

ALICE HLT TPC Tracking on GPUs

I: Introduction

II: Integration

III: GPU Tracker Performance

IV: CPU / GPU Tracker Comparison

David Rohr for the ALICE Collaboration
CERN – 28.5.2013

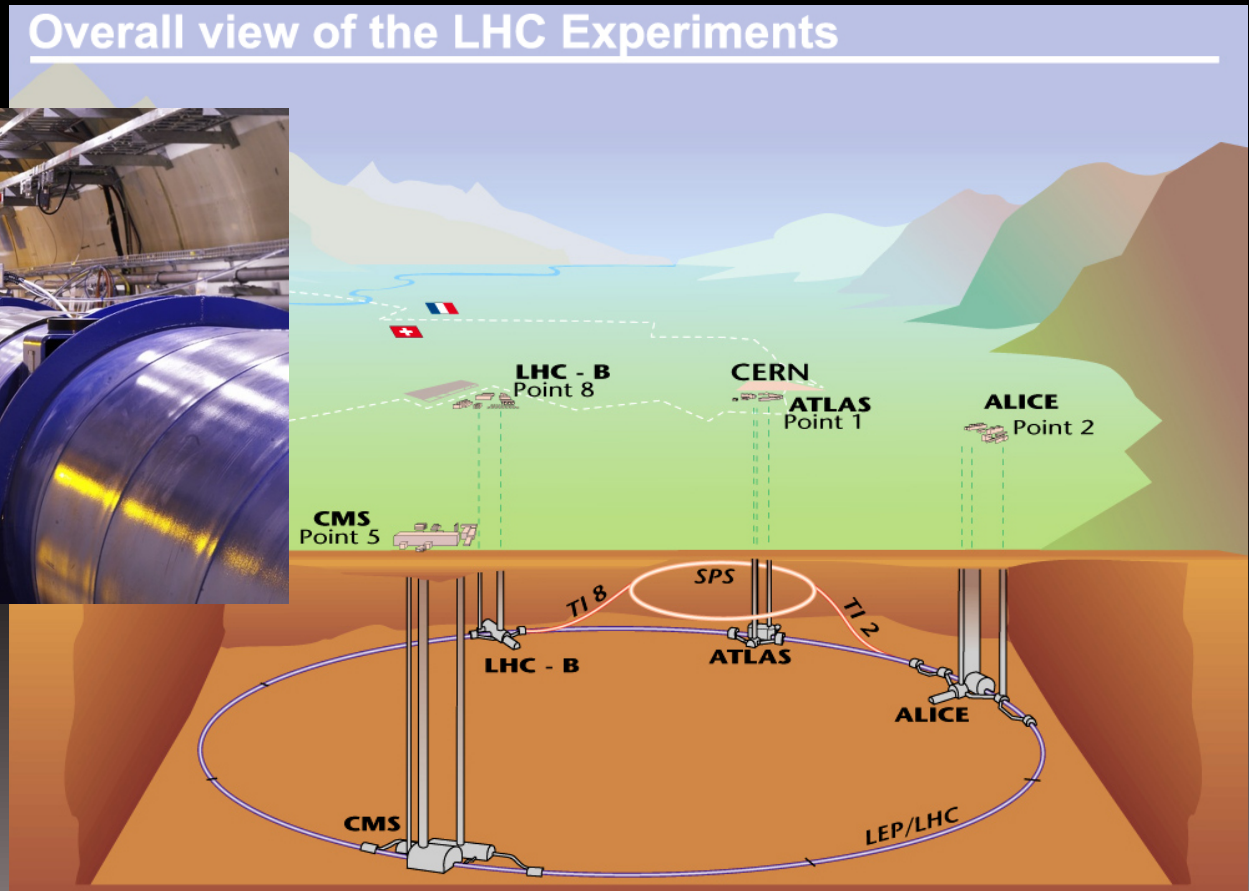


INTRODUCTION

Introduction

- The Large Hadron Collider (LHC) at CERN
 - The Large Hadron Collider is today's largest particle accelerator colliding protons at an energy of up to 14 TeV and ions at more than 1 PeV in its 27km tunnel.

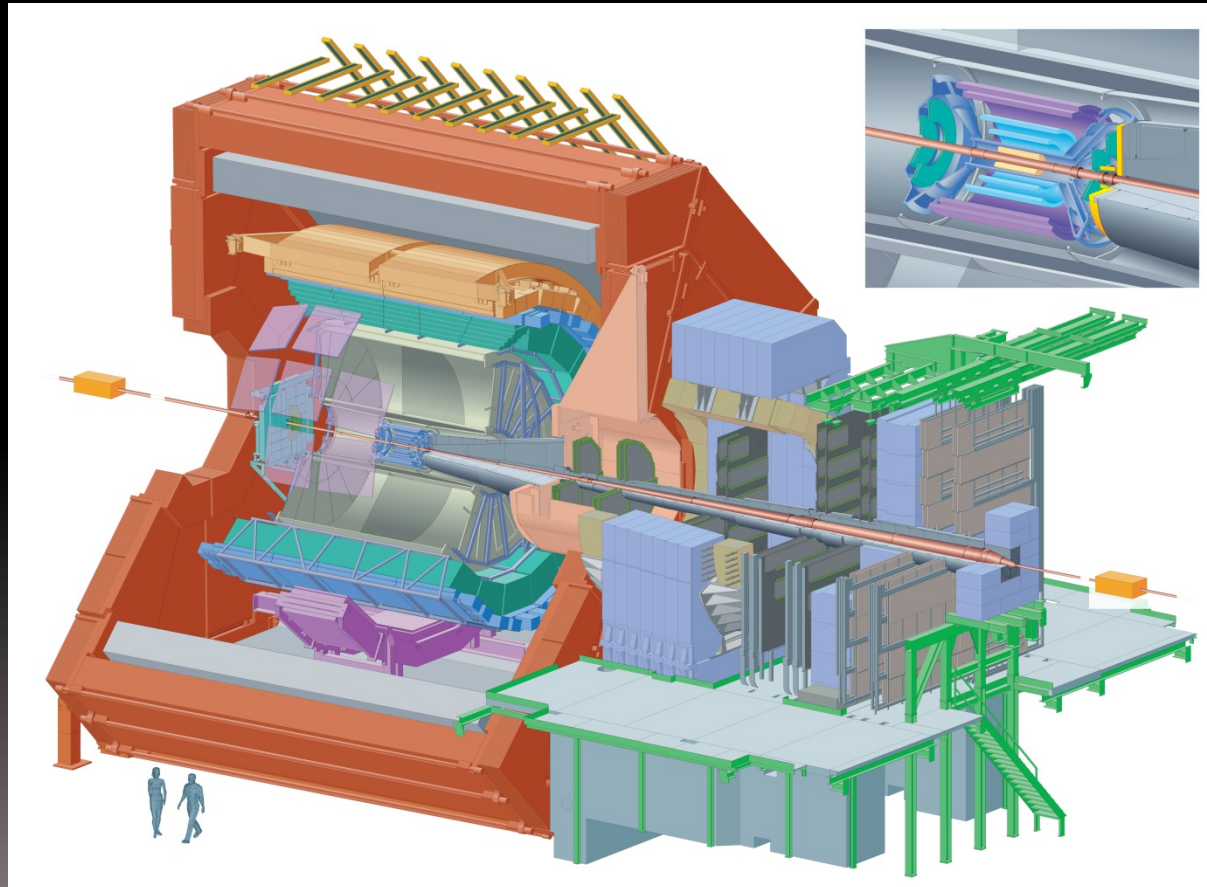
Overall view of the LHC Experiments



Introduction

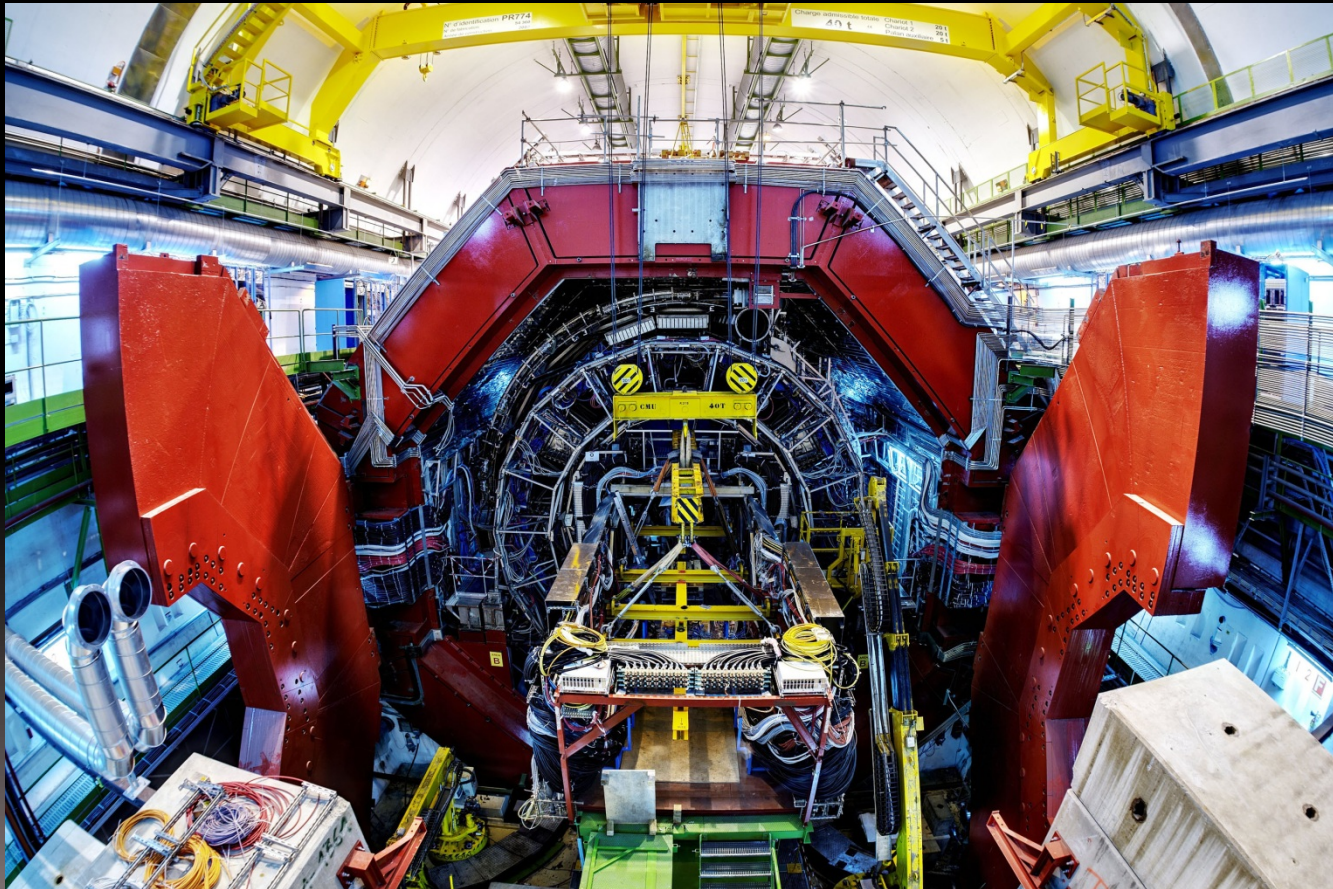
- The ALICE detector

- ALICE is one of the major four experiments of the Large Hadron Collider at CERN. It was specifically designed to study heavy ion collisions.



