

Modelling with Space-Charge

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Reference: "Computer Simulation Using Particles", R.W. Hockney and J.W. Eastwood (UKAEA Culham and Reading University).

ICFA Space-Charge Workshop April 2003



Historical

- 1980's inertial confinement fusion, behaviour of beams under intense space charge
 - -Lawson, Reiser, Keefe, Wangler..
- 1990's spallation neutron sources: EHF, JHF, ESS, SNS – Machida, Holmes ...
- 2000's proton drivers, neutrino factory, Fermilab upgrades
- 2010's ...



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Message: Don't run codes blindly and assume the answers are always right. Question the results. It pays to know what is in the codes, what they calculate and how. In accelerator modelling, all-purpose "black boxes" don't always work



Overview

- Principles of simulation with space-charge
- Calculation of space-charge forces
- Analytical models
- Formulation of results
- Benchmarking and validation
- Use of codes
- Illustrations
- List of codes



Basic Equations (Paraxial)

$$x'' + k_x(s)x - \frac{q}{m_0\gamma^3\beta^2c^2} E_x(x, y, z, s) = 0$$

$$y'' + k_y(s)y - \frac{q}{m_0\gamma^3\beta^2c^2} E_y(x, y, z, s) = 0$$
(1)
(2)

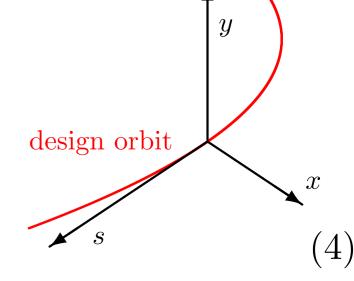
$$z'' + k_z(s)z - \frac{q}{m_0\gamma^3\beta^2c^2} E_z(x, y, z, s) = 0$$
(3)

Particle coordinates (x, y, z) with respect to frame whose motion is given by s Factor $1/\gamma^2$ from electrostatic-magnetostatic effects

Other factor γ from relativistic mass $m = m_0 \gamma$

Space-charge field \mathbf{E} from Maxwell's equation:

$$\nabla \cdot \mathbf{E} = \frac{q}{\epsilon_0} \ n(x, y, z, s)$$



where n(x, y, z, s) is the number density of the beam distribution.

n(x, y, z, s) given by the particle density f(x, y, z, x', y', z', s) in six-dimensional phase space, which must satisfy the Vlasov equation

$$\frac{\partial f}{\partial s} + (\mathbf{x}' \cdot \nabla) f - (\mathbf{k} - \frac{q}{m_0 \gamma^3 \beta^2 c^2} \mathbf{E}) \cdot \nabla_{\mathbf{x}'} f = 0, \tag{5}$$

through

$$n = \iiint f(x, y, z, x', y', z', s) \, \mathrm{d}x' \, \mathrm{d}y' \, \mathrm{d}z'. \tag{6}$$

The total number of particles in the beam is

$$N = \iiint n(x, y, z, s) \, \mathrm{d}x \, \mathrm{d}y \, \mathrm{d}z. \tag{7}$$

This is a complete set of seven coupled equations in which the distribution determines the forces, which determine the motion, which determines the distribution, and so on. **Recall:** For a 2D uniform beam with elliptical cross section $\frac{x^2}{a^2} + \frac{y^2}{b^2} \leq 1$, space-charge forces are linear and given by

$$\mathbf{E} = \frac{Nq}{\pi\epsilon_0(a+b)} \left(\frac{x}{a}, \frac{y}{b}\right),$$

where N is the number of particles per unit length.

Equations of particle motion and envelope equations are then:

$$\begin{cases} x'' + k_x(s)x - \frac{2K}{a+b}\frac{x}{a} = 0\\ y'' + k_y(s)y - \frac{2K}{a+b}\frac{y}{b} = 0\\ a'' + k_x(s)a - \frac{\epsilon_x^2}{a^3} - \frac{2K}{a+b} = 0\\ b'' + k_b(s)b - \frac{\epsilon_y^2}{b^3} - \frac{2K}{a+b} = 0 \end{cases}$$
$$= \frac{I}{I_0}\frac{2}{(\beta\gamma)^3} \text{ is the Perveance and } I_0 = \frac{4\pi\epsilon_0 m_0 c^3}{q}$$

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For non-linear beams, rms beam size is $\tilde{a} = \sqrt{\langle x^2 \rangle}$ and rms evolution equations are

$$\frac{\mathrm{d}^2 \tilde{a}}{\mathrm{d}s^2} + k_x(s)\tilde{a} - \frac{\tilde{\epsilon}^2}{\tilde{a}^3} - \frac{q}{m_0\gamma^3\beta^2c^2}\frac{\langle xE_x\rangle}{\tilde{a}} = 0 \tag{1}$$

$$\frac{\mathrm{d}^2}{\mathrm{d}s^2}\tilde{\epsilon}^2 = \frac{2q}{m_0\gamma^3\beta^2c^2}\left[\langle x^2\rangle\langle x'E_x\rangle - \langle xx'\rangle\langle xE_x\rangle\right] \tag{2}$$

where
$$\tilde{\epsilon} = \sqrt{\langle x^2 \rangle \langle x'^2 \rangle - \langle xx' \rangle^2}$$
 is the rms emittance. (3)

Sacherer showed that for ellipsoidal particle densities of the form

$$n(x, y, z, s) = n\left(\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2}\right)$$

the averages $\langle xE_x \rangle, \langle yE_y \rangle$ etc depend only very weakly on the exact charge distribution.

So the general rms envelope equation is the same as for an equivalent KV beam.

Envelope Codes

2D (transverse) codes use envelope equations for KV beam:

$$a'' + k_x(s)a - \frac{\epsilon_x^2}{a^3} - \frac{2K}{a+b} = 0 \qquad K = \frac{I}{I_0} \frac{2}{(\beta\gamma)^3} \text{ is the Perveance}$$

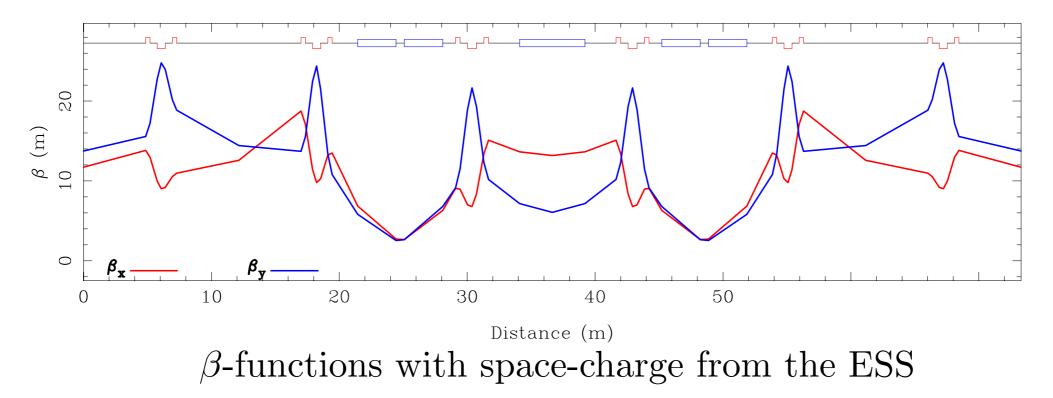
$$b'' + k_y(s)b - \frac{\epsilon_y^2}{b^3} - \frac{2K}{a+b} = 0$$
Define
$$\mathbf{X} = \begin{bmatrix} a\\a'\\b\\b' \end{bmatrix} \implies \frac{d\mathbf{X}}{ds} = \frac{d}{ds} \begin{bmatrix} a\\a'\\b\\b' \end{bmatrix} = \begin{bmatrix} -k_x(s)a + \frac{2K}{a+b} + \frac{\epsilon_x^2}{a^3}\\b'\\-k_y(s)b + \frac{2K}{a+b} + \frac{\epsilon_y^2}{b^3} \end{bmatrix}$$

Integrate using standard numerical packages based on, for example, Runge-Kutta techniques.

Output either as beam sizes or Twiss parameters defined by $\beta_x = a^2/\epsilon_x$, $\alpha_x = -aa'/\epsilon_x$ etc

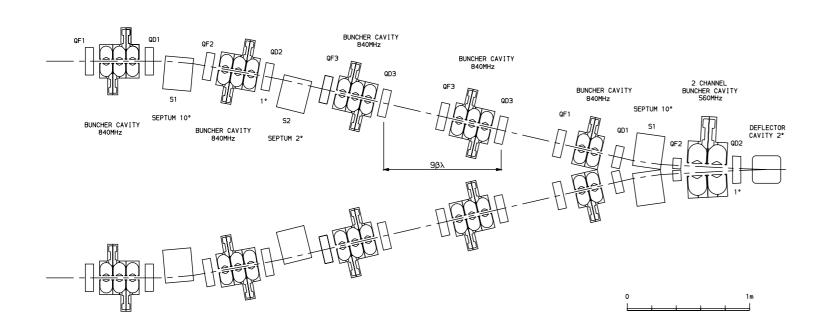
Examples of Envelope Codes

- KVBL (Prior) Includes matching, parameter optimisation, graphical output; switches to standard matrix methods in absence of spacecharge
- WinAgile (Bryant) Similar to KVBL but Windows based with GUI
- Trace2D Old code from Los Alamos, based on matrices with space charge kicks in the middle of elements
- Trace3D Development of Trace2d to include momentum effects; works from a keyboard implemented graphics system.



KVBL: ESS Funnel (1996)

- 57 mA linac current (H⁻)
- Achromatic in all planes
- Uniform optics to minimise non-linear space-charge effects



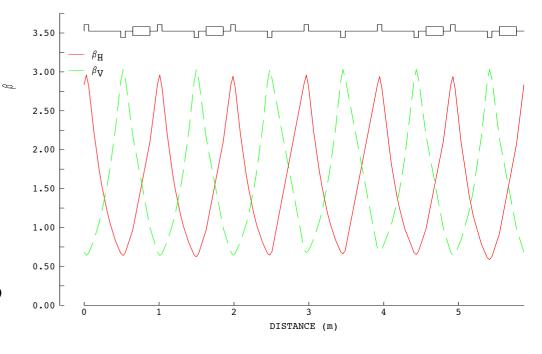
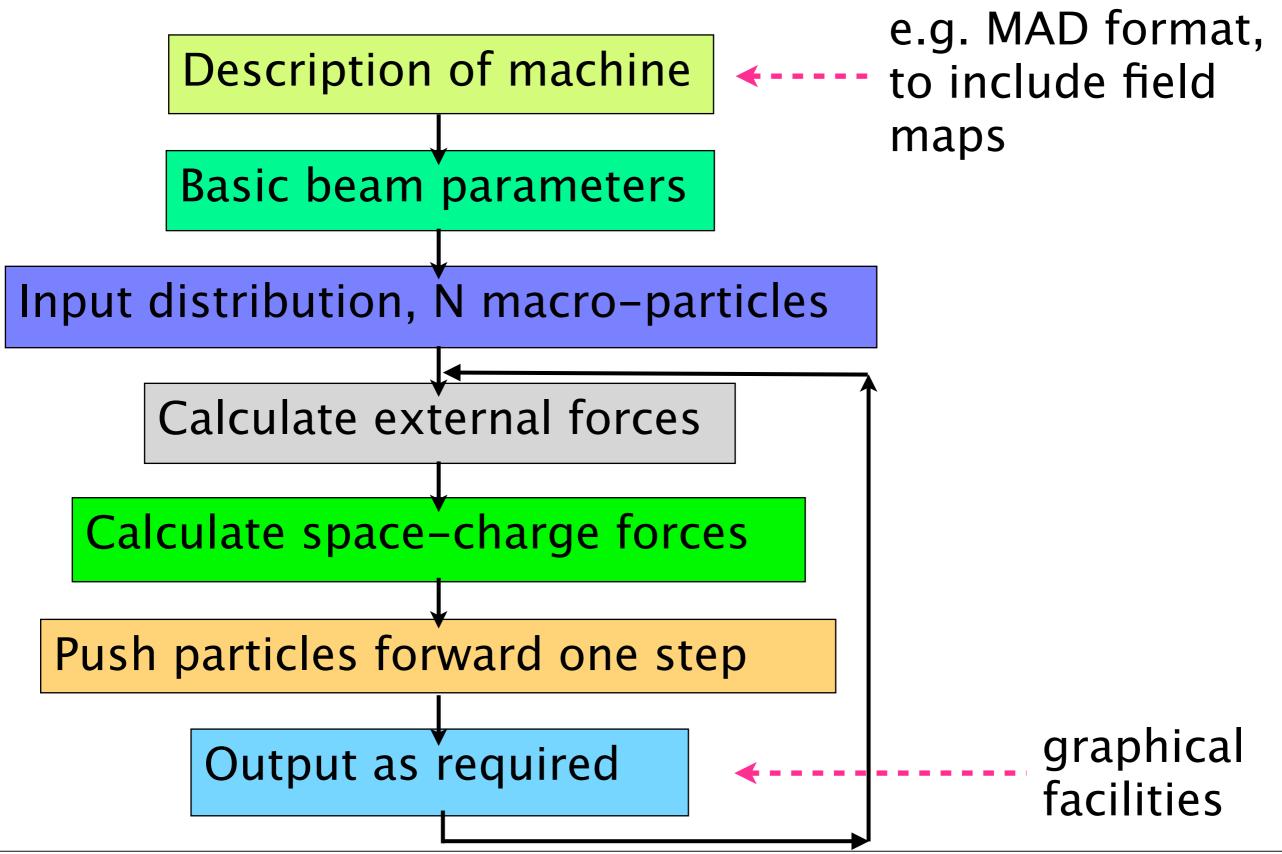


Figure 3: Focusing parameters for the ESS funnel

Enabled emittance growth to be reduced to <1% cf $\sim50\%$ in early LANL experiments

Basic Tracking Procedures



Input Beam Distribution

- How many macro-particles are needed to model a beam of 10¹⁰-10¹⁴ real particles?
 - sufficiently many for good statistics
 - predicted effects should not be a consequence of reduced number of particles, statistical errors, rounding and interpolation errors.
- Most space-charge codes now use ~10⁵-10⁶ simulation particles; some runs have been made with 10⁷-10⁸.



Initial Particle Distribution

- Can be read from a given dataset, for example from a previous run, or can be based on physical data.
- Can be a model distribution KV, Waterbag, Gaussian, semi-Gaussian etc
- Also include stationary distributions (self-consistent functions of the Hamiltonian H)
 - generate a normalised distribution; then scale and rotate as appropriate
 - may need to change coordinates, e.g Cartesians to 4D-polar system
 - can be fitted to given beam sizes or created as an rms equivalent beam



Method based on f(x) dx = dF(x) where F'(x) = f(x); this may not always be possible.

Method of Ratio of Uniform Deviates:

The density function f(x) can be generated through a uniform filling of the region

$$0 < u < \sqrt{f\left(\frac{v}{u}\right)}$$

of the two-dimensional (u, v) plane with a random number generator. Then $x = \frac{v}{u}$ has the desired density function.

Example: The Cauchy Distribution
$$f(x) = \frac{1}{\pi} \frac{1}{1+x^2}$$
.
The sampling region is

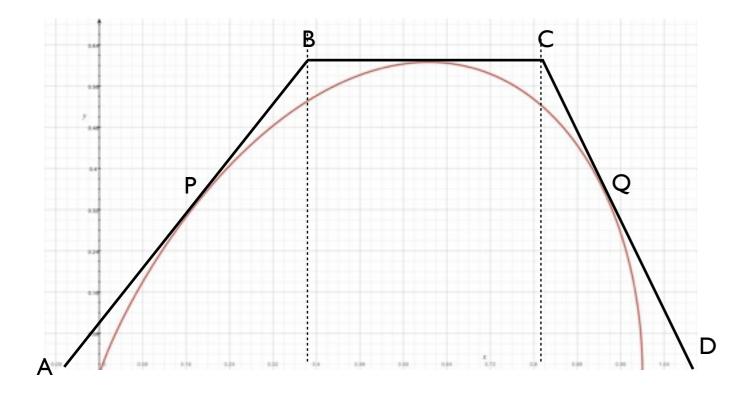
$$\left\{ (u,v): 0 \le u \le \left[1 + \left(\frac{v}{u}\right)^2 \right]^{-\frac{1}{2}} \right\} = \{ (u,v): u^2 + v^2 \le 1, u \ge 0 \}.$$

Half circle, centred on origin, radius 1.

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Example: Gaussian Distribution $f(x) = \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}x^2}$. The sampling region is

$$\left\{ (u,v): 0 \le u \le e^{-\frac{v^2}{2u^2}} \right\} = \{ (u,v): v \le \sqrt{-2u^2 \ln u}, \ 0 \le u \le 1 \}.$$



Sampling method: adjust tangents at P, Q to minimise area ABCD.

 \implies Probability that a point within ABCD is also within required region is 0.922. Method uses some simple initial pre-sampling to check that a point (u, v) lies in region; if so, then a more accurate check.

Approach turns out to be faster than most other methods and also gives a very good model of the required distribution.

Solution of Equations of Motion

Equations of motion of the form Euler (forward) difference method:

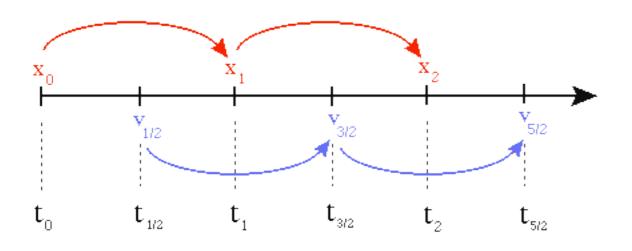
$$\mathbf{x}'' = \mathbf{F}(s, \mathbf{x}, \mathbf{x}') \\ \begin{bmatrix} \mathbf{x}_{n+1} \\ \mathbf{x}'_{n+1} \end{bmatrix} = \begin{bmatrix} \mathbf{x}_n + h\mathbf{x}'_n \\ \mathbf{x}'_n + h\mathbf{F}(s_n, \mathbf{x}_n, \mathbf{x}'_n) \end{bmatrix}$$

h is step length

Accuracy is only $O(h^2)$

Could use Runge-Kutta method accurate to $O(h^4)$, but requires extra storage and 4 calculations of \mathbf{F} for each particle instead of one. Can be reduced by Blum's method, but unlikely to give a viable method for modelling $\gtrsim 10^5$ particles in a realistic time.

Symplectic Leap-frog Integration Scheme

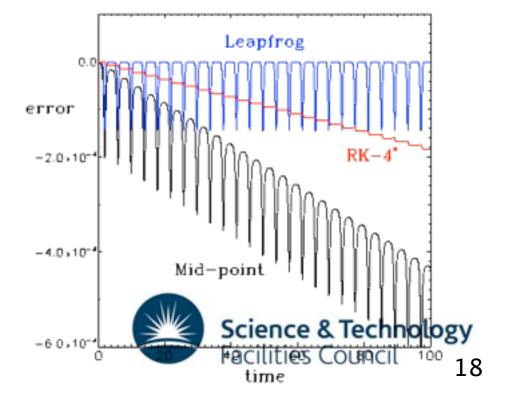


Interleave position and velocity half a step out of phase, and leap-frog coordinates forward in distance or time.

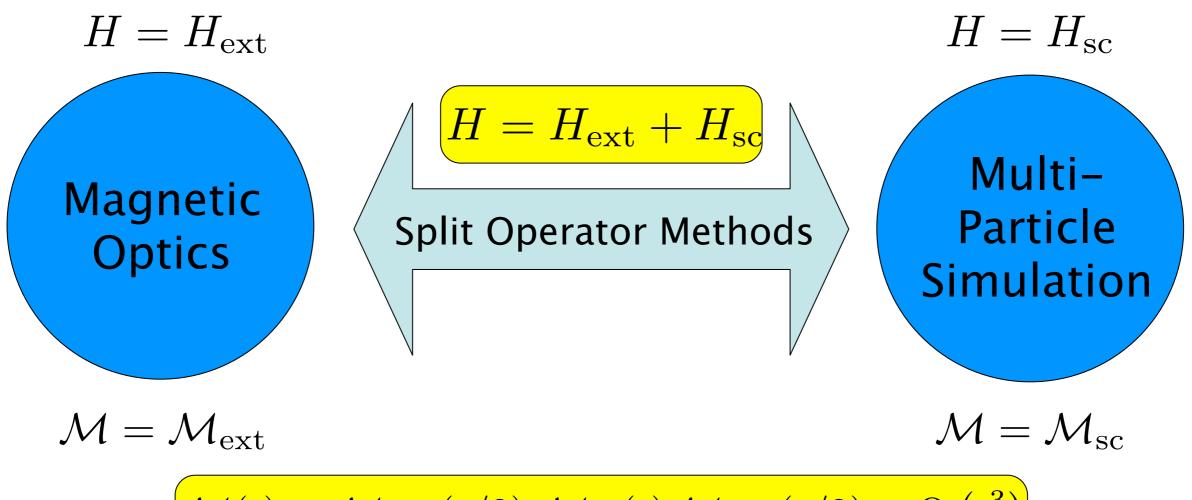
$$\mathbf{x}_{n+1} = \mathbf{x}_n + h \mathbf{x'}_{n+\frac{1}{2}}$$
 Error is $O(h^3)$
$$\mathbf{x'}_{n+\frac{1}{2}} = \mathbf{x'}_{n-\frac{1}{2}} + \frac{1}{2} h \left[\mathbf{F}(s_n, \mathbf{x}_n, \mathbf{x'}_{n-\frac{1}{2}}) + \mathbf{F}(s_n, \mathbf{x}_n, \mathbf{x'}_{n+\frac{1}{2}}) \right]$$

Step length must be chosen to allow plasma oscillations to be represented $(\omega_p h/\beta c \ll 2)$

Method is extremely stable. It has a timereversible property, which avoids long-term drift caused by systematic errors that could mask the true solution. Note: even 4th order Runge-Kutta suffers.



Split Operator Approach



 $\mathcal{M}(t) = \mathcal{M}_{\text{ext}}(t/2) \mathcal{M}_{\text{sc}}(t) \mathcal{M}_{\text{ext}}(t/2) + O(t^3)$

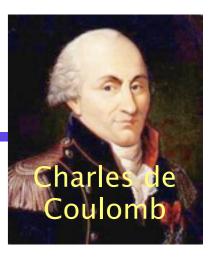
Philosophy:

- Do not take tiny steps to push $\sim 10^7 10^8$ particles 業
- Do take tiny steps to compute maps, then push particles with maps. *

Acknowledgement: Rob Ryne/Ji Qiang – IMPACT



Space-Charge Calculations



Many different approaches, most based on approximations.

- Use Coulomb forces between pairs of particles to calculate forces at each step.
- Assume variation of space-charge with distance is small; impose space-charge kicks once or twice per element, but track using non-space-charge methods otherwise.
- Use KV linear space-charge formula, scaled by longitudinal line density.
- Calculate space-charge potential from Poisson's equation in beam-frame, either in 3D or 2+1D.

Note: some methods ignore boundary effects



Space-Charge Options

- Coulomb approach is O(N²) and very time consuming. Problems when particles move too close together ⇒ cut-off distance needed (Debye length). Also open to rounding errors, especially on the axes where transverse forces should sum to zero.
 e.g 2D circular uniform beam, N = 50,000 simulation particles: calculations take several minutes and only 60% within 10% error band.
- 2D+1D approach gives good results (beam split into 2D slices for transverse forces, then longitudinal force from line density).
- Finite difference method represents sophisticated approach but inclusion of boundaries (image effects) not easy.
- Finite elements provide most flexible approach and can call on huge range of engineering expertise.



Example: SIMPSONS

• Solves Poisson's equation in cylindrical coordinates for perfectly conducting circular pipe:

$$\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial\Phi}{\partial r}\right) + \frac{1}{r^2}\frac{\partial^2\Phi}{\partial\phi^2} = -\frac{\rho}{\epsilon_0\gamma^2}$$

• Charge distribution is Fourier transformed in azimuthal direction

$$\Phi = \sum_{m} \phi_{m} e^{im\phi}$$

$$\frac{\rho}{\epsilon_{0}\gamma^{2}} = \sum_{m} n_{m} e^{im\phi}$$

$$\left\{ \begin{array}{c} \phi_{m} = \frac{1}{2\pi} \int_{0}^{2\pi} \Phi(r, z, \phi) e^{-im\phi} d\phi \\ n_{m} = \frac{1}{2\pi} \int_{0}^{2\pi} \frac{\rho(r, z, \phi)}{\epsilon_{0}\gamma^{2}} e^{-im\phi} d\phi \end{array} \right.$$

• Then
$$n_m(r,z) = -\frac{1}{r}\frac{\partial}{\partial r}\left(r\frac{\partial}{\partial r}\phi_m(r,z)\right) + \frac{m^2}{r^2}\phi_m(r,z)$$



SIMPSONS (cont)

• Solution with $\phi_m = 0$ on r = b is

$$\phi_m = W(r) - \left(\frac{r}{b}\right)^m W(b), \qquad \phi_{-m} = \phi_m^*, \ m \ge 0$$

where

$$W(r,z) = \begin{cases} \int_0^r \ln\left(\frac{r}{r'}\right) n_m(r',z)r' \,\mathrm{d}r' & \text{for } m = 0\\ \frac{r^m}{2m} \int_0^r n_m(r',z)r'^{1-m} \,\mathrm{d}r' - \frac{r^{-m}}{2m} \int_0^r n_m(r',z)r'^{1+m} \,\mathrm{d}r' & \text{for } m \neq 0 \end{cases}$$

• In practice, integral is replaced by summation over grid points.

• Then
$$\vec{E} = \nabla \Phi = \sum_{m} \left(\frac{\partial \phi_m}{\partial r}, \frac{im}{r} \phi_m, \frac{\partial \phi_m}{\partial z} \right) e^{im\phi}$$



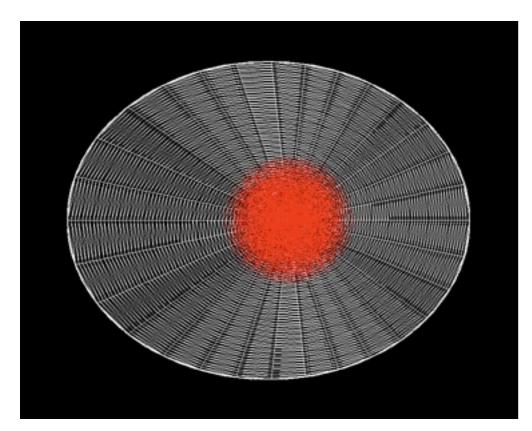
Finite Element Approach

Based on the variational problem:

$$\delta\pi(\phi) = 0, \text{ where } \pi(\phi) = \frac{1}{2} \int_{V} |\nabla\phi|^2 \, \mathrm{d}V + \frac{1}{\epsilon_0} \int_{V} \rho\phi \, \mathrm{d}V - \int_{\partial V} \bar{\phi}_n \phi \, \mathrm{d}S$$

Equivalent to
$$\nabla^2 \phi = -\frac{\rho}{\epsilon_0}$$
 in $V, \ \phi = \bar{\phi}, \ \frac{\partial \phi}{\partial n} = \bar{\phi}_n$ on ∂V

Cover region with mesh to fit boundaries:



Fit a polynomial to each mesh:

$$\phi = a_0 \qquad \text{order } 0$$

$$+a_1x + a_2y + a_3z \qquad \text{order } 1$$

$$+a_4x^2 + a_5y^2 + a_6z^2$$

$$+a_7xy + a_8xz + a_9yz \qquad \text{order } 2$$

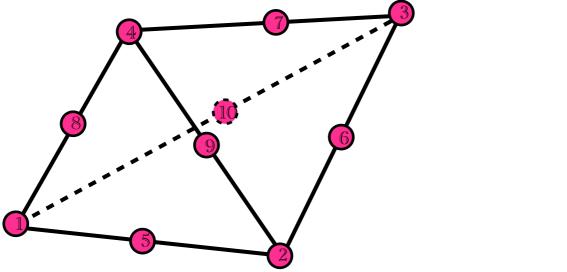
$$+ \dots$$

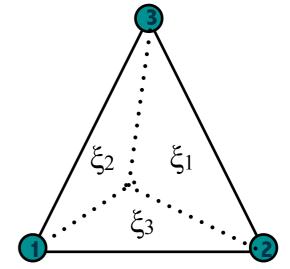
$$= \sum_i f_i(\xi_j)\phi_i \qquad \text{Science & Technology}$$

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 f_i are shape functions, ξ_i are areal coordinates. Look for a complete set to chosen order. For example to order 2, 10 unknowns (a_0, \ldots, a_9) , so need 10 nodes:





Variational problem turns into sparse matrix equation for potential at nodes given by

$$K_{ij}\phi_j = Q_i,\tag{1}$$

where Q_i come from charge distribution

$$\rho(\mathbf{x}) = \sum_{\text{particles } i} q_i \delta(\mathbf{x} - \mathbf{x}_i) \qquad \Longrightarrow \int \rho \phi \, \mathrm{d}V = \sum_{\text{particles } i} q_i \phi(\mathbf{x}_i).$$

 (K_{ij}) depends only on mesh. (1) is solved by standard methods (Gaussian elimination, triple factoring, conjugate gradient etc).

