RF Measurement Concepts

Fritz Caspers, Piotr Kowina

Accelerator Physics (advanced level)
Trondheim, Norway, 19 - 29 August 2013

Contents

- RF measurement methods – some history and overview

- Superheterodyne Concept and its application

- Voltage Standing Wave Ratio (VSWR)

- Introduction to Scattering-parameters (S-parameters)

- Properties of the S matrix of an N-port (N=1…4) and examples

- Smith Chart and its applications

- Appendices

Measurement methods - overview (1)

There are many ways to observe RF signals. Here we give a brief overview of the five main tools we have at hand

- ◆ Oscilloscope: to observe signals in time domain
  - periodic signals
  - burst signal
  - application: direct observation of signal from a pick-up, shape of common 230 V mains supply voltage, etc.

- ◆ Spectrum analyzer: to observe signals in frequency domain
  - sweeps through a given frequency range point by point
  - application: observation of spectrum from the beam or of the spectrum emitted from an antenna, etc.
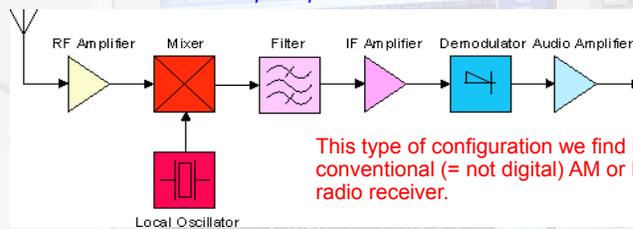
Measurement methods - overview (2)

- ◆ Dynamic signal analyzer (FFT analyzer)
  - Acquires signal in time domain by fast sampling
  - Further numerical treatment in digital signal processors (DSPs)
  - Spectrum calculated using Fast Fourier Transform (FFT)
  - Combines features of a scope and a spectrum analyzer: signals can be looked at directly in time domain or in frequency domain
  - Contrary to the SPA, also the spectrum of non-repetitive signals and transients can be observed
  - Application: Observation of tune sidebands, transient behavior of a phase locked loop, etc.
- ◆ Coaxial measurement line
  - old fashion method – no more in use but good for understanding of concept
- ◆ Network analyzer
  - Excites a network (circuit, antenna, amplifier or similar) at a given CW frequency and measures response in magnitude and phase => determines S-parameters
  - Covers a frequency range by measuring step-by-step at subsequent frequency points
  - Application: characterization of passive and active components, time domain reflectometry by Fourier transforming reflection response, etc.

Superheterodyne Concept (1)

Design and its evolution

The diagram below shows the basic elements of a single conversion superhet receiver. The essential elements of a local oscillator and a mixer followed by a fixed-tuned filter and IF amplifier are common to all superhet circuits. [super ετερω δυναμισ] a mixture of latin and greek … it means: *another force becomes superimposed.*

RF Amplifier   Mixer   Filter   IF Amplifier   Demodulator   Audio Amplifier
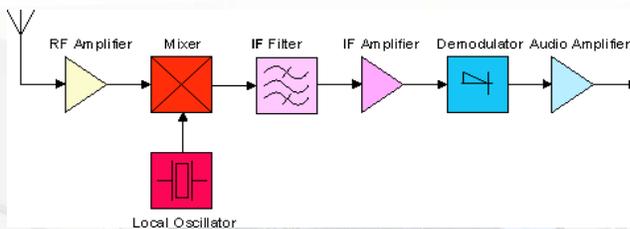
Local Oscillator

This type of configuration we find in any conventional (= not digital) AM or FM radio receiver.

The advantage to this method is that most of the radio's signal path has to be sensitive to only a narrow range of frequencies. Only the front end (the part before the frequency converter stage) needs to be sensitive to a wide frequency range. For example, the front end might need to be sensitive to 1–30 MHz, while the rest of the radio might need to be sensitive only to 455 kHz, a typical IF. Only one or two tuned stages need to be adjusted to track over the tuning range of the receiver; all the intermediate-frequency stages operate at a fixed frequency which need not be adjusted.

en.wikipedia.org

Superheterodyne Concept (2)

RF Amplifier   Mixer   **IF** Filter   IF Amplifier   Demodulator   Audio Amplifier

Local Oscillator

RF Amplifier = wideband front end amplification (RF = radio frequency)

The Mixer can be seen as an analog multiplier which multiplies the RF signal with the **LO** (local oscillator) signal.

The local oscillator has its name because it's an oscillator situated in the receiver locally and not as far away as the radio transmitter to be received.
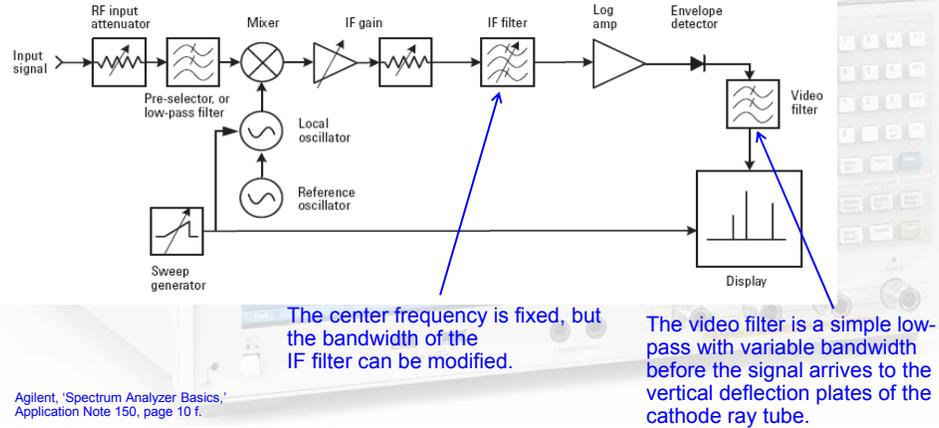
IF stands for intermediate frequency.

The demodulator can be an amplitude modulation (AM) demodulator (envelope detector) or a frequency modulation (FM) demodulator, implemented e.g. as a PLL (phase locked loop).

The tuning of a normal radio receiver is done by changing the frequency of the LO, not of the IF filter.

en.wikipedia.org

3

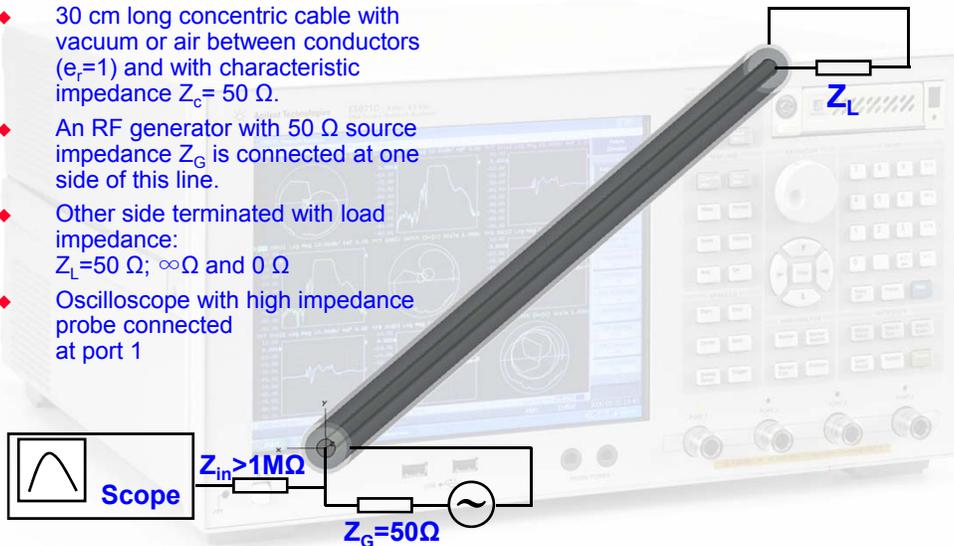# Example for Application of the Superheterodyne Concept in a Spectrum Analyzer

The center frequency is fixed, but the bandwidth of the IF filter can be modified.

The video filter is a simple low-pass with variable bandwidth before the signal arrives to the vertical deflection plates of the cathode ray tube.
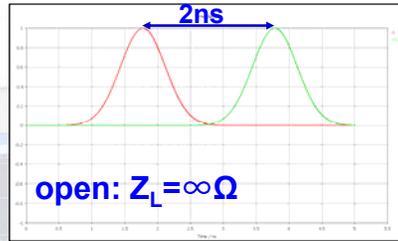
Agilent, 'Spectrum Analyzer Basics,' Application Note 150, page 10 f.

CAS, Trondheim, August 2013   RF Measurement Concepts, Caspers, Kowina   7

Another basic measurement example

- 30 cm long concentric cable with vacuum or air between conductors (e_r=1) and with characteristic impedance Z_c= 50 Ω.

- An RF generator with 50 Ω source impedance Z_G is connected at one side of this line.

- Other side terminated with load impedance:
  Z_L=50 Ω; ∞Ω and 0 Ω

- Oscilloscope with high impedance probe connected at port 1

Z_L

Z_{in}>1MΩ   **Scope**
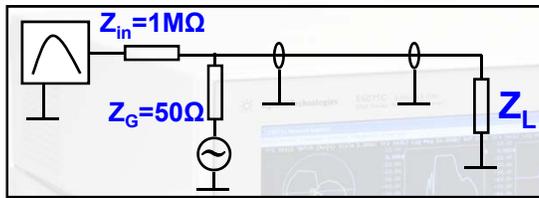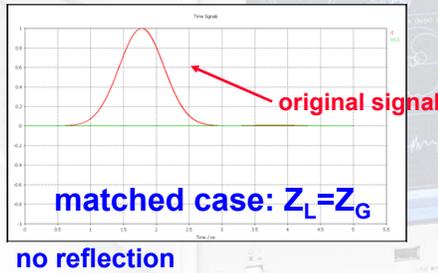
Z_G=50Ω

CAS, Trondheim, August 2013   RF Measurement Concepts, Caspers, Kowina   8
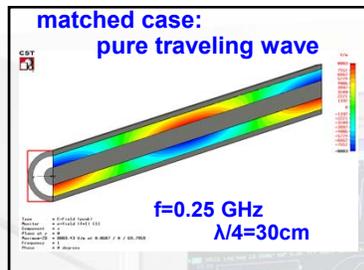
4

Measurements in time domain using Oscilloscope

$Z_{in}=1M\Omega$

$Z_G=50\Omega$

Z_L

2ns

open: $Z_L=\infty\,\Omega$

total reflection; reflected signal in phase, delay 2x1 ns.

original signal

matched case: $Z_L=Z_G$

no reflection

reflected signal

short: $Z_L=0\,\Omega$

total reflection; reflected signal in contra phase

How good is actually our termination?

matched case: pure traveling wave

standing wave

open

f=1 GHz
λ=30cm

f=0.25 GHz
λ/4=30cm

short

f=1 GHz
λ=30cm

Caution: the colour coding corresponds to the radial electric field strength – these are not scalar equipotential lines which are anyway not defined for time dependent fields
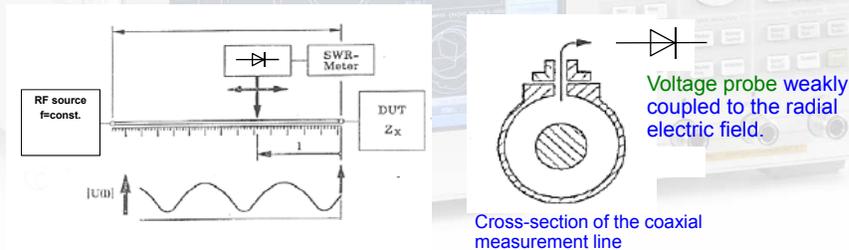
◆ The patterns for the short and open case are equal; only the phase is opposite which correspond to different position of nodes.

