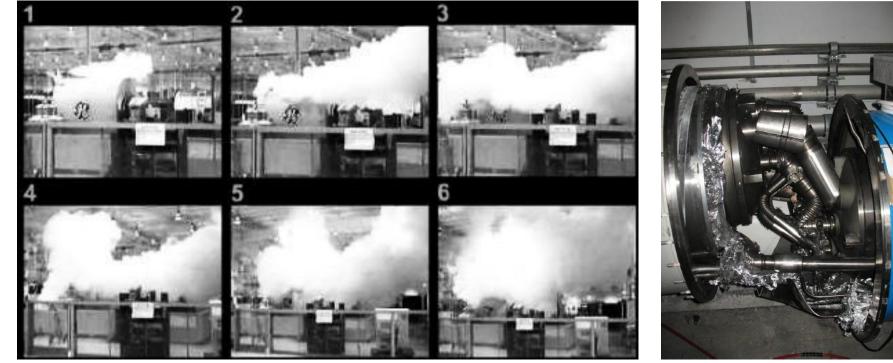
- To put out (a fire, for example); extinguish.
- To suppress; squelch: The disapproval of my colleagues quenched my enthusiasm for the plan.
- 3. To put an end to; **destroy**.
- 4. To slake; satisfy: Mineral water quenched our thirst.
- 5. To cool (hot metal) by thrusting into water or other liquid.

Coke being pushed into a *quenching car* 

A potentially destructive phenomenon involving hot metals and cold liquids that requires shutting down and causes much consternation in the office

## Really, what is a quench ?

 Quench is the result of a resistive transition in a superconducting magnet, leading to appearance of voltage, temperature increase, thermal and electromagnetic forces, and cryogen expulsion.



This is a quench of a GE MRI magnet during tests at the plant

This is the result of a chain of events triggered by a quench in an LHC bus-bar

## Why is it a problem ?

• the magnetic energy stored in the field:

$$E_{m} = \oint_{V} \frac{B^{2}}{2m_{0}} dv = \frac{1}{2}LI^{2}$$

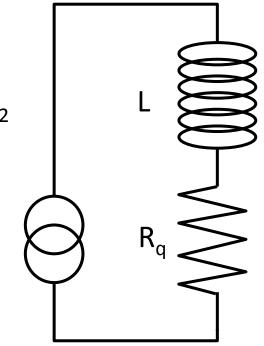
is converted to heat through Joule heating  $R_{\alpha} I^2$ 

- If this process happened uniformly in the winding pack:
  - Cu melting temperature 1356 K
  - corresponding  $E_m$ =5.2 109 J/m<sup>3</sup>

limit would be Bmax  $\leq$  115 T: NO PROBLEM !

#### BUT

 the process does not happen uniformly, and as little as 1 % of the total magnet mass can absorb total energy – large damage potential !





## Issues to be considered

- Temperature increase and temperature gradients (thermal stresses)
- Voltages within the magnet, and from the magnet to ground (whole circuit)
- Forces caused by thermal and electromagnetic loads during the magnet discharge transient
- Cryogen pressure increase and expulsion

A quench invariably requires **detection** and may need **actions** to safely turn-off the power supply (possibly more)

## Outline

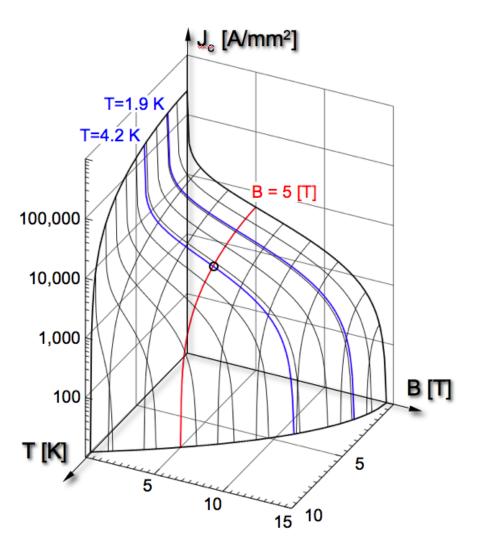
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## Superconductor limits

- A superconductor is such only within a limited space of field *B*, temperature *T*, and current density *J*
- This defines a critical surface  $J_C(B, T, \varepsilon, \Phi)$  beyond which the superconducting material becomes normal conducting
- The maximum current that a superconductor can carry is the critical current:

$$I_C = J_C A_{SC}$$



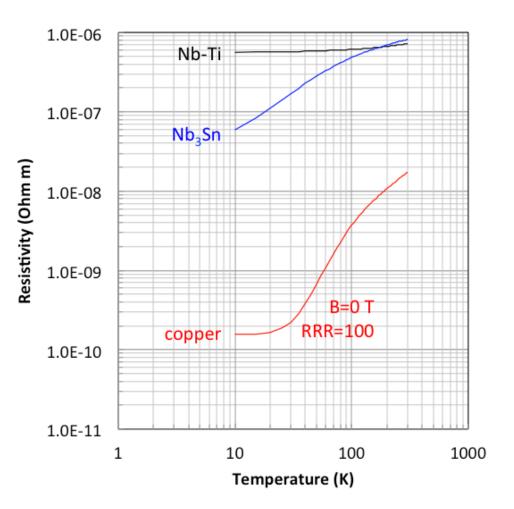


### Normal state resistivity

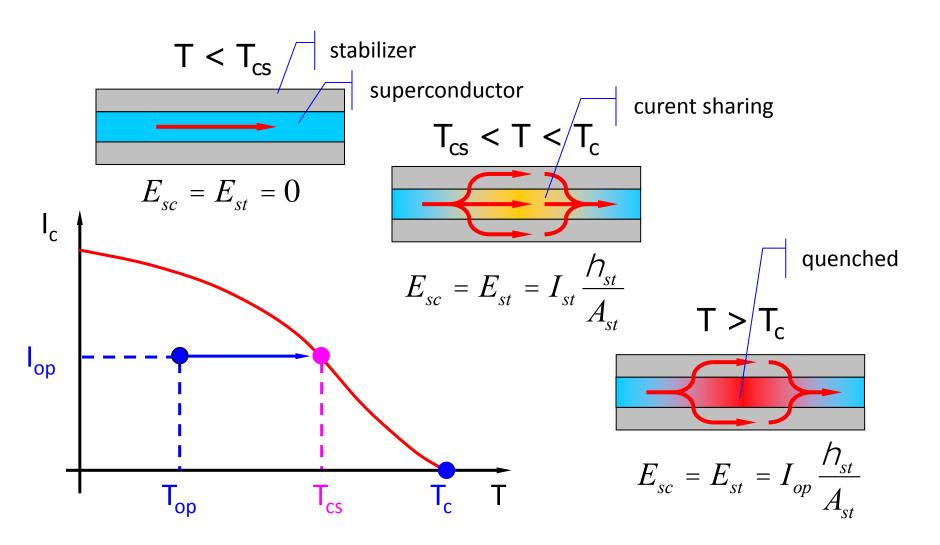
 The critical field of a superconductor is proportional to its normal state resistivity (GLAG):

 $B_C \propto \gamma T_C \rho_n$ 

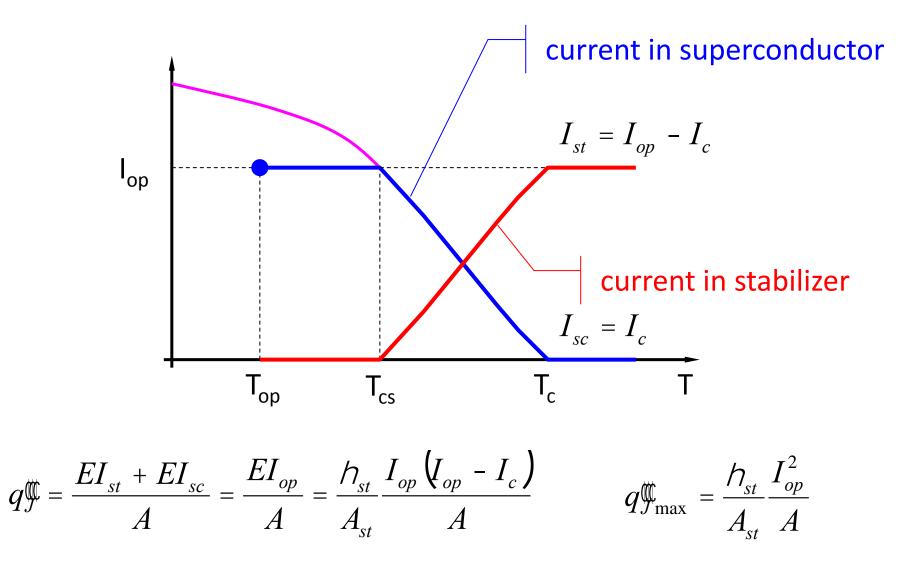
- good superconductors (high  $B_C$ ) are bad normal conductors (high  $\rho_n$ )
- Typically, the normal state resistivity of LTS materials is two to four orders of magnitude higher than the typical resistivity of good stabilizer materials



