















#### I Motivation

# II Procedure for cooling muons

# **III MICE description**

# **IV** State Machine operation

## V Future









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# The goal of MICE is:

- Design, build, commission and operate a realistic section of muon cooling channel
- Measure its performance in a variety of modes of operation and beam conditions





#### **Results to be used to optimize Neutrino Factory and Muon Collider designs.**

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# *Motivation: Neutrino Factory*





# IDS-NF baseline design

Neutrino Factory: accelerate and store muons to produce neutrinos



High energy  $v_e$  are unique among future facilities.

 $V_e \rightarrow V_\mu$ long baseline oscillations manifested by wrong sign muons:

 $v_{\mu} + N \rightarrow \mu + X$ 

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# Motivation Muon Collider





#### Historically, we've fallen off the curve:



•µ accelerator solution fundamental particles cleaner interactions tunable interaction energy •μ lifetime: 2.2μs (rest frame) **Technological challenge**, but not impossible

Intermediate Higgs factory

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# **Motivation:** Muon Accelerator







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# **MICE** is the

Muon onization Cooling Experiment **MICE** is a proof of principle experiment to demonstrate that we can "cool" a beam of muons.









Why cool muons?
muons are created as tertiary particles
created with large inherent emittance - beam spread in 6D phase space:
X, Y, Z
Px, Py, Pz



- accelerators require particles in tight bunches
- must "cool" muons reduce emittance of beam
  - "smaller beam" reduces cost of accelerator
  - "smaller beam" increases luminosity

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# V I Motivation

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 Recall: μ's are created with large emittance
 "Cooling" muons refers to reducing the emittance of the muon beam.

•Conventional techniques won't work (too slow)

- •Due to short muon lifetime, the only viable option is ionization cooling. Must cool AND accelerate muons rapidly:
  - diagram vectors represent momentum
  - lose momentum in  $p_T$  and  $p_L$
  - restore p<sub>L</sub>

 Magnetic fields focus muons at absorber to reduce x & y where they lose momentum

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•es



Cooling is: •Momentum loss in all dimensions via dE/dx •Replace longitudinal momentum with RF

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# **MICE Procedure**





- MICE will measure a 10% cooling effect with 1% accuracy => a 0.1% relative emittance measurement 1.create beam of muons
- 2.identify muons and reject background
- 3.measure muon emittance
- 4."cool" muons in low-Z absorber
- 5.restore longitudinal momentum
- 6.re-measure muon emittance
- 7.identify muons to reject e's from  $\mu$  decay

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# **Description:** The Lab



United



# **Rutherford Appleton Laboratory**

ISIS

MICE Hall R5.2



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**ISIS Accelerator** 





#### **ISIS Accelerator at RAL**





Description: Experiment





# Beamline - create beam of muons Particle ID - verify/tag muons (before/after) Trackers - measure emittance (before/after) Absorber (LH<sub>2</sub> or LiH) - cooling RF - re-establish longitudinal momentum



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# Description: Who are MICE?





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# **MICE Schedule**









# μ Beam Creation

 $\overline{\Box}$ 



μ



## Selecting a muon beam

DK solenoid



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# **Beam Selection**





#### μ direction in π rest frame $p_{D1} ≈ p_{D2}$ : beamline optimized for calibration studies and rate





# $\begin{array}{l} p_{D1}\simeq 2p_{D2};\\ \mbox{beamline optimized for}\\ \pi \mbox{-----} \mu \ transmission \end{array}$

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# **Beam Preparation**





# Muon beam preparation for MICE measurements

vary p<sub>D1</sub>/p<sub>D2</sub> to select beam

p<sub>tgt</sub>: p at target p<sub>sol</sub>: p at DS p<sub>dif</sub>: p at diffuser momentum (MeV/c)