◆ In case of perfect matching: traveling wave only. Otherwise mixture of traveling and standing waves.

Voltage Standing Wave Ratio (1)

Origin of the term *"VOLTAGE Standing Wave Ratio – VSWR"*:

In the old days when there were no Vector Network Analyzers available, the reflection coefficient of some DUT (device under test) was determined with the coaxial measurement line.

Coaxial measurement line: coaxial line with a narrow slot (slit) in length direction. In this slit a small voltage probe connected to a crystal detector (detector diode) is moved along the line. By measuring the ratio between the maximum and the minimum voltage seen by the probe and the recording the position of the maxima and minima the reflection coefficient of the DUT at the end of the line can be determined.

Voltage probe weakly coupled to the radial electric field.

Cross-section of the coaxial measurement line

Voltage Standing Wave Ratio (2)

VOLTAGE DISTRIBUTION ON LOSSLESS TRANSMISSION LINES

For an ideally terminated line the magnitude of voltage and current are constant along the line, their phase vary linearly.

In presence of a notable load reflection the voltage and current distribution along a transmission line are no longer uniform but exhibit characteristic ripples. The phase pattern resembles more and more to a staircase rather than a ramp.

A frequently used term is the "Voltage Standing Wave Ratio VSWR" that gives the ratio between maximum and minimum voltage along the line. It is related to load reflection by the expression

$$V_{\max} = |a| + |b|$$
$$V_{\min} = |a| - |b|$$

$$VSWR = \frac{V_{\max}}{V_{\min}} = \frac{|a| + |b|}{|a| - |b|} = \frac{1 + |\Gamma|}{1 - |\Gamma|}$$

Remember: the reflection coefficient Γ is defined via the ELECTRIC FIELD of the incident and reflected wave. This is historically related to the measurement method described here. We know that an open has a reflection coefficient of $\Gamma=+1$ and the short of $\Gamma=-1$. When referring to the magnetic field it would be just opposite.
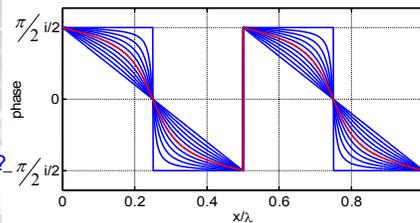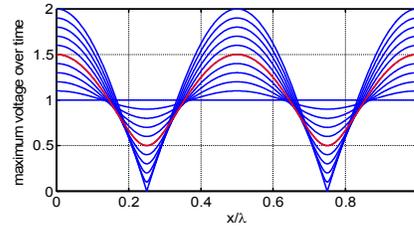
Voltage Standing Wave Ratio (3)

Γ	VSWR	Refl. Power $|-\Gamma|^2$
0.0	1.00	1.00
0.1	1.22	0.99
0.2	1.50	0.96
0.3	1.87	0.91
0.4	2.33	0.84
0.5	**3.00**	**0.75**
0.6	4.00	0.64
0.7	5.67	0.51
0.8	9.00	0.36
0.9	19	0.19
1.0	∞	0.00

With a simple detector diode we cannot measure the phase, only the amplitude.

Why? – What would be required to measure the phase?

Answer: Because there is no reference. With a mixer which can be used as a phase detector when connected to a reference this would be possible.

S-parameters- introduction (1)

Look at the windows of this car:
- part of the light incident on the windows is reflected
- the rest is transmitted

◆ The optical reflection and transmission coefficients characterize amounts of transmitted and reflected light.

◆ Correspondingly: S-parameters characterize reflection and transmission of voltage waves through n-port electrical network
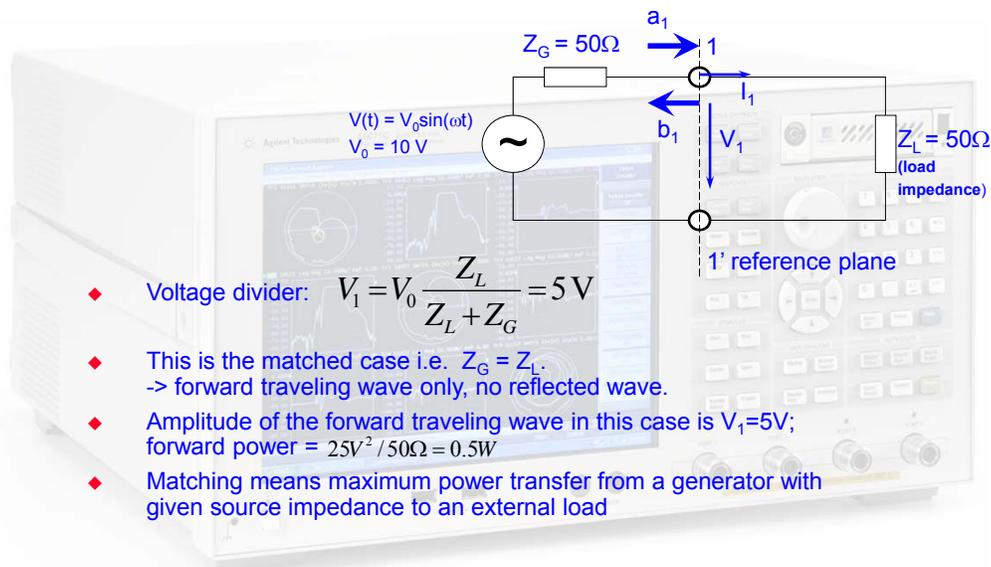
◆ Caution: in the microwave world reflection coefficients are expressed in terms of voltage ratio whereas in optics in terms of power ratio.

S-parameters- introduction (2)

- When the linear dimmensions of an object approche one tenth of the (free space) wavelength this circuit can not be modeled precisely anymore with the single lumped element.

- Kurokawa in 1965 introduced „power waves" instead of voltage and current waves used so far   K. Kurokawa, 'Power Waves and the Scattering Matrix,' IEEE Transactions on Microwave Theory and Techniques, Vol. MTT-13, No. 2, March, 1965.

- The essencial difference between power wave and current wave is a normalisation to square root of characteristic impedance $\sqrt{Z_c}$

- The abbreviation *S* has been derived from the word *scattering*.

- Since S-parameters are defined based on traveling waves
  -> the absolute value (modulus) does not vary along a lossless transmissions line
  -> they can be measured on a DUT (Device Under Test) situated at some distance from an S-parameter measurement instrument (like Network Analyser)

- How are the S-parameters defined?

Simple example: a generator with a load

- Voltage divider: $V_1 = V_0 \dfrac{Z_L}{Z_L + Z_G} = 5\,\text{V}$

- This is the matched case i.e. $Z_G = Z_L$.
  -> forward traveling wave only, no reflected wave.

- Amplitude of the forward traveling wave in this case is V_1=5V; forward power = $25 V^2 / 50\Omega = 0.5W$

- Matching means maximum power transfer from a generator with given source impedance to an external load
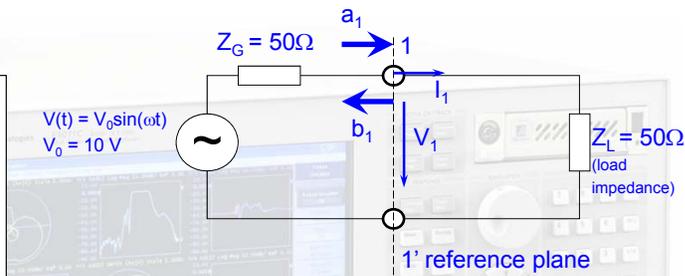
Power waves definition (1)

(*see Kurokawa paper):

$$a_1 = \frac{V_1 + I_1 Z_c}{2\sqrt{Z_c}},$$

$$b_1 = \frac{V_1 - I_1 Z_c}{2\sqrt{Z_c}},$$
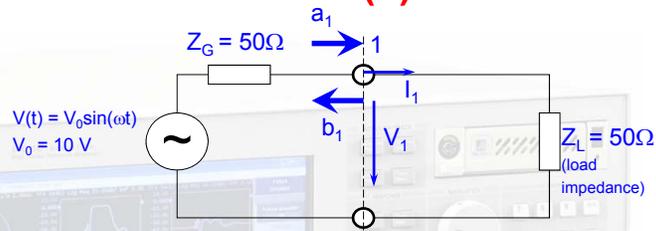
where the characteristic impedance $Z_c = Z_G$

$Z_G = 50\Omega$

a_1

1

$V(t) = V_0\sin(\omega t)$
$V_0 = 10$ V

I_1

b_1 V_1

$Z_L = 50\Omega$ (load impedance)

1' reference plane

Definition of power waves:

- a_1 is the wave incident to the terminating one-port (Z_L)
- b_1 is the wave running out of the terminating one-port
- a_1 has a peak amplitude of 5V / $\sqrt{50\Omega}$; voltage wave would be just 5V.
- What is the amplitude of b_1? Answer: $b_1 = 0$.
- Dimension: [V/$\sqrt{Z}$], in contrast to voltage or current waves
    Caution! US notation: power = $|a|^2$ whereas European notation (often): power = $|a|^2/2$

Power waves definition (2)

$$a_1 = \frac{V_1 + I_1 Z_c}{2\sqrt{Z_c}},$$

$$b_1 = \frac{V_1 - I_1 Z_c}{2\sqrt{Z_c}}, \text{ with } Z_c = Z_G$$

$Z_G = 50\Omega$

a_1

1

$V(t) = V_0\sin(\omega t)$
$V_0 = 10$ V

I_1

b_1 V_1

$Z_L = 50\Omega$ (load impedance)

More practical method for determination: Assume that the generator is terminated with an external load equal to the generator impedance. Then we have the matched case and only a forward traveling wave (no reflection). Thus, the voltage on this external resistor is equal to the voltage of the outgoing wave.

