



# Development of a 3.2 Gpixel Camera for the Large Synoptic Survey Telescope (LSST)

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LSST Camera Electronics Project Manager

For the LSST Camera Electronics Team

15-Sept-2008





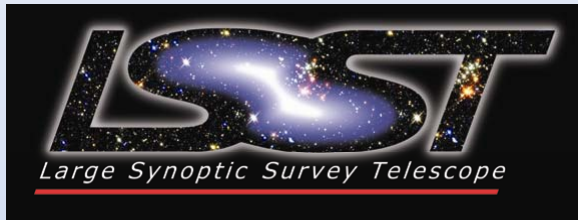
## Overview

- Major science drivers
- Critical specifications
- Telescope
- Camera
  - Sensors
  - Readout electronics



## Major Science Drivers

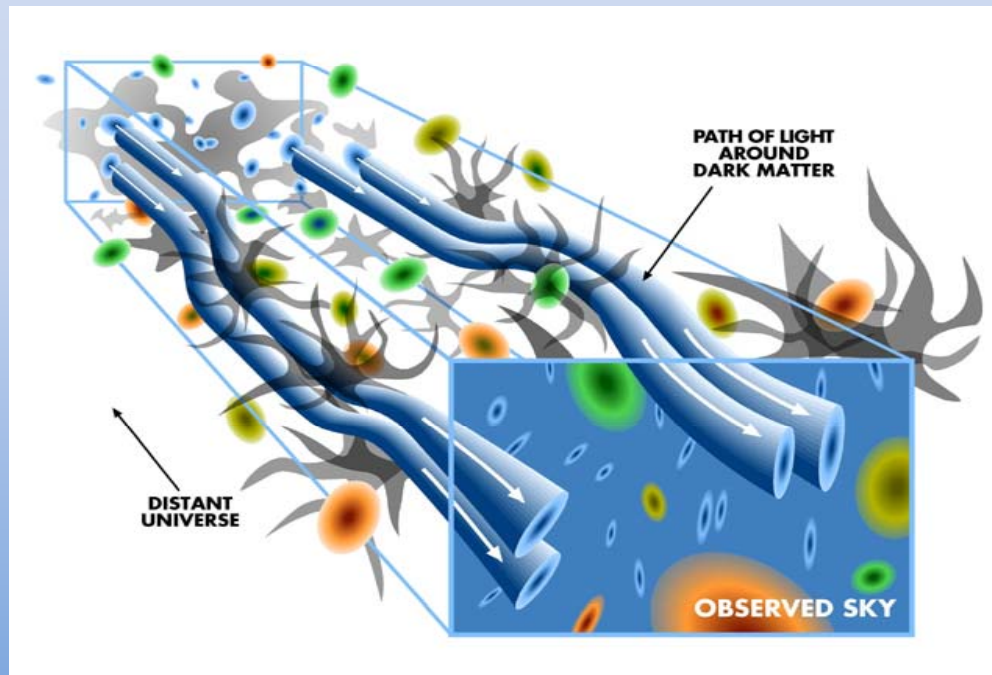
- “Synoptic survey” : Comprehensive & multipurpose
- Survey entire visible sky ( $20,000 \text{ deg}^2$ ) in five filter bands (400 nm – 1,000 nm) every 3 nights
  - ◆ Dark matter survey → Weak gravitational lensing
  - ◆ Dark energy probe → Type 1a supernovae discovery  $> 10^3/\text{night}$
- Galactic structure
- Near Earth Objects & Potentially Hazardous Asteroids
- Transient phenomena



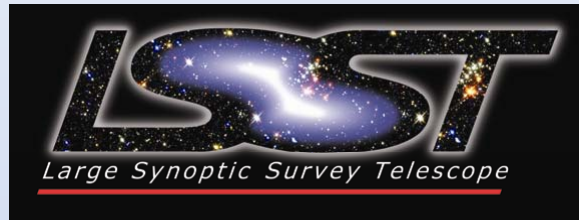
# Dark Matter Survey

- Weak lensing-

Apparent rotation of ellipticities of faint galaxies  
→ Cosmic Shear



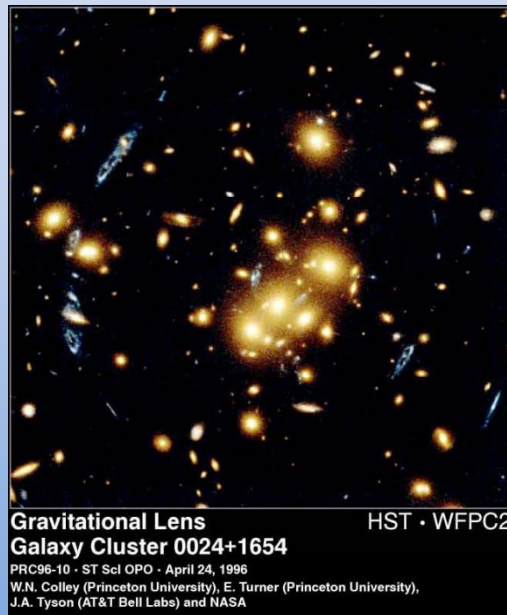
T. Tyson



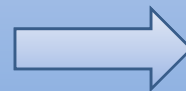
# Dark Matter Survey

- Weak lensing -

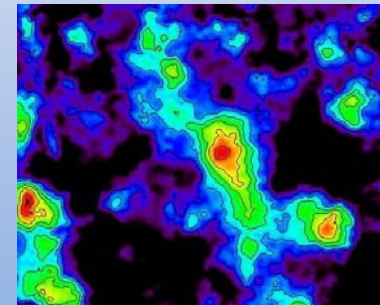
Strongly lensed galaxy



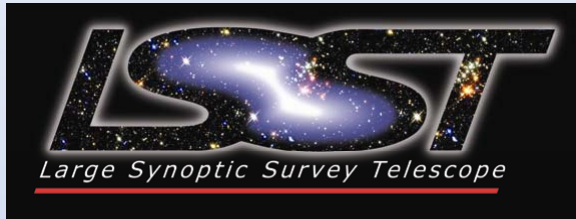
- Weak lensing -  
Measurements of ellipticity  
correlations of large  
numbers of faint galaxies  
→ “cosmic shear”



