



CMS microstrip tracker readout at the SLHC

Imperial College
London

OUTLINE

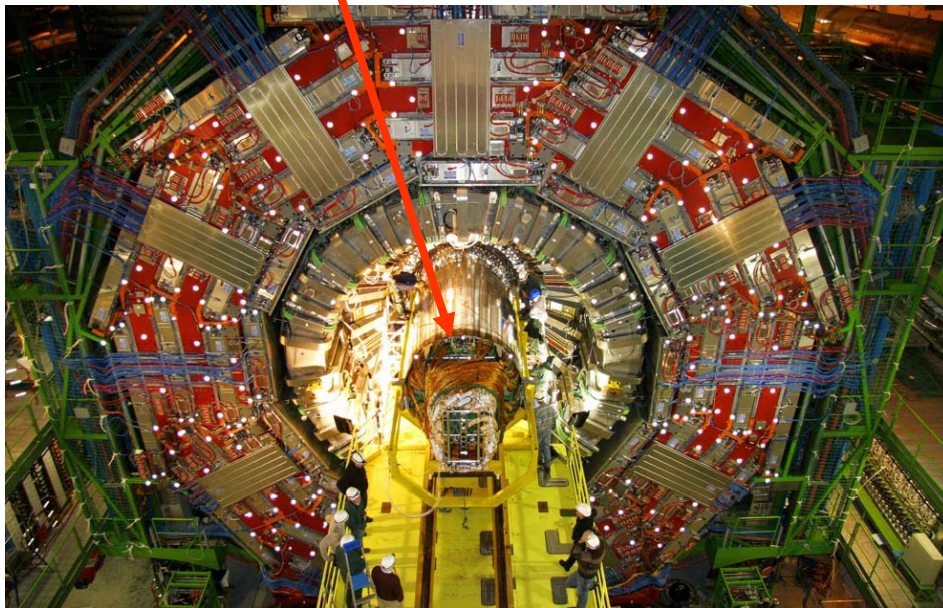
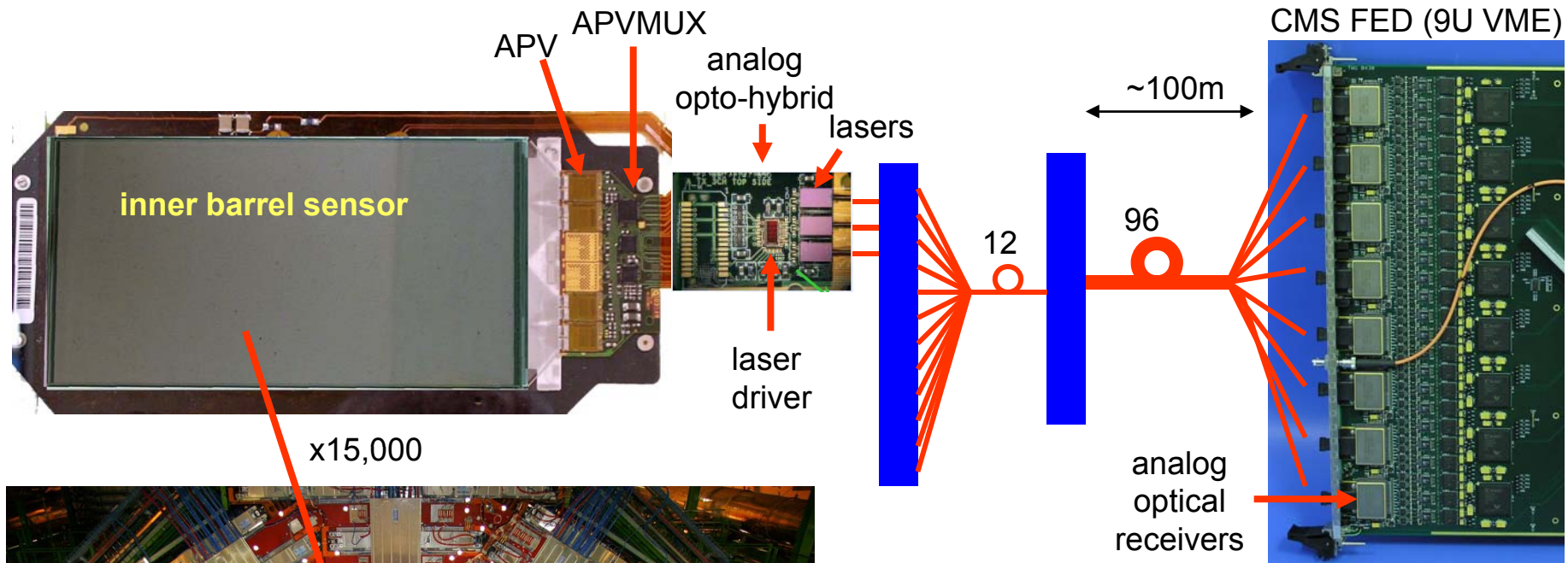
brief review of LHC strip readout architecture
possible architectures for SLHC
FE chip power estimates
triggering architectures
summary

Mark Raymond and Geoff Hall, *Imperial College London, UK.*

Topical Workshop on Electronics for Particle Physics, Naxos, Greece / September 2008



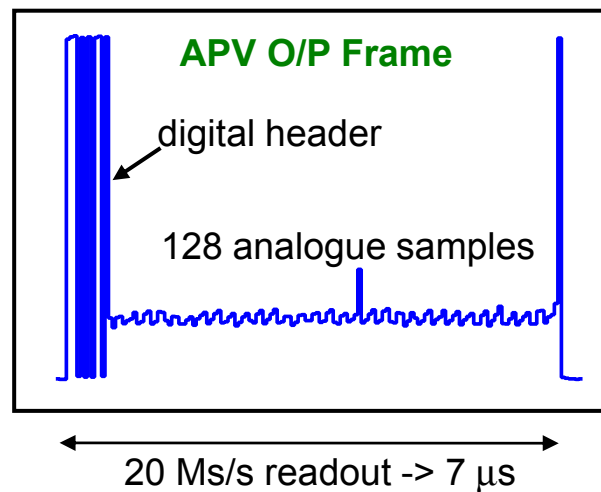
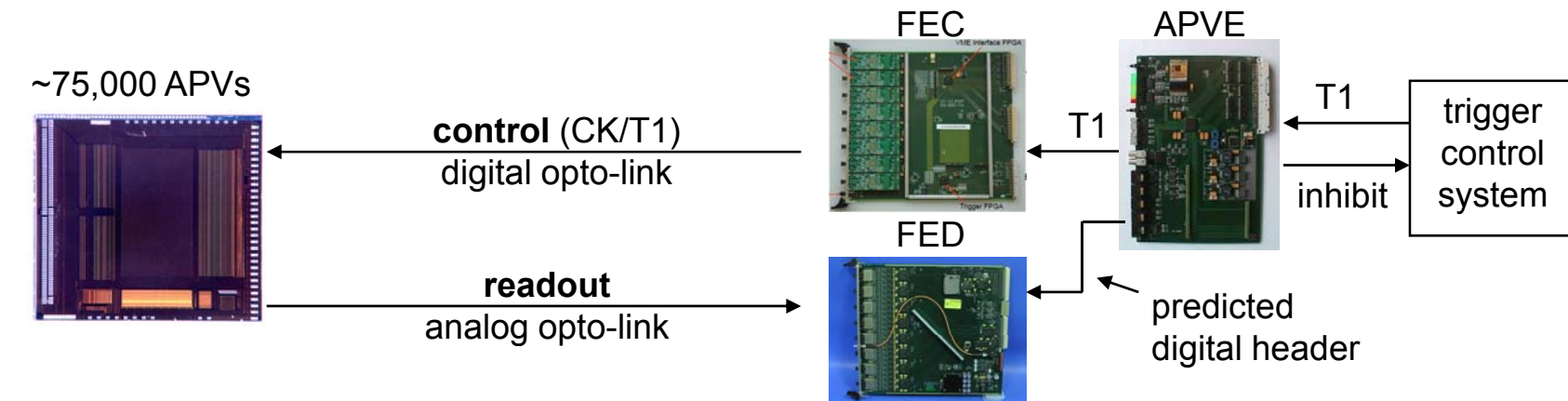
CMS LHC Si strip readout system