### The *current sharing* process

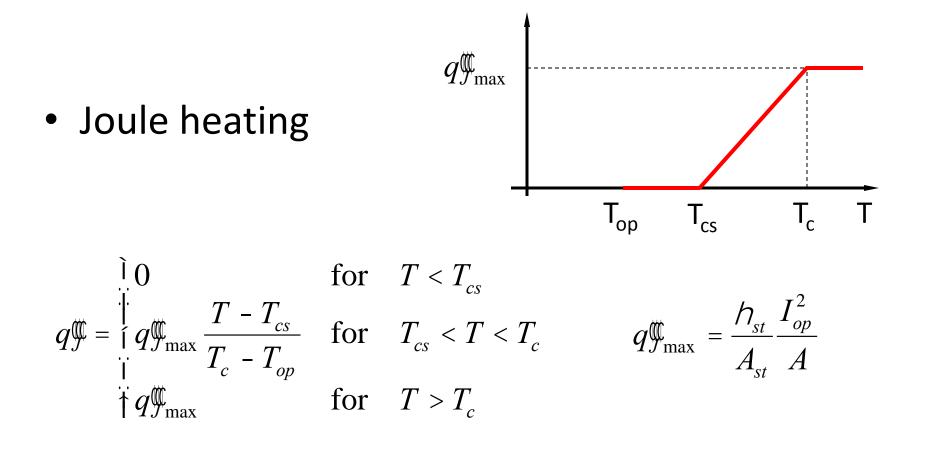


#### Current sharing and Joule heating

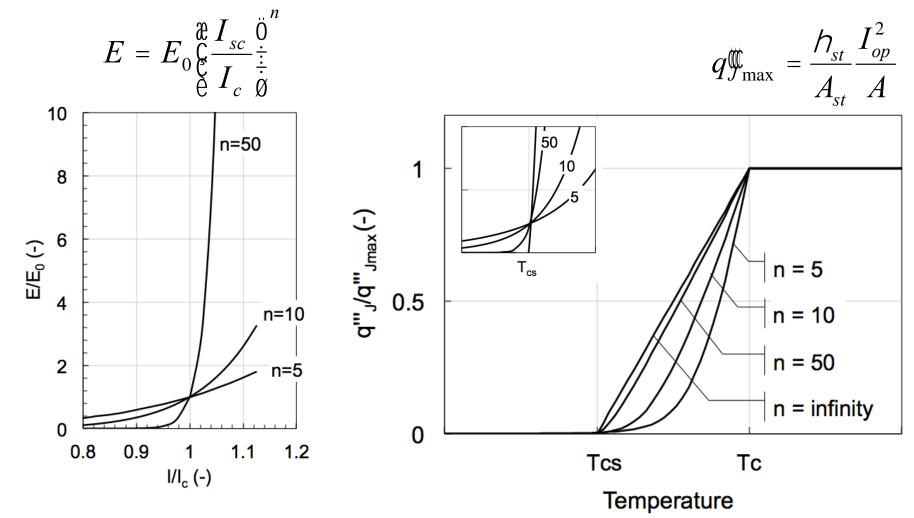


### Joule heating approximation

• linear approximation for Jc(T):  $I_c \gg I_{op} \frac{T_c - T}{T_c - T}$ 



#### Joule heating for finite *n*-index



A finite *n*-index *mollifies* the transition

**Q:** quantitative effect of finite, low n-index ?

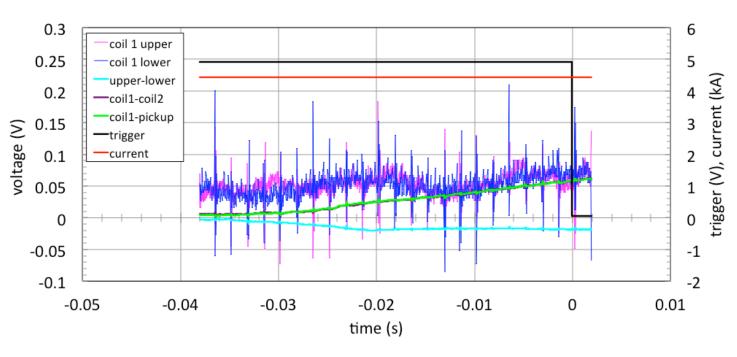
### Normal zone voltage

• The normal zone generates a voltage

$$V_{NZ} = RI = \frac{\eta_{st}}{f_{st}} J_{op} L_{NZ}$$

 This voltage is visible at the magnet terminals, but is generally *muddled* by noise

Compensation techniques reduce noise. Example of FCM magnet, coil differences, as well as a cowound wire are used

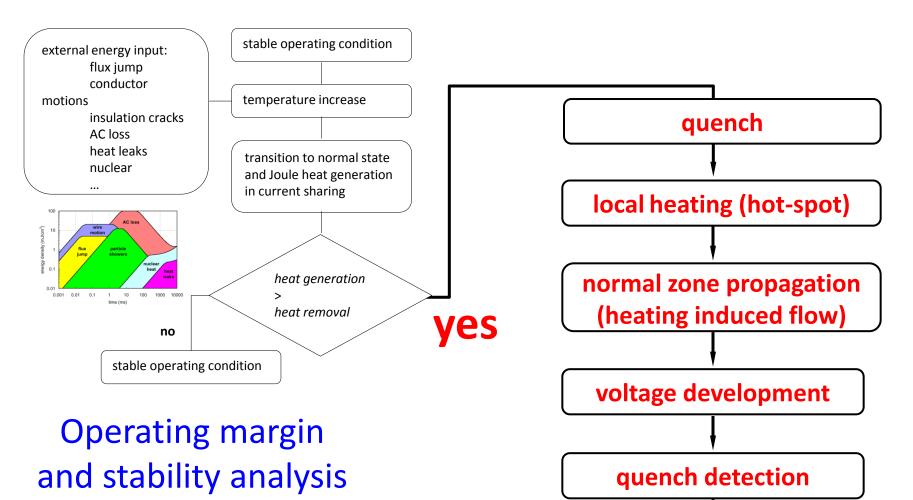


#### Q: what is the intrinsic detection level of a given method ?

# Outline

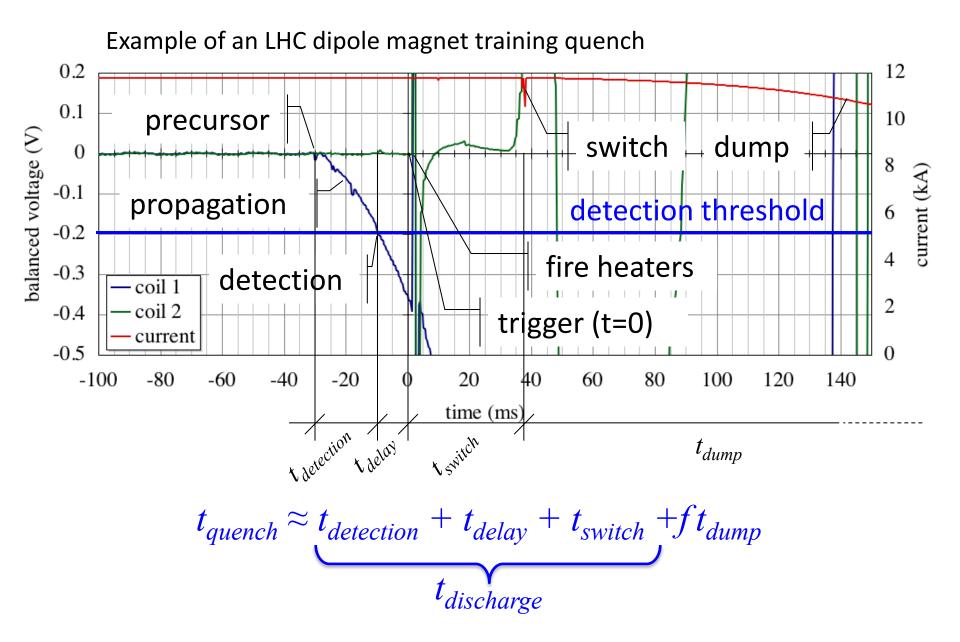
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## Quench sequence



safety discharge

## Detection, switch and dump



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## A multi-physics playground !

• Heat conduction in solids

Temperature, quench propagation

$$A\overline{C}\frac{\partial T_{co}}{\partial t} - \frac{\partial}{\partial x}\left(A\overline{k}\frac{\partial T_{co}}{\partial x}\right) = A\dot{q}_{Joule}^{\prime\prime\prime} + p_{w}h\left(T_{he} - T_{co}\right)$$

Coolant mass, momentum and energy

Pressure, flow, propagation  

$$A_{he}\rho_{he}\frac{\partial v_{he}}{\partial t} + A_{he}\rho_{he}v_{he}\frac{\partial v_{he}}{\partial x} + A_{he}\frac{\partial p_{he}}{\partial x} = -A_{he}F_{he}$$

$$A_{he}\frac{\partial p_{he}}{\partial t} + A_{he}v_{he}\frac{\partial p_{he}}{\partial x} + A_{he}\rho_{he}c_{he}^{2}\frac{\partial v_{he}}{\partial x} = A_{he}\phi_{he}v_{he}F_{he} + \phi_{h}p_{w}h(T_{co} - T_{he})$$

$$A_{he}\rho_{he}c_{he}\frac{\partial T_{he}}{\partial t} + A_{he}\rho_{he}v_{he}c_{he}\frac{\partial T_{he}}{\partial x} + A_{he}\rho_{he}\phi_{he}c_{he}T_{he}\frac{\partial v_{he}}{\partial x} = A_{he}v_{he}F_{he} + p_{w}h(T_{co} - T_{he})$$

