

# Summary of the WP2 Session

**F. Gaede/DESY, P. Mato/CERN**

AIDA 2nd Annual Meeting, Frascati, 10-12 April 2013

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# WP2 Goals and Tasks

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- ❖ Goals

- ❖ Develop core software tools that are useful for the HEP community at large and in particular for the next big planned projects: sLHC and Linear Collider (ILC/CLIC)

- ❖ Tasks

- ❖ Task 2.1: Coordination and communication
- ❖ Task 2.2: Geometry toolkit for HEP
- ❖ Task 2.3: Reconstruction toolkit for HEP

- ❖ Subtask coordinators

- ❖ Geometry - Gabriele Cosmo, CERN
- ❖ Tracking - Steven Aplin, DESY --> **Christoph Rosemann, DESY**
- ❖ Particle Flow - Mark Thomson, UCam
- ❖ Alignment - Chris Parkes, UniGla
- ❖ Pile-up - Lucia Silvestris, INFN

<https://aidasoft.web.cern.ch>

# Reminder: Deliverables

Deliverable Number <sup>61</sup>	Deliverable Title	Partners (lead beneficiary)	e <sup>62</sup>	Dissemination level <sup>63</sup>	Delivery date <sup>64</sup>	
D2.1	Project web infrastructure to document software packages	CERN	5.00 O	PU	3	done
D2.2	Central code repositories and other infrastructure required for the software development	DESY	5.00 O	PP	4	done
D2.3	Software design for geometry toolkit including the interfaces for the reconstruction toolkits	CERN, DESY, LLR, UniGla, STFC		PU	12	done
D2.4	Software design for tracking toolkit	DESY, CERN, OeAW, KFKI			12	done
D2.5	Software design for PFA tools	Ucam, LLR, CERN,		PU	12	done
D2.6	Design for handling the pile-up in sLHC	INFN, NTU, KFKI		PU	30 17	next
D2.7	Software toolkit for detector geometry, materials and detection technologies	CERN, DESY, LLR, UniGla, STFC		PU	38	
D2.8	Software toolkit with tracking algorithms	DESY, CERN, OeAW, KFKI			38	
D2.9	Particle Flow software tools	Ucam, LLR, CERN,		PU	38	
D2.10	Alignment tools software tools	UniGla	30.00 O	PU	38	
D2.11	Trigger simulation software tool	STFC	20.00 O	PU	38	

# Reminder: Milestones

Milestone number <sup>59</sup>	Milestone name	Partners (lead beneficiary)		Comments	
MS10	Running first prototype of the particle flow algorithm.	Ucam,LLR,CERN	10	Application to LC detector (Task 2.3)	done
MS11	Running prototype of tracking toolkit including some algorithms	DESY	18	Application to ILD-TPC simulation (Task 2.2)	done
MS12	Running prototype of the geometry toolkit	CERN, DESY, LLR	26	Application to ILD detector simulation (Task 2.2)	next
MS13	Running prototype of the tracking code for the pile-up	INFN, NTU, KFKI	26	Application to sLHC simulation (Task 2.3)	next
MS14	Integration of tracking toolkit into LC software framework	DESY, CERN, OeAW	44	Validation of physics performance (Task 2.3)	
MS15	Application of PFA tools to sLHC detectors	Ucam, LLR	44	Demonstration of concept (Task 2.3)	
MS16	Application of alignment tools to sLHC	UniGla	44	Validation of performance (Task 2.3)	
MS17	Integration of pile-up tracking code in sLHC software frameworks	INFN, NTU, KFKI		Validation of tracking efficiency (Task 2.3)	

# Agenda of WP2 Session

10 talks covering  
all tasks and sub-  
tasks of the WP2  
work package

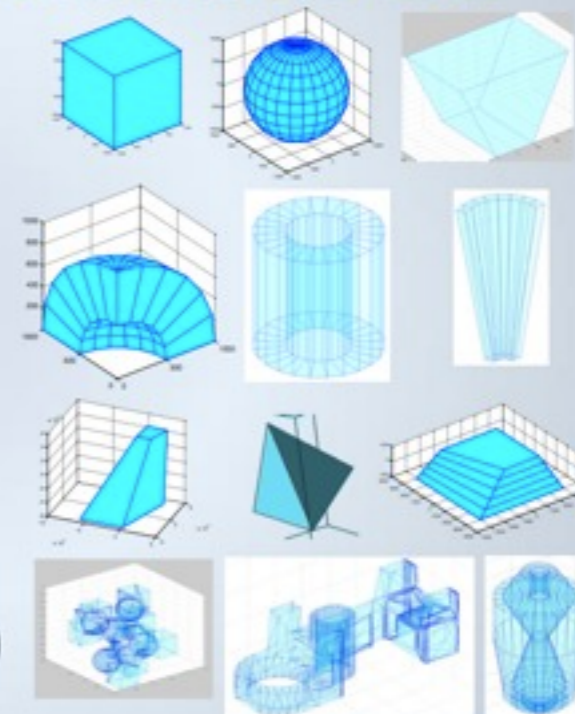
	<b>Introduction</b>	<i>Frank-Dieter GAEDE</i>	
	<i>Aula Seminari, LNF Bldg 36</i>		09:30 - 09:40
	<b>Development status of USolids Library</b>	<i>Marek GAYER</i>	
	<i>Aula Seminari, LNF Bldg 36</i>		09:40 - 10:00
10:00	<b>Status of DD4Hep</b>	<i>Markus FRANK</i>	
	<i>Aula Seminari, LNF Bldg 36</i>		10:00 - 10:20
	<b>New Developments for Mokka</b>	<i>Vincent BOUDRY</i>	
	<i>Aula Seminari, LNF Bldg 36</i>		10:20 - 10:40
	<b>Status of Pile Up Task</b>	<i>Lucia SILVESTRIS</i>	
	<i>Aula Seminari, LNF Bldg 36</i>		10:40 - 11:00
11:00			
	<b>New Developments for Particle Flow</b>	<i>Prof. Mark Andrew THOMSON et al.</i>	
	<i>Aula Seminari, LNF Bldg 36</i>		11:30 - 11:50
12:00	<b>Status of Tracking task</b>	<i>Christoph ROSEMANN</i>	
	<i>Aula Seminari, LNF Bldg 36</i>		11:50 - 12:10
	<b>Status of (LHCb) Alignment</b>	<i>Christoph HOMBACH</i>	
	<i>Aula Seminari, LNF Bldg 36</i>		12:10 - 12:30
	<b>Clustering, energy loss, and vertexing tools for Si detectors</b>	<i>Ferenc SIKLER</i>	
	<i>Aula Seminari, LNF Bldg 36</i>		12:30 - 12:50
13:00	<b>tkLayout - A Tracker Layout Modeling Tool"</b>	<i>Dr. Jelena ILIC</i>	
	<i>Aula Seminari, LNF Bldg 36</i>		12:50 - 13:10
	<b>PFA activities at LLR</b>	<i>Manqi RUAN et al.</i>	
	<i>Aula Seminari, LNF Bldg 36</i>		13:10 - 13:30

# Unified Solids

- ❖ Goals
  - ❖ Optimize and guarantee better long-term maintenance of ROOT and Geant4 solids libraries (about 70-80% of code investment for the geometry modeler concerns solids)
  - ❖ Get the best of each implementation
- ❖ Huge work done evaluating CPU performance, precision and robustness (stress testing) of each basic 3D shape
- ❖ In particular:
  - ❖ Multi-union
  - ❖ Tessellated Solid
  - ❖ Polycone

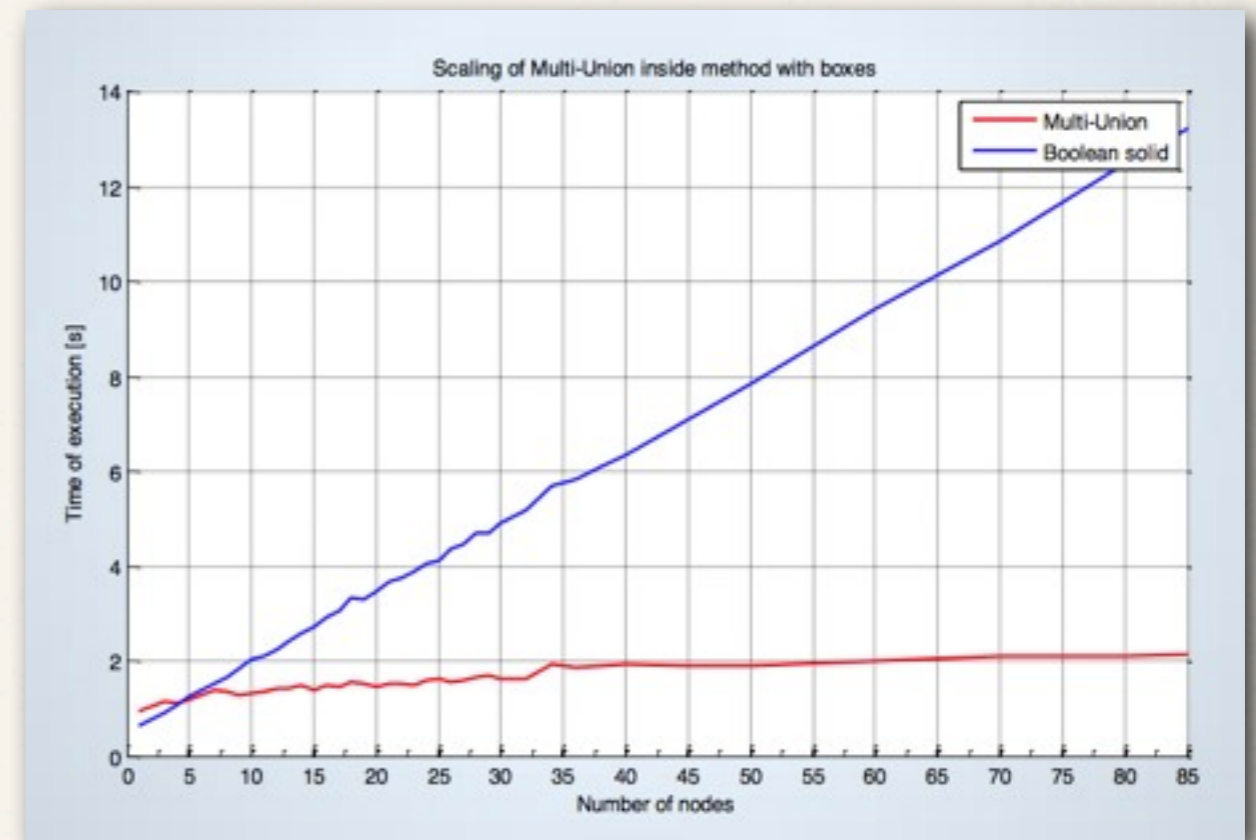
## Solids implemented so far

- Box
- Orb
- Trapezoid
- Sphere (+ sphere section)
- Tube (+ cylindrical section)
- Cone (+ conical section)
- Generic trapezoid
- Tetrahedron
- Arbitrary Trapezoid (ongoing)
- **Multi-Union**
- **Tessellated Solid**
- **Polycone** (close to be finished)



