

A new camera concept for Cherenkov telescopes

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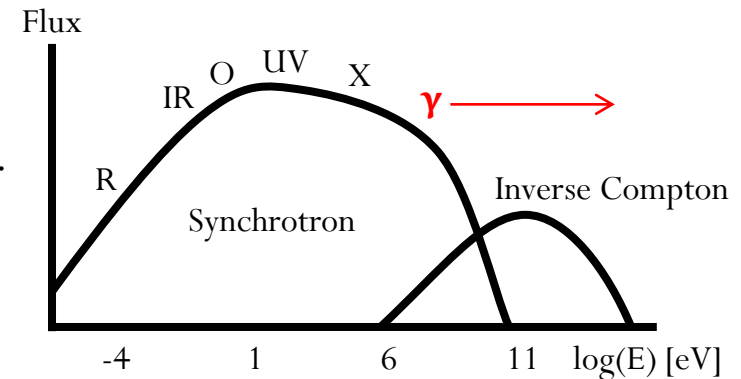


**University of
Zurich**^{UZH}

Motivation

Ground-based very high energy gamma-ray astronomy

- Non-thermal processes generate gamma-rays (keV – PeV).
- Investigation of galactic and extragalactic objects: SNR, pulsars, x-binaries, Active Galactic Nuclei etc.
- Improve understanding of processes of high energy gamma-ray production.
- New physics: indirect dark matter searches, test of quantum gravity models
- Ground-based high energy gamma-ray astronomy uses atmosphere as calorimeter and thus profits of a very large collection area.
- **Imaging Atmospheric Cherenkov Telescopes** cover energy range of 10 GeV – 100 TeV.

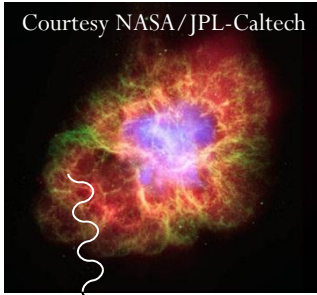


Current and future ground-based telescopes:

MAGIC, H.E.S.S., VERITAS, FACT

Cherenkov Telescope Array (under development)

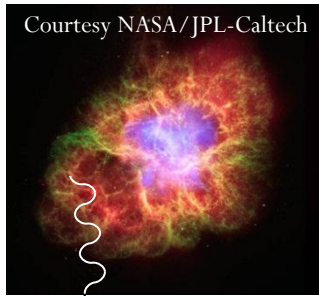
Working principle



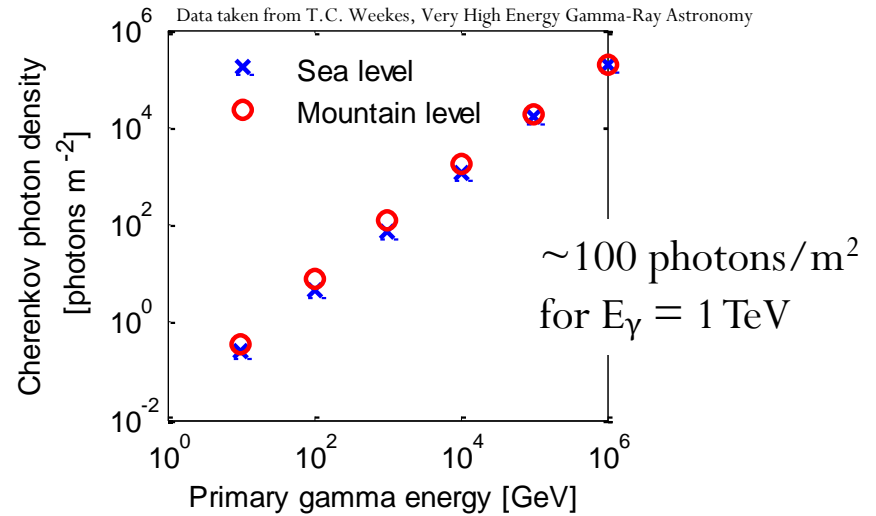
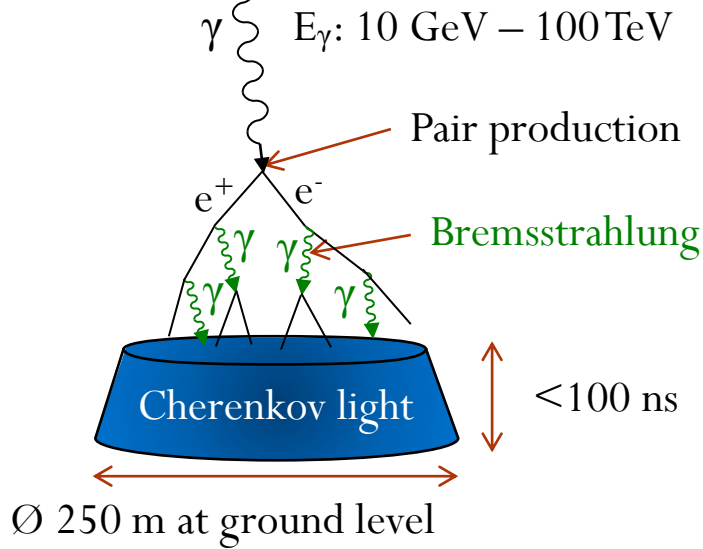
γ $E_\gamma: 10 \text{ GeV} - 100 \text{ TeV}$



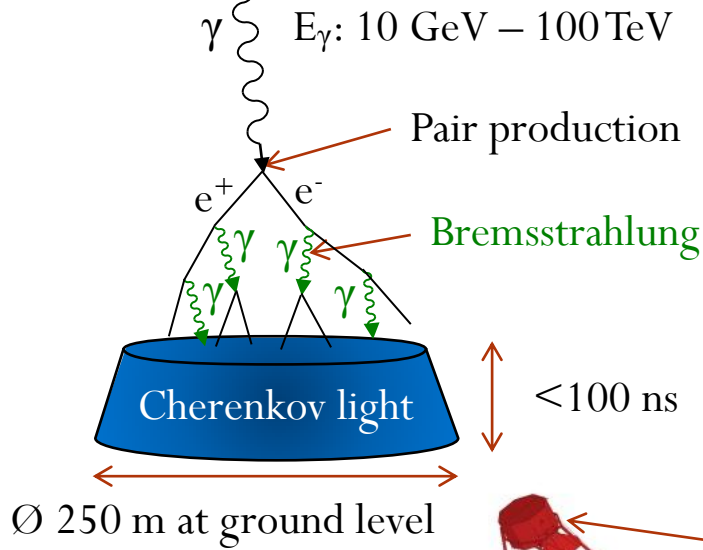
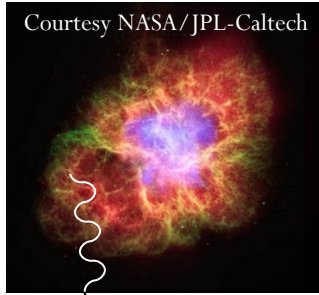
Working principle



