

# Track Fitting with the SciFi Trackers

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on behalf of the Tracker Group

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# Overview

## 1. Kalman Track Fitting

- Misalignment Search
- $\chi^2$  and P-Value of the fit

## 2. First hints of Emittance Analysis

- Resolution of the track parameters
- Bunch Emittance
- Single Particle Emittance
- Resolution of Single Particle Emittance
- Emittance change in Stage 4 with LH<sub>2</sub>

# Misalignments

## The precision can't be limited by misalignments

They are taken into account by:

- shifting expectation of where the particles hit the detector;
- feeding uncertainty in the misalignment into covariance matrices - reduces weight of the measurements.

**Impacts P-Value of the track.**

# Misalignment Search

By construction, the station is displaced from the centre by less than the channel width (1.4 mm) - Geoff Barber

Precision laser measurements have verified this for the input tracker - David Addey's NIM paper.

## Despite all that...

Added an algorithm which looks for misalignments in the station planes.

Integrated with the Kalman Filter.

Iterative: if run is a misalignment search, misalignment values are updated after each track.

Performance tested with misaligned detector simulation.

# Misalignment Search

Update of misalignment (s):

$$s_1 = s_0 + \textit{GainMatrix} \times (\textit{measurement} - \textit{optimal}_{\textit{removed}}) \quad (1)$$

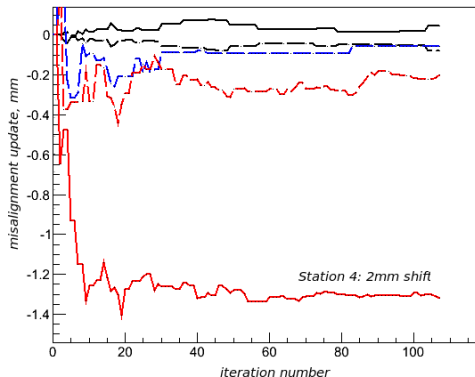
*optimal<sub>removed</sub>*: optimal estimation when the station measurement is removed from the fit.

The error associated with  $s_0$  is also updated. As it becomes smaller, the convergence of the misalignments is damped.

The precision is limited by the measurement error - the channel width.

# Misalignment Search

Figure shows update of misalignment parameters in  $(x, y)$  of stations 2, 3, 4. All stations are aligned expect station 4:  $\Delta x = 2mm$ .



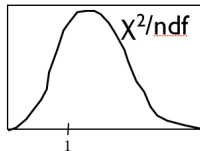
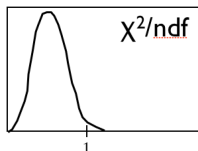
Optimal estimations are already found after 10 tracks.  
→ compare with classical method (mean of residuals of large number of tracks...)  
**RMS spread of  $\sim 350\mu m$ .**

# $\chi^2$ and P-Value of the Fit

P-value is the probability that the observed  $\chi^2$  exceeds the expected  $\chi^2$  value by chance.

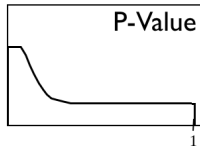
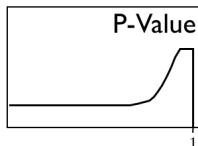
## We might overfit:

- pull towards data points is too strong;
- the residuals are too small, the  $\chi^2$  is too small



## We might underfit:

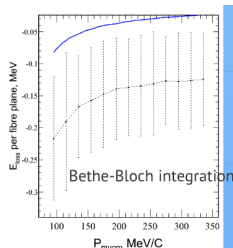
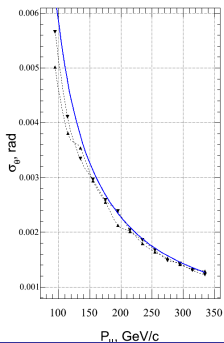
- the residuals are too large the  $\chi^2$  is large



# $\chi^2$ and P-Value of the Fit

It's a balance between:

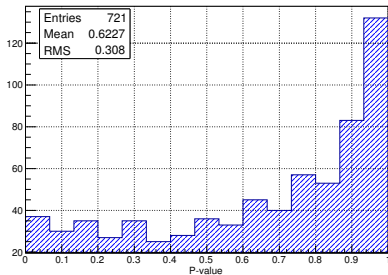
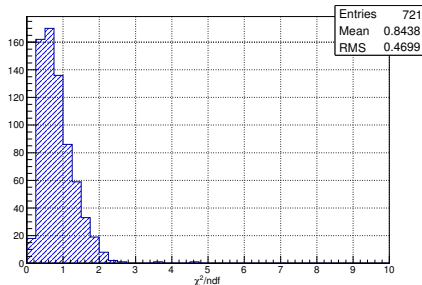
- error assigned to the measurement;
- MCS and  $E_{loss}$  models;
- seed covariance;
- misalignments (themselves and their covariance).





# $\chi^2$ and P-Value of the Fit

Example of  $\chi^2$  distri



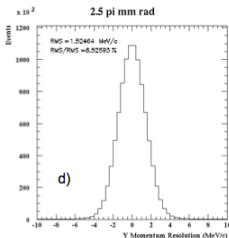
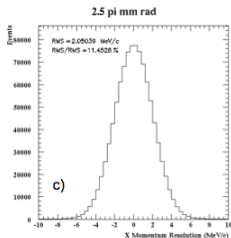
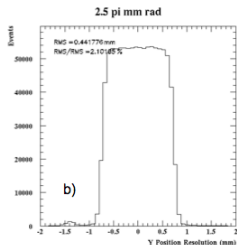
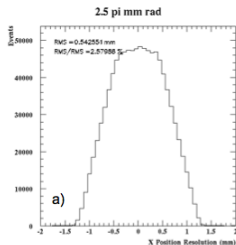
## Goals for the analysis:

Reproduce results of MICE Note 90.

Reconstruct Single Particle  
Emittance.

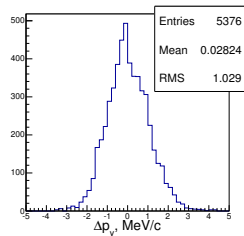
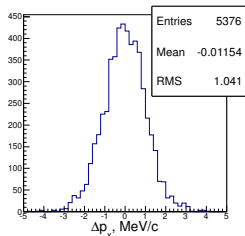
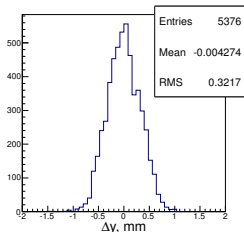
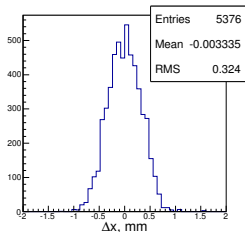
# Resolution of the Reconstruction

From MICE Note 90: (cites an RMS value of  $370\mu\text{m}$  single-view position reconstruction)

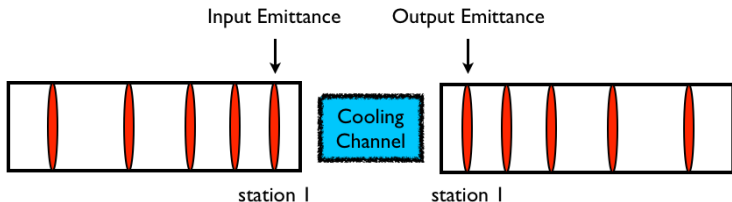


# Resolution of the Reconstruction

Current results: (beam 4d emittance = 4;  $E_\mu = 200\text{MeV}/c$ )



# Definitions for the next slides



$\epsilon_N$  is bunch emittance;  $\epsilon_j$  is single particle emittance.

Test geometry: only the two tracker solenoids (diffuser, trackers, coupling coils, cryostats).