Tomographic  
reconstruction of dark  
matter density from  
shear data



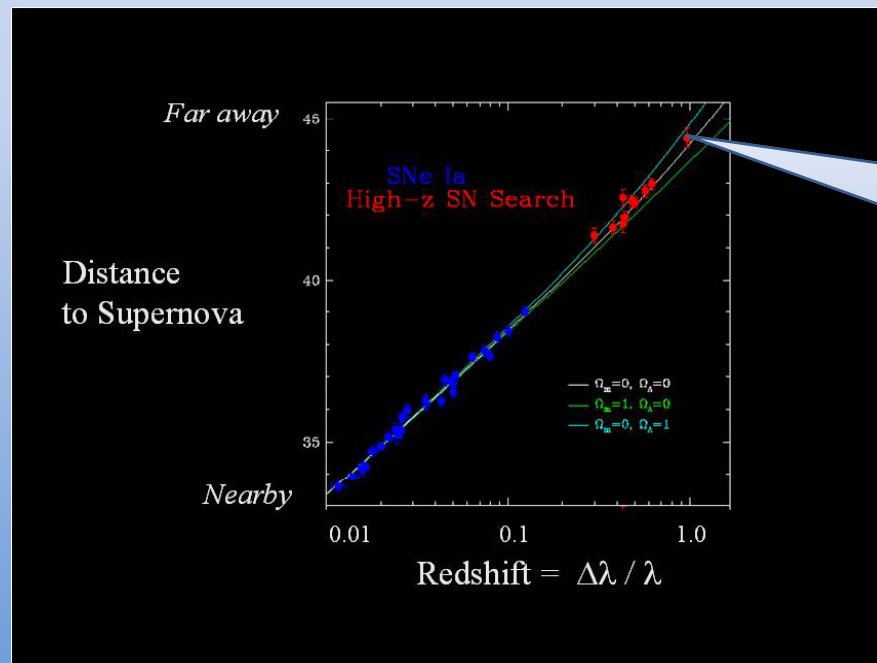
T. Tyson



# Dark Energy Measurement

- Type 1A Supernovae -

- High statistics measurements of Type 1A SN  $\rightarrow > 10^3$  per observing night
- Redshift & distance measurement
  - Fixed luminosity (standard candle)  $\rightarrow$  distance
  - *Photometric* redshift measurements in five filter bands to  $Z = 1.2$



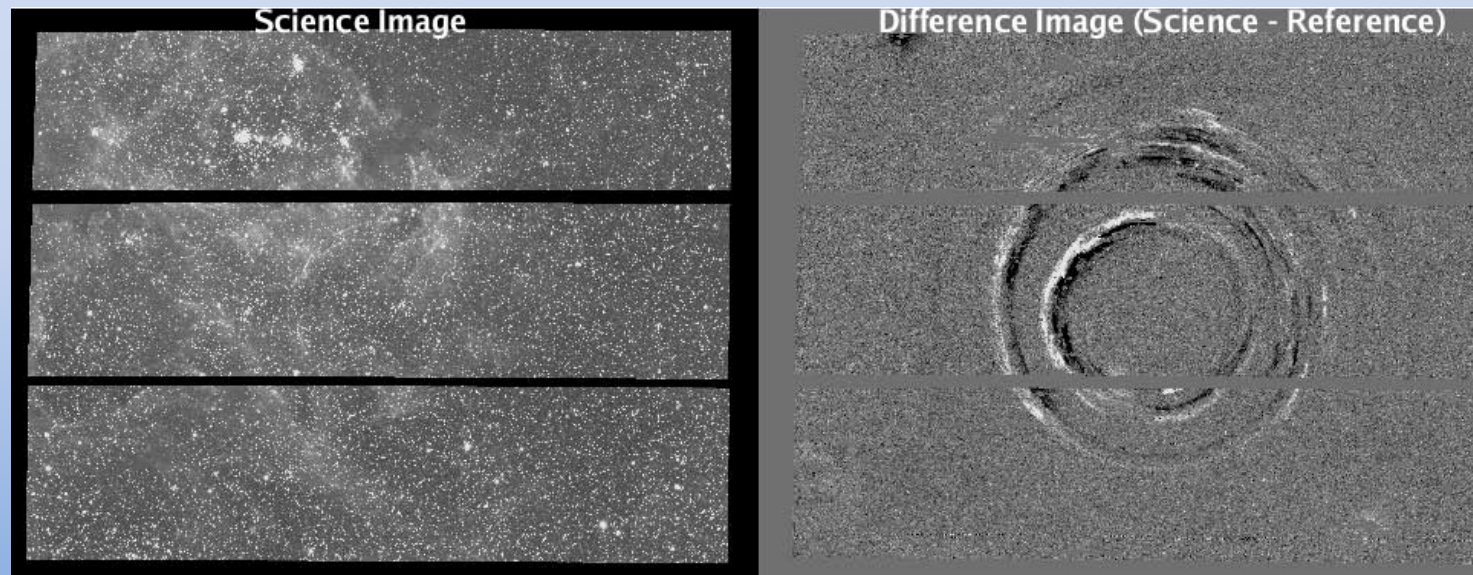
Deviations from linearity  
 $\rightarrow$  Acceleration  
 $\rightarrow$  Dark Energy  
 $\rightarrow$  Cosmological constant





## - Transient phenomena -

### Differential images of SN 1987A

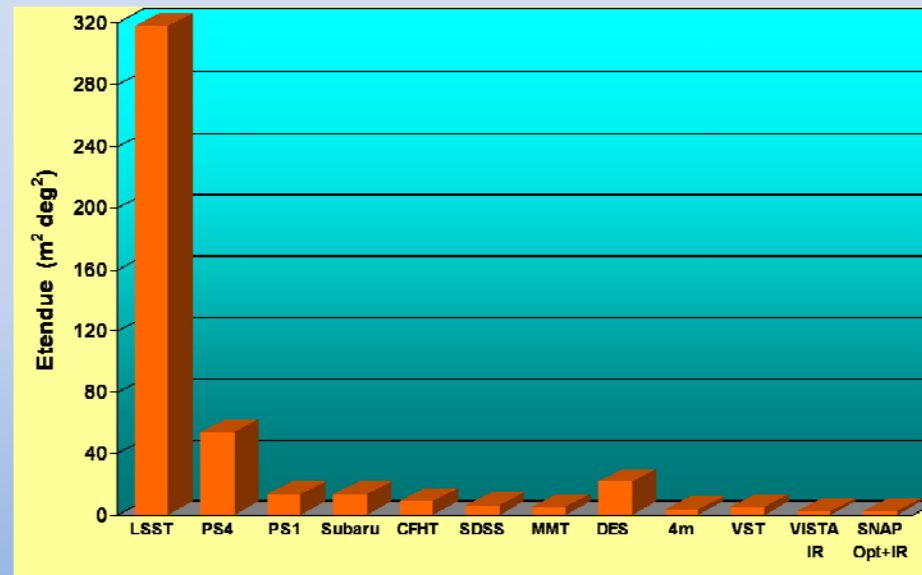


A. Becker, U. Washington (SDSS)



## Critical Specifications - Telescope -

- Survey telescope figure of merit “Etendue”  $\{(\text{Dia})^2 \times (\text{FoV solid angle})\}$

