

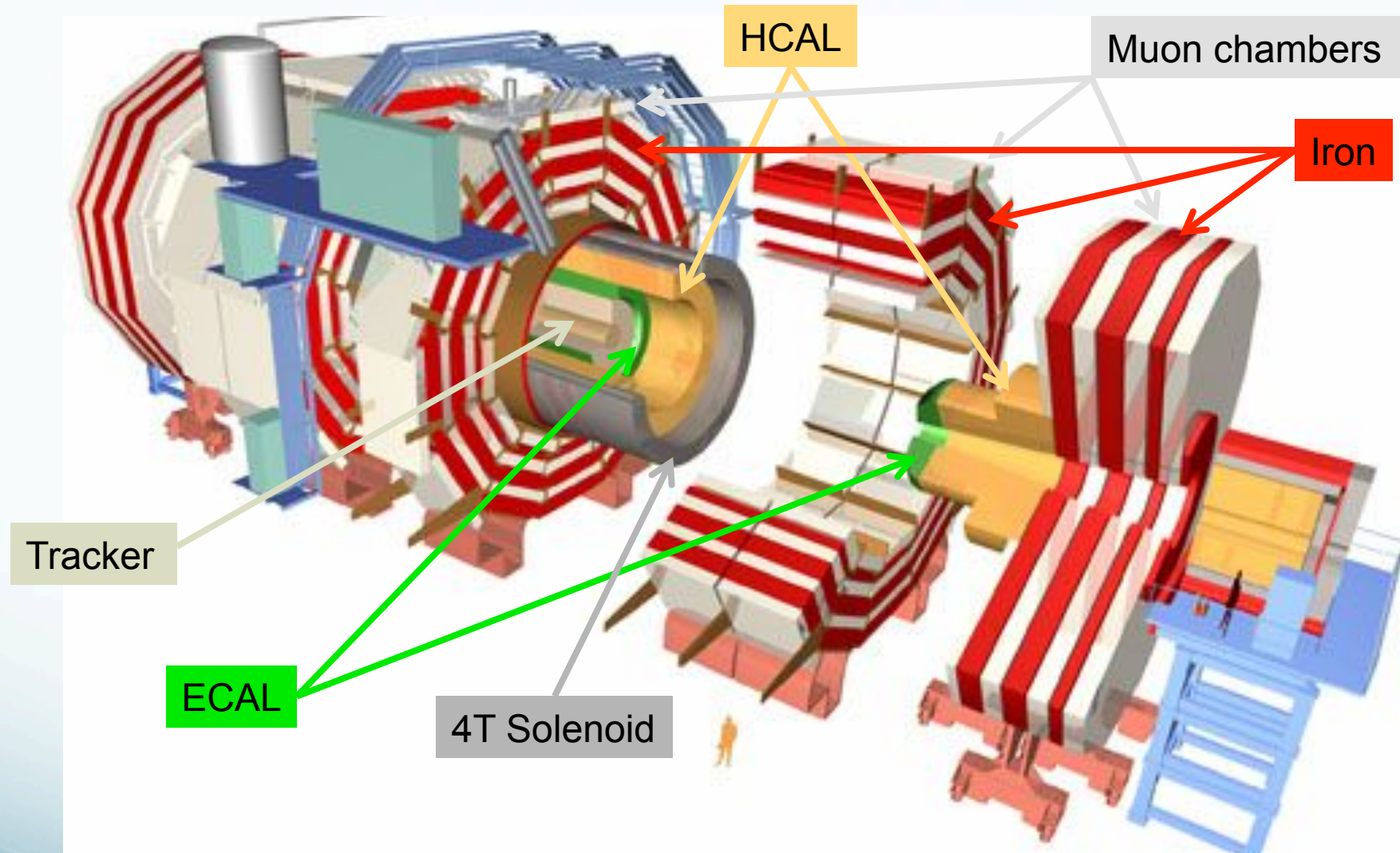
The CMS Tracker Upgrade for HL-LHC

Overview

Outline

- The HL-LHC Tracker: requirements
- Overview of R&D
 - ⊙ Development of “ p_T modules”
 - ⊙ Mechanical structures
 - ⊙ Track trigger
- Expected performance
- Ultimate pixel upgrade
- Summary and outlook

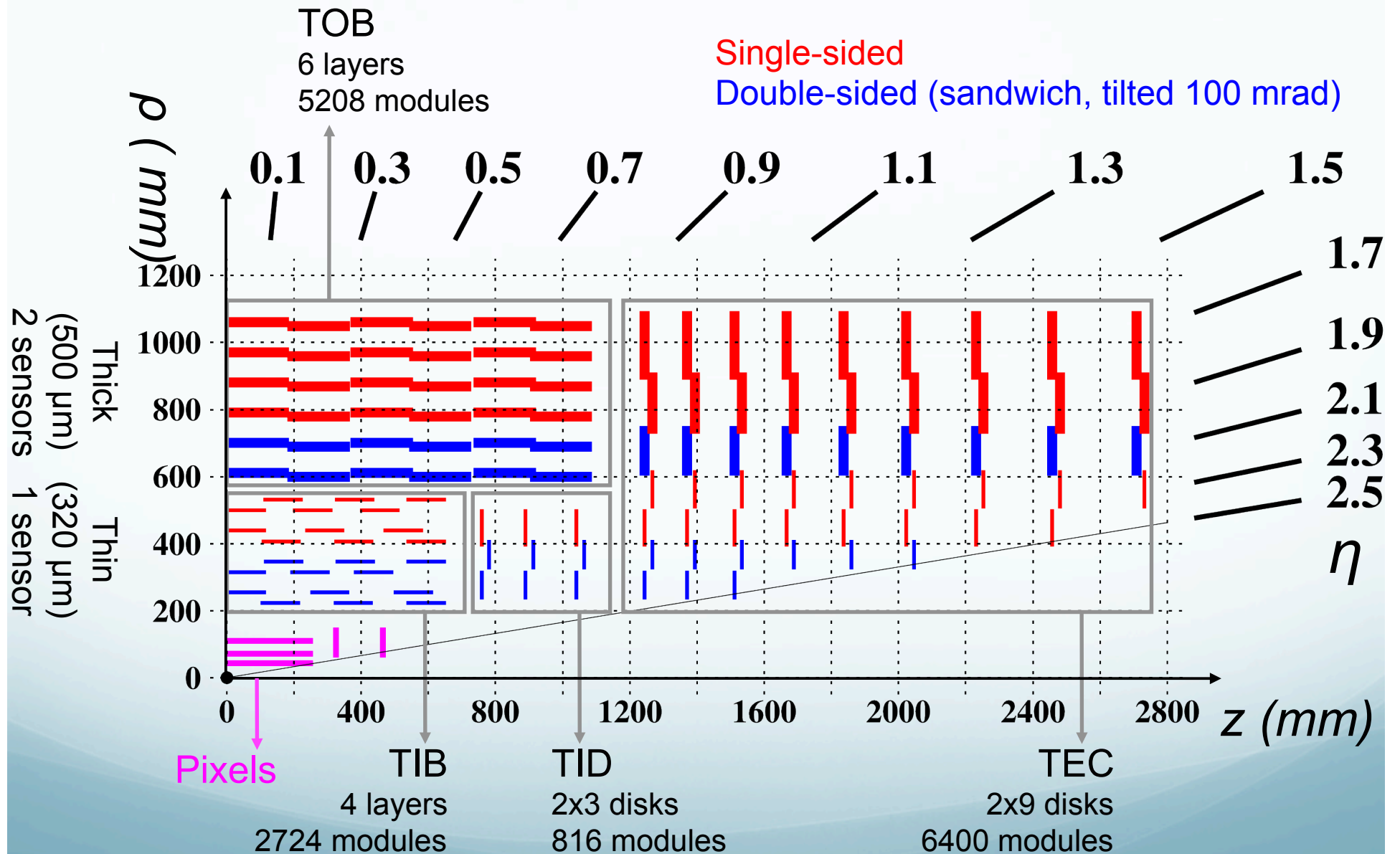
The Tracker in CMS



- Total weight: 12,500 t
- Overall diameter: 15 m

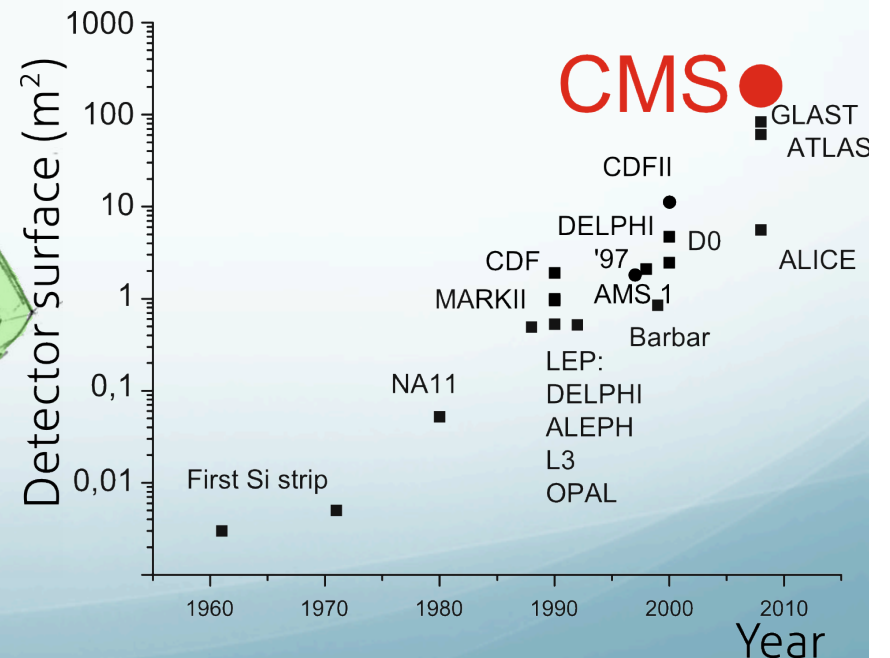
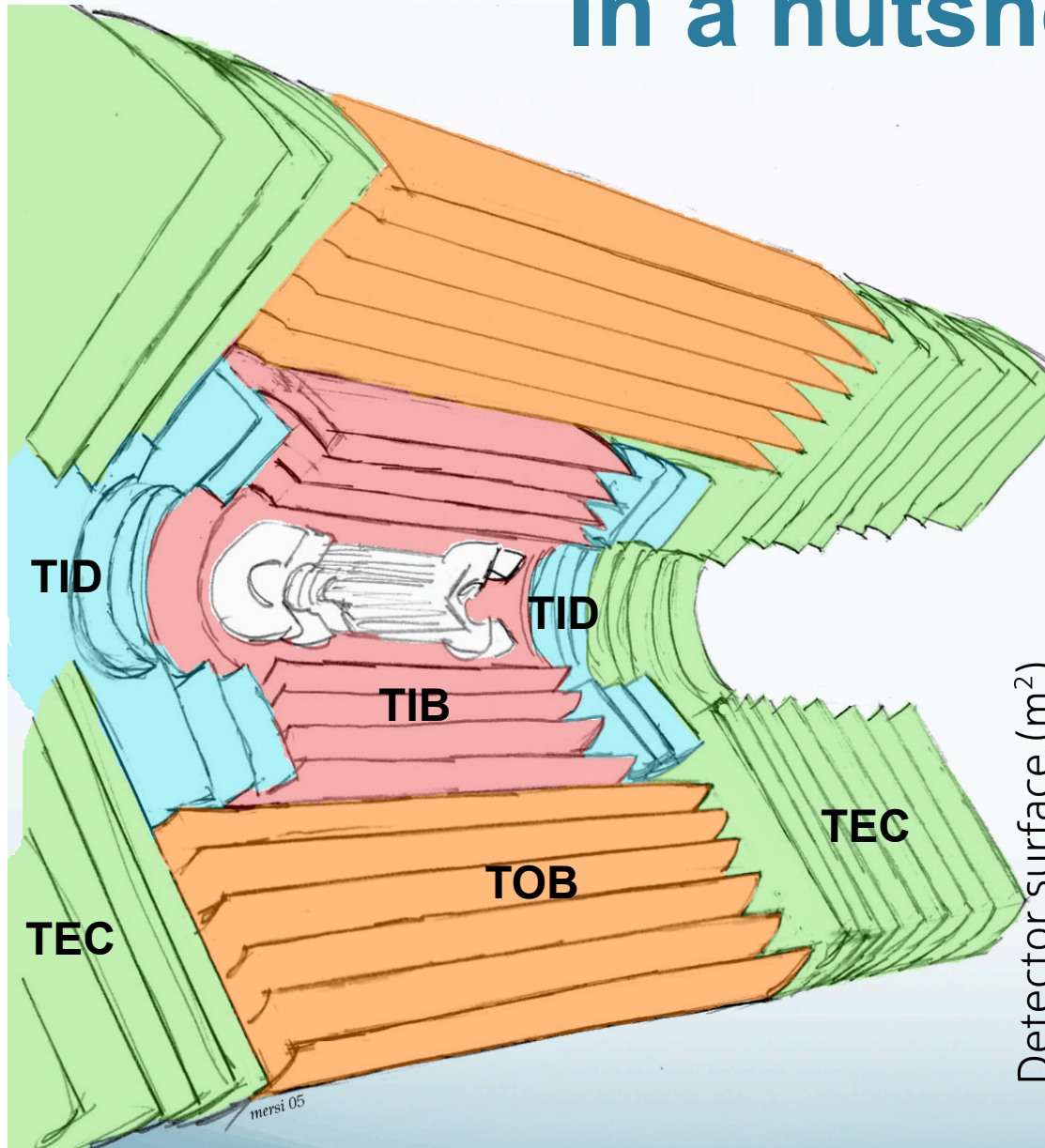
- Overall length: 21.6 m
- Magnetic field: 3.8 T

The Tracker layout

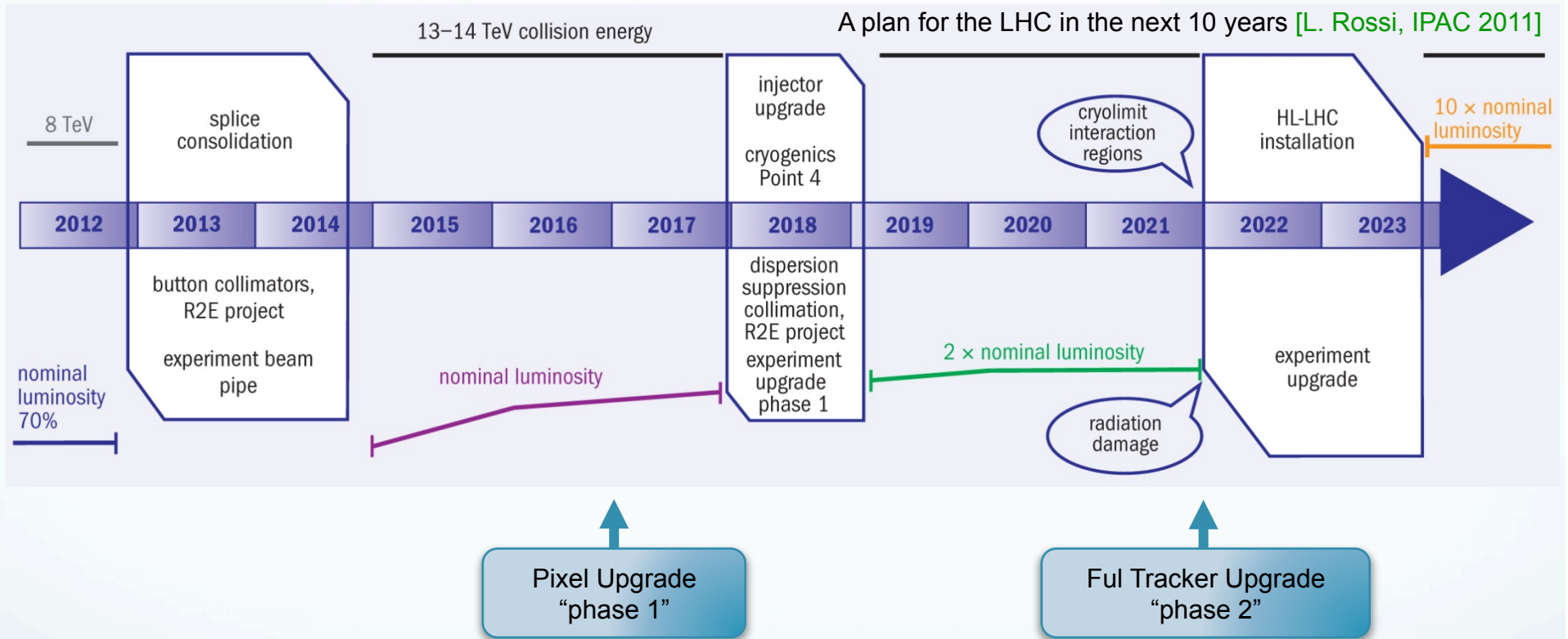


In a nutshell...

Volume	23 m ³
Active area	210 m ²
Modules	15'148
Front-end chips	72'784
Read-out channels	9'316'352
Bonds	24'000'000
Optical channels	36'392
Raw data rate:	1 Tbyte/s
Power dissipation:	30 kW
Operating T:	-10°C



The HL-LHC



Basic requirements and guidelines - I

➤ Radiation hardness

- ⊙ Ultimate integrated luminosity considered $\sim 3000 \text{ fb}^{-1}$
 - ★ To be compared with original $\sim 500 \text{ fb}^{-1}$

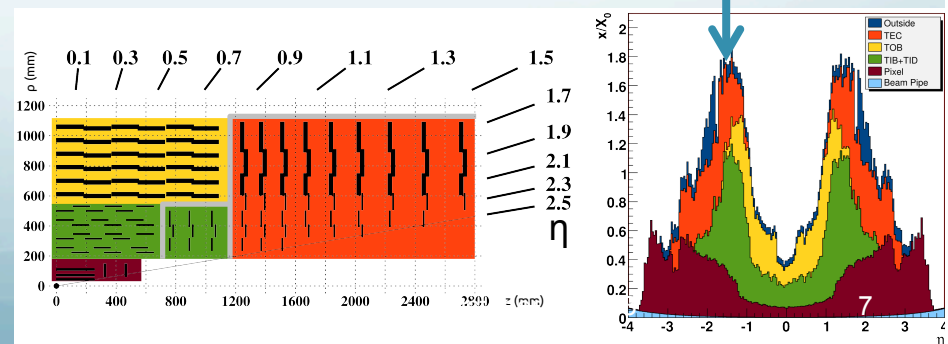
➤ Granularity

- ⊙ Resolve ~ 140 (and up to 200) collisions per bunch crossing, with $\sim 100\%$ occupancy
 - ❖ The original design figure for the present Tracker was 25!
 - ★ Requires much shorter strips!

Substantially higher channel count!

➤ Improve tracking performance

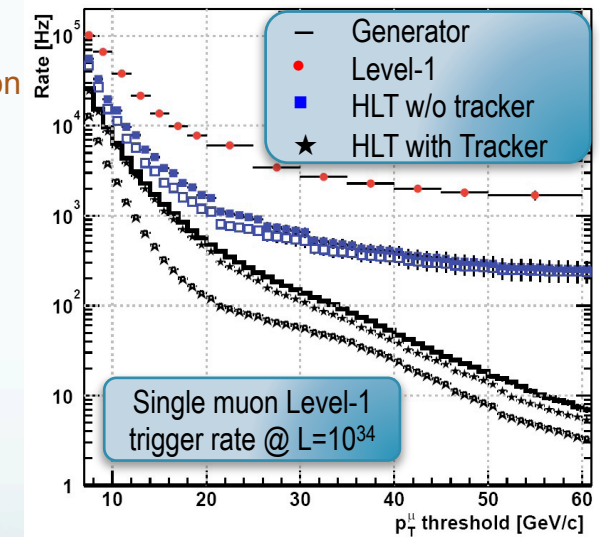
- ⊙ Improve performance @ low p_T
- ⊙ Reduce rates of nuclear interactions, γ conversions, bremsstrahlung...
 - ★ Reduce material in the tracking volume
- ⊙ Improve performance @ high p_T
 - ★ Reduce average pitch



Basic requirements and guidelines – II

➤ Tracker input to Level-1 trigger

- ⊙ μ , e and jet rates would substantially increase at high luminosity
 - ★ Even considering “phase-1” trigger upgrades
- ⊙ Increasing thresholds would affect physics performance
 - ★ Performance of algorithms degrades with increasing pile-up
 - ❖ Muons: increased background rates from accidental coincidences
 - ❖ Electrons/photons: reduced QCD rejection at fixed efficiency from isolation
- ⊙ Even HLT without tracking seems marginal
- ⊙ Add tracking information at Level-1
 - ★ Move part of HLT reconstruction into Level-1!

