



# IPM EM Simulations

9<sup>th</sup> DITANET Topical Workshop on Non-Invasive Beam Size  
Measurement for High Brightness Proton and Heavy Ion  
Accelerators

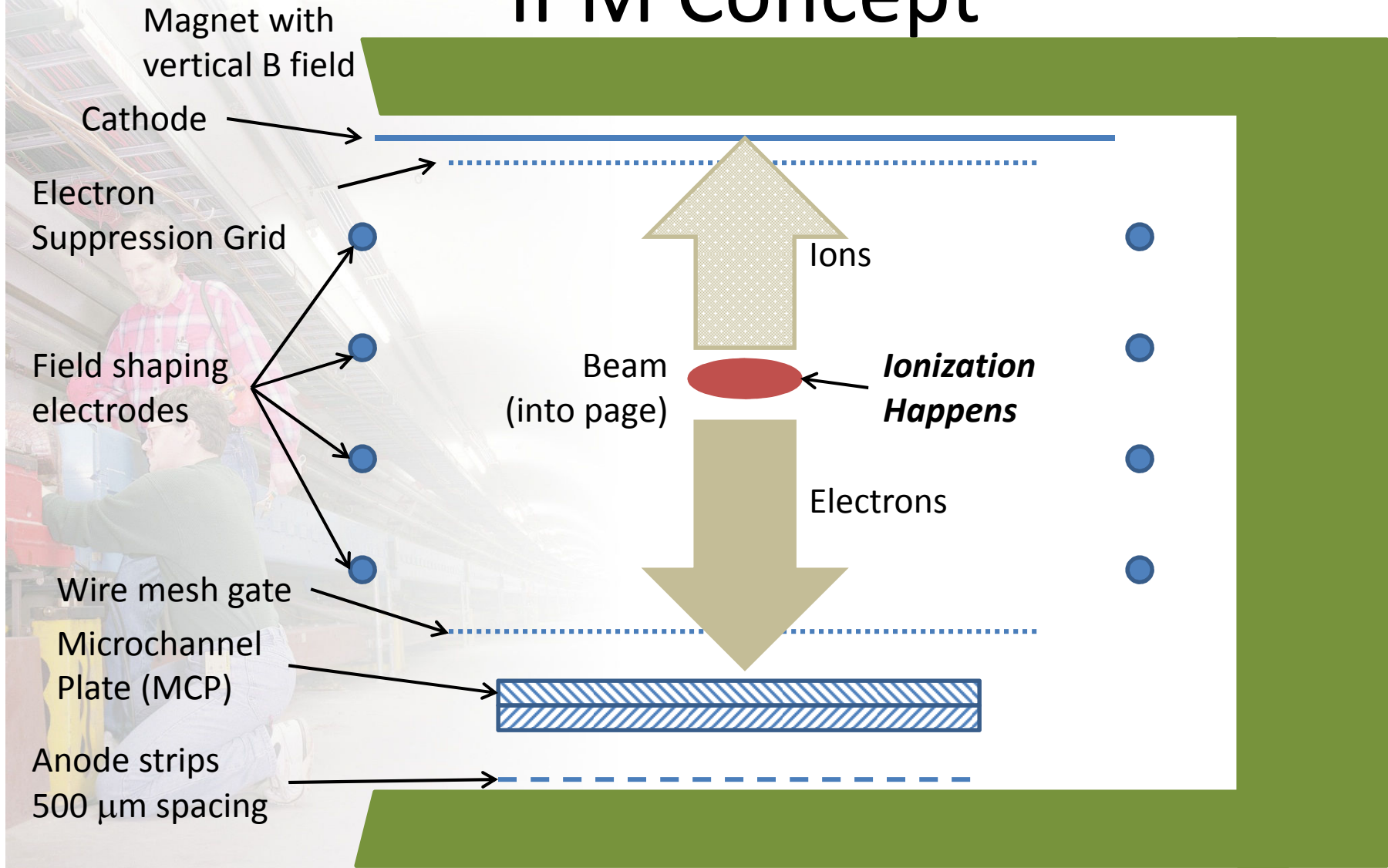
15-18 April 2013

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*Fermilab*

# Nova Era Main Injector / Recycler

- Recycler accumulates protons from Booster synchrotron
  - 8 GeV
  - $\sim 5 \times 10^{13}$  protons
- Main Injector receives beam from Recycler
  - 8 GeV incoming
  - Up to 120 GeV outgoing
    - Nova neutrino experiment
  - 588 53-MHz rf buckets
    - each bucket  $\sim 18$  ns
    - $1 \times 10^{11}$  protons per bucket
    - Bunch length typically  $\sim 1-3$  ns

# IPM Concept



# Gated IPM Concept

- Problem with MCP is short lifetime
  - Plate is using up lifetime whenever beam is in the machine and the IPM voltage is on
  - Voltage takes a while to raise and lower
- Would like to be able to gate the charge to preserve the MCP
  - Stop the electrons and ions from reaching the MCP
  - Allow the electrons and ions an escape path from the IPM active region
    - i.e. no Penning traps

# Gated IPM Concept

- The force on a charged particle is
 
$$\vec{F} = q \left( \vec{E} + \frac{\vec{v}}{c} \times \vec{B} \right) = m \frac{d\vec{v}}{dt}$$
- Assume that  $\vec{E} = E_0 \hat{x}$  and  $\vec{B} = B_0 \hat{y}$
- Solve the differential equations and one gets the usual solution of circular motion in the  $\hat{x} - \hat{z}$  plane, constant motion along  $\hat{y}$  and a drift along  $\vec{E} \times \vec{B}$  which in this case is  $\hat{z}$ , i.e. along the beam
- Putting in the values for the electric and magnetic fields gives us a drift velocity of  $\sim 10 \text{ cm}/\mu\text{s}$  along the proton beam direction
  - The electrons will have drifted beyond the MCP in  $\sim 1-2 \mu\text{s}$

# MATLAB Simulation

- Simulation tracks particles through arbitrary E and B fields
- Uses interpolation to obtain the fields at any point from previously calculated field distributions
- Propagates using a relativistic formula

$$\begin{aligned}\mathbf{F}(\mathbf{r}, t) &= \frac{d\mathbf{p}}{dt} = m \frac{d\tilde{\gamma}\mathbf{v}}{dt} \\ &= m \left( \mathbf{v} \frac{d\tilde{\gamma}}{dt} + \tilde{\gamma}\mathbf{a} \right) \\ \mathbf{F}(\mathbf{r}, t) &= m\tilde{\gamma} \left( \mathbf{a} + \tilde{\gamma}^2 \tilde{\boldsymbol{\beta}} (\tilde{\boldsymbol{\beta}} \cdot \mathbf{a}) \right)\end{aligned}$$



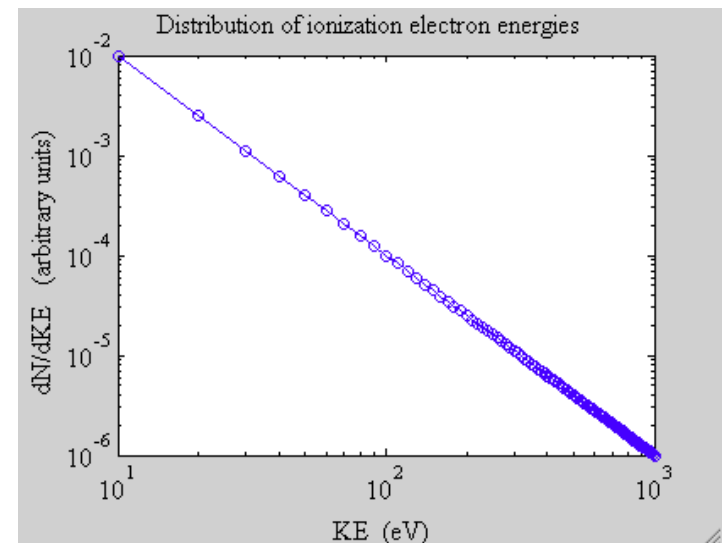
$$\begin{aligned}\mathbf{a} &= \frac{1}{\tilde{\gamma}m(1 + \tilde{\gamma}^2 \tilde{\boldsymbol{\beta}}^2)} \left[ \mathbf{I} + \tilde{\gamma}^2 (\tilde{\boldsymbol{\beta}}^2 \mathbf{I} - \tilde{\boldsymbol{\beta}} \tilde{\boldsymbol{\beta}}^T) \right] \mathbf{F} \\ &= \frac{1}{\tilde{\gamma}m} \left[ \mathbf{I} - \frac{\tilde{\gamma}^2}{(1 + \tilde{\gamma}^2 \tilde{\boldsymbol{\beta}}^2)} \tilde{\boldsymbol{\beta}} \tilde{\boldsymbol{\beta}}^T \right] \mathbf{F} \\ \mathbf{a} &= \frac{1}{\tilde{\gamma}m} \left[ \mathbf{I} - \tilde{\boldsymbol{\beta}} \tilde{\boldsymbol{\beta}}^T \right] \mathbf{F}\end{aligned}$$

