ATLAS REQUIREMENTS AND PLANS FOR SRM2



GRAEME STEWART
UNIVERSITY OF GLASGOW





OVERVIEW

- ◆ The ATLAS Computing Model
- ◆ Storage Essentials
- ◆ SRM v2.2
 - **◆** Current Tests
 - ◆ New Features
 - ◆ Information System and Client Tools
- ◆ CCRC and FDR
- **◆** Conclusions

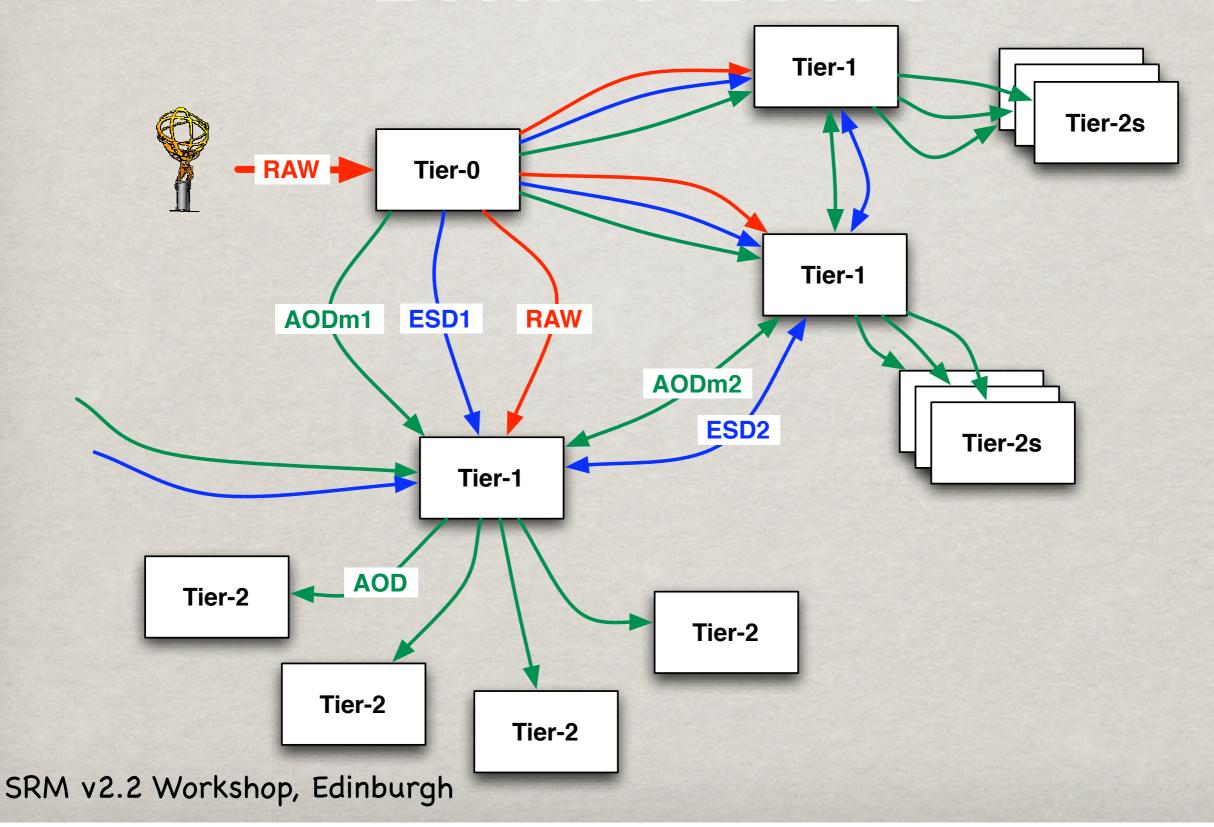


ATLAS COMPUTING MODEL

- ◆ Tier0
 - Copy RAW data to Castor tape for archival
 - ◆ Copy RAW data to Tier-1s for storage and reprocessing
 - Run first-pass calibration/alignment (within 24 hrs)
 - ◆ Run first-pass reconstruction (within 48 hrs)
 - ◆ Distribute reconstruction output (ESDs, AODs & TAGS) to Tier-1s
- ◆ Tier-1s:
 - ◆ Store and take care of a fraction of RAW data
 - ◆ Run "slow" calibration/alignment procedures
 - Rerun reconstruction with better calib/align and/or algorithms
 - ◆ Distribute reconstruction output to Tier-2s
 - Keep current versions of ESDs and AODs on disk for analysis
- ◆ Tier-2s:
 - Run simulation
 - Keep current versions of AODs on disk for analysis