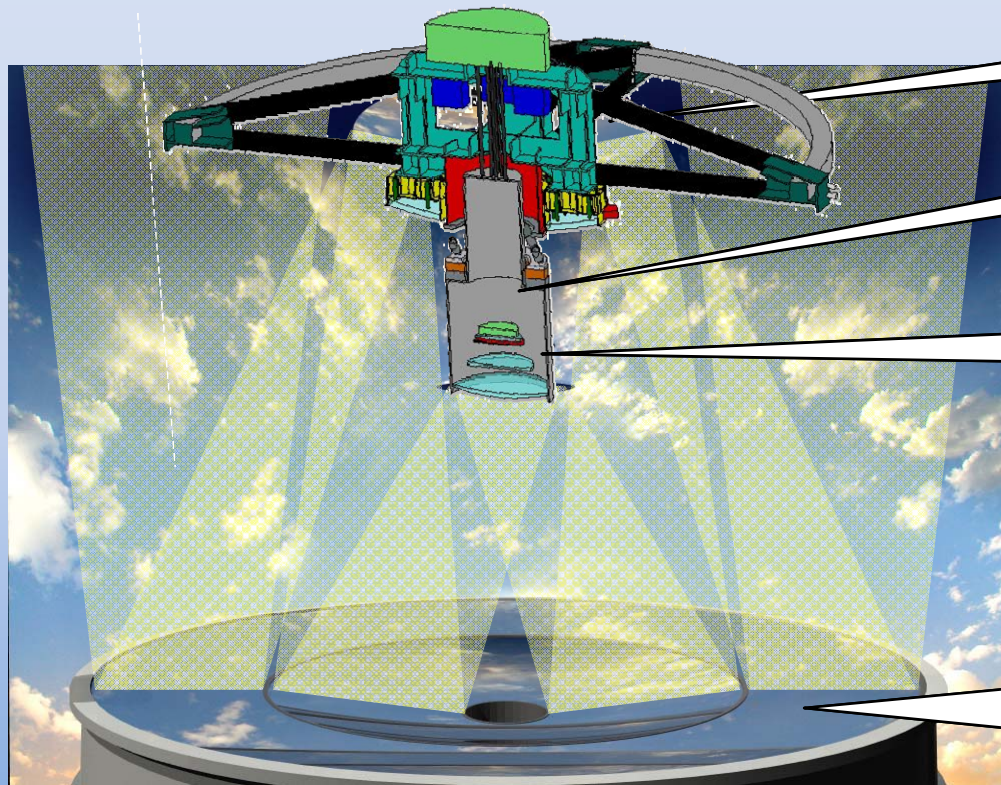


- Large aperture ~ 8.4 m, (6.7 m equivalent clear aperture)
- Large FoV ~ 3.5 deg
- Large focal plane ~ 64 cm diameter
- LSST Etendue ~ 320 (deg²)(m²)
- High “throughput”





## Optics



Convex secondary

Location of camera

Corrector lenses to form  
flat image plane

8.4 m primary/tertiary 6.7 m  
effective aperture  
Active optics [\*]  
fl~10 m → f1.2 beam

[\*] Corrects gravitational sag due to mirror inclination



## Spin casting at the Steward Mirror Lab U. Arizona



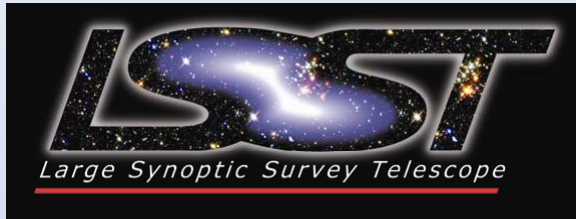
Lid is lifted from the primary/tertiary mirror blank 23-July-08  
Made possible by grant from Bill Gates, Charles Simonyi – Microsoft Corp.



## Critical Specifications - Camera & Sensors-

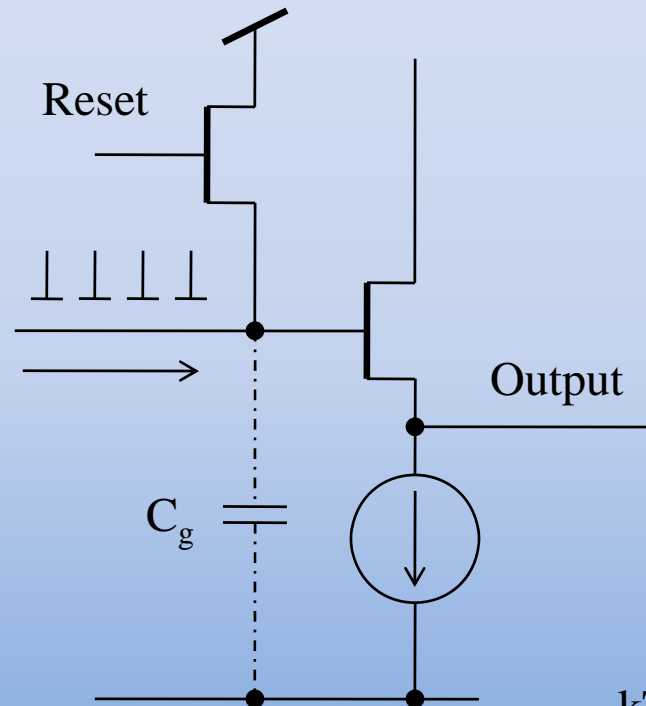
- Image sensors
  - Large focal plane → ~ 64 cm dia
  - ~ 200x 16-Mpixel CCD image sensors, 10 $\mu$  pixels (0.2") → 3.2 Gpixels
  - Back side illuminated
  - Small “Point spread function” – PSF (minimum spot size) < 7.5  $\mu$  (10  $\mu$  max)
  - Low f-number = 1.2 → must be flat to 10 $\mu$  (peak-valley) across focal plane
  - High quantum efficiency 400 nm – 1,000 nm (40%, 80%, 40%)
  - Low leakage < ~ 1 e/s per pixel → T~ -100 C
  - High “full well” capacity ~ 100,000 e/pixel
- Back-to-back 15 second exposures on each piece of sky → Cosmic ray rejection
- 2 second readout → low dead time, high throughput
- Sky shot noise limited images → CCD *read noise* ~ 5 e rms
- Focal plane contained in a *contamination free* evacuated cryostat to prevent fogging of sensor surfaces

Note: Last three requirements highly constrain the readout topology



# Critical Specifications

- Implications for readout & sensors -



CCD output “amplifier”

Typical sensitivity  $S = 5 \mu\text{V}/e$   
 $\rightarrow C_g \sim 32 \text{ ff}$

Dominant noise source  $\rightarrow$  “kTC noise”

$$\sigma_{kTC} = \sqrt{k \cdot T \cdot C_g} \rightarrow \sqrt{\frac{V_T}{S}} \approx 50e \text{ (cold)}$$

kTC noise easily removed by

- Correlated Double Sampling (Clamp & Sample)
- Dual Slope Integration (optimal)





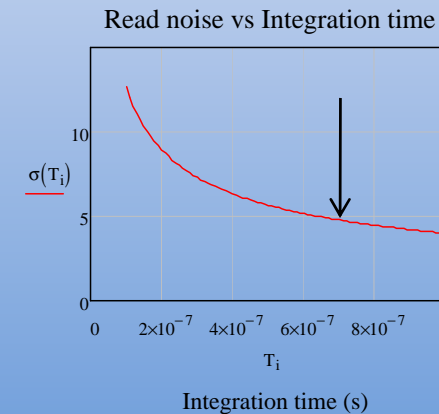
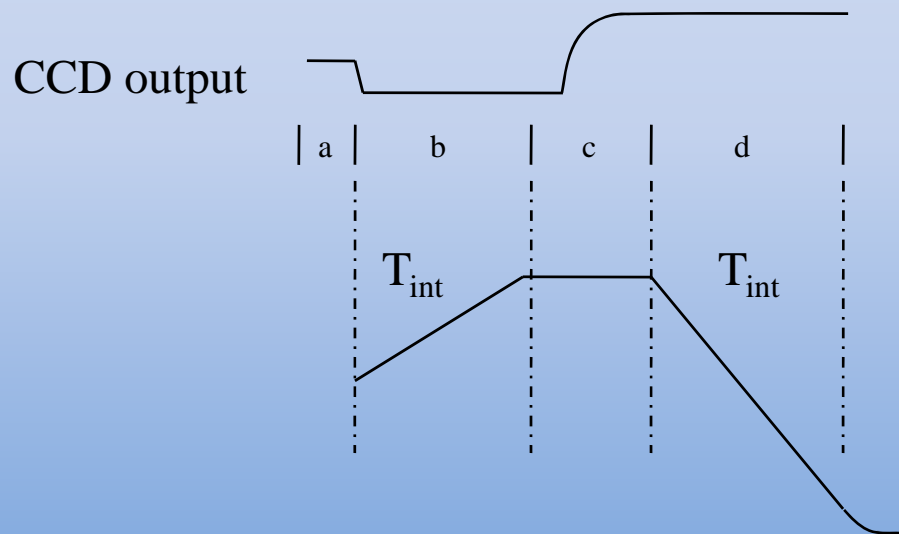
## Dual Slope Integration sequence