	140	200	240
3	$p_{tgt}=321$	$p_{tgt}=390$	p <sub>tgt</sub> =453
	$p_{sol}=185$	$p_{sol}=231$	p <sub>sol</sub> =265
	$p_{dif}=151$	$p_{dif}=207$	p <sub>dif</sub> =245
6	$p_{tgt}=328$	p <sub>tgt</sub> =409	p <sub>tgt</sub> =472
	$p_{sol}=189$	p <sub>sol</sub> =238	p <sub>sol</sub> =276
	$p_{dif}=148$	p <sub>dif</sub> =215	p <sub>dif</sub> =256
1 0	p <sub>tgt</sub> =338 p <sub>sol</sub> =195 p <sub>dif</sub> =164	p <sub>tgt</sub> =429 p <sub>sol</sub> =251 p <sub>dif</sub> =229	p <sub>tgt</sub> =486 p <sub>sol</sub> =285 p <sub>dif</sub> =267

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emittance



# **MICE PID: Detectors**





#### <u>Upstream PID:</u> <u>discriminate p, π, μ</u> • Time of Flight - ToF0 & ToF1 • Threshold Cerenkov





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#### Downstream PID: reject decay electrons • Time of Flight - ToF2 • Kloe-light Calorimeter - KL

: Electron-Muon Ranger -EMR





# **MICE Cooling Channel**







# **MICE Tracking**



 Two trackers - before/after Measures x, y, x', y', z 5 stations/tracker •3 stereo planes/station - U/V/W •1400 350µm fibers/plane double layer, 7 fibers/group •<0.2% dead channels</p> •>10.5 photoelectrons/MIP •470µm RMS position resolution



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CHEP'13 poster P2.19



**Spectrometer Solenoids** 





# 4 T superconducting solenoids 20 cm warm bore 2.9 m long

•5 coils:
•1 tracker coil
•2 end coils
•2 matching coils





# **Absorber/Focus Coils**



# LH<sub>2</sub> Absorbers

#### Focus Coil 2 coils operated: •solenoid mode •flip mode



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# **RF/Coupling Coils**





## 201 MHz RF Cavity





#### **Coupling Coil**



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# 🖌 I Motivation

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# Framework: EPICS





Experimental Physics & Industrial Control Systems •HW+Drivers connect to IOCs (Input/Output Controllers) •IOCs create PVs (process variables) to represent params •PVs further described with native fields •PVs available on LAN to other IOCs or clients



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![](_page_30_Picture_0.jpeg)

# Framework: EPICS

![](_page_30_Picture_2.jpeg)

Start

CC5

42.8

4.24 K

Trim2

-28.98 A

0.16 V

E2: 249.73 A

43.0 K

\_ 0 ×

![](_page_30_Figure_3.jpeg)

![](_page_30_Figure_4.jpeg)

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![](_page_31_Picture_0.jpeg)

# **Controls & Monitoring**

![](_page_31_Picture_2.jpeg)

![](_page_31_Picture_3.jpeg)

#### •Beamline

- target
- decay solenoid
- conventional magnets
- proton absorber
- beam stop
- diffuser

#### Particle ID (PID)

- GVal
- ToF 1/2/3
- CKOV A/B
- KL
- EMR

#### Environment

• temp./humidity..

# Facilities/Computing

# Tracking Spectrometers spectrometer solenoids

• trackers

## •AFC

- absorbers
- focusing coils
- •RFCC
  - RF (acceleration)
  - coupling coils

#### These magnets require:

- vacuum
- cryogenics
- power supplies

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![](_page_32_Picture_0.jpeg)

![](_page_32_Picture_1.jpeg)

![](_page_32_Picture_2.jpeg)

 Different sub-systems have different needs •Each sub-system has 10<sup>1</sup>-10<sup>3</sup> PVs Many PVs have up to 4 alarm limits Each PV has different archiving needs For different operational states: - the PVs of interest change - the alarm limits change - the archiving needs change - the list of critical PVs change

#### **Too much room for human error!**

## e.g. Powering a superconducting magnet

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![](_page_33_Picture_0.jpeg)

# Problem? .... No problem

![](_page_33_Picture_2.jpeg)