# Matlab Simulation

- Once the acceleration is determined, a discrete evaluation of the differential equation of motion is used to step the particles
- The magnetic and electric fields are handled separately
  - Magnetic contribution to the motion is only applied to the components perpendicular to the B field
  - Magnitude of the velocity perpendicular to the B field is forced to be preserved, since the B field does no work
    - This in particular helps with the tight spirals along the field lines

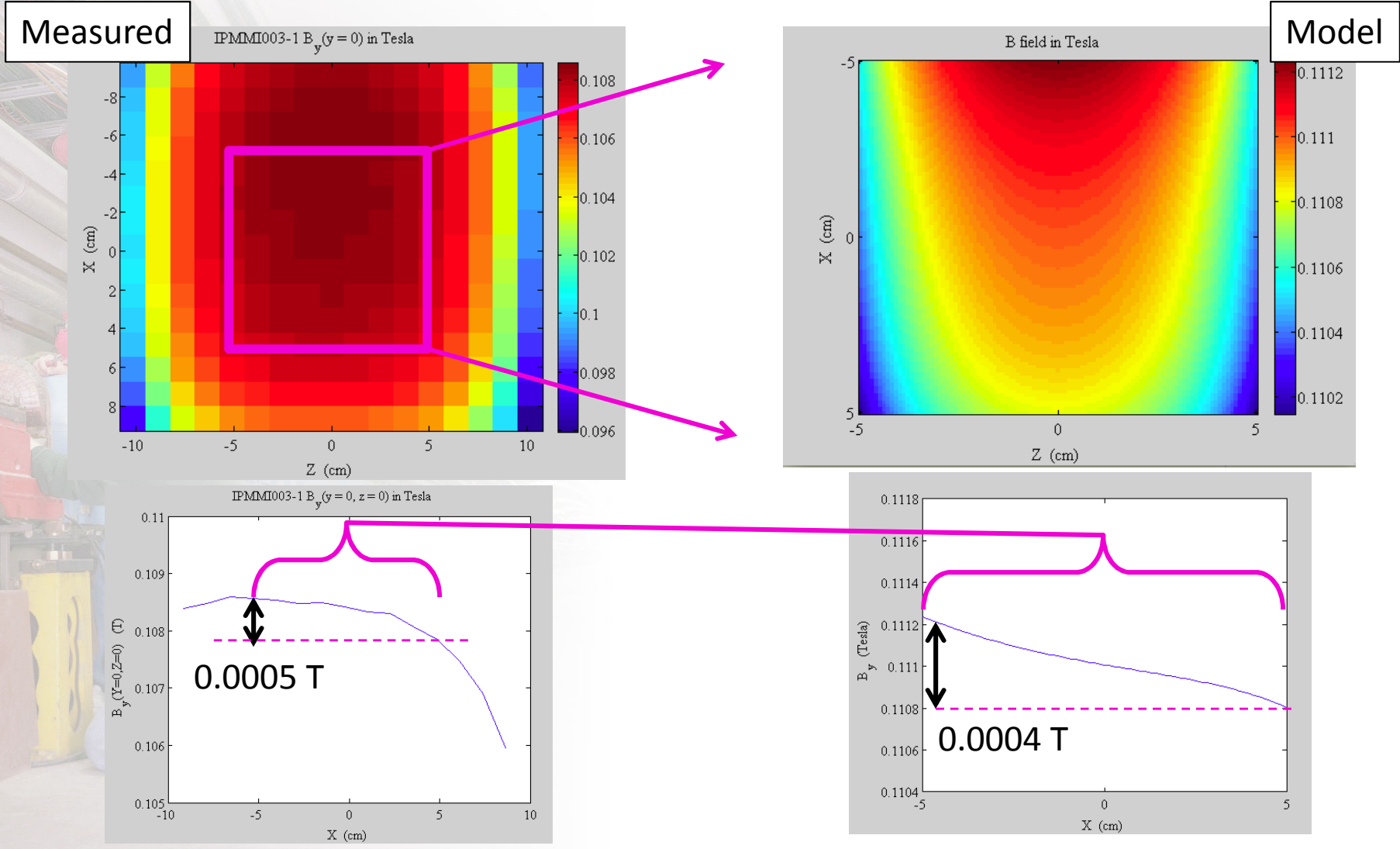
# Matlab Simulation

- The electric and magnetic fields of the bunch are calculated before hand for various bunch parameters
  - Shifted as a function of time to represent the moving beam
- Electric field of IPM from a Poisson calculation
- Magnetic field from 3-D magnet model
- Ionized particle distributions are random in emission angle with  $1/E^2$  energy distribution →