Introduction

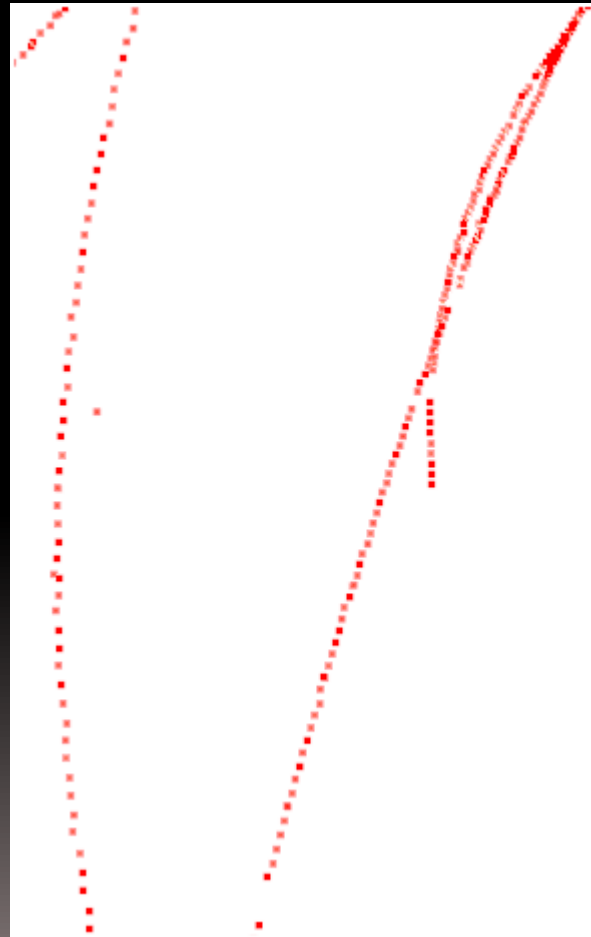
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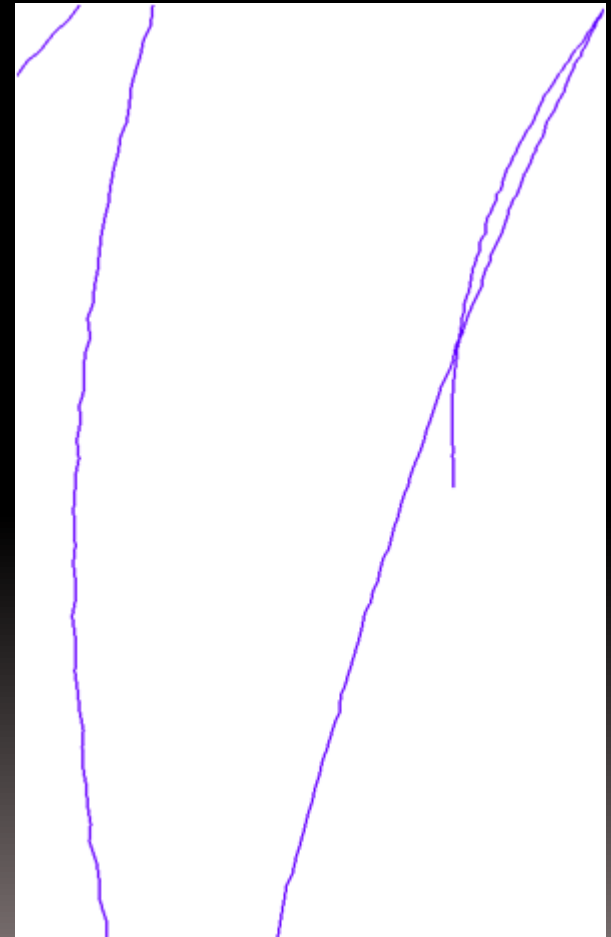
Introduction

Tracking

Clusters

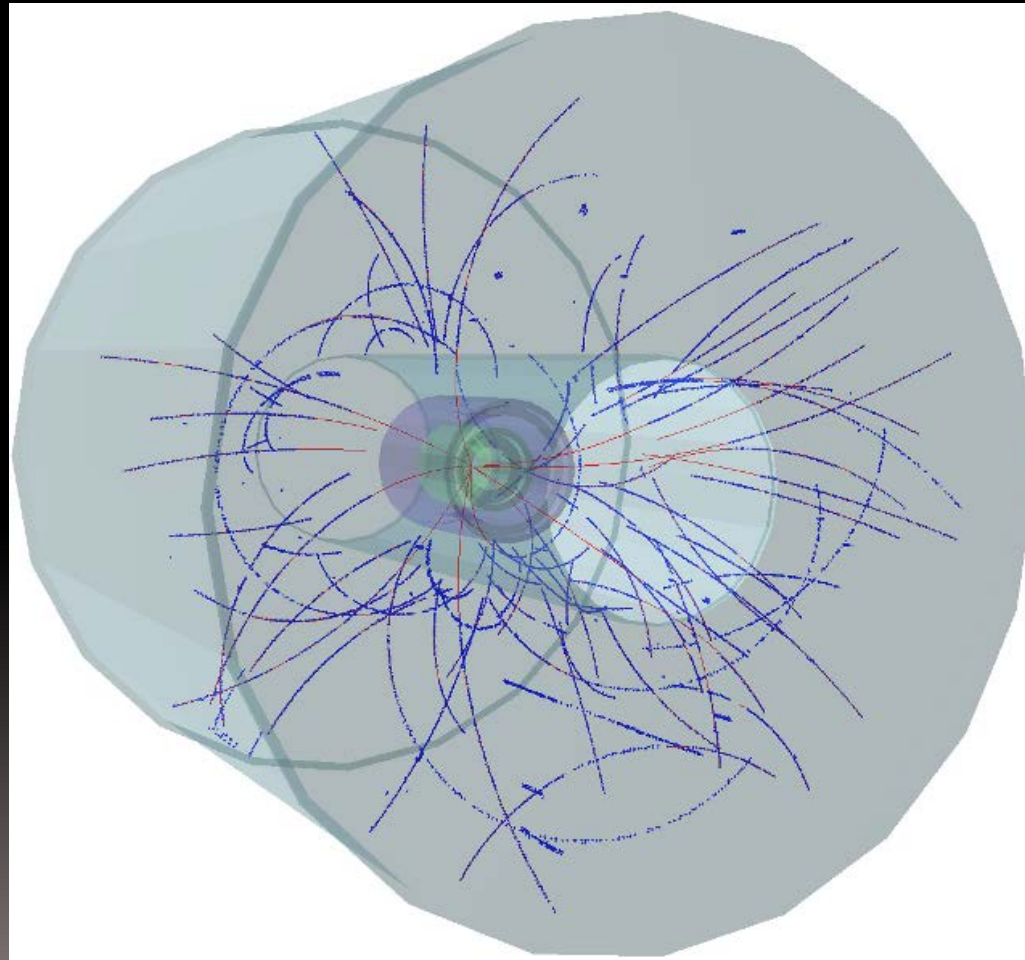


Tracks



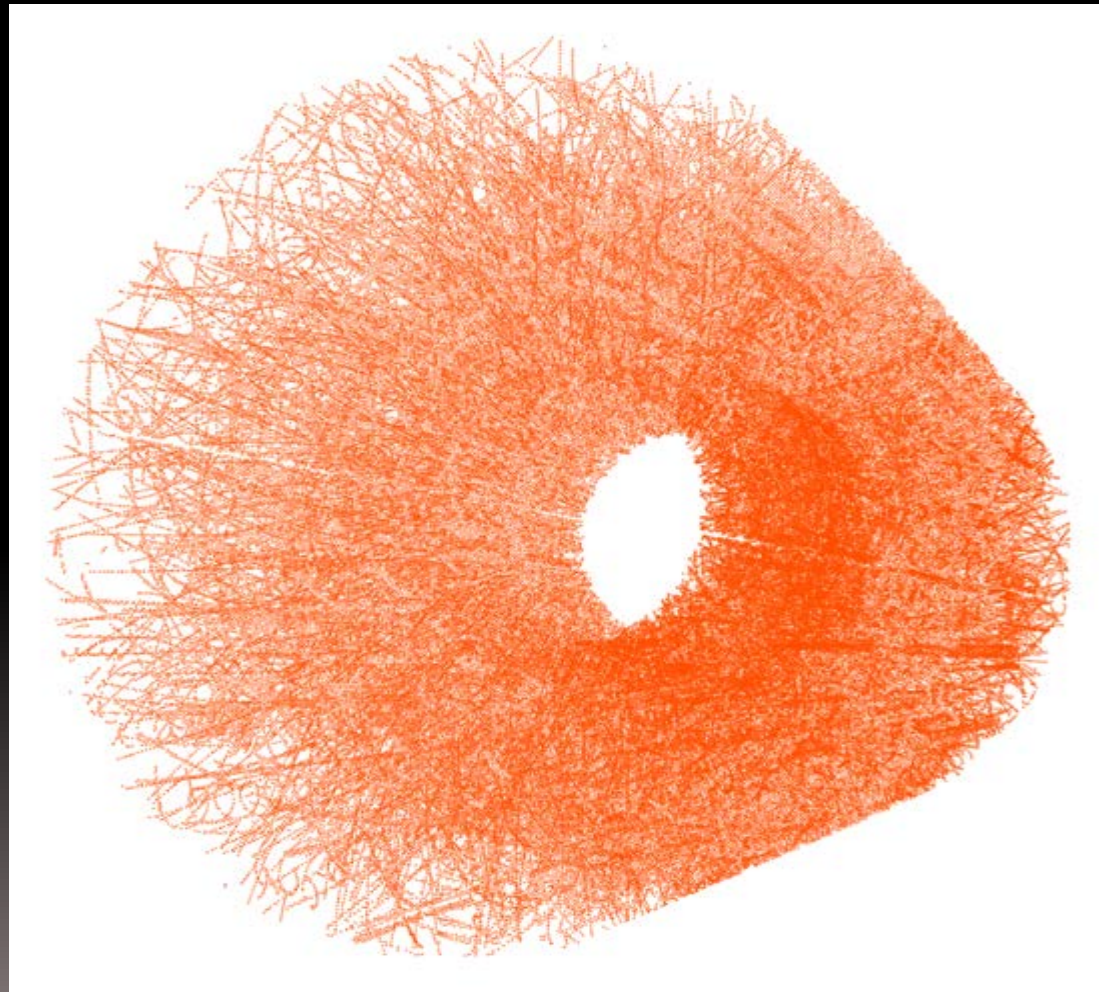
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- Proton event in TPC