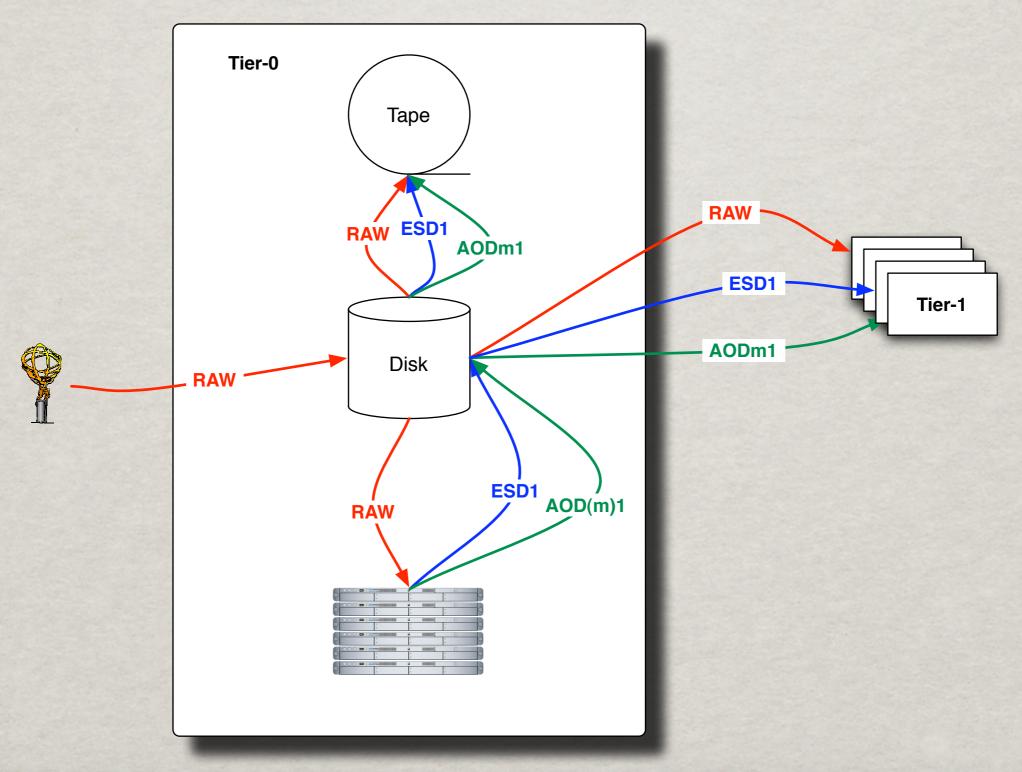


OVERVIEW OF REAL DATA FLOWS





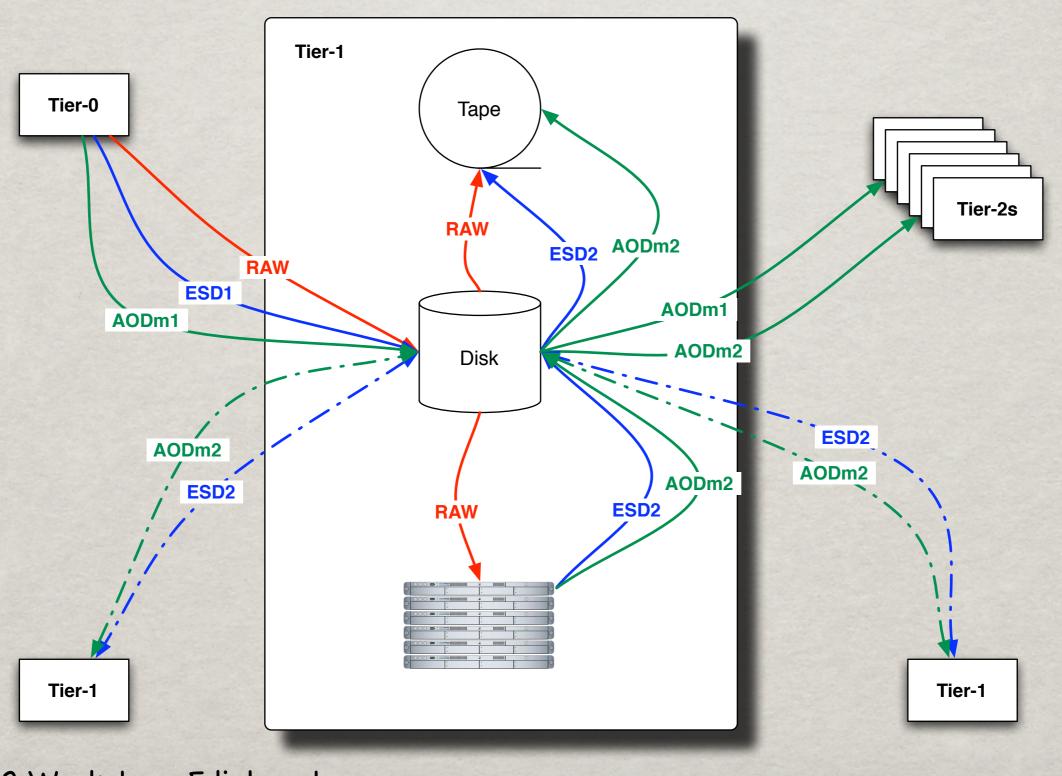
AT THE TIER-O



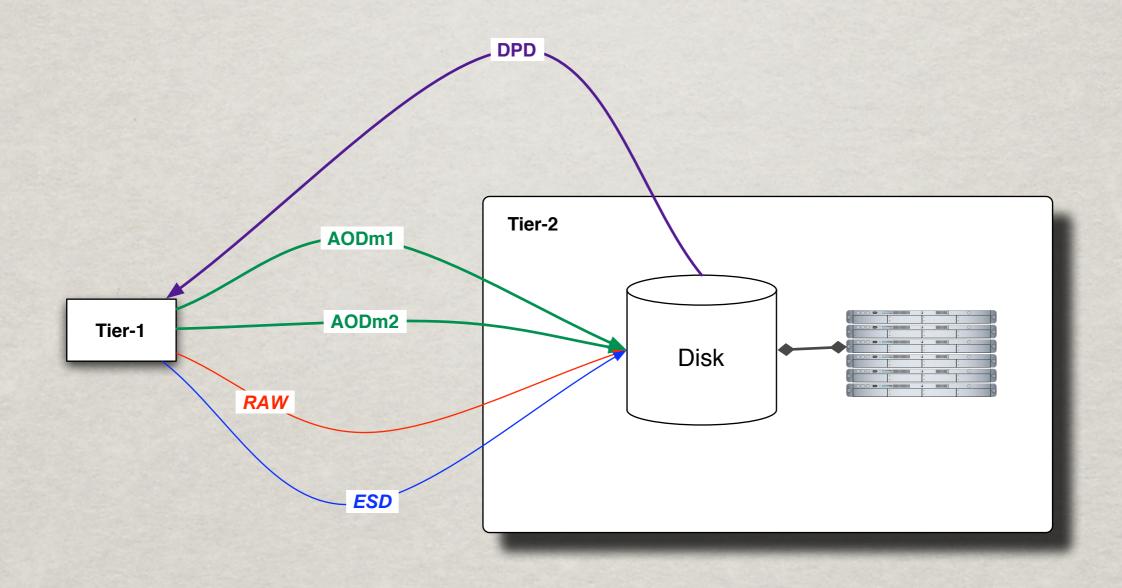


SRM v2.2 Workshop, Edinburgh

AT THE TIER-1



AT THE TIER-2





MONTECARLO PRODUCTION

- ◆ ATLAS Monte Carlo production constantly simulates events, digitises, reconstructs, etc. at T1 and T2
- ◆ This provides flows of simulated RAW, ESD and AOD from T2s to their T1
 - ◆ (There will be attempts to zip, e.g., hits files on the T2, but the T1 will still need to run merge jobs)
- ◆ Extensive use of DDM to stage input data to T2s and recover outputs from T2 to T1