CMS strip tracker readout analog

APV25 0.25 μm CMOS FE chip
APV outputs analog samples @ 20 Ms/s
APVMUX interleaves 2 APVs onto 1 line @ 40 MHz
Laser Driver modulates laser current to drive
optical link @ 40 Ms/s / fibre
O/E conversion on FED and digitization
@ ~ 9 bits (effective)

LHC control / readout chain overview



no zero-suppression (sparsification) on detector

all 75,000 APVs operating synchronously
(all FE chips doing same thing at same time)

advantages

- can be emulated externally (APVE) to prevent APV buffer overflows
- no need to timestamp on front end
- data volume occupancy independent
- easy to identify upset chips (digital header)

pedestal, CM subtraction and zero suppression on FED raw data also available for setup, performance monitoring and fault diagnosis

analog, unsparsified readout provides relatively simple and robust system

SLHC challenges for CMS tracker

power – the big issue

higher luminosity, higher granularity => more FE chips
electronics related material dominates material budget
(cabling, cooling)

triggering

not possible to keep L1 trigger rate at 100 kHz without
contribution from tracker

=> new features and existing architectures need re-design

can make best use of advances in:

electronics technology

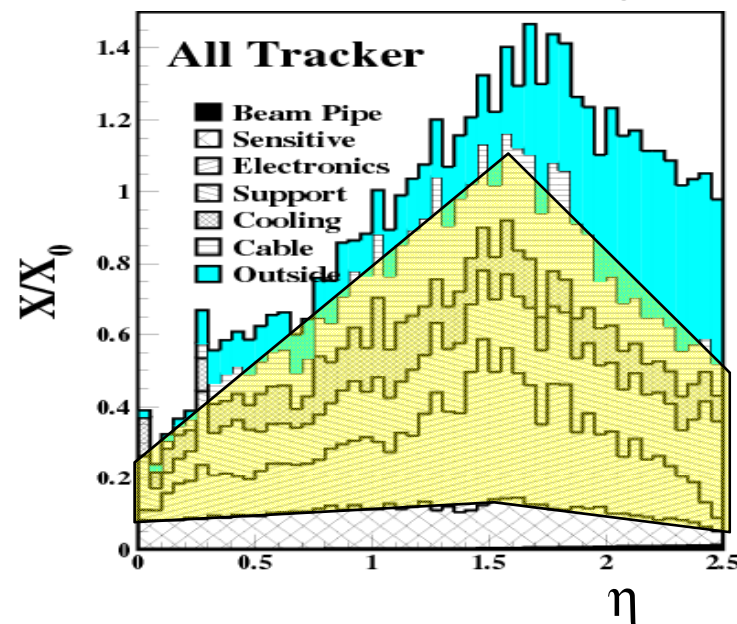
finer feature sizes, lower supply voltages
=> reduced power consumption
but savings depend on any additional FE functionality

off-detector link technology

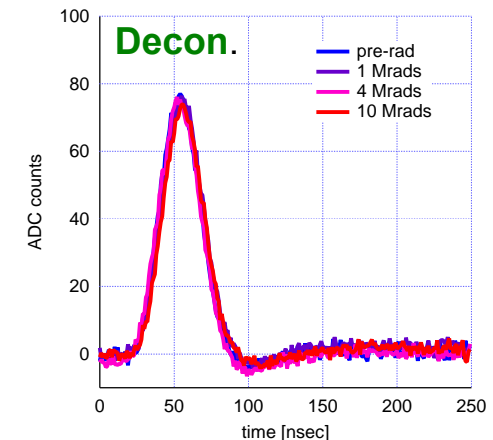
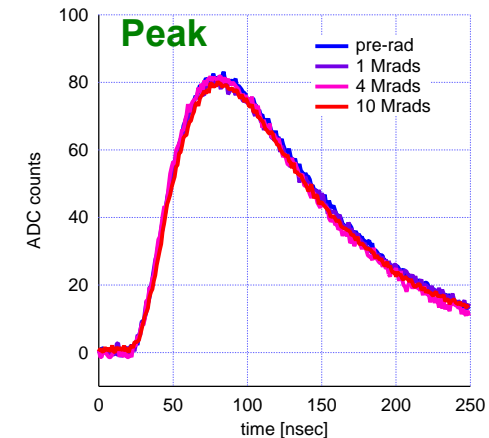
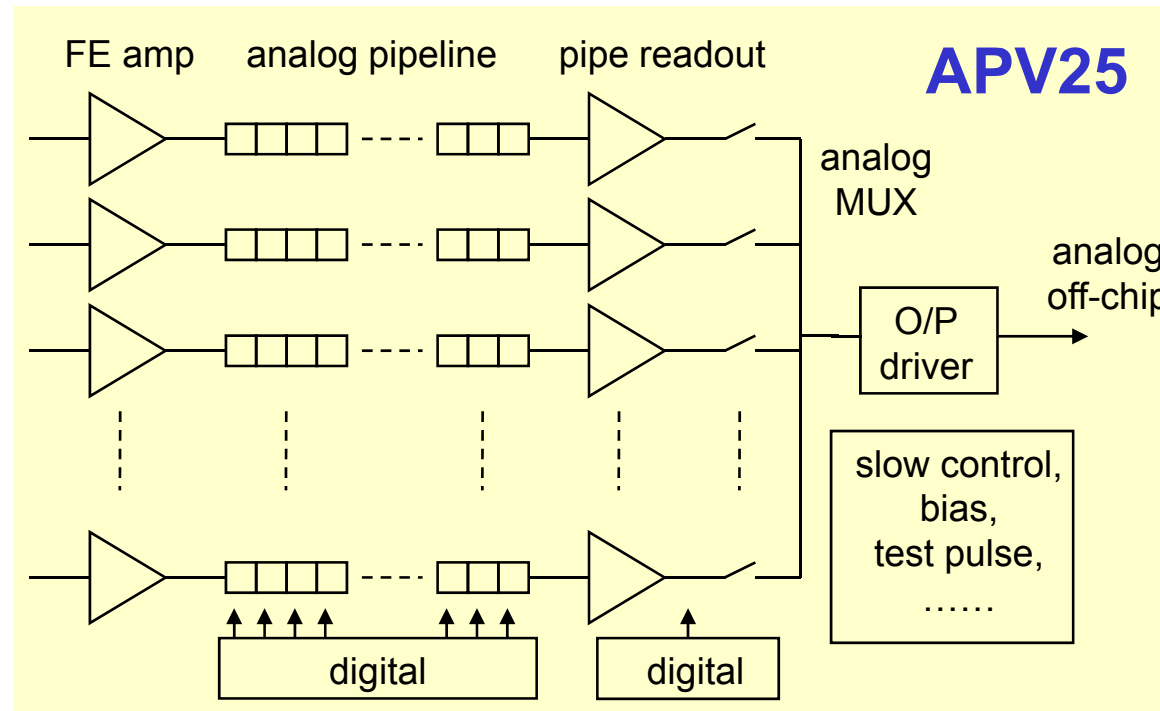
high speed digital, ~ multi - Gbps
but more channels so power consumption an issue here
=> digitization on front end if want to retain pulse ht. info

