

# Particle Tracking with the SciFi Trackers

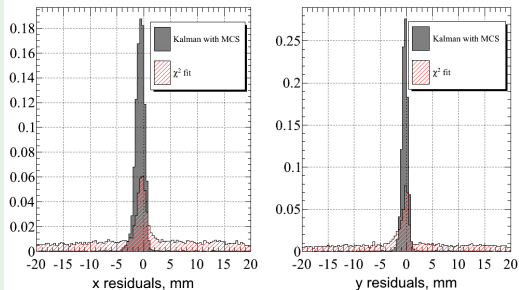
Edward SANTOS

*Supervisor: Prof. Kenneth Long*

18th October, 2012

# At CM 33...

First results with a Kalman Filter:  
straight tracks with multiple scattering.



And the promise of:

Helical Tracking;

Energy Loss;

May run analysis:

- add propagation in quadrupoles;
- link TOF's and Single Station.

# Tracking in Solenoidal Field

The equations for the propagation of the state-vector are non-linear.

- First-order expansion is required.

Doesn't care about particle ID... till MCS and energy loss are added.  
Mass is necessary.

- For now, muon assumption in the Monte-Carlo.
- Alternative would be try different mass assumptions and keep the best  $\chi^2$ .

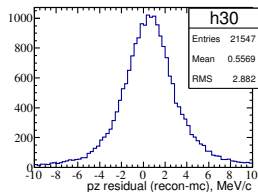
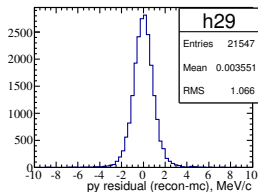
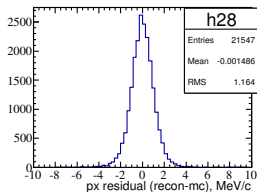
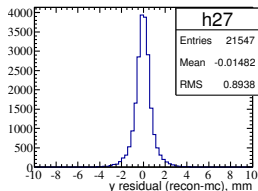
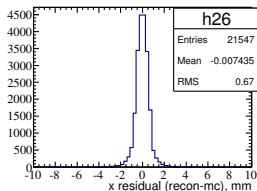
Next slide shows residuals

**Reconstruction - Monte-Carlo truth**

for  $x, y, p_x, p_y, p_z$ .

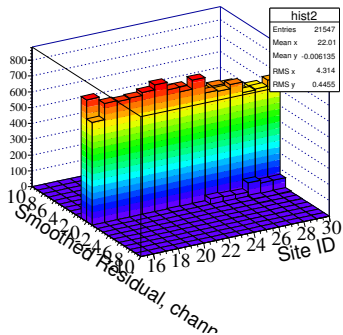
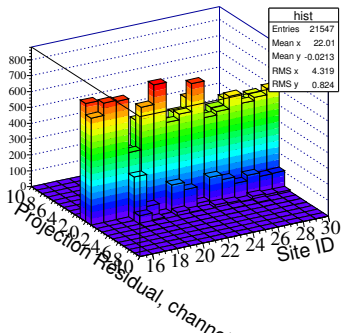
# Solenoidal Field, no corrections

## Position and Momentum residuals



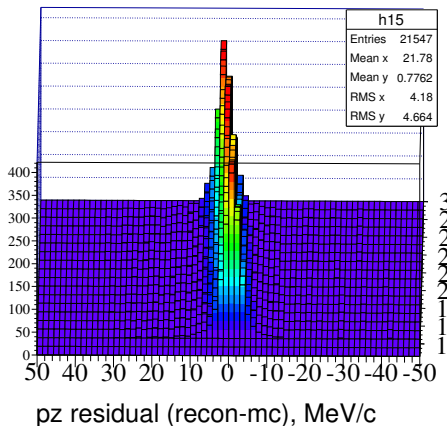
# Solenoidal Field, no corrections

Channel residuals ▶ getting your eyes ready for real data...