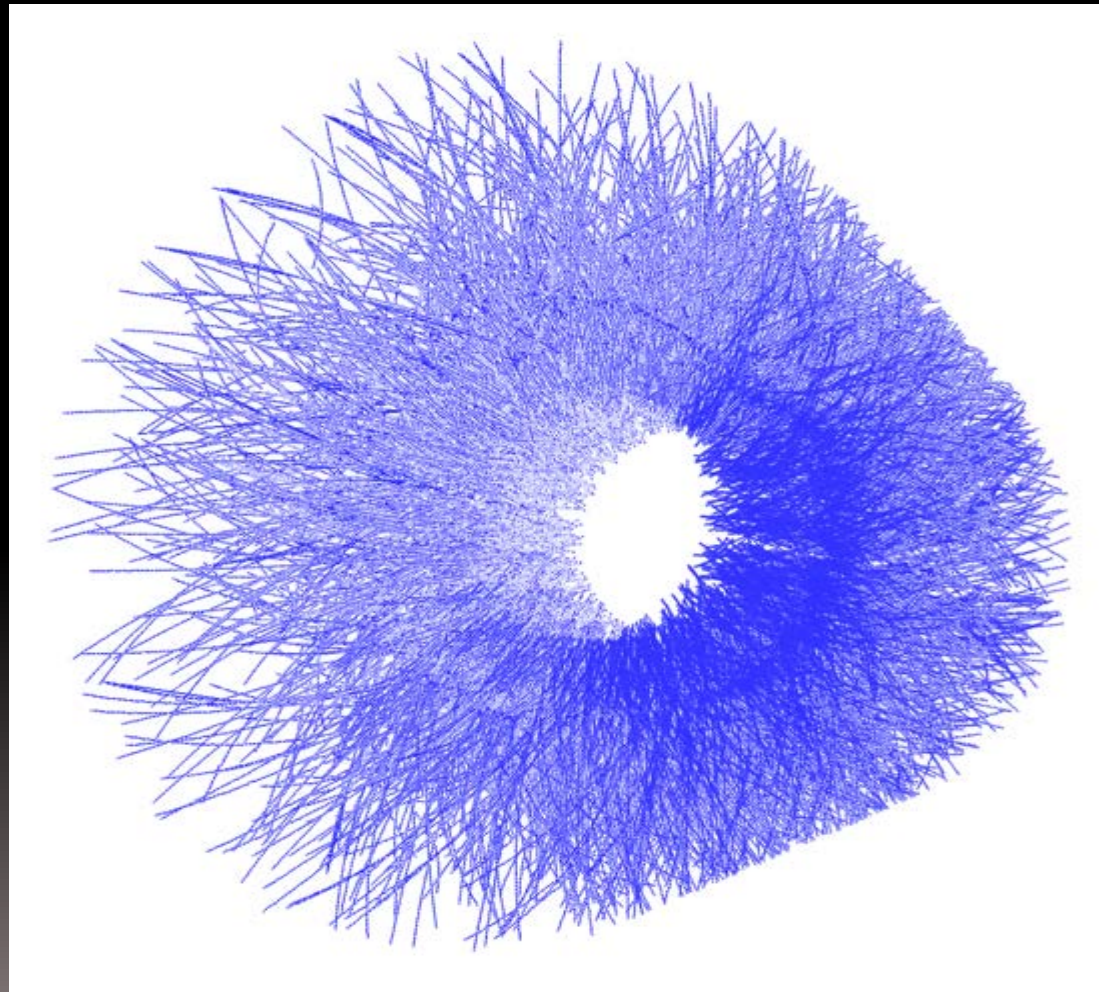
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- TPC clusters of heavy-ion event.



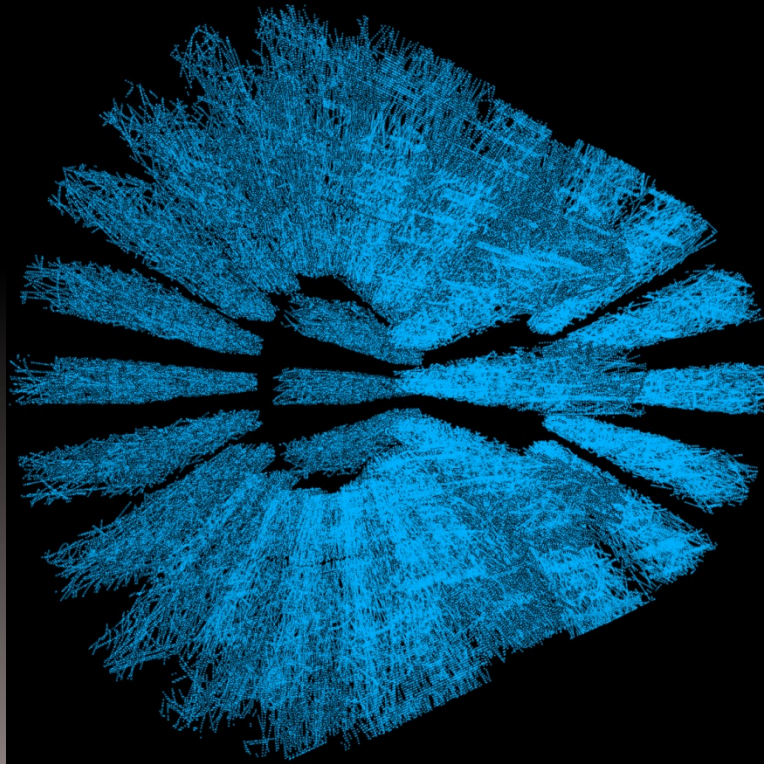
Introduction

- Tracks reconstructed from the clusters.



Introduction

- ALICE HLT tracker divides the TPC in slices and processes the slices individually.
- Track segments from all slices are merged later.



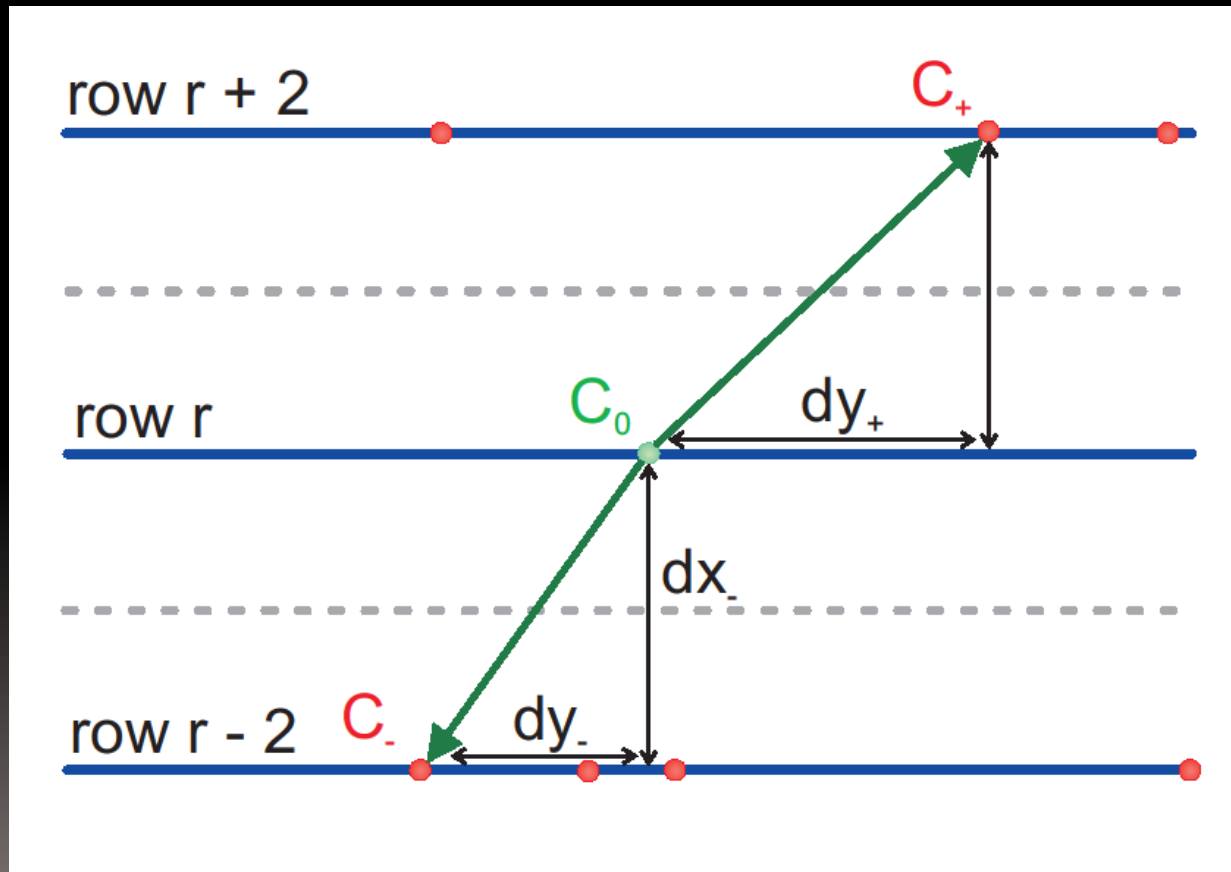
Introduction

Tracking algorithm

Category of task	Name of task	Description on task
	(Initialization)	
Combinatorial part (Cellular automation)	I: Neighbors finding	Construct seeds (Track candidates)
	II: Evolution	
Kalman filter part	III: Tracklet construction	Fit seed, extrapolate tracklet, find new clusters
	IV: Tracklet selection	Select good tracklets, assign clusters to tracks
	(Tracklet output)	