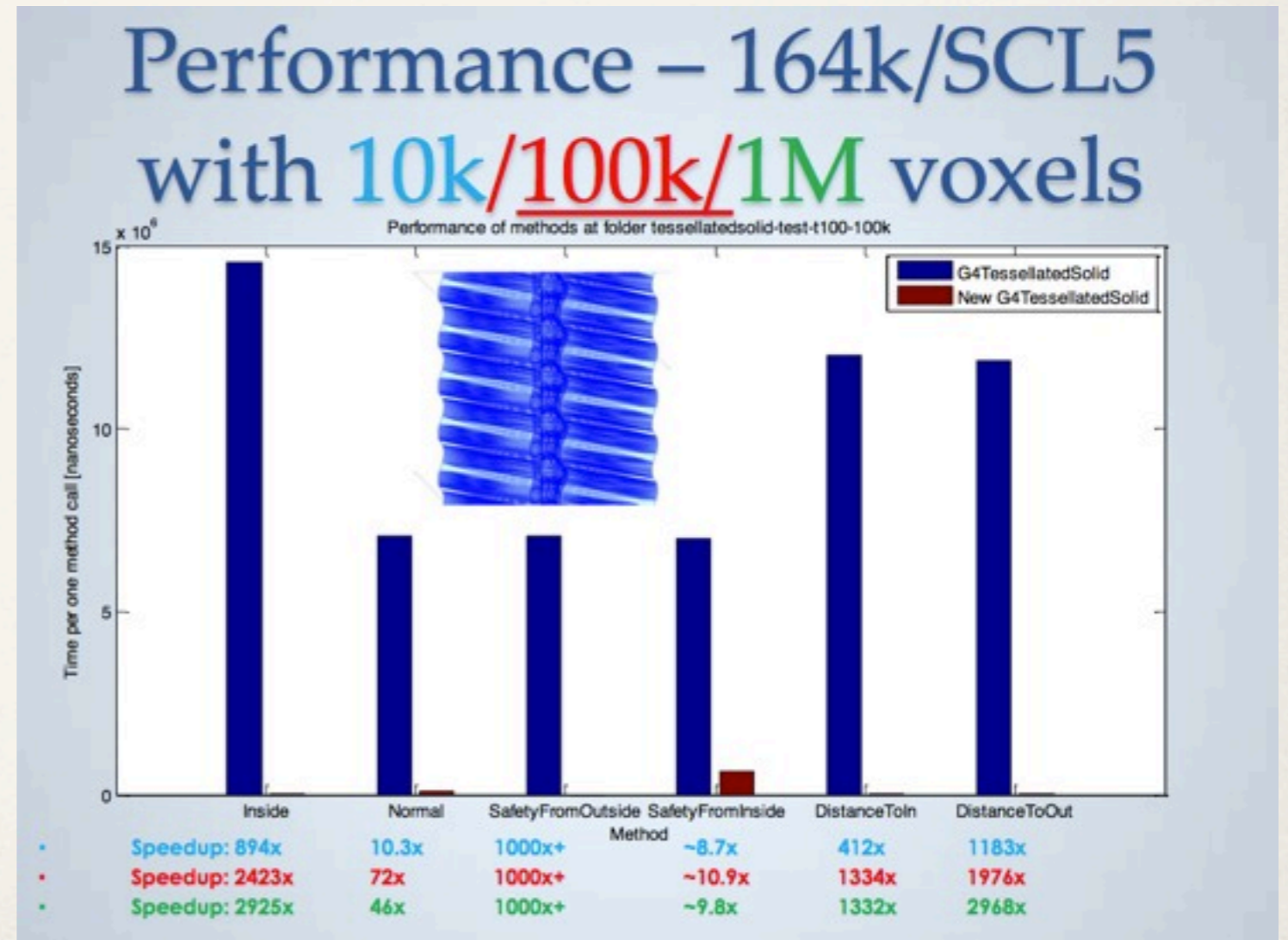
# Multi-Union

- ❖ Existing CSG Boolean solids (ROOT and Geant4) are represented as binary trees
  - ❖ Linear performance
- ❖ Implemented a new solid as a union of many solids using voxelization technique to optimize speed and scalability
  - ❖ 3D space partition for fast localization of components
  - ❖ Aiming for a  $\log(n)$  scalability
- ❖ Useful for complex composites made of many solids



# Tessellated solids

- ❖ Connected triangular and quadrangular facets forming solid
- ❖ Old implementation was slow, no spatial optimization
- ❖ We use spatial division of facets into 3D grid forming “voxels”
- ❖ Factor thousands faster for LHCb provided foil test case (164k facets)
- ❖ Implemented in Geant4 9.6 as G4TesselatedSolid
- ❖ Total memory save is about ~50%

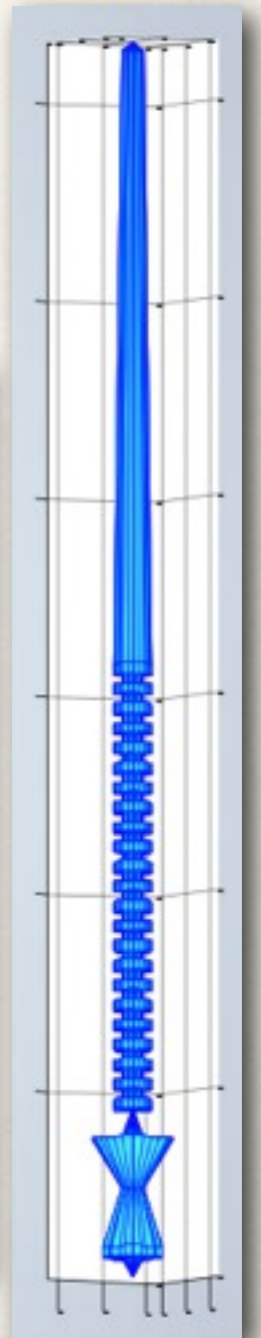
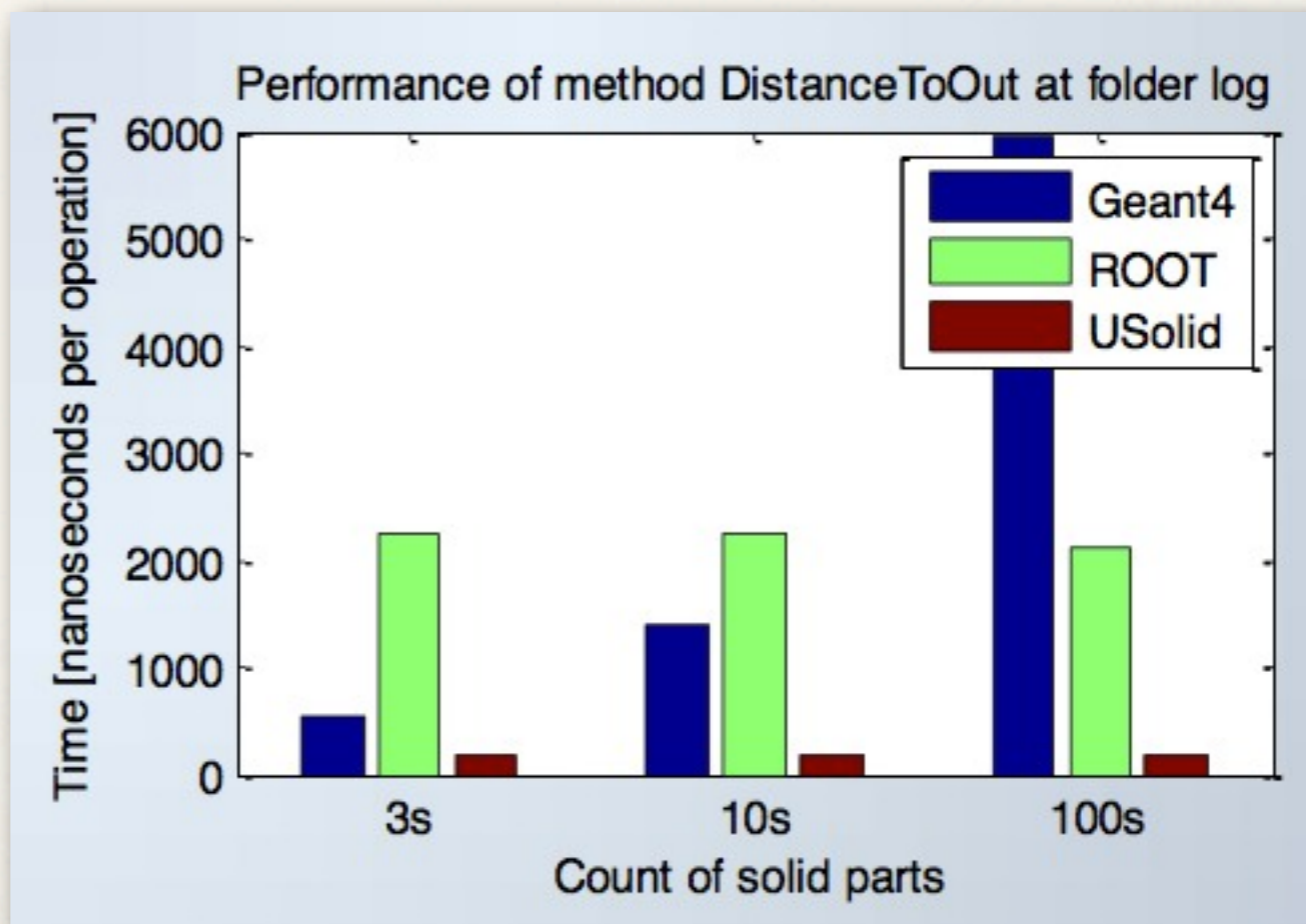




# Polycone

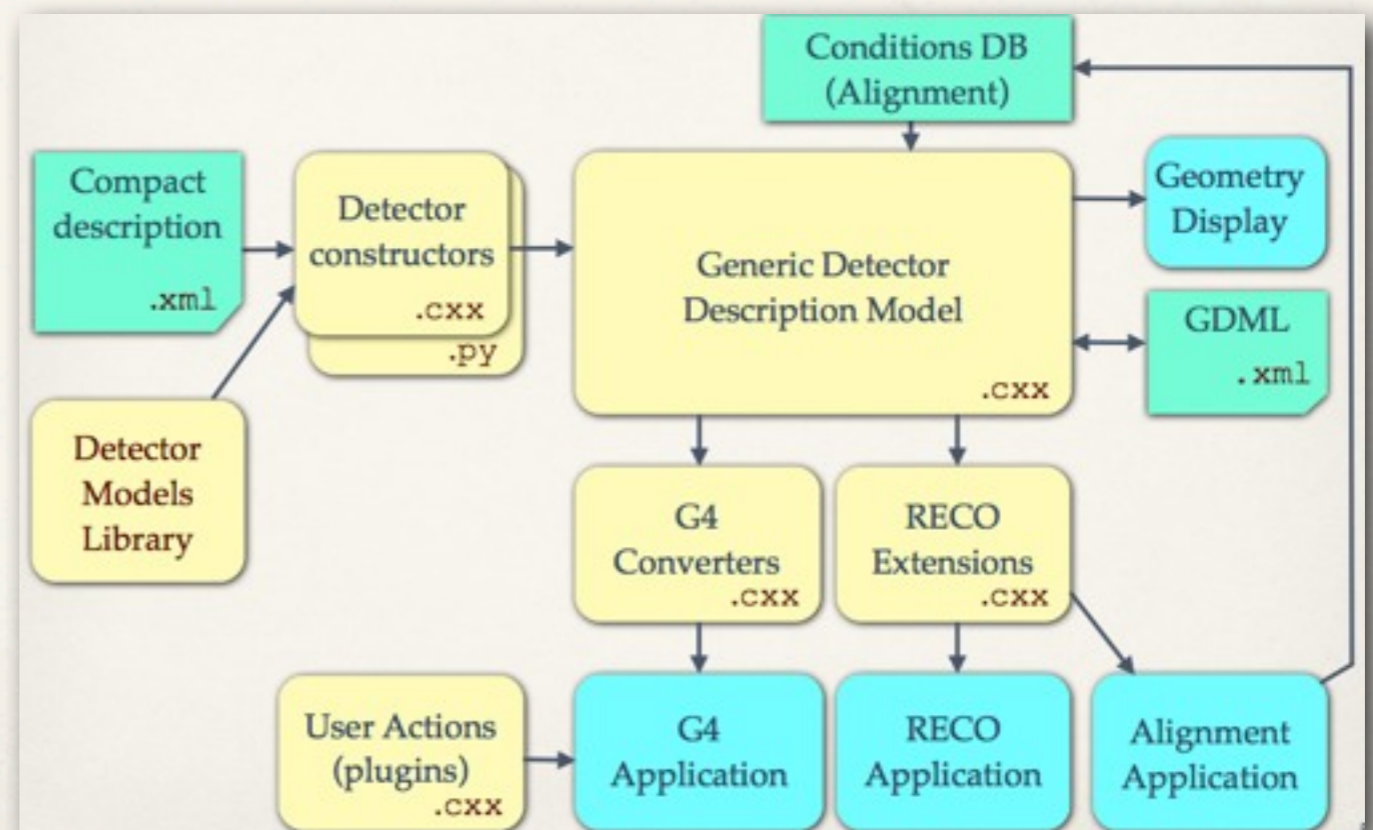
- ❖ Polycone is an important solid, heavily used in most experimental setups
- ❖ Implementation based on composition of separate instances of cones, tubes (or their sections)
- ❖ Significant performance improvement over Geant4 & ROOT