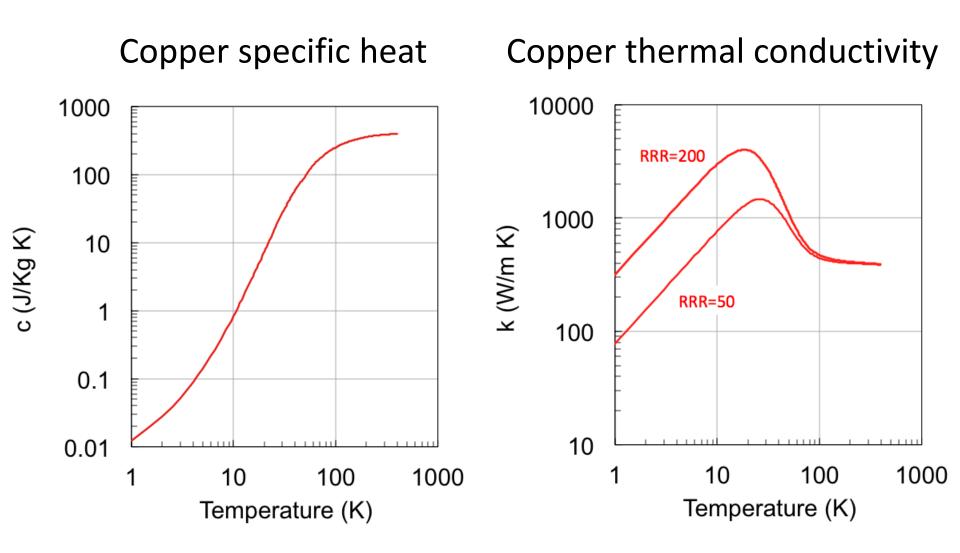
• Operating current

Joule heat (temperature), voltages

$$\mathbf{L}\frac{d\mathbf{I}}{dt} + \mathbf{R}\mathbf{I} = \mathbf{V}$$

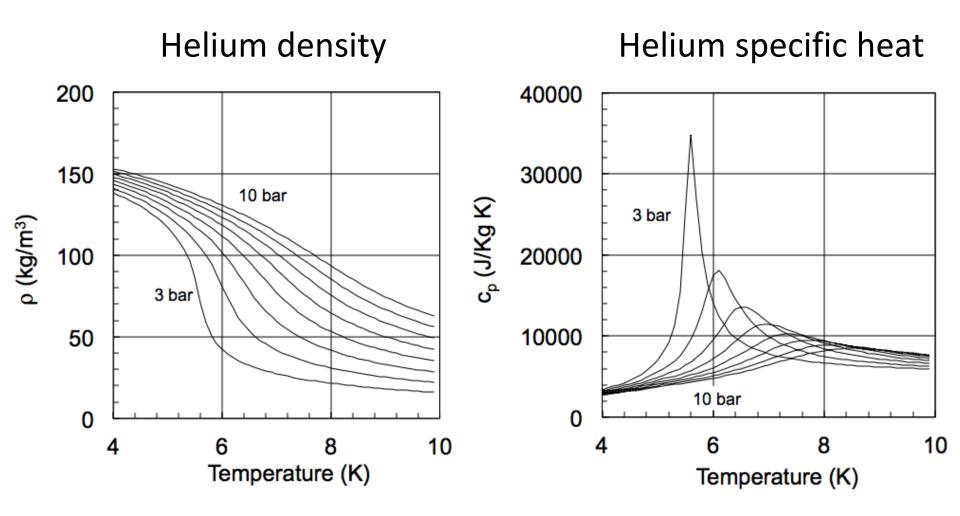
#### Q: which tools ?

#### **Transport properties**



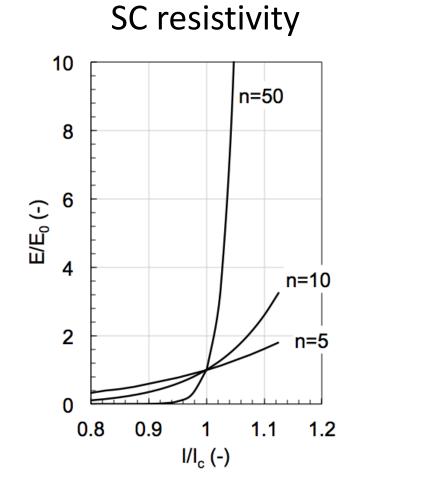
Orders of magnitude variation in the range of interest

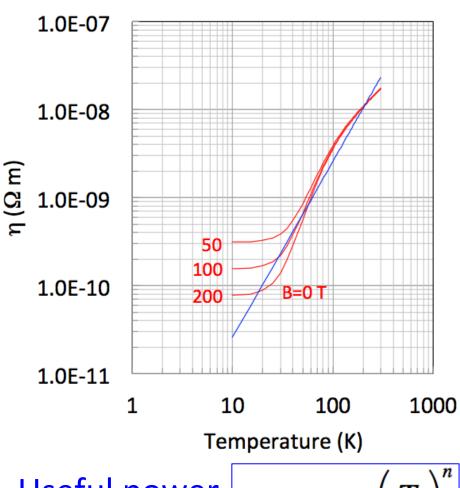
### Fluid properties



#### Factors of variation in the range of interest

## **Electrical properties**

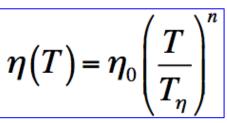




copper resistivity

**Highly non-linear** 

Useful power approximation

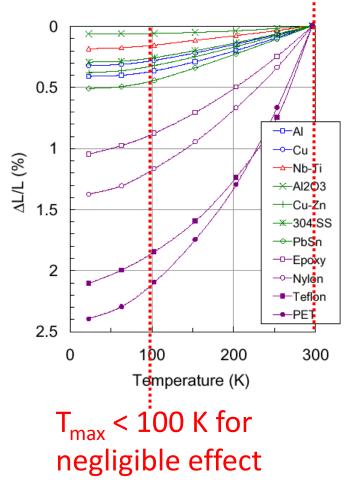


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## Hot-spot limits

T<sub>max</sub> < 300 K for well-supported coils (e.g. accelerator magnets)



- the quench starts in a point and propagates with a *quench propagation velocity*
- the initial point will be the *hot spot* at temperature  $T_{max}$
- $T_{max}$  must be limited to:
  - limit thermal stresses (see graph)
  - avoid material damage (e.g. resins have typical T<sub>cure</sub> 100...200 °C)

Q: What are the real limits for the hot-spot temperature ?

## Adiabatic heat balance

 The simplest (and conservative) approximation for the evolution of the maximum temperature during a quench is to assume adiabatic behavior at the location of the hot-spot:

$$A\overline{C}\frac{\partial T_{co}}{\partial t} - \frac{\partial}{\partial x}\left(A\overline{k}\frac{\partial T_{co}}{\partial x}\right) = A\dot{q}_{Joule}^{\prime\prime\prime} + p_{w}h\left(T_{he} - T_{co}\right) \quad \Longrightarrow$$

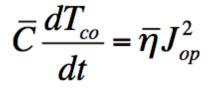
$$\bar{C}\frac{dT_{co}}{dt} = \bar{\eta}J^2$$

• Average heat capacity:  $\overline{C} = \sum_{i} f_i \rho_i c_i$ 

• Average resistivity: 
$$\frac{1}{\overline{\eta}} = \sum_{i} \frac{f_i}{\eta_i}$$

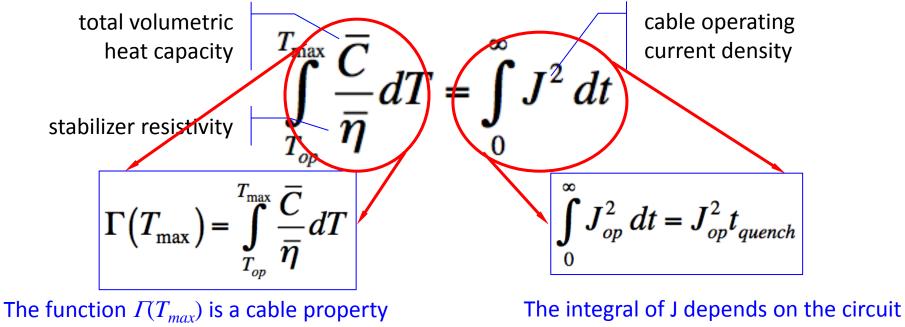
#### Hot spot temperature

• adiabatic conditions at the hot spot :



• can be integrated:

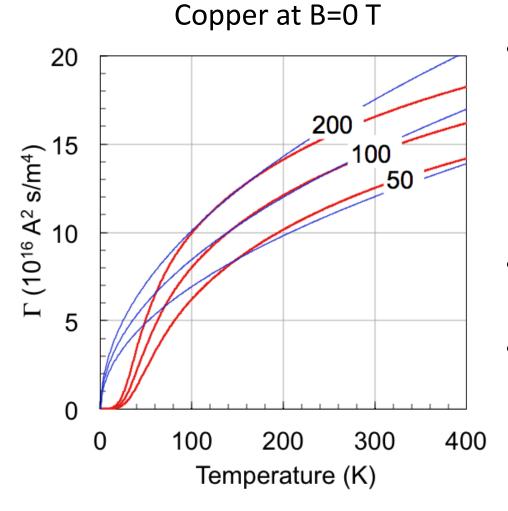
B.J. Maddock, G.B. James, Proc. IEE, 115 (4), 543, 1968



#### quench capital

**quench tax** 

## $\Gamma(T_{max})$ for pure materials



 Assume that the cable is made of stabilizer only (good first guess):

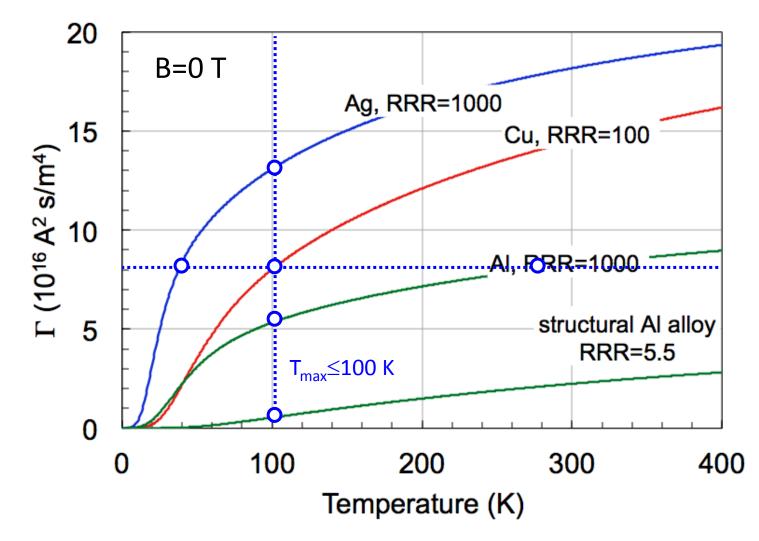
$$\overline{C} = \rho_{st} c_{st} \qquad \overline{\eta} = \eta_{st}$$

- $\Gamma(T_{max})$  is a *material property* and can be tabulated
- A useful approximation is:

$$\Gamma(T) \approx \Gamma_0 \left(\frac{T}{T_{\Gamma}}\right)^{\frac{1}{2}}$$

Wilson's Gamma

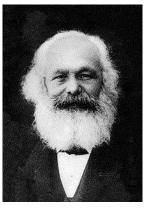
 $\Gamma(T_{max})$  for typical stabilizers



Larger value of  $\Gamma$  corresponds to lower  $T_{max}$  for a given quench tax, or higher quench capital for a given  $T_{max}$ 

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### Quench Capital vs. Tax

$$\Gamma(T_{\max}) = \int_{T_{op}}^{T_{\max}} \frac{\overline{C}}{\overline{\eta}} dT = \int_{0}^{\infty} J^2 dt = J_{op}^2 t_{quench}$$

