



DETECTOR CONTROL SYSTEM FOR THE ALICE EXPERIMENT AT CERN -LHC

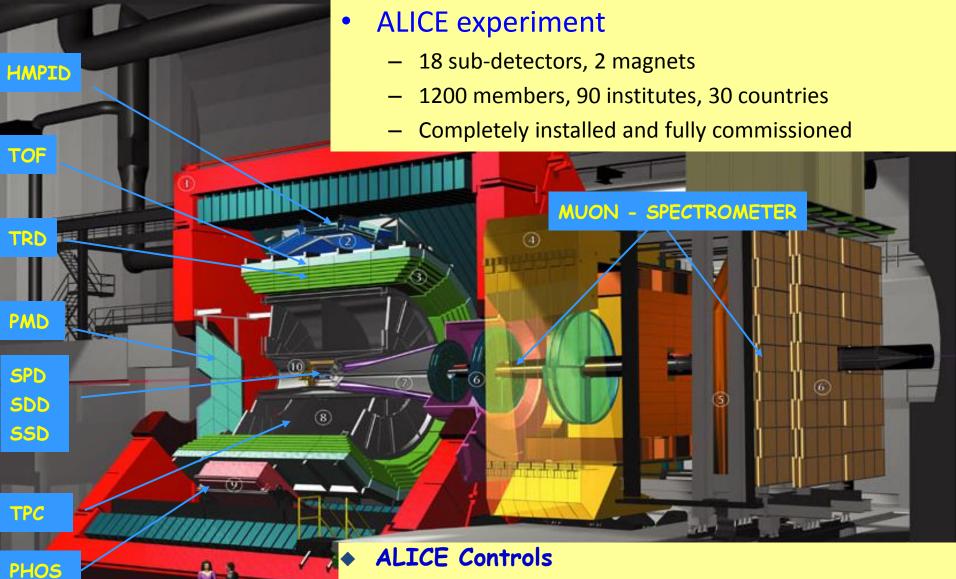
ICTDHEP JAMMU 11th September 2013

Anik Gupta

Special Thanks to the ALICE CONTROLS COORDINATION

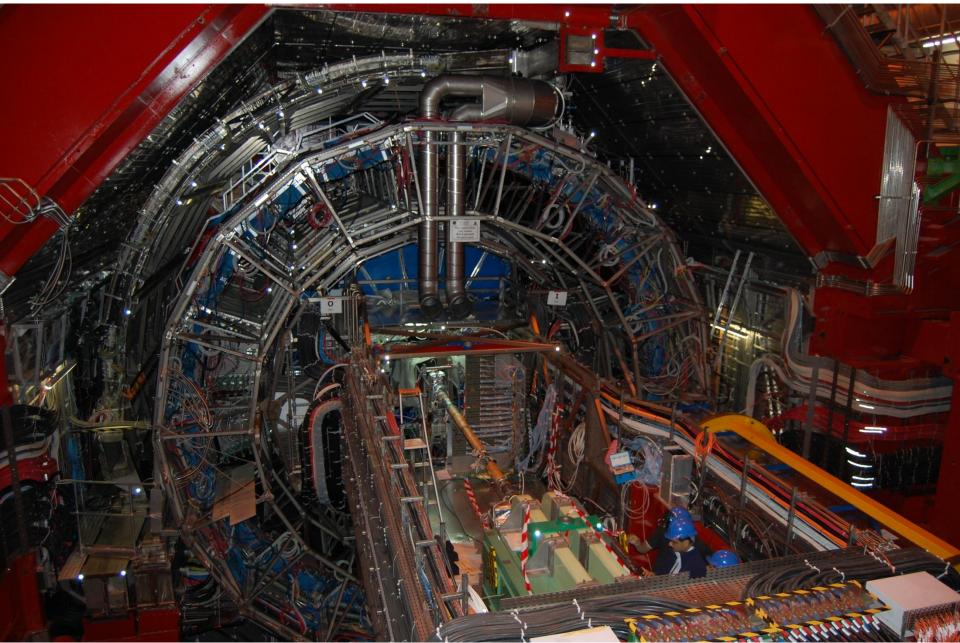
Based on slides given by Peter Chochula, Andre Augustinus and ALICE DCS TRAINING SLIDES

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Detectors not shown FMD, VO, TO, ZDC, EMC, CPV, ACO

- **ALICE** Controls
 - Started 12 years ago
 - Small(Very Important) central team
 - Detector groups & LHC experiments (JCOP) Anik Gupta ICTDHEP In total ~100 people involved





ALICE DCS



- The two main tasks of the ALICE Detector Control System (DCS) are
 - To assure maximum protection such that detector equipment cannot be damaged by adverse beam conditions
 - To assure that, whenever beam conditions allow, the detector is in optimal condition to take physics data



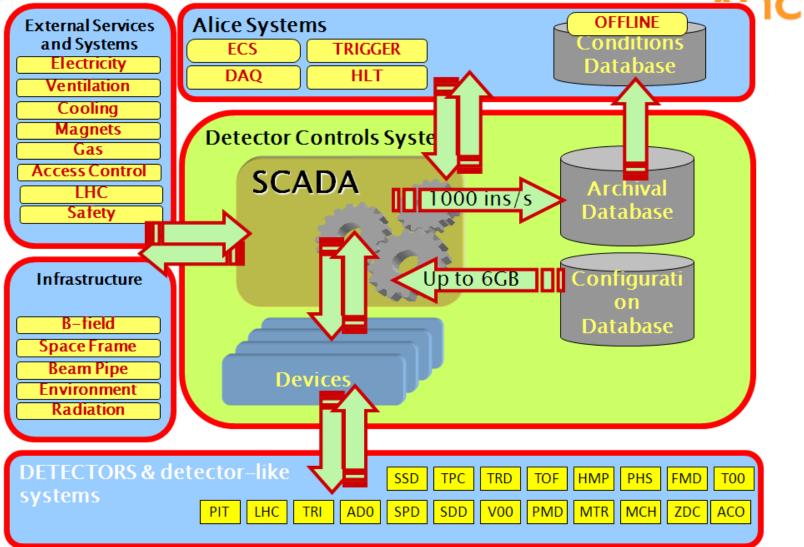
ALICE DCS



- To achieve this, the ALICE DCS
 - controls all relevant detector equipment,
 - maintains the synchronization with the LHC machine operation,
 - monitors and controls the experiment infrastructure and services,
 - provides reliable communication with LHC and other online systems,
 - has adopted the PVSSII SCADA as main tool (a CERN-wide standard for control systems)
 - PVSSII has recently be re-branded as "WinCC Open Architecture" after purchase by Siemens



The DCS Context

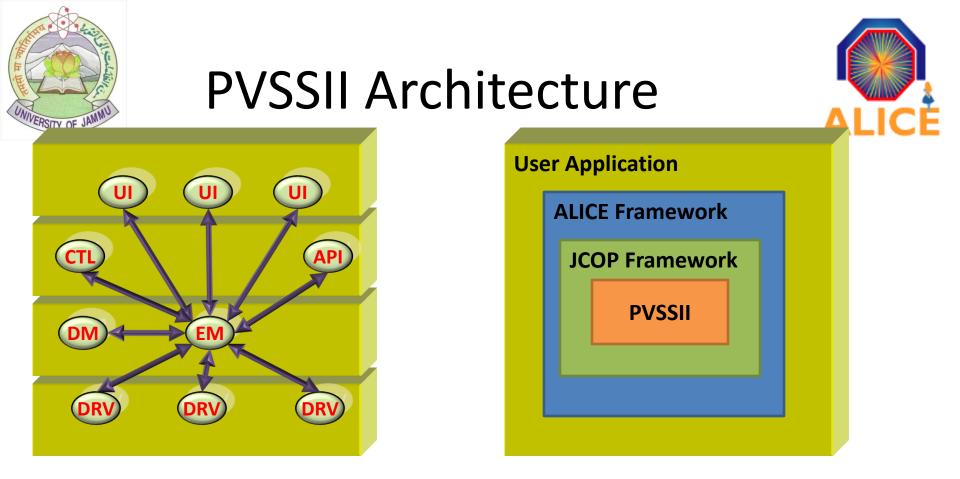




ALICE DCS



- Detector systems are responsibility of detector projects
 - Detector experts implement the local detector controls
- DCS central team (6 people):
 - provides standards, guidelines, infrastructure and support
 - supervises implementation of detector systems
 - implements the overall control of all local control systems
 - implements the interfaces with external systems and the other ALICE online systems
 - assures smooth operation during data taking campaigns



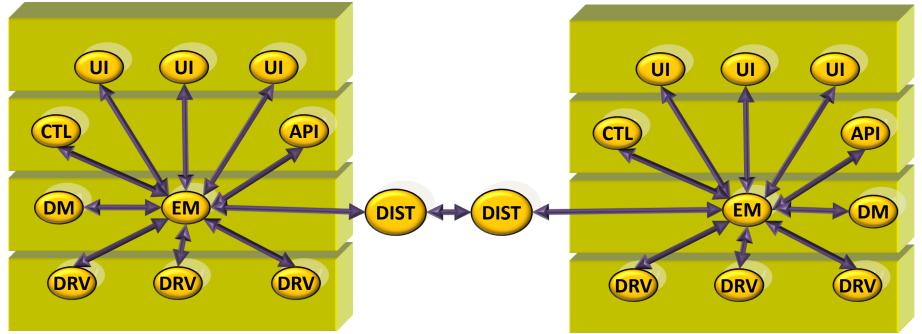
- PVSSII system is composed of specialized program modules (managers) ▣
- Managers communicate via TCP/IP
- ALICE DCS is built from 100 PVSS systems composed of 900 managers
- PVSSII is extended by JCOP and ALICE frameworks on top of which User applications are built

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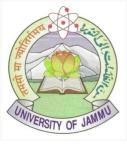


Distributed PVSS System





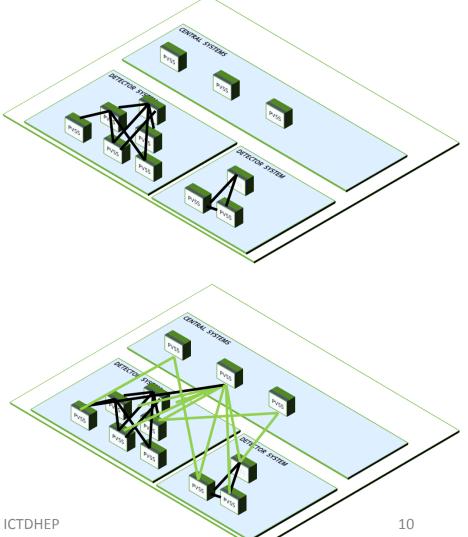
- Several PVSSII systems can be connected into one distributed system using a specialized manager (DIST)
- The ALICE distributed system consists of over 100 individual systems

