## The First Experience of Crab Crossing at KEKB

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#### Table 1: Machine parameters of KEKB

Date	11/15/2006		Design		
	LER	HER	LER	HER	
Current	1.65	1.33	2.6	1.1	A
Bunches/ring	13	89	50	000	
Bunch current	1.19	0.96	0.52	0.22	mA
Bunch spacing	1.8-	-2.4	C	).6	m
Emittance $\varepsilon_x$	18	24	18	18	nm
$eta_x^*$	59	56	33	33	cm
$eta_y^*$	0.65	0.59	1.0	1.0	cm
Hor. size @ IP	103	116	77	77	$\mu m$
Ver. size @ IP	1.9	1.9	1.9	1.9	$\mu m$
Beam-beam $\xi_x$	0.115	0.075	.039	.039	
Beam-beam $\xi_y$	0.101	0.056	.052	.052	
Bunch length	7	6	4	4	mm
Luminosity	17	.12		10	/nb/s
∫Lum./day	(12)	32	$\sim$	600	/pb
$\int \text{Lum.}/7 \text{ days}$	7.	82		_	/fb
$\int \text{Lum.}/30 \text{ days}$	30	.21			/fb

70% higher than the design

doubled the design

### The power of Continuous Injection Mode



KEKB has 22 mrad horizontal crossing angle at the IP:

- •Easier beam separation
- •Simpler design around the IP.
- •Less number of components.
- •Less synchrotron radiation.
- •Less luminosity-dependent background.
- •Space for compensation solenoid, etc.





## Crab Crossing @ KEKB



### More gain than geometrical overlap is expected: Head-on + hor. half integer tune = 10 + synchrotron motion



head-on: beam distribution is symmetric in x.

The beam-beam force becomes nearly independent on x at horizontal half integer and with head-on collision (Ohmi & Perevedentsev)

# Single Crab Cavity Scheme



•Beam tilts all around the ring.

z-dependent horizontal closed orbit.

•tilt at the IP:

$$\frac{\theta_x}{2} = \frac{\sqrt{\beta_x^C \beta_x^*} \cos(\psi_x^C - \mu_x/2)}{2\sin(\mu_x/2)} \frac{V_C \omega_{\rm rf}}{Ec}$$

Table 1: Typical parameters for the crab crossing.

Ring	LER	HER	
$\theta_x$	22		mrad
$\beta_x^*$	80	80	cm
$\mid \beta_x^C$	73	162	m
$\mu_x/2\pi$	0.505	0.511	
$\psi_x^C/2\pi$	$\sim 0.25$	$\sim 0.25$	
$V_C$	0.95	1.45	V
$\omega_{\rm rf}/2\pi$	509		MHz

\* saves the cost of the cavity and cryogenics.

\* avoids synchrotron radiation hitting the cavity.

#### Crab Cavity & Coaxial Coupler in Cryomodule





- \* Phase stability of the crab mode was better than the requirement with the rf feedback.
- \* Slow stability below 1 Hz is shown above.

\* Independent measurement by a spectrum analyzer shows better than 0.01 deg for f > 2 kHz, 0.1 deg for 2 Hz < f < 2 kHz.

\* Backlash or friction exists in the coaxial tuner for the LER.

## Phase stability

- \* Spectrum of pick up signal is consistent with phase detector data.
- \* Phase fluctuation faster than 1 kHz is less than ±0.01°, and slow fluctuation from ten to several hundreds of hertz is about ±0.1°.
- \* They are much less than the allowed phase error obtained from the beam-beam simulations for the crabbing beams in KEKB.

According to b-b simulation by Ohmi-san, allowed phase error for N-turn correlation is  $0.1 \times \sqrt{N}$  (degree).



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K. Akai

LER crab cavity. Beam current was between 450 and 600 mA.

## Finally two crab cavity was installed in KEKB, one for each ring in January 2007.



HER (e-, 8 GeV)

LER (e+, 3.5 GeV)

## Crab Crossing Started at KEKB First time in the world!

- \* A number of checks have confirmed the effective head-on collision:
  - · streak camera
  - · crab-phase scan
  - sign change and scan of crab voltage
  - horizontal beam-beam kick
  - · vertical crabbing
- The highest vertical beam-beam tune-shift parameter is about 0.088 so far, which is higher than the geometrical gain due to head-on by 15%.
- Due to the low-current operation with longer bunch spacing (98 ns), the effect from electron cloud has been negligible.
- \* There are a few issues are speculated for the reason why the luminosity is lower than the prediction, but not yet confirmed.





#### Number of trips per cavity per ring. From March/1 to June/22 (114days)



Green line shows the maintenance day. Black line shows the warm-up period.







#### Sign Change in the Crab Angle H. Koiso



## V<sub>crab</sub> Scan (HER)

H. Koiso



#### **Vertical Crabbing ?**

H. Koiso



Vertical size dependence on the vertical crossing angle should be symmetric around the vertical head-on collision.

## **Specific Luminosity**



- \* A number of measurements indicate effective head-on collision.
- \* The vertical tune shift became higher than 0.088. Before crab, it was 0.055.
- The specific luminosity / bunch was improved more than the geometrical gain.
- \* Need more time to achieve the goal (X2 specific luminosity).