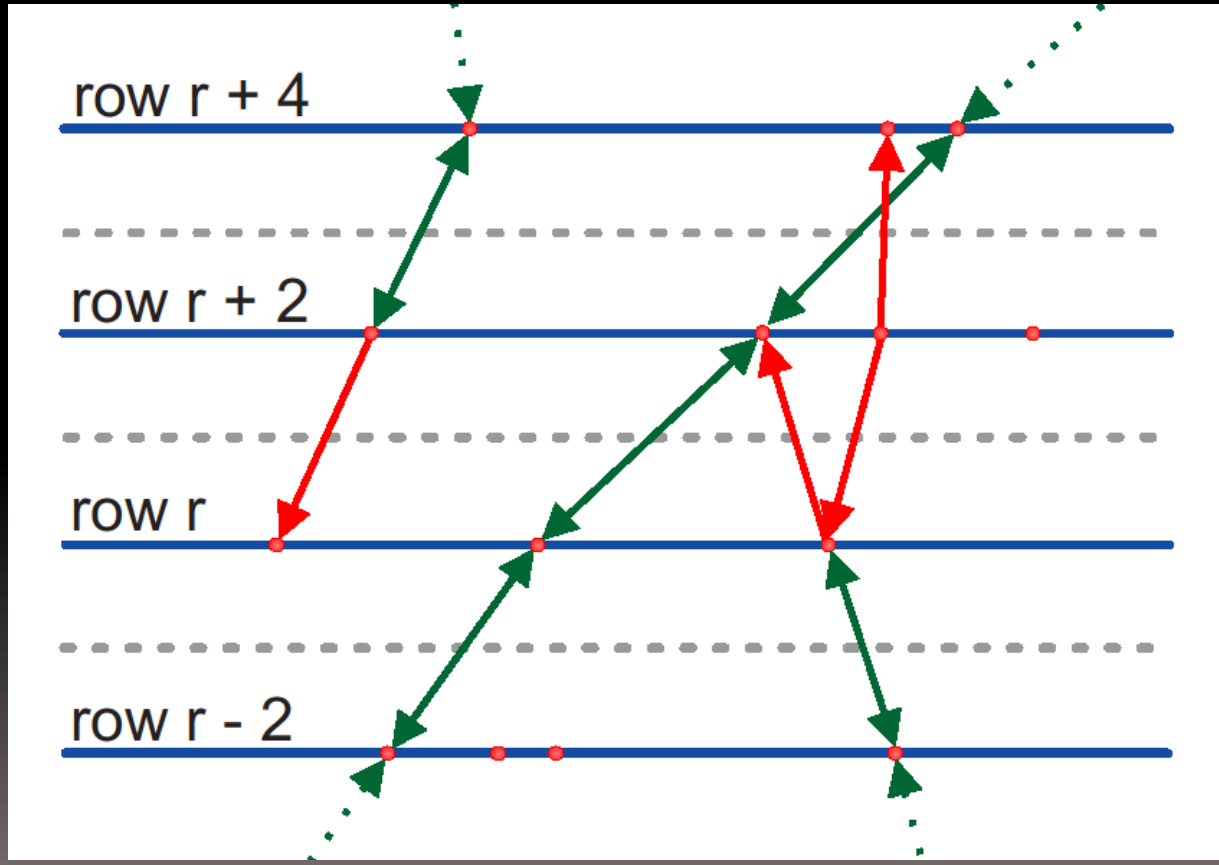
Introduction

Illustration of neighbors finding



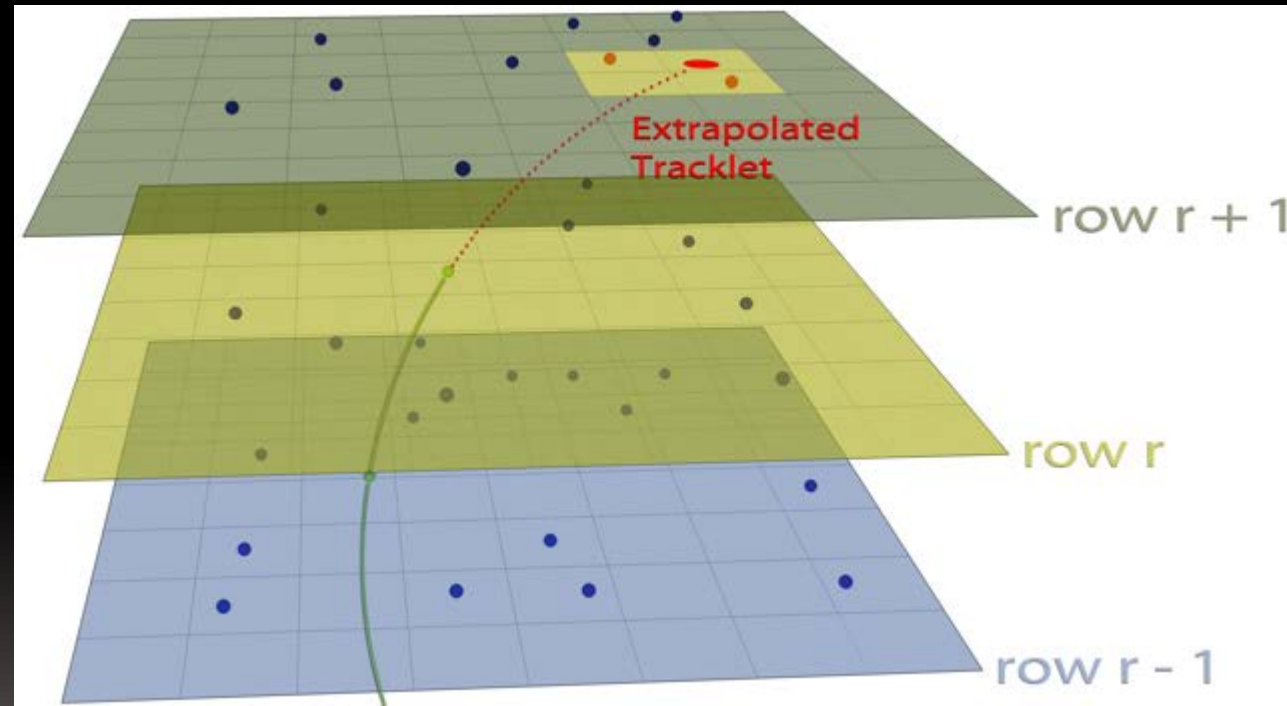
Introduction

Illustration of evolution step



Introduction

Illustration of tracklet construction



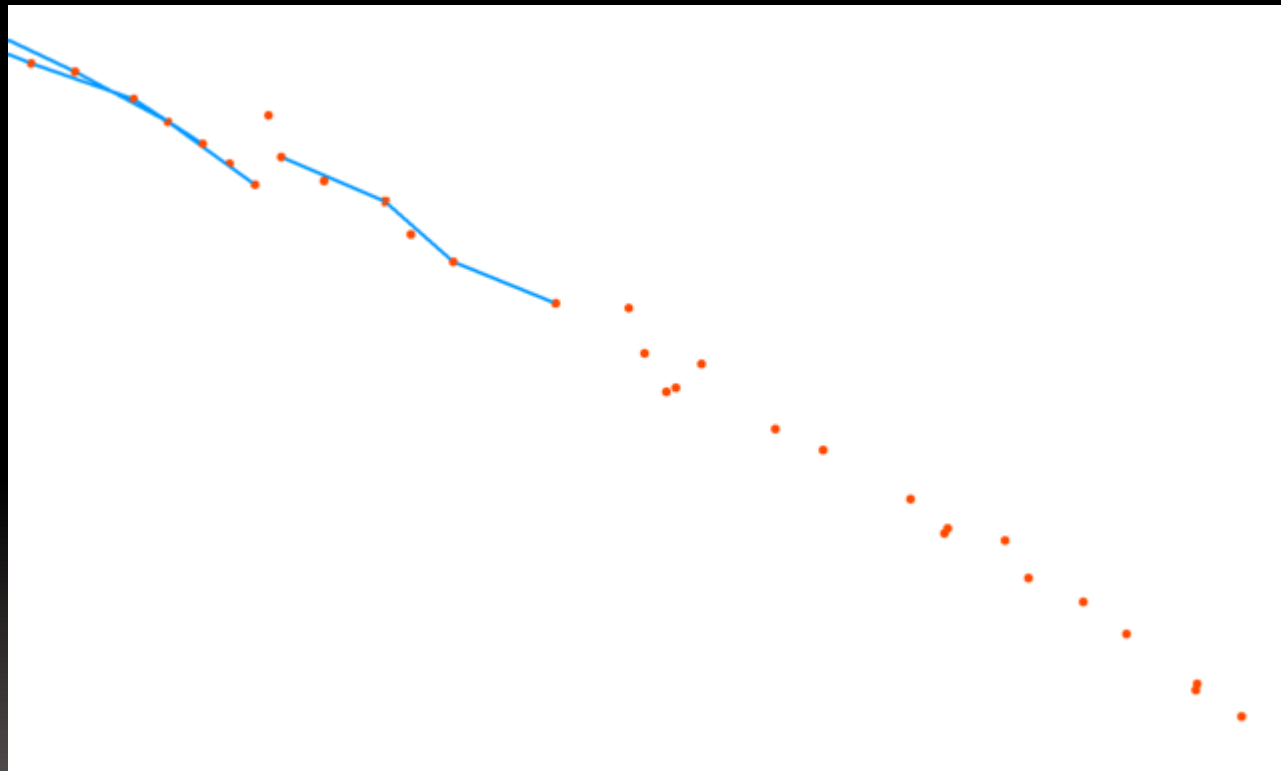
Green: Seed

Red: Extrapolation

Clusters close to the extrapolation point are searched