- Reset
- Integrate baseline up
- Move charge to output fet
- Integrate signal down

$$\sigma = \frac{e_n}{S} \cdot \frac{1}{\sqrt{T_{\text{int}}}}$$

For typical “science grade” CCD

$$e_n \approx 10 \text{ to } 20 \frac{nV}{\sqrt{Hz}}$$



$$\rightarrow T_{\text{read}} > \sim 2 \mu\text{s/pixel}$$



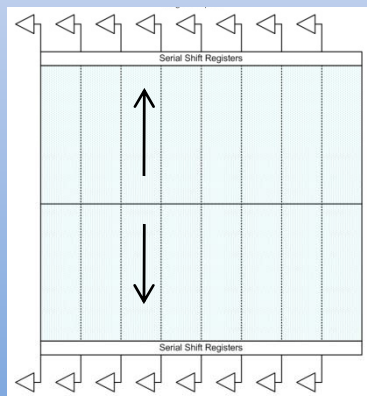
## Critical Specifications

- Implications for Sensors -

- At  $f_{\text{pixel-read}} = 500 \text{ kpixels/sec} \rightarrow 32 \text{ sec Read Time (with one output amplifier)}$

*$\rightarrow$  Each CCD must have 16 parallel outputs & electronic readout channels*

*$\rightarrow \sim 200 \text{ sensors} \rightarrow 3,200 \text{ parallel readout channels}$*



- 16x segments, gap-less
- $\frac{1}{2} \text{ k} \times 2\text{k}$  each
- $\sim 40 \text{ mm} \times 40 \text{ mm}$





## Critical Specifications - Implications for Sensor Thickness -

Conflicting requirements →

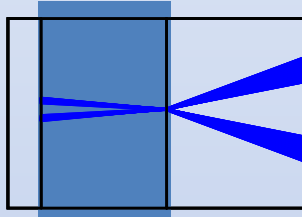
- Small PSF
  - Blue light has very small absorption length
    - favors thin sensor to minimize diffusion
    - favors full depletion in high resistivity silicon
- High QE in red
  - Red light has very long absorption length
  - *Thin* sensor would be transparent in red & near IR → favors thick sensor
- Optimization : “Study of Silicon Sensor Thickness Optimization for LSST” [1]
  - Calculations
  - Simulations

[1] <http://www.inst.bnl.gov/~poc/LSST/Study%20of%20sensor%20thickness.doc>

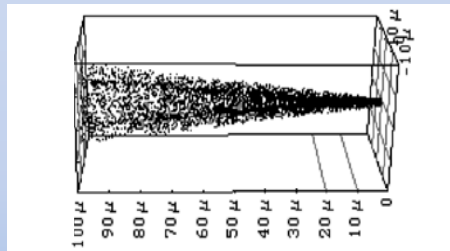
LSST Sensor Working Group D. Figer, J. Geary, K. Gilmore, S. Marshall, **P. O'Connor**, J. Oliver, **V. Radeka**, C. Stubbs, **P. Takacs**, T. Tyson



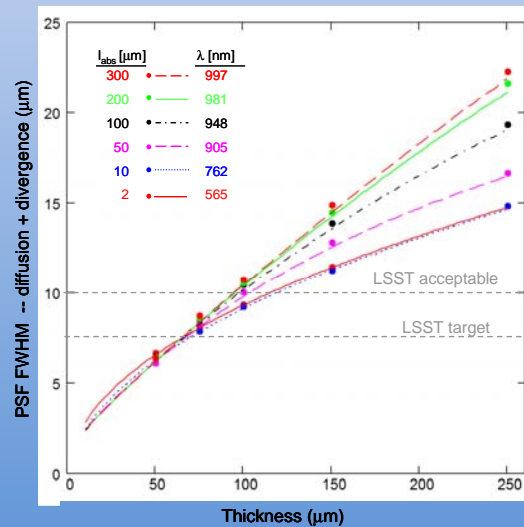
## Effect of sensor thickness on PSF



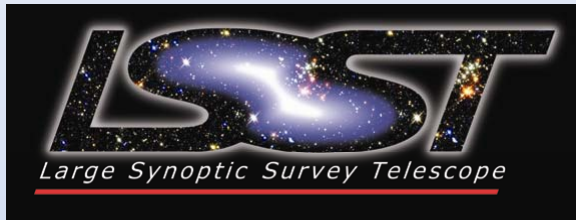
Beam divergence : f1.2 beam  $\rightarrow$  46 deg max



Beam divergence in red, (simulation)

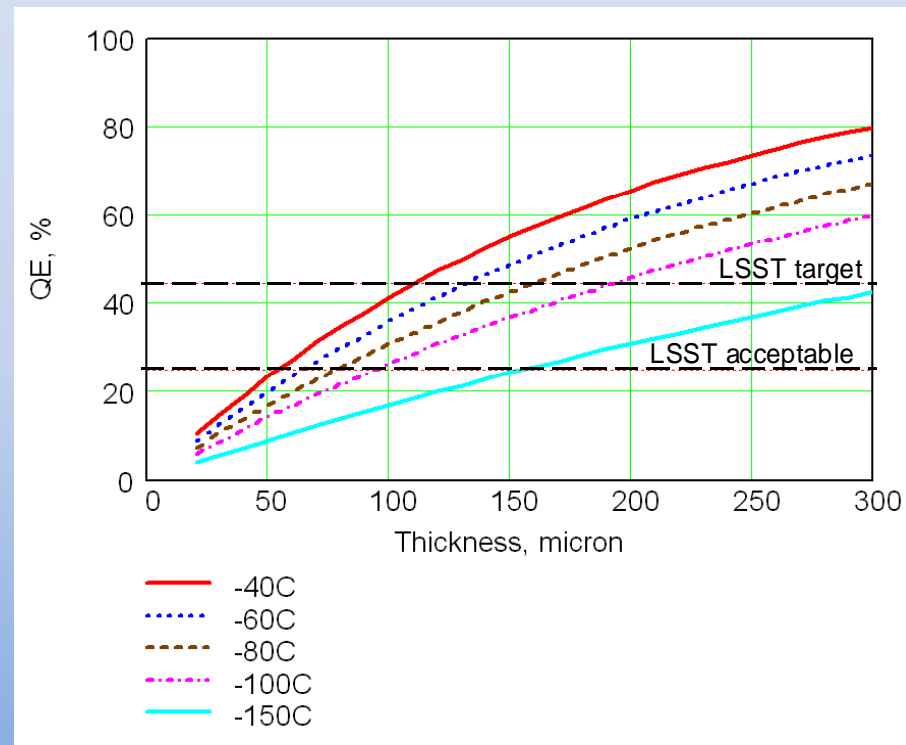


PSF vs Thickness : Divergence + diffusion  
 $\rightarrow$  Sets thickness limit  $t \leq 100 \mu$