will examine pros and cons of different FE chip architectures

CMS tracker material budget



front end chip architectures



existing LHC architecture – APV25

slow 50 nsec CR-RC FE amplifier, analog pipeline, 2.7 mW/channel

peak/deconvolution pipe readout modes

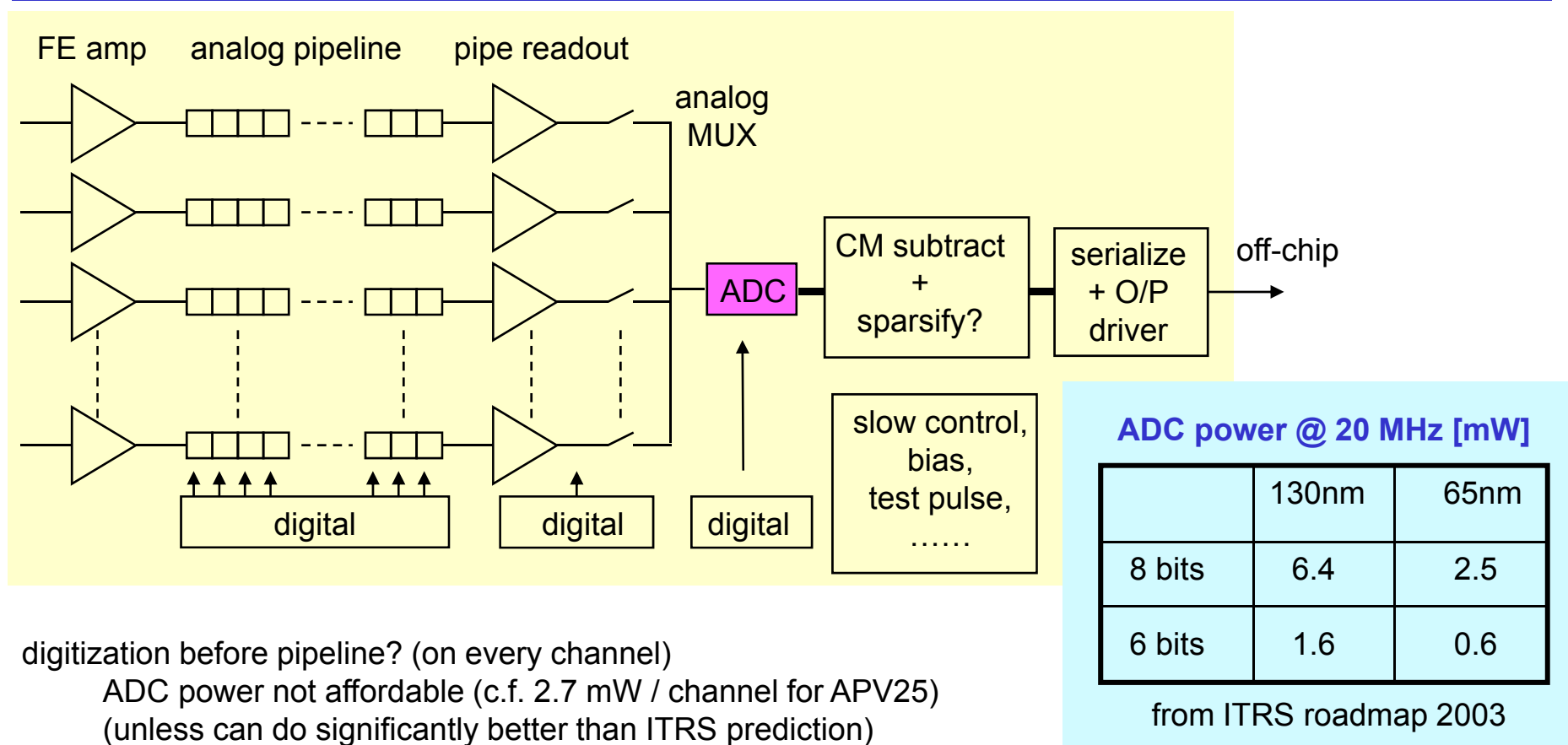
peak mode -> 1 sample -> normal CR-RC pulse shape

deconvolution -> weighted sum of 3 consecutive samples combined to give single BX resolution

all analog approach – not compatible with digital off-detector data transmission

moving to SLHC – if want to retain pulse height information – where to digitise?

“digital APV” architecture



digitization before pipeline? (on every channel)

ADC power not affordable (c.f. 2.7 mW / channel for APV25)
(unless can do significantly better than ITRS prediction)

digitization after analog mux => only one ADC per chip, ADC power becomes ~negligible

e.g. 6.4 mW (0.13 μm , 8 bits) / 128 = 50 μW / channel

analog pipeline remains so could retain slow shaping + analog deconvolution approach

pipeline implementation with gate capacitance still possible for 0.13? (probably not for finer processes)

but rather complicated chip – all the complexity of current APV + more (e.g. sparsification)

binary architecture – un-sparsified

what about binary un-sparsified?

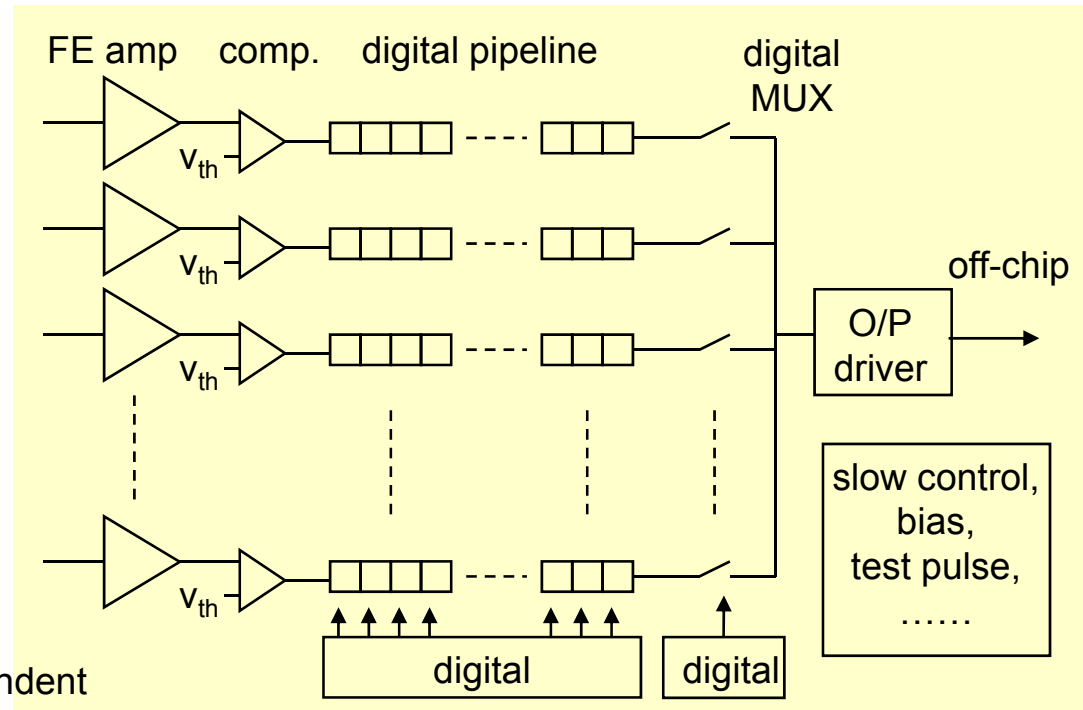
much simpler than “digital APV”
particularly for pipeline and readout side

need fast front end and comparator
=> more power here

but no ADC power and simpler digital
functionality will consume less

allows retention of features we like

simpler synchronous system
no FE timestamping
data volume known, occupancy independent
(so no trigger-to-trigger variation)



but less diagnostics (can measure front end pulse shape on every channel in present system
some loss of position resolution, common mode immunity)

binary, un-sparsified is an option we are considering

front end amplifier power

0.25 μm APV25 was designed for long strips $\sim 12 - 19 \text{ cm}$ ($15 - 25 \text{ pF}$)

needed high I/P device g_m for noise and speed

$$\text{noise} \propto C_{\text{SENSOR}}/\sqrt{g_m}$$

$$\text{risetime} \propto C_{\text{SENSOR}}/g_m$$

-> led to large $I_{\text{DS}} = 400 \mu\text{A}$, for $g_m = 8 \text{ mA/V}$

APV25 uses 3 power rails

middle voltage rail introduced to save power
at expense of PSU complexity

at SLHC

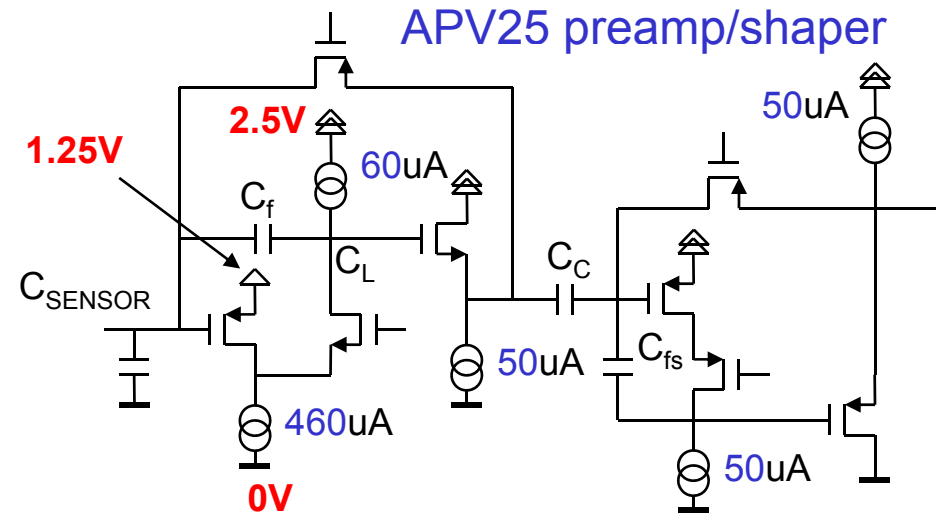
e.g. if strip length \downarrow factor 2 (or more)