Space-charge forces calculated from

$$\mathbf{F} = -\nabla\phi = -\sum_{i,j} \frac{\partial f_i}{\partial \xi_j} \phi_i \nabla \xi_j.$$

• Since stiffness matrix (K_{ij}) depends only on mesh, can be set up and pre-inverted, giving a fast, simple "black-box" for space-charge calculations

$$\phi_i = \sum_j K_{ij}^{-1} \rho_j$$

Standard Test: 2D uniform circular beam, N = 50,000 macro-particles

- 3rd Order, \sim 400 mesh elements, find > 95% within 10% error band
- 1st order, \sim 3000 mesh elements, find > 90% within 10% error band

- Simple conversion to different coordinate systems.
 - For example, 2D transverse (x, y) Poisson solver to axisymmetric 3D (r, z) code through $x \to r, y \to z, dx dy \to r dr dz$
- 2D code easily converted to 3D, triangular elements to tetrahedra
- Fits all boundaries likely in accelerators. For analytical purposes, "infinite" boundaries modelled using super-elements or matching to $\ln r$ (2D) or 1/r (3D) potentials at sufficiently large distances.
- Longitudinal boundary conditions generally periodic (bunch to bunch in linacs or rings)
- May require large amount of storage (not a problem nowadays) and CPU
 - can be parallelised using method of *static condensation* to split into substructures
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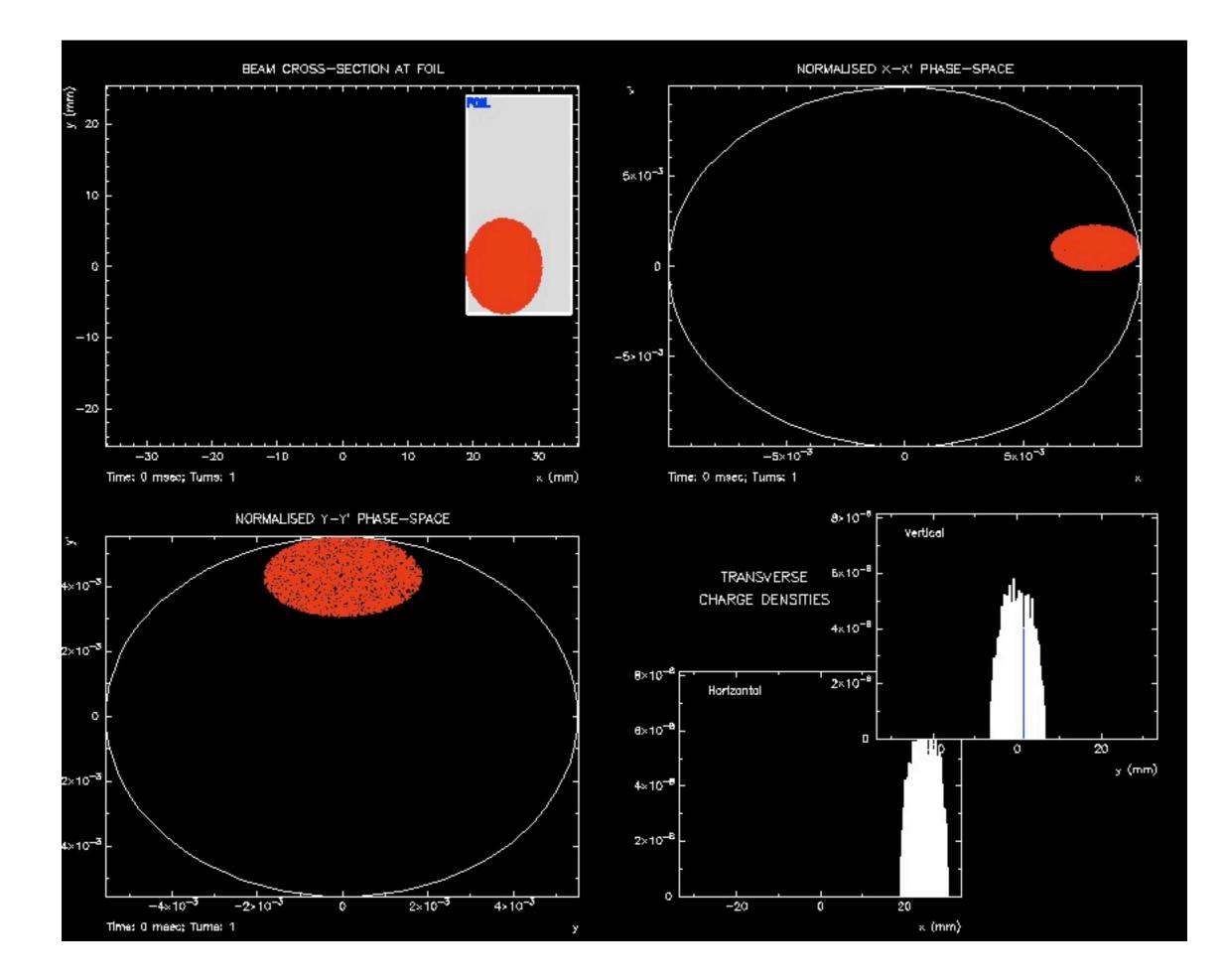
Example: Multiturn Injection at FNAL

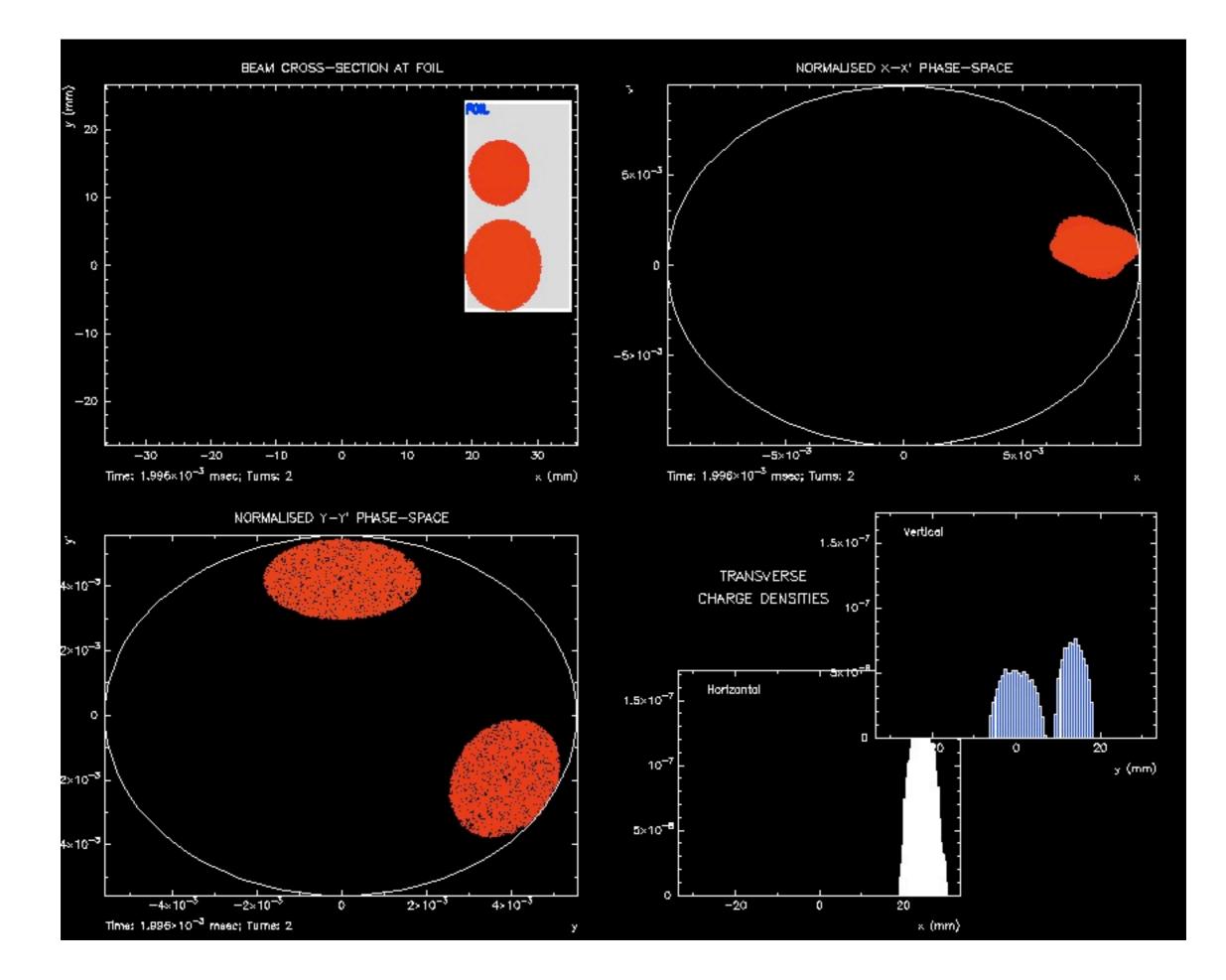
Injection into a 0.4-8 GeV RCS designed as replacement for Fermilab booster

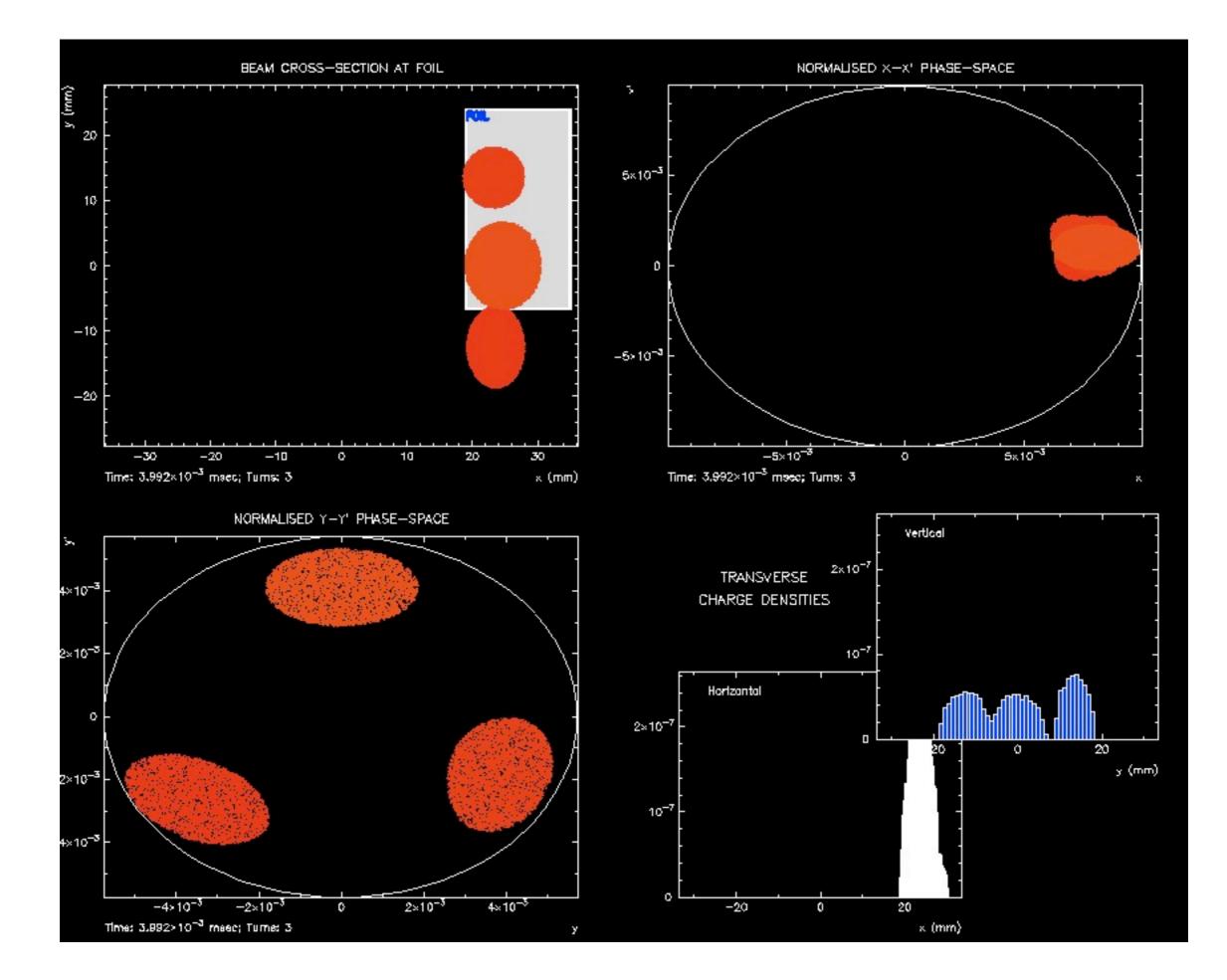
- 400 MeV H⁻ injection
- 45 injection turns, 474 m ring
- Phase space painting
 - -Horizontal orbit bumps
 - -Vertical variation of beam angle

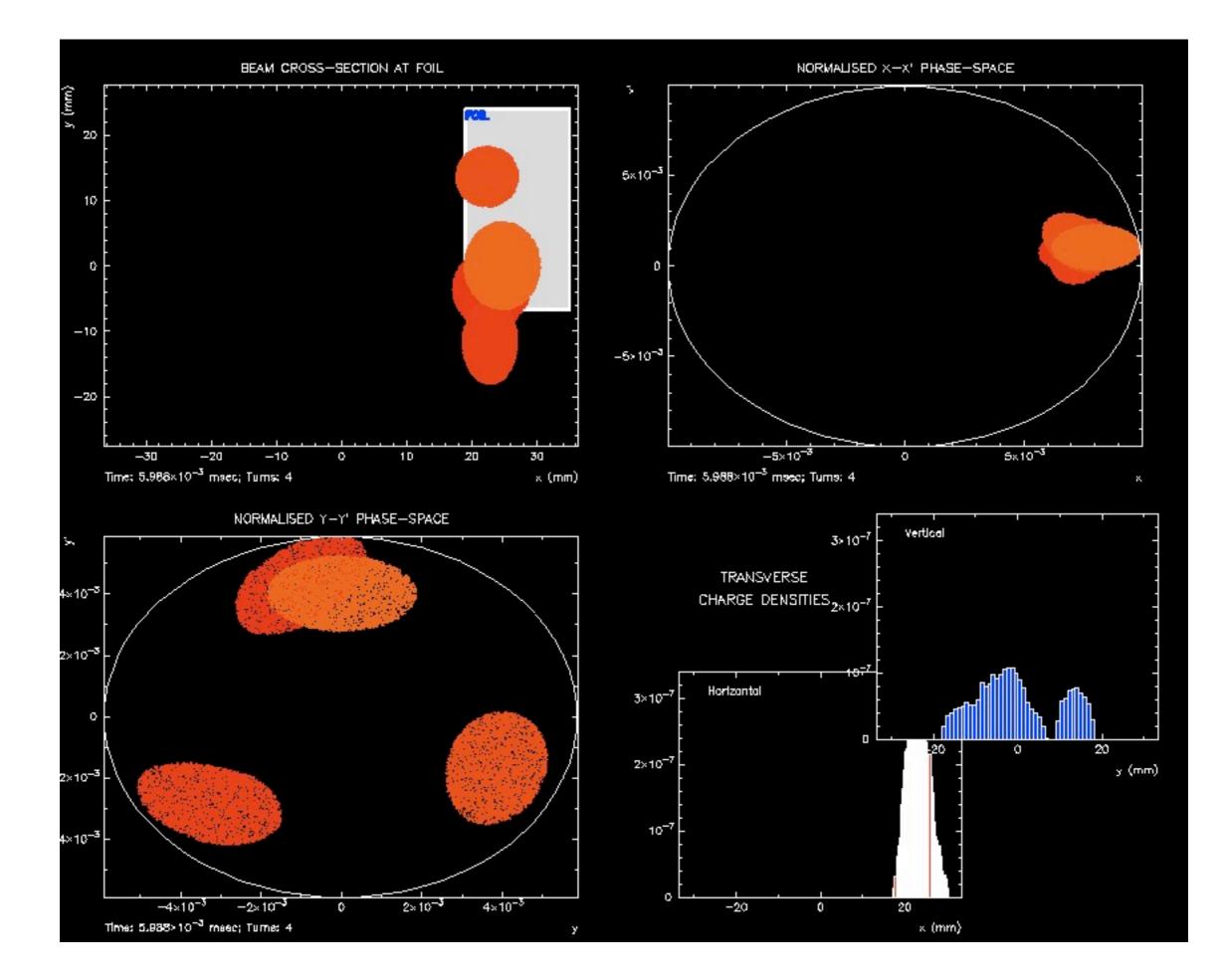
Basic injection parameters and painting optimisation using codes MISxxx (C.Prior)