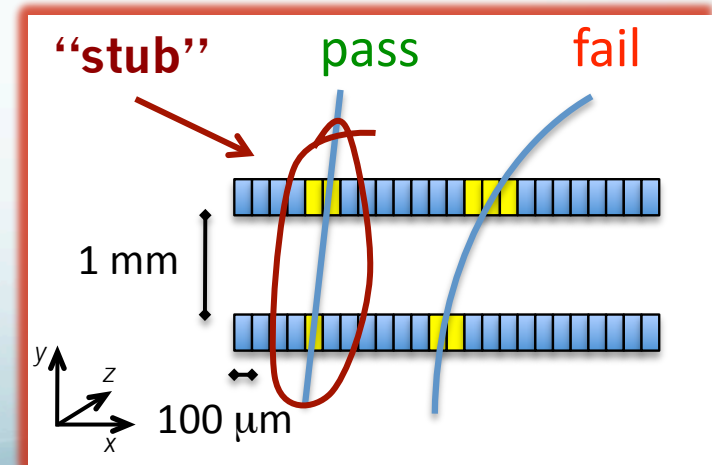


➤ Goal for “track trigger”:

- ⊙ Reconstruct tracks above 2 GeV
- ⊙ Identify the origin along the beam axis with ~ 1 mm precision

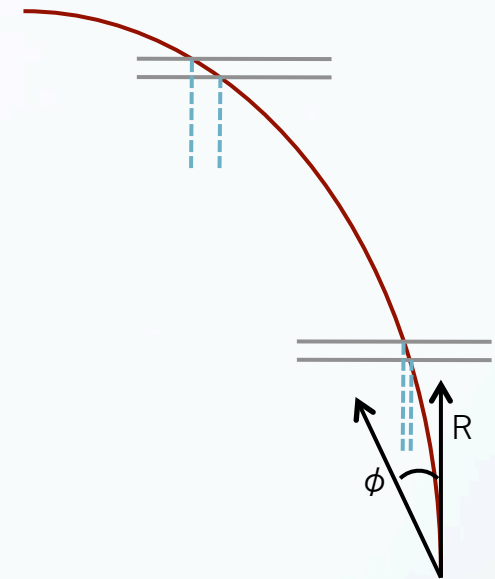
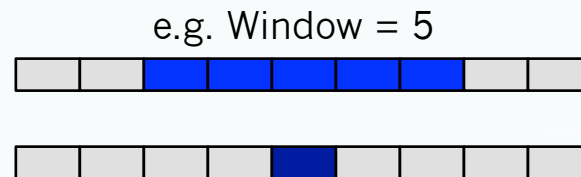
General concept

- Silicon modules provide at the same time “Level-1 data” (@ 40 MHz), and “readout data” (upon Level-1 trigger)
 - ⊙ The whole tracker sends out data at each BX: “push path”
- Level-1 data require local rejection of low- p_T tracks
 - ⊙ To reduce the data volume, and simplify track finding @ Level-1
 - ⊙ Threshold of ~ 2 GeV \Rightarrow data reduction of one order of magnitude or more
- Design modules with p_T discrimination (“ p_T modules”)
 - ⊙ Correlate signals in two closely-spaced sensors
 - ⊙ Exploit the strong magnetic field of CMS
- Level-1 “stubs” are processed in the back-end
 - ⊙ Form Level-1 tracks, p_T above ~ 2 GeV
 - ⊙ To be used to improve different trigger channels

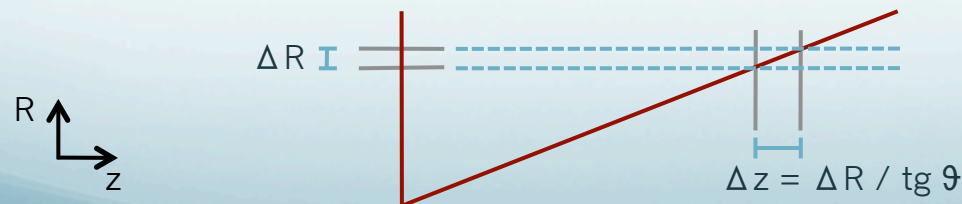


More on p_T modules working principle

- Sensitivity to p_T from measurement of $\Delta(R\phi)$ over a given ΔR
- For a given p_T , $\Delta(R\phi)$ increases with R
 - ⊙ A same geometrical cut, corresponds to harder p_T cuts at large radii
 - ⊙ At low radii, rejection power limited by pitch
 - ⊙ Optimize selection window and/or sensors spacing
 - ★ To obtain, ideally, consistent p_T selection through the tracking volume



- In the barrel, ΔR is given directly by the sensors spacing
- In the end-cap, it depends on the location of the detector
 - ⊙ End-cap configuration typically requires wider spacing



p_T modules

2 Strip sensors

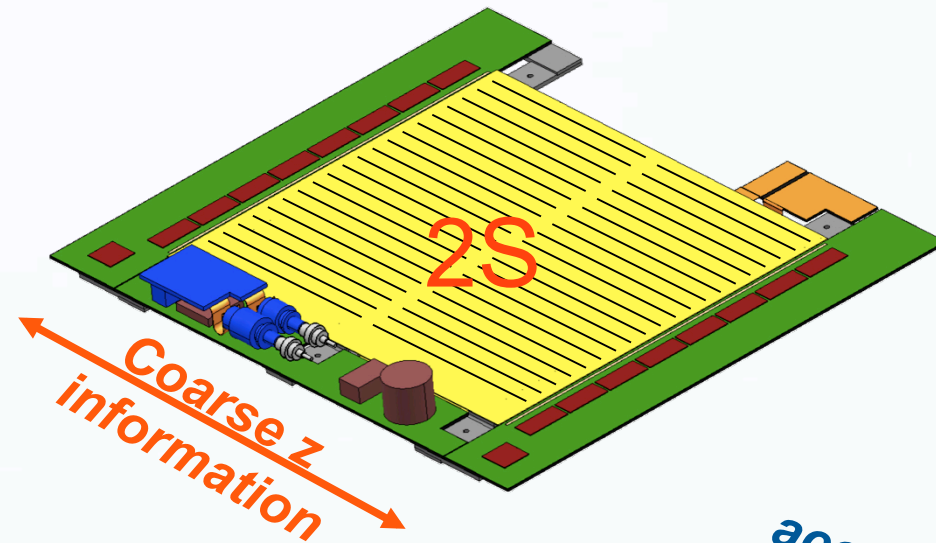
Strips: 5 cm \times 90 μ m

Strips: 5 cm \times 90 μ m

P = 2.7 W

~ 92 cm² active area

For r > 60 cm



Pixel + Strip sensors

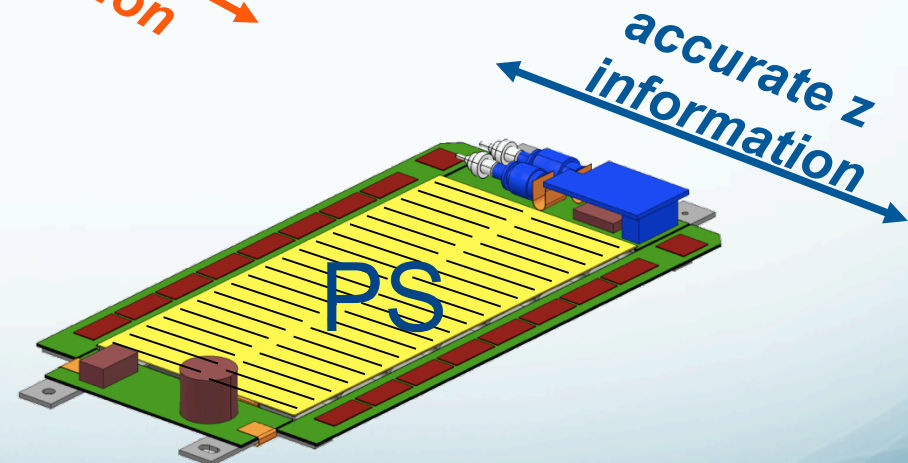
Strips: 2.5 cm \times 100 μ m

Pixels: 1.5 mm \times 100 μ m

P = 5.0 W

~ 44 cm² active area

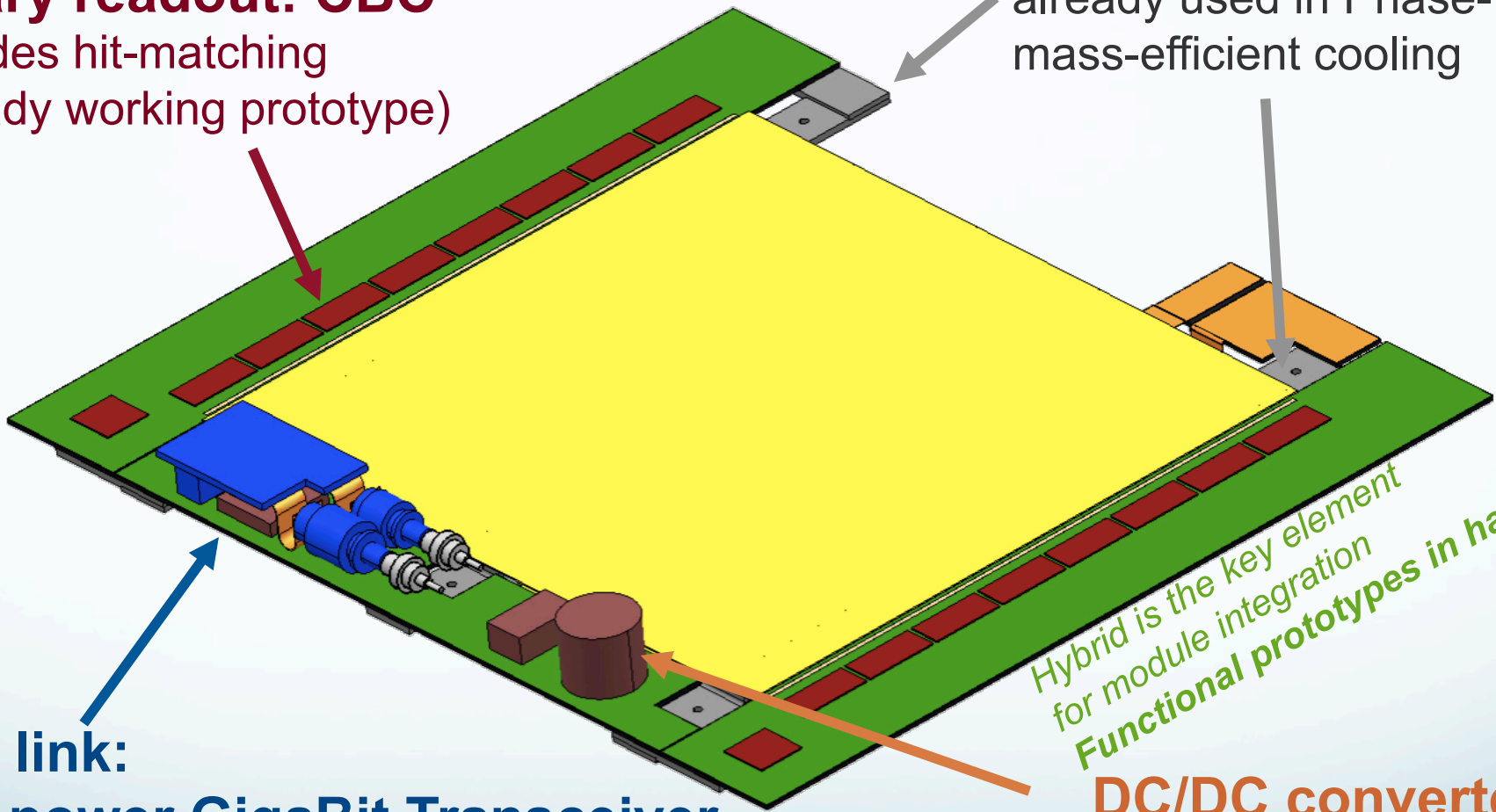
For r > 20 cm



2S module

Binary readout: CBC
provides hit-matching
(already working prototype)

CO₂ cooling
already used in Phase-1
mass-efficient cooling



Data link:
Low-power GigaBit Transceiver
IpGBT currently under development
integrated at module level

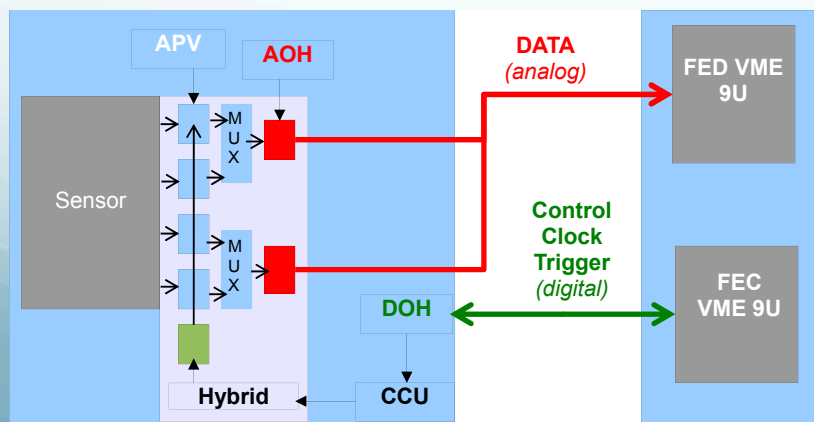
*Hybrid is the key element
for module integration
Functional prototypes in hand!*

DC/DC converter
already used in Phase-1
10 V lines: lower current, lower material

Electronics: old and new

OLD

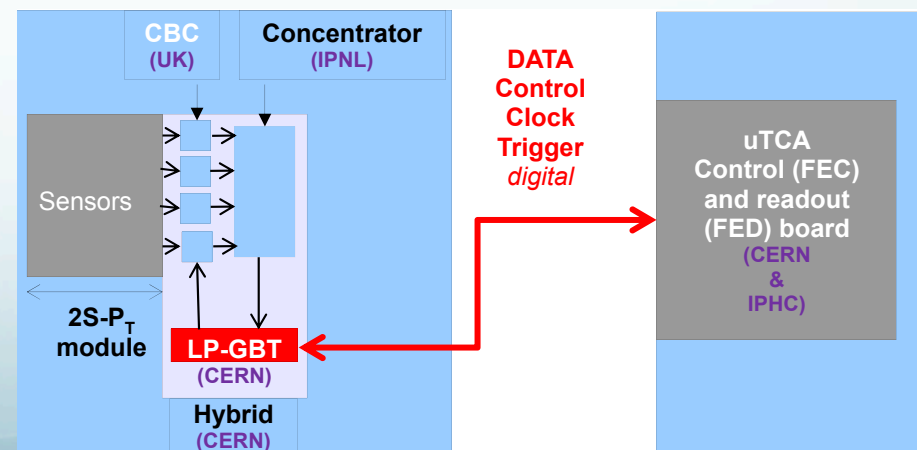
- Readout (unidirectional) and control (bidirectional) in two separate links and separate systems of front-end and back-end boards. Slow-control data in readout link.
- Analogue readout. Allows for common mode subtraction and energy loss measurement.
- 0.25 μm ASIC; > 2 mW/ch.



D. Abbaneo - IPM School, Tehran

NEW

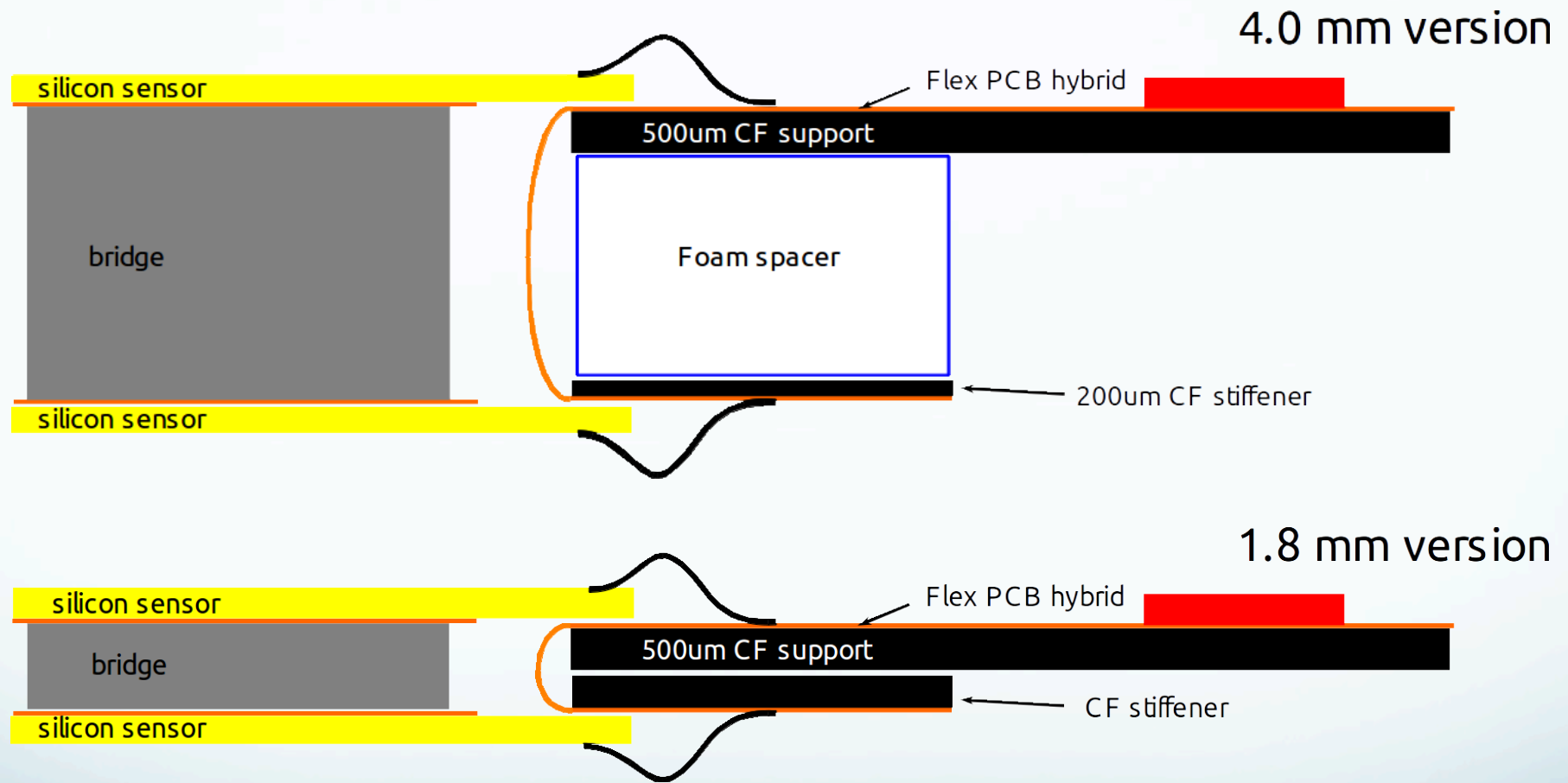
- Single bidirectional link carries all the data, including new L! trigger output!
- Binary readout. Requires perfect grounding! More suitable for high granularity and low power per channel
- 130 nm (or 65 nm) ASIC; about 0.3 mW/ch for the strips.