$$a_1 = \frac{V_0}{2\sqrt{Z_c}} = \frac{\text{incident voltage wave}\,(port1)}{\sqrt{Z_c}} = \frac{V_1^{inc}}{\sqrt{Z_c}}$$
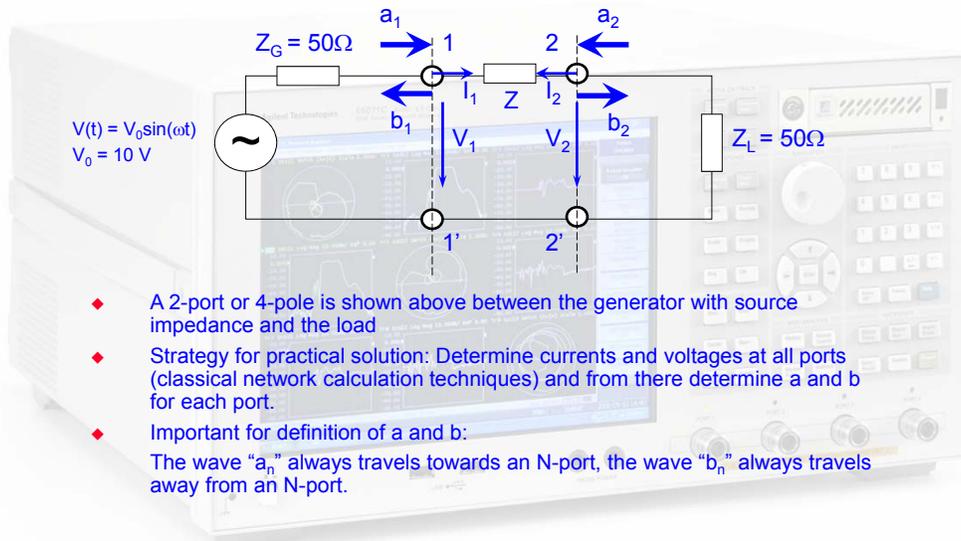
$$b_1 = \frac{\text{reflected voltage wave}\,(port1)}{\sqrt{Z_c}} = \frac{V_1^{refl}}{\sqrt{Z_c}}$$

$$V_i = \sqrt{Z_c}\,(a_i + b_i) = V_i^{inc} + V_i^{refl}$$

$$I_i = \frac{1}{\sqrt{Z_c}}(a_i - b_i) = \frac{V_i^{refl}}{Z_c}$$
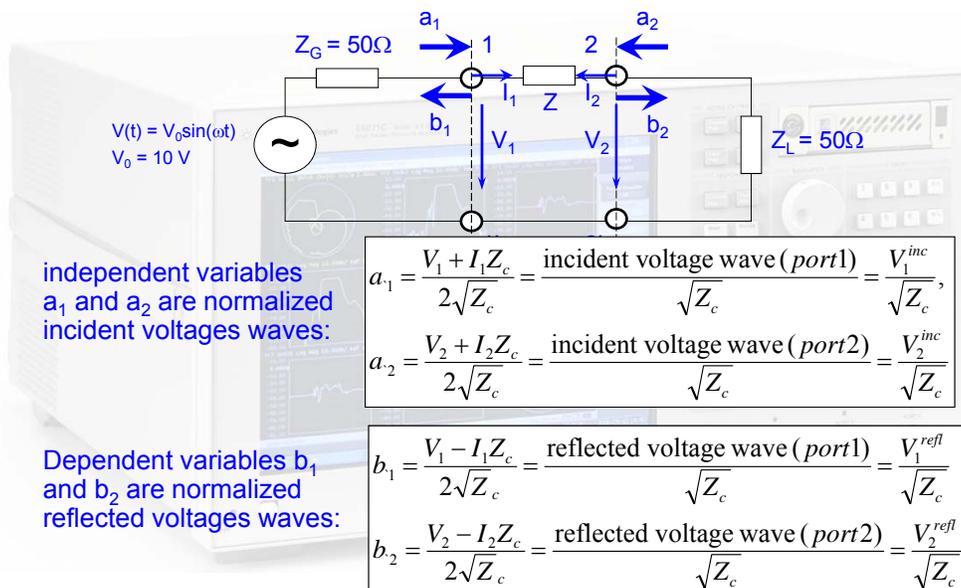
Caution! US notation: power = $|a|^2$ whereas European notation (often): power = $|a|^2/2$

9

Example: a 2-port (2)

- A 2-port or 4-pole is shown above between the generator with source impedance and the load
- Strategy for practical solution: Determine currents and voltages at all ports (classical network calculation techniques) and from there determine a and b for each port.
- Important for definition of a and b:
  The wave "a_n" always travels towards an N-port, the wave "b_n" always travels away from an N-port.

Example : a 2-port (2)

- independent variables a_1 and a_2 are normalized incident voltages waves:

$$a_1 = \frac{V_1 + I_1 Z_c}{2\sqrt{Z_c}} = \frac{\text{incident voltage wave}\,(port1)}{\sqrt{Z_c}} = \frac{V_1^{inc}}{\sqrt{Z_c}},$$

$$a_2 = \frac{V_2 + I_2 Z_c}{2\sqrt{Z_c}} = \frac{\text{incident voltage wave}\,(port2)}{\sqrt{Z_c}} = \frac{V_2^{inc}}{\sqrt{Z_c}}$$

- Dependent variables b_1 and b_2 are normalized reflected voltages waves:

$$b_1 = \frac{V_1 - I_1 Z_c}{2\sqrt{Z_c}} = \frac{\text{reflected voltage wave}\,(port1)}{\sqrt{Z_c}} = \frac{V_1^{refl}}{\sqrt{Z_c}}$$

$$b_2 = \frac{V_2 - I_2 Z_c}{2\sqrt{Z_c}} = \frac{\text{reflected voltage wave}\,(port2)}{\sqrt{Z_c}} = \frac{V_2^{refl}}{\sqrt{Z_c}}$$

10

S-Parameters – definition (1)

The linear equations decribing two-port network are:

$b_1 = S_{11}a_1 + S_{12}a_2$

$b_2 = S_{22}a_2 + S_{21}a_2$

The S-parameters S_{11}, S_{22}, S_{21}, S_{12} are given by:

$$S_{11} = \left. \frac{b_1}{a_1} \right|_{a_2=0} \equiv \text{Input reflection coeff.} \, (Z_L = Z_c \Rightarrow a_2 = 0)$$

$$S_{22} = \left. \frac{b_2}{a_2} \right|_{a_1=0} \equiv \text{Output reflection coeff.} \, (Z_G = Z_c \Rightarrow a_1 = 0)$$

$$S_{21} = \left. \frac{b_2}{a_1} \right|_{a_2=0} \equiv \text{Forward transmission gain}$$

$$S_{12} = \left. \frac{b_1}{a_2} \right|_{a_1=0} \equiv \text{Backward transmission gain}$$

S-Parameters – definition (2)

$$S_{11} = \frac{b_1}{a_1} = \frac{\dfrac{V_1}{I_1} - Z_c}{\dfrac{V_1}{I_1} + Z_c} = \frac{Z_1 - Z_c}{Z_1 + Z_c},$$

$$Z_1 = Z_c \frac{(1 + S_{11})}{(1 - S_{11})}, \quad \text{whereas: } Z_1 = \frac{V_1}{I_1} \text{ is the input impedance at port 1}$$

$$|S_{11}|^2 = \frac{\text{Power reflected from input}}{\text{Power incident on input}}$$

$$|S_{22}|^2 = \frac{\text{Power reflected from output}}{\text{Power incident on output}}$$

$$|S_{21}|^2 = \text{Forward transmitted power with } Z_S = Z_L = Z_c$$

$$|S_{12}|^2 = \text{Backward transmitted power with } Z_S = Z_L = Z_c$$

Here the US notion is used, where power = $|a|^2$.
European notation (often): power = $|a|^2/2$
These conventions have no impact on S parameters, only relevant for absolute power calculation

The Scattering-Matrix (1)

Waves traveling towards the n-port: $(a) = (a_1, a_2, a_3, \ldots a_n)$
Waves traveling away from the n-port: $(b) = (b_1, b_2, b_3, \ldots b_n)$

The relation between a_i and b_i (i = 1..n) can be written as a **system of n linear equations** (a_i = the independent variable, b_i = the dependent variable):

one - port	$b_1 = S_{11}a_1 + S_{12}a_2 + S_{13}a_3 + S_{14}a_4 + \ldots$
two - port	$b_2 = S_{21}a_1 + S_{22}a_2 + S_{23}a_3 + S_{44}a_4 + \ldots$
three - port	$b_3 = S_{31}a_1 + S_{32}a_2 + S_{33}a_3 + S_{44}a_4 + \ldots$
four - port	$b_4 = S_{41}a_1 + S_{42}a_2 + S_{33}a_3 + S_{44}a_4 + \ldots$

In compact matrix notation, these equations can also be written as:

$$(b) = (S)(a)$$

The Scattering Matrix (2)

The simplest form is a passive **one-port (2-pole)** with some reflection coefficient Γ.
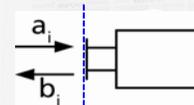
$$(S) = S_{11} \quad \rightarrow \quad b_1 = S_{11}a_1$$

Reference plane

With the reflection coefficient Γ it follows that

$$S_{11} = \frac{b_1}{a_1} = \Gamma$$

What is the difference between Γ and S11 or S22?

- Γ is a general definition of some complex reflection coefficient.
- On the contrary, for a proper S-parameter measurement all ports of the Device Under Test (DUT) including the generator port must be terminated with their characteristic impedance in order to assure that waves traveling away from the DUT (b_n-waves) are not reflected back and convert into a_n-waves.
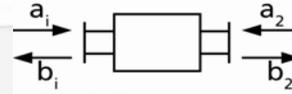
The Scattering Matrix (3)

Two-port (4-pole)

$$(S) = \begin{bmatrix} S_{11} & S_{12} \\ S_{21} & S_{22} \end{bmatrix} \qquad \begin{aligned} b_1 &= S_{11}a_1 + S_{12}a_2 \\ b_2 &= S_{21}a_1 + S_{22}a_2 \end{aligned}$$

A non-matched load present at port 2 with reflection coefficient Γ_{load} transfers to the input port as

$$\Gamma_{in} = S_{11} + S_{21}\frac{\Gamma_{load}}{1 - S_{22}\Gamma_{load}}S_{12}$$

- ◆ For a proper S-parameter measurement all ports of the Device Under Test (DUT) including the generator port must be terminated with their characteristic impedance in order to assure that waves traveling away from the DUT (b_n-waves) are not reflected back and convert into a_n-waves.