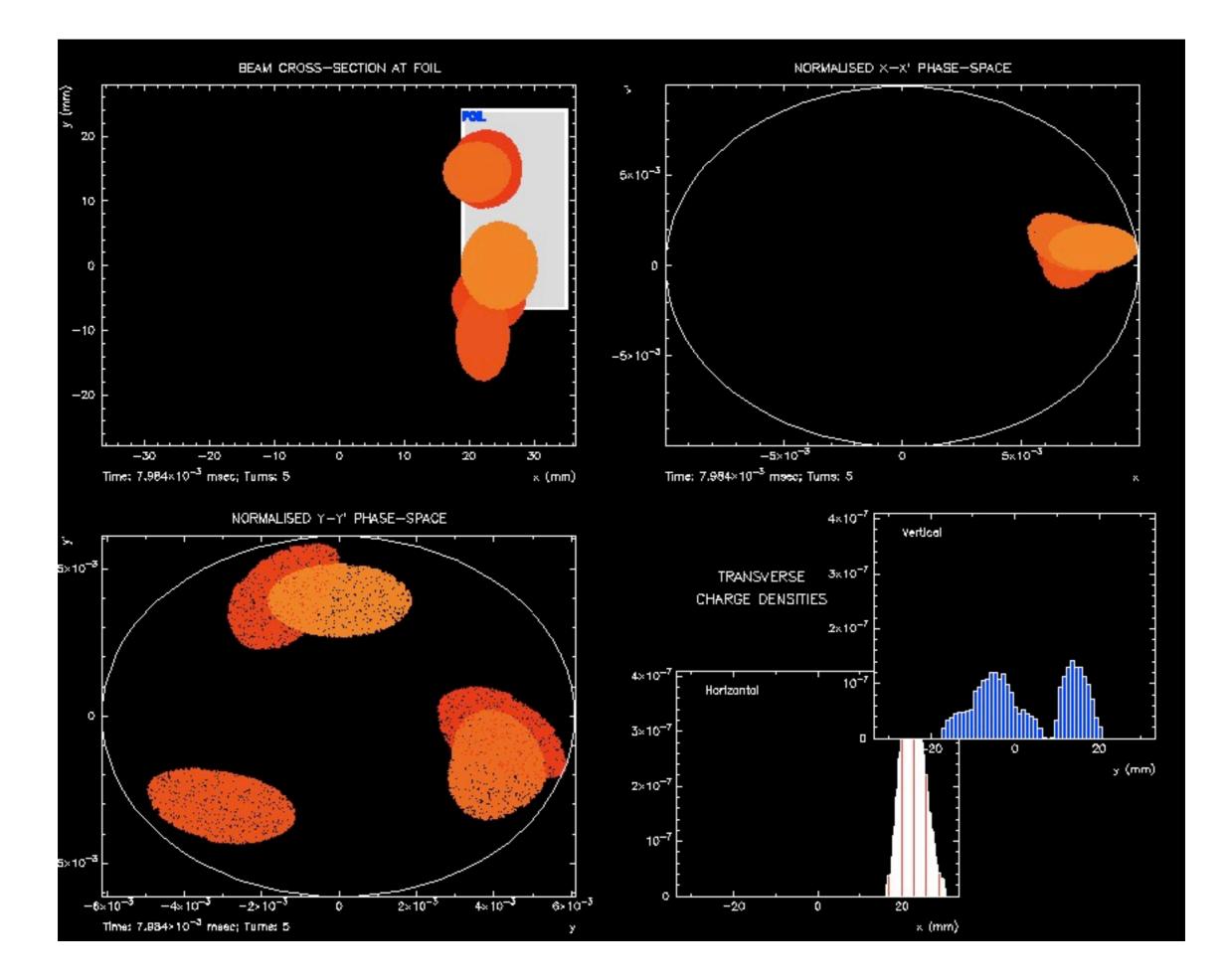


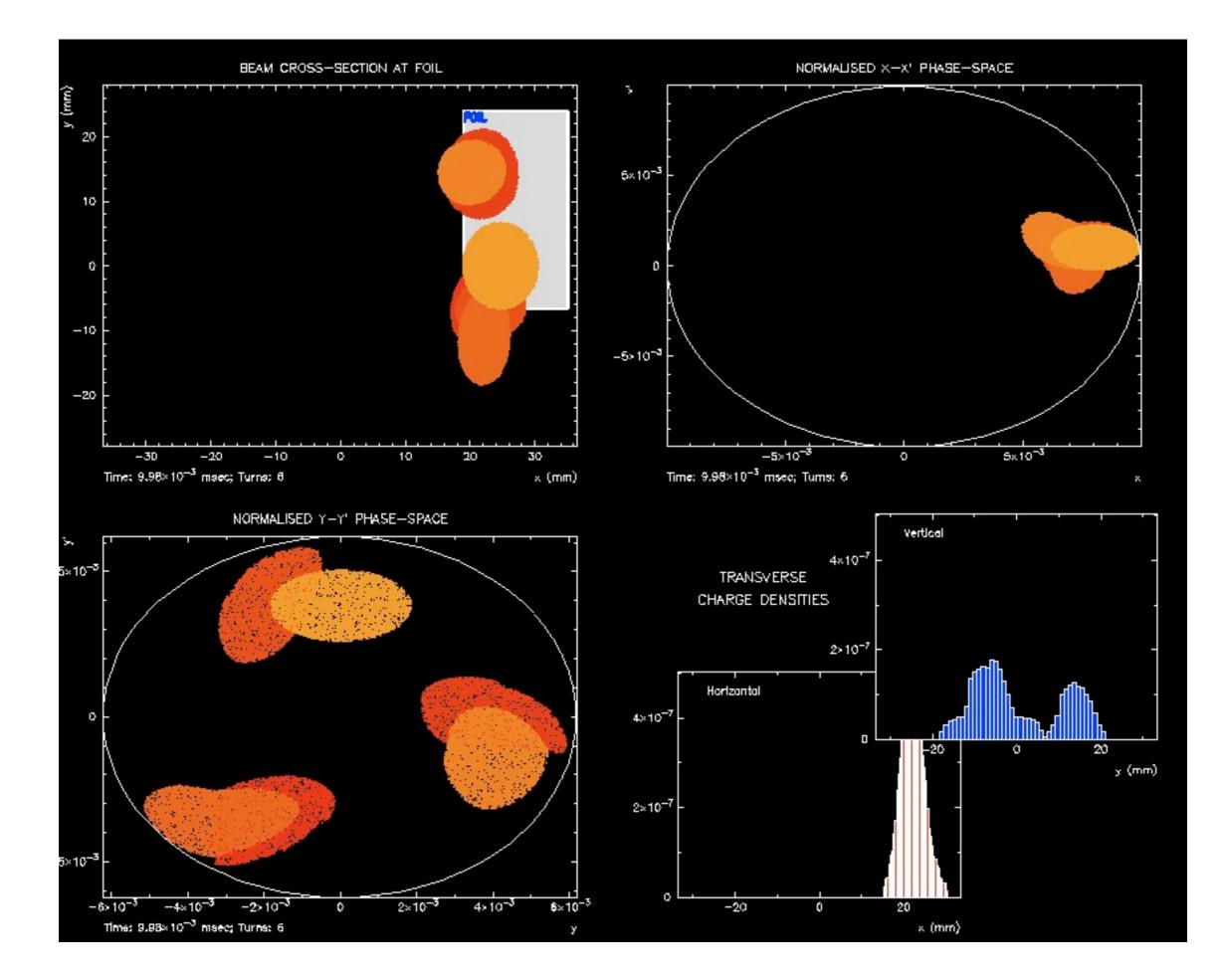


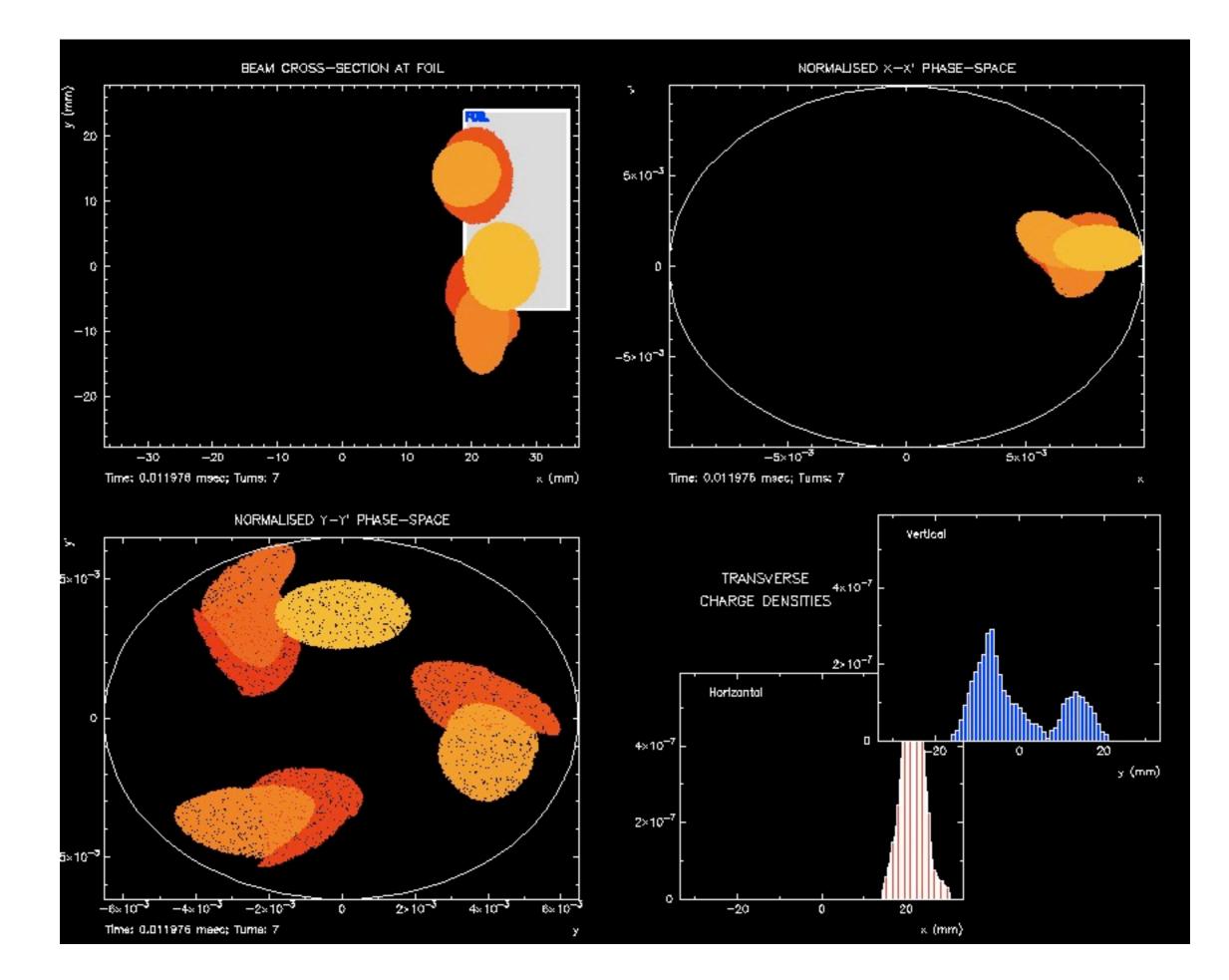


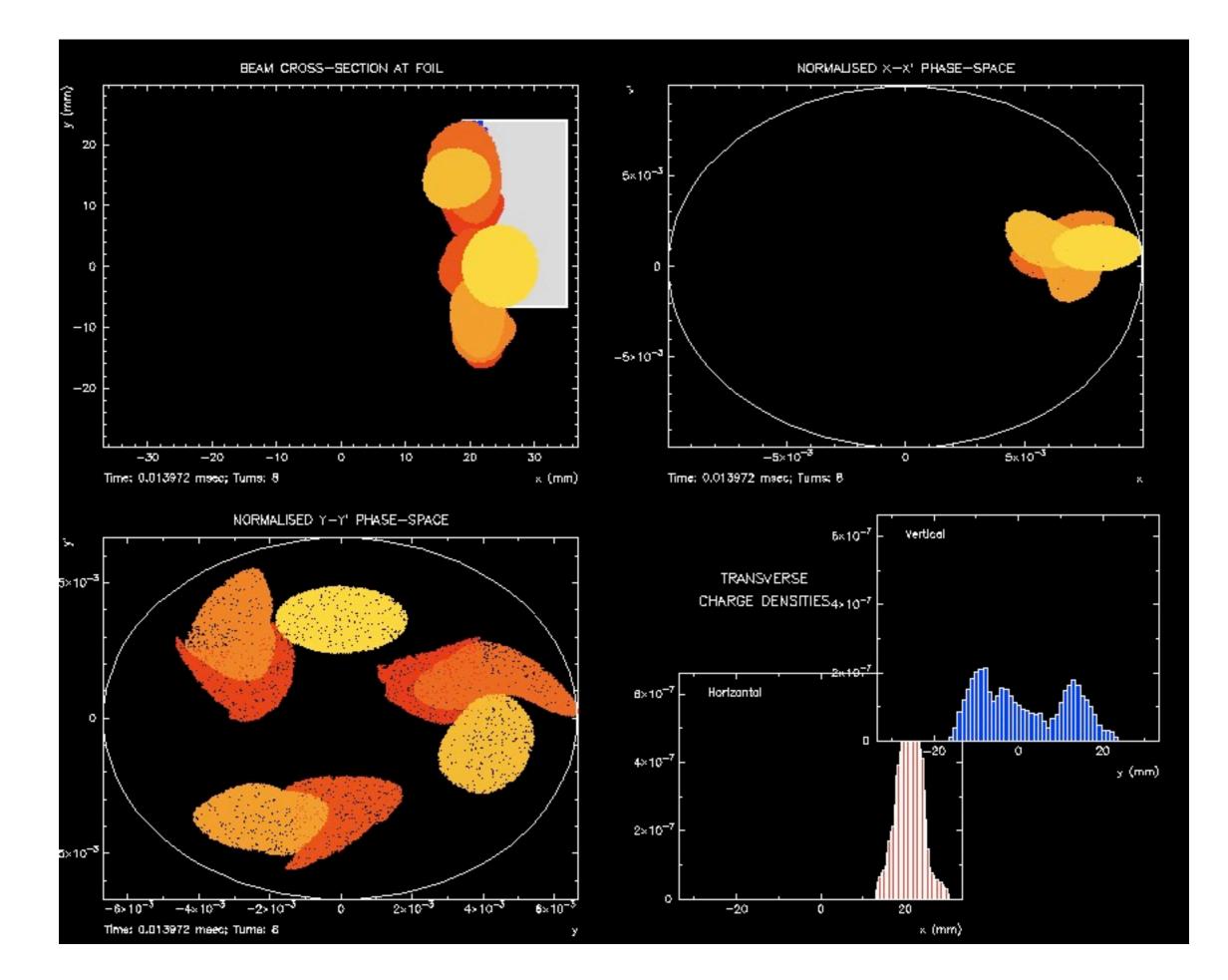


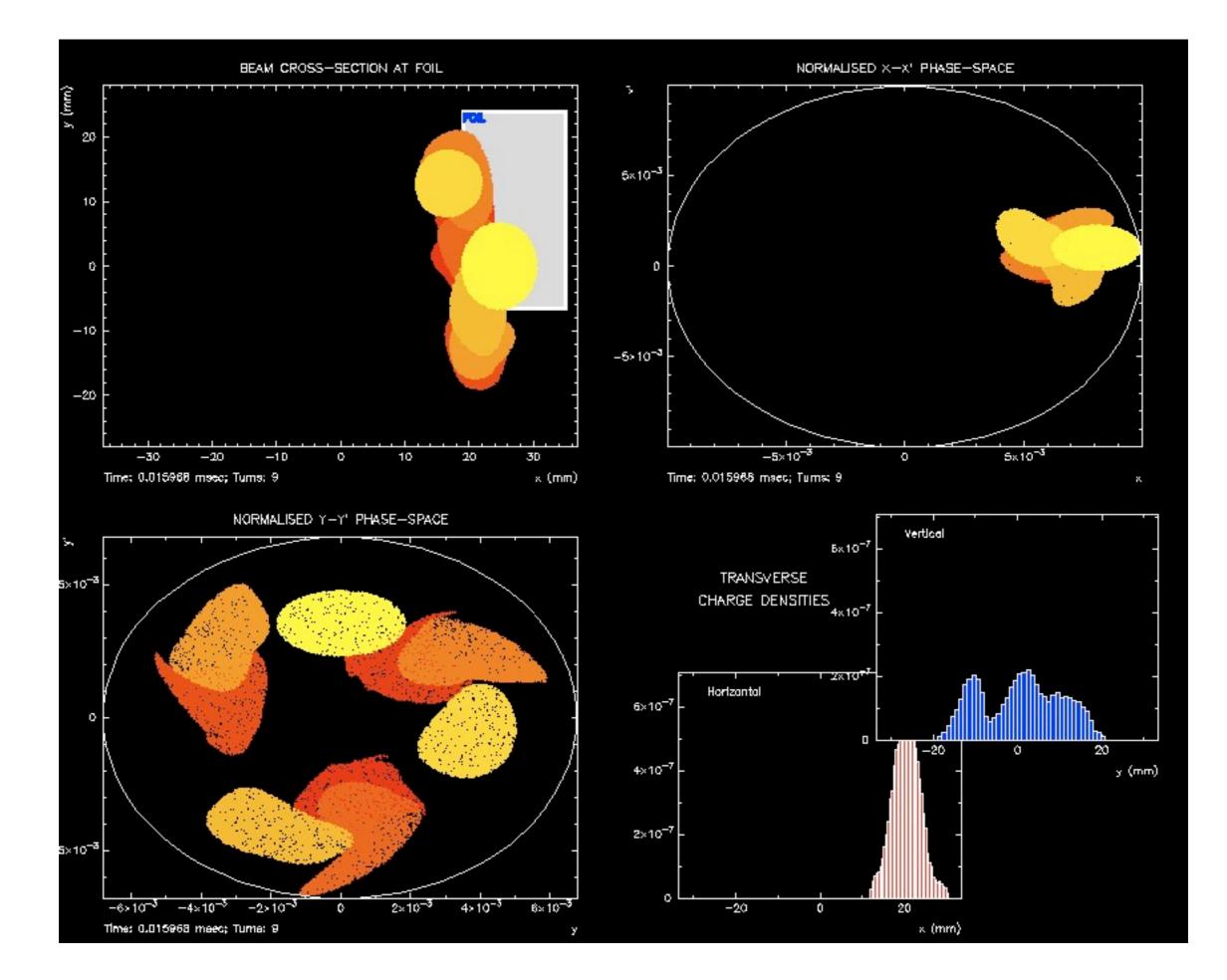


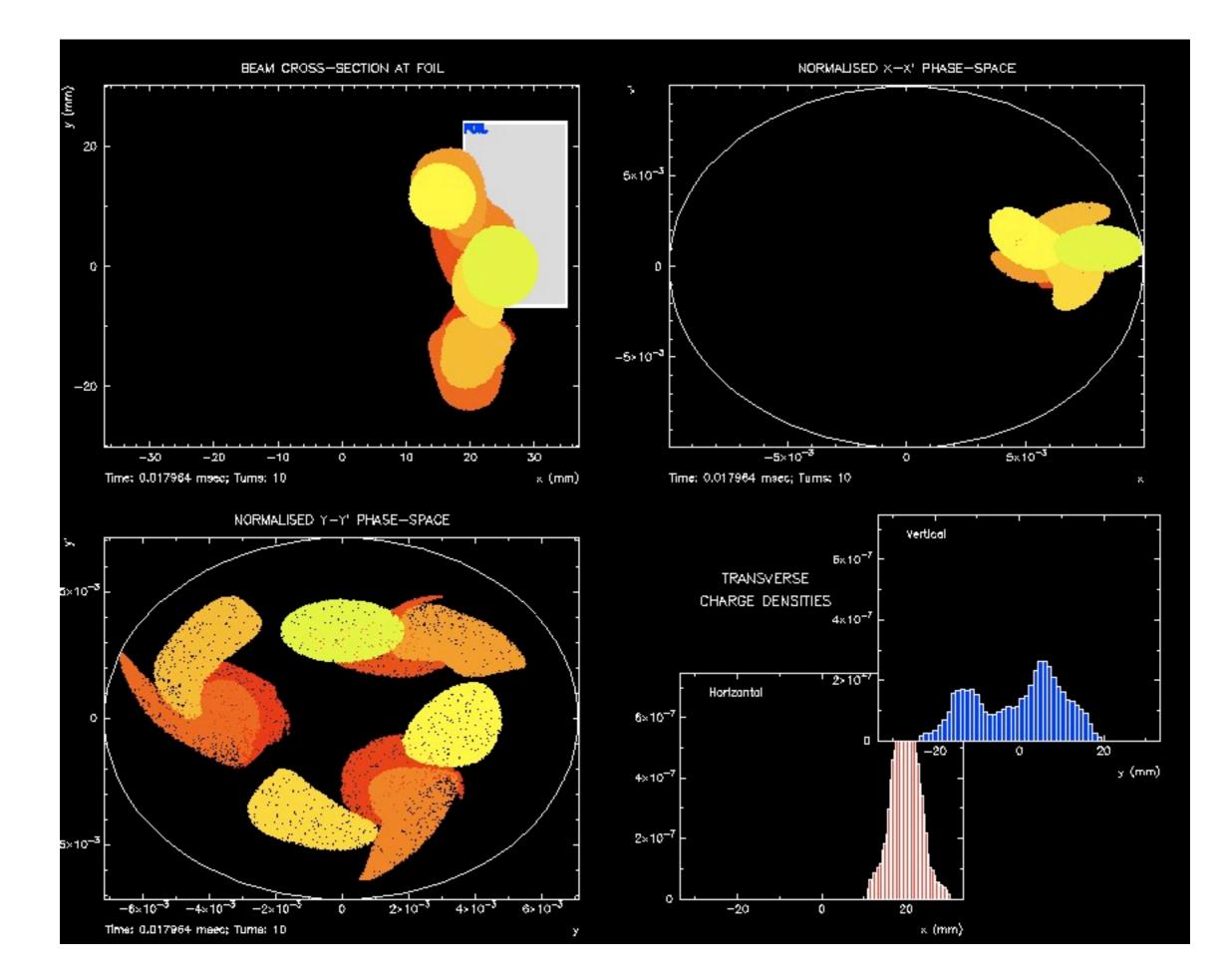


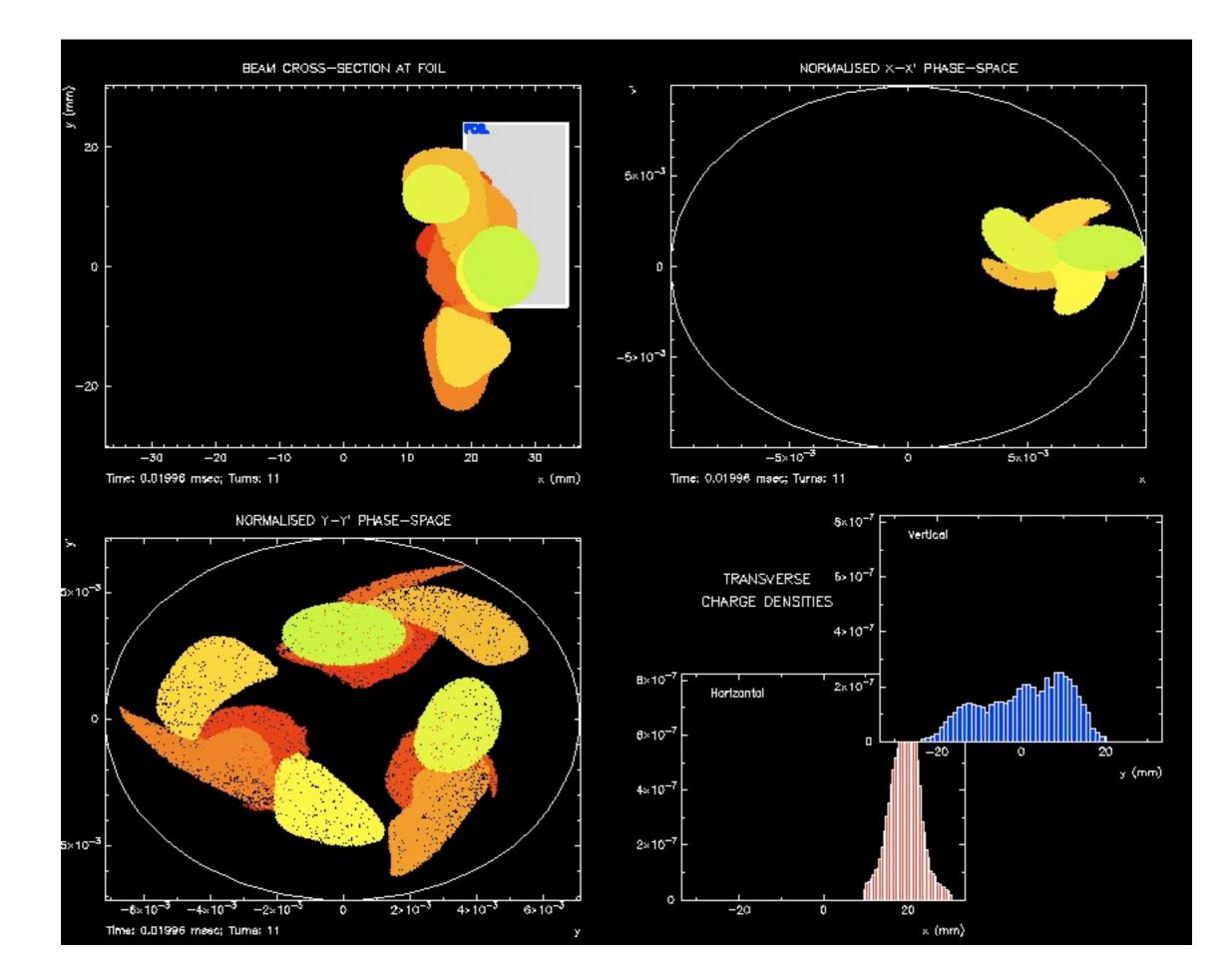


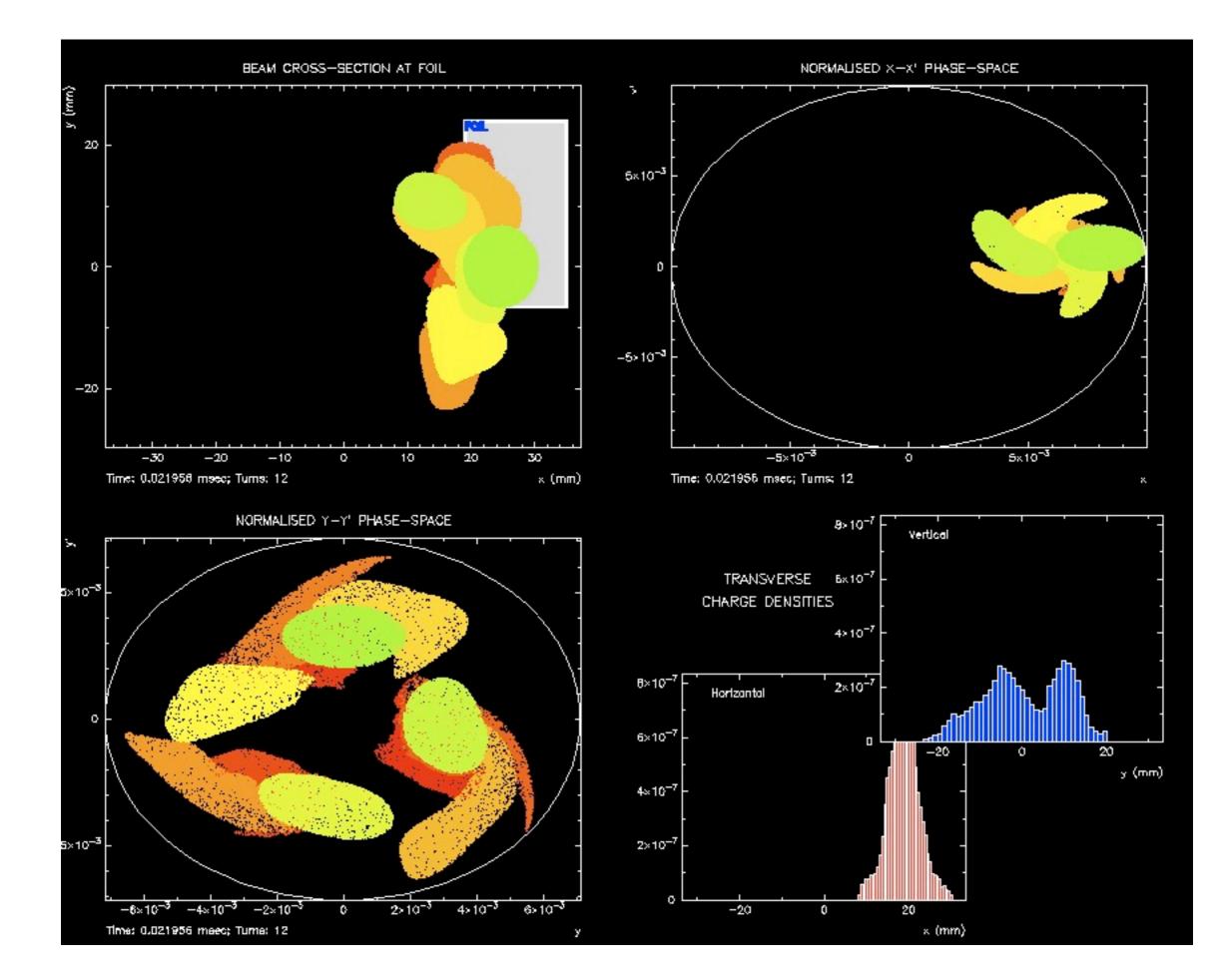


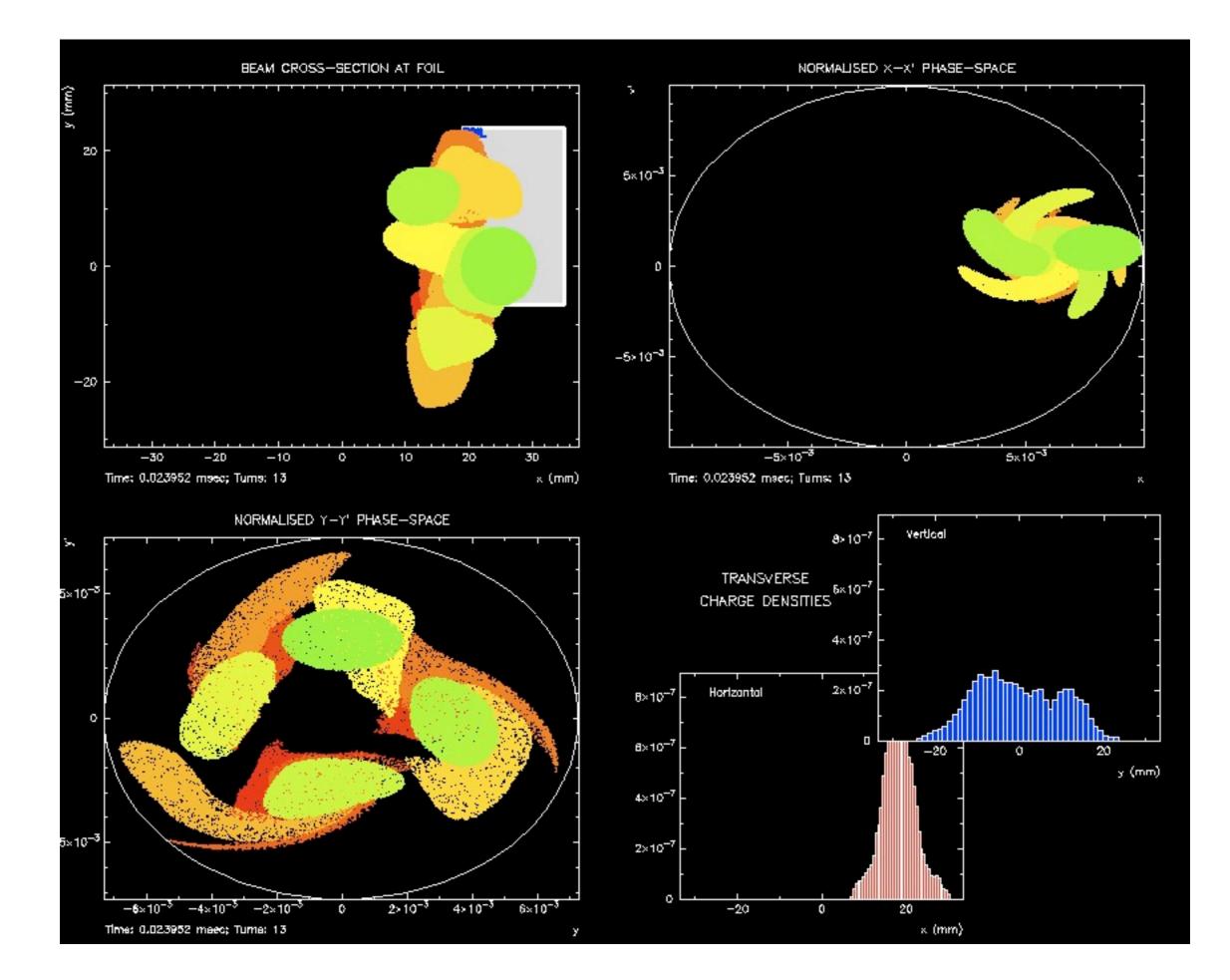


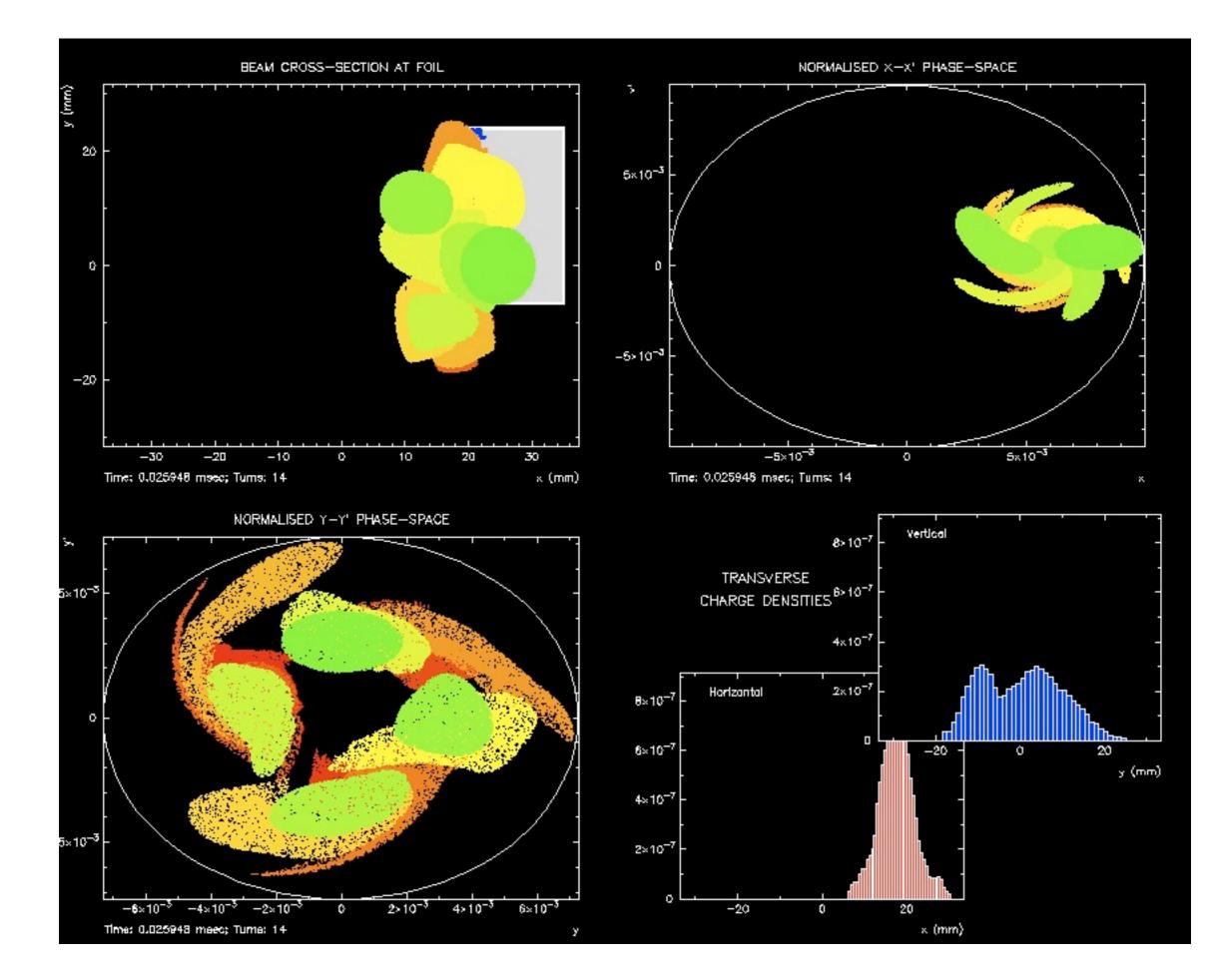


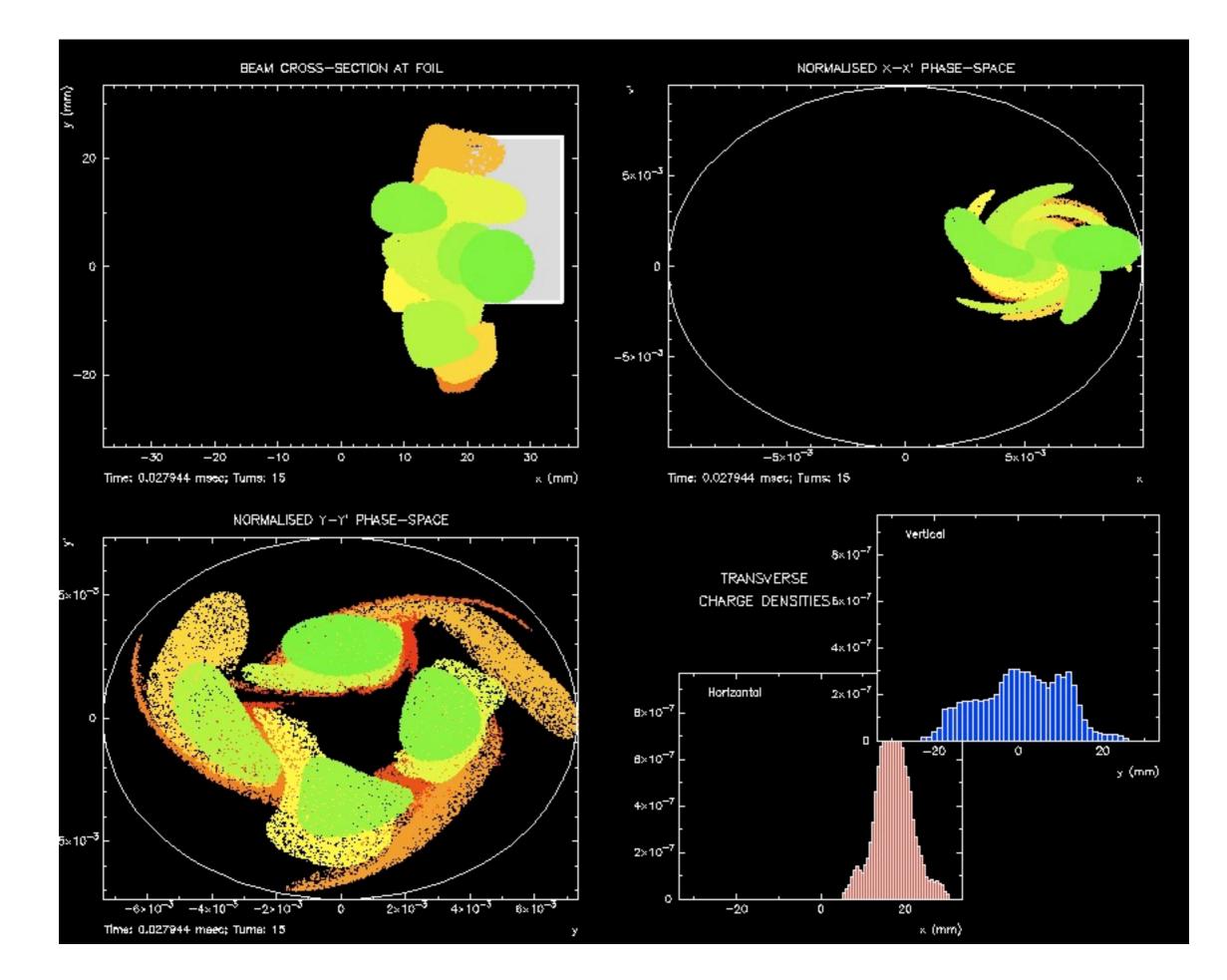


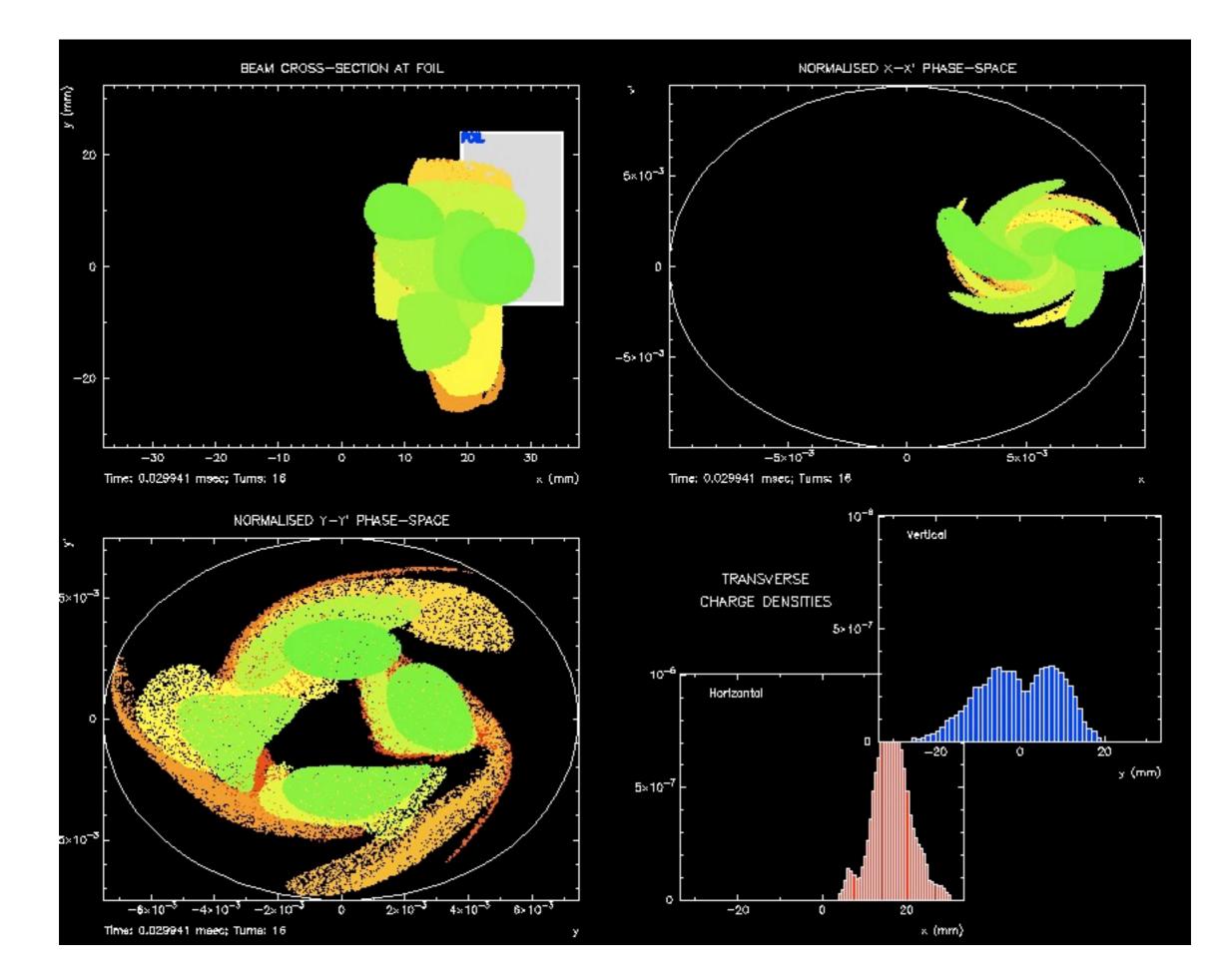


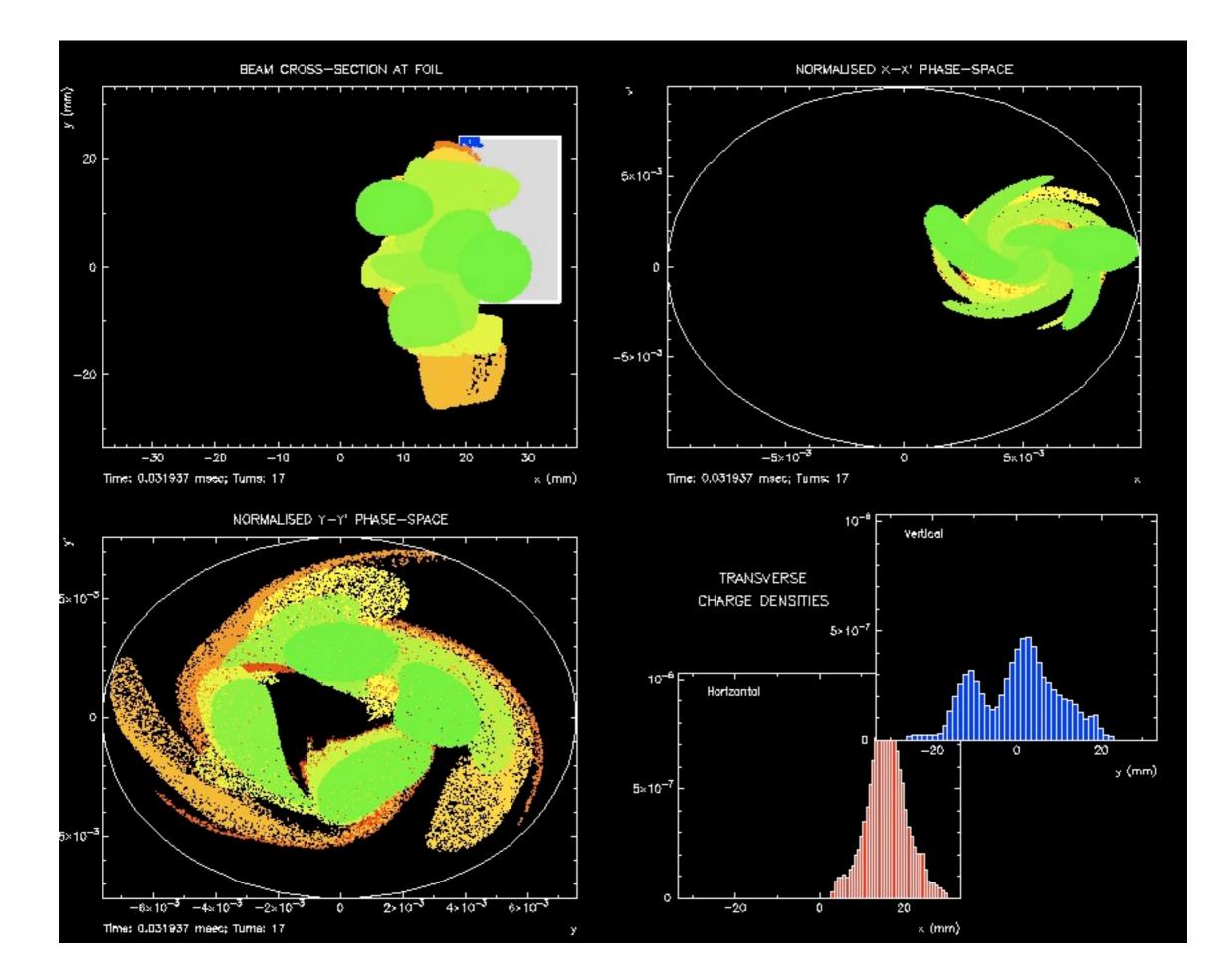


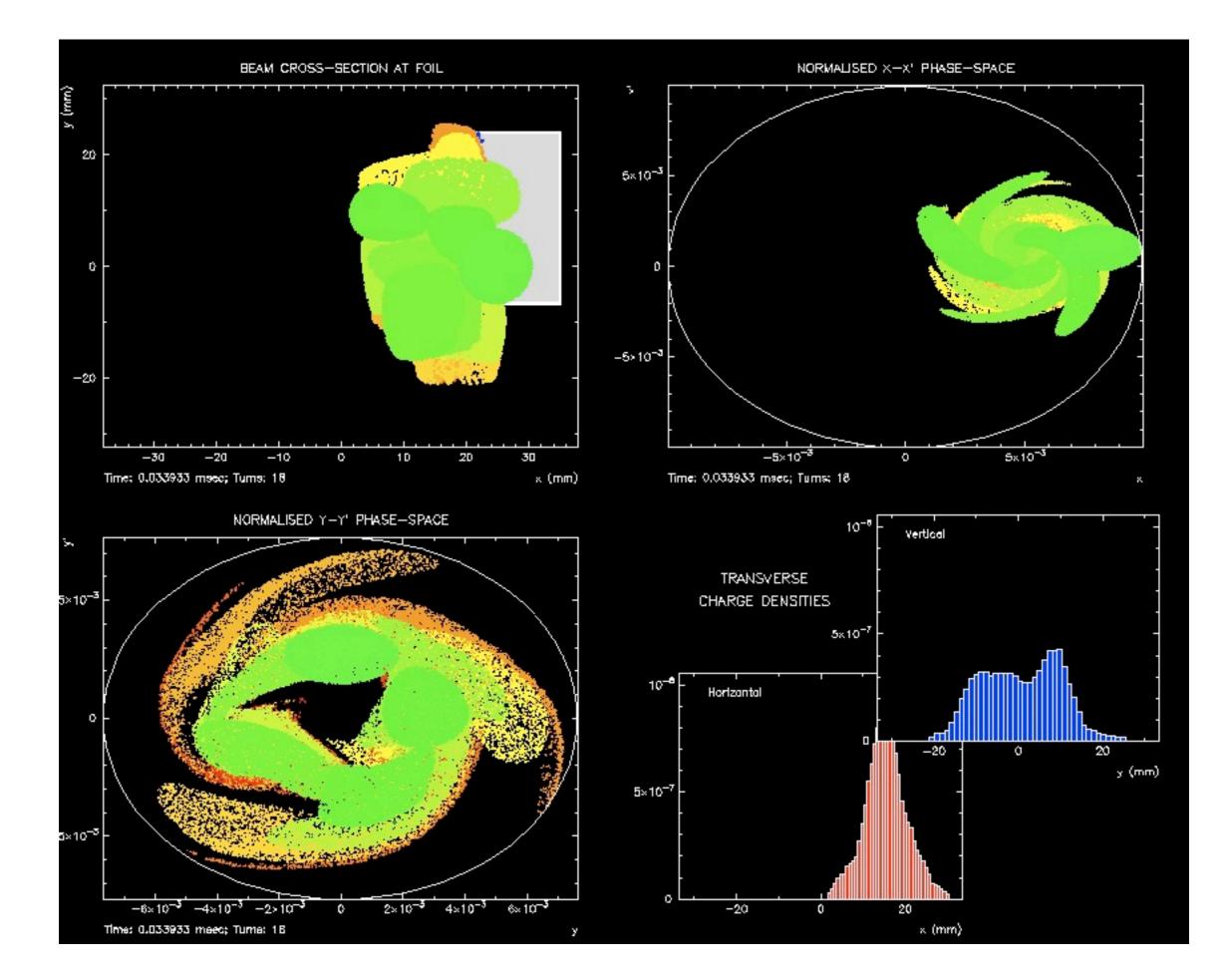


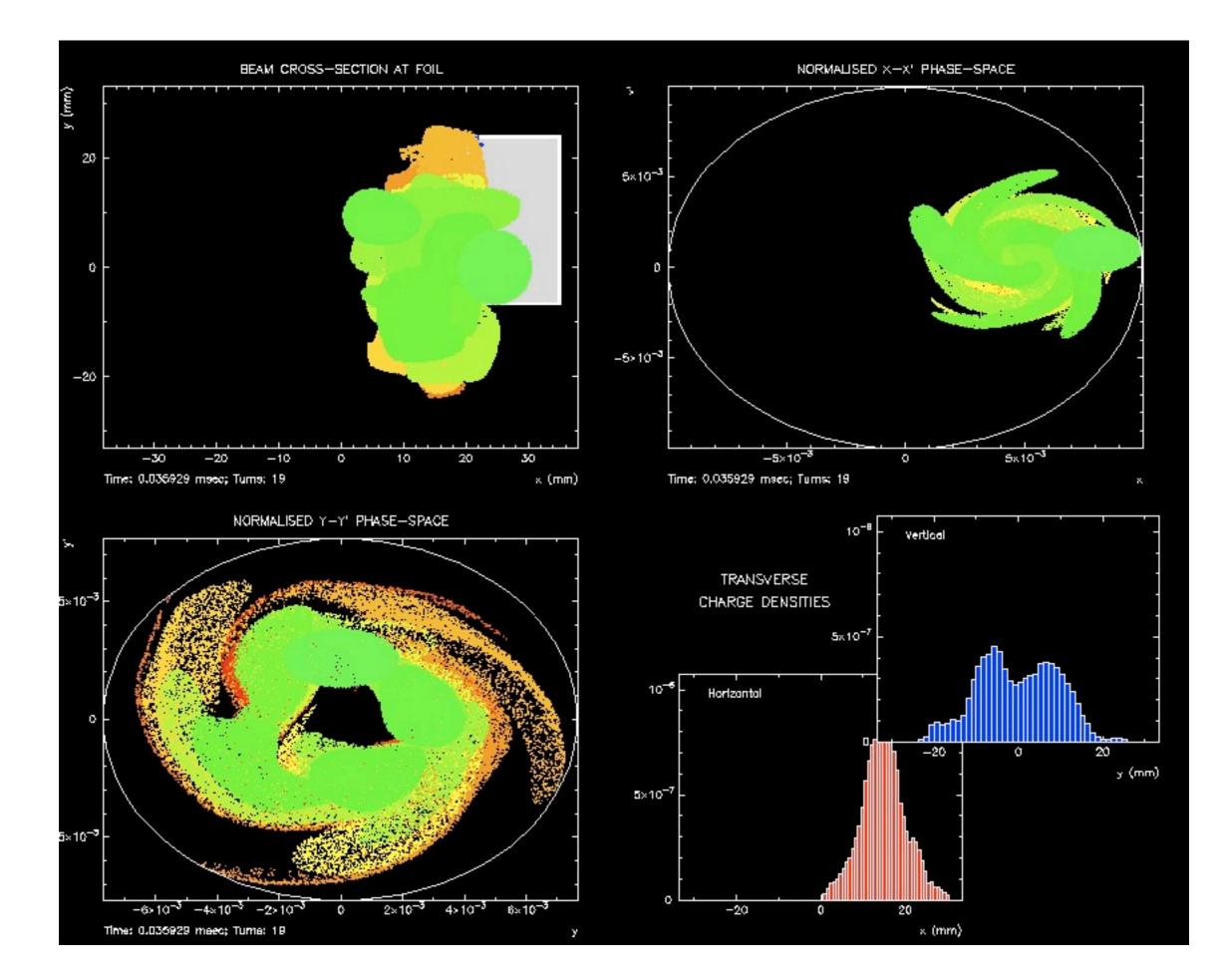


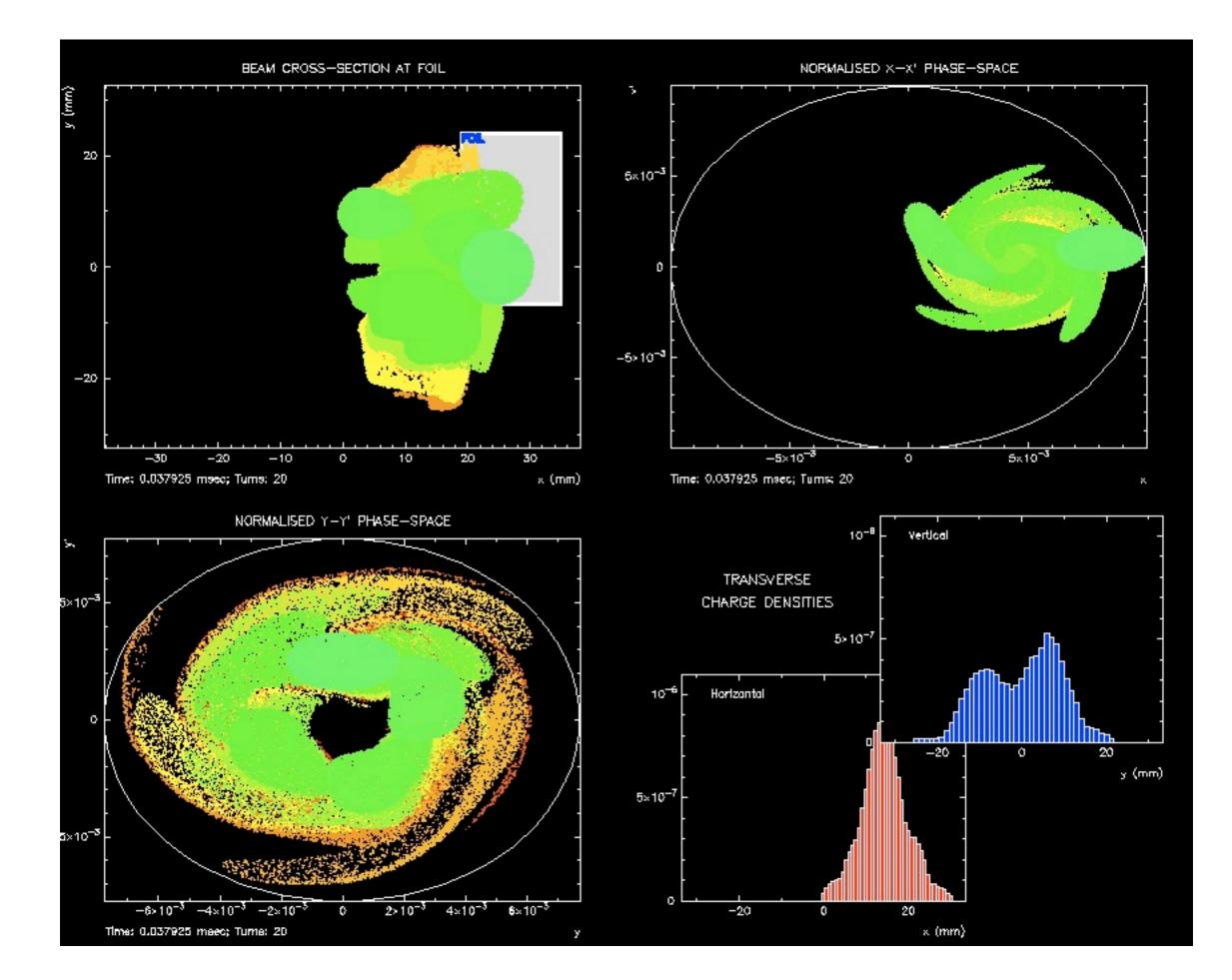


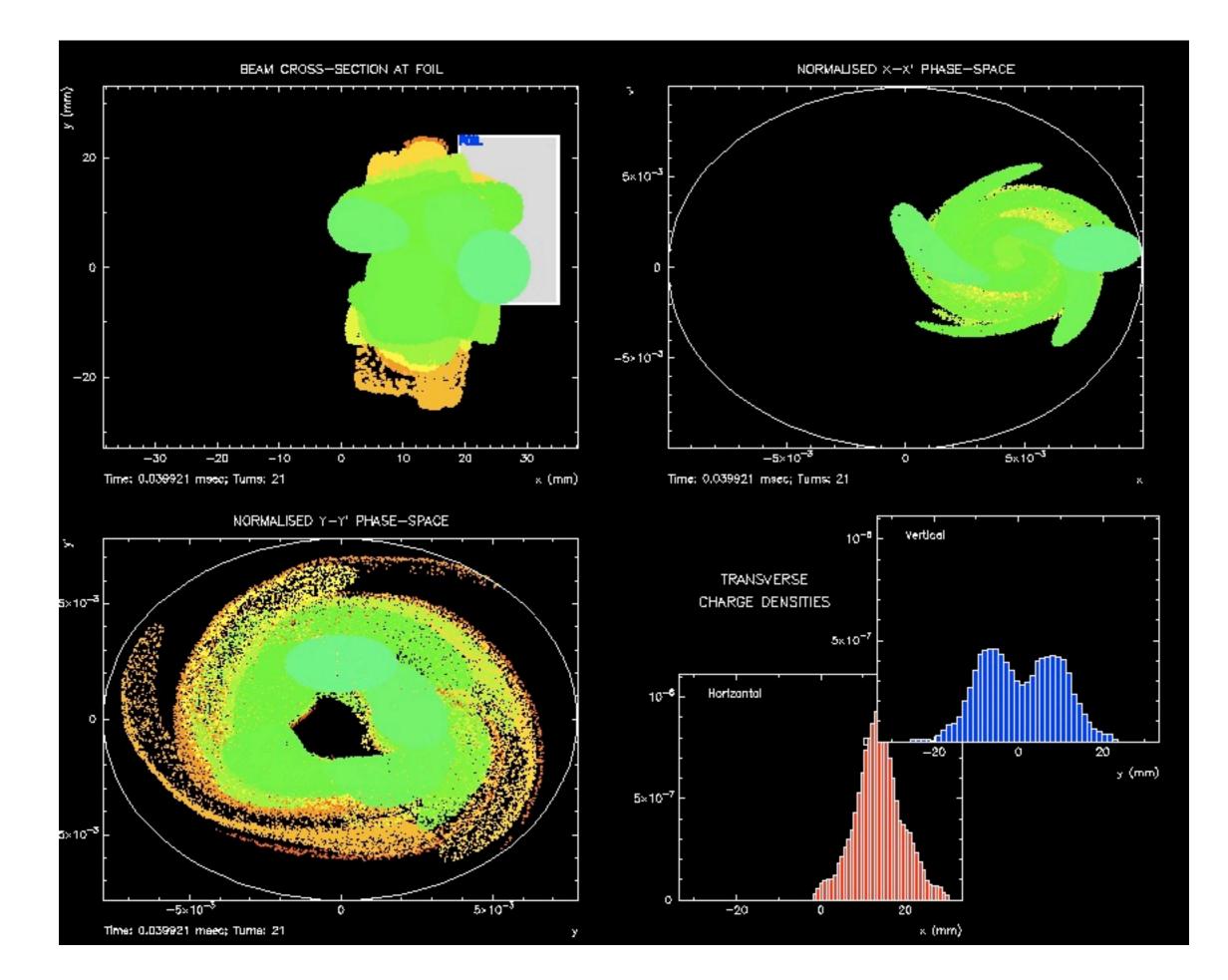


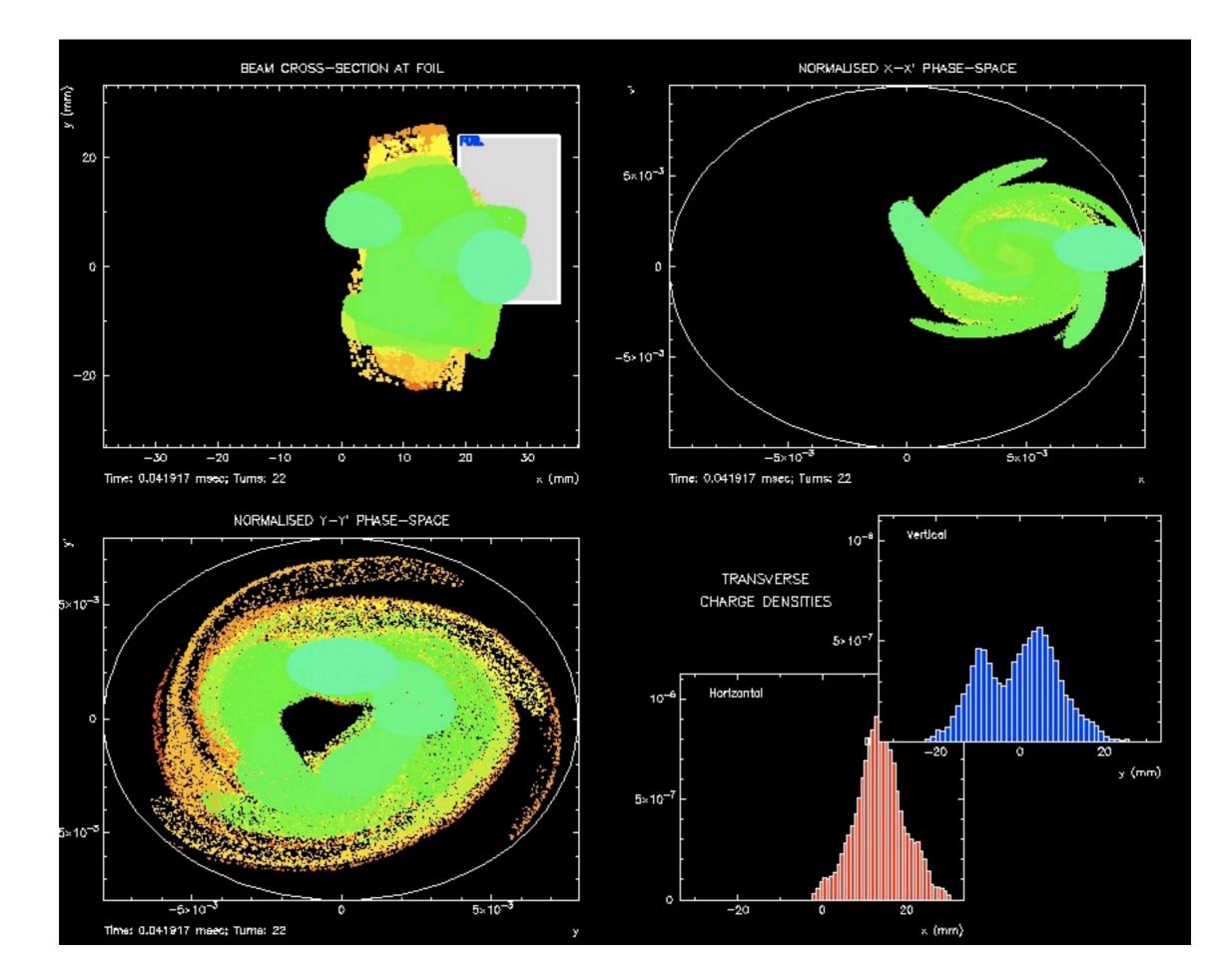


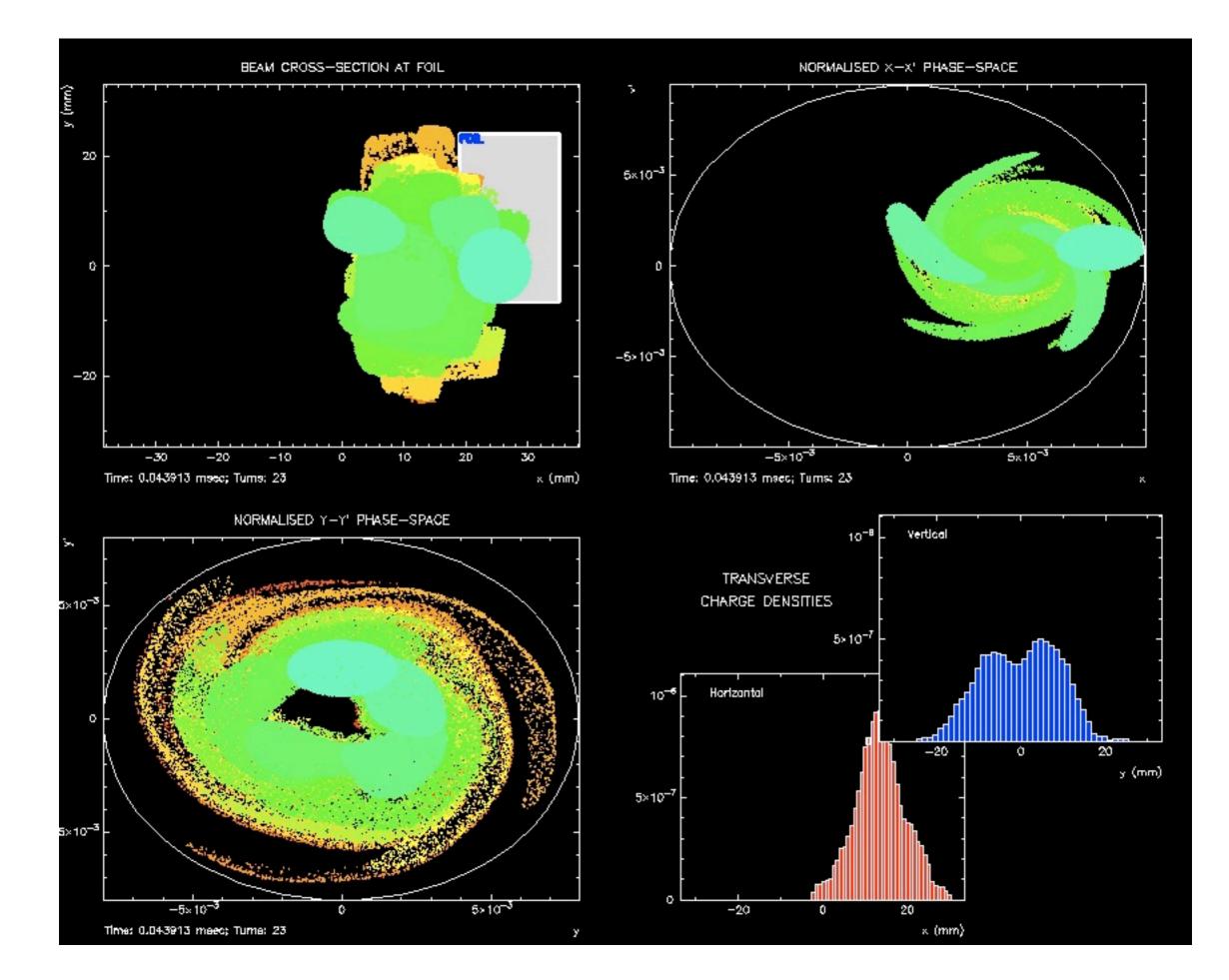


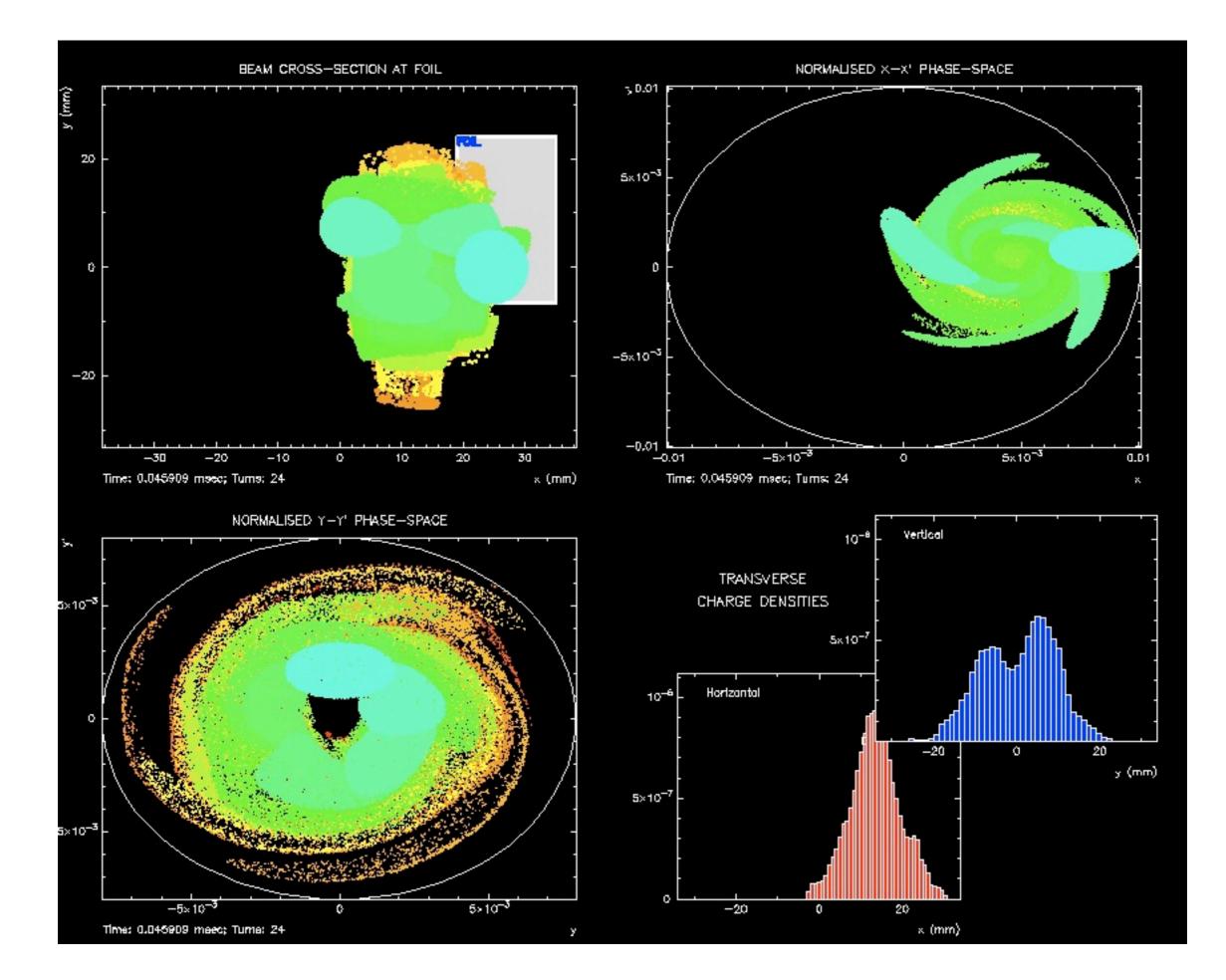