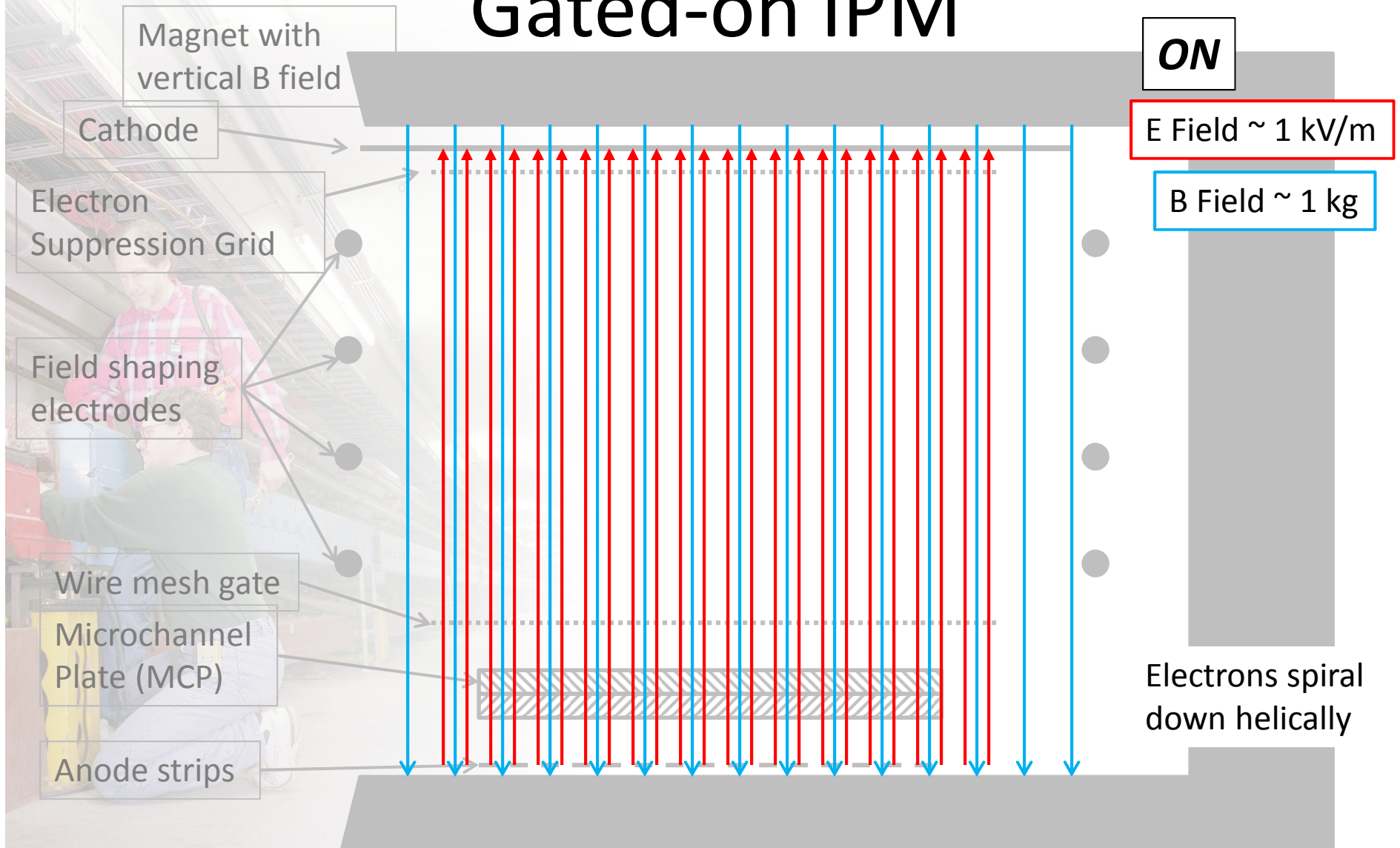




# Magnetic Field in Simulation



# Gated-on IPM

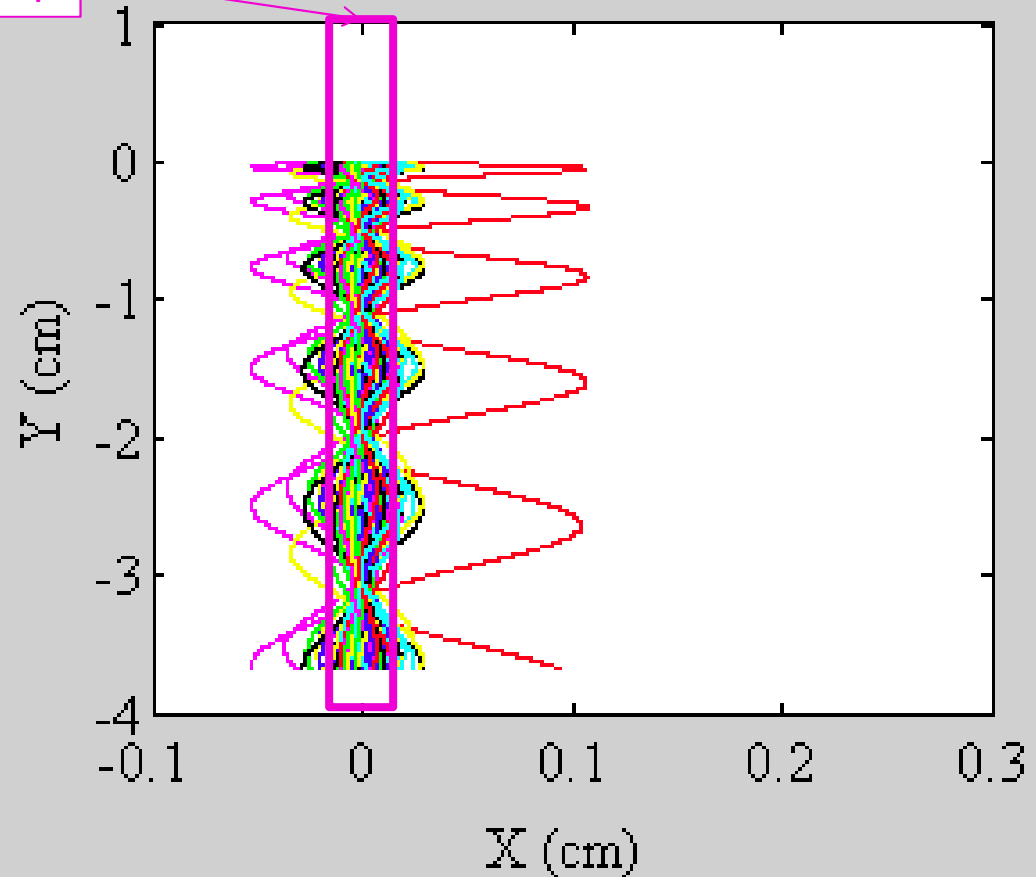


# Gated-on IPM

Particles originating from single point (resolution contribution)

Elapsed time  $\sim 1.7$  ns

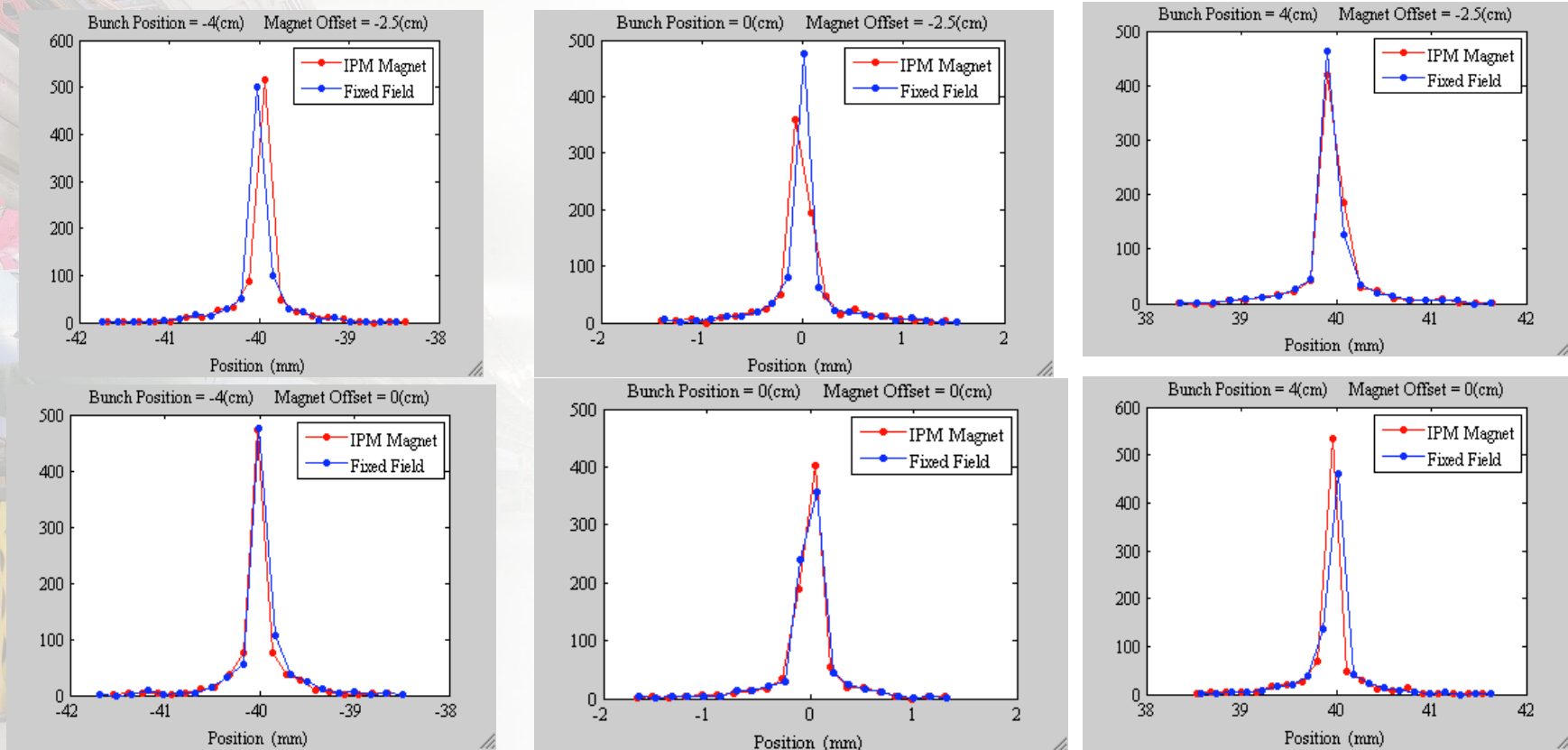
Anode Strip



# Gated-on IPM

Particles originating from single point  
(resolution contribution)

Bunch offset refers to x



# Gated-on Expected Signal

- From figure 7 of Sauli #, the number of primary ion pairs produced in one centimeter of a gas species  $i$  at one atmosphere of pressure by one minimum ionizing particle can be roughly parameterized as