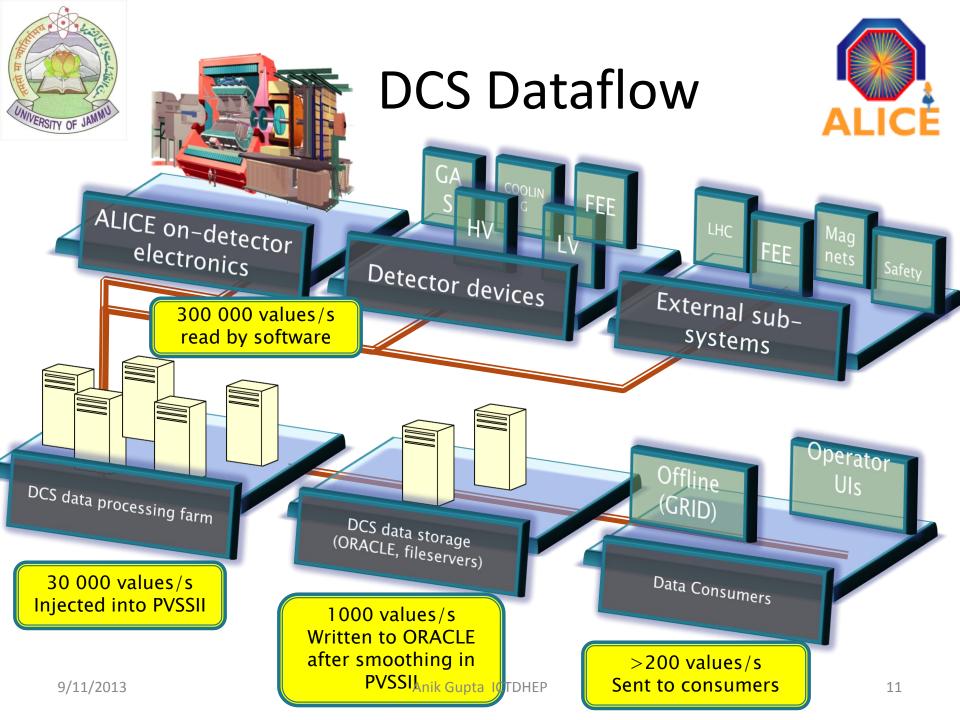


ALICE DCS Distributed System

 Each detector provides an autonomous distributed system

 Central servers connect to all detectors providing one large distributed system







DCS Computing





- 170 servers
- 700 embedded computers
- Oracle DB with 144TB raw storage
- 1,200, network attached devices





Challenges



- The DCS project in ALICE has been launched relatively late, when many of the detector developments were in advanced stage, and technology choices already made
- The ALICE experiment consists of 18 different detectors
 Compared to ~5 for ATLAS/CMS
- In order to guarantee a smooth integration a huge effort went into hiding complexity and diversity, and standardization on all levels



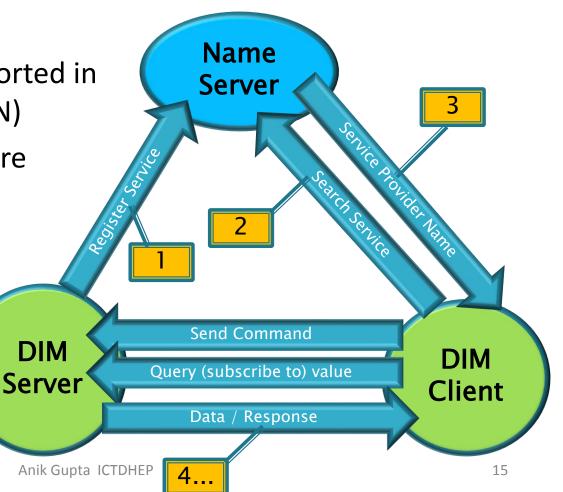
Challenges - standardization



- ③ High level of standardization achieved for power supplies and services (cooling, PLC based applications...)
 - Limited number of device models, supported centrally at CERN
 - Accessed by standard interfaces: CANbus, Profibus or Ethernet
 - OPC technology used as software interface
 - industry standard, supported in PVSSII
- 🐵 Large diversity in the front-end part
 - Different architectures and requirements
 - Variety of control buses (JTAG, CANbus, Profibus, RS232, Ethernet, custom buses – Easynet, DDL …)
 - DIM technology used to hide diversity

Distributed Information Management (DIM)

- CERN DIM used for command and data transfer
 - Implemented and supported in PVSSII and C++ (by CERN)
 - Client/server architecture
 - Robust and stable
 - Proven technology already in LEP era





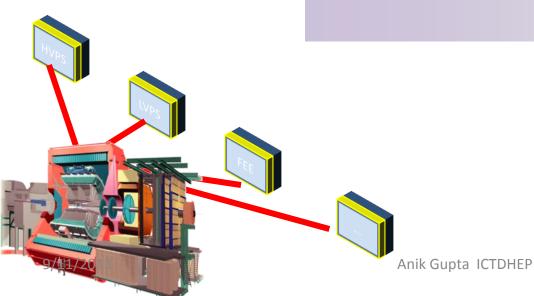
Building blocks of ALICE DCS



1200 network-attached devices270 crates (VME and power supplies)4 000 controlled voltage channels

 18 detectors with different requirements

 Effort to device standardization
 Still large diversity mainly in FEE part
 Large number of busses (CANbus, JTAG, Profibus, RS232, Ethernet, custom links...)





OPC SERVER

OPCSERVER

Device DRIVER

Device DRIVER

Device DRIVER

180 000 OPC items 100 000 Front-End (FED) services **1 000 000 parameters supervised by the DCS** Monitored at typical rate of 1Hz



Hardware diversity is managed through standard

•OPC servers for commercial devices •FED servers for custom hardware Provides hardware abstraction, uses CERN **DIM (TCP/IP based) protocol for** DEVICE ACCESS and ABSTRACTION

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FEDSERVER

Device DRIVER



OPC SERVER

Device DRIVER

BACKEND SISTEMS DCS Oracle RAC (able to process up to 150 00

DETECTOR SISTE

Defice ACCESS

Device DRIVER

OPC SERVER

Device DRIVER



ECTOR SYSTEM

CENTRAL SYSTEMS

Anik Gupta ICTINEP

FEDSERVER

AS ASSRACTION

Device DRIVER

FEDSERVER





OPERATIONS LAVER

 PVSSII distributed system is not a natural system representation for the operator •ALICE DCS Is modeled as a FSM using CERN SMI++ tools

PVSS

OPC SERVER

Device DRIVER

Defice Access

Device DRIVER

•Hide experiment complexity •Focus on operational aspect

OPC SERVER

Device DRIVER

FEDSERVER

PVSS

NO ABSTRACTION

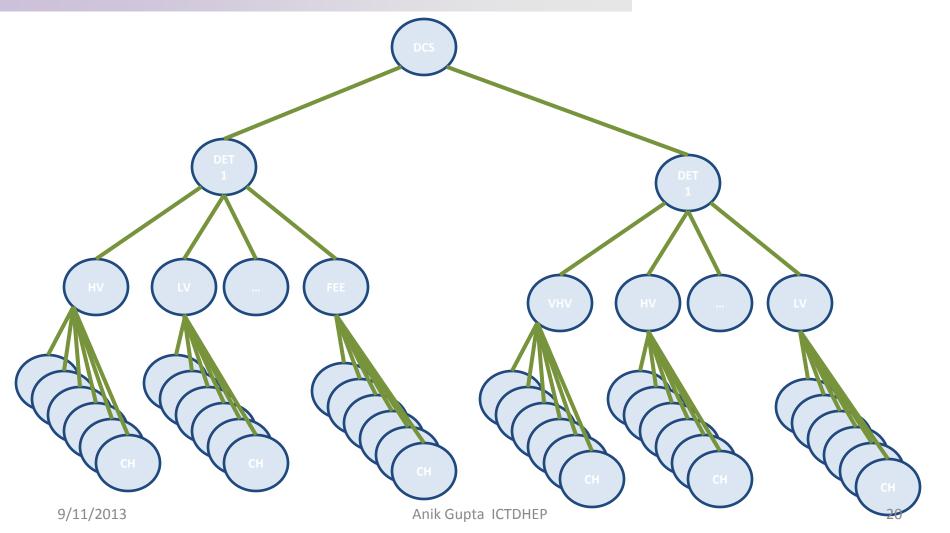
Device DRIVER

FEDSERVER

•Hierarchical approach:

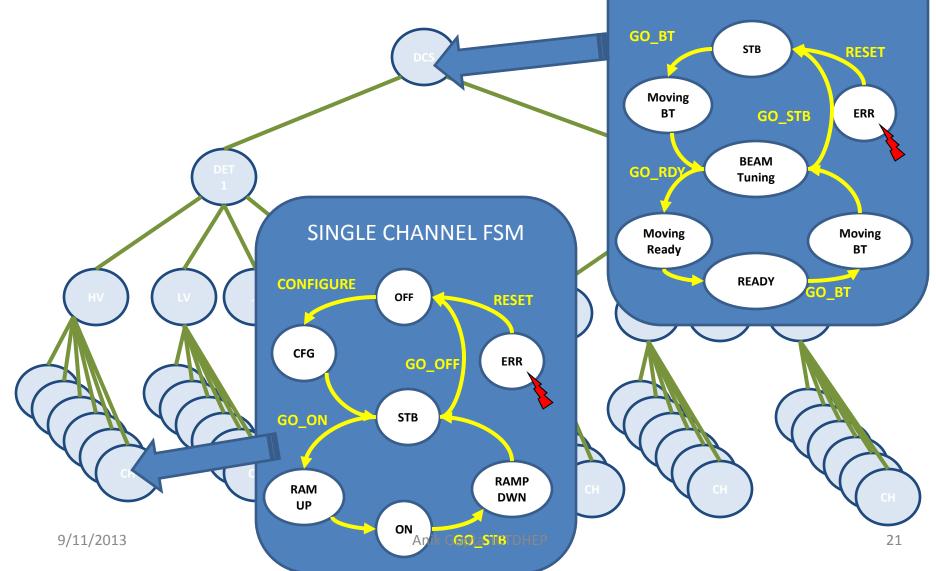
- ALICE DCS is represented as a tree composed of detector systems
- •Each detector system is composed of subsystems
- •Subsystems are structured to devices (crates, boards) and channels





DCS devices are described as FSM
State diagrams are standardized for channels and devices of the same type
Top level DCS takes into account status of all leaves