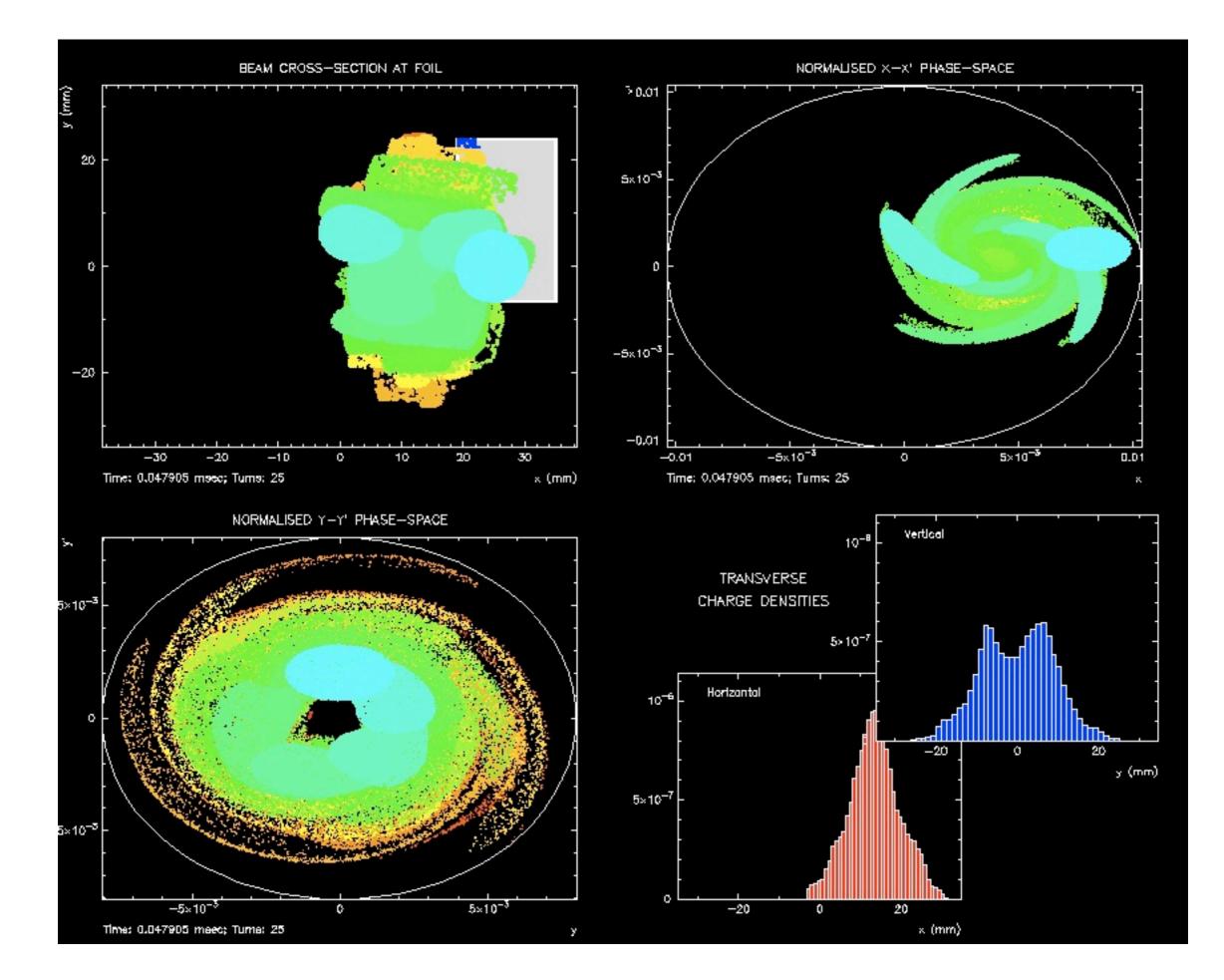


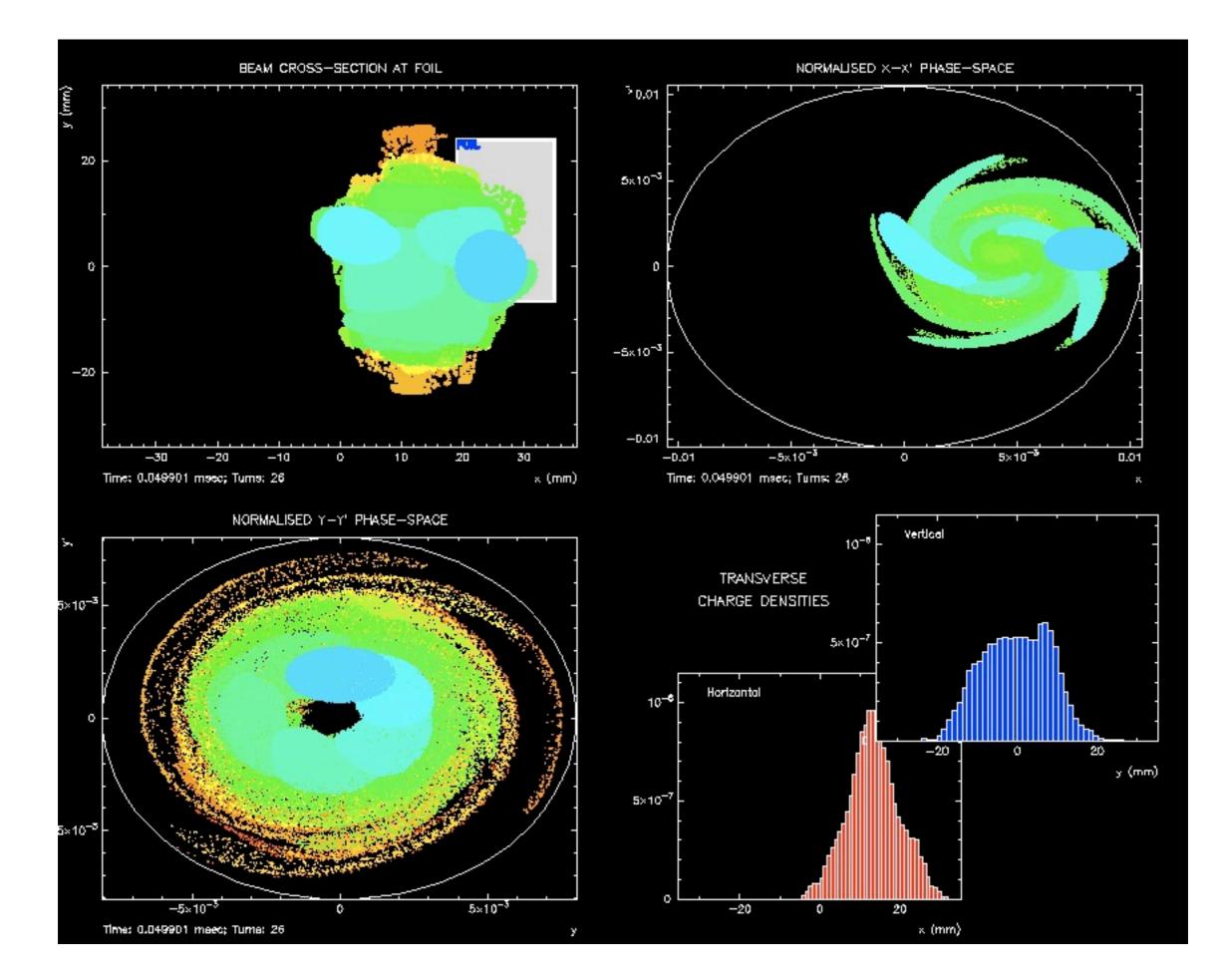


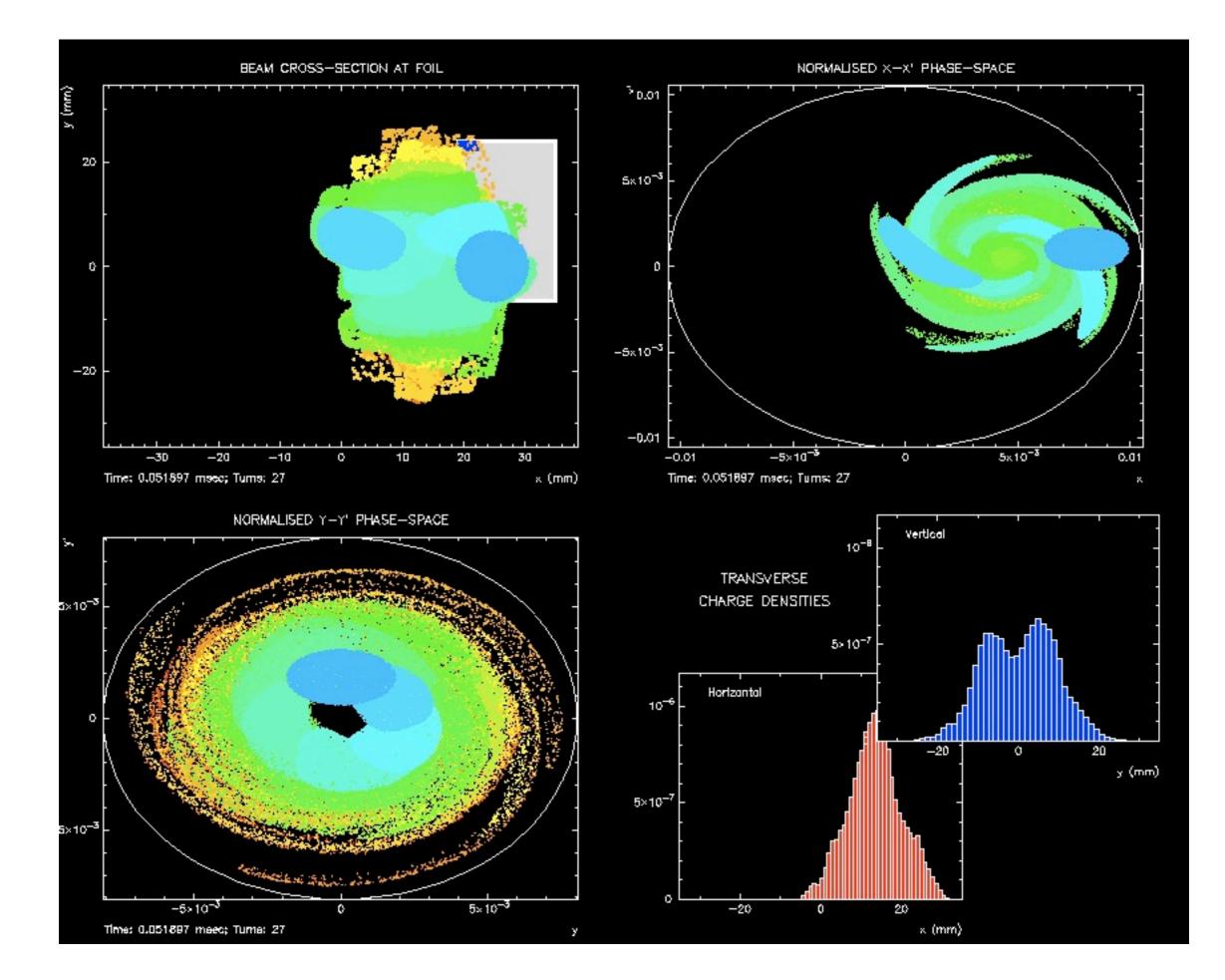


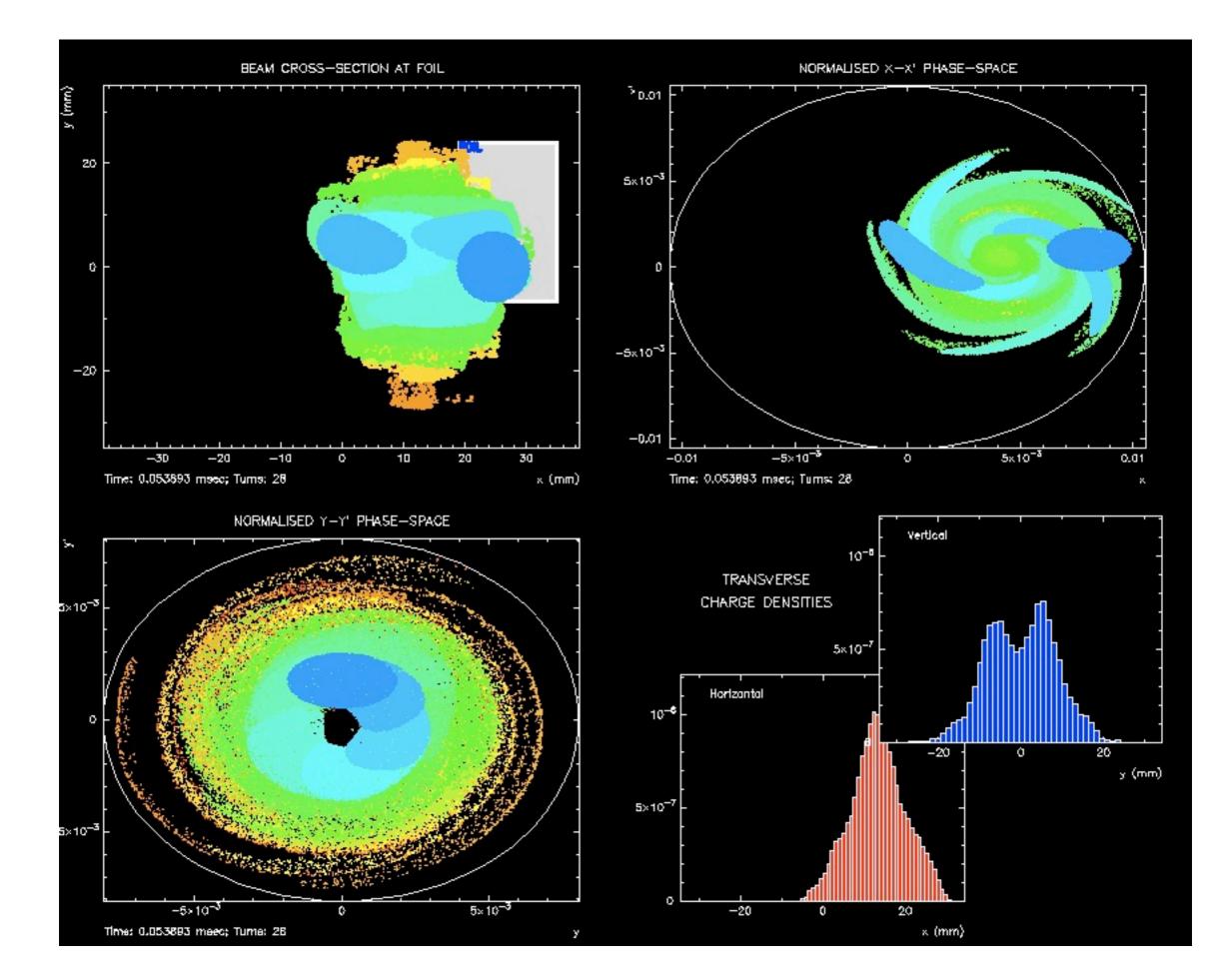


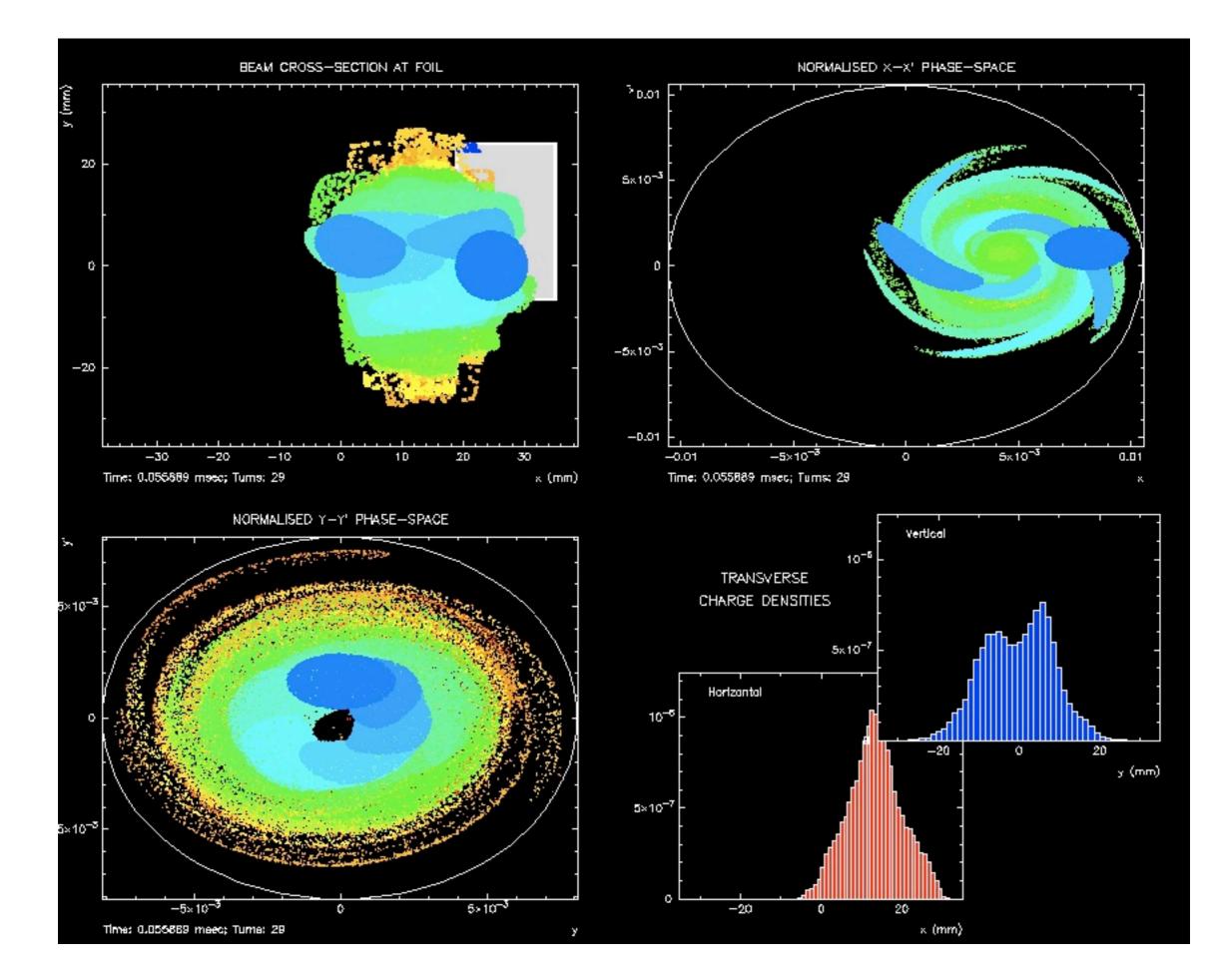


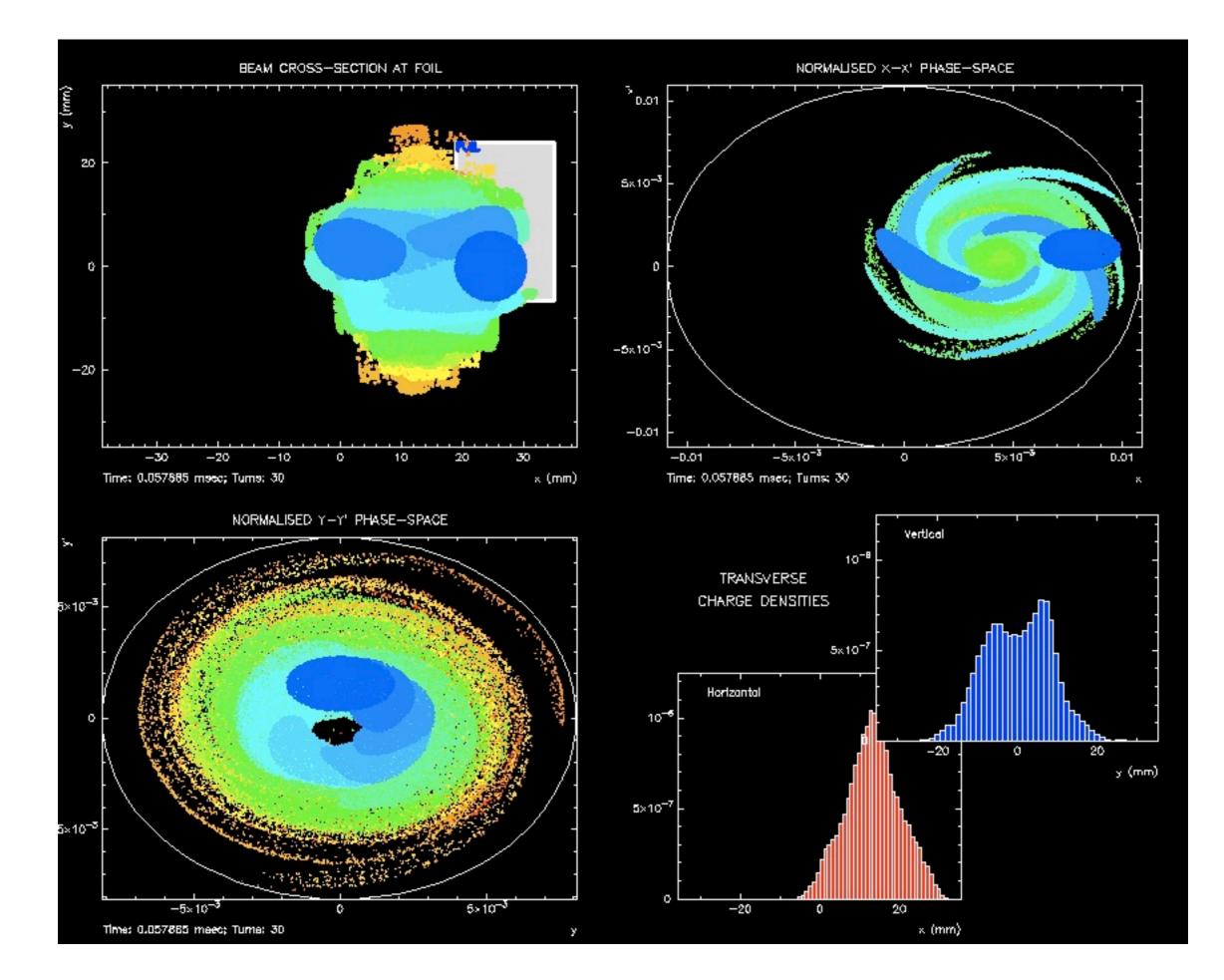


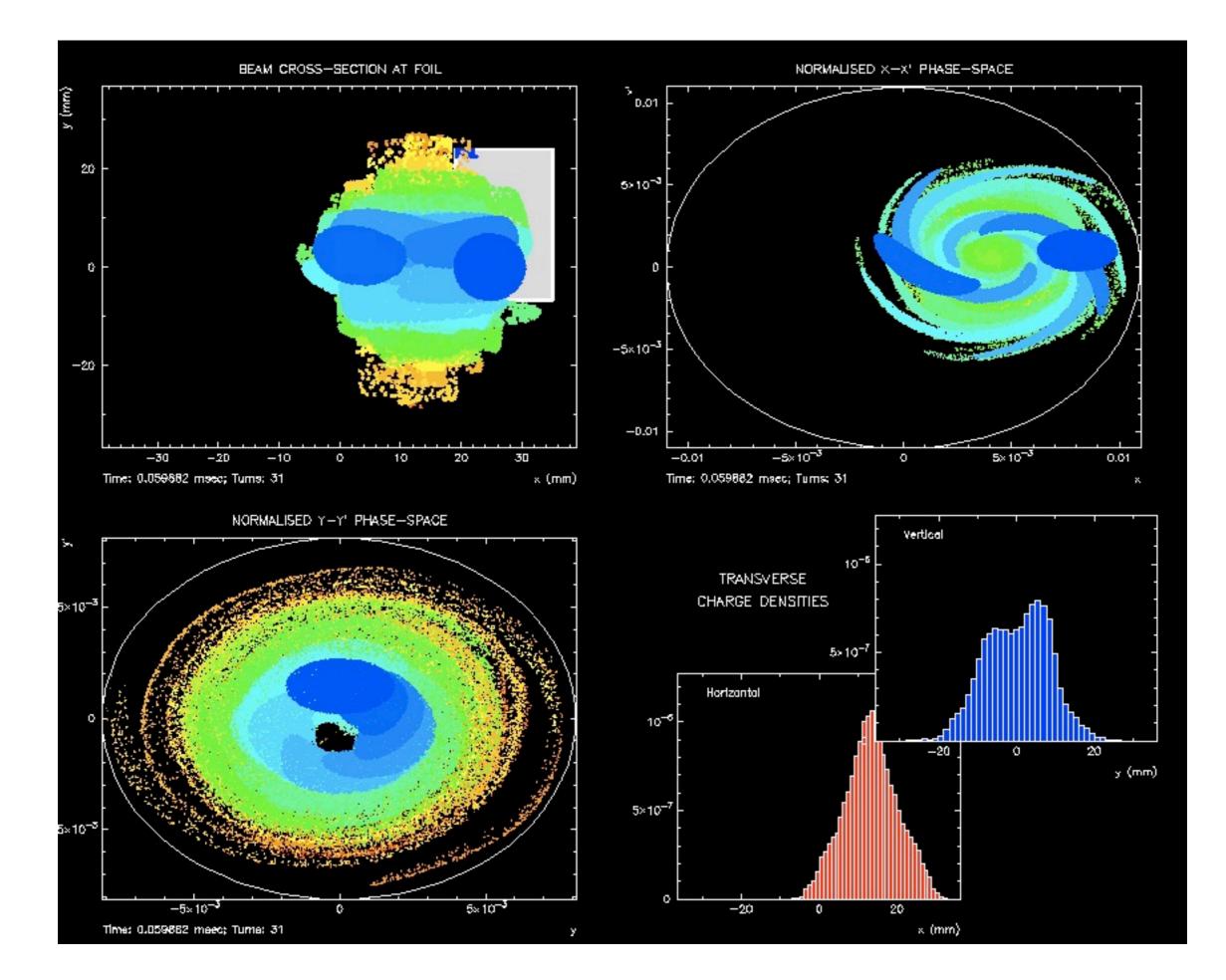


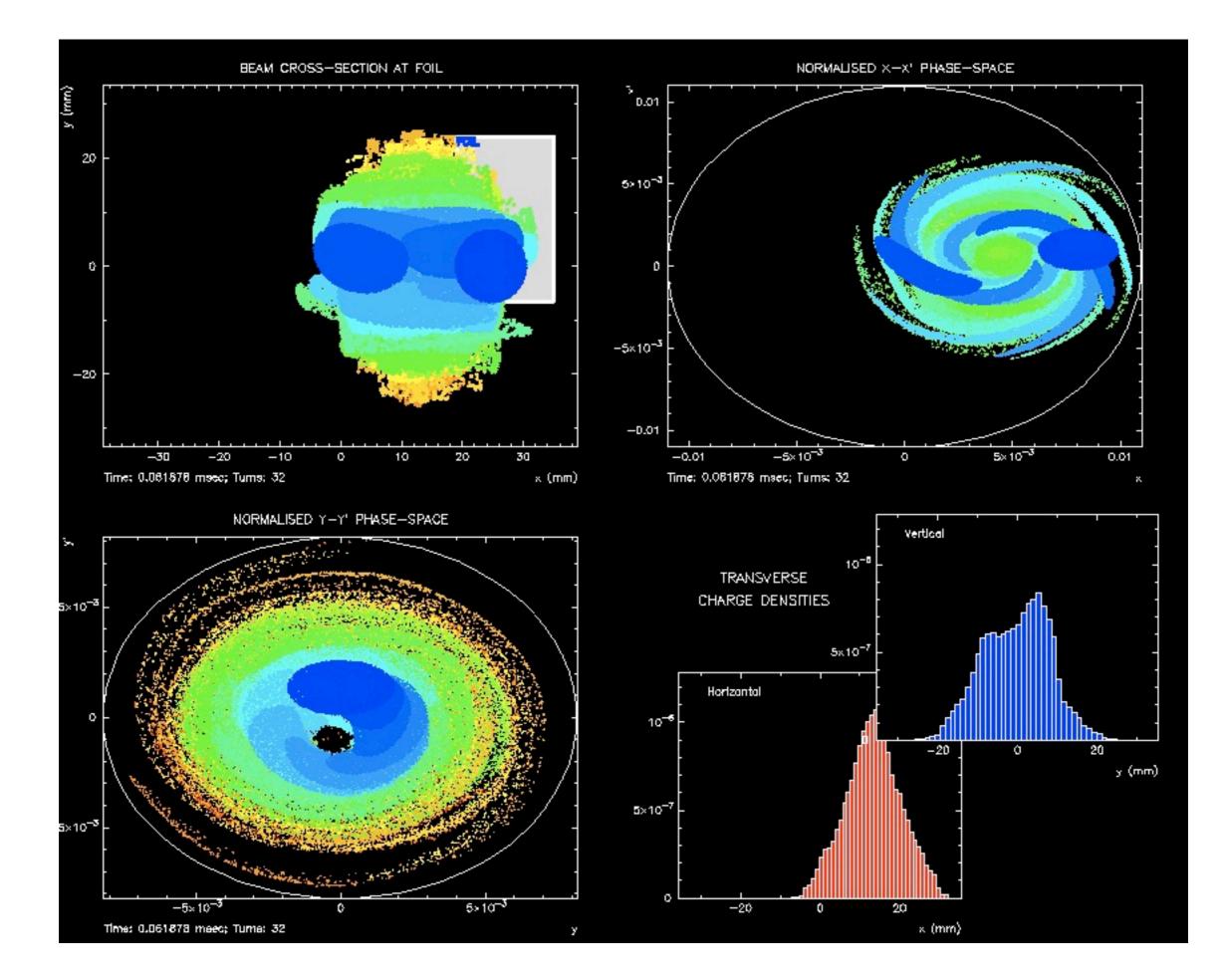


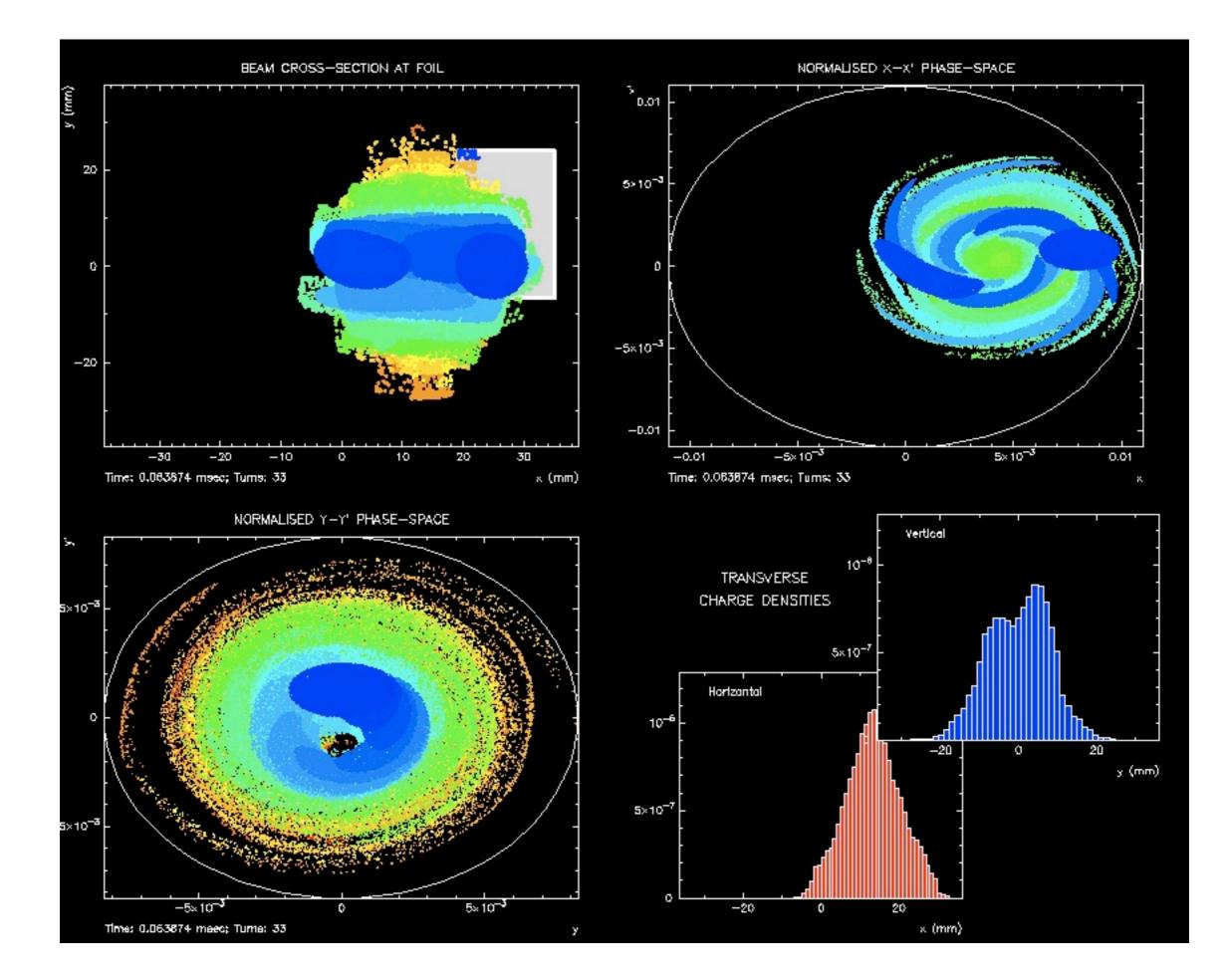


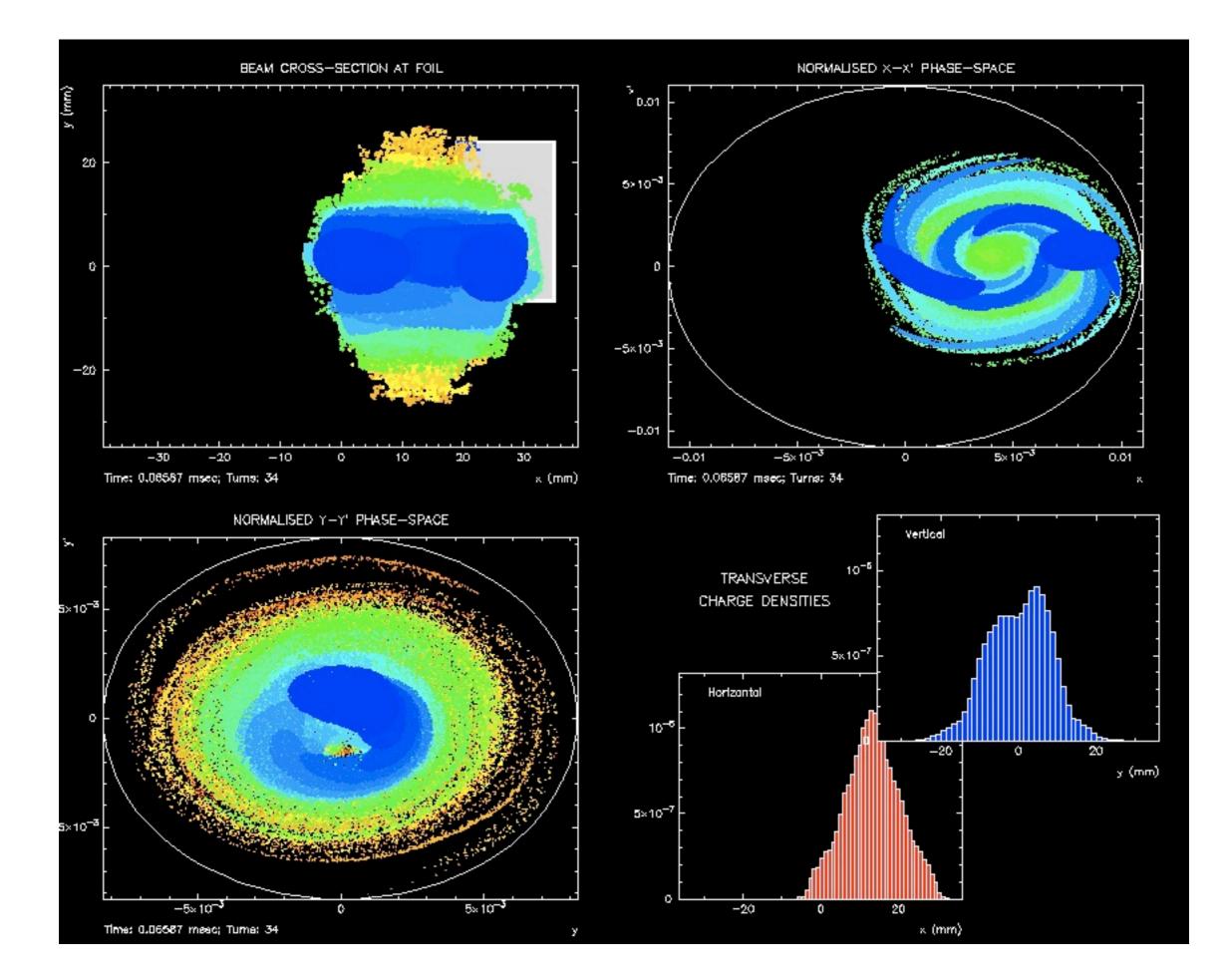


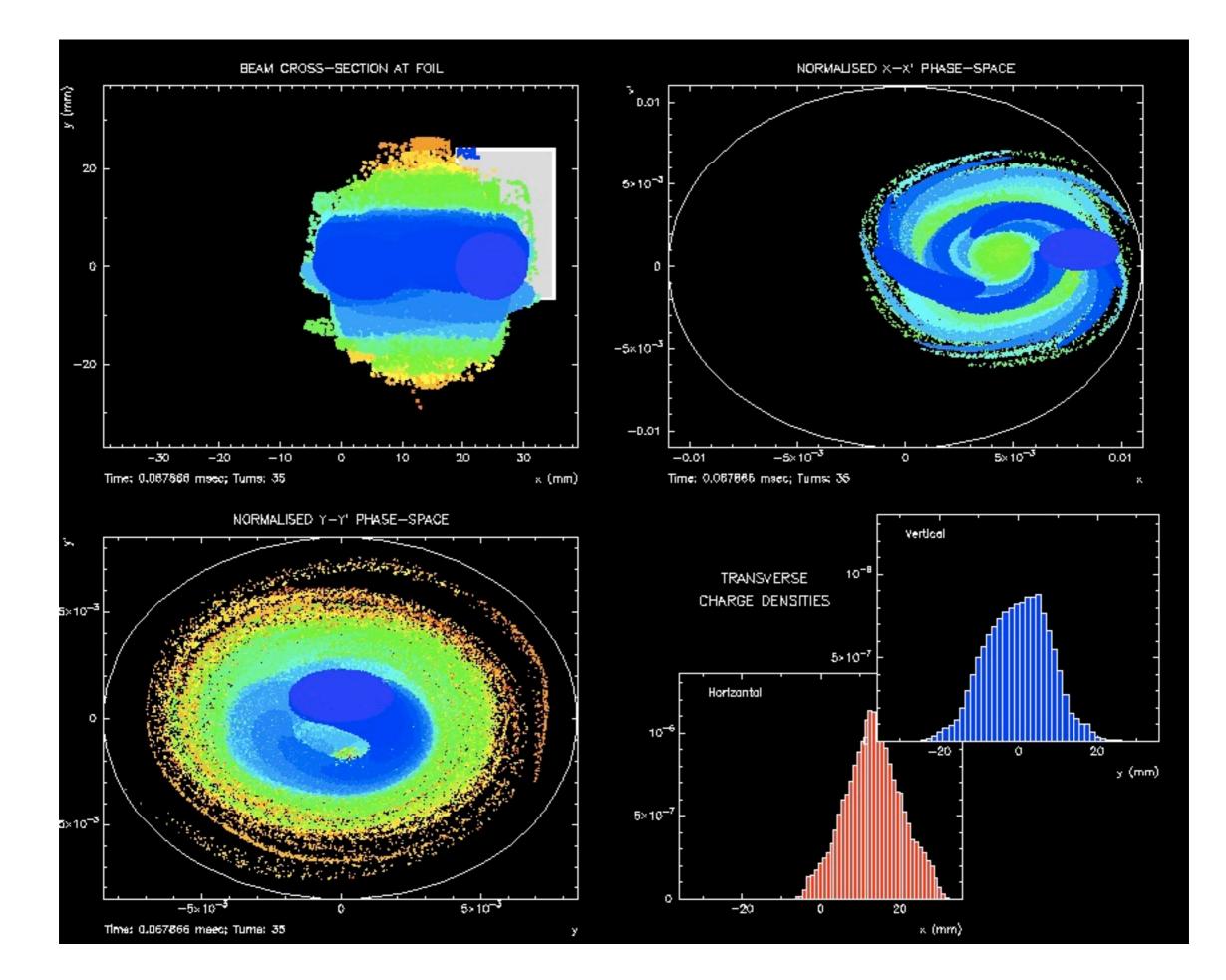


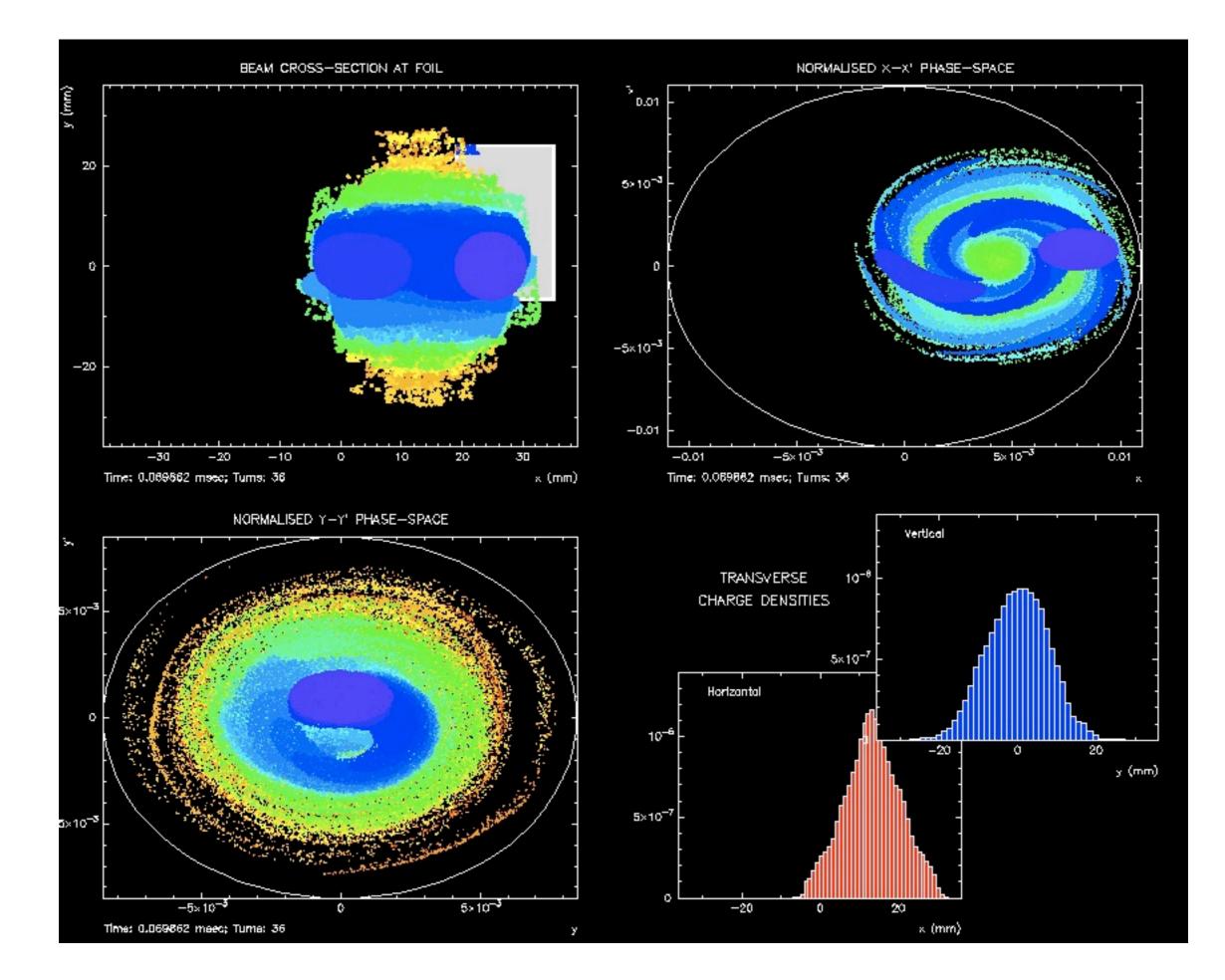


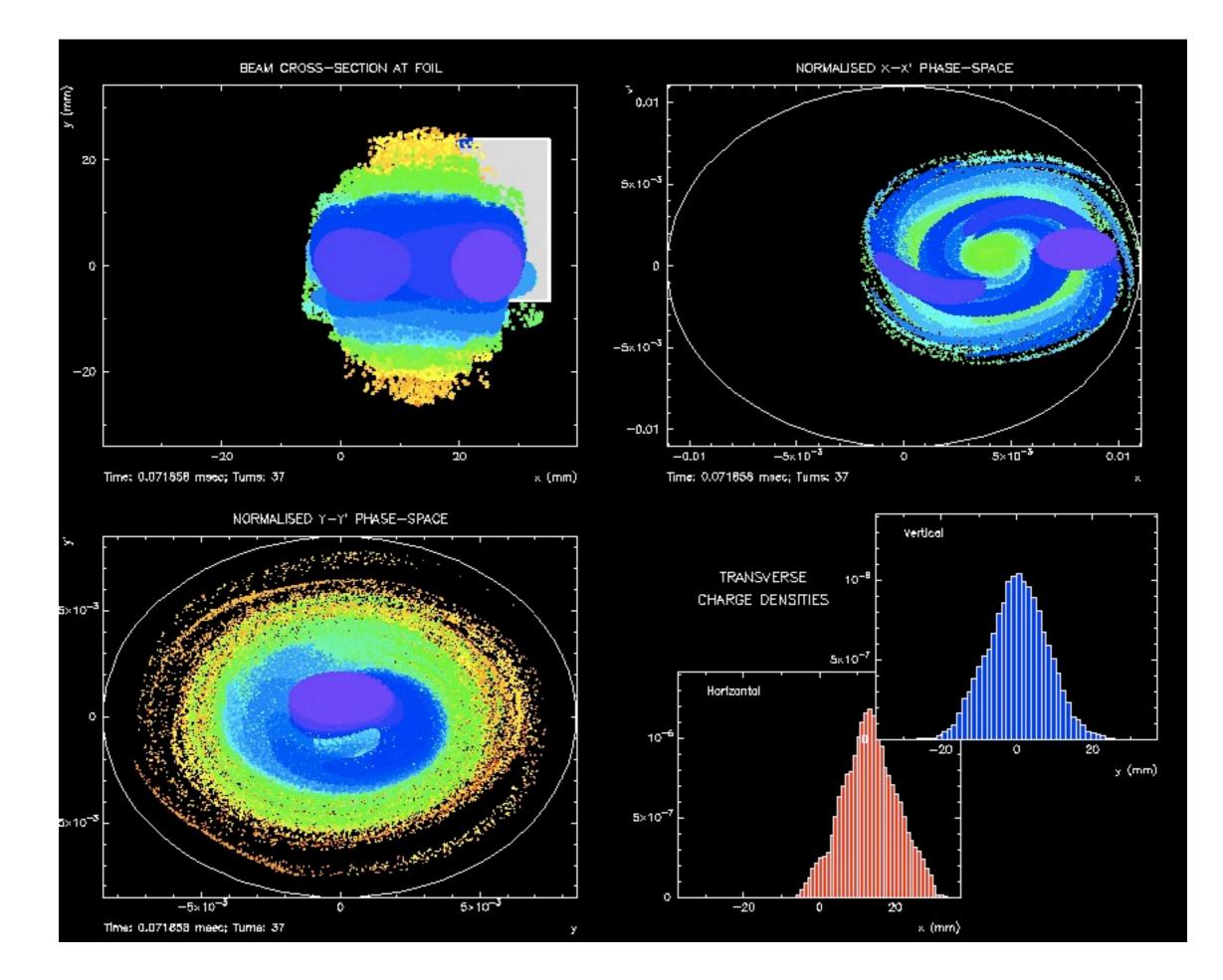


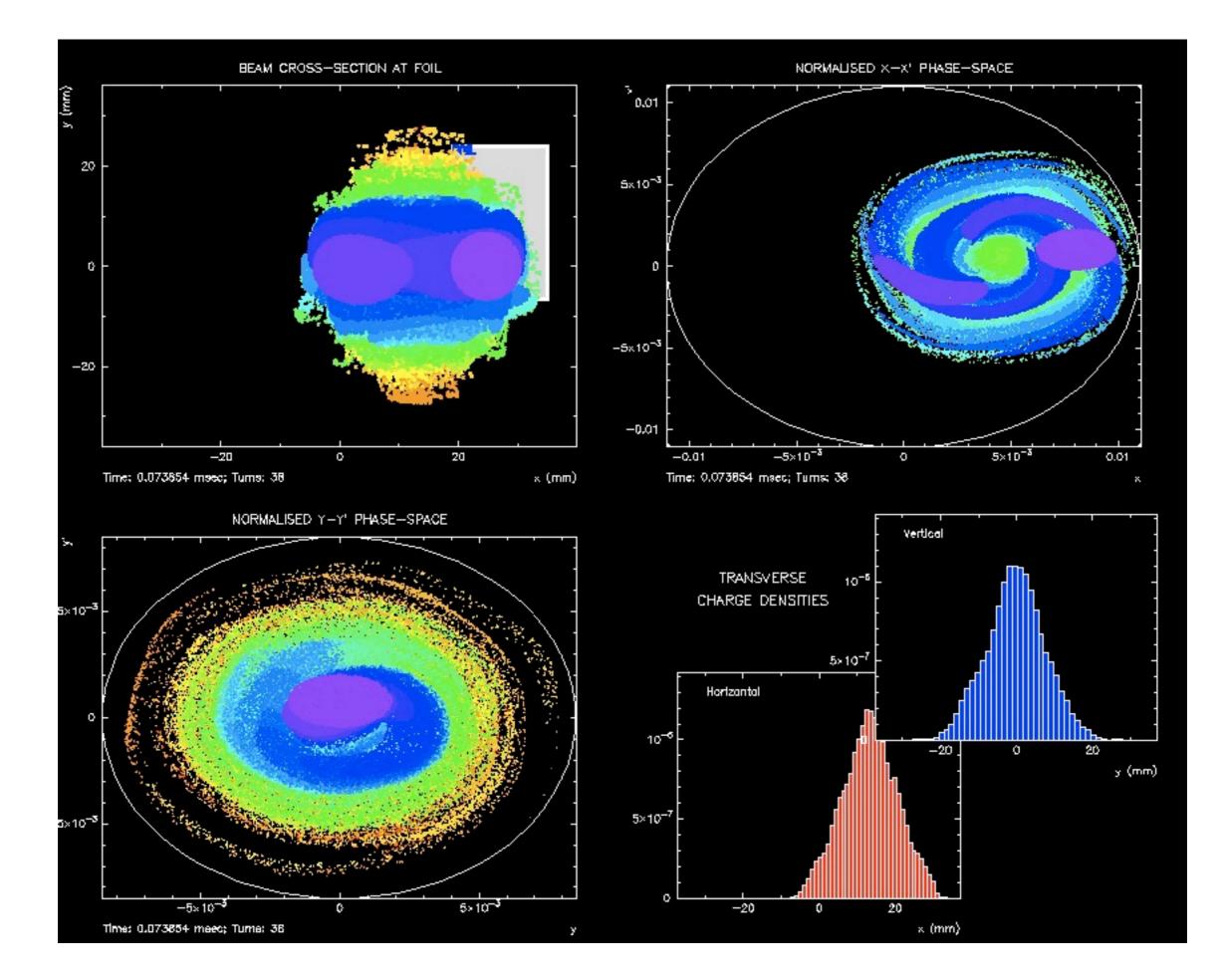


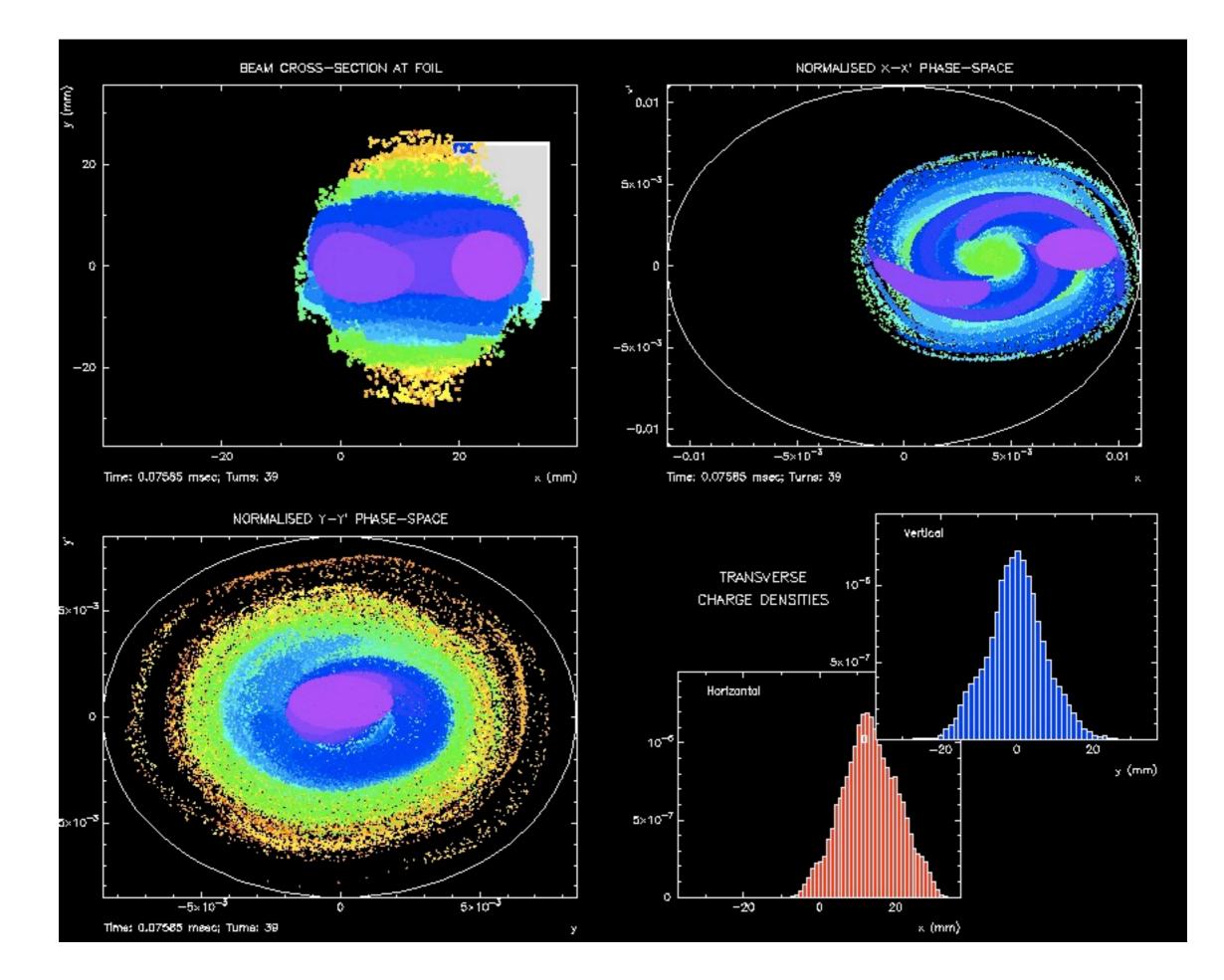


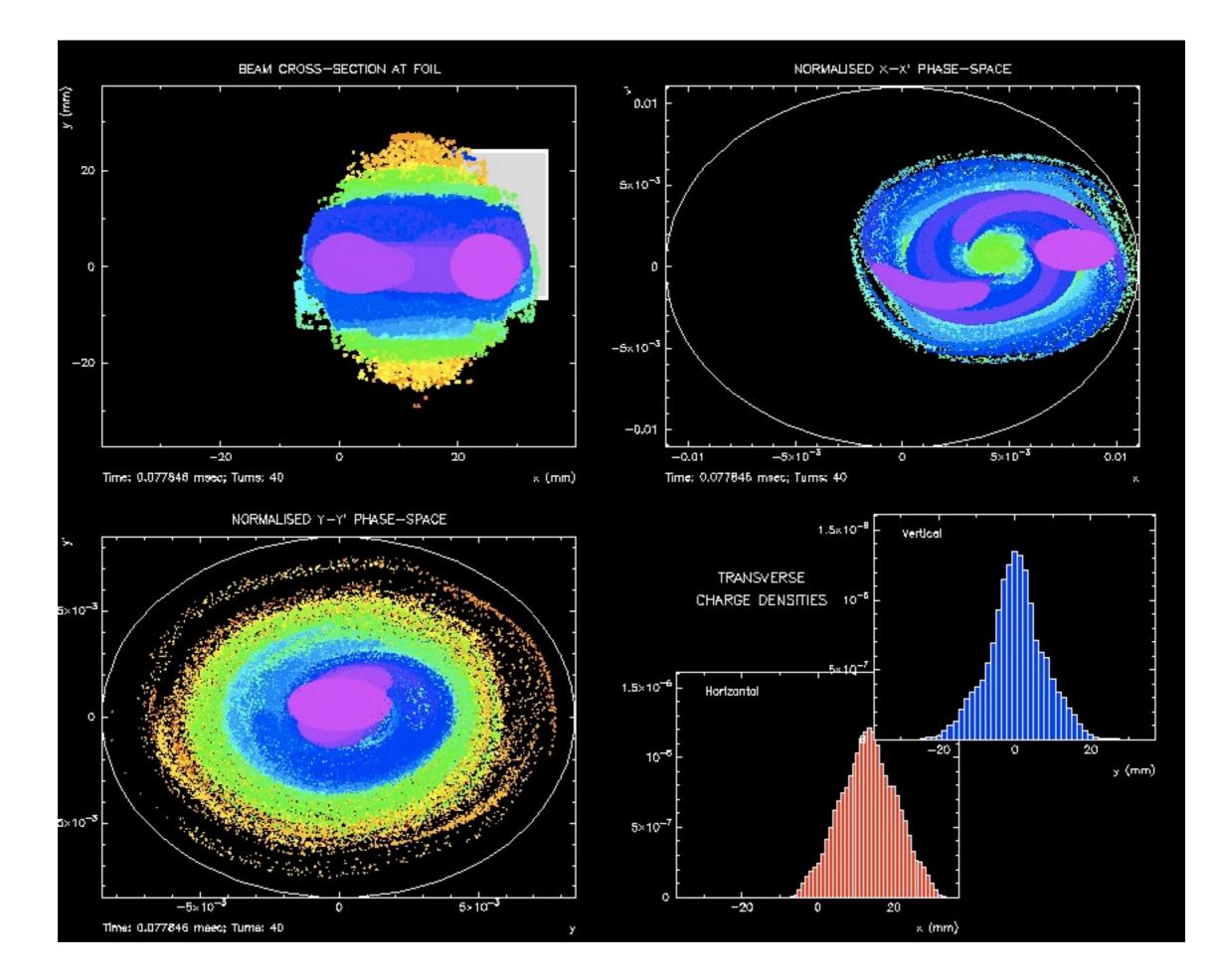


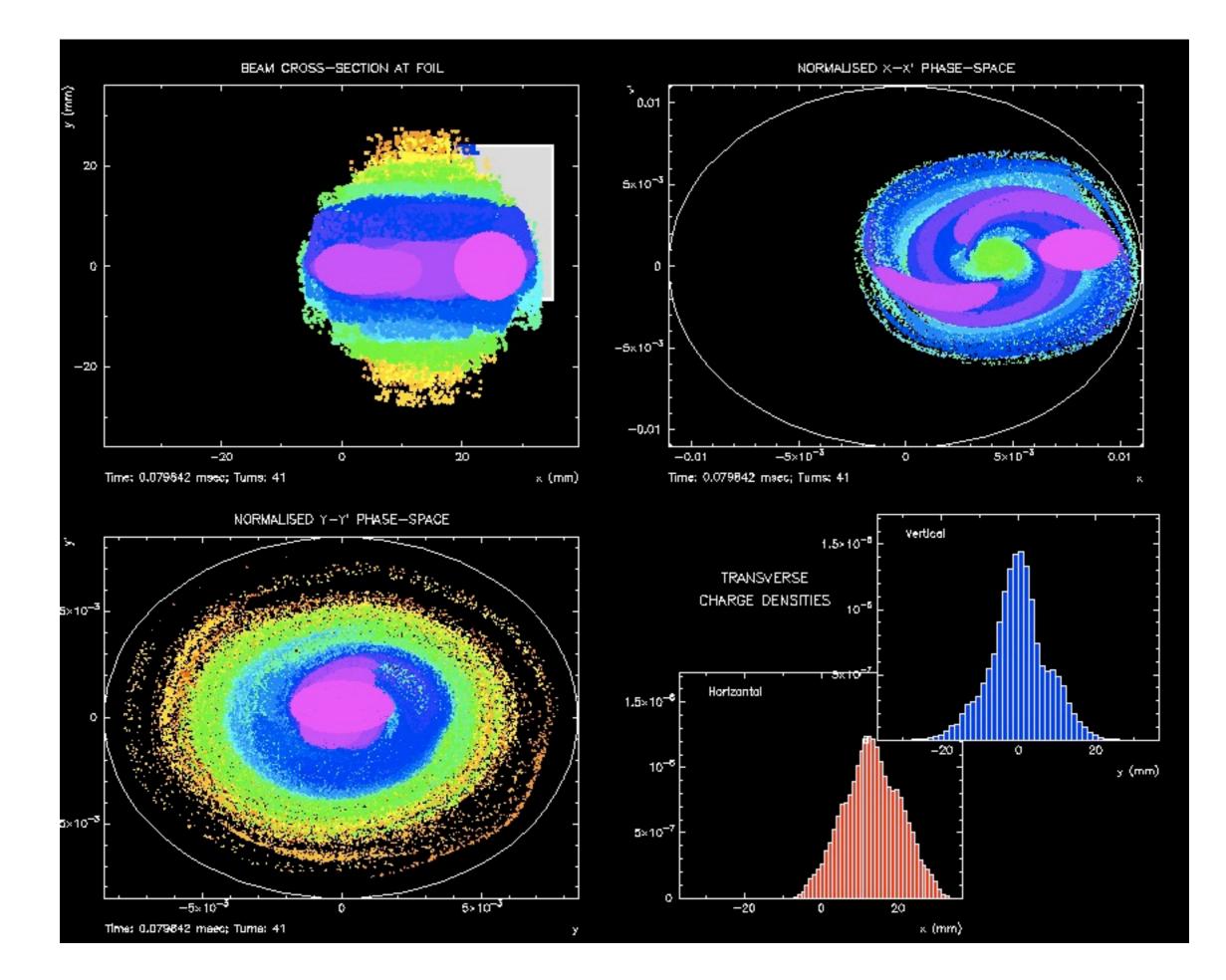


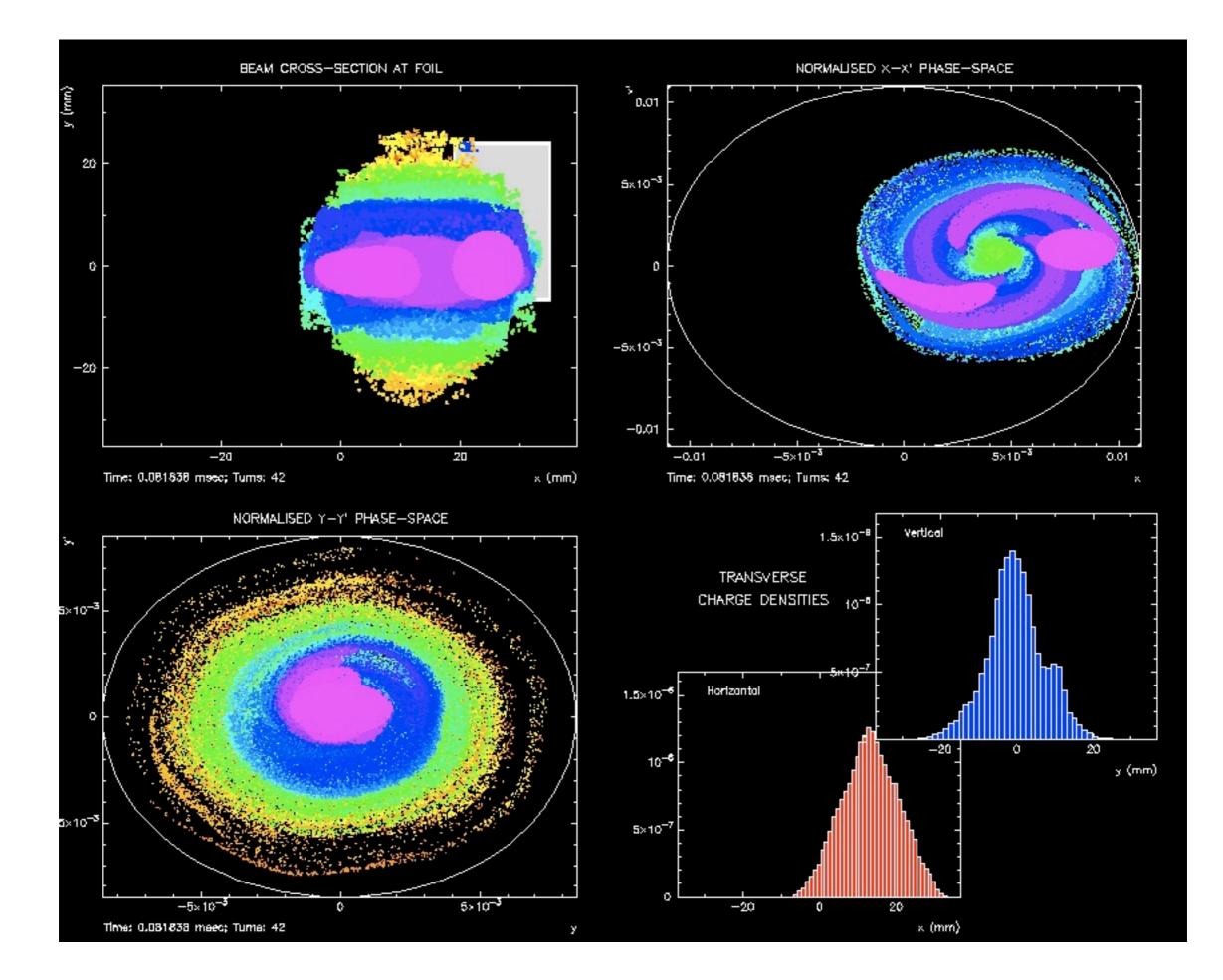


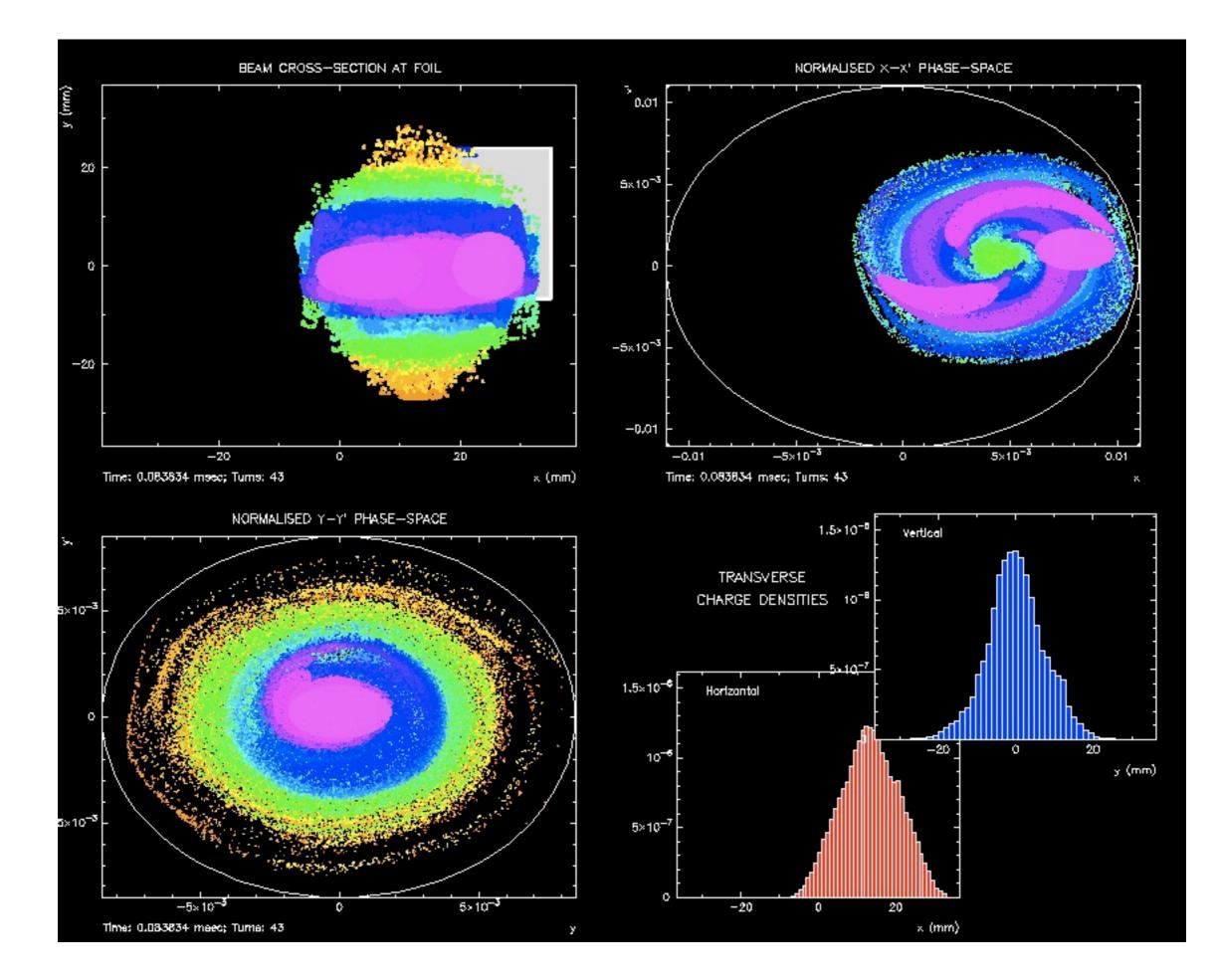