$$n_i \approx \frac{3}{2} Z_i$$

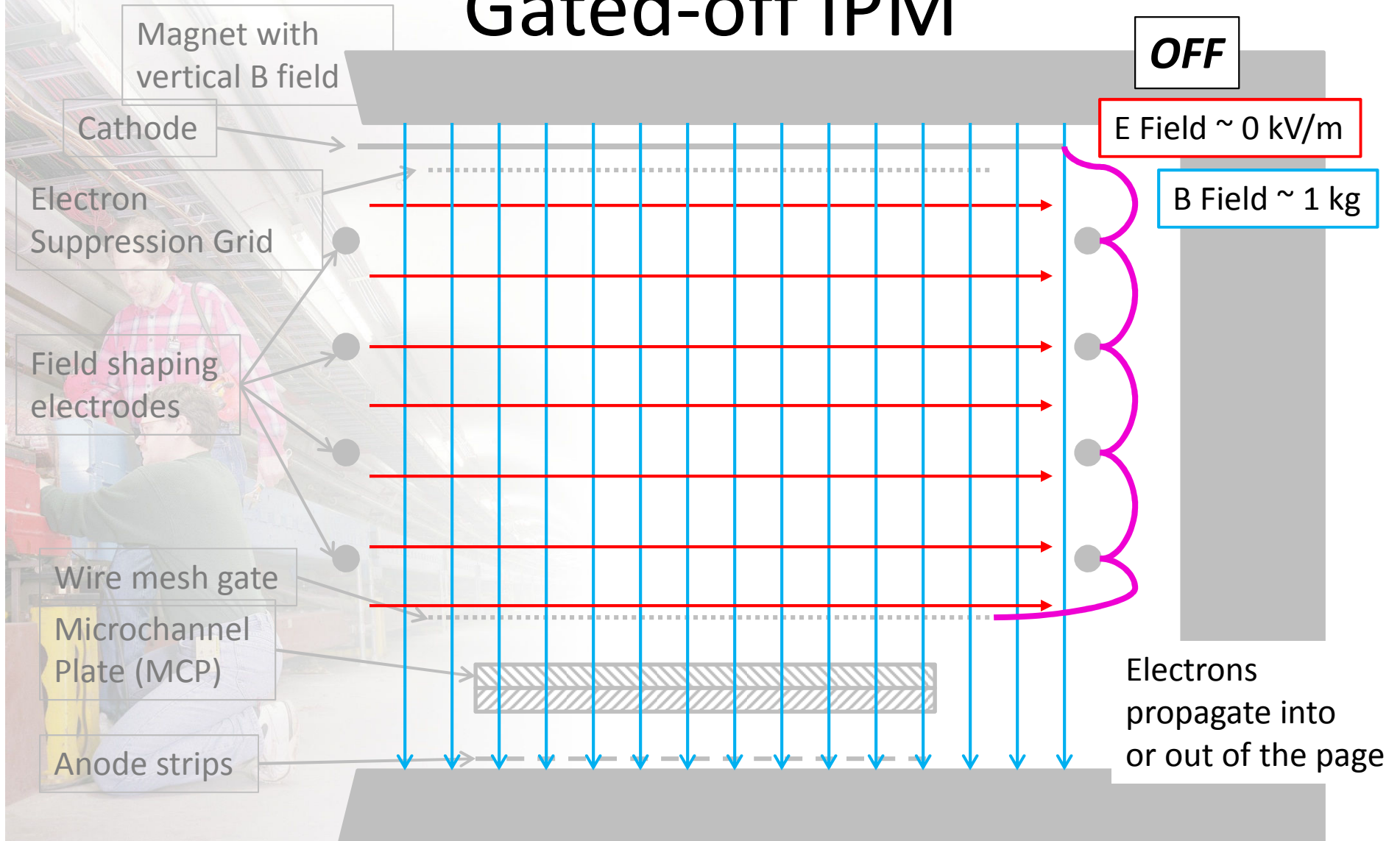
- Expressing this in terms of the proton bunch parameters and partial pressures in the beampipe one arrives at

$$n_j(t) \approx \frac{QL\delta}{500e\sigma_T\sigma_t2\pi} \left[ e^{-\frac{(j\Delta)^2}{2\sigma_T^2}} \right] \left[ e^{-\frac{t^2}{2\sigma_t^2}} \right] \sum_i Z_i P_i$$

- At the peak of a Main Injector bunch, the number of ionization electrons is **~10** per anode strip (no MCP gain)

#F. Sauli, "Principles of Operation of Multiwire Proportional and Drift Chambers", CERN 77-09, 3/5/77.

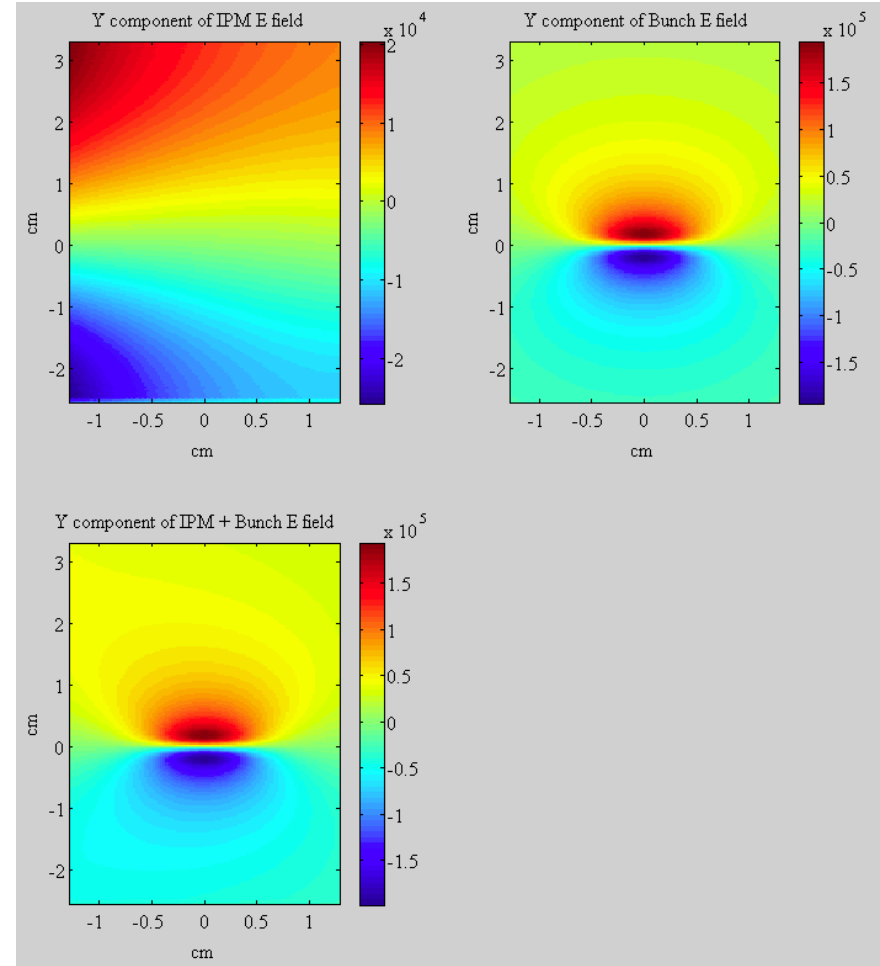
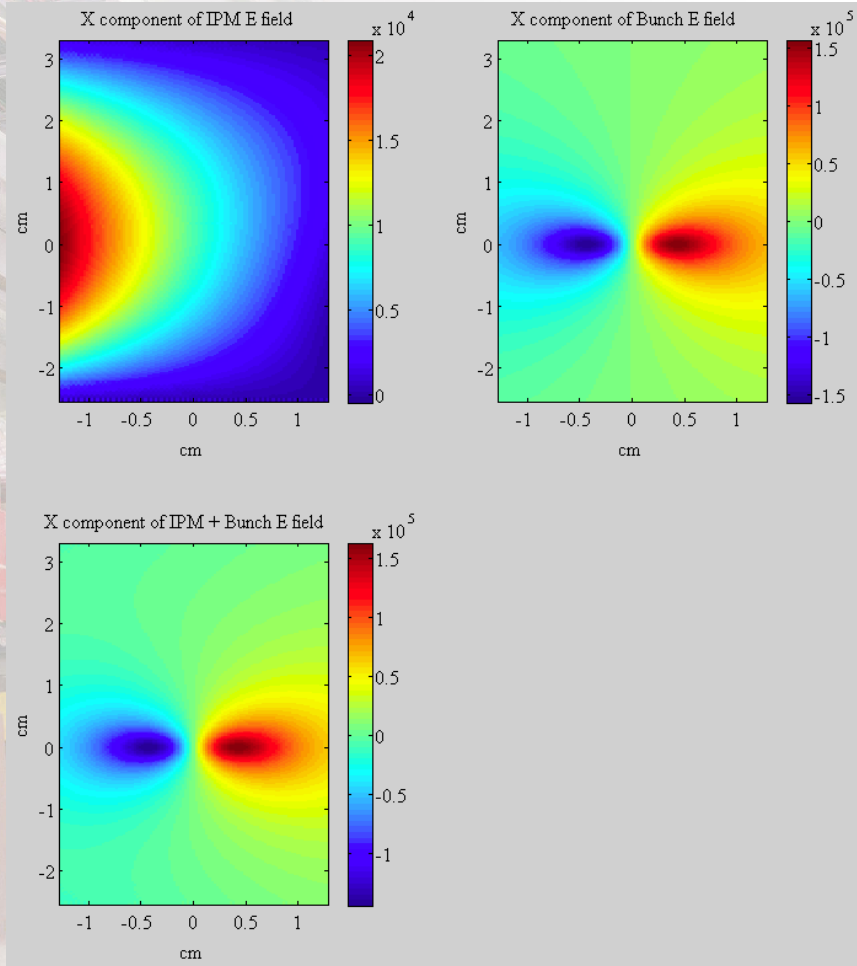
# Gated-off IPM



