



GEORG-AUGUST-UNIVERSITÄT
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A BLUE implementation in BAT

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Overview

- The problem: combining several measurements with Gaussian uncertainties
- Solutions: BLUE and the Maximum Likelihood method / Bayesian inference
- The implementation in BAT
- Conclusions

The problem:

- Aim: combine several measurements
- Context: TOPLHC WG
- Difficulties:
 - One or several observables, e.g. top-quark mass, W-helicity fractions, etc.
 - Correlations between measurements, e.g. via sources of systematic uncertainty, partially overlapping data sets, etc.
 - Correlations between observables, e.g. W-helicity fractions (sum=1)
 - **Technical problems**

Solutions

- **BLUE: Best Linear Unbiased Estimator**

- Construct weighted average which is
 - linear,
 - unbiased, and
 - has best (smallest) variance

L. Lyons, D. Gibaut, and P. Clifford,
How to combine correlated estimates of a single physical quantity,
Nucl. Instrum. Meth. A 270 (1988) 110.

A. Valassi,
Combining correlated measurements of several different physical quantities,
Nucl. Instrum. Meth. A 500 (2003) 391.

- **ML Method/Bayesian inference:**

- Construct statistical model with Gaussian PDFs including correlations
- Calculate maximum and estimate uncertainty
- Traditionally done using Minuit

Technical problems encountered:

- Limited to 20 input measurements
→ cannot combine all single measurements
- No information about correlation due to individual sources of uncertainty
→ Can not easily combine combinations (arithmetic mean of corr. coefficients)
- Not possible to include constraints (or priors)
→ sum of fractions equals unity
- No proper propagation of uncertainty
→ rely on Gaussian estimate for right-handed fraction (also neg. values)
- No measure for consistency of measurements
→ Quantify agreement of measurements “by eye”
- No uncertainty on correlation coefficients
→ Simple stability checks

All these issues are solved in the BAT implementation



<http://www.mppmu.mpg.de/bat/>

Repeat combination with BAT implementation:

- BLUE results:

- F0: 0.626 ± 0.034 (stat.) ± 0.048 (syst.)

- FL: 0.359 ± 0.021 (stat.) ± 0.028 (syst.)