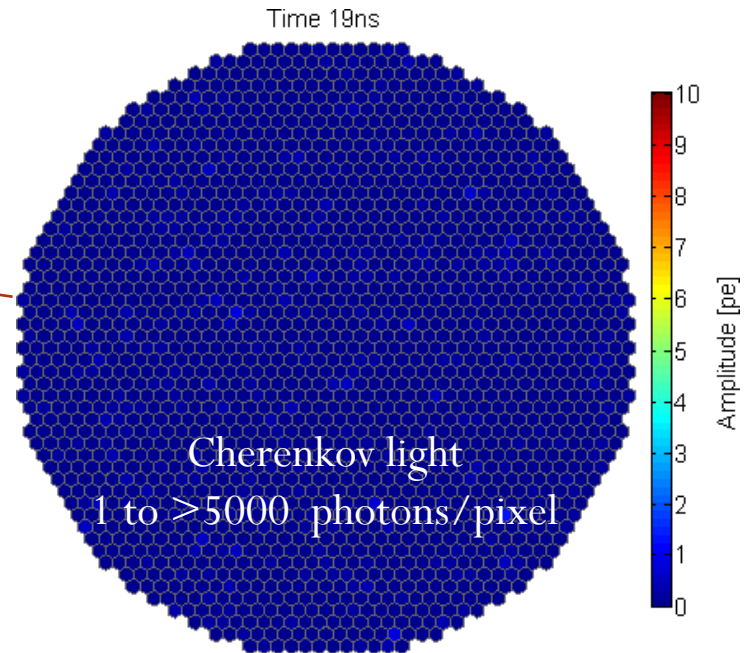
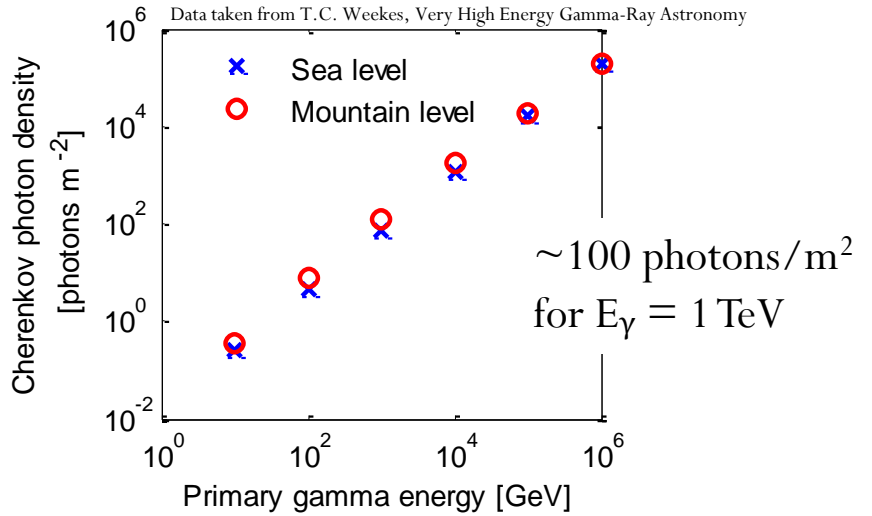
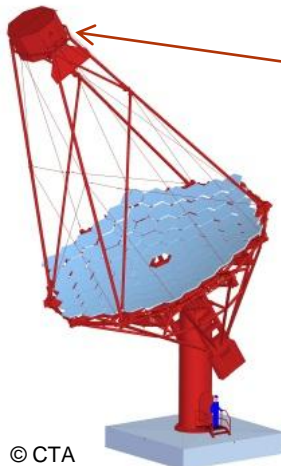
Courtesy NASA/JPL-Caltech