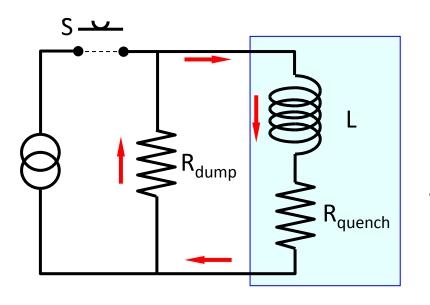


- The real problem is to determine the integral of the current waveform: how much is the quench time t<sub>quench</sub>?
- Consider two limiting cases:
  - External-dump: The magnet is dumped externally on a large resistance (R<sub>dump</sub> >> R<sub>quench</sub>) as soon as the quench is detected
  - Self-dump: The circuit is on a short circuit and is dumped on its internal resistance (R<sub>dump</sub> = 0)

## External dump

B.J. Maddock, G.B. James, Proc. Inst. Electr. Eng., 115, 543, 1968

 $R_{dump} >> R_{quench}$ 



quench

 The magnetic energy is extracted from the magnet and dissipated in an external resistor:

$$I = I_{op} e^{\frac{t - t_{discharge}}{t_{dump}}} \qquad t_{dump} = \frac{L}{R_{dump}}$$

The *quench tax* integral is:

$$\int_{0}^{\infty} J^{2} dt = J_{op}^{2} \left( t_{discharge} + \frac{t_{dump}}{2} \right)$$

• and the quench time is:

$$t_{quench} = \left(t_{discharge} + \frac{t_{dump}}{2}\right)$$

#### Dump time constant

• Magnetic energy:

$$E_m = \frac{1}{2}LI_{op}^2$$

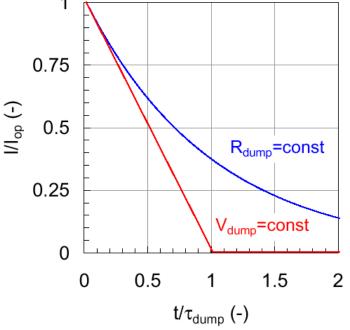
• Maximum terminal voltage:

$$V_{\rm max} = R_{dump} I_{op}$$

• Dump time constant:

 $t_{dump} = \frac{2E_m}{V_{max}I_{op}}$ maximum terminal voltage operating current

interesting alternative: non-linear R<sub>dump</sub> or voltage source



Increase  $V_{\text{max}}$  and  $I_{\text{op}}$  to achieve fast dump time

## Scaling for external dump

• Use Wilson's Gamma

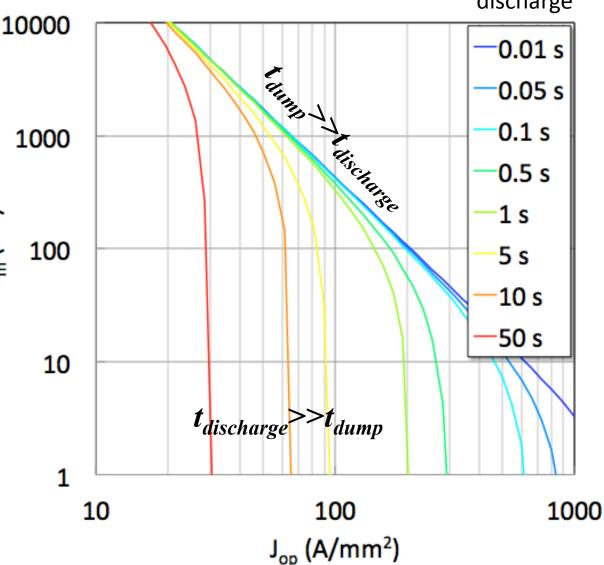
$$T_{\max} = \frac{T_{\Gamma}}{\Gamma_0^2} J_{op}^4 \left( t_{discharge} + \frac{E_m}{V_{\max} I_{op}} \right)^2$$

- To limit the hot-spot temperature:
  - Detect rapidly (quench propagation)
  - Use a large terminal voltage (voltage rating)
  - Make the cable large (reduce inductance)

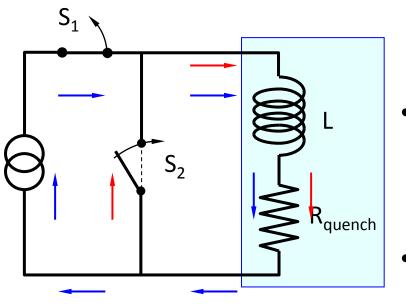
## Sample scaling study – external dump

t<sub>discharge</sub>

- Cu/Nb<sub>3</sub>Sn
- f<sub>Cu</sub> = 0.55
- $f_{SC} = 0.45$
- I<sub>op</sub> = 10 kA
- E<sub>m</sub> (MJ) • V<sub>max</sub> = 10 kV
- $T_{max} = 300 \text{ K}$



## Self dump



normal operation

— quench

- The magnetic energy is completely dissipated in the internal resistance, which depends on the temperature and volume of the normal zone
- In this case it is not possible to separate the problem in quench capital and quench tax, but we can make approximations
- Assume that:
  - The whole magnet is normal at t<sub>discharge</sub> (perfect heaters)
  - The current is constant until  $t_{quench}$  then drops to zero
  - Wilson's Gamma and the power resistivity

### Scaling for self dump

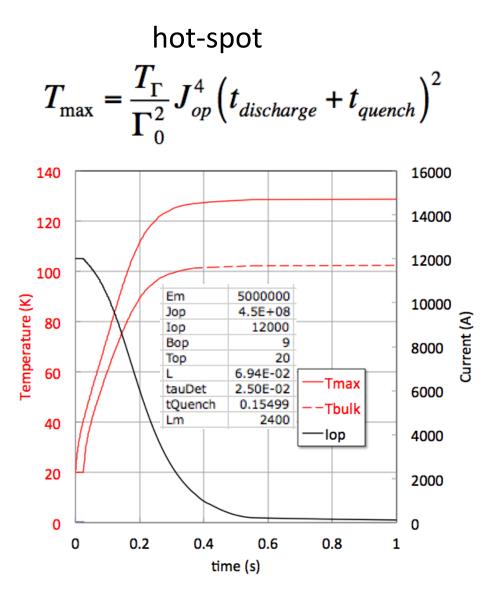
• Temperature

magnet bulk  $T_{bulk} = \frac{T_{\Gamma}}{\Gamma_0^2} (2n+1)^{\frac{2}{2n+1}} \left(\frac{e_m}{\alpha}\right)^{\frac{2}{2n+1}}$ 

• Quench time

$$t_{quench} = (2n+1)^{\frac{1}{2n+1}} \left(\frac{e_m}{\alpha}\right)^{\frac{1}{2n+1}} \frac{1}{J_{op}^2}$$

$$\alpha = \eta_0 \left( \frac{T_{\Gamma}}{T_{\eta} \Gamma_0^2} \right)^n$$



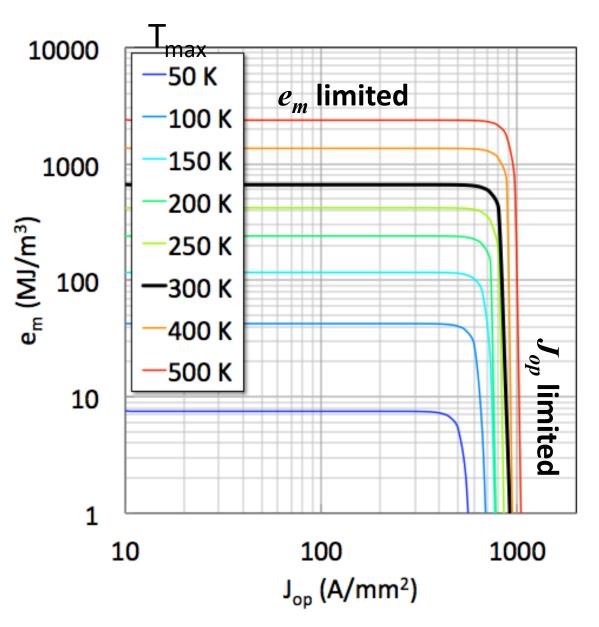
### Sample scaling study – self dump



• f<sub>Cu</sub> = 0.55

- $f_{SC} = 0.45$
- I<sub>op</sub> = 10 kA
- t<sub>discharge</sub> = 0.1 s

Ezio will dwell more on these results



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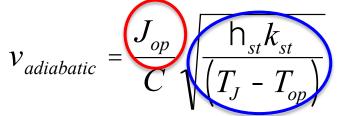
# How long is *t*<sub>discharge</sub> ?

- It depends on
  - Quench initiation and propagation velocity (3-D)
  - Detection thresholds, methods, lags
  - Quench heater method, firing delay, efficiency
  - Quench-back mechanisms
- An accurate knowledge and control of  $t_{discharge}$ is of paramount importance for the protection of magnets running at high  $J_{op}$

Q: What is the most efficient method to detect a quench ? Q: What is the most efficient method to induce a quench ?