SOME NOTES

- ◆ All data flow is mediated by ATLAS
 Distributed Data Management system
 (DDM)
- ◆ Actual transfers in and out of SEs done by FTS
- ◆ A very important use case is *reprocessing* recover RAW from tape and reprocess to generate new ESD and AOD
 - ◆ We also have to exercise expected failure modes (disk array on fire!)



ESSENTIAL FEATURES OF STORAGE FOR ATLAS

- 1. Storage systems should be reliable and robust.
- 2. If failures do occur error, then error messages should be clear and consistent.
- 3. We need to know what's on tape and what's on disk.

(The brief answer to the title of this session are the 3 points above.)



REPORT CARD: SRM v1.1

- 1. Reliable and robust?
 - · No.
- 2. Clear error messages?
 - · No.
- 3. What's on tape and what's on disk?
 - Not really.

SRM 1.1's only advantage is a long history in production already - it's the devil we know.

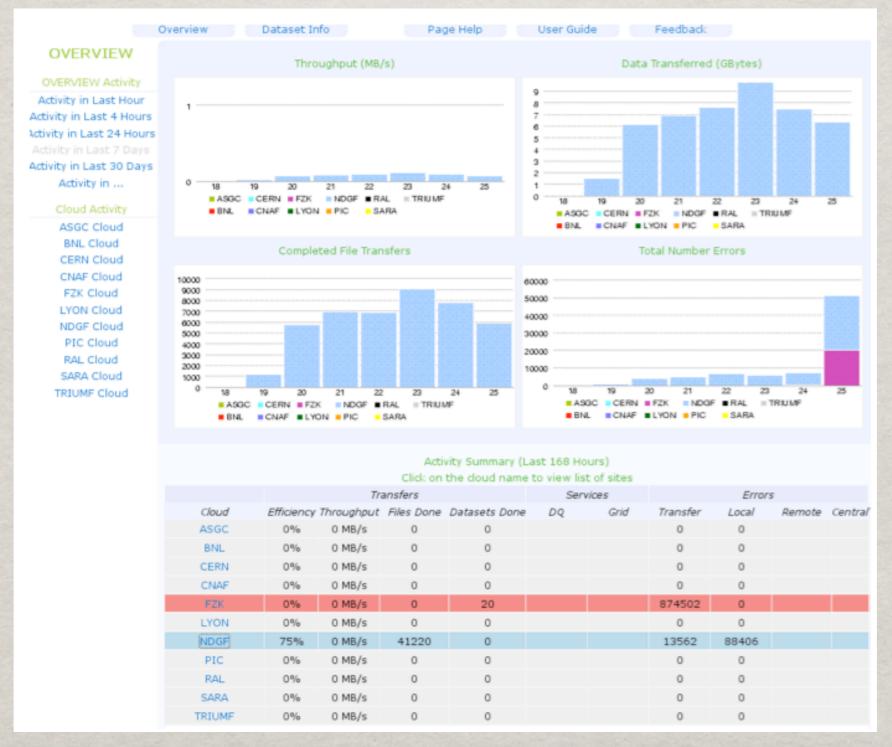


SRM V2.2: NEW KID ON THE BLOCK

- ◆ ATLAS have been testing SRM v2.2
 - ◆ However these tests are still an an early stage
- ◆ Moving fully to SRM v2 will imply a lot of changes to ATLAS Distributed Data Management
 - So we want to get it right
 - ◆ And we plan to incrementally use SRM v2.2 features