Working principle

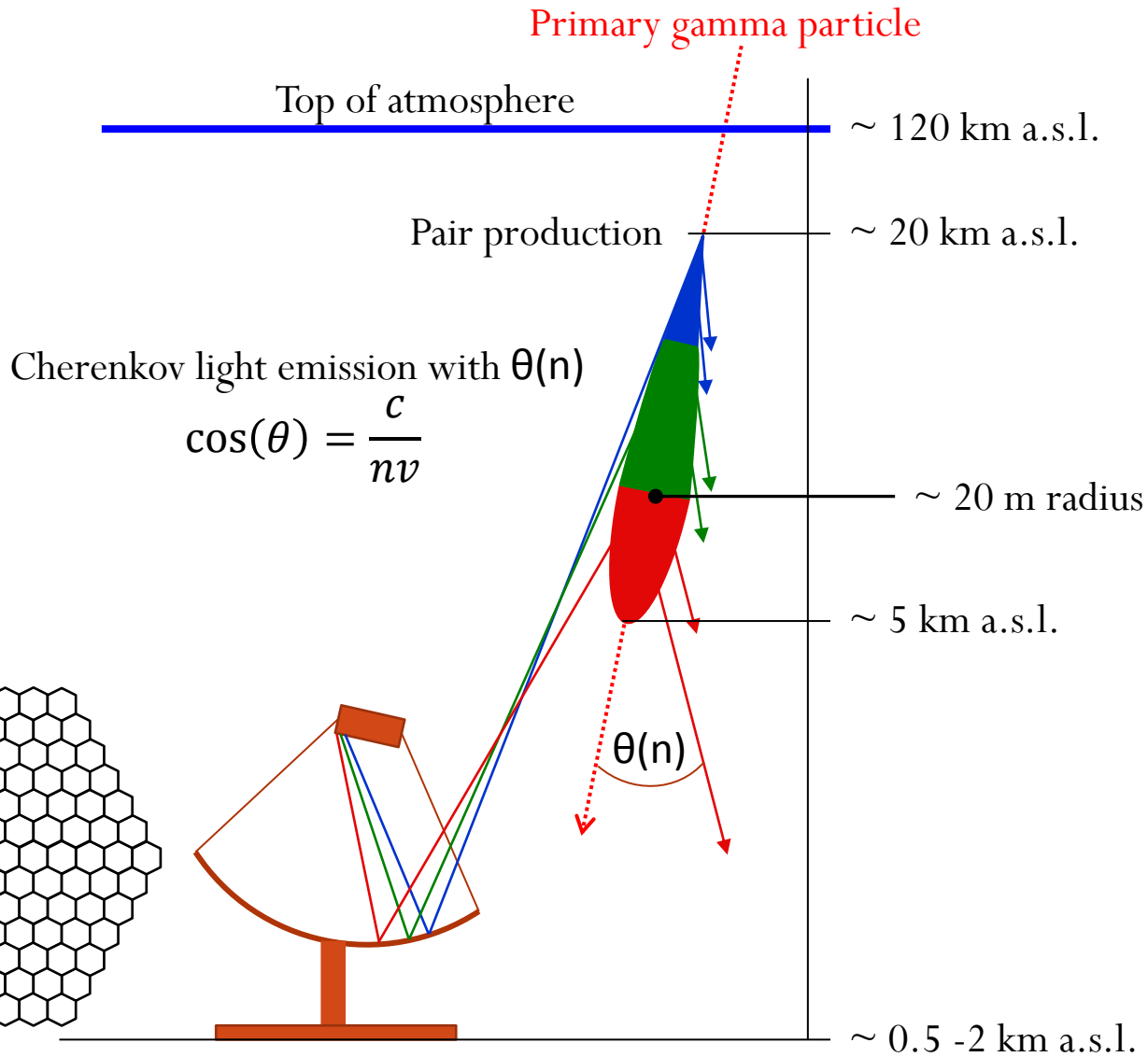


Mirror with $\varnothing 12 \text{ m}$ has 100 m^2 collection area



Working principle

$n = 1$

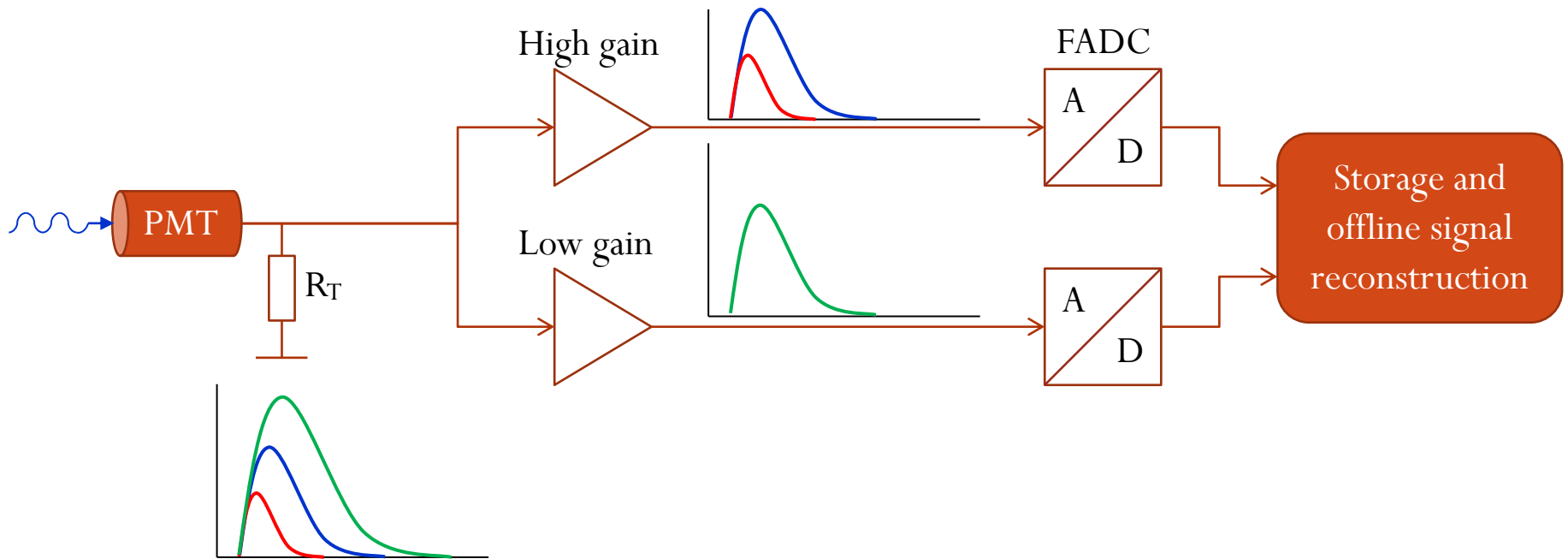


$n = 1.00029$ a.s.l.
 $\theta \approx 1.3^\circ$

Handling large dynamic signals

Large dynamic amplitude range can be treated in two ways:

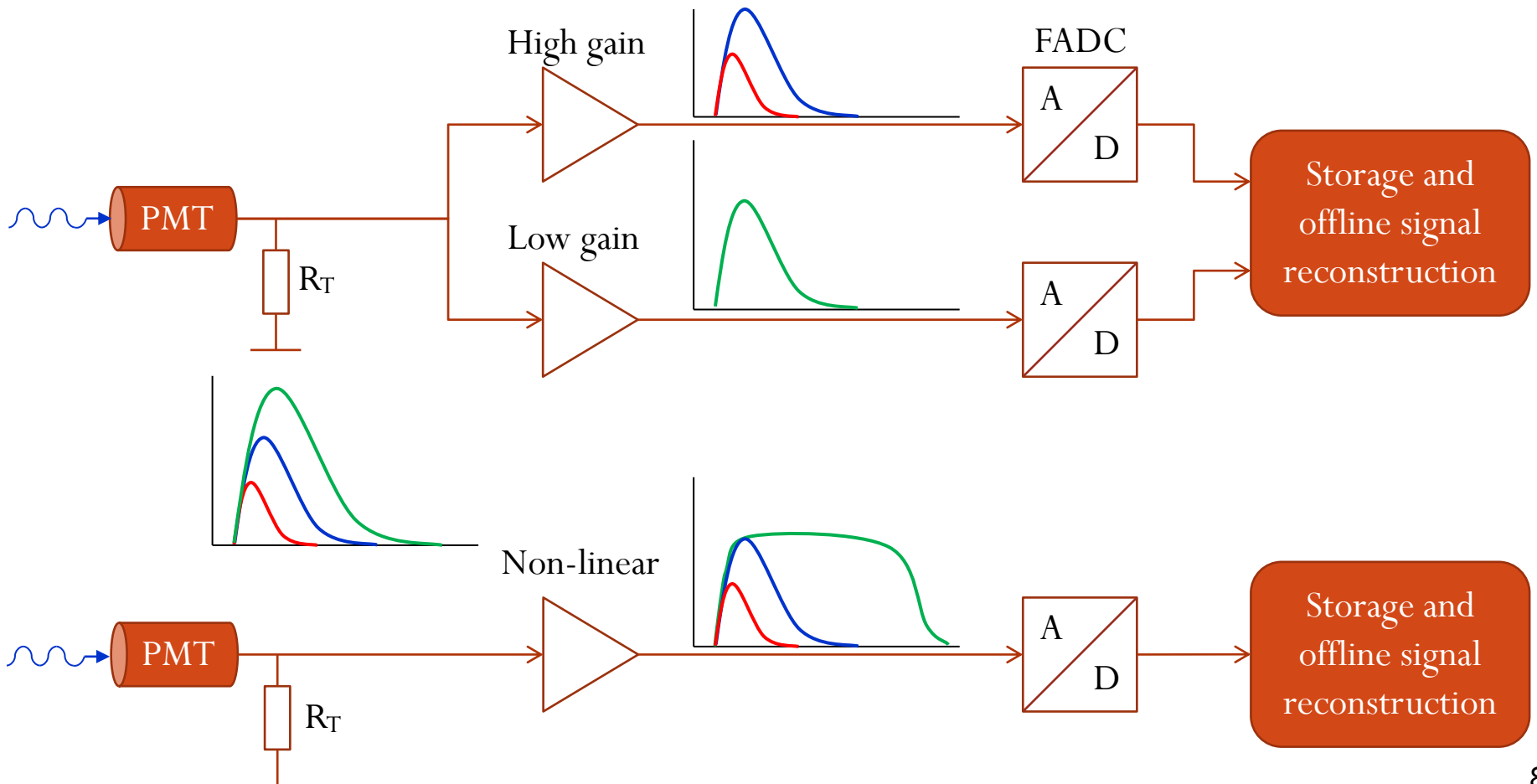
- dual signal path with
 - a high gain covering the low amplitude range (e.g. 0.2 – 200 pe) and
 - a low gain covering the high amplitude range (e.g. 20 – 5000 pe)



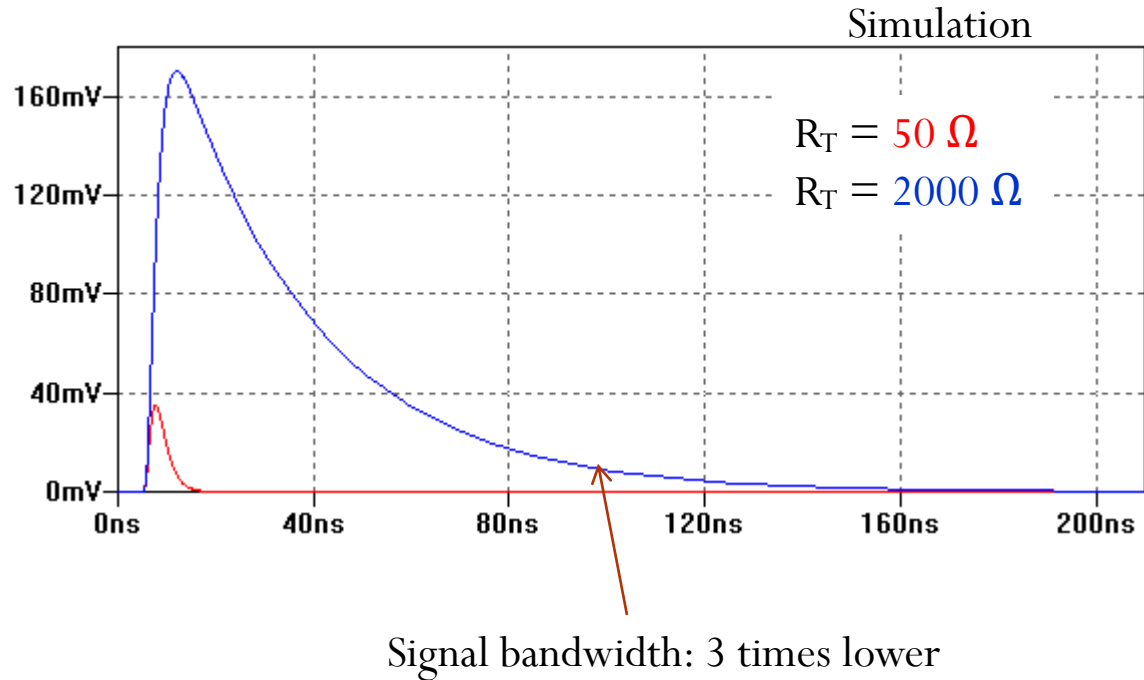
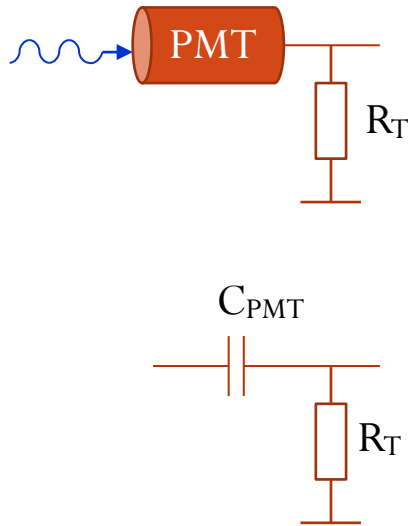
Handling large dynamic signals