# Gated-off Fields

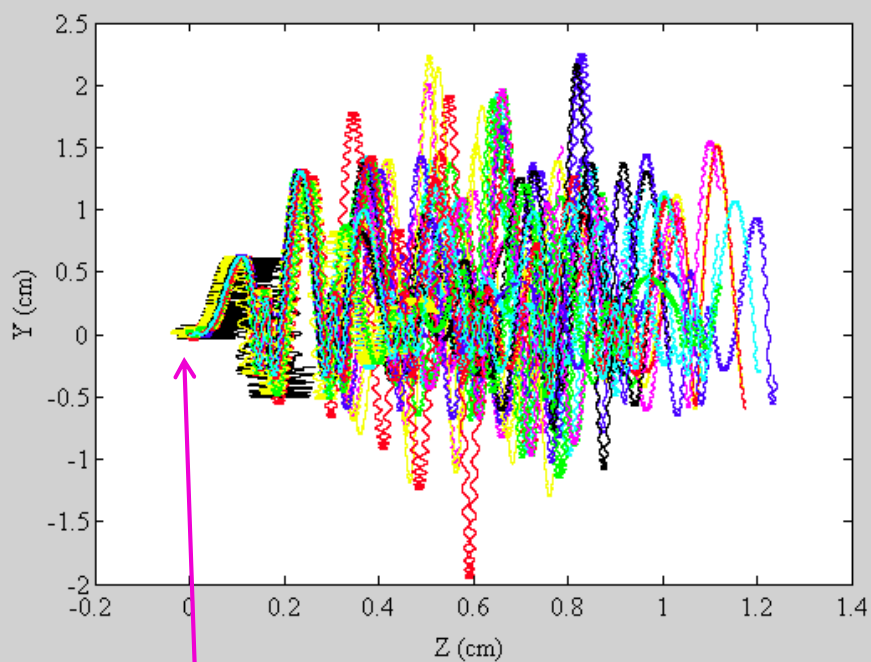
X Component of E field

Y Component of E field



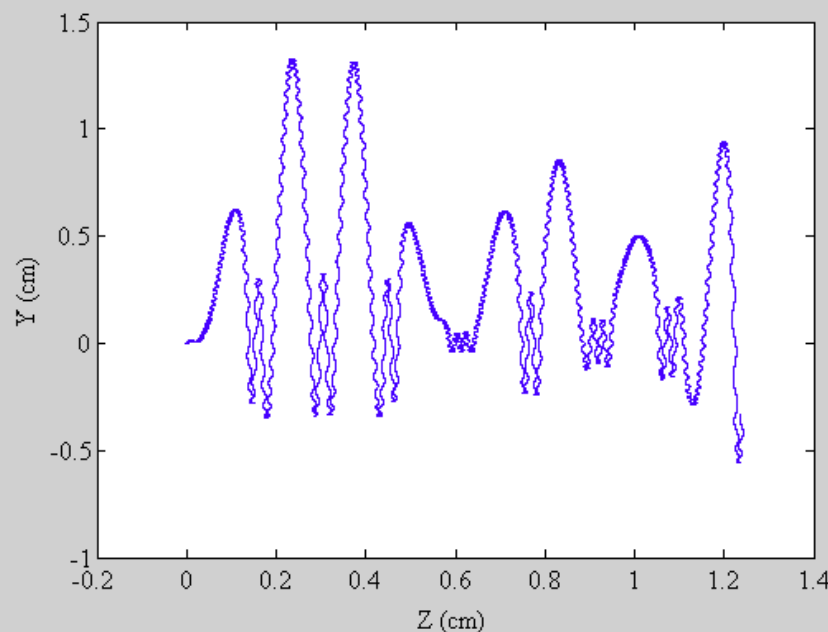
# Gated-off Motion

Electron drift along beam direction



Particle origination point

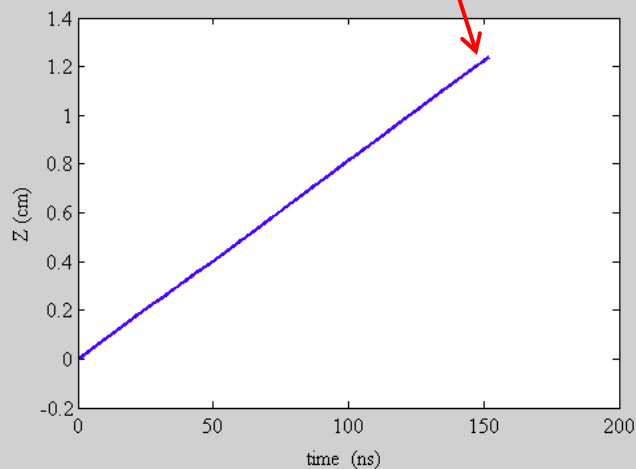
Single particle



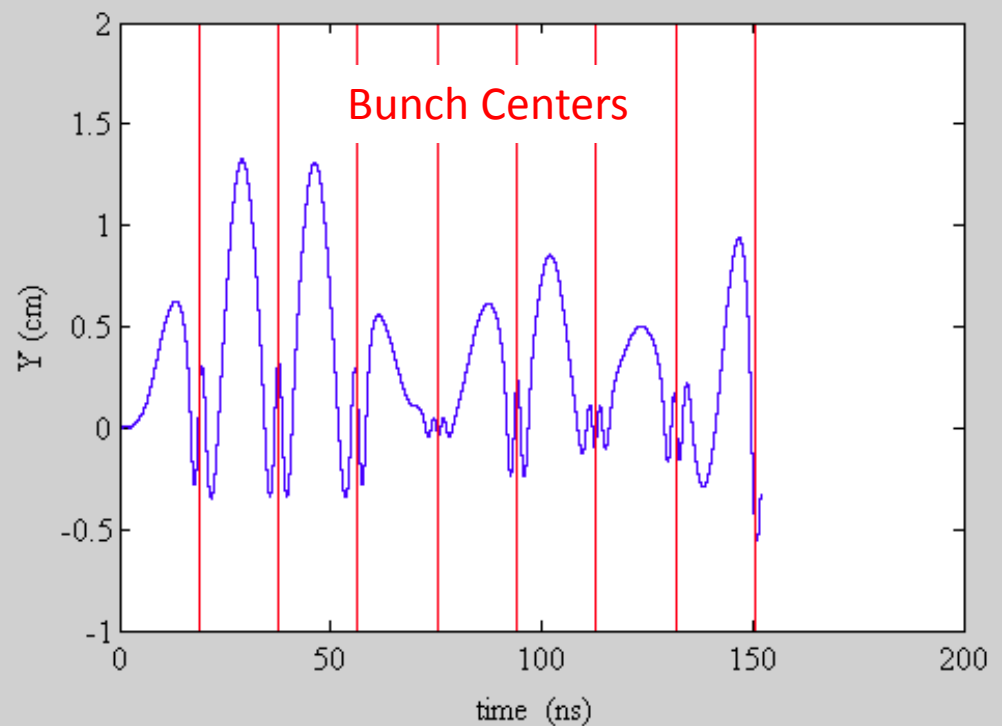


# Gated-off Behavior

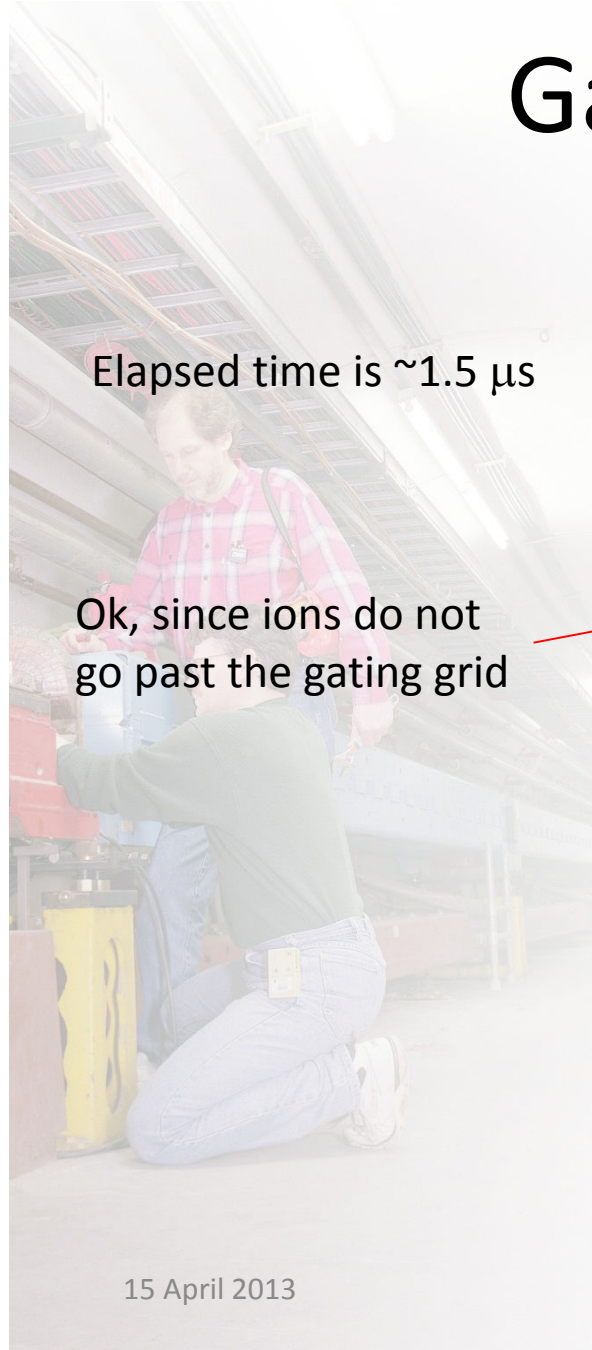
Drift Velocity  
 $1.2 \text{ cm} / 150 \text{ ns} = 8 \text{ cm}/\mu\text{s}$   
 Compared to  
 $10 \text{ cm}/\mu\text{s}$  analytically  
 estimated