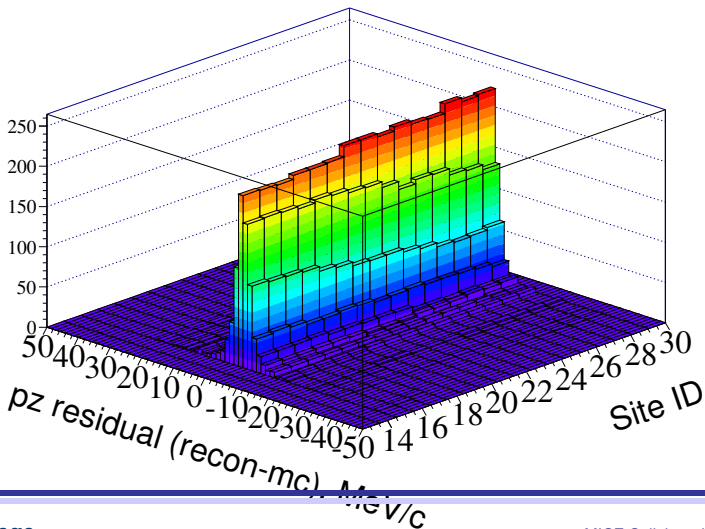
# Solenoidal Field, no corrections

$P_z$  residual shifts along the track:  $E_{loss}$  effect.



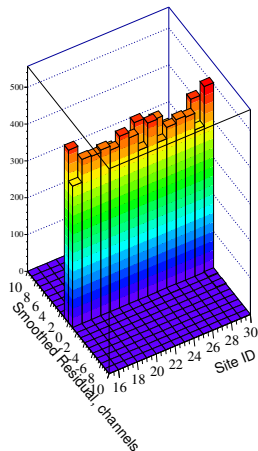
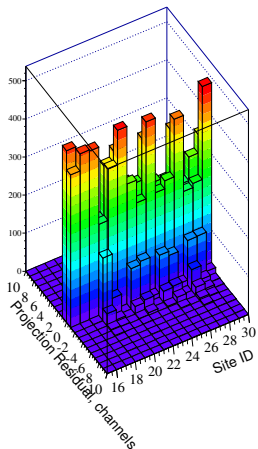
# Solenoidal Field, with MCS and $E_{loss}$

$P_z$  shift is gone.



# Solenoidal Field, with MCS and $E_{loss}$

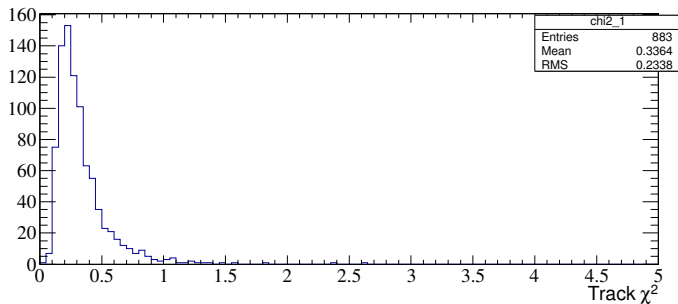
Channel residuals are improved!





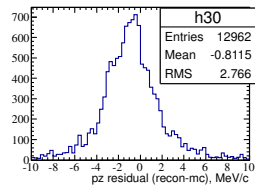
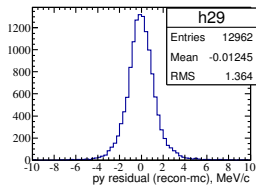
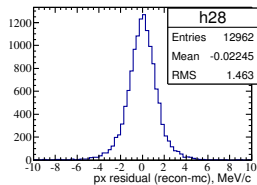
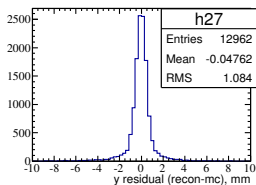
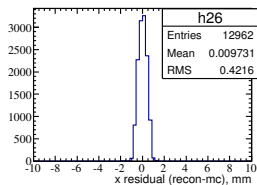
# Solenoidal Field, with MCS and $E_{loss}$

$\chi^2/ndf$  for each track



# Solenoidal Field, with MCS and $E_{loss}$

Not a closed issue. Corrections need refinement.