Large dynamic amplitude range can be treated in two ways:

- dual signal path with
 - a high gain covering the low amplitude range (e.g. 0.2 – 200 pe) and
 - a low gain covering the high amplitude range (e.g. 20 – 5000 pe)
- single signal path with **non-linear** signal treatment



Signal shaping



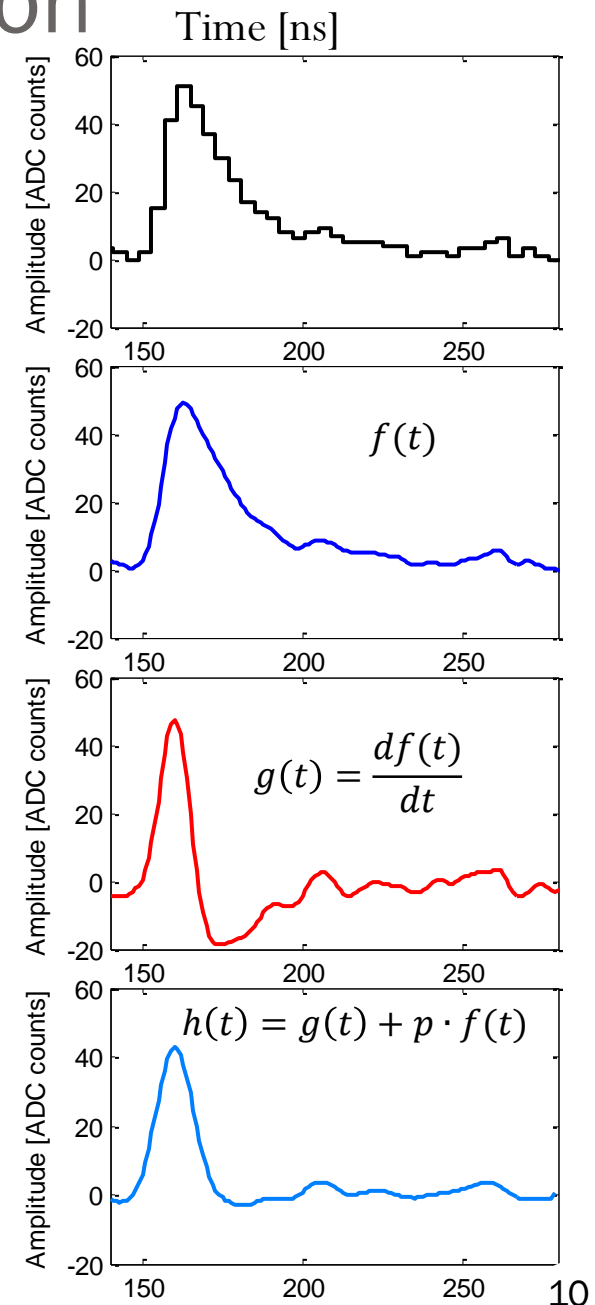
Termination resistor R_T influences signal bandwidth:

50Ω versus 2000Ω gives 3 times lower bandwidth

- ⇒ Larger termination resistor allows to digitize signals with a lower sampling rate (~ 3 times)
- ⇒ Use of reconstruction algorithm on digitized data still produces good timing and amplitude resolution

Signal reconstruction

1. Measured and digitized PMT signal (4 ns sample interval)
2. Up-sampling: linear interpolation (1 ns sample interval) and smoothing (moving average filter)
3. Differentiation and smoothing
⇒ Center of gravity above zero = photon arrival time
4. Base line restoration: pole-zero cancellation ($0 < p < 1$) and smoothing
⇒ Peak maximum = pulse amplitude
⇒ Peak area proportional to pulse amplitude



Signal reconstruction

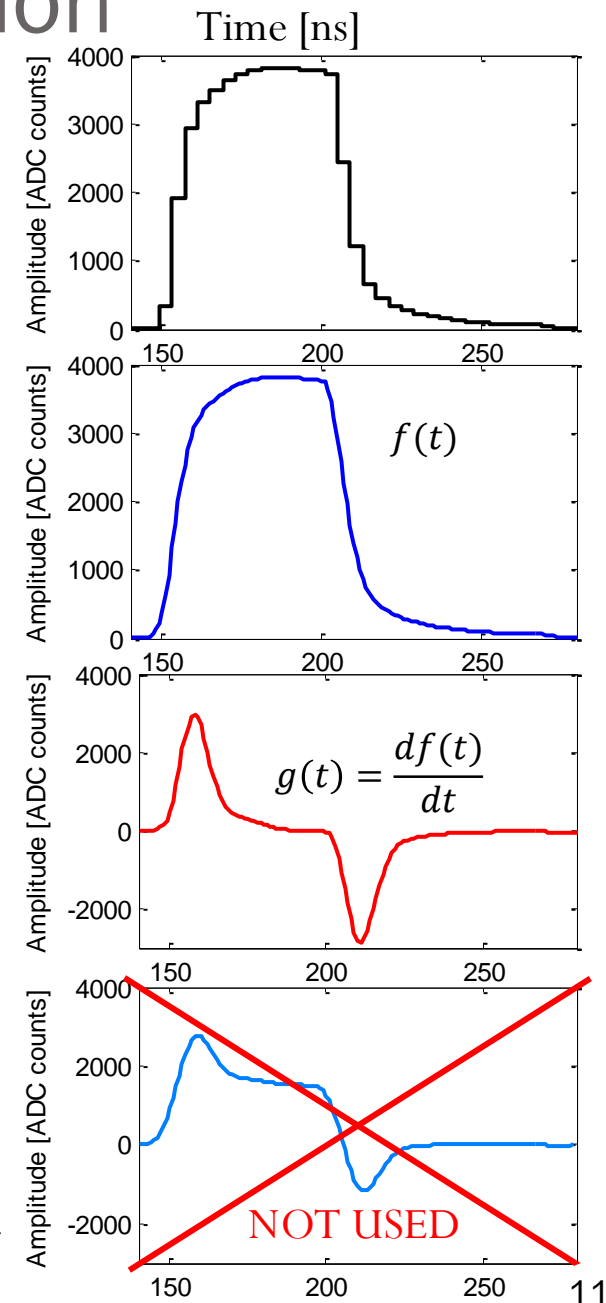
1. Measured and digitized PMT signal (4 ns sample interval)

2. Up-sampling: linear interpolation (1 ns sample interval) and smoothing (moving average filter)

3. Differentiation and smoothing
 \Rightarrow Center of gravity above zero = photon arrival time

4. Amplitude determined by integration of up-sampled signal over fixed window size (typically 200 ns)

\Rightarrow Peak area proportional to pulse amplitude: $A = \int_{k=i}^{i+200} f(t) dt$