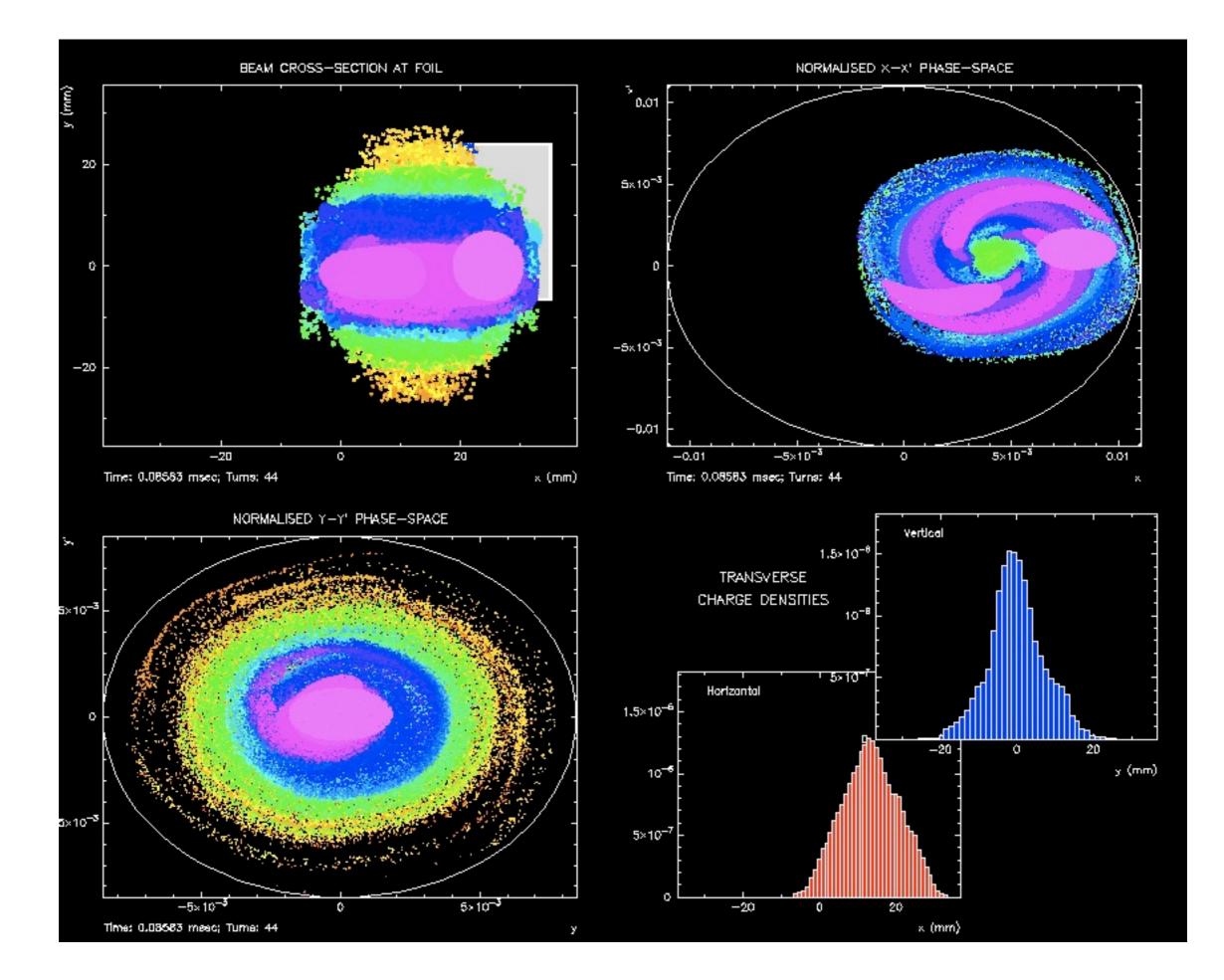


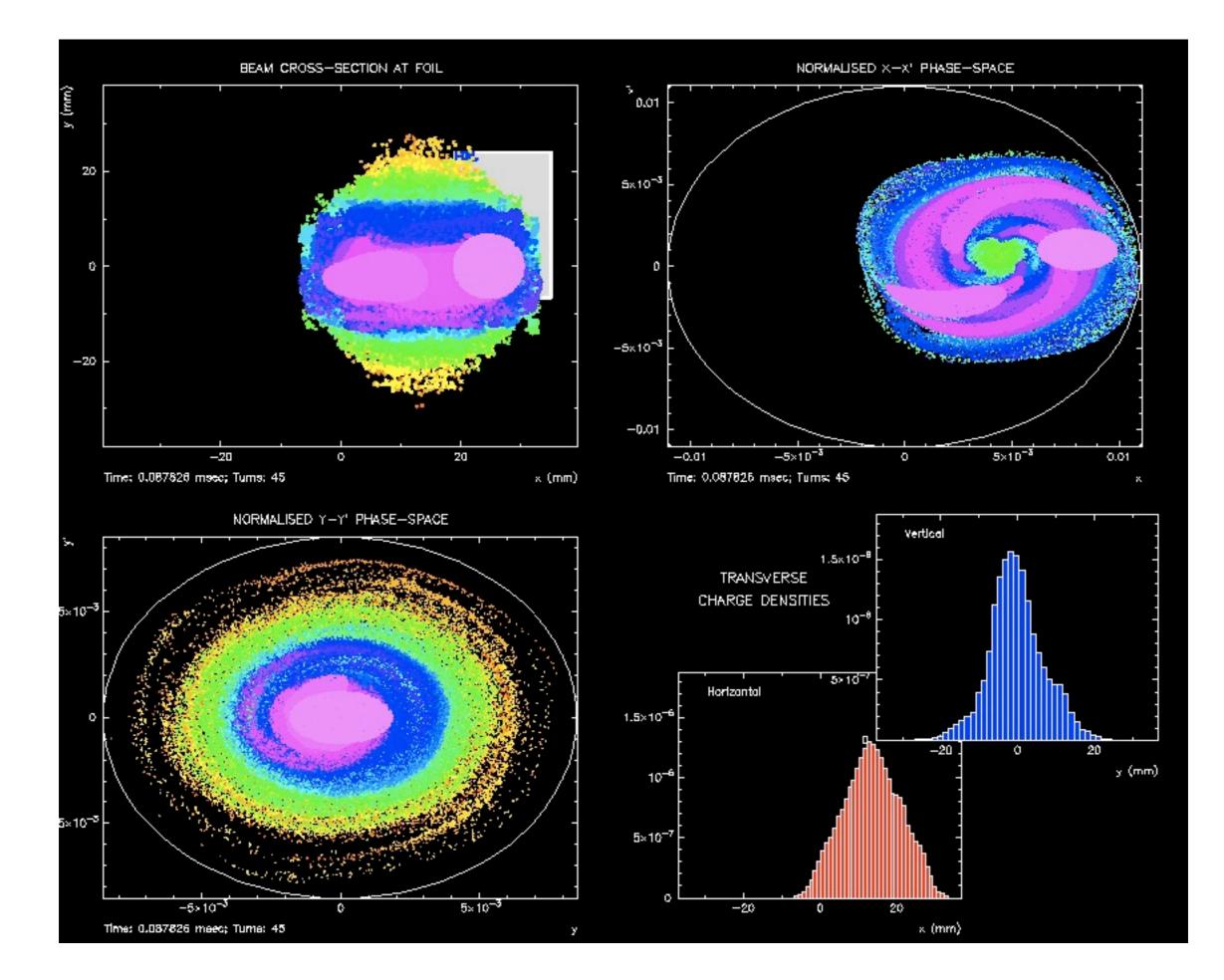






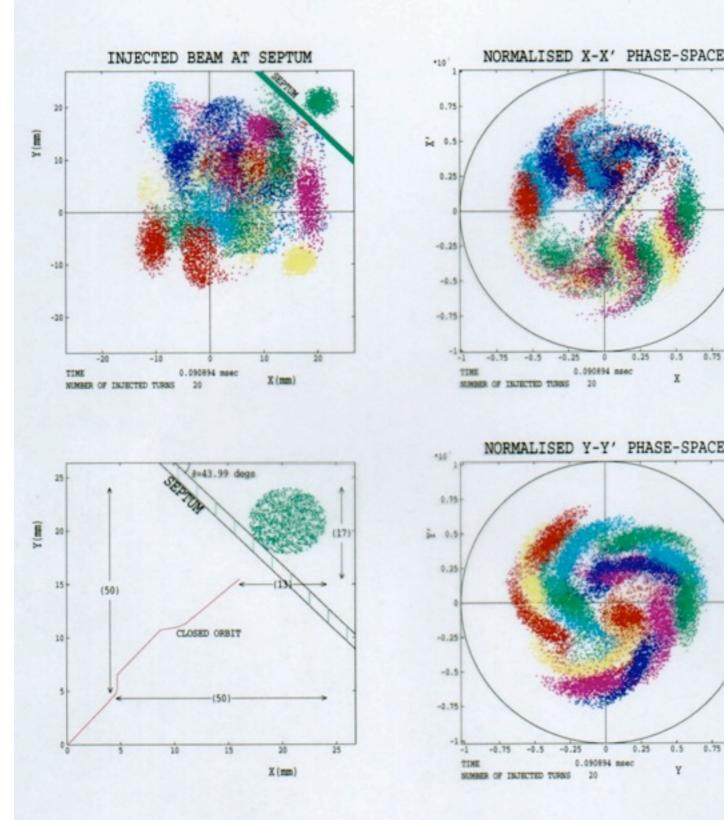






Heavy Ion Fusion (HIDIF)

PHASE-SPACE



Multiturn Injection modelled with TRACK2D

- 20 turns of 400 mA Bi⁺¹ beam.
- Space-charge tune depression ~0.04.
- Two-plane injection using tilted electrostatic septum
- Note distortion of individual turns in phase space



Science & Technology Facilities Council 74

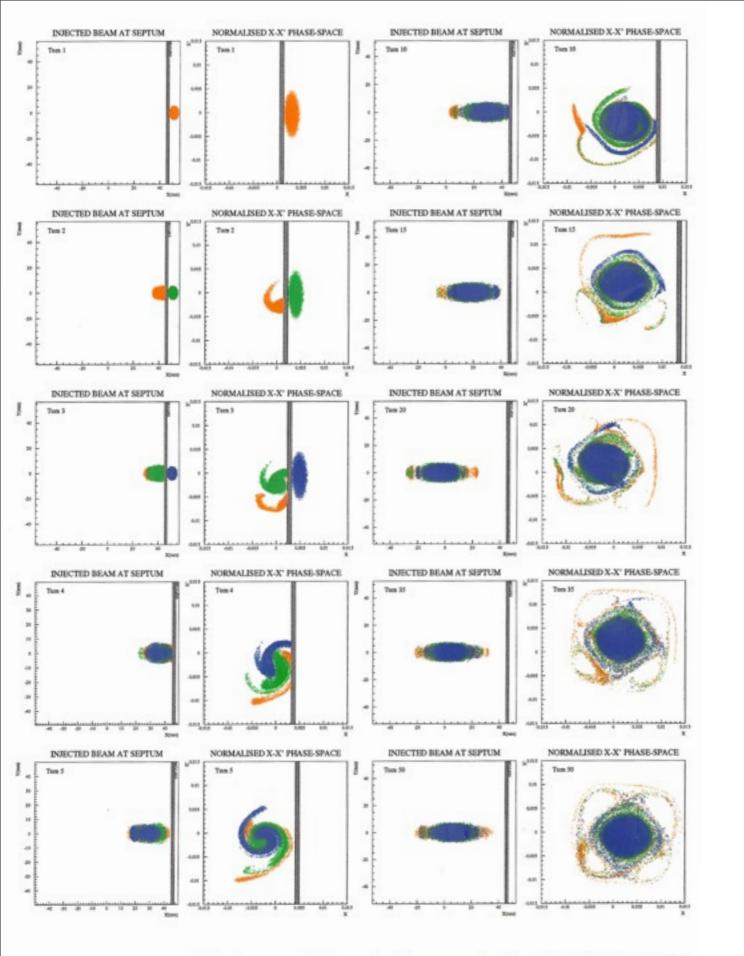


Figure 4.11: Simulation of the three-turn betatron stacking process for the production of the LHC beam in the PS Booster. Clearly visible is a fourth order transverse resonance which builds up in the horizontal phase plane. Study from ~1998 of 3 turn stacking process in PS-Booster using TRACK2D

Shows beam loss at septum and development of a 4th order spacecharge resonance