# 1. Bunch Emittance

Used ensemble of many particles to calculate bunch emittance:

$$V = \langle (u_i - \bar{u}_i)(u_j - \bar{u}_j) \rangle \quad (2)$$

where  $u = [x, p_x^c, y, p_y^c]^T$ .

$$\epsilon_N = \frac{4 \sqrt{|V|}}{m_\mu} \quad (3)$$

With the test geometry and the beam previously defined:

$$\epsilon_N^{Input} = 4.33$$

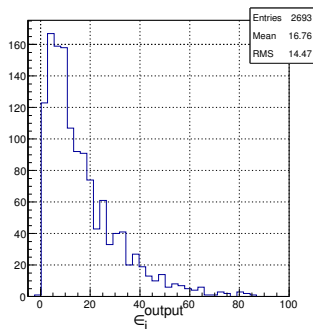
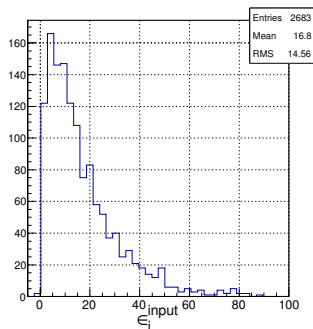
$$\epsilon_N^{Output} = 4.28$$

Emittance calculated from MC truth: 4.299 and 4.306 respectively.

## 2. Single Particle Emittance

Single particle emittance calculated from the bunch emittance<sup>1</sup>:

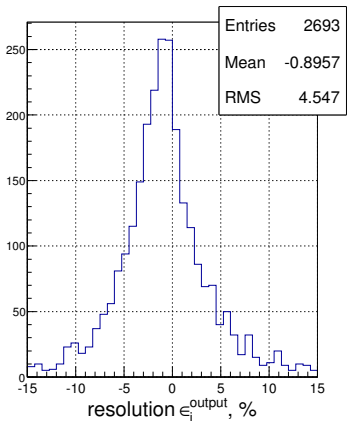
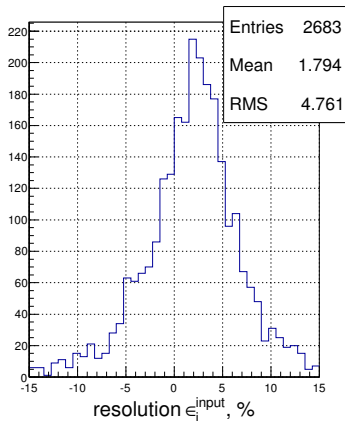
$$\epsilon_i = \epsilon_N u^T V^{-1} u \quad (4)$$



Verifies  $\langle \epsilon_i \rangle = 2N\epsilon_N$ .

<sup>1</sup>Chris Rogers thesis

# Emittance Resolution



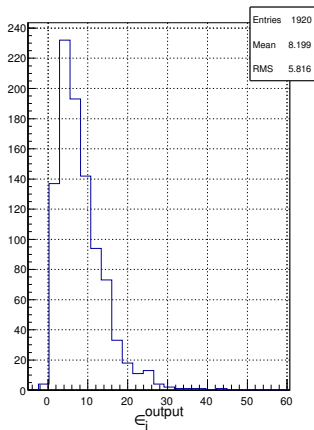
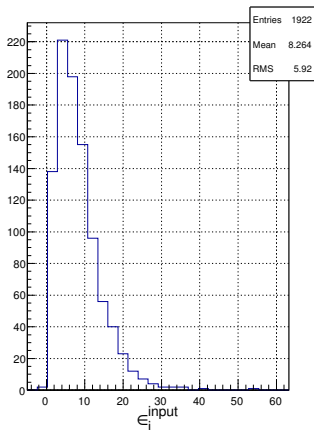
Centroid is displaced.



# Emittance change in Stage 4 with $LH_2$ . Initial beam emittance = 2

Bunch Emittance: 2.12, 2.06

Bunch emittance from SPE mean: 2.08, 2.06



# Conclusion

Kalman Filter at polishing stage:

- flattening the P-value is challenging.

Emittance studies underway:

- repeat and extend MICE Note 90.

Acknowledgements:

To Prof. Kenneth Long and Dr. Jaroslaw Pasternak for helpful conversations.