Work will continue with the remaining most critical solids  
Change over



# DD4Hep

- ❖ Development of detector description toolkit
  - ❖ **For the full experiment life cycle** (design, construction, operation)
  - ❖ **Consistent description with single source** (simulation, reconstruction, analysis)
  - ❖ **Full description** (geometry, readout, alignment, etc.)
- ❖ Main components of the toolkit and design choices
  - ❖ Detector Element
  - ❖ Compact descrip. (XML)
  - ❖ Based on TGeo (ROOT)
  - ❖ Converters and adaptors
  - ❖ Data + Behaviour



# DD4Hep: Reconstruction Extensions

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- ❖ Client ‘extensions’ and specialized ‘views’
  - ❖ Customize a Detector Element object to support specific reconstruction questions and cached data
- ❖ Example: TPC (A.Muennich)
  - ❖ The “PadLayout” is retrieved from the detector element if present
- ❖ Adding an extension is possible anywhere
  - ❖ Extensions are not confined to detector constructor
  - ❖ Could also be somewhere in the reconstruction code

# Geant4 Gateway

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- ❖ Conversion of the Generic Geometry to Geant4 geometry.  
Two approaches:
  - ❖ **In Memory Translation to Geant4**
    - ❖ This processing chain was implemented
    - ❖ Requires additional development of *sensitive detectors*
  - ❖ **Generate GDML** (with lccd extensions) to be compatible with SiD simulation application 'slic'
    - ❖ Approach taken by LCD at the last software workshop
    - ❖ Re-use treatment of *sensitive detectors*
    - ❖ Mokka (LCD simulation) would need to be migrated

# Adaptation of Mokka to DD4Hep

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- ❖ Mokka detector parameters stored a MySQL DB
  - ❖ Many sub-detectors, versions and options (~323 versions in total)
  - ❖ Need to be extracted and formatted in DD4Hep XML files
- ❖ Mokka 'drivers' to construct detectors in Geant4
  - ❖ Need to be translated into 'DD4Hep' detector constructors (Python or C++ code snippets)
  - ❖ Collaborative effort required (identify contact people)
- ❖ Review of sensitive detectors
  - ❖ Collaborative effort required (identify contact people)

# Pile-up Sub-task

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- ❖ Development of a toolkit to handle high multiplicity events
  - ❖ Main motivation:
    - ❖ pile up in sLHC will increase with respect to “nominal (2011) LHC”
    - ❖ requires a more efficient way to manage high particle multiplicity events (CPU and Memory)
    - ❖ Aiming for a set of generic and reusable algorithms / functions
- ❖ In CMS enters in **Mixing Module** (Simulation) and **Tracking Module** (Reconstruction)
  - ❖ So far the work has been based on CMSWS (CMS Framework)

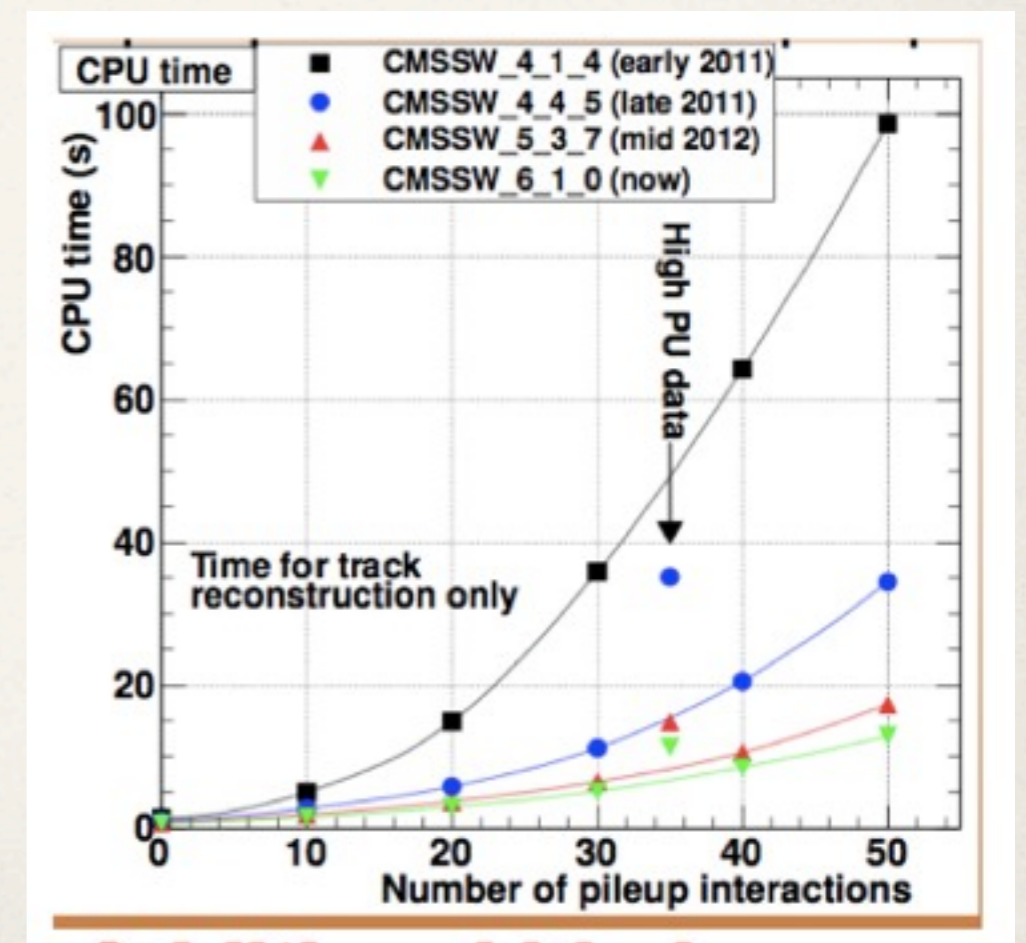
# CMS Improvements 2011-2013

- ❖ Mixing Module

- ❖ Mixing module superimpose pileup events to a signal event
- ❖ Memory limited: max 300 events with 2GB / core
- ❖ Keep the memory under 2 GB / core with 140 pile-up events and 5 bunch crossing (700 events)

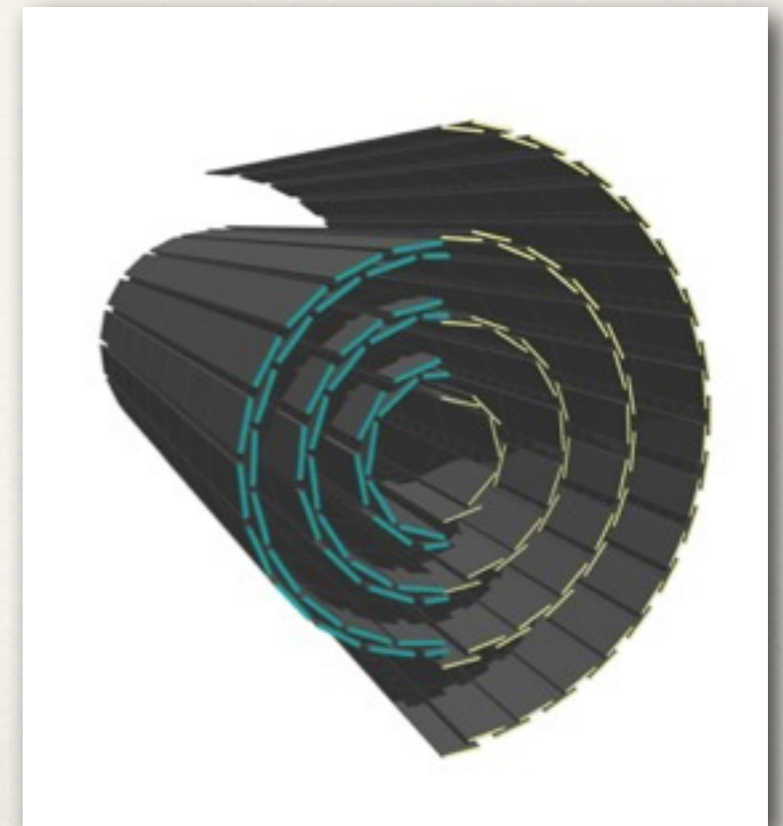
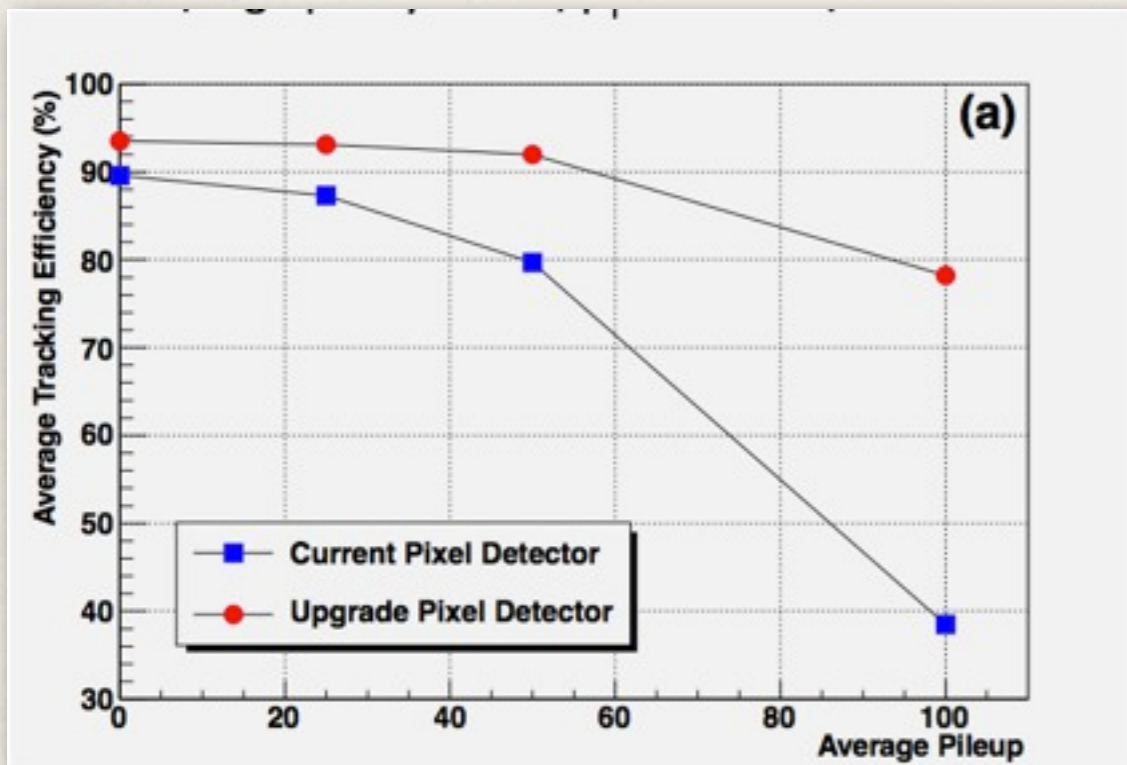
- ❖ Tracking

- ❖ CPU powerN increase with number of pileup interactions
- ❖ Several optimization campaigns has bring the CPU to reasonable levels