October 9, 2013

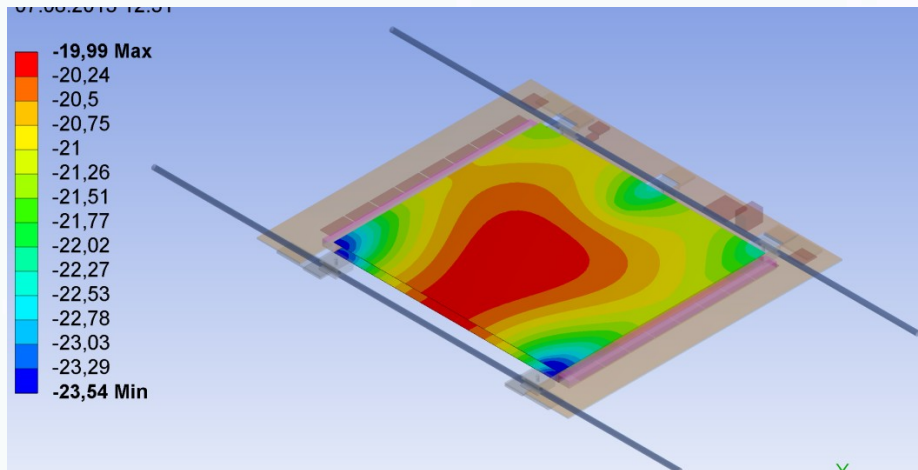
13

Connectivity



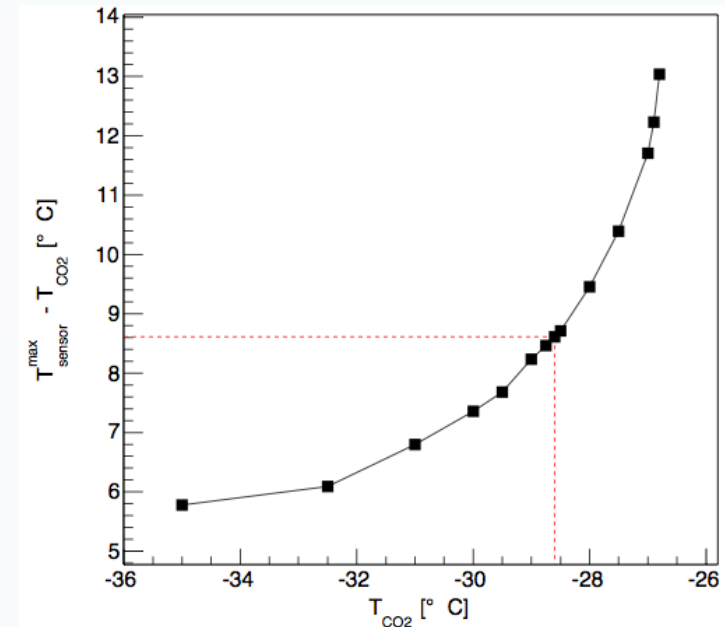
Different sensor spacings obtained by variations of the same design

2S modules: thermal performance

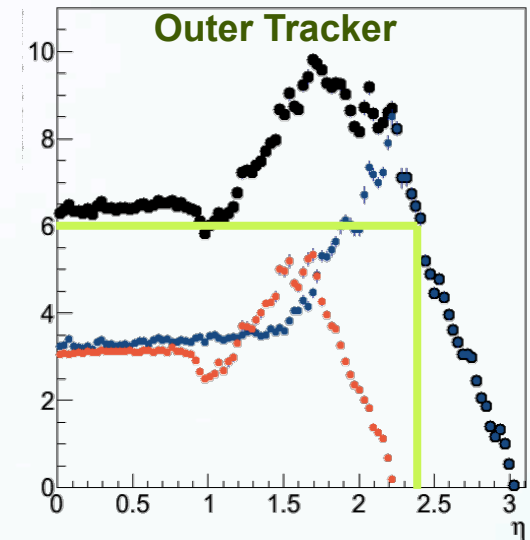
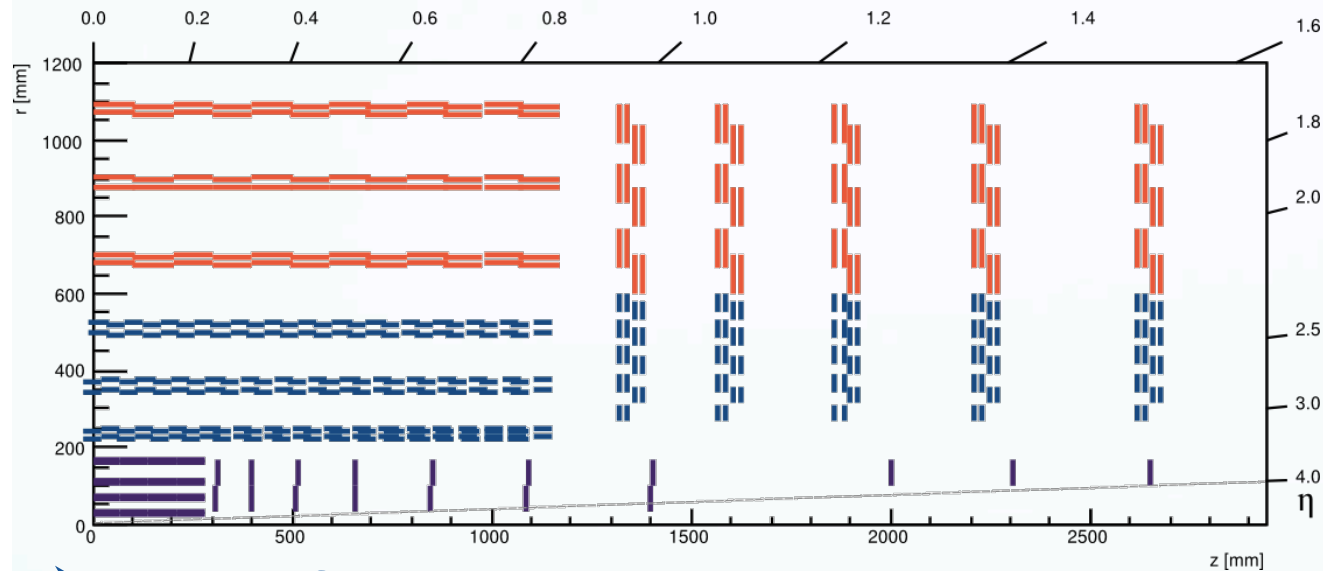


Heat transfer coefficients:

- pipe \rightarrow CO₂ = 5'000 W/m²/K
- module \rightarrow cooling blocks = 10'000 W/m²/K
- Simulation includes the dark current model for a fluence of 7.35×10^{14} neq/cm² (worst possible condition)
- T_{CO₂} tuned to obtain **T_{SENSOR} ≤ -20 °C**
 - Temperature gradient on sensors = 3.5 °C
 - **T_{CO₂} = -28.6 °C** to obtain T_{SENSOR} < -20 °C
 - Thermal runaway at T_{CO₂} ≈ -27 °C

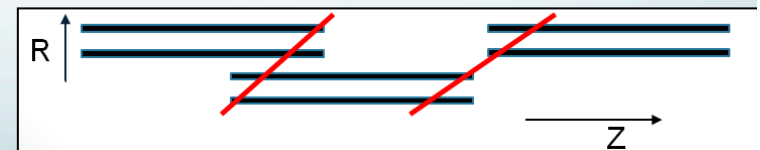


Tracker Layout



➤ Main features

- ⊙ ×4 granularity in strip sensors (avg)
- ⊙ 3 more layers of pixellated sensors in the Outer Tracker
 - ★ Unambiguous 3d coordinates – helps track finding in high pile-up
- ⊙ 12 hits up to $\eta \approx 2.4$ available at Level-1
- ⊙ Extended coverage up to $\eta \approx 4$
- ⊙ Form hermetic surfaces (cylinders and disks) for stub finding
 - ★ Taking into account IP spread



Tracker in Numbers

OLD

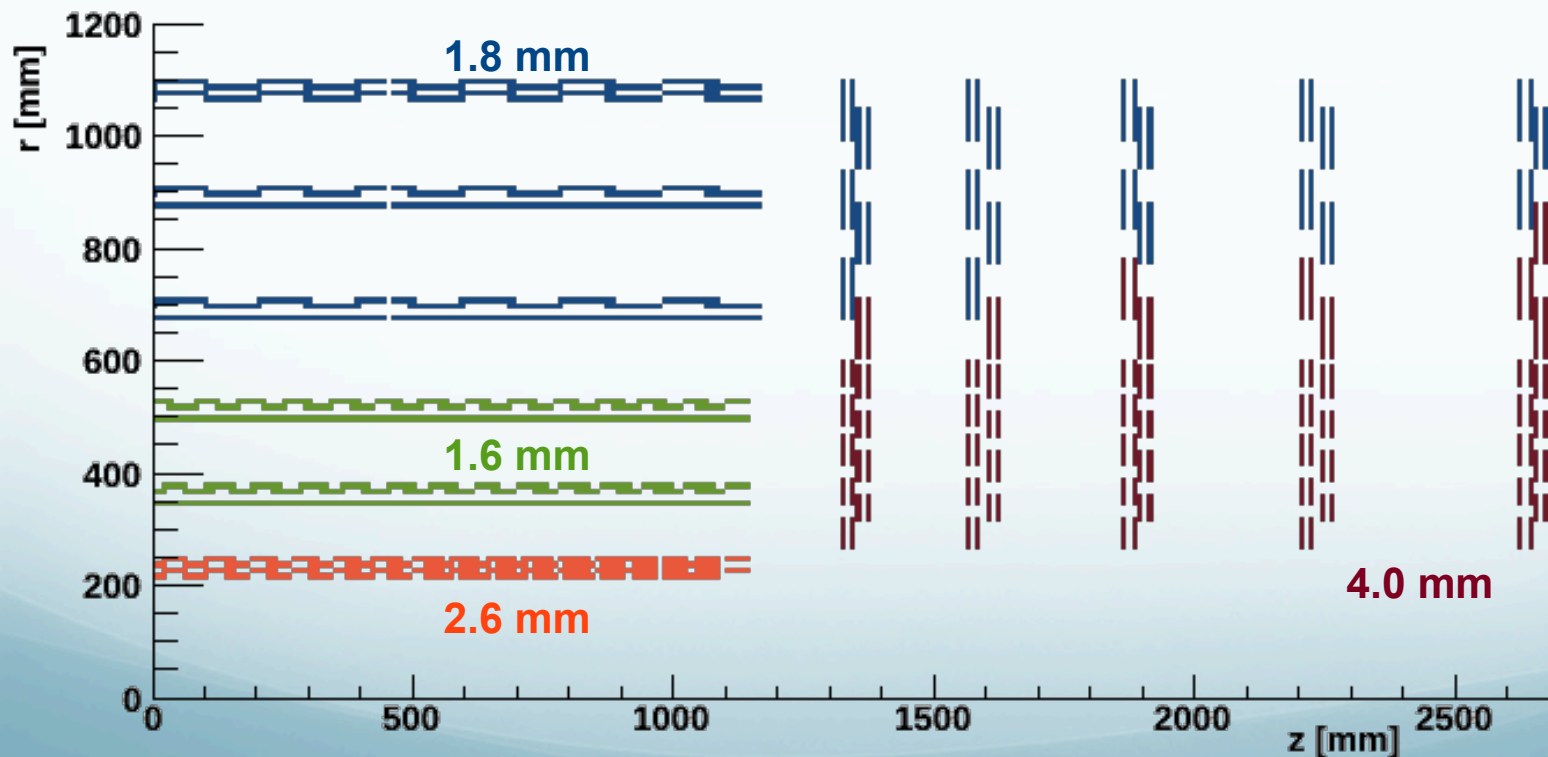
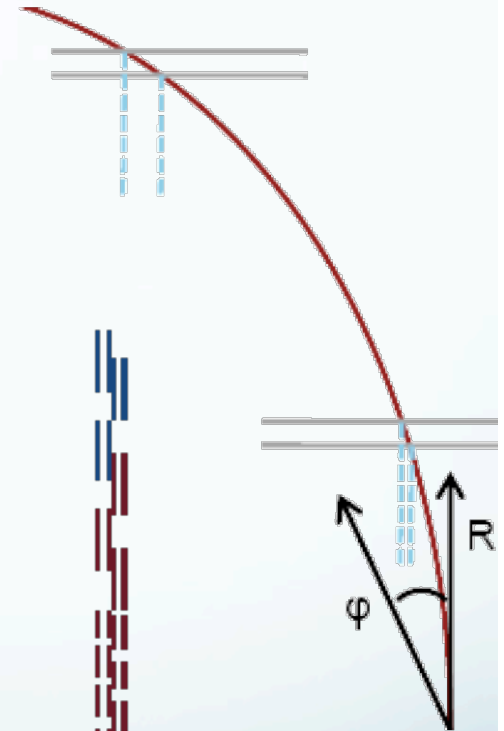
- Total n of modules 15,148
- Total active surface 210 m²
- Total n of strips 9.3 M
- Power in the tracking volume
~ 30 kW

NEW

- N of modules 15,508
 - ⊙ 7084 PS modules
 - ⊙ 8424 2S modules
- Total active surface 218 m²
 - ⊙ 155 m² strips (2S)
 - ⊙ 31 m² strips (PS)
 - ⊙ 31 m² macro-pixels (PS)
- Total n of strips 47.8 M
- Total n of pixels 218 M
- Power in the tracking volume
~70 kW

Optimization of module parameters

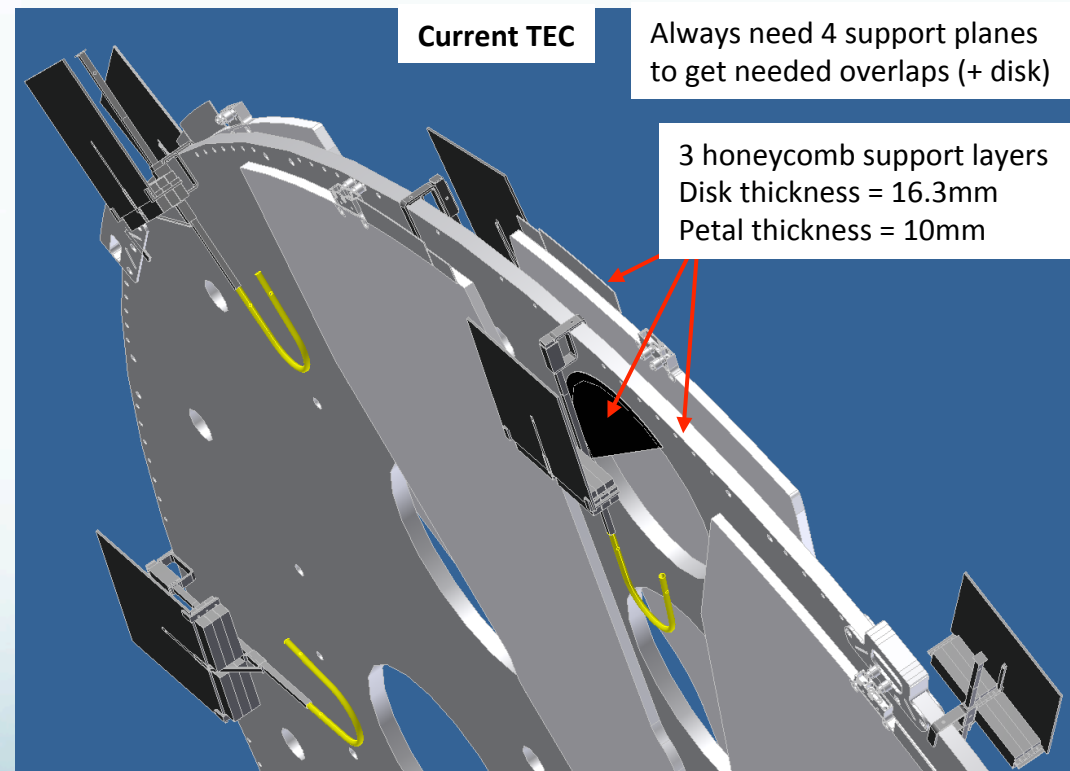
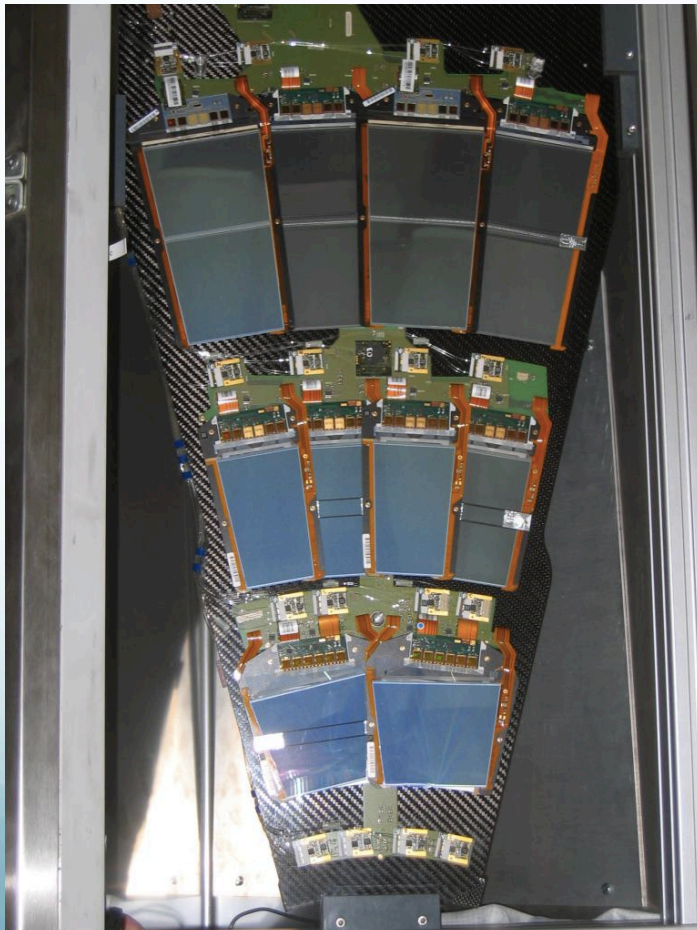
- Keep as targets:
 - ⊙ <1% efficiency @ $p_T = 1\text{ GeV}$
 - ⊙ maximize efficiency @ $p_T = 2\text{ GeV}$
- Limit choice of spacing to “a few” different values
- Optimize width of acceptance window at the same time
 - ⊙ between 3 and 16 strips for the example below