## Effect of sensor thickness on QE

### Silicon QE @ 1000 nm vs Thickness



To get  $> 25\%$  QE @ - 100C  $\rightarrow t \geq 100\mu$

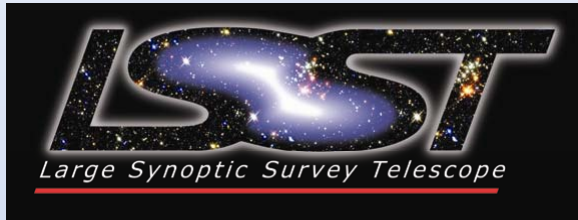
Optimal sensor thickness = 100  $\mu$



## Sensor Requirements cont'

### - Temperature Stability -

- Sensor QE is very temperature dependent near  $\sim 1,000$  nm
- For accurate photometry, temperature stability  $\sim \pm 0.1^\circ\text{C}$
- Sources of heat
  - CCD gates (*small*)
  - CCD output amplifiers (*medium*)
  - Heat radiation through lens (*large*  $\sim \frac{1}{2}$  W per sensor)
- Heat removal by thermal straps to a cryogenic plate
- Thermal control loop
  - High stability temp sensors close to CCD package
  - Heaters  $\rightarrow 0$  to  $\sim \frac{1}{4}$  W per sensor on sensor package or cold straps



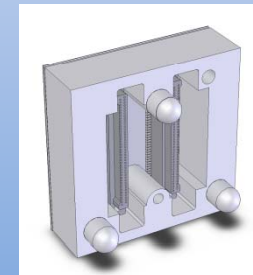
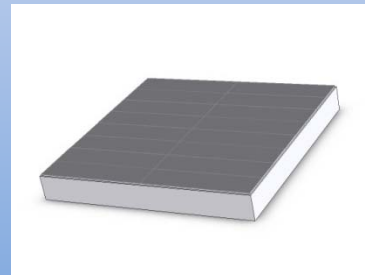
## Sensor Status

An array of “study” sensors has been produced by

- e2v
- STA/ITL
  - 100 $\mu$  to 150 $\mu$  thickness
  - All fully depleted between 10V – 25V “back window bias”
  - Sizes 1 MPixels to 16 Mpixels
  - Multiple output ports
  - Tested @ BNL
  - Not final package

“Pre-Production” sensors

- E2v
- STA/ITL
- 100 $\mu$  thickness
- Final packaging
  - 4 side buttable
  - flat to 6  $\mu$  (p-v)
- Expected → Fall 2010



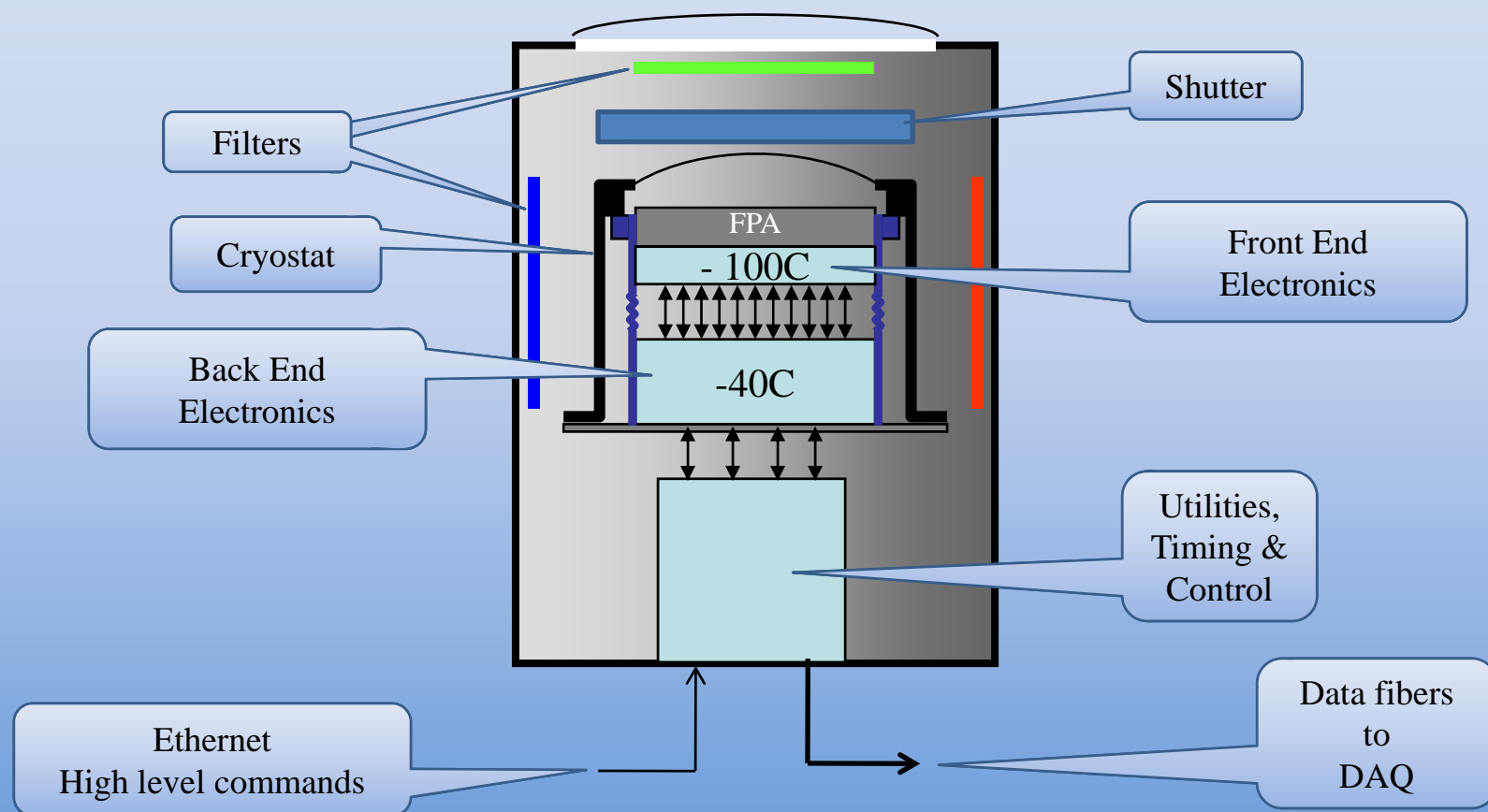


## Focal Plane Construction

- 3 x 3 arrays of CCDs are mounted into a precision “Raft”
- 144 Mpixels per Raft
- 21 Rafts are mounted onto a rigid (SiC) “Grid”
- Major issues
  - Each sensor has ~ 150 bond pads
  - Total of ~ 30,000 bond pads
  - Sensors reside in high-vacuum cryostat
  - To avoid 30,000 cryostat feedthroughs, all readout electronics is placed within cryostat.
  - Each Raft is modular. All its readout electronics must reside in the shadow of the Raft.
- Raft electronics is divided into two sections
  - Analog, front end, in cryo-zone (-100C)
  - ADC/digital in warmer zone (- 40C)