# TOF's + Single Station Fit

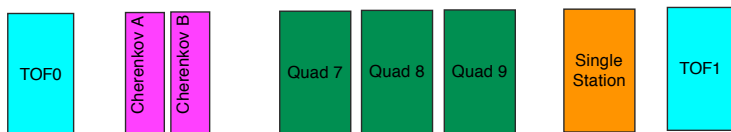
This section looks at data from runs **4102** & **4103**:

Pions, 200 MeV/c (nominal Q1-6)

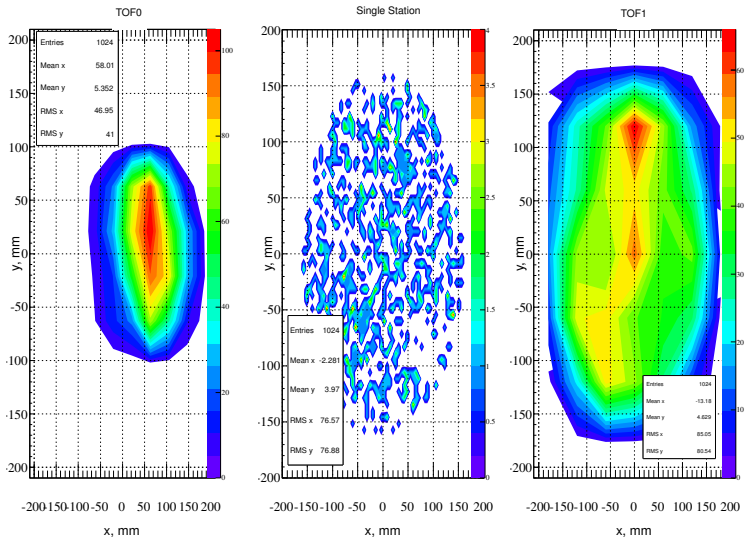
Beamline Polarity: +

Run 4102: Q7-9 off

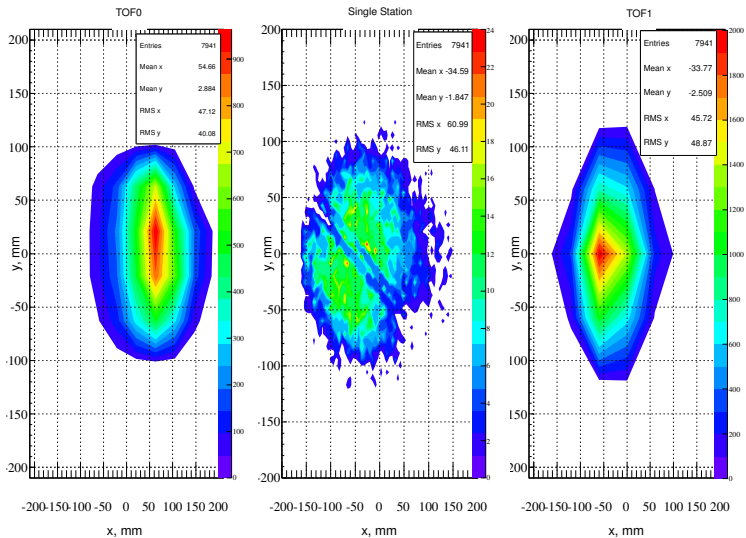
Run 4103: Q7-9 set for 200 MeV/c



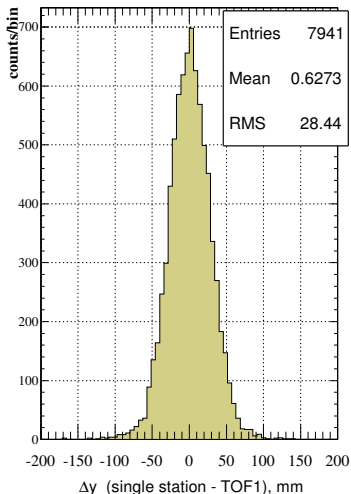
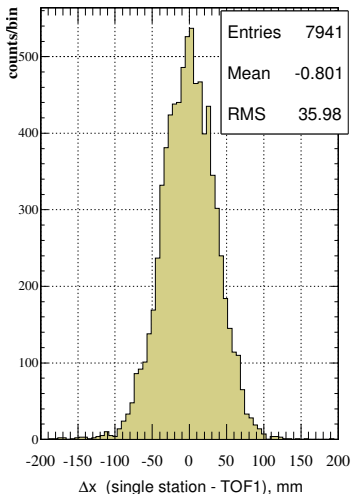