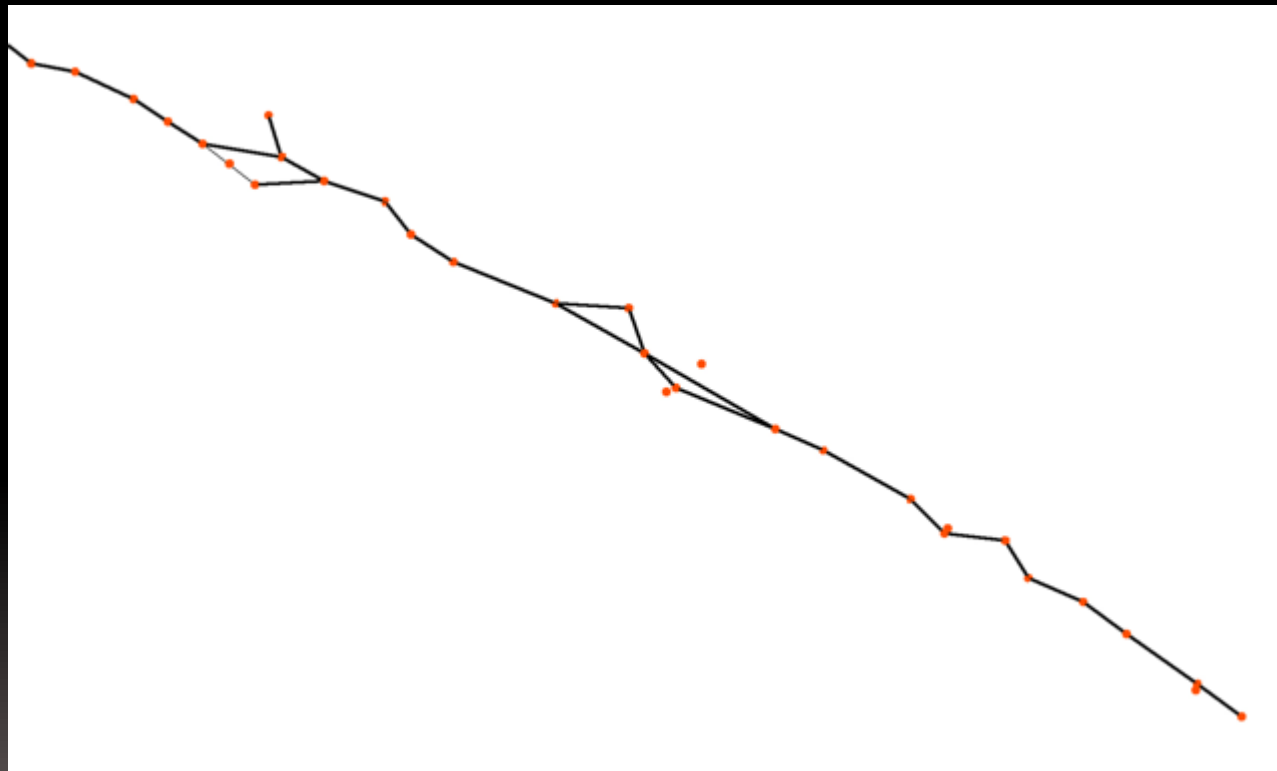
Introduction

Illustration of evolution step



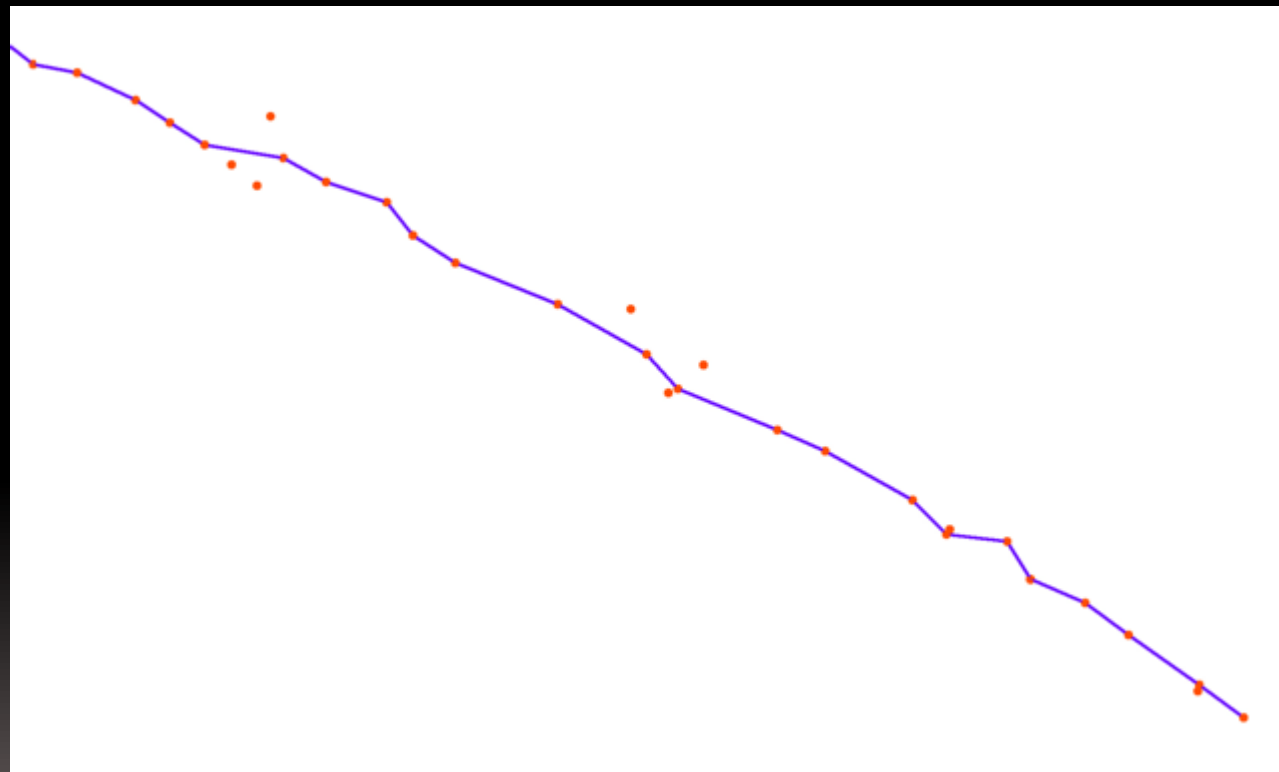
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Illustration of tracklet construction



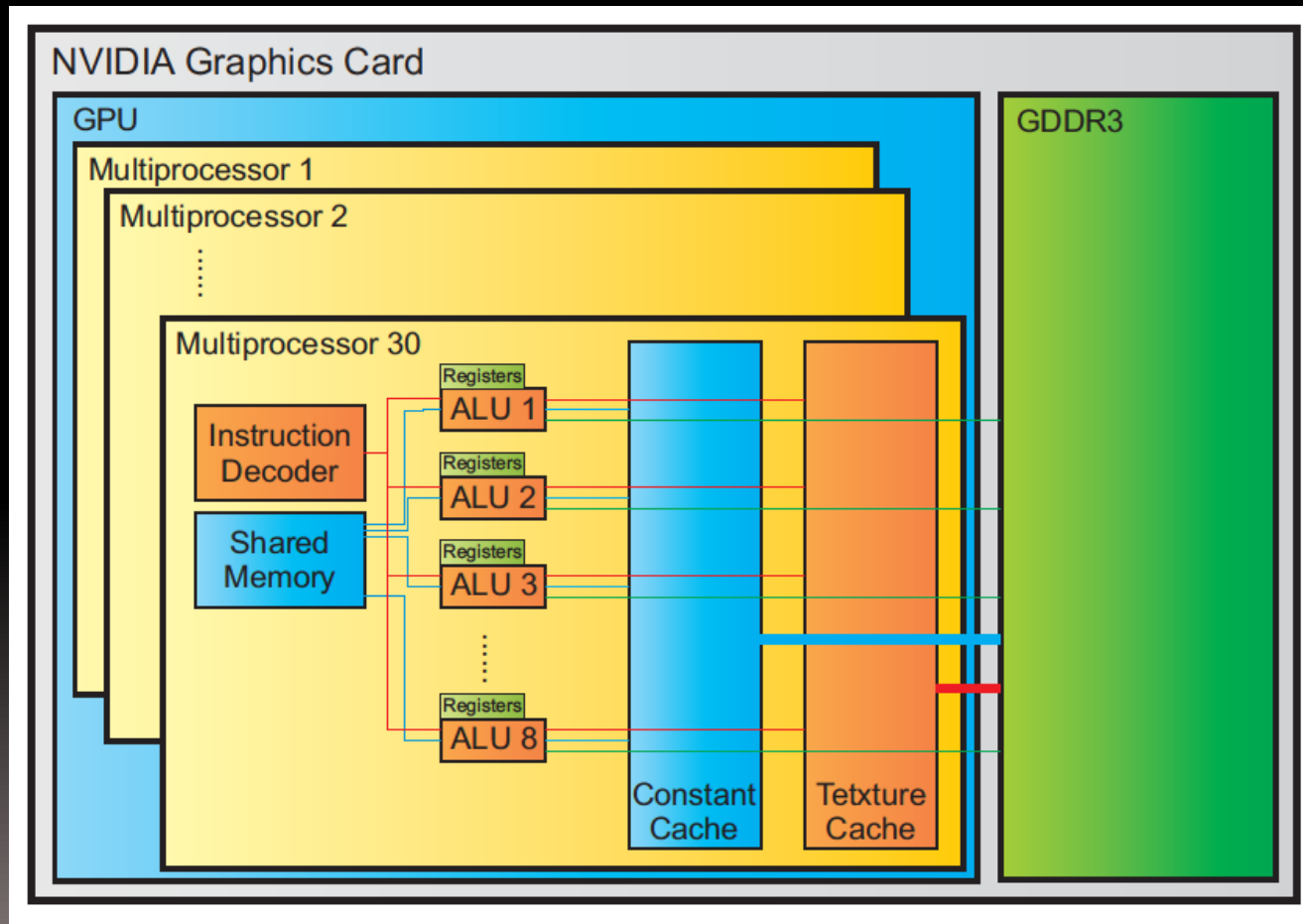
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Illustration of tracklet selection