Evaluation of scattering parameters (1)

<u>Basic relation:</u>

$$b_1 = S_{11}a_1 + S_{12}a_2$$
$$b_2 = S_{21}a_1 + S_{22}a_2$$

<u>Finding S_{11}, S_{21}:</u> ("forward" parameters, assuming port 1 = input, port 2 = output e.g. in a transistor)

- connect a generator at port 1 and inject a wave a_1 into it
- connect reflection-free terminating lead at port 2 to assure $a_2 = 0$
- calculate/measure
  - wave b_1 (reflection at port 1, no transmission from port2)
  - wave b_2 (reflection at port 2, no transmission from port1)
- evaluate

$$S_{11} = \frac{b_1}{a_1}\bigg|_{a_2=0} \qquad \text{"input reflection factor"}$$

$$S_{21} = \frac{b_2}{a_1}\bigg|_{a_2=0} \qquad \text{"forward transmission factor"}$$

DUT = Device Under Test

Matched receiver or detector

$Z_g = 50\Omega$

4-port

DUT 2-port

Directional Coupler

prop. a_1

proportional b_1

proportional b_2

13

Evaluation of scattering parameters (2)

Finding S_{12}, S_{22}: ("backward" parameters)

- interchange generator and load
- proceed in analogy to the forward parameters, i.e. inject wave a_2 and assure $a_1 = 0$
- evaluate

$$S_{12} = \left. \frac{b_1}{a_2} \right|_{a_1=0} \qquad \text{"backward transmission factor"}$$
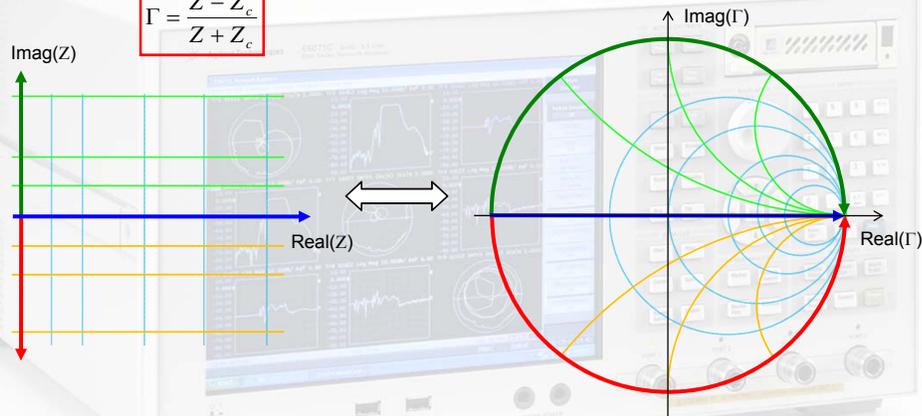
$$S_{22} = \left. \frac{b_2}{a_2} \right|_{a_1=0} \qquad \text{"output reflection factor"}$$

For a proper S-parameter measurement all ports of the Device Under Test (DUT) including the generator port must be terminated with their characteristic impedance in order to assure that waves traveling away from the DUT (b_n-waves) are not reflected back and convert into a_n-waves.

The Smith Chart (1)

The Smith Chart (in impedance coordinates) represents the complex Γ-plane within the unit circle. It is a conformal mapping of the complex Z-plane on the Γ-plane using the transformation:

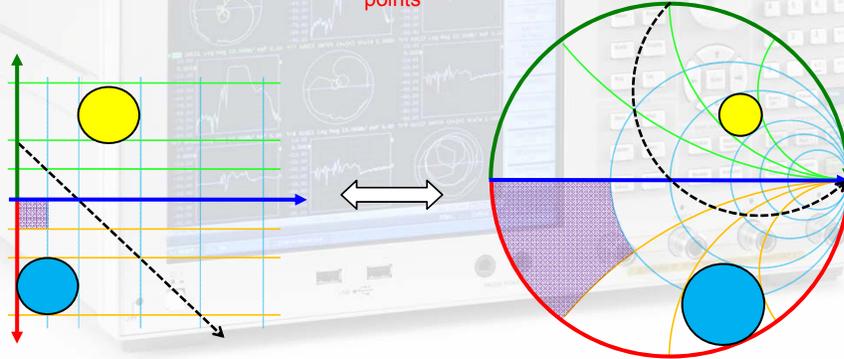$$\Gamma = \frac{Z - Z_c}{Z + Z_c}$$

→The real positive half plane of Z is thus transformed into the interior of the unit circle!

The Smith Chart (2)

This is a "bilinear" transformation with the following properties:
- generalized circles are transformed into generalized circles
  - circle → circle
  - straight line → circle
  - circle → straight line
  - straight line → straight line
- angles are preserved locally

a straight line is nothing else than a circle with infinite radius

a circle is defined by 3 points

a straight line is defined by 2 points

The Smith Chart (3)

Impedances Z are usually first normalized by
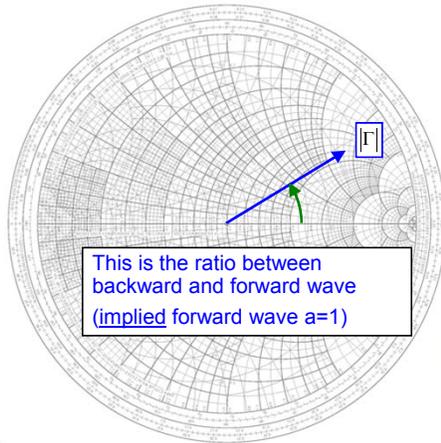
$$z = \frac{Z}{Z_c}$$

where Z_0 is some characteristic impedance (e.g. 50 Ohm). The general form of the transformation can then be written as

$$\Gamma = \frac{z-1}{z+1} \quad resp. \quad z = \frac{1+\Gamma}{1-\Gamma}$$

This mapping offers several practical advantages:

1. The diagram includes all "passive" impedances, i.e. those with positive real part, from zero to infinity in a handy format. Impedances with negative real part ("active device", e.g. reflection amplifiers) would be outside the (normal) Smith chart.

2. The mapping converts impedances or admittances into reflection factors and vice-versa. This is particularly interesting for studies in the radiofrequency and microwave domain where electrical quantities are usually expressed in terms of "direct" or "forward" waves and "reflected" or "backward" waves. This replaces the notation in terms of currents and voltages used at lower frequencies. Also the reference plane can be moved very easily using the Smith chart.

15

The Smith Chart (4)

The Smith Chart (*Abaque Smith* in French) is the linear representation of the complex reflection factor

$$\Gamma = \frac{b}{a}$$

i.e. the ratio backward/forward wave.

The upper half of the Smith-Chart is "inductive" = positive imaginary part of impedance, the lower half is "capacitive" = negative imaginary part.
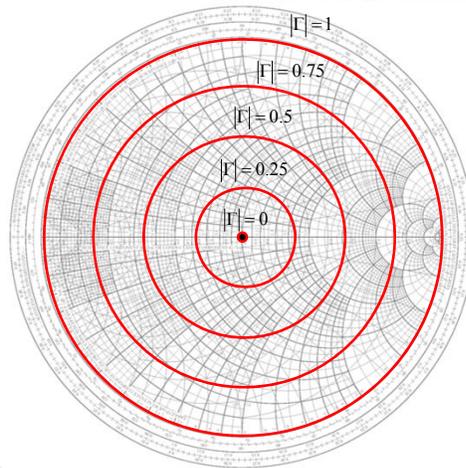
$|\Gamma|$

This is the ratio between backward and forward wave (implied forward wave a=1)

The Smith Chart (5)

3. The distance from the center of the diagram is directly proportional to the magnitude of the reflection factor. In particular, the perimeter of the diagram represents total reflection, $|\Gamma|=1$. This permits easy visualization matching performance.

(Power dissipated in the load) = (forward power) – (reflected power)

$$P = |a|^2 - |b|^2$$
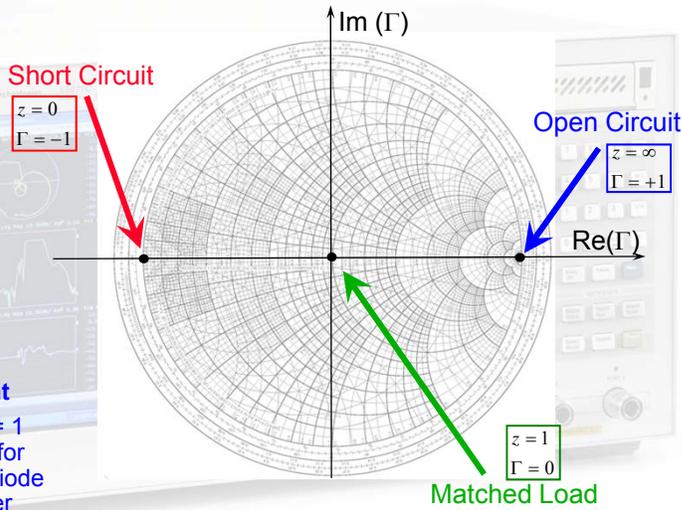$$= |a|^2 \left(1 - |\Gamma|^2\right)$$

available source power

"(mismatch)" loss

$|\Gamma| = 1$

$|\Gamma| = 0.75$

$|\Gamma| = 0.5$

$|\Gamma| = 0.25$

$|\Gamma| = 0$

16

Important points

Important Points:

- **Short Circuit**
  $\Gamma = -1, z = 0$

- **Open Circuit**
  $\Gamma = 1, z \to \infty$

- **Matched Load**
  $\Gamma = 0, z = 1$

- On circle $\Gamma = 1$
  lossless element

- Outside circle $\Gamma = 1$
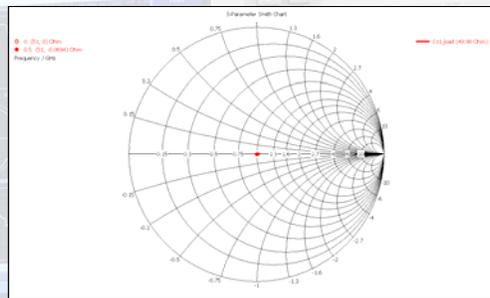 **active element**, for instance tunnel diode reflection amplifier

Short Circuit
$z = 0$
$\Gamma = -1$

Open Circuit
$z = \infty$
$\Gamma = +1$

Im (Γ)

Re(Γ)

$z = 1$
$\Gamma = 0$

Matched Load

Coming back to our example

matched case:
pure traveling wave=> no reflection

Coax cable with vacuum or air
with a lenght of 30 cm

f=0.25 GHz
λ/4=30cm

f=1 GHz
λ/4=7.5cm

Caution: on the printout this snap shot of the traveling wave appears as a standing wave, however this is meant to be a traveling wave

17

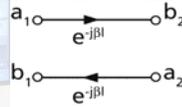# Impedance transformation by transmission lines

The S-matrix for an ideal, lossless transmission line of length L is given by

$$\mathbf{S} = \begin{bmatrix} 0 & e^{-j\beta l} \\ e^{-j\beta l} & 0 \end{bmatrix}$$
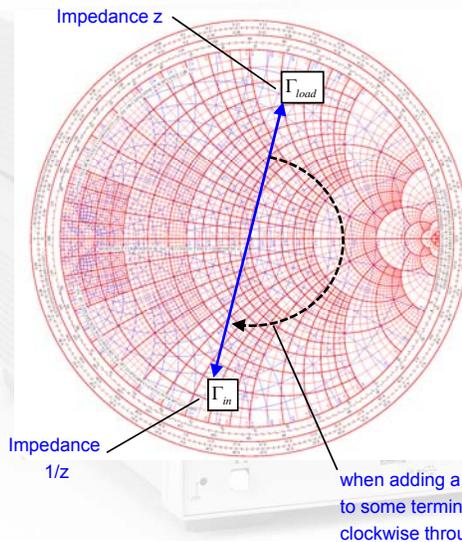
where $\beta = 2\pi / \lambda$

is the propagation coefficient with the wavelength λ (this refers to the wavelength on the line containing some dielectric).

