Enabling Breakthroughs Via Innovative Spatial Data Management

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Spatial Data Management Challenge

Model Visualization



Single Neuron 3D Model



Model of 1 Million Neurons:
→ Cylinder representation 270 GB
→ Mesh representation 5.8 TB
→ Will grow orders of magnitude!



Spatial Range Queries

State of the Art (R-Tree): Hierarchy of Minimum Bounding Rectangles (MBR)





STEP2: Qualerry Construction



Overlap reduces performance, increases with data density



FLAT: A Two Phase Spatial Index

Add reachability information during index construction

Key Idea:

1) SEEDING: Find any arbitrary object inside the query region cheaply.

2) CRAWLING: Retrieve remaining

Querying overhead <u>independent</u> of data density → Speedup of 2-8x compared to current methods



Moving Range Queries

Model analysis: User issues series of consecutive queries



I/O expensive \rightarrow long wait

Series of spatial queries

Neuron branch

Use idle time \rightarrow predict next query & prefetch

Neuron Tissue Sample (1692 neurons)



Time



SCOUT: Content Aware Prefetching

- Key Idea: Use content of previous queries
- Structure followed can be any one of the many paths in the result
- Insight: Iterative candidate pruning, structure followed is common among all queries



SCOUT achieves between 72% and <u>91%</u> prediction accuracy \rightarrow Speedup of 4-15x compared to state of the art



Touch Detection – Spatial Join

Modeling synapses: place synapses where neurons intersect \rightarrow In-Memory Spatial Join

State of the art join approaches:

- Space-oriented Partitioning (Partition Based Spatial Join, Size Separation Spatial Join)
- Data-oriented Partitioning (Synchronized R-Tree Traversal, Indexed Nested Loop (R-Tree))



Space-oriented Partitioning: ex. **PBSM**





Data-oriented Partitioning: ex. Sync R-Tree Join





Using TOUCH results in a one to two orders of magnitude speedup for the spatial join

both worlds:

directly assign elements

Dataset A

use filtering



Demo

• FLAT - Efficient Range Query Execution on Dense Data

 SCOUT – Content Aware Prefetching

 TOUCH - Efficient In-Memory Spatial Join









Execution Time: 29.141 Execut Number of Comparisons: 30887184 Numb Number of Intersections: 11161 Numb

Execution Time: 56.824 Number of Comparisons: 59331860 Number of Intersections: 11161