Mechanics: endcap

➤ Current TEC concept

- ⊙ “Petals” on disk
- ⊙ Petals populated with wedge-shaped modules



HL-TEC

➤ Double-disk concept

⦿ Each disk split in two dees

★ Eliminates the central support

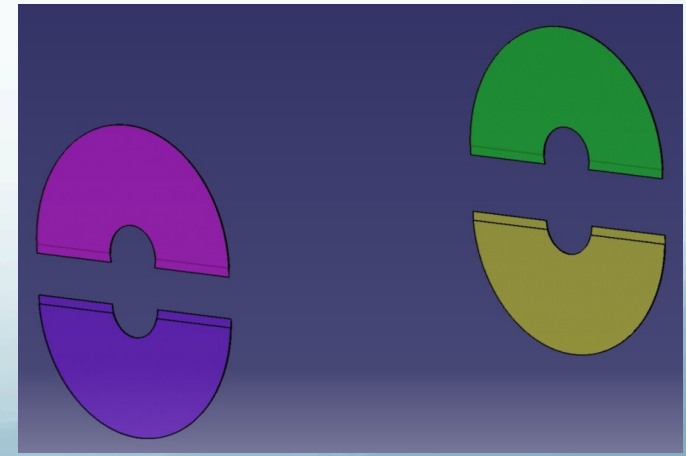
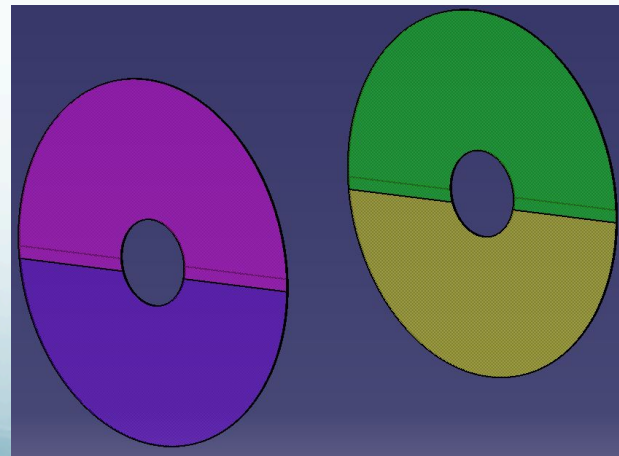
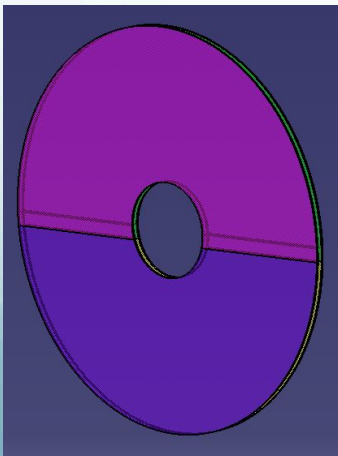
⦿ Larger units allow to make use of same rectangular modules as in barrel

★ Implies some additional overlap

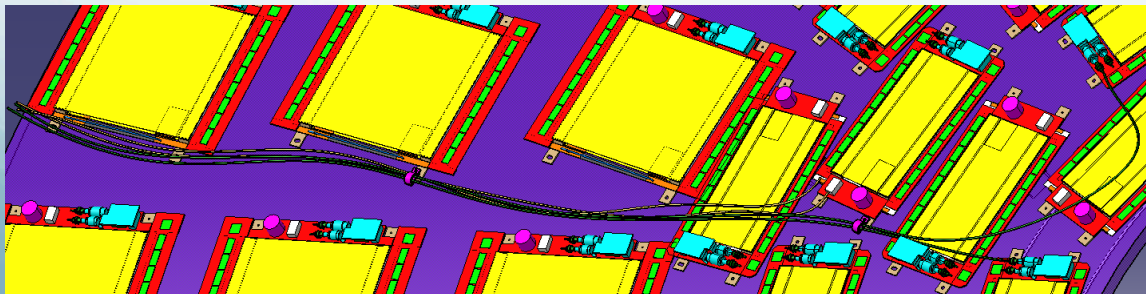
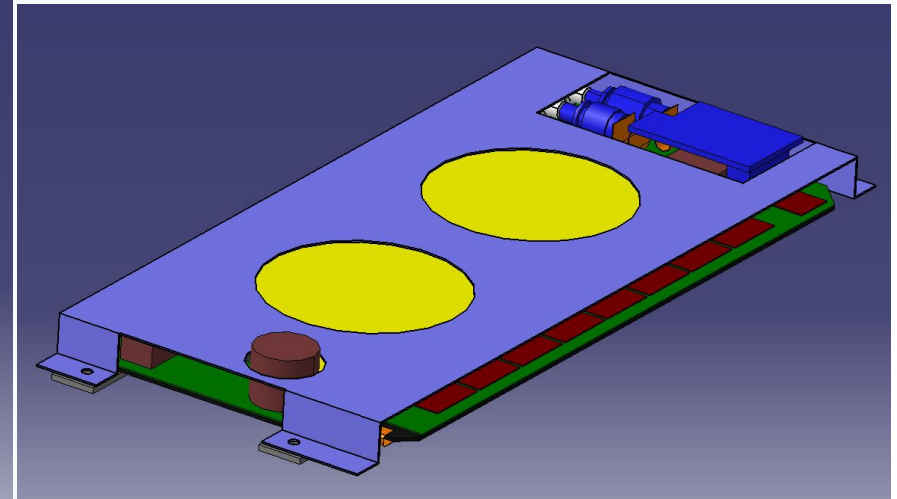
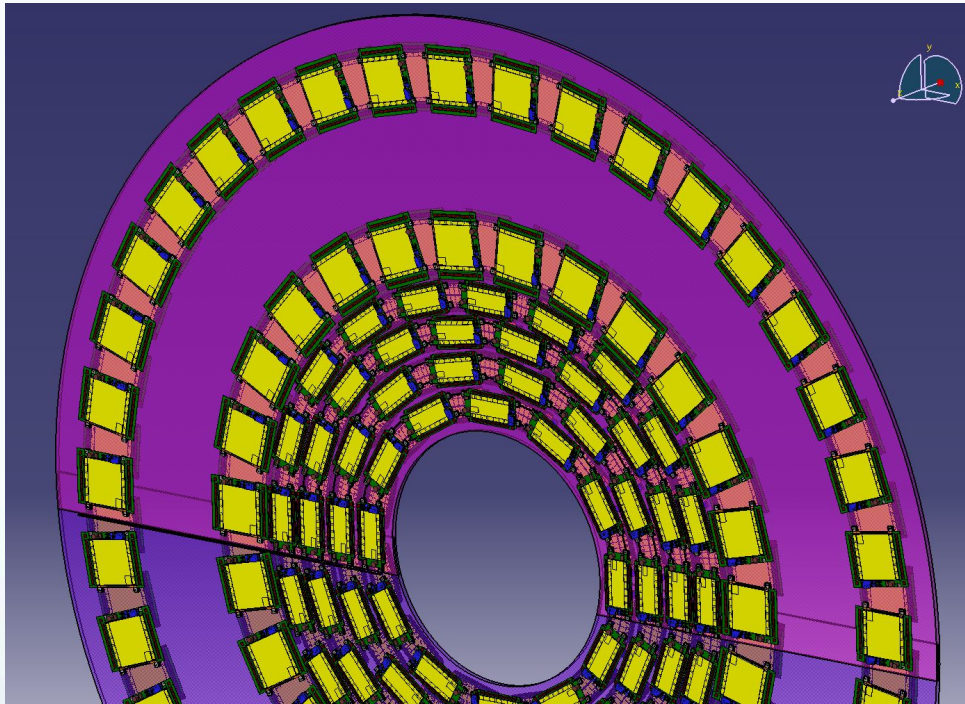
★ Greatly simplifies production

❖ N.B. The HL-TEC disk has 15 rings wrt 7 in present TEC!

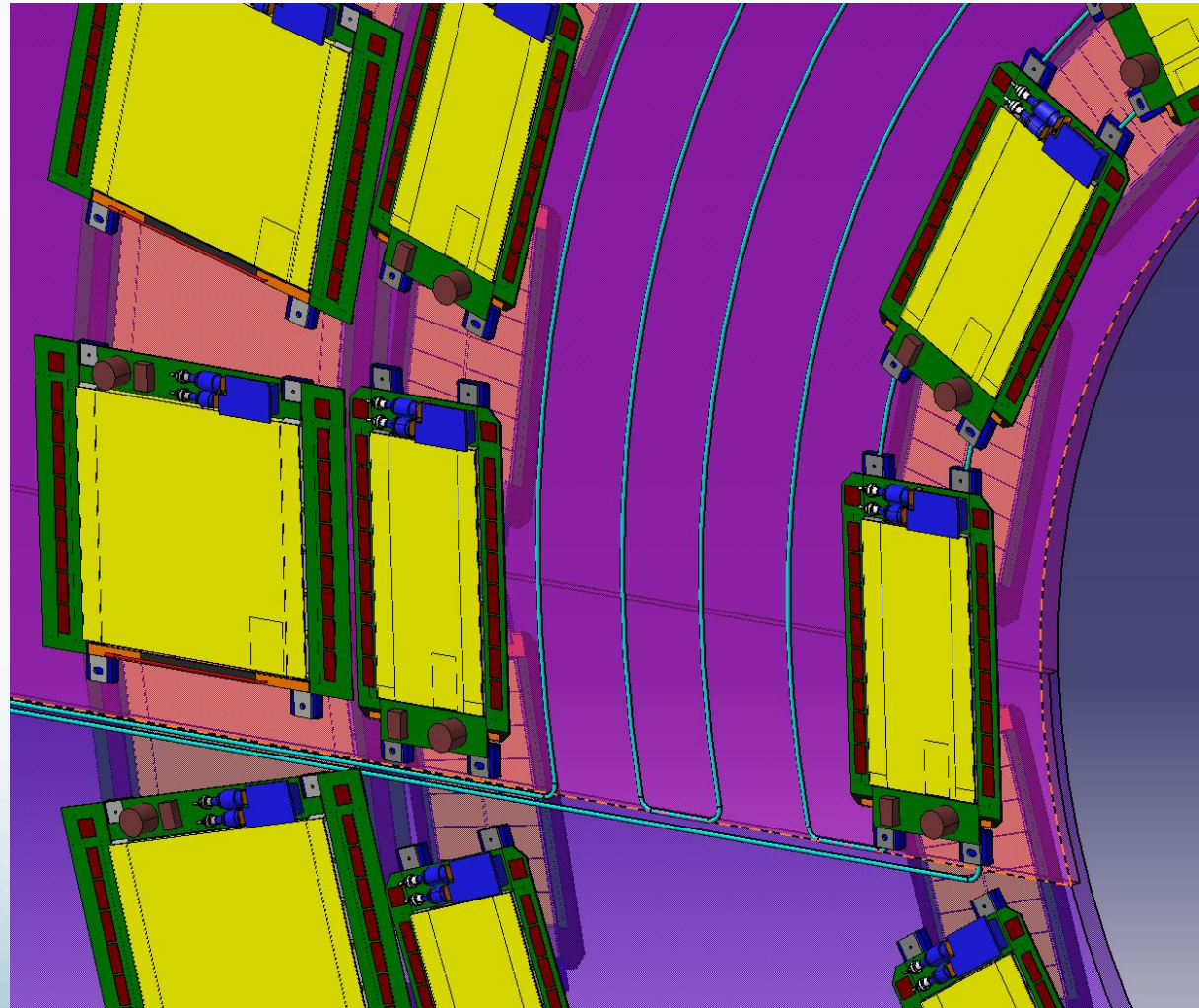
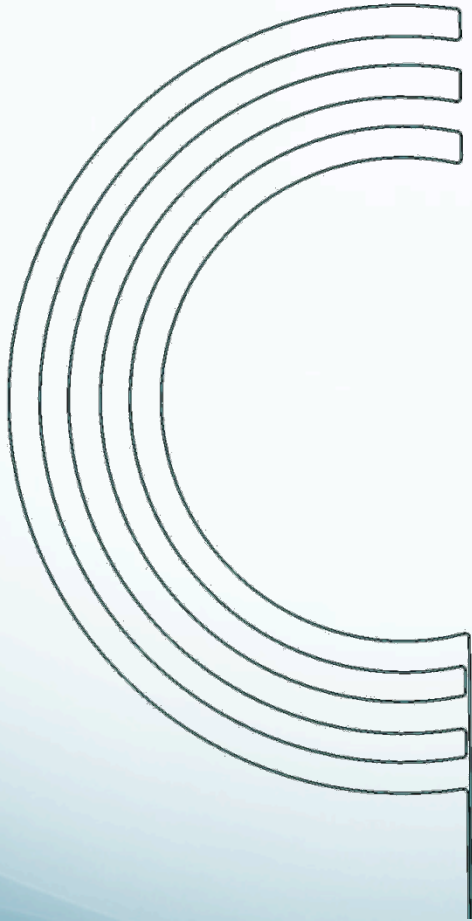
❖ Pitch-adpters are not conceivable with the increased channel density



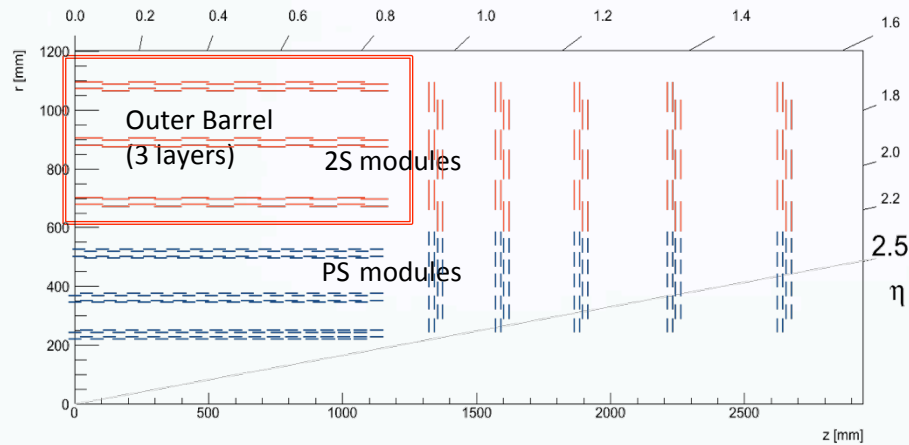
Overlaps and services



Cooling



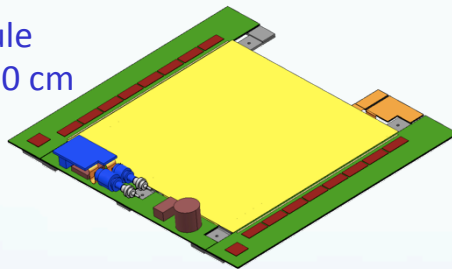
Outer Barrel concept



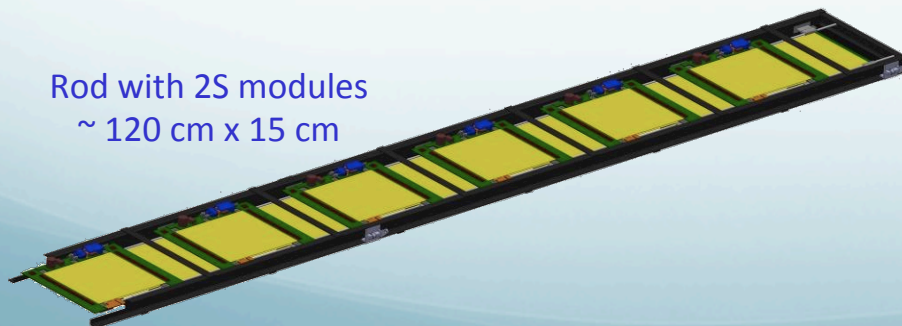
Based on the current TOB design

- 1 support wheel
- Rods installed from the two ends

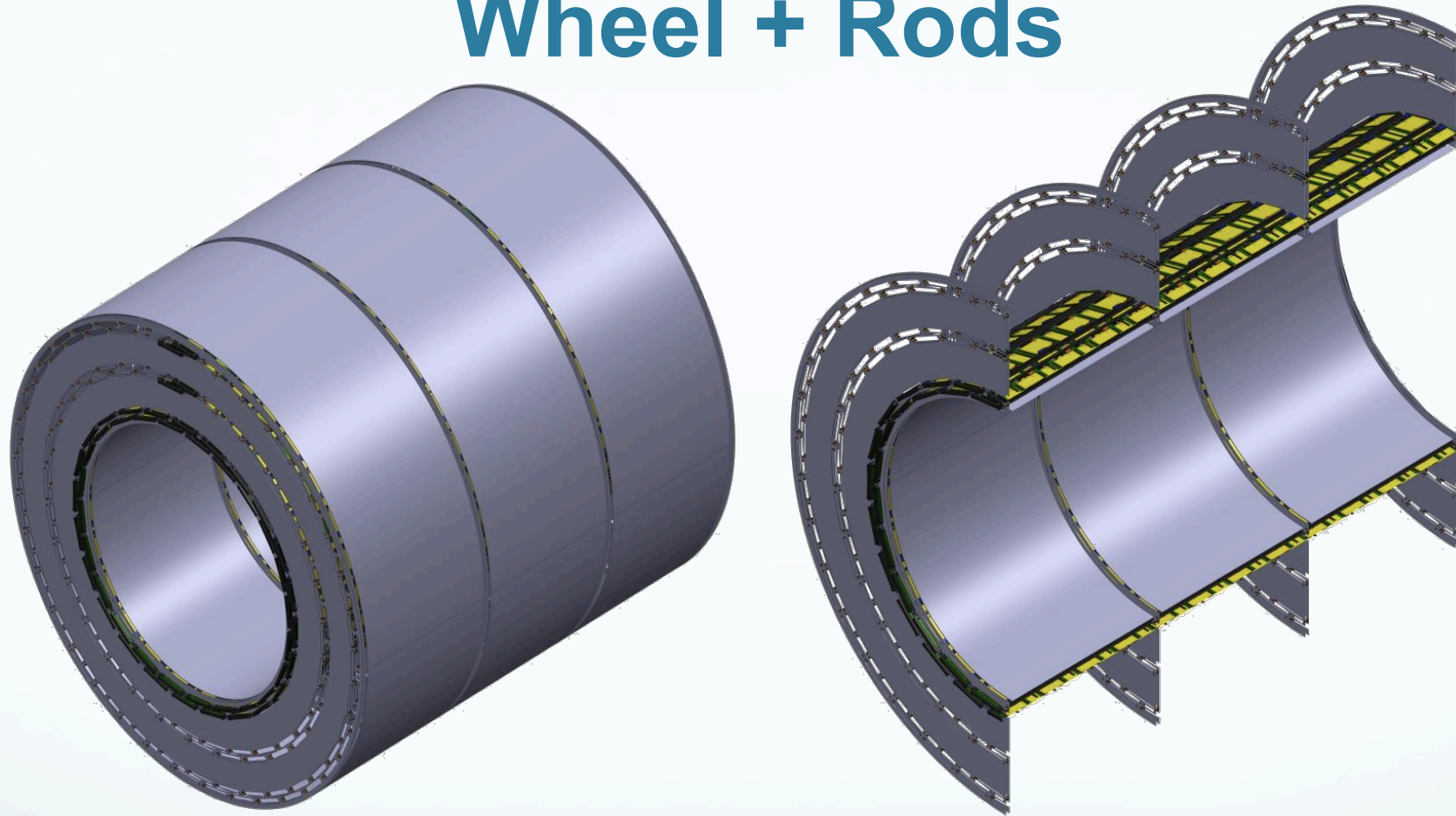
2S module
~ 10 cm x 10 cm



Rod with 2S modules
~ 120 cm x 15 cm



Wheel + Rods



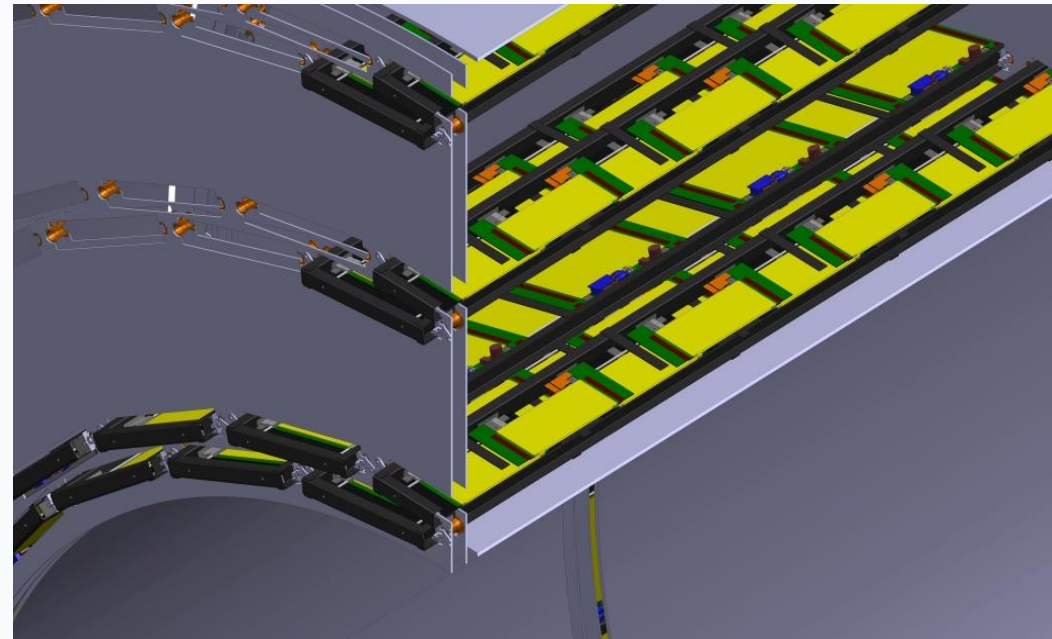
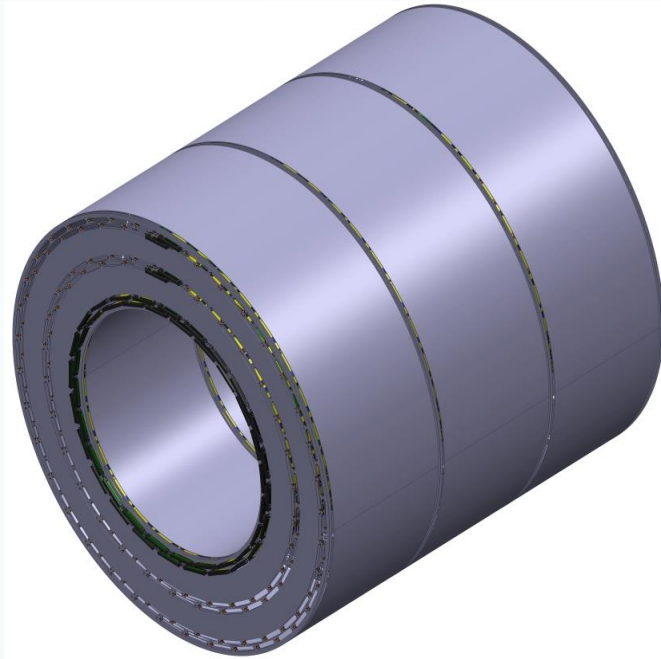
- Wheel = 4 disks joined together by 3 inner and 3 outer cylinders
- Rods are half length of the barrel, with overlap in the middle
- Rods inserted from the two ends, each rod supported by two disks