$a_1 \circ \xrightarrow{e^{-j\beta l}} \circ b_2$

$b_1 \circ \xleftarrow{e^{-j\beta l}} \circ a_2$

$$\Gamma_{in} = \Gamma_{load}\, e^{-j2\beta l}$$

How to remember that when adding a section of line we have to turn clockwise: assume we are at Γ = -1 (short circuit) and add a very short piece of coaxial cable. Then we have made an inductance thus we are in the upper half of the Smith-Chart.

N.B.: It is supposed that the reflection factors are evaluated with respect to the characteristic impedance Z_c of the line segment.

λ/4 - Line transformations

Impedance z

Γ_{load}

Impedance 1/z

Γ_{in}

when adding a transmission line to some terminating impedance we move clockwise through the Smith-Chart.

A transmission line of length

$$l = \lambda / 4$$

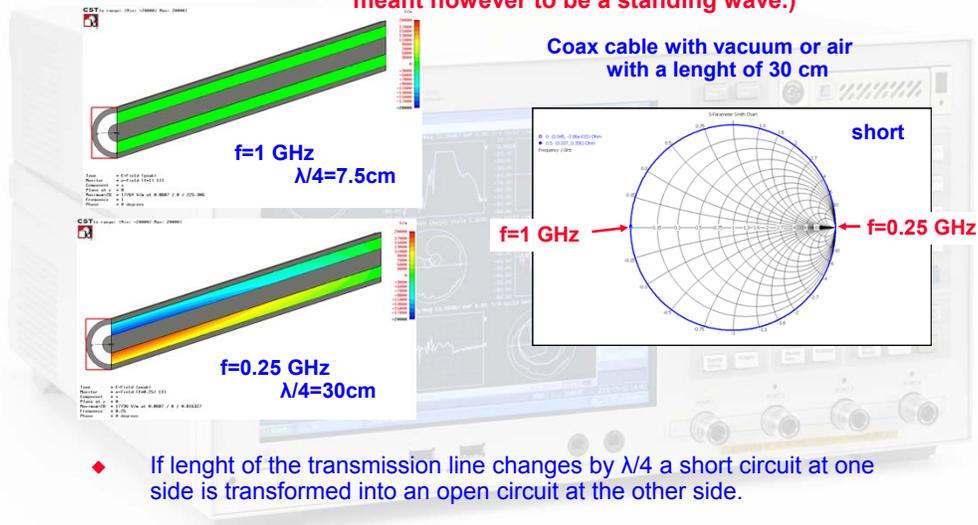transforms a load reflection Γ_{load} to its input as

$$\Gamma_{in} = \Gamma_{load}\, e^{-j2\beta l} = \Gamma_{load}\, e^{-j\pi} = -\Gamma_{load}$$

This means that a normalized load impedance z is transformed into 1/z.

In particular, a short circuit at one end is transformed into an open circuit at the other. This is the principle of λ/4-resonators.
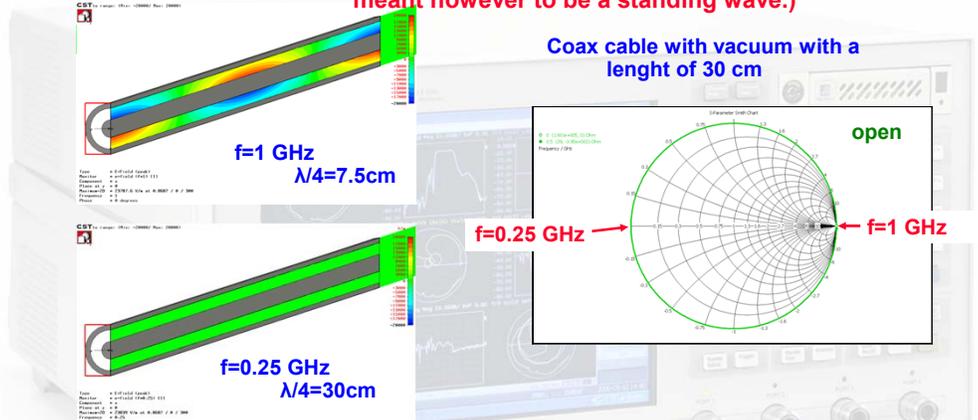
Again our example (shorted end)

short : standing wave (on the printout you see only a snapshot of movie. It is meant however to be a standing wave.)

Coax cable with vacuum or air with a lenght of 30 cm

f=1 GHz
λ/4=7.5cm

f=0.25 GHz
λ/4=30cm

short

f=1 GHz → ← f=0.25 GHz

◆ If lenght of the transmission line changes by λ/4 a short circuit at one side is transformed into an open circuit at the other side.

Again our example (open end)

open : standing wave (on the printout you see only a snapshot of movie. It is meant however to be a standing wave.)

Coax cable with vacuum with a lenght of 30 cm

f=1 GHz
λ/4=7.5cm

f=0.25 GHz
λ/4=30cm

open

f=0.25 GHz → ← f=1 GHz

◆ The patterns for the short and open terminated case appear similar; However, the phase is shifted which correspond to a different position of the nodes.

◆ If the length of a transmission line changes by λ/4, an open become a short and vice versa!
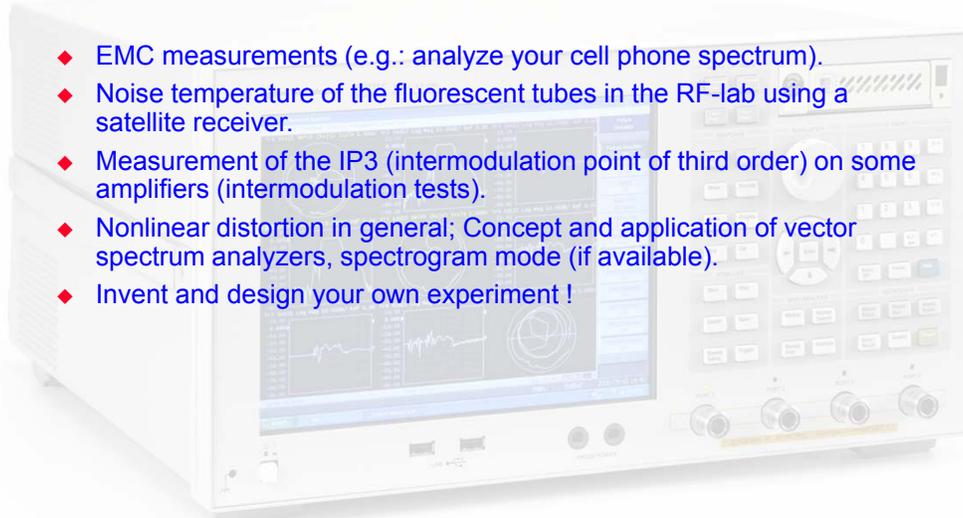
What awaits you?

Photo from RF-Lab CAS 2011, CHIOS

Measurements using Spectrum Analyzer and oscilloscope (1)

- Measurements of several types of modulation (AM, FM, PM) in the time-domain and frequency-domain.
- Superposition of AM and FM spectrum (unequal height side bands).
- Concept of a spectrum analyzer: the superheterodyne method. Practice all the different settings (video bandwidth, resolution bandwidth etc.). Advantage of FFT spectrum analyzers.
- Measurement of the RF characteristic of a microwave detector diode (output voltage versus input power... transition between regime output voltage proportional input power and output voltage proportional input voltage); i.e. transition between square low and linear region.
- Concept of noise figure and noise temperature measurements, testing a noise diode, the basics of thermal noise.
- Noise figure measurements on amplifiers and also attenuators.
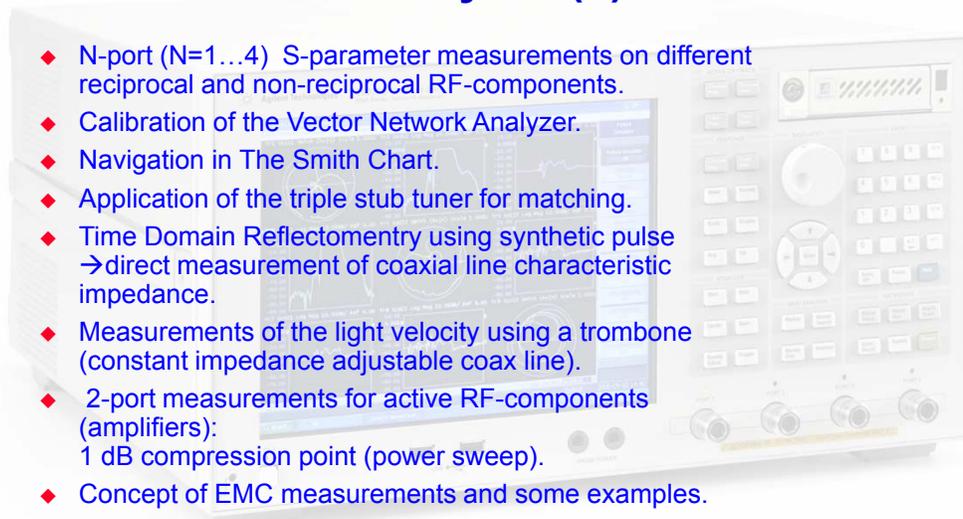- The concept and meaning of ENR (excess noise ratio) numbers.

Measurements using Spectrum Analyzer and oscilloscope (2)

- ◆ EMC measurements (e.g.: analyze your cell phone spectrum).
- ◆ Noise temperature of the fluorescent tubes in the RF-lab using a satellite receiver.
- ◆ Measurement of the IP3 (intermodulation point of third order) on some amplifiers (intermodulation tests).
- ◆ Nonlinear distortion in general; Concept and application of vector spectrum analyzers, spectrogram mode (if available).
- ◆ Invent and design your own experiment !

Measurements using Vector Network Analyzer (1)

- ◆ N-port (N=1…4) S-parameter measurements on different reciprocal and non-reciprocal RF-components.
- ◆ Calibration of the Vector Network Analyzer.
- ◆ Navigation in The Smith Chart.
- ◆ Application of the triple stub tuner for matching.
- ◆ Time Domain Reflectomentry using synthetic pulse →direct measurement of coaxial line characteristic impedance.
- ◆ Measurements of the light velocity using a trombone (constant impedance adjustable coax line).
- ◆ 2-port measurements for active RF-components (amplifiers):
  1 dB compression point (power sweep).
- ◆ Concept of EMC measurements and some examples.