Y motion vs time

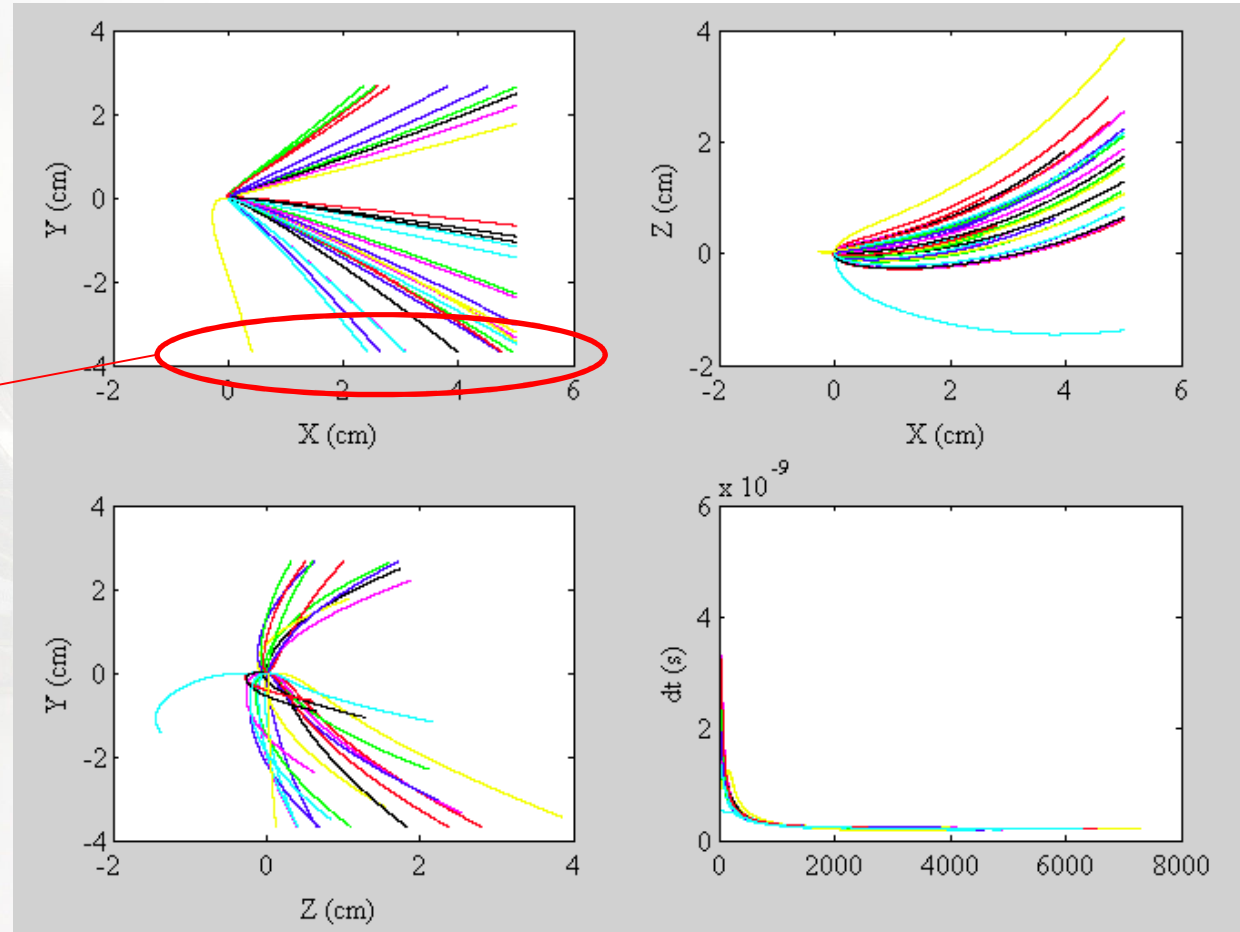


# Gated-off Ion Paths



Elapsed time is  $\sim 1.5 \mu\text{s}$

Ok, since ions do not go past the gating grid



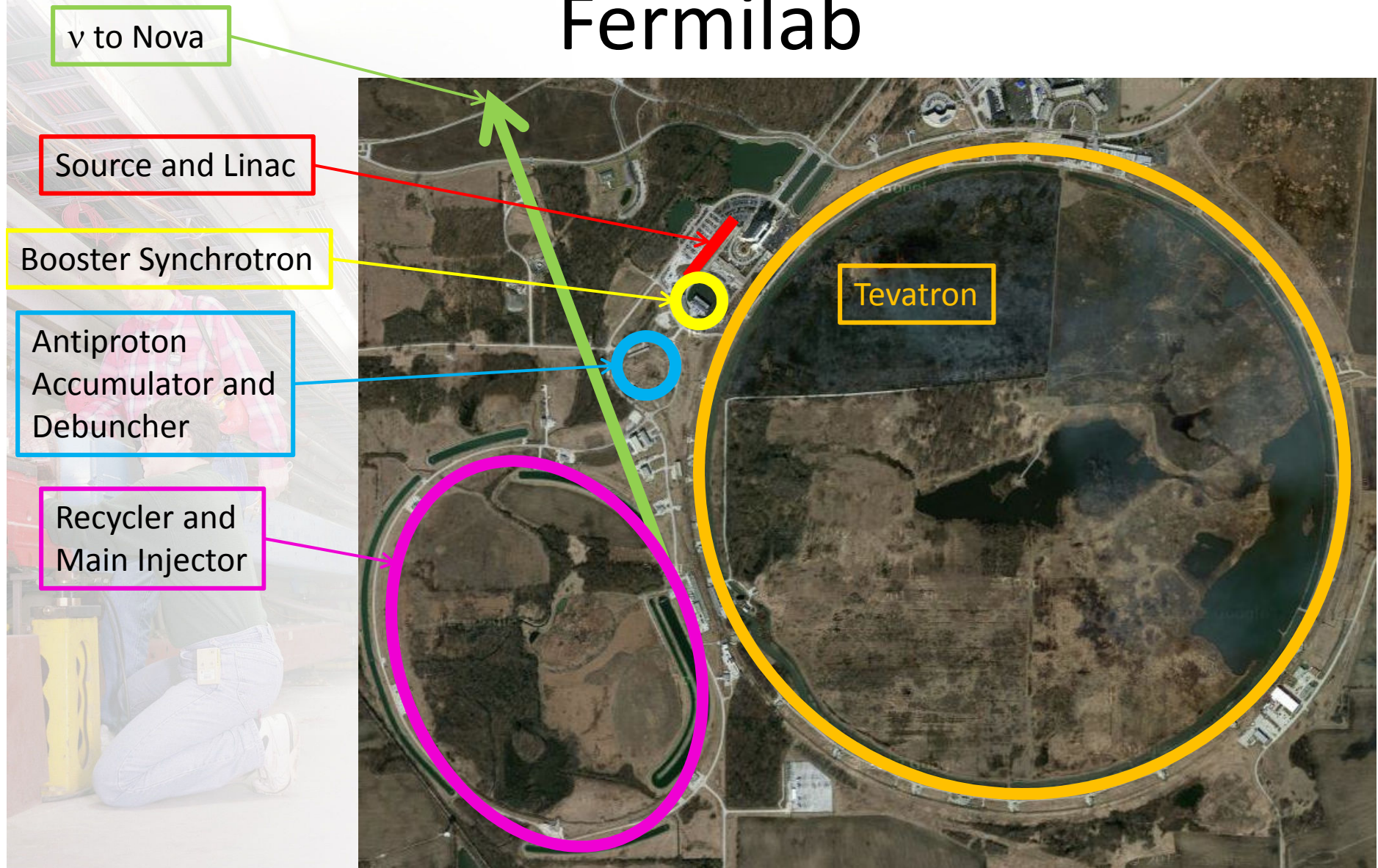
# Conclusions

- Where do the electrons go when they reach the edge of the E field region?
  - Need 3-D E field calculation