SRM V2.2 TESTS: DCACHE





SRM V2.2 TESTS: STORM





SRM V2.2 TESTS: CONCLUSIONS SO FAR

- ◆ SRM v2 works well as a replacement for SRM v1
- ◆ For dCache and STORM at least, reliability seems good
- Unfortunately problems with the DDM configuration meant the test endpoints got muddled with production
- So we need new rounds of testing
 - ◆ We haven't tried any new features!



SRM V2.2 REPORT CARD

- ◆ Reliable and robust?
 - ◆ Dedicated tests for dCache, STORM went well (errors were from CASTOR source)

Very hopeful on this front - we really do need improvements in this area.

GSSD Stress tests are very valuable; however, real production scale tests of SRM v2.2 have not yet happened.



SRM V2.2 REPORT CARD

- ◆ Good error messages?
 - ◆ Significant improvements expected here
 - ◆ FTS 2.0 already categorises errors as belonging to source or destination
 - We need this to be exposed to ATLAS tools so DDM shifters can take appropriate actions

Looks as if we can expect good news here too



SPACE TOKENS AND NEW FUNCTIONALITY

- ◆ ATLAS requirement at T0 and T1 is to know what's on tape and what's on disk (online and nearline, if you prefer)
 - Note we don't want too much complexity or abstraction from our point of view
- ◆ At the moment we have not tested space tokens, and they are not integrated yet into DDM
 - ◆ Aim will be to start simple, so we shall ask, in the first instance
 - ◆ ATLAS_DISK
 - ◆ ATLAS_TAPE
 - ◆ At T2s we will probably not declare space tokens at all initially, i.e., we will be using the "default" (whatever that is!)



SPACE TOKENS IN THE FUTURE

- Dependent on the success of basic use of space tokens we can envisage extending to
 - ◆ A T1D1 token for cloud produced AOD and ESD
 - ◆ Extending the use of space tokens at T2s to protect production areas, e.g.,
 - ◆ ATLAS_PROD
 - ◆ ATLAS_USER
- But nothing is settled yet (sorry!)
- Operation and management of space tokens is almost at important as functionality
- Dynamic space reservation will not be used by users, but could be explored for high level user tools, e.g., ganga



SRMLS

- ◆ Is a *good thing* and will help in data placement (recovery from aborted or partial transfers)
- ◆ It will also help greatly in validating the contents of the LFC
 - ◆ (This is envisaged as a constant background task)



STAGING FILES: SRINGONLINE

- ◆ Reprocessing requires recall of RAW data from tape
 - ◆ This can be seriously painful
- srmBringOnline would provide a good way of doing this across T0/1 implementations
 - ◆ But it needs to be tested
 - ◆ (There are always nasty ways to recall files from tape!)



GLUE INFORMATION SYSTEM

- ◆ ATLAS has partly isolated itself from problems with the grid information systems
 - ◆ It's unacceptable to drop important sites because of BDII problems
- ◆ However, information is gathered from here to populate more dynamic systems, like pilot scheduler systems
 - ◆ So accurate publishing of information through GLUE will help us a lot