C. Prior & P. Knaus

Special Case: 1D Longitudinal Codes

$$\frac{\mathrm{d}\Delta\phi}{\mathrm{d}t} = \frac{h\omega_0^2\eta}{\beta^2 \mathcal{E}} \left(\frac{\Delta\mathcal{E}}{\omega_0}\right), \qquad \frac{\mathrm{d}}{\mathrm{d}t} \left(\frac{\Delta\mathcal{E}}{\omega_0}\right) = \frac{q}{2\pi} \left[V(\phi) - V(\phi_s) + U_s(\phi)\right]$$
$$U_s = -q\beta c R \left[\frac{g_0}{2\beta} \frac{Z_0}{\gamma^2} - \omega_0 L\right] \frac{\partial\lambda}{\partial s}$$

Tracking uses symplectic mapping with space charge calculated from derivative of the line density.

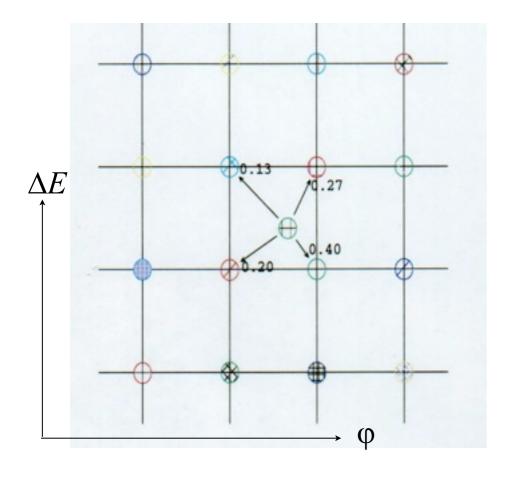
CODES: ESME (FNAL), LONG1D (TRIUMF), TRACK1D (RAL)

A major issue in a high intensity proton accelerator is building up the beam intensity through several turns of injection. For the SNS, $N_{turns} = 1600$ turns