### **Propagation velocity**

• Adiabatic conductor (e.g. fully impregnated)



Bath cooled conductor (e.g. porous insulation)

$$v_{quench} = \frac{1 - 2y}{\sqrt{1 - y}} v_{adiabatic}$$

$$=\frac{hwA_{st}(T_J - T_{op})}{h_{st}I_{op}^2} \gg \frac{1}{a_{Stekly}}$$

• Force-flow cooled conductor (e.g. ITER CICC)

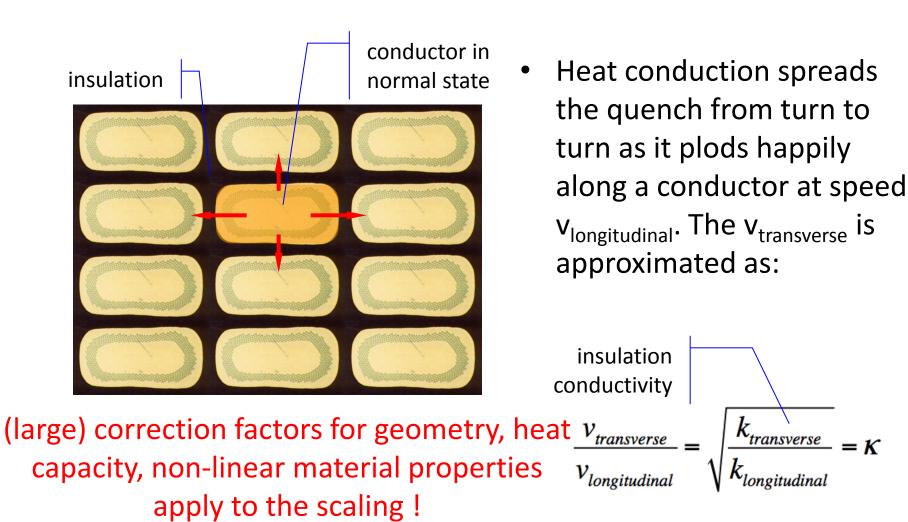
$$v_{quench} = \frac{R\Gamma_0 L_q}{2p_0} \frac{1}{f_{st}} \frac{h_q J_{op}^2}{C}$$
 Low pressure rise regime

y

The quench propagation velocity is a constant that scales with a power (1...2) of  $J_{op}$  and B(1...2)

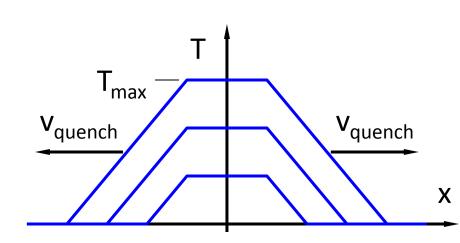
#### Q: do we know the propagation velocity in our magnets ?

## Turn-to-turn propagation



### Quench voltage: 1-D

- take: M. Wilson, *Superconducting Magnets*, Plenum Press, 1983.
  - short initial normal zone, initially at constant current
  - Wilson's Gamma and power resistivity (n≈2)
  - 1-D quench propagation with  $v_{quench}$  = constant
- then:

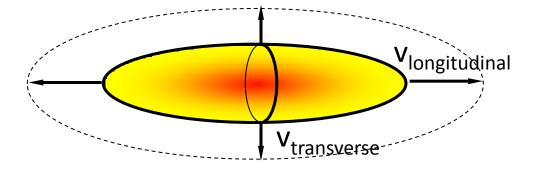


$$V \approx \frac{2}{5} \alpha J_{op}^9 v_q t^5$$
$$\alpha = \eta_0 \left(\frac{T_{\Gamma}}{T_{\eta} \Gamma_0^2}\right)^n$$

### Quench voltage : 3-D

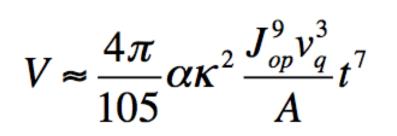
• In reality the quench propagates in 3-D

M. Wilson, *Superconducting Magnets*, Plenum Press, 1983.



VS.

• The voltage can be computed solving a volume integral:



**3-D** 

 $V \approx \frac{2}{5} \alpha J_{op}^9 v_q t^5$ 

1-D

### Scaling study – detection time

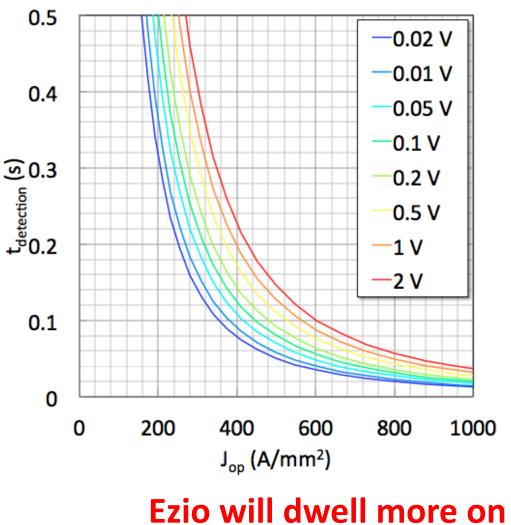
• Take for simplicity the 1-D case, with:

$$v_q = \frac{J_{op}}{C} \sqrt{\frac{\overline{\eta}\overline{k}}{\left(T_s - T_{op}\right)}} = \beta J_{op}$$

• The detection time scales as:

$$t_{detection} = \left(\frac{V_{detection}}{\frac{2}{5}\alpha\beta}\right)^{\frac{1}{5}} \frac{1}{J_{op}^{2}}$$

Cable and field dependent

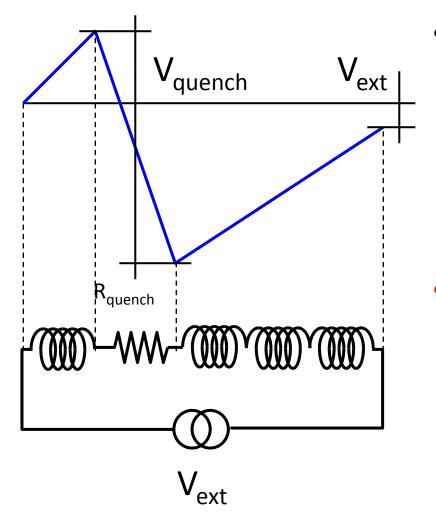


### these results

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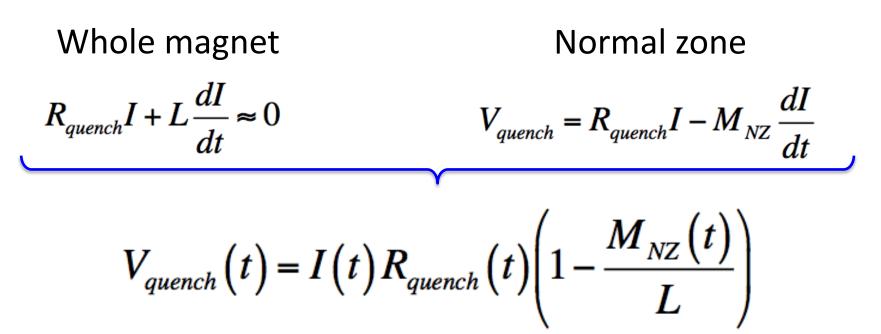
### Quench voltage



- electrical stress can cause serious damage (arcing) to be avoided by proper design:
  - insulation material
  - insulation thickness
  - electric field concentration
- REMEMBER: in a quenching coil the maximum voltage is not necessarily at the terminals

#### Q: what is an appropriate voltage criterion for our magnets ?

### Voltage peak (self-dump)



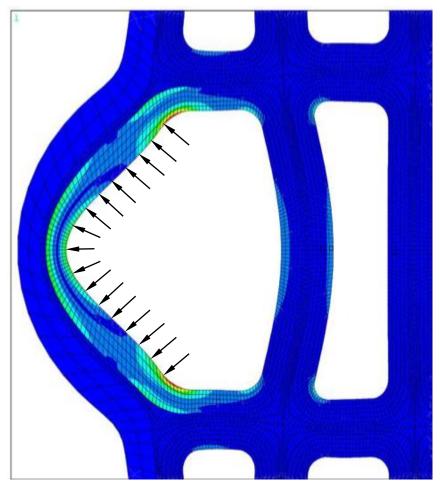
- $R_{quench}(t)$  increases with time (see earlier)
- I(t) decreases with time as the energy is dissipated
- $1-M_{NZ}(t)/L$  decreases with time as the normal zone propagates
- $V_{quench}(t)$  reaches a maximum during the dump

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## Helium expulsion

- The helium in the normal zone is heated:
  - The pressure increaseses:
     by how much ? (stresses in the conduits/pipes !)
  - Helium is blown out of the normal zone: at which rate ? (venting and sizing of buffers !)



Analysis of deformation of the CICC jacket in EDIPO, by courtesy of A. Portone, F4E, Barcelona

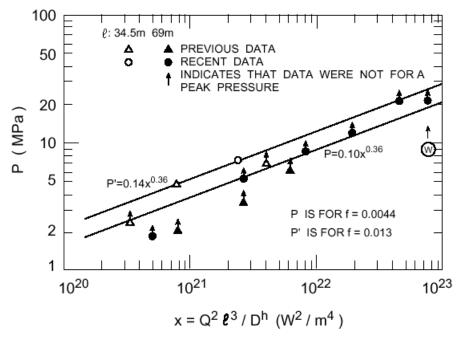
#### Pressure rise

J.R. Miller, L. Dresner, J.W. Lue, S.S. Shen, H.T. Yeh, Proc. ICEC-8, 321, 1980.

- Maximum pressure during quench for:
  - full length normal
  - constant heating rate

$$p_{\max} = 0.65 \stackrel{\acute{e}}{\underline{e}} \frac{f}{D_h} \stackrel{\ast}{\underline{e}} \frac{L}{2} \stackrel{"o}{\underline{o}}^3 \stackrel{\ast}{\underline{e}} \frac{h_{st}}{f_{he}} \stackrel{J^2}{J^2_{op}} \stackrel{"o}{\underline{o}}^2 \stackrel{"u}{\underline{u}}^{0.36}$$

- Wall thickness and diameter of venting lines must be sized accordingly !
- Use numerical codes to get proper estimates



## Outline

- What is a quench ? Process and issues
- The transition from SC to NC state
- The event tree
- Physics of a quench
- Hot-spot temperature limits
  - External-dump and self-dump limits
  - Quench propagation and time scales
- Quench voltages
- Pressure and expulsion
- Conclusions and open questions

## Conclusions – 1/2

- Physics:
  - Do we know the propagation velocity in our magnets ?
  - Quantitative effect of finite, low n-index ?
- Limits:
  - What are the *real* limits for the hot-spot temperature ?
  - What is an appropriate voltage criterion for our magnets ?
- Detection:
  - What is the most efficient method to detect a quench ?
  - What is the intrinsic detection level of a given method ?
- Dump:
  - What is the most efficient method to induce a quench ?
- Tools:
  - What is the optimal design method ?