=> $C_{\text{SENSOR}} \downarrow$ factor 2 => $g_m \downarrow$ factor 4 for same noise

0.13 μm simulations -> $g_m \sim 2 \text{ mA/V}$ achievable for $\sim 100 \mu\text{A}$

supply rail halves for 0.13 so factor of 8 power savings in input device possible (over APV25)

can choose to sacrifice some of this gain to simplify PSU system, by going to 2 rail design



simulated FE amplifier performance

0.13 μm simulation example

for short strips ($C_{\text{SENSOR}} \sim 5 \text{ pF}$) choose preamp and shaper input device currents (and R_{fs}) to achieve
50 and **20** nsec CR-RC pulse shapes

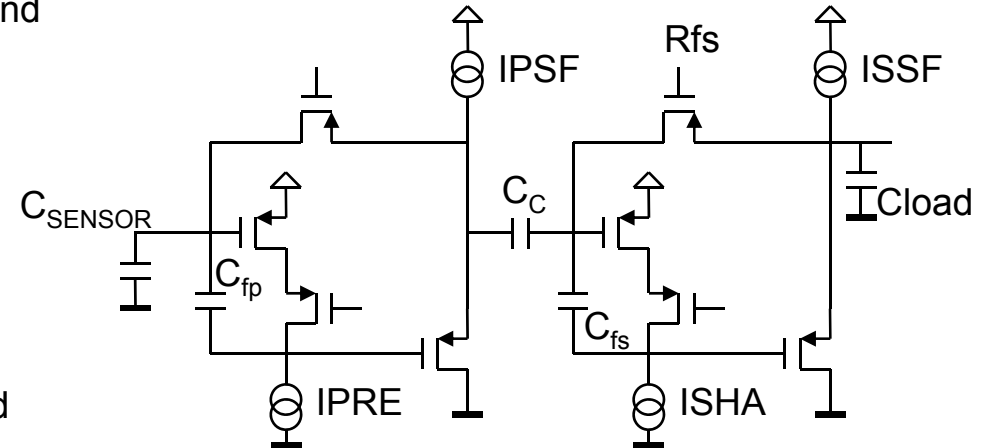
peaking time	50 ns	20 ns
IPRE [μA]	40	90
IPSF [μA]	15	15
ISHA [μA]	10	30
ISSF [μA]	35	15
total [μA]	100	150
power [μW]	120	180
noise [e]	800	890

speed

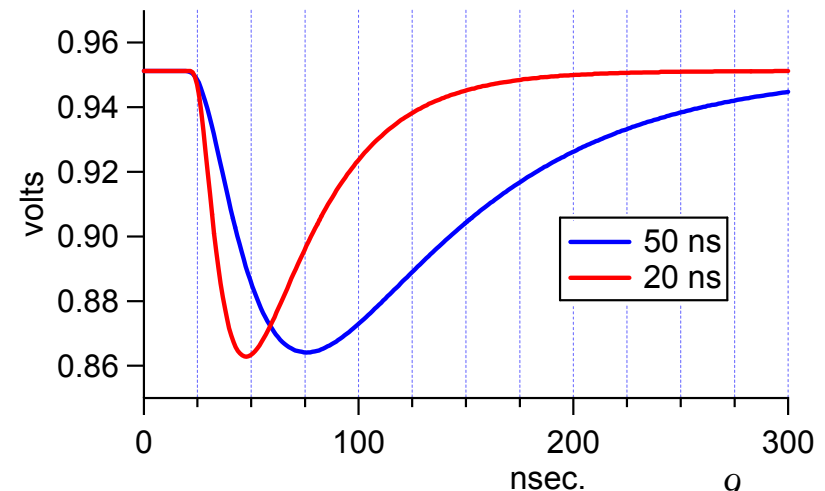
pipe capacitance

=> for short (~few cm) strips can get quite good preamp/shaper noise performance for > factor 5 less than APV (~1 mW) even with only 2 rails

0.13 μm preamp/shaper – 2 supply rails only



simulated pulse shapes ($C_{\text{SENSOR}} = 5 \text{ pF}$)



SLHC FE chip overall power estimates

APV25 [μ W/channel]

preamp/shaper	1050
inverter	500
APSP	200
mux & output stages	550
digital	<u>400</u>
	2700

plenty of uncertainty in many of the 0.13 μ m numbers
(simulations, estimates, guesses)
(particularly digital consumption)

binary (unsparsified) likely to offer least FE chip power

target ~ **500 μ W** / channel for short strip readout chip @ SLHC

0.13 pipeline chip with pulse ht. info – “digital APV”

preamp/shaper	120	50 ns shaping, $C_{DET} \sim 5$ pF , simulations
pipe readout	50	APV25 / 4 (guess)
ADC	50	1 ADC / chip (ITRS estimate)
digital	120	(APV25 / 10) x 3 (/10 for technology, x3 for SEU)
fast serial output	<u>230</u>	30 mW / 128 (guestimate for fast LVDS – maybe)
	570	could do better with diff. current ?)

0.13 binary chip – non-sparsified readout

preamp/shaper	180	20 ns, $C_{DET} \sim 5$ pF, fast FE required
comparator	20	simulations
digital	60	much simpler than above
fast serial output	<u>230</u>	just guess same as above
	490	

system architectures

system architecture depends a lot on FE chip architecture

data volume determines ratio of FE chips to off-detector link

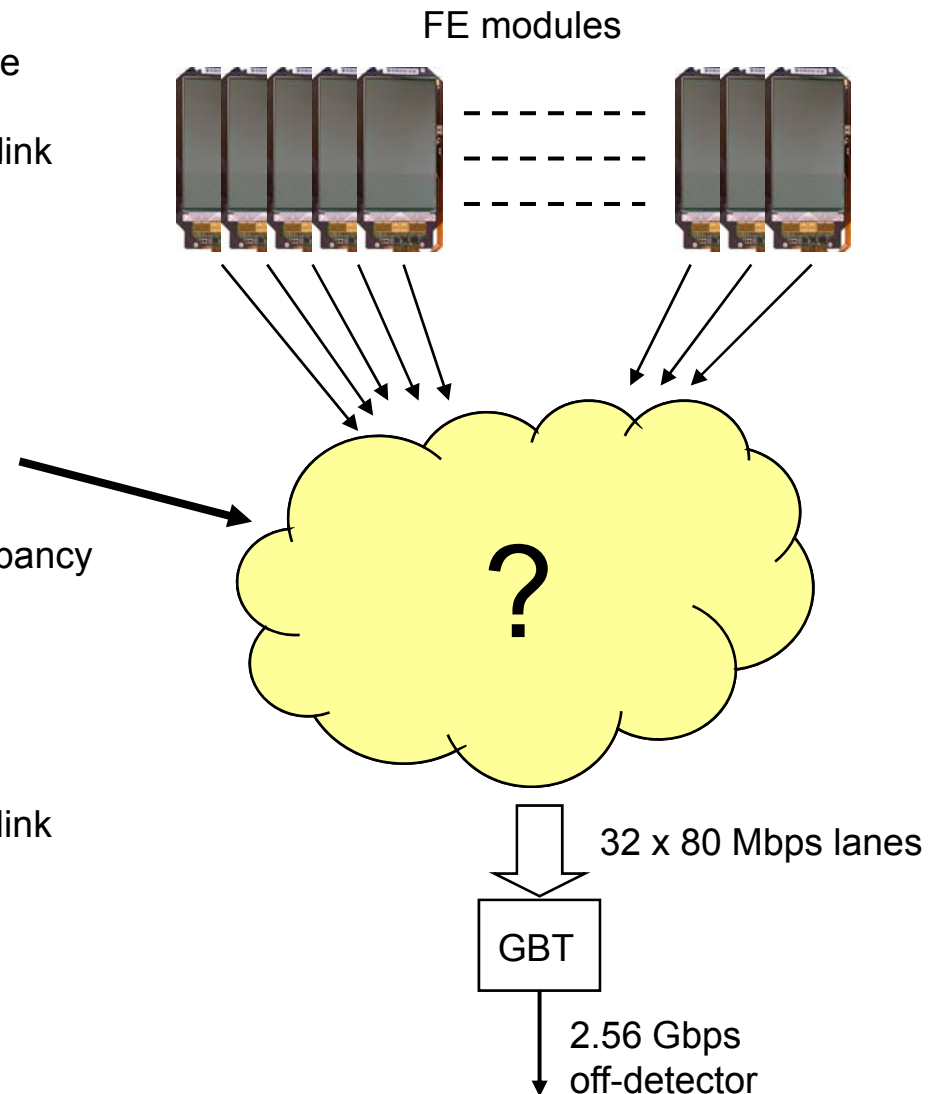
data volume depends on
sparsification or not
pulse height info