Introduction

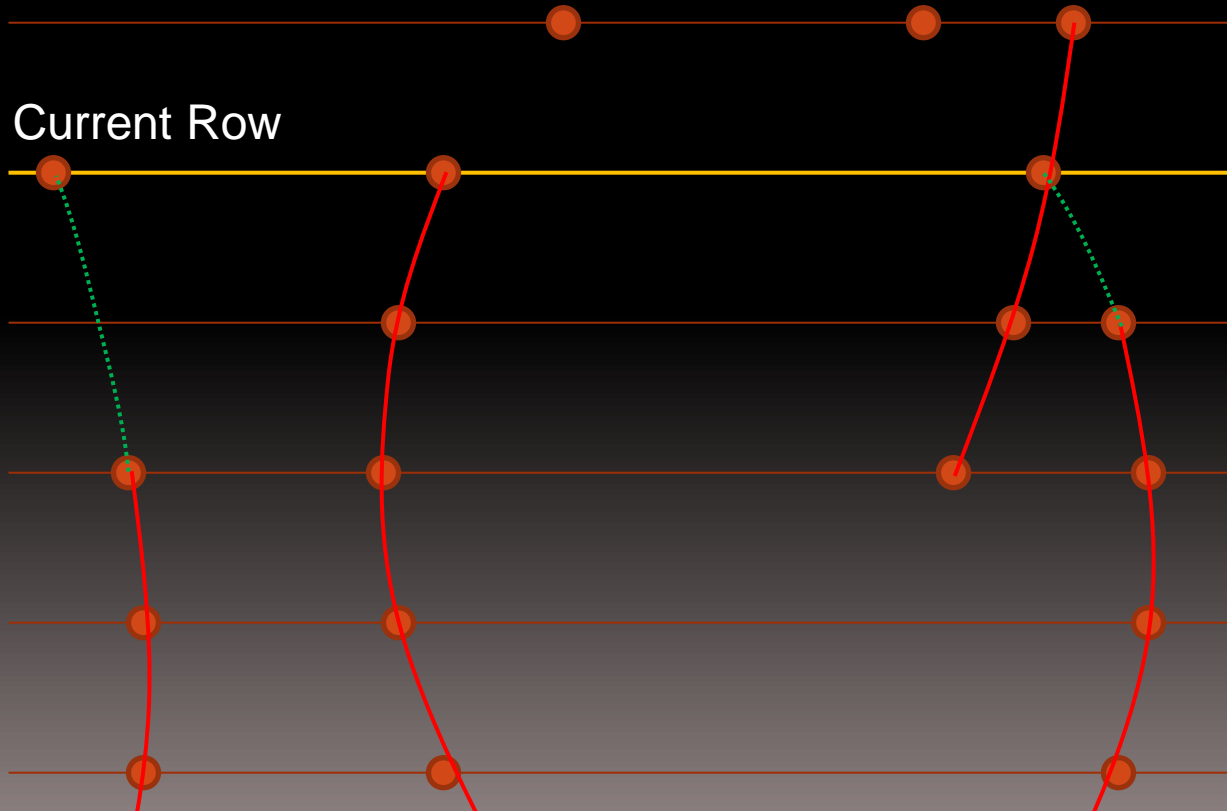
NVIDIA CUDA GPU



Introduction

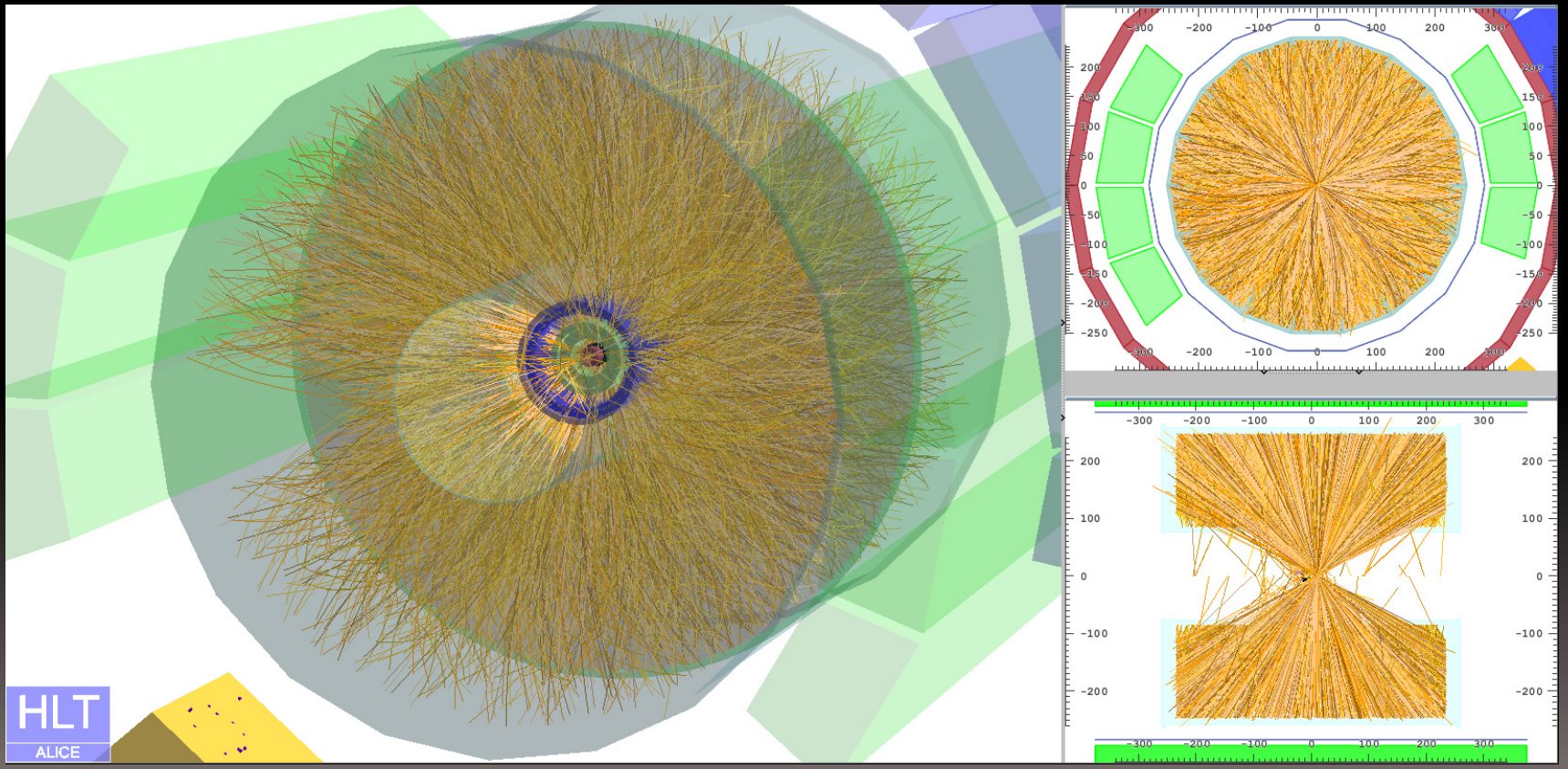
Parallel Tracklet Construction

Tracklets are independent and can be processed simultaneously
Because of Data Locality the Tracklets are processed for a common Row



Introduction

Screenshot of ALICE Online-Event-Display during first physics-fill with active GPU Tracker



A vertical bar on the left side of the slide, composed of several colored segments: a small red segment at the top, followed by a grey segment, a yellow segment, and a larger red segment at the bottom.

INTEGRATION

Integration

- GPU and CPU tracker share a common source files.
- Specialist wrappers for CPU and GPU exist, that include these common files.

common.cpp:

```
__DECL FitTrack(int n) {  
....  
}
```

cpu_wrapper.cpp:

```
#define __DECL void  
#include ``common.cpp``  
  
void FitTracks() {  
  for (int i = 0; i < nTr; i++) {  
    FitTrack(n);  
  }  
}
```

gpu_wrapper.cpp:

```
#define __DECL __device void  
#include ``common.cpp``  
  
__kernel void FitTracksGPU() {  
  FitTrack(threadIdx.x);  
}  
  
void FitTracks() {  
  FitTracksGPU<<<nTr>>>();  
}
```

Integration

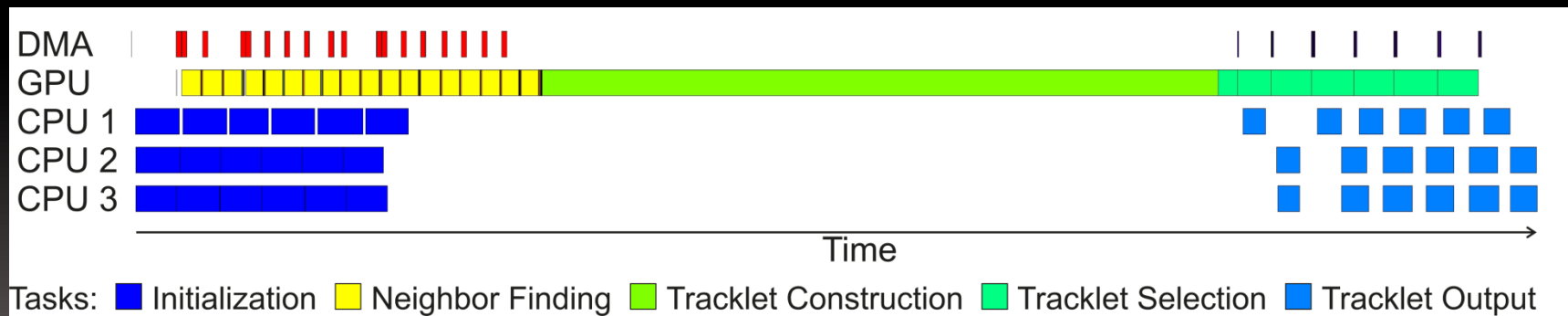
- The GPU Tracker is accessed via a virtual interface. The actual implementation is contained in a dedicated library (cagpu), which links against the CUDA runtime.
- AliRoot opens cagpu with dlopen, this creates a clear separation between AliRoot and CUDA.
- The same AliRoot binaries can be used on compute nodes with GPU and without GPU.
- This scheme is easily adoptable to other programming APIs, such as OpenCL.



CPU / GPU PERFORMANCE

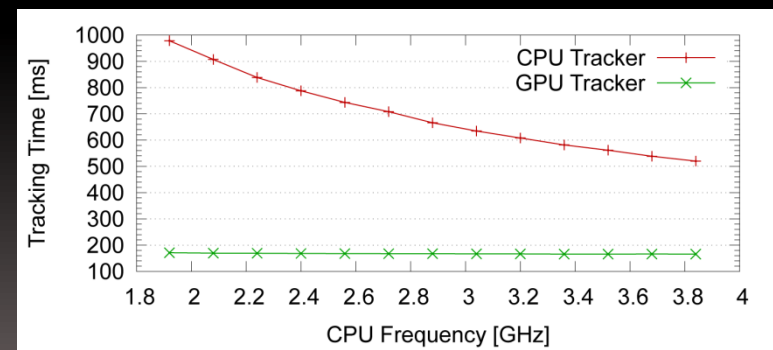
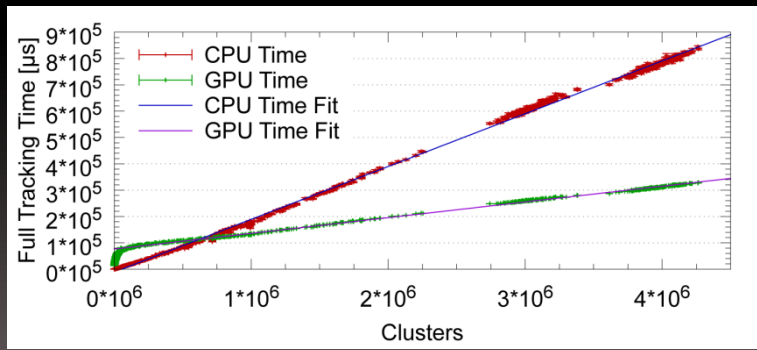
GPU Tracker Performance

- For good performance the GPU tracker pipelines the slices such that initialization on CPU, GPU tracking, and DMA transfer can overlap.
- A multithreaded pipeline ensures the CPU can keep step.