Measurements using Vector Network Analyzer (2)

- ◆ Measurements of the characteristic cavity properties (Smith Chart analysis).
- ◆ Cavity perturbation measurements (bead pull).
- ◆ Beam coupling impedance measurements with the wire method (some examples).
- ◆ Beam transfer impedance measurements with the wire (button PU, stripline PU.)
- ◆ Self made RF-components: Calculate build and test your own attenuator in a SUCO box (and take it back home then).
- ◆ Invent and design your own experiment!

Invent your own experiment!

Build e.g. Doppler traffic radar (this really worked in practice during CAS 2011 RF-lab, CHIOS)

or „Tabacco-box" cavity

or test a resonator of any other type.

You will have enough time to think

and have a contact with hardware and your colleagues.

We hope you will have a lot of fun…

Appendix A: Definition of the Noise Figure

$$F = \frac{S_i / N_i}{S_o / N_o} = \frac{N_o}{GN_i} = \frac{N_o}{GkT_0 B} = \frac{GN_i + N_R}{GkT_0 B} = \frac{GkT_0 B + N_R}{GkT_0 B}$$

- F is the *Noise factor* of the receiver
- S_i is the available signal power at input
- $N_i = kT_0 B$ is the available noise power at input
- T_0 is the absolute temperature of the source resistance
- N_o is the available noise power at the output , including amplified input noise
- N_r is the noise added by receiver
- G is the available receiver gain
- B is the effective noise bandwidth of the receiver
- If the noise factor is specified in a logarithmic unit, we use the term Noise Figure (*NF*)

$$NF = 10 \lg \frac{S_i / N_i}{S_o / N_o} \, dB$$

Measurement of Noise Figure
(using a calibrated Noise Source)

Calibrated T_H, T_C Source — DUT — Power Meter

$kT_H B \longrightarrow$
$kT_C B \longrightarrow$

$N_{OH} = FGkT_O B + (T_H - T_O)kBG$
$N_{OC} = FGkT_O B + (T_C - T_O)kBG$

$$\therefore Y = \frac{N_{OH}}{N_{OC}} = \frac{FT_O + T_H - T_O}{FT_O + T_C - T_O}; \quad F = \frac{\left(\dfrac{T_H}{T_O} - 1\right) - Y\left(\dfrac{T_C}{T_O} - 1\right)}{Y - 1}$$

Example:
T_H=10,290°K (argon source), T_C=300°K
Measured Y factor: Y=9 dB (7.94:1)
Then,
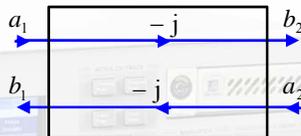
$$F = \frac{\dfrac{10290}{290} - 1 - 7.94\left(\dfrac{300}{290} - 1\right)}{7.94 - 1} = 4.94; \quad NF(dB) = 10 \log(4.94) = 6.9 dB$$

Appendix B: Examples of 2-ports (1)

Line of Z=50Ω, length l=λ/4
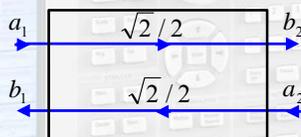
$$(S) = \begin{bmatrix} 0 & -j \\ -j & 0 \end{bmatrix} \quad \begin{array}{l} b_1 = -j\, a_2 \\ b_2 = -j\, a_1 \end{array}$$

Port 1: **Port 2:**

a_1 → $-j$ → b_2

b_1 ← $-j$ ← a_2

Attenuator 3dB, i.e. half output power

$$(S) = \frac{1}{\sqrt{2}} \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \quad \begin{array}{l} b_1 = \dfrac{1}{\sqrt{2}} a_2 = 0.707\, a_2 \\ b_2 = \dfrac{1}{\sqrt{2}} a_1 = 0.707\, a_1 \end{array}$$

a_1 → $\sqrt{2}/2$ → b_2

b_1 ← $\sqrt{2}/2$ ← a_2

RF Transistor

$$(S) = \begin{bmatrix} 0.277\, e^{-j59°} & 0.078\, e^{j93°} \\ 1.92\, e^{j64°} & 0.848\, e^{-j31°} \end{bmatrix}$$

backward transmission

forward transmission

non-reciprocal since $S_{12} \neq S_{21}$!
=different transmission forwards and backwards

a_1 → $1.92\, e^{j64°}$ → b_2

$0.277\, e^{-j59°}$

b_1 ← $0.848\, e^{-j31°}$ ← a_2

$0.078\, e^{j93°}$

Examples of 2-ports (2)

Ideal Isolator

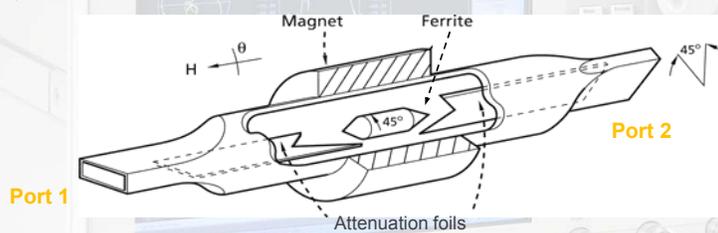$$(S) = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \quad b_2 = a_1$$

only forward transmission

Port 1: **Port 2:**

a_1 → → b_2

Faraday rotation isolator

Magnet   Ferrite

H

45°

45°

Port 2

Attenuation foils

Port 1

The left waveguide uses a TE_{10} mode (=vertically polarized H field). After transition to a circular waveguide, the polarization of the mode is rotated counter clockwise by 45° by a ferrite. Then follows a transition to another rectangular waveguide which is rotated by 45° such that the forward wave can pass unhindered. However, a wave coming from the other side will have its polarization rotated by 45° clockwise as seen from the right hand side.
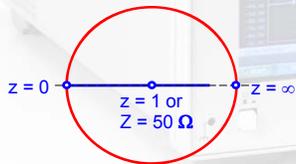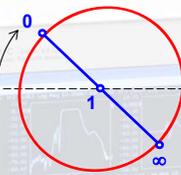
Looking through a 2-port (1)

In general:

$$\Gamma_{in} = S_{11} + \frac{S_{12} S_{21} \Gamma_L}{1 - S_{22} \Gamma_L}$$

were Γ_{in} is the reflection coefficient when looking through the 2-port and Γ_{load} is the load reflection coefficient.
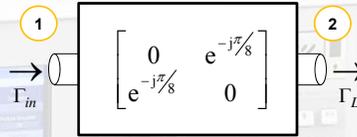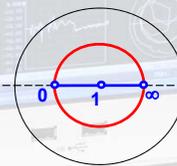
The outer circle and the real axis in the simplified Smith diagram below are mapped to other circles and lines, as can be seen on the right.
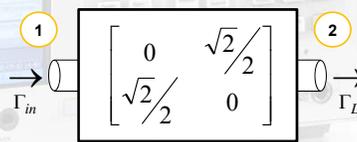
Line $\lambda/16$:

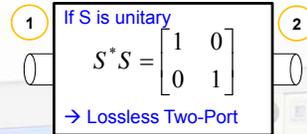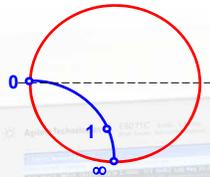$$\begin{bmatrix} 0 & e^{-j\pi/8} \\ e^{-j\pi/8} & 0 \end{bmatrix}$$

$$\Rightarrow \Gamma_{in} = \Gamma_L \, e^{-j\pi/4}$$

Attenuator 3dB:

$$\begin{bmatrix} 0 & \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} & 0 \end{bmatrix}$$

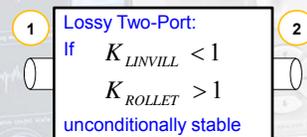$$\Rightarrow \Gamma_{in} = \frac{\Gamma_L}{2}$$

z = 0 z = 1 or Z = 50 Ω z = ∞

Looking through a 2-port (2)

Lossless Passive Circuit

Lossy Passive Circuit

Active Circuit

If S is unitary

$$S^* S = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

→ Lossless Two-Port

Lossy Two-Port:
If $\quad K_{LINVILL} < 1$
$\quad\quad K_{ROLLET} > 1$
unconditionally stable

Active Circuit:
If $\quad K_{LINVILL} \geq 1$
$\quad\quad K_{ROLLET} \leq 1$
potentially unstable

26

Examples of 3-ports (1)

Resistive power divider

Port 1: a_1 **Port 2:** b_2

$Z_0/3$ $Z_0/3$

b_1 a_2

$$(S) = \frac{1}{2}\begin{bmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{bmatrix}$$

$$b_1 = \frac{1}{2}(a_2 + a_3)$$

$$b_2 = \frac{1}{2}(a_1 + a_3)$$
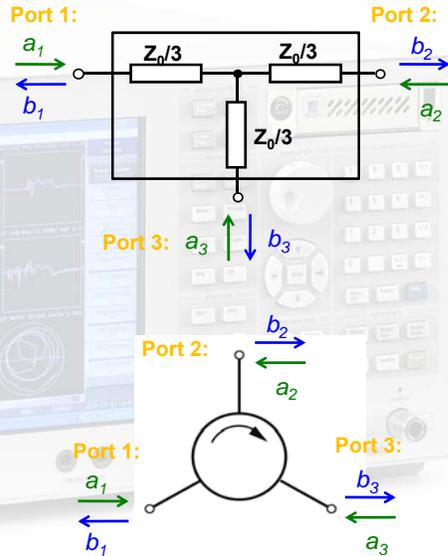
$$b_3 = \frac{1}{2}(a_1 + a_2)$$

$Z_0/3$

Port 3: a_3 b_3

3-port circulator

$$(S) = \begin{bmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

$$b_1 = a_3$$

$$b_2 = a_1$$

$$b_3 = a_2$$

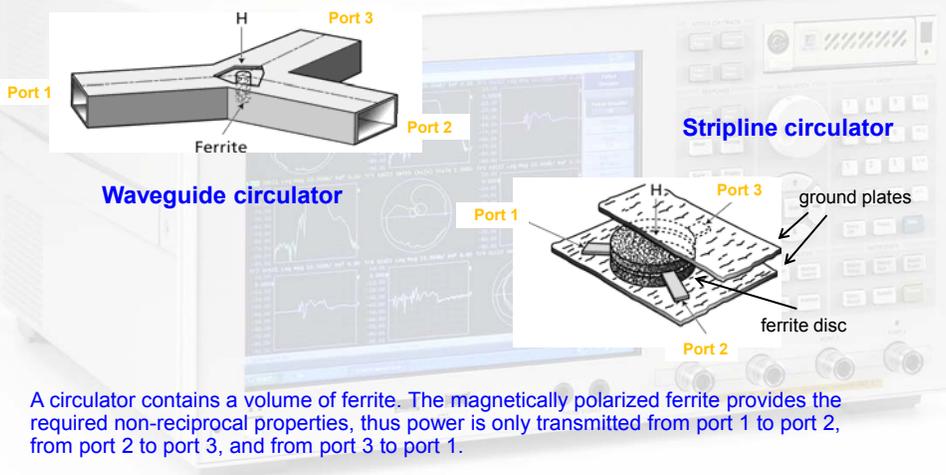**Port 2:** b_2 a_2

Port 1: a_1 b_1 **Port 3:** b_3 a_3

The ideal circulator is lossless, matched at all ports, but not reciprocal. A signal entering the ideal circulator at one port is transmitted exclusively to the next port in the sense of the arrow.