# CMS Strategies for 2015 and Phase 1

- ❖ **Generic improvements** as in 2011 / 2012 (smarter coding, compilers, seed cleaning) and iterative tracking tuning | tracking developers
- ❖ Tracking code reengineering; major redesign of the tracking code to implement **parallelization and vectorization**
- ❖ **New tracking algorithms** (Hough transform)
- ❖ Work done CMS Pixel @ Phase 1





# Future Activities

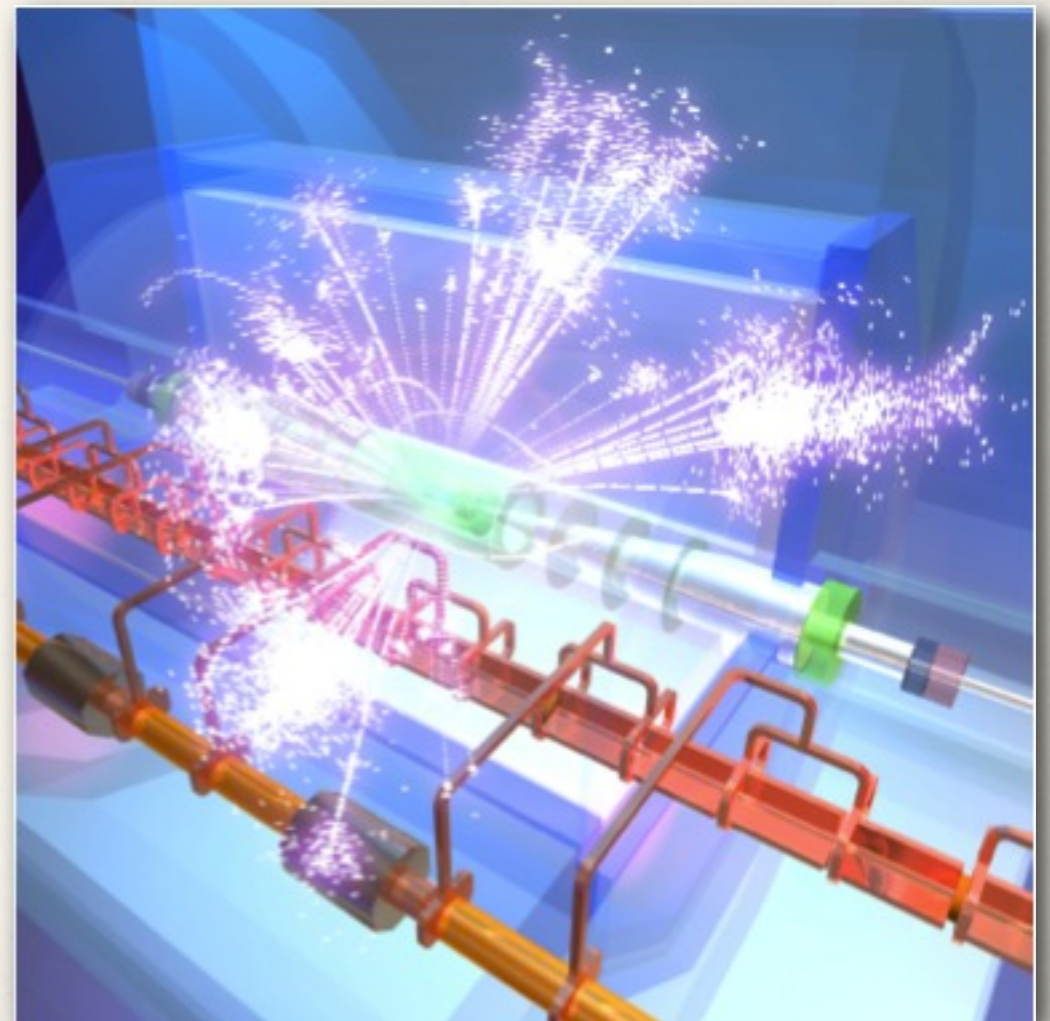
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- ❖ New person fully dedicated to AIDA project will be hired (April-May 2013)
  - ❖ Fully involved in the tracking code developing for 2015 data taking and phase 1 and phase 2 preparation
  - ❖ Deliverable 2.6
- ❖ Identify components that need to be optimized and / or redesigned
- ❖ Start the iterative procedure for each component according to the priority list (from August 2013)
  - ❖ Integration into the CMSSW
  - ❖ Validation of the Physics performance

# Particle Flow Calorimeter

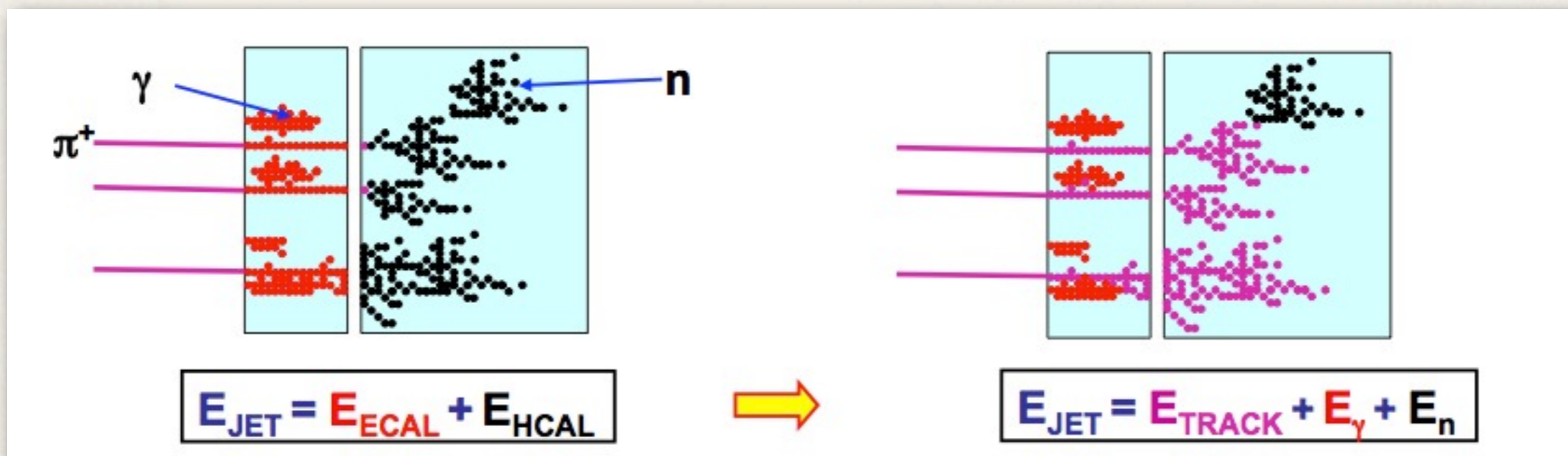
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- ❖ Cambridge
  - ❖ Framework
  - ❖ Algorithm development / optimisation
- ❖ CERN
  - ❖ extensive validation
  - ❖ performance benchmarking
- ❖ LLR
  - ❖ algorithm development




# Particle Flow Ingredients

- ❖ Goal
  - ❖ Improved energy resolution
- ❖ Requires
  - ❖ Highly granular detector
  - ❖ Sophisticated reconstruction software




# AIDA work

- ❖ PandoraPFA initially very focussed on ILC reconstruction
- ❖ Evolved to generic, fast implementations, easy adaptable (plugins), decoupled from geometry toolkit



## PandoraPFA



- ★ PandoraPFA initially very focussed on ILC reconstruction
- ★ Initially code developed in “physicist style”
  - resulted in single use-case unmanagable “**rat’s nest**”
- ★ AIDA funded work has enabled this to be developed into a genuine **Framework** for particle flow

**Redesign**

➔

**Implementation**

➔

**Generalisation**

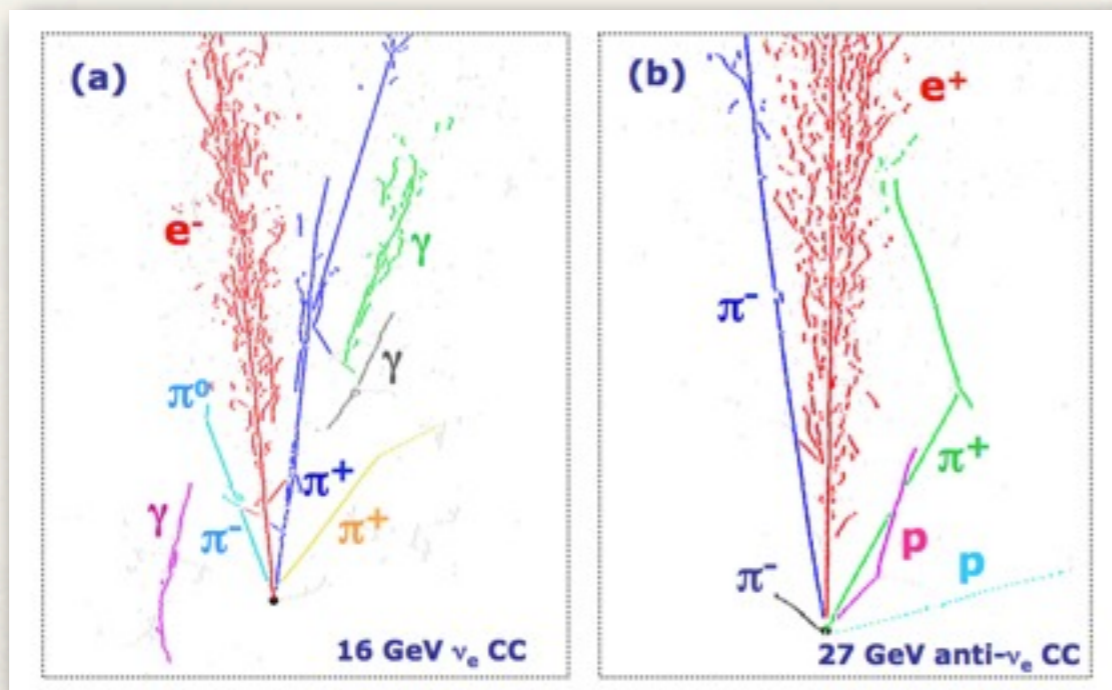
Software engineering

Coding

Development through multiple use cases

# PandoraPFA Applications

- ❖ Generalization
  - ❖ Fine Granularity calorimetry
    - e.g. LC detectors
  - ❖ Coarse Granularity calorimetry
    - e.g. LHC detectors
  - ❖ Liquid Argon reconstruction
    - Neutrino physics



## CALICE application

★ CERN developed client to PandoraPFA for CALICE test beam  
e.g. 80 GeV pion test beam

★ Worked out of the box...  
★ "Generic" but this is an LC calorimeter prototype...