(simplified) TOP LEVEL FSM

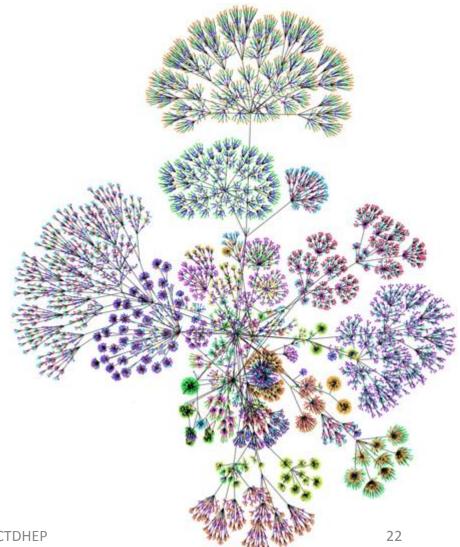




ALICE Central FSM Hierarchy



- Scale:
 - 1 top DCS node
 - 19 detector nodes
 - 100 subsystems
 - 5 000 logical nodes
 - 10 000 devices (leaves)
 - Each leaf can represent a complex unit containing many channels

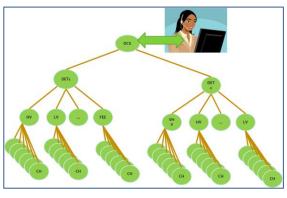


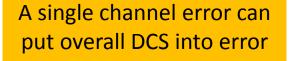


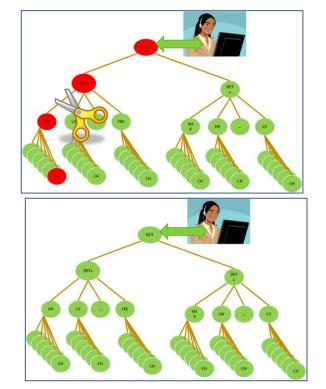
Hierarchy Partitioning



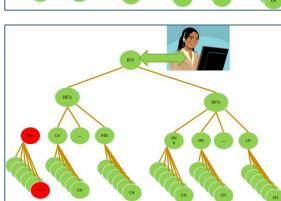
Partitioning allows for concurrent operation



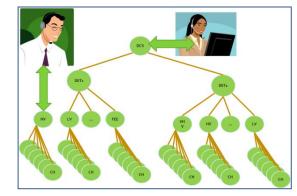




Operator includes the repaired part²³



Operator excludes the 9/11 affected part



Remote expert cures the problem

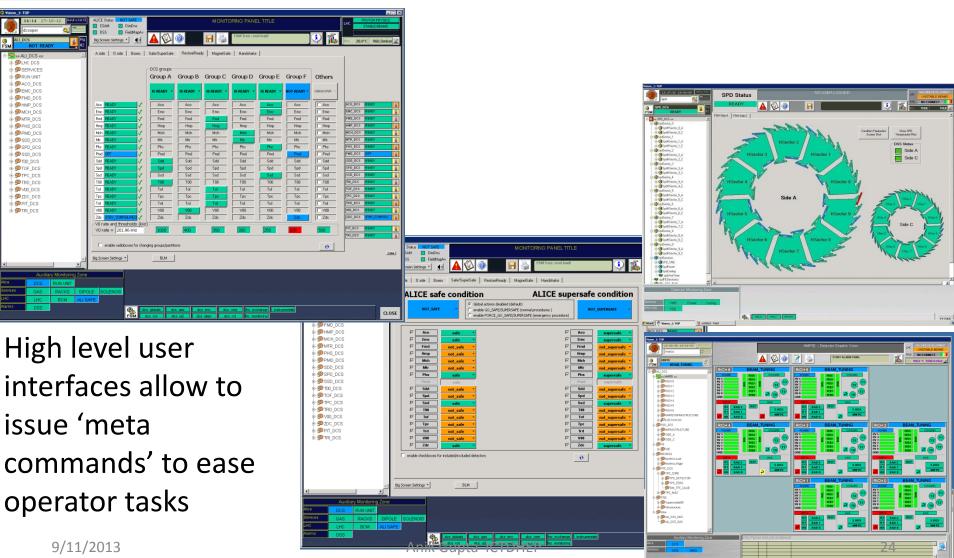


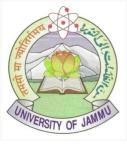
User Interface



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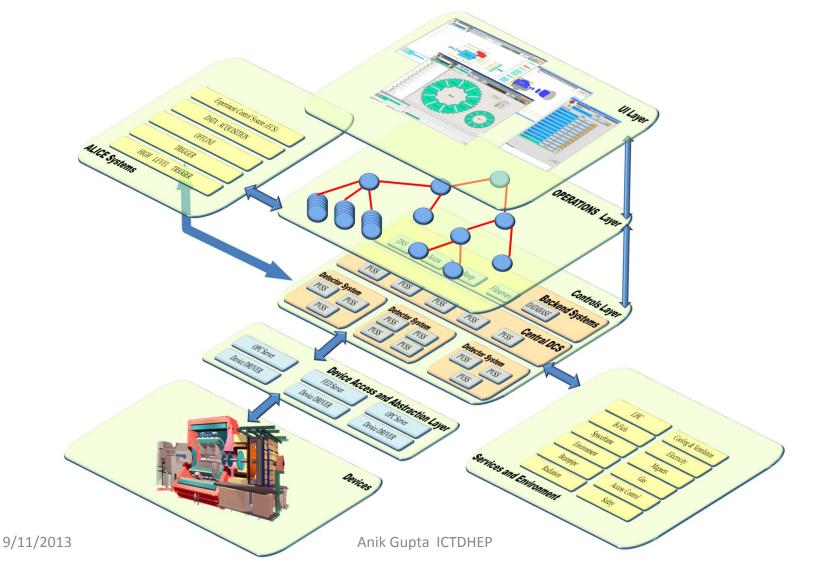


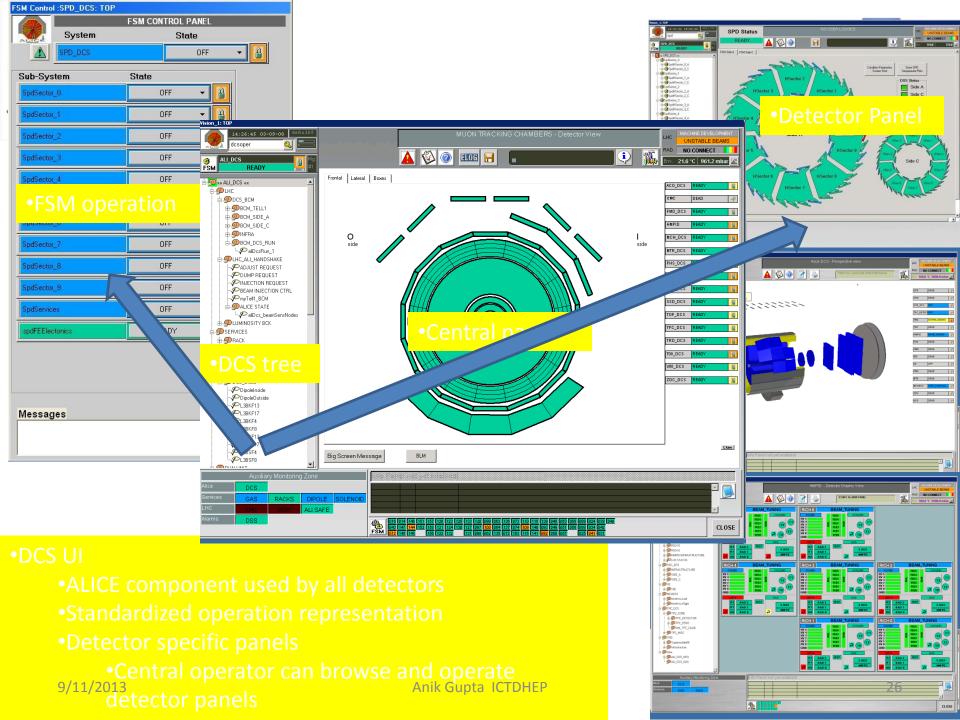


Putting pieces together



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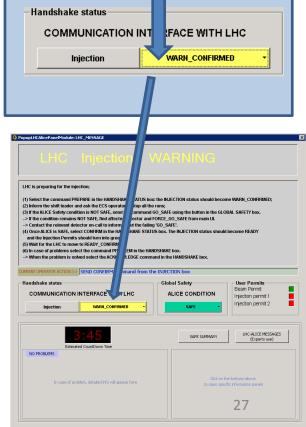