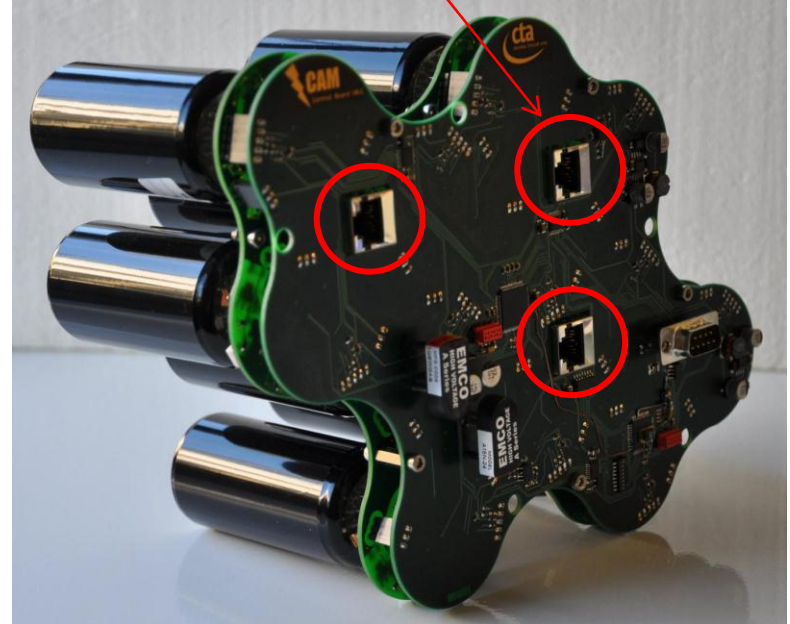
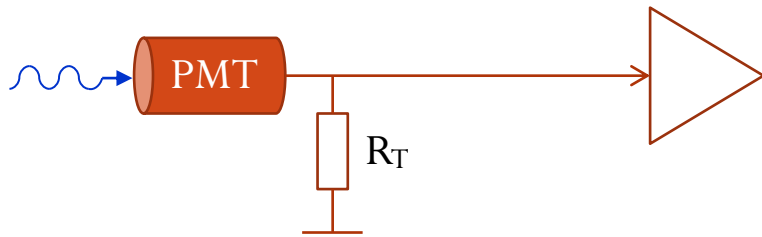


Towards a real camera...

The Photo-Detector-Plane

Photo-Detector-Plane (PDP) consisting of:

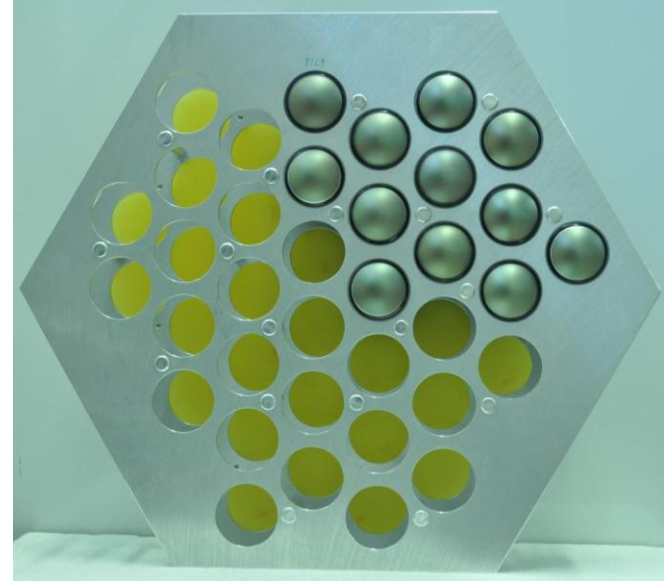
- Photomultiplier
- Signal amplifier: analogue signal transmission over CAT5/6 cables
- HV generators: 500 and 1500 kV
- CAN bus for slow control



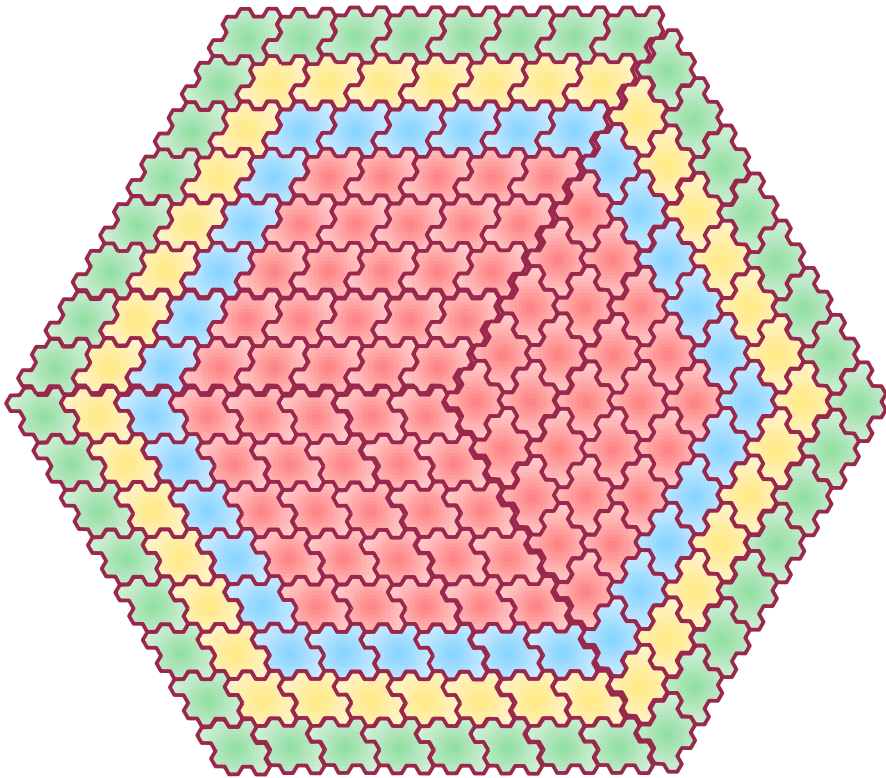
Developed and built at University of Zurich





The Photo-Detector-Plane

Lab test setup: PDP with 12 PMTs

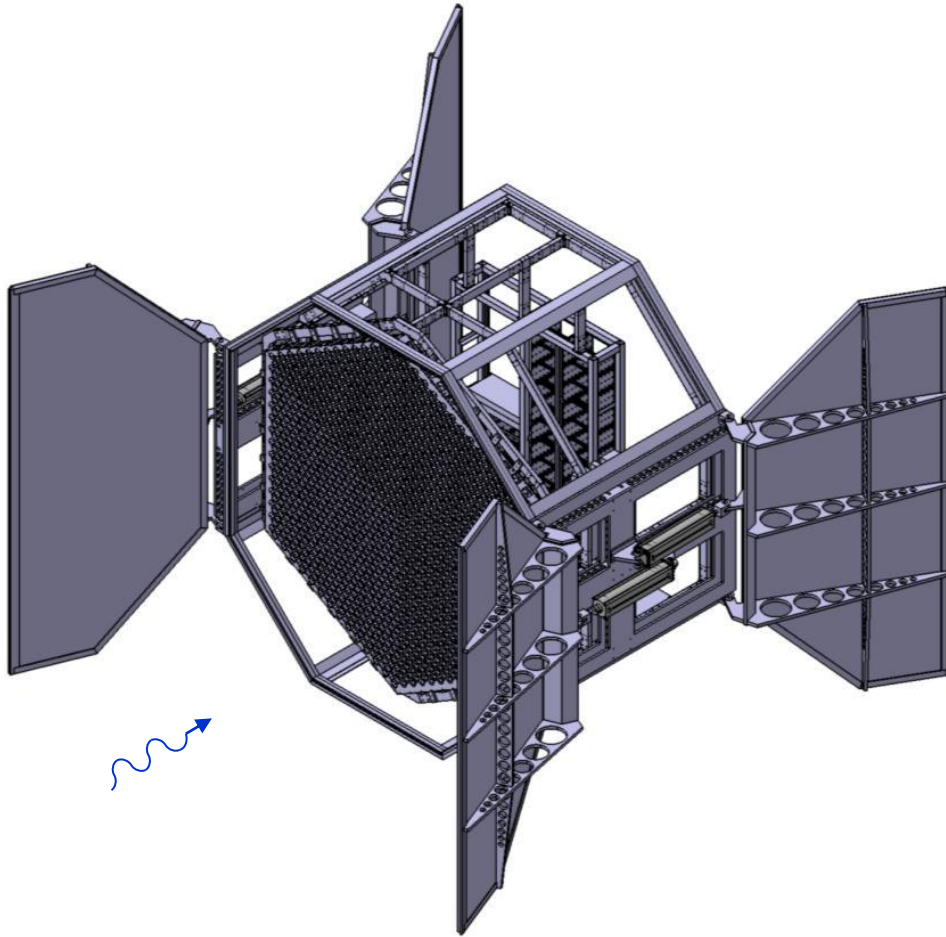


Possible PDP assemblies for different telescope sizes



-  900 pixel, 1550 mm flat to flat
-  1296 pixel, 1860 mm flat to flat
-  1764 pixel, 2170 mm flat to flat
-  2304 pixel, 2480 mm flat to flat

