



CMS Tracker commissioning and first operation experience

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C. Delaere · CERN on behalf of the CMS collaboration





- Short introduction on the tracker
- Description of the program at TIF
- Strategy and results from the commissioning
 - Trigger
 - DAQ system
 - Commissioning procedure
- Results on "low-level detector performance"
 - □ Noise and S/N
 - Efficiency
 - ...
- General experience on operating the Tracker at different temperatures.

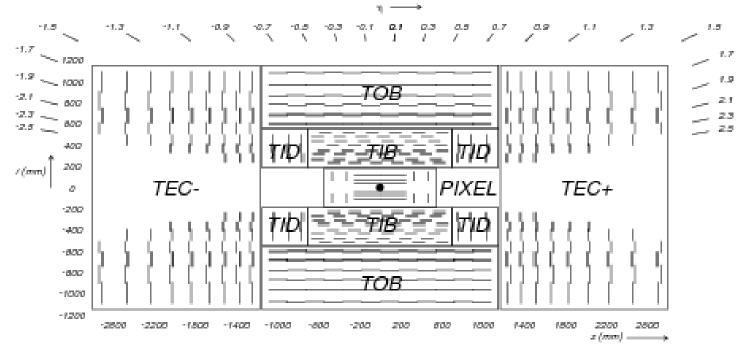
Plan

- Tracker
- Services
- Collaboration



General Layout

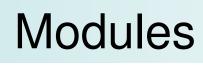




Considering only the silicon strip tracker:

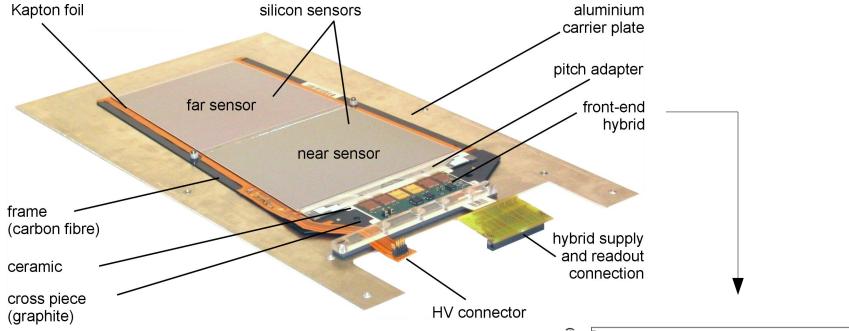
- 200 m² of silicon
- 24244 sensors (i.e. 15148 modules)
- 11'059'200 channels
- 4 subdetectors (+pixel), covers pseudorapidities $|\eta| < 2.5$
- 100 kHz readout (on L1 accept)



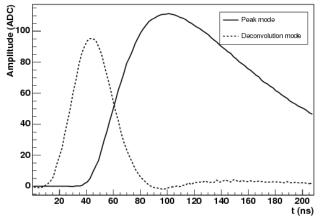




TEC module on its transport plate:



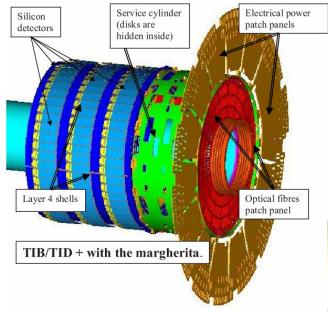
- Each module embed analog readout chips (APV25).
- It can be operated in two modes:
 - □ Peak mode : signal lasts for >100ns
 - Deconvolution mode: signal lasts for 25ns