# Why the specific luminosity drops faster than expected?

## Speculations:

- \* Lifetime may be limited by the dynamic- $\beta$  and
  - dynamic emittance caused by bea-beam.
- \* Electron Cloud in the LER: Luminosity becomes better for longer bunch spacing.
- \* The SPOOABS nature in the optimum condition of the collision: Too many parameters.
- \* Synchrotron-betatron resonance near 1/2 integer.
- \* .. and more ..

## LER dynamic-ß and emittance



45.506

43.57

.0059

.9

.09

.1

-LER

 $v_{\mathbf{x}}$ 

 $\nu_{\rm v}$ 

β<sub>8</sub> [m]

β<sub>y</sub> [m]

ξ<sub>s</sub> max

 $\xi_{\nu}$  max

The focusing force of the beam-beam interaction not only squeezes the beam at the interaction point, but increases the emittance drastically.

Y. Funakoshi



#### The lifetime may be limited by the dynamic beta effect.



Y. Funakoshi

#### **Specific Luminosity becomes better for longer bucket spacing. Due to e-cloud?**



## Too many tuning knobs?

Table 3: Tuning knobs for the crab crossing and their observables. Many depend only on the beam size  $\sigma_y$  at the synchrotron radiation monitor (SRM), besides the luminosity  $\mathcal{L}$ .

Knob	Observable	frequency: every
Relative beam offset IP	Beam-beam kick measured by BPMs around the IP	1 sec
Relative beam angle IP	BPMs around the IP	1 sec
Global closed orbit	All $\sim 450 \text{ BPMs}$	15 sec
Beam offset at crab cavities[11]	BPMs around the crab cavity	1 sec
Betatron tunes	tunes of non-colliding pilot bunches	$\sim 20 \text{ sec}$
Relative rf phase	center of gravity of the vertex	10 min.
Global couplig, dispersion, beta-beat	orbit response to kicks & rf frequency	$\sim$ 14 days
LER to HER crab voltage ratio	response in the hor. beam-beam kick. vs. crab rf phase	$\sim$ 7 days
Rf phase of crab cavity	hor. kick vs. crab voltage response	$\sim$ 7 days
Vertical waist position	$\mathcal{L}$ and $\sigma_y$ at the SRM	$\sim 1 \text{ day}$
Local x-y couplings and dispersions at IP	$\mathcal{L}$ and $\sigma_y$ at the SRM	$\sim$ 1 day each
Sextupole settings	$\mathcal{L}$ and lifetime	$\sim$ 3 days
X-y coupling parameter at the crab cavities	$\mathcal{L}$ and $\sigma_y$ at the SRM	$\sim$ 3 days
Crab kick voltage	$\mathcal{L}$ and $\sigma_y$ at the SRM	$\sim$ 7 days

Many knobs are determined by scans only on the luminosity, beam sizes, and the lifetime.

Scan is slow, each takes about 30 minutes.

Question in the multi-dimensional nonlinear optimization.

#### sharply-peaked-optimum-on-a-broad- shoulder (SPOOABS)

An example: the Horizontal Offset and the crossing angle at the IP
Luminosity
beam-beam kick



 Luminosity degrades by a small error in any one of the collision parameters. The horizontal offset of two beams and the crossing angle at the IP are such an example.

- Horizontal offset must be much less than 25  $\mu\text{m}$ , and the crossing angle less than 1.5 mrad to see the effect of crab crossing.
- There are more than 20 of such parameters. If one of them is largely off, the optima of other parameters cannot be found.

## **Downhill simplex method**

 $\begin{array}{c} \mbox{Method of Minimization} \\ \{1, 2, 3\} \ 1(best) < 2(next-to-the worst) < 3(worst) \\ Evaluate \ 3_R \\ \ If \ 3_R < 1, \\ \ If \ 3_E < 3_R, \ \{1, 2, 3_E\}: Expand \ , \ if \ not, \ \{1, 2, 3_R\}: Reflect \\ \ If \ 1 < 3_R < 2, \ \ \{1, 2, 3_R\}: Reflect \\ \ If \ 2 < 3_R < 3, \ Reflect \ 2 \ \ proposed \ by \ A. \ Hutton \\ \ If \ 3_{C+} < 3_R, \ \{1, 2, 3_{C+}\}: Contract+ \ , \ if \ not, \ \{1, 2, 3_R\}: Reflect \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ 3 < 3_R \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R, \ Reflect \ 2 \\ \ If \ 3 < 3_R \ Reflect \ 2 \\ \ If \ 3 < 3_R \ Reflect \ 2 \\ \ If \ 3 < 3_R \ Reflect \ 3 < 3_R \ Reflect \ 2 \ Reflect \ 3 < 3_R \ Reflect \ 3 \ Reflect \ 3$ 

• If  $3_{C-} < 3$ ,  $\{1, 2, 3_{C-}\}$ : Contract-, if not,  $\{1, 2_S, 3_S\}$ : Shrink/Reflect2



## Luminosity optimization (Dec. 2)

**Current Simplex (Graphic View)** 



## Issue 3: Synchrotron-betatron resonance



## Finding better sextupole setting: "bungee jump"



## Vertical emittance small enough?



# Summary

The crab cavities were successfully produced and installed at KEKB.

No serious problem has been seen for the crab cavities in the beam operation since Feb. 2007.

Single crab cavity scheme is working fine.

Effective head-on collision was achieved.

The crab crossing gave specific luminosity higher than the geometrical gain at least for low bunch current.

No clear reason was confirmed why the luminosity did not reach the predicted value for higher bunch current.

Needs more studies to reach the high luminosity predicted by simulations.