Mechanical structure

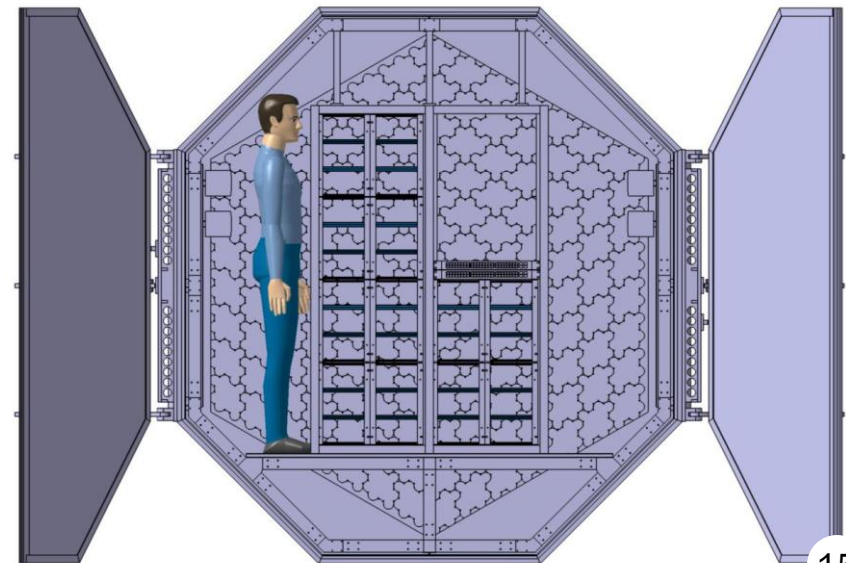


Design study by S. Steiner, UZH

A possible design of the mechanical structure

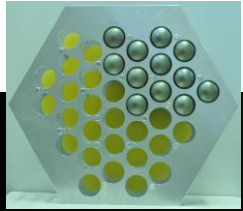
- ~ 2.7 m flat to flat
- ~ 2 m depth
- 1.7 t weight

Back view

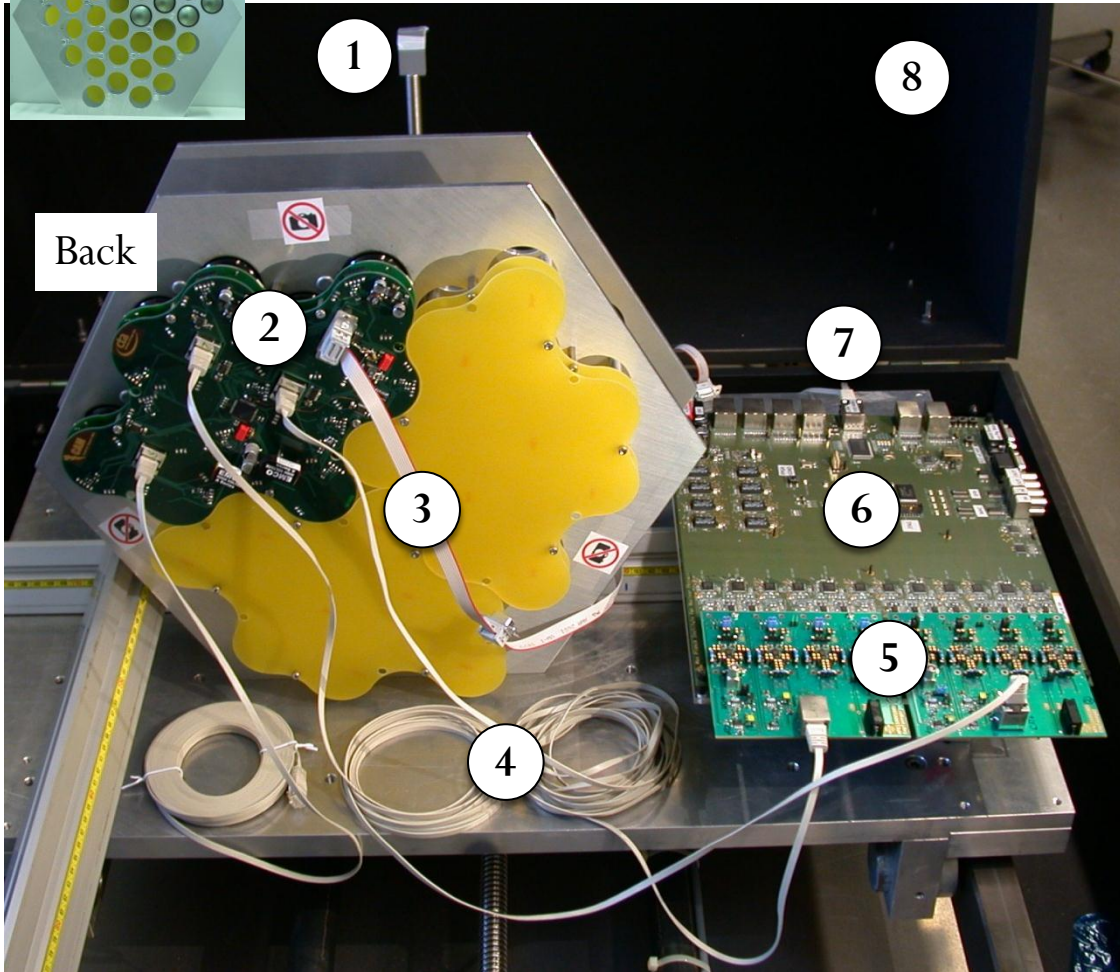


Test camera setup

Front



Back



- 1 Laser pulses fed in with optical fiber
- 2 Board with 12 PMTs
- 3 CAN bus (slow control + 24V)
- 4 Analogue pixel signal transmission via CAT 5 cables (1 cable per 4 pixels)
- 5 FADC drivers for 8 FADC
- 6 FPGA board
- 7 Event transmission via LAN to computer disk
- 8 Dark box