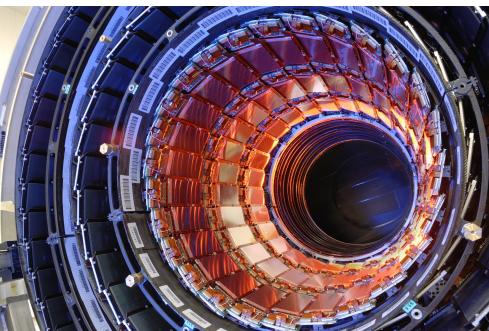


TIB/TID







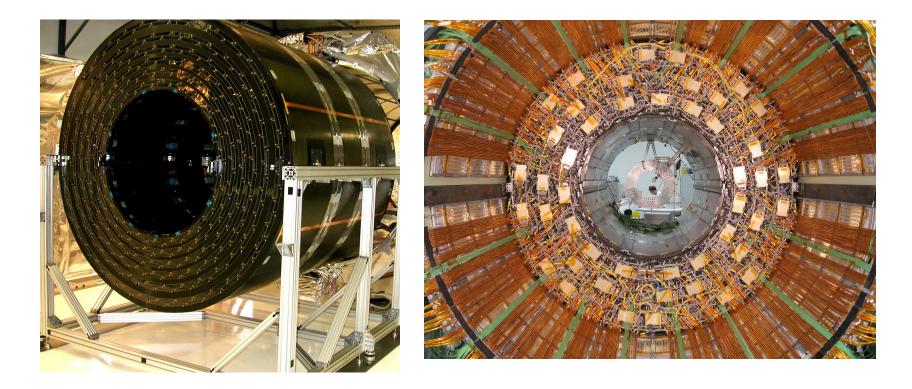




TOB



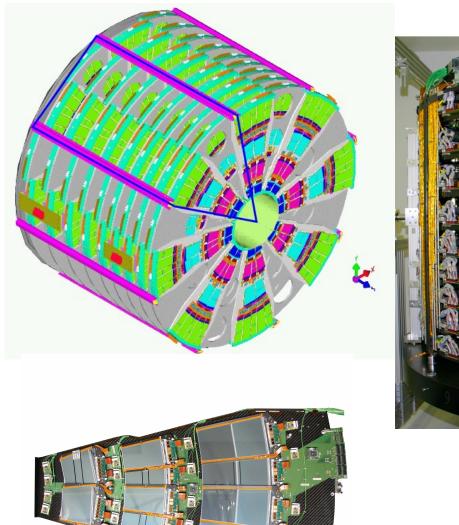


















- TIF stands for "Tracker Integration Facility"
- TIF was tremendous opportunity to gain experience with all aspects of detector operations before installation.
- Part I : Integration (from November to March)
 - At each integration step, pre-tests, survey, mechanical integration, connection, post-tests.
 - □ Installation of services (LV, HV, Detector safety, Dry air, Cooling,...)
- Part II : Warm developments (from March to May)
 - Weekdays: development of subsystems

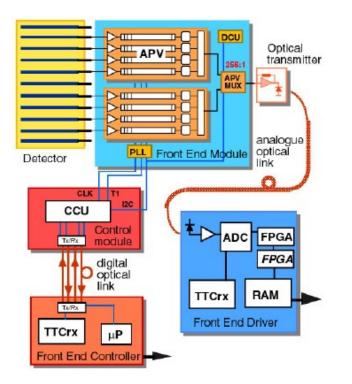
=> Operate 12.5% of the tracker

- o DAQ procedures Commissioning
- o Detector tests, noise studies, hardware fixes
- U Weekend: Cosmics
 - o Data for tracking and alignment studies
- Part III : Cold operation (from May to July)
 - □ Operation at 10°C, 0°C, -10°C and -15°C (coolant temperature)
 - o Performances and safety, temperature-dependent defaults, ...
 - □ Cosmic data and Laser Alignment at various temperatures



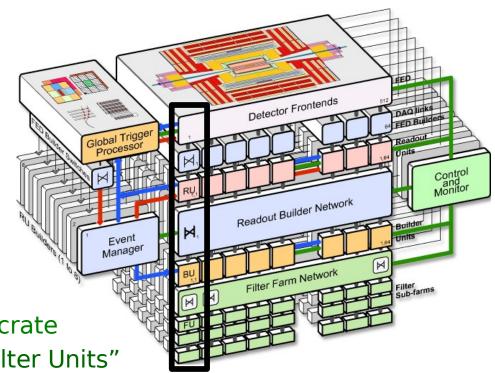
Readout and DAQ architecture





- The CMS tracker DAQ for the TIF operation mimics the final CMS DAQ
 - Distributed architecture
 - Two "Readout Units" per VME crate
 - Several "Builder Units" and "Filter Units"

- The CMS tracker readout consist of :
 - The front-end that does analog pulseshaping and optical transmission.
 - □ The **FED** that houses ADCs.
 - The FEC for clock/trigger distribution + front-end control.