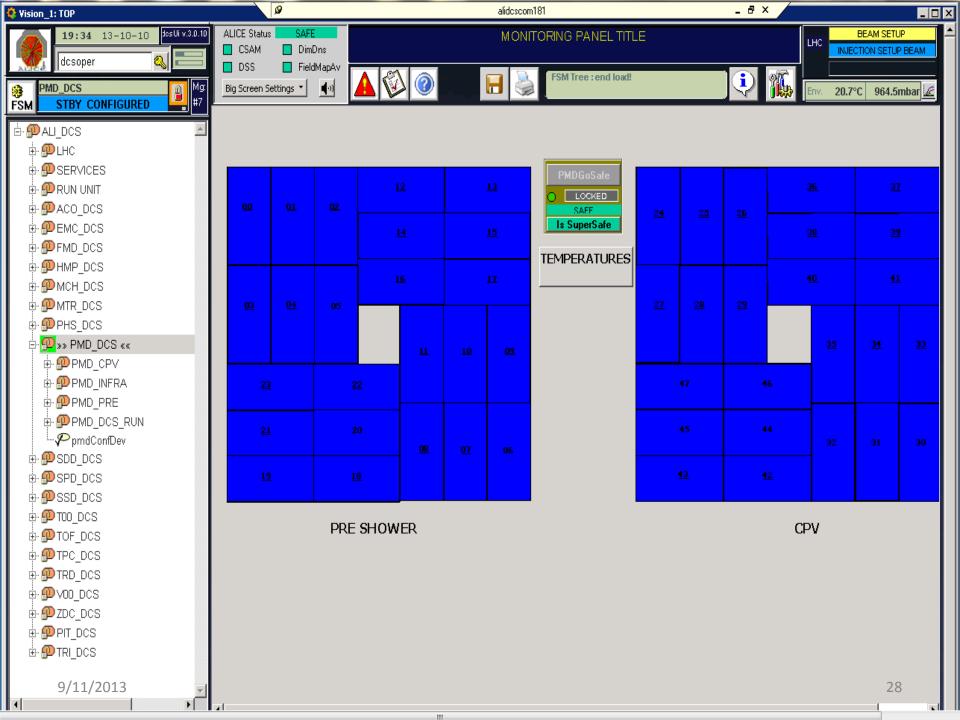


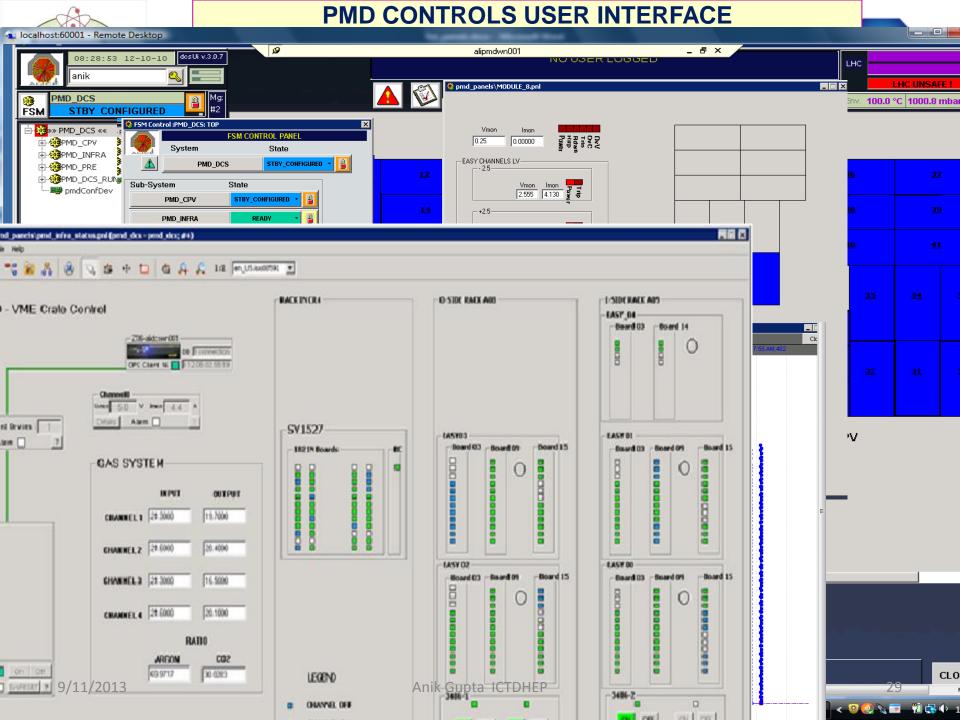
High Level Pa

poperanea oras rooma are_ estimate and	
LHC Injection WARNING	
	– Handshake status
LHC is preparing for the injection; (1) Select the command PREPARE in the HANDSHAKE STATUS box: the INJECTION status should become WARN_CONFRMED; (2) Inform the sith leader and ask the ECS operator to stop all the runs;	COMMUNICATION INTERFACE WITH LHC
(3) If the ALICE Safety condition is NOT SAFE, send the command GO_SAFE using the button in the GLOBAL SAFETY box.	Injection 🔪 WARNING 🗸
> Contact the relevant detector on-call to inform about the failing 'GO_SAFE'.	
(4) Once ALICE is SAFE, select CONFIRM in the HANDSHAKE STATUS box. The INJECTION status should become READY and the Injection Permits should turn into green;	Prepare
(5) Wait for the LHC to move to READY_CONFIRMED; (6) In case of problems select the command PROBLEM in the HANDSHAKE box.	Problem
> When the problem is solved select the ACKNOWLEDGE command in the HANDSHAKE box.	
JRRENT OPERATOR ACTION >> SEND PREPARE command from the INJECTION box	
Handshake status	
COMMUNICATION INTERFACE WITH LHC	
Injection VARNING - SAFE - Injection permit 2	Handshake status
	COMMUNICATION INT FACE WITH LHC
Estimated CountDown Time	Injection WARN_CONFIRMED -
NO PROBLEMS	
Click on the buttons above	
In case of problem, detailed info will appear here Click on the buttons above to open specific information purels	

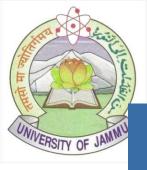
- Critical actions use high level panels
- All tools needed for the task are available on the panel
- Expert system guides the operator







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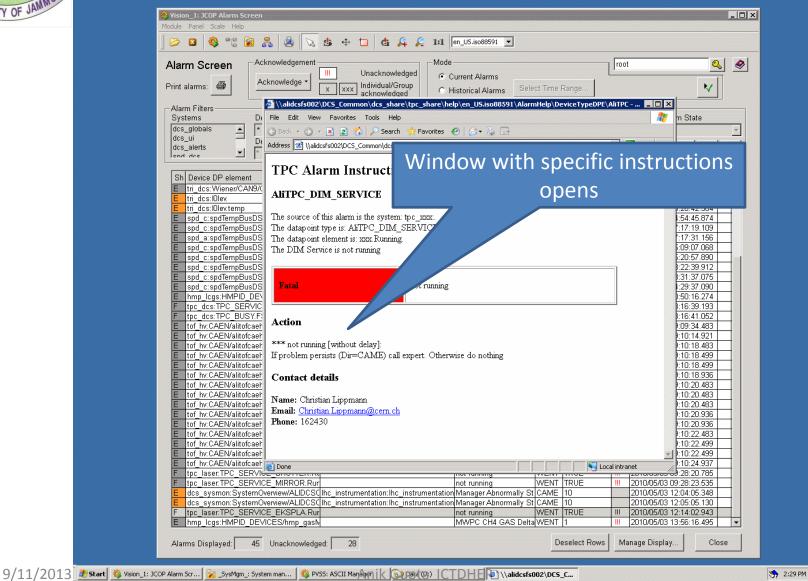


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Getting help on Alerts



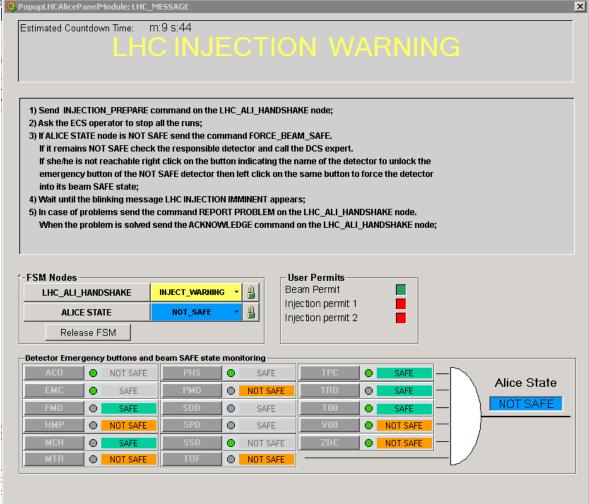






- This procedure is always executed before the LHC changes the operational mode
- The goal is to ring ALICE to safe mode and confirm this to LHC
- Handshake is initiated on LHC request and the DCS operator follows the instructions given at the operational panels (see following slides)

Handshake





-FSM Nodes		
LHC_ALI_HANDSHAKE	INJECT_WARNING +	<u></u>
ALICE STATE	INJECT_PREPARE	<u></u>
Release FSM	REPORT_PROBLEM	

-FSM Nodes	
LHC_ALI_HANDSHAKE	INJECT_WARN_CONF -
ALICE STATE	NOT_SAFE •
Release FSM	FORCE_BEAM_SAFE

FSM Nodes		
LHC_ALI_HANDSHAKE	INJECT_WARN_CONF *	<u></u>
ALICE STATE	SAFE 🔻	
Release FSM		

II: Injection Imminent

X



PopupLHCAlicePanelModule: LHC_MESSAGE

ERSITY OF JAN

Estimated Countdown Time: m:1 s:41 LHC INJECTION IMMINENT

1) If ALICE STATE node is NOT SAFE send the command FORCE_BEAM_SAFE.

If after 2 minutes it remains NOT SAFE check the responsible detector and call the DCS expert.

If she/he is not reachable right click on the button indicating the name of the detector to unlock the emergency button

of the NOT SAFE detector then left click on the same button to force the detector into its beam SAFE state;

2)Ask the TRI shifter to switch on the LHC clock;

3) Once ALICE is in beam SAFE state send CONFIRM_INJECT on the LHC_ALI_HANDSHAKE node;

4) Wait for the blinking message LHC INJECTION STARTED;

5) In case of problems send the command REPORT PROBLEM on the LHC_ALI_HANDSHAKE node. When the problem is solved send the ACKNOWLEDGE command on the LHC_ALI_HANDSHAKE node;

-FSM Nodes			User Permits
LHC_ALI_HANDSHAKE	INJECT_IMMINENT	P	Beam Permit
ALICE STATE	SAFE 🗣	e	Injection permit 1 Injection permit 2
Release FSM			, ,



FSM Nodes		
LHC_ALI_HANDSHAKE	INJECT_IMMINENT *	<u></u>
ALICE STATE		<u></u>
Release FSM	CONFIRM_INJECT	

FSM Nodes	
LHC_ALI_HANDSHAKE	INJECT_IMMINENT 🔻 🔒
ALICE STATE	
Release FSM	CONFIRM_INJECT

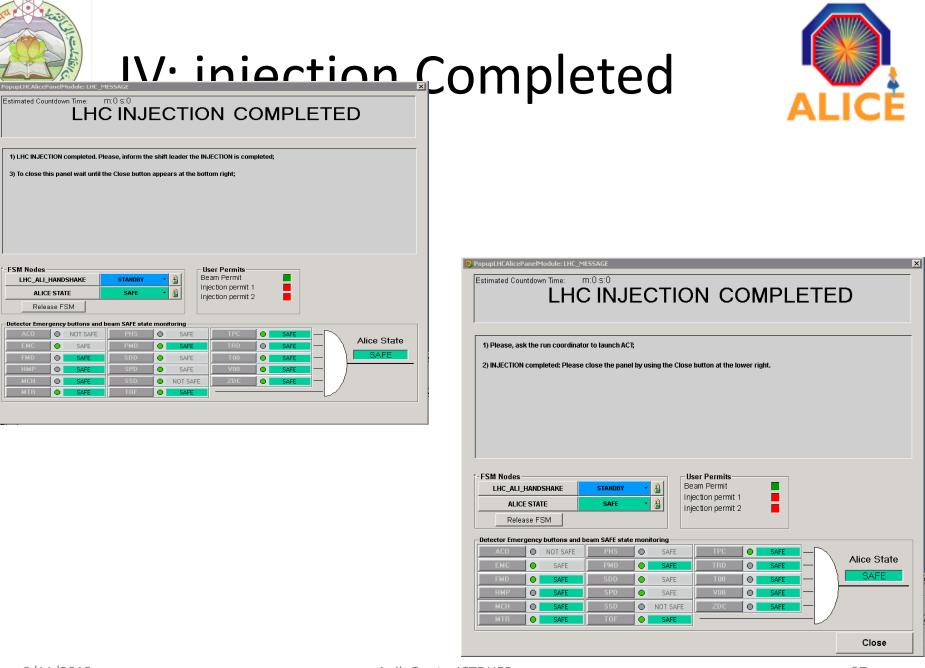


III: Injection READY



PopupLHCAlicePanelModule: LHC_MESSAGE

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THE INJECTION	n is unuer wa	y ,							
Wait until the b	blinking mess	age INJECTION	COMPL	ETED appea	rs;				
In case ALICE	flip in NOT SA	FE state send th	ne comr	nand REPOR	RT PROBLEM on th	ne LHC_AL	I_HANDS	HAKE node,	
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M Nodes LHC_ALI_HAN ALICE ST Release	TATE FSM	SAFE	•	E I I	Beam Permit njection permit 1	2	SAFE		
M Nodes LHC_ALI_HAN ALICE ST Release Rector Emergen	FSM FSM NOT SAFE	SAFE	• ate mon	itoring E	Beam Permit njection permit 1 njection permit 2		SAFE		Alice State
M Nodes LHC_ALI_HAN ALICE ST Release tector Emergen	TATE FSM Not SAFE	SAFE d beam SAFE sta	ate mon	itoring SAFE	Beam Permit njection permit 1 njection permit 2				Alice State
M Nodes LHC_ALI_HAM ALICE SI Release Rector Emergen ACO	FSM NOT SAFE SAFE	d beam SAFE sta	ate mon	ittoring SAFE	Beam Permit njection permit 1 njection permit 2		SAFE		
M Nodes LHC_ALI_HAN ALICE ST Release Rector Emergen ACO	TATE FSM NOT SAFE SAFE SAFE	d beam SAFE sto PHS PMD SDD		itoring SAFE SAFE	Beam Permit njection permit 1 njection permit 2		SAFE SAFE		