### Conclusions – 2/2

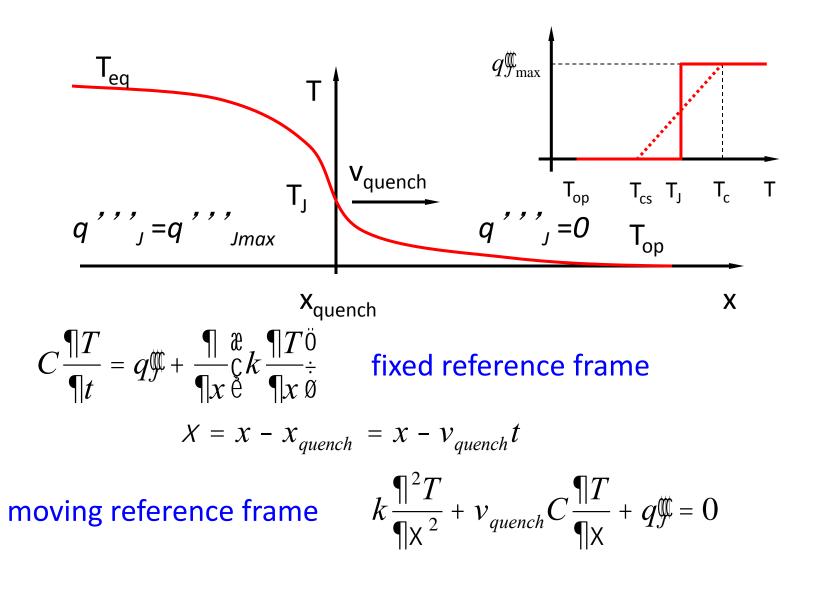
 There is obviously much more, for the rest of the workshop !



### **Backup slides**

- Propagation velocities
- Shaji's universe of quench
- Quench detection methods
- Protection strategies

#### Adiabatic propagation



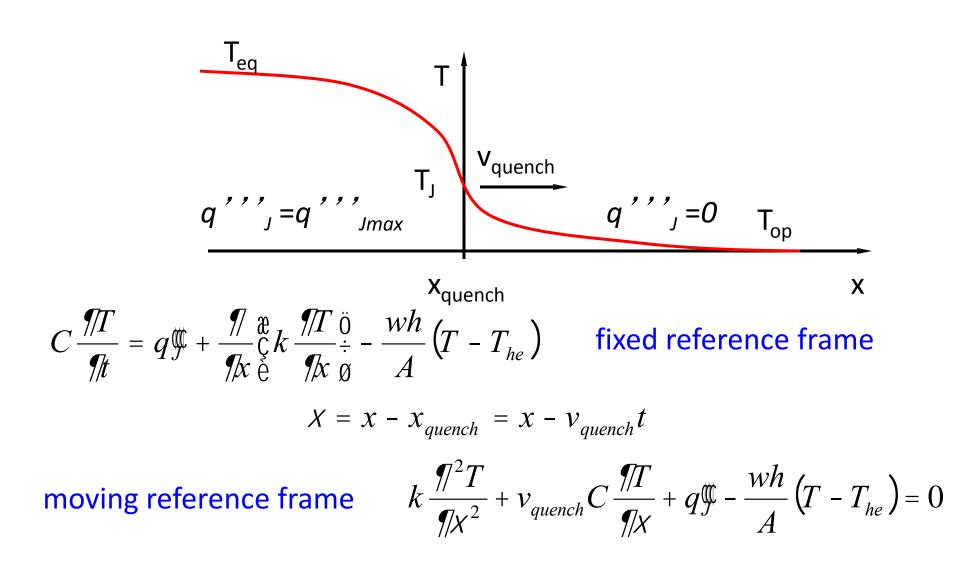
#### Adiabatic propagation

for *constant* properties ( $\eta$ , k, C)

$$v_{adiabatic} = \frac{J_{op}}{C} \sqrt{\frac{h_{st}k_{st}}{\left(T_J - T_{op}\right)}}$$

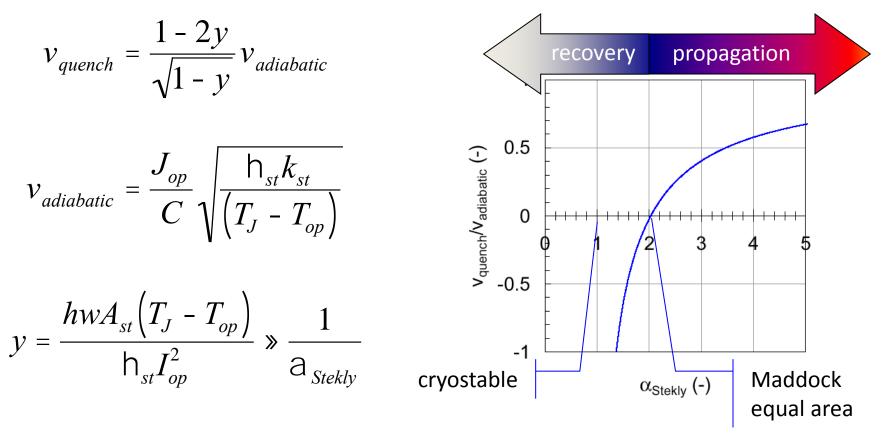
- Constant quench propagation speed
- Scales linearly with the current density (and current)
- Practical estimate. HOWEVER, it can give largely inaccurate (overestimated) values

#### **Bath-cooled propagation**



#### **Bath-cooled propagation**

for *constant* properties (η, k, C)

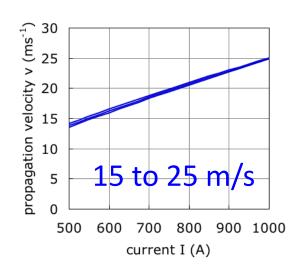


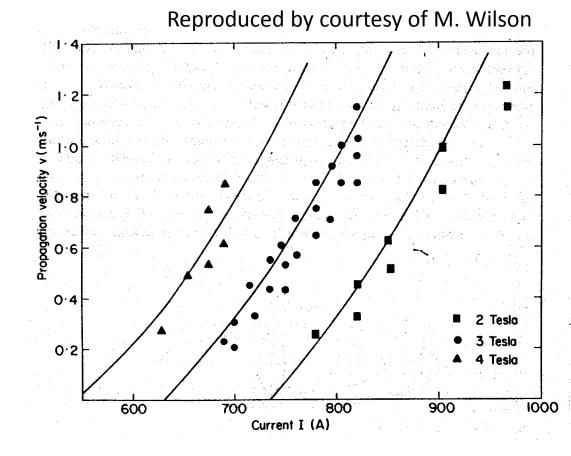
M. Wilson, *Superconducting Magnets*, Plenum Press, 1983.

### Data for bath-cooled quench

J.R. Miller, J.W. Lue, L. Dresner, IEEE Trans. Mag., 13 (1), 24-27, 1977.

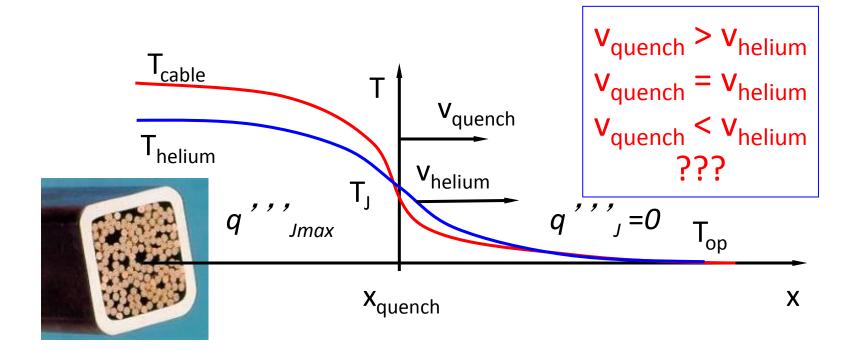
- NbTi conductor
  - $A_{NbTi} = 0.5 \text{ mm}^2$
  - $A_{Cu} = 5.1 \text{ mm}^2$
- Adiabatic propagation velocities:



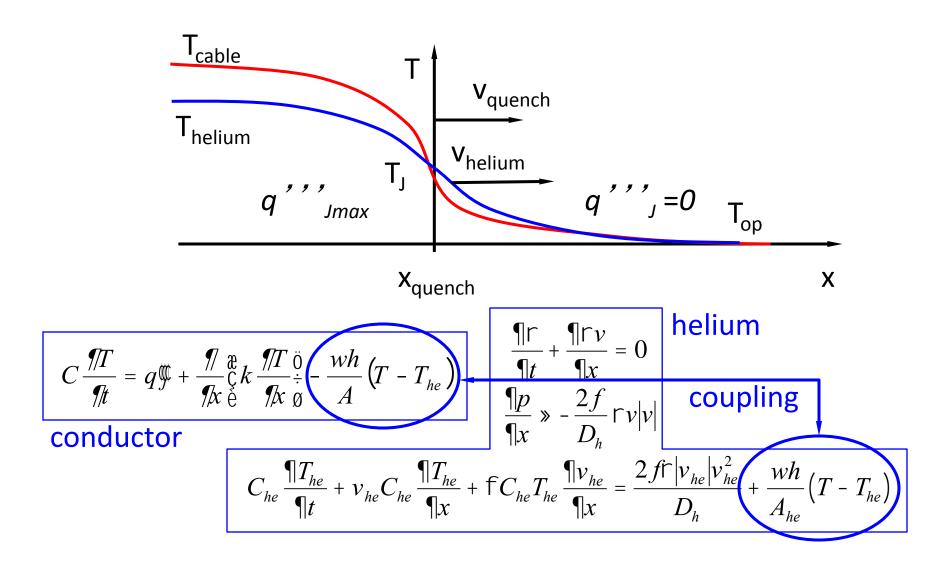


### Force-flow-cooled propagation

- the helium is heated in the normal zone and expands (dp/dT < 0)</li>
  - pressure increase
  - heating induced massflow of *hot* helium



#### Force-flow-cooled propagation



# Dresner's helium bubble

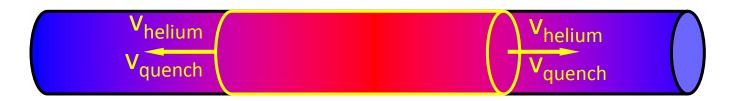
• Dresner's postulate: L. Dresner, Proc. 10<sup>th</sup> Symp. Fus. Eng.ng, 2040, 1983

...the velocity of the normal zone propagation equals the local velocity of expansion of helium.

consequence:

L. Dresner, Proc. 11<sup>th</sup> Symp. Fus. Eng.ng, 1218, 1985

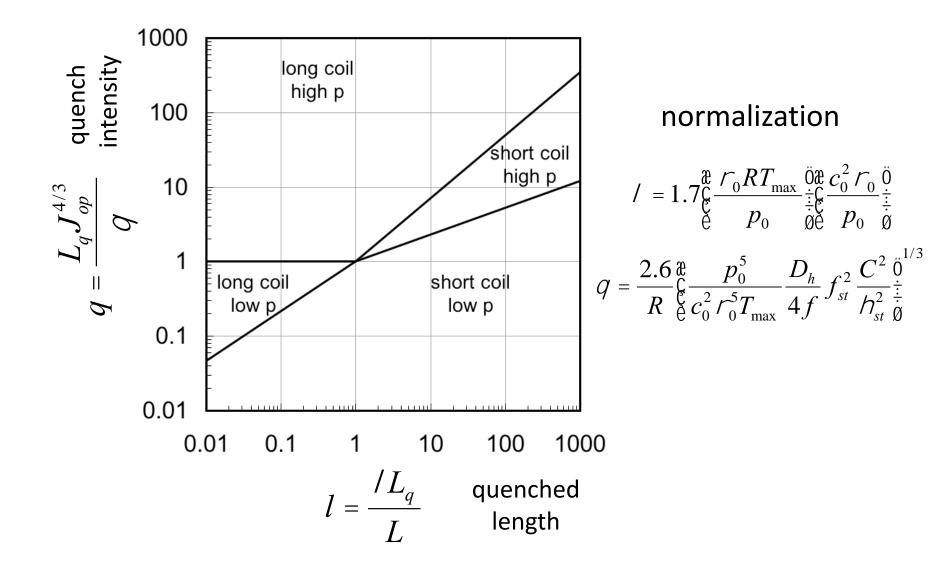
...the normal zone engulfs no new helium, or in other words [...] the heated helium comprises only the atoms originally present in the initial normal zone. We are thus led to the picture of a bubble of hot helium expanding against confinement by the cold helium on either side of it.



• OK if *h* is large and cable conduction is small

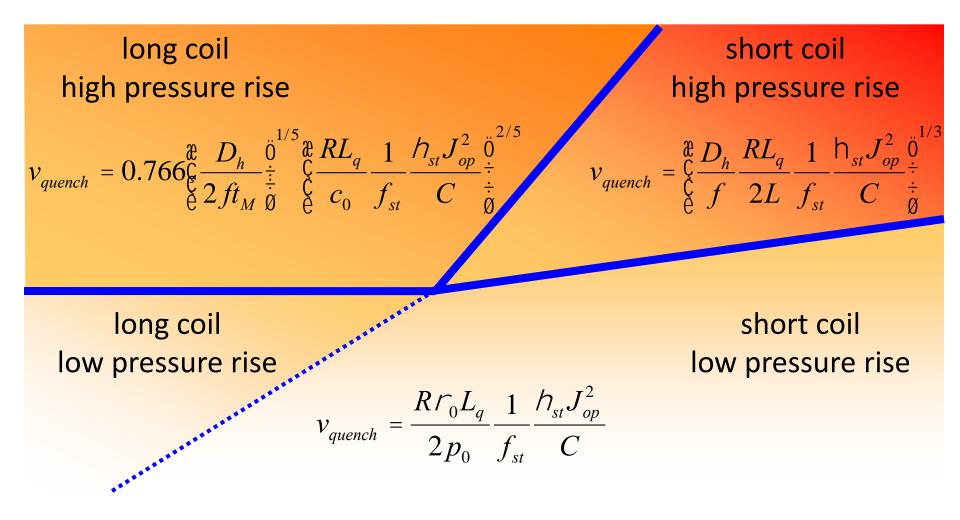
### Shajii's Universe of Quench

A. Shajii, J. Freidberg, J. Appl. Phys., **76** (5), 477-482, 1994.



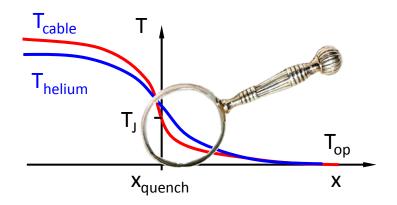
### **Propagation speed**

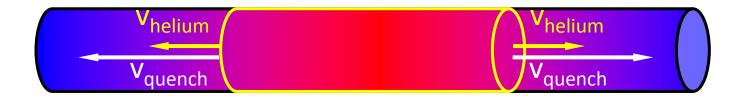
A. Shajii, J. Freidberg, J. Appl. Phys., 76 (5), 477-482, 1994.



## Thermal-hydraulic quench-back

- The helium at the front:
  - is compressed adiabatically (Dresner)
  - performs work agains the frictional drag (Shajii and Freidberg)
- Both effects cause pre-heating of the helium and superconductor
- The normal front advances faster than the helium expulsion velocity

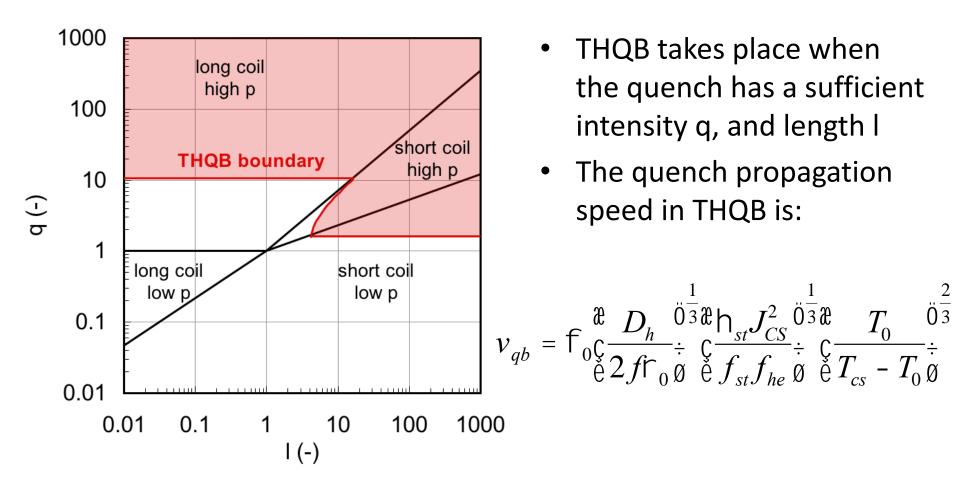




The normal zone engulfs an increasing mass and the quench accelerates: a Thermal-Hydraulic Quench-Back !

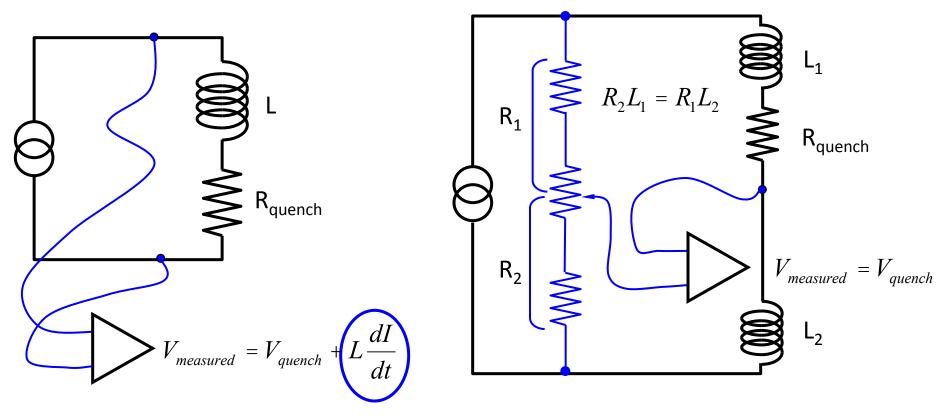
## THQB in Shajii's UoQ

A. Shajii, J. Freidberg, Int J. Heat Mass Transfer, **39**(3), 491-501, 1996.



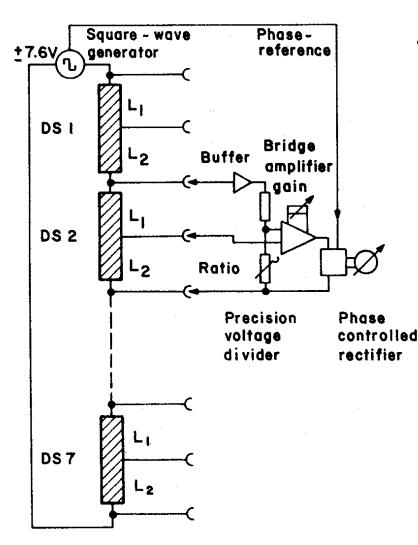
### Quench detection: voltage

- a direct quench voltage measurement is subject to inductive pick-up (ripple, ramps)
- immunity to inductive voltages
   (and noise rejection) is achieved
   by compensation

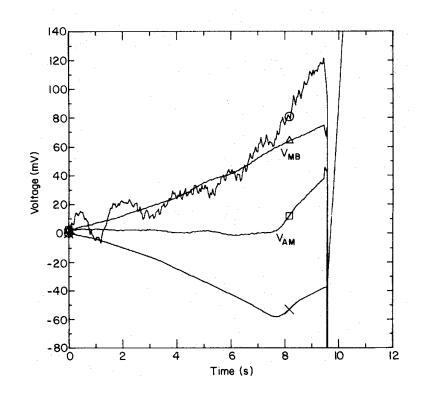


#### LCT quench detection scheme



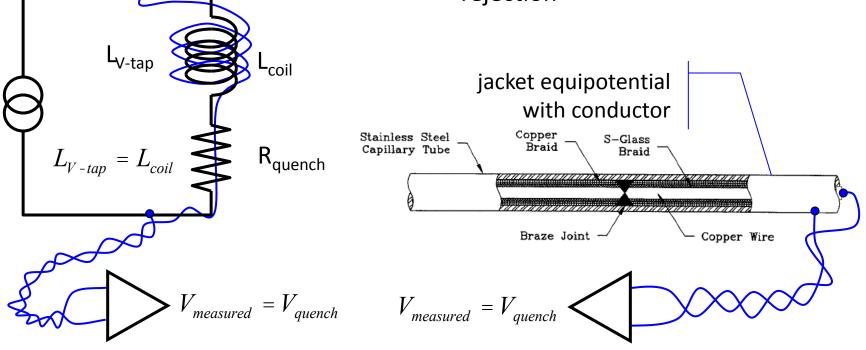


 A symmetric bridge does not see a symmetric quench ! BEWARE of all possible conditions