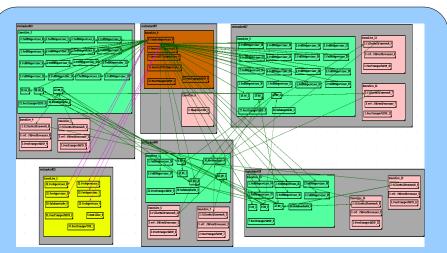




12.5% test configuration



- The 12.5% system consist of:
 - □ 65 FEDs (5188 FED channels)
 - □ 8 FECs (2161 modules)
 - 🗆 6 RU
 - 🗆 6 BU
 - 🛛 12FU
 - 1 LTC + 3 TTCci
 - 1 StorageManager



Example configuration for the 4% test. Running on 6 PCs Each box represents a process. Lines are network connections.

- It corresponds to slightly more than ½ DAQ slice (aka partition) in the final setup.
- Scales well and runs smoothly at up to 5Hz (limited by the disk write speed).

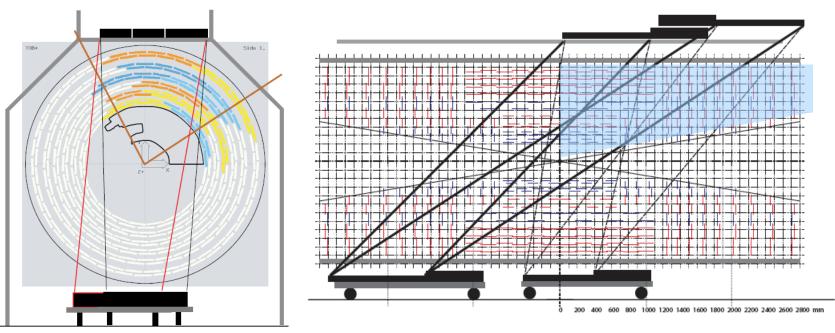


Trigger configuration



The CMS tracker requires an external trigger.

- Most of the commissioning is performed using a cyclic trigger.
- A scintillator-based cosmic trigger has been installed.



The CMS tracker requires an external trigger.

 Coincidence between scintillators above and below the tracker Trigger rate : 6.5+-0.1 Hz

• 5cm of lead installed to cut the low-energy tail.



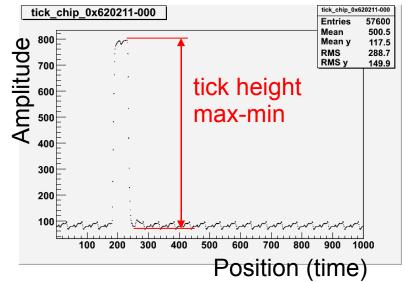
Commissioning sequence

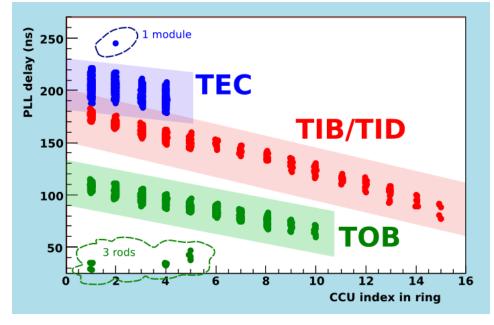


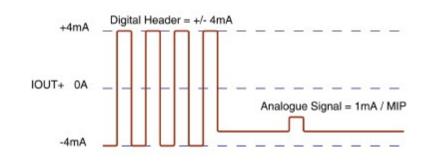
- The commissioning of the tracker is subdivided is various steps:
 - □ Control-PSM map
 - o Control the electric cabling
 - □ Control-Readout map
 - o Control the optical cabling
 - Internal Timing
 - o Synchronize the readout
 - Optical Gain
 - o Tune the amplitude of the signal
 - Analog baseline tune
 - □ Tuning the APV pulse shape
 - Pedestal and noise
 - o to be stored in the online database for later reference
 - APV latency scan
 - o find the right bunch-crossing (25ns)
 - □ Fine tuning of the pulse shape sampling
 - o tune to 1ns taking into account effects from TOF, etc.
- Lots of data has been obtained. In the following slides, I will give some selected results.