UN



Estimated Countdown Time: m:9 s:34

Handshake I: Dump WARNING



LHC_ALI_HANDSHAKE	DUMP_WARNING	•	ľ
ALICE STATE	DUMP_PREPARE	-	ſ
Release FSM			

-FSM Nodes	
LHC_ALI_HANDSHAKE	DUMP_WARN_CONF *
ALICE STATE	NOT_SAFE •
Release FSM	

FSM Nodes							
LHC_ALI_HANDSHAKE	DUMP_WARN_CONF *						
ALICE STATE	SAFE 🔻	<u></u>					
Release FSM							

 Send DUMP_PREPARE command on the LHC_ALI_HANDSHAKE node;
 Ask the ECS operator to stop all the runs;
 If ALICE STATE node is NOT SAFE send the command FORCE_BEAM_SAFE. If it remains NOT SAFE check the responsible detector and call the DCS expert. If she/he is not reachable right click on the button indicating the name of the detector to unlock the emergency button of the NOT SAFE detector then left click on the same button to force the detector into its beam SAFE state;
 Wait until the blinking message LHC DUMP IMMINENT appears;
 In case of problems send the command REPORT PROBLEM on the LHC_ALI_HANDSHAKE node;

LHC_ALI	HANDSHAKE	DUMP_WARNIN	IG 🔹		am Permit				TELL 1
ALIC	E STATE	NOT_SAFE		<u>n 1</u>	ction permit ction permit				READY
Rele	ase FSM				1				
ector Erne	rgency buttons and	l beam SAFE stat	e monito	orina					
ACO	NOT SAFE	PHS		SAFE	TPC		NOT SAFE		
EMC	SAFE	PMD		SAFE	TRD	0	NOT SAFE	ī— `	Alice State
FMD	NOT SAFE	SDD		SAFE	T00		SAFE		NOT SAFE
HMP	SAFE	SPD	0	NOT SAFE	V00		SAFE		
MCH	SAFE	SSD	0	NOT SAFE	ZDC		SAFE		/
MTR	SAFE	TOF		NOT SAFE					

II: DUMP Imminent

×



PopupEHCAlicePanelModule: EHC_MESSAGE
Estimated Countdown Time: m:1 s:42
LHC DUMP IMMINENT

1) If ALICE STATE node is NOT SAFE send the command FORCE_BEAM_SAFE.

If after 2 minutes it remains NOT SAFE check the responsible detector and call the DCS expert.

If she/he is not reachable right click on the button indicating the name of the detector to unlock the emergency button

of the NOT SAFE detector then left click on the same button to force the detector into its beam SAFE state;

2)Ask the TRI shifter to switch on the CTP clock;

3) Once ALICE is in beam SAFE state send CONFIRM_DUMP on the LHC_ALI_HANDSHAKE node;

4) Wait for the blinking message LHC DUMP STARTED;

5) In case of problems send the command REPORT PROBLEM on the LHC_ALI_HANDSHAKE node. When the problem is solved send the ACKNOWLEDGE command on the LHC_ALI_HANDSHAKE node;

M Nodes LHC_ALI_HANDSHAKE	DUMP_IMMINENT	- 8	Beam Permit	Tell1 Status TELL 1
ALICE STATE	SAFE	•	Injection permit 1	READY
Release FSM			-	***



LHC_ALI_HANDSHAKE	DUMP_IMMINENT *	9
ALICE STATE	REPORT PROBLEM	
Release FSM	CONFIRM_DUMP	

LHC_ALI_HANDSHAKE	DUMP_IMMINENT
ALICE STATE	REPORT_PROBLEM
Release FSM	CONFIRM_DUMP



Estimated Countdown Time: m:1 s:35

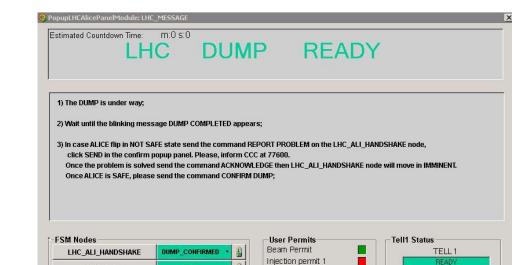
1) If ALICE STATE node is NOT SAFE send the command FORCE BEAM SAFE.

III: Dump READY



If after 2 minutes it remains NOT SAFE check the responsible detector and call the DCS expert. If she/he is not reachable right click on the button indicating the name of the detector to unlock the emergency button of the NOT SAFE detector then left click on the same button to force the detector into its beam SAFE state: 2)Ask the TRI shifter to switch on the CTP clock; 3) Once ALICE is in beam SAFE state send CONFIRM_DUMP on the LHC_ALI_HANDSHAKE node; 4) Wait for the blinking message LHC DUMP STARTED; 5) In case of problems send the command REPORT PROBLEM on the LHC_ALI_HANDSHAKE node. When the problem is solved send the ACKNOWLEDGE command on the LHC_ALI_HANDSHAKE node; -FSM Nodes User Permits Tell1 Status Beam Permit LHC_ALI_HANDSHAKE DUMP READY TELL 1 Injection permit 1 ALICE STATE SAFE Injection permit 2 Release FSM

ACO		NOT SAFE	PHS		SAFE			SAFE		
EMC	•	SAFE	PMD	•	SAFE	TRD	•	SAFE	_	Alice Stat
FMD		SAFE	SDD	0	SAFE	T 00		SAFE		SAFE
HMP	0	SAFE	SPD		NOT SAFE	¥00	0	SAFE		
мсн	0	SAFE	SSD		NOT SAFE	ZDC	0	SAFE		/
MTR	0	SAFE	TOF	0	SAFE					/



â

SAFE

SAFE

SAFE

NOT SAFE

SAFE

0

0

0

NOT SAFE

0

0

Injection permit 2

0

0

0

0

0

SAFE

SAFE

SAFE

SAFE

SAFE

SAFE

Detector Emergency buttons and beam SAFE state monitoring

SAFE

SAFE

SAFE

SAFE

SAFE

ALICE STATE

Release FSM

NOT SAFE

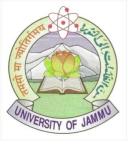
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•

Alice State





IV: Dumn Completed



1) Please, inform the shift leader that the handshake is over;

2) DUMP completed: Please close the panel by using the Close button at the lower right.

M Nodes LHC_ALI	; _Hands	HAKE	STANDBY	- 8	Beam Permits			Tell1 Star	TELL1
ALI	CE STATE		SAFE	- 8	Injection permit Injection permit				READY
Rel	ease FSN	M							
	_	1	earn SAFE stat	-					
ACO		NOT SAFE	PHS	SAF	E TPC		SAFE		Alian Ctat
and the second		SAFE	PMD	SAF	E TRD	0	SAFE	\	Alice Stat
EMC			and the same states	CORRECTOR CONTRACTOR	and the second se				
EMC		SAFE	SDD	SAF	E TOO	0	SAFE	n <u></u>	SAFE
			SDD SPD	SAF		•	SAFE SAFE		SAFE
FMD	•	SAFE		-	AFE V00				SAFE



Handshake I: Adjust WARNING



stimated Co	ountdown Time:	m:9 s:35 C A							
2) Ask the I 3) If ALICE 9 If it rema If she/he emerger into its b 4) Wait unti	JUST_PREPARE cc ECS operator to sto STATE node is NOT sins NOT SAFE chee is not reachable ri ncy button of the Ni eam SAFE state; I the blinking mess of prohlems send fl	p all the runs; SAFE send the c ck the responsib ght click on the I DT SAFE detector	ommar le dete button i r then li T IMMIN	- nd FORCE_BEAN ctor and call the indicating the na eft click on the IENT appears;	1_SAFE. DCS expert. ame of the det same button t	o forc	e the detector AKE node.		
When th FSM Node	e problem is solve	I send the ACKN	OWLED	OGE command o	er Permits— m Permit		DSHAKE node	; -Tell1 Sta	TELL 1
When th FSM Node LHC_AL	e problem is solve s	t.	owled	OGE command o Usi Bea Inje	er Permits— m Permit ction permit 1	- 	DSHAKE node		
When th FSM Node LHC_AL ALI	e problem is solver s I_HANDSHAKE	ADJUST_WARN	owled	OGE command o Usi Bea Inje	er Permits— m Permit	- 	DSHAKE node		TELL 1
When th FSM Node LHC_AL ALI Rel	e problem is solver s 1_HANDSHAKE ICE STATE	ADJUST_WARN	OWLEE	DGE command of Bea Inje	er Permits— m Permit ction permit 1	- 	DSHAKE node		TELL 1
When th FSM Node LHC_AL ALI Rel	e problem is solver s I_HANDSHAKE ICE STATE lease FSM	ADJUST_WARH NOT_SAFE	OWLEE	DGE command of Bea Inje	er Permits— m Permit ction permit 1	- 	NOT SAFE		TELL 1 READY
When th FSM Node LHC_AL ALI Rel Detector Em	e problem is solver I_HANDSHAKE ICE STATE lease FSM	ADJUST_WARN NOT_SAFE	OWLEE	DGE command of Bea Inje	er Permits m Permit ction permit 1 ction permit 2	1			TELL 1 READY Alice State
When th FSM Node LHC_AL ALI Rel Detector Em ACO	e problem is solver s I_HANDSHAKE ICE STATE lease FSM ergency buttons ar	ADJUST_WARN NOT_SAFE d beam SAFE sta PHS PMD	OWLEE	DGE command of Beau Inje	er Permits m Permit ction permit 1 ction permit 2 TPC		NOT SAFE		TELL 1 READY
When th FSM Node LHC_AL Rel Detector Em ACO EMC	e problem is solver S I_HANDSHAKE ICE STATE lease FSM ergency buttons ar NOT SAFE SAFE	ADJUST_WARN NOT_SAFE d beam SAFE sta PHS PMD	owler IING -	BGE command d Bea Inje Inje SAFE SAFE	er Permits m Permit ction permit 1 ction permit 2 TPC TRD		NOT SAFE NOT SAFE		TELL 1 READY Alice State
When th FSM Node LHC_AL ALI Rel Detector Em ACD EMC FMD	e problem is solver s I_HANDSHAKE ice STATE iease FSM ergency buttons ar O NOT SAFE SAFE NOT SAFE	ADJUST_WARM NOT_SAFE d beam SAFE sta PHS PMD SDD	te mon	CE command of Use Beat Inje Inje Inje Inje SAFE SAFE SAFE SAFE	er Permits m Permit ction permit 1 ction permit 2 TPC TRD T00	2	NOT SAFE SAFE		TELL 1 READY Alice State