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## Neutrino Physics

★ Liquid Argon TPCs likely to form basis of future neutrino oscillation experiments

★ Large volume detectors with ~1mm<sup>3</sup> granularity

- i.e. Fine Granularity calorimeters

★ Long standing problem

- lack of automated reconstruction software
  - non-trivial – large numbers of hits
  - applications often run into memory/CPU limitations

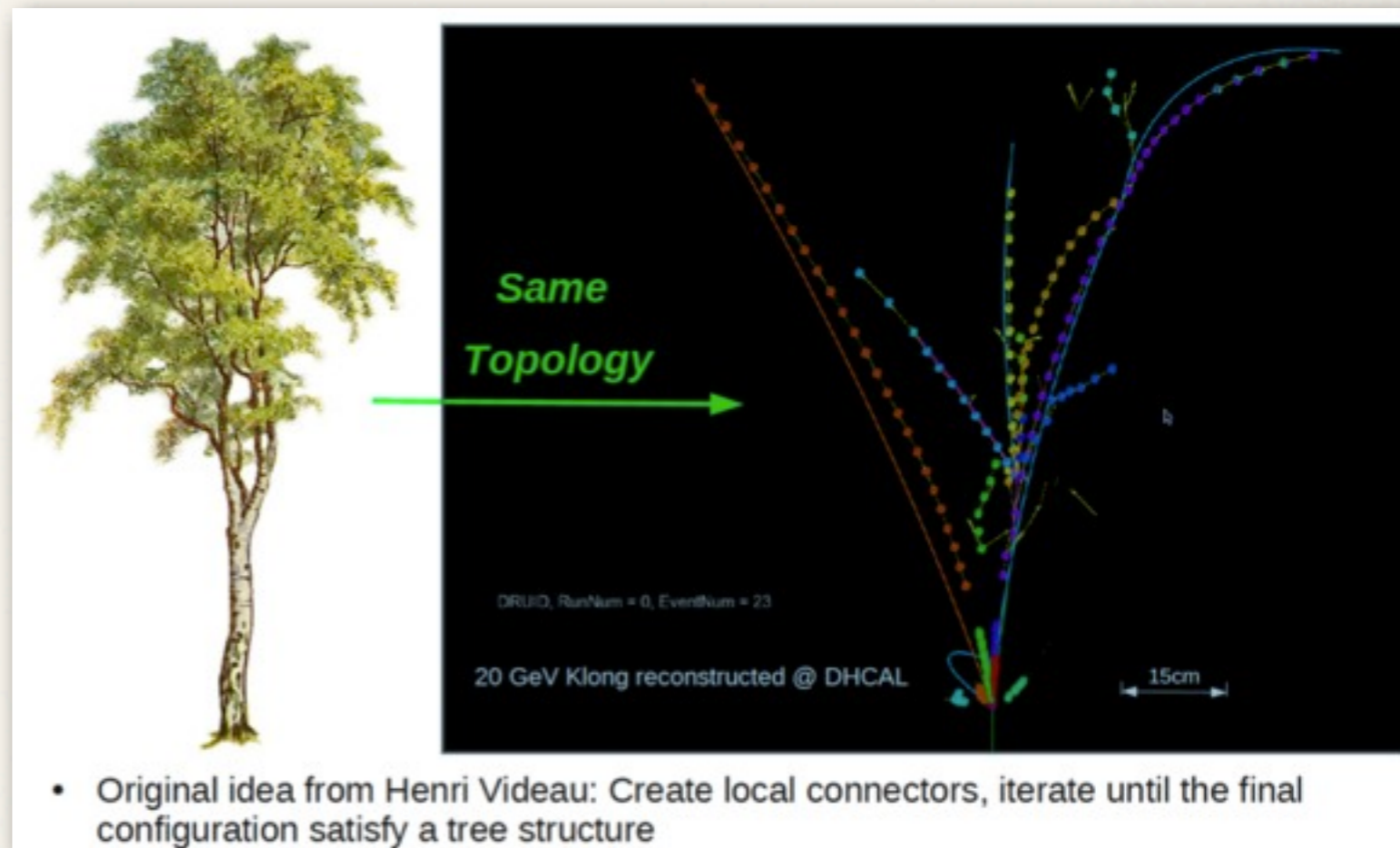
➡ Optimised framework... PandoraPFA

★ Recently Cambridge developed initial set of Liquid Argon algorithms to plug into PandoraPFA framework

★ Work in progress, but generating interest in EU (Laguna/LBNO) and US (LBNE)

# Alternative clustering algorithms

- ❖ Arbor: Shower / Jet reconstruction
  - ❖ LLR Work
  - ❖ Idea: Create local connectors, iterate until the final configuration satisfy a tree structure
  - ❖ Possible integration into PandoraPFA
  - ❖ Application to LHC



# Four Algorithms

**AIDA** Algorithm - III LML

- Final Connector Set ( as LCRRelation )
  - Clean: keep at most one connect ( with possible cut ) end at given hit
    - Current order parameter :  $(\text{Angle}(\text{link}, \text{ref\_dir}) + 0.02) * (\text{link\_length})$
    - Order parameter can be defined according to a semi-local fit

**AIDA** Algorithm - 1 LML

Take all clean hits  
With intra-layer clustering  
If needed

Create all possible connectors  
(i.e, dis < threshold &&  
NL\_begin < NL\_end)

Cleaning: only one  
Connector is allowed to end  
At each hit

- Clean
  - If a hit is the end of many connectors, keep the one with extreme order
  - Current Order parameter:  $\text{Ang}(P1, P2) * \text{sqrt}(\text{Dis}(P1, P2))$

**AIDA** Algorithm - IV LML

- Branch Set ( As Cluster Collection )
  - Create all the possible branches
  - Loop the branches with length order, flag each hit (as belong to previous (longer) branches). End the branch at the flagged hits
  - An unique branch configuration from connections
  - Branch - daughter particle trajectory
- Link Branches to Bush
- Operational: Arbor operated independently for ECAL & HCAL.

**AIDA** Algorithm - II LML

- Iteration the Connector Set ( 3 times )
  - Create new possible connector
    - If hit found in the explored region, add new connector
    - Definition of the region ( function to be optimized )
  - For each hit, get reference direction vector ( function to be optimized )
    - Current function: mean of outgoing and hit position (Normalized vectors)
    - If only one outgoing link: connector direction

# Arbor Status

- ❖ Promising separation between nearby shower Jet E:  $\sim$  PandoraPFA
- ❖ Goal: precisely identify and measure every particle reaching calorimeter

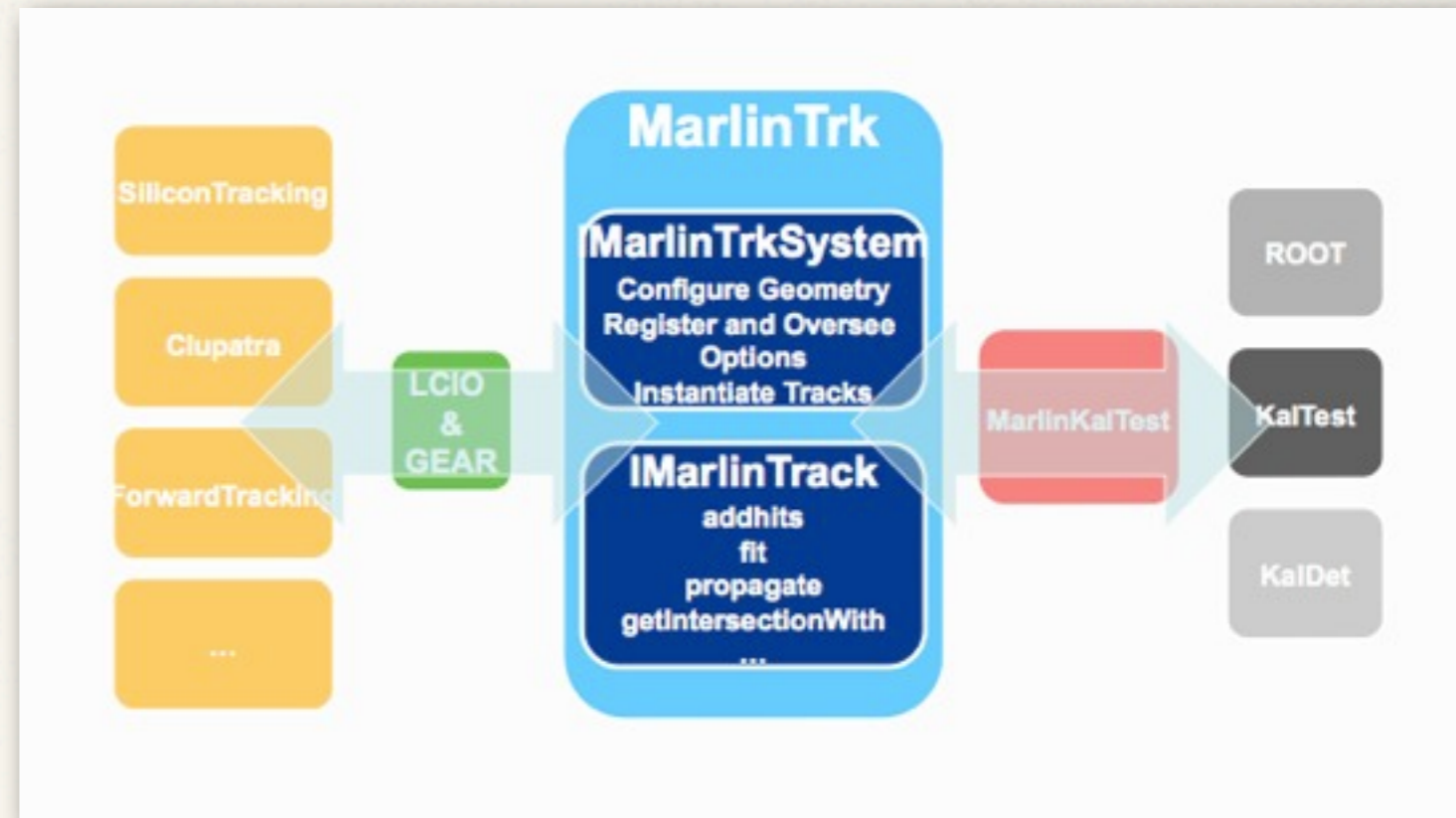


- ❖ Stabilized core algorithm
- ❖ Successful tagging of sub shower structure
- ❖ Good separation between nearby shower
- ❖ Reasonable jet energy performance lots of optimization remains



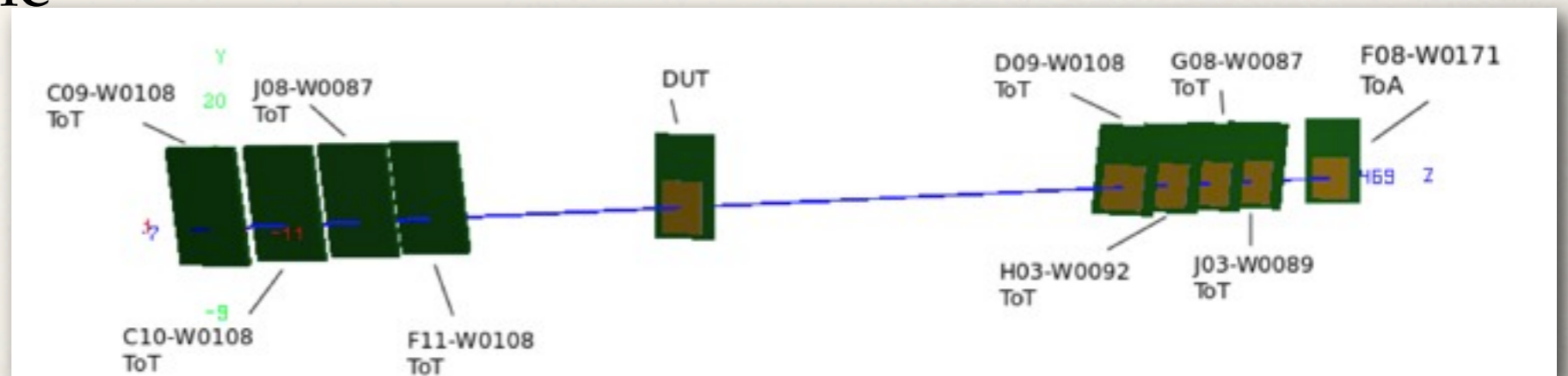
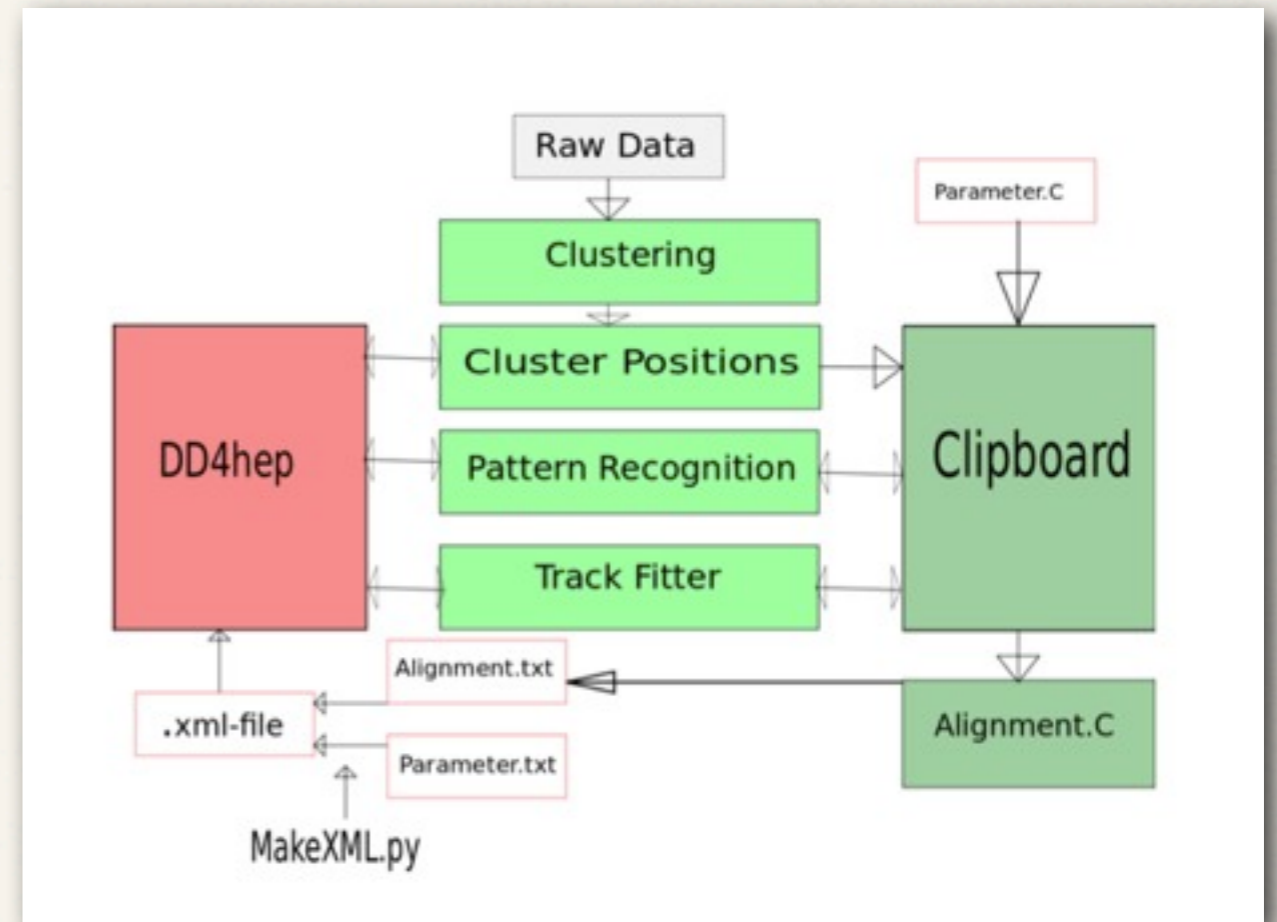
# Tracking Task

