

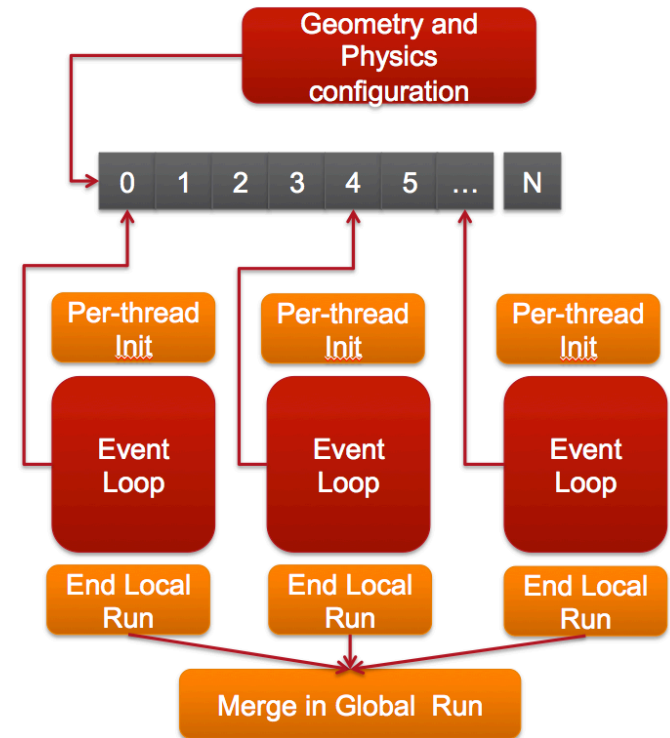
Hadronics Framework and MT

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Parallel session 7B - Hadronics issues related to MT

Review of MT workflow

- Basic design: only most memory consumption objects are shared
 - Geometry, EM tables
- There is a special “thread” (not a real thread, the main function): the master. It owns fully initialized G4 (physics, geometry), done in sequential mode, but does not process events during the event loop



Our goal

- Up to now **Hadronics is thread-private:**
 - Each worker owns instances of hadronics model/physics
 - Processes do not share anything
- To further reduce memory usage we can share parts of hadronics
- Use master thread to get data to-be-shared
 - Similarly to what is done in EM
 1. The master thread is configured before workers
 2. Workers EM processes get the pointer of the “pre-initialized” data to be shared

Kernel

- Kernel cannot have knowledge of hadronics framework
- Kernel has **single shared** instance of G4VUserPhysicsList, during run initialization:
 1. It loops on all particles and calls:
`G4VserPhsyicsList::PreaprePhysicsTable(G4ParticleDefinition*) ::BuildBphysicsTable(G4ParticleDefinition*)`
 2. These will loop on all processes attached to the particles and call:
 - `G4VProcess::{Prepare,Build}PhysicsTable(const G4ParticleDefinition&)` for sequential and master thread
 - `G4VProcess::{Prepare,Build}WorkerPhysicsTable(const G4ParticleDefinition&)` for workers

Extended G4VProcess interface

- `virtual void BuildWorkerPhysicsTable(const G4ParticleDefinition& part) { BuilPhysicsTable(part); }`
- `virtual void PrepareWorkerPhysicsTable(const G4ParticleDefinition&) { PreparePhysicsTable(part); }`
- The two methods provide default behavior (**fully backward compatible**)
- Additional method:
 - `const G4VProcess* GetMasterProcess() const;`
 - Can be used to get to-be-shared parts of process

- Two **separate** entities that can have a MT awareness:
 - Cross-sections
 - Hadronic Models
- Since the two are separate need to address both independently
- **G4HadronicProcess is generic container, should be modified minimally**

CrossSection : general considerations

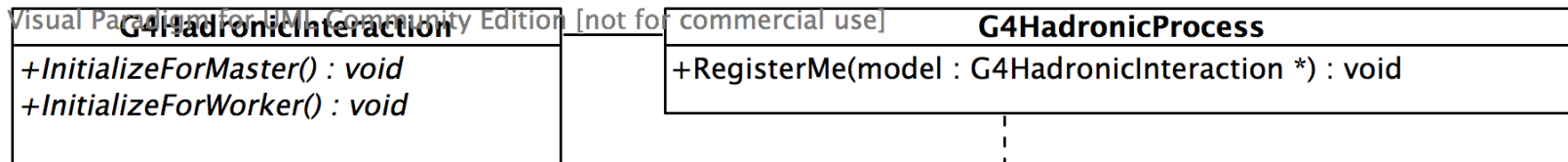
- Base class of hadronics framework, inherits from G4VProcess
- `G4HadronicProcess::PreparePhysicsTable(part)`
registers process for particle in TLS G4HadronicProcessStore,
nothing to do with XS
- `G4HadronicProcess::BuildPhysicsTable(part)`
 - Forward calls to `G4CrossSectionDataStore::BuildPhysicsTable`
 - That loops on all XS to call equivalent method
- Do we need to implement a `BuildWorkerPhysicsTable` in
cross-section classes?
 - **No** if we use factory when we want to share

- Two assumptions:
 1. Cross-section is implemented with factory mechanism
 - 2. The entire cross-section object can be shared among threads**
- if (1&&2) use factory macros:
 - **G4_DECLARE_XS_FACTORY** Factory creates cross-section for each thread
 - **G4_DECLARE_SHAREDXS_FACTORY** Factory creates a singleton (shared) cross-section
- To be tested, will need some further tuning
- If this does not cover all cases, we need to implement new `WorkerBuildPhysicsTable` mechanism

- `G4HadronicProcess` inherits from `G4VProcess`
- **Models are not owned directly by processes**, but registered in the `G4EnergyRangeManager` (one for each `G4HadronicProcess`)
- Models can be shared among processes
- For models `G4HadronicInteraction` there is **no state aware** methods: needs an “initialize” and “initialize for thread”

- `G4HadronicInteraction::InitializeForMaster()` , `::InitializeForWorker()`
 - Virtual methods
 - With default empty implementation
 - Full backward compatibility
- Modify
`G4HadronicProcess::RegisterMe(G4HadronicInteraction *a)` to call the correct initialize
 - Process knows if it is master or worker
- **Limitation:** to implement for worker models “GetMasterModel” is more complex (but can be done with some caveats), do we need this?

Possible implementation



RegisterMe modifications:

```
void RegisterMe( G4HadronicInteraction* aModel)
// [...]

G4bool isMaster = ( this == GetMasterProcess() );
if ( isMaster ) {
    aModel->InitializeForMaster();
} else {
    aModel->InitializeForWorkers();
}

return;
}
```

Conclusions

- A possible inclusion of MT capabilities in HAD framework is possible in an **evolutionary approach**
 - Without changing public interfaces (e.g. only adds methods)
 - Fully backward compatible
 - One limitation: models do not have access to “master” model (can be changed)
 - Cross-sections are shared entirely (e.g. full object) in a very simple way (single XS can still implement ad-hoc sharing of parts of data structures)