-FSM Nodes LHC_ALI_HANDSHAKE ADJUST_WARNING ADJUST_PREPARE Release FSM

-FSM Nodes	
LHC_ALI_HANDSHAKE	ADJUST_WARN_CONF •
ALICE STATE	NOT_SAFE •
Release FSM	FORCE_BEAM_SAFE

FSM Nodes		
LHC_ALI_HANDSHAKE	ADJUST_WARN_CONF *	<u></u>
ALICE STATE	SAFE 🔫	<u> </u>
Release FSM		

II: Adjust Imminent

FSM Nodes

LHC_ALI_HANDSHAKE

ALICE STATE

Release FSM



0

A

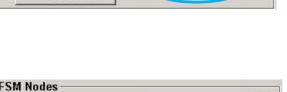
PopupLHCAlicePanelModule: LHC_MESSAGE
Estimated Countdown Time: m: 1 s:38
LHC ADJUST IMMINENT

1) If ALICE STATE node is NOT SAFE send the command FORCE_BEAM_SAFE.

If after 2 minutes it remains NOT SAFE check the responsible detector and call the DCS expert. If she/he is not reachable right click on the button indicating the name of the detector to unlock the emergency button of the NOT SAFE detector then left click on the same button to force the detector into its beam SAFE state;

- 2) Once ALICE is in beam SAFE state send CONFIRM_ADJUST on the LHC_ALI_HANDSHAKE node;
- 3) Wait for the blinking message LHC ADJUST STARTED;

4) In case of problems send the command REPORT PROBLEM on the LHC_ALI_HANDSHAKE node. When the problem is solved send the ACKNOWLEDGE command on the LHC_ALI_HANDSHAKE node;



ADJUST IMMINENT

REPORT PROBLEM

CONFIRM_ADJUST

M Nodes LHC_ALI_HANDSHAKE	ADJUST_IMMINENT	- 121	Beam Permit	Tell1 Status TELL 1	
ALICE STATE	SAFE	•	Injection permit 1	READY	
Release FSM		10.00			

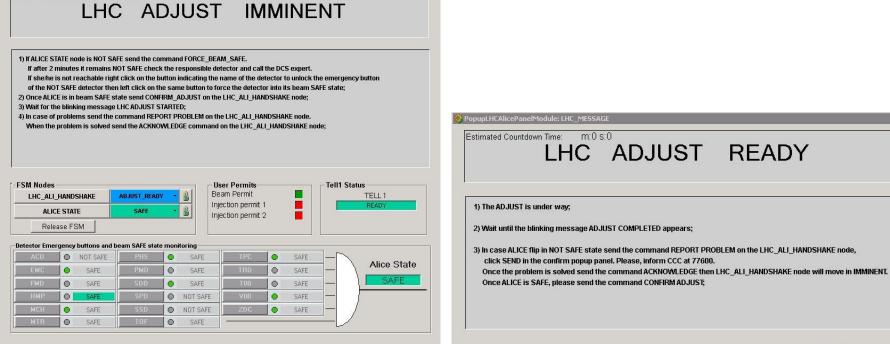
ACO	•	NOT SAFE	PHS		SAFE	TPE	•	SAFE	-	
EMC	•	SAFE	PMD	•	SAFE	TRD	0	SAFE		Alice State
FMD	•	SAFE	SDD	•	SAFE	T00	0	SAFE	-	SAFE
HMP.	0	SAFE	SPD		NOT SAFE	V00	0	SAFE	—	
MCH		SAFE	SSD	0	NOT SAFE	200	0	SAFE		/
MTR	•	SAFE	TOF	0	SAFE					

LHC_ALI_HANDSHAKE	ADJUST_IMMINENT *	0
ALICE STATE	REPORT_PROBLEM	A
Release FSM	CONFIRM_ADJUST	-



III: Adjust READY





M Nodes	s I_handshake	ADJUST_CONFIR	AMED -	Beam Permits			Tell1 Status		
ALI	ICE STATE	SAFE	- 8	Injection permit			READY		
Rel	ease FSM								
		and beam SAFE stat	-	1			7 ~		
	🔵 🔍 NOT SA	FE PHS	SAI	FE TPC		SAFE	-		
EMC	SAFE	PMD	SAI	FE TRD	•	SAFE]_ ``	Alice State	
EMC FMD	SAFE		SAI			SAFE SAFE		Alice State	
		SDD		FE TOO	1.5.5			\	
FMD	SAFE	SDD SPD	O SAI	FE TOO SAFE VOO	•	SAFE		\	





PopupLHCAlicePanelModule: LHC_ME55AGE

Estimated Countdown Time: m:0 s:0 LHC ADJUST COMPLETED

1) Please, inform the shift leader that the handshake is over;

2) ADJUST completed: Please close the panel by using the Close button at the lower right.

SM Nodes LHC_ALI	s I_handshake	STANDBY		Beam Permits		Tell1 Status TELL 1 READY		
ALI	CE STATE	SAFE	- 8	Injection permit	1999 - 1999 - 1999 - 1999 - 1999 - 1999 - 1999 - 1999 - 1999 - 1999 - 1999 - 1999 - 1999 - 1999 - 1999 - 1999 -			
Rel	ease FSM	Т			0.000			
etector Ema	ergency buttons and	bearn SAFE sta	te monitoring -					
ACO	NOT SAFE	PHS	SAF	TPC	SAFE			
EMC	SAFE	PMD	SAF	TRD	SAFE	Alice Sta		
FMD	SAFE	SDD	SAF	T00	SAFE	SAFE		
НМР	SAFE	SPD	NOT S	FE V00	SAFE			
MCH	SAFE	SSD	🔵 🔵 NOT S	FEZDC	SAFE			
MTR	O SAFE	TOF	SAF					





ALICE Safety



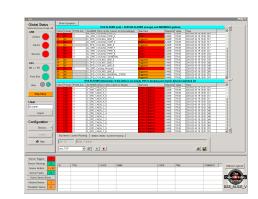




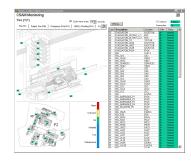
• The DCS receives safety related information:

- DSS
- Sniffer
- CSAM







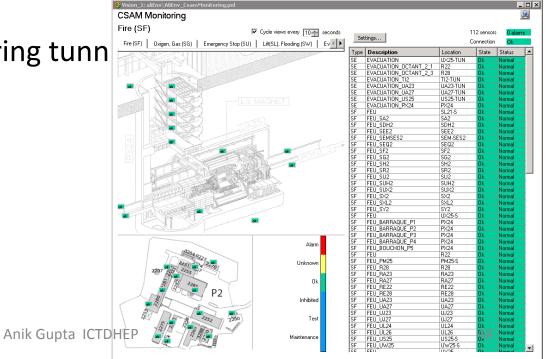




CSAM

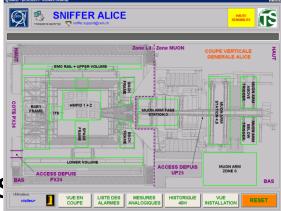


- CSAM (CERN Safety Alarm Monitoring)
 - Collects, transmits and presents all safety alarms
 - UI in ALICE presents all level 3 alarms relevant to point 2
 - Experiment, neighboring tunn



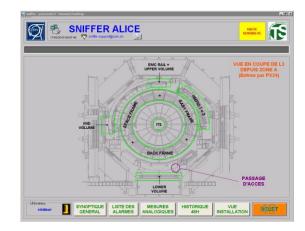


Sniffer



- Sniffer system monitors gas samples solenoid volume and around/below muon arm
 - Detection of smoke, flammable gas and ODH
 - Alarm list view (default) and synoptic views











- DSS (Detector Safety System)
 - Robust, redundant part of DCS, PLC based
 - Shared by experiment safety and environment monitoring and detector interlocks
 - Can take pre-programmed actions
- Basic concept:
 - A logical (and, or) combination of (triggered) inputs can raise an alarm. An alarm can trigger one or more outp (action)