- ❖ Prototype in the context of ILD
- ❖ Current work related to geometry
  - ❖ Challenges:
    - ❖ Solve the problem(s): design interface and algorithms
    - ❖ Efficiency: accuracy vs. time consumption
- ❖ In progress:
  - ❖ Exchange the algorithmic side for easier connection with geometry
  - ❖ Started working with GENFIT: generic tracking tool, used for Belle-2
  - ❖ Very large overlap with goals of tracking WP
  - ❖ Geometry is based / built with TGeo
  - ❖ Clear connection to DD4Hep



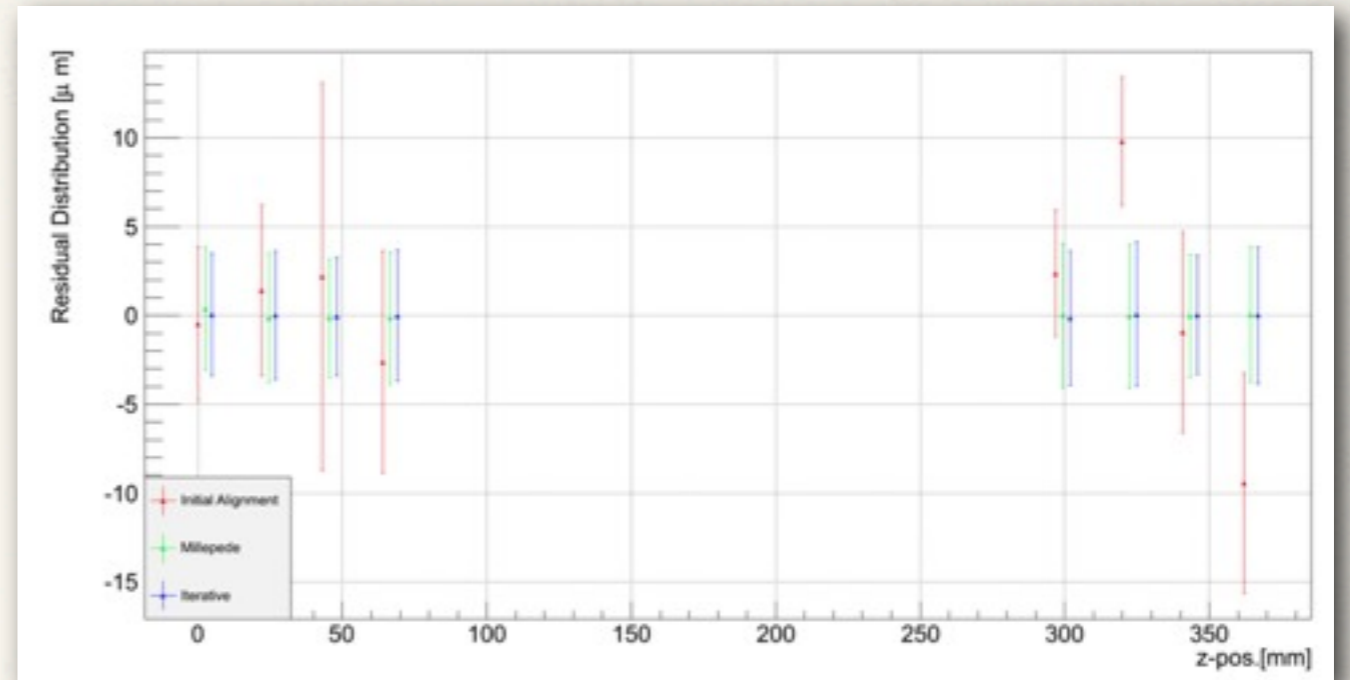
# Alignment: Test-Beam Telescope

- ❖ Software components:
  - ❖ Raw data processing
    - ❖ Specific to telescope
  - ❖ DD4hep Geometry Package
    - ❖ **First real usage of it**
  - ❖ Millepede for Alignment
    - ❖ Minimization of  $\chi^2$  via single matrix inversion



# Test-Beam Telescope Results

- ❖ Alignment by combination of Millepede and iterative method
- ❖ Several angle-scans were performed for various devices with different thicknesses / technologies at different bias voltages.
- ❖ Paper in preparation, including use of AIDA-work.

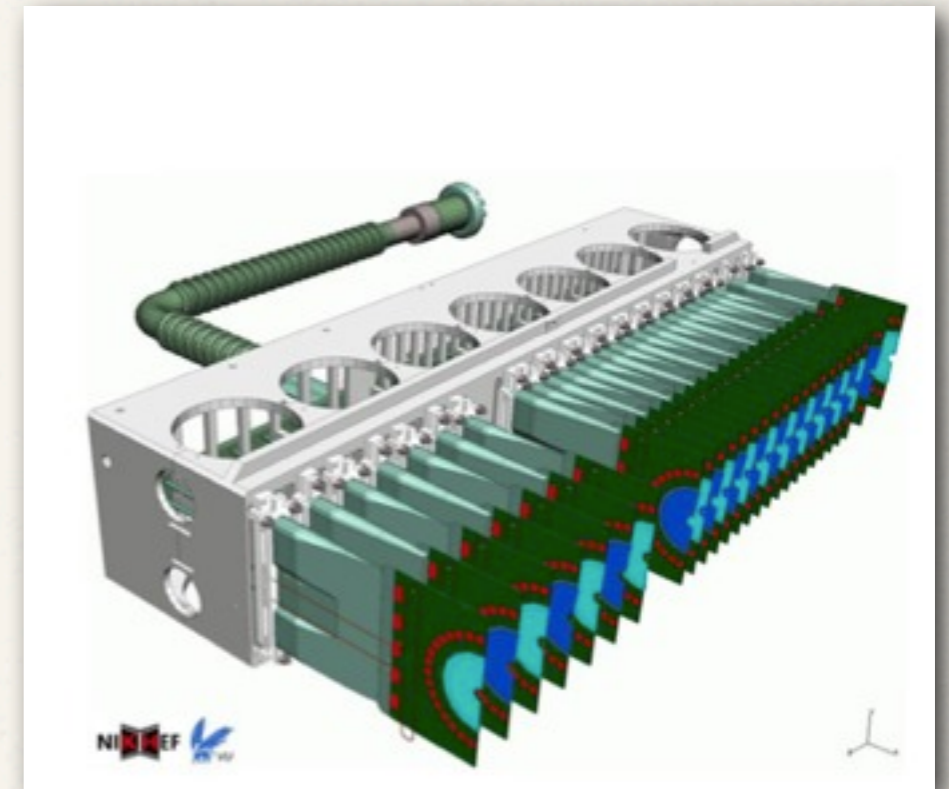


## Comparison Millepede vs. Iterative

	Millepede	Iterative
Time for 1 iteration with ≈3500 tracks(on 1.6 GHz CPU)	3-4min	4-5min
Iterations needed for alignment	1	3-4
Pros	Fast and stable	Sensitive to every dof
Cons	No sensitivity to $\Delta_\alpha$ , $\Delta_\beta$	Time consuming carefull monitoring needed

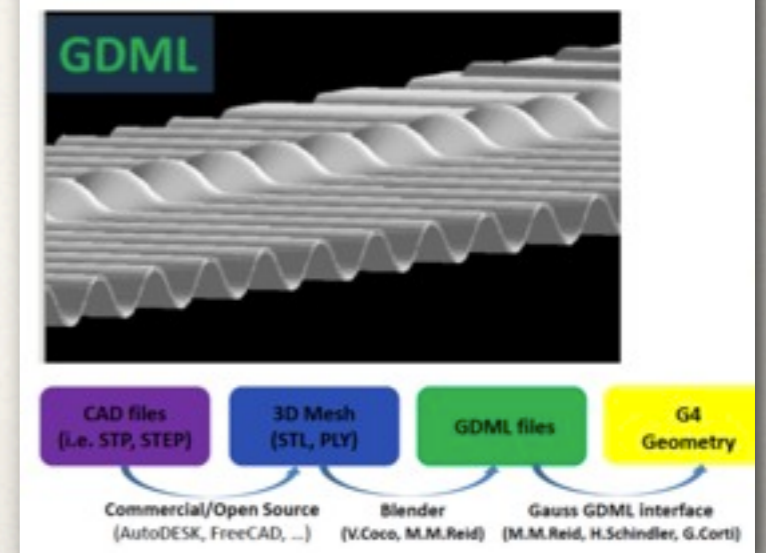
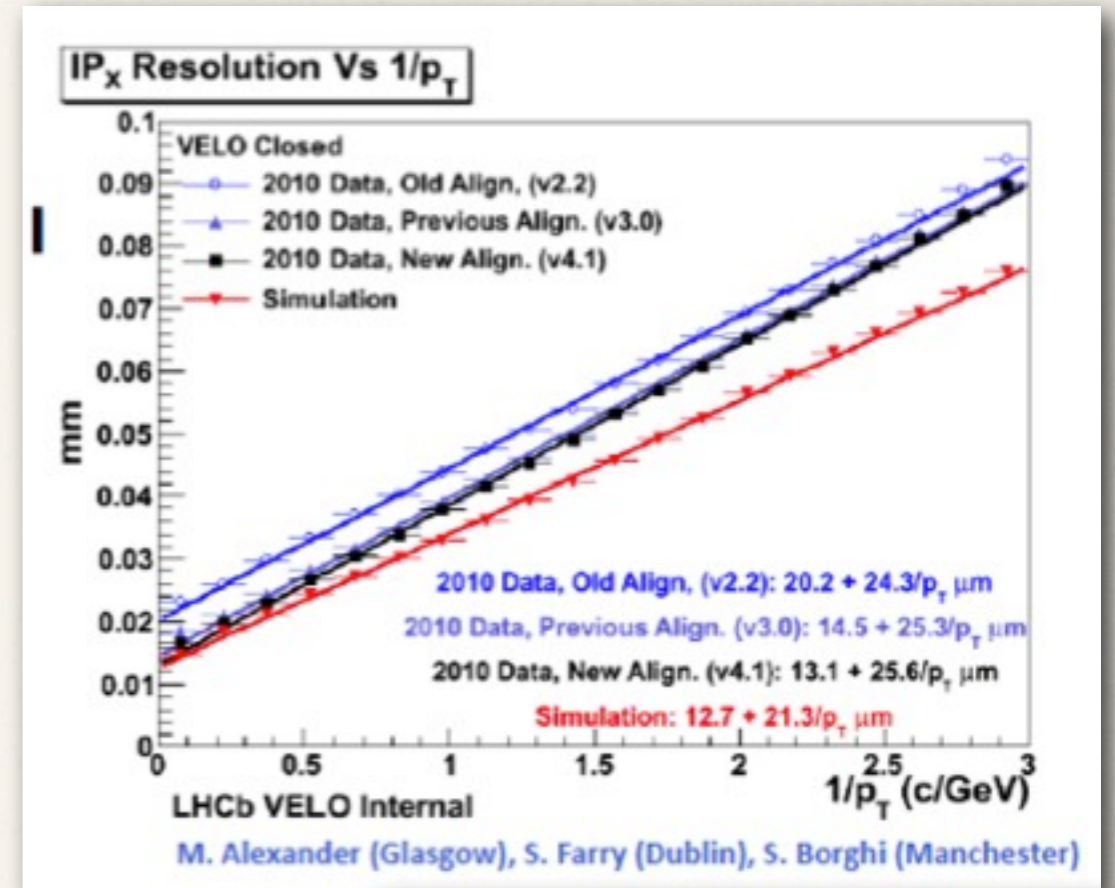
# LHCb Velo