sparsification increases complexity of what goes here

e.g. need extra stage of buffering to combine occupancy
dependent data volumes in sparsified system

unsparsified simplifies merging architecture

link power / sensor channel depends on no. of FE chips/link



estimated link power contribution

no. of chips / link depends on estimations of data volume – some details in backup slides

	link speed	# of 128 chan. chips/link	power per link	link power/ sensor chan.
LHC unparsified analog	0.36 Gb/s (effective)	2 / analog fibre	60 mW	230 μ W
SLHC digital APV no sparsification	2.5 Gb/s	32 / GBT	~ 2W	490 μ W
SLHC digital APV with sparsification	2.5 Gb/s	256 / GBT	~ 2W	60 μ W
SLHC binary unparsified	2.5 Gb/s	128 / GBT	~ 2W	120 μ W

LHC unparsified analog

230 μ W / sensor channel: ~ 10% of overall channel budget
need to do better at SLHC (e.g. 10% of 0.5 mW = 50 μ W)

SLHC digital APV without sparsification not viable

link power contribution too high (no. of channels will increase at SLHC)

SLHC digital APV with sparsification appears best

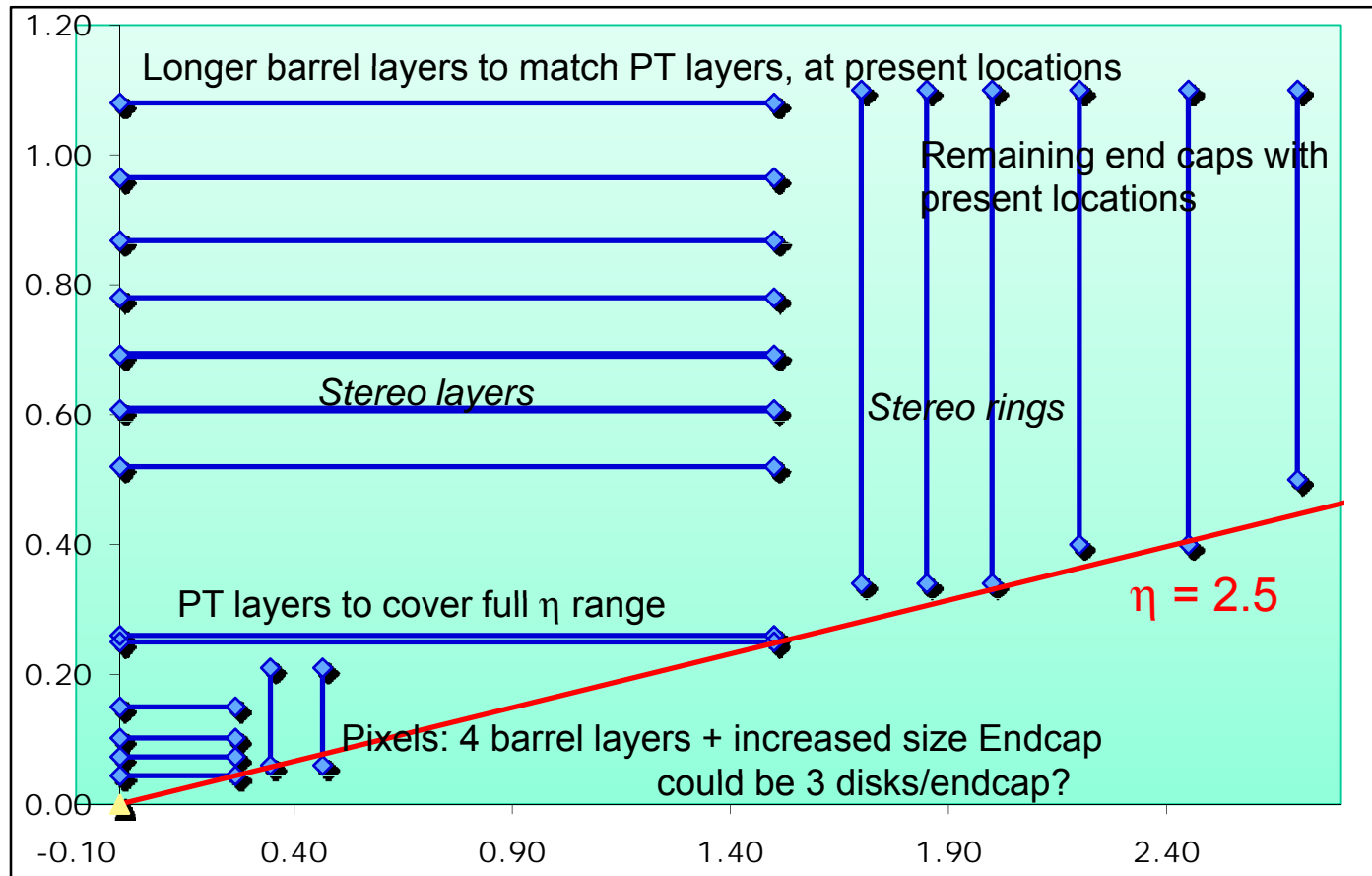
but can only be achieved with extra buffering between FE chips and link
more chips to develop, some additional power

SLHC binary unparsified next best

has strong system advantages

Triggering

CMS can't keep trigger rate at 100 kHz at SLHC without P_T information from tracker
major new feature for CMS tracker - ideas how to do it are still developing
current assumption is that there will probably be dedicated **PT** layers, providing prompt trigger info
i.e. different from more conventional, triggered pipeline chip, layers
will summarise a few ideas for triggering layers here



one possible
"strawman" layout

X section through one
quarter of tracker

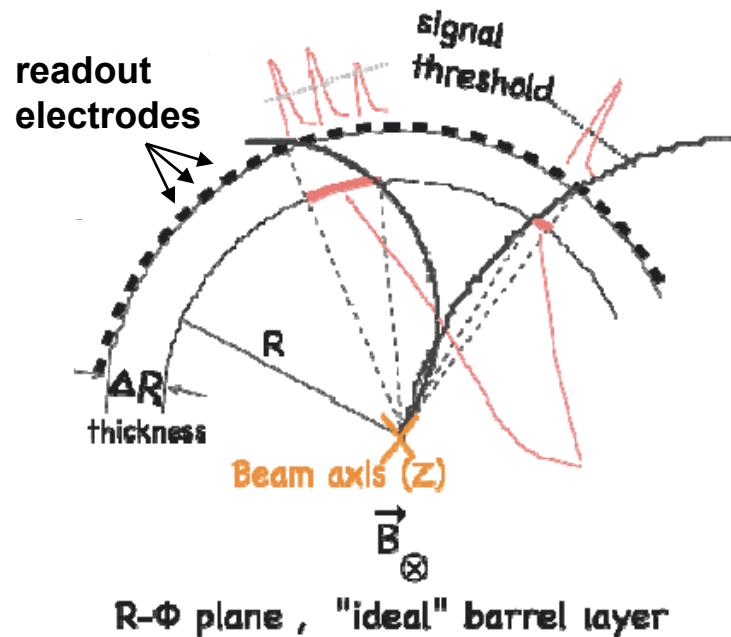
some possible approaches

stacked tracking

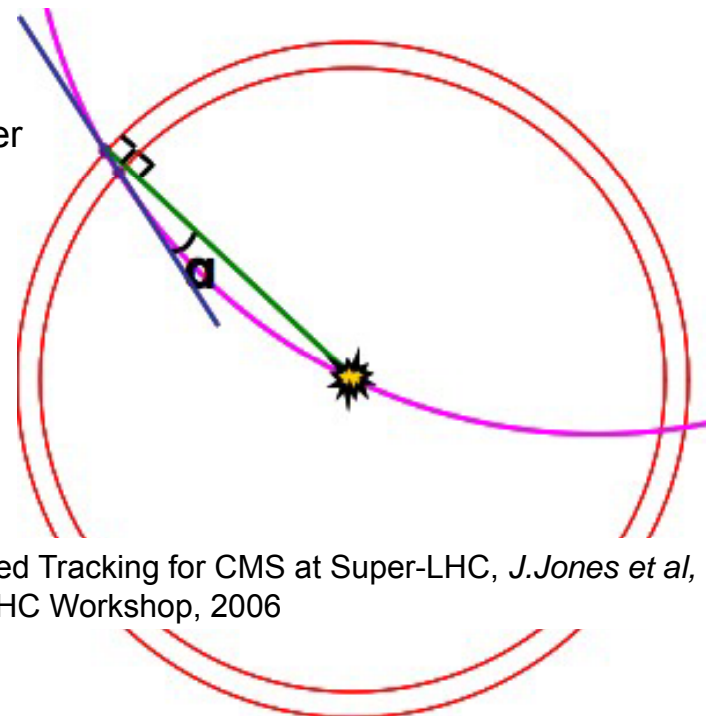
correlate hits from tracks in closely spaced layers
high PT track passes through pixels directly above each other
needs separate chip to perform correlation