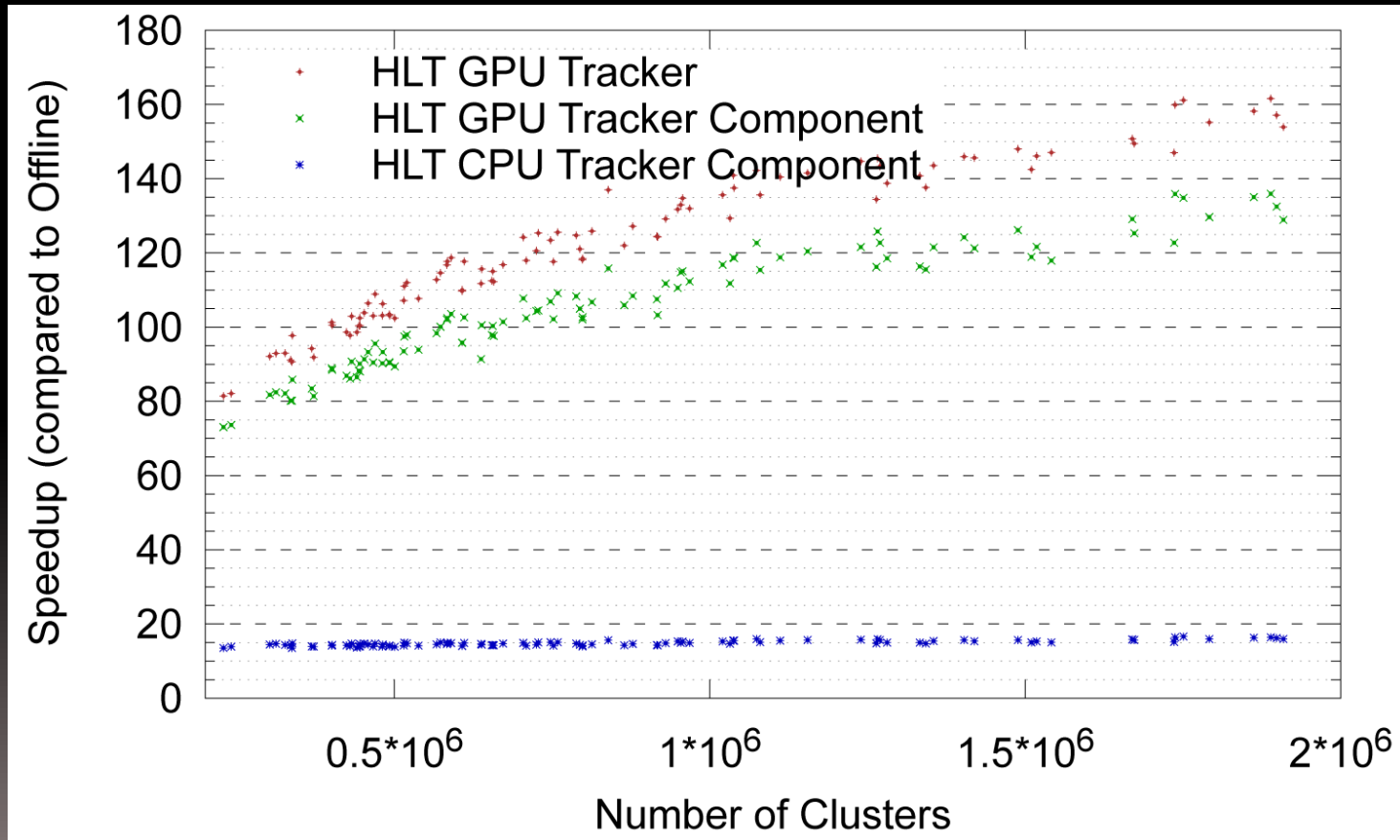
GPU Tracker Performance

- Tracking time depends linearly on input data size.
- GPU tracking time independent from CPU performance (if initialization is fast enough).



GPU Tracker Performance

- Speedup of HLT GPU tracker v.s.offline and CPU Tracker (four CPU cores used each)





CPU / GPU TRACKER COMPARISON

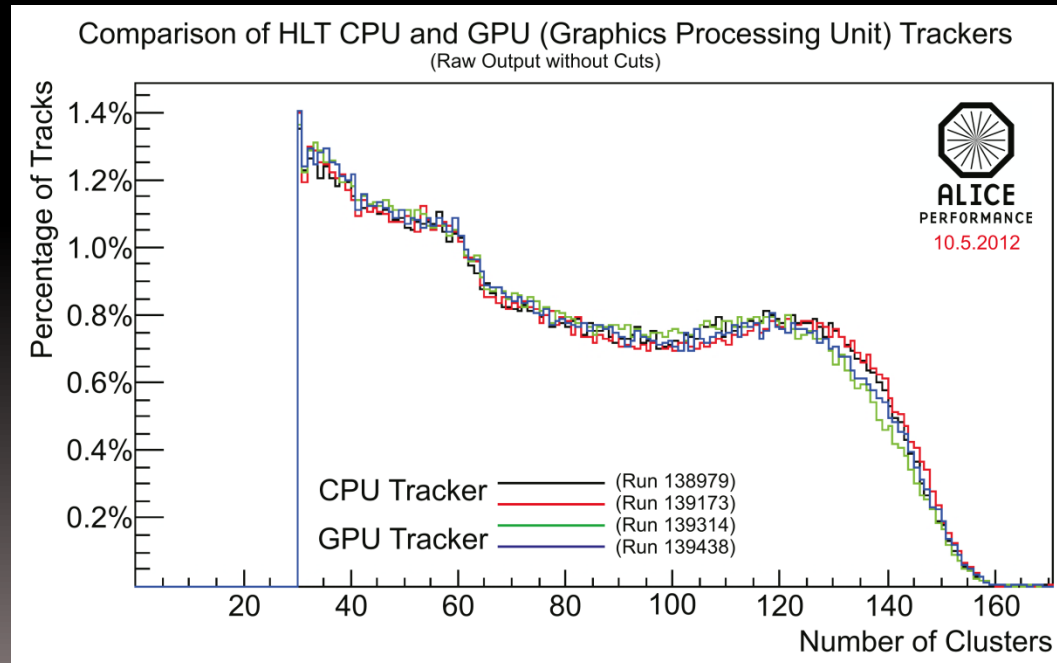
CPU / GPU Tracker Comparison

- Comparison of GPU and CPU Tracker during 2010 run
 - No significant variations in physically observables.
 - Only the number of clusters per track statistics shows a variation.



CPU / GPU Tracker Consistency

- Inconsistencies during November 2010 run
 - Cluster to track assignment
 - Track Merger
 - Non-associative floating point arithmetics



CPU / GPU Tracker Consistency

- Cluster to track assignment
 - **Problem:** Cluster to track assignment was depending on the order of the tracks.
 - Each cluster was assigned to the longest possible track. Out of two tracks of the same length, the first one was chosen.
 - Concurrent GPU tracking processes the tracks in an undefined order.
 - **Solution:** Both the χ^2 and the track length are used as criteria. It is extremely unlikely that two tracks coincide in both values.



CPU / GPU Tracker Consistency

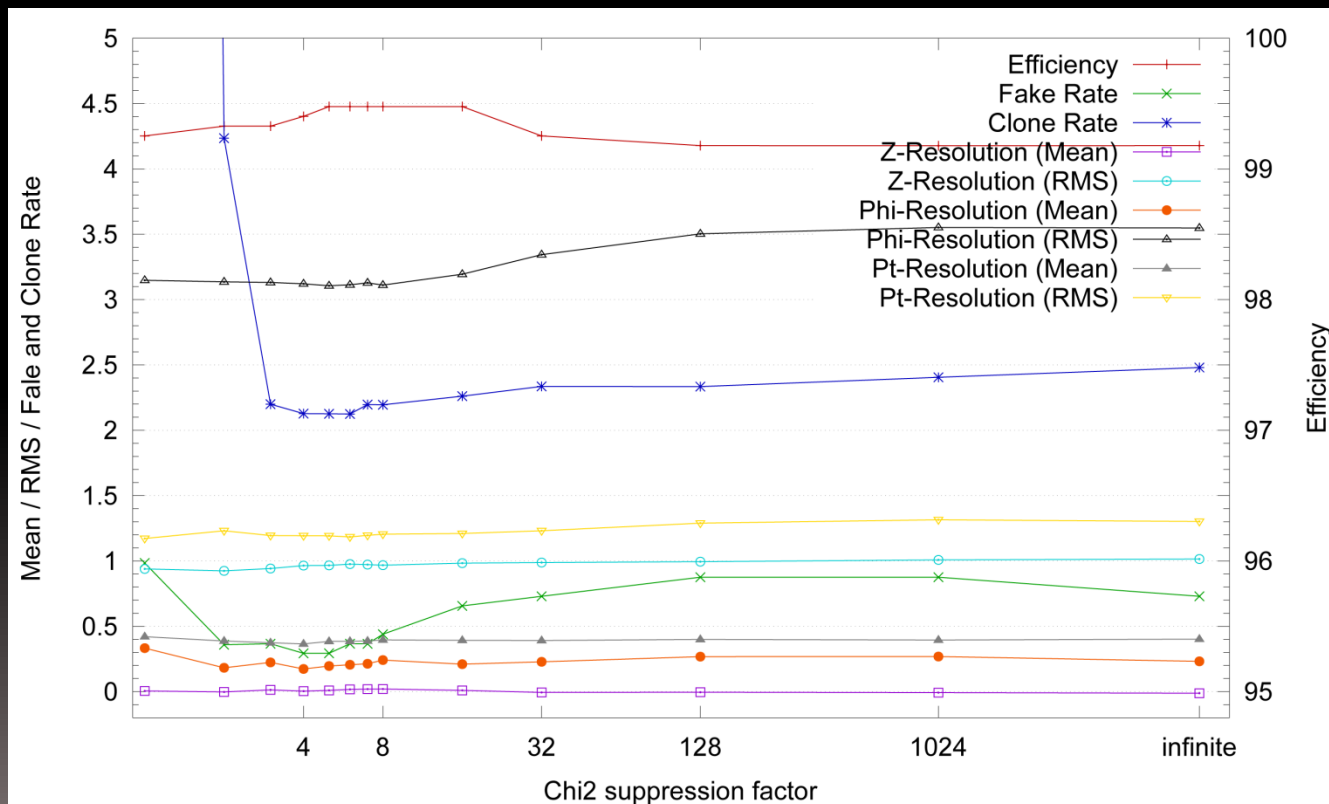
- How to combine χ^2 and track length?
 - Regarding the deviation between the track and the cluster for each cluster individually leads to many clones.
 - Hence, the total deviation of the track is used.
 - Small tracks have a higher probability for having a small χ^2 , the right weight for both parameters must be determined.
 - Therefore, a χ^2 suppression factor is introduced, that weights χ^2 less than the tracklet length.