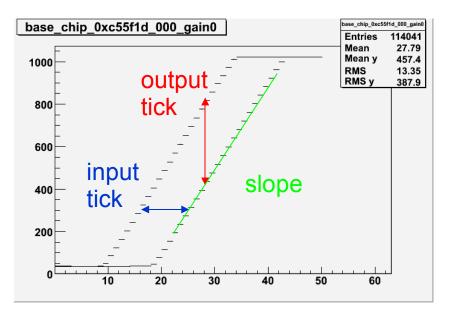
- The first data-related commissioning step deals with the internal synchronization of the tracker.
 - One programmable "phaselocked loop" delay chip on each module.
 - Accommodates for the different fiber length / electrical datapath.

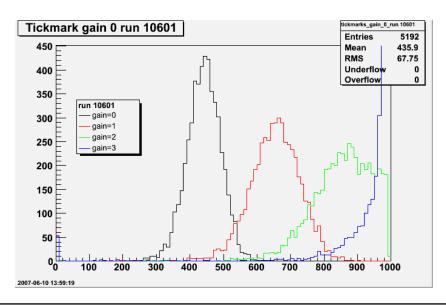


Gain scans



- Used to set the proper AOH (analog opto-hybrid) settings :
 - Laser bias,
 - Input signal scale factor.
- What is monitored :
 - Output tickmark height,
 - Generation "Slope",
 - Estimated input tickmark,
- Optimal parameters are automatically determined for each AOH.
 - Depends on the temperature.
 - Depends on the integrated fluency.

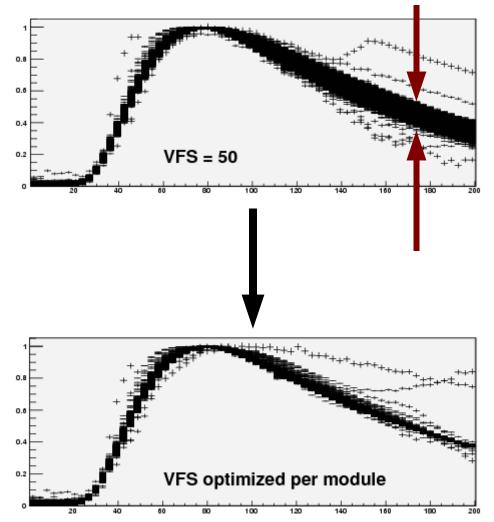






Pulse shape tune



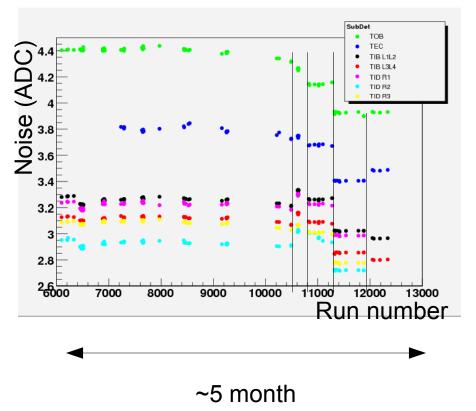


- The APV pulse shape has to be tuned for each chip:
 - Homogeneity of the tracker response
 - Guarantee performances over time
 - Reduce the systematics in dE/dx studies
 - Impact on the offline absolute calibration
 - Impact on the response to off-time particles (e.g. Stable heavy particles).
- Here one example: "VFS tune" (the shaper feedback voltage bias).



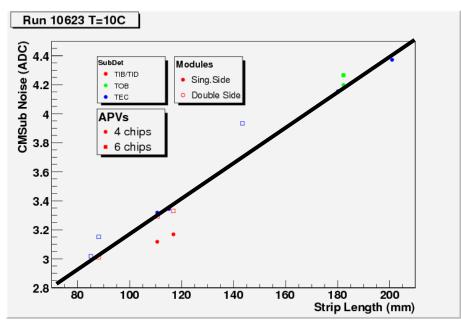
Noise study





- As expected, the noise scales with the strip length.
- Other effects (like the number of chips/module) are small.

- The noise is stable over time.
- Changes correspond to different temperature phases.
- Lower than 5 ADC in peak mode.