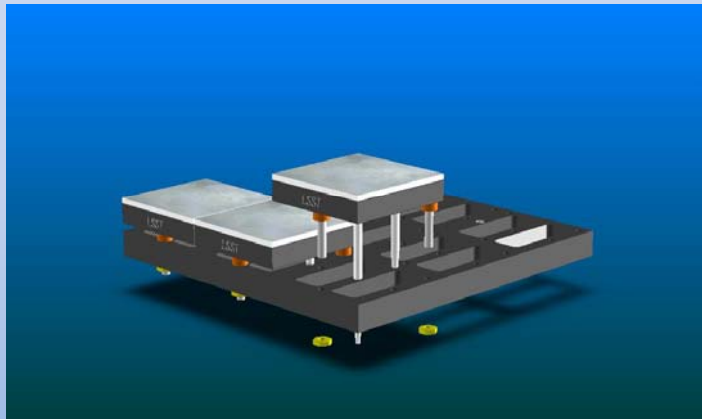
## Camera Overview





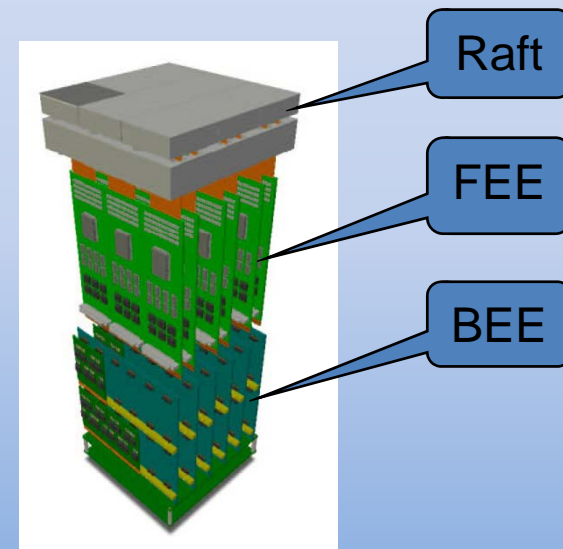
## Focal Plane Construction

9 Sensor Raft



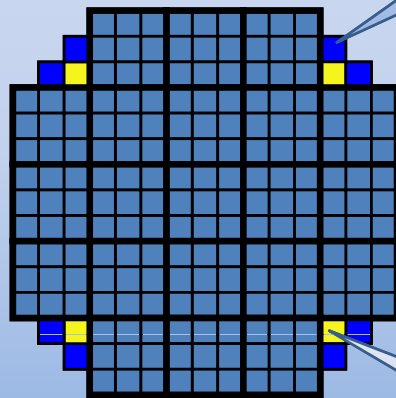
- Trimmed for flatness requirement during assembly
- Very high image “fill factor”  $> \sim 90\%$

Raft Tower Assembly





21 “Science Rafts”  
4 special purpose  
“corner Rafts”

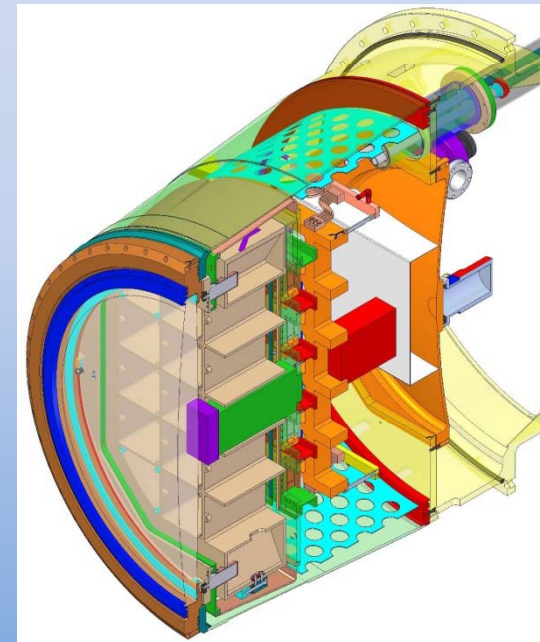


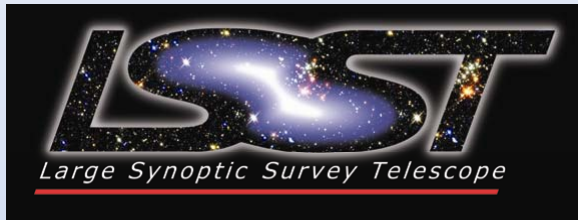
~ 64 cm dia

“Guide” sensors for  
telescope fine steering

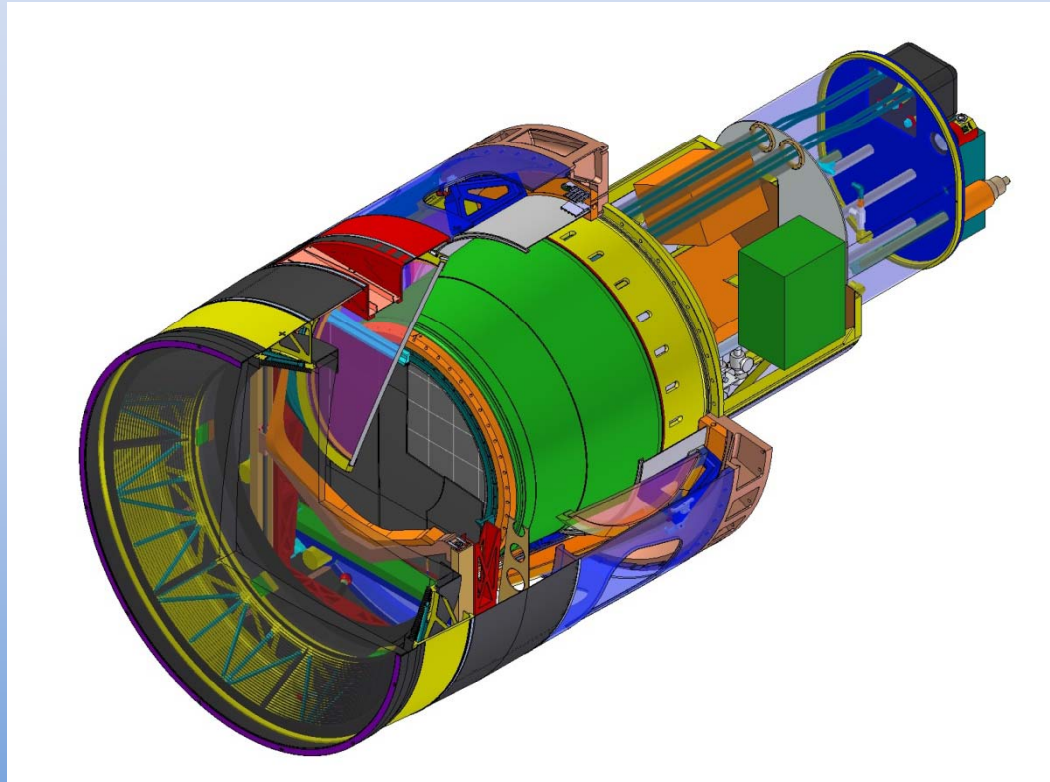
“Wavefront” sensors  
determine mirror  
distortions for active  
mirror adjustments