Module cooling



- In old TOB: cooling pipes on the outside of the Rod C-profiles
- Current studies: cooling pipe inside C-profile, closer to the modules
 - ⦿ Tight space, but seems OK
 - ⦿ Strength of structure to be re-evaluated (notably in cold)

Cooling



Layer	L1	L2	L3	Totals
# mod	1152	1488	1824	4464
along phi	48	62	76	
mod/rod	12	12	12	
W/mod	3.5	3.5	3.5	
W/rod	42	42	42	
W one end	2016	2604	3192	7812
W total	4032	5208	6384	15624

➤ Two rods in series give “CO2-suitable” cooling circuits:

- ⊙ 2 x 2.5 m = 5 m pipe length with 1.5 - 2 mm pipe diameter.
- ⊙ 84 W per line
- ⊙ 186 lines in total (93 per end)
- ⊙ 186 supply capillaries from manifolds at TK Bulkheads
- ⊙ Return pipes (size?) to manifolds at TK Bulkheads
- ★ Alternative: return manifolding at the TOB end

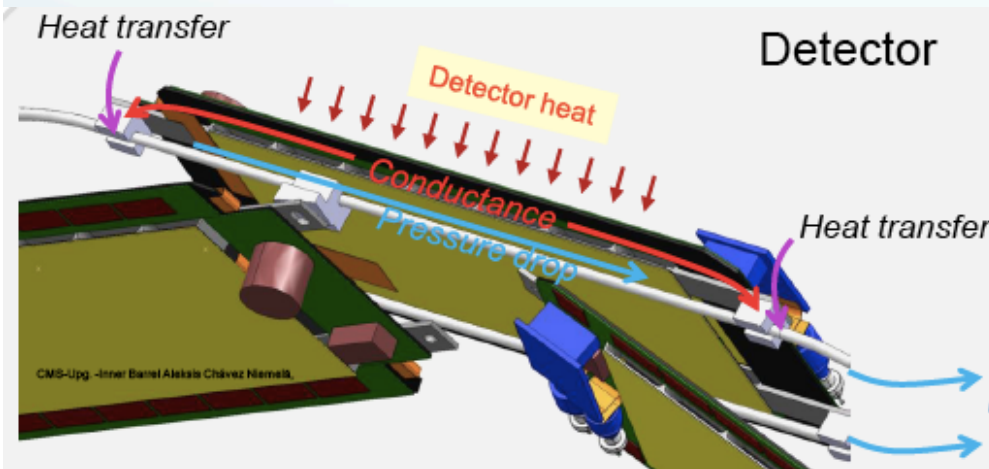
Cooling: old and new

OLD

- Liquid C_6F_{14}
- Transfer heat into liquid (+ 2°C over a detector loop)
- Design goals were -10°C silicon; -20°C coolant
- Design goals not really achieved...

NEW

- Two-phase CO_2
- Pump in liquid CO_2 ; evaporate CO_2 at constant temperature along the cooling loop. Much better heat transfer coefficient!
- MUST make sure that “boiling” starts before entering the detector, and sufficient liquid remains at the end! Pressure drop along the pipes translate to decrease in temperature!
- Complicated process... a lot of thermodynamics!
- Design goals are -20°C silicon; -30°C coolant



Evaluation of different tracker geometries and options: layout modelling

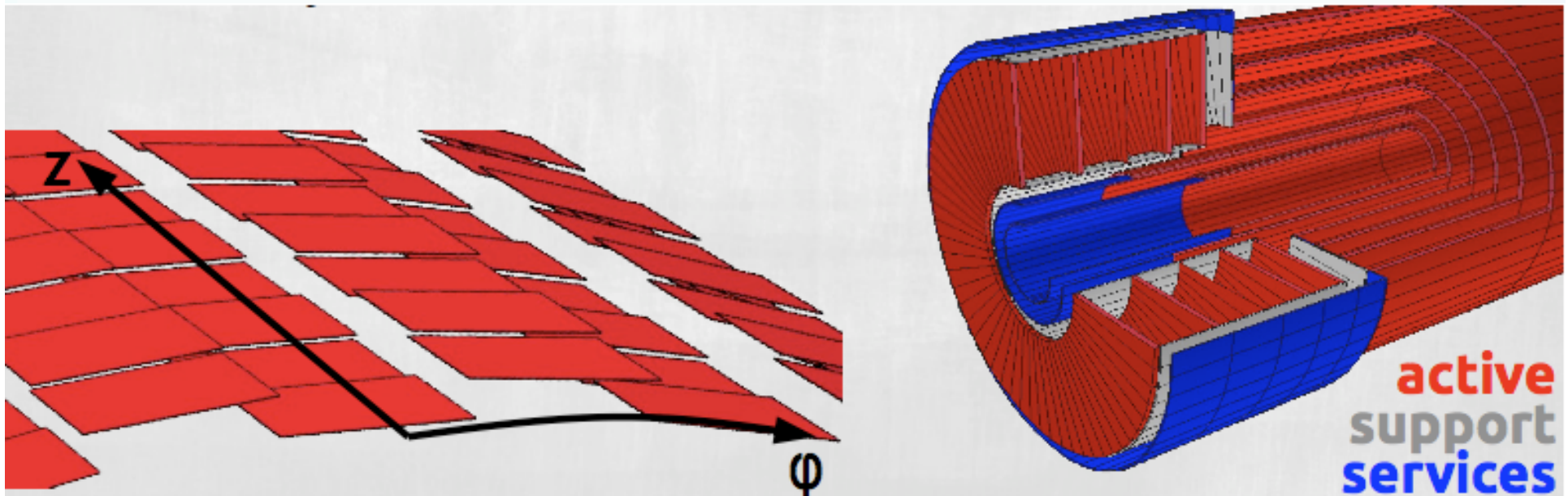
- Dedicated standalone software package[©]

© N. De Maio, S. Mersi, G. Bianchi

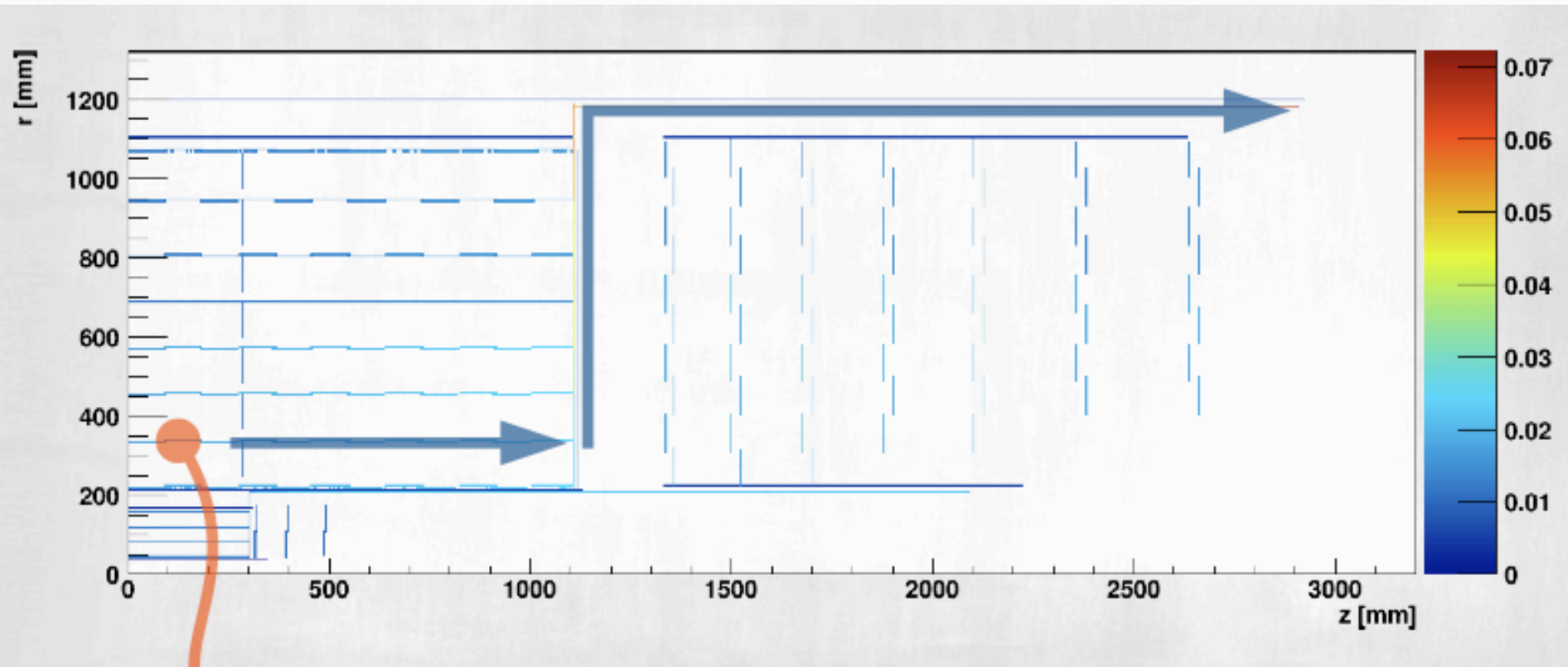
Based also on work from V. Karimaki and G. Hall

- Allows to place in space active and passive volumes

- ⊙ Starting from a small sets of simple parameters



➤ Simple (semi-automatic) modelling of services



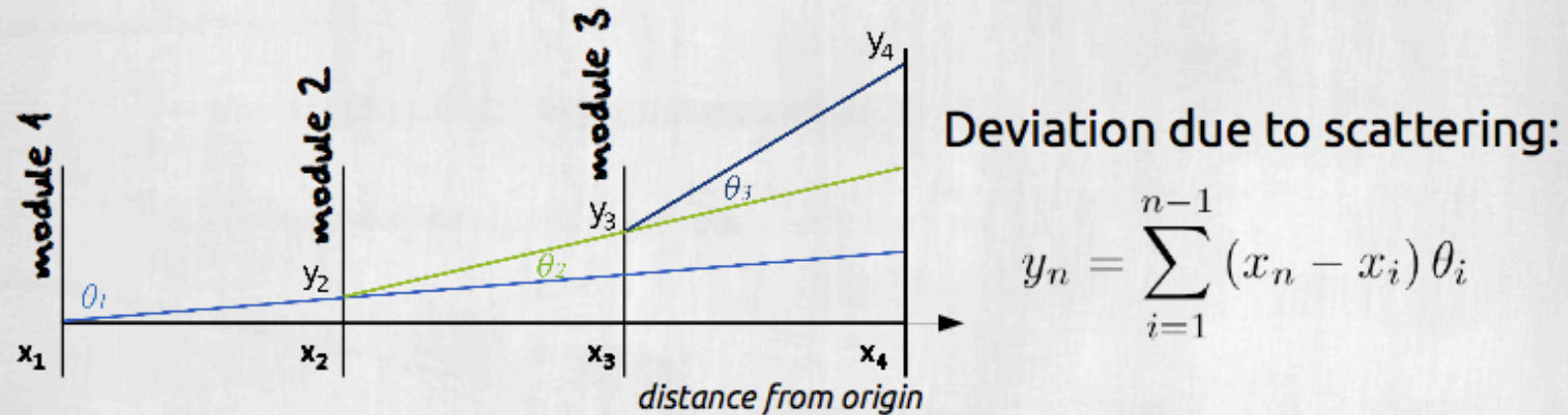
Material on
active elements

+

Material for services
automatically routed

➤ Implements estimates of tracking performance

- ▣ Use measurement errors to estimate the errors in track fit parameters
- ▣ **Multiple scattering** treated as (correlated) a measurement error



Error correlation matrix:

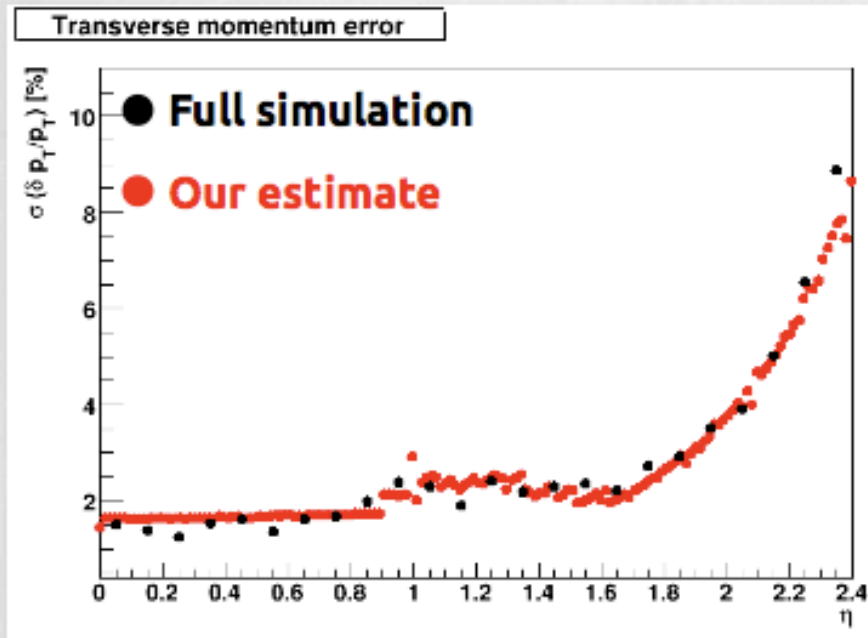
$$\sigma_{n,m} = \langle y_n y_m \rangle = \sum_{i=1}^{n-1} (x_m - x_i) (x_n - x_i) \langle \theta_i^2 \rangle$$

$$\sigma_n^2 = \frac{p^2}{12}$$

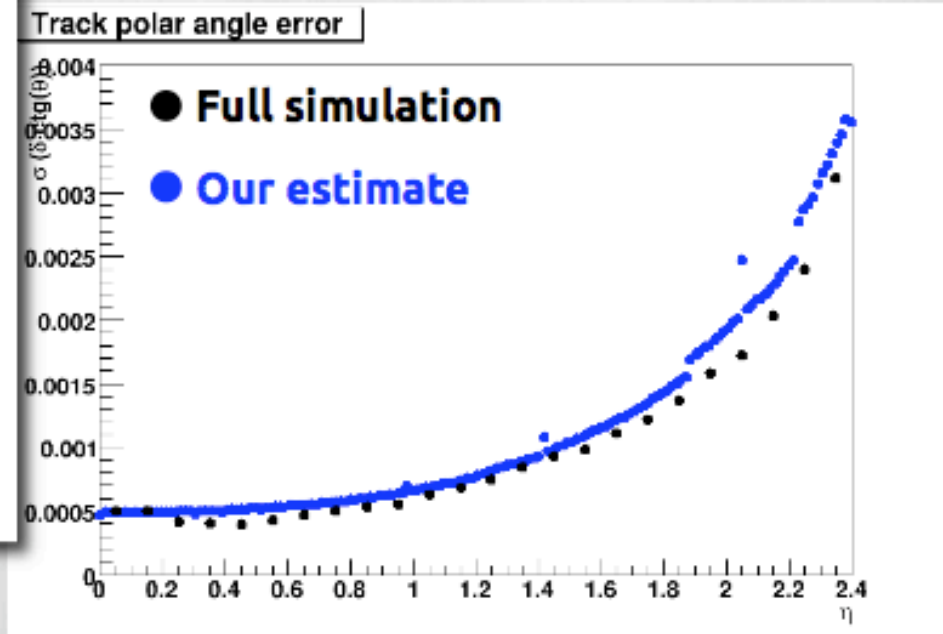
- As well as fraction of interacting particles
- Can be used in the same way to evaluate trigger performance potential

- Validated by modelling the present tracker

10 GeV

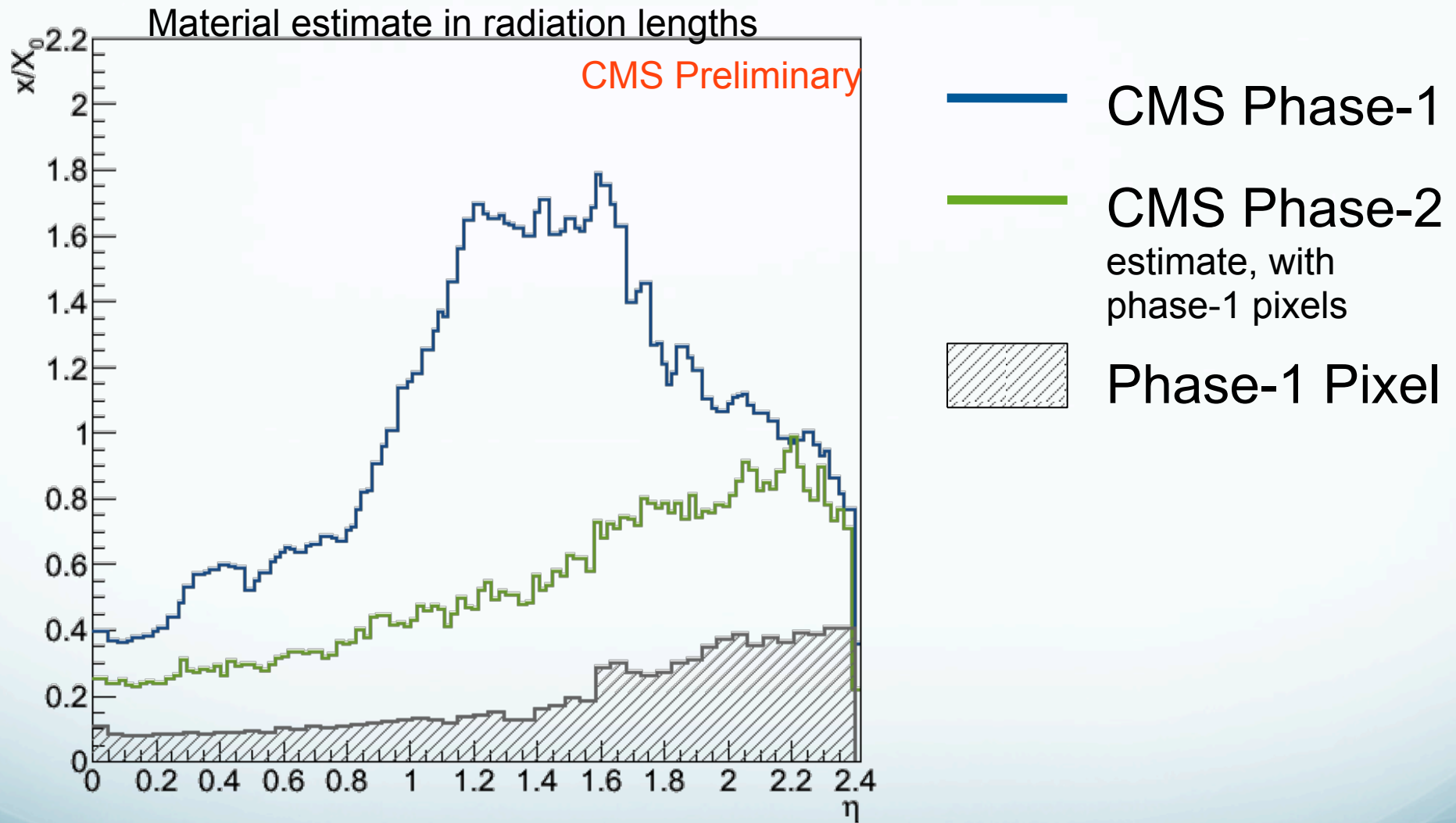


100 GeV



- Excellent accuracy out of the box!