Examples of 3-ports (2)

Practical implementations of circulators:

H   Port 3

Port 1

Port 2

Ferrite

Waveguide circulator

Stripline circulator

H   Port 3   ground plates

Port 1

Port 2

ferrite disc

A circulator contains a volume of ferrite. The magnetically polarized ferrite provides the required non-reciprocal properties, thus power is only transmitted from port 1 to port 2, from port 2 to port 3, and from port 3 to port 1.

Examples of 4-ports (1)

Ideal directional coupler

$$(S) = \begin{bmatrix} 0 & \mathrm{j}k & \sqrt{1-k^2} & 0 \\ \mathrm{j}k & 0 & 0 & \sqrt{1-k^2} \\ \sqrt{1-k^2} & 0 & 0 & \mathrm{j}k \\ 0 & \sqrt{1-k^2} & \mathrm{j}k & 0 \end{bmatrix} \text{ with } k = \left| \frac{b_2}{a_1} \right|$$

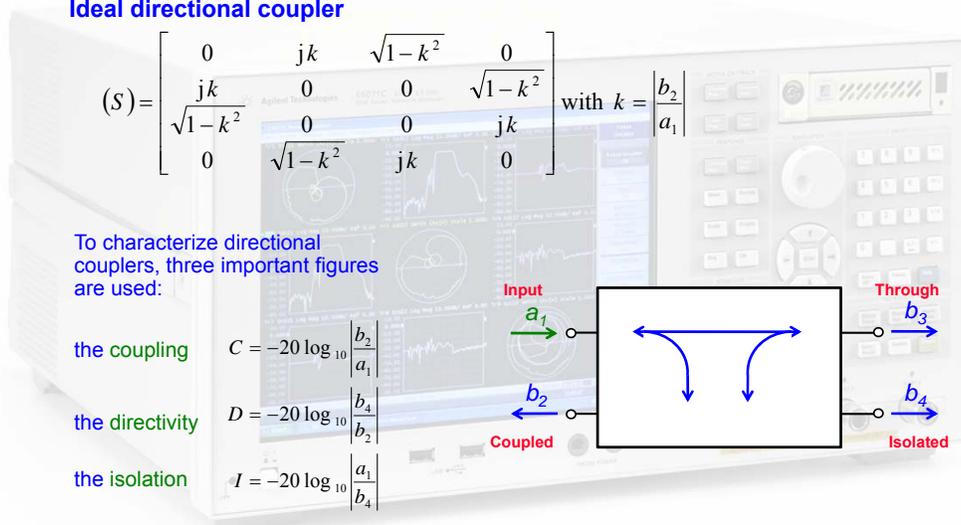To characterize directional couplers, three important figures are used:

the coupling $\quad C = -20 \log_{10} \left| \dfrac{b_2}{a_1} \right|$

the directivity $\quad D = -20 \log_{10} \left| \dfrac{b_4}{b_2} \right|$

the isolation $\quad I = -20 \log_{10} \left| \dfrac{a_1}{b_4} \right|$

Input a_1 — **Through** b_3

b_2 — **Coupled** — **Isolated** b_4

Appendix C: T matrix

The T-parameter matrix is related to the incident and reflected normalised waves at each of the ports.

$$\begin{pmatrix} b_1 \\ a_1 \end{pmatrix} = \begin{bmatrix} T_{11} & T_{12} \\ T_{21} & T_{22} \end{bmatrix} \begin{pmatrix} a_2 \\ b_2 \end{pmatrix}$$

T-parameters may be used to determine the effect of a cascaded 2-port networks by simply multiplying the individual T-parameter matrices:

$$[T] = \left[T^{(1)}\right]\left[T^{(2)}\right]...\left[T^{(N)}\right] = \prod_N \left[T^{(i)}\right]$$

b_1 — a_2 — b_3 — a_4
$T^{(1)}$ $T^{(2)}$
a_1 — b_2 — a_3 — b_4

T-parameters can be directly evaluated from the associated S-parameters and vice versa.
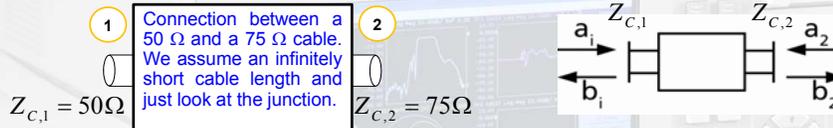
From S to T:

$$[T] = \frac{1}{S_{21}} \begin{bmatrix} -\det(S) & S_{11} \\ -S_{22} & 1 \end{bmatrix}$$

From T to S:

$$[S] = \frac{1}{T_{22}} \begin{bmatrix} T_{12} & \det(T) \\ 1 & -T_{21} \end{bmatrix}$$

Appendix D: A Step in Characteristic Impedance (1)

Consider a connection of two coaxial cables, one with $Z_{C,1}$ = 50 Ω characteristic impedance, the other with $Z_{C,2}$ = 75 Ω characteristic impedance.

Connection between a 50 Ω and a 75 Ω cable. We assume an infinitely short cable length and just look at the junction.

$Z_{C,1} = 50\Omega$ $Z_{C,2} = 75\Omega$

Step 1: Calculate the reflection coefficient and keep in mind: all ports have to be terminated with their respective characteristic impedance, i.e. 75 Ω for port 2.
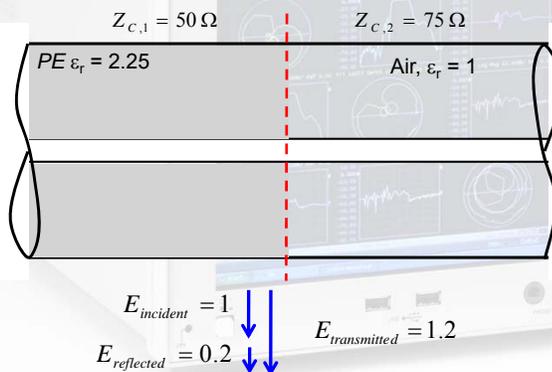
$$\Gamma_1 = \frac{Z - Z_{C,1}}{Z + Z_{C,1}} = \frac{75 - 50}{75 + 50} = 0.2$$

Thus, the voltage of the reflected wave at port 1 is 20% of the incident wave and the reflected power at port 1 (proportional Γ^2) is 0.2^2 = 4%. As this junction is lossless, the transmitted power must be 96% (conservation of energy). From this we can deduce $b_2^2 = 0.96$. But: how do we get the voltage of this outgoing wave?

Example: a Step in Characteristic Impedance (2)

Step 2: Remember, a and b are power-waves and defined as voltage of the forward- or backward traveling wave normalized to $\sqrt{Z_c}$.

The tangential electric field in the dielectric in the 50 Ω and the 75 Ω line, respectively, must be continuous.

$Z_{C,1} = 50\,\Omega$ $Z_{C,2} = 75\,\Omega$

$PE\ \varepsilon_r = 2.25$ Air, $\varepsilon_r = 1$

$E_{incident} = 1$

$E_{reflected} = 0.2$ $E_{transmitted} = 1.2$

t = voltage transmission coefficient $t = 1 + \Gamma$ in this case.

This is counterintuitive, one might expect 1-Γ. Note that the voltage of the transmitted wave is higher than the voltage of the incident wave. But we have to normalize to $\sqrt{Z_c}$ to get the corresponding S-parameter. $S_{12} = S_{21}$ via reciprocity! But $S_{11} \neq S_{22}$, i.e. the structure is NOT symmetric.

Example: a Step in Characteristic Impedance (3)

Once we have determined the voltage transmission coefficient, we have to normalize to the ratio of the characteristic impedances, respectively. Thus we get for

$$S_{12} = 1.2\sqrt{\frac{50}{75}} = 1.2 \cdot 0.816 = 0.9798$$

We know from the previous calculation that the reflected <u>power</u> (proportional Γ^2) is 4% of the incident power. Thus 96% of the power are transmitted.

Check done $\quad S_{12}{}^2 = 1.44\frac{1}{1.5} = 0.96 = (0.9798)^2$

$$S_{22} = \frac{50-75}{50+75} = -0.2 \quad \text{To be compared with S11 = +0.2!}$$
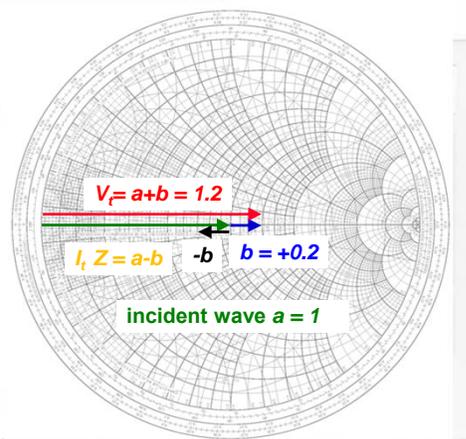

Example: a Step in Characteristic Impedance (4)

Visualization in the Smith chart:

As shown in the previous slides the voltage of the transmitted wave is

$V_t = a + b$ with $t = 1 + \Gamma$
and subsequently the current is

$I_t Z = a - b$.

Remember: the reflection coefficient Γ is defined with respect to voltages. For currents the sign inverts. Thus a positive reflection coefficient in the normal definition leads to a subtraction of currents or is negative with respect to current.
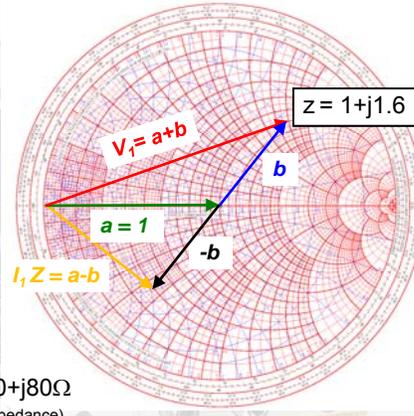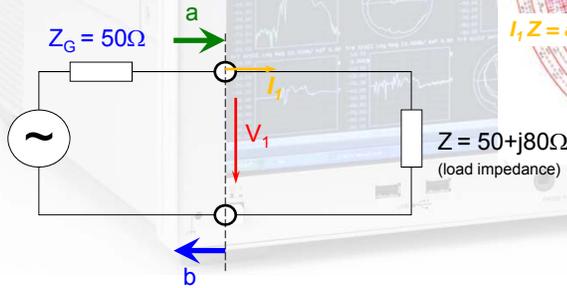
$V_t = a+b = 1.2$

$I_t Z = a-b$ -b   b = +0.2

incident wave a = 1
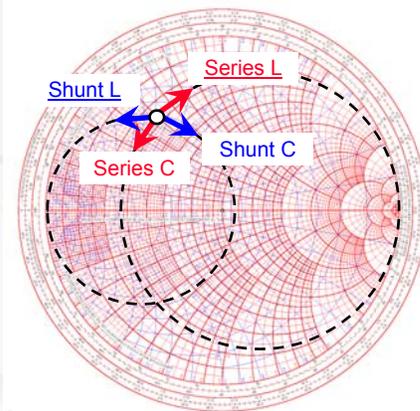
Note: here Z_{load} is real

Example: a Step in Characteristic Impedance (5)

General case:

Thus we can read from the Smith chart immediately the amplitude and phase of voltage and current on the load (of course we can calculate it when using the complex voltage divider).