# Extras

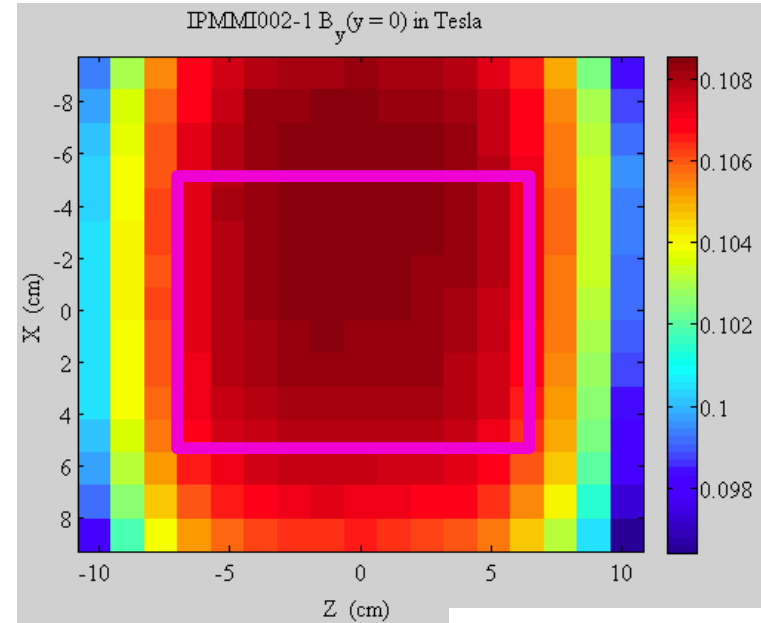
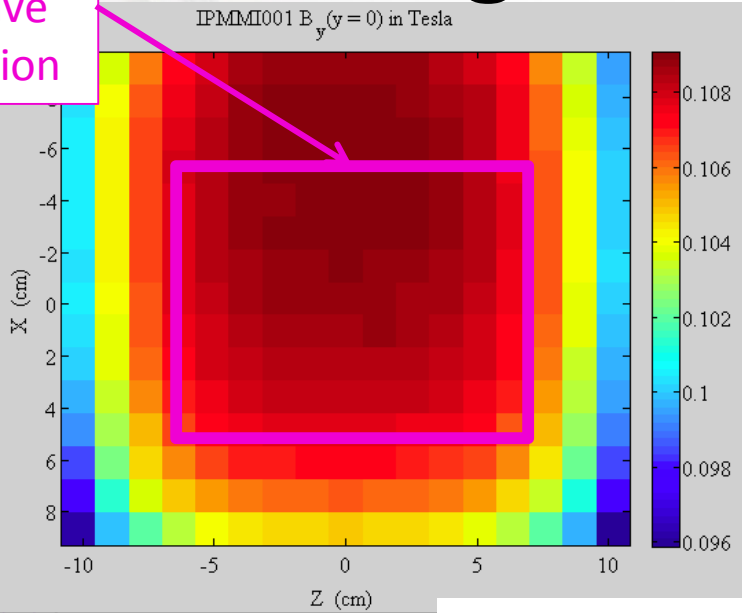


# Fermilab

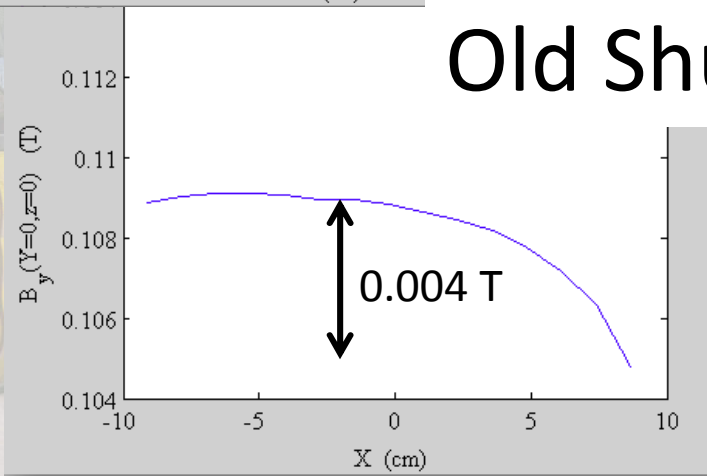


# Magnet Measurements

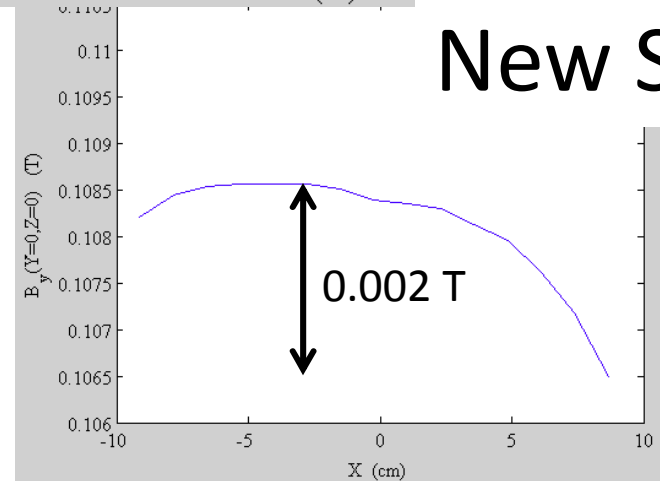
IPM  
Active  
Region



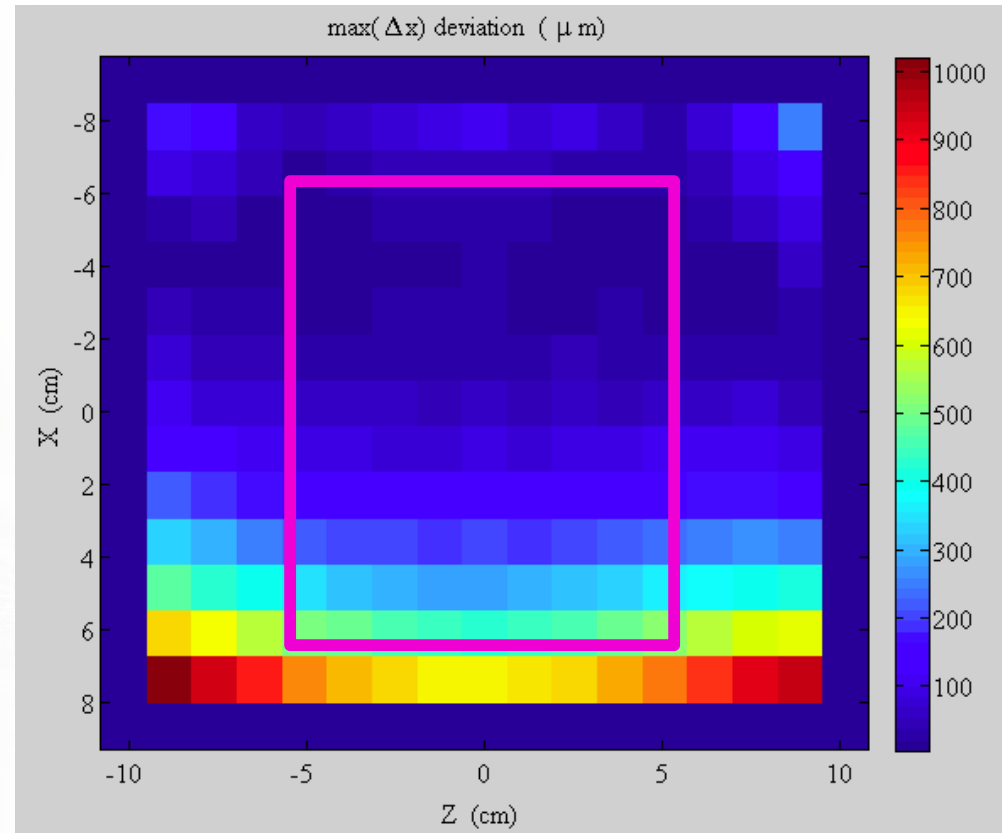
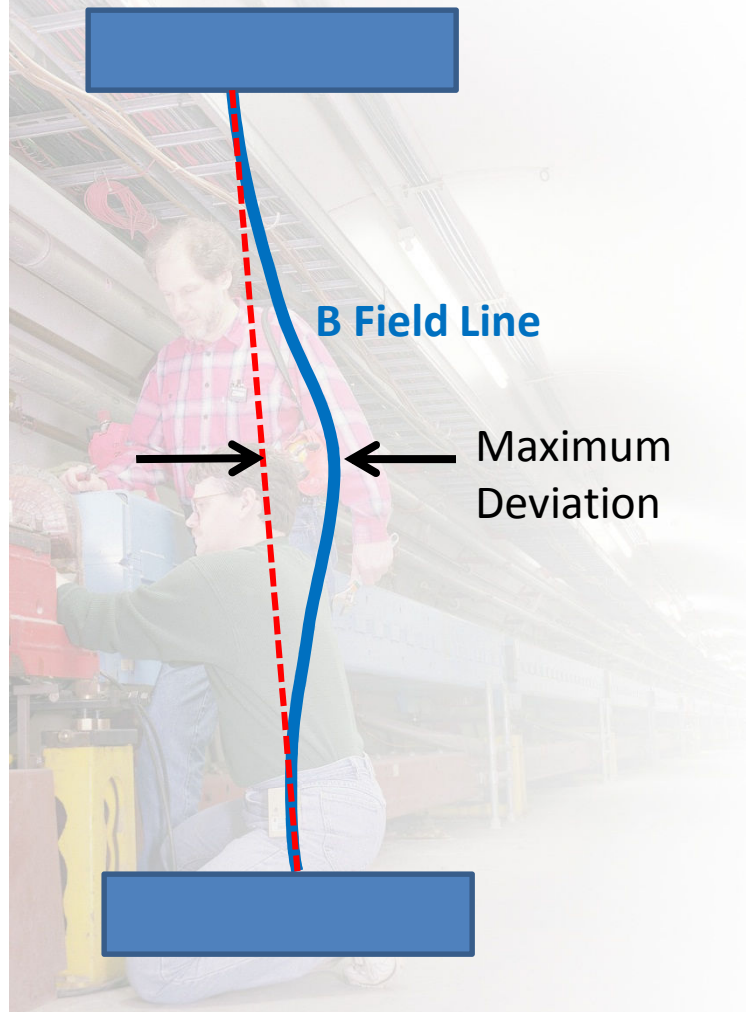
Old Shunt