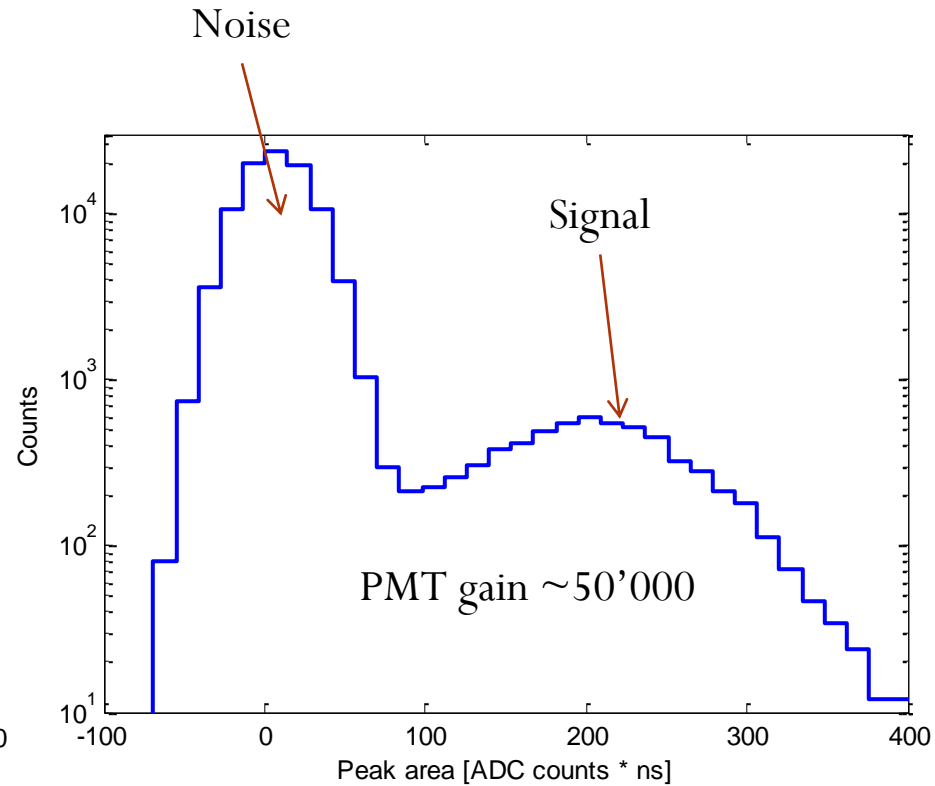
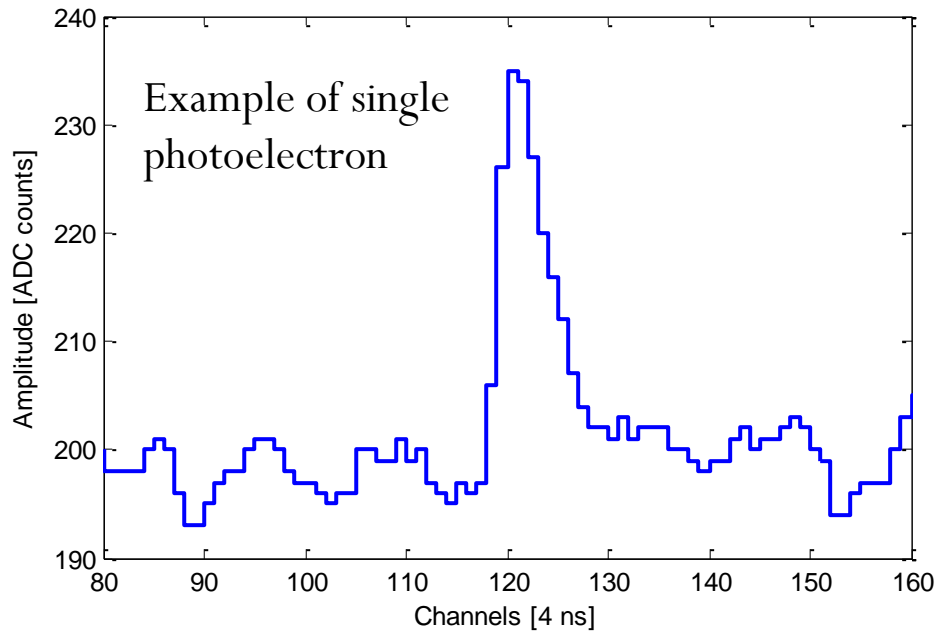
Not shown:

- PC with offline analysis software
- Slow control PC
- 24V power supply

Single photoelectron response

Measured with:

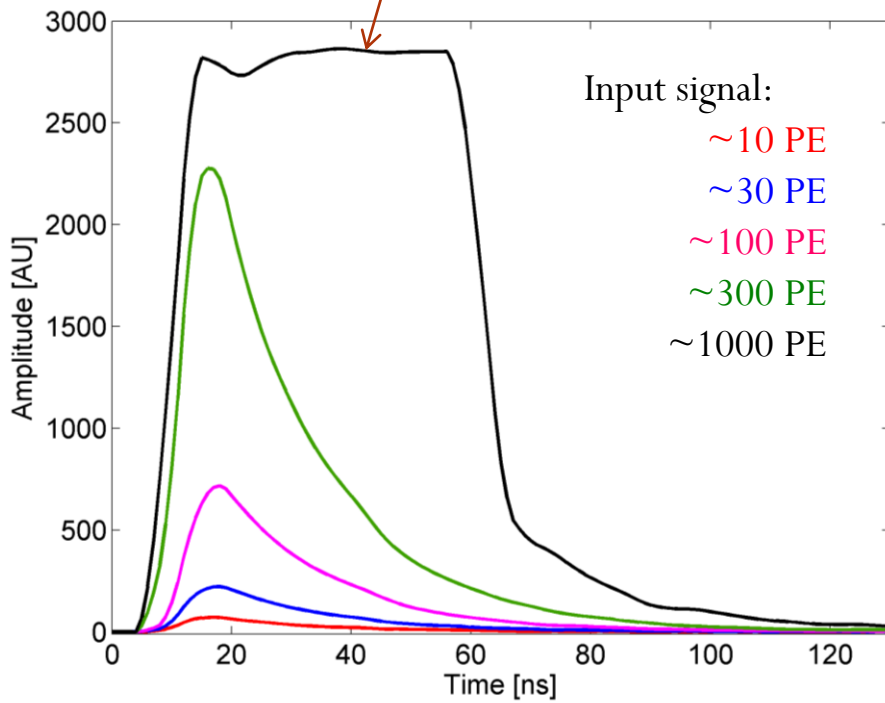
- High voltage of (1000 ± 20) V
- Amplifier gain of 12



Full range resolution

Measurement of linearity with **electric pulser**

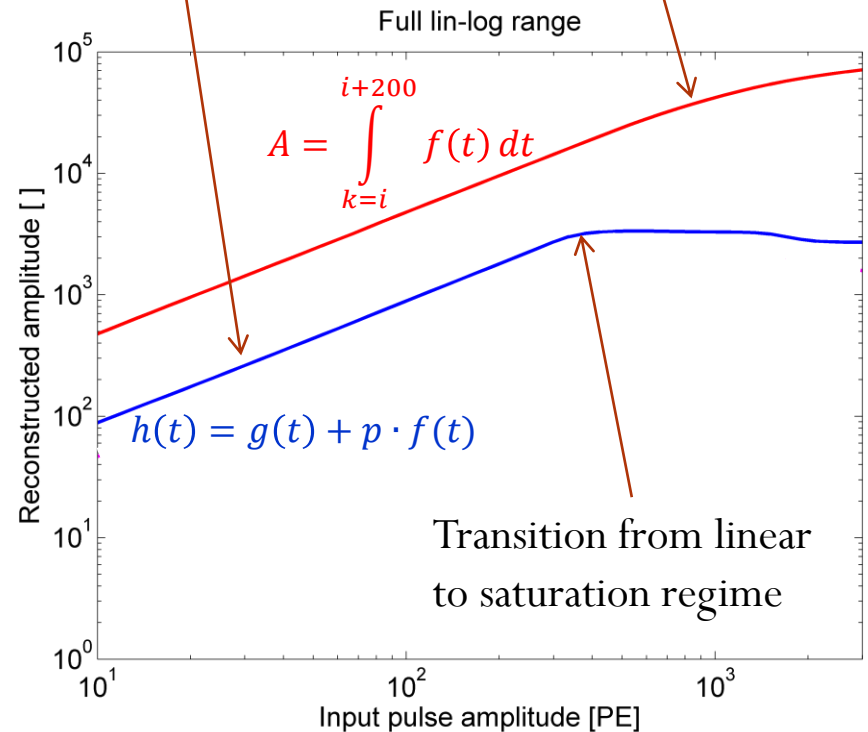
Output of preamplifier saturates while input · gain is larger than output swing. Eventually, the output recovers as saturation conditions fail.



Measured signals, resolution 1 ns / sample

Pulse amplitude reconstructed by pulse area

Pulse amplitude reconstructed by pulse maximum



Summary

- Investigation of a single signal path concept for signals with large dynamic range
- Development of signal reconstruction algorithms

- Advantages
 - Lower power consumption
 - Lower costs (everything is needed only once)
 - Digitized signals don't produce huge data streams

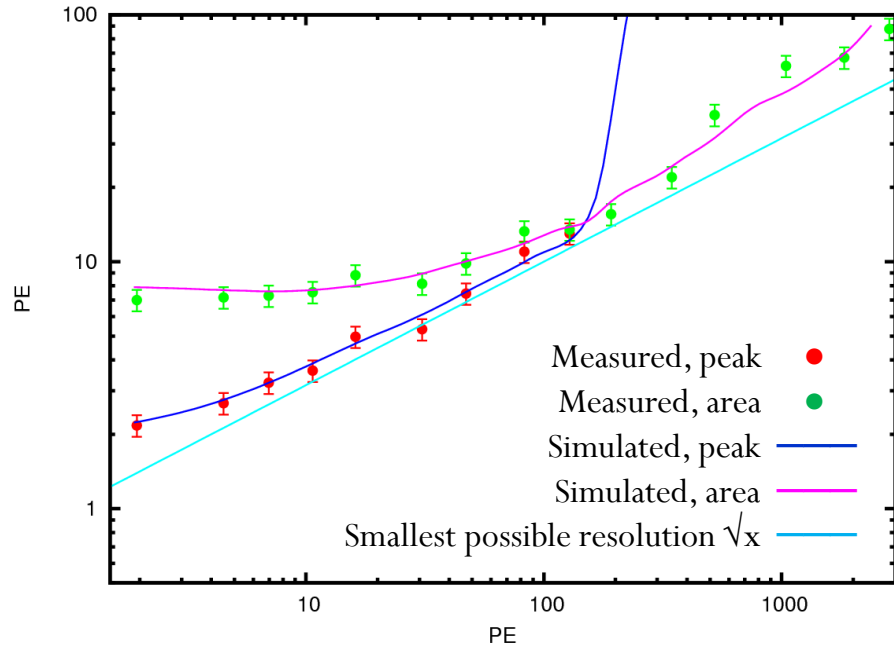
- Disadvantages
 - Amplitude and time resolution slightly worse than dual signal path concept