Material



Will the “phase-2” pixel detector be as light as the phase 1?

Some performance highlights

➤ Calculated performance with a “phase-1” pixel detector

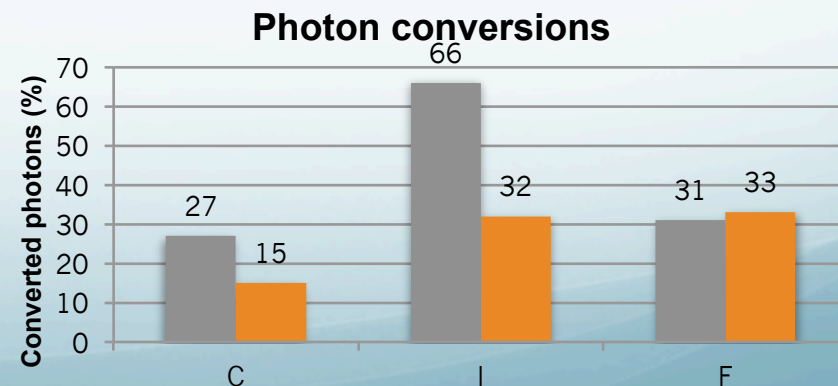
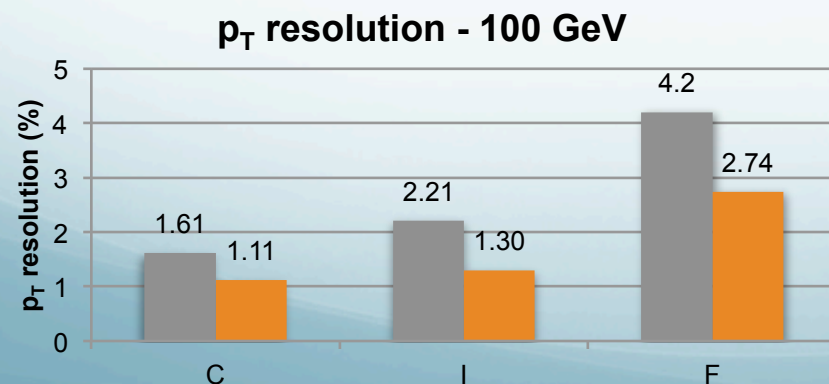
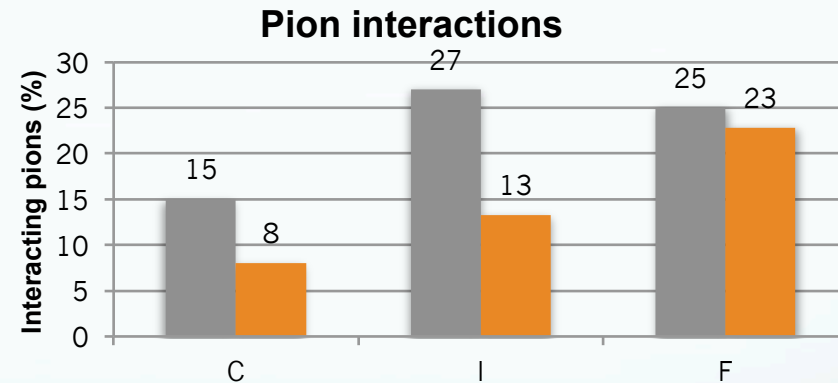
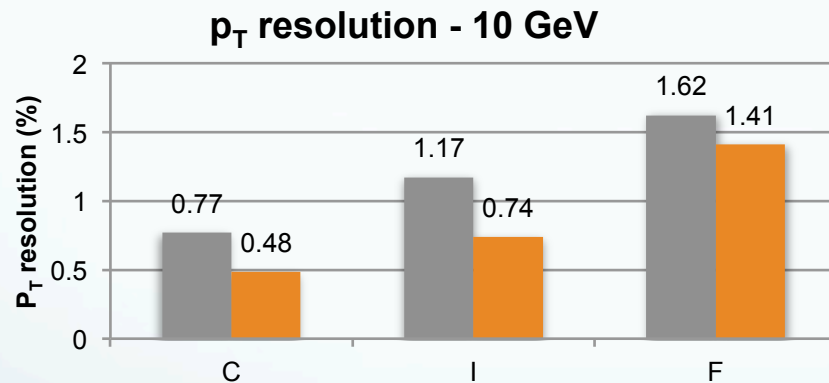
Rapidity regions

C 0 – 0.8

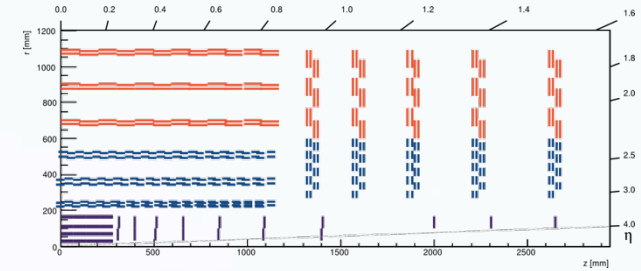
I 0.8 – 1.6

F 1.6 – 2.4

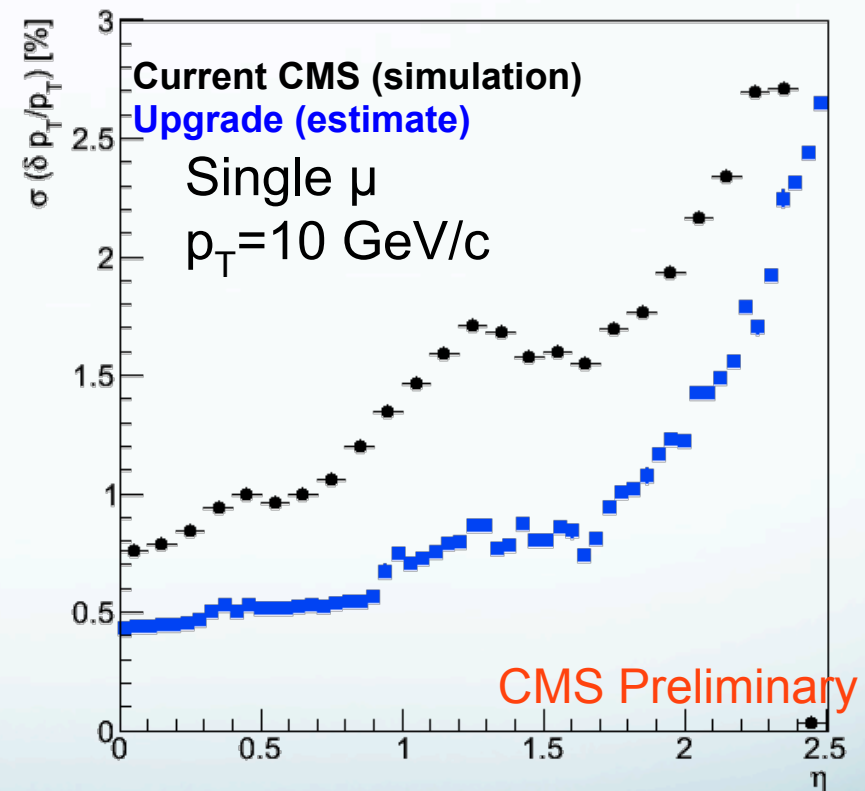
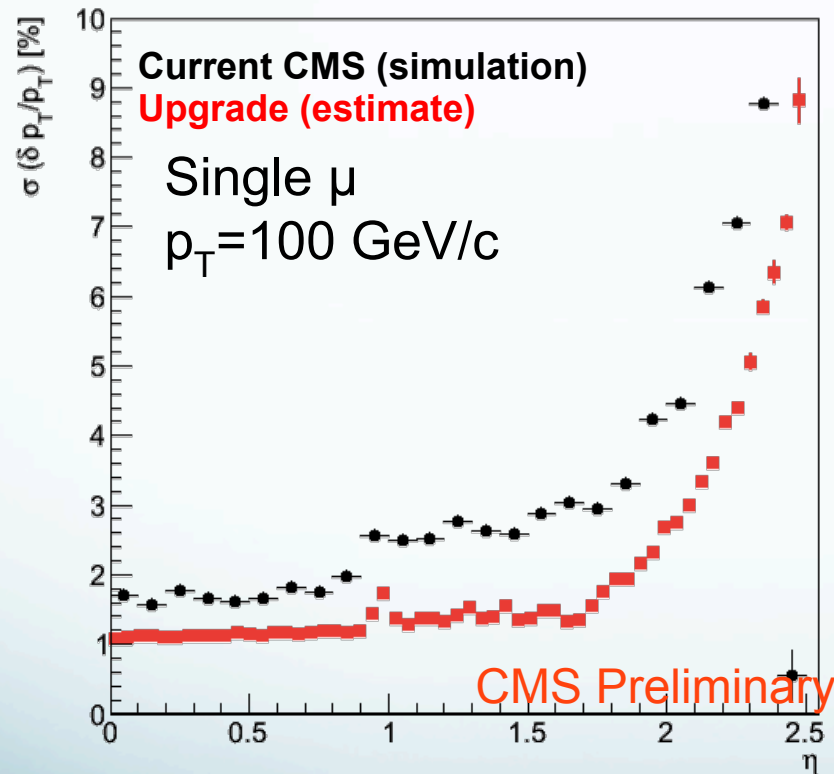
■ CMS
■ Upgrade



Tracking resolution



p_T resolution of single muons

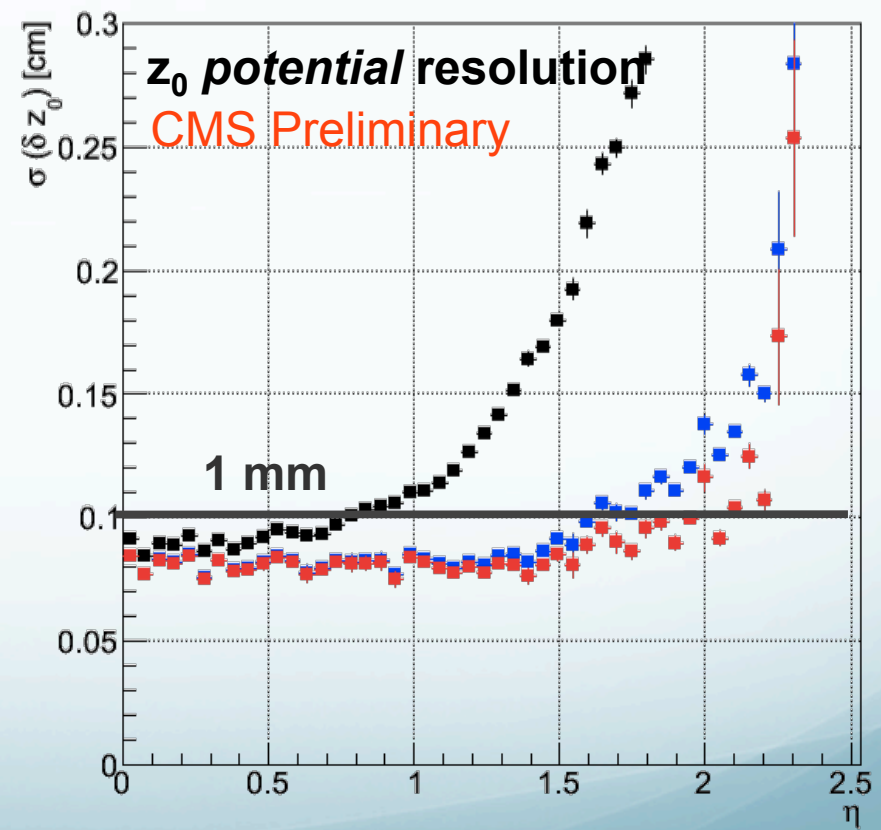
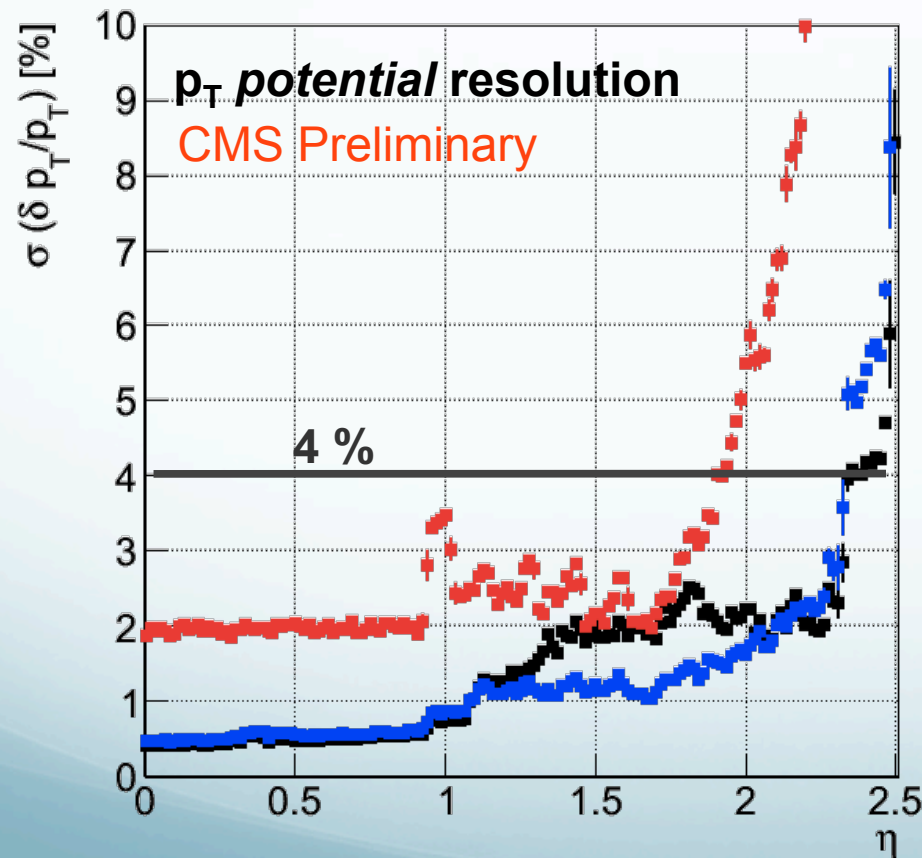


Significant improvement expected in the whole p_T range

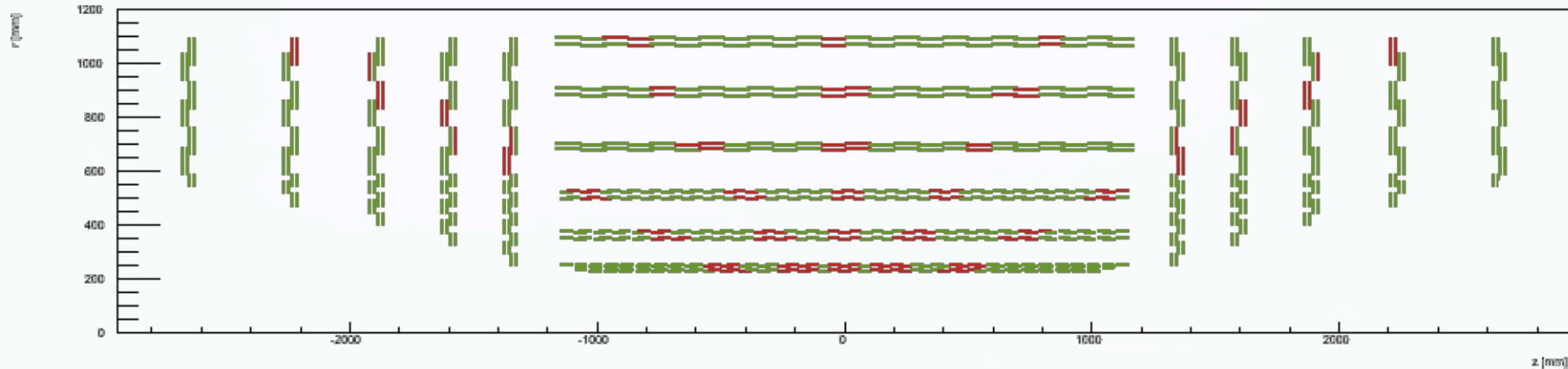
Tracking resolution @ Level-1

Single μ $p_T=2$ GeV/c
Single μ $p_T=10$ GeV/c
Single μ $p_T=100$ GeV/c

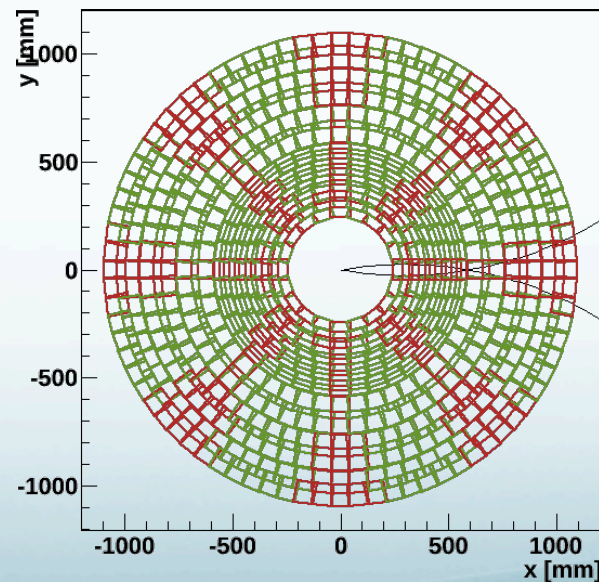
Potential p_T resolution using all stub info