CPU / GPU Tracker Consistency

- Determinining best suppression factor
 - A factor of infinite equals the old method were only the track length is decisive.
 - Incorporating χ^2 improves efficiency and resolution.
 - At low suppression factor only the χ^2 is decisive and the tracking becomes unstable.
 - Currently, a factor of 6 is used.

CPU / GPU Tracker Consistency

- Determinining best suppression factor



CPU / GPU Tracker Consistency

- Track merger
 - **Problem:** Result of the track merger depended on the order of input tracks.
 - **Solution:** Merger input is sorted.
 - Sorting is performed during a reformatting step.
 - No additional data copy.
 - No performance penalty.



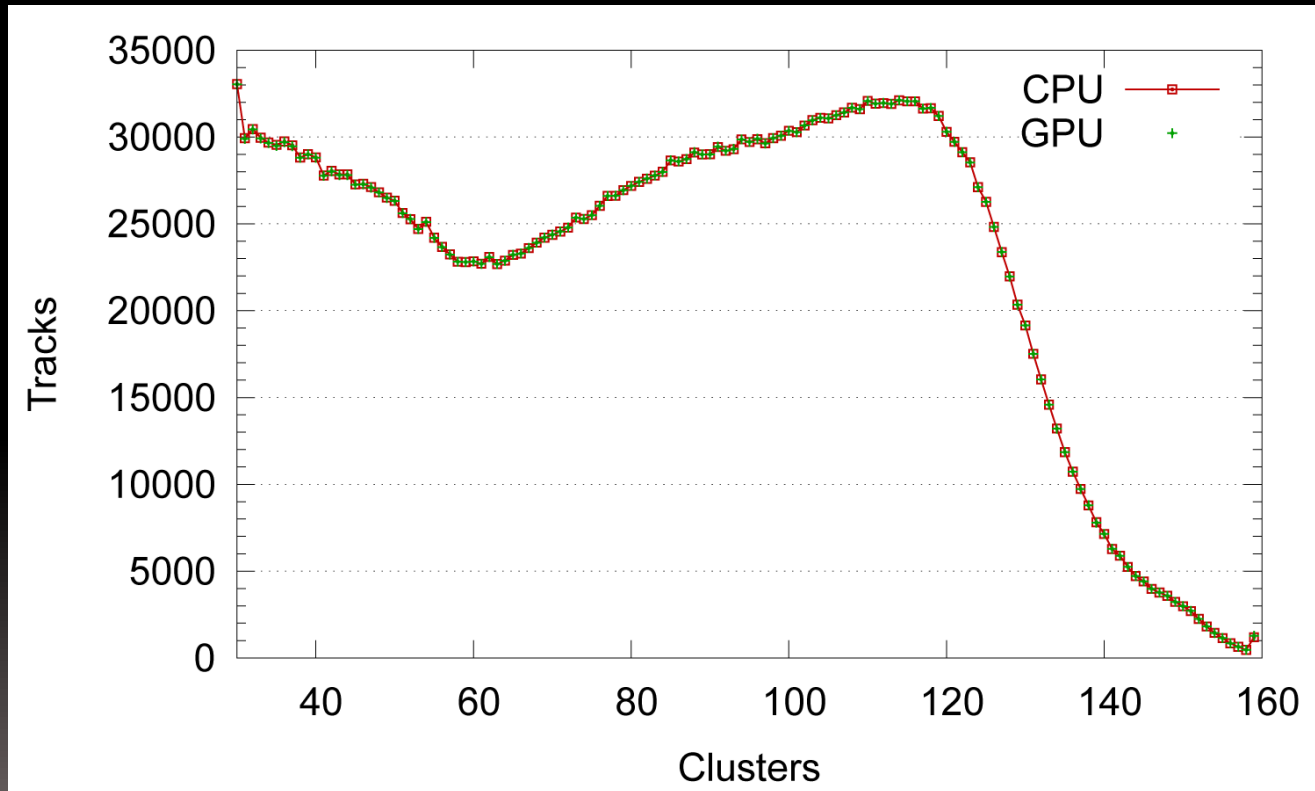
CPU / GPU Tracker Consistency

- Non associative floating point arithmetics
 - **Problem:** Different compilers perform the arithmetics in different order (also on the CPU).
 - **Solution:** Cannot be fixed, but...
 - Slight variations during the extrapolations do not matter as long as the clusters stay the same.
 - Inconsistent clusters: 0,00024%



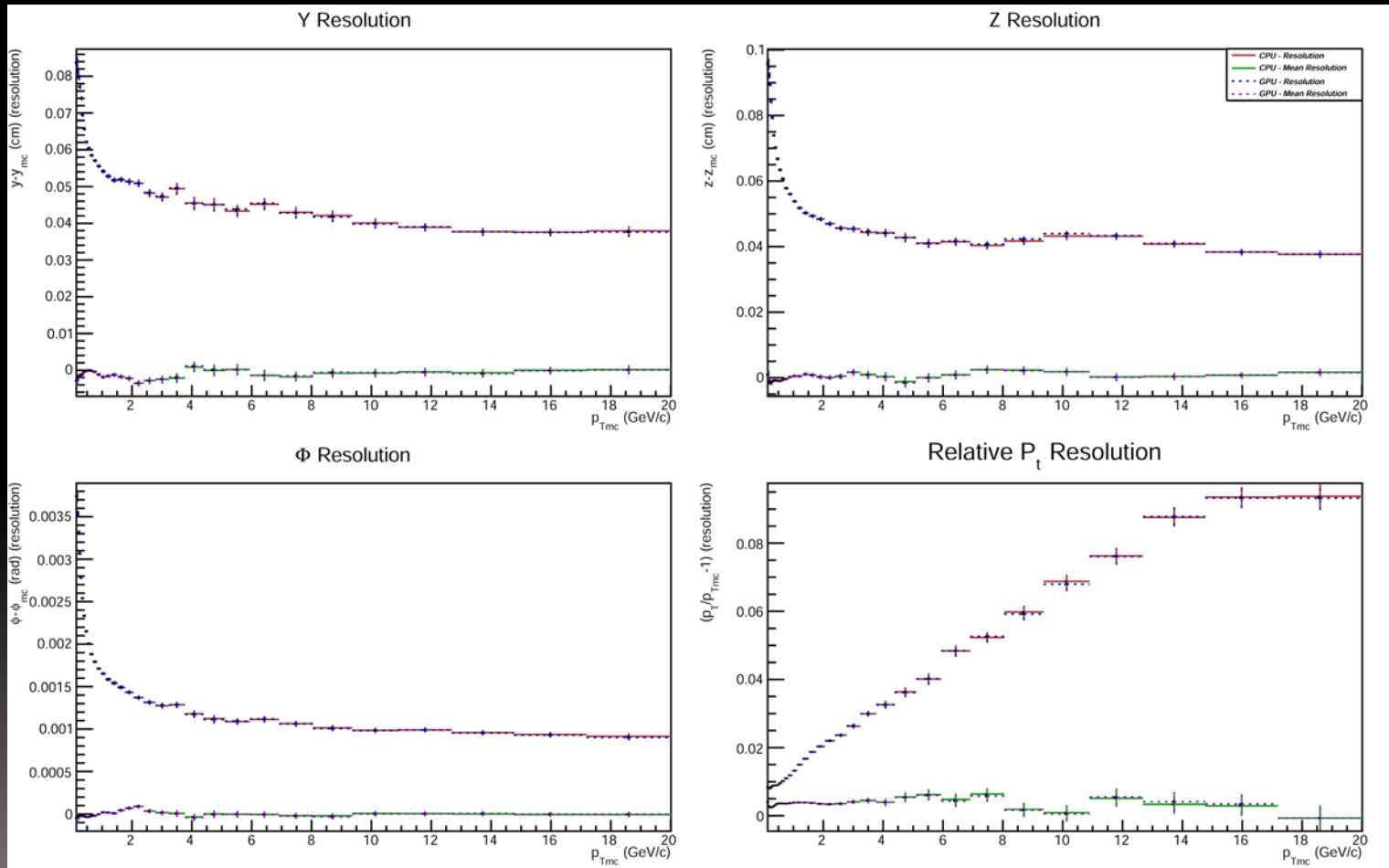
CPU / GPU Tracker Consistency

- Cluster per track statistic with improvements



CPU / GPU Tracker Consistency

- Resolution Comparison



Summary ALICE GPU Tracker

- Threefold performance increase of GPU tracker compared to all CPUs of a node, tenfold increase in a reasonable HLT scenario.
- GPU tracker performance is independent from CPU and depends linearly on data size.
- Results of GPU and CPU tracker match almost completely. Only 0.00024% of the clusters differ due to non-associative floating-point arithmetic.
- Common source code ensures great maintainability, separation from libAliHLTPC makes a common binary work on all nodes – with and without GPU.
- With global tracking the tracker can track across slice boundaries but still exploit data locality

Lattice QCD on GPUs

- We use GPU-enabled lattice code based on OpenCL.
- Simulation of strong force.
- Lattice-QCD is essentially a Monte-Carlo simulation.
- Computes statistics for various trajectory in the phase space under certain constraints (energy conservation).
- Entirely memory-throughput-bound problem.



Lattice QCD on GPUs

- Two sources for inconsistent results between CPU and GPU
 - Fast Random Number Generator used, parallel execution processes other paths in the phase-space.
 - This is no problem since at the end only the average counts, the exact path is not so relevant. Naturally, it should not be biased.
 - Also inconsistent results in deterministic steps like conjugate-gradient inversion algorithm.
 - Again, since the exact path in phase-space does not matter, this is no problem.