cluster width discrimination

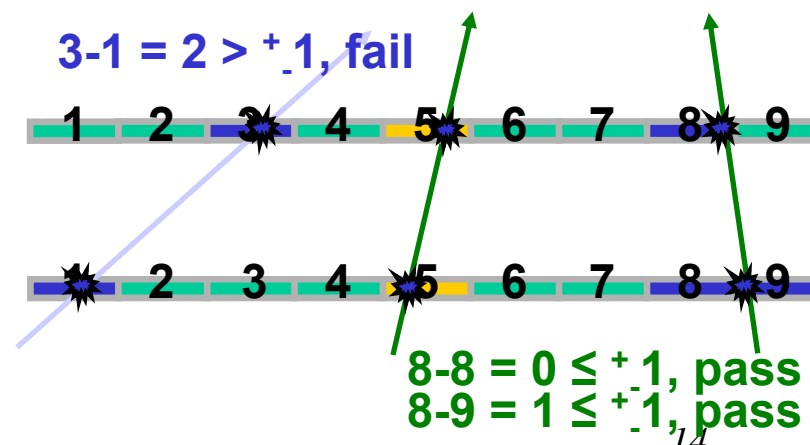
high PT track \rightarrow narrow cluster width
basic concepts clear but need to understand issues associated with practical implementations (e.g. power, construction, cost, ...)



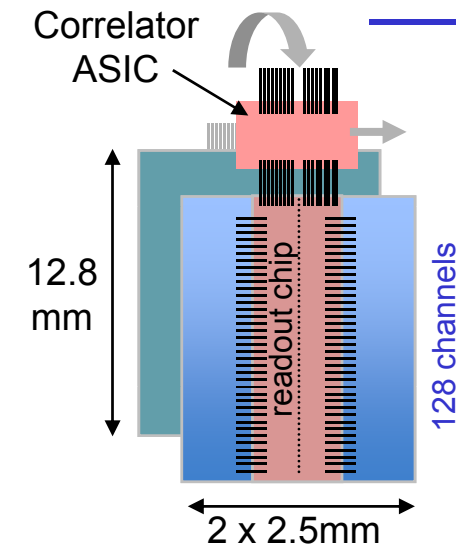
Track momentum discrimination using cluster width
in Si strip sensors, G.Barbagli, F.Palla, G. Parrini, TWEPP07



Stacked Tracking for CMS at Super-LHC, J.Jones et al, 12th LHC Workshop, 2006



possible PT module for inner layer



2 layer stacked tracking approach

80 mm x 25.6 mm sensors segmented into 2.5 mm x 100 μ m pixels tiled with readout chips – could be wire bonded for easy prototyping

readout chip ideas (see * and backup slides for more details)

each chip deals with 2 x 128 channel columns
use cluster width discrimination to reduce data volume

correlator

compares hit pattern and address from both layers
if match then shift result off-detector

data volumes

need to transmit all correlated hit patterns every BX
predicted occupancy + reduction from correlation
=> 1 link can serve 2 PT modules

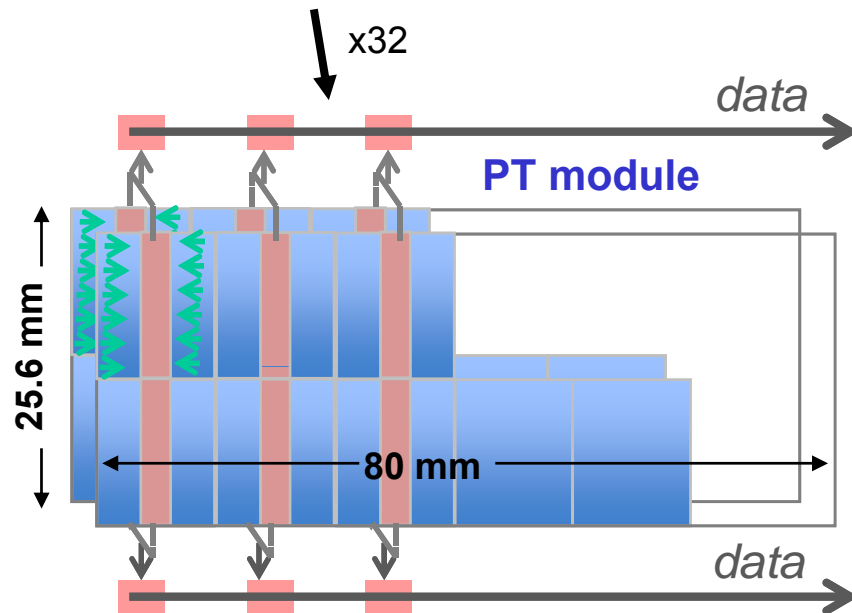
link power

need ~ 3000 PT modules for 3m length cylinder, $r=25$ cm
so 1500 links (@2.56 Gbps) => **3 kW** @ 2W / link