![](_page_33_Picture_3.jpeg)

### **EPICS state notation language employed:**

- define equipment operational states
  for each state:
  - define transitions out of state
  - set alarm limits
  - set archiving features
  - define critical variables
- •check for software interlocks; e.g. quench
  •check for errors
- check for transition

# All parameters come from configuration database (CDB) – ensures correct settings

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![](_page_34_Picture_0.jpeg)

State Machine Requirements

![](_page_34_Picture_2.jpeg)

![](_page_34_Picture_3.jpeg)

# **Subsystem Owners must enumerate the states and provide:**

1)Description of state 2)Transition into state 3)PVs of interest 4)Alarm limits for PVs 5)Archiving features for PVs 6)AutoSMS (auto dialer) flag 7)Hardware interlocks 8)Software "interlocks" (enables)

# Required for each stateLoaded into the CDB

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![](_page_35_Picture_0.jpeg)

State Machine Procedures

![](_page_35_Picture_2.jpeg)

![](_page_35_Picture_3.jpeg)

#### For each subsystem & state, the algorithm:

Transitions:
manual
automatic

![](_page_35_Figure_6.jpeg)

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![](_page_36_Picture_0.jpeg)

# State Machine: SS Example

![](_page_36_Picture_2.jpeg)

**Spectrometer Solenoid Magnets:** 1)Offline 2)Pumping: establish insulating vacuum 3)Pumped\_Warm: insulating vacuum established 4)Pre\_Cooling: N, pre-cooling (T>100K) 5)Cooling: cryo-coolers lower shield/cold mass T 6)LHe Filling: add liquid He 7)Cold Ready: cold and stable 8) Ramping: applying current 9)Powered: stable operation **10)Quenched: quench detected** 11)Error: error requires operator intervention 12)Testing: interlocks disabled for manual testing

#### **Presently used in training/mapping SS magnets**

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![](_page_37_Picture_0.jpeg)

# State Machine: Target Example

![](_page_37_Picture_2.jpeg)

Target Example: 1)Offline 2)Parked\_Powered 3)Raised\_Holding 4)Raised\_Actuating 5)Moving\_Holding 6)Lowered\_Holding 7)Lowered\_Actuating 8)Error 9)Unknown

![](_page_37_Picture_4.jpeg)

![](_page_37_Figure_5.jpeg)

![](_page_37_Figure_6.jpeg)

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![](_page_38_Figure_0.jpeg)

# CHEP'13 poster P1.01

State machines for magnet control greatly reduces complexity of RunControl. RC need only check state of each magnet.

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**CDB** 

**CDB** 

Comment

Comment

![](_page_39_Picture_0.jpeg)

![](_page_39_Picture_1.jpeg)

![](_page_39_Picture_2.jpeg)

![](_page_39_Picture_3.jpeg)

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![](_page_40_Picture_0.jpeg)

# MICE Next Steps

![](_page_40_Picture_2.jpeg)

![](_page_40_Picture_3.jpeg)

![](_page_40_Picture_4.jpeg)

#### Now that Step I is complete:

![](_page_40_Picture_6.jpeg)

Fill up this hall!!!

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![](_page_41_Picture_0.jpeg)

**Prepare for Step IV** 

![](_page_41_Picture_2.jpeg)

![](_page_41_Picture_3.jpeg)

#### **Equipment is arriving:**

![](_page_41_Picture_5.jpeg)

![](_page_41_Picture_6.jpeg)

More under test: •SS1 •FC for AFC •EMR

![](_page_41_Picture_8.jpeg)

![](_page_42_Picture_0.jpeg)

![](_page_42_Picture_1.jpeg)

![](_page_42_Picture_2.jpeg)

![](_page_42_Picture_3.jpeg)

- MICE is a precision experiment: 0.1%
  MICE is preparing for Step IV
- C&M challenge to provide systematic operational settings
- State machine operation of major sub-systems meets this challenge

![](_page_42_Picture_7.jpeg)