are required; for the ESS, $N_{turns} \sim 1000$. For reliable results, need ~ 5000 particles per turn, so $\gtrsim 5 \times 10^6$ overall.

One solution is to use "painting" technique with variable charge build-up. Restricts total to $\sim 10^5$ particles, yet has ~ 5000 per turn.

Facilities Council

Charge Assignment to Grid



TRACK1D assignment uses Triangular Shaped Cloud (TSC). Line density smoothed with cubic splines to remove statistical effects. Includes corrections to counteract artificial spreading of the beam.

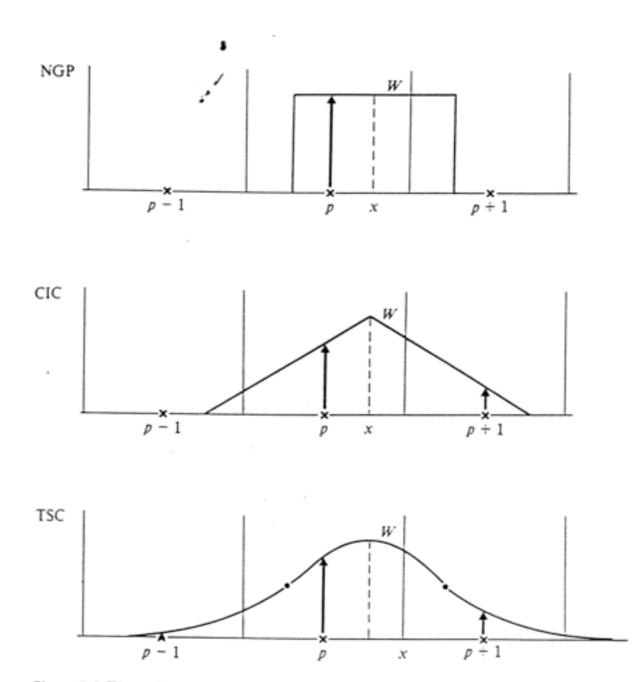


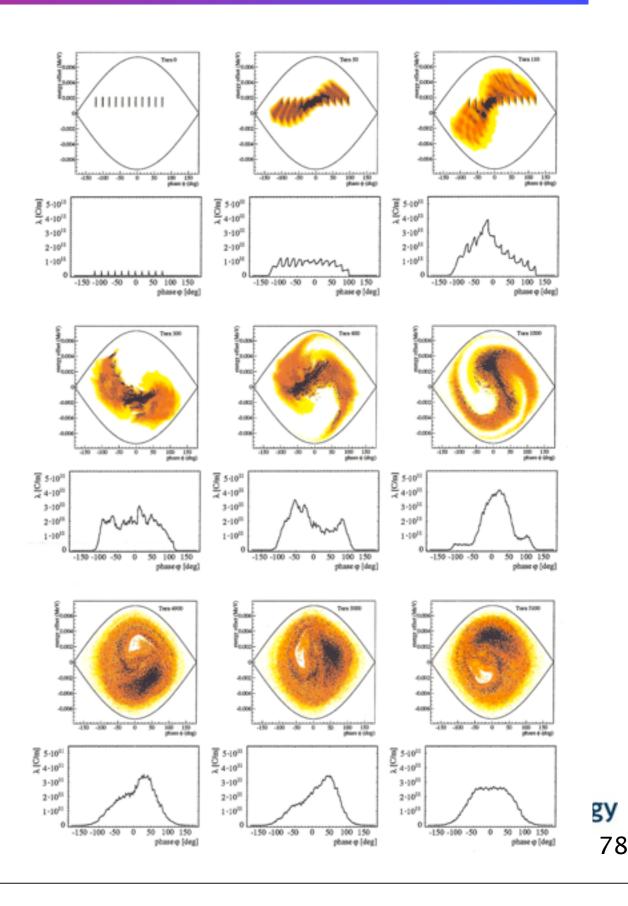
Figure 5-5 The assignment function shape interpretation of charge assignment. The fraction of charge assigned from a particle at position x to a given mesh point is equal to the value of the assignment function W at that point.