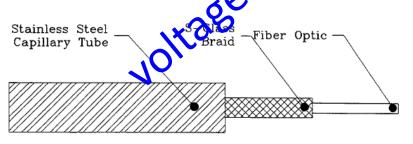
### Co-wound voltage taps

- co-wound (non-inductive) voltage taps are an alternative to achieve compensation
- sometimes the voltage tap can be directly inserted in the conductor, thus providing the best possible voltage compensation and noise rejection

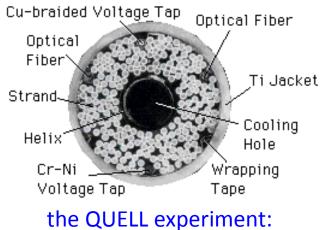


# Quench detection: indirect

- <u>quench antenna' s</u>: variation of magnetization and current distribution in cables generates a voltage pick-up from a magnetic dipole change localised at the quenching cable
- <u>optical fibers in cables/coils</u>: variation of fiber refraction index with temperature is detected as a change of the interference pattern of a laser beam traveling along the fiber



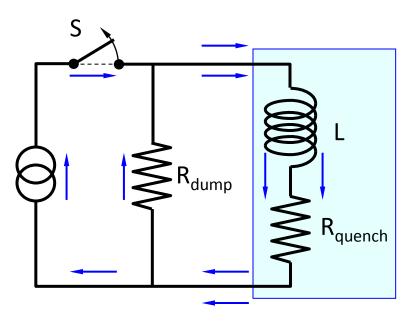
- pressure gauges and flow-meters: heating induced flow in internally cooled capies is detected at the coil inlet outlet
- <u>co-wound superconducting wires</u>:
   variation of resistance with temperature can be measured



a quench detection nightmare

# Strategy 1: energy dump

B.J. Maddock, G.B. James, Proc. Inst. Electr. Eng., 115, 543, 1968



$$R_{dump} >> R_{quench}$$

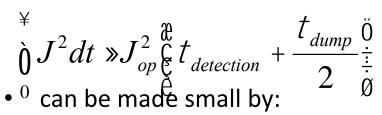
normal operation

quench

the magnetic energy is extracted from the magnet and dissipated in an external resistor:

$$I = I_{op} e^{-\frac{(t - t_{detection}}){t_{dump}}} \quad t_{dump} = \frac{L}{R_{dump}}$$

the integral of the current: <sup>*dump*</sup>



- - fast detection
  - fast dump (large R<sub>dump</sub>)

#### Dump time constant

• magnetic energy:

$$E_m = \frac{1}{2}LI_{op}^2$$

• maximum terminal voltage:

$$V_{\rm max} = R_{dump} I_{op}$$

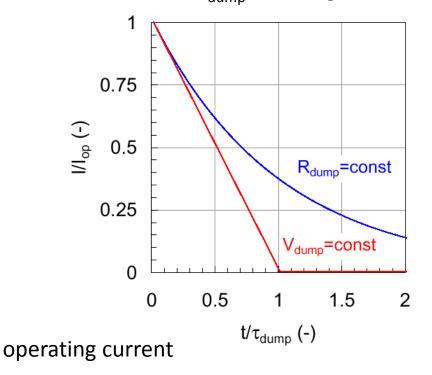
voltage

• dump time constant:

t<sub>dump</sub>

maximum terminal

interesting alternative: non-linear R<sub>dump</sub> or voltage source

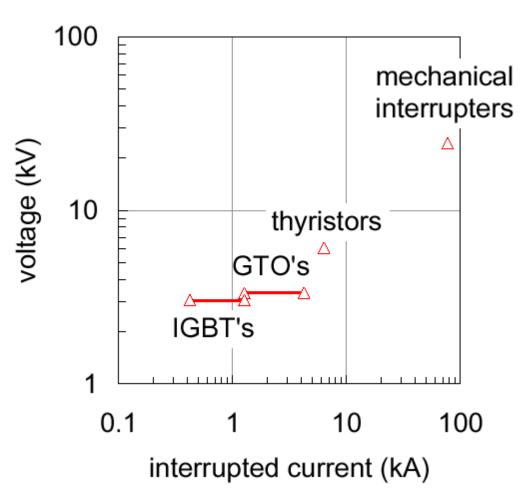


increase  $V_{\text{max}}$  and  $I_{\text{op}}$  to achieve fast dump time

 $=\frac{L}{R_{dump}}=\frac{2E_m}{V_{\max}I_{op}}$ 

# Switches

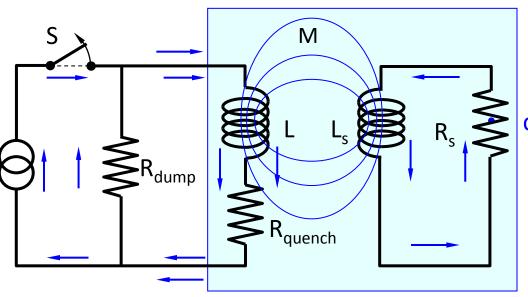
By courtesy of J.H. Schlutz, MIT-PSFC, 2002.



- switching kA' s currents under kV' s of voltage is not easy:
  - mechanical interrupters
  - thyristor's
  - Gate Turn-Off thyristor' s
  - Insulated Gate Bipolar Transistor's
  - fuses (explosive, water cooled)
  - superconducting
- cost and reliability are most important !

### Strategy 2: coupled secondary

 the magnet is coupled inductively to a secondary that absorbs and dissipates a part of the magnetic energy



• advantages:

- magnetic energy partially dissipated in R<sub>s</sub> (lower T<sub>max</sub>)
- lower effective magnet inductance (lower voltage)
- heating of R<sub>s</sub> can be used to speed-up quench propagation (quench-back)

disadvantages:

induced currents (and dissipation) during ramps

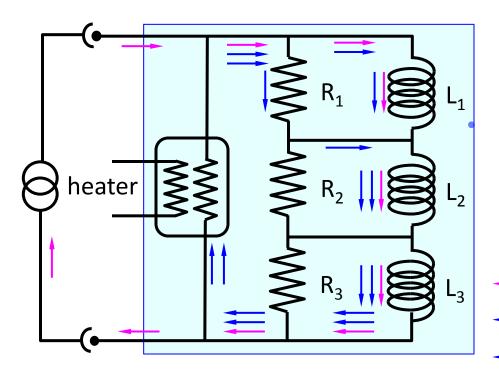
— normal operation

— quench

### Strategy 3: subdivision

P.F. Smith, Rev. Sci. Instrum., **34** (4), 368, 1963.

 the magnet is divided in sections, with each section shunted by an alternative path (resistance) for the current in case of quench



- advantages:
  - passive
  - only a fraction of the magnetic energy is dissipated in a module (lower T<sub>max</sub>)
  - transient current and dissipation can be used to speed-up quench propagation (quench-back)

disadvantages:

 induced currents (and dissipation) during ramps

- charge
- normal operation

— quench

## T<sub>max</sub> in subdivided system

P.F. Smith, Rev. Sci. Instrum., **34** (4), 368, 1963.

- in a subdivided system the energy dumped in each section is reduced because of
  - the resistive bypass
  - inductive coupling, reducing the effective inductance of each section:

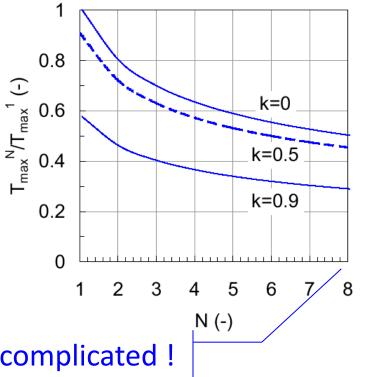
$$L_{effective} \mapsto (1 - k^2) L_{section} \gg (1 - k^2) \frac{L_{system}}{N}$$

• the hot spot temperature scales as:

$$T_{\rm max} \mu \sqrt[3]{L_{\rm effective}}$$

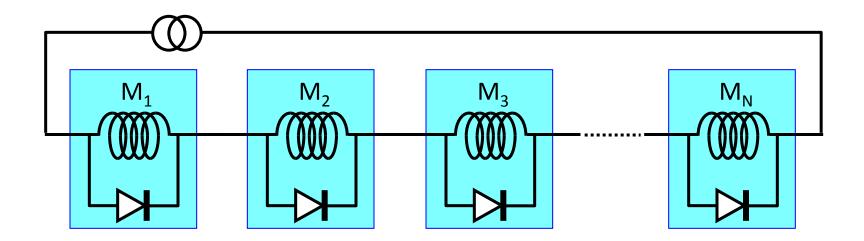
construction becomes complicated !

ratio of  $T_{max}^{N}$  in a system subdivided in N sections relative to the  $T_{max}^{1}$  in the same system with no subdivision



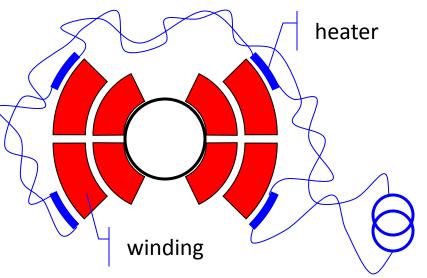
### Magnet strings

- magnet strings (e.g. accelerator magnets, fusion magnetic systems) have exceedingly large stored energy (10' s of GJ):
  - energy dump takes very long time (10...100 s)
  - the magnet string is *subdivided* and each magnet is bypassed by a diode (or thyristor)
  - the diode acts as a shunt during the discharge



### Strategy 4: heaters

- the quench is spread actively by firing heaters embedded in the winding pack, in close vicinity to the conductor
- heaters are mandatory in:
  - high performance, aggressive, cost-effective and highly optimized magnet designs...
  - ...when you are really desperate



- advantages:
  - homogeneous spread of the magnetic energy within the winding pack
- disadvantages:
  - active
  - high voltages at the heater