# Run 4102: Q7-9 off



# Run 4103: Q7-9 set for 200 MeV/c

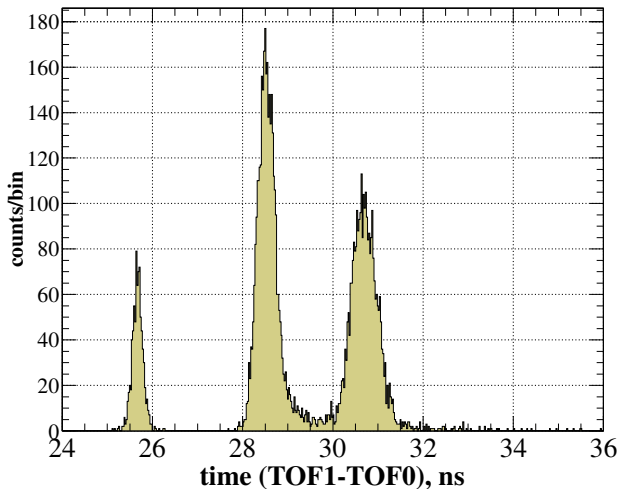


# First look at the data: do the particle positions for Single Station and TOF1 agree?

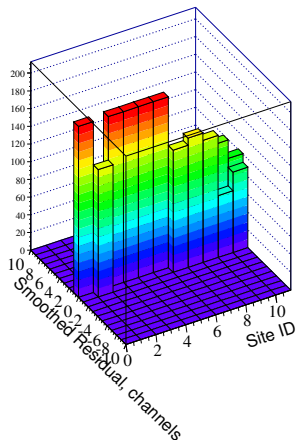
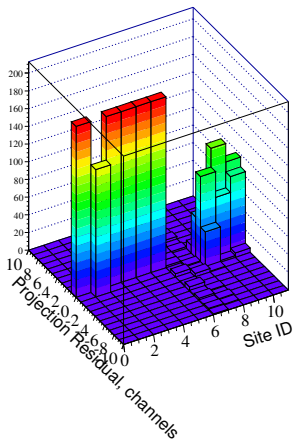


# Preparing the Filter: PID

From left to right: positrons, muons, pions.

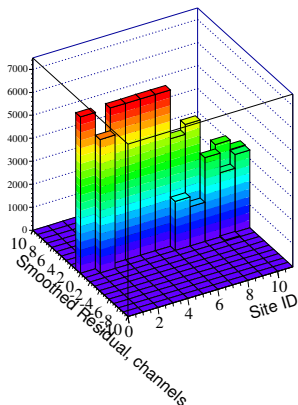
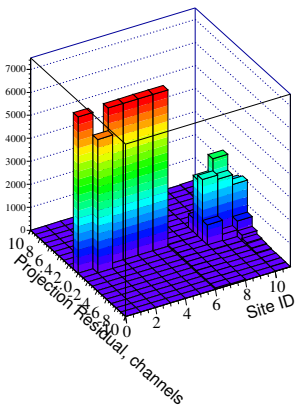