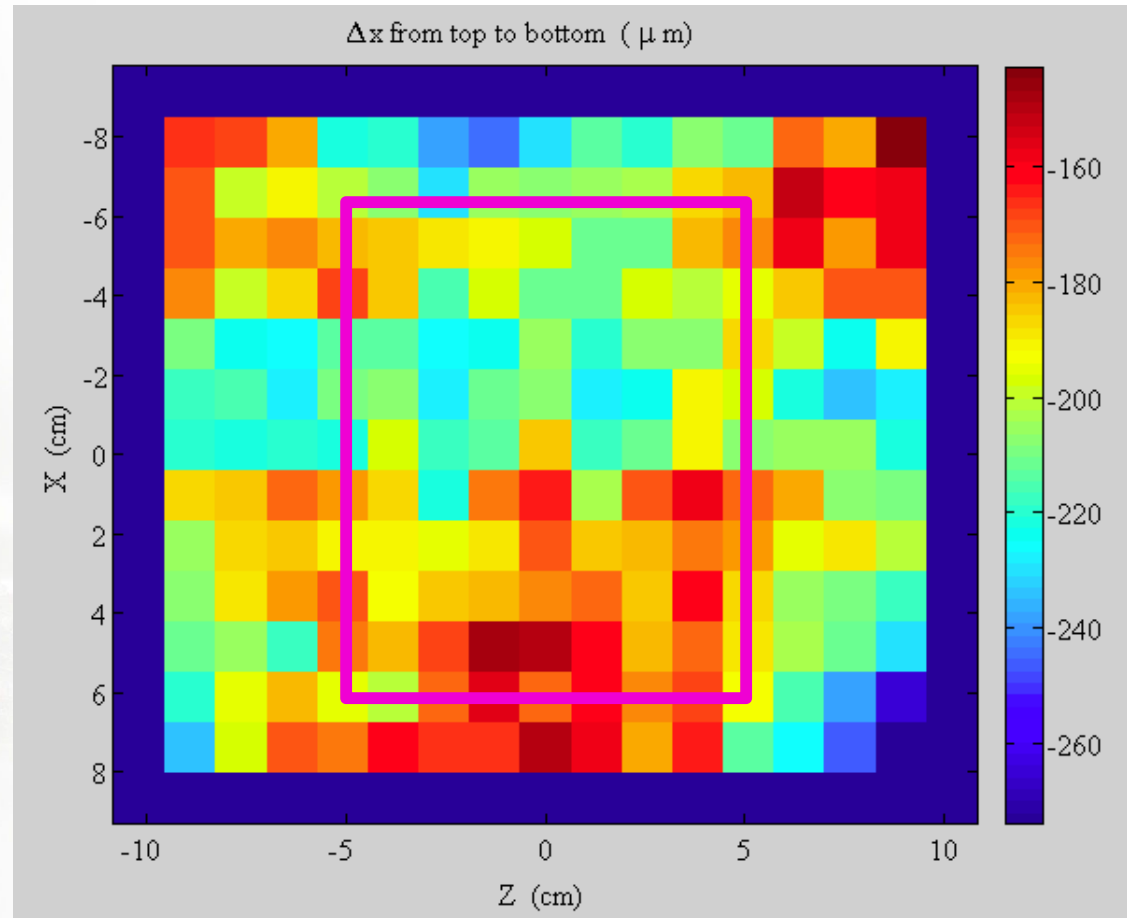
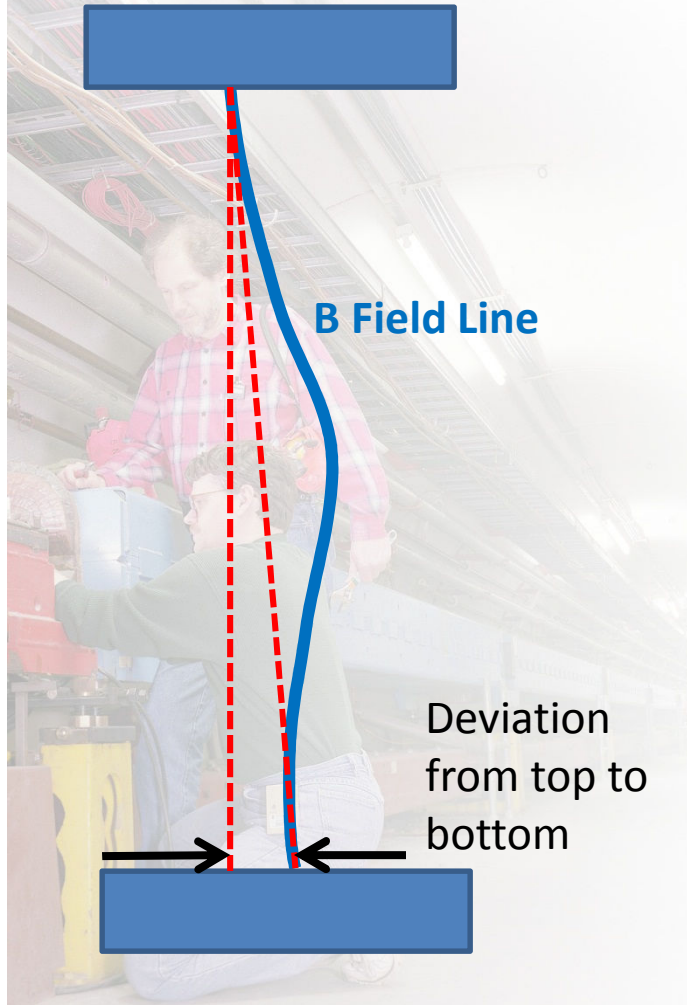
New Shunt



# Magnet Measurements



# Magnet Measurements



Average value of  $200 \mu m$  could be hall probe rotation; corresponds to  $\sim 0.1$  degrees



# MI Orbit Perturbation

- Measured magnet integrated field is  $\sim 0.001 \text{ T}\cdot\text{m}$
- Maximum displacement around the ring for the measured field integral is

$$D = \frac{\int B_y dl}{\rho_m} \frac{\beta}{2 \sin \pi \nu}$$

- For the Main Injector  $\rho_m \sim 27 \text{ T}\cdot\text{m}$  and the maximum  $\beta$  is 50 and the tune,  $\nu$ , is 0.43  
 –  $D \sim 0.001 \text{ m}$