DSS



Global Status —	Sho	ow Synop	otics									
10/03/1611:55:46 PI	. I				DSS ALARMS	(red) + SENSOR AL	ARMS (orange) an	d WARNINGS (y	ellow)			
VAM		Priority	PVSS Ack	ALARMS (Click in this colur	nn to Acknowledge)	Alert text	Direction	Value	Time		
		50		ML_OFD_C	OODING_FIFE_3		ZSIGIIII	CANNE	TROL	2010-00-10 19:10.		
Actions	A	99			OOLING_PIPE_4		Alarm	CAME	TRUE	2010-03-16 19:10:		
	W	40			DOLING_LINE_3		Triggered	CAME	TRUE	2010-03-16 19:10:		
	A	99			OOLING_PIPE_9		Alarm	CAME	TRUE	2010-03-16 19:10:		
Alarms 🛑 🚽	W	40			DOLING_LINE_4		Triggered	CAME	TRUE	2010-03-16 19:10:		
	A		iii		OOLING_PIPE_7		Alarm	CAME	TRUE	2010-03-16 19:10:		
	A				OOLING_PIPE_6		Alarm	CAME	TRUE	2010-03-16 19:10:		
Sensors (A				OOLING_PIPE_8		Alarm	CAME	TRUE	2010-03-16 19:10:		_
	A	99			OOLING_GENER	RAL	Alarm	CAME	TRUE	2010-03-16 19:10:		
	- W	40			DOLING_LINE_5		Triggered	CAME	TRUE	2010-03-16 19:10:		_
s	n W	40			DOLING_LINE_7		Triggered	CAME	TRUE	2010-03-16 19:10:		_
	W	40			DOLING_LINE_6		Triggered	CAME	TRUE	2010-03-16 19:10:		_
<-> FE (A	99			ooling_Anomaly		Alarm	CAME	TRUE	2010-03-16 19:10:		
	W	40			DOLING_LINE_8		Triggered	CAME	TRUE	2010-03-16 19:10:		
	W	40			DOLING_GENER	AL_STATE	Triggered	CAME	TRUE	2010-03-16 19:10:		
ront End	W	40		DI_SPD_CO	DOLING_LINE_9		Triggered	CAME	TRUE	2010-03-16 19:10:	01.379	•
				DSS ACTION	IS (interlocks) : i	f this table is not en	ıpty, DSS is keepir	ng part of your d	etector	switched off		
Alive 🔿 🔿	Short	Priority	PVSS Ack	ACTIONS (Click in this colu	mn to Reset)	Alert text	Direction	Value	Time		
	-	100		U SFU CA		,	Action mggereu	CANTE	TROL	2010-00-10 19.10.		_
	5 <u>S</u>			0_SPD_CA			Action Triggered	CAME	TRUE	2010-03-16 19:10:		
Stop Siren	S			0_SPD_CA			Action Triggered	CAME	TRUE	2010-03-16 19:10:		
				0_SPD_CA			Action Triggered	CAME	TRUE	2010-03-16 19:10:		
	S			0_SPD_CA			Action Triggered	CAME	TRUE	2010-03-16 19:10:		
er				0_SPD_CA			Action Triggered	CAME	TRUE	2010-03-16 19:10:		
	· S			0_SPD_CA			Action Triggered	CAME	TRUE	2010-03-16 19:10:		
soper	S S			O_SPD_CA			Action Triggered	CAME	TRUE	2010-03-16 19:10:		
	l S			0_SPD_CA			Action Triggered	CAME	TRUE	2010-03-16 19:10:		_
Logout	S S			0_SPD_CA			Action Triggered	CAME	TRUE	2010-03-16 19:10:		
	- <u>s</u>			0_SPD_CA			Action Triggered	CAME	TRUE	2010-03-16 19:10:		_
-	S			0_SPD_CA			Action Triggered	CAME	TRUE	2010-03-16 19:10:		_
nfiguration —				O_SPD_CA			Action Triggered	CAME	TRUE	2010-03-16 19:10:		
	(S			0_SPD_CA			Action Triggered	CAME	TRUE	2010-03-16 19:10:		
Browse *	S			O_SPD_CA	AEN_C_9		Action Triggered	CAME	TRUE	2010-03-16 19:10:	01.379	
	S	100		0_SPD_CA	AEN_C_8		Action Triggered	CAME	TRUE	2010-03-16 19:10:	01.379	-
Create *	Top	(âlerts (C	Current/Runn		n / Alerts / Current /	Rupping						
			- anomene - realing	ing bouon	Tradito / Odifelit/	rearining					- 1	
🤣 Help	24	- 12	Mode :	Current							-	
~ ····			1									
		TOP		1 🛃 🕨						alr		
	aes	108	-] <u>B</u>] _ P						<u>e</u>		
_	-											
nsor Triggers: 11												
Isor Warnings: 0												_
isor wannings.	ID		TYPE		CLASS	NAME		USER	TIME		COMMENT	R
nsor Inhibits: 1 + 3	32											
									-			- 11
nsor Faults: 0												
kno Sensor Errors					1							De
												_
sked Alarms: 1					1			1	1			

DSS inputs and alarms

DSS outputs (actions)

Alarms are acknowledged, and actions are reset by single click on the name (first alarm, then action)

44	40		[bi]ar.b]oooniko]nike]o	niggereu	VANL	INVE	2010/03/10 13:10:01:340	
A	99		AL_SPD_Cooling_Anomaly	Alarm	CAME	TRUE	2010-03-16 19:10:01.348	
W	40		DI_SPD_COOLING_LINE_8	Triggered	CAME	TRUE	2010-03-16 19:10:01.364	
W	40		DI DE COOLING GENERAL STATE	Triggered	CAME	TRUE	2010-03-16 19:10:01.379	
107	40		DI SPD COOLING LINE 9	Triggered	CAME	TRUE	2010-03-16 19:10:01.379	
		C	OSS ACTIONS (interlocks) : if this table is not e	mpty, DSS is keeping par	t of your d	etector sv	vitched off	
	Defendance	D) (OO A -1-	ACTIONS (OF all in this and using the Decent)	A Louis A court	D: 12			
On of	Priority	PVSS Ack	ACTIONS (Click in this column to Reset)	Alert text	Direction	Value	Time	
-01		PV55 ACK	CLICK IN THIS COLUMN TO RESET	Alert text Action mggereu	CAME	Value	lime 2010-03-10 19:10:01:301	
S S	100				CAINE			-
S S	100			Action mggered	CAINE	TROL	2010-03-10 19.10.01.301	

Anik Gupta ICTDHEP

DSS ALICE V

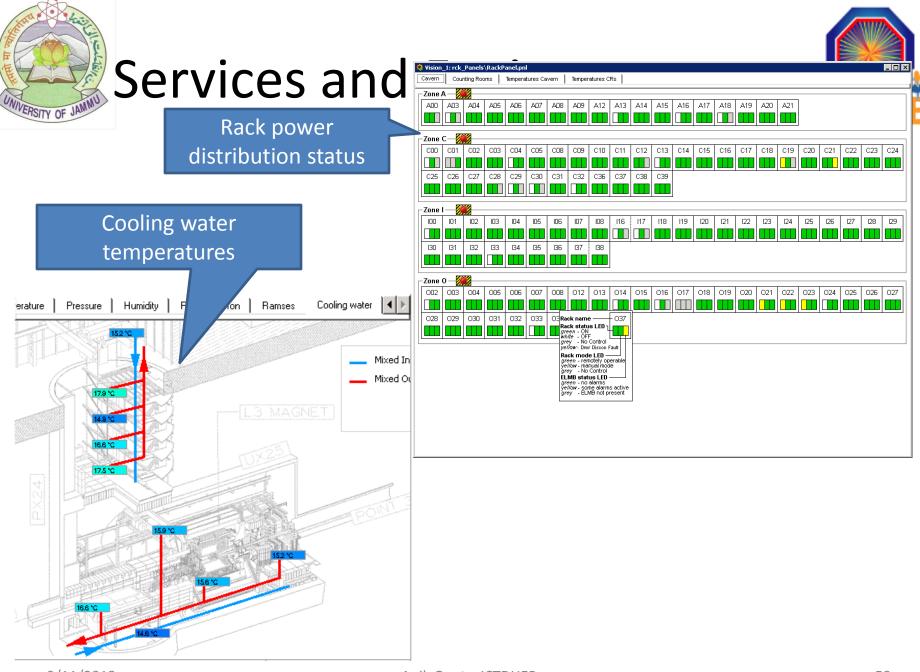
"Disabled" Alarms:



Services and Environment



- To run the experiment, services are needed:
 - Power (electricity)
 - Cooling (water)
 - Magnet (solenoid, dipole)
 - Gas
- The DCS monitors the status of these services
- The DCS monitors the environment of the experiment
 - Temperatures, atmospheric pressure, humidity
 - Radiation
 - Magnetic field





Services and Environment

0.100 A

A

0.000

20.17

Current

Set Current

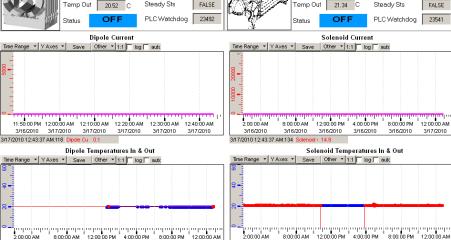
Temp In

Dipole

Magnet status

Gas systems status

DIP OK	Mixer		Pump		Exhaust		Distribution	Purifier	Others
TOF EC State Run Status Nominal	RunStable Line1Ratio Line2Ratio Line3Ratio TotalFlow	OK 93.0 % 0.0 %	Run InPressure OutPressure	0.6 bar	Recirculating CirculationFlow BufferPressure CirculationPressu.	0.9 Nm3/h 0.6 bar 0.6 bar	RunReady 61.62	Nominal Run Xal (22) ColARunVolume 82.0 m3 ColBRunVolume 0.0 m3 ColAInFlow 0.6 m3 ColAInFlow 0.0 m3	'n
TRD But State Run Status Nominal	RunStable Line1Ratio Line2Ratio 1 TotalFlow	00.0 %	OutPressure	1.0 bar	Recirculating CirculationFlow BufferPressure CirculationPressu.	2.3 Nm3/h 1.0 bar 0.9 bar	65 66 67 68 69 70 71 72	Stop CA108 ColARunVolume 343.0 m3 ColBRunVolume 0.0 m3 ColBInFlow 1.7 m3 ColBInFlow 0.0 m3	
TPC Run State Status Nominal	RunStable Line1Ratio Line2Ratio Line3Ratio TotalFlow	9.0 % 4.2 % 46.1 l/h	Run InPressure OutPressure Pump1 CurrentLoad Pump1 CurrentSpeed PressureSetpoint		Recirculating BufferPressure CirculationPressu.	2.0 bar 1.4 bar			ColARunVolume 0.0 m3 ColBRunVolume 0.0 m3 h ColAnFlow 0.0 m3/h ColBInFlow 0.0 m3/h Absorber 0.0 m3/h
HMP Pue State Run Status Nominal	Line2Ratio TotalFlow 2	100.0 % 0.0 % 270.0 1/h					BunReady 61		
MTR Bue State Run Status Nominal	RunStable Line1Ratio Line2Ratio Line3Ratio Line4Ratio TotalFlow 1	OK 89.7 % 0.0 % 10.0 % 0.3 % 71.1 l/h					RunReady 61		RunReady EvaporatorPressu0.0 bar Humidity 6145.1 ppm Humidifier
PMD pue State Run Status Nominal	RunStable Line1Ratio Line2Ratio TotalFlow	70.0 % 30.0 % 89.5 l/h					RunReady 61		
MCH Pro State Run Status Nominal	RunStable Line1Ratio Line2Ratio TotalFlow 4	80.0 % 20.0 % 196.7 l/h					RunReady 61[62		
CPV Exc State Status Not Ready	Stop Line1Ratio Line2Ratio TotalFlow	0.0 % 0.0 % 0.0 l/h					Stop 61		00:38 3/17/2010