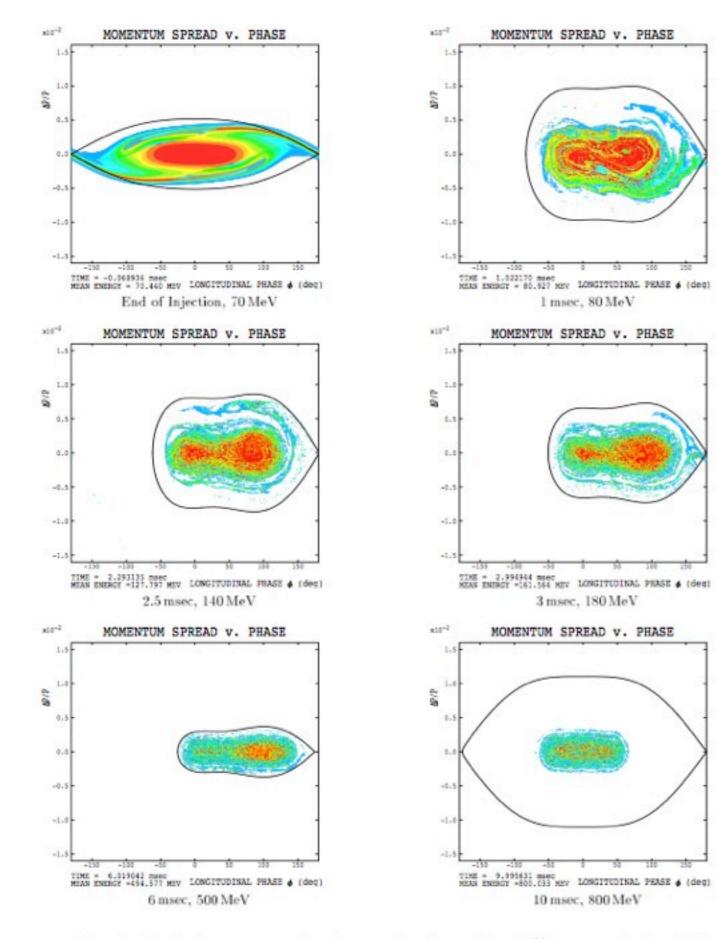


Longitudinal Study of CERN-PS

C. Prior & P. Knaus, ~1998

- Off-energy injection
- 11 micro-bunches per bucket
- Tracked for ~10 synchrotron periods
- No beam loss, good distribution





Longitudinal phase space plots for acceleration of 3×10^{13} protons in the ISIS synchrotron from 70 MeV to 800 MeV with dual harmonic RF system. Dual harmonic (h=2/4) injection, trapping and acceleration in ISIS. I 50 turns of 70-800 MeV beam

C. Prior, ICANS 1996

Available Codes I

IMPACT Rob Ryne, Ji Qiang (LBL); mainly a linac code with new MaryLie developments for modelling rings

TRACEWIN Nicolas Pichoff (CEA); Windows linac code

ORBIT Jeff Holme, Sarah Cousineau (SNS); ring code developed for SNS; exists in different versions at ORNL, FNAL, BNL

SIMPSONS Shinji Machida (RAL); used for J-PARC modelling

ACCSIM Fred Jones (TRIUMF); developed from matrix applications with space-charge kicks

- **TRACKxD** Chris Prior (RAL); x = 1, 2, 3; used for ISIS, ESS, SNS, HIDIF, Neutrino Factory and other modelling
 - GPT Bas van der Geer (Pulsar Physics); Commercial code developed initially for high intensity, very short electron bunches.

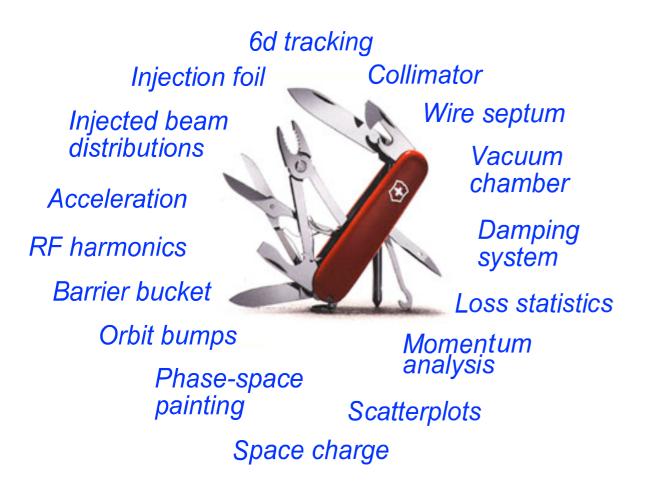


Codes II

- OPAL Andreas Adelmann (PSI); major advances; fully 3D; developed mainly for cyclotron studies
- **BEST** Hong Qin (PPPL); based on δf -method. Used for investigating two-stream instabilities.
- Micromap Ingo Hofmann, Giuliano Franchetti (GSI); used for modelling FAIR and for comparison with earlier theories.
 - WARP David Grote, Alex Friedmann (LLNL); fully 3D, mainly for early stages of acceleration, from ion gun.
 - PATH Alessandra Lombardi (CERN); originally written to model the muon beam for the CERN neutrino factory, later developed for protons.
 - VADOR Eric Sonnendrucker (Strasbourg); Vlasov solver
- PARMILA Jim Billen (LANL); long established linac code; works in association with Trace3D; also PARMELA.

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Goals



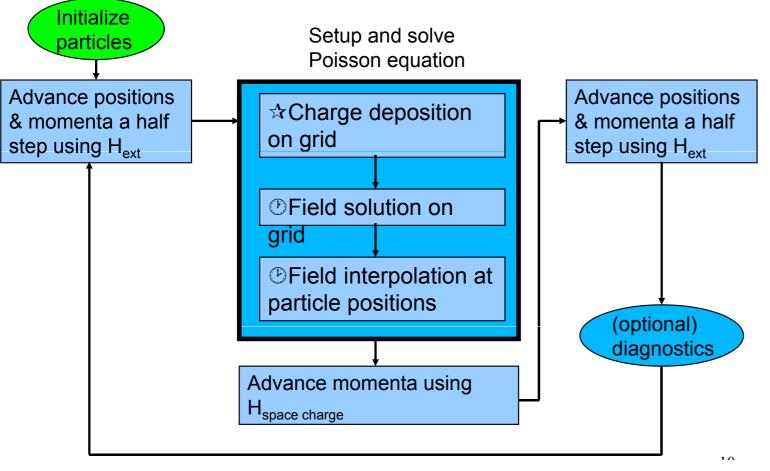
From: ACCSIM, Fred Jones (TRIUMF)

Plus:

- Full treatment of field maps
- Off-axis beams
- Full suite of routines for beam diagnostics
- Higher order effects
- Secondary particle effects
 - electron cloud
 - decays (muons)



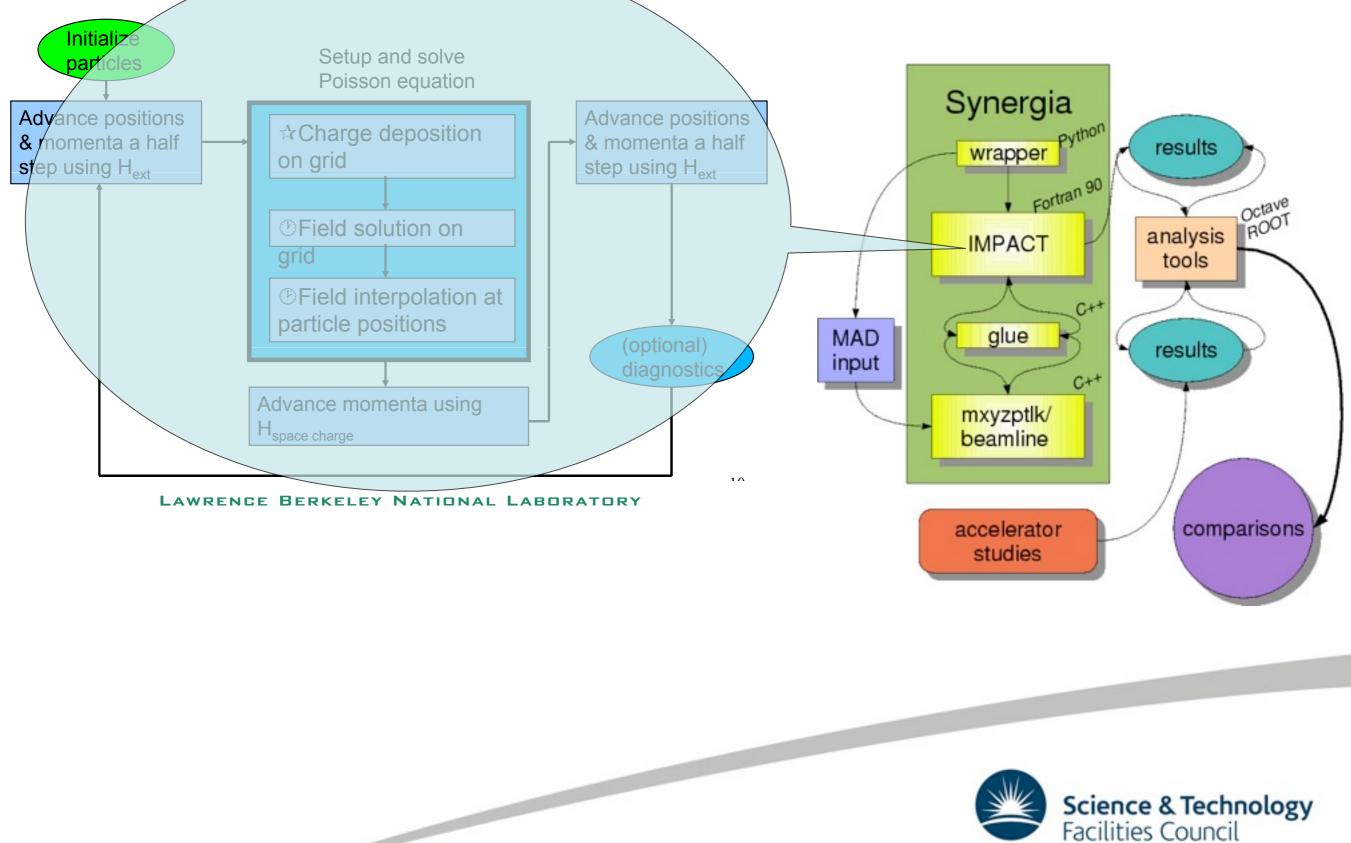
Components of a typical Beam Modelling Package



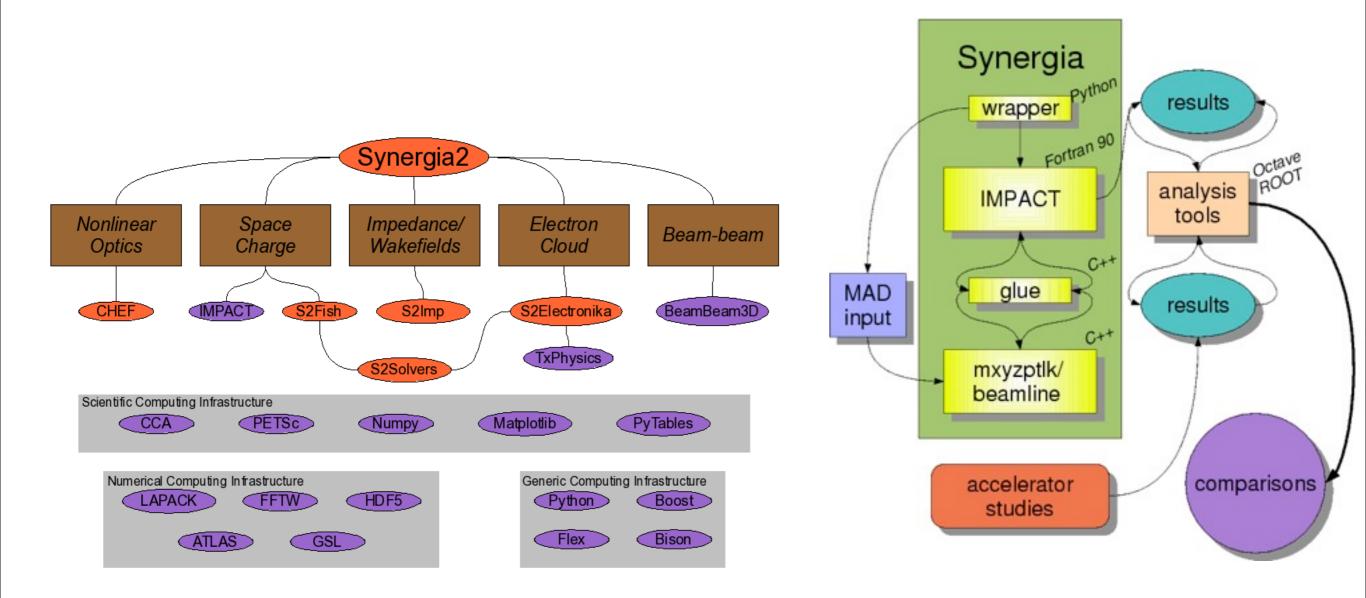
LAWRENCE BERKELEY NATIONAL LABORATORY



Components of a typical Beam Modelling Package



Components of a typical Beam Modelling Package



Synergia: Fermilab code, P. Spentzouris

8



How accurate are the codes?

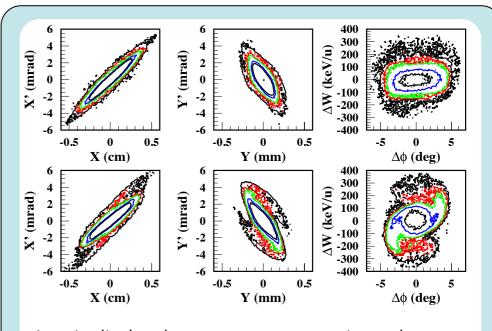
-SYN

- All codes should have a set of basic tests, preferably with known analytical solutions
- Benchmarking should cover
 - code v. code
 - code v. experiment
- Recent examples

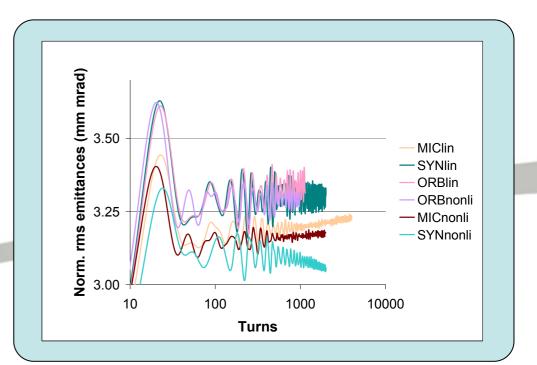
Monday, 15 April 2013

- Montague resonance tests with CERN PS, 2Qh-2Qv=0 (ACCSIM, SYNERGIA, MICROMAP, SIMPSONS, IMPACT, ORBIT, SIMBAD)
- HIPPI linac injector comparison

- Electron cloud studies (PEHT, PEHTS, QUICKPIC, HEADTAIL)
- Study of Hofmann resonances at KEK (IMPACT, TraceWin)

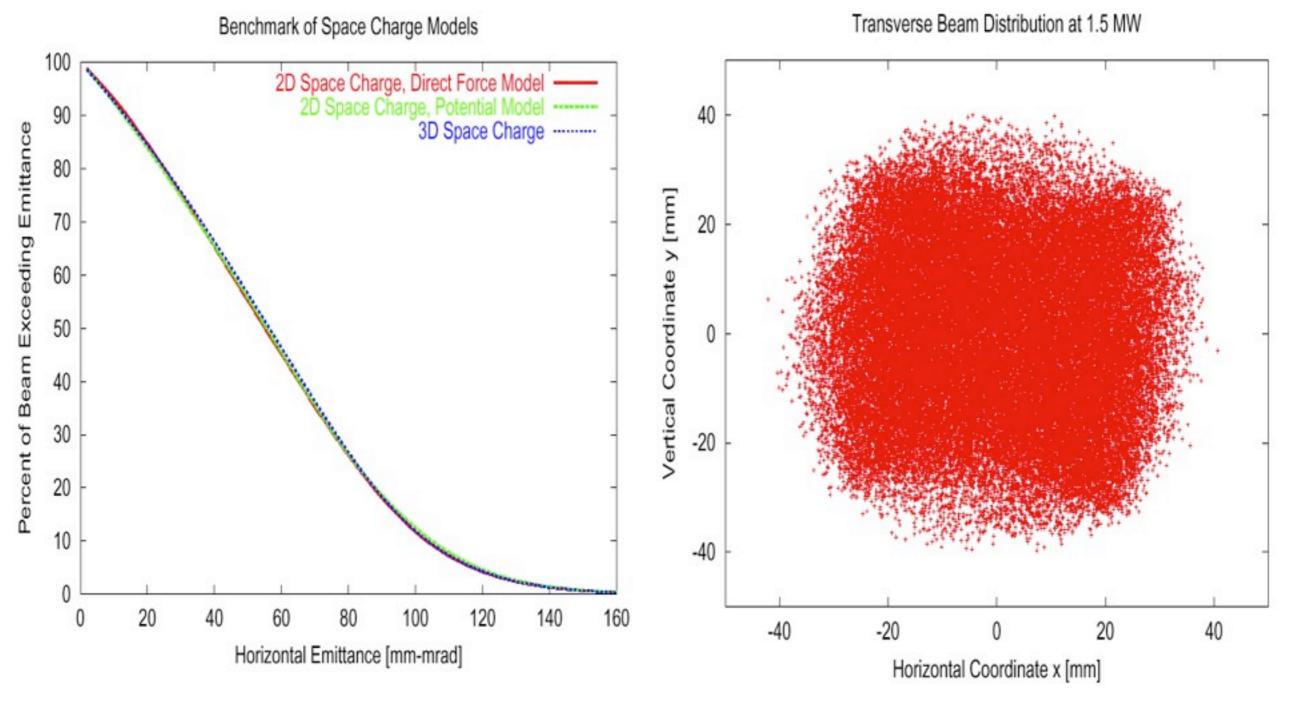


Longitudinal phase space: comparison between simulations using PARMILA and TRACK of SNS-DTL, 38 mA H⁻ beam, 10⁵ particles. Discrepancies caused by different fringe field models and space-charge routines.



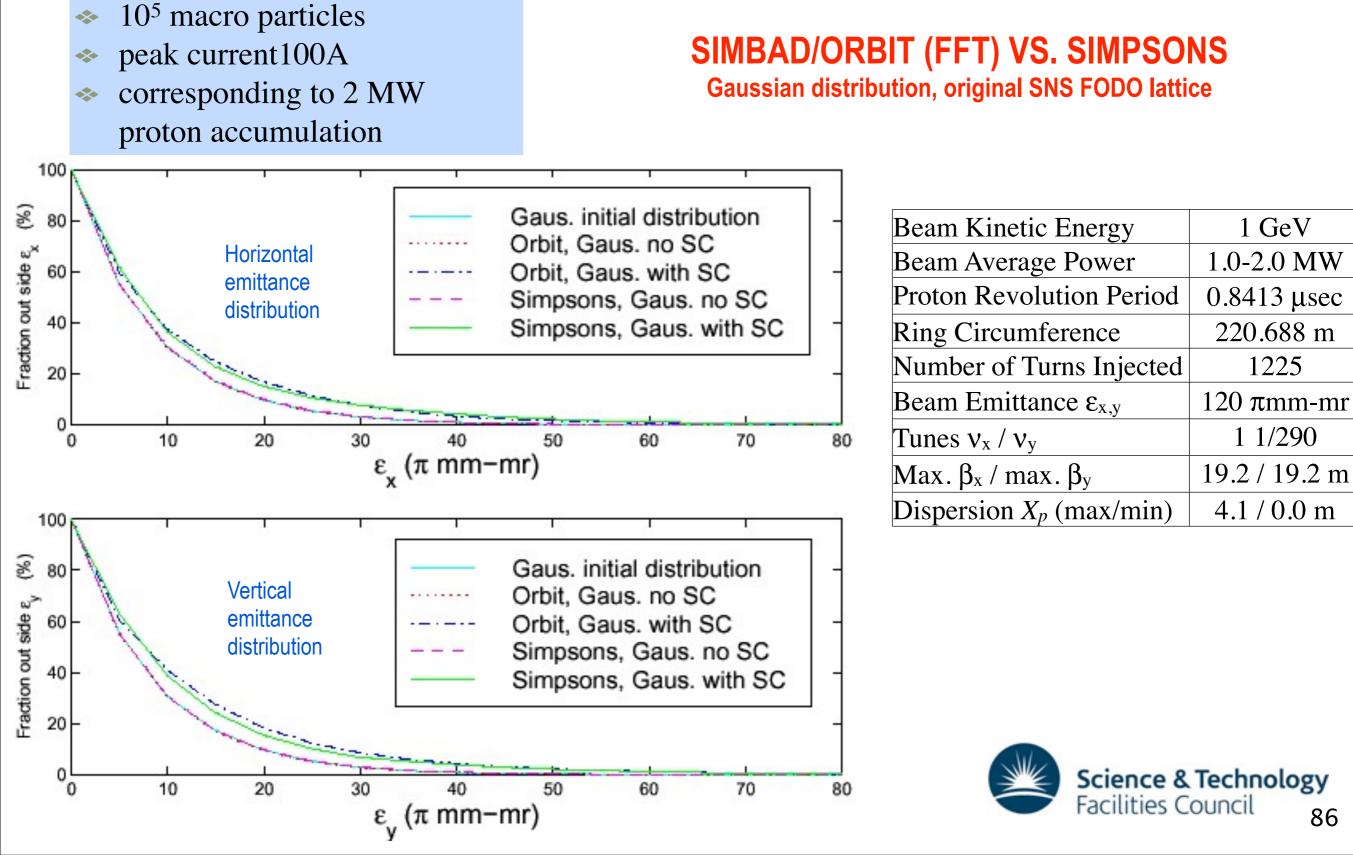
See ICFA Beam Dynamics Newsletter 41, December 2006

ORBIT Application: SNS 1.44 MW Injection Space Charge Benchmark and Final Distribution





Code v. Code



Scope of Existing Codes with Space Charge

Results/predictions

- Beam profile measurements: CERN-PSB, KEK-PS, PSR
- Injection losses (e.g. mismatch, emittance transfer)
- Coherent resonances -- intensity limitation
- Benchmarks with Accsim, Orbit, Simpsons, show long-term (50k turns) RMS matching to high degree of precision

Study

- Beam redistribution while preserving RMS matching
- Intrinsic resonance due to space charge (sensitive to working point, observed independently in most codes)
- Synchro-betatron effects -- space charge, chromaticity
- Halo parameters and other amplitude measures
- Stationary distributions (not widely used?)
- Still a need for more accessible benchmarks and test cases



Vlasov Solvers

- High intensity beams are usually modeled by the Vlasov equation.
- The distribution function f(x, v, t) is given by

$$\frac{\partial f}{\partial t} + v \cdot \nabla_x f + \frac{q}{m} \left(E + v \times B \right) \cdot \nabla_v f = 0,$$

generally coupled with the Poisson or Maxwell equations.

- Numerical simulations are mostly performed using PIC method.
- Important noise in PIC methods especially in poorly populated regions of phase space makes it hard to see phenomena like e.g.
 - particle trapping (strong Landau damping) in plasmas
 - halo formation in beams
- Computers now powerful enough to do realistic physics using a grid in phase space.
- Provides alternative to PIC for code benchmarking.

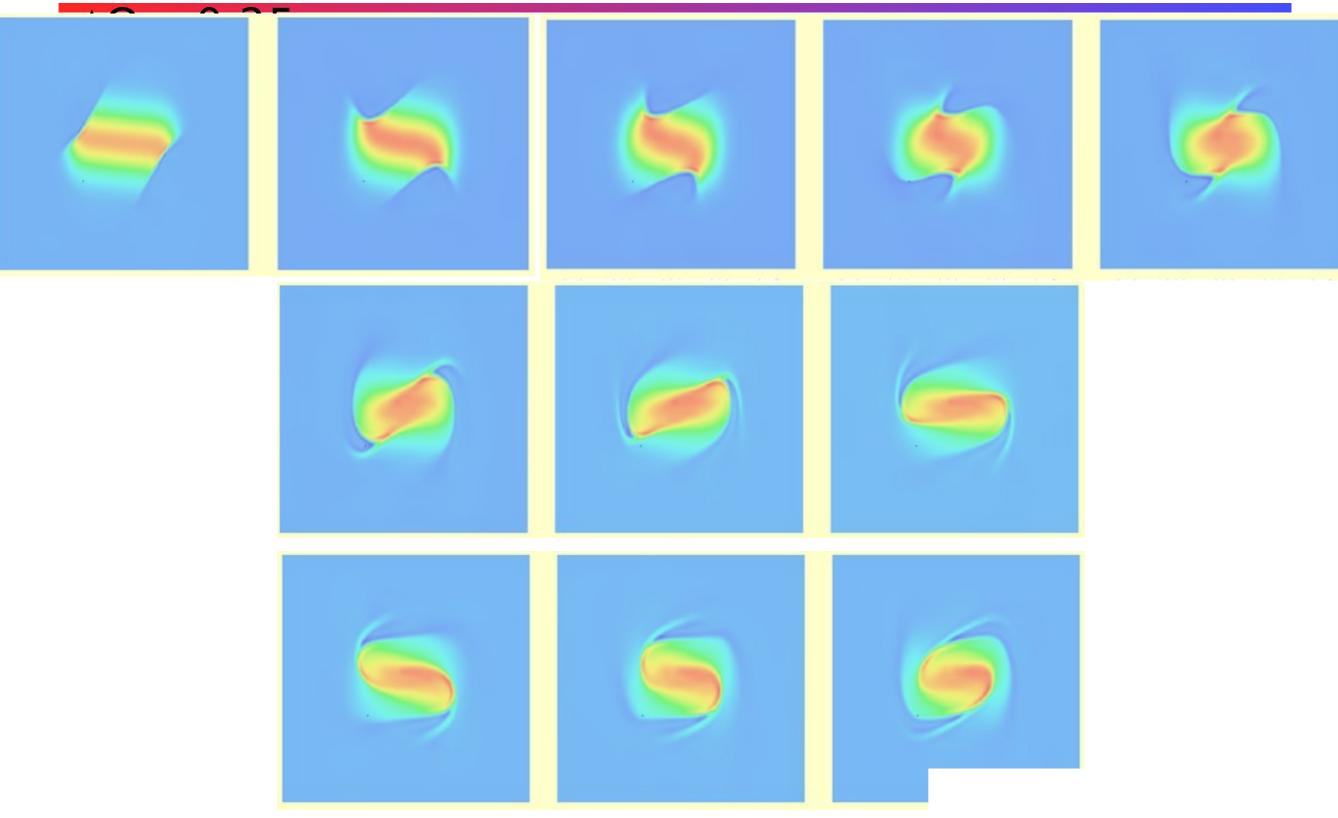
Proposal to develop 4D-->6D Vlasov solver with Jonathan Smith (Tech-X)and Hartree Centre, Daresbury

Difficult in >2D phase space because of very large number of grid points. Hence very slow.

Use symmetry or conserved quantities on characteristics

Optimise number of grid points for specific simulations

Example: Evolution of a Semi-Gaussian beam of 80keV Potassium ions in a uniform focussing channel,



Results from VADOR code, E. Sonnendrucker, Strasbourg

Monday, 15 April 2013

Spreadsheet of Space-Charge Codes I

Code	Language	Platform	GUI	Parallel	$1\mathrm{D}/2\mathrm{D}/3\mathrm{D}$	Particles	linacs/rings
IMPACT	F90	Unix/Linux	no	MPI	3D	$> 10^{6}$	linacs
ML-IMPACT	F90	Unix/Linux/Mac	no	MPI	3D	$> 10^{6}$	linacs/rings
PARMILA	F90	Windows	no	no	2D/3D	10^4 - 10^5	linacs/ transfer lines
GPT	C, C++	Windows	yes	MPI scans	3D	10^{6}	linacs/FEL/ transfer lines
BEST	F90	Unix/Linux	python/IDL	MPI/ OpenMP	3D	$> 10^{6}$	linacs/rings
VADOR	C++	Unix/Linux	no	MPI	2D	n/a	linacs
SPUNCH	F77	Linux	no		1D	10^{4}	LEBT
PATH	F90	Windows	yes	no	3D	10^{5}	linacs/rings
TRACEWIN	C++	Windows	yes	no	2D/3D	10^{5}	linacs
DYNAC	F77	Linux/Unix/ Windows	no	no	2D/3D	10^{5}	linacs
Synergia	F90/C++/ Python	Unix	no	MPI	3D	$> 10^{6}$	linacs/rings
WARP	Python/ F77/F90/C	Linux/Unix/ Windows/Mac	Under dev	MPI	3D/rz/xy	up to 10^8	linacs/rings

Spreadsheet of Space-Charge Codes II

Code	Space Charge Solver	Boundaries/Images	Impedances	Field Maps	Integration order
IMPACT	spectral	open/periodic/ rectangular/circular	no	yes	2nd order in z
ML-IMPACT	spectral	elliptical/ polygon/lossy	yes	no	2nd in z 5th Runge-Kutta
PARMILA					
GPT	3D multigrid	open conductive rect. pipe, cathode	no	2D,3D	5th Runge-Kutta
BEST	spectral, FD	circular conducting wall	automatic/ external	no	user specified
VADOR	FFT	conductive wall any shape	no	no	2nd
SPUNCH	exact for disc- shaped particles	circular conducting wall	n/	n/a	1st
PATH	Schell, pt-to-pt	open	no	yes	?
TRACEWIN	Scheff/PICNIC/Gaussup	open	no	no	?
DYNAC	Scheff/Scherm/Hersc	open	no	yes	3rd analytical
Synergia	spectral (IMPACT)	open/periodic/ rectangular/circular	no	yes	2nd order in z
WARP	FFT, Cap matrix, multigrid, adaptive mesh, refined MG	square/round pipe, internal conductors, bent pipe, general	ad hoc	no	2nd order

Spreadsheet of Space-Charge Codes III

Code	t or s tracking	Graphics	Portability	tability Source code available?		Standard test cases
IMPACT	S	post proc. with MPI	all unix platforms	to collaborators	partial	yes
ML-IMPACT	S	post proc.		to collaborators	partial	yes
GPT	t	built in	portable except user interface	all beamline components	yes	yes
BEST	t	netcdf, IDL	any Linux	yes	no	yes
VADOR	s	GNUplot, openDX	any Linux	yes	almost	yes
SPUNCH	S	built in	fully portable	yes	no	yes
PATH	S	built in	any Windows	yes	yes	?
TRACEWIN	S	built in	any Windows	no	yes	?
DYNAC	t,s	GNUplot	fully portable	yes	yes	yes
Synergia	S	post proc. Root+Openinventor	all Linux	yes	in progress	not yet
WARP	t,s	PyGist 2D OpenDX 3D	portable	yes	online	yes

Final Message

SAVE EVERYTHING:

Even if you think the job is finished, don't for one moment think you will never need the data or the code again.