- Concept may be installed in first Cherenkov camera for the Cherenkov Telescope Array

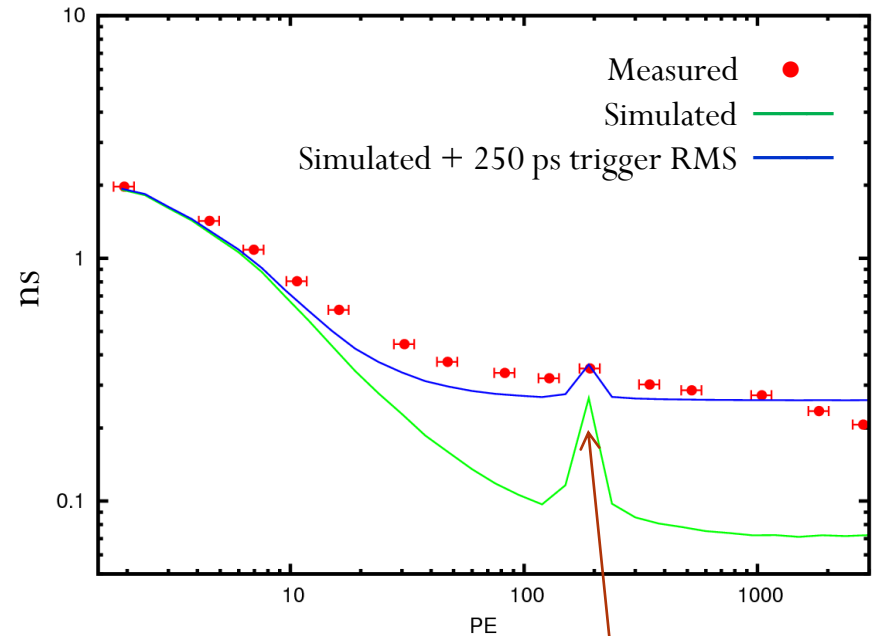
Full range resolution

Measurement of linearity with **pulsed laser**, light bulb as noise source (0.24 events / ns) and **PMT**

Amplitude resolution



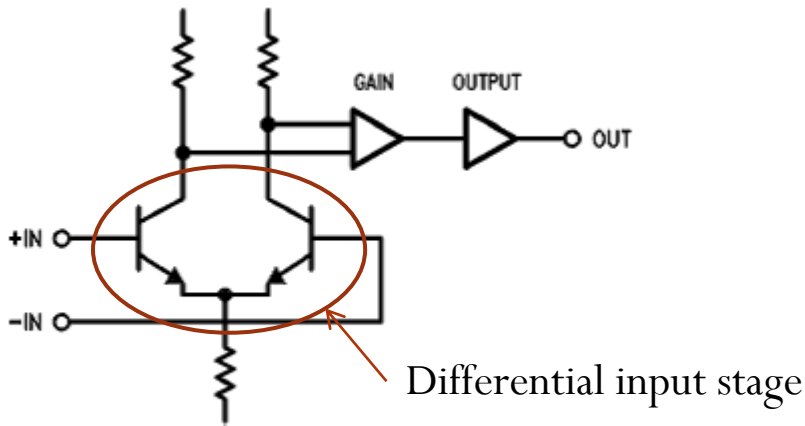
Time resolution



Transition from linear to saturation regime

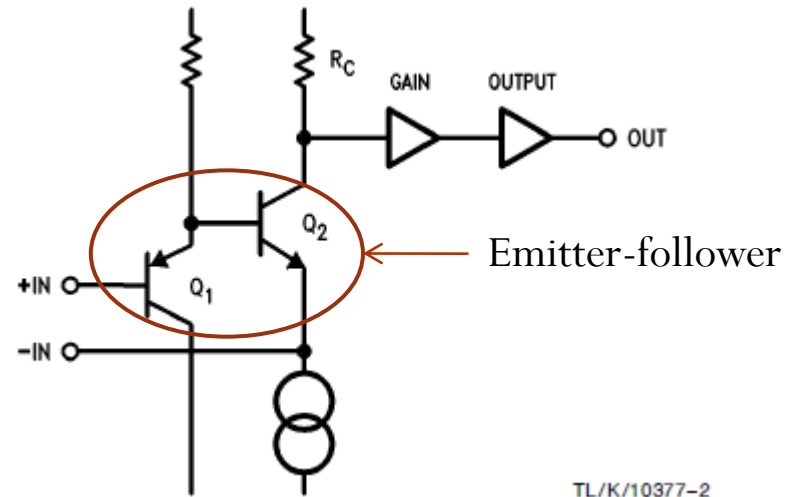
'Non-linear' amplifier

Voltage-feedback-operational-amplifier

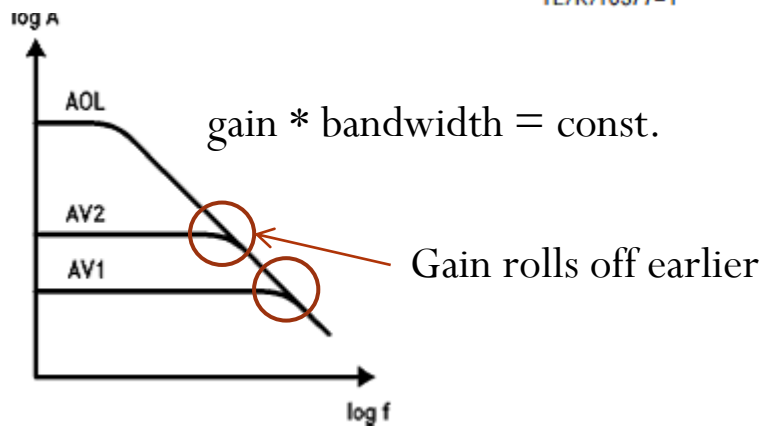


TL/K/10377-1

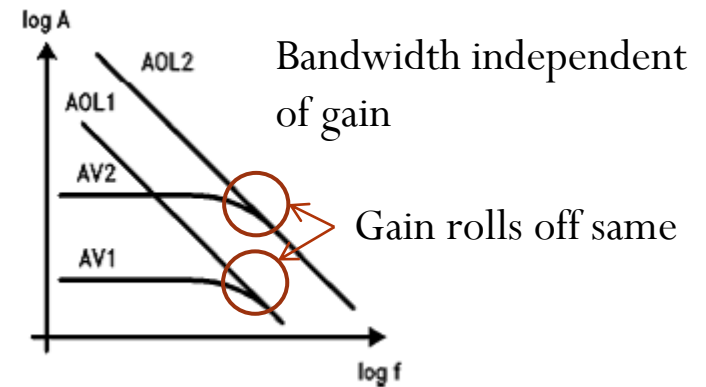
Current-feedback-operational-amplifier



TL/K/10377-2



TL/K/10377-5



TL/K/10377-6

$$\frac{U_{out}}{U_{in}} \sim \frac{1}{1 + \frac{1}{A_{OL}(j\omega)} \cdot \frac{R_F + R_G}{R_G}}$$

$$\frac{U_{out}}{U_{in}} \sim \frac{1}{1 + \frac{1}{Z_{TR}(j\omega)} \cdot R_F}$$