# Fitting with Quads OFF



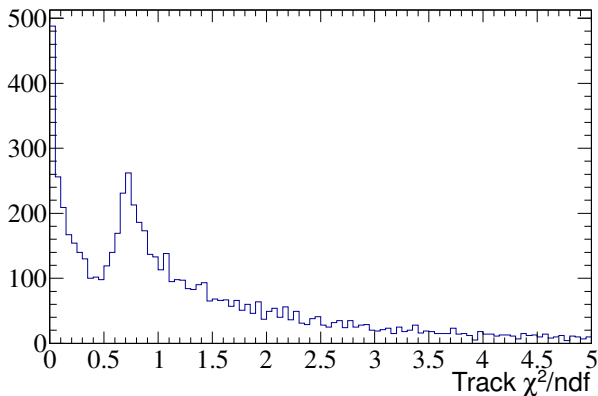


# Fitting with Quads ON



# Fitting with Quads ON

Track  $\chi^2/ndf$



# Summary

## The SciFi Kalman Track Fitting

- includes **Energy Loss** and **Multiple Scattering**;
- *needs refinement*

Can follow tracks in regions with:

- no field,
- solenoidal field;
- quadrupole field;

Work to be done:

- consider inhomogeneous magnetic fields;
- add alignment functionality.
- ...

# Acknowledgments:

Adam and Summer (SciFi Pattern Recognition)

Jason and Matt for helping on Geometry and ConfigDB

Linda for all the prompt replies pointing me on the right direction

Maria Leonova for her perfect and prompt answers to my beam line questions

Jaroslav Pasternak for the discussions on the quad drift

Yordan for help in TOF related issues.

# Backup Notes

## a word about Multiple Scattering & Energy Loss

Multiple Scattering Adds to Covariance Matrix

$$\langle x_i, x_j \rangle = \sigma^2(\theta) \left( \frac{\partial x_i}{\partial \theta_1} \frac{\partial x_j}{\partial \theta_1} + \frac{\partial x_i}{\partial \theta_2} \frac{\partial x_j}{\partial \theta_2} \right)$$

Energy loss computed from Bethe-Bloch

$$\Delta p = \int_0^L \frac{dp}{dx} dx = \int_0^L \frac{1}{\beta} \frac{dE}{dx} dx = \int_0^L \frac{A}{\beta^3} \left[ \ln \left( \frac{2m_e c^2 \beta^2 \gamma^2}{I_0} \right) - \beta^2 \right] dx$$

impacts the state vector momentum components. For a minimum ionising muon,  $\Delta p \approx 0.133 \text{ MeV}/c$  per SciFi plane.

# Track Fitting Generalities

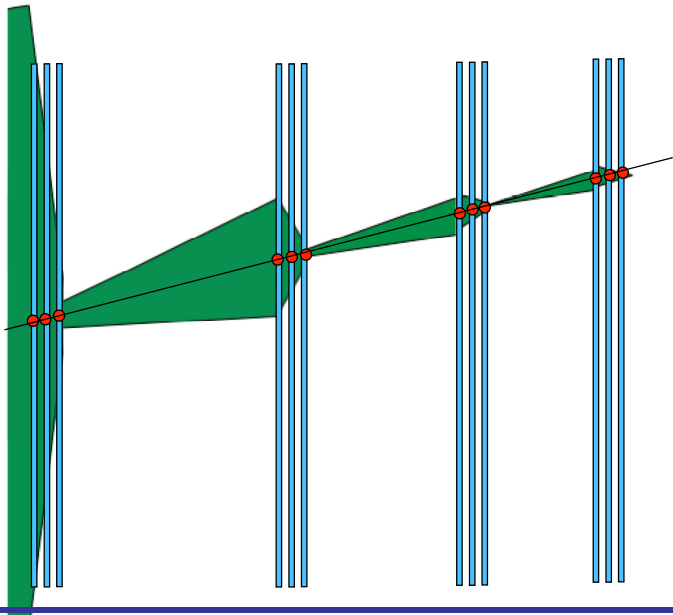
## Ingredients

a State Vector  $[x, p_x, y, p_y, 1/p_z]$ ;