$Z_G = 50\Omega$

$Z = 50+j80\Omega$
(load impedance)

$z = 1+j1.6$

$V_1 = a+b$

b

$a = 1$

$-b$

$I_1 Z = a-b$

Appendix E: Navigation in the Smith Chart (1)

in blue: Impedance plane (=Z)

in red: Admittance plane (=Y)

Series L

Shunt L

Shunt C

Series C

	Up	Down
Red circles	Series L	Series C
Blue circles	Shunt L	Shunt C

31

Navigation in the Smith Chart (2)

G

R

Toward load

Toward generator

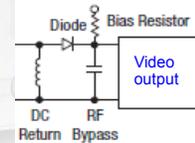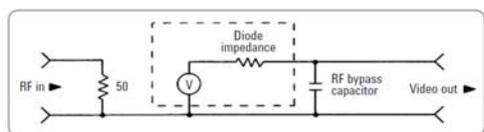| Red arcs	Resistance R
Blue arcs	Conductance G
Con-centric circle	Transmission line going Toward load Toward generator

Appendix F: The RF diode (1)

- We are not discussing the generation of RF signals here, just the detection
- Basic tool: fast RF* diode (= Schottky diode)
- In general, Schottky diodes are fast but still have a voltage dependent junction capacity (metal – semi-conductor junction)

A typical RF detector diode

Try to guess from the type of the connector which side is the RF input and which is the output

Equivalent circuit:

RF in ▶ 50 Diode impedance V RF bypass capacitor Video out ▶

Diode Bias Resistor
Video output
DC Return RF Bypass

*Please note, that in this lecture we will use RF for both the RF and micro wave (MW) range, since the borderline between RF and MW is not defined unambiguously
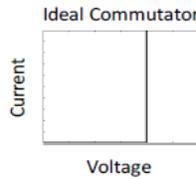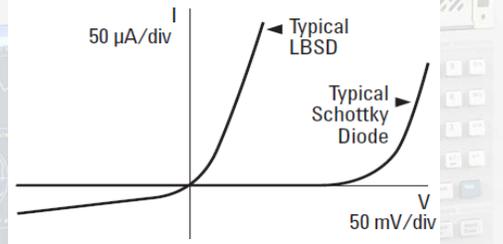
32

The RF diode (2)

◆ Characteristics of a diode:

The current as a function of the voltage for a barrier diode can be described by the Richardson equation:

$$I = AA^{**}_2 \, exp\left(-\frac{q\phi B}{kT}\right)\left[exp\left(\frac{qv}{NkT}\right)-1\right]$$

where
A = area (cm²)
A** = modified Richardson constant (amp/oK)²/cm²)
k = Boltzman's Constant
T = absolute temperature (°K)
ϕB = barrier heights in volts
V = external voltage across the depletion layer
(positive for forward voltage) - V - IR$_S$
R$_S$ = series resistance
I = diode current in amps (positive forward current)
n = ideality factor

I
50 µA/div ◄ Typical LBSD

Typical Schottky Diode

V
50 mV/div

Ideal Commutator

Current

Voltage

◆The RF diode is NOT an ideal commutator for small signals! We cannot apply big signals otherwise burnout
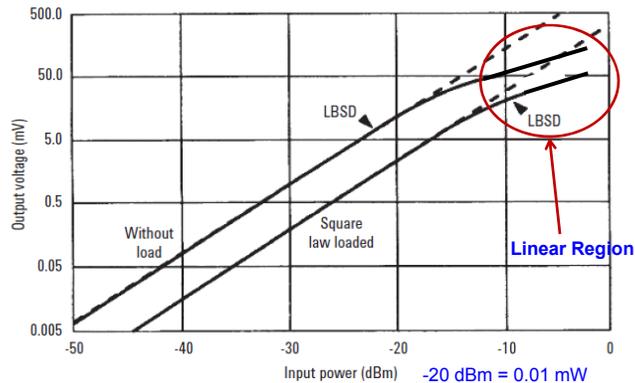

The RF diode (3)

◆ This diagram depicts the so called square-law region where the output voltage (V$_{Video}$) is proportional to the input power

Since the input power is proportional to the square of the input voltage (V$_{RF}^2$) and the output signal is proportional to the input power, this region is called square- law region.

In other words:

$$V_{Video} \sim V_{RF}^2$$

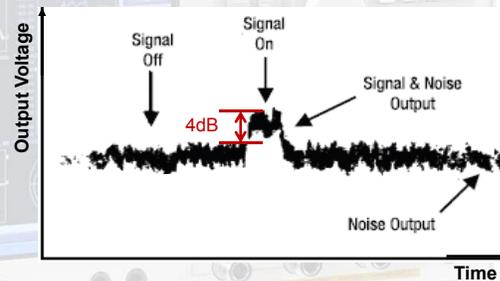Output voltage (mV)

500.0

50.0

5.0

0.5

0.05

0.005

LBSD

LBSD

Without load

Square law loaded

Linear Region

-50   -40   -30   -20   -10   0

Input power (dBm)   -20 dBm = 0.01 mW

◆ The transition between the linear region and the square-law region is typically between -10 and -20 dBm RF power (see diagram).

33

The RF diode (5)

- Due to the square-law characteristic we arrive at the thermal noise region already for moderate power levels (-50 to -60 dBm) and hence the V_{Video} disappears in the thermal noise

- This is described by the term *tangential signal sensitivity* (TSS) where the detected signal (Observation BW, usually 10 MHz) is 4 dB over the thermal noise floor

---

Appendix G: The RF mixer (1)

- For the detection of very small RF signals we prefer a device that has a linear response over the full range (from 0 dBm (= 1mW) down to thermal noise = -174 dBm/Hz = $4 \cdot 10^{-21}$ W/Hz)
- This is the RF mixer which is using 1, 2 or 4 diodes in different configurations (see next slide)
- Together with a so called LO (local oscillator) signal, the mixer works as a signal multiplier with a very high dynamic range since the output signal is always in the "linear range" provided, that the mixer is not in saturation with respect to the RF input signal (For the LO signal the mixer should always be in saturation!)
- The RF mixer is essentially a multiplier implementing the function

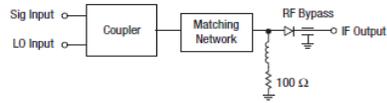 $f_1(t) \cdot f_2(t)$ with $f_1(t)$ = RF signal and $f_2(t)$ = LO signal

$$a_1 \cos(2\pi f_1 t + \varphi) \cdot a_2 \cos(2\pi f_2 t) = \frac{1}{2} a_1 a_2 [\cos((f_1 + f_2)t + \varphi) + \cos((f_1 - f_2)t + \varphi)]$$

- Thus we obtain a response at the IF (intermediate frequency) port that is at the sum and difference frequency of the LO and RF signals
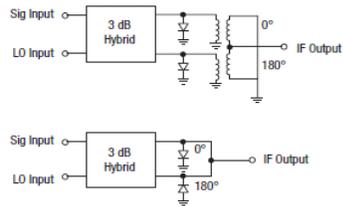
The RF mixer (2)

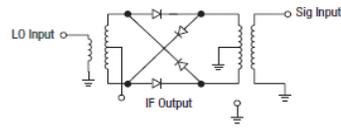◆ **Examples of different mixer configurations**

A. Single-Ended Mixer

Sig Input — Coupler — Matching Network — RF Bypass — IF Output — 100 Ω

B. Balanced Mixers

Sig Input — 3 dB Hybrid — 0° / 180° — IF Output

Sig Input — 3 dB Hybrid — 0° / 180° — IF Output

C. Double-Balanced Mixer

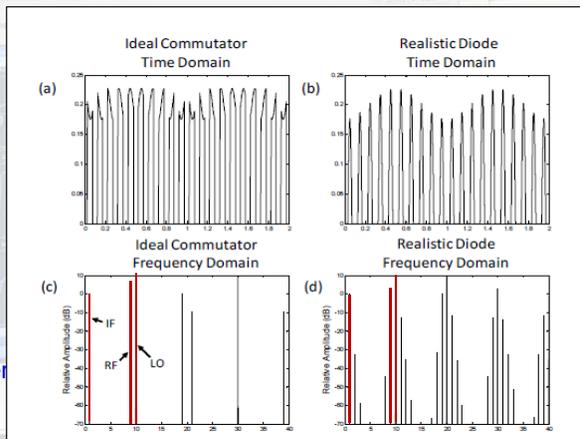LO Input — Sig Input — IF Output

HMC-C035 MIXER

◆ A typical coaxial mixer (SMA connector)

The RF mixer (3)

◆ **Response of a mixer in time and frequency domain:**

◆ Input signals here:
◆ LO = 10 MHz
◆ RF = 8 MHz

◆ Mixing products at 2 and 18 MHz and higher order terms at higher frequencies

Ideal Commutator Time Domain (a)

Realistic Diode Time Domain (b)

Ideal Commutator Frequency Domain (c)

Realistic Diode Frequency Domain (d)

The RF mixer (4)

Dynamic range and IP3 of an RF mixer

◆ The abbreviation IP3 stands for the third order intermodulation point where the two lines shown in the right diagram intersect. Two signals $(f_1, f_2 > f_1)$ which are closely spaced by Δf in frequency are simultaneously applied to the DUT. The intermodulation products appear at $+ \Delta f$ above f_2 and at $- \Delta f$ below f_1.

◆ This intersection point is usually not measured directly, but extrapolated from measurement data at much smaller power levels in order to avoid overload and damage of the DUT.

TYPICAL 2-TONE 3rd-ORDER
INPUT INTERCEPT POINT, +16dBm

◆ DESIRED IF OUTPUT
□ 3rd ORDER IM OUTPUT

-17 - (-69) = 52dB suppression
IM3 Level = -52dBc

-72dBc

-92dBc

IF OUTPUT POWER, EACH TONE, dBm

RF INPUT POWER, EACH TONE, dBm

71