L3 Solenoid

Emcy ShutDown TRUE

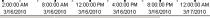
NEGATIVE

FALSE

Polarity

Ramping Sts





14.900 A

0.000

21.09

Current

Set Current

Temp In

Emcy ShutDown TRUE

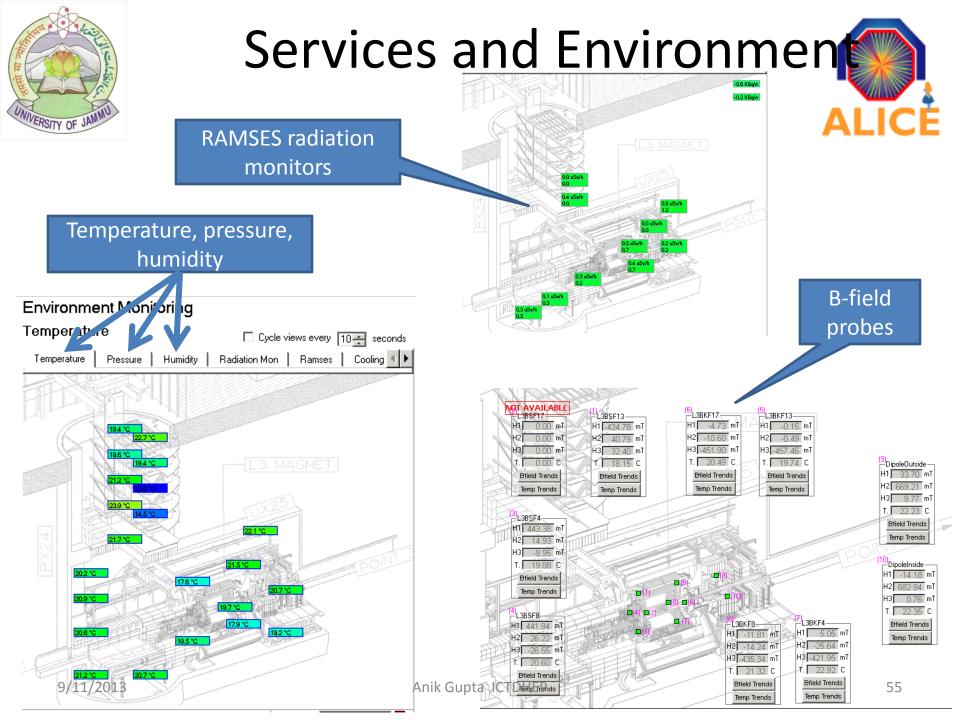
NEGATIVE

FALSE

Polarity

Ramping Sts

3/17/2010 12:43:51 AM.662 Solenoid 21.09 Solenoid 21.34









- ALICE DCS is based on commercial SCADA system called WinCC Open Architecture hitherto known as PVSSII
- DCS has to assure efficient, yet safe operation
 - Standardize where possible; hide complexity and diversity
 - Modelling through finite state machines
 - Continuously Develop user interfaces to ease operator tasks
- Future
 - Exploit experience of last years of operations
 - Review state machines, simplify where possible
 - Improve user interface
 - Aim for further automation in the operation
 - Improve robustness of the communication with external systems





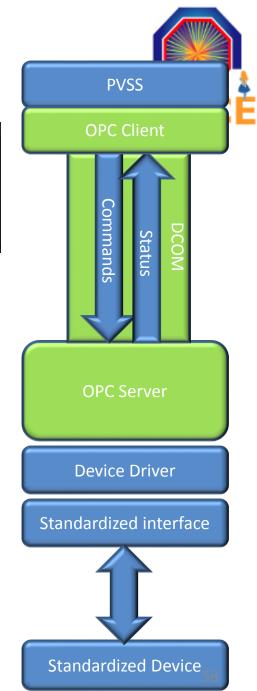
BACKUP SLIDES



OPC Technology

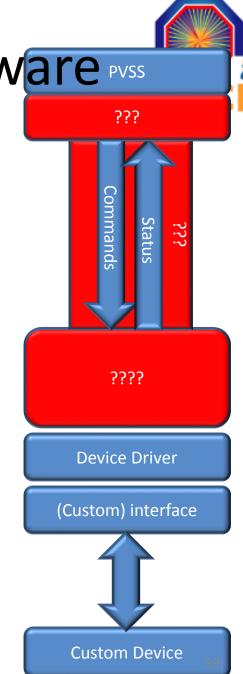


- OPC industrial standard
- Implemented in PVSS as a manager providing generic interface
- In ALICE most commercial devices are controlled via OPC
- ~200 000 OPC items used in DCS



Controlling Custom Hardware

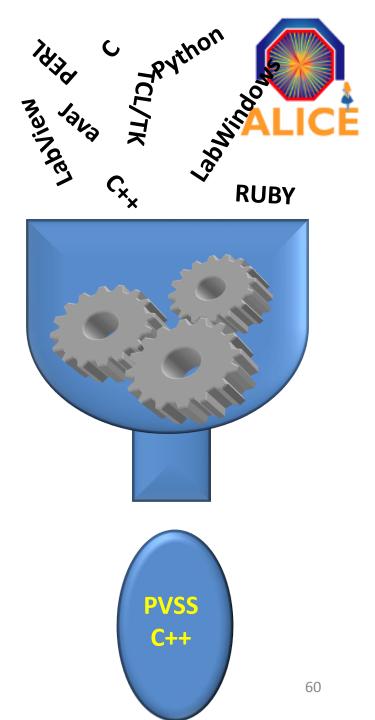
- Custom modules typically come with software packages developed by engineers
 - Incompatible with PVSS
- Missing link to PVSS
 - Transport protocol
 - Communication standard
- The main objective of ALICE DCS:
 - Hide the device complexity
 - Provide a generic communication protocol covering all custom architectures





 The tools supplied with the hardware were designed for laboratory environment

- First step:
 - PVSS and C++ imposed as the only platforms for the production system

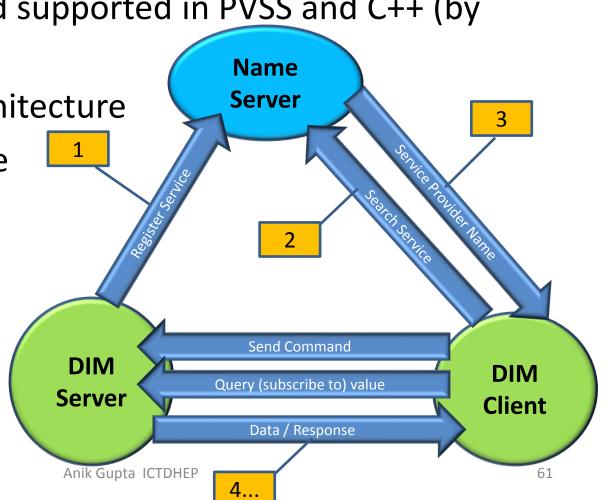


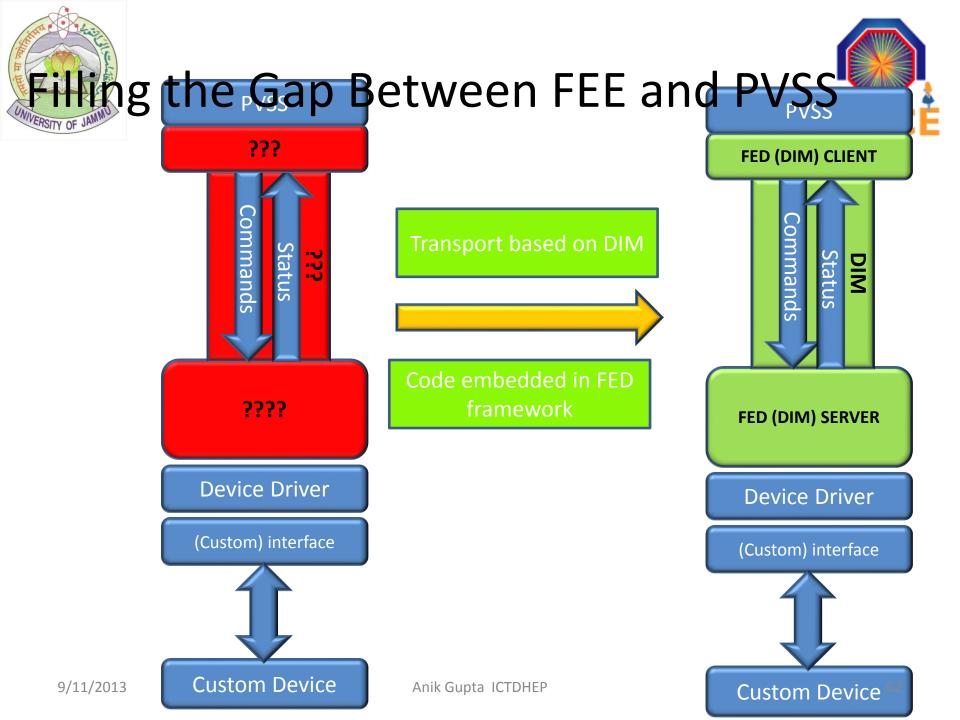


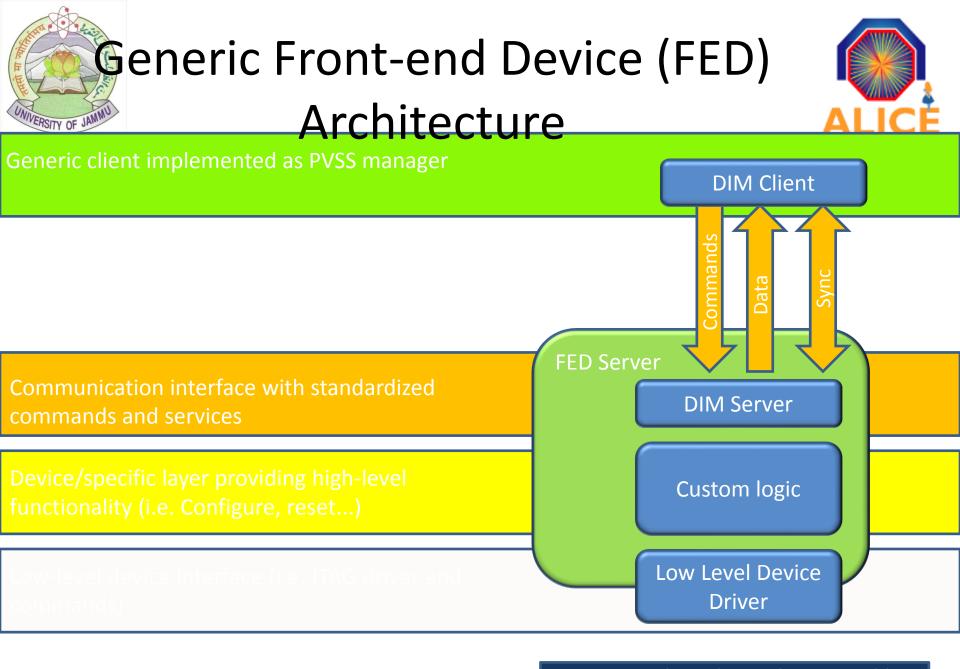
The Choice of the Transport Protocol



- CERN DIM used for command and data transfer
 - Implemented and supported in PVSS and C++ (by CERN)
 - Client/server architecture
 - Robust and stable







9/11/2013

Anik Gupta ICTDHE

~100 000 data channels serviced by FEDs in ALICE