- ❖ Status of alignment
- ❖ Two alignment methods used:
  - ❖ Based on Millepede
  - ❖ Iterative procedure using Kalman track fits.
  - ❖ Sensor misalignments are known to be better than  $4\ \mu\text{m}$ .
- ❖ Alignment of two detector-halves is carefully monitored after every run by comparing reconstructed primary vertex or track-residuals in overlap-region.
- ❖ In 2012: Misalignment in X less than  $5\ \mu\text{m}$ . Difference between 2012 and 2013:  $\approx 2\ \mu\text{m}$ .



# LHCb Velo Material Description

- ❖ Discrepancy in IP-resolution between simulation and data.
- ❖ Alignment issues can be ruled out as data and MC agree at high momenta
- ❖ Reasons could be mass / material distributions or Geant4 multiple scattering
- ❖ Better description of the RF-Foil surrounds VELO sensors to separate them from primary vacuum
  - ❖ Using the new tessellated from USolids



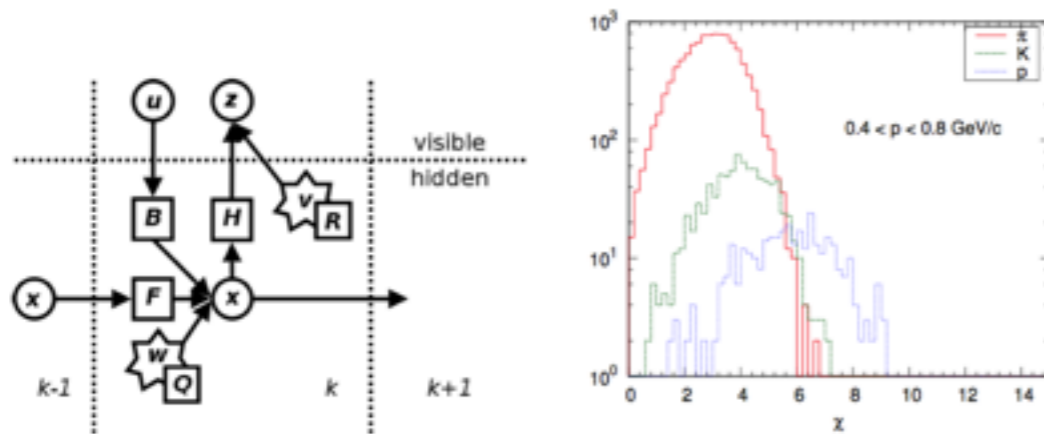
# Clustering, Energy loss, and Vertexing Algorithms for Si detectors (Wigner RCP)

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- ❖ Set of new algorithms for Si detectors
  - ❖ Kalman tracking (possibility to use track  $\chi^2 / \text{ndf}$  for PID)
  - ❖ Re-estimation of cluster position
  - ❖ Estimation of cluster deposit (fully corrected)
  - ❖ Estimation of most probable energy loss for tracks ("dE/dx")
  - ❖ Gain calibration of detector elements
  - ❖ Light event viewer in web browser (via LiveGraphics3D)
  - ❖ Configurable packages (eventSimulator, siEnergyLoss)
  - ❖ Control plots

❖

## Kalman tracking

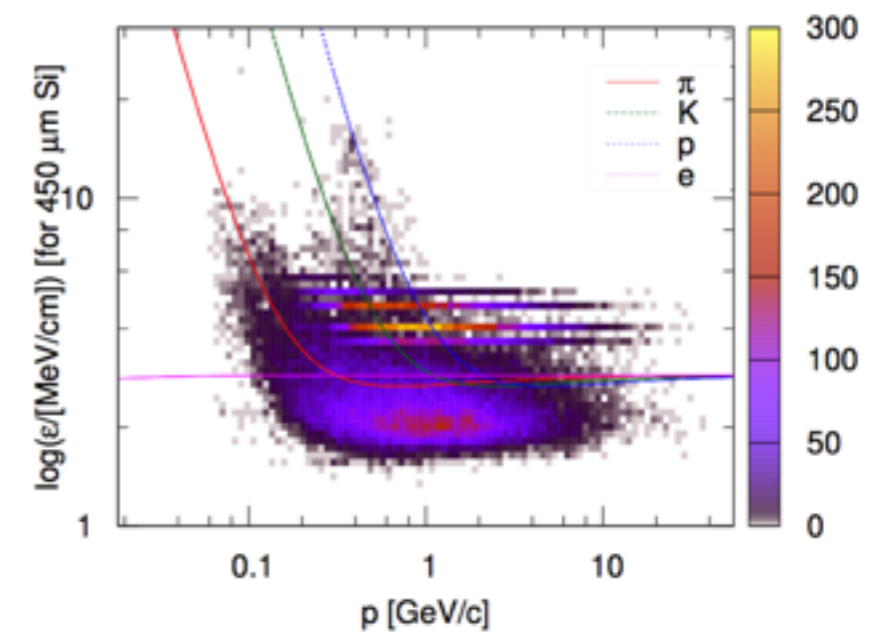


### • Kalman filter

- Known physics effects (F, Q), measurement uncertainties (V, R)
- Prediction + filtering + smoothing
- State vector:  $x = (\kappa, \theta, \psi, r\phi, z)$ , 5 dimensions
- Measurement operator, covariance of noise

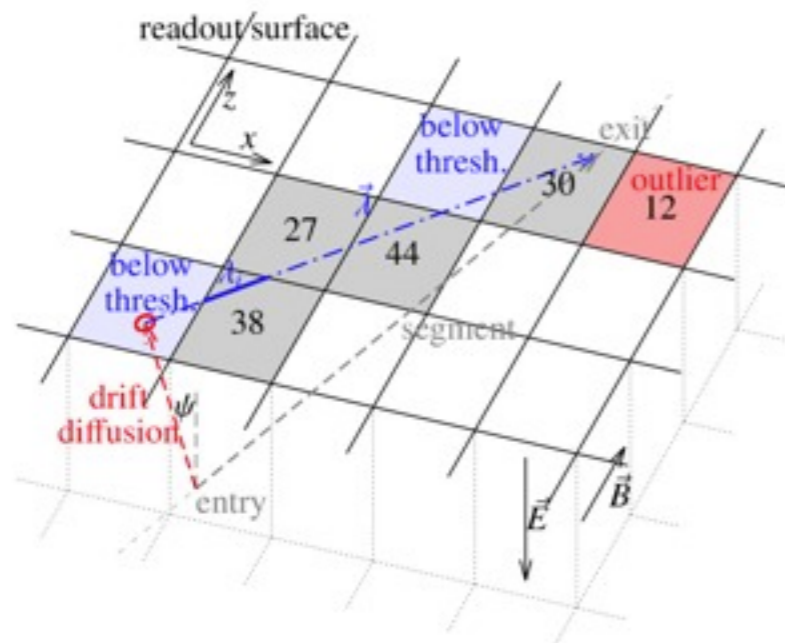
Possibility to use track-fit  $\sqrt{\chi^2/\text{ndf}}$  for enhancement

## Estimation of most probable energy loss for tracks

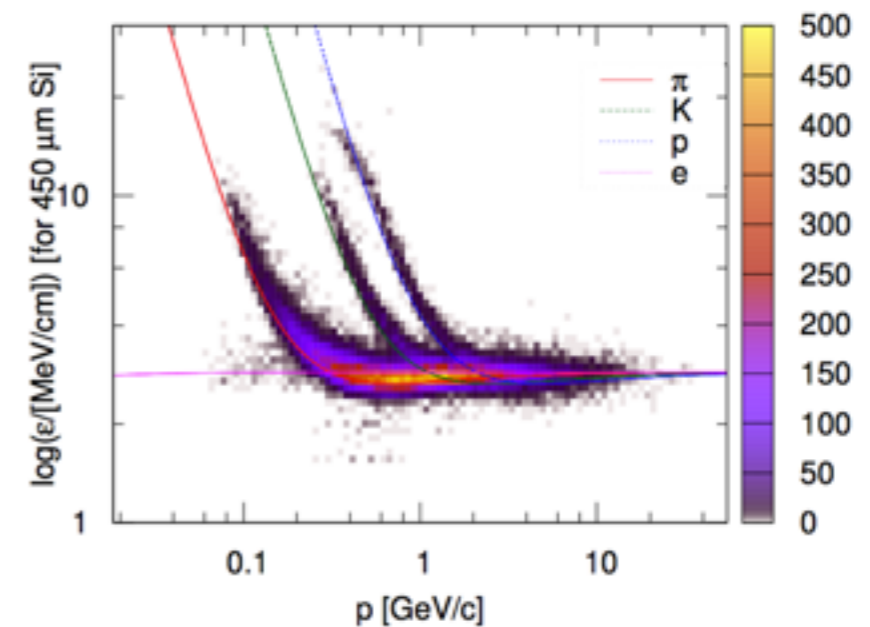


Most probable energy loss rate  $\epsilon$   
over a reference path length of  $l_0 = 450 \mu\text{m}$   
Without calibration!