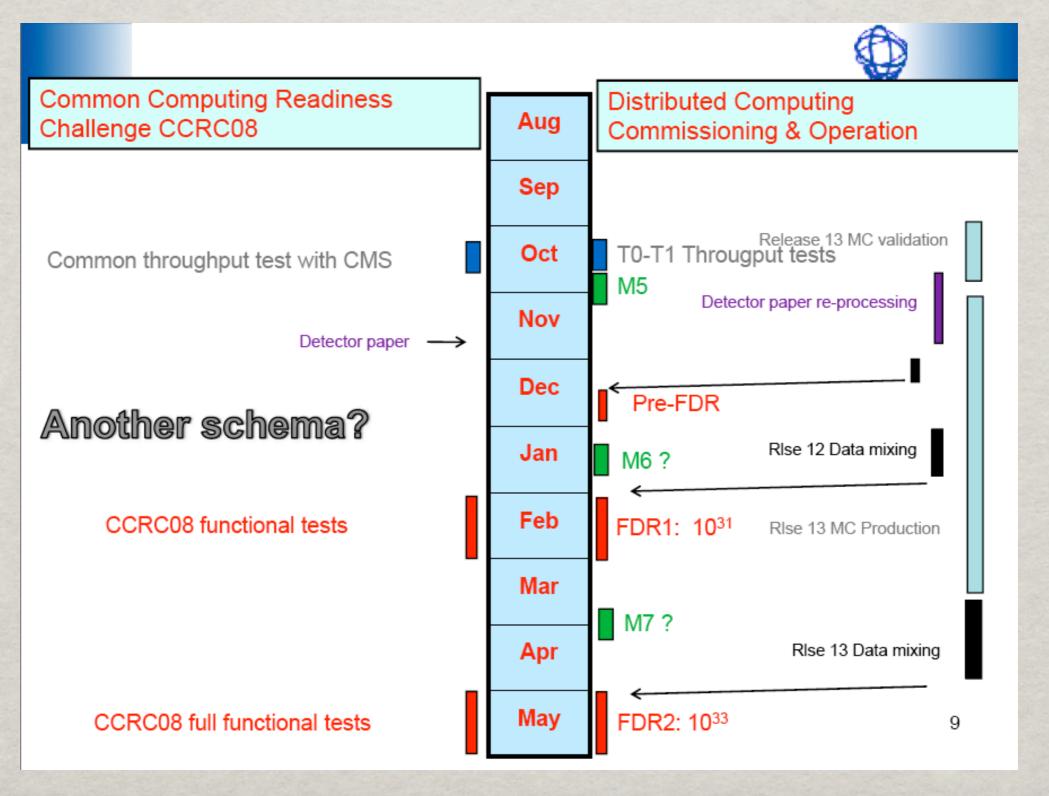


CLIENT TOOLS

- We'd like command line tools to issue, e.g., srm-ls and srm-stage
 - ◆ These should be scriptable
 - ◆ Should also not need to use BDII
- ◆ Python bindings for SRM access will also be very useful
 - ◆ Thread safe, no BDII, catalog plugins



THE BIG TESTS



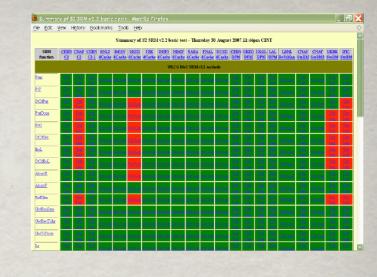


TESTING SCHEDULES

- ◆ Two weeks of dedicated SRM v2.2 testing in November (i.e., now)
- ◆ After this, we, anticipate moving to using SRM v2.2 endpoints as these become available at sites
- ◆ In FDR 1 we must exercise reprocessing plan is to use SRM v2.2 functionality for this
- ◆ Conversion of DDM to use space tokens properly will happen in time for FDR2



CONCLUSIONS



- ◆ GSSD group have done a good job (well done!) of guiding SRM v2 development and deployment
- ◆ ATLAS certainly hope to be able to move to SRM v2 smoothly in advance of data taking
- ◆ New features will be tested at scale and incorporated more widely into the system if successful
- ◆ At the moment there isn't really a recipe :-(
- ◆ It will be a process of evolution and we'll have to work together to ensure success