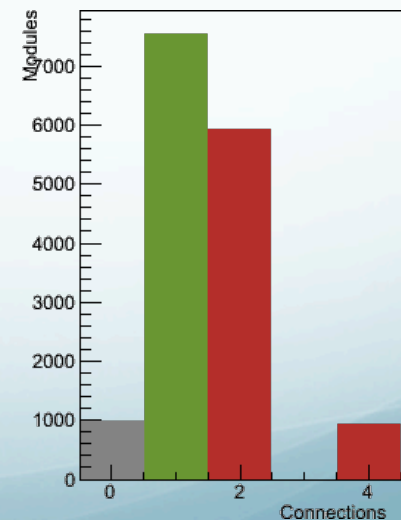
Track finding @ Level-1



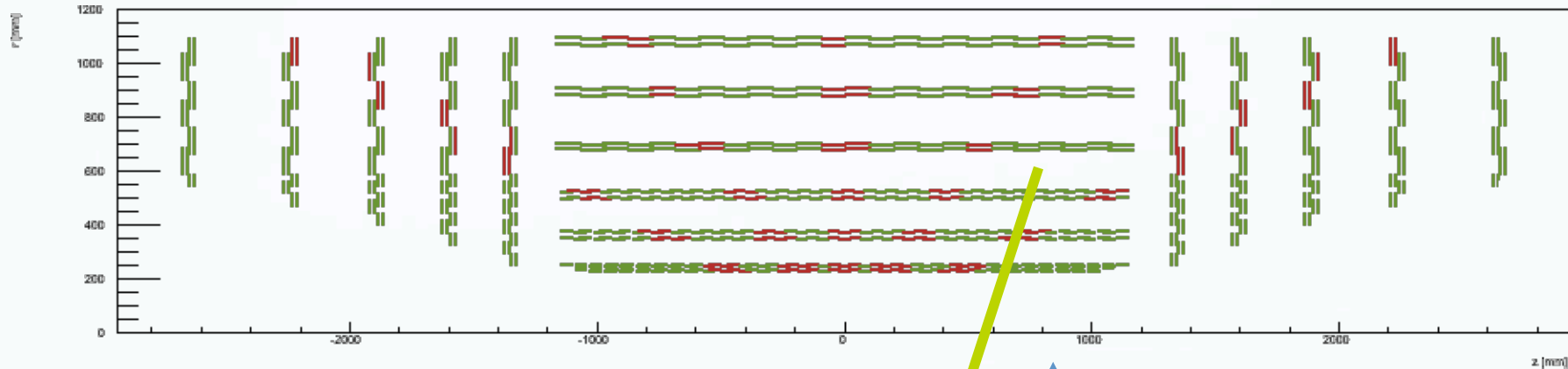
- Each sector independent
- Overlap regions depend on
 - ⊙ Luminous region Δz
 - ⊙ Minimum p_T cut



Number of sectors connected to a module

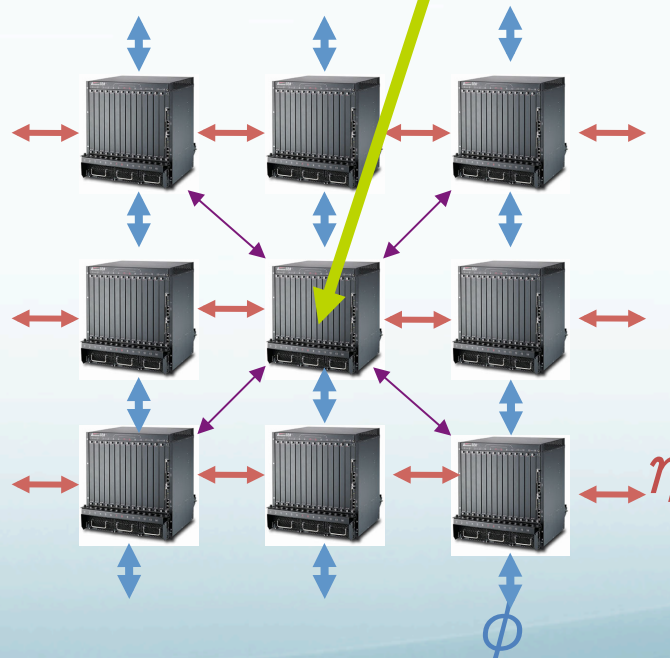


Track finding @ Level-1



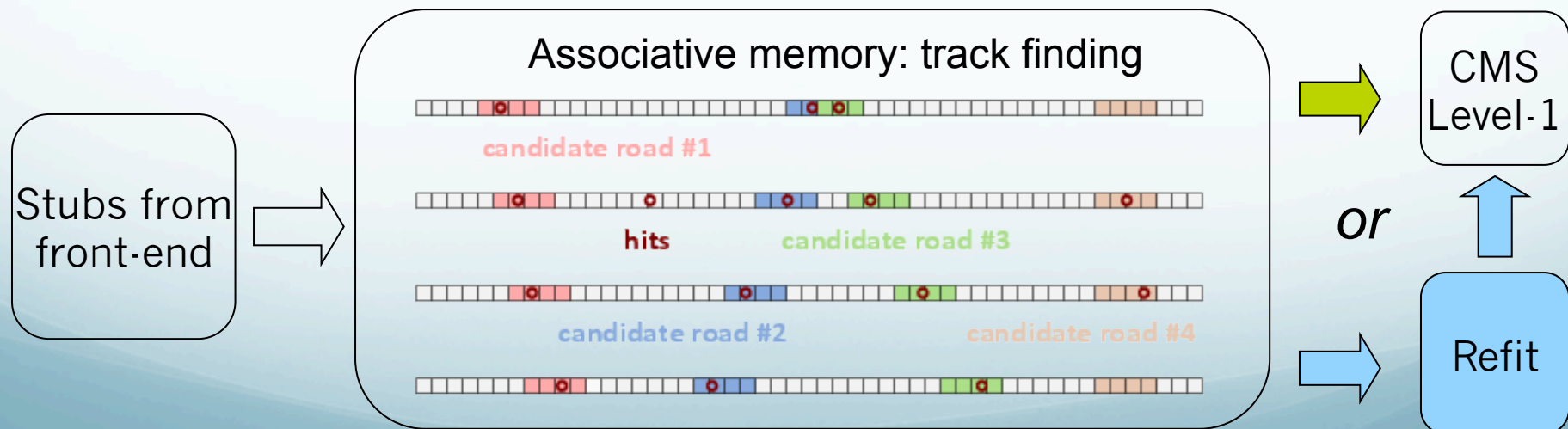
Simple
Trigger Tower
Interconnections

*Each box represents
a trigger tower*



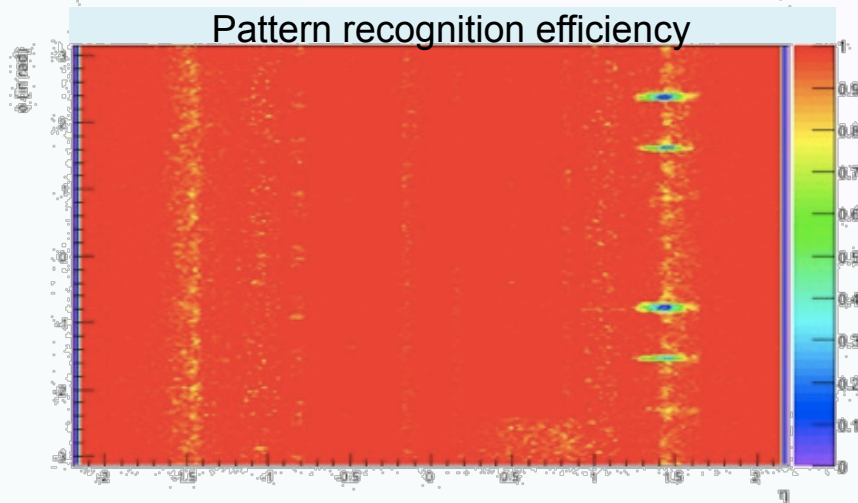
Track finding at Level-1

- Within a latency of $O(\mu\text{s})$: Associative Memories
 - ⊙ Pattern matching using AM technologies dates back to CDF SVT to enhance collection of events with long-lived hadrons
 - ⊙ HL-LHC: much higher occupancy, higher event rates, higher granularity
 - ⊙ Plan of development
 - ★ **Software emulation** (ongoing)
 - ★ Build a **demonstrator system** using ATLAS FastTrack boards (started)
 - ★ Develop dedicated AM chips and boards

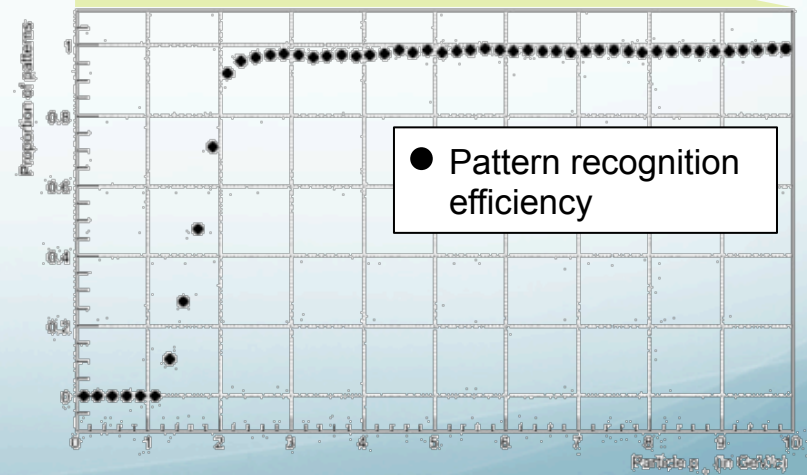
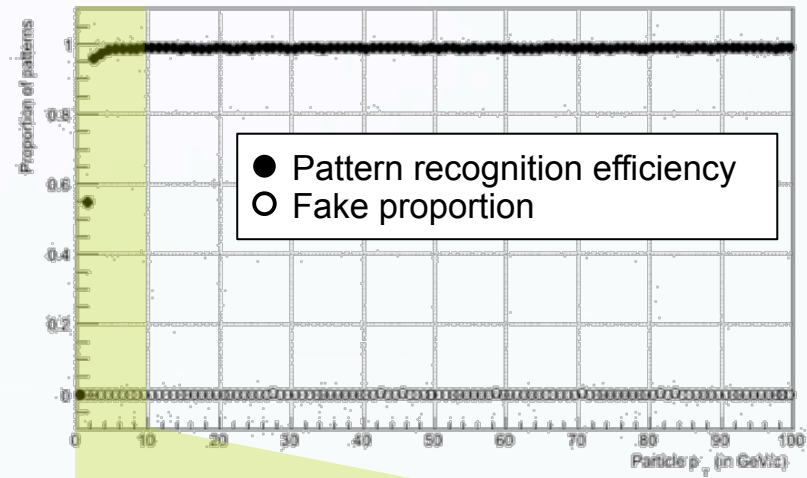


Trigger board emulation

VERY preliminary results!

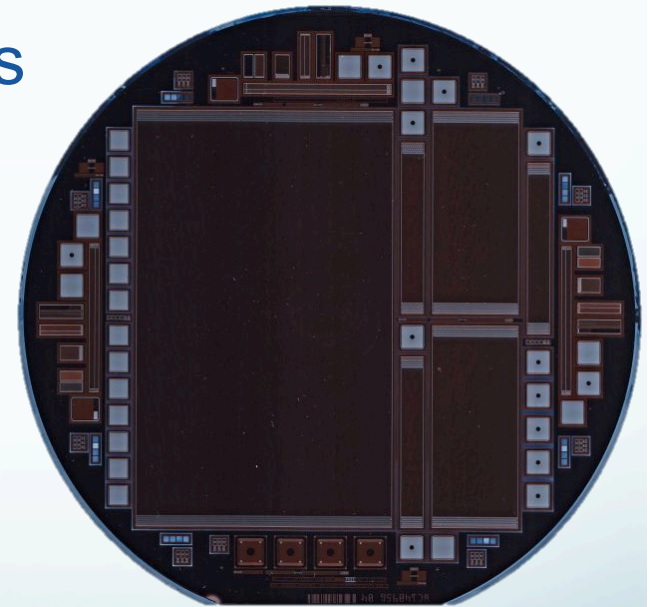


- Preliminary studies indicate that full efficiency can be achieved over the whole η range
- Sharp turn-on curve of the efficiency around ~ 1.5 GeV/c
- Implementation in hardware?

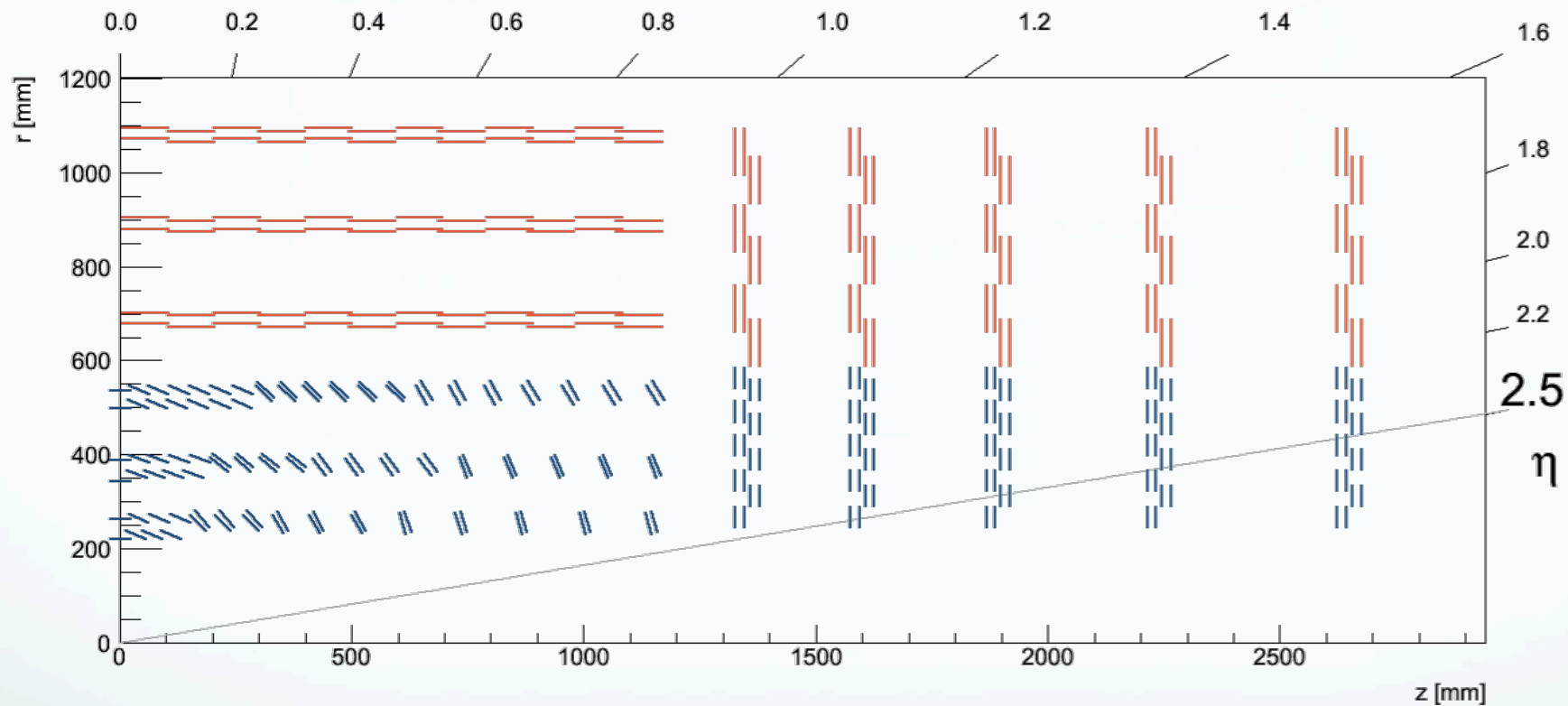


Sensors R&D

- ◎ Key element to achieve enhanced radiation tolerance and improved performance
- Select material and technology that offers adequate performance after irradiation
- Understand in detail sensors properties
 - ◎ Signal
 - ★ Design of readout electronics
 - ◎ Leakage current vs operating temperature
 - ★ Module design
 - ★ Cooling requirements
 - ★ Sealing
 - ◎ “Annealing”
 - ★ Requirements for maintenance periods
- Identify and qualify vendors who can provide sensors of the appropriate quality

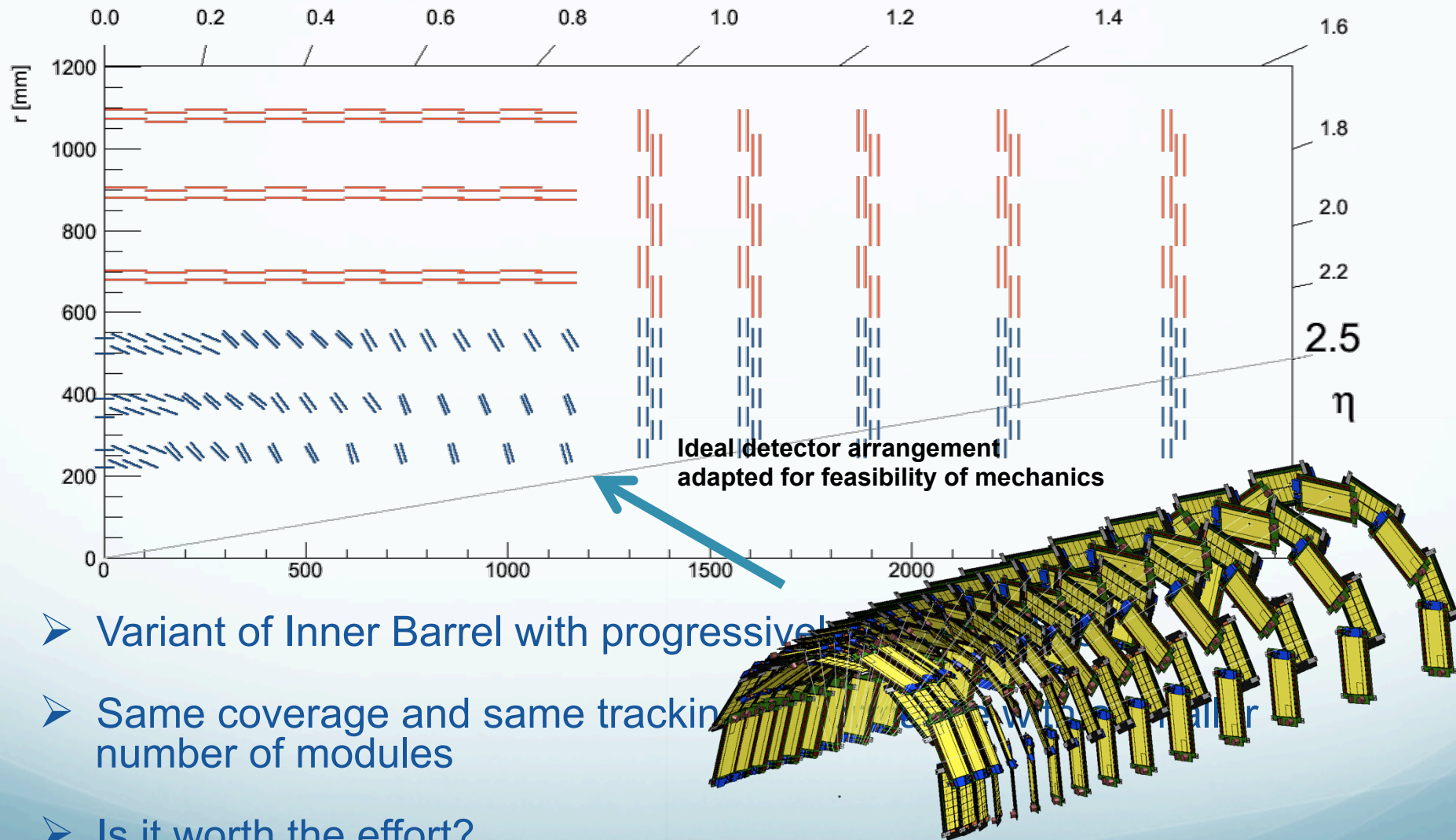


Beyond baseline?



- Variant of Inner Barrel with progressively tilted modules
- Same coverage and same tracking performance with a smaller number of modules
- Is it worth the effort?