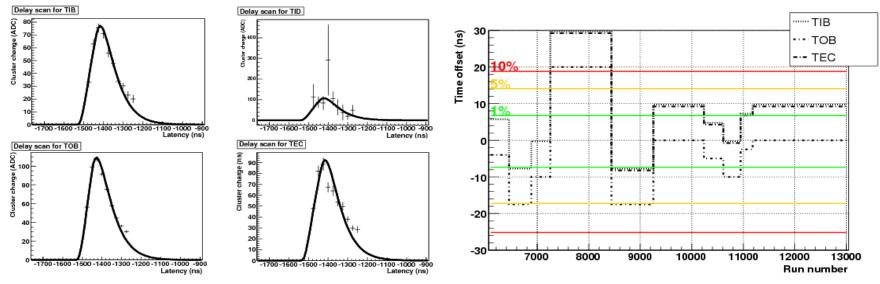




Latency



- The aim of latency scans is to be synchronized with the external trigger, i.e. to find the right bunch-crossing.
- The APV latency can be set by steps of 25ns.
- The best latency is set by reconstructing the pulse shape and by choosing the working point closest to the maximum.

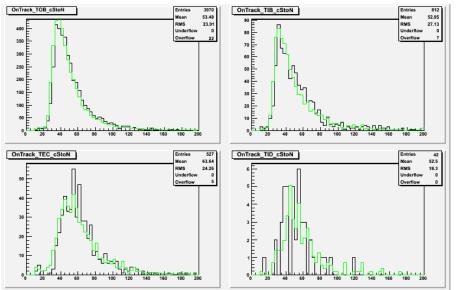


- The remaining uncertainty on S/N from synchronization on cosmics is better than 3%, after that rough preliminary tune.
- In CMS, there will be an additional "finedelay tune" to achieve a precision of 1ns.



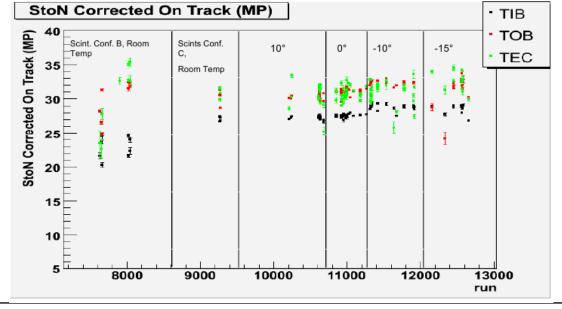
Signal to noise





- Very good S/N values are achieved:
 - □ ~27 for TIB,
 - \Box ~31 for TOB,
 - \Box ~31 for TEC.
- Very low amount of noise clusters.
- Nice Landau shape.

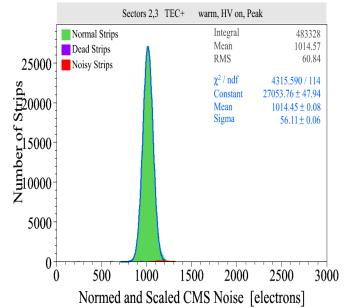
- The S/N is stable with time.
- Care has to be taken about:
 - Temperature
 - Front-end configuration
- The behavior is well understood.



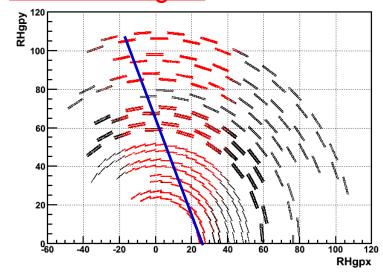


Efficiency from data

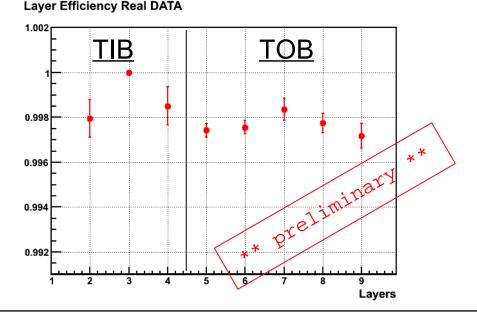




Selected Region



- The number of bad (dead or noisy) strips determined during integration is 0.2%
- The tracker efficiency has been cross-checked from data using single track events.
- Results are excellent:
 Efficiency >99.7% everywhere.