## Clustering (pixels and strips)



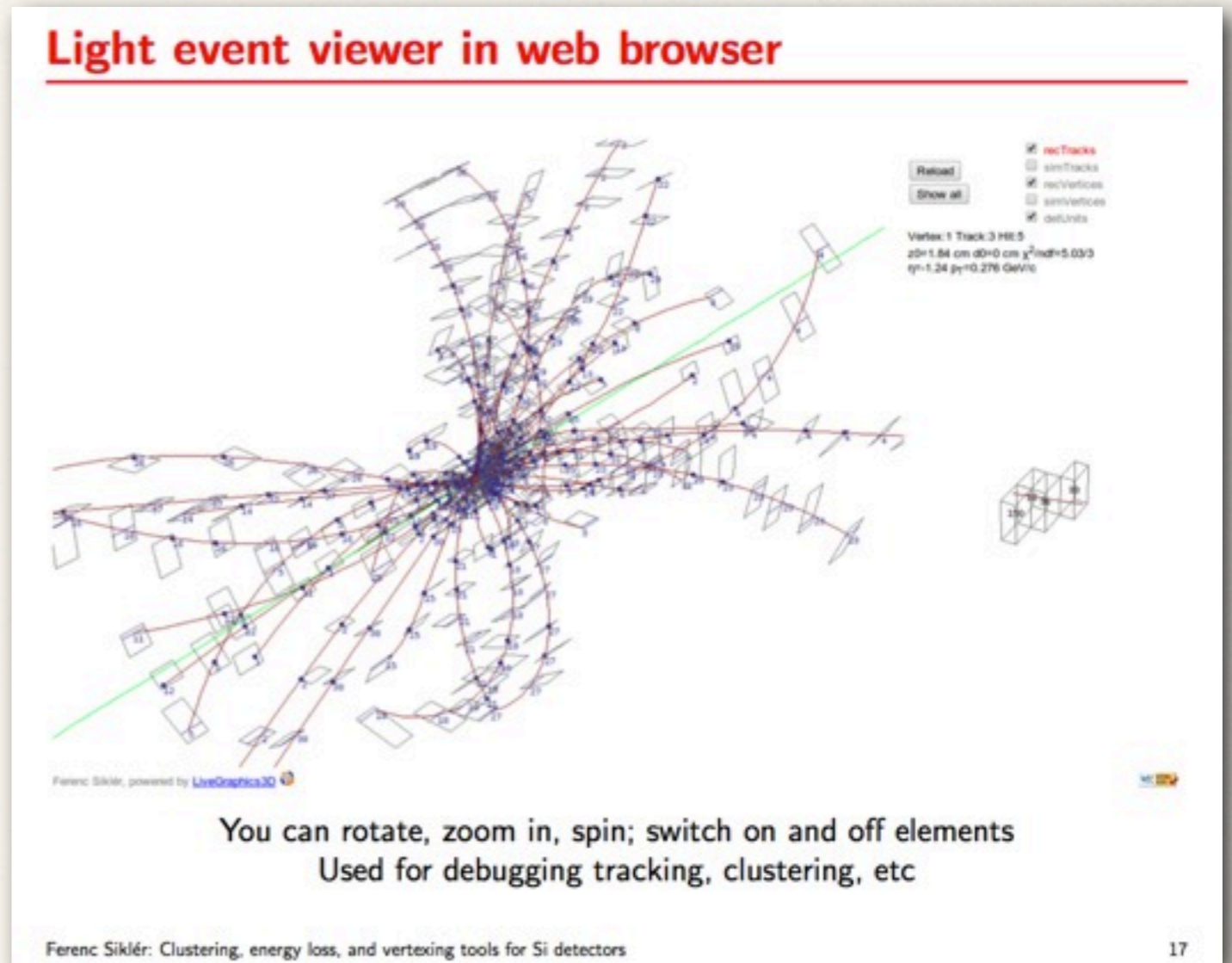
## Estimation of most probable energy loss for tracks



Most probable energy loss rate  $\epsilon$   
over a reference path length of  $l_0 = 450 \mu\text{m}$   
Well done

# Status and Outlook

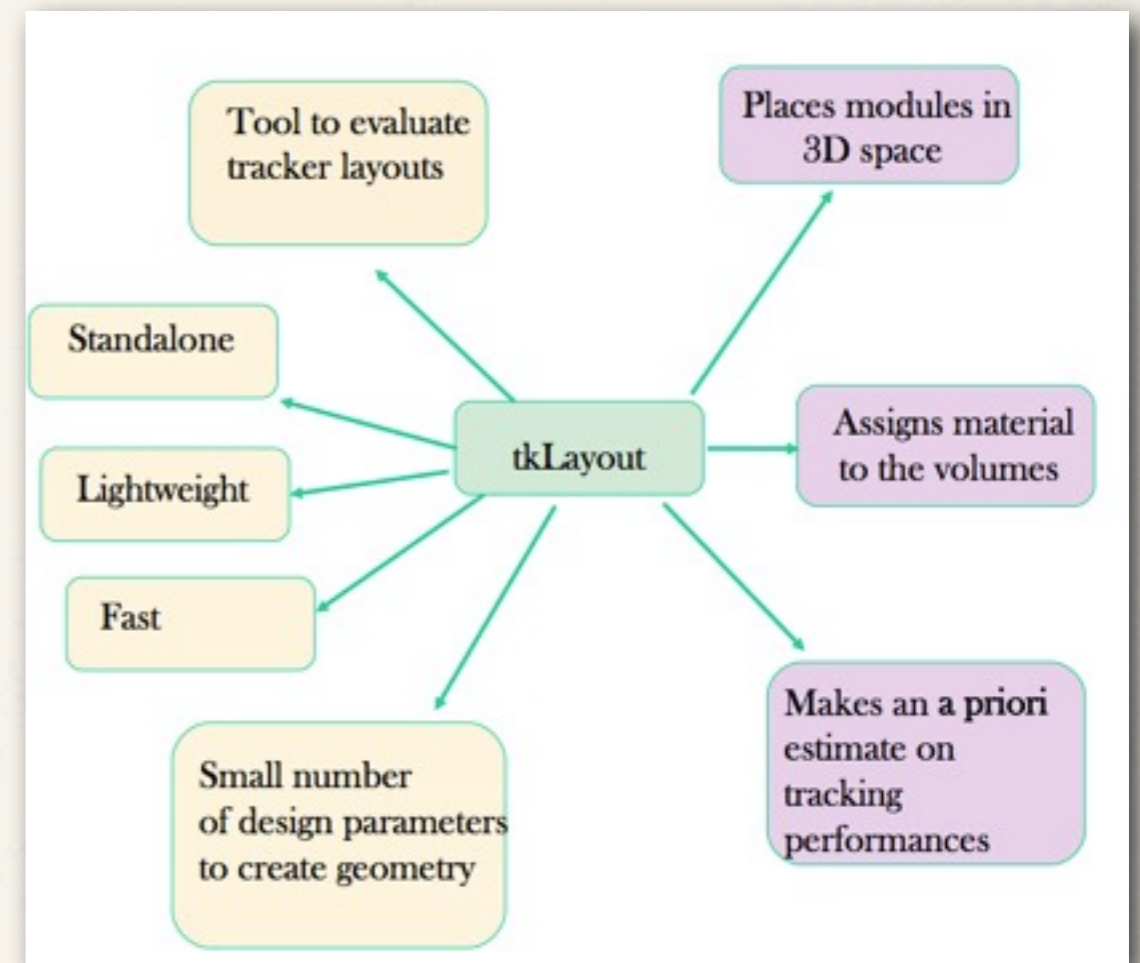
- ❖ Most of the packages are ready for use
- ❖ Methods used in CMS papers on particle spectra
- ❖ Next:
  - ❖ pattern recognition for tracking
  - ❖ use of cluster shape information for low fake rate pattern recognition
  - ❖ use refined cluster resolution and residuals for re-tracking
  - ❖ finish documentation





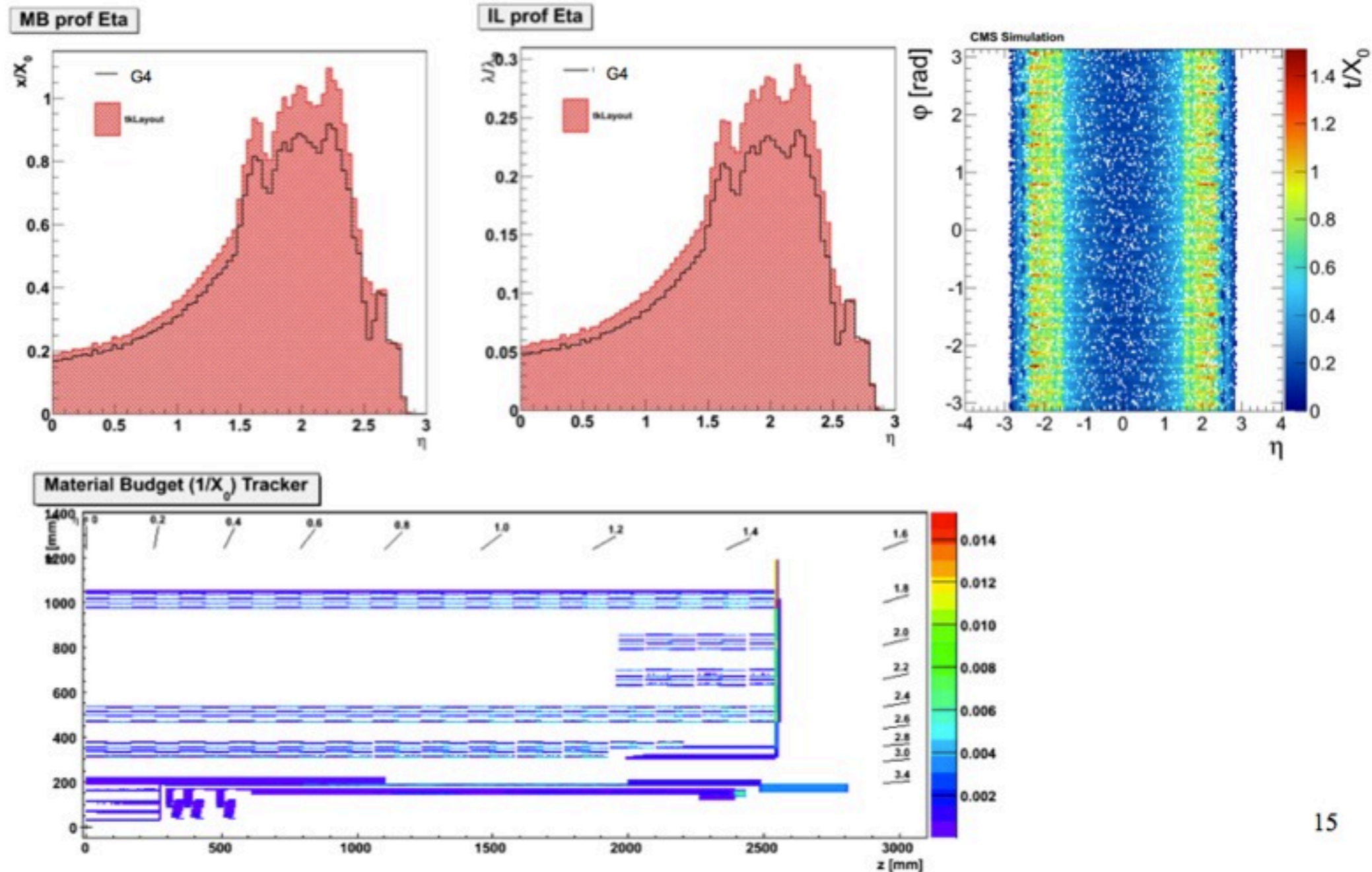
# A Tracker Layout Modeling Tool

- ❖ How to evaluate performances of a (tracker) detector geometry without having to full simulate millions of events
- ❖ The **tkLayout** package
  - ❖ Compare different detector layouts
  - ❖ No Monte Carlo
  - ❖ Ingredients:
    - ❖ Error propagation
    - ❖ Sensor resolution (measurement error)
    - ❖ Multiple scattering (treated as a correlated a measurement error)



# Comparing with G4 simulations

Examples from the evaluation of the LongBarrel configuration



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# Conclusions

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- ❖ Progress has been reported in all sub-tasks
  - ❖ Deliverables and Milestones achieved (with one exception)
- ❖ Started to see the use of geometry toolkit (DD4Hep) in other Sub-tasks
- ❖ Most of the work done is the context of a given experiment (LC, LHC)
  - ❖ This is fine but we need to make an effort to generalize and develop experiment independent software (PandoraPDF is an excellent example)
- ❖ Final goal is to deliver a set of generic and reusable libraries that can be used by the HEP community
  - ❖ Available in an open code repository
  - ❖ Proper documentation