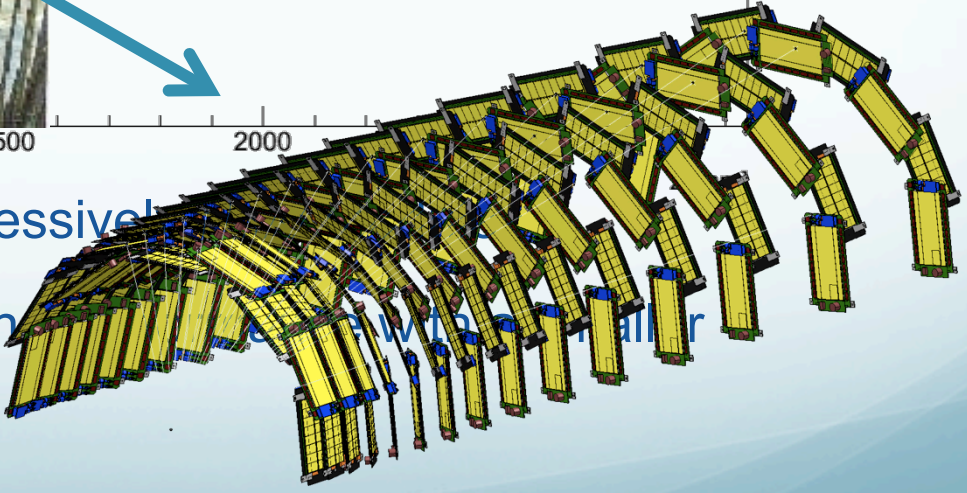
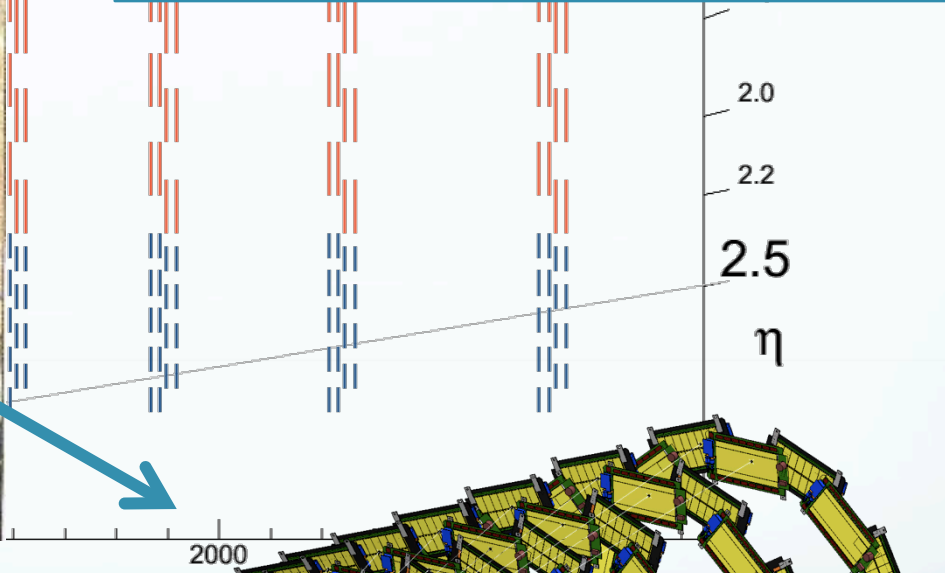
Beyond baseline?



- Variant of Inner Barrel with progressively increasing number of modules
- Same coverage and same tracking performance
- Is it worth the effort?



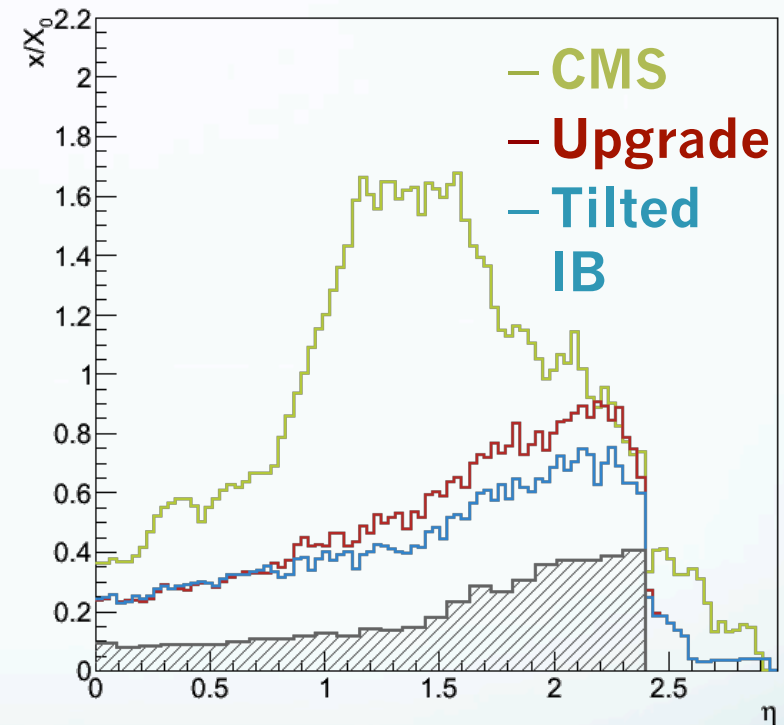
Also Known As:
“The Dinosaur”



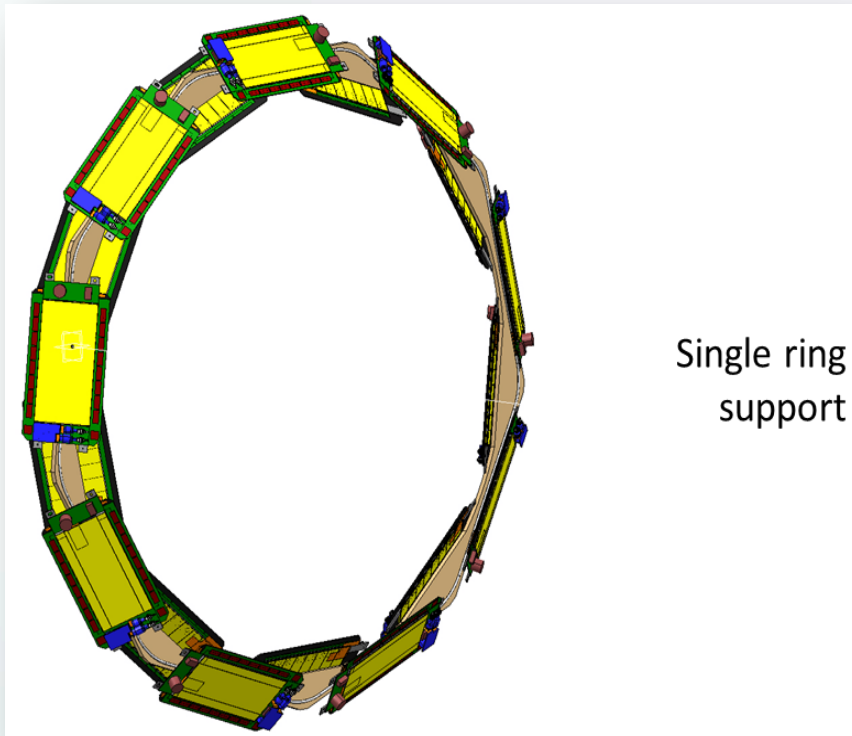
- Variant of Inner Barrel with progressively
- Same coverage and same tracking number of modules
- Is it worth the effort?

Advantages

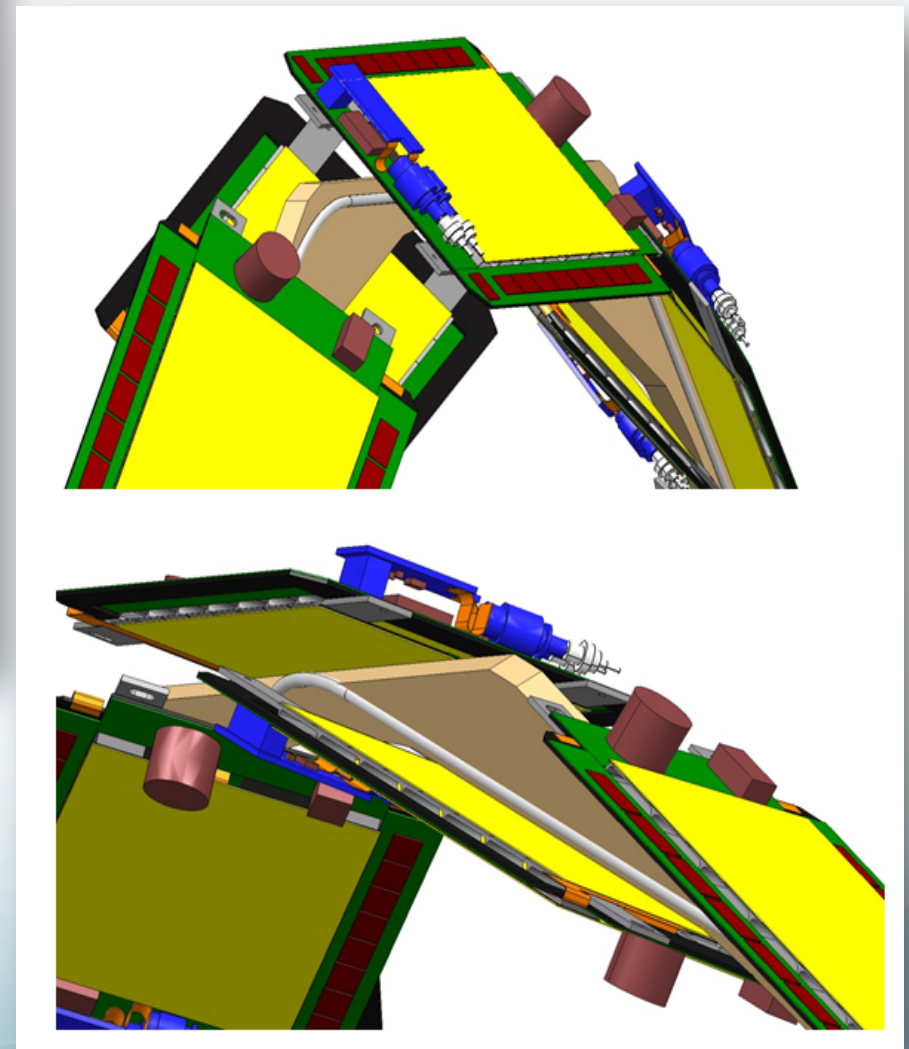
- **Smaller N of modules**
 - ⊙ N of PS modules 4164 → 2836 (-30%)
 - ★ For the inner barrel only
- **Smaller power**
 - ⊙ 23 kW → 16 kW
 - ⊙ Nicely matching TOB and each TEC!
- **Interesting reduction in material**
 - ⊙ In a volume far from the calorimeters
- **And finally also some relevant financial saving**
 - ⊙ ... ~ 5% on the overall Tracker cost!



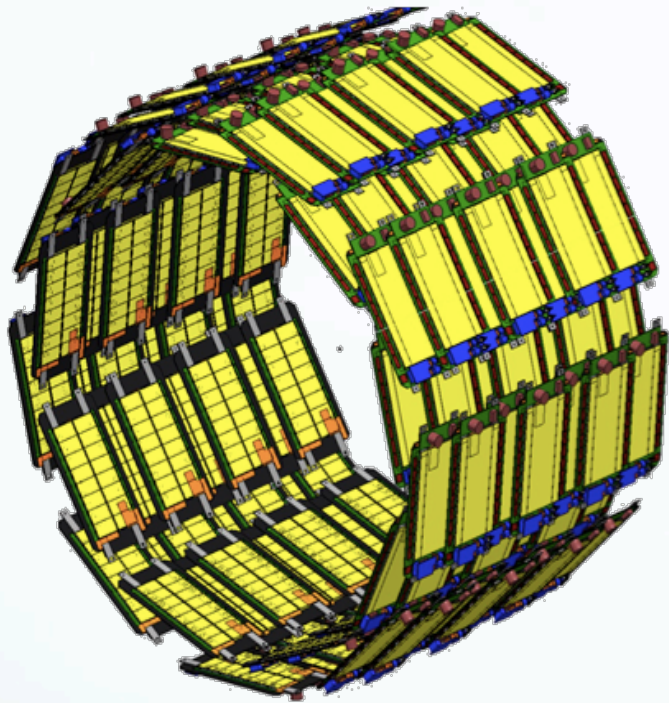
3D geometry studies



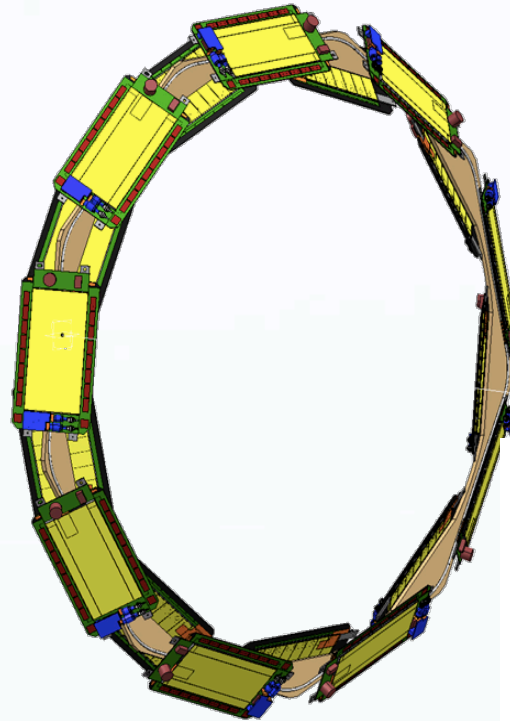
Single ring support



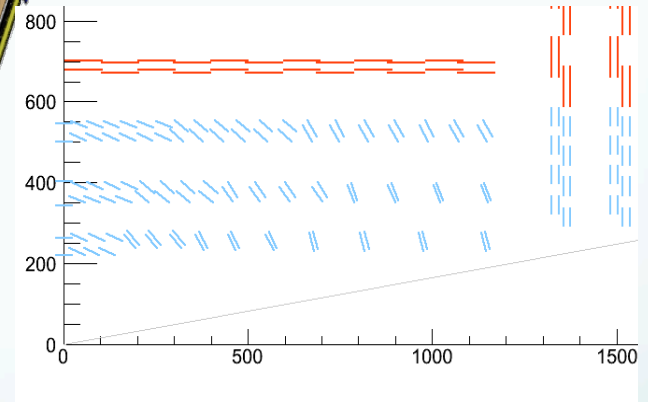
3D geometry studies



**Central region
with horizontal modules**



**End Rings
with Tilted modules**

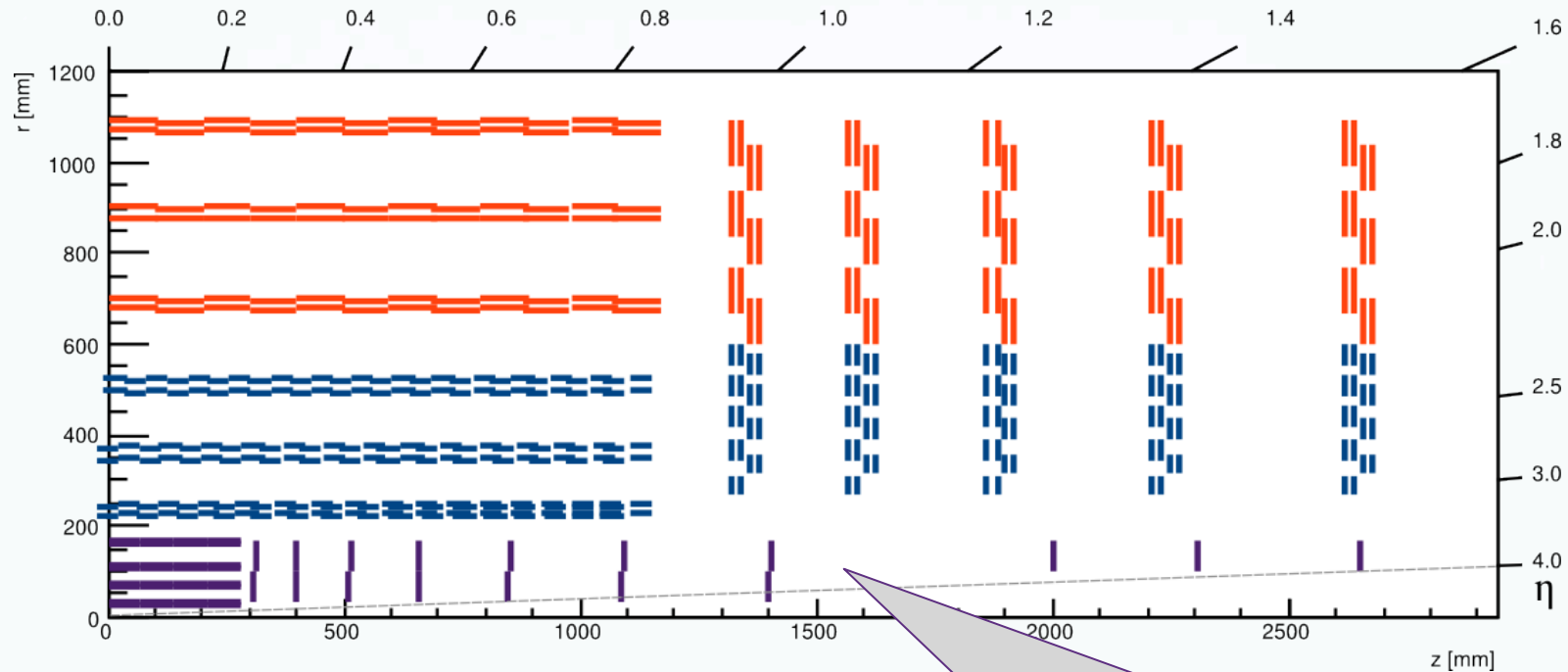


- Use the tilted modules where they are the most valuable to gain material, in the forward region
- In the central region the modules are arranged horizontally

Phase-2 pixel

- The phase-1 pixel detector is not the CMS ultimate pixel
- Construction time is shorter, ~ 2 more years to converge on a design compared to the outer tracker
- Discussions started; convergence on some basic concepts
 - ⊙ Aiming at a significantly smaller pixel size. Possibly as small as $30 \times 100 \mu\text{m}^2$?
 - ⊙ 65 nm seems to be a good technology choice
 - ★ Strong technology node, likely to be available for very long
 - ★ Can squeeze 4× digital logic in same area wrt 130 nm
 - ⊙ Thin planar sensors with small pixels could be a robust baseline
 - ⊙ 3d silicon very appealing option with potentially excellent performance
 - ★ Need to evaluate production issues and cost
 - ⊙ Several important system issues need to be addressed
 - ★ Optical components and DC-DC converter electronics unlikely to be useable in the pixel volume!

Phase-2 pixel



Fluence 2×10^{16} neq cm^{-2} @ $r=5$ cm
With current CMS pixel @600V
CCE = 50% at 10^{16} neq cm^{-2}

➤ Tracking up to $\eta \approx 4$

➤ One more open question about trigger

- ⊙ Data reduction not applicable below ~ 20 cm
- ⊙ Maybe Region-Of-Interest @Level-1.5? (with input from calorimeters/muons?)

Summary and outlook

- Designing an Outer Tracker with:
 - ⊙ Higher granularity
 - ⊙ Enhanced radiation hardness
 - ⊙ Improved tracking performance (... and lighter!)
 - ⊙ L1 Track finding capability
 - ★ Reconstruct tracks above ~ 2 GeV
 - ★ With ~ 1 mm z_0 resolution

- All the necessary R&D activities are ongoing
 - ⊙ A lot of interesting and creative work!

- Draft schedule developed for delivery in LS3

- Phase 2 pixel project on the starting blocks
 - ⊙ Many open questions to be answered!