VERTEX 2007 Christophe Delaere CMS Tracker Commissioning



Experience gained



- Completed tracker maintaining high quality of production.
- Developed "Standard" DAQ/Detector Control /Data Quality tools.
- Substantial dataset to evaluate TK performance at various temperatures.
- Important "engineering" tests
 - □ Grounding scheme for all subdetectors
 - Many permutations of interference (noise) tests o TIB/TOB/TEC/FPIX, Plus versus Minus,...
 - □ Thermal performance at various temperatures
 - Laser Alignment at various temperatures
 - Zero Suppression vs Virgin Raw data
 - □ Stability of Noise, Gain, etc over time
- Cosmic Data Taking
 - □ 5,025,043 events taken
 - $\hfill\square$ Are used for tracking and alignment studies
 - o Will be presented in talks by Carten Noeding and Gero Flucke





- Developed Bookkeeping/Communication tools
 - Run Summary, Elog, Snapshot server
 - □ Run Quality flags, Data Tx and Access procedures
- Gained experience in various fields:
 - DAQ Operations, Calibration, Bookkeeping
 - Database management
 - Detector Control System performance, monitoring, archiving
 - Interlock operations, validation
 - Power Supplies System behavior, quirks
 - Data Quality Monitoring
 - Shifts and Operations
- Got the confidence that we can run the TK safely and effectively.
- New Experts!



Conclusions



- The CMS tracker has been (pre)commissioned during 6 months.
- The acquisition and commissioning software has been heavily developed/tested/extended.
- Tracker performances are excellent:
 - □ Typical S/N ~30
 - □ 0.2% Bad strips
 - □ Module efficiency >99.7%
- A large set of cosmic events has been recorded for further study.

See the talks by Carsten Noeding and Gero Flucke

- A lot of experience has been gained in operating the tracker safely and efficiently.
- Looking forward to have data as part of CMS.



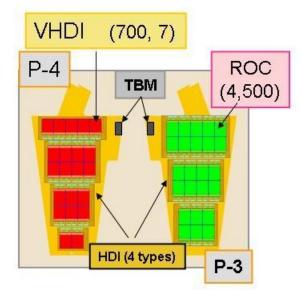
Backup slides











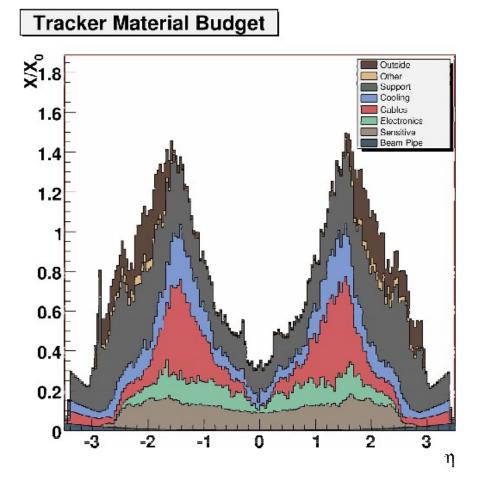


Will be covered by Mauro Dinardo.



Material budget

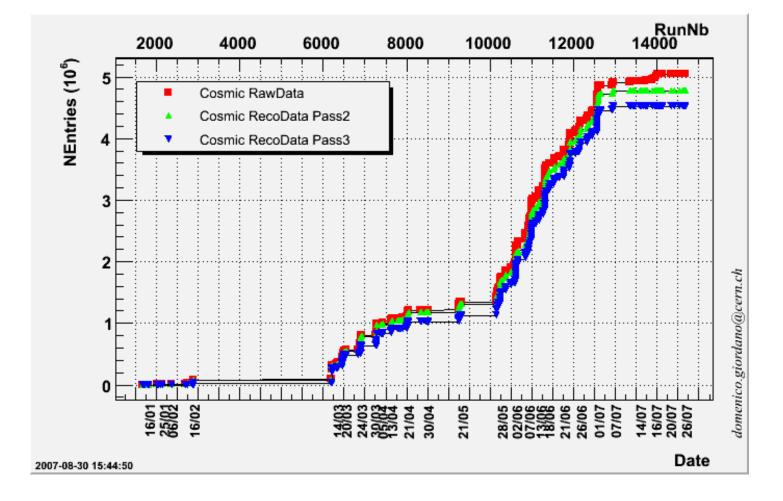






Distributed data processing







Fine delay scan



- A precision of 1ns on the detector synchronization is obtained:
 By running the detector in deconvolution mode
 By scanning PLL (on the detector front-end)
- It requires many corrections for time-of-flight, length of the readout fibers, etc.
- Will be crucial at high luminosity