## Cryostat Assembly





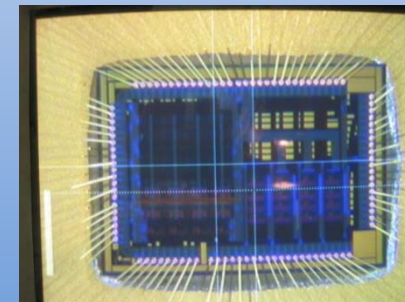
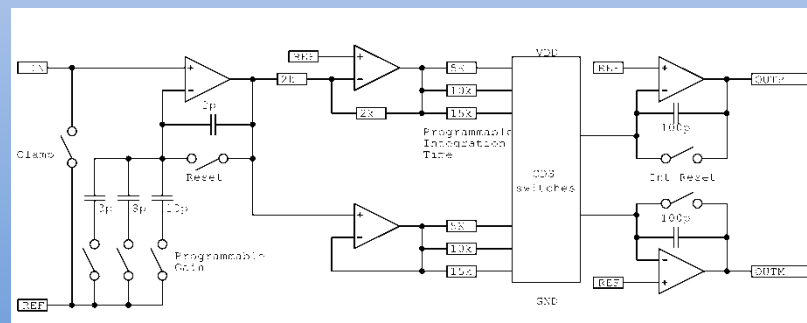
## Camera with filters





## Front End Electronics

- Located within “grid” : Operates at – 100C to – 120C
- Each “FEB” services 24 CCD segments – 6 FEBs per Raft
- Analog functionality in 2 ASICs
  - Analog Signal Processing ASIC (ASPIC)
  - LPNHE/IN2P3 collaboration[1] - France
  - Dual Slope Integrator : Programmable gain
  - Specs:
    - $e_n < \sim 5 \text{ nV/rt(Hz)}$
    - $x\text{-talk} < \sim 10^{-3}$  (achieved in 1<sup>st</sup> version)
  - Differential output to Back End Boards (ADCs) via shielded flex cable
  - 8 channel ASIC, AMS 0.35 $\mu$  CMOS @ 5V, ~ 25mW/ch



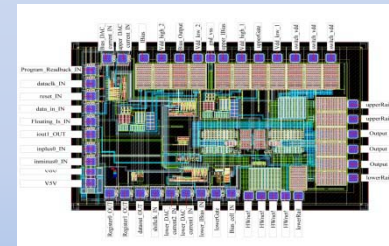
[1] V. Tocut, H. Lebbolo, C. De La Taille, P. Antilogus, S. Bailey, M. Moniez, F. Wicek, R. Sefri



## Front End Electronics – cont

### Sensor Control Chip (SCC)

- ORNL – U. Tennessee [1]
- Receives LVDS signals from BEBs → Converts to Clock levels to CCDs
- Parallel gates (4), Serial gates(3), Reset(1)
- Clock Hi/Lo levels in range 0V to ~ 25V, programmable on BEB
- 4 channels per chip, 2 chips per CCD.
- CCD bias level buffers in range up to ~ 30V
- ATMEL BCD-SOI process. HV to 45V
- Status
  - 1<sup>st</sup> submission tested & fully functional
  - Some pulse shape “wrinkles” (fully understood in simulation)
  - 2<sup>nd</sup> submission → Fall '08



### Additional FEB functionality

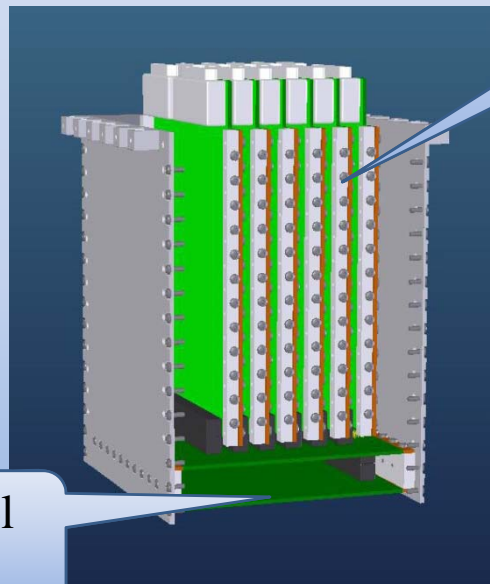
- Temp sensing & other usual monitoring
- Raft heaters → Part of focal plane thermal control loop

[1] P. Stankus, C. Britton, Z. Ning, N. Ericson



## Back End Electronics

Raft Control Crate



Raft Control  
Module

Back End Boards

- 6x Back End Boards (BEBs)
- 24 channels ea, 18 bit 1 MHz ADCs (COTS)
- Temp sensor processing
- Programmable bias & clock levels for FEBs
- Sensor heater control
- Misc slow controls

- FPGA (Xilinx) based programmable “Readout State Machine”
- Collects all ADC data @ 100 MHz
- All control loops stored locally
- Responds to high level commands from Timing & Control Module (TCM)
- All Rafts in fully synchronous operation
- “Rocket i/o” data output to drive data fiber to DAQ (~1.6 Gb/s)
- Power PC for non-time critical operations



## Back End Electronics

### - Data Volume -

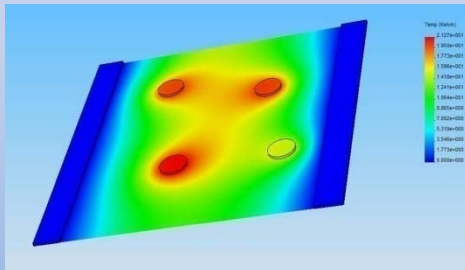
- Per image: 3.2 Gpixels → ~ 7 GB
  - Per minute : 4 images → ~28 GB
  - Per night : ~ 600 min → ~ 16 TB
  - Per year : → ~ 5 PB
- 
- All fibers received by “Science Data System” – (SLAC)
  - Public data set



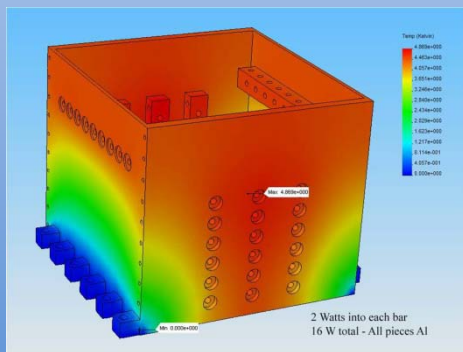
## Additional Electronics Issues

### Thermal management

- Thermal paths & modeling
  - ICs and components to ground/thermal planes
  - “Chip scale” packaging
  - Conduction bars
  - Crates/housing
  - Cold plates / cryoplates