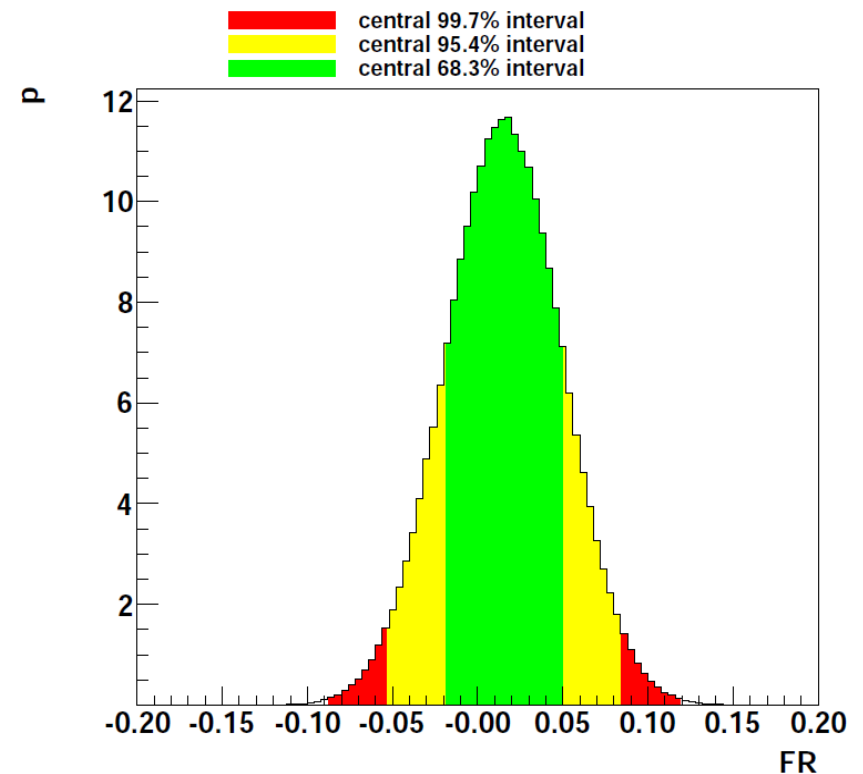
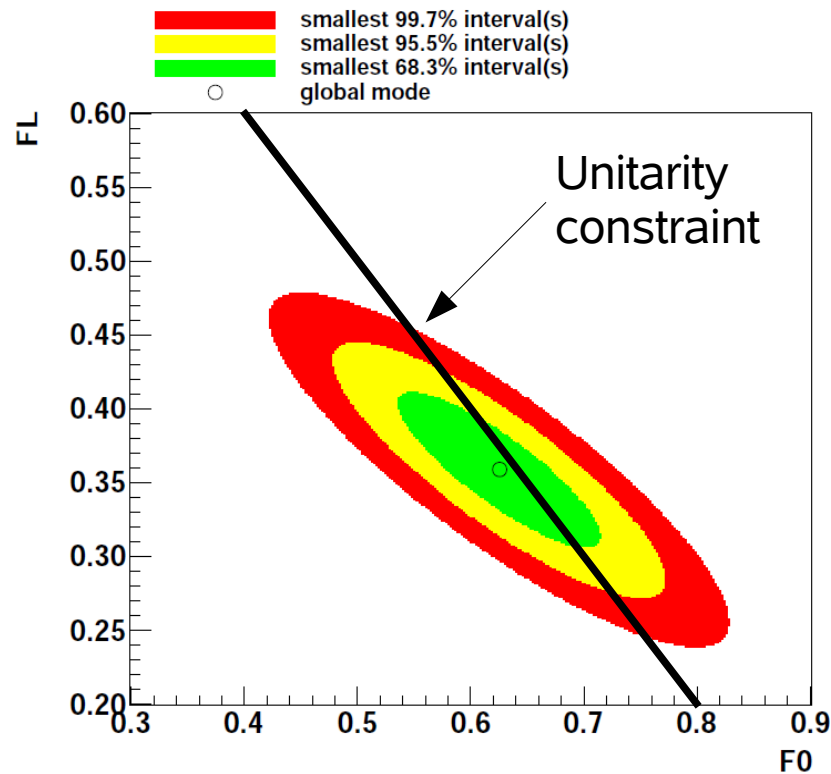
- Weights [%]:

• A10lj	F0:	+12.2	+7.4
• A10lj	FL:	+19.0	+11.6
• A11lj	F0:	+39.4	-8.4
• A11lj	FL:	-16.0	+35.4
• A11dil	F0:	+13.0	+2.8
• A11dil	FL:	+4.9	+15.2
• C11lj	F0:	+35.4	-1.8
• C11lj	FL:	-7.9	+37.8

Same as is note
(rounding)

Repeat combination with BAT implementation:

- ML/Bayesian inference without constraints: same as BLUE

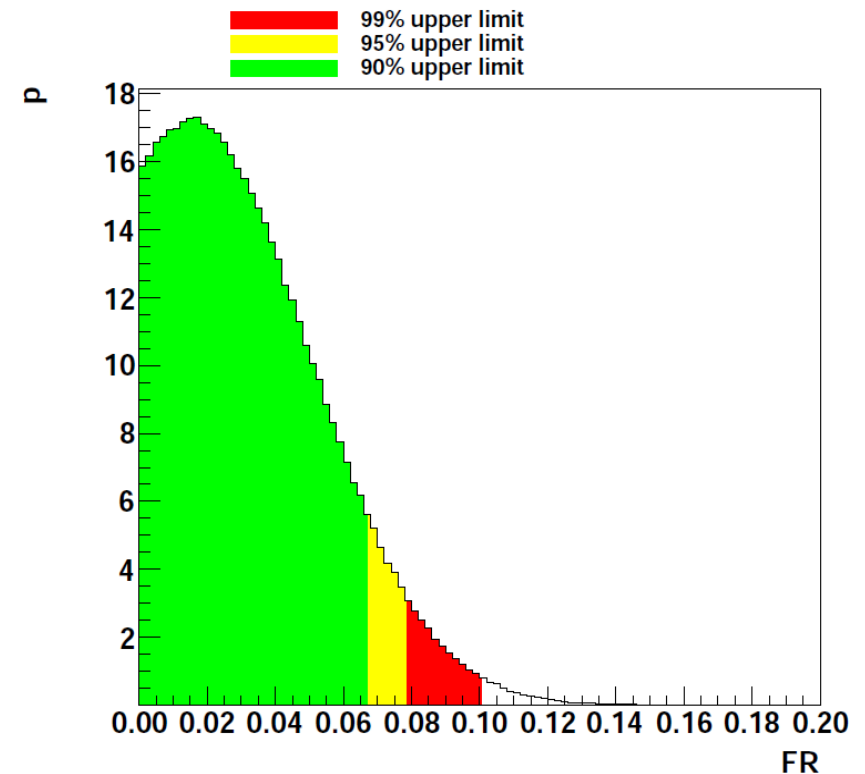
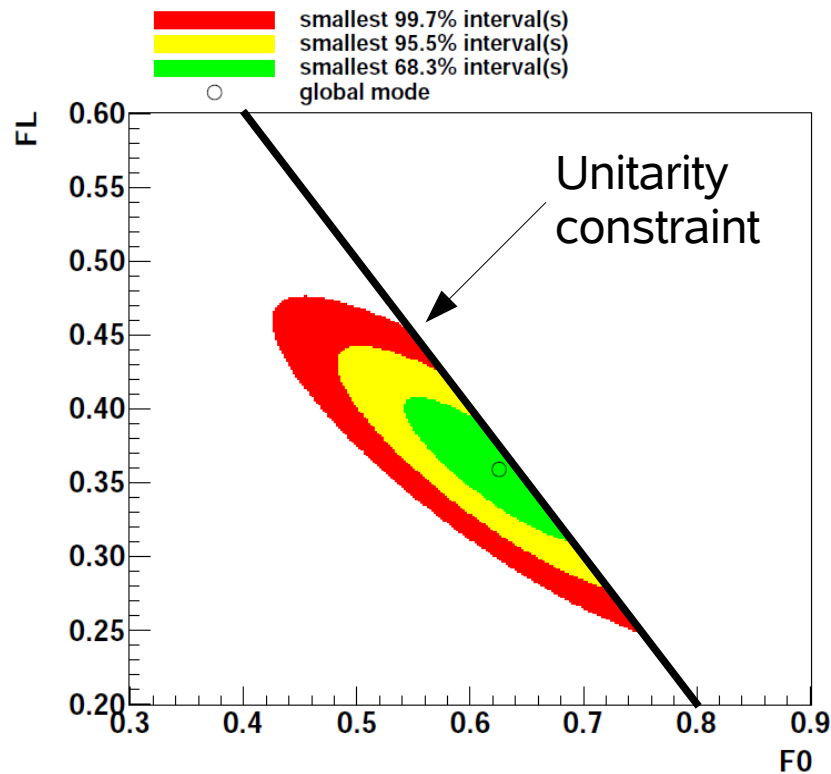


Global mode = BLUE solution

Propagation of uncertainty: FR can be negative

Repeat combination with BAT implementation:

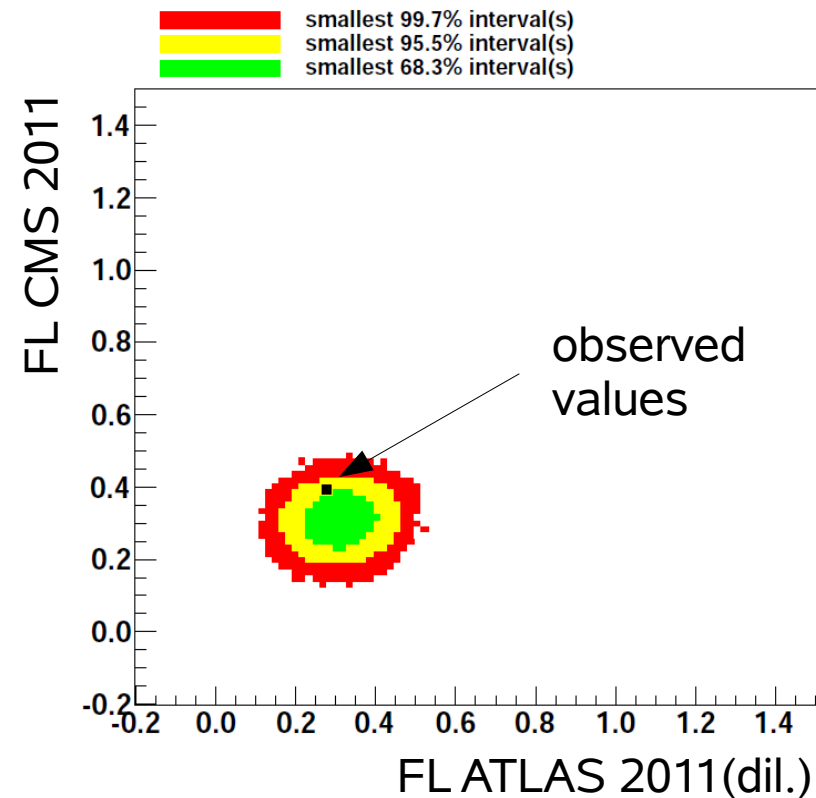
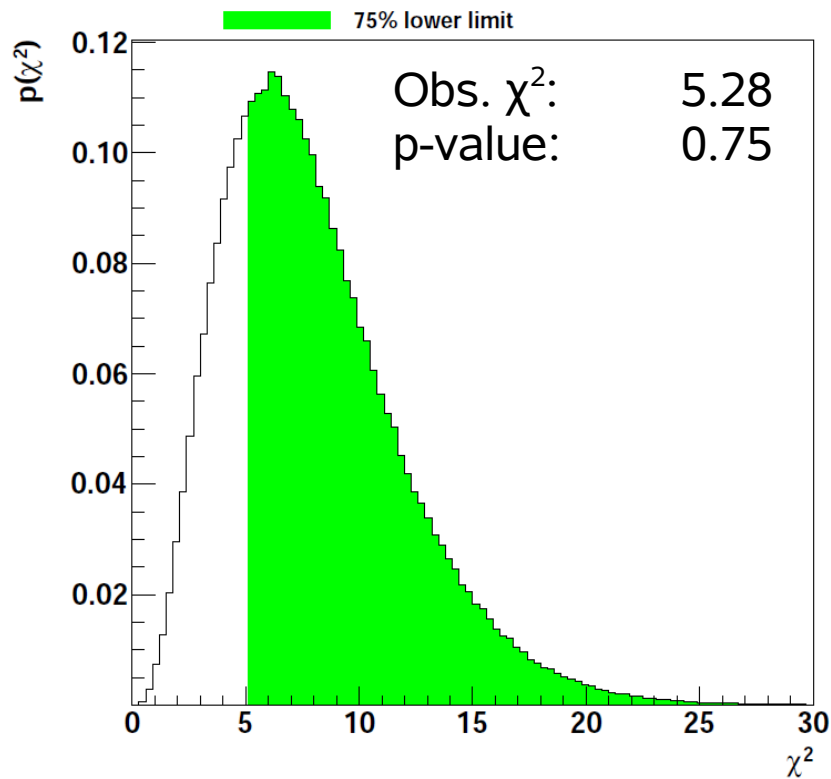
- ML/Bayesian inference with constraints



Non-trivial shape close to the boundary
 Set limits on $FR > 0$, do not quote a measurement

Repeat combination with BAT implementation:

- Goodness-of-fit: assume SM values and throw toys

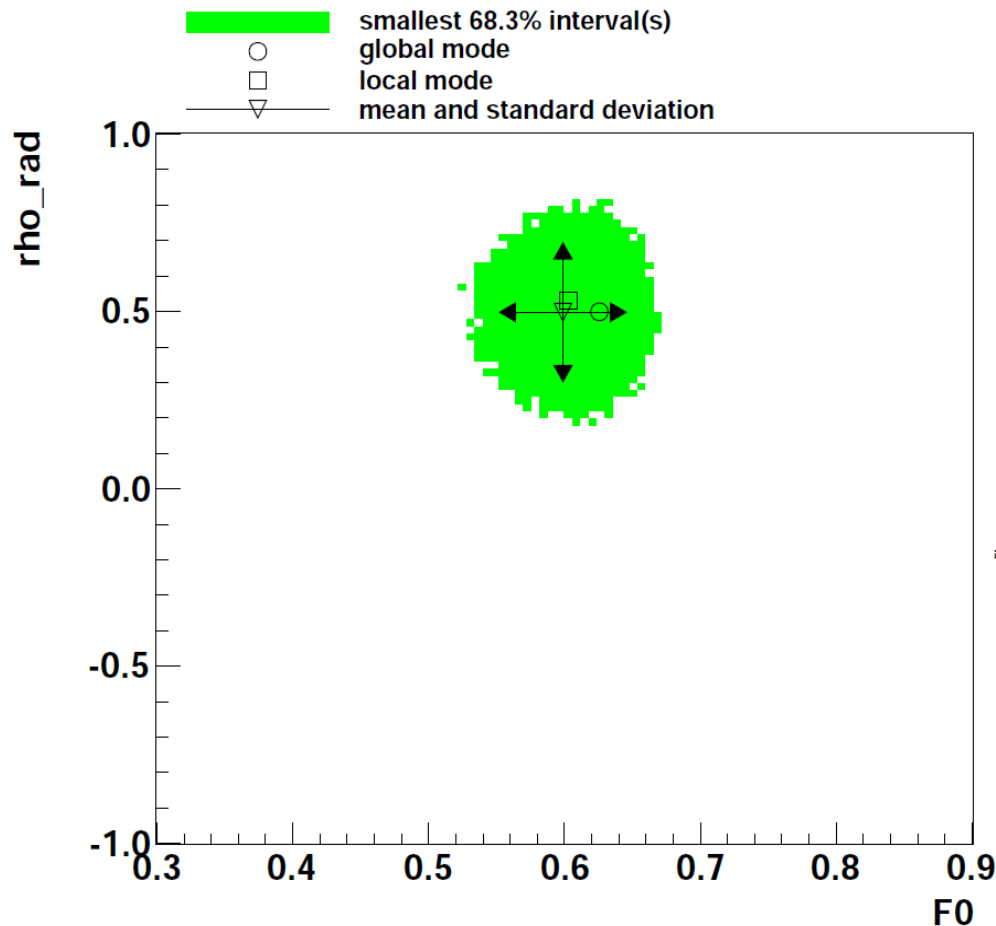


Good overall agreement
Agreement among measurements



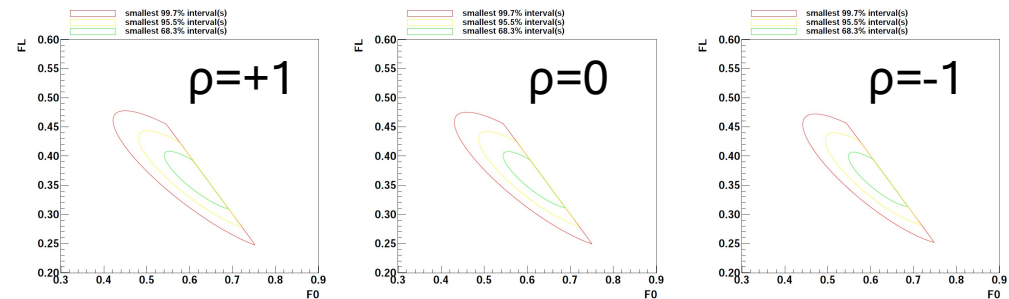
Repeat combination with BAT implementation:

- Parametrize correlation coefficient “Radiation” with nuisance parameter (prior: Gaussian with mean 0.5 and std. 0.2)



No strong dependence on correlation coefficient

Can also produce “slices” with fixed correlation coefficient



Conclusions:

- Features of BAT-implementation:
 - Not limited in the number of input measurements
 - Possible to include constraints and priors
 - Information about correlation due to individual sources of uncertainty
 - (non-Gaussian) Propagation of uncertainty
 - Goodness-of-fit tests:
 - Overall agreement
 - Agreement of individual measurements
 - Correlation coefficients can be parametrized with nuisance parameters
 - Interface is a simple text file (like in previous implementation)
- **Code will be part of next BAT release**
- **If interested now: write me an email**

Physics case:

- Polarization of W bosons in top-quark decays:
 - Two observables, F_0 and F_L

$$\frac{1}{\Gamma} \frac{d\Gamma}{d\cos\theta^*} = \frac{3}{8}(1 + \cos\theta^*)^2 F_R + \frac{3}{8}(1 - \cos\theta^*)^2 F_L + \frac{3}{4} \sin^2\theta^* F_0$$