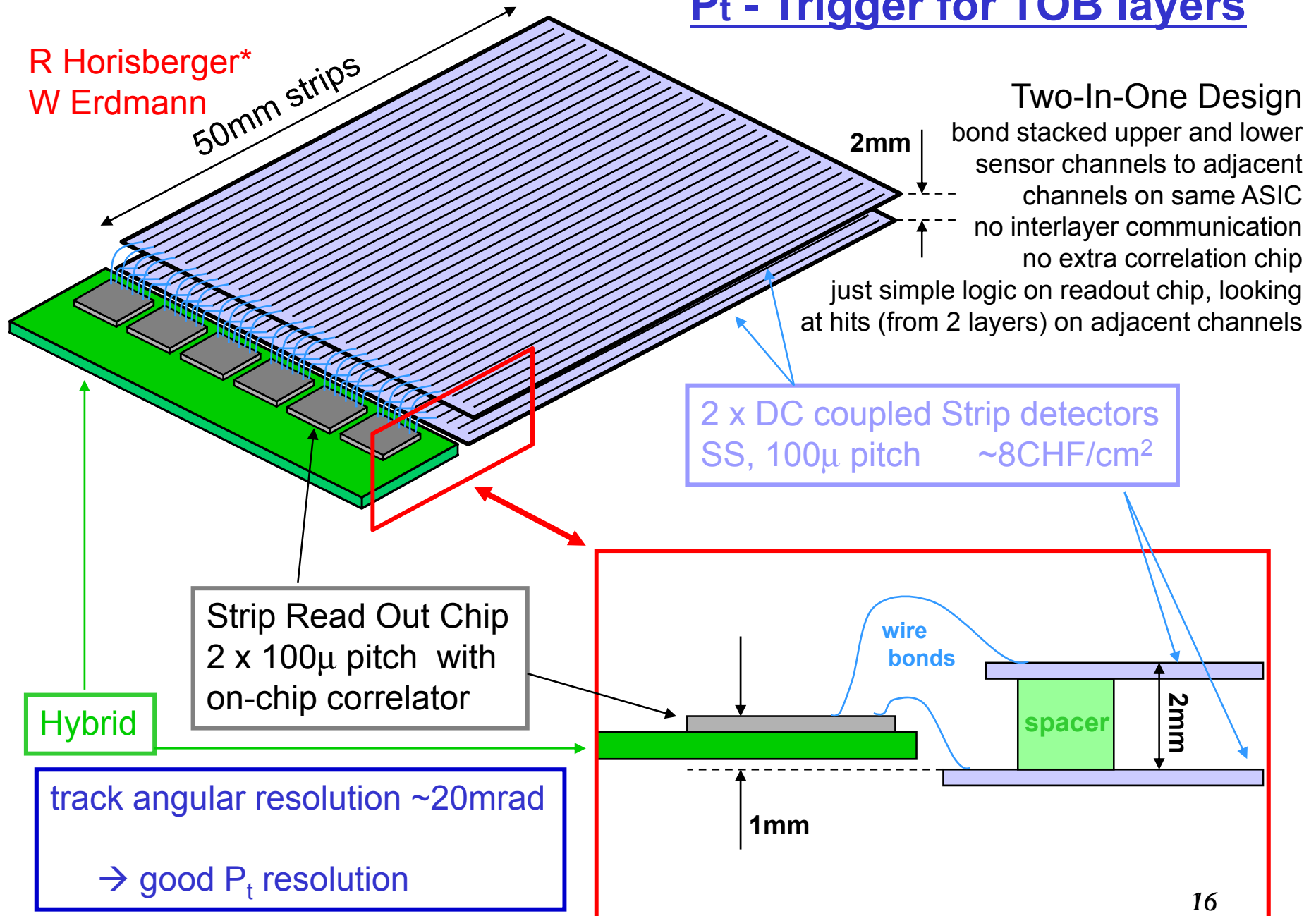
readout power

50 μ W / pixel (extrapolate from current pixels)
=> **2.4 kW** for 8192 x 2 x 3000 channels

=> this will not be a low power layer



P_t - Trigger for TOB layers



* <http://indico.cern.ch/getFile.py/access?contribId=3&sessionId=0&resId=0&materialId=0&confId=36580>

summary

a snapshot of where CMS SLHC tracker readout is at the moment – things will change

have started to think about pros and cons of different architectures

trade-offs between power, FE chip and system complexity, system robustness, and performance

timescales

~ 3 year readout chip development programme about to start

year 1: test structures for different sensor options

polarity, strip length, DC coupling

year 2: full chip prototype

year 3: final prototype

need clearer system level definition here
e.g. sensor choices,
powering scheme – serial/parallel
analog/binary, sparsify or not

binary, non-sparsified could be preferred for short strip pipeline type readout

simpler chip, simpler system

frees up resources to tackle ...

... triggering

this is the most challenging aspect of the CMS tracker for SLHC

dedicated triggering layers probably the way to go

ideas still developing, need further investigation (simulation)

could be several more chips to develop here

extra slides

data volume calculation details

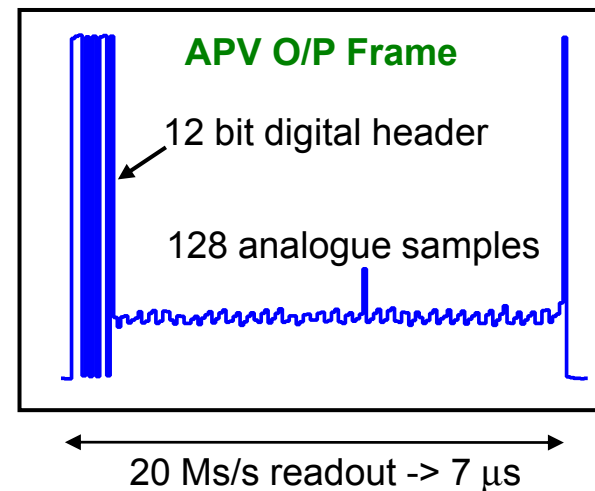
LHC unparsified analog

raw link data bandwidth 9 bits (effective) x 40 Ms/s = 0.36 Gbps

actual triggered data rate = 280 samples per 2 APVs (per data frame) @ 100 kHz (L1 trigger rate)
(2 APVs data interleaved at 40 Ms/s on one fibre)

= 280 x 9 bits x 100 kHz = 0.25 Gbps

so link use efficiency factor ~ 70% (0.25/0.36)



SLHC unparsified “analog” readout

raw GBT data BW 2.56 Gbps organized as up to 30 x 80 Mbps lanes
assume 2 W / GBT

raw data volume per 128 chan.chip for 6 bits ADC @ 100 KHz L1 trigger rate

$$= 128 \times 6 \times 100 \text{ kHz} = \mathbf{77 \text{ Mbps}}$$

=> only 1 chip / GBT lane

=> 32 chips / GBT

=> $2 / (128 \times 32) = \mathbf{490 \text{ } \mu\text{W} / \text{sensor channel}}$

factor ~ 3 higher than LHC figure

actually would be unfeasible to fit 77 Mbps onto 80 Mbps lane

link use factor too high - buffer depth on FE would have to be very deep

would need higher BW link or only 5 bits ADC

SLHC sparsified “analog” readout

data volume determined by occupancy (ave. no. of hits above threshold / BX)

assume 4% occupancy (higher luminosity compensated by higher granularity)

=> 5 hits / 128 channel chip on average

assume 6 bits ADC for pulse height info

data volume / L1 trigger

assume each FE chip produces a data packet in response to L1 trigger, comprising:

8 bits individual chip address

12 bits timestamp (LHC orbit)

7 bits channel address + 6 bits ADC value for each hit (13 bits / hit)

= 85 bits for data packet containing 5 hits

=> average raw data volume per L1 trigger = $85 \times 100 \text{ kHz} = \mathbf{8.5 \text{ Mbps}}$

=> ~ 8 chip / GBT lane

=> 256 chips / GBT

=> $2 / (128 \times 256) = \mathbf{61 \text{ } \mu\text{W} / \text{sensor channel}}$

but $8.5 \text{ Mbps} \times 8 = 68 \text{ Mbps}$ – **85%** of 80 Mbps / GBT lane - rather high use of link BW

binary, non-sparsified, data volumes

only 1 bit / hit, occupancy irrelevant, this is a significant advantage of not sparsifying

raw data volume per L1 trigger, per 128 chan. chip = $(128+16) \times 100 \text{ kHz} = \mathbf{14.4 \text{ Mb/s}}$

(16 bits for digital header information – e.g. error bits and triggered pipeline location like APV)

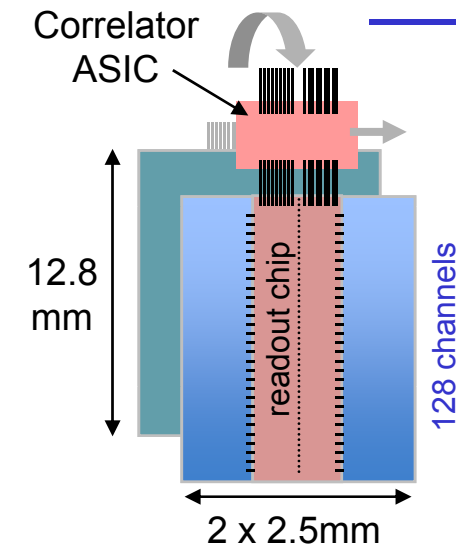
=> ~ 4 chip / GBT lane

=> 128 chips / GBT

=> $2 / (128 \times 128) = \mathbf{122 \text{ } \mu\text{W} / \text{sensor channel}}$

$14.4 \text{ Mbps} \times 4 = 58 \text{ Mbps}$ – only 73 % of 80 Mbps / GBT lane - comfortable use of link BW

PT module for inner layer(1)



use stacked tracking approach – 2 layers

but long pixels: 2.5 mm x 100 μ m allows wire bonding and easy prototyping

readout chip ideas (see * for more details)