Board level  $R_t \sim 20\text{C/W}$  across 2 oz copper plane



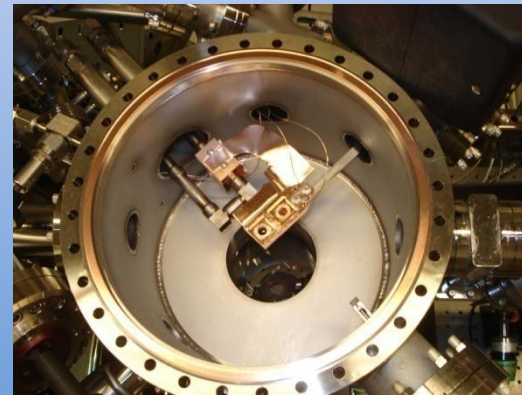
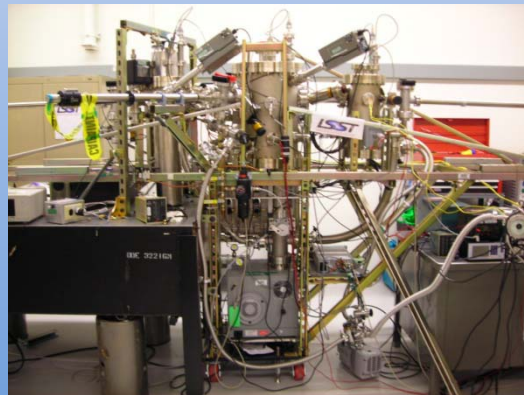
Crate level  $R_t < \sim 0.5\text{C/W}$



## Additional Electronics Issues

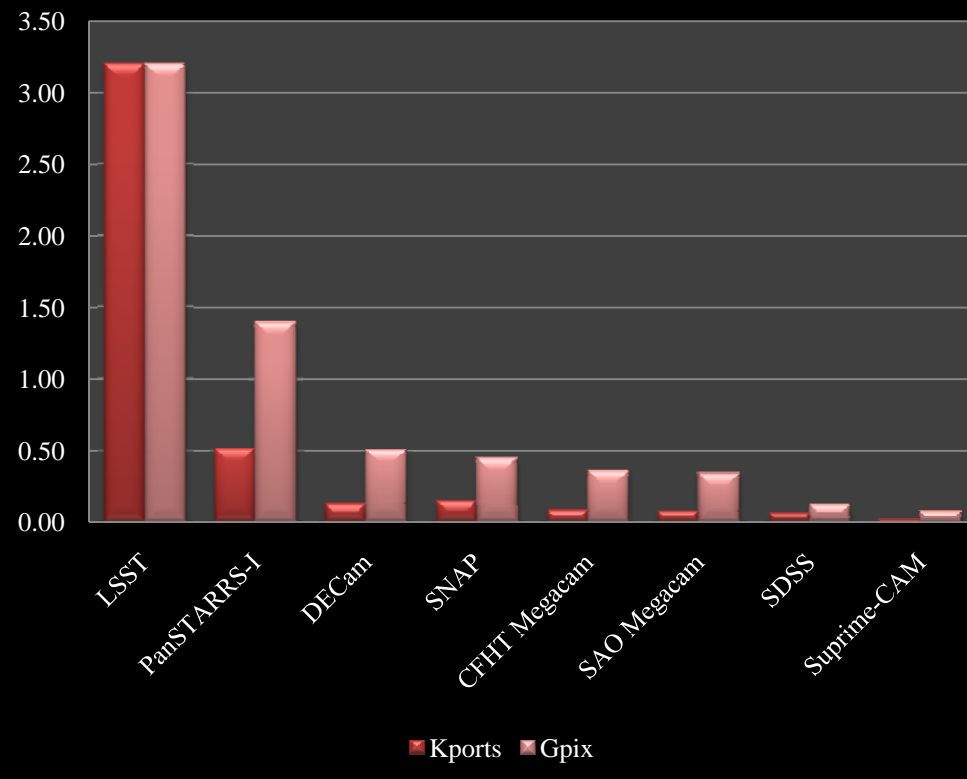
### Contamination & outgassing

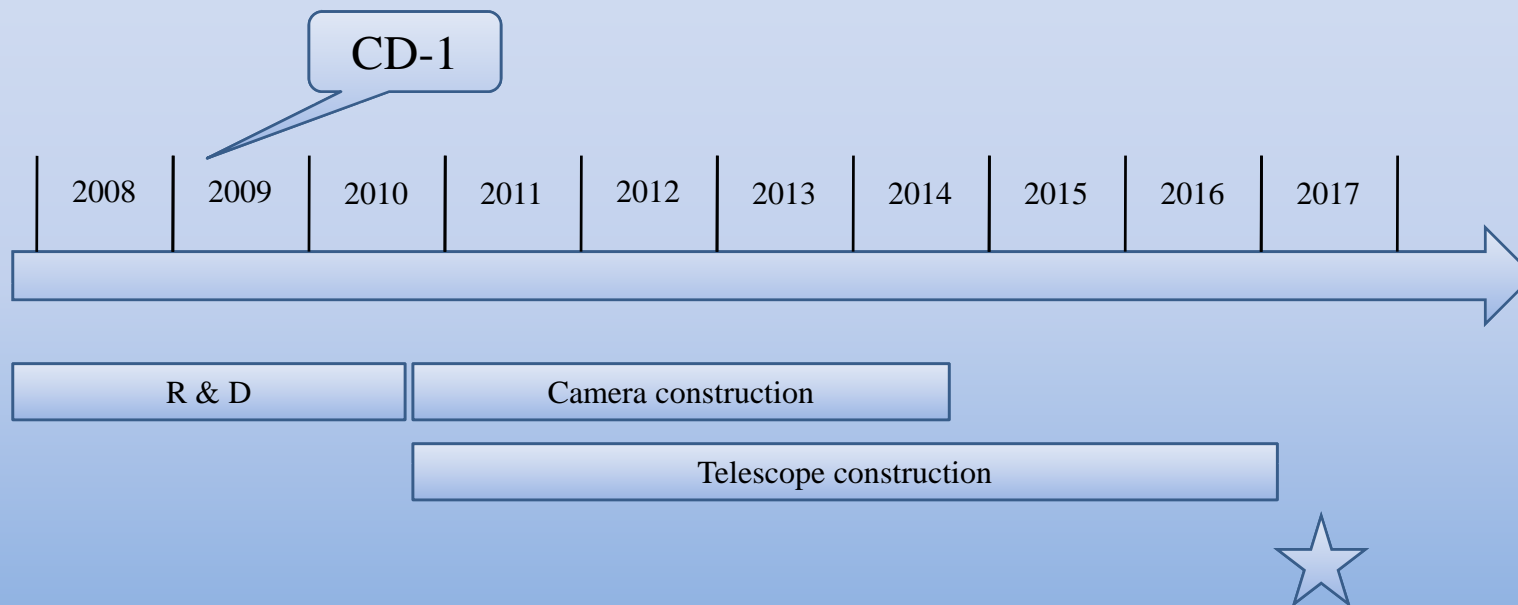
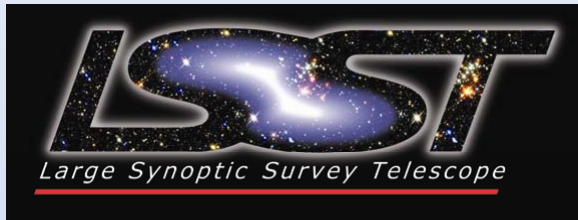
- Outgassing materials may condense on sensor surface
- $\sim 2 \text{ m}^2$  of pcb materials in cryostat
- Polyimide pcb construction (if necessary)
- Parylene (vapor deposition) or similar coatings
- Electronics separated from focal plane by molecular barriers (tortuous paths) and separate vacuum pumping
- All in-cryostat materials tested / certified in test “Materials Test Facility” @ SLAC
- Optical loss measurement over LSST pass band & residual gas analyzer (RGA)





## Comparison of LSST with existing or in-development cameras









Telescope and site : Cerro Pachon, Chile