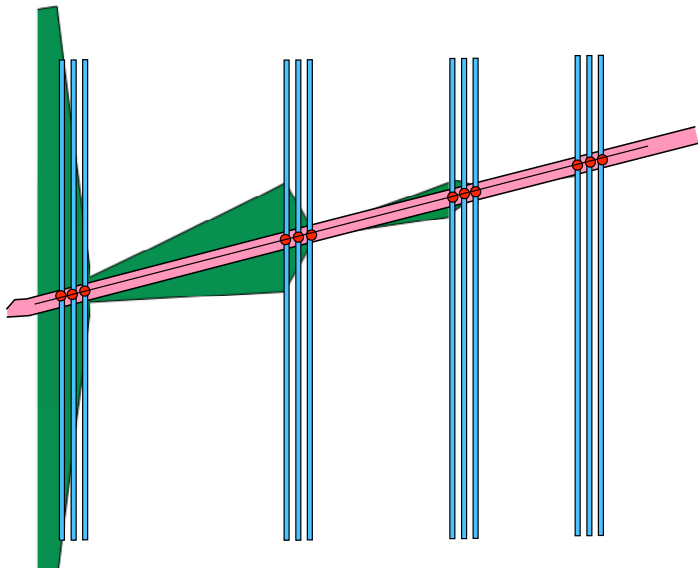
a matrix to extrapolate that state vector along the beam line (*Projection*);

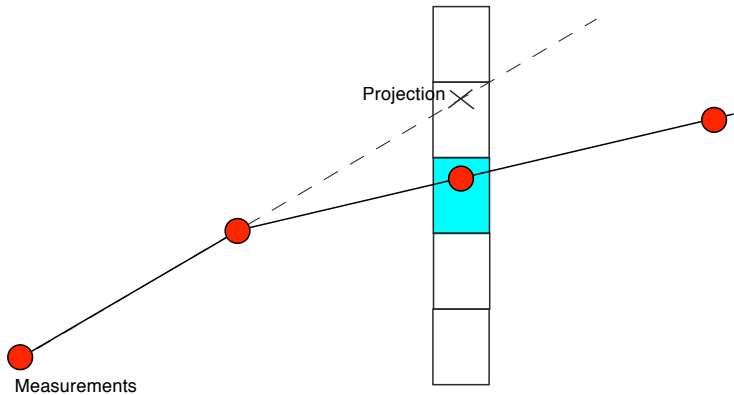
a matrix to convert state vector into "expected measurement." This is **detector dependent**.

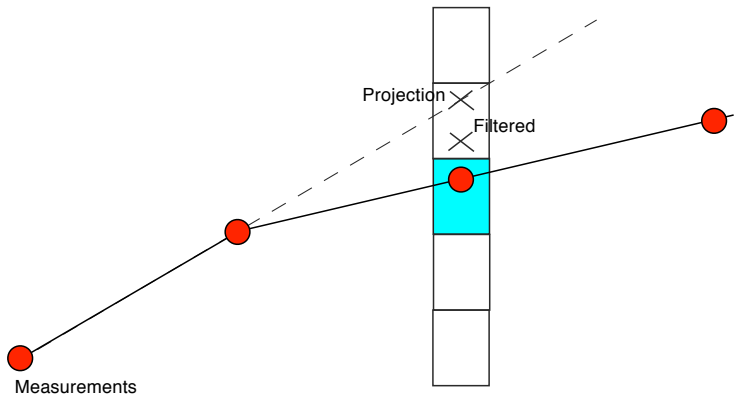
The state vector has a variance/covariance matrix associated with. It is also propagated and filtered.











▶ (go back)