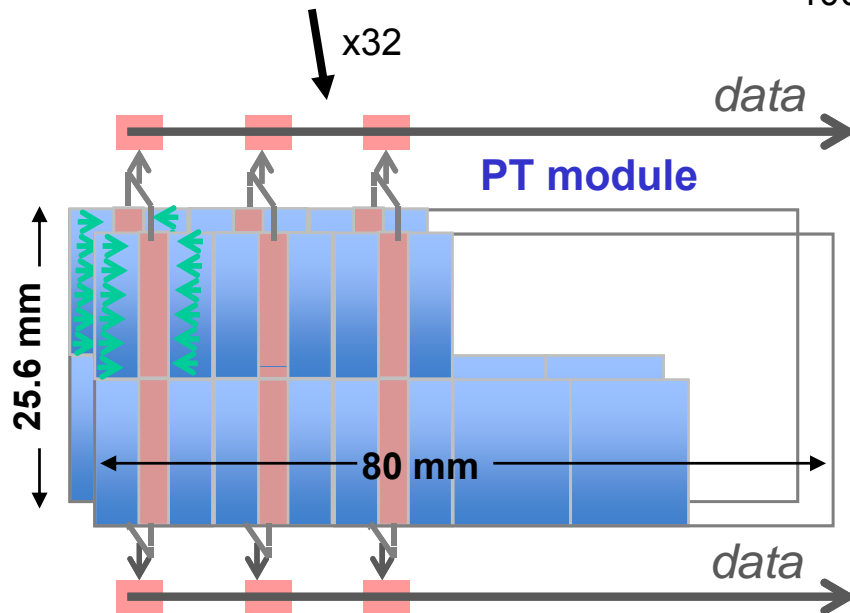
each chip deals with 2 x 128 channel columns

each column divided into 32 x 4 channel groups

transmit 5 bit group address and 4 bit hit pattern to correlator

provides more info than single channel addresses

can also use cluster width discrimination to reduce valid patterns
1000, 0100, 0010, ... 1100, 0110, ... but not 1110, 0111



correlator

compares hit pattern and address from both layers
(no address decoding required)
if match then shift result off-detector

note: not quite as simple as this

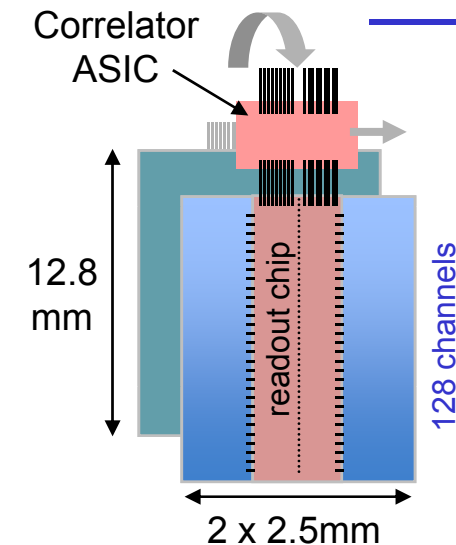
will need extra features to cope with:

hits in adjacent groups

more than one (or two) cluster groups

(should be rare)

PT module for inner layer (2)



data volumes

need to transmit all correlated hit patterns every BX
 for low predicted occupancy (0.5% @ 40 MHz & 10^{35})
 and PT reduction factor 20 (from correlation)
 get 2 hits / PT module per BX (1 hit = address + hit pattern)
 2.56 Gbps link -> 64 bits / BX
 so 1 link can serve 2 PT modules

link power

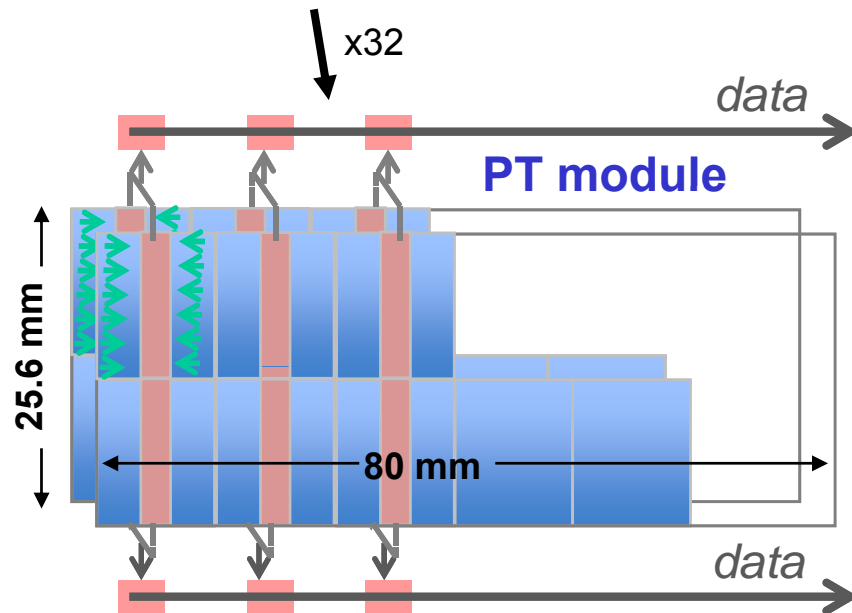
3m length cylinder, 25 cm radius
 need ~3000 PT modules so 1500 links
 => **3 kW** @ 2W / link

readout power

50 μ W / pixel (extrapolate from current pixels)
 => **2.4 kW** for 8192 x 2 x 3000 channels

+ other digital functionality (correlation, short distance digital transmission)

=> this will not be a low power layer



ADC power consumption

ADC Scaling *

- A/D Performance **Figure of Merit**

$$\text{FoM} = 2^{\text{ENOB}} * f_{\text{sample}} / P$$

Year	2003	2006	2009	2012	2015
Tech [nm]	130	90	65	45	32
FoM [GHz/W]x10 ³	0.8	1.2	1.6-2.5	2.5-5	4-10

From ITRS roadmap 2003

International Technology Roadmap for Semiconductors (ITRS-2003)

(forecast from the semiconductor industry with 15 year perspective)

based on general considerations
(individual architecture dependent)

ADC power given by process,
Effective No. Of Bits, conversion
frequency and FoM

ADC on every channel hard to do

6 bits @ 20 MHz -> 1.6 mW (0.13μm)

ADC on every chip quite possible

8 bits @ 20 MHz -> 6.4/128 -> 50 μW/chan

APV25 power
2.7 mW / chan.

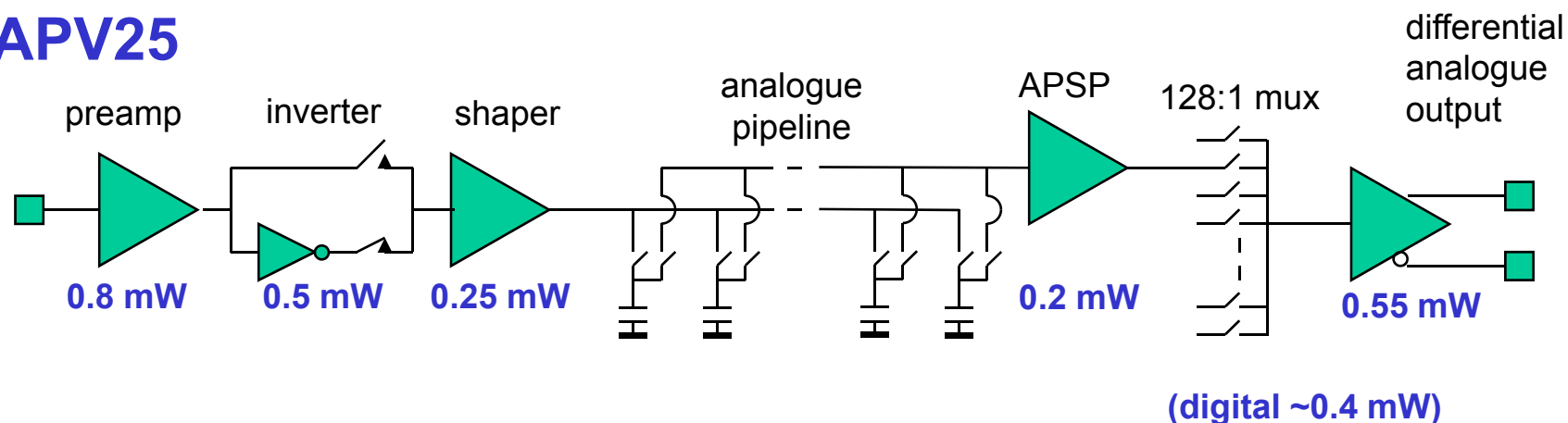
ADC power @ 20 MHz [mW]

	130nm	65nm
8bits	6.4	2.5
6bits	1.6	0.6

* from A. Marchioro talk at 2nd CMS SLHC workshop

APV25 power breakdown

APV25



input amplifier power the largest component for APV25 at LHC

preamp dominates amplifier power (I/P device current)

inverter power not relevant to SLHC

APV25 designed to cope with 2 sensor polarities

APV25 power breakdown [mW/channel]

preamp/shaper	1.05
inverter	0.5
APSP	0.2
mux & output stages	0.55
digital	0.4
	<hr/>
	2.7

$L=10^{34}$